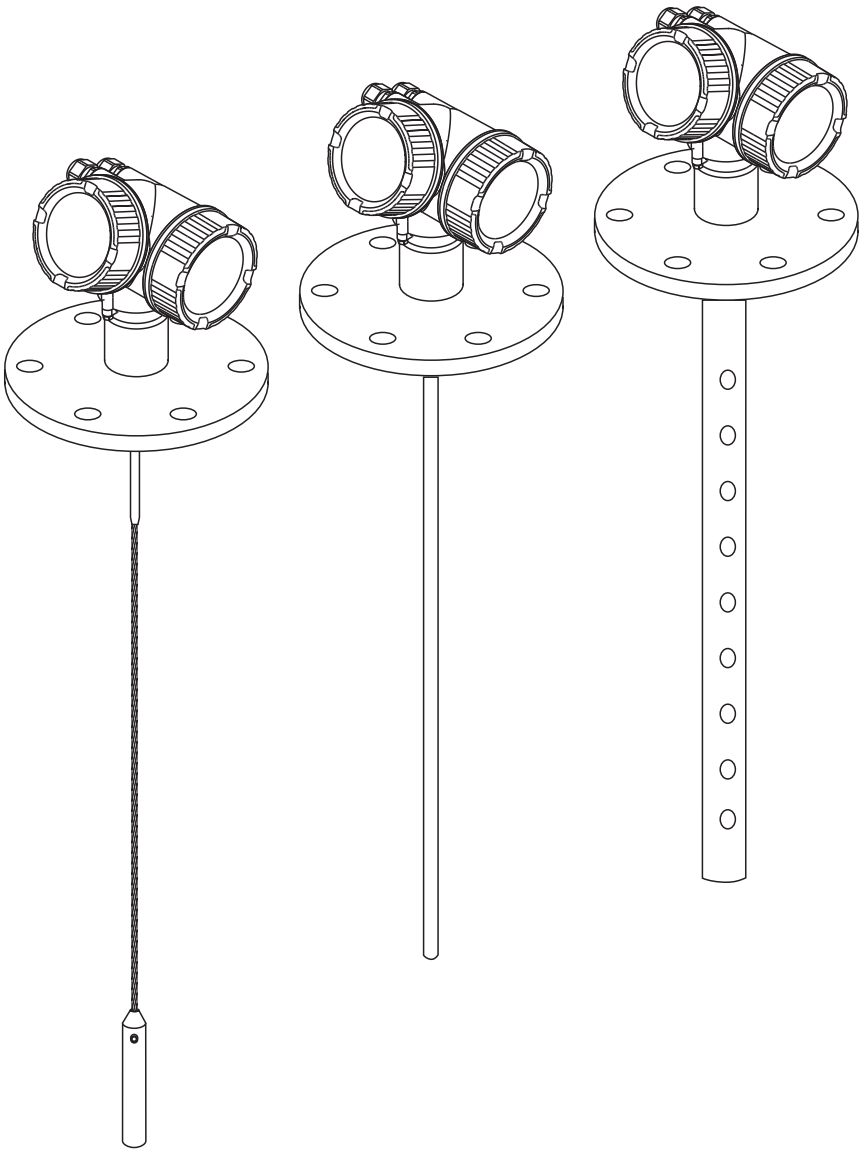
GP01140F/00/EN/01.19
71424614
2019-03-04

01.03.zz (Device firmware)

Description of Device Parameters
Levelflex FMP5x
Modbus

Guided wave radar



Endress+Hauser
People for Process Automation

Table of contents

1 Important document information

1.1 Document function

The document is part of the Operating Instructions and serves as a reference for parameters, providing a detailed explanation of each individual parameter of the operating menu.

1.2 Symbols

1.2.1 Safety symbols

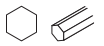
Symbol	Meaning
DANGER	**DANGER!** This symbol alerts you to a dangerous situation. Failure to avoid this situation will result in serious or fatal injury.
WARNING	**WARNING!** This symbol alerts you to a dangerous situation. Failure to avoid this situation can result in serious or fatal injury.
CAUTION	**CAUTION!** This symbol alerts you to a dangerous situation. Failure to avoid this situation can result in minor or medium injury.
NOTICE	**NOTE!** This symbol contains information on procedures and other facts which do not result in personal injury.

1.2.2 Electrical symbols

Symbol	Meaning
⎓	Direct current
~	Alternating current
⎓ ~	Direct current and alternating current
⏚	**Ground connection** A grounded terminal which, as far as the operator is concerned, is grounded via a grounding system.
⊕	**Protective Earth (PE)** A terminal which must be connected to ground prior to establishing any other connections. The ground terminals are situated inside and outside the device: ▪ Inner ground terminal: Connects the protectiv earth to the mains supply. ▪ Outer ground terminal: Connects the device to the plant grounding system.

1.2.3 Tool symbols

Symbol	Meaning
 A0013442	Torx screwdriver
 A0011220	Flat blade screwdriver

Symbol	Meaning
 A0011219	Cross-head screwdriver
 A0011221	Allen key
 A0011222	Hexagon wrench

1.2.4 Symbols for certain types of information

Symbol	Meaning
	**Tip** Indicates additional information.
	Reference to documentation.
	Reference to page.
	Reference to graphic.
 A0028662	Operation via local display.
 A0028663	Operation via operating tool.
 A0028665	Write-protected parameter.

1.2.5 Symbols in graphics

Symbol	Meaning
1, 2, 3 ...	Item numbers
A, B, C, ...	Views
A-A, B-B, C-C, ...	Sections

1.2.6 Symbols at the device

Symbol	Meaning
	**Safety instructions** Observe the safety instructions contained in the associated Operating Instructions.
	**Temperature resistance of the connection cables** Specifies the minimum value of the temperature resistance of the connection cables.

1.3 Supplementary documentation

Document	Purpose and content of the document
Technical Information TI01454F (FMP51, Modbus)	**Planning aid for your device** The document contains all the technical data on the device and provides an overview of the accessories and other products that can be ordered for the device.
Brief Operating Instructions KA01421F (FMP51, Modbus)	**Guide that takes you quickly to the 1st measured value** The Brief Operating Instructions contain all the essential information from incoming acceptance to initial commissioning.
Description of Device Parameters GP01140F (FMP51, Modbus)	**Reference for your parameters** The document provides a detailed explanation of each individual parameter in the operating menu. The description is aimed at those who work with the device over the entire life cycle and perform specific configurations.

1.4 Terms and abbreviations

Term/abbreviation	Explanation
BA	Document type "Operating Instructions"
KA	Document type "Brief Operating Instructions"
TI	Document type "Technical Information"
SD	Document type "Special Documentation"
XA	Document type "Safety Instructions"
PN	Nominal pressure
MWP	Maximum Working Pressure The MWP can also be found on the nameplate.
ToF	Time of Flight
ε_r (DC value)	Relative dielectric constant
BD	Blocking Distance; no signals are analyzed within the BD.
PLC	Programmable Logic Controller
CDI	Common Data Interface

1.5 Registered trademarks

Modbus®
Registered trademark of SCHNEIDER AUTOMATION, INC.

KALREZ®, VITON®
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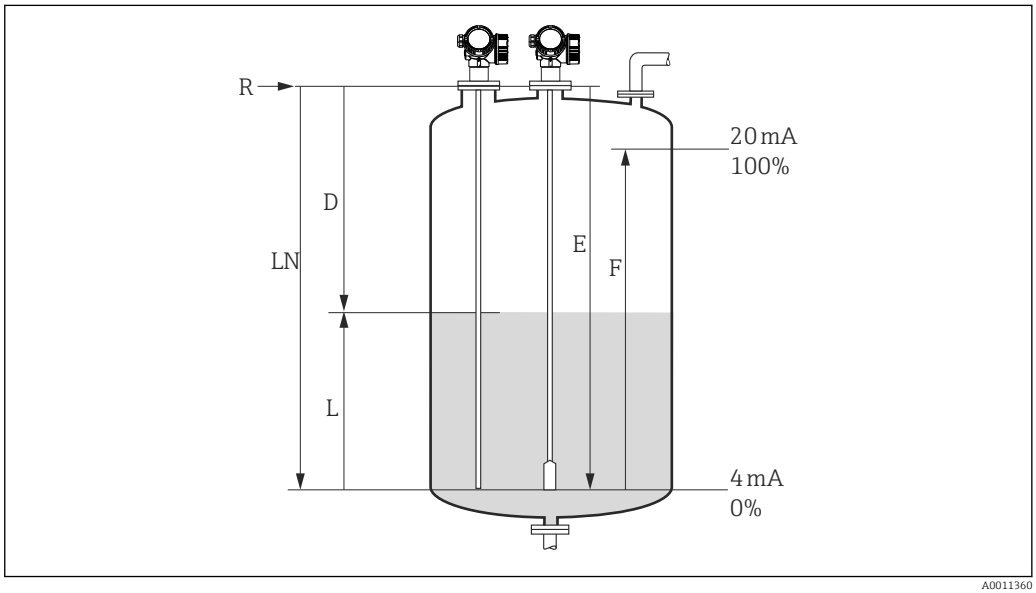
2 Basic principles

2.1 Time-of-Flight principle

The Levelflex uses the guided propagation and reflection of electromagnetic pulses in order to determine the distance to a target object. The time that passes between emitting and receiving the pulses is a measurement for the distance to the object. Since the pulses have to travel to the object and back, the distance D is the result of half of the product of the duration t and the velocity of propagation c:

$D = \Delta t \times c/2$

From D, the level is then calculated with the help of the calibration parameters.



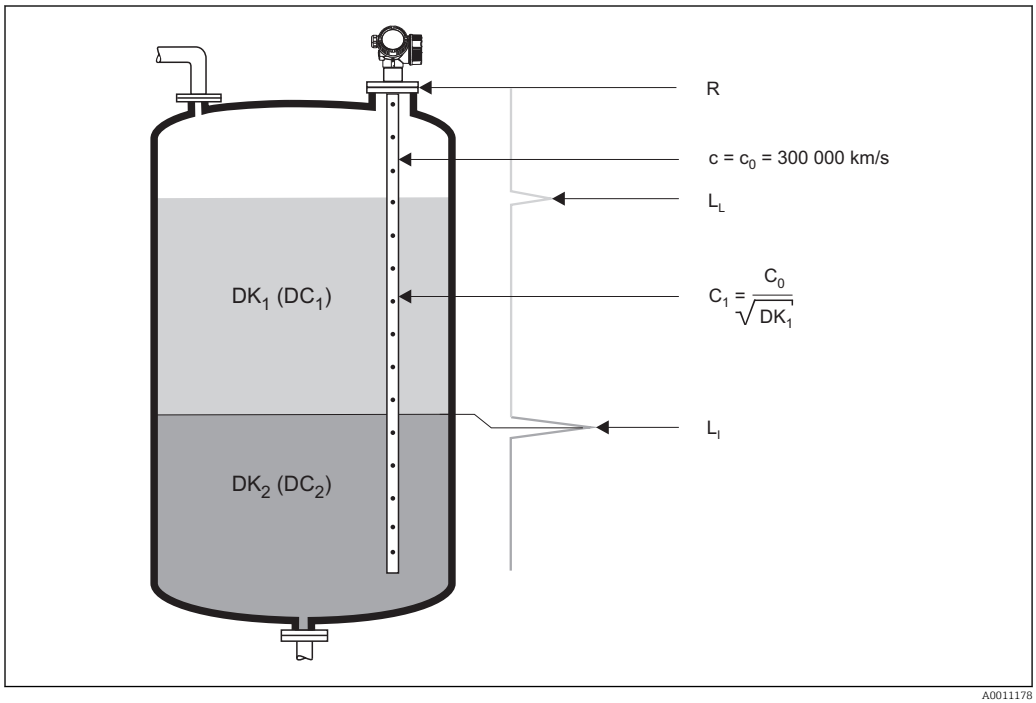
1 *Calibration parameters for the time-of-flight principle*

LN Length of the probe
D Distance
L Level
R Reference point of the measurement
E Empty calibration (= zero)
F Full calibration (= span)

2.2 Interface measurement

Interface measurement is possible with FMP51, FMP52, FMP54 and FMP55. It can be activated via the **Operating mode** parameter (→ 50).

When the high-frequency pulses hit the surface of the medium, only a percentage of the transmission pulse is reflected. In the case of media with a low dielectric constant DC_1, in particular, the other part penetrates the medium. The pulse is reflected once more at the interface point to a second medium with a higher dielectric constant, DC_2. The distance to the interface layer can now also be determined taking into account the delayed time-of-flight of the pulse through the upper medium.



2 *Interface measurement with the guided radar*

Preconditions for an interface measurement

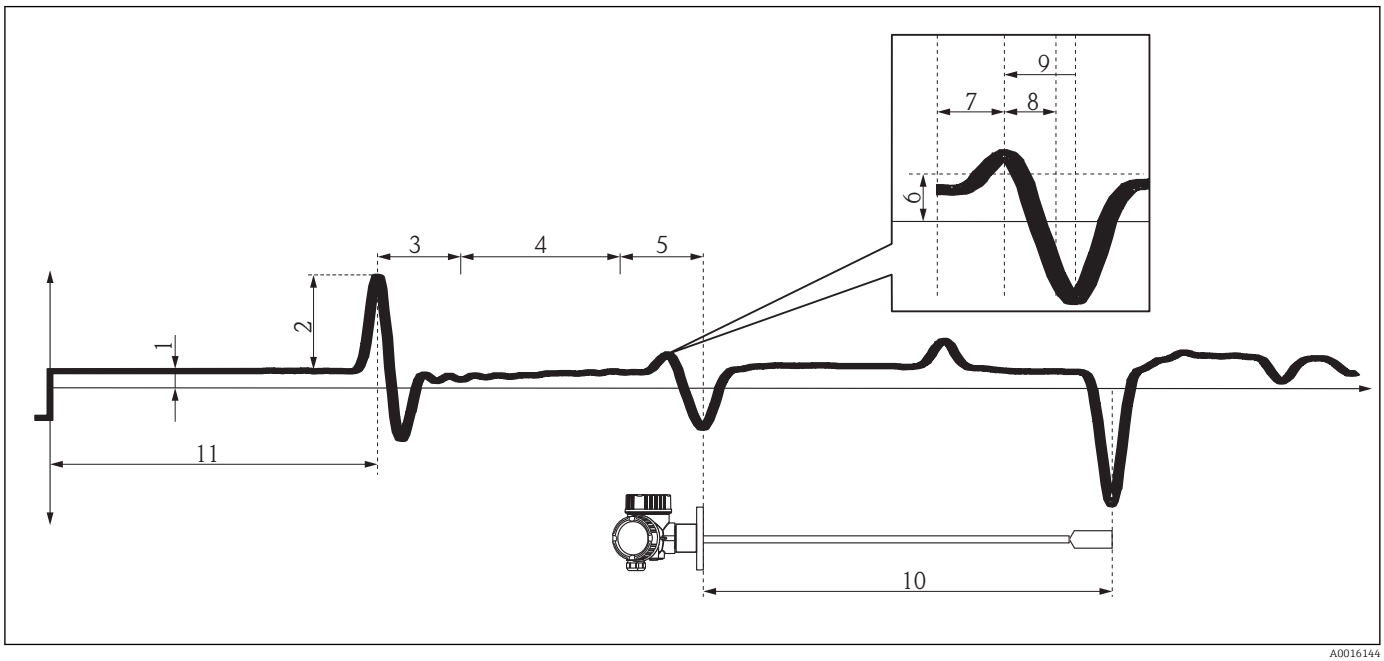
- The dielectric constant (DC) of the upper medium must be known and constant.
- The DC of the upper medium may not be greater than 10.
- The DC difference between the upper medium and lower medium must be > 10
- The upper medium must have a minimum thickness of 60 mm (2.4 in).

For dielectric constants (DC values) of many media commonly used in various industries refer to:

- the Endress+Hauser DC manual (CP01076F)
- the Endress+Hauser "DC Values App" (available for Android and iOS)

2.3 Envelope curve

The Levelflex emits individual pulses in quick succession and scans their reflection again with a fluctuating delay. The amounts of entergy received are arranged according to their time of flight. The graphic represenataion of this sequence is called "envelope curve". The following diagram shows a sketch of a typical envelope curve:



3 *Important features of the envelope curve*

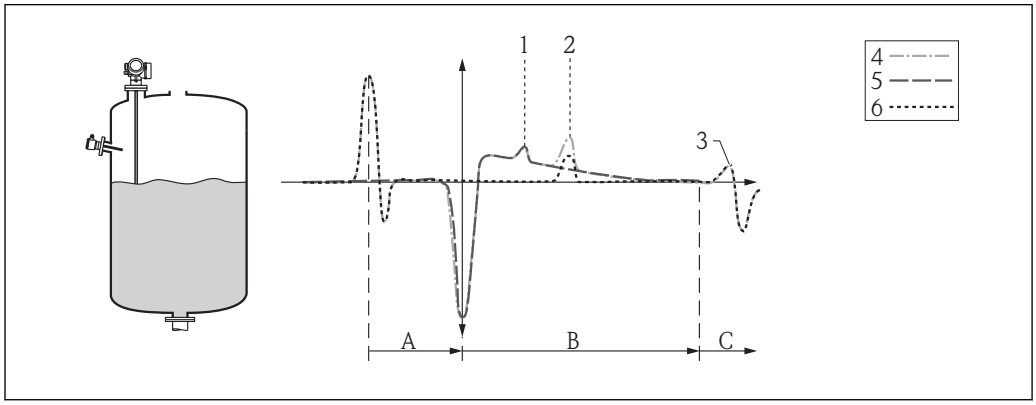
1 *Env.curve offset*
2 *Ref. echo ampl.*
3 *Electr.zero dist*
4 *Cable zero dist.*
5 *Ant. zero dist.*
6 *Thres. f. z-dist*
7 *F zdist.win.left*
8 *Fzdist.win.right*
9 *Fine zero dist.*
10 *Physical length of the probe (LN)*
11 *Ref.echoposition*

2.4 Mapping and subtracted curve

The mapping is used to suppress static interference signals which may be generatet by internal tank or silo fittings. A **mapping curve**, representing the **envelope curve** of an empty tank or silo as precisely as possible, is used for the mapping.

After a mapping, the signal evaluation does not use the envelope curve but the **subtracted curve**, instead:

Subtracted curve = Envelope curve - Mapping curve



4 *Mapping and subtracted curve*

1 Interference echo
2 Level echo
3 End-of-probe echo
4 Envelope curve
5 Mapping curve
6 Subtracted curve
A Internal area (Z distances)
B Level area
C End-of-probe area (EOP)

2.5 Echo tracking

Levelflex uses an echo tracking algorithm. This means, echoes in subsequent envelope curves are not evaluated independently but are considered to be a sequence of moving echos. To do so, each echo is surrounded by a window of a certain width and the echo is searched for within this window in the next envelope curve. If an echo of this type is found, it is allocated to the "track" of the previous echo. Each track can be assigned a specific meaning (level echo track, interface echo track, end-of-probe echo track, multiple echo track).

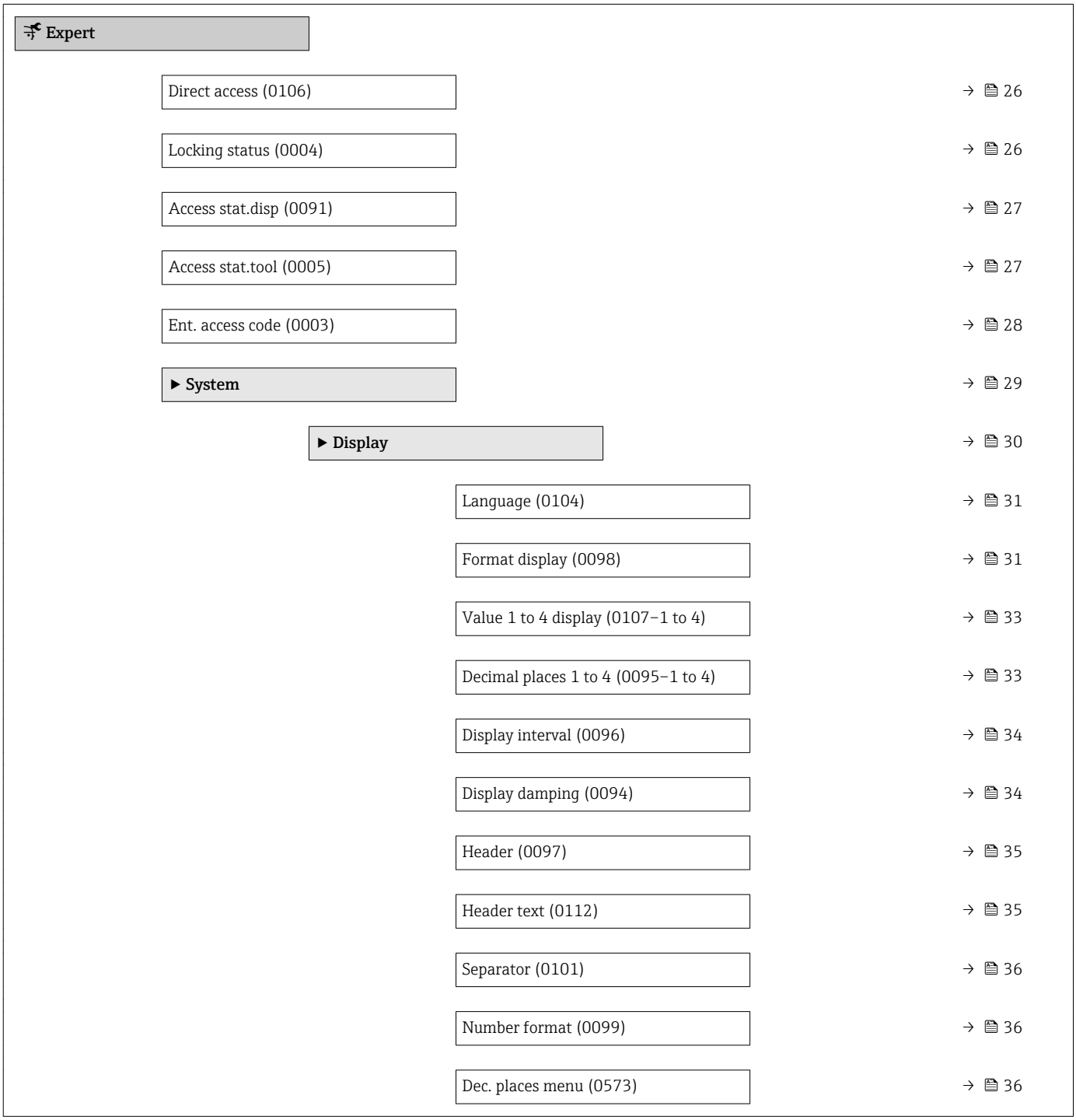
For a given installation, these tracks are in a well-defined relationship to each other. This relationship is recorded during the measuruement such that later on reliable measuring values can be obtained even if the echo is temporarily lost or if the device is temporarily switched off.

For details on the echo tracking refer to: → 136.

3 Overview of the operating menu

- The following table lists all parameters the "Expert" menu may contain. The page number refers to where a description of the parameter can be found.
- Depending on the device version and parametrization some parameters will not be available in a given situation. For details on the conditions refer to the "Prerequisite" category in the description of the respective parameter.
- The representation essentially corresponds to the menu seen when using an operating tool (e.g. FieldCare). On the local display there may be minor differences in the menu structure. Details are mentioned in the description of the respective submenu.

Navigation Expert



- Int. criterion (1184) → 148
- Measur. cap. (1066) → 148
- Build-up ratio (1210) → 148
- Build-up thres. (1211) → 148
- Empty capacitan. (1122) → 149

▶ **Output** → 151

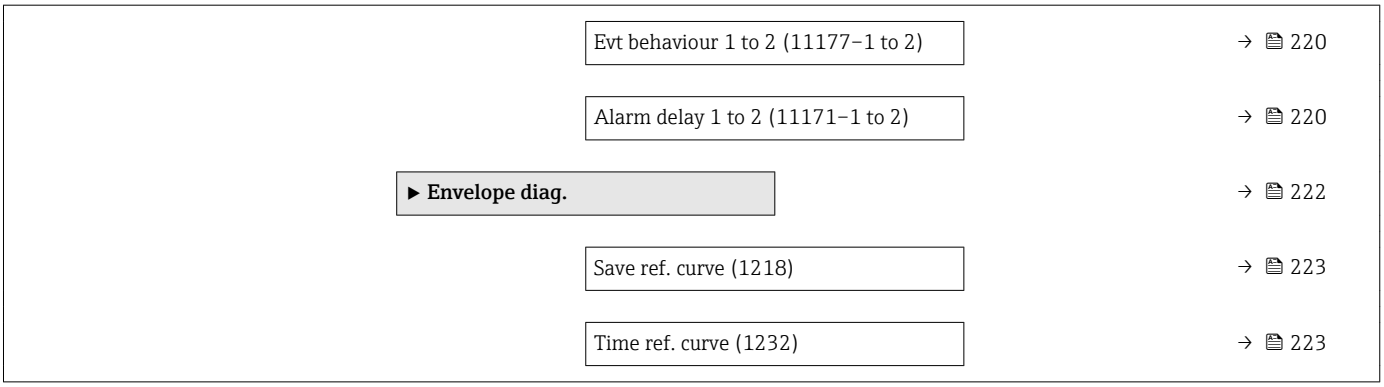
- ▶ **Switch output** → 152
  - Switch out funct (0481) → 153
  - Assign diag. beh (0482) → 153
  - Assign limit (0483) → 154
  - Switch-on value (0466) → 154
  - Switch-off value (0464) → 155
  - Assign status (0485) → 156
  - Switch-on delay (0467) → 156
  - Switch-off delay (0465) → 156
  - Failure mode (0486) → 157
  - Switch status (0461) → 157
  - Invert outp.sig. (0470) → 157

▶ **Communication** → 158

- ▶ **Diag. config.** → 159
- ▶ **Configuration** → 161
  - HART short tag (0220) → 162
  - Device tag (0215) → 162
  - HART address (0219) → 162
  - No. of preambles (0217) → 162

- Logging interval (0856) → 191
- Clear logging (0855) → 191
- ▶ **Min/max val.** → 193
  - Max. level value (2357) → 194
  - Time max. level (2385) → 194
  - Min. level value (2358) → 194
  - Time min. level (2386) → 194
  - Max.drain.speed (2320) → 195
  - Max. fill. speed (2360) → 195
  - Reset min/max (2324) → 195
  - Max.interf.value (2361) → 196
  - Time max. interf (2388) → 196
  - Min.interf.value (2362) → 196
  - Time min. interf (2387) → 196
  - I max. draining (2363) → 197
  - I max.fill speed (2359) → 197
  - Max.electr.temp. (12506) → 197
  - Time max.el.temp (12507) → 197
  - Min.electr.temp. (12508) → 198
  - Time min.el.temp (12509) → 198
  - Res.min/max temp (12510) → 198
- ▶ **Simulation** → 200
  - Assign meas.var. (2328) → 201
  - Value proc. var. (2329) → 201
  - Switch sim. (0462) → 201

- Switch status (0463) → 202
- Sim. alarm (0654) → 202
- ▶ **Device check** → 203
  - Start dev. check (1013) → 204
  - Result dev.check (1014) → 204
  - Last check time (1203) → 204
  - Level signal (1016) → 205
  - Launch signal (1012) → 205
  - Interface signal (1015) → 205
- ▶ **Adv.diagn. 1 to 2** → 213
  - Assign signal 1 to 2 (11179–1 to 2) → 214
  - Link AD 1 to 2 to (11180–1 to 2) → 214
  - Link. logic AD 1 to 2 (11181–1 to 2) → 215
  - Sample time 1 to 2 (11187–1 to 2) → 215
  - Calc. type 1 to 2 (11174–1 to 2) → 215
  - Check mode 1 to 2 (11175–1 to 2) → 216
  - Calc. unit 1 to 2 (11188–1 to 2) → 217
  - Upper limit 1 to 2 (11182–1 to 2) → 218
  - Lower limit 1 to 2 (11184–1 to 2) → 218
  - Hysteresis 1 to 2 (11178–1 to 2) → 219
  - Maximum value 1 to 2 (11183–1 to 2) → 219
  - Minimum value 1 to 2 (11185–1 to 2) → 219
  - Reset min/max 1 to 2 (11186–1 to 2) → 219
  - Stat. AD event 1 to 2 (11176–1 to 2) → 220

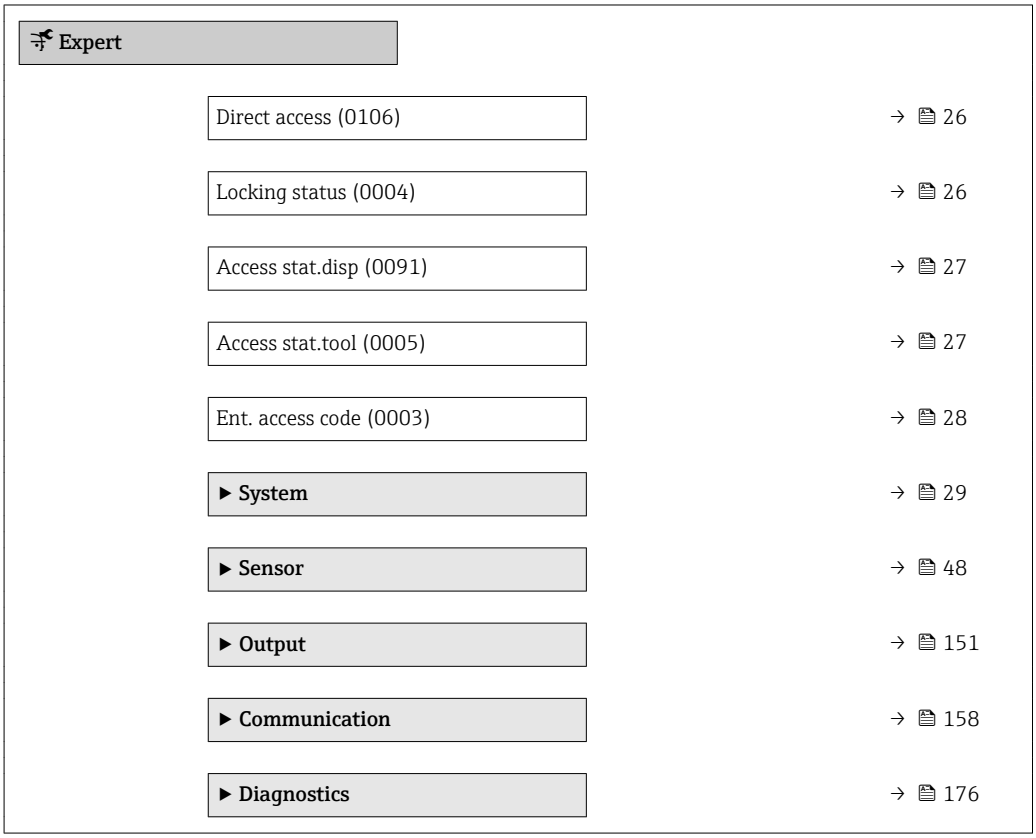

Evt behaviour 1 to 2 (11177–1 to 2)
→ 220
Alarm delay 1 to 2 (11171–1 to 2)
→ 220
▶ Envelope diag.
→ 222
Save ref. curve (1218)
→ 223
Time ref. curve (1232)
→ 223

4 "Expert" menu

Das **Expert** menu enthält alle Parameter des Geräts. Es ist nach den Funktionsblöcken des Geräts aufgebaut.

4.1 Structure of the menu

Navigation Expert



4.2 Description of parameters

Navigation Expert

Direct access

Navigation Expert → Direct access (0106)

Description Enter the access code of a parameter in order to access this parameter directly (i.e. without navigation).

User entry 0 to 65 535

Factory setting 0

Additional information The direct access code consists of a five digit number and an optional channel code, which specifies an input or output channel, e.g. 00353-2
- Leading zeros need not to be entered.
  Example: You may enter "353" instead of "00353"
- If the channel code is not entered, channel 1 is automatically selected.
  Example: By entering "353" you access the following parameter: Curr.output 1 → Current span (0353)
- In order to access a different channel: Enter the direct access code with the channel code.
  Example: By entering "353-2" you access the following parameter: Curr.output 2 → Current span (0353)

In this document, the direct access code is added in brackets after the parameter name in the *Navigation* category.

Locking status

Navigation Expert → Locking status (0004)

Description Indicates the write protection with the highest priority that is currently active.

User interface
- Hardware locked
- SIL locked
- WHG locked
- Temp. locked

Additional information

Meaning and priorities of the types of write protection

- **Hardware locked (priority 1)**
  The DIP switch for hardware locking is activated on the main electronics module. This locks write access to the parameters.
- **SIL locked (priority 2)**
  The SIL mode is activated. Writing access to the relevant parameters is denied.
- **WHG locked (priority 3)**
  The WHG mode is activated. Writing access to the relevant parameters is denied.
- **Temp. locked (priority 4)**
  Write access to the parameters is temporarily locked on account of internal processes in progress in the device (e.g. data upload/download, reset etc.). The parameters can be modified as soon as the processes are complete.

On the display module, the 🔒-symbol appears in front of parameters that cannot be modified since they are write-protected.

Access stat.disp

Navigation Expert → Access stat.disp (0091)

Prerequisite The device has a local display.

Description Indicates access authorization to parameters via local display.

User interface

- Operator
- Maintenance
- Service

Additional information

If a 🔒 symbol appears in front of a parameter, the parameter cannot be changed via the local display with the current access authorization.

The access authorization can be changed via the **Ent. access code** parameter (→ 28).

If additional write protection is active, this restricts the current access authorization even further. The write protection status can be viewed via the **Locking status** parameter (→ 26).

Access stat.tool

Navigation Expert → Access stat.tool (0005)

Description Indicates access authorization to parameters via operating tool (e.g. FieldCare).

User interface

- Operator
- Maintenance
- Service

Additional information

The access authorization can be changed via the **Ent. access code** parameter (→ 28).

If additional write protection is active, this restricts the current access authorization even further. The write protection status can be viewed via the **Locking status** parameter (→ 26).

Ent. access code

Navigation

Expert → Ent. access code (0003)

Description

Enter access code to disable write protec..

User entry

0 to 9 999

Additional information

- For local operation, the customer-specific access code, which has been defined in the **Def. access code** parameter (→ 45), has to be entered.
- If an incorrect access code is entered, the user retains his current access authorization.
- The write protection affects all parameters marked with the -symbol in this document. On the local display, the -symbol in front of a parameter indicates that the parameter is write-protected.
- If no key is pressed for 10 min, or the user switches from the navigation and editing mode back to the measured value display mode, the device automatically locks the write-protected parameters after another 60 s.

Please contact your Endress+Hauser Sales Center if you lose your access code.

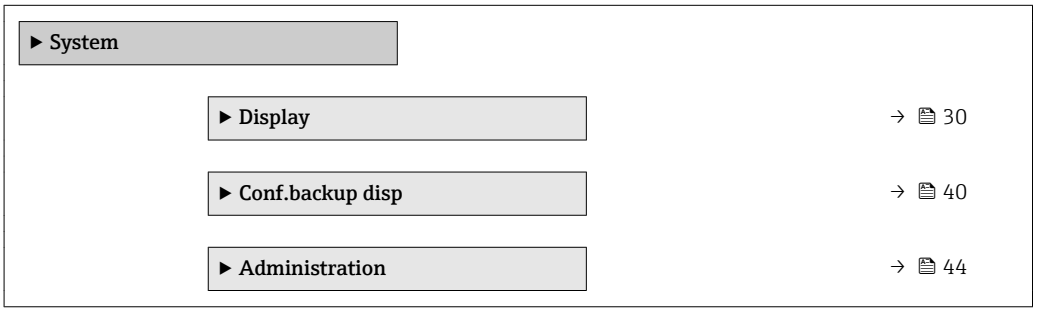
Read access	Operator
Write access	Maintenance

4.3 "System" submenu

The **System** submenu contains all general parameters which affect neither the measurement nor the measured value communication.

4.3.1 Structure of the submenu

Navigation Expert → System



4.3.2 "Display" submenu

The **Display** submenu is used to configure the representation of measured values on the local display module. Up to four measured values can be allocated to the local display module. Additionally, display characteristics such as the format of numbers, the associated texts or the display contrast can be configured.

This submenu is only visible if a display module is connected to the device.

Structure of the submenu

Navigation Expert → System → Display

▶ **Display**	
Language	→ 31
Format display	→ 31
Value 1 to 4 display	→ 33
Decimal places 1 to 4	→ 33
Display interval	→ 34
Display damping	→ 34
Header	→ 35
Header text	→ 35
Separator	→ 36
Number format	→ 36
Dec. places menu	→ 36
Contrast display	→ 37
Backlight	→ 37
Access stat.disp	→ 38

Structure of the submenu

Navigation Expert → System → Display

Language

Navigation
Expert → System → Display → Language (0104)
Expert → System → Display → Language (0104)

Description
Set display language.

Selection
- English
- Deutsch
- Français
- Español
- Italiano
- Nederlands
- Portuguesa
- Polski
- русский язык(Ru)
- Svenska
- Türkçe
- 中文 (Chinese)
- 日本語 (Japanese)
- 한국어 (Korean)
- Bahasa Indonesia
- tiếng Việt (Vit)
- čeština (Czech)

Factory setting
The language selected in feature 500 of the product structure.
If no language has been selected: **English**

Additional information

Read access	Operator
Write access	Operator

Format display

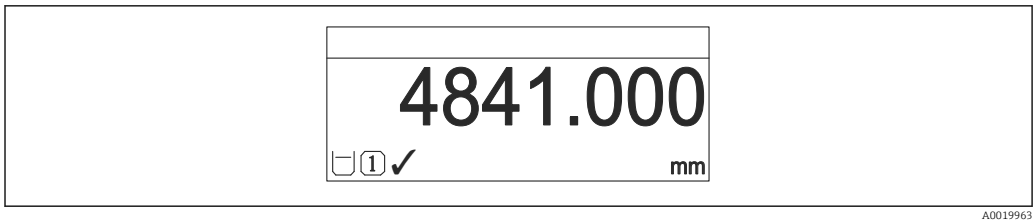
Navigation
Expert → System → Display → Format display (0098)
Expert → System → Display → Format display (0098)

Description
Select how measured val. are shown on the display.

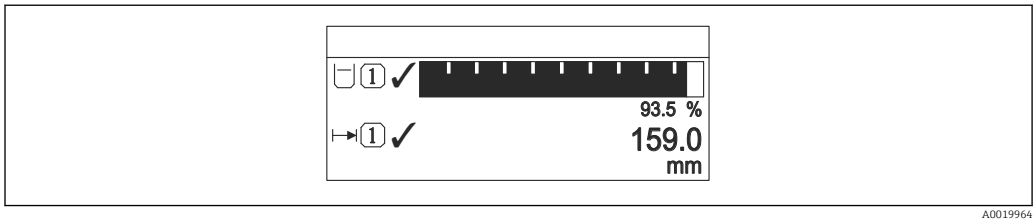
Selection
- 1 value, max.
- Bargr. + 1 value
- 2 values
- Val. large+2val.
- 4 values

Factory setting
1 value, max.

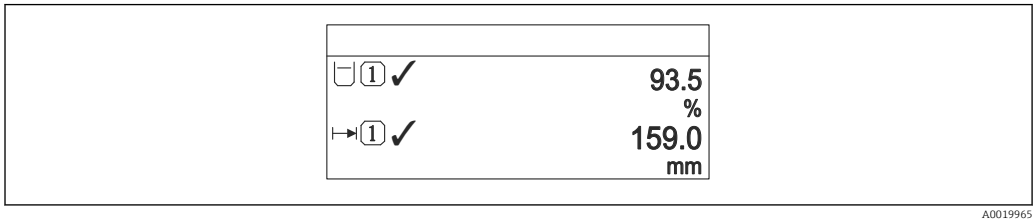
Additional information



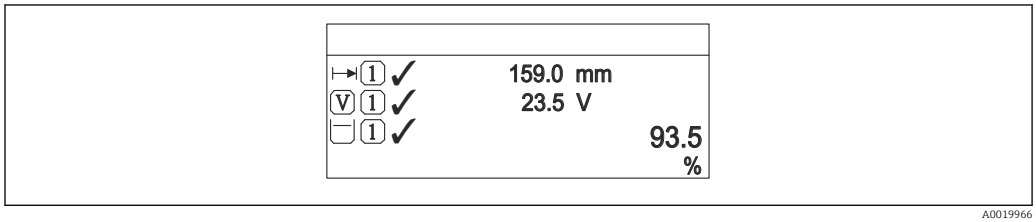
5 *"Format display" = "1 value, max."*



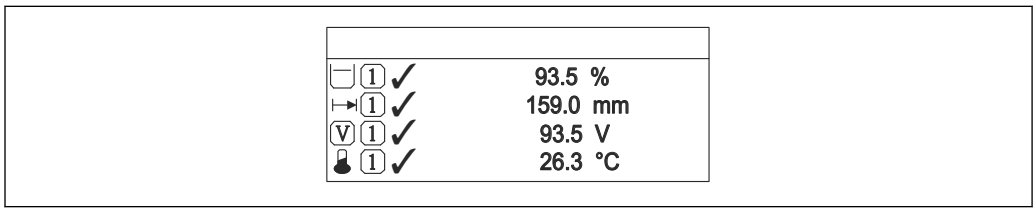
6 *"Format display" = "Bargr. + 1 value"*



7 *"Format display" = "2 values"*



8 *"Format display" = "Val. large+2val."*



9 *"Format display" = "4 values"*

- The **Value 1 to 4 display** → 33 parameters specify which measured values are shown on the display and in which order.
- If more measured values are specified than the current display mode permits, the values alternate on the device display. The display time until the next change is configured in the **Display interval** parameter (→ 34).

Read access	Operator
Write access	Operator

Value 1 to 4 display

Navigation

Expert → System → Display → Value 1 display (0107)

Expert → System → Display → Value 1 display (0107)

Description

Select measured value that is shown on the display.

Selection

- Level linearized
- Distance
- Interf. lineariz
- Interface dist.
- Thickn.upp.layer
- Curr.output 1
- Measur. curr.
- Curr.output 2
- Terminal volt.
- Electronic temp.
- Measur. cap.
- Analog out. AD 1
- Analog out. AD 2

Factory setting

For level measurements
- Value 1 display: Level linearized
- Value 2 display: Distance
- Value 3 display: Current output 1
- Value 4 display: None

For interface measurements and one current output
- Value 1 display: Interface linearized
- Value 2 display: Level linearized
- Value 3 display: Thickness upper layer
- Value 4 display: Current output 1

For interface measurements and two current outputs
- Value 1 display: Interface linearized
- Value 2 display: Level linearized
- Value 3 display: Current output 1
- Value 4 display: Current output 2

Additional information

Read access	Operator
Write access	Maintenance

Decimal places 1 to 4

Navigation

Expert → System → Display → Decimal places 1 (0095)

Expert → System → Display → Decimal places 1 (0095)

Description

Select number of decimal places for display value.

Selection
- x
- x.x
- x.xx
- x.xxx
- x.xxxx

Factory setting x.xx

Additional information The setting does not affect the measuring or computational accuracy of the device.

Read access	Operator
Write access	Maintenance

Display interval

Navigation
Expert → System → Display → Display interval (0096)
Expert → System → Display → Display interval (0096)

Description Time meas. val. are shown if displ. alternates.

User entry 1 to 10 s

Factory setting 5 s

Additional information This parameter is only relevant if the number of selected measuring values exceeds the number of values the selected display format can display simultaneously.

Read access	Operator
Write access	Operator

Display damping

Navigation
Expert → System → Display → Display damping (0094)
Expert → System → Display → Display damping (0094)

Description Display reaction time to fluctuations of meas.val..

User entry 0.0 to 999.9 s

Factory setting 0.0 s

Additional information

Read access	Operator
Write access	Maintenance

Header

Navigation

Expert → System → Display → Header (0097)

Expert → System → Display → Header (0097)

Description

Select display header contents.

