# Functional Safety Manual Cerabar PMD50

Differential pressure measurement and pressure measurement

Differential pressure transmitter with metallic measuring cell



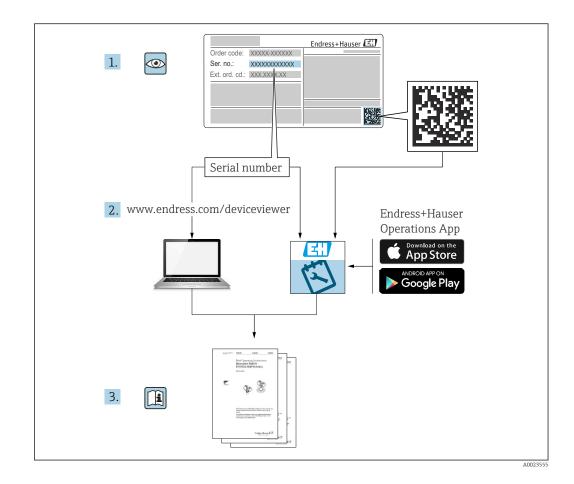
FY01109P/00/EN/01.24-00

01.00.zz (Device firmware)

71685349 2024-11-28







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## **Declaration of Conformity** 1 SIL 00543 01.24 Endress+Hauser People for Process Automation **Declaration of Conformity** Functional Safety according to IEC 61508 Based on NE 130 Form B.1 Endress+Hauser SE+Co. KG, Hauptstraße 1, 79689 Maulburg being the manufacturer, declares that the product Deltabar PMD50 is suitable for the use in safety-instrumented systems according to IEC 61508. The instructions of the corresponding functional safety manual must be followed. This declaration of conformity is exclusively valid for the listed products and accessories in delivery status. Maulburg, October 21, 2024 Endress+Hauser SE+Co. KG i. V. i. V. E-SIGNED by Stefan Jäger E-SIGNED by Lars Kretschmer on 07 November 2024 10:27:37 CET on 06 November 2024 16:29:07 CET Lars Kretschmer Stefan Jäger Dept. Man. R&D Quality Management/FSM Dept. Man. R&D Devices Pressure **Research & Development Research & Development** A0057087

#### Safety-related characteristic values 1.1

SIL\_00543\_01.24

#### E Endress+Hauser

People for Process Automation

General	-1					
Device designation and permissible types <sup>1)</sup>	Deltabar P	MD50 ** BA *	* * *	* * * * * * * * * *	+ [LA ]	
Safety-related output signal	4 20 mA					
Fault signal		′ ≥ 21.0 mA				
Process variable/function			ure, lev	vel and flow measure	ment	
Safety function(s)	MIN / MAX	•				
Device type acc. to IEC 61508-2	🗌 Туре А			🛛 Туре В		
Operating mode		mand Mode	×	ligh Demand Mode		
Valid hardware version 01.00.ww (ww: any double number)						
Valid software version	-	zz: any double nu				
Safety manual	FY01109P					
Complete HW/SW evaluation parallel to developme FMEDA and change request acc. to IEC 61508-2, 3		1508-2, 3				
ype of evaluation Evaluation of "proven in use" performance for l and change request acc. to IEC 61508-2, 3		3				
(check only <u>one</u> box) Evaluation of HW/SW field data to view IEC 61511		, 	5			
				A acc. to IEC 61508-2	2 for devices w/o softwa	
Evaluation through – report/certificate no.		land 968/FSP 28	313	-		
Test documents	Developme	ent documents		Test reports	Data sheets	
SIL – Integrity	1					
Systematic safety integrity				□ SC 2	SC 3	
Hardware safety integrity	Single channel use (HFT = 0)			SIL 2 capable	SIL 3 capable	
	Multi chan	nel use (HFT $\geq 1$	.)	SIL 2 capable	SIL 3 capable	
FMEDA					1	
Safety function	MIN		MAX		RANGE	
λ <sub>DU</sub> <sup>2),3)</sup>	35 FIT		35 F		35 FIT	
λ <sub>DD</sub> <sup>2),3)</sup>	892 FIT		892		892 FIT	
λs <sup>2),3)</sup>	688 FIT		688		688 FIT	
SFF	98%		98%		98%	
$PFD_{avg}$ (T <sub>1</sub> = 1 year) <sup>3)</sup> (single channel architecture)	1.6 · 10 <sup>-4</sup>		1.6 ·		1.6 · 10 <sup>-4</sup>	
PFH	3.5 · 10⁻ <sup>8</sup> 1	l/h	3.5 ·	10⁻ <sup>8</sup> 1/h	3.5 · 10⁻ <sup>8</sup> 1/h	
PTC <sup>4)</sup> A / B	92% / 33%	6	92%	/ 33%	92% / 33%	
Diagnostic test interval <sup>5)</sup>	≤ 30 min		≤ 30	min	≤ 30 min	
Fault reaction time <sup>6)</sup>	≤ 5 s		≤ 5 s		≤ 5 s	
Comments						
-						
Declaration						
Our internal company quality managemen evident in the future	t system ensur	res information o	on safe	ty-related systematic	faults which become	

 $^{3)}$  Valid for average ambient temperature up to +40 °C (+104 °F)

For continuous operation at ambient temperature close to +60 °C (+140 °F), a factor of 2.1 should be applied

<sup>4)</sup> PTC = Proof Test Coverage

<sup>5)</sup> All diagnostic functions are performed at least once within the diagnostic test interval <sup>6)</sup> Maximum time between error recognition and error response

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## 2 About this document

#### 2.1 Document function

This Safety Manual applies in addition to the Operating Instructions, Technical Information and Ex-specific Safety Instructions. The supplementary device documentation must be observed during installation, commissioning and operation. The requirements specific to the protection function are described in this Safety Manual.

General information on functional safety (SIL) is available at: www.endress.com/SIL

## 2.2 Symbols

#### 2.2.1 Safety symbols

#### **DANGER**

This symbol alerts you to a dangerous situation. Failure to avoid this situation will result in serious or fatal injury.

#### **WARNING**

This symbol alerts you to a potentially dangerous situation. Failure to avoid this situation can result in serious or fatal injury.

#### **A** CAUTION

This symbol alerts you to a potentially dangerous situation. Failure to avoid this situation can result in minor or medium injury.

#### NOTICE

This symbol alerts you to a potentially harmful situation. Failure to avoid this situation can result in damage to the product or something in its vicinity.

#### 2.2.2 Symbols for certain types of information and graphics

#### 🚹 Tip

Indicates additional information

#### 

Reference to documentation

#### 

Reference to graphic

#### 

Notice or individual step to be observed

#### 1., 2., 3.

Series of steps

## Result of a step

**1, 2, 3, ...** Item numbers

#### **A, B, C, ...** Views

## 2.3 Supplementary device documentation

For an overview of the scope of the associated Technical Documentation, refer to the following:

- Device Viewer (www.endress.com/deviceviewer): Enter the serial number from the nameplate
- *Endress+Hauser Operations app*: Enter serial number from nameplate or scan matrix code on nameplate.

The following document types are available in the download area of the Endress+Hauser website (www.endress.com/downloads):

#### 2.3.1 Further applicable documents

- TI01774P
- BA02333P
- KA01680P
- GP01223P

#### 2.3.2 Technical Information (TI)

#### Planning aid

The document contains all the technical data on the device and provides an overview of the accessories and other products that can be ordered for the device.

#### 2.3.3 Operating Instructions (BA)

#### Your reference guide

These Operating Instructions contain all the information that is required in various phases of the life cycle of the device: from product identification, incoming acceptance and storage, to mounting, connection, operation and commissioning through to troubleshooting, maintenance and disposal.

#### 2.3.4 Brief Operating Instructions (KA)

#### Guide that takes you quickly to the 1st measured value

The Brief Operating Instructions contain all the essential information from incoming acceptance to initial commissioning.

#### 2.3.5 Description of Device Parameters (GP)

#### Parameter reference document

The document is part of the Operating Instructions and provides a detailed explanation of each individual parameter in the operating menu.

#### 2.3.6 Safety Instructions (XA)

Depending on the approval, the following Safety Instructions (XA) are supplied with the device. They are an integral part of the Operating Instructions.

The nameplate indicates the Safety Instructions (XA) that are relevant to the device.

#### 2.3.7 Certificate

The associated certificate is available in the Endress+Hauser Device Viewer ( Section 2.3) or can be found in the Declaration of Conformity ( Section 1) of the applicable Functional Safety Manual. This certificate must be valid at the time of delivery of the device.

## 3 Design

#### 3.1 Permitted devices types

The details pertaining to functional safety in this manual relate to the device versions listed below and are valid as of the specified firmware and hardware versions.

Unless otherwise specified, all subsequent versions can also be used for safety functions.

A modification process according to IEC 61508:2010 is applied for any device modifications.

Any exemptions from possible combinations of features are saved in the Endress +Hauser ordering system.

Valid device versions for safety-related use:

#### 3.1.1 Order codes

PMD50

**Code: 010 "Approval"** Version: all

**Code: 020 "Output"** Version: BA; 2-wire 4–20 mA HART

**Code: 030 "Indication; operation"** Version: all

**Code: 040 "Housing; material"** Version: all

**Code: 050 "Electrical connection"** Version: all

**Code: 055 "Pressure type"** Version: all

Code: 075 "Sensor range" Version: all

**Code: 090 "Calibration; unit"** Version: all

**Code: 095 "Installation"** Version: all

**Code: 110 "Process connection"** Version: all

**Code: 170 "Membrane material"** Version: all

Code: 180 "Fill fluid" Version: all

Code: 200 "Seal" Version: all

**Code: 520 "Membrane coating"** Version: all

**Code: 545 "Reference accuracy"** Version: all

**Code : 550 "Calibration"** Version: all **Code: 560 "Extended nominal pressure PN"** Version: all

Code: 570 "Service" Version: all

**Code: 580 "Test, certificate, declaration"** Version: all

**Code: 590 "Additional approval"** Version: all Version **"LA"** must be selected for use as a safety function as per IEC 61508.

Code: 610 "Accessories mounted"

Version: all

**Code: 620 "Accessories enclosed"** Version: all

**Code: 850 "Firmware version"** Version: all

**Code: 895 "Marking"** Version: all

#### Valid versions

- Firmware: See Declaration of Conformity ( $\rightarrow$  device nameplate)
- Hardware: See Declaration of Conformity ( $\rightarrow$  device nameplate)

## 3.2 Identification marking

SIL-certified devices are marked with the SIL logo 🗊 on the nameplate.