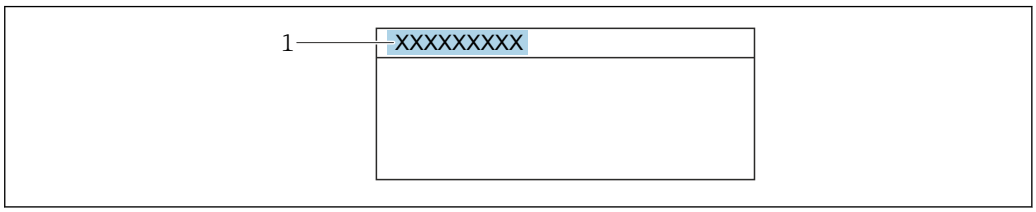
Selection

- Device tag
- Free text

Factory setting

Device tag

Additional information



1 Position of the header text on the display

Meaning of the options

- **Device tag**
  Is defined in the **Device tag** parameter (→ 162)
- **Free text**
  Is defined in the **Header text** parameter (→ 35)

Read access	Operator
Write access	Maintenance

Header text

Navigation

Expert → System → Display → Header text (0112)

Expert → System → Display → Header text (0112)

Prerequisite

Header (→ 35) = **Free text**

Description

Enter display header text.

Factory setting

Additional information

The number of characters which can be displayed depends on the characters used.

Read access	Operator
Write access	Maintenance

Separator

Navigation
Expert → System → Display → Separator (0101)
Expert → System → Display → Separator (0101)

Description
Select separator for displaying numerical values.

Selection
- .
- ,

Factory setting
.

Additional information

Read access	Operator
Write access	Maintenance

Number format

Navigation
Expert → System → Display → Number format (0099)
Expert → System → Display → Number format (0099)

Description
Choose number format for the display.

Selection
- Decimal
- ft-in-1/16"

Factory setting
Decimal

Additional information
The **ft-in-1/16"** option is only valid for distance units.

Read access	Operator
Write access	Maintenance

Dec. places menu

Navigation
Expert → System → Display → Dec. places menu (0573)
Expert → System → Display → Dec. places menu (0573)

Description
Select number of decimal places for the representation of numbers within the operating menu.

Selection
- x
- x.x
- x.xx
- x.xxx
- x.xxxx

Factory setting x.xxxx

Additional information
- Is only valid for numbers in the operating menu (e.g. **Empty calibr.**, **Full calibr.**), but not for the measured value display. The number of decimal places for the measured value display is defined in the **Decimal places 1 to 4** → 33 parameters.
- The setting does not affect the accuracy of the measurement or the calculations.

Read access	Operator
Write access	Maintenance

Contrast display

Navigation
Expert → System → Display → Contrast display (0105)
Expert → System → Display → Contrast display (0105)

Description Adjust display contrast setting to ambient cond..

User entry 20 to 80 %

Factory setting Dependent on the display.

Additional information
Setting the contrast via push-buttons:
- Darker: press the ⊖ E buttons simultaneously.
- Brighter: press the ⊕ E buttons simultaneously.

Read access	Operator
Write access	Operator

Backlight

Navigation
Expert → System → Display → Backlight (0111)
Expert → System → Display → Backlight (0111)

Prerequisite The device has the SD03 local display (with optical keys).

Description Switch the local display backlight on and off.

Selection
- Disable
- Enable

Factory setting Disable

Additional information

Meaning of the options
- **Disable**
  Switches the backlight off.
- **Enable**
  Switches the backlight on.

Regardless of the setting in this parameter the backlight may be automatically switched off by the device if the supply voltage is too low.

Read access	Operator
Write access	Operator

Access stat.disp

Navigation

Expert → System → Display → Access stat.disp (0091)

Expert → System → Display → Access stat.disp (0091)

Prerequisite

The device has a local display.

Description

Indicates access authorization to parameter.

Additional information

The access authorization can be changed via the **Ent. access code** parameter (→ 28).

If additional write protection is active, this restricts the current access authorization even further. The write protection status can be viewed via the **Locking status** parameter (→ 26).

Read access	Operator
Write access	-

4.3.3 "Conf.backup disp" submenu

This submenu is only visible if a display module is connected to the device.

All software configurations are initially stored in a memory module (HistoROM) in the housing and are thus permanently connected with the device. As an additional option, the display module contains a backup memory for the device configuration. The transmission of configuration data between these two memory modules is controlled by the **Config. managem.** parameter (→ 41). It provides the following options:

- **Execute backup**
  Saves the current device configuration in the display module.
- **Restore**
  This option can be used to restore a configuration back into the device which has previously been saved in the display module.
- **Duplicate**
  If the configuration has been saved into the display module, the module can be connected to a different device and the configuration can be duplicated to this device. This allows to efficiently configure a number of devices in the same way.
- **Compare**
  The comparison result indicates whether the device configuration has been changed since the last backup.

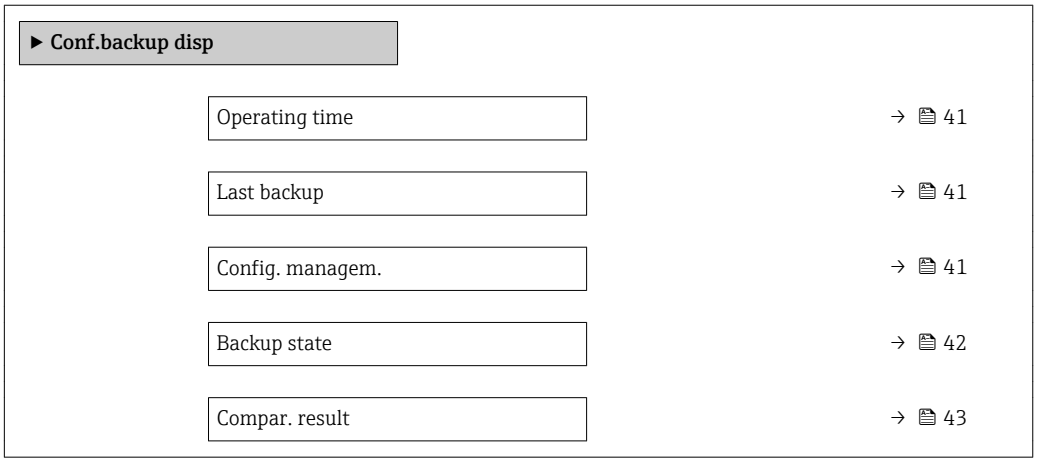
For FMP51, FMP52, FMP54, FMP55: Configurations can only be exchanged between devices which are in the same operating mode (see the **Operating mode** parameter (→ 50)).

If an existing backup is restored to a different device using the **Restore** option, it may occur that some device functionalities are no longer available. Even a reset to the delivery state won't restore the original state in some cases.

In order to transfer the configuration to a different device only the **Duplicate** option should be used.

Structure of the submenu

Navigation Expert → System → Conf.backup disp



Description of parameters

Navigation Expert → System → Conf.backup disp

Operating time

Navigation
Expert → System → Conf.backup disp → Operating time (0652)
Expert → System → Conf.backup disp → Operating time (0652)

Description
Indicates how long device has been in operation.

Additional information
Maximum time
9 999 d (≈ 27 years)

Read access	Operator
Write access	-

Last backup

Navigation
Expert → System → Conf.backup disp → Last backup (0102)
Expert → System → Conf.backup disp → Last backup (0102)

Description
Indicates when last backup was saved to display.

Additional information

Read access	Operator
Write access	-

Config. managem.

Navigation
Expert → System → Conf.backup disp → Config. managem. (0100)
Expert → System → Conf.backup disp → Config. managem. (0100)

Description
Select action for managing the device data.

Selection
- Cancel
- Execute backup
- Restore
- Duplicate
- Compare
- Clear backup

Factory setting
Cancel

Additional information

Meaning of the options

- **Cancel**
  No action is executed and the user exits the parameter.
- **Execute backup**
  A backup copy of the current device configuration in the HistoROM (built-in in the device) is saved to the display module of the device.
- **Restore**
  The last backup copy of the device configuration is copied from the display module to the HistoROM of the device.
- **Duplicate**
  The transmitter configuration is duplicated to another device using the transmitter display module. The following parameters, which characterize the individual measuring point are **not** included in the transmitted configuration:
  – HART date code
  – HART short tag
  – HART message
  – HART descriptor
  – HART address
  – Device tag
  – Medium type
- **Compare**
  The device configuration saved in the display module is compared to the current device configuration of the HistoROM. The result of this comparison is displayed in the **Compar. result** parameter (→ 43).
- **Clear backup**
  The backup copy of the device configuration is deleted from the display module of the device.

While this action is in progress, the configuration cannot be edited via the local display and a message on the processing status appears on the display.

If an existing backup is restored to a different device using the **Restore** option, it may occur that some device functionalities are no longer available. In some cases even a device reset will not restore the original status.

In order to transmit a configuration to a different device, the **Duplicate** option should always be used.

Read access	Operator
Write access	Maintenance

Backup state

Navigation Expert → System → Conf.backup disp → Backup state (0121)

Description Displays which backup action is currently in progress.

Additional information

Read access	Operator
Write access	-

Compar. result

Navigation

Expert → System → Conf.backup disp → Compar. result (0103)

Expert → System → Conf.backup disp → Compar. result (0103)

Description

Comp. between present device data and disp. backup.

Additional information

Meaning of the display options

- **Set. identical**
  The current device configuration of the HistoROM is identical to the backup copy in the display module.
- **Set. not ident.**
  The current device configuration of the HistoROM is not identical to the backup copy in the display module.
- **No backup**
  There is no backup copy of the device configuration of the HistoROM in the display module.
- **Backup corrupt**
  The current device configuration of the HistoROM is corrupt or not compatible with the backup copy in the display module.
- **Check not done**
  The device configuration of the HistoROM has not yet been compared to the backup copy in the display module.
- **Dataset incomp.**
  The data sets are incompatible and can not be compared.

To start the comparison, set **Config. managem. (→ 41)** = **Compare**.

If the transmitter configuration has been duplicated from a different device by **Config. managem. (→ 41)** = **Duplicate**, the new device configuration in the HistoROM is only partially identical to the configuration stored in the display module: Sensor specific properties (e.g. the mapping curve) are not duplicated. Thus, the result of the comparison will be **Set. not ident.**.

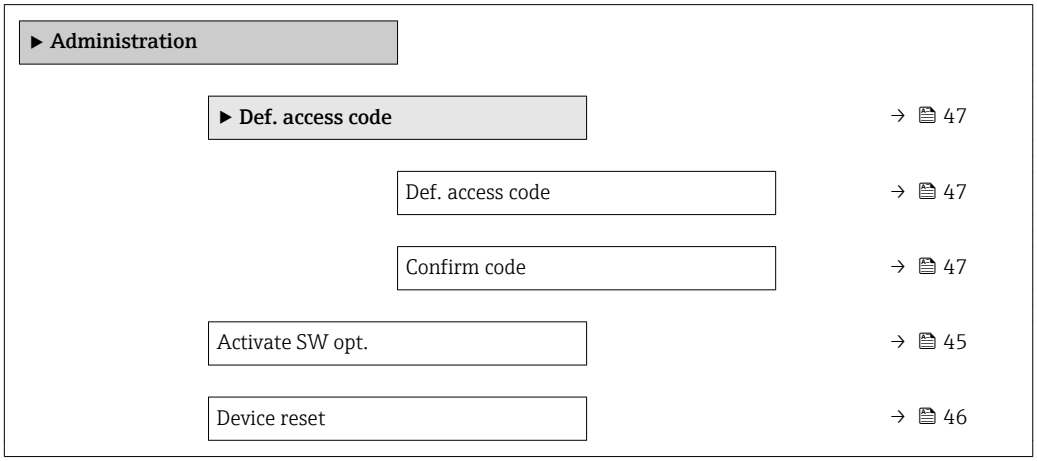
Read access	Operator
Write access	-

4.3.4 "Administration" submenu

The **Administration** submenu contains all parameters for the management of the device. Its structure depends on the user interface:

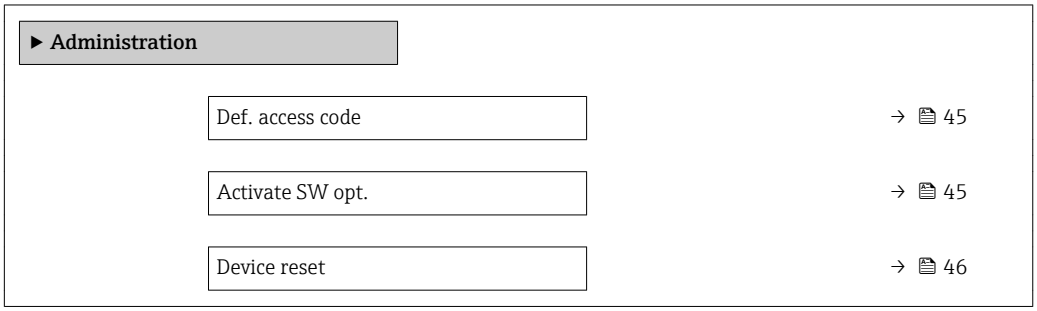
Structure of the submenu on the local display

Navigation Expert → System → Administration



Structure of the submenu in an operating tool

Navigation Expert → System → Administration



Description of parameters

Navigation Expert → System → Administration

Def. access code

Navigation Expert → System → Administration → Def. access code (0093)

Description Define release code for write access to parameters.

User entry 0 to 9 999

Factory setting 0

Additional information

If the factory setting is not changed or 0 is defined as the access code, the parameters are not write-protected and the configuration data of the device can then always be modified. The user is logged on in the *Maintenance* role.

The write protection affects all parameters marked with the symbol in this document. On the local display, the symbol in front of a parameter indicates that the parameter is write-protected.

Once the access code has been defined, write-protected parameters can only be modified if the access code is entered in the **Ent. access code** parameter (→ 28).

Please contact your Endress+Hauser Sales Center if you lose your access code.

For display operation: The new access code is only valid after it has been confirmed in the **Confirm code** parameter (→ 47).

Read access	Operator
Write access	Maintenance

Activate SW opt.

Navigation Expert → System → Administration → Activate SW opt. (0029)

Expert → System → Administration → Activate SW opt. (0029)

Description Enter code to unlock specific software options.

User entry Positive integer

Factory setting 0

Additional information

Read access	Operator
Write access	Maintenance

Device reset

Navigation

Expert → System → Administration → Device reset (0000)

Expert → System → Administration → Device reset (0000)

Selection

- Cancel
- To bus defaults
- To fact.defaults
- To delivery set.
- Of customer set.
- To transd.def.
- Restart device

Factory setting

Cancel

Additional information

Meaning of the options

- **Cancel**
  No action
- **To fact.defaults**
  All parameters are reset to the order-code specific factory setting.
- **To delivery set.**
  All parameters are reset to the delivery setting. The delivery setting may differ from the factory default if customer specific settings have been ordered.
  This option is only visible if customer specific settings have been ordered.
- **Of customer set.**
  All customer parameters are reset to their factory setting. Service parameters, however, remain unchanged.
- **To transd.def.**
  Every measurment-related parameter is reset to its factory setting. Service parameters and communication-related parameters, however, remain unchanged.
- **Restart device**
  The restart resets every parameter which is stored in the volatile memory (RAM) to the factory setting (e.g. measured value data). The device configuration remains unchanged.

Read access	Operator
Write access	Maintenance

"Def. access code" wizard

Navigation Expert → System → Administration → Def. access code

Def. access code

Navigation Expert → System → Administration → Def. access code → Def. access code

Description → 45

Confirm code

Navigation Expert → System → Administration → Def. access code → Confirm code

Description Confirm the entered access code.

User entry 0 to 9 999

Factory setting 0

Additional information

Read access	Operator
Write access	Maintenance

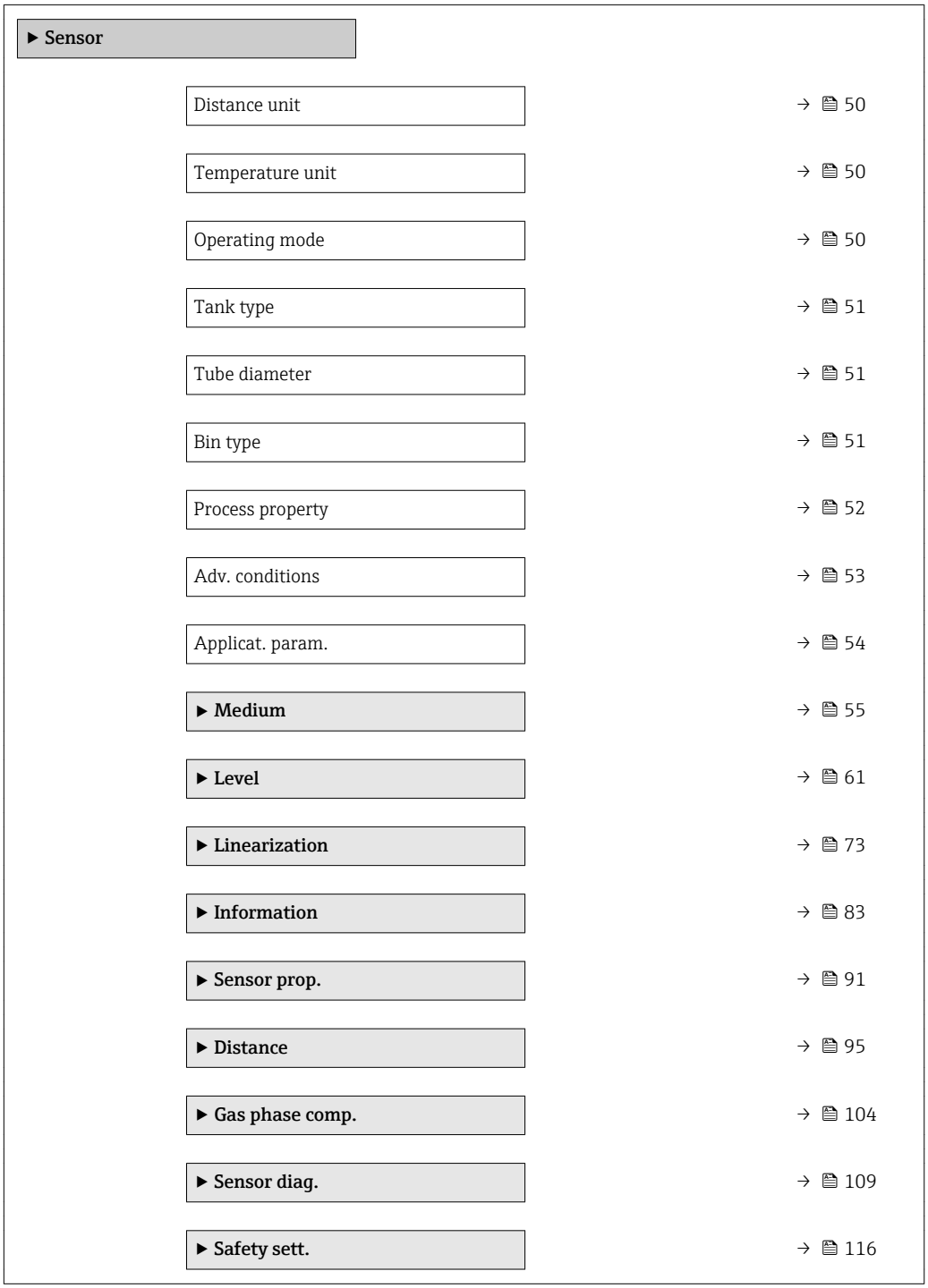
4.4 "Sensor" submenu

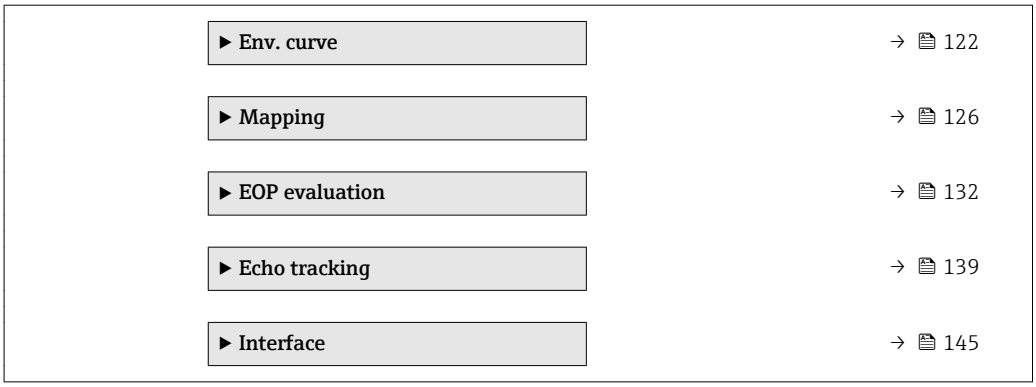
The **Sensor** submenu contains all parameters related to the measurement and the sensor settings.

Navigation Expert → Sensor

4.4.1 Structure of the submenu

Navigation Expert → Sensor




▶ Env. curve
→ 122
▶ Mapping
→ 126
▶ EOP evaluation
→ 132
▶ Echo tracking
→ 139
▶ Interface
→ 145

4.4.2 Description of parameters

Navigation Expert → Sensor

Distance unit

Navigation Expert → Sensor → Distance unit (0551)

Description Select distance unit.

Selection

SI units	*US units*
▪ mm	▪ ft
▪ m	▪ in

Factory setting m

Temperature unit

Navigation Expert → Sensor → Temperature unit (0557)

Description Select temperature unit.

Selection

SI units	*US units*
▪ °C	▪ °F
▪ K	▪ °R

Factory setting °C

Operating mode

Navigation Expert → Sensor → Operating mode (1046)

Prerequisite The device has the "interface measurement" application package (available for FMP51, FMP52, FMP54) [1].

Description Select operating mode.

Selection
- Level
- Interf.+capacit.
- Interface

Factory setting FMP51/FMP52/FMP54: **Level**

1) Product structure: Feature 540 "Application Package", Option EB "Interface measurement"

Tank type

Navigation Expert → Sensor → Tank type (1175)

Prerequisite **Medium type (→ 56)** = **Liquid**

Description Select tank type.

Selection
- Metallic
- Bypass / pipe
- Non metallic
- Mounted outside
- Coaxial

Factory setting Depending on the probe

Additional information
- Depending on the probe some of the options mentioned above may not be available or there may be additional options.
- For coax probes and probes with metallic center washer **Tank type** parameter corresponds to the type of probe and cannot be changed.

Tube diameter

Navigation Expert → Sensor → Tube diameter (1117)

Prerequisite **Tank type (→ 51)** = **Bypass / pipe**

Description Specify diameter of bypass or stilling well.

User entry 0 to 9.999 m

Factory setting 0.0384 m

Bin type

Navigation Expert → Sensor → Bin type (1176)

Prerequisite **Medium type (→ 56)** = **Solid**

Description Specify bin type.

Selection
- Concrete
- Plastic wood
- Metallic
- Aluminium
- Buffer silo fast
- Bin/ Pile

- Crusher / belt
- Silo
- Workbench test

Factory setting Metallic

Process property

Navigation Expert → Sensor → Process property (1081)

Description Specify typical rate of level change.

Selection

For "Medium type" = "Liquid"
- Very fast > 10 m (400 in)/min
- Fast > 1 m (40 in)/min
- Standard < 1 m (40in) /min
- Medium < 10 cm (4in) /min
- Slow < 1 cm (0.4in) /min
- No filter / test

For "Medium type" = "Solid"
- Very fast > 100 m (333 ft) /h
- Fast > 10 m (33 ft) /h
- Standard < 10 m (33 ft) /h
- Medium < 1 m (3ft) /h
- Slow < 0.1 m (0.3ft) /h
- No filter / test

Factory setting Std.<1m 40"/min

Additional information The device adjusts the signal evaluation filters and the damping of the output signal to the typical rate of level change defined in this parameter:

For "Operating mode" = "Level" and "Medium type" = "Liquid"

Process property	Step response time / s
Fst>10m400"/min	5
Fast>1m 40"/min	5
Std.<1m 40"/min	14
Med<10cm 4"/min	39
Sl.<1cm .4"/min	76
No filter / test	< 1

For "Operating mode" = "Level" and "Medium type" = "Solid"

Process property	Step response time / s
Fast>100m333'/h	37
Fast>10m(33ft)/h	37
Std.<10m(33ft)/h	74
Med <1m (3ft) /h	146

Process property	Step response time / s
Slow<.1m(.3ft)/h	290
No filter / test	< 1

For "Operating mode" = "Interface" or "Interf.+capacit."

Process property	Step response time / s
Fst>10m400"/min	5
Fast>1m 40"/min	5
Std.<1m 40"/min	23
Med<10cm 4"/min	47
Sl.<1cm .4"/min	81
No filter / test	2.2

Other values of the step-response time (e.g. intermediate values) can be defined by the following parameters:
- **Dead time (→ 97)**
- **Integration time (→ 98)**

Adv. conditions

Navigation Expert → Sensor → Adv. conditions (1177)

Prerequisite **Operating mode (→ 50)** = **Level**

Description Specify additional process conditions (if required).

Selection
- None
- Oil/Watercondens
- Probe near bott.
- Build up
- Foam >5cm/0,16ft

Factory setting None

Additional information

Meaning of the options
- **Oil/Watercondens** (only **Medium type** = **Liquid**)
  Makes sure that in the case of two-phase media only the total level is detected (example: oil/condensate application).
- **Probe near bott.** (only for **Medium type** = **Liquid**)
  Improves the empty detection, especially if the probe is mounted close to the tank bottom.
- **Build up**
  Enables a safe empty-detection even if the end-of-probe signal has shifted due to build-up.
- **Foam >5cm/0,16ft** (only for **Medium type** = **Liquid**)
  Optimizes the signal evaluation in applications with foam formation.

Applicat. param.

Navigation

Expert → Sensor → Applicat. param. (1126)

Expert → Sensor → Applicat. param. (1126)

Description

Indicates whether settings depending on the application parameters (e.g. **Adv. conditions (→ 53)**, **Tank type (→ 51)** and **Tube diameter (→ 51)**) have been changed after the basic setup.

User interface

- Changed
- Not changed

Additional information

Meaning of the options

- **Changed**
  Parameters have been changed. The device is no longer in the state defined by the application parameters.
- **Not changed**
  There have been no changes. The device is still in the state defined by the application parameters.

4.4.3 "Medium" submenu

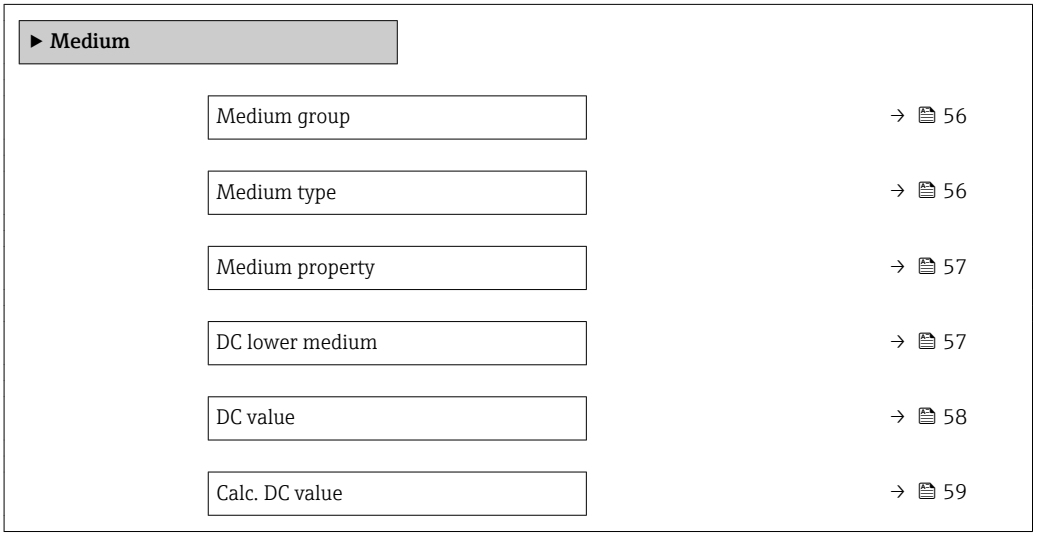
The **Medium** submenu is used to specify the relevant properties of the measured medium, especially the dielectric constant (DC).

The dielectric constant is used to calculate the threshold for the level echo and (if applicable) the interface echo.

For FMP51/FMP52/FMP54/FMP55: The **Operating mode** parameter (→ 50) determines which parameters this submenu contains.

Structure of the submenu

Navigation Expert → Sensor → Medium



Description of parameters

Navigation Expert → Sensor → Medium

Medium group

Navigation Expert → Sensor → Medium → Medium group (1208)

Prerequisite
- For FMP51/FMP52/FMP54/FMP55: **Operating mode (→ 50)** = **Level**
- **Medium type (→ 56)** = **Liquid**

Description Select medium group.

Selection
- Others
- Water based DC>4

Factory setting Others

Additional information This parameter roughly specifies the dielectric constant (DC) of the medium. For a more detailed definition of the DC use the **Medium property** parameter (→ 57).

The **Medium group** parameter presets the **Medium property** parameter (→ 57) as follows:

Medium group	Medium property (→ 57)
Others	Unknown
Water based DC>4	DC 4 … 7

The **Medium property** parameter can be changed at a later point of time. However, when doing so, the **Medium group** parameter retains its value. Only the **Medium property** parameter is relevant for the signal evaluation.

The measuring range may be reduced for small dielectric constants. For details refer to the Technical Information (TI) of the respective device.

Medium type

Navigation Expert → Sensor → Medium → Medium type (1049)

Description Specify type of medium.

User interface
- Liquid
- Solid

Factory setting FMP50, FMP51, FMP52, FMP53, FMP54, FMP55: **Liquid**

Additional information The **Solid** option is only available for **Operating mode (→ 50)** = **Level**

This parameter determines the value of several other parameters and strongly influences the complete signal evaluation. Therefore, it is strongly recommended **not to change** the factory setting.

Medium property

Navigation Expert → Sensor → Medium → Medium property (1165)

Prerequisite
- **Operating mode (→ 50)** = **Level**
- **EOP level eval.** ≠ **Fix DC**

Description Specify relative dielectric constant ε_r of the medium.

Selection
- Unknown
- DC 1.4 … 1.6
- DC 1.6 … 1.9
- DC 1.9 … 2.5
- DC 2.5 … 4
- DC 4 … 7
- DC 7 … 15
- DC > 15

Factory setting Dependent on **Medium type (→ 56)** and **Medium group (→ 56)**.

Additional information *Dependency on "Medium type" and "Medium group"*

Medium type (→ 56)	Medium group (→ 56)	Medium property
Solid		Unknown
Liquid	Water based DC>4	DC 4 … 7
	Others	Unknown

For dielectric constants (DC values) of many media commonly used in various industries refer to:
- the Endress+Hauser DC manual (CP01076F)
- the Endress+Hauser "DC Values App" (available for Android and iOS)

For **EOP level eval.** = **Fix DC**, the exact dielectric constant has to be entered into the **DC value** parameter. Therefore, the **Medium property** parameter is not available in this case.

DC lower medium

Navigation Expert → Sensor → Medium → DC lower medium (1154)

Prerequisite **Operating mode (→ 50)** = **Interface** or **Interf.+capacit.**

Description Specify the relative dielectric ocnstant ε_r of the lower medium.

User entry 1 to 100

Factory setting 80.0

Additional information

For dielectric constants (DC values) of many media commonly used in various industries refer to:
- the Endress+Hauser DC manual (CP01076F)
- the Endress+Hauser "DC Values App" (available for Android and iOS)

The factory setting, $\varepsilon_r = 80$, is valid for water at 20 °C (68 °F).

DC value

Navigation

Expert → Sensor → Medium → DC value (1201)

Description

- For level measurements:
  Specify dielectric constant ε_r.
- For interface measurements:
  Specify dielectric constant ε_r of the upper medium.

User entry

Signed floating-point number

Factory setting

Dependent on the following parameters:
- Operating mode (→ 50)
- Medium property (→ 57)
- Medium type (→ 56)
- Bin type (→ 51)or Tank type (→ 51)

Additional information

Dependence of the factory settings on other parameters

For "Operating mode" = "Level"

Medium property (→ 57)	Medium type (→ 56)	Bin type (→ 51) or Tank type (→ 51)	DC value
Unknown	Solid	Bin type (→ 51) ▪ Aluminium ▪ Plastic wood	1.9
		Bin type (→ 51) ▪ Concrete ▪ Metallic	1.6
	Liquid	Tank type (→ 51) Coaxial	1.4
		Any other tank type	1.9
DC 1.4 … 1.6	Solid	Bin type (→ 51) ▪ Concrete ▪ Aluminium ▪ Plastic wood	1.6
		Bin type (→ 51) Metallic	1.4
	Liquid	Tank type (→ 51) ▪ Non metallic ▪ Mounted outside	1.6
		Any other tank type	1.4
DC 1.6 … 1.9			1.6
DC 1.9 … 2.5			1.9
DC 2.5 … 4			2.5

Medium property (→ 57)	Medium type (→ 56)	Bin type (→ 51) or Tank type (→ 51)	DC value
DC 4 ... 7			4
DC 7 ... 15			7
DC > 15			15

For "Operating mode" = "Interf.+capacit." or "Interface":
DC value = 1.9

As the value defines the echo threshold, it may not exceed the actual DC of the medium. Dielectric constants above DC = 15 have only a very limited influence on the echo threshold.

Calc. DC value

Navigation Expert → Sensor → Medium → Calc. DC value (1118)

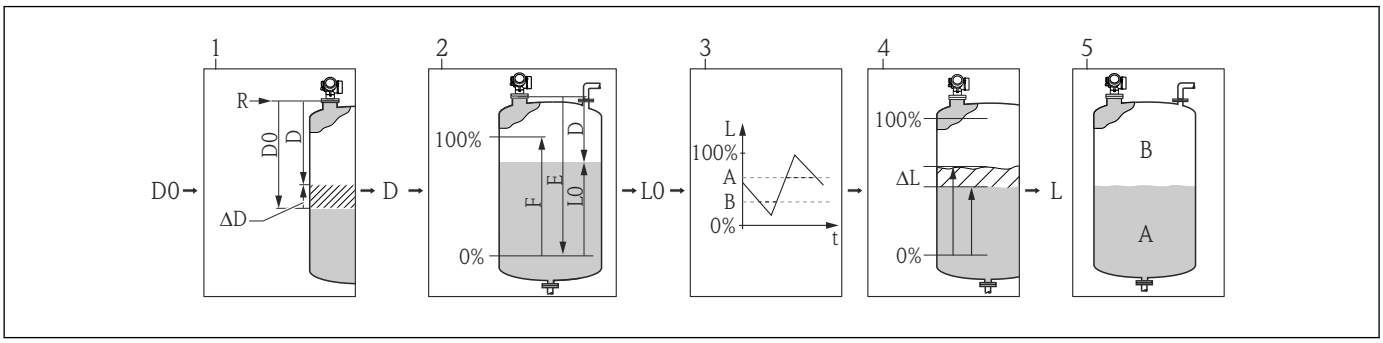
Prerequisite **EOP level eval.** = **Automatic DC**

Description
- For **Operating mode (→ 50)** = **Level:**
  Displays the dielectric constant calculated from the level and end-of-probe signals.
- For **Operating mode (→ 50)** = **Interface** or **Interf.+capacit.**:
  - For **Interface prop. (→ 146)** = **Special: auto DC**:
    Displays the dielectric constant of the upper medium which has been calculated from the level and interface signal.
  - Else:
    Identical to **DC value (→ 58)**.

User interface 1.0 to 100.0

4.4.4 "Level" submenu

The **Level** submenu (→ 61) is used to configure the calculation of the level from the measured distance.



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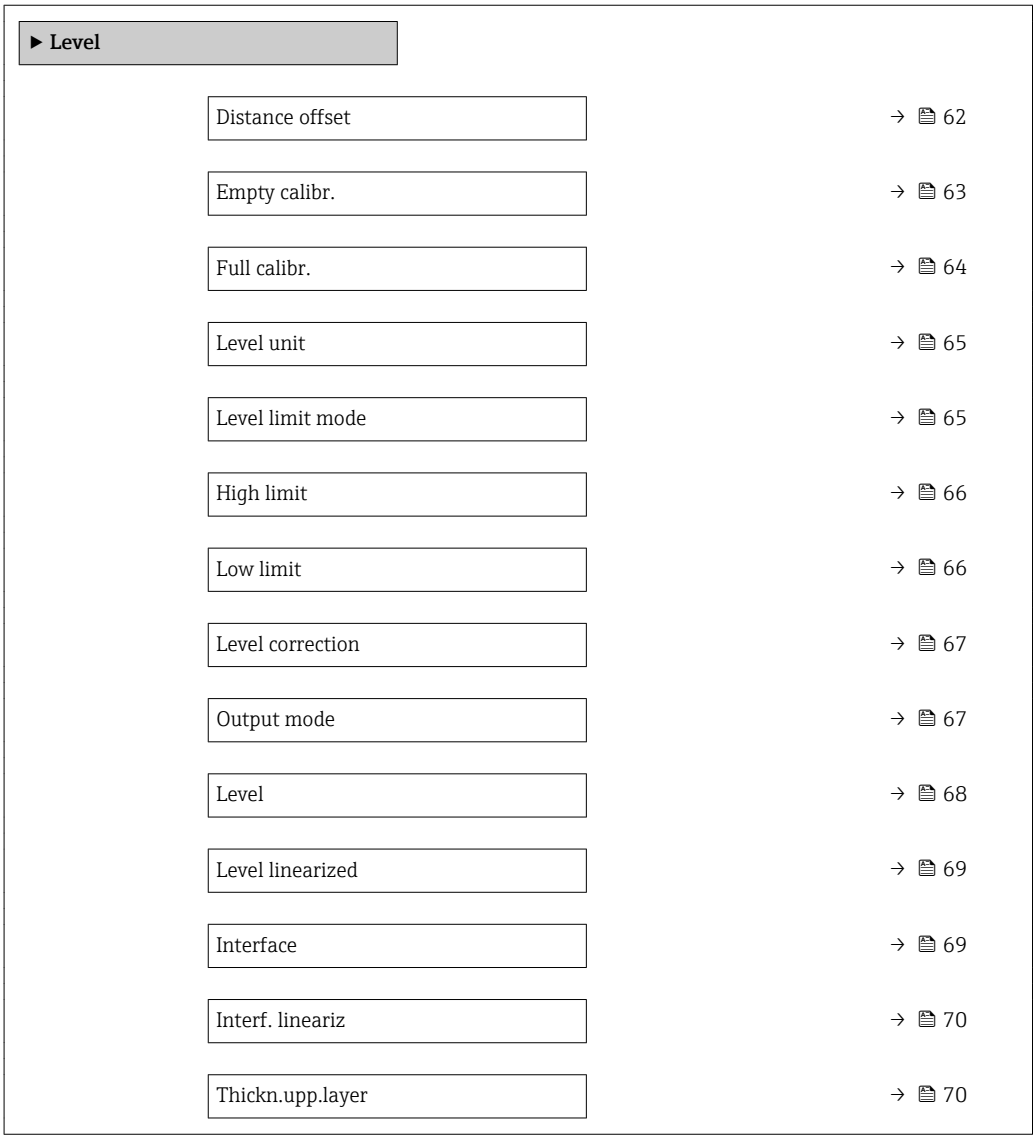
10 Calculation of the level from the measured distance

1 Correction of the measured distance
2 Level calculation
3 Level limitation
4 Correction of the level
5 Definition of the output value: Level (A) or Ullage (B)

Structure of the submenu

Navigation Expert → Sensor → Level



Description of parameters

Navigation Expert → Sensor → Level

Distance offset

Navigation
Expert → Sensor → Level → Distance offset (2309)
Expert → Sensor → Level → Distance offset (2309)

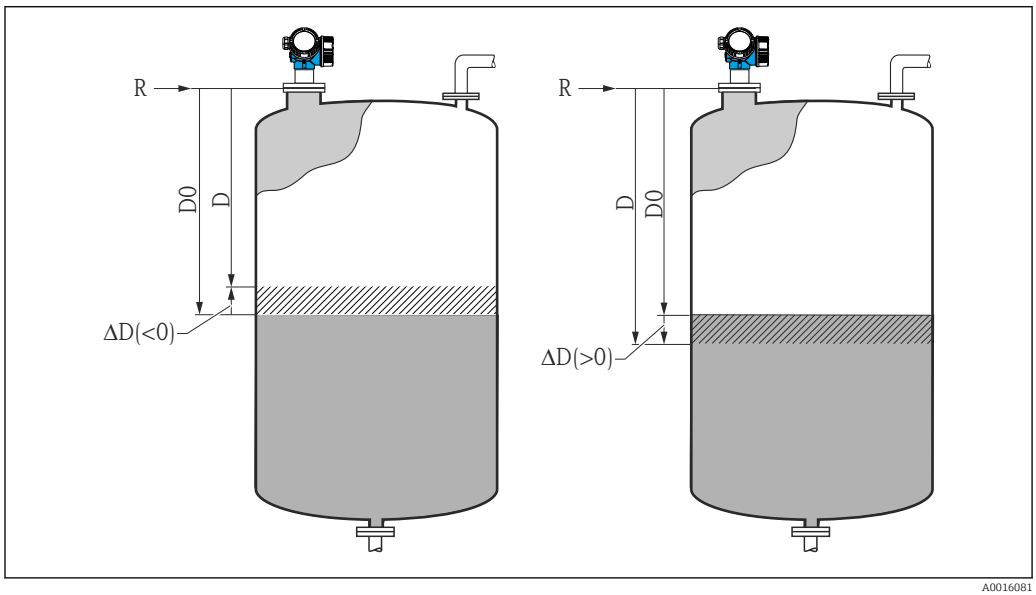
Description
Specify distance offset.

User entry
−200 to 200 m

Factory setting
0 m

Additional information
The value specified in this parameter is added to the measured distance between the reference point of the measurement and the level echo.

- Positive values increase the distance and thus decrease the level.
- Negative values decrease the distance and thus increase the level.



11 Effect of "Distance offset (→ 62)"

ΔD Distance offset
D0 Measured distance
D Corrected distance (is used to calculate the level)
R Reference point

The value entered in this parameter changes the distance input into the level block and thus influences the measured level.This change, however, is not taken into account in the displayed distance.

Read access	Operator
Write access	Maintenance

Empty calibr.

Navigation

Expert → Sensor → Level → Empty calibr. (2343)

Expert → Sensor → Level → Empty calibr. (2343)

Description

Distance process connection to min. level.

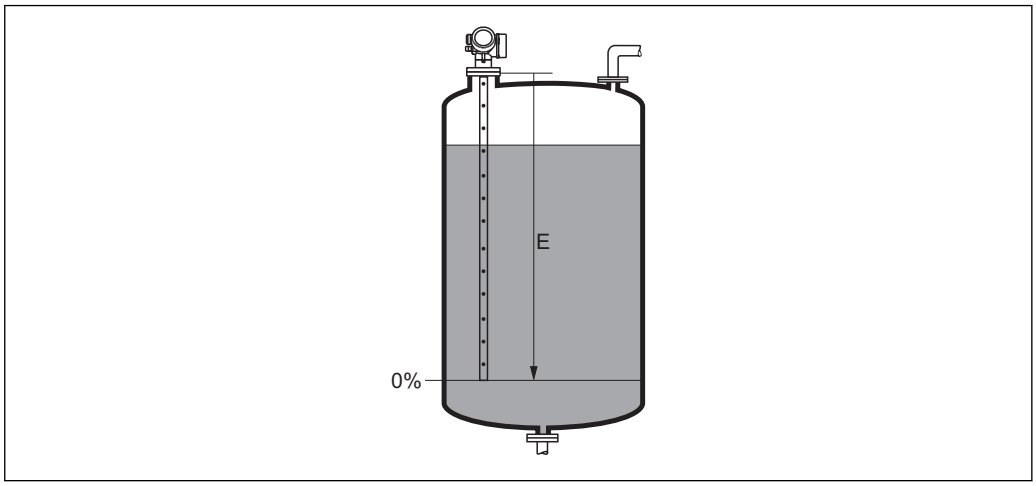
User entry

Depending on the probe

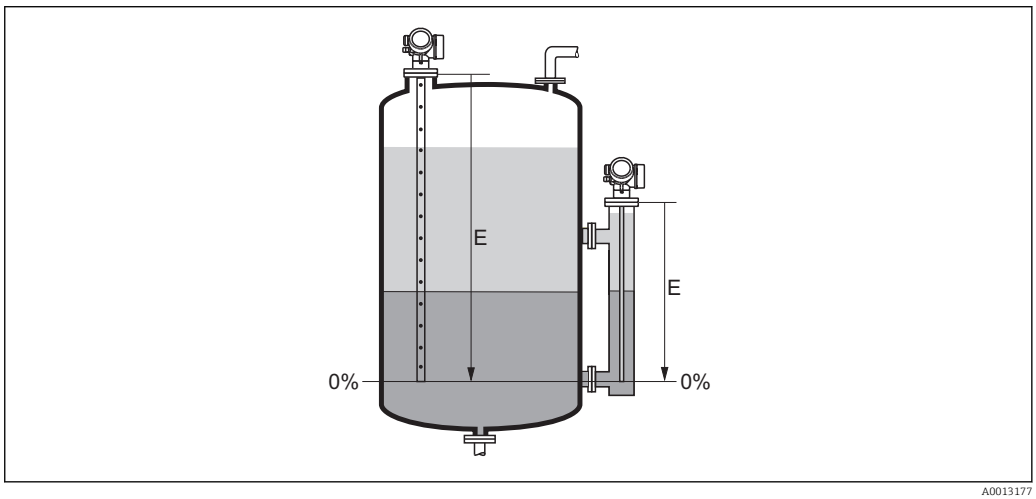
Factory setting

Depending on the probe

Additional information



12 *Empty calibr. (E) for level measurements in liquids*



13 *Empty calibr. (E) for interface measurements*

In the case of interface measurements the **Empty calibr.** parameter is valid for both, the total and the interface level.