## 3.3 Safety function

The device's safety functions are:

Differential pressure or relative pressure measurement

- Range monitoring (RANGE)
- Maximum monitoring (MAX)
- Minimum monitoring (MIN)

For the safety function, the limit values for maximum or minimum monitoring must be defined by the user at a downstream logic unit (e.g. PLC, limit signal transmitter, etc.) for the safety-related output signal.

The same safety-related characteristic values that apply for range monitoring also apply for maximum or minimum monitoring.

Internal device errors result in a failure current at the analog output if safe measuring operation is no longer possible.

The assessment of the functional safety of a device includes the basic unit with the main electronics, sensor electronics, and sensor up to the sensor membrane and the process connection mounted directly on the device. Process adapters and mounted/ enclosed accessories are not taken into account in the rating.

Detailed measurement errors, such as for other temperature ranges, can be calculated with the "Sizing Pressure Performance" Applicator.



■ 1 QR code for the "Sizing Pressure Performance" Applicator

#### 3.3.1 Safety-related output signal

The device's safety-related signal is the analog output signal: 4 to 20 mA. All safety measures refer exclusively to this signal.

In addition, the device also communicates via HART<sup>®</sup> for information purposes and comprises all the HART<sup>®</sup> features with additional device information. HART<sup>®</sup> communication is not part of the safety function.

The safety-related output signal is fed to a downstream logic unit, e.g. a programmable logic controller or a limit signal transmitter, where it is monitored for the following:

- Overshooting and/or undershooting of a specified limit value
- The occurrence of a fault, e.g., failure current (≤ 3.6 mA, ≥ 21.0 mA, signal cable open circuit or short-circuit).

#### NOTICE

In an alarm condition

• Ensure that the equipment under control achieves or maintains a safe state.

#### 3.3.2 Safe measurement

The transmitter's safety function comprises a transmitted current output signal that is proportional to the pressure value. All safety functions can be used in combination with all sensor configurations from the "Structure of the measuring system" section.

#### 3.3.3 Redundant configuration of multiple sensors

This section provides additional information regarding the use of homogeneously redundant sensors, e.g. in a 1002 or 2003 architecture. The failure rates for HFT = 1 are based on an analysis in accordance with:

IEC 61508-6: 2010, Annex D.4: "Using the  $\beta$ -factor to calculate the probability of failure in an E/E/PE safety-related system due to common cause failures".

The device meets the requirements for SIL 3 in homogeneously redundant applications. The following common cause factors  $\beta$  and  $\beta$ D can be used for the design.

- β for homogeneously redundant use: 5 %
- $\beta D$  for homogeneously redundant use: 2 %

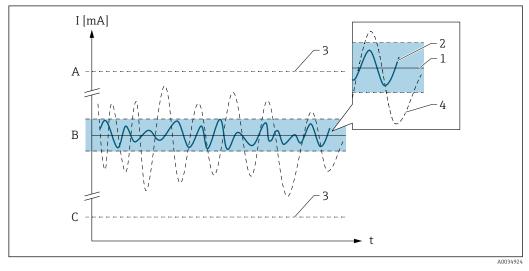
The system-specific analysis can produce other values depending on the specific installation and use of additional components.

The following are possible measures to reduce the common cause factors:

- Sensors installed in a physically separate location
- Cables routed separately
- Separate protection from environmental influences, e.g.:
  - Impact
  - Sunshine
  - EMC and/or overvoltage

## 3.4 Basic conditions for use in safety-related applications

The device must be used correctly for the specific application, taking into account the medium properties and ambient conditions. Carefully follow instructions pertaining to critical process situations and installation conditions from the Operating Instructions. The application-specific limits must be observed. The specifications in the Operating Instructions and the Technical Information must not be exceeded.



#### 3.4.1 Random failures in accordance with IEC/EN 61508

- A HI alarm ≥ 21 mA
- B SIL error range ±2%
- C LO alarm ≤ 3.6 mA

#### No device error

- No failure
- No impact on the safety-related output signal
- Impact on measurement uncertainty:
  - 1 within the specification (🔳 TI, BA etc.)

#### $\lambda_{S}$ (Safe)

- Safe failure
- No impact on the safety-related output signal: output signal enters the safe state
- Impact on the measurement uncertainty:
  - 2 Moves within the specified SIL error band B
  - 3 Has no effect

#### $\lambda_{DD}$ (Dangerous detected)

- Dangerous, detected failure
- Impact on the safety-related output signal: results in a failure mode at the output signal
- Impact on the measurement uncertainty:
  - 3 Has no effect

#### $\lambda_{DU}$ (Dangerous undetected)

- Dangerous and undetected failure
- Impact on the safety-related output signal: can be outside the defined error range B
- Impact on the measurement uncertainty:
  - 4 May be outside the specified error range

#### 3.4.2 Safety measured error

The total deviations with regard to the safety-related current output are composed of:

- A) Measured errors under reference operating conditions: according to TI
- B) Measured errors due to process/installation/ambient conditions: according to TI
- C) Measured errors due to ambient conditions (EMC): ±0.5 % in relation to the span of the safety-related current output
- D) Measured errors due to random component failures (SIL error range): ±2.0 % in relation to the span of the safety-related current output

Strong, pulse-like EMC interference on the power supply line can cause transient (< 1 s) deviations in the output signal ( $\geq \pm 1.0$  % in relation to the span of the safety-related current output. For this reason, filtering with a time constant of  $\geq 1$  s should be performed in the downstream logic unit.