Read access	Operator
Write access	Maintenance

Full calibr.

Navigation

Expert → Sensor → Level → Full calibr. (2308)

Expert → Sensor → Level → Full calibr. (2308)

Description

Span: max. level - min level.

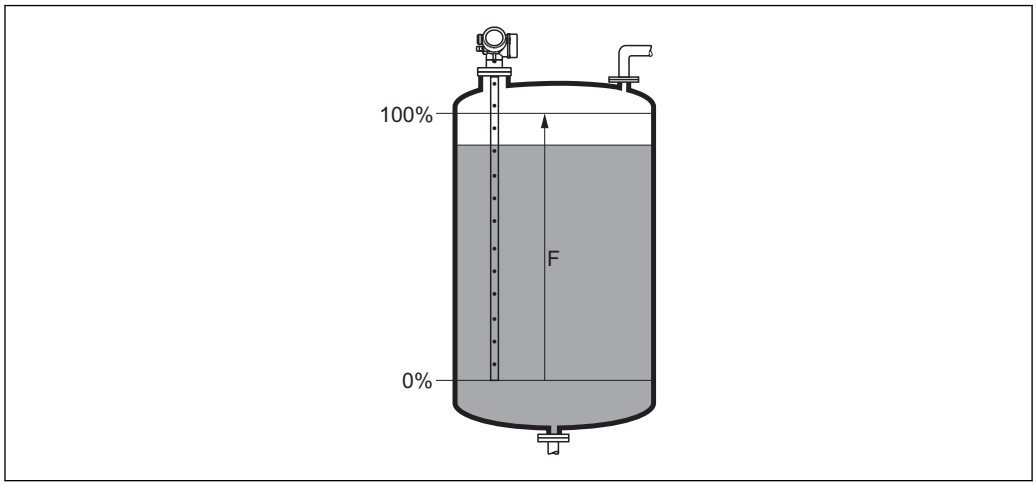
User entry

Depending on the probe

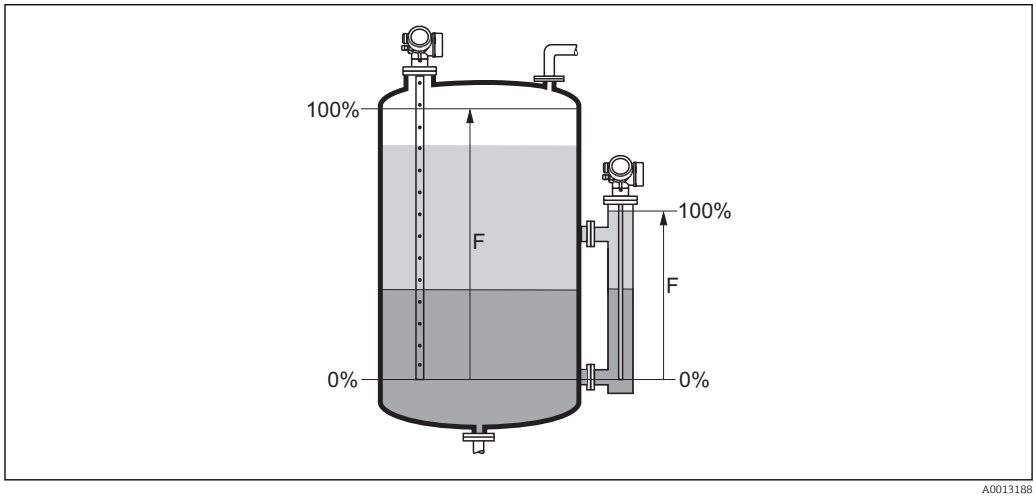
Factory setting

Depending on the probe

Additional information



14 *Full calibr. (F) for level measurements in liquids*



15 *Full calibr. (F) for interface measurements*

In the case of interface measurements the **Full calibr.** parameter is valid for both, the total and the interface level.

Read access	Operator
Write access	Maintenance

Level unit

Navigation
Expert → Sensor → Level → Level unit (0576)
Expert → Sensor → Level → Level unit (0576)

Description
Select level unit.

Selection

SI units
- %
- m
- mm

US units
- ft
- in

Factory setting
%

Additional information
The level unit may differ from the distance unit defined in the **Distance unit** parameter (→ 50):
- The unit defined in the **Distance unit** parameter is used for the basic calibration (**Empty calibr. (→ 63)** and **Full calibr. (→ 64)**).
- The unit defined in the **Level unit** parameter is used to display the (unlinearized) level.

Read access	Operator
Write access	Maintenance

Level limit mode

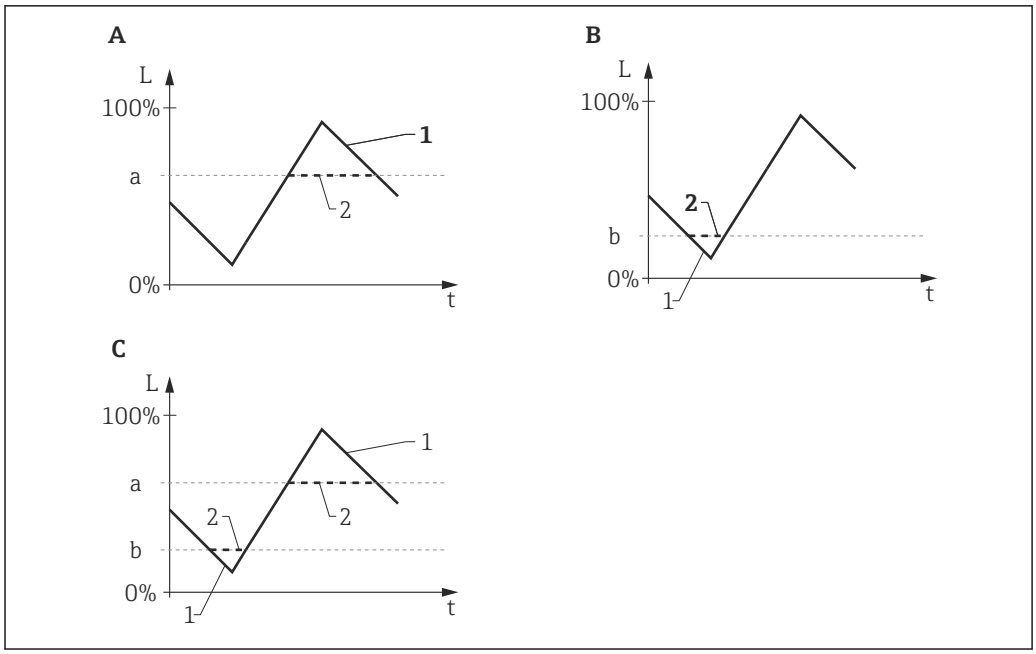
Navigation
Expert → Sensor → Level → Level limit mode (2314)

Description
Select the type of level limitation.

Selection
- Off
- Low limit
- High limit
- Low + High Limit

Factory setting
Low limit

Additional information
The parameter determines to which direction the level is limited. The exact limits are defined in the **High limit (→ 66)** und **Low limit (→ 66)** parameters.



16 *Effect of the "Level limit mode", "High limit" and "Low limit" parameters*

A "Level limit mode" = "High limit"
B "Level limit mode" = "Low limit"
C "Level limit mode" = "Low + High Limit"
a "High limit"
b "Low limit"
1 Level before limitation
2 Level after limitation

High limit

Navigation Expert → Sensor → Level → High limit (2312)

Prerequisite **Level limit mode (→ 65)** = **High limit** or **Low + High Limit**

Description Specify upper limit.

User entry Signed floating-point number

Factory setting 0 %

Additional information Levels exceeding the value specified in this parameter will be ignored. Instead, the device uses the maximum level specified in this parameter (for measured value transformation and output).

Low limit

Navigation Expert → Sensor → Level → Low limit (2313)

Prerequisite **Level limit mode (→ 65)** = **Low limit** or **Low + High Limit**

Description Specify lower level limit.

User entry −200 000.0 to 200 000.0 %

Factory setting 0.0 %

Additional information Levels falling below the value specified in this parameter will be ignored. Instead, the device uses the minimum level specified in this parameter (for measured value transformation and output).

Level correction

Navigation Expert → Sensor → Level → Level correction (2325)

Description Specify level correction (if required).

User entry −200 000.0 to 200 000.0 %

Factory setting 0.0 %

Additional information The value specified in this parameter is added to the measured level (before linearization).

Output mode

Navigation Expert → Sensor → Level → Output mode (2317)

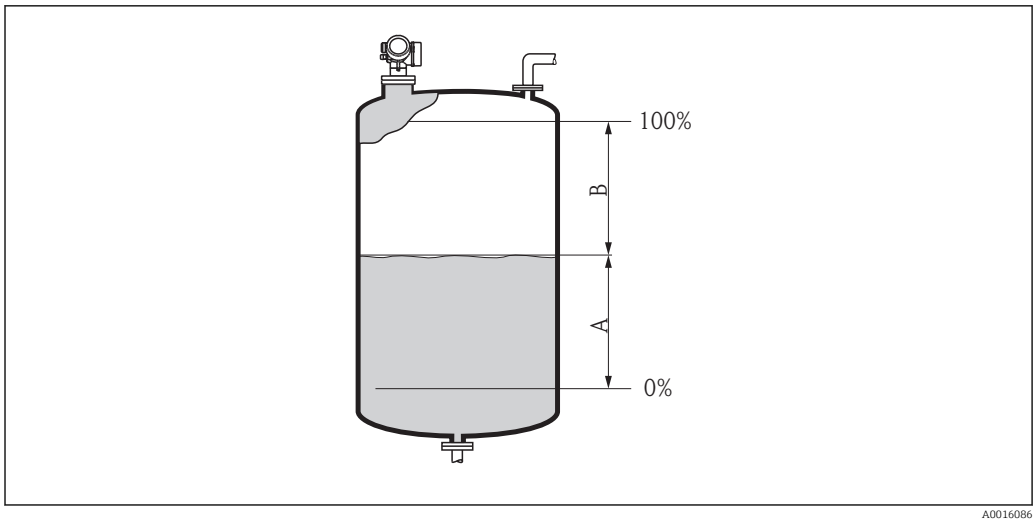
Description Select output mode.

Selection
- Ullage
- Level linearized

Factory setting Level linearized

Additional information

Meaning of the options
- **Ullage**
  The remaining space in the tank or silo is indicated.
- **Level linearized**
  The level is indicated (more precisely: the linearized value if a linearization has been activated).



17 *Definition of the "Output mode (→ 67)" parameter*

A Level linearized
B Ullage

The **Ullage** option is not available for **Linearize. type (→ 75)** = **Table**.

Level

Navigation

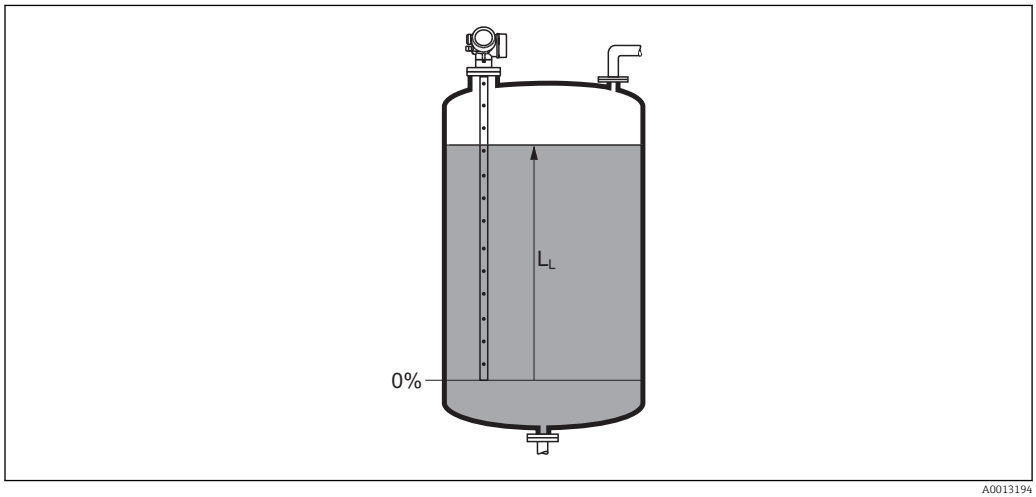
Expert → Sensor → Level → Level (2319)

Expert → Sensor → Level → Level (2319)

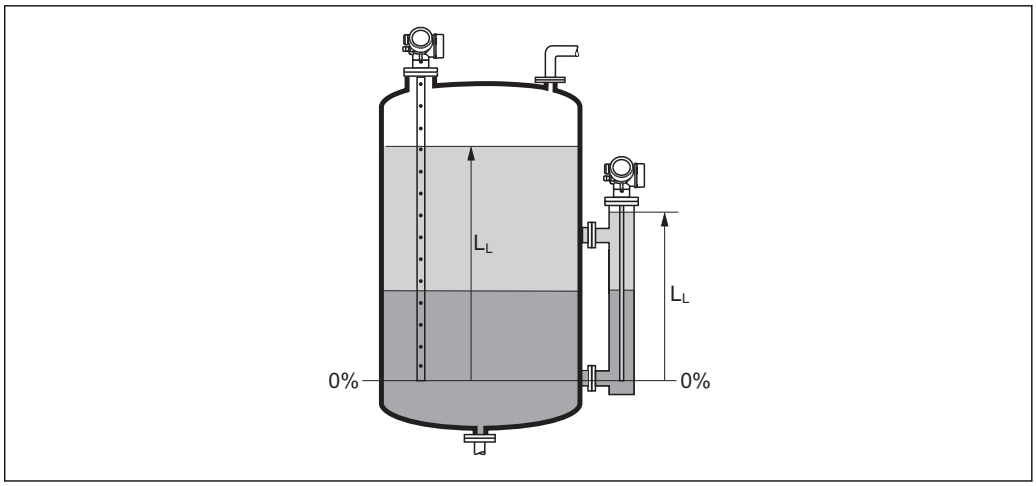
Description

Displays measured level L_L (before linearization).

Additional information



18 *Level in case of liquid measurements*



19 *Level in case of interface measurements*

- The unit is defined in the **Level unit** parameter (→ 65).
- In case of interface measurements, this parameter always refers to the total level.

Read access	Operator
Write access	-

Level linearized

Navigation

Expert → Sensor → Level → Level linearized (2318)

Expert → Sensor → Level → Level linearized (2318)

Description

Displays linearized level.

Additional information

- The unit is defined by the **Unit lineariz.** parameter → 76.
- For interface measurements, this parameter always refers to the total level.

Read access	Operator
Write access	-

Interface

Navigation

Expert → Sensor → Level → Interface (2352)

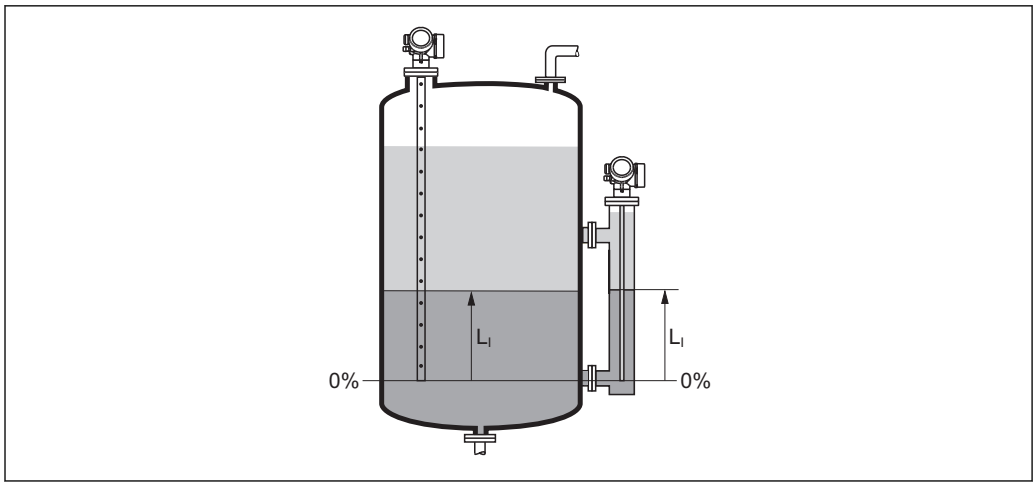
Prerequisite

Operating mode (→ 50) = **Interface** or **Interf.+capacit.**

Description

Displays the measured interface level L_I (before linearization).

Additional information



The unit is defined in the **Level unit** parameter (→ 65).

Interf. lineariz

Navigation Expert → Sensor → Level → Interf. lineariz (2382)

Prerequisite **Operating mode (→ 50)** = **Interface** or **Interf.+capacit.**

Description Displays the linearized interface height.

Additional information The unit is defined in the **Unit lineariz.** parameter → 76.

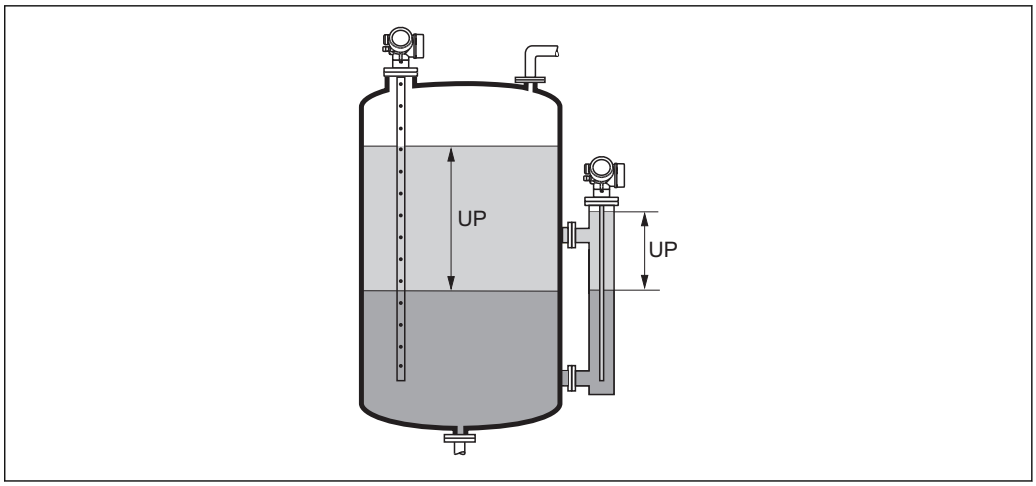
Thickn.upp.layer

Navigation Expert → Sensor → Level → Thickn.upp.layer (2330)

Prerequisite **Operating mode (→ 50)** = **Interface** or **Interf.+capacit.**

Description Displays the upper interface thickness (UP).

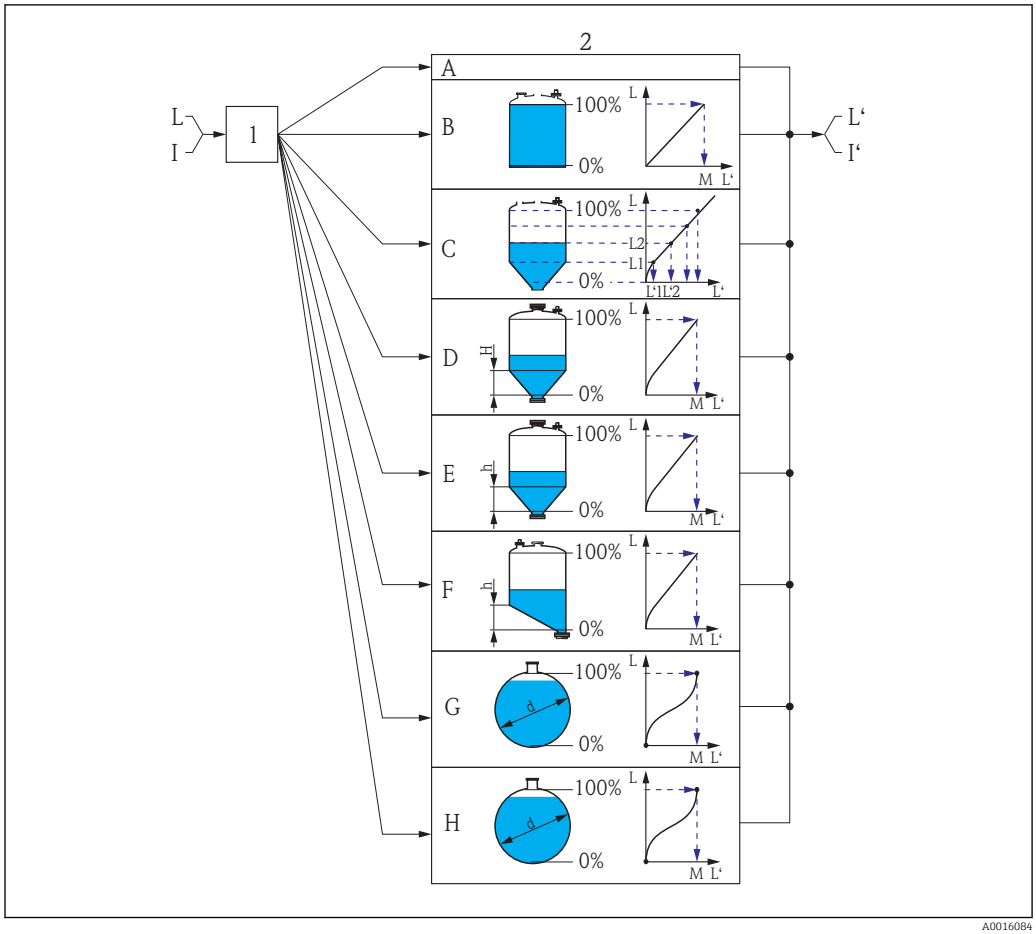
Additional information



UP Thickn.upp.layer

The unit is defined by the **Unit lineariz.** parameter → 76.

4.4.5 "Linearization" submenu

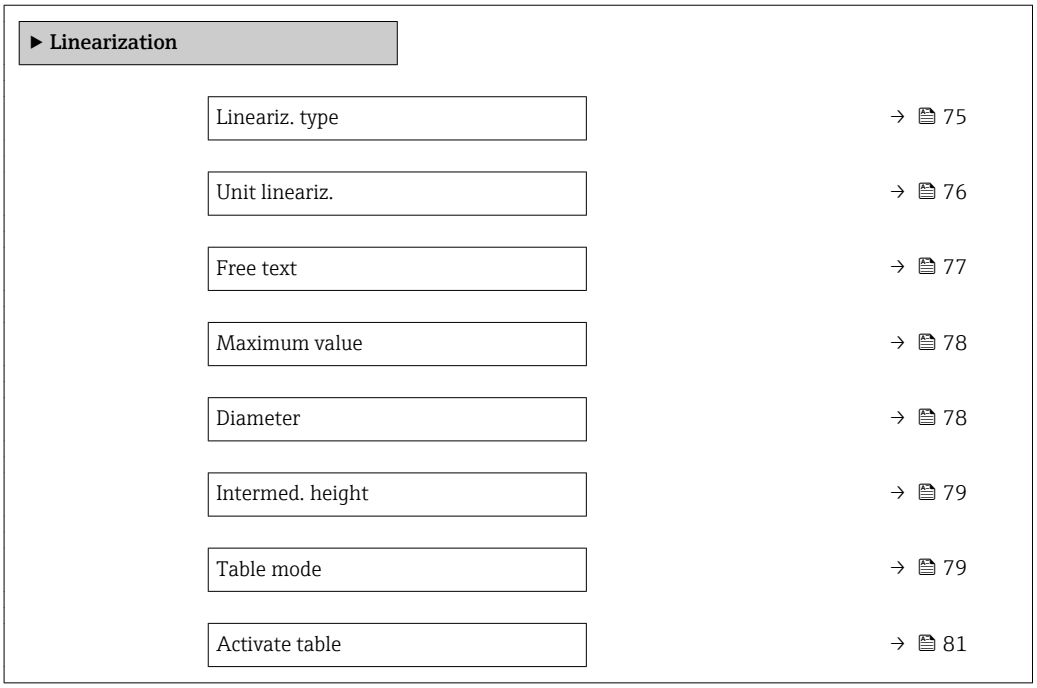


20 *Linearization: Transformation of the level and (if relevant) the interface height into a volume or weight; the transformation is dependent on the shape of the vessel.*

1 *Selection of linearization type and unit*
2 *Configuration of the linearization*
A *Lineariz. type (→ 75) = None*
B *Lineariz. type (→ 75) = Linear*
C *Lineariz. type (→ 75) = Table*
D *Lineariz. type (→ 75) = Pyramid bottom*
E *Lineariz. type (→ 75) = Conical bottom*
F *Lineariz. type (→ 75) = Angled bottom*
G *Lineariz. type (→ 75) = Horizontal cyl.*
H *Lineariz. type (→ 75) = Sphere*
I *For "Operating mode (→ 50)" = "Interface" or "Interf.+capacit.": Interface before linearization (measured in distance units)*
I' *For "Operating mode (→ 50)" = "Interface" or "Interf.+capacit.": Interface after linearization (corresponds to volume or weight)*
L *Level before linearization (measured in distance units)*
L' *Level linearized (→ 69) (corresponds to volume or weight)*
M *Maximum value (→ 78)*
d *Diameter (→ 78)*
h *Intermed. height (→ 79)*

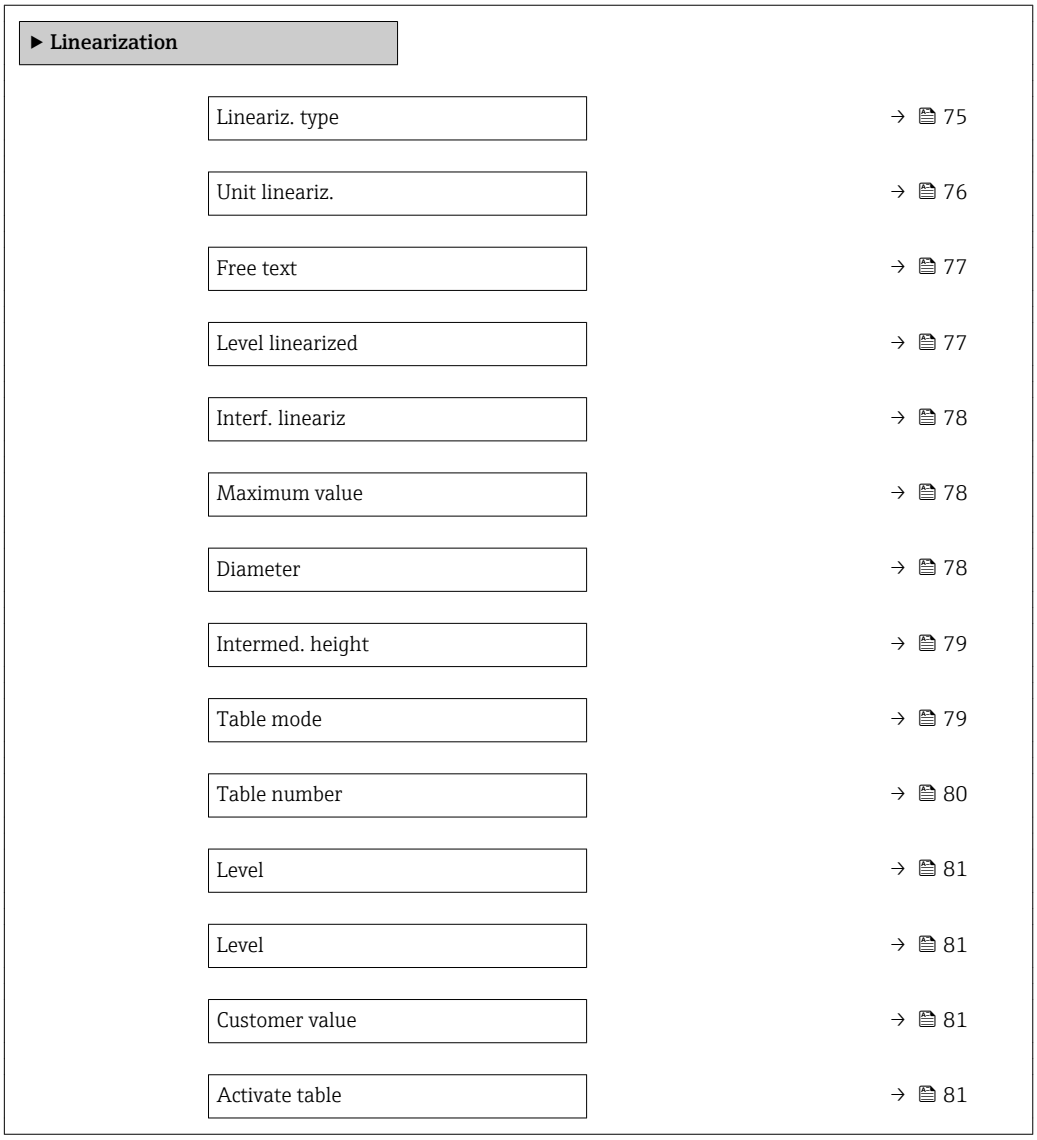
Structure of the submenu on the local display

Navigation Expert → Sensor → Linearization



Structure of the submenu in an operating tool (e.g. FieldCare)

Navigation Expert → Sensor → Linearization



Description of parameters

Navigation Expert → Sensor → Linearization

Lineariz. type

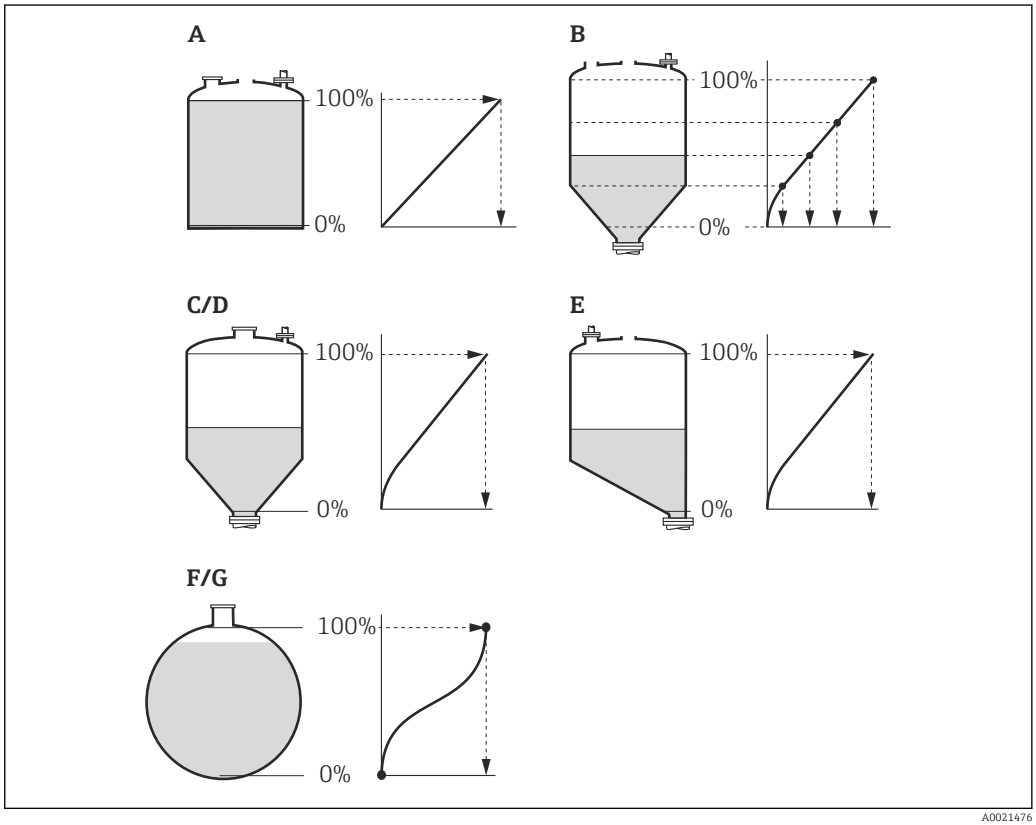
Navigation Expert → Sensor → Linearization → Lineariz. type (2339)

Description Select linearization type.

Selection
- None
- Linear
- Table
- Pyramid bottom
- Conical bottom
- Angled bottom
- Horizontal cyl.
- Sphere

Factory setting None

Additional information



21 Linearization types

A None
B Table
C Pyramid bottom
D Conical bottom
E Angled bottom
F Sphere
G Horizontal cyl.

Meaning of the options

- **None**
  The level is transmitted in the level unit without linearization.
- **Linear**
  The output value (volume/weight) is directly proportional to the level L. This is valid, for example, for vertical cylinders. The following additional parameters have to be specified:
  – **Unit lineariz. (→ 🖹 76)**
  – **Maximum value (→ 🖹 78)**: Maximum volume or weight
- **Table**
  The relationship between the measured level L and the output value (volume/weight) is given by a linearization table consisting of up to 32 pairs of values "level - volume" or "level - weight", respectively. The following additional parameters have to be specified:
  – **Unit lineariz. (→ 🖹 76)**
  – **Table mode (→ 🖹 79)**
  – For each table point: **Level (→ 🖹 81)**
  – For each table point: **Customer value (→ 🖹 81)**
  – **Activate table (→ 🖹 81)**
- **Pyramid bottom**
  The output value corresponds to the volume or weight in a silo with pyramid bottom. The following additional parameters have to be specified:
  – **Unit lineariz. (→ 🖹 76)**
  – **Maximum value (→ 🖹 78)**: Maximum volume or weight
  – **Intermed. height (→ 🖹 79)**: The height of the pyramid
- **Conical bottom**
  The output value corresponds to the volume or weight in a tank with conical bottom. The following additional parameters have to be specified:
  – **Unit lineariz. (→ 🖹 76)**
  – **Maximum value (→ 🖹 78)**: Maximum volume or weight
  – **Intermed. height (→ 🖹 79)**: The height of the conical part of the tank
- **Angled bottom**
  The output value corresponds to the volume or weight in a silo with an angled bottom. The following additional parameters have to be specified:
  – **Unit lineariz. (→ 🖹 76)**
  – **Maximum value (→ 🖹 78)**: Maximum volume or weight
  – **Intermed. height (→ 🖹 79)**: Height of the angled bottom
- **Horizontal cyl.**
  The output value corresponds to the volume or weight in a horizontal cylinder. The following additional parameters have to be specified:
  – **Unit lineariz. (→ 🖹 76)**
  – **Maximum value (→ 🖹 78)**: Maximum volume or weight
  – **Diameter (→ 🖹 78)**
- **Sphere**
  The output value corresponds to the volume or weight in a spherical tank. The following additional parameters have to be specified:
  – **Unit lineariz. (→ 🖹 76)**
  – **Maximum value (→ 🖹 78)**: Maximum volume or weight
  – **Diameter (→ 🖹 78)**

Unit lineariz. 🔒

Navigation 🖭 Expert → Sensor → Linearization → Unit lineariz. (2340)

Prerequisite **Linearis. type (→ 🖹 75)** ≠ None

Description Select unit of the lineaized value.

Selection

SI units
- STon
- t
- kg
- cm^3
- dm^3
- m^3
- hl
- l
- %

US units
- lb
- UsGal
- ft^3

Imperial units
impGal

Custom-specific units
Free text

Factory setting

%

Additional information

The selected unit is only used to be indicated on the display. The measured value is **not** transformed according to the selected unit.

It is also possible to configure a distance-to-distance linearization, i.e. a transformation from the level unit to a different distance unit. To do so, select the **Linear** linearization mode. In order to define the new level unit, select the **Free text** option in the **Unit linearize.** parameter and enter the required unit into the **Free text** parameter (→ 77).

Free text

Navigation

Expert → Sensor → Linearization → Free text (2341)

Prerequisite

Unit linearize. (→ 76) = Free text

Description

Enter unit symbol.

User entry

Up to 32 alphanumerical characters (letters, numbers, special characters)

Factory setting

Free text

Level linearized

Navigation

Expert → Sensor → Linearization → Level linearized (2318)

Description

Displays linearized level.

Additional information

- The unit is defined by the **Unit linearize.** parameter → 76.
- For interface measurements, this parameter always refers to the total level.

Read access	Operator
Write access	-

Interf. lineariz

Navigation Expert → Sensor → Linearization → Interf. lineariz (2382)

Prerequisite **Operating mode (→ 50)** = **Interface** or **Interf.+capacit.**

Description Displays the linearized interface height.

Additional information The unit is defined in the **Unit lineariz.** parameter → 76.

Maximum value

Navigation Expert → Sensor → Linearization → Maximum value (2315)

Prerequisite **Lineariz. type (→ 75)** has one of the following values:
- Linear
- Pyramid bottom
- Conical bottom
- Angled bottom
- Horizontal cyl.
- Sphere

Description Specify the maximum content of the vessel (100%) measured in the units after linearization.

User entry −50 000.0 to 50 000.0 %

Factory setting 100.0 %

Diameter

Navigation Expert → Sensor → Linearization → Diameter (2342)

Prerequisite **Lineariz. type (→ 75)** has one of the following values:
- Horizontal cyl.
- Sphere

Description Specify tank diameter.

User entry 0 to 9 999.999 m

Factory setting 2 m

Additional information The unit is defined in the **Distance unit** parameter (→ 50).

Intermed. height

Navigation Expert → Sensor → Linearization → Intermed. height (2310)

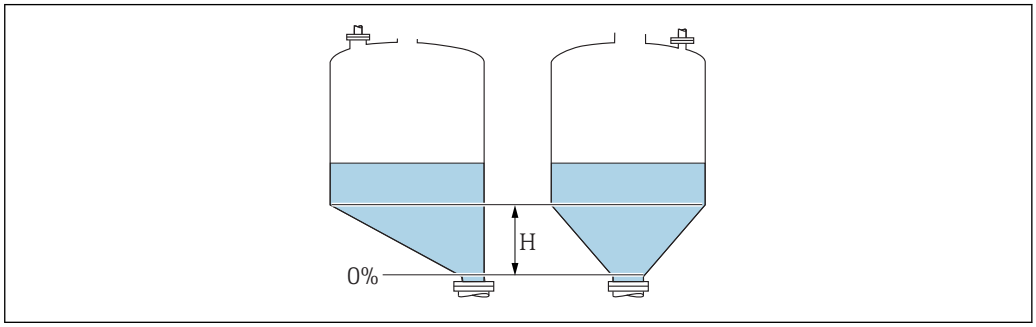
Prerequisite **Lineariz. type (→ 75)** has one of the following values:
- Pyramid bottom
- Conical bottom
- Angled bottom

Description Specify intermediate height H.

User entry 0 to 200 m

Factory setting 0 m

Additional information



H Intermediate height

The unit is defined in the **Distance unit** parameter (→ 50).

Table mode

Navigation Expert → Sensor → Linearization → Table mode (2303)

Prerequisite **Lineariz. type (→ 75)** = **Table**

Description Select editing mode of the linearization table.

Selection
- Manual
- Semiautomatic
- Clear table
- Sort table

Factory setting Manual

Additional information

Meaning of the options
- **Manual**
  The level and the associated linearized value are entered manually for each linearization point.
- **Semiautomatic**
  The level is measured by the device for each linearization point. The associated linearized value is entered manually.
- **Clear table**
  Deletes the existing linearization table.
- **Sort table**
  Rearranges the linerization points into an ascending order.

Conditions the linearization table must meet:
- The table may consist of up to 32 pairs of values "Level - Linearized Value".
- The table must be monotonic (monotonically increasing or decreasing).
- The first linearization point must refer to the minimum level.
- The last linearization point must refer to the maximum level.

Before entering a linearization table, the values for **Empty calibr. (→ 63)** and **Full calibr. (→ 64)** must be set correctly.

If values of the table need to be changed after the full or empty calibration have been changed, a correct evaluation is only ensured if the existing table is deleted and the complete table is entered again. To do so delete the existing table (**Table mode (→ 79)** = **Clear table**). Then enter a new table.

How to enter the table
- Via FieldCare
  The table points can be entered via the **Table number (→ 80)**, **Level (→ 81)** and **Customer value (→ 81)** parameters. As an alternative, the graphic table editor may be used: Device Operation → Device Functions → Additional Functions → Linearization (Online/Offline)
- Via local display
  Select the **Edit table** submenu to call up the graphic table editor. The table is displayed and can be edited line by line.

The factory setting for the level unit is "%". If you want to enter the linearization table in physical units, you must select the appropriate unit in the **Level unit** parameter (→ 65) beforehand.

Table number

Navigation Expert → Sensor → Linearization → Table number (2370)

Prerequisite **Lineariz. type (→ 75)** = **Table**

Description Select table point you are going to enter or change.

User entry 1 to 32

Factory setting 1

Level (Manual)

Navigation Expert → Sensor → Linearization → Level (2383)

Prerequisite
- **Lineariz. type (→ 75)** = **Table**
- **Table mode (→ 79)** = **Manual**

Description Enter level value of the table point (value before linearization).

User entry Signed floating-point number

Factory setting 0 %

Level (Semiautomatic)

Navigation Expert → Sensor → Linearization → Level (2389)

Prerequisite
- **Lineariz. type (→ 75)** = **Table**
- **Table mode (→ 79)** = **Semiautomatic**

Description Displays measured level (value before linearization). This value is transmitted to the table.

Customer value

Navigation Expert → Sensor → Linearization → Customer value (2384)

Prerequisite **Lineariz. type (→ 75)** = **Table**

Description Enter linearized value for the table point.

User entry Signed floating-point number

Factory setting 0 %

Activate table

Navigation Expert → Sensor → Linearization → Activate table (2304)

Prerequisite **Lineariz. type (→ 75)** = **Table**

Description Activate (enable) or deactivate (disable) the linearization table.

Selection
- Disable
- Enable

Factory setting Disable

Additional information

Meaning of the options

- **Disable**
  The measured level is not linearized.
  If **Lineariz. type (→ 75)** = **Table** at the same time, the device issues error message F435.
- **Enable**
  The measured level is linearized according to the table.

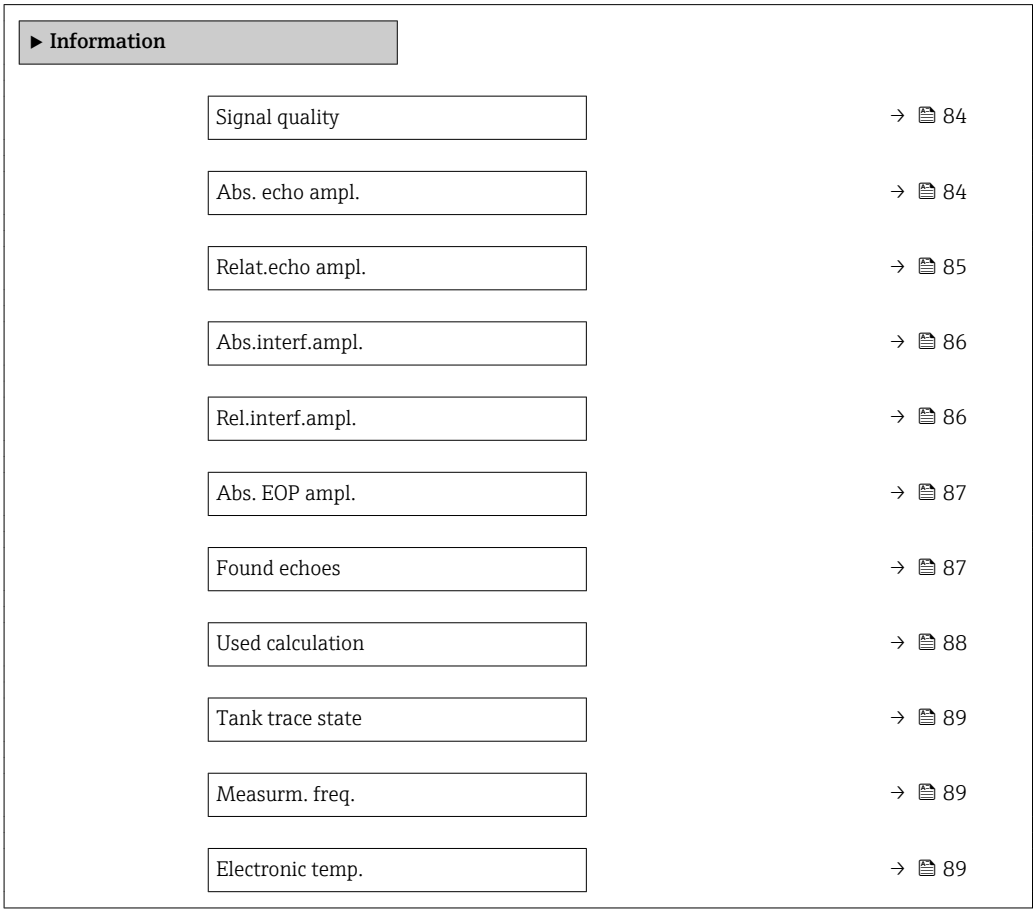
When editing the table, the **Activate table** parameter is automatically reset to **Disable** and must be reset to **Enable** after the table has been entered.