#### 3.4.3 Systematic faults

Systematic faults are faults for which a cause can be clearly identified and which can only be eliminated by modifying the design or the manufacturing process, the method of operation, the operating instructions, or other influencing factors.

Failures caused by systematic faults are always reproducible and can be avoided by taking appropriate measures.

#### Measures for avoidance:

• Faults during commissioning or maintenance:

Possible remedy: Write protection via hardware DIP switch or software wizard safety mode (see Section 4.5.2) with verification of the CRC device configuration checksum.

Planning faults:

Avoid using unsuitable device configuration for the application. Possible remedy: Use Endress+Hauser Applicator to calculate the total performance.



■ 2 QR code for the "Sizing Pressure Performance" Applicator

## 3.5 Dangerous undetected failures in this scenario

An incorrect output signal that deviates from the value specified in this manual but is still in the range of 4 to 20 mA, is considered a "dangerous, undetected failure".

## 3.6 Useful lifetime of electrical components

The established failure rates of electrical components apply within the useful lifetime as per IEC 61508-2:2010 section 7.4.9.5 note 3.

In accordance with DIN EN 61508-2:2011 section 7.4.9.5 (national footnote N3), appropriate measures taken by the manufacturer and operator can extend the useful lifetime.

## 4 Commissioning (installation and configuration)

## 4.1 Requirements for personnel

The personnel for installation, commissioning, diagnostics and maintenance must fulfill the following requirements:

- Trained, qualified specialists must have a relevant qualification for this specific function and task.
- Personnel must be authorized by the plant owner/operator.
- Be familiar with federal/national regulations.
- Before starting work: personnel must read and understand the instructions in the manual and supplementary documentation as well as the certificates (depending on the application).
- Personnel must follow instructions and comply with general policies.

The operating personnel must fulfill the following requirements:

- Personnel are instructed and authorized according to the requirements of the task by the facility's owner-operator.
- Personnel follow the instructions in this manual.

## 4.2 Installation

The mounting and wiring of the device and the permitted orientations are described in the Operating Instructions pertaining to the device.

Correct installation is a prerequisite for safe operation of the device.

## 4.3 Commissioning

The commissioning of the device is described in the Operating Instructions pertaining to the device.

Prior to operating the device in a safety instrumented system, verification must be carried out by means of a test sequence as described in **the section "Proof testing"**.

## 4.4 Operation

The operation of the device is described in the Operating Instructions pertaining to the device.

## 4.5 Device configuration for safety-related applications

## 4.5.1 Adjustment of the measuring point

Measuring point adjustment is described in the Operating Instructions.

The following safety-related parameters must be configured or checked:

- Lower range value output
- Upper range value output
- Simulation
- Current range output
- Failure behavior current output
- Loop current mode
- Measuring mode current output
- Damping
- Output current transfer function
- Sensor pressure range behavior
- HP/LP swap
- Assign PV

For details → 🗊 GP01223P

The **CRC device configuration** parameter is unique and is based on the current safety-related parameter settings.

CRC device configuration based on current settings of safety relevant parameters. The CRC device configuration is unique and can be used to detect changes in safety relevant parameter settings.

The following are also relevant to safety:

- Zero adjustment offset
- Lower sensor trim
- Upper sensor trim

## 4.5.2 Device protection

The devices can be protected against external influences as follows:

- Software write protection
- Is set with the **Safety mode** wizard
- Hardware write protection
   Optional via DIP switch <a>[</a> (HW lock) on the electronic insert

The application of these methods is described below.

## 4.5.3 Configuration and locking methods

The following operating methods are possible to configure the safety function:

- DTM-based software such as Field Care or Device Care
- Operation via buttons (magnetic buttons)
- Asset management tools such as PDM or AMS

The safety function can be set in a variety of ways, which are described in detail below:

- Default setting ex works
- On-site setting
- Configuration and locking using the wizard
- Configuration and locking without the wizard

## 4.5.4 Default setting ex works

Prerequisite

The customer specified the desired configuration in the order, which was then written to the device during the production process.

A function test must be performed on-site by the user before the device may be used in SIL mode. This can be done, for example, by using one of the procedures described for proof testing (see the "Proof testing" section). It is recommended to approach the measured value for this purpose (test sequence A).

 To protect against external influences, the device can be locked using hardware write protection (DIP switch <a>L</a> (HW lock) on the electronic insert).

• The device is unlocked in the order configuration.

#### 4.5.5 On-site setting

To commission the device, carry out and document the following steps in the order shown.

Recommended for initial commissioning:

Reset the device according to the Operating Instructions. This resets all parameters to defined values (factory settings or customized settings).

**1.** Check the position of the DIP switch **L** (HW lock) on the electronic insert, set it to "OFF" if necessary.

2. Configure the device as explained in Section 9.6.3 of the Operating Instructions.

3. Lock the device using the DIP switch 🕹 (HW lock) on the electronic insert.

A function test must then be performed before the device may be used in SIL mode. This can be done, for example, by using one of the procedures described for proof testing (see the "Proof testing" section). It is recommended to approach the measured value for this purpose (test sequence A).

#### 4.5.6 Configuration and locking using the wizard

By limiting the possibilities during parameter configuration, this method offers added safety against incorrect settings.

Recommended for initial commissioning:

Reset the device according to the Operating Instructions. This resets all parameters to defined values (factory settings or customized settings).