4.4.6 "Information" submenu

The **Information** submenu comprises all display parameters which give information about the current state of the measurement.

Structure of the submenu

Navigation Expert → Sensor → Information



Description of parameters

Navigation Expert → Sensor → Information

Signal quality

Navigation Expert → Sensor → Information → Signal quality (1047)

Description Displays the signal quality of the evaluated echo.

Additional information

Meaning of the display options

- **Strong**
  The evaluated echo exceeds the threshold by at least 10 mV.
- **Medium**
  The evaluated echo exceeds the threshold by at least 5 mV.
- **Weak**
  The evaluated echo exceeds the threshold by less than 5 mV.
- **No signal**
  The device does not find a usable echo.

The signal quality indicated in this parameter always refers to the currently evaluated echo: either the level/interface echo [2] or the end-of-probe echo. To differentiate between these two, the quality of the end-of-probe echo is always displayed in brackets.

In case of a lost echo (**Signal quality = No signal**) the device generates the following error message:
- F941, for **Output echo lost (→ 117) = Alarm**.
- S941, if another option has been selected in **Output echo lost (→ 117)**.

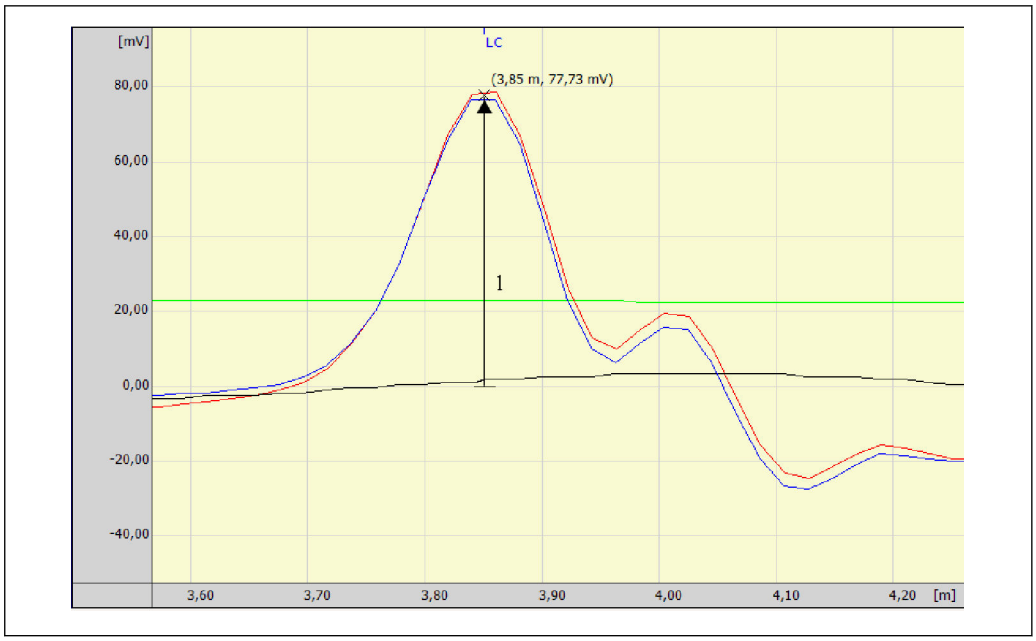
Abs. echo ampl.

Navigation Expert → Sensor → Information → Abs. echo ampl. (1127)

Description Displays the absolute amplitude of the level echo in the subtracted curve.

2) Of these two echos the one with the lower quality is indicated.

Additional information



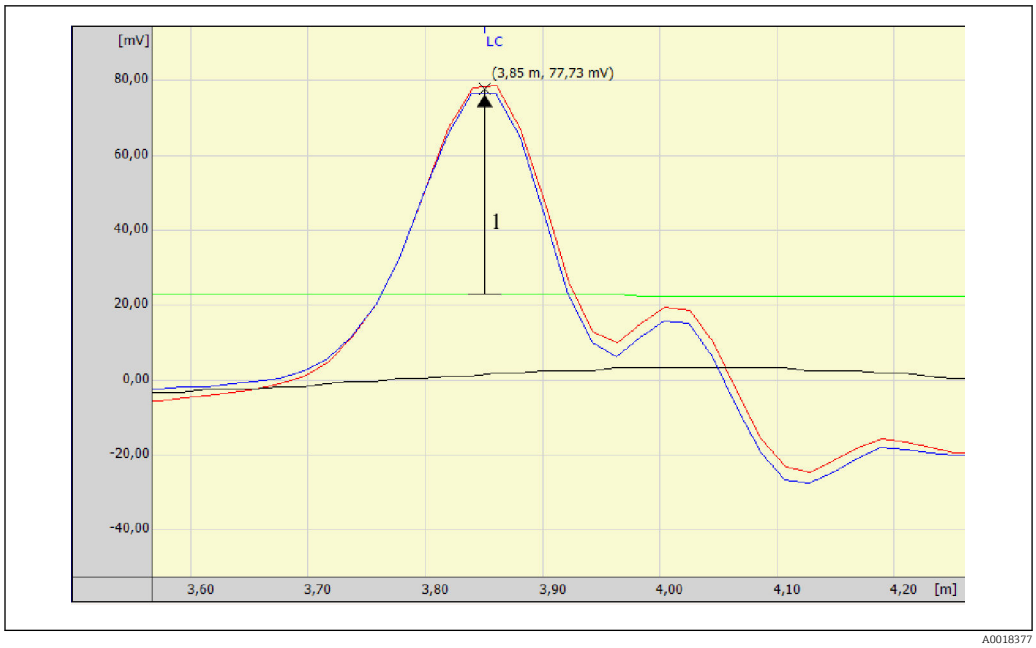
1 Absolute echo amplitude in the envelope curve as measured from the 0mV line

Relat.echo ampl.

Navigation Expert → Sensor → Information → Relat.echo ampl. (1089)

Description Displays the relative amplitude of the level echo in the subtracted curve. The relative amplitude is the difference between the level echo and the echo threshold.

Additional information



1 The relative echo amplitude is the difference between the amplitude in the envelope curve (blue) and the echo threshold (green).

In the envelope curve display of FieldCare, the absolute echo amplitude is indicated instead of the relative amplitude (see the number on the top right of the echo peak in the example).

Abs.interf.ampl.

Navigation Expert → Sensor → Information → Abs.interf.ampl. (1129)

Prerequisite **Operating mode (→ 50)** = **Interface** or **Interf.+capacit.**

Description Displays the absolute amplitude of the interface echo in the subtracted curve.

Rel.interf.ampl.

Navigation Expert → Sensor → Information → Rel.interf.ampl. (1090)

Prerequisite **Operating mode (→ 50)** = **Interface** or **Interf.+capacit.**

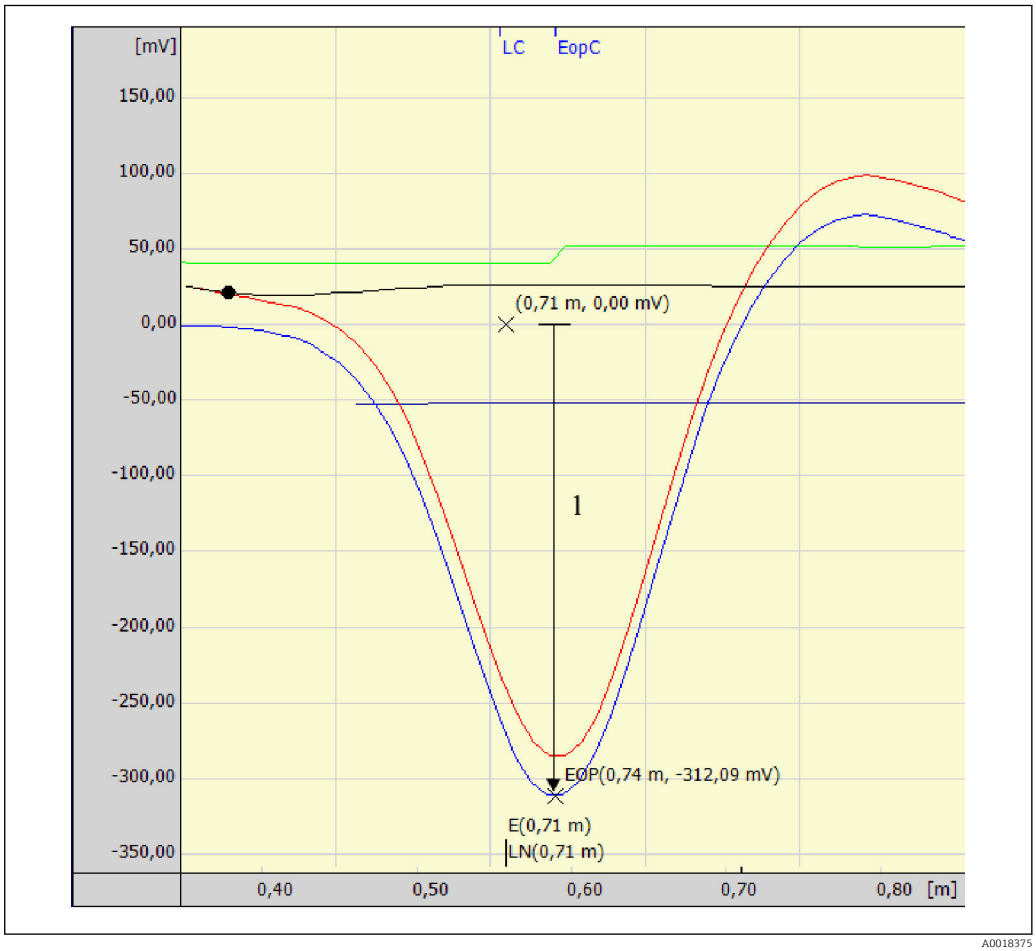
Description Displays the relative amplitude of the interface echo in the subtracted curve.

Abs. EOP ampl.

Navigation Expert → Sensor → Information → Abs. EOP ampl. (1128)

Description Displays the absolute amplitude of the end-of-probe signal in the subtracted curve.

Additional information



1 Absolute EOP amplitude (example for an insulated end-of-probe)

Polarity of the end-of-probe signal

- For probe ends which are freely suspended in the medium or insulated against the tank, the end-of-probe signal is negative.
- For probe ends which are grounded to the tank potential, the end-of-probe signal is positive.

To ensure correct evaluation of the end-of-probe signal, its polarity must be specified in the **EOP search mode** parameter (→ 133).

Found echoes

Navigation Expert → Sensor → Information → Found echoes (1068)

Description Indicates which echoes have been found.

User interface

- None
- Level
- Interface
- EOP
- Level + interf.
- Level and EOP
- Interf. and EOP
- Level+interf+EOP
- EOP (TT)
- Multip. echo(TT)
- EOP (LN)
- EOP
- Level and EOP
- Level+interf(C)
- Level(C)+interf

Used calculation

Navigation Expert → Sensor → Information → Used calculation (1115)

Description Indicates which echoes are used for the calculation of the measured value.

Additional information

Meaning of the options

- **None**
  The measured value is not calculated (e.g. due to a lost echo)
- **Level**
  The level is calculated from the direct level echo.
- **EOP**
  The level is calculated from the end-of-probe signal (EOP).
- **EOP (TT)**
  The level is calculated from the end-of-probe signal (EOP) taking into account the tank table (TT).
- **Multip. echo(TT)**
  The level is calculated from the multiple echo, taking into account the tank table (TT).
- **EOP (LN)**
  An empty tank is detected from the end-of-probe signal (EOP) in the interface mode.
- **Level and EOP**
  The level is calculated from the direct level echo. Its plausibility is checked by the end-of-probe signal (EOP). This situation may occur if the device is in the interface mode and the tank contains only one medium.
- **Interface**
  The interface height is calculated from the direct interface echo. This situation may occur if **Tank level (→ 146)** = **Fully flooded**.
- **Level + interf.**
  The level is calculated from the direct level echo. The interface height is calculated from the direct interface echo.

Tank trace state

Navigation Expert → Sensor → Information → Tank trace state (1206)

Description Indicates the current state of the tank trace.

Additional information

Meaning of the options
- **Not active**
  A valid tank trace is not available.
- **EOP (TT)**
  A valid EOP tank trace is available.
- **Multip. echo(TT)**
  A valid multiple echo tank trace is available.
- **EOP+Multiplecho**
  A valid EOP and multiple echo tank trace are available.

Measurm. freq.

Navigation Expert → Sensor → Information → Measurm. freq. (1180)

Description Displays the current measurement frequency (number of pulses per second).

Additional information The measurement frequency is dependent on the length of the probe. Refer to the Technical Information (TI) of the respective device for details.

Electronic temp.

Navigation Expert → Sensor → Information → Electronic temp. (1062)

Description Displays the current temperature of the electronics.

Additional information The unit is defined in the **Temperature unit** parameter (→ 50).

4.4.7 "Sensor prop." submenu

The **Sensor prop.** submenu comprises all parameters which describe the measurement-related properties of the probe and the envelope curve.

Probe length correction

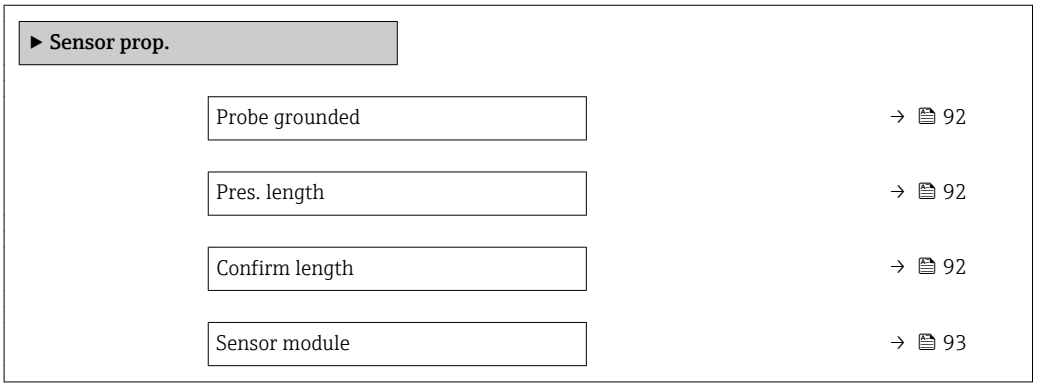
For the signal evaluation it is essential that the Levelflex allocates the end-of-probe signal correctly. To ensure this one can manually enter the actual length of the probe or one can perform a probe length correctionn several times until the displayed length of the probe matches the actual length of the probe (LN). To do so one needs the following parameters:

- **Pres. length (→ 92)**
- **Confirm length (→ 92)**

When operating via the local display module, the **Confirm length (→ 92)** and **Pres. length (→ 92)** parameters are comprised in the **Prob.length corr** sequence.

Structure of the submenu

Navigation Expert → Sensor → Sensor prop.



Description of parameters

Navigation Expert → Sensor → Sensor prop.

Probe grounded

Navigation Expert → Sensor → Sensor prop. → Probe grounded (1222)

Prerequisite **Operating mode (→ 50)** = **Level**

Description Specify whether the probe is grounded.

Selection
- No
- Yes

Factory setting No

Pres. length

Navigation Expert → Sensor → Sensor prop. → Pres. length (1078)

Description
- In most cases:
  Displays the length of the probe according to the currently measured end-of-probe signal.
- For **Confirm length (→ 92)** = **Manual input**:
  Enter actual length of probe.

User entry 0 to 200 m

Factory setting 4 m

Confirm length

Navigation Expert → Sensor → Sensor prop. → Confirm length (1080)

Description Select, whether the value displayed in the **Pres. length** parameter → 92 matches the actual length of the probe. Based on this input, the device performs a probe length correction.

Selection
- Probe length OK
- Length too small
- Length too big
- Probe covered
- Manual input
- Length unknown

Factory setting Probe length OK

Additional information

Meaning of the options

- **Probe length OK**
  To be selected if the indicated length is correct. An adjustment is not required. The device quits the sequence.
- **Length too small**
  To be selected if the displayed length is smaller than the actual length of the probe. A different end of probe signal is allocated and the newly calculated length is displayed in the **Pres. length** parameter → 92. This procedure has to be repeated until the displayed value matches the actual length of the probe.
- **Length too big**
  To be selected if the displayed length is bigger than the actual length of the probe. A different end of probe signal is allocated and the newly calculated length is indicated in the **Pres. length** parameter → 92. This procedure has to be repeated until the displayed value matches the actual length of the probe.
- **Probe covered**
  To be selected if the probe is (partially or completely) covered. A probe length correction is impossible in this case. The device quits the sequence.
- **Manual input**
  To be selected if no automatic probe length correction is to be performed. Instead, the actual length of the probe must be entered manually into the **Pres. length** parameter → 92 [3].
- **Length unknown**
  To be selected if the acutal length of the probe is unknown. A probe length correction is impossible in this case and the device quits the sequence.
  .

Sensor module

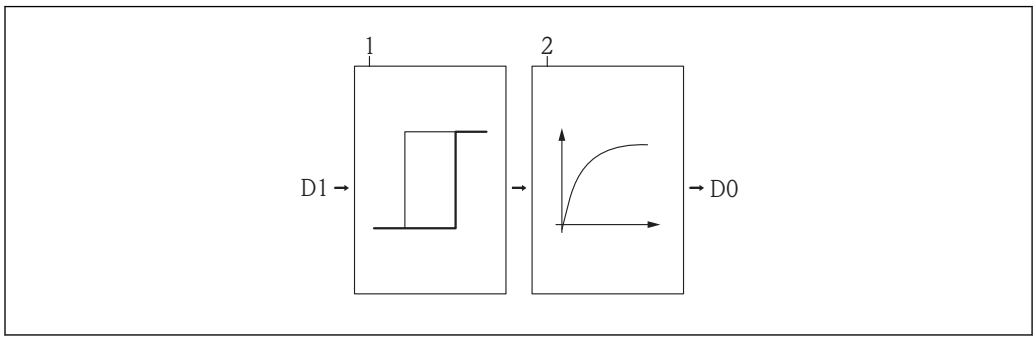
Navigation Expert → Sensor → Sensor prop. → Sensor module (1101)

Description Displays the type of sensor module.

3) When operated via FieldCare, the **Manual input** option needs not to be selected explicitly. In FieldCare the length of the probe can always be edited.

4.4.8 "Distance" submenu

The **Distance** submenu contains all parameters which control the filtering of the raw distance D1. The resulting distance D0 is used for the subsequent calculation of the level.

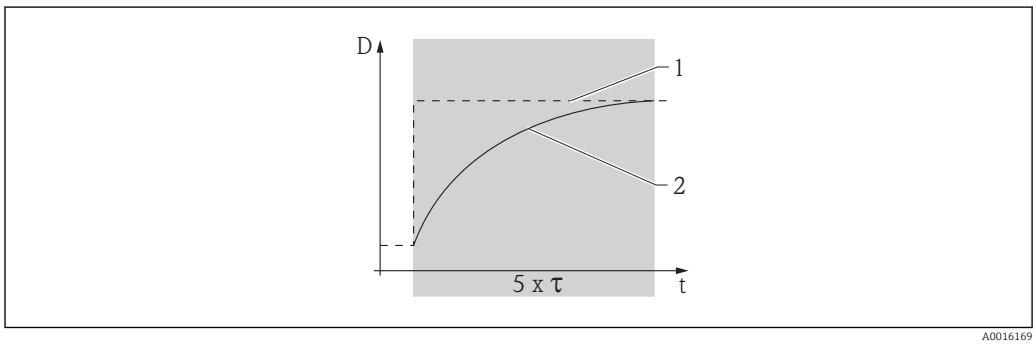


22 The configurable distance filters

1 Dead time (→ 97)
2 Integration time (→ 98) (low pass filter)

Low pass filter

The low pass filter dampens the distance signal with a user defined integration time τ (**Integration time** parameter (→ 98)). After a sudden change of the level, it takes about 5 x τ, until the new measured value is obtained.

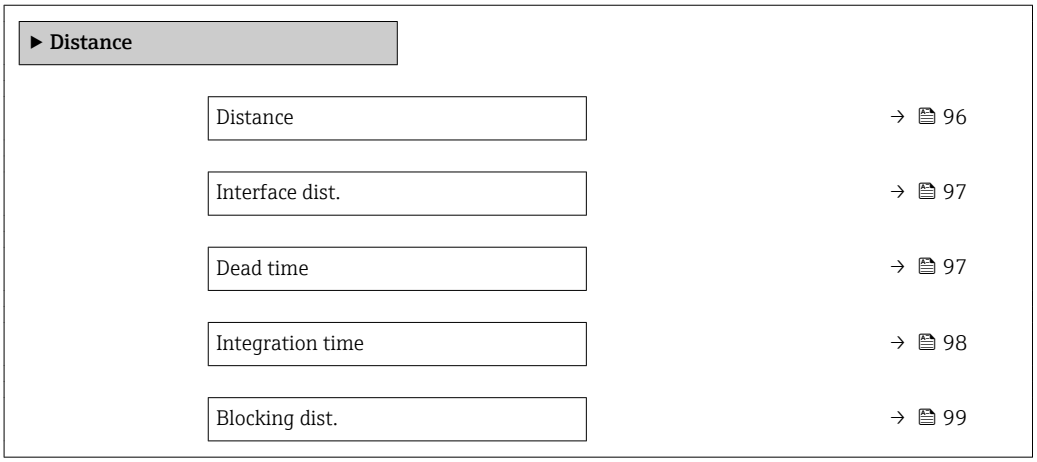


23 Low pass filter

1 Signal before the low pass filter
2 Signal after the low pass filter
τ Integration time (→ 98)

Structure of the submenu

Navigation Expert → Sensor → Distance



Description of parameters

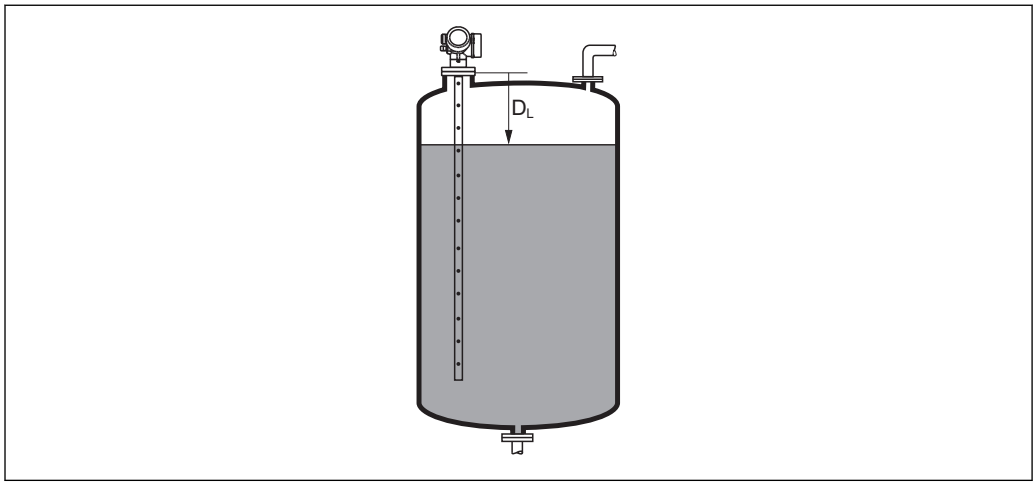
Navigation Expert → Sensor → Distance

Distance

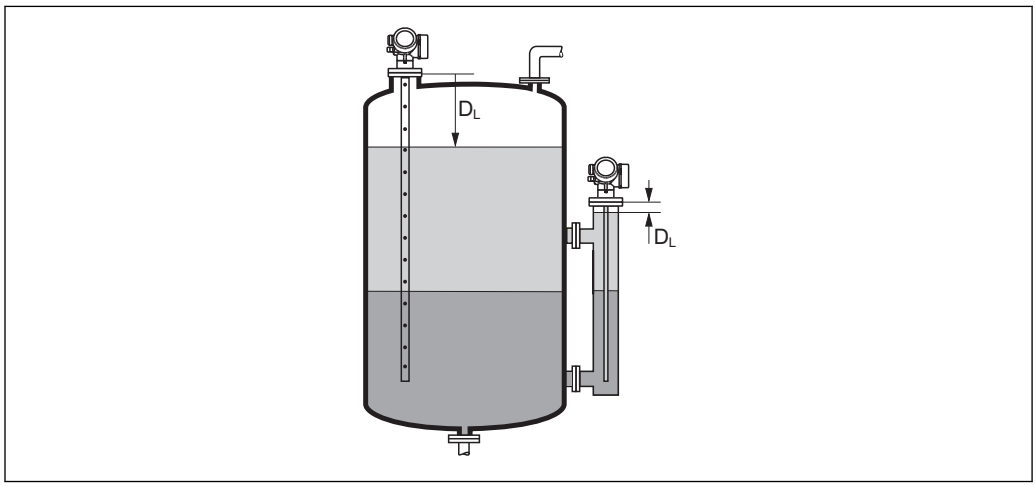
Navigation Expert → Sensor → Distance → Distance (1124)

Description Displays the measured distance D_L between the reference point (lower edge of the flange or threaded connection) and the level.

Additional information



24 *Distance for liquid measurements*



25 *Distance for interface measurements*

The unit is defined in the **Distance unit** parameter (→ 50).

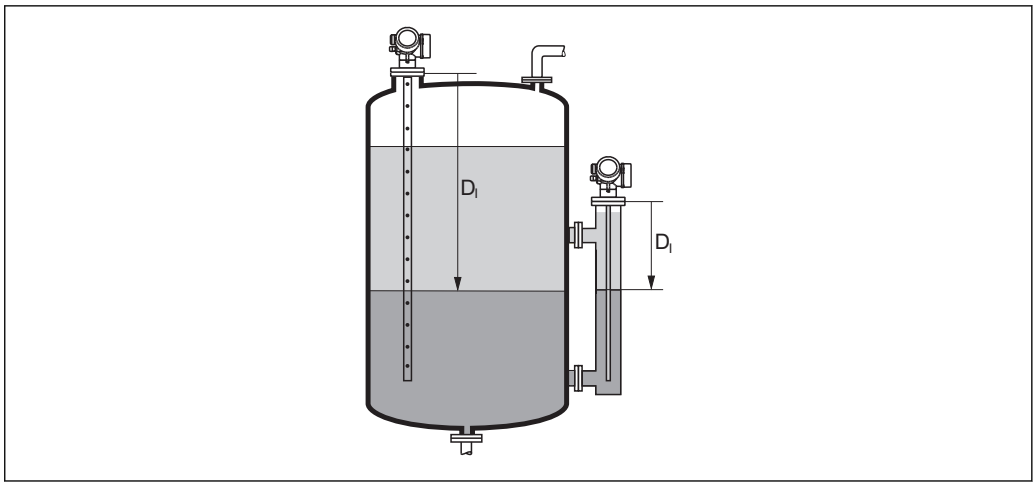
Interface dist.

Navigation Expert → Sensor → Distance → Interface dist. (1067)

Prerequisite **Operating mode (→ 50)** = **Interface** or **Interf.+capacit.**

Description Displays the measured distance D_I between the reference point (lower edge of flange or threaded connection) and the interface.

Additional information



A0013202

The unit is defined in the **Distance unit** parameter (→ 50).

Dead time

Navigation Expert → Sensor → Distance → Dead time (1199)

Description Define the dead time (in seconds).

User entry 0 to 60 s

Factory setting **Dependent on the following parameters:**
- **Medium type (→ 56)**
- **Process property (→ 52)**

Additional information *Factory setting for level measurements with "Medium type" = "Liquid"*

Process property (→ 52)	Dead time
Fast>1m 40"/min	0 s
Std.<1m 40"/min	1 s
Med<10cm 4"/min	3 s
Sl.<1cm .4"/min	6 s
No filter / test	0 s

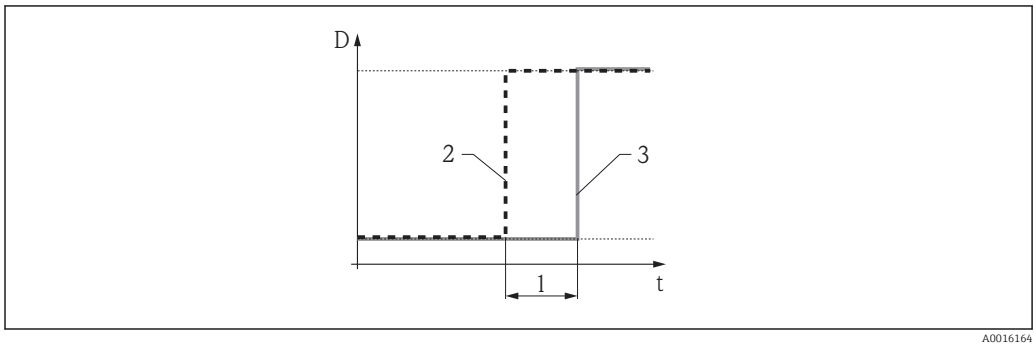
Factory setting for level measurements with "Medium type" = "Solid"

Process property (→ 52)	Dead time
Fast>10m(33ft)/h	1 s
Std.<10m(33ft)/h	3 s
Med <1m (3ft) /h	5 s
Slow<.1m(.3ft)/h	10 s
No filter / test	0 s

Factory setting for interface measurements

Process property (→ 52)	Dead time
Fast>1m 40'/min	0 s
Std.<1m 40'/min	10 s
Med<10cm 4'/min	10 s
Sl.<1cm .4'/min	10 s
No filter / test	0 s

Application
Sudden changes of the measured distance are ignored during the time span defined in this parameter. In this way it is possible to prevent short-term interferences form disturbing the output signal.



26 Effect of the dead time

1 Dead time
2 Signal before the dead time filter
3 Signal after the dead time filter

Disadvantages
- The device slows down.
- Fast level changes are registered with a delay.

Integration time

Navigation Expert → Sensor → Distance → Integration time (1092)

Description Define the integration time (in seconds).

User entry 0.0 to 200 000.0 s

Factory setting

Dependent on the following parameters:
- **Medium type (→ 56)**
- **Process property (→ 52)**

Additional information

Factory setting for "Medium type" = "Liquid"

Process property (→ 52)	Integration time
Fast>1m 40"/min	1 s
Std.<1m 40"/min	5 s
Med<10cm 4"/min	15 s
Sl.<1cm .4"/min	30 s
No filter / test	0 s

Factory setting for "Medium type" = "Solid"

Process property (→ 52)	Integration time
Fast>10m(33ft)/h	37 s
Std.<10m(33ft)/h	74 s
Med <1m (3ft) /h	145 s
Slow<.1m(.3ft)/h	290 s
No filter / test	< 0.8 s

Increasing the integration time results in a calmer measuring signal. However, it also causes a delayed reaction to level changes.

Blocking dist.

Navigation

Expert → Sensor → Distance → Blocking dist. (1144)

Description

Specify upper blocking distance UB.

User entry

0 to 200 m

Factory setting

- For coax probes: 0 mm (0 in)
- For rod and rope probes up to 8 m (26 ft): 200 mm (8 in)
- For rod and rope probes above 8 m (26 ft): 0.025 * Sondenlänge

For FMP51/FMP52/FMP54 with the **Interface measurement** application package [4] and for FMP55:
100 mm (3.9 in) for all antenna types

Additional information

Signals in the upper blocking distance are only evaluated if they have been outside the blocking distance when the device was switched on and move into the blocking distance

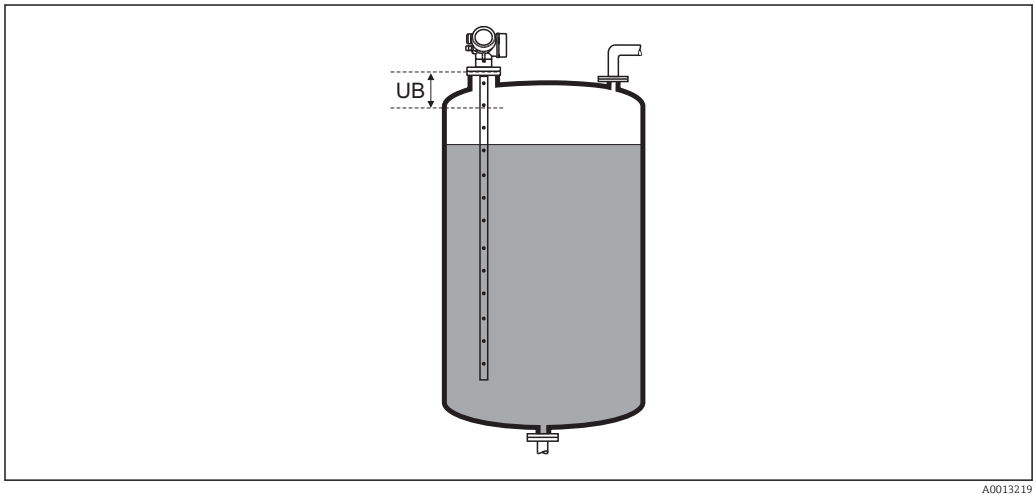
4) Ordering feature 540 "Application Package", option EB "Interface measurement"

due to a level change during operation. Signals which are already in the blocking distance when the device is switched on, are ignored.

This behavior is only valid if the following two conditions are met:
- Expert → Sensor → Echo tracking → Evaluation mode (1112) = **Short time hist.** or **Long time hist.**)
- Expert → Sensor → Gas phase comp. → GPC mode (1034)= **On**, **Without correct.** or **External correct**

If one of these conditions is not met, signals in the blocking distance will always be ignored.

If required, a different behavior for signals in the blocking distance can be defined by the Endress+Hauser service.



27 Blocking distance (UB) for liquid measurements

4.4.9 "Gas phase comp." submenu

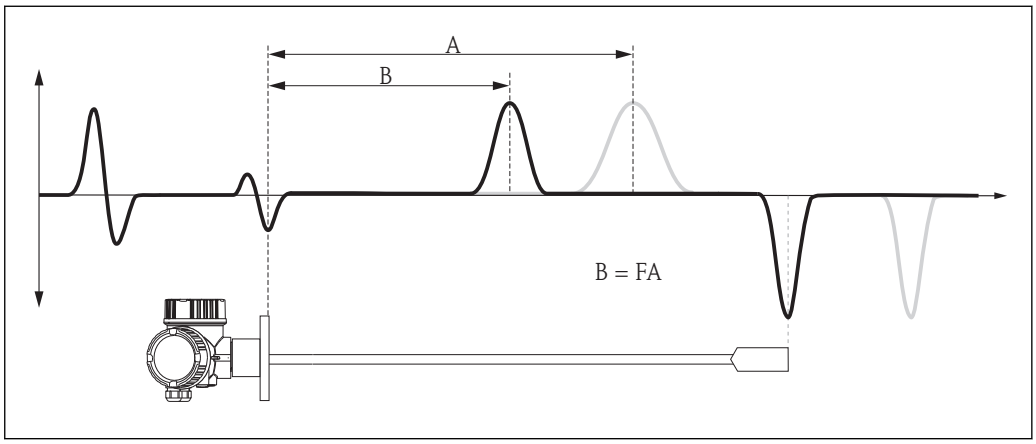
For FMP51, FMP52 and FMP54: The **Gas phase comp.** submenu (→ 104) is only available if **Operating mode (→ 50)** = **Level**.

Gas phase compensation with reference signal

This type of gas phase compensation requires a reference signal at a defined distance from the process connection which must be above the maximum level. The current speed of propagation is determined from the shift of this reference signal The envelope curve can be scaled accordingly.

Constant gas phase compensation factor

If the properties of the gas phase (pressure, temperature, composition) do not change over the time and are known, a gas phase compensation can also be performed without a reference signal. Instead, a constant, user-defined correction factor is applied in this case. This factor is used to scale the envelope curve (and thus the measured echo distance).

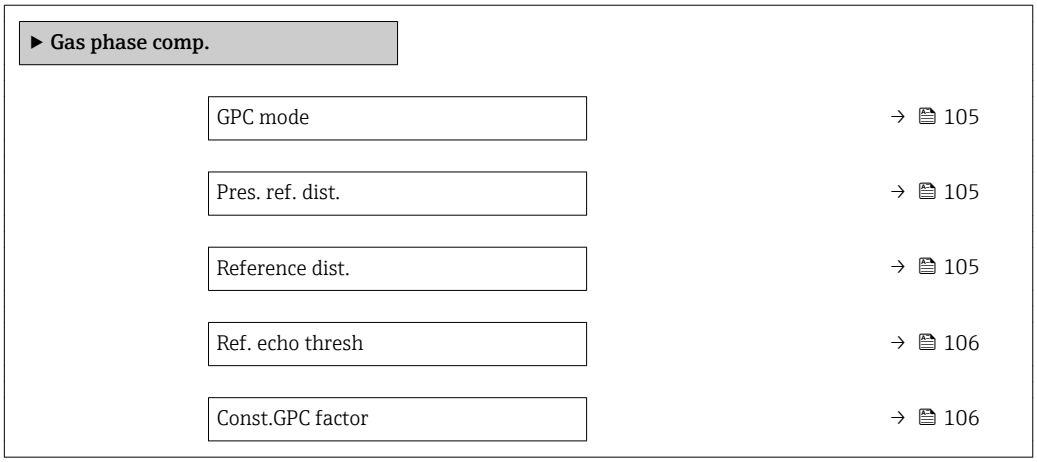


28 Gas phase compensation with a constant correction factor F

A Position of the level echo in the original envelope curve
B Position of the level echo in the corrected envelope curve.

Structure of the submenu

Navigation Expert → Sensor → Gas phase comp.



Description of parameters

Navigation Expert → Sensor → Gas phase comp.

GPC mode

Navigation Expert → Sensor → Gas phase comp. → GPC mode (1034)

Description Select gas phase compensation mode.

Selection
- Off
- On
- Without correct.
- External correct
- Const.GPC factor

Factory setting Off

Additional information

Meaning of the options
- **Off**
  The gas phase compensation is deactivated.
- **On**
  This option can only be selected for probes with reference echo. The gas phase compensation is calculated from the position of this reference echo. In FieldCare, the displayed envelope curve does already contain the correction.
- **Without correct.**
  The correction factor is calculated from the reference echo but not applied to the measurement. In FieldCare, the envelope curve is displayed without the correction. This option is only used for diagnostic purposes and should not be selected in normal applications.
- **Const.GPC factor**
  The correction factor is a constant defined by the user. A reference echo is not needed. In FieldCare, the displayed envelope curve does already contain the correction.

Pres. ref. dist.

Navigation Expert → Sensor → Gas phase comp. → Pres. ref. dist. (1076)

Prerequisite **GPC mode (→ 105)** = **On** or **Without correct.**

Description Displays the currently measured distance of the reference echo.

Reference dist.

Navigation Expert → Sensor → Gas phase comp. → Reference dist. (1033)

Prerequisite **GPC mode (→ 105)** = **On** or **Without correct.**

Description Enter actual distance of the reference echo.

User entry 0 to 200 m

Factory setting According to the probe

Ref. echo thresh

Navigation Expert → Sensor → Gas phase comp. → Ref. echo thresh (1168)

Prerequisite **GPC mode (→ 105)** = **On** or **Without correct.**

Description Define threshold for the reference echo.

User entry −999.0 to 999.0 mV

Factory setting −80 mV

Additional information
- Only echoes exceeding the defined threshold are accepted as reference echo.
- Positive reference echoes are not suited for Levelflex as they might be mistaken for the level echo.

Const.GPC factor

Navigation Expert → Sensor → Gas phase comp. → Const.GPC factor (1217)

Prerequisite **GPC mode (→ 105)** = **Const.GPC factor**

Description Specify constant correction factor for the measured distance.

User entry 0.5 to 1.5

Factory setting 1

4.4.10 "Sensor diag." submenu

The **Sensor diag.** submenu comprises all parameters which contain information about the state of the probe and the HF cable.

Broken probe detection

In the case of a broken probe caused by mechanical wear, a negative echo arises at the breaking point. If the broken probe detection is active, the device looks for a signal of this type and creates an error message if required.

The borken probe detection can only be used if an interference echo suppression (map) has been correctly recorded.

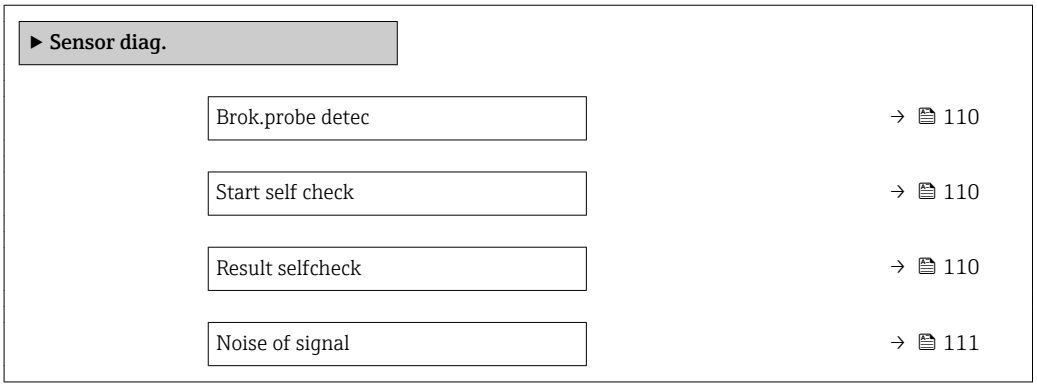
Self check

The **Start self check (→ 🖹 110)** and **Result selfcheck (→ 🖹 110)** parameters are used for the proof-test which is required for SIL applications in regular intervals. For details refer to the description of the test procedure C in the Functional Safety Manual SD00326F.

For the self check, a test signal is generated in the sensor module and fed onto the analog signal path. The device software checks whether this test signal is within the admissible amplitude and distance ranges. The result of the self check is displayed in the **Result selfcheck** parameter (→ 🖹 110).

Structure of the submenu

Navigation Expert → Sensor → Sensor diag.



Description of parameters

Navigation Expert → Sensor → Sensor diag.

Brok.probe detec

Navigation
Expert → Sensor → Sensor diag. → Brok.probe detec (1032)
Expert → Sensor → Sensor diag. → Brok.probe detec (1032)

Description
Switch the broken probe detection on or off.

Selection
- Off
- On

Factory setting
Off

Additional information
If the broken probe detection is switched on: As soon as a broken probe is detected, the device generates ana alarm and the diagnostic message **Br.probe detect.**.

Start self check

Navigation
Expert → Sensor → Sensor diag. → Start self check (1133)

Description
Start a self check of the device.

Selection
- No
- Yes

Factory setting
No

Additional information
For the self check, a test signal is generated in the sensor module and fed onto the analog signal path. The device software checks whether this test signal is within the admissible amplitude and distance ranges. The result of the self check is displayed in the **Result selfcheck** parameter (→ 110).

The self check is used for the proof-test which is required for SIL applications in regular intervals. For details refer to the description of the test procedure C in the Functional Safety Manual SD00326F.

Result selfcheck

Navigation
Expert → Sensor → Sensor diag. → Result selfcheck (1134)

Description
Displays the result of the self check.