- 1. Check the position of the DIP switch 🕹 (HW lock) on the electronic insert, set it to "OFF" if necessary.
- 2. Carry out the configuration as described in the Operating Instructions, while paying attention to the restrictions (see below). **Simulation** parameter must be set to **Off** option.
- 3. Guidance  $\rightarrow$  Safety mode
- 4. In the SIL preparation, enter "**7452**" for Enter safety locking code.
  - └ Locking status = **Temporarily locked** option

A temporary lock is only implemented if all of the following restrictions regarding configuration options are implemented:

- Loop current mode parameter is set to Enable option
- Simulation parameter is set to Off option
- Assign PV parameter is set to Pressure option
- 5. Perform **Safety mode** wizard step by step. Under **Locking** wizard enter "**7452**" for Enter safety locking code again.
- 6. Once all pages have been edited, click the Finish button to close the wizard.
  - Locking status = Safety locked option Optionally, it is also possible to lock via DIP switch L (HW lock) on the electronic insert.

A function test must then be performed before the device may be used in SIL mode. This can be done using one of the procedures described for proof testing (see the "Proof testing" section). It is recommended to approach the measured value for this purpose (test sequence A).

The current **"CRC device configuration" parameter** is saved at the end of the wizard and the device is safety-locked. If a device is unlocked and locked again, the current **CRC device configuration** parameter is compared with the **Stored CRC device configuration** parameter. If there is no deviation, the device is safety-locked after confirming the device identification, without requiring another confirmation of the safety-related parameter settings. If the values deviate from one another, the safety-related parameter settings must be confirmed once again.

If the wizard is canceled, locking is not active on the device.

• Edit all the necessary wizard pages.

#### 4.5.7 Configuration and locking without the wizard

A larger number of safety-related parameters can be freely configured. This means that the device can be adapted to difficult applications.

Recommended for initial commissioning:

Reset the device according to the Operating Instructions. This resets all parameters to defined values (factory settings or customized settings).

- 1. Check the position of the DIP switch 🕹 (HW lock) on the electronic insert, set to "OFF" if necessary.
- 2. Carry out the configuration as described in the Operating Instructions. Restriction the **Simulation** parameter must be set to the **Off** option.
- 3. Lock the device using the DIP switch 🕹 (HW lock) on the electronic insert.
- 4. Check the device settings and document them in a suitable manner. The Fieldcare print function is an easy way to document the device settings.

A function test must then be performed before the device may be used in SIL mode. This can be done using one of the procedures described for proof testing (see the "Proof testing" section). It is recommended to approach the measured value for this purpose (test sequence A).

#### 4.5.8 Unlocking device

When safety locking is active on a device, the device is protected against unauthorized operation by means of a locking code and, as an additional option, by means of a write protection switch (DIP switch  $\pounds$  (HW lock) on the electronic insert). The device must be unlocked in order to change parameters and to reset self-holding diagnostic messages.

- 1. Check the position of the DIP switch 🕹 (HW lock) on the electronic insert, set to "OFF" if necessary.
- 2. Select the **"Guidance** menu  $\rightarrow$  **Safety mode** wizard to call up the wizard.
- 3. In the **Preparation** wizard, enter **"7452**" for Enter safety unlocking code.
  - └ Locking status = **Unlocked**

#### 4.6 Parameters and default settings for the SIL mode

The following settings are not permitted for the SIL mode:

- **Simulation** parameter:
- Pressure
- Current output
- Diagnostic event simulation
- Loop current mode parameter: Disable

## 5 Operation

#### 5.1 Device behavior when switched on

Once switched on, the device runs through a diagnostic phase of approx. 5 s. The current is  $\leq$  3.6 mA during this phase.

During the diagnostic phase, no communication is possible via the service interface (CDI) or via HART.

## 5.2 Device behavior in safety function demand mode

The device outputs a current value corresponding to the measured value. This value must be monitored and processed further in a connected logic unit.

#### 5.3 Device behavior in the event of alarms and warnings

The output current in the event of an alarm can be set to a value of  $\leq$  3.6 mA or  $\geq$  21 mA.



The factory setting of the pressure transmitters is  $\leq$  3.6 mA (min. alarm).

In some cases (e.g. failure of power supply, a cable open circuit and faults in the current output itself, where the error current  $\ge 21.0$  mA cannot be set), output currents  $\le 3.6$  mA irrespective of the configured fault current can occur.

In some other cases (e.g., cabling short-circuit), output currents of  $\ge 21$  mA occur irrespective of the configured failure current.

The factory setting for the failure current on max. alarm (**Failure current** parameter) is 22.5 mA.

For alarm monitoring, the downstream logic unit must therefore be able to recognize max. alarms ( $\geq$  21.0 mA) and LO alarms ( $\leq$  3.6 mA).

#### 5.4 Alarm and warning messages

The behavior of the device in the event of an alarm and warnings is described in the relevant Operating Instructions.

Correlation between the error code and the current that is output:

#### Error code "Fxxx"

Current output:  $\geq 21 \text{ mA or} \leq 3.6 \text{ mA}$ Comment: xxx = three-digit number

**Error code ""Mxxx" / "Cxxx" / "Sxxx""** Current output: As per measured value Comment: xxx = three-digit number

## 6 Proof testing

The safety-related functionality of the device in the SIL mode must be verified during commissioning, when changes are made to safety-related parameters, and also at appropriate time intervals. This enables this functionality to be verified within the entire safety instrumented system. The time intervals must be specified by the operator.