Additional information

Meaning of the options
- **Ok**
  The self check has been passed.
- **Not ok**
  The self check failed.
- **Check not done**
  A self check has not been performed.

Noise of signal

Navigation

Expert → Sensor → Sensor diag. → Noise of signal (1105)

Expert → Sensor → Sensor diag. → Noise of signal (1105)

Description

Displays the noise of signal in the envelope curve

4.4.11 "Safety sett." submenu

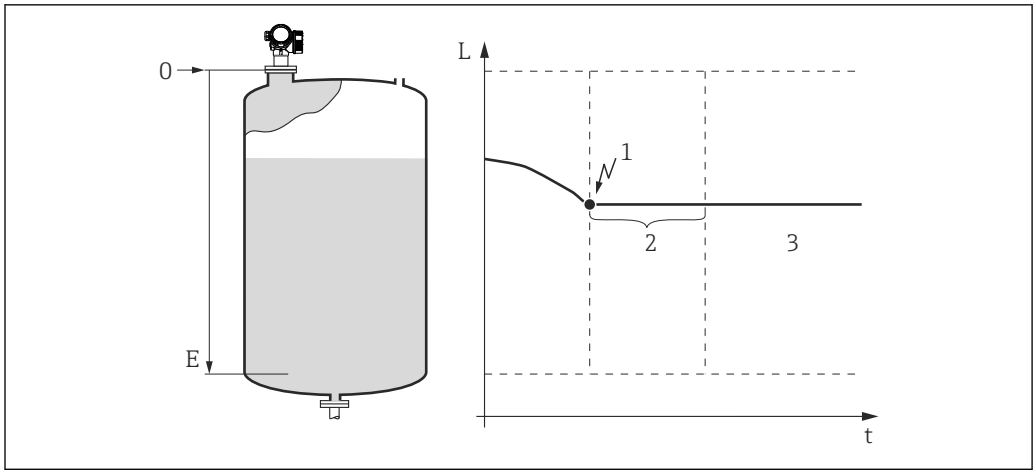
The **Safety sett.** submenu contains all parameters which determnine the behavior of the device in critical situations such as an echo loss or an undershooting of a user defined safety distance.

Behavior in the case of an echo loss

The bahavior in case of an echo loss is defined in the **Output echo lost** parameter (→ 117). Depending on the selected option, suitable values must be selected in a number of additional parameters:

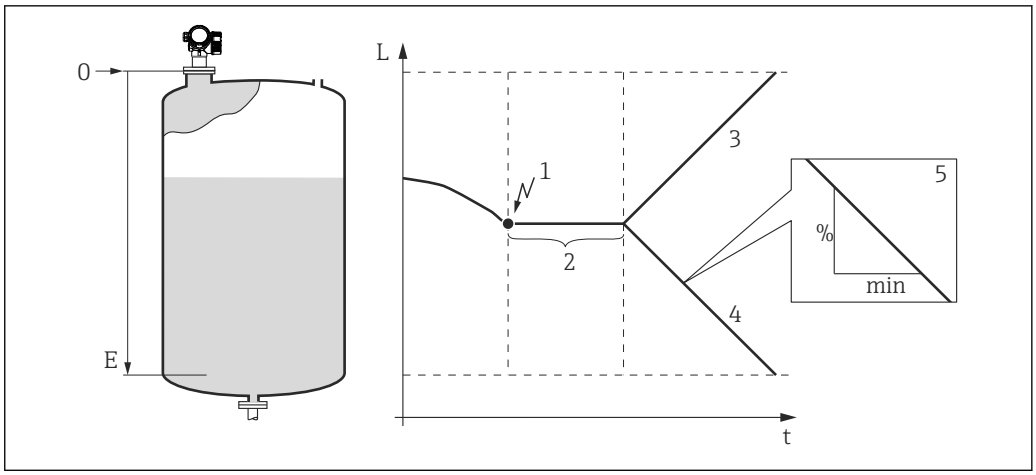
Option selected in in "Output echo lost (→ 117)"	Required additional parameters
Last valid value	Delay echo lost (→ 118)
Ramp echo lost	▪ Ramp echo lost (→ 118) ▪ Delay echo lost (→ 118)
Value echo lost	▪ Value echo lost (→ 117) ▪ Delay echo lost (→ 118)
Alarm	1)

1) The alarm bahavior ist defined in the submenus "Curr.output" (HART) or "Analog input" (PROFIBUS PA, FOUNDATION Fieldbus).



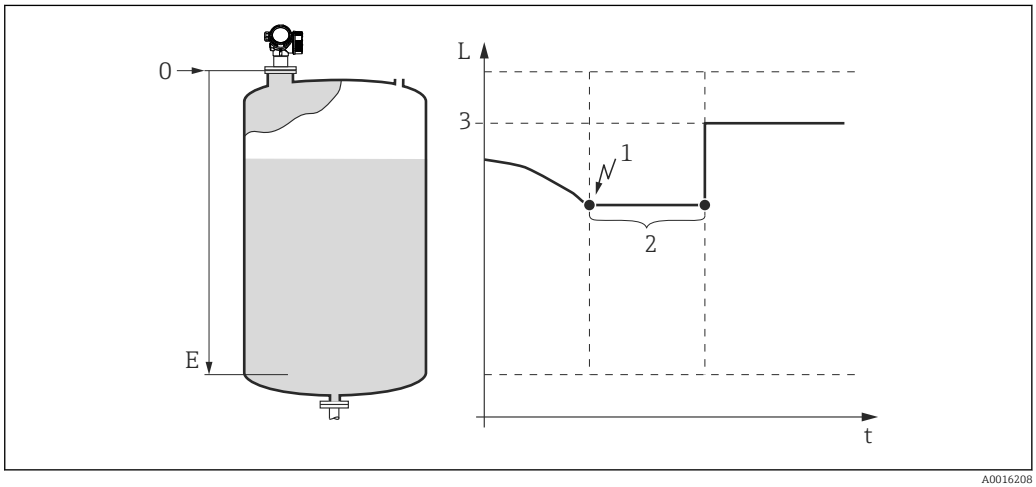
29 "Output echo lost (→ 117)" = "Last valid value"

1 Echo loss
2 Delay echo lost (→ 118)
3 The last valid measured value is held.



30 *"Output echo lost (→ 117)" = "Ramp echo lost"*

1 *Echo loss*
2 *"Delay echo lost (→ 118)"*
3 *For a positive ramp: The measured value is increased with a constant rate until it reaches the maximum value (100%).*
4 *For a negative ramp: The measured value is decreased with a constant rate until it reaches the minimum value (0%).*
5 *The ramp is specified as "percentage of the defined measuring span per minute".*

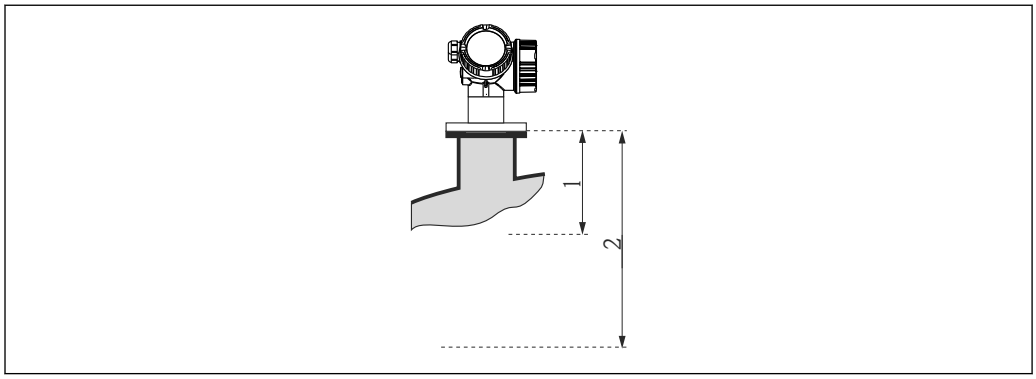


31 *"Output echo lost (→ 117)" = "Value echo lost"*

1 *Echo loss*
2 *Delay echo lost (→ 118)*
3 *Value echo lost (→ 117)*

Safety distance

In order to get a warning message if the level rises into the proximity of the upper blocking distance, a safety distance can be defined in the **Safety distance** parameter (→ 🖹 119).

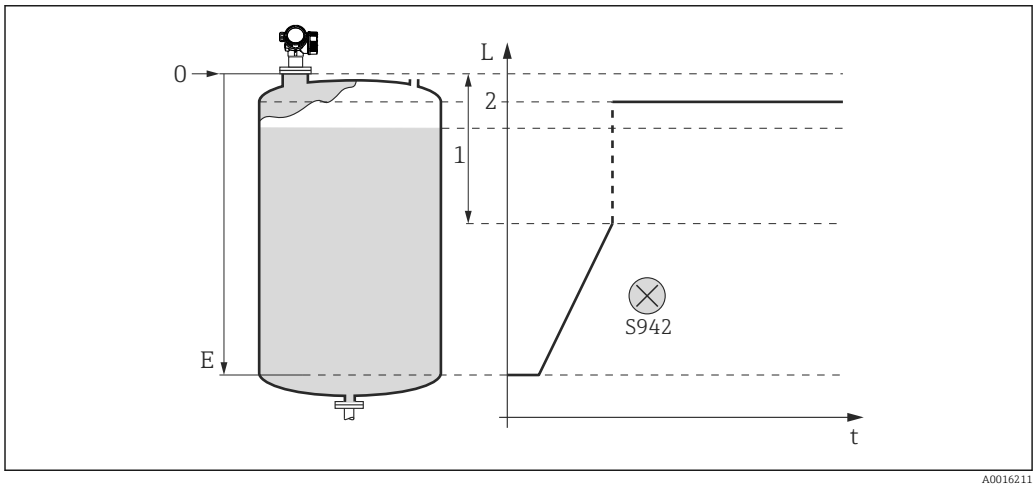


32 *Definition of the safety distance*

1 Blocking dist. (→ 🖹 99)
2 Safety distance (→ 🖹 119)

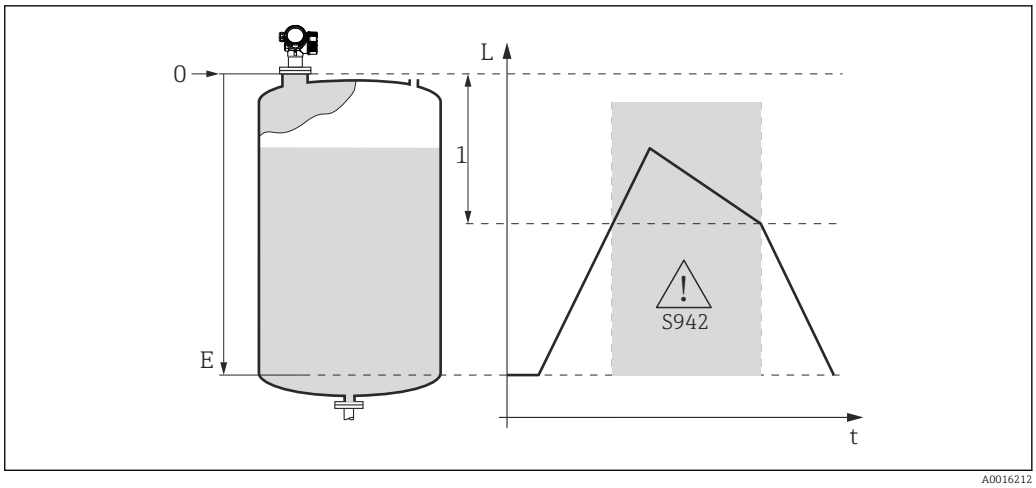
The behavior of the device in case the level rises into the safety distance is defined in the following parameters:

- **In safety dist. (→ 🖹 119)**
- **Acknowl. alarm (→ 🖹 119)**



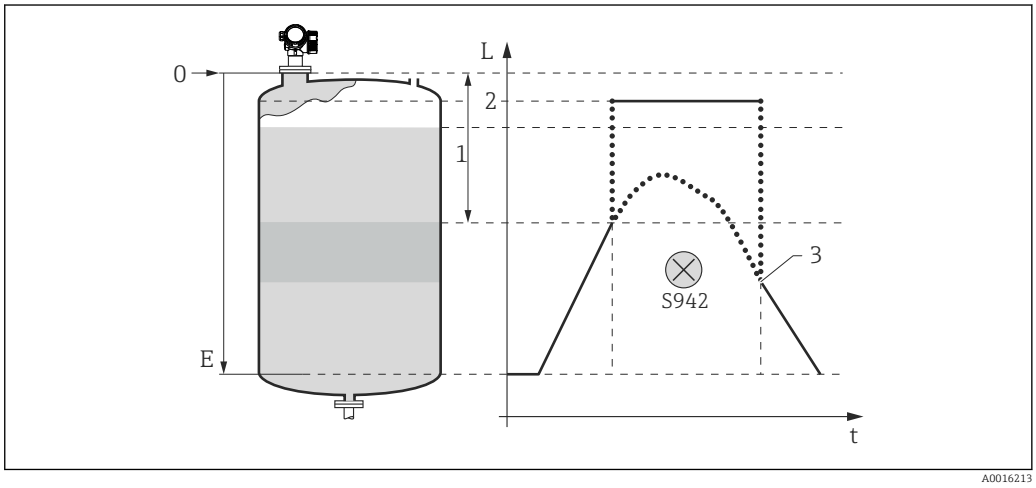
33 *"In safety dist." = "Alarm": If the safety distance is undershot, the device generates an alarm.*

1 Safety distance (→ 🖹 119)
2 Value defined in "Failure mode"



34 *"In safety dist." = "Warning": If the safety distance is undershot, the device continues measuring but nevertheless generates a warning.*

1 Safety distance (→ 119)

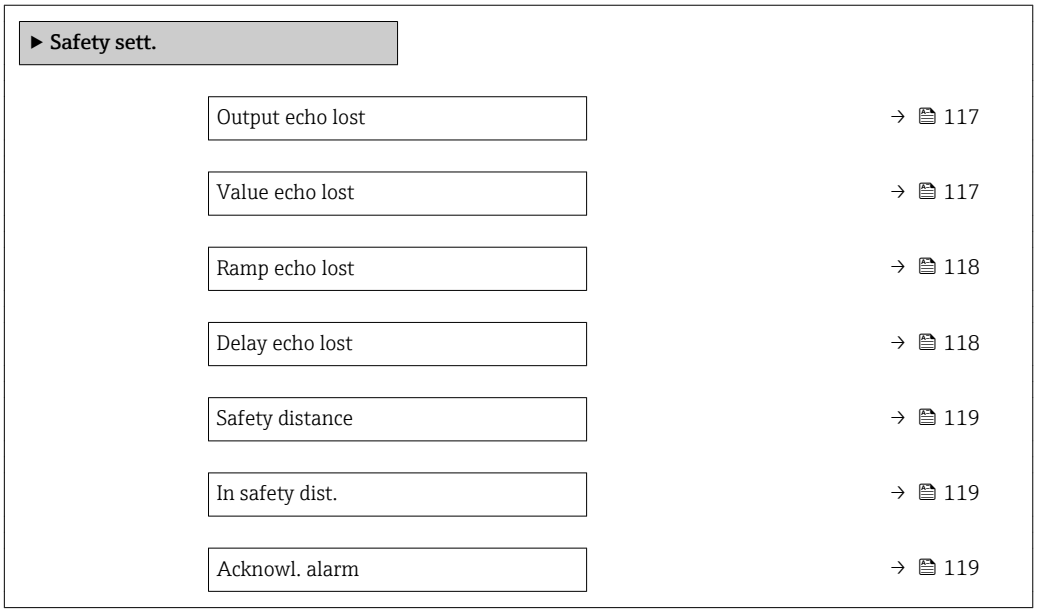


35 *"In safety dist." = "Self holding": If the safety distance is undershot, the device generates an alarm. The measurement is not resumed until this alarm has been acknowledged by the user.*

1 Safety distance (→ 119)
2 Value defined in "Failure mode"
3 Acknowl. alarm (→ 119)

Structure of the submenu

Navigation Expert → Sensor → Safety sett.



Description of parameters

Navigation Expert → Sensor → Safety sett.

Output echo lost

Navigation Expert → Sensor → Safety sett. → Output echo lost (2307)

Description Define the behavior of the output signal in case of a lost echo.

Selection
- Last valid value
- Ramp echo lost
- Value echo lost
- Alarm

Factory setting Last valid value

Additional information

Meaning of the options
- **Last valid value**
  The last valid value is kept in the case of a lost echo.
- **Ramp echo lost**
  In the case of a lost echo the output value is continously shifted towards 0% or 100%. The slope of the ramp is defined in the **Ramp echo lost** parameter (→ 118).
- **Value echo lost**
  In the case of a lost echo the output assumes the value defined in the **Value echo lost** parameter (→ 117).
- **Alarm**
  In the case of a lost echo the device generates an alarm; see the **Failure mode** parameter

Value echo lost

Navigation Expert → Sensor → Safety sett. → Value echo lost (2316)

Prerequisite **Output echo lost (→ 117)** = **Value echo lost**

Description Define output value in case of a lost echo.

User entry 0 to 200 000.0 %

Factory setting 0.0 %

Additional information Use the unit which has been defined for the measured value output:
- without linearization: **Level unit (→ 65)**
- with linearization: **Unit lineariz. (→ 76)**

Ramp echo lost

Navigation Expert → Sensor → Safety sett. → Ramp echo lost (2323)

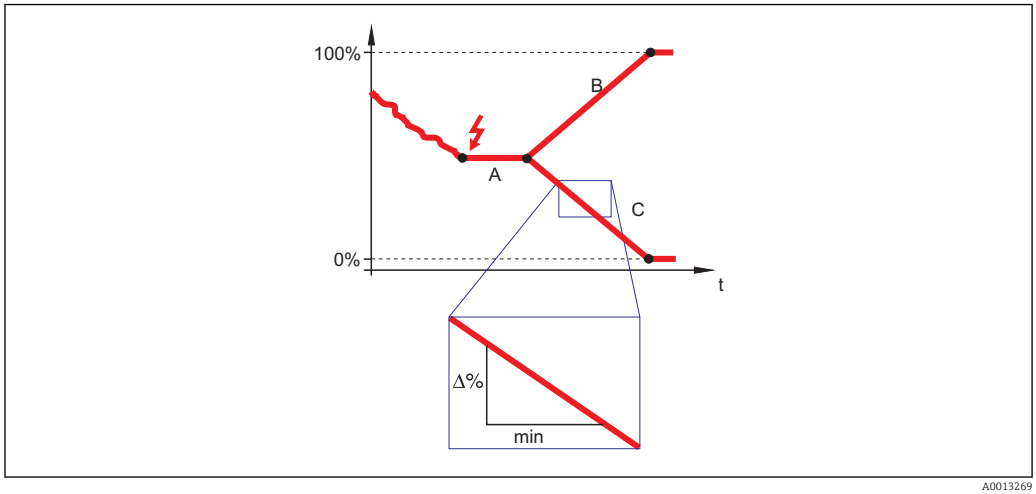
Prerequisite **Output echo lost (→ 117) = Ramp echo lost**

Description Define the slope of the ramp in the case of a lost echo.

User entry Signed floating-point number

Factory setting 0.0 %/min

Additional information



A Delay echo lost (→ 118)
B Ramp echo lost (→ 118) (positive value)
C Ramp echo lost (→ 118) (negative value)

- The unit for the slope of the ramp is "percentage of the measuring range per minute" (%/min).
- For a negative slope of the ramp: The measured value is continuously decreased until it reaches 0%.
- For a positive slope of the ramp: The measured value is continuosly increased until it reaches 100%.

Delay echo lost

Navigation Expert → Sensor → Safety sett. → Delay echo lost (1193)

Description Define the delay in the case of an echo loss.

User entry 0 to 99 999.9 s

Factory setting 60.0 s

Additional information After an echo loss, the device waits for the time specified in this parameter before reacting as specified in the **Output echo lost** parameter (→ 117). This helps to avoid interruptions of the measurement by short-term interferences.

Safety distance

Navigation Expert → Sensor → Safety sett. → Safety distance (1093)

Description Define safety distance.

User entry −200 to 200 m

Factory setting 0 m

Additional information The safety distance is measured from the reference point of the measurement (lower edge of the flange or threaded connection). The safety distance can be used to generate a warning before the level rises into the blocking distance. The **In safety dist.** parameter (→ 119) defines the reaction of the device if the level rises into the safety distance.

In safety dist.

Navigation Expert → Sensor → Safety sett. → In safety dist. (1018)

Description Define reaction if the level rises into the safety distance.

Selection
- Off
- Alarm
- Warning
- Self holding

Factory setting Warning

Additional information

Meaning of the options
- **Off**
  No reaction if the level rises into the safety distance
- **Alarm**
  The device assumes the alarm state and generates the diagnostic message **In safety dist.**.
- **Warning**
  The device assumes the warning state and generates the diagnostic message **In safety dist.**.
- **Self holding**
  The device assumes the defined alarm state. Additionally, the diagnostic message **In safety dist.** is generated. If the level drops out of the safety distance, the alarm remains active. The measurement is continued only after a reset of the self holding via the **Acknowl. alarm** parameter (→ 119).

Acknowl. alarm

Navigation Expert → Sensor → Safety sett. → Acknowl. alarm (1130)

Prerequisite **In safety dist. (→ 119)** = **Self holding**

Description Reset the self holding alarm of the device.

Selection
- No
- Yes

Factory setting No

Additional information

Meaning of the options
- **No**
  The alarm is **not** rest.
- **Yes**
  The alarm is reset. The measurement is resumed.

4.4.12 "Env. curve" submenu

The **Env. curve** submenu (→ 122) is only available on the display module (not in FieldCare). It is used to display the envelope curve on the display module. When operating via FieldCare, the envelope curve can be displayed in the envelope curve editor (**Device Operation → Device Functions → Additional Functions → Envelope Curve**).

Description of parameters

Navigation Expert → Sensor → Env. curve

Env. curve

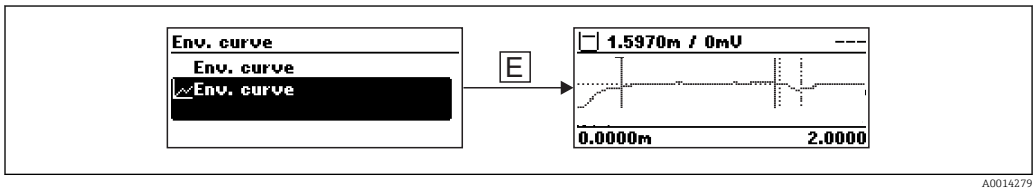
Navigation Expert → Sensor → Env. curve → Env. curve (1207)

Description Define which curves are included in the envelope curve display on the display module.

Selection
- Env. curve
- Envelope + Map
- Subtr. + Thres.
- Envelope + Ref.

Factory setting Env. curve

Additional information The display of the selected curve is called up as follows:



To quit the envelope curve display, press the "+" and "-" keys simultaneously.

When operating via FieldCare, the envelope curve can be displayed in the envelope curve editor (**Device Operation → Device Functions → Additional Functions → Envelope Curve**).

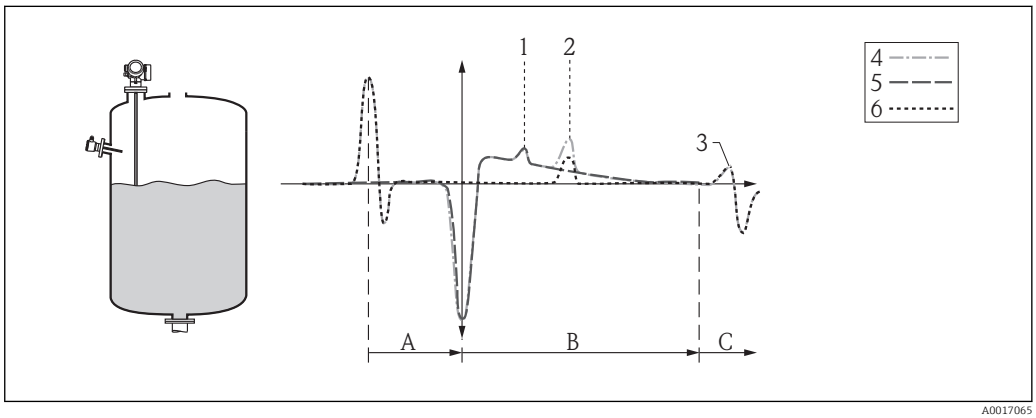
4.4.13 "Mapping" submenu

The mapping is used to suppress static interference signals which may be generatet by internal tank or silo fittings. A mapping curve, representing the envelope curve of an empty tank or silo as precisely as possible, is used for the mapping.

Mapping curve and subtracted curve

After a mapping, the signal evaluation does not use the envelope curve but the subtracted curve, instead:

Subtracted curve = Envelope curve - Mapping curve



36 *Mapping and subtracted curve*

1 Interference echo
2 Level echo
3 End-of-probe echo
4 Envelope curve
5 Mapping curve
6 Subtracted curve
A Internal area (Z distances)
B Level area
C End-of-probe area (EOP)

Static map

The static map is typically used for rod and coax probes. It is recorded during the commissioning. It is essential that the probe is completely uncovered when recording the map.

When recording a new static envelope curve, the previous curve is deleted.

Dynamic map

The dynamic map is, for example, used for probes with a reference signal for gas phase compensation. In the case of a static map this reference signal would be suppresed and would no longer be visible in the subtracted curve.

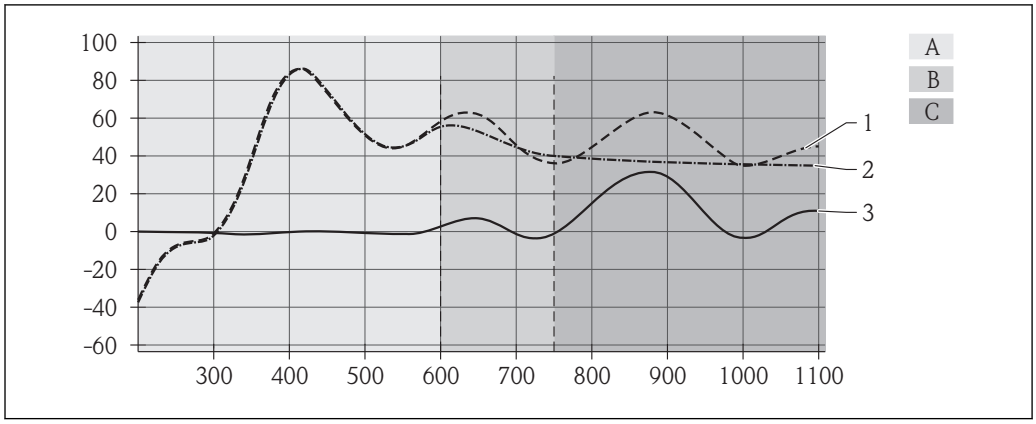
Before the dynamic mapping curve can be used, a static map - if present - must be deleted.

The dynamic map continuously adjusts itself to the changing conditions within the vessel. An averaging width of 1 500 mm (60 in) is used for this. This prevents the dynamic map from suppressing the acutal level echo.

Combined map

If it is not possible to record the map with the probe being completely uncovered (e.g. because the vessel can not be completely emptied during the commissioning procedure), a combined map can be used instead. In this case, a static map is only recorded for the upper part of the probe (defined by the **Map. end point** parameter (→ 129)). In the lower

part, a dynamic map is used. Both curves are connected by an interpolation area to ensure a smooth transition.



37 Combined mapping curve

1 Envelope curve
2 Mapping curve
3 Subtracted curve
A Static area
B Transition area (interpolation)
C Dynamic area

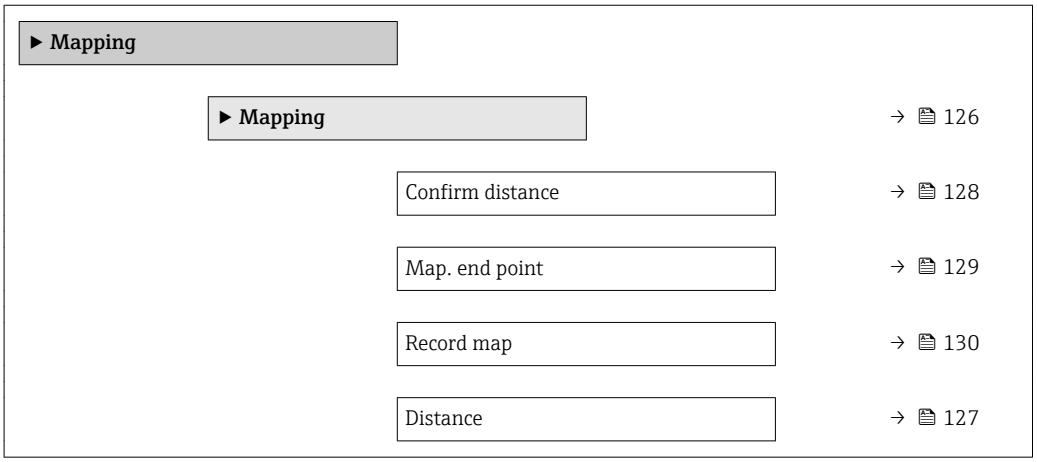
The initial map

An initial map is stored in the device. This map is active under the following conditions:
- if no static map has been recorded,
- if the static map has been deactivated,
- if the static map has been deleted.

The form of the initial map depends on a number of settings of the basic calibration and is designed to suppress typical interferences in the upper part of the probe. It can not be changed by the user.

Structure of the submenu on the local display

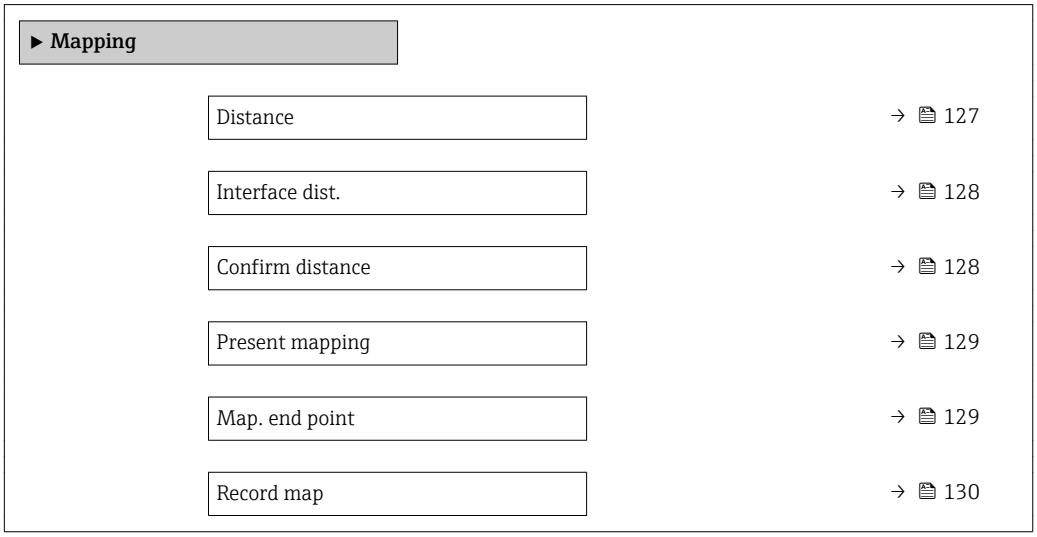
Navigation Expert → Sensor → Mapping



Structure of the submenu in an operating tool

Navigation Expert → Sensor → Mapping

"Mapping" submenu



Description of parameters

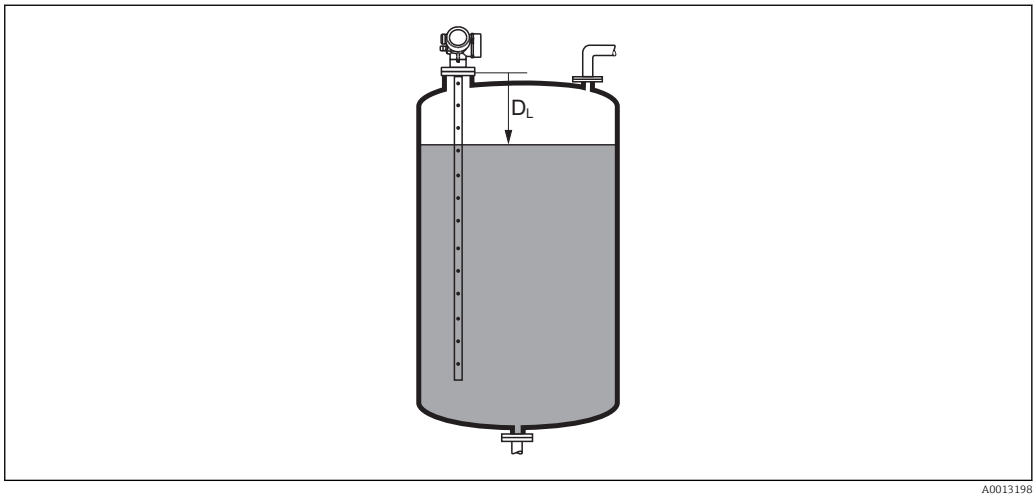
Navigation Expert → Sensor → Mapping

Distance

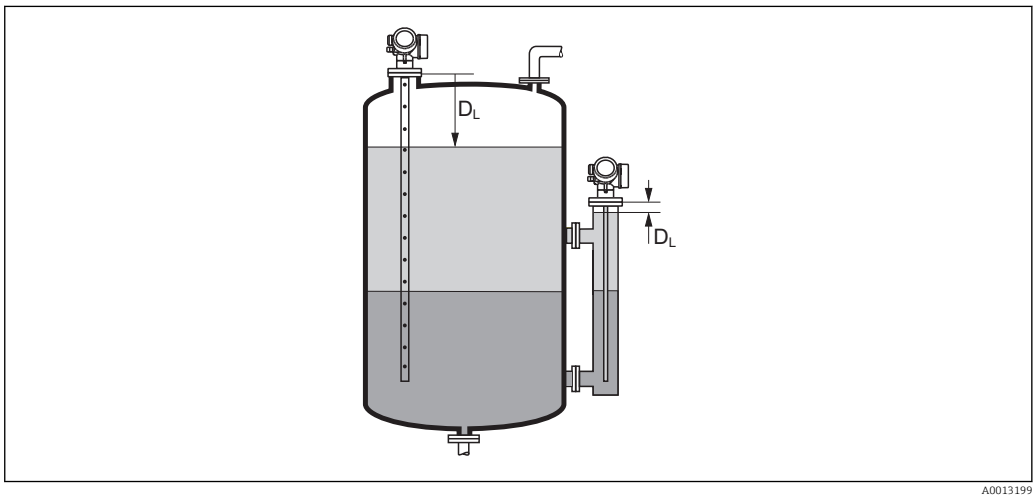
Navigation Expert → Sensor → Mapping → Distance (1124)

Description Displays the measured distance D_L between the reference point (lower edge of the flange or threaded connection) and the level.

Additional information



38 *Distance for liquid measurements*



39 *Distance for interface measurements*

The unit is defined in the **Distance unit** parameter (→ 50).

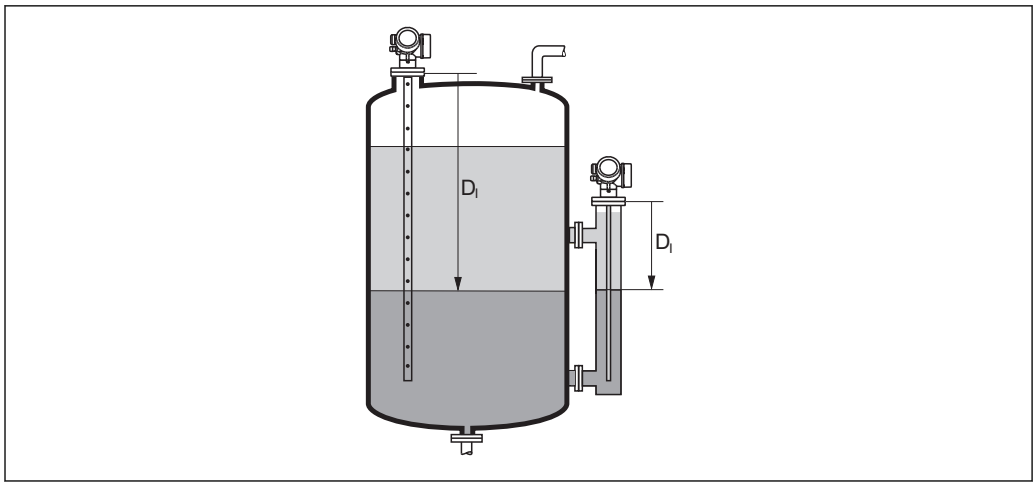
Interface dist.

Navigation Expert → Sensor → Mapping → Interface dist. (1067)

Prerequisite **Operating mode (→ 50)** = **Interface** or **Interf.+capacit.**

Description Displays the measured distance D_I between the reference point (lower edge of flange or threaded connection) and the interface.

Additional information



A0013202

The unit is defined in the **Distance unit** parameter (→ 50).

Confirm distance

Navigation Expert → Sensor → Mapping → Confirm distance (1045)

Description Specify, whether the measured distance matches the real distance.

Depending on the selection the device automatically sets the range of mapping.

Selection

- Manual map
- Distance ok
- Distance unknown
- Dist. too small
- Distance too big
- Tank empty
- Delete map

Factory setting Distance unknown

Additional information

Meaning of the options

- **Manual map**
  To be selected if the range of mapping is to be defined manually in the **Map. end point** parameter (→ 129). In this case it is not necessary to confirm the distance.
- **Distance ok**
  To be selected if the measured distance matches the actual distance. The device performs a mapping.
- **Distance unknown**
  To be selected if the actual distance is unknown. A mapping can not be performed in this case.
- **Dist. too small**
  To be selected if the measured distance is smaller than the actual distance. The device searches for the next echo and returns to the **Confirm distance** parameter. The distance is recalculated and displayed. The comparison must be repeated until the displayed distance matches the actual distance. After this, the recording of the map can be started by selecting **Distance ok**.
- **Distance too big** [5)]
  To be selected if the measured distance exceeds the actual distance. The device adjusts the signal evaluation and returns to the **Confirm distance** parameter. The distance is recalculated and displayed. The comparison must be repeated until the displayed distance matches the actual distance. After this, the recording of the map can be started by selecting **Distance ok**.
- **Tank empty**
  To be selected if the tank is completely empty. The device records a mapping covering the complete measuring range.
- **Factory map**
  To be selected if the present mapping curve (if one exists) is to be deleted. The device returns to the **Confirm distance** parameter and a new mapping can be recorded.

When operating via the display module, the measured distance is displayed together with this parameter for reference purposes.

For interface measurements the distance always refers to the toatal level (not the interface level).

If the teaching procedure with the **Dist. too small** option or the **Distance too big** option is quit before the distance has been confirmed, a map is **not** recorded and the teaching procedure is reset after 60 s.

Present mapping

Navigation Expert → Sensor → Mapping → Present mapping (1182)

Description Indicates up to which distance a mapping has already been recorded.

Map. end point

Navigation Expert → Sensor → Mapping → Map. end point (1022)

Prerequisite **Confirm distance (→ 128)** = **Manual map** or **Dist. too small**

5) Only available for "Expert → Sensor → Echo tracking → **Evaluation mode** parameter (→ 140)" = "Short time hist." or "Long time hist."

Description Specify new end of the mapping.

User entry 0 to 200 000.0 m

Factory setting 0.1 m

Additional information This parameter defines up to which distance the new mapping is to be recorded. The distance is measured from the reference point, i.e. from the lower edge of the mounting flange or the threaded connection.

For reference purposes the **Present mapping** parameter (→ 129) is displayed together with this parameter. It indicates up to which distance a mapping has already been recorded.

Record map

Navigation Expert → Sensor → Mapping → Record map (1069)

Prerequisite **Confirm distance (→ 128)** = **Manual map** or **Dist. too small**

Description Start recording of the map.

Selection
- No
- Record map
- Delete map

Factory setting No

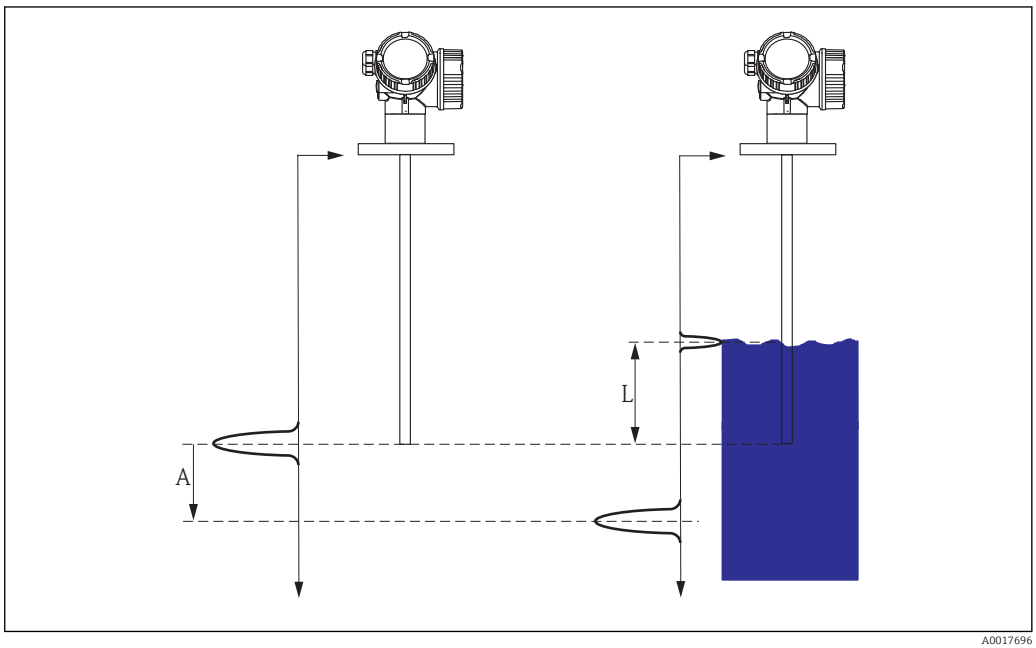
Additional information

Meaning of the options
- **No**
  The map is not recorded.
- **Record map**
  The map is recorded. After the recording is completed, the new measured distance and the new mapping range appear on the display. When operating via the local display, these values must be confirmed by pressing ☑.
- **Delete map**
  The mapping (if one exists) is deleted and the device displays the recalculated measured distance and the mapping range. When operating via the local display, these values must be confirmed by pressing ☑.

4.4.14 "EOP evaluation" submenu

As an alternative to evaluating the direct level signal, Levelflex can calculate the level via the shift of the end-of-probe signal (EOP). Details on the EOP evaluation are configured in the **EOP evaluation** submenu.

Shift of the end-of-probe signal (EOP)



40 *Shift of the end-of-probe signal (EOP) depending on the level*

A *EOP shift*
L *Level*

When evaluating the end-of-probe signal, you make use of the fact that electromagnetic pulses propagate more slowly in a medium than in air. As a consequence the end-of-probe signal moves downwards when the level is increased. By inverting this relationship one can calculate the level *L* from the end-of-probe shift *A*:

$L = A / (\mathrm{SQRT}(DK) - 1)$

Where *DC* is the dielectric constant of the medium.

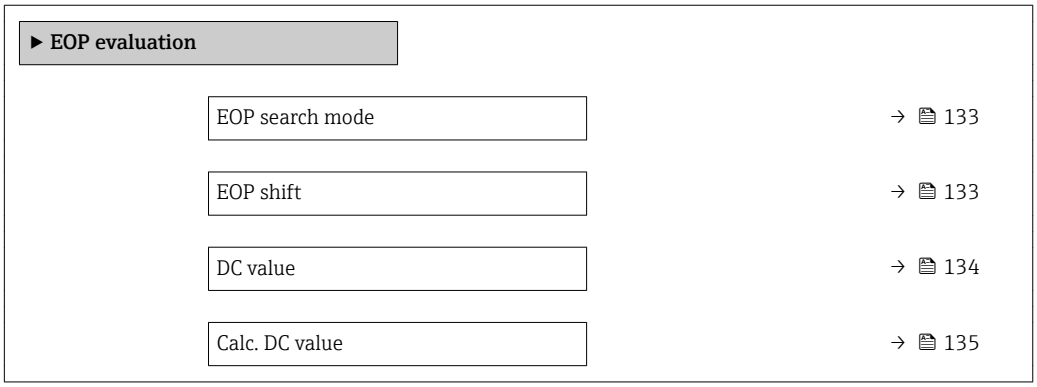
If both, the level signal and the end-of-probe signal are known, the dielectric constant *DC* can be calculated:

$DK = (A/L + 1)^2$

The calcluated DC value is displayed in the **Calc. DC value** parameter (→ 59).

Structure of the submenu

Navigation Expert → Sensor → EOP evaluation



Description of parameters

Navigation Expert → Sensor → EOP evaluation

EOP search mode

Navigation
Expert → Sensor → EOP evaluation → EOP search mode (1026)
Expert → Sensor → EOP evaluation → EOP search mode (1026)

Prerequisite
Operating mode parameter (→ 50) = **Level**

Description
Select method for the detection of the end-of-probe signal.

Selection
- Empty recog.only
- Negative EOP
- Positive EOP
- Neg.EOPhigh

Factory setting
Negative EOP

Additional information
Meaning of the options
- **Empty recog.only**
  Positive and negative end-of-probe signals are searched for. However, the level is not calculated from the end-of-probe signal.
  – If no level signal is present and if the end-of-probe signal is within the range defined in the **EOPrange up.area** parameter, the level is set to 0%, which means an empty tank or silo is assumed.
  – If no level signal is present and if the end-of-probe-signal is beyond the range defined in the **EOPrange up.area** parameter, an echo loss is reported.
- **Negative EOP**
  Only negative end-of-probe signals are searched for. This is the correct option if the probe end is insulated.
- **Positive EOP**
  Only positive end-of-probe signals are searched for. This is the correct option if the end of the probe is connected to ground.
- **Neg.EOPhigh**
  The resolution at the end of the probe is improved by a deconvolution algorithm. This is only possible if the end-of-probe postion in the case of an empty tank has been stored by selecting the **Tank empty** option in the **Confirm distance** parameter (→ 128).

EOP shift

Navigation
Expert → Sensor → EOP evaluation → EOP shift (1027)
Expert → Sensor → EOP evaluation → EOP shift (1027)

Prerequisite
EOP level eval. ≠ **Off**

Description
Displays the current shift of the end-of-probe signal as compared to the empty vessel.

DC value

Navigation Expert → Sensor → EOP evaluation → DC value (1201)

Description
- For level measurements:
  Specify dielectric constant ε_r.
- For interface measurements:
  Specify dielectric constant ε_r of the upper medium.

User entry Signed floating-point number

Factory setting Dependent on the following parameters:
- Operating mode (→ 50)
- Medium property (→ 57)
- Medium type (→ 56)
- Bin type (→ 51)or Tank type (→ 51)

Additional information *Dependence of the factory settings on other parameters*

For "Operating mode" = "Level"

Medium property (→ 57)	Medium type (→ 56)	Bin type (→ 51) or Tank type (→ 51)	DC value
Unknown	Solid	Bin type (→ 51) • Aluminium • Plastic wood	1.9
		Bin type (→ 51) • Concrete • Metallic	1.6
	Liquid	Tank type (→ 51) Coaxial	1.4
		Any other tank type	1.9
DC 1.4 ... 1.6	Solid	Bin type (→ 51) • Concrete • Aluminium • Plastic wood	1.6
		Bin type (→ 51) Metallic	1.4
	Liquid	Tank type (→ 51) • Non metallic • Mounted outside	1.6
		Any other tank type	1.4
DC 1.6 ... 1.9			1.6
DC 1.9 ... 2.5			1.9
DC 2.5 ... 4			2.5
DC 4 ... 7			4
DC 7 ... 15			7
DC > 15			15

For "Operating mode" = "Interf.+capacit." or "Interface":
DC value = 1.9

As the value defines the echo threshold, it may not exceed the actual DC of the medium. Dielectric constants above DC = 15 have only a very limited influence on the echo threshold.

Calc. DC value

Navigation
Expert → Sensor → EOP evaluation → Calc. DC value (1118)
Expert → Sensor → EOP evaluation → Calc. DC value (1118)

Prerequisite
EOP level eval. = **Automatic DC**

Description
- For level measurements:
  Displays calculated dielectric constant ε_r.
- For interface measurements:
  Displays calculated dielectric constant ε_r or the upper medium.

Additional information
The exact meaning of this parameter is dependent on further settings:
- **Operating mode (→ 50)** = **Level**:
  Displays the dielectric constant which is calculated from the end-of-probe signal and the level [6)]
- **Operating mode (→ 50)** = **Interface** or **Interf.+capacit.**:
  - For **Interface prop. (→ 146)** = **Special: auto DC**:
    Automatically calculated DC of the upper medium
  - In any other case:
    Identical to the **DC value** parameter (→ 58)

6) The correct calculation of the dielectric constant is only possible for media with a small dielectric constant and weak signal damping, for which the level signal and the end-of-probe signal can be evaluated simultaneously. Among these media are for example oil, solvents and synthetic granules.

4.4.15 "Echo tracking" submenu

The echo tracking algorithm takes into account the change in time of the individual echoes when evaluating the envelope curve. This improves the allocation of the echoes to the level or interface signal. Different types of echo tracking can be selected in the **Evaluation mode** parameter (→ 140). A number of further parameters is used to configure the echo tracking more precisely.

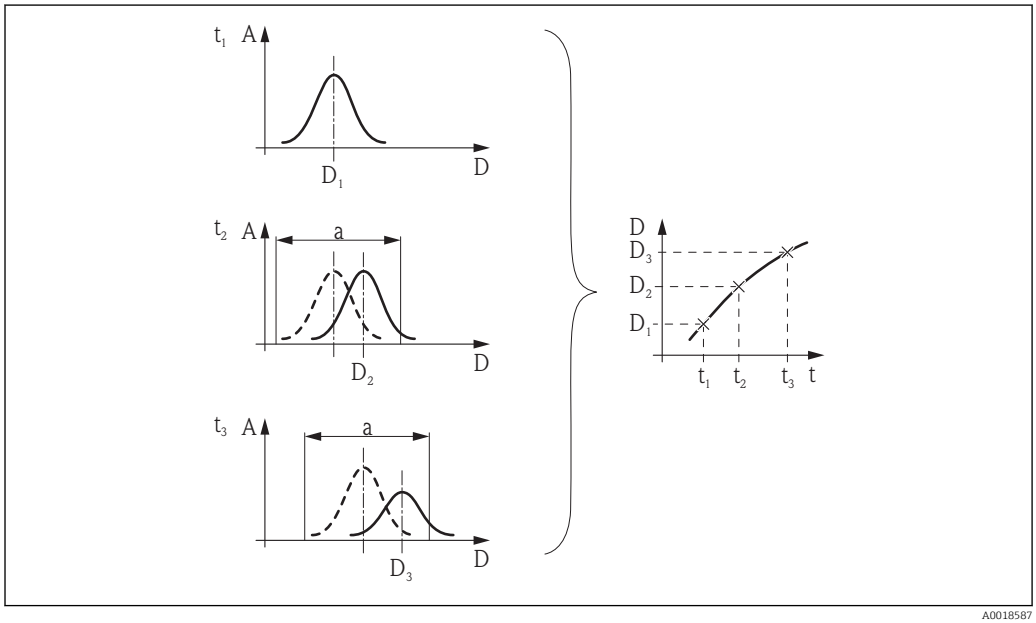
"Evaluation mode" = "History off"

The envelope curve is evaluated statically.

"Evaluation mode" = "Short time hist."

The static envelope curve evalauation is taken as a starting point.

The position of the individual echoes is tracked. The track contains the position, the velocity, the relative and the absolute echo amplitude. Normally the strongest echo within a search window is selected and allocated to the track.



41 *Definition of a track: In a new envelope curve, the echo is searched for in a window of width "a" centered around the echo position in the previous envelope curve. The change of the echo position in the course of time defines the track.*

In this evaluation mode it is possible to activate the moving track recognition (**Mov.track recog.** parameter).

The moving track recognition is used to distinguish the level echo from interference echoes. It makes use of the fact that an echo which moves in one direction for a certain time is likely to be the level echo. Interference echoes, on the other hand, normally stay at the same position within the envelope curve.

If the moving track recognition is switched on, this distinction is used as an additional criterion to identify the level echo.

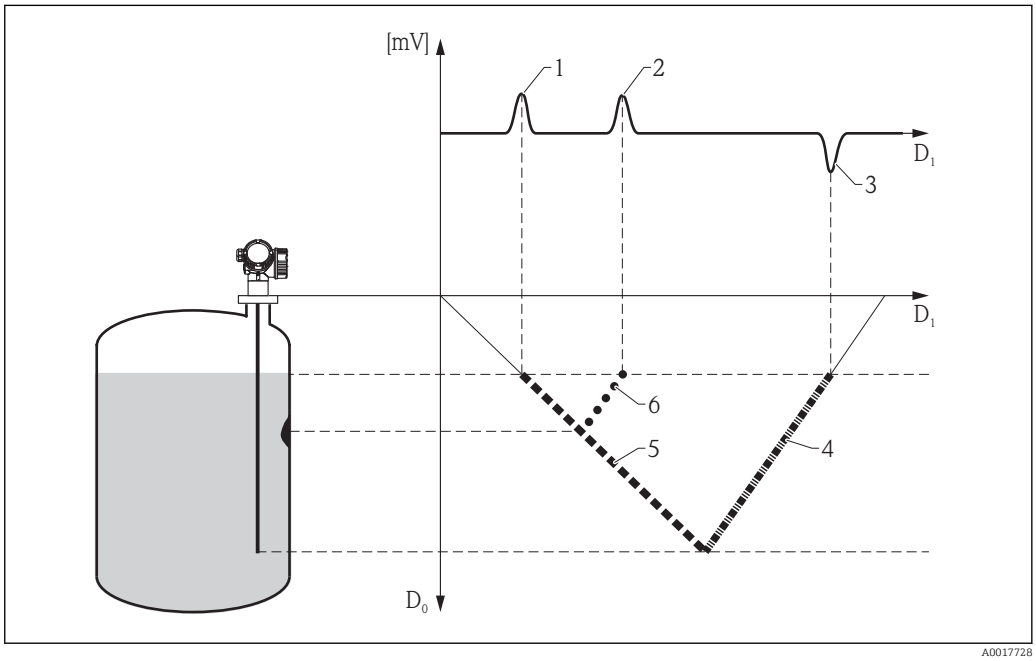
"Evaluation mode" = "Long time hist."

The **Long time hist.** option is not available for interface measurements.

A so-called tank history is used for the determination of the level and a consistency check of the echoes.

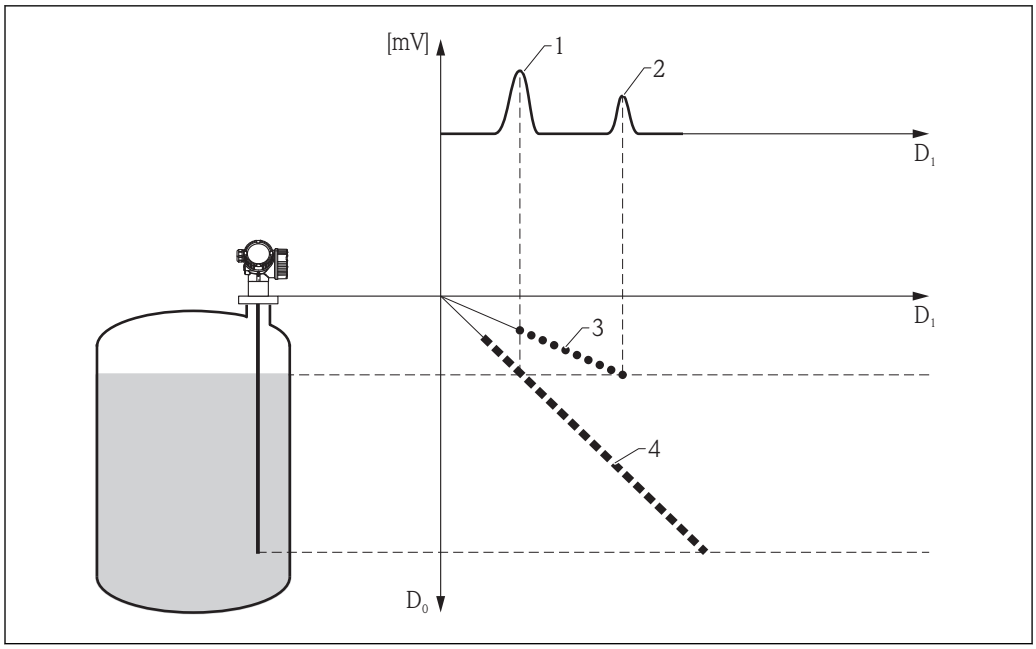
For a given tank with a given medium, the positions of the level, interface, multiple and end-of-probe or tank bottom echoes are in a defined relation to each other. This relationship is recorded during the operation of the device and stored in the tank history. On the basis of this tank history, echoes can be reliably allocated, even if one echo is lost temporarily or if the device was switched off for a while.

Schematic exmaples



42 Example 1: Tank history with interference echo and end of probe echo (small DC values)

D0 Actual level distance
D1 Distance of the signal in the envelope curve
1 Level echo
2 Interference echo
3 End-of-probe echo
4 Track "End-of-probe echo" (stored in the tank history)
5 Track "Level echo" (stored in the tank history)
6 Track "Interference echo" (stored in the tank history)

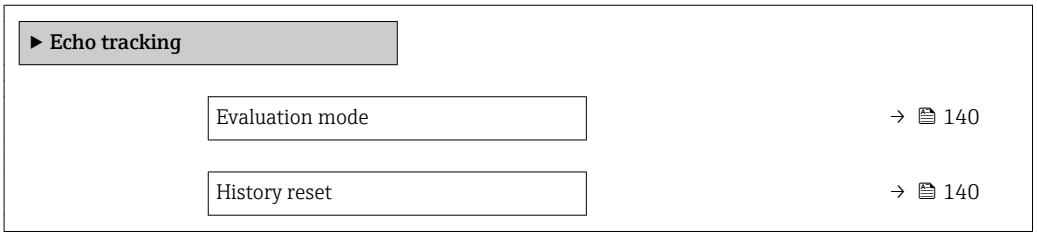


43 *Example 2: Tank history with a multiple echo (large DC values)*

D0 Actual level distance
D1 Distance of the signal in the envelope curve
1 Level echo
2 Multiple echo
3 Track "Multiple echo" (stored in the tank history)
4 Track "Level echo" (stored in the tank history)

Structure of the submenu

Navigation Expert → Sensor → Echo tracking



Description of parameters

Navigation Expert → Sensor → Echo tracking

Evaluation mode

Navigation Expert → Sensor → Echo tracking → Evaluation mode (1112)

Description Select evaluation mode for echo tracking.

Selection
- History off
- Short time hist.
- Long time hist.

Factory setting
- For level measurements:
  Long time history
- For interface measurements:
  Short time history
- Exceptions:
  - For FMP54 and any FMP5x with center washer:
    Short time history
  - For **Tank type (→ 51)** = **Bypass / pipe**:
    Short time history
  - If the gas phase compensation is active, i.e. **GPC mode (→ 105)** ≠ **Off**:
    History off
  - For **Process property (→ 52)** = **Very fast > 100 m (333 ft) /h** or **No filter / test**:
    History off

Additional information

Meaning of the options
- **History off**
  The envelope curve is evaluated only statically.
- **Short time hist.**
  In addition to the static algorithms a dynamic echo trace is continuously created.
- **Long time hist.**
  (Only available for level measurements)
  In addition to the static algorithms and the dynamic echo trace a tank trace is continuously generated. Using the tank trace the device can determine the level even if the level echo ist lost temporarily.

- The **Long time hist.** option is not available for interface measurements.
- The **Long time hist.** option is not recommended if there are substantial changes of the medium or process conditions within a short period of time (e.g. in the case of changing dielectric constants or boiling media).

History reset

Navigation Expert → Sensor → Echo tracking → History reset (1145)

Description Reset history of the echo and tank tracking.

Selection
- Reset done
- Restart tracking
- Delete history

Factory setting
Reset done

Additional information
Meaning of the options
- **Reset done**
  Does not initiate an action but is only a display option. It is displayed as soon as the reset operation has been accomplished.
- **Restart tracking**
  The echo tracking is reset. The tank trace, however, is maintained.
- **Delete history**
  The echo tracking and tank trace are reset.

4.4.16 "Interface" submenu

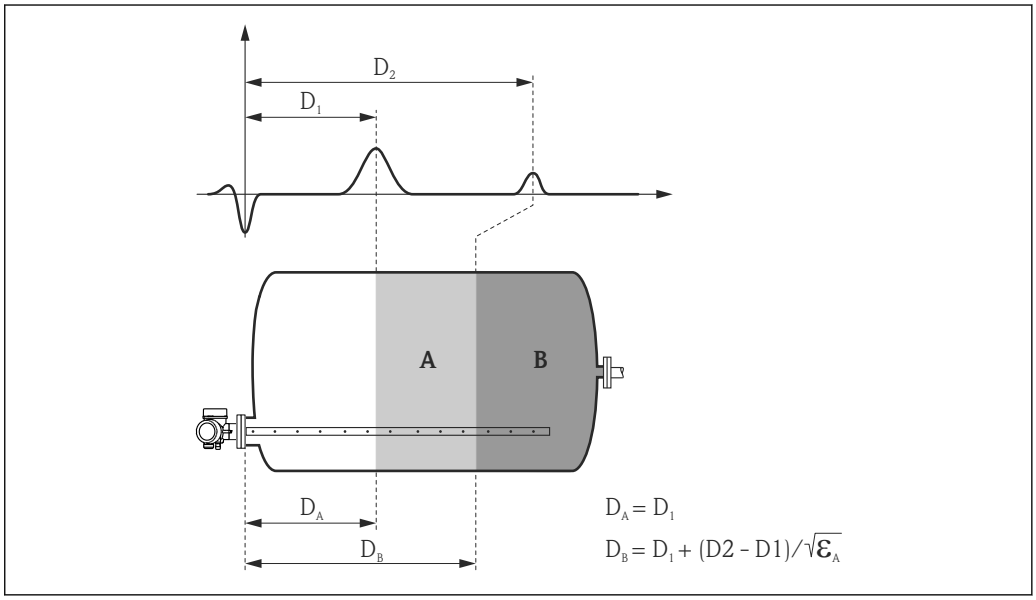
Operating mode (→ 📄 50)	Evaluated signals	available for	Description
Interface	Signal of the guided radar	FMP51	→ 📄 143

Interface measurement with guided radar (without capacitance measurement)

Basic principles

When the high-frequency pulses hit the surface of the medium, only a percentage of the transmission pulse is reflected. In the case of media A with a low dielectric constant ε_A, in particular, the other part penetrates the medium. The pulse is reflected once more at the interface point to a second medium, B, with a higher dielectrdic constant ε_B. Thus, the envelope curve contains a level echo D_1 as well as an interface echo D_2.

When evaluating the interface echo, Levelflex must take into account the fact that electromagnetic pulses propagate slower in a medium than in air. Therefore, the interface echo appears shifted into the direction of larger distances. Using the dielectric constant of the upper medium, Levelflex can automatically compensate for this shift:



44 *Interface measurement with the guided radar*

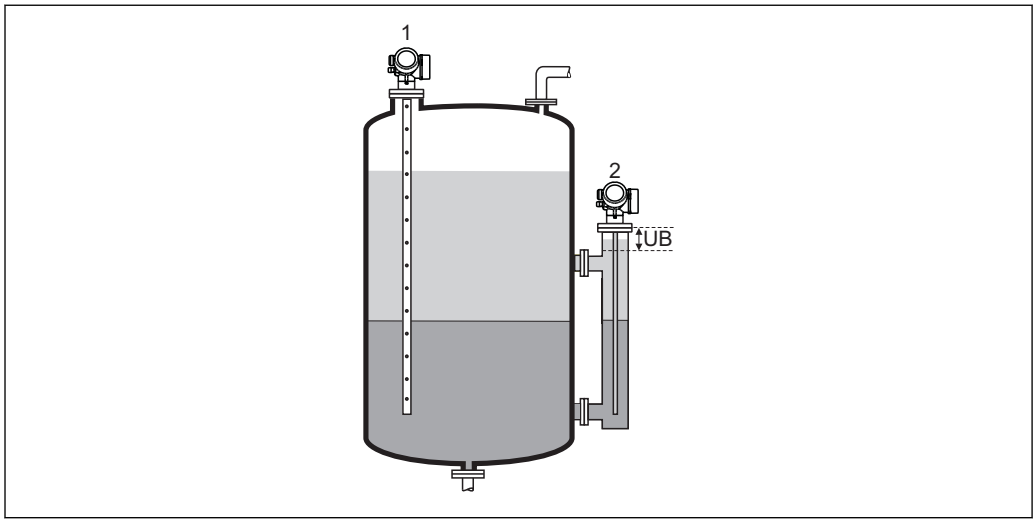
If an interface measurement is activated, **Evaluation mode (→ 140)** = **Short time hist.** is the only option. The **Long time hist.** option can not be used in combination with an interface meaurement.

Prerequisites for an interface measurement

- The dielectric constant of the upper medium must be constant and known.
- Dielectric constant of the upper medium: $\varepsilon_A \leq 10$
- Dielectric constant of the lower medium: $\varepsilon_B \geq \varepsilon_A + 10$

Tank level

For interface measurements it is important whether the container is partially filled or fully flooded. This must be specified by the user in the **Tank level** parameter (→ 🖹 146) :

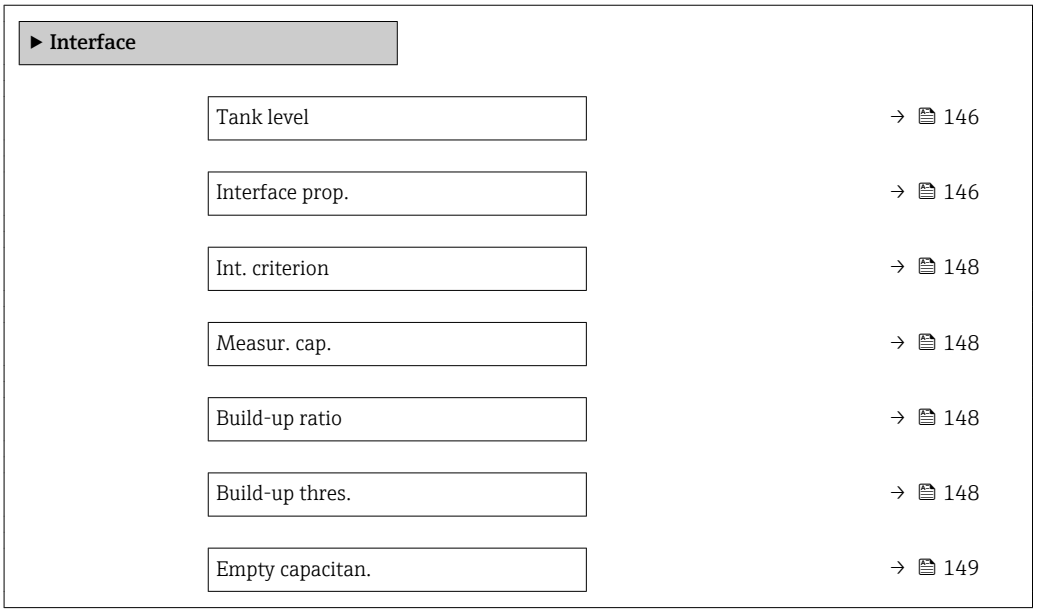


1 Partially filled
2 Fully flooded
UB Blocking dist. (→ 🖹 99)

- **Tank level (→ 🖹 146)** = **Partially filled**
  In this case the device looks for two signals: the interface echo and the level echo; if required, the end-of-probe signal is used for signal evaluation, too → 🖹 131.
- **Tank level (→ 🖹 146)** = **Fully flooded**
  This is typically used for bypass applications. In this case, the device searches for the interface echo only; if required, the end-of-probe signal is used for signal evaluation, too → 🖹 131. If this option is selected, the total level must always be within the upper blocking distance (UB) in order to avoid that it is mistaken for the interface signal.

Structure of the submenu

Navigation Expert → Sensor → Interface



Description of parameters

Navigation Expert → Sensor → Interface

Tank level

Navigation Expert → Sensor → Interface → Tank level (1111)

Prerequisite **Operating mode (→ 50) = Interface**

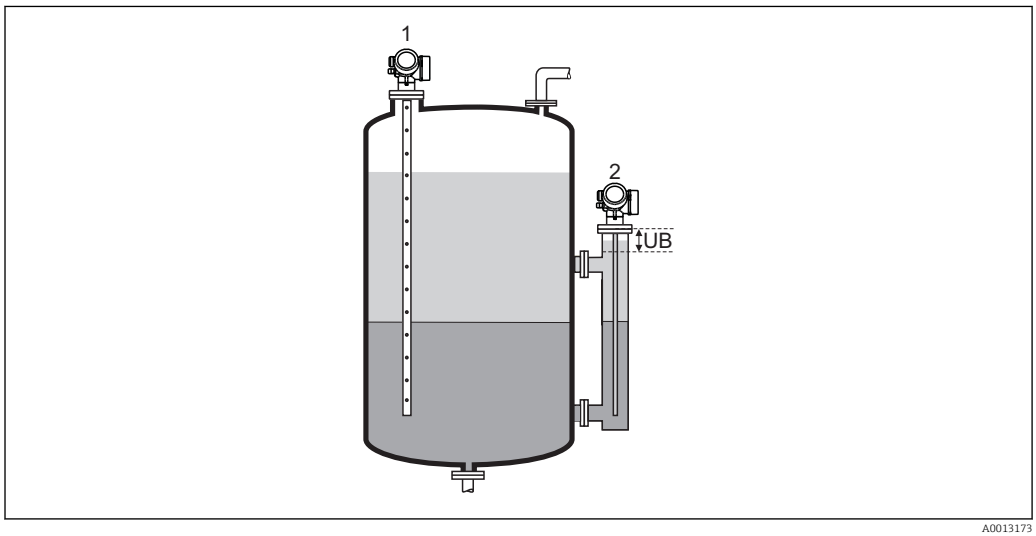
Description Specify whether the tank or bypass is completely flooded or not.

Selection
- Partially filled
- Fully flooded

Factory setting Partially filled

Additional information

Meaning of the options
- **Partially filled**
  The device searches for 2 echo signals, one for the interface and one for the total level.
- **Fully flooded**
  The device searches for the interface level only. With this setting it is essential that the upper level signal always is within the upper blocking distance (UB) in order to avoid that it is evaluated by mistake.



1 Partially filled
2 Fully flooded
UB Upper blocking distance

Interface prop.

Navigation Expert → Sensor → Interface → Interface prop. (1107)

Prerequisite **Operating mode (→ 50) = Interf.+capacit.**

Description

Select interface property.

The interface property determines how the Guided Radar and the Capacitance Measurement interact.

Selection

- Special: auto DC
- Build up
- Standard
- Oil/Watercondens

Factory setting

Standard

Additional information

Meaning of the options

- **Special: auto DC**
  - Condition:
    The specific capacitance (pF/m) is known. [7)]
  - Signal evaluation:
    As long as a clear interface is detected, both the total and the interface level are determined via the Guided Radar. The dielectric constant of the upper medium is continuously adjusted. If an emulsion layer is present, the total level is determined via the Guided Radar whereas the interface level is determined via the Capacitance Measurement.
- **Build up**
  - Condition:
    The dielectric constant of the upper medium and the specific capacitance (pF/m) are known. [7)]
  - Signal evaluation:
    As long as a clear interface is detected, the interface level is determined via the Guided Radar as well as via the Capacitance Measurement. If these two values start to diverge from each other due to build-up formation, an error message is generated. If an emulsion layer is present, the total level is determined via the Guided Radar whereas the interface level is determined via the Capacitance Measurement.
- **Standard**
  - Condition:
    The dielectric constant of the upper medium is known.
  - Signal evaluation:
    As long as a clear interface is detected, the specific capacitance (pF/m) is continuously adjusted. Therefore build-up has only little influence on the measurement. If an emulsion layer is present, the total level is determined via the Guided Radar whereas the interface level is determined via the Capacitance Measurement.
- **Oil/Watercondens**
  - Condition:
    The dielectric constant of the upper medium and the specific capacitance (pF/m) are known. [7)]
  - Signal evaluation:
    The total level is always determined via the Guided Radar. The interface level is always determined via the Capacitance Measurement.

7) The specific capacitance of the media depends on the DC value and the geometry of the probe, which may differ noticeably. For rod probes < 2 m, the probe geometry is measured after production and the resulting specific capacitance for conductive media is preset on delivery.

Int. criterion

Navigation
Expert → Sensor → Interface → Int. criterion (1184)
Expert → Sensor → Interface → Int. criterion (1184)

Prerequisite
Operating mode (→ 50) = **Interface** or **Interf.+capacit.**

Description
Displays the threshold (in mV) for the recognition of the interface signal.

Measur. cap.

Navigation
Expert → Sensor → Interface → Measur. cap. (1066)
Expert → Sensor → Interface → Measur. cap. (1066)

Prerequisite
Operating mode (→ 50) = **Interf.+capacit.**

Description
Displays the measured capacitance (pF).

Build-up ratio

Navigation
Expert → Sensor → Interface → Build-up ratio (1210)
Expert → Sensor → Interface → Build-up ratio (1210)

Prerequisite
Interface prop. (→ 146) = **Build up**

Description
Indicates the relative deviation between the interface distance measured by the radar and the capacitance, respectively.

Additional information
Formula by which this value is calculated:

$| (D_{Radar} - D_{Capa}) / D_{Radar} |$

If this ratio exceeds the value defined in the **Build-up thres.** parameter (→ 148), an error message is generated.

Build-up thres.

Navigation
Expert → Sensor → Interface → Build-up thres. (1211)
Expert → Sensor → Interface → Build-up thres. (1211)

Prerequisite
Interface prop. (→ 146) = **Build up**

Description
Define threshold for build-up detection.

User entry
Signed floating-point number

Factory setting 0.1

Additional information If the **Build-up ratio** parameter (→ 148) exceeds the value specified in this parameter, the corresponding error message is generated.

Empty capacitan.

Navigation
Expert → Sensor → Interface → Empty capacitan. (1122)
Expert → Sensor → Interface → Empty capacitan. (1122)

Prerequisite **Operating mode (→ 50)** = **Interf.+capacit.**

Description Specify capacitance for the empty tank.

User entry 0.0 to 10 000.0 pF

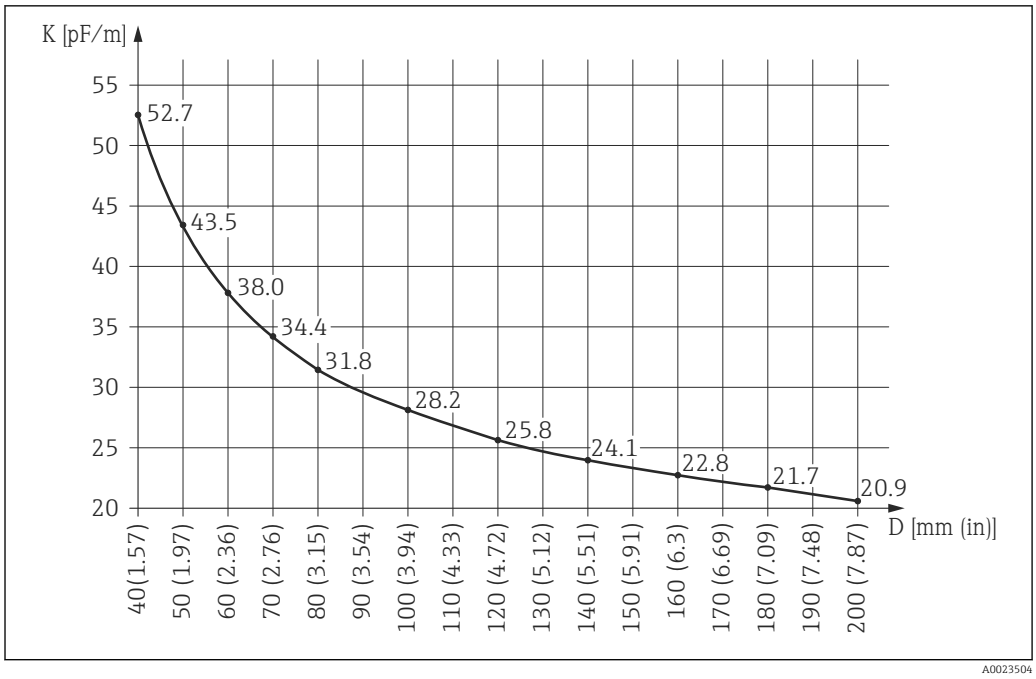
Factory setting 0.0 pF

Additional information Normally, the device determines the empty capacitance automatically if during commissioning **Confirm distance (→ 128)** = **Tank empty** is selected. In exceptional cases - if emptying the tank during commissioning is impossible - a calculated value can be entered manually.

Calculation of the empty capacitance

1. Read the empty capacitance per meter from the diagram.
2. Multiply the read value by the length of the probe.
3. Add the result to the basic capacitance of the device according to the following table:

Device version	Basic capacitance
Compact device	29.5 pF
Feature 600 "Probe Design", option model MB "Sensor remote, 3m/9ft cable, detachable +mounting bracket"	278.4 pF



45 Empty capacitance per meter according to bypass or stilling well diameter

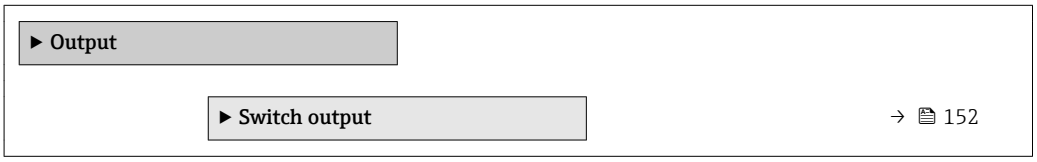
D Bypass or stilling well diameter
K Capacitance per meter

4.5 "Output" submenu

The **Output** submenu contains all parameters needed to configure the current and switch outputs.

4.5.1 Structure of the submenu

Navigation Expert → Output

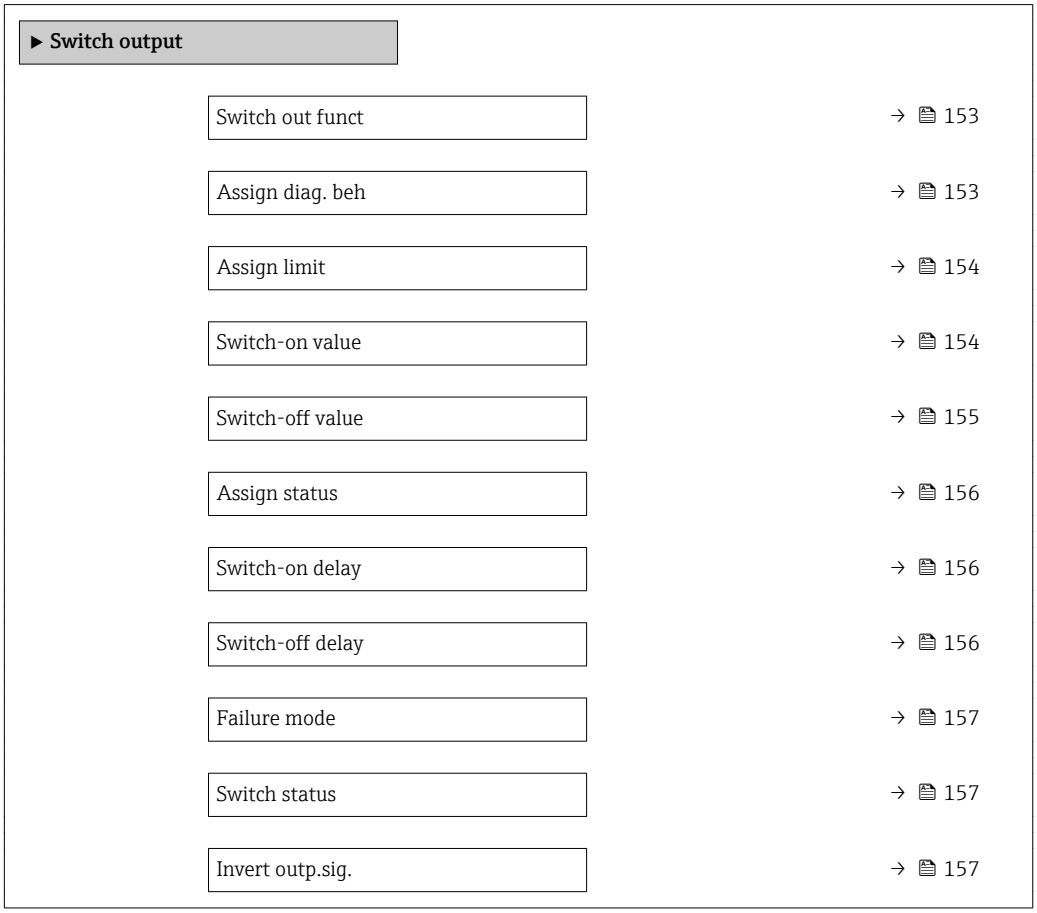


4.5.2 "Switch output" submenu

The **Switch output** submenu is used to configure the switch output of the device.

Structure of the submenu

Navigation Expert → Output → Switch output



Description of parameters

Navigation Expert → Output → Switch output

Switch out funct

Navigation Expert → Output → Switch output → Switch out funct (0481)

Description Select function for switch output.

Selection
- Off
- On
- Diag. behavior
- Limit
- Digital Output

Factory setting Off

Additional information

Meaning of the options
- **Off**
  The output is always open (non-conductive).
- **On**
  The output is always closed (conductive).
- **Diag. behavior**
  The output is normally closed and is only opened if a diagnostic event is present. The **Assign diag. beh** parameter (→ 153) determines for which type of event the output is opened.
- **Limit**
  The output is normally closed and is only opened if a measured variable exceeds or falls below a defined limit. The limit values are defined by the following parameters:
  – **Assign limit (→ 154)**
  – **Switch-on value (→ 154)**
  – **Switch-off value (→ 155)**
- **Digital Output**
  The switching state of the output tracks the output value of a DI function block. The function block is selected in the **Assign status** parameter (→ 156).

The **Off** and **On** options can be used to simulate the switch output.

Assign diag. beh

Navigation Expert → Output → Switch output → Assign diag. beh (0482)

Prerequisite **Switch out funct (→ 153) = Diag. behavior**

Description Select diagnostic behavior for switch output.

Selection
- Alarm
- Alarm or warning
- Warning

Factory setting Alarm

Assign limit

Navigation Expert → Output → Switch output → Assign limit (0483)

Prerequisite **Switch out funct (→ 153) = Limit**

Description Select process variable for limit monitoring.

Selection
- Off
- Level linearized
- Distance
- Interf. lineariz
- Interface dist.
- Thickn.upp.layer
- Terminal volt.
- Electronic temp.
- Measur. cap.
- Relat.echo ampl.
- Rel.interf.ampl.
- Abs. echo ampl.
- Abs.interf.ampl.

Factory setting Off

Switch-on value

Navigation Expert → Output → Switch output → Switch-on value (0466)

Prerequisite **Switch out funct (→ 153) = Limit**

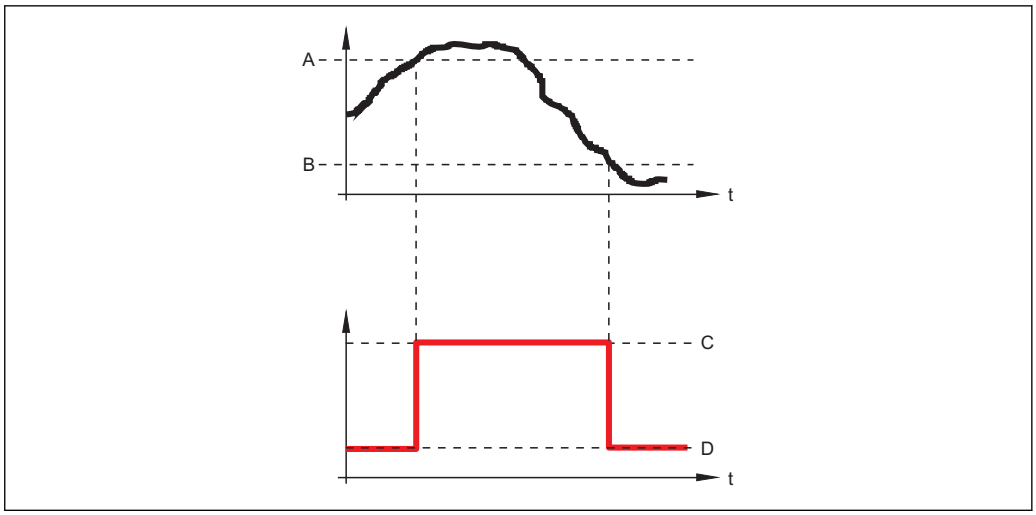
Description Enter measured value for the switch-on point.

User entry Signed floating-point number

Factory setting 0

Additional information The switching behavior depends on the relative position of the **Switch-on value** and **Switch-off value** parameters:

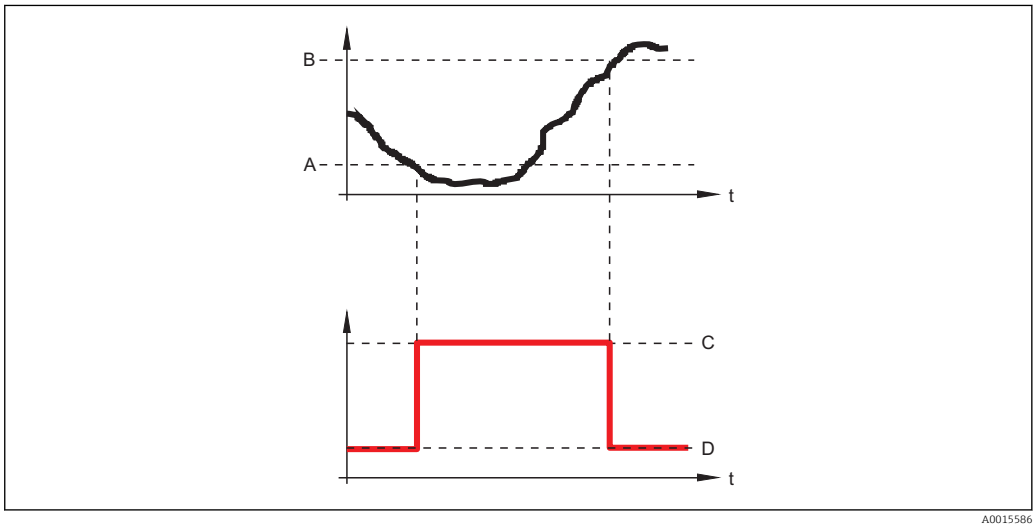
Switch-on value > Switch-off value
– The output is closed if the measured value is larger than **Switch-on value**.
– The output is opened if the measured value is smaller than **Switch-off value**.



A0015585

A Switch-on value
B Switch-off value
C Output closed (conductive)
D Output opened (non-conductive)

Switch-on value < Switch-off value
– The output is closed if the measured value is smaller than **Switch-on value**.
– The output is opened if the measured value is larger than **Switch-off value**.



A0015586

A Switch-on value
B Switch-off value
C Output closed (conductive)
D Output opened (non-conductive)

Switch-off value

Navigation Expert → Output → Switch output → Switch-off value (0464)

Prerequisite **Switch out funct (→ 153) = Limit**

Description Enter measured value for the switch-off point.

User entry Signed floating-point number

Factory setting 0

Additional information The switching behavior depends on the relative position of the **Switch-on value** and **Switch-off value** parameters; description: see the **Switch-on value** parameter (→ 🖹 154).

Assign status

Navigation Expert → Output → Switch output → Assign status (0485)

Prerequisite **Switch out funct (→ 🖹 153)** = **Digital Output**

Description Select device status for switch output.

Selection
- Off
- Digital out AD 1
- Digital out AD 2

Factory setting Off

Additional information The **Digital out AD 1** and **Digital out AD 2** options refer to the Advanced Diagnostic Blocks → 🖹 206. A switch signal generated in these blocks can be transmitted via the switch output.

Switch-on delay

Navigation Expert → Output → Switch output → Switch-on delay (0467)

Prerequisite
- **Switch out funct (→ 🖹 153)** = **Limit**
- **Assign limit (→ 🖹 154)** ≠ **Off**

Description Define switch-on delay.