#### 

#### The safety function is not guaranteed during a proof test

Suitable measures must be taken to guarantee process safety during the test.

- The safety-related output signal 4 to 20 mA must not be used for the safety instrumented system during testing.
- ► A completed test must be documented; the reports provided in the Appendix can be used for this purpose (see Section 8.2).
- The operator specifies the test interval and this must be taken into account when determining the probability of failure PFD<sub>avg</sub> of the sensor system.

If no operator-specific proof testing requirements have been defined, the following is a possible alternative for testing the transmitter depending on the measured variable used for the safety function. The individual proof test coverages (PTC) that can be used for calculation are specified for the test sequences described below.

#### NOTICE

#### If there is a device fault before the test, an alarm is output

• The cause of the fault must be first eliminated before starting the proof test.

#### NOTICE

#### If HW write protection is enabled

 Remove HW write protection before carrying out the proof test. If necessary, enable HW write protection again on completion of the proof test.

#### NOTICE

#### If SW write protection is enabled

► Remove SW write protection before carrying out the proof test.

#### Overview of the proof tests:

- Test sequence A
  - Simulate min. and max. alarm current
  - Approach the lower and upper measured value
- Test sequence B
   Simulate min, and may, alarm

Simulate min. and max. alarm current

#### Note the following for the test sequences:

- The individual proof test coverages (PTC) that can be used for calculation are specified in the Declaration of Conformity
- The measuring instruments (e.g. ammeter) recommended for the verification should be sufficiently precise
- The test must be carried out in such a way that it verifies the correct operation of the safeguard in interaction with all of the components

## 6.1 Test sequence A

Proof test procedure:

- **1.** Identify the device (check the Device tag, Device ID, Serial number, Firmware version and Hardware version)
- 2. Read out the setting for the customer-specific **Failure current** parameter (≥ 21 mA) and note it down

- 3. Simulate the maximum Alarm current (**Diagnostics** menu → **Simulation** submenu → **Current output** submenu).
- 4. Check whether the safety instrumented system downstream from the device detects the alarm as expected. Alternatively, measure the output current and compare it with the simulated alarm current.
- Simulate the minimum Alarm current (Diagnostics menu → Simulation submenu → Current output submenu)
- 6. Check whether the safety instrumented system downstream from the device detects the alarm as expected. Alternatively, measure the output current and compare it with the simulated alarm current.
- 7. Approach process conditions at the end of the measuring range (16 to 20 mA approx.) or apply using pressure reference.
- 8. Check the safety-related output and assess for accuracy. The result of this step is satisfactory if the output current is within the required accuracy range.
- **9.** Approach process conditions at the start of the measuring range (4 to 8 mA approx.) or apply using pressure reference.
- **10.** Check the safety-related output and assess for accuracy. The result of this step is satisfactory if the output current is within the required accuracy range.

#### NOTICE

The proof test has failed if the measured current value deviates from the expected current value by >  $\pm 2\%$  (based on the span of the safety-related current output).

- ► For troubleshooting measures, see the Operating Instructions.
- ► This test is used to detect 92 % (remaining failure rate  $\lambda_{DU}$  = 3 FIT) of dangerous undetected failures (proof test coverage, PTC = 92 %).

## 6.2 Test sequence B

Proof test procedure:

- 1. Identify the device (check the Device tag, Device ID, Serial number, Firmware version and Hardware version)
- 2. Read out the setting for the customer-specific **Failure current** parameter (≥ 21 mA) and note it down.
- 3. Simulate the maximum Alarm current (**Diagnostics** menu → **Simulation** submenu → **Current output** submenu).
- 4. Check whether the safety instrumented system downstream from the device detects the alarm as expected. Alternatively, measure the output current and compare it with the simulated alarm current
- Simulate the minimum Alarm current (Diagnostics menu → Simulation submenu → Current output submenu).
- 6. Check whether the safety instrumented system downstream from the device detects the alarm as expected. Alternatively, measure the output current and compare it with the simulated alarm current.

#### NOTICE

The proof test has failed if the downstream safety instrumented system does not detect the alarm.

- ► For troubleshooting measures, see the Operating Instructions.
- ► This test is used to detect 33 % (remaining failure rate  $\lambda_{DU} = 23$  FIT) of dangerous undetected failures (proof test coverage, PTC = 33 %).

## 6.3 Verification criterion

If one of the test criteria from the test sequences described above is not fulfilled, the device may no longer be used as part of a safety instrumented system.

- The purpose of proof-testing is to detect dangerous undetected device failures ( $\lambda_{DU}$ ).
- This test does not cover the impact of systematic faults on the safety function, which must be assessed separately.
- Systematic faults can be caused, for example, by process material properties, operating conditions, build-up or corrosion.
- As part of the visual inspection, for example, ensure that all of the seals and cable entries provide adequate sealing and that the device is not visibly damaged.

## 7 Repair and error handling

## 7.1 Maintenance

Maintenance instructions and instructions regarding recalibration may be found in the Operating Instructions pertaining to the device.

Alternative monitoring measures must be taken to ensure process safety during configuration, proof-testing and maintenance work on the device.

## 7.2 Repair

Repair means restoring functional integrity by replacing defective components.