User entry 0.0 to 100.0 s

Factory setting 0.0 s

Switch-off delay

Navigation Expert → Output → Switch output → Switch-off delay (0465)

Prerequisite
- **Switch out funct (→ 🖹 153)** = **Limit**
- **Assign limit (→ 🖹 154)** ≠ **Off**

Description Define switch-off delay.

User entry 0.0 to 100.0 s

Factory setting 0.0 s

Failure mode

Navigation Expert → Output → Switch output → Failure mode (0486)

Description Define output behavior in alarm condition.

Selection
- Actual status
- Open
- Closed

Factory setting Open

Switch status

Navigation Expert → Output → Switch output → Switch status (0461)

Description Displays the current state of the switch output.

Invert outp.sig.

Navigation Expert → Output → Switch output → Invert outp.sig. (0470)

Description Specify whether the output signal is to be inverted.

Selection
- No
- Yes

Factory setting No

Additional information

Meaning of the options
- **No**
  The behavior of the switch output is as described above.
- **Yes**
  The states **Open** and **Closed** are inverted as compared to the description above.

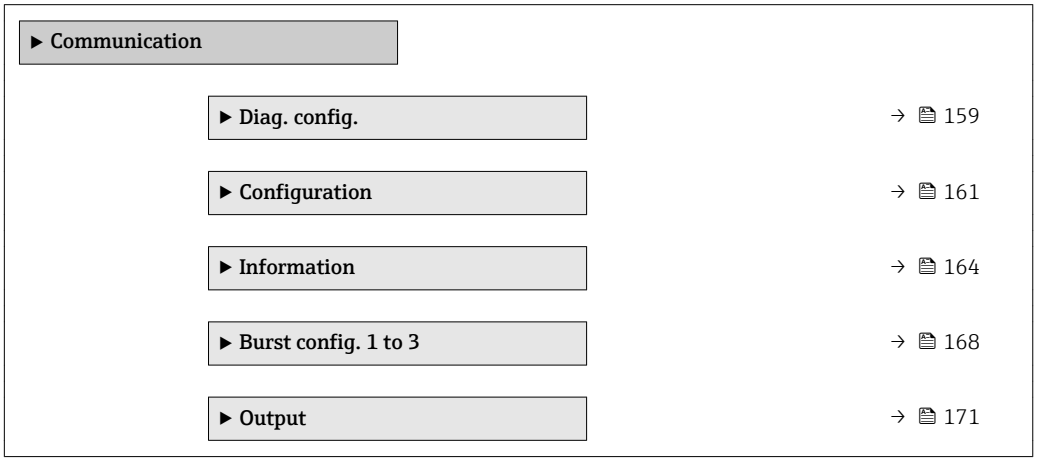
4.6 "Communication" submenu

Communication submenu (→ 158) enthält alle Parameter zur Steuerung der HART-Schnittstelle.

Configuration of the Modbus communication, see separate documentation: BA01957F (Operating Instructions FMP51, Modbus)

4.6.1 Structure of the submenu

Navigation Expert → Communication



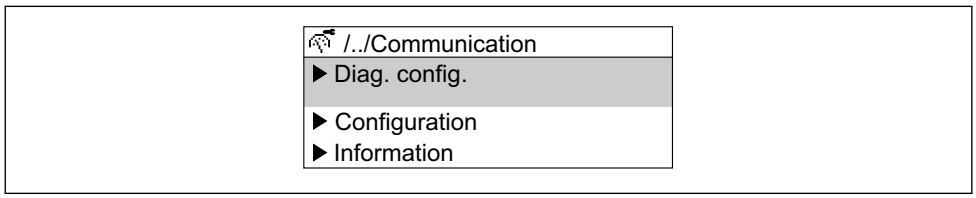
4.6.2 "Diagnostic configuration" submenu

In diesem Untermenü kann einzelnen Fehlermeldungen ein Status nach der NAMUR-Empfehlung NE107 zugeordnet werden. Dies betrifft folgende Fehlermeldungen:
- **In safety dist.**
- **Echo lost**
- **AD occured** (falls eine Erweiterte Diagnose aktiviert wurde)

Navigation Expert → Communication → Diag. config.

Configuration via local display

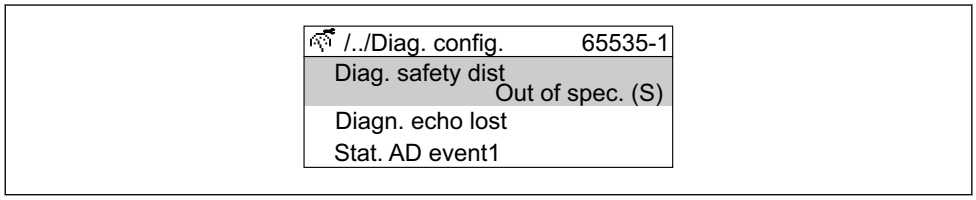
1.



A0030197-EN

Go to the **Diag. config.** submenu.

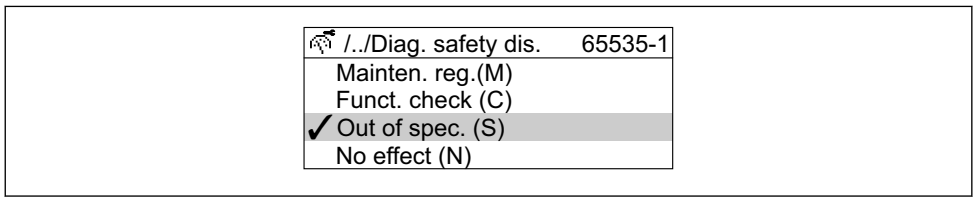
2.



A0030198-EN

Select an error message.

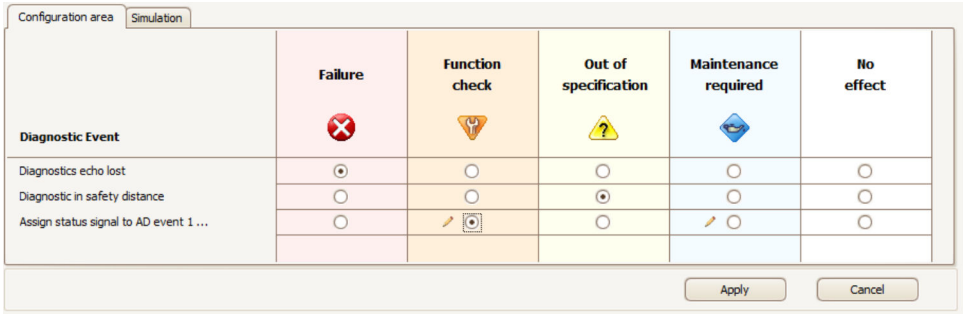
3.



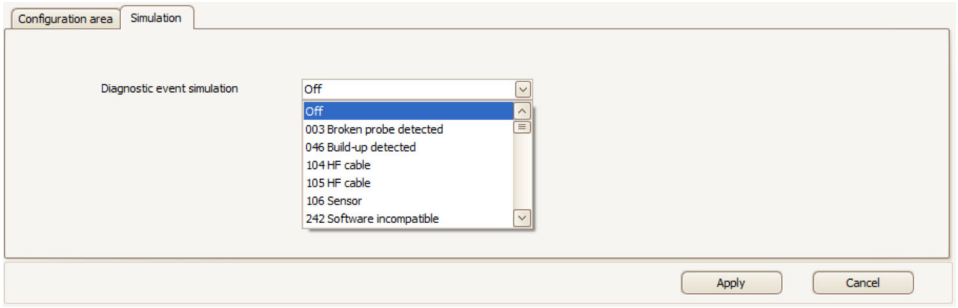
A0030199-EN

Select a status according to NE107.

Configuration via FieldCare

1. Go to the **Diag. config.** submenu.
2. 

   Mark the desired behavior of the individual error messages in the table and click "Apply" to confirm your selection.

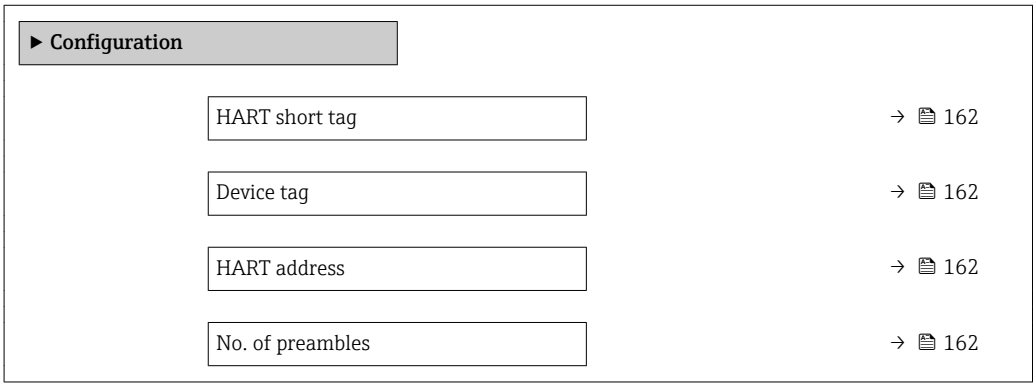
3. 

   Error messages can be simulated in the "Simulation" dialog in order to check the correct behavior.

4.6.3 "Configuration" submenu

Structure of the submenu

Navigation Expert → Communication → Configuration



Description of parameters

Navigation Expert → Communication → Configuration

HART short tag

Navigation Expert → Communication → Configuration → HART short tag (0220)

Description Define short tag for the measuring point.

Factory setting SHORTTAG

Device tag

Navigation Expert → Communication → Configuration → Device tag (0215)

Description Enter tag for measuring point.

Factory setting FMP5x

HART address

Navigation Expert → Communication → Configuration → HART address (0219)

Description Define HART address of the device.

User entry 0 to 63

Factory setting 0

Additional information
- Measured value transmission via the current value is only possible for address "0". For any other address the current is fixed at 4.0 mA (multidrop mode).
- For a system according to HART 5.0 possible addresses are 0 to 15.
- For a system according to HART 6.0 possible addresses are 0 to 63.

No. of preambles

Navigation Expert → Communication → Configuration → No. of preambles (0217)

Description Define number of preambles within the HART telegram.

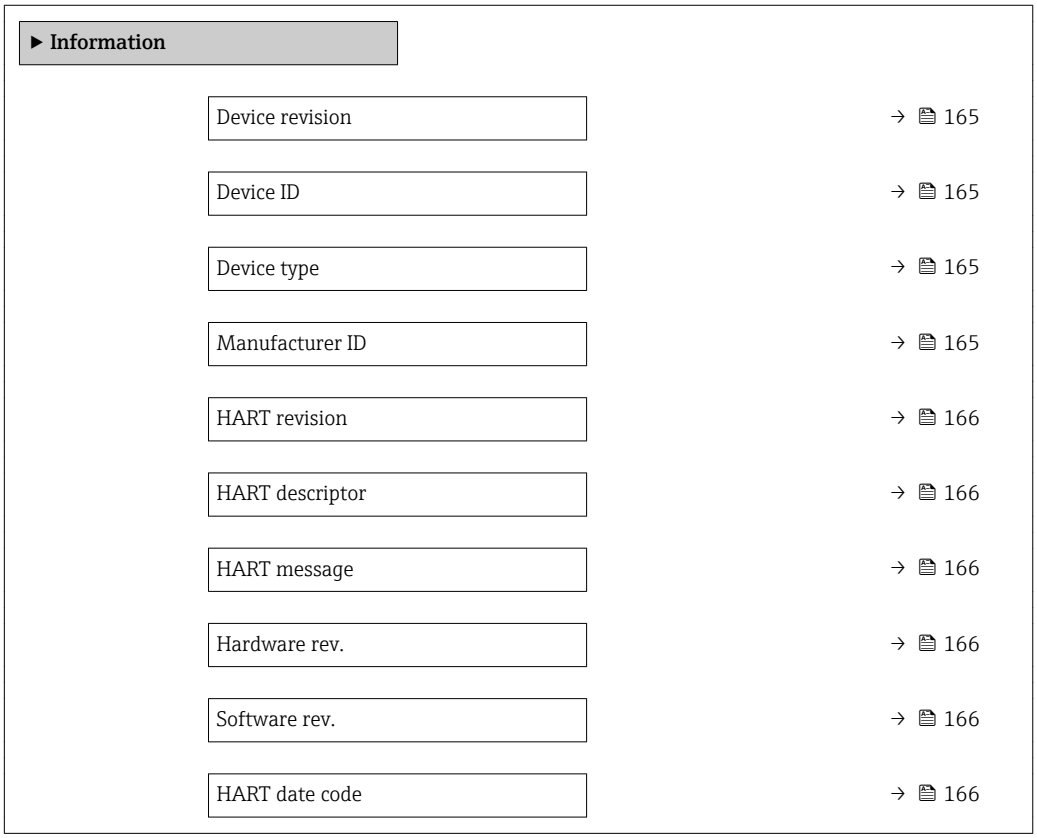
User entry 2 to 20

Factory setting 5

4.6.4 "Information" submenu

Structure of the submenu

Navigation Expert → Communication → Information



Description of parameters

Navigation Expert → Communication → Information

Device revision

Navigation Expert → Communication → Information → Device revision (0204)

Description Displays the device revision registered for this device at the HART Communication Foundation.

Additional information The device revision is used to allocate the correct Device Description file (DD) to the device.

Device ID

Navigation Expert → Communication → Information → Device ID (0221)

Description Displays Device ID.

Additional information In addition to the Device type and Manufacturer ID, the Device ID is part of the unique device identification (Unique ID) which characterizes each HART device unambiguously.

Device type

Navigation Expert → Communication → Information → Device type (0222)

Description Displays the device type with which the device is registered with the the HART Communication Foundation.

Additional information The device type is needed to allocate the correct Device Description file (DD) to the device.

Manufacturer ID

Navigation Expert → Communication → Information → Manufacturer ID (0223)

Description Displays the manufactured ID with which the device is registered with the HART Communication Foundation.

HART revision

Navigation Expert → Communication → Information → HART revision (0205)

Description Indicates HART revision of the device.

HART descriptor

Navigation Expert → Communication → Information → HART descriptor (0212)

Description Enter descriptor for the measuring point.

Factory setting FMP5x

HART message

Navigation Expert → Communication → Information → HART message (0216)

Description Define HART message which is sent via the HART protocol if requested by the master.

Factory setting FMP5x

Hardware rev.

Navigation Expert → Communication → Information → Hardware rev. (0206)

Description Indicates hardware revision of the device.

Software rev.

Navigation Expert → Communication → Information → Software rev. (0224)

Description Indicates software revision of the device.

HART date code

Navigation Expert → Communication → Information → HART date code (0202)

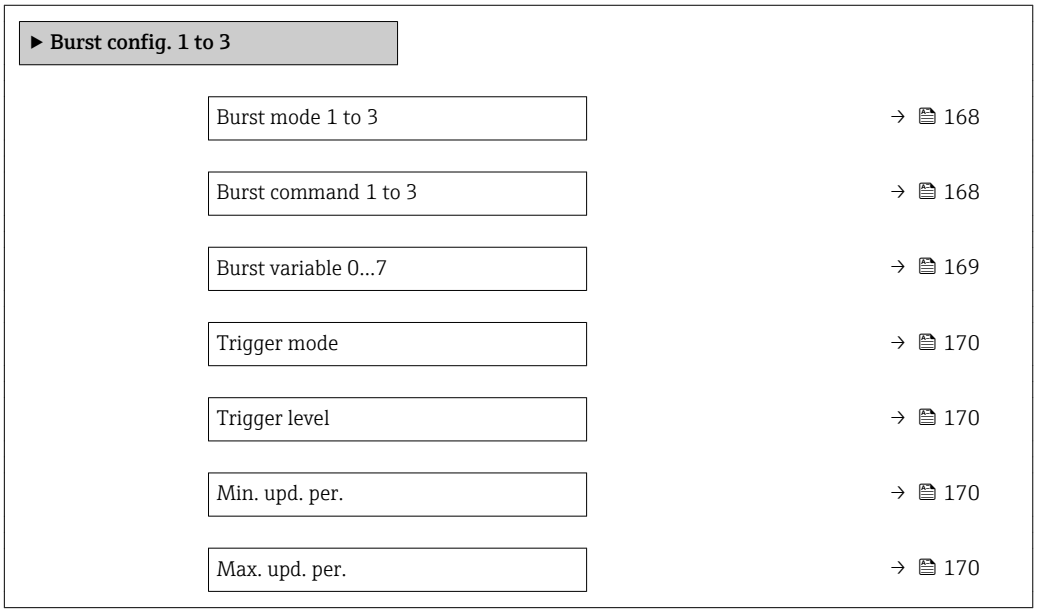
Description Enter date of the last configuration change.

Additional information Format: YYYY-MM-DD

4.6.5 "Burst config. 1 to 3" submenu

Structure of the submenu

Navigation Expert → Communication → Burst config. 1 to 3



Description of parameters

Navigation Expert → Communication → Burst config. 1 to 3

Burst mode 1 to 3

Navigation Expert → Communication → Burst config. 1 to 3 → Burst mode 1 to 3 (2032–1 to 3)

Description Switch HART burst mode for burst message on.

Selection
- Off
- On

Factory setting Off

Burst command 1 to 3

Navigation Expert → Communication → Burst config. 1 to 3 → Burst command 1 to 3 (2031–1 to 3)

Description Select the command that is sent to the HART master.

Selection
- Primary var (PV)
- Current/%Range
- DynamicVariables
- DV with status
- Device variables
- Add.device stat

Factory setting Current/%Range

Burst variable 0...7

Navigation Expert → Communication → Burst config. 1 to 3 → Burst variable 0 (2033)

Description Command 9, 33: assign a variable to burst variable.

Selection
- Level linearized
- Distance
- Unfiltered dist.
- Interface *
- Interface dist. *
- Unfilt. I. dist. *
- Thickn.upp.layer *
- Terminal volt.
- Electronic temp.
- Measur. cap. *
- Abs. echo ampl.
- Relat.echo ampl.
- Abs.interf.ampl. *
- Rel.interf.ampl. *
- Abs. EOP ampl.
- Noise of signal
- EOP shift
- Calc. DC value *
- Analog out. AD 1
- Analog out. AD 2
- Not used
- Percent of range
- Measur. curr.
- Primary var (PV)
- Second.var(SV)
- Tertiary var(TV)
- Quaterna.var(QV)

Factory setting Not used

* Visibility depends on order options or device settings

Trigger mode

Navigation Expert → Communication → Burst config. 1 to 3 → Trigger mode (2044–1 to 3)

Description Select the event that triggers the burst message.

Selection
- Continuous
- Window
- Rising
- Falling
- On change

Factory setting Continuous

Trigger level

Navigation Expert → Communication → Burst config. 1 to 3 → Trigger level (2043–1 to 3)

Description Define point of time when burst message is sent.

User entry Signed floating-point number

Factory setting 2.0E-38

Min. upd. per.

Navigation Expert → Communication → Burst config. 1 to 3 → Min. upd. per. (2042–1 to 3)

Description Min. time span between 2 responses of one message.

User entry Positive integer

Factory setting 1 000 ms

Max. upd. per.

Navigation Expert → Communication → Burst config. 1 to 3 → Max. upd. per. (2041–1 to 3)

Description Max. time span between 2 responses of one message.

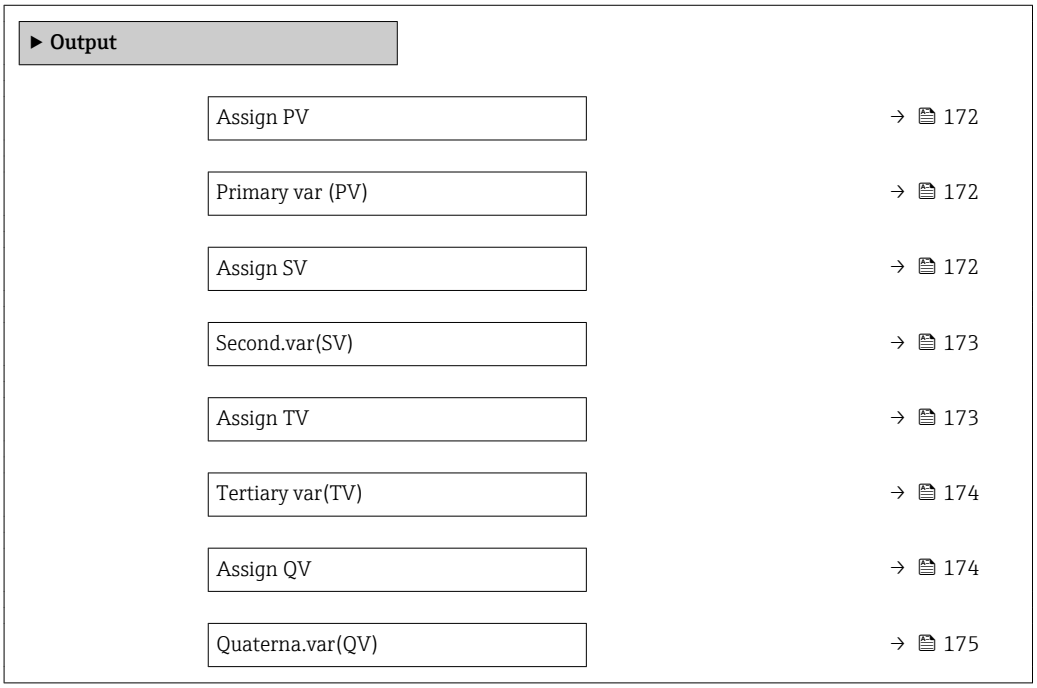
User entry Positive integer

Factory setting 2 000 ms

4.6.6 "Output" submenu

Structure of the submenu

Navigation Expert → Communication → Output



Description of parameters

Navigation Expert → Communication → Output

Assign PV

Navigation
Expert → Communication → Output → Assign PV (0234)
Expert → Communication → Output → Assign PV (0234)

Selection
- Level linearized
- Distance
- Interf. lineariz
- Interface dist.
- Thickn.upp.layer
- Electronic temp.
- Measur. cap.
- Relat.echo ampl.
- Rel.interf.ampl.
- Analog out. AD 1
- Analog out. AD 2

Factory setting
- For level measurements: **Level linearized**
- For interface measurements: **Interface linearized**

Additional information

Read access	Operator
Write access	Maintenance

Primary var (PV)

Navigation Expert → Communication → Output → Primary var (PV) (0201)

Description Displays primary HART variable (PV).

Assign SV

Navigation
Expert → Communication → Output → Assign SV (0235)
Expert → Communication → Output → Assign SV (0235)

Description Select measuring variable for secondary HART variable (SV).

Selection
- None
- Level linearized
- Distance
- Unfiltered dist.
- Interf. lineariz
- Interface dist.

- Unfilt. I. dist.
- Thickn.upp.layer
- Terminal volt.
- Electronic temp.
- Measur. cap.
- Abs. echo ampl.
- Relat.echo ampl.
- Abs.interf.ampl.
- Rel.interf.ampl.
- Abs. EOP ampl.
- Noise of signal
- EOP shift
- Calc. DC value
- Sensor debug
- Analog out. AD 1
- Analog out. AD 2

Factory setting

- For level measurements: **Distance**
- For interface measurements: **Level linearized**

Additional information

Read access	Operator
Write access	Maintenance

Second.var(SV)

Navigation Expert → Communication → Output → Second.var(SV) (0226)

Description Displays secondary HART variable (SV).

Assign TV

Navigation Expert → Communication → Output → Assign TV (0236)
Expert → Communication → Output → Assign TV (0236)

Description Select measuring variable for third HART variable (TV).

Selection

- None
- Level linearized
- Distance
- Unfiltered dist.
- Interf. lineariz
- Interface dist.
- Unfilt. I. dist.
- Thickn.upp.layer
- Terminal volt.
- Electronic temp.
- Measur. cap.
- Abs. echo ampl.
- Relat.echo ampl.
- Abs.interf.ampl.

- Rel.interf.ampl.
- Abs. EOP ampl.
- Noise of signal
- EOP shift
- Calc. DC value
- Sensor debug
- Analog out. AD 1
- Analog out. AD 2

Factory setting

- For level measurements: **Absolute echo amplitude**
- For interface measurements: **Thickness upper layer**

Additional information

Read access	Operator
Write access	Maintenance

Tertiary var(TV)

Navigation Expert → Communication → Output → Tertiary var(TV) (0228)

Description Displays third HART variable (TV).

Assign QV

Navigation Expert → Communication → Output → Assign QV (0237)

Description Select measuring variable for fourth HART variable (QV).

Selection

- None
- Level linearized
- Distance
- Unfiltered dist.
- Interf. lineariz
- Interface dist.
- Unfilt. I. dist.
- Thickn.upp.layer
- Terminal volt.
- Electronic temp.
- Measur. cap.
- Abs. echo ampl.
- Relat.echo ampl.
- Abs.interf.ampl.
- Rel.interf.ampl.
- Abs. EOP ampl.
- Noise of signal
- EOP shift
- Calc. DC value
- Sensor debug
- Analog out. AD 1
- Analog out. AD 2

Factory setting

- For level measurements: **Relative echo amplitude**
- For interface measurements: **Absolute interface amplitude**

Additional information

Read access	Operator
Write access	Maintenance

Quaterna.var(QV)

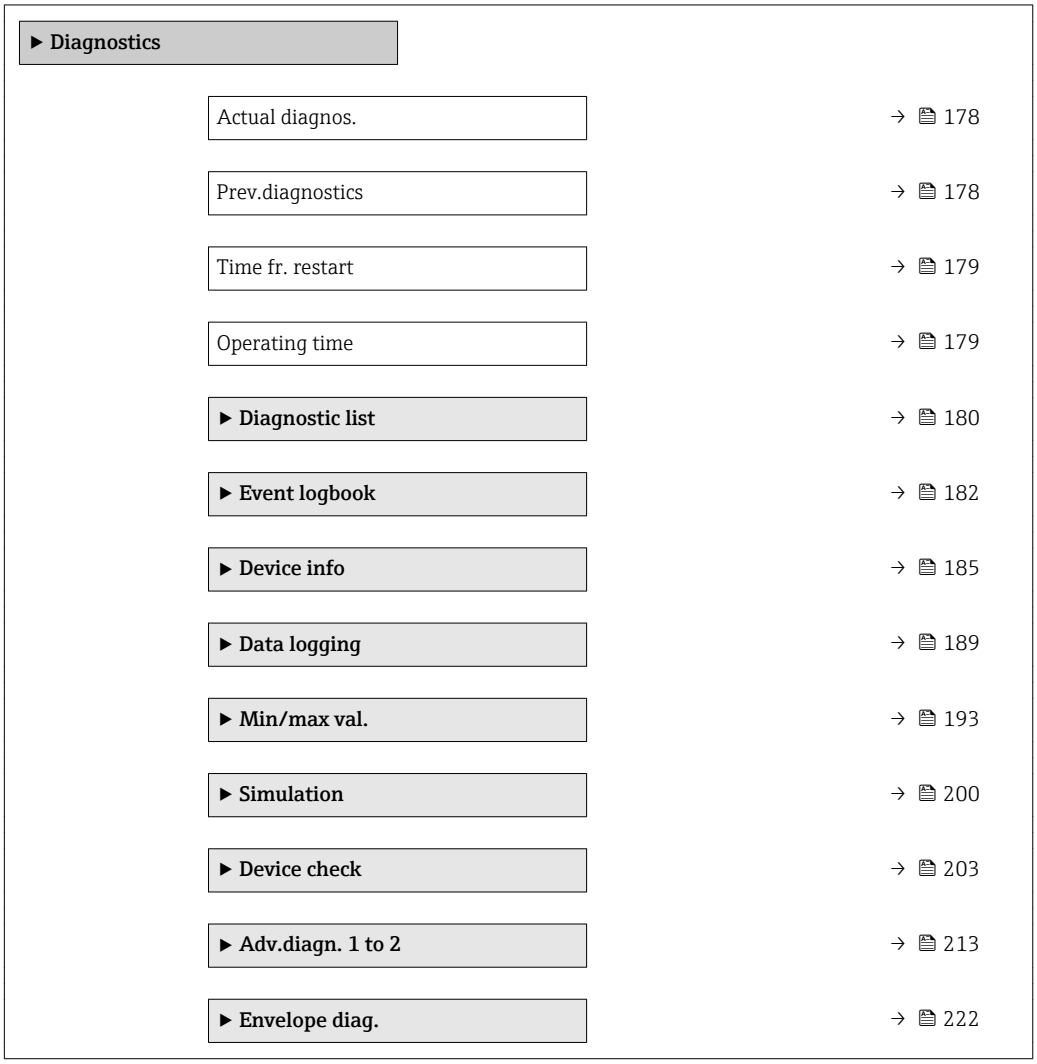
Navigation Expert → Communication → Output → Quaterna.var(QV) (0203)

Description Displays fourth HART variable (QV).

4.7 "Diagnostics" submenu

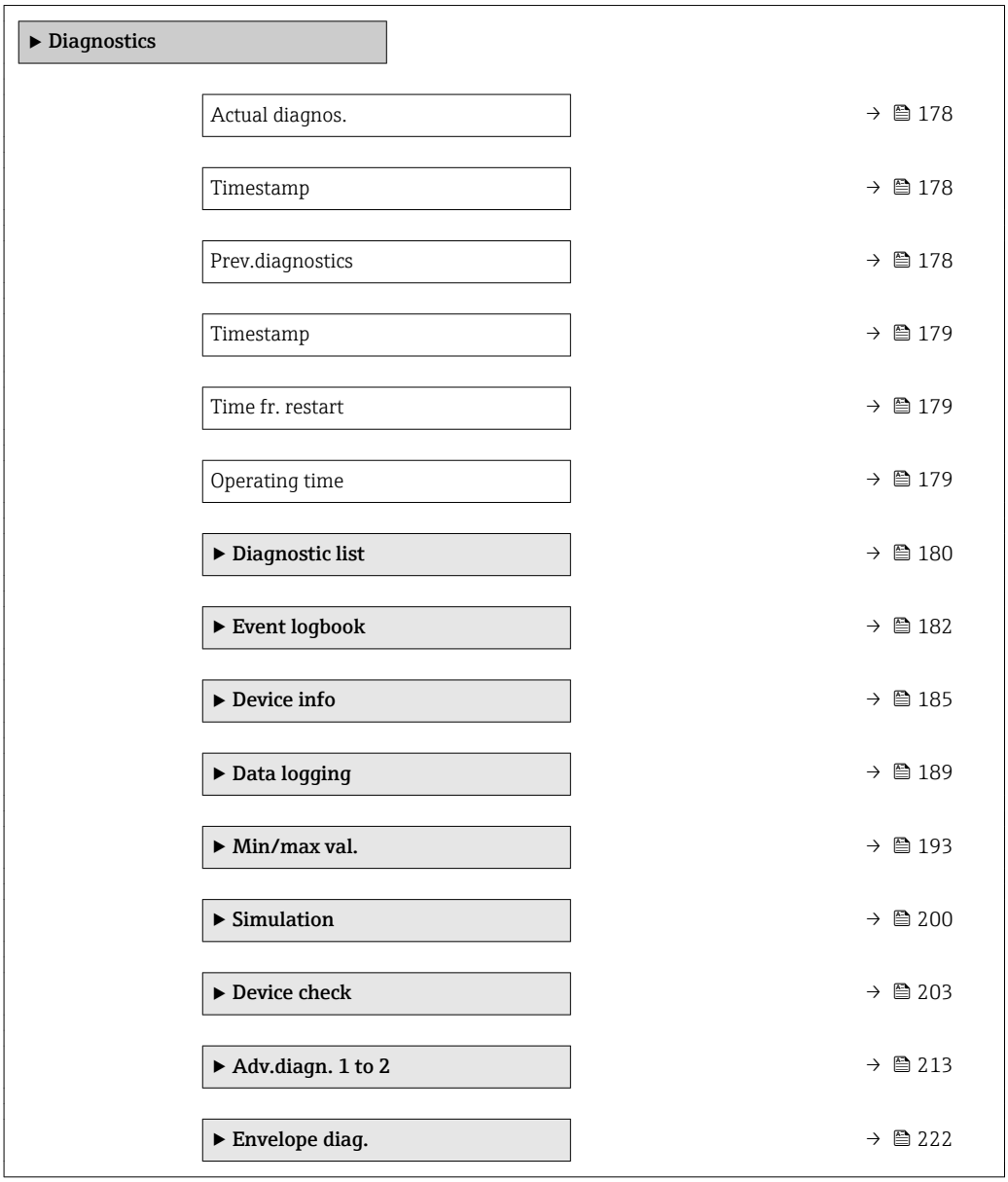
4.7.1 Structure of the submenu on the local display

Navigation Expert → Diagnostics



4.7.2 Structure of the submenu in an operating tool

Navigation Expert → Diagnostics



4.7.3 Description of parameters

Navigation Expert → Diagnostics

Actual diagnos.

Navigation Expert → Diagnostics → Actual diagnos. (0691)

Description Displays current diagnostic message.

Additional information The display consists of:
- Symbol for event behavior
- Code for diagnostic behavior
- Operating time of occurrence
- Event text

If several messages are active at the same time, the messages with the highest priority is displayed.

Information on what is causing the message, and remedy measures, can be viewed via the ⓘ symbol on the display.

Timestamp

Navigation Expert → Diagnostics → Timestamp (0667)

Description Displays timestamp for the **Actual diagnos.** parameter (→ 178).

User interface Days (d), hours (h), minutes (m), seconds (s)

Prev.diagnostics

Navigation Expert → Diagnostics → Prev.diagnostics (0690)

Description Displays the last diagnostic message which has been active before the current message.

Additional information The display consists of:
- Symbol for event behavior
- Code for diagnostic behavior
- Operating time of occurrence
- Event text

The condition displayed may still apply. Information on what is causing the message, and remedy measures, can be viewed via the ⓘ symbol on the display.

Timestamp

Navigation Expert → Diagnostics → Timestamp (0672)

Description Displays timestamp for the **Prev.diagnostics** parameter (→ 178).

User interface Days (d), hours (h), minutes (m), seconds (s)

Time fr. restart

Navigation Expert → Diagnostics → Time fr. restart (0653)

Description Displays the time the device has been in operation since the last device restart.

User interface Days (d), hours (h), minutes (m), seconds (s)

Operating time

Navigation Expert → Diagnostics → Operating time (0652)

Description Indicates how long device has been in operation.

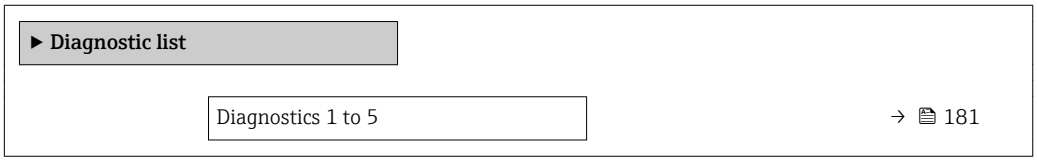
User interface Days (d), hours (h), minutes (m), seconds (s)

Additional information *Maximum time*
9 999 d (≈ 27 years)

4.7.4 "Diagnostic list" submenu

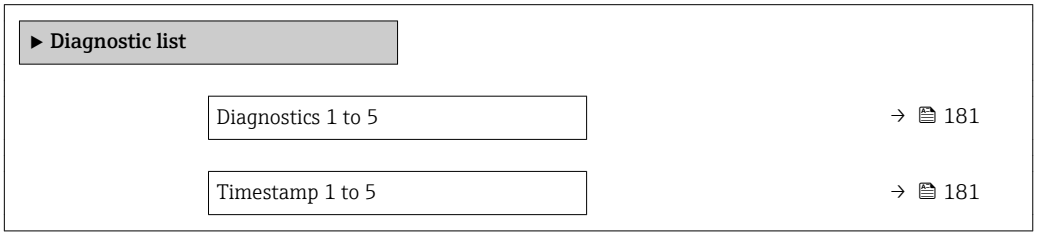
Structure of the submenu on the local display

Navigation Expert → Diagnostics → Diagnostic list



Structure of the submenu in an operating tool

Navigation Expert → Diagnostics → Diagnostic list



Description of parameters

Navigation Expert → Diagnostics → Diagnostic list

Diagnostics 1 to 5

Navigation Expert → Diagnostics → Diagnostic list → Diagnostics 1 to 5 (0692–1 to 5)

Description Display the current diagnostics messages with the highest to fifth-highest priority.

Additional information The display consists of:
- Symbol for event behavior
- Code for diagnostic behavior
- Operating time of occurrence
- Event text

Timestamp 1 to 5

Navigation Expert → Diagnostics → Diagnostic list → Timestamp (0683)

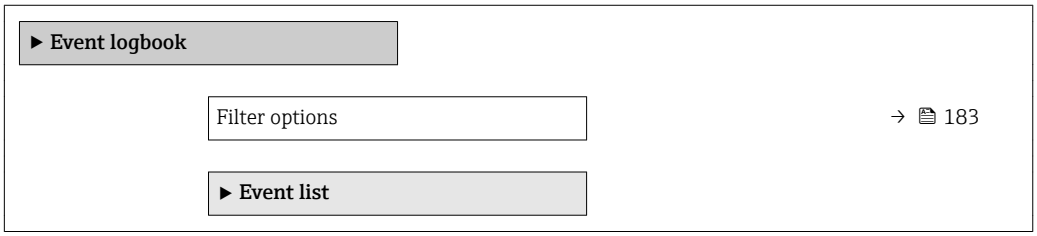
Description Displays timestamp for the **Diagnostics 1 to 5** parameter (→ 181).

User interface Days (d), hours (h), minutes (m), seconds (s)

4.7.5 "Event logbook" submenu

Structure of the submenu on the local display

Navigation Expert → Diagnostics → Event logbook



Structure of the submenu in an operating tool

Navigation Expert → Diagnostics → Event logbook

Description of parameters

Navigation Expert → Diagnostics → Event logbook

Filter options

Navigation Expert → Diagnostics → Event logbook → Filter options (0705)

Description Select category (status signal) whose event messages are displayed in the events list.

Selection
- All
- Failure (F)
- Funct. check (C)
- Out of spec. (S)
- Mainten. req.(M)
- Information (I)

Factory setting All

Additional information
- This parameter is only used for operation via the local display.
- The status signals are categorized according to NAMUR NE 107.

"Event list" submenu

The **Event list** submenu (→ 184) is only available when operating via the local display.

The **Event list** submenu doesn't contain any parameters but only the list of events of the category selected in the **Filter options** parameter. A maximum of 100 event messages is displayed in chronological order.

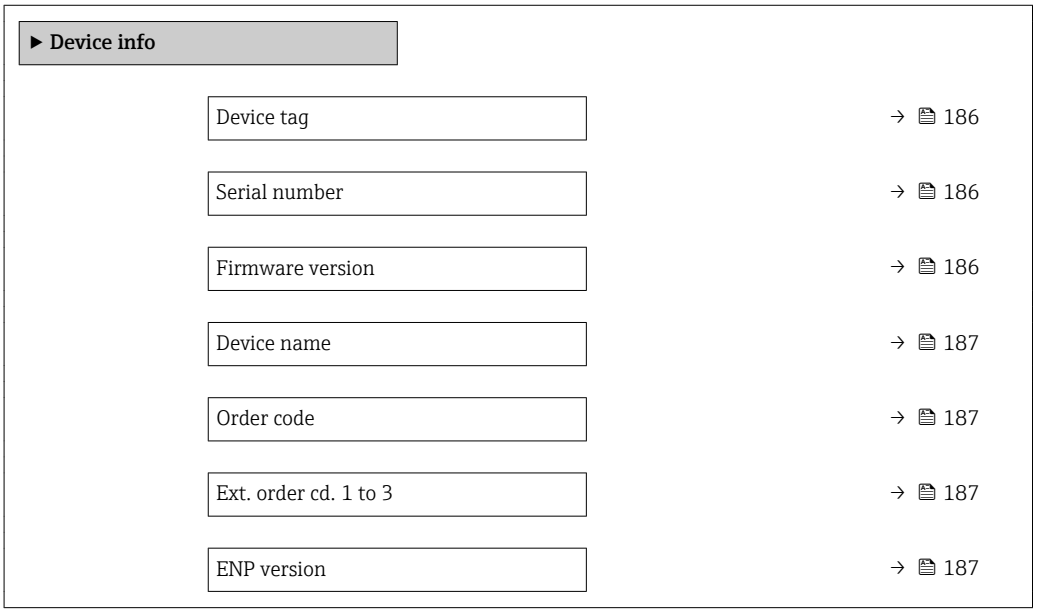
The following status symbols indicate, whether an event has appeared or disappeared at the time stated:
- : Event appeared
- : Event disappeared

Remedy measures concerning the cause of the message can be called up via the symbol on the display.

4.7.6 "Device info" submenu

Structure of the submenu

Navigation Expert → Diagnostics → Device info



Description of parameters

Navigation Expert → Diagnostics → Device info

Device tag

Navigation

Expert → Diagnostics → Device info → Device tag (0011)

Expert → Diagnostics → Device info → Device tag (0011)

Description

Enter tag for measuring point.

Factory setting

FMP5x

Additional information

Read access	Operator
Write access	-

Serial number

Navigation

Expert → Diagnostics → Device info → Serial number (0009)

Expert → Diagnostics → Device info → Serial number (0009)

Additional information

Uses of the serial number
- To identify the device quickly, e.g. when contacting Endress+Hauser.
- To obtain specific information on the device using the Device Viewer: www.endress.com/deviceviewer

The serial number is also indicated on the nameplate.

Read access	Operator
Write access	-

Firmware version

Navigation

Expert → Diagnostics → Device info → Firmware version (0010)

Expert → Diagnostics → Device info → Firmware version (0010)

User interface

xx.yy.zz

Additional information

For firmware versions differing only in the last two digits ("zz") there is no difference concerning functionality or operation.

Read access	Operator
Write access	-

Device name

Navigation

Expert → Diagnostics → Device info → Device name (0013)

Expert → Diagnostics → Device info → Device name (0013)

Additional information

Read access	Operator
Write access	-

Order code

Navigation

Expert → Diagnostics → Device info → Order code (0008)

Expert → Diagnostics → Device info → Order code (0008)

Additional information

The order code is generated from the extended roder code, which defines all device features of the product structure. In contrast, the device features can not be read directly from the order code.

Read access	Operator
Write access	Service

Ext. order cd. 1 to 3

Navigation

Expert → Diagnostics → Device info → Ext. order cd. 1 (0023)

Expert → Diagnostics → Device info → Ext. order cd. 1 (0023)

Description

Display the three parts of the extended order code.

Additional information

The extended order code indicates the version of all the features of the product structure and thus uniquely identifies the device.

Read access	Operator
Write access	Service

ENP version

Navigation

Expert → Diagnostics → Device info → ENP version (0012)

Expert → Diagnostics → Device info → ENP version (0012)

User interface

xx.yy.zz

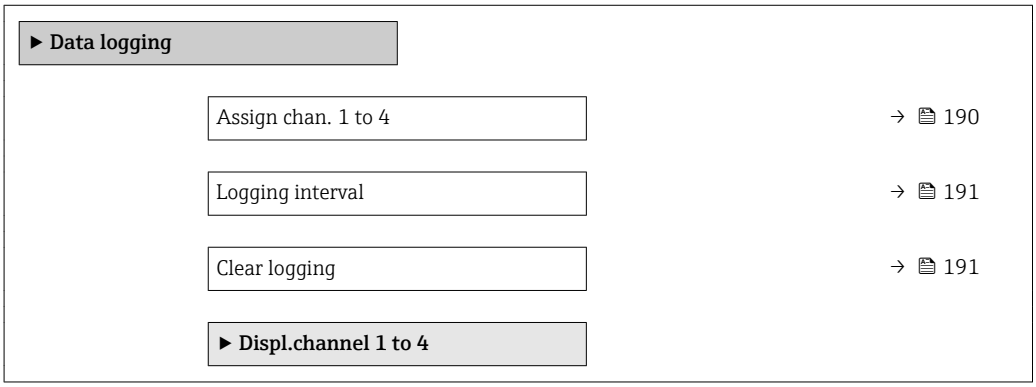
Additional information

Read access	Operator
Write access	-

4.7.7 "Data logging" submenu

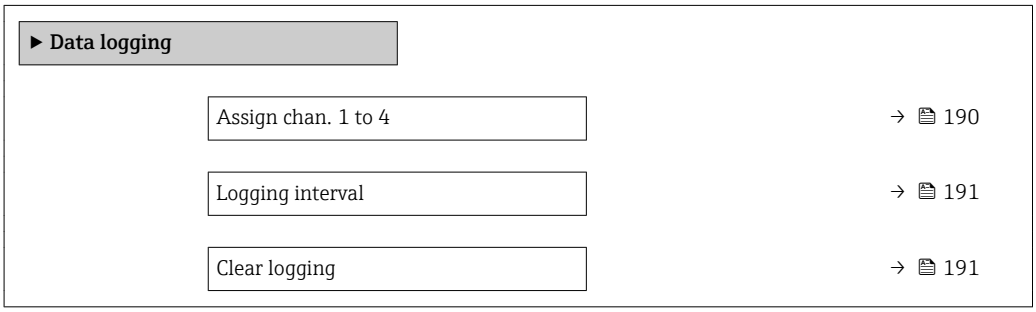
Structure of the submenu on the local display

Navigation Expert → Diagnostics → Data logging



Structure of the submenu in an operating tool

Navigation Expert → Diagnostics → Data logging



Description of parameters

Navigation Expert → Diagnostics → Data logging

Assign chan. 1 to 4

Navigation Expert → Diagnostics → Data logging → Assign chan. 1 (0851)

Description Allocate a process variable to the respective data logging channel.

Selection
- Off
- Level linearized
- Distance
- Unfiltered dist.
- Interf. lineariz
- Interface dist.
- Unfilt. I. dist.
- Thickn.upp.layer
- Curr.output 1
- Measur. curr.
- Curr.output 2
- Terminal volt.
- Electronic temp.
- Measur. cap.
- Abs. echo ampl.
- Relat.echo ampl.
- Abs.interf.ampl.
- Rel.interf.ampl.
- Abs. EOP ampl.
- EOP shift
- Noise of signal
- Calc. DC value
- Analog out. AD 1
- Analog out. AD 2

Factory setting Off

Additional information A total of 1000 measured values can be logged. This means:
- 1000 data points if 1 logging channel is used
- 500 data points if 2 logging channels are used
- 333 data points if 3 logging channels are used
- 250 data points if 4 logging channels are used

If the maximum number of data points is reached, the oldest data points in the data log are cyclically overwritten in such a way that the last 1000, 500, 333 or 250 measured values are always in the log (ring memory principle).

The logged data are deleted if a new option is selected in this parameter.

Logging interval

Navigation Expert → Diagnostics → Data logging → Logging interval (0856)

Description Define logging interval t_{log}.

User entry 1.0 to 3 600.0 s

Factory setting 30.0 s

Additional information This parameter defines the interval between the individual data points in the data log, and thus the maximum loggable process time T_{log}:

- If 1 logging channel is used: $T_{log} = 1000 \cdot t_{log}$
- If 2 logging channels are used: $T_{log} = 500 \cdot t_{log}$
- If 3 logging channels are used: $T_{log} = 333 \cdot t_{log}$
- If 4 logging channels are used: $T_{log} = 250 \cdot t_{log}$

Once this time elapses, the oldest data points in the data log are cyclically overwritten such that a time of T_{log} always remains in the memory (ring memory principle).

The logged data are deleted if this parameter is changed.

Example

When using 1 logging channel
- $T_{log} = 1000 \cdot 1$ s = 1 000 s ≈ 16.5 min
- $T_{log} = 1000 \cdot 10$ s = 1 000 s ≈ 2.75 h
- $T_{log} = 1000 \cdot 80$ s = 80 000 s ≈ 22 h
- $T_{log} = 1000 \cdot 3\,600$ s = 3 600 000 s ≈ 41 d

Clear logging

Navigation Expert → Diagnostics → Data logging → Clear logging (0855)

Description Initiate a deletion of the complete logging memory.

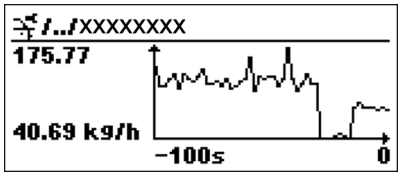
Selection
- Cancel
- Clear data

Factory setting Cancel

"Displ.channel 1 to 4" submenu

The **Displ.channel 1 to 4** submenu is only available when operating via the local display. When operating via FieldCare, the diagram can be displayed in the "Event List / HistoROM" function.

The **Displ.channel 1 to 4** submenu displays the measured value trend of the respective logging channel.



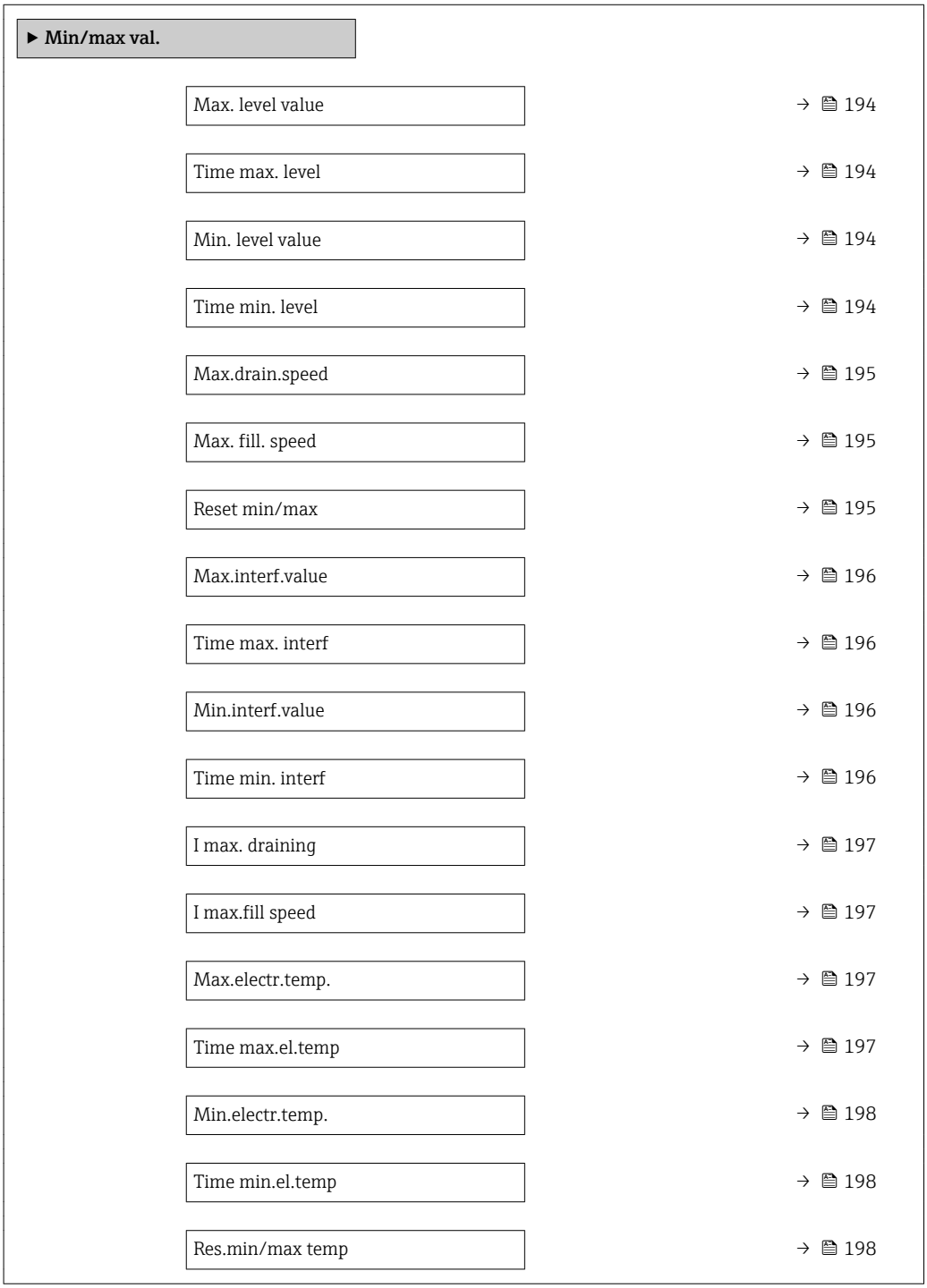
- x-axis: displays 125 to 500 measured values of a process variable (the number of values depending on the number of selected channels).
- y-axis: displays the approximate measured value span and constantly adapts this to the ongoing measurement.

To quit the diagram and to return to the operating menu, press ⊞ and ⊟ simultaneously.

4.7.8 "Min/max val." submenu

Structure of the submenu

Navigation Expert → Diagnostics → Min/max val.



Description of parameters

Navigation Expert → Diagnostics → Min/max val.

Max. level value

Navigation
Expert → Diagnostics → Min/max val. → Max. level value (2357)
Expert → Diagnostics → Min/max val. → Max. level value (2357)

Description
Displays maximum level measured in the past.

Additional information

Read access	Operator
Write access	-

Time max. level

Navigation
Expert → Diagnostics → Min/max val. → Time max. level (2385)
Expert → Diagnostics → Min/max val. → Time max. level (2385)

Description
Displays operating time at which the maximum level has been obtained.

Additional information

Read access	Operator
Write access	-

Min. level value

Navigation
Expert → Diagnostics → Min/max val. → Min. level value (2358)
Expert → Diagnostics → Min/max val. → Min. level value (2358)

Description
Displays minimum level measured in the past.

Additional information

Read access	Operator
Write access	-

Time min. level

Navigation
Expert → Diagnostics → Min/max val. → Time min. level (2386)
Expert → Diagnostics → Min/max val. → Time min. level (2386)

Description
Displays operating time at which the minimum level has been obtained.

Additional information

Read access	Operator
Write access	-

Max.drain.speed

Navigation

Expert → Diagnostics → Min/max val. → Max.drain.speed (2320)

Expert → Diagnostics → Min/max val. → Max.drain.speed (2320)

Description

Displays maximum draining speed measured in the past.

Additional information

Read access	Operator
Write access	-

Max. fill. speed

Navigation

Expert → Diagnostics → Min/max val. → Max. fill. speed (2360)

Expert → Diagnostics → Min/max val. → Max. fill. speed (2360)

Description

Displays maximum filling speed measured in the past.

Additional information

Read access	Operator
Write access	-

Reset min/max

Navigation

Expert → Diagnostics → Min/max val. → Reset min/max (2324)

Expert → Diagnostics → Min/max val. → Reset min/max (2324)

Description

Select which min/max values are to be reset.

Selection

- None
- Drain/fill speed
- Level
- I drain/fill spd
- Interface
- Reset all

Factory setting

None

Additional information

Read access	Operator
Write access	Maintenance

Max.interf.value

Navigation
- Expert → Diagnostics → Min/max val. → Max.interf.value (2361)
- Expert → Diagnostics → Min/max val. → Max.interf.value (2361)

Prerequisite
Operating mode (→ 50) = **Interface** or **Interf.+capacit.**

Description
Displays minimum interface height measured in the past.

Time max. interf

Navigation
- Expert → Diagnostics → Min/max val. → Time max. interf (2388)
- Expert → Diagnostics → Min/max val. → Time max. interf (2388)

Prerequisite
Operating mode (→ 50) = **Interface** or **Interf.+capacit.**

Description
Displays operating time at which the maximum interface height has been obtained.

Min.interf.value

Navigation
- Expert → Diagnostics → Min/max val. → Min.interf.value (2362)
- Expert → Diagnostics → Min/max val. → Min.interf.value (2362)

Prerequisite
Operating mode (→ 50) = **Interface** or **Interf.+capacit.**

Description
Displays minimum interface height measured in the past.

Time min. interf

Navigation
- Expert → Diagnostics → Min/max val. → Time min. interf (2387)
- Expert → Diagnostics → Min/max val. → Time min. interf (2387)

Prerequisite
Operating mode (→ 50) = **Interface** or **Interf.+capacit.**

Description
Displays operating time at whicht the minimum interface height has been obtained.

I max. draining

Navigation
Expert → Diagnostics → Min/max val. → I max. draining (2363)
Expert → Diagnostics → Min/max val. → I max. draining (2363)

Prerequisite
Operating mode (→ 50) = **Interface** or **Interf.+capacit.**

Description
Displays maximum drainging speed of the lower medium measured in the past.

I max.fill speed

Navigation
Expert → Diagnostics → Min/max val. → I max.fill speed (2359)
Expert → Diagnostics → Min/max val. → I max.fill speed (2359)

Prerequisite
Operating mode (→ 50) = **Interface** or **Interf.+capacit.**

Description
Displays maximum filling speed of the lower medium measured in the past.

Max.electr.temp.

Navigation
Expert → Diagnostics → Min/max val. → Max.electr.temp. (12506)

Description
Displays maximum electronics temperature measured in the past.

Additional information

Read access	Operator
Write access	-

Time max.el.temp

Navigation
Expert → Diagnostics → Min/max val. → Time max.el.temp (12507)

Description
Displays operating time at which the maximum electronics temperature has been obtained.

Additional information

Read access	Operator
Write access	-

Min.electr.temp.

Navigation Expert → Diagnostics → Min/max val. → Min.electr.temp. (12508)

Description Displays minimum electronics temperature measured in the past.

Additional information

Read access	Operator
Write access	-

Time min.el.temp

Navigation Expert → Diagnostics → Min/max val. → Time min.el.temp (12509)

Description Displays operating time at which the minimum electronics temperature has been obtained.

Additional information

Read access	Operator
Write access	-

Res.min/max temp

Navigation Expert → Diagnostics → Min/max val. → Res.min/max temp (12510)

Description Select which min/max values are to be reset.

User interface
- None
- Electronic temp.
- Reset all

Factory setting None

Additional information

Read access	Operator
Write access	Service

4.7.9 "Simulation" submenu

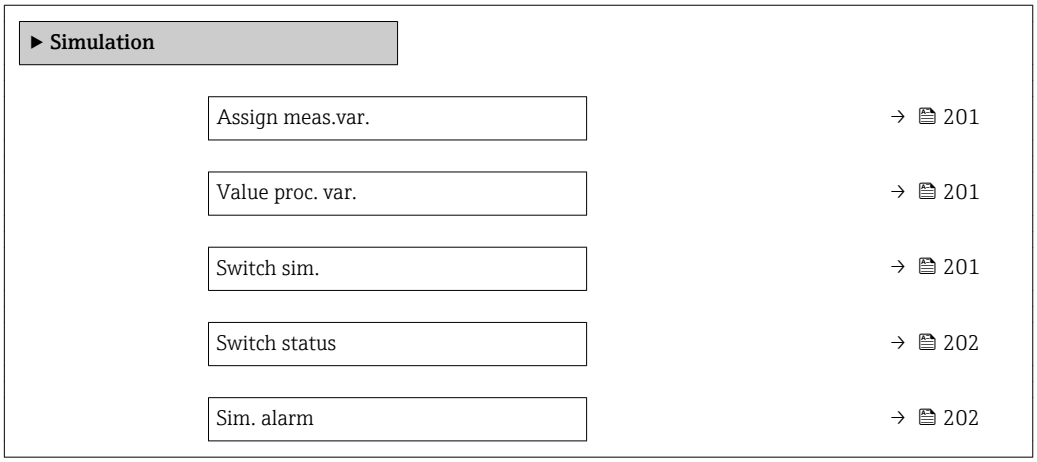
The **Simulation** submenu is used to simulate specific measuring values or other conditions. This helps to check the correct configuration of the device and connected control units.

Conditions which can be simulated

Condition to be simulated	Associated parameters
Specific value of a process variable	▪ Assign meas.var. (→ 🖹 201) ▪ Value proc. var. (→ 🖹 201)
Specific state of the switch output	▪ Switch sim. (→ 🖹 201) ▪ Switch status (→ 🖹 202)
Existence of an alarm	Sim. alarm (→ 🖹 202)

Structure of the submenu

Navigation Expert → Diagnostics → Simulation



Description of parameters

Navigation Expert → Diagnostics → Simulation

Assign meas.var.

Navigation Expert → Diagnostics → Simulation → Assign meas.var. (2328)

Description Selct process variable to be simulated.

Selection
- Off
- Level
- Interface
- Level linearized
- Interf. lineariz
- Thickn.lineariz.

Factory setting Off

Additional information
- The value of the variable to be simulated is defined in the **Value proc. var.** parameter (→ 201).
- If **Assign meas.var.** ≠ **Off**, a simulation is active. This is indicated by a diagnotic message of the *Function check (C)* category.

Value proc. var.

Navigation Expert → Diagnostics → Simulation → Value proc. var. (2329)

Prerequisite **Assign meas.var. (→ 201)** ≠ **Off**

Description Specify value of the process value being simulated.

User entry Signed floating-point number

Factory setting 0

Additional information Downstream measured value processing and the signal output use this simulation value. In this way, users can verify whether the measuring device has been configured correctly.

Switch sim.

Navigation Expert → Diagnostics → Simulation → Switch sim. (0462)

Description Switch the simulation of the switch output on or off.

Selection
- Off
- On

Factory setting Off

Switch status

Navigation Expert → Diagnostics → Simulation → Switch status (0463)

Prerequisite **Switch sim. (→ 201)** = **On**

Description Define the switch state to be simulated.

Selection
- Open
- Closed

Factory setting Open

Additional information The switch status assumes the value defined in this parameter. This helps to check correct operation of connected control units.

Sim. alarm

Navigation Expert → Diagnostics → Simulation → Sim. alarm (0654)

Description Switch alarm simulation on or off.

Selection
- Off
- On

Factory setting Off

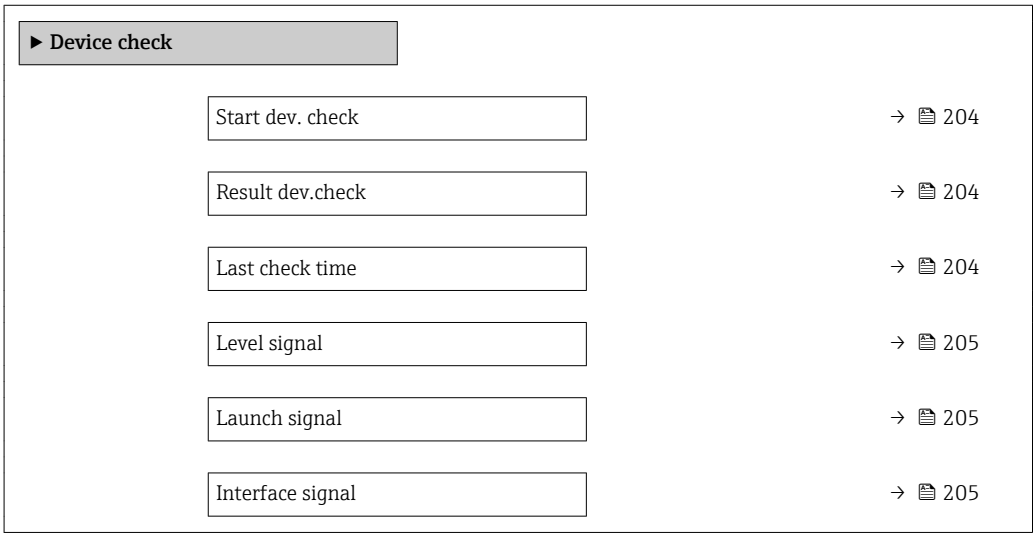
Additional information When selecting the **On** option, the device generates an alarm. This helps to check the correct output behavior of the device in the case of an alarm.

An active simulation is indicated by the diagnostic message **C484 Sim. fail. mode**.

4.7.10 "Device check" submenu

Structure of the submenu

Navigation Expert → Diagnostics → Device check



Description of parameters

Navigation Expert → Diagnostics → Device check

Start dev. check

Navigation Expert → Diagnostics → Device check → Start dev. check (1013)

Description Start a device check.

Selection
- No
- Yes

Factory setting No

Additional information In the case of a lost echo a device check can not be performed.

Result dev.check

Navigation Expert → Diagnostics → Device check → Result dev.check (1014)

Description Displays the result of the device check.

Additional information

Meaning of the display options
- **Installation ok**
  Measurement possible without restrictions.
- **Accuracy reduced**
  A measurement is possible. However, the measuring accuracy may be reduced due to the signal amplitudes.
- **Meas.capab. red.**
  A measurement is currently possible. Howerver, there is the risk of an echo loss. Check the mounting position of the device and the dielectric constant of the medium.
- **Check not done**
  No device check has been performed.

Last check time

Navigation Expert → Diagnostics → Device check → Last check time (1203)

Description Displays the operating time at which the last device check has been performed.

Level signal

Navigation Expert → Diagnostics → Device check → Level signal (1016)

Prerequisite Device check has been performed.

Description Displays result of the device check for the level signal.

User interface
- Check not done
- Check not OK
- Check OK

Additional information For **Level signal** = **Check not OK**: Check the mounting position of the device and the dielectric constant of the medium.

Launch signal

Navigation Expert → Diagnostics → Device check → Launch signal (1012)

Prerequisite Device check has been performed.

Description Displays result of the display check for the launch signal.

User interface
- Check not done
- Check not OK
- Check OK

Additional information For **Launch signal** = **Check not OK**: Check the mounting position of the device. In non-metallic vessels use a metal plate or a metal flange.

Interface signal

Navigation Expert → Diagnostics → Device check → Interface signal (1015)

Prerequisite
- **Operating mode (→ 50)** = **Interface** or **Interf.+capacit.**
- Device check has been performed.

Description Displays result of the device check for the interface signal.

User interface
- Check not done
- Check not OK
- Check OK

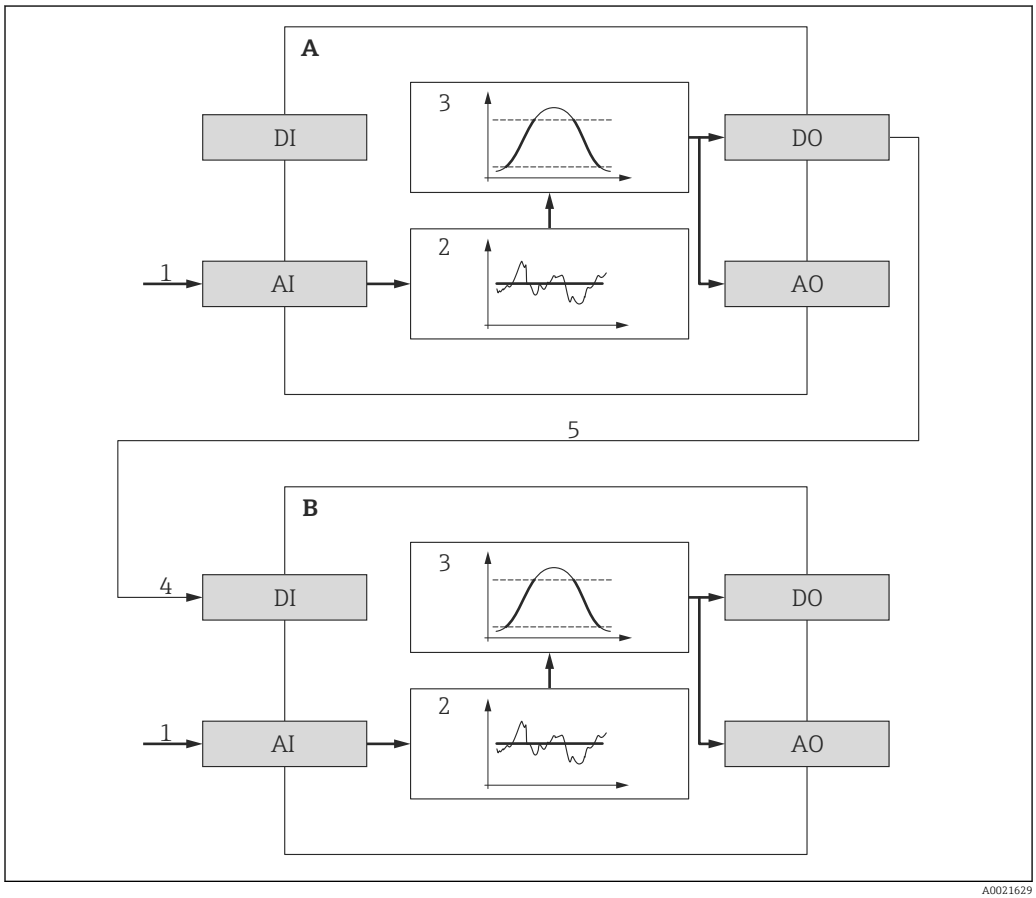
4.7.11 "Adv.diagn. 1 to 2" submenu

Mode of operation

The Advanced Diagnostics offers additional options to monitor the process. The device contains two Advanced Diagnostic Blocks which can be used separately or in combination.

A measuring variable can be assigned to the input of each Advanced Diagnostic Block. Based on a freely configurable time interval, the variable can be submitted to a statistical function (e.g. maximum, minimum, mean, slope). Finally, a limit detection can be parametrized and its result can be transmitted to a digital output.

The result can be displayed and evaluated by a DCS or PLC. If required, it can also be linked to the second Advanced Diagnostic block and thus it is possible to combine the two results by the logical operators AND or OR.



46 *Combined Advanced Diagnostic blocks*

A Advanced Diagnsotics 1
B Advanced Diagnsotics 2
AI Analog input of the respective block
DI Digital input of the respective block
AO Analog output of the respective block
DO Digital output of the respective block
1 Analog process variable
2 Statistical calculation (maximum, minimum, mean, slope)
3 Limit check
4 Digital input of AD2
5 Digital output of AD1 is linked to digital input of AD2

Overview of the Advanced Diagnostic functionalities

Task	Associated parameters
Allocation of a process variable to the analog input of the block.	Assign signal (→ 214)
Linking the digital input to the digital output of the other block.	▪ Link AD to (→ 214) ▪ Link. logic AD (→ 215)
Calculation of one of the following quantities for a freely configurable sampling interval: ▪ Maximum ▪ Minimum ▪ Mean ▪ Std. deviation ▪ Diff.Max. - Min. ▪ Slope	▪ Sample time (→ 215) ▪ Calc. type (→ 215) ▪ Calc. unit (→ 217)
Drag indicator for the calculated quantity	▪ Maximum value (→ 219) ▪ Minimum value (→ 219) ▪ Reset min/max (→ 219)
Limit check	▪ Check mode (→ 216) ▪ Upper limit (→ 218) ▪ Lower limit (→ 218) ▪ Hysteresis (→ 219)
Reaction in case of a limit violation	▪ Stat. AD event (→ 220) ▪ Evt behaviour (→ 220) ▪ Alarm delay (→ 220)

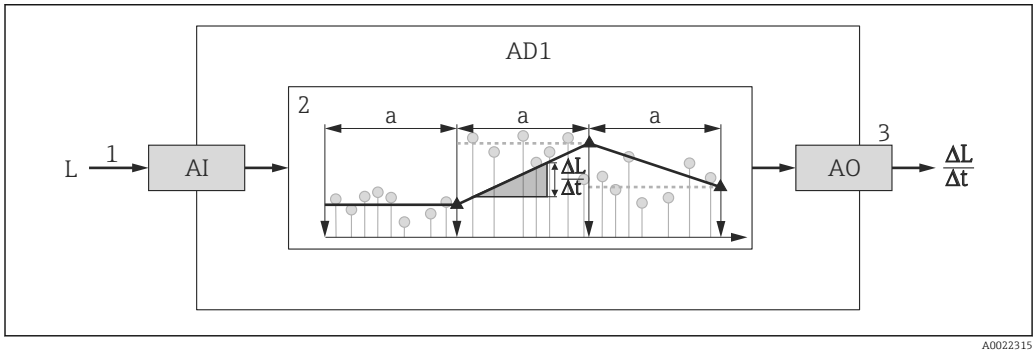
Example 1: Draining/filling speed

Only one Advanced Diagnostic Block is needed for this application. In the example this is **Adv.diagn. 1 (→ 213)**. However, **Adv.diagn. 2 (→ 213)** could be used just as well.

The level change rate (i.e. draining or filling speed) allows the customer to instantly realize whether or not the level is changing, and at which rate. The rate at which the level is changing must be observed as powerful pumps can create significant over and underpressure in a tank. Pressure relieve valves can only operate properly up to a certain level change rate. This is in particular valid for almost emptied tanks. The level change rate is also an intermediate result for calculating transfer estimates, such as time to fill, time to empty, time to target, etc.

Basic idea

The Advanced Diagnostics is used to calculate the draining or filling speed from the measured level. The result can be transmitted via the current output or the HART communication interface.



47 *Calculation of the draining or filling speed*

1 *Allocation of the (linearized) level to Advanced Diagnsotic Block AD1*
2 *Calculation of the draining or filling speed ΔL/Δt within the sampling interval a.*
3 *ΔL/Δt can be transmitted via the current output or the HART communication interface.*

Configuration of the calculation

The calculation of the rate of level change is configured as follows:

1. Select **Assign signal 1** = **Level linearized**.
2. Select **Link AD 1 to** = **None** (= factory setting)
3. Define **Sample time 1** in accordance with the expected draining or filling speed.
4. Select **Calc. type 1** = **Slope**.
5. Select a suitable option in **Calc. unit 1**, e.g.: **"Level unit" / s**

As the rate of level change is not to be checked for limit violation, the following parameters may retain their factory settings:
- **Check mode 1**
- **Stat. AD event (→ 220)**
- **Evt behaviour (→ 220)**
- **Alarm delay (→ 220)**

With this configuration, the **Maximum value 1** and **Minimum value 1** drag indicators display the maximum or minimum value the rate of lavel change has obtained. Positive values indicate filling (rising level), negative values indicate draining (falling level). If required, the drag indicators can be reset by the **Reset min/max 1** parameter.

Allocation of the calculated rate of level change to the current output

1. Navigate to the following submenu: Expert → Output → Curr.output 1.
2. Select **Assign curr.** = **Analog out. AD 1**.
3. Select **Turn down** = **On**.
4. Enter maximum expected draining speed (negative value) in **4 mA value**.
5. Enter maximum expected filling speed (positive value) in **20 mA value**.

With this configuration, the rate of level change is transmitted via the current output. The relationship between the rate of level change and the output current is as follows:

$$\frac{\Delta L}{\Delta t} = \frac{5W_4 - W_{20}}{4} + \frac{W_{20} - W_4}{16\ mA}\ I$$

A0022342

Where:
- $\Delta L/\Delta t$: Rate of level change [8)]
- W_4 : **4 mA value**
- W_{20} : **20 mA value**
- I: Output current

In the case of a constant level ($\Delta L/\Delta t = 0$) the current is:

$$I_0 = 4\ mA - \frac{W_4}{W_{20} - W_4}\ 16\ mA$$

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Allocation of the calculated rate of level change to the HART output

1. Navigate to the following submenu: Expert → Communication → Output
2. Select **Assign PV (→ 🖹 172)** = **Analog out. AD 1**.

With this configuration, the **Primary var (PV)** parameter (→ 🖹 172) displays the calculated filling or draining speed. Positive values indicate filling; negative values indicate draining.

Instead of PV, it is also possible to allocate the rate of level change to SV, TV or QV.

8) Negative values: draining speed; Positive values: filling speed

Example 2: Foam detection

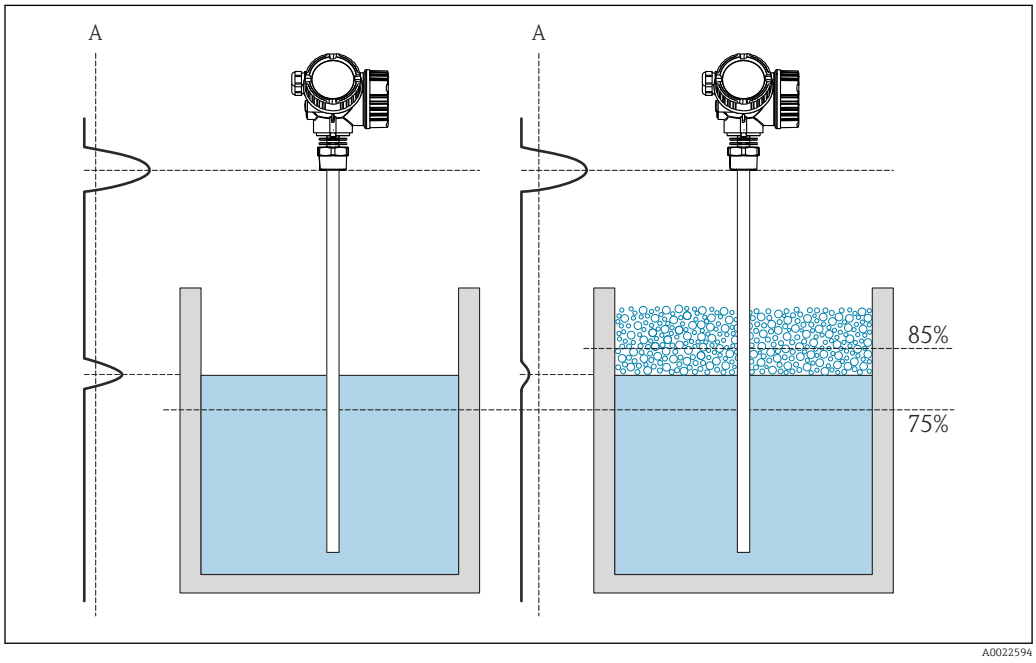
In this example, both Advance Diagnostic Blocks are used.

Preconditions

- The process runs at a fixed level (in the example: 80 %)
- If foam occurs during the operation, the vessel should automatically be sprinkled with water from the top or an antifoam agent should be added to dissolve the foam.

Basic idea

The echo amplitude decreases in the case of foam formation. This can be used by the Advanced Diagnostics to detect the foam. The foam detection, however, should only be active as long as the level is between 75 % and 85 %.



48 *Decrease of the amplitude in case of foam formation*

A Amplitude threshold for foam detection

Configuration of the level monitoring

In order to ensure that the level is within the correct range, configure the **Adv.diagn. 1** submenu (→ 213) submenu as follows:

1. Navigate to the **Adv.diagn. 1** submenu (→ 213)
2. Select **Assign signal 1** = **Level linearized**.
3. Select **Check mode 1** = **Out of range**
4. Set **Upper limit 1** = 85 %.
5. Set **Lower limit 1** = 75 %.

Check mode 1 = **Out of range** checks whether the level is outside a defined range. As long as this is the case, the block outputs "0" (INACTIVE). If the level gets into the defined range, the block outputs "1" (ACTIVE).

Configuration of the foam detection

For the foam detection, configure the **Adv.diagn. 2** submenu (→ 213) as follows:

1. Select **Assign signal 2** = **Relat.echo ampl.**.

2. Use the **Minimum value 2** parameter to observe the echo amplitude for the specified level (80 % in the example) for a while and determine a suitable lower limit for the amplitude (130 mV in the example).
3. Select **Calc. type 2** = **Mean**.
4. Enter **Sample time 2** = "60 s".
5. Select **Check mode 2** = **Lower limit**.
6. Enter the amplitude limit determined in step 2 into the **Lower limit 2** parameter (130 mV in the example).

With these settings, the Advanced Diagnostic Block behaves as follows:
- If the amplitude is above 130 mV (i.e.: no foam), the block assumes the digital value "0" (INACTIVE).
- If the amplitude is below 130 mV (i.e.: foam present), the block assumes the digital value "1" (ACTIVE).

Configuration of the block linking

The linking logic is configured in the **Adv.diagn. 2** submenu (→ 213):

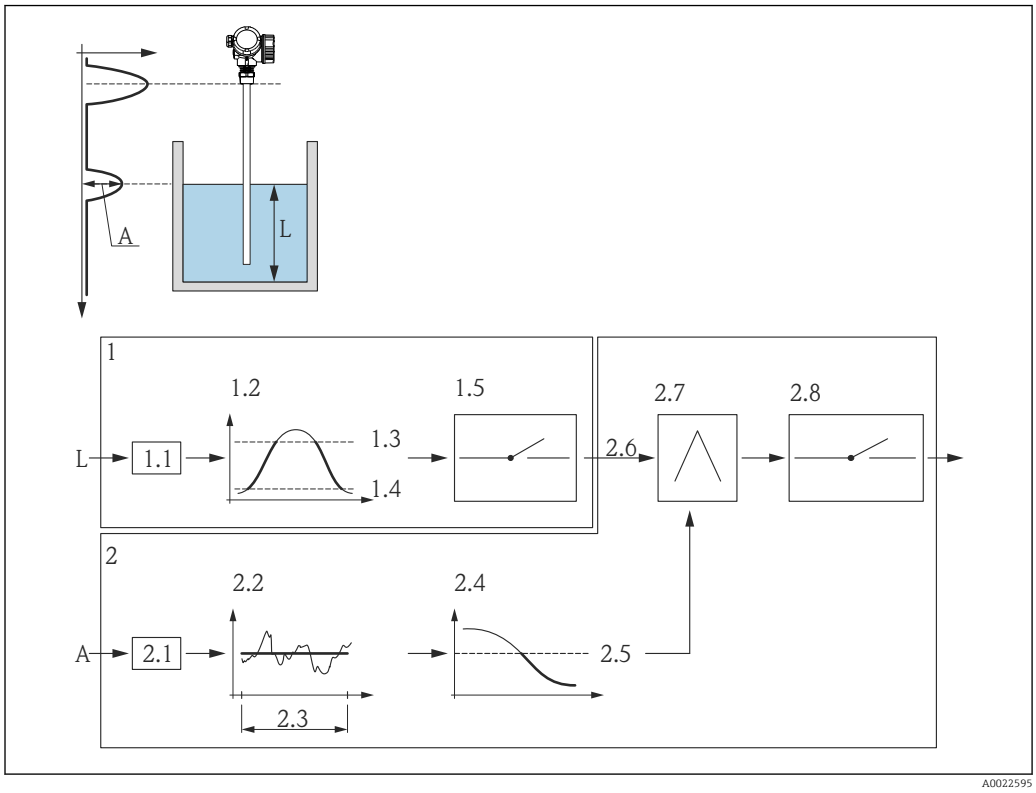
1. Select **Link AD 2 to** = **Digital out AD 1**.
2. **Select Link. logic AD 2** = **AND**.

With this configuration the output of **Advanced Diagnostics 2** assumes the following value:
- 0 (INACTIVE) - if at least one of the two blocks is in the "0" (INACTIVE) status.
- 1 (ACTIVE) - if both blocks are in the "1" (ACTIVE) status.
  For the example this means:
  - A diagnostic signal is output, if the level is within the defined range and the signal amplitude is below the threshold (i.e. foam is present).
  - If, on the other hand, the level is out of the defined range or if the signal amplitude exceeds the threshold (i.e. no foam), **no** diagnostic signal is transmitted via the switch output.

The digital output signal of **Adv.diagn. 2** can be linked to the switch output of the device:

Expert → Output → Switch output → Assign status (0485) = Digital out AD 2

Overview: Foam detection with the advanced diagnostics

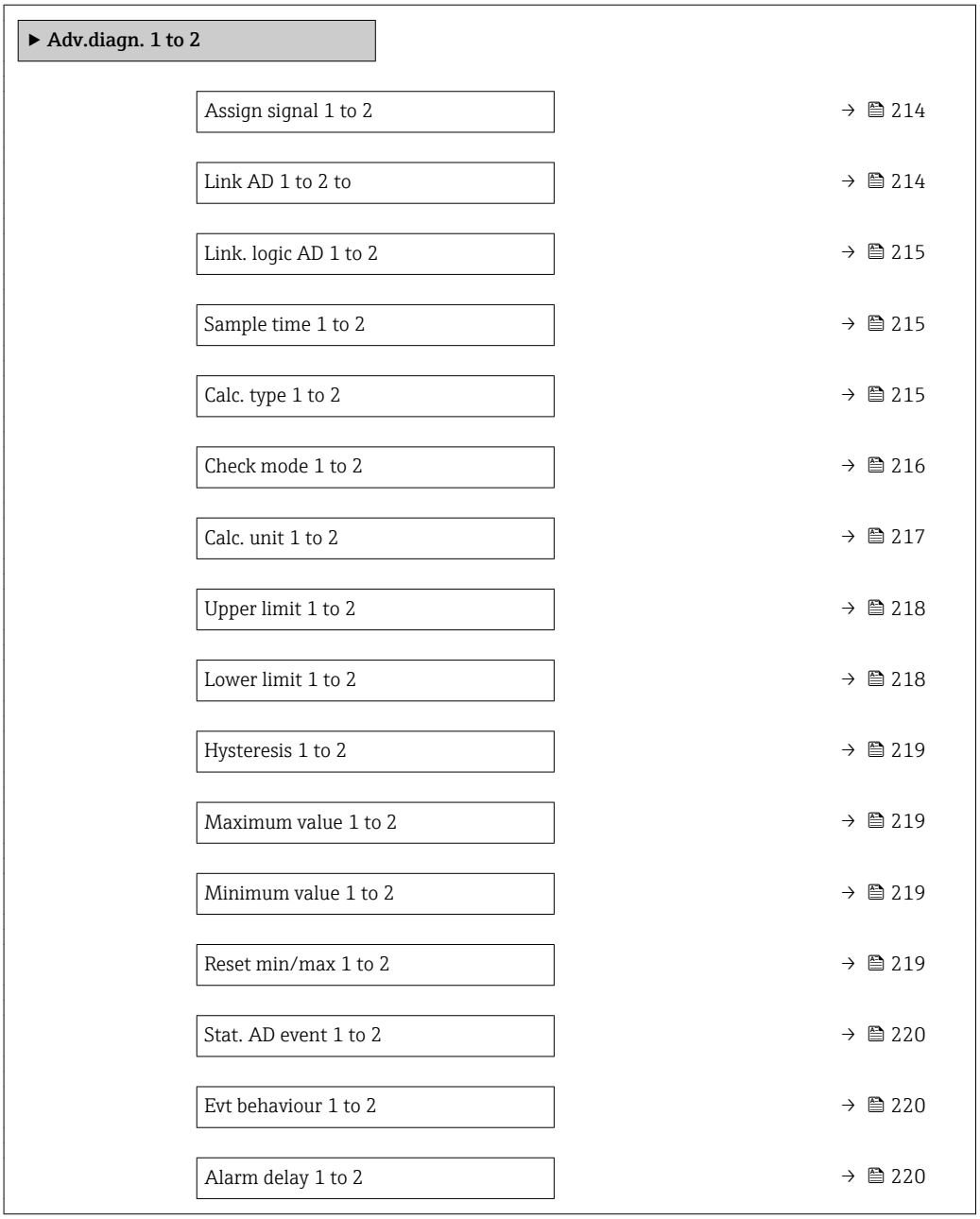


49 *Configuration of the Advanced Diagnostics for foam detection*

L Level
A Amplitude
1 Advanced diagnostics 1: Monitoring the level
1.1 "Assign signal 1" = "Relat.echo ampl."
1.2 "Check mode 1" = "Out of range"
1.3 "Upper limit 1" = 85 %
1.4 "Lower limit 1" = 75 %
1.5 Digital output of Advanced Diagnostics 1
2 Advanced Diagnostics 2: Monitoring the amplitude
2.1 "Assign signal 2" = "Relat.echo ampl."
2.2 "Calc. type 2" = "Mean"
2.3 "Sample time 2" = 60 s
2.4 "Check mode 2" = "Lower limit"
2.5 "Lower limit 2" = 130 mV
2.6 "Link AD 2 to" = "Digital out AD 1"
2.7 "Link. logic AD 2" = "AND"
2.8 Digital output of Advanced Diagnostics 2

Structure of the submenu

Navigation Expert → Diagnostics → Adv.diagn. 1 to 2



Description of parameters

Navigation Expert → Diagnostics → Adv.diagn. 1 to 2

Assign signal 1 to 2

Navigation Expert → Diagnostics → Adv.diagn. 1 to 2 → Assign signal 1 to 2 (11179–1 to 2)

Description Allocate a measuring variable to the Advanced Diagnostic Block.

Selection
- None
- Level linearized
- Distance
- Unfiltered dist.
- Interf. lineariz
- Interface dist.
- Unfilt. I. dist.
- Thickn.upp.layer
- Electronic temp.
- Measur. cap.
- Relat.echo ampl.
- Abs. echo ampl.
- Abs.interf.ampl.
- Rel.interf.ampl.
- Abs. EOP ampl.
- EOP shift
- Noise of signal
- Measur. curr.
- Terminal volt.
- Calc. DC value
- Sensor debug

Factory setting None

Link AD 1 to 2 to

Navigation Expert → Diagnostics → Adv.diagn. 1 to 2 → Link AD 1 to 2 to (11180–1 to 2)

Description Link the digital input (DI) of the Advanced Diagnostic Block to the digital output (DO) of the other Advanced Diagnostic Block.

Selection
- None
- Digital out AD 1
- Digital out AD 2

Factory setting None

Link