#### Only original Endress+Hauser spare parts may be used for this purpose.

Document the repair with the following information:

- Serial number of the device
- Date of the repair
- Type of repair
- Person who performed the repair

Components may be repaired/replaced by the customer's technical staff if **original Endress+Hauser spare parts** are used (they can be ordered by the end user), and if the relevant installation instructions are followed.

A proof test must always be performed after every repair.



Installation Instructions are supplied with the original spare part and can also be accessed in the Download Area at www.endress.com

Send in replaced components to Endress+Hauser for fault analysis.

When returning the defective component, always enclose the "Declaration of Hazardous Material and Decontamination" with the note "Used as SIL device in a safety instrumented system".

Information on returns: http://www.endress.com/support/return-material

## 7.3 Modification

Modifications are changes to SIL devices that are already delivered or installed:

- Modifications to SIL devices by the user are not permitted because they can impair the functional safety of the device
- Modifications to SIL devices may be performed onsite at the user's plant following approval by the Endress+Hauser manufacturing center
- Modifications to SIL devices must be performed by personnel authorized to do so by Endress+Hauser
- Only original spare parts from Endress+Hauser may be used for modifications
- All modifications must be documented in the Endress+Hauser Device Viewer (www.endress.com/deviceviewer)
- All modifications require a change nameplate or replacement of the original nameplate.

## 7.4 Decommissioning

When decommissioning, the requirements according to IEC 61508-1:2010 section 7.17 must be observed.

## 7.5 Disposal

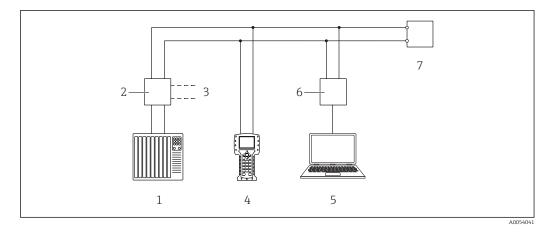
If required by the Directive 2012/19/EU on waste electrical and electronic equipment (WEEE), the product is marked with the depicted symbol in order to minimize the disposal of WEEE as unsorted municipal waste. Do not dispose of products bearing this marking as unsorted municipal waste. Instead, return them to the manufacturer for disposal under the applicable conditions.

## 8 Appendix

## 8.1 Structure of the measuring system

#### 8.1.1 System components

An example of the devices in the measuring system is shown in the following graphic.



- 1 PLC (programmable logic controller)
- 2 Transmitter power supply unit, e.g. RN series active barrier (with communication resistor)
- 3 Connection for Commubox (HART interface)
- 4 HART Communicator
- 5 Computer with operating tool (e.g. FieldCare, DeviceCare, AMS Device Manager, SIMATIC PDM) with COM DTM "CDI Communication TCP/IP"
- 6 Commubox FXA195, Commubox FXA291 (CDI)
- 7 Transmitter

An analog signal (4 to 20 mA) in proportion to the pressure is generated in the transmitter. This is sent to a downstream logic unit (e.g. PLC, limit signal transmitter, etc.) where it is monitored to determine whether:

- it exceeds or drops below a predefined value
- it is outside a range to be monitored
- a fault has occurred (e.g. sensor error, interruption or short-circuit of the sensor line, failure of the supply voltage)

For fault monitoring, the logic unit must recognize both HI alarms ( $\geq$ 21 mA) and LO alarms ( $\leq$ 3.6 mA).

#### 8.1.2 Description of use as a safeguard

The process membrane is deflected on both sides by the acting pressures. A fill fluid transfers the pressure to a side of the measuring element where a resistance bridge is located (semiconductor technology). The change in the bridge output voltage, which depends on the differential pressure, is measured and processed further.

#### 8.1.3 Installation conditions

The installation conditions for various measurements are described in the Technical Information for the device.

Correct installation is a prerequisite for safe operation of the device.

#### 8.1.4 Measurement function

The measuring principle and the measurement functions are described in the Operating Instructions for the device.

### 8.2 Commissioning or proof test report

The following device-specific test report acts as a print/master template and can be replaced or supplemented any time by the customer's own SIL reporting and testing system.

## 8.2.1 Test Report - Page 1 -

Device information
System
Device tag
Device name/Order code
Serial number
Firmware version
Hardware revision

Test information
Company/contact person
Performed by
Date/time
Inspector

Verification result	
Overall result	
🗆 Pass 🖌	🗆 Fail 🔀

Notes		

Date

Signature

Signature of tester

## 8.2.2 Test Report - Page 2 -

Device information	
System	
System Device tag Serial number	
Serial number	

#### Preparation

I have read the warning texts.  $\hfill\square$  Yes

#### Visual inspection

Proof test report: Test sequence A				
Test steps				
1. Read out max. Failure current				
Actual value:				mA
2. Simulate max. Failure current				
Is the alarm detected by the downstream safety instrumented system?				
□ Yes	No			
3. Simulate min. Failure current				
Is the alarm detected by the downstream safety instrumented system?				
□ Yes	No			
4. Approach upper measured value (approx. 16 to 20 mA) or apply it via pressure reference				
Actual value:				mA
5. Measure Output current				
Actual value:				mA
6. Result (Max. toler. deviation < +/-2%), with reference to the span of the safety-related current output?		Yes	No	
7. Approach lower measured value (approx. 4 to 8 mA) or apply it via pressure reference				
Actual value:				mA
8. Measure Output current				
Actual value:				mA
9. Result (Max. toler. deviation < +/-2%), with reference to the span of the safety-related current output?		Yes	No	

## 8.2.3 Test Report - Page 3 -

Device information	
System	
Device tag	
Serial number	

#### Preparation

I have read the warning texts.  $\hfill\square$  Yes

#### Visual inspection

Proof test report: Test sequence B	
Test steps	
1. Read out max. Failure current	
Actual value:	mA
2. Simulate max. Failure current	
Is the alarm detected by the downstream safety instrumented system?	
□ Yes	No
3. Simulate min. Failure current	
Is the alarm detected by the downstream safety instrumented system?	
□ Yes	No

	Endress + Hauser
Plant operator:	
Device and verification information Page 1	
Serial number Device tag Operating time	SIL
Device information	
Device tag Device name Serial number Firmware version Hardware revision SIL Locking CRC device configuration Stored CRC device configuration Timestamp stored CRC device config. Operating time Configuration counter	
Notes	

## 8.2.4 Commissioning Test Report - Page 1 -

Image: Second Second

SIL Commissioning	Endress + Hauser	
Plant operator:		
Device and verification information Page 2		
Serial number Device tag Operating time		
SIL preparation		
Proof test via Bluetooth allowed? SIL preparation		
Character test string Result		
Inspector Location Date/time		
Notes 		
		A004520

## 8.2.5 Commissioning Test Report - Page 2 -

Example of a commissioning report using the wizard - Page 2 -

Plant operator:  Device and verification information Page 3 Serial number Device tag Operating time  Parameter CRC  Current output simulation Lover range value output Upper range value output Upper range value output Current range function Current rang	Plant operator:  Device and verification information Page 3  Serial number Device tag Operating time  Device tag Operating time  Device tag Operating time  Device tag Operating time  Device tage Current output simulation Current output Current out	SIL Commissioning	Endress + Hauser
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Device tag Operating time  Parameter CRC  Current output simulation Lower range value output Upper range value output Upper range value output Upper range value output Current range output Failure behavior current output Loop current node Measuring mode current output Damping Output current transfer function Sensor pressure range behavior Asign PV Parameter additional Zero adjustment offset Lower sensor trim	Device ng Operating time Operating t	Device and verification information Page 3	
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Current range output Failure behavior current output Loop current mode Measuring mode current output Damping Output current transfer function Sensor pressure range behavior Assign PV Parameter additional Zero adjustment offset Lower sensor trim	Current range output Failure behavior current output Loop current mode Measuring mode current output Damping Output current transfer function Sensor pressure range behavior Assign PV Parameter additional Zero adjustment offset Lower sensor trim	Lower range value output	
Failure behavior current output         Loop current mode         Measuring mode current output         Damping         Output current transfer function         Sensor pressure range behavior         Assign PV         Parameter additional         Zero adjustment offset         Lower sensor trim	Failure behavior current output         Loop current mode         Measuring mode current output         Damping         Output current transfer function         Sensor pressure range behavior         Assign PV         Parameter additional         Zero adjustment offset         Lower sensor trim	Upper range value output	
Loop eurrent mode Measuring mode current output Damping Output current transfer function Sensor pressure range behavior Assign PV Parameter additional Zero adjustment offset Lower sensor trim	Loop eurrent mode Measuring mode current output Damping Output current transfer function Sensor pressure range behavior Assign PV Parameter additional Zero adjustment offset Lower sensor trim	Current range output	
Measuring mode current output Damping Output current transfer function Sensor pressure range behavior Assign PV Parameter additional Zero adjustment offset Lower sensor trim	Measuring mode current output Damping Output current transfer function Sensor pressure range behavior Assign PV Parameter additional Zero adjustment offset Lower sensor trim	Failure behavior current output	
Damping Output current transfer function Sensor pressure range behavior Assign PV Parameter additional Zero adjustment offset Lower sensor trim	Damping Output current transfer function Sensor pressure range behavior Assign PV Parameter additional Zero adjustment offset Lower sensor trim	Loop current mode	
Output current transfer function Sensor pressure range behavior Assign PV Parameter additional Zero adjustment offset Lower sensor trim	Output current transfer function Sensor pressure range behavior Assign PV Parameter additional Zero adjustment offset Lower sensor trim	Measuring mode current output	
Sensor pressure range behavior Assign PV Parameter additional Zero adjustment offset Lower sensor trim	Sensor pressure range behavior Assign PV Parameter additional Zero adjustment offset Lower sensor trim	Damping	
Assign PV Parameter additional Zero adjustment offset Lower sensor trim	Assign PV Parameter additional Zero adjustment offset Lower sensor trim	Output current transfer function	
Parameter additional Zero adjustment offset Lower sensor trim	Parameter additional Zero adjustment offset Lower sensor trim	Sensor pressure range behavior	
Zero adjustment offset Lower sensor trim	Zero adjustment offset Lower sensor trim	Assign PV	
Zero adjustment offset Lower sensor trim	Zero adjustment offset Lower sensor trim	Parameter additional	
Lower sensor trim	Lower sensor trim		
		Zero adjustment offset	
		Lower sensor trim	

#### 8.2.6 Commissioning Test Report - Page 3 -

Example of a commissioning report using the wizard - Page 3 -

## 8.3 Version history

#### FY01109F; version 01.24

- Firmware version: 01.00.zz (zz: any double number)
- Hardware version: 01.00.ww (ww: any double number) or from date of device delivery
- Changes: First version

A0045209



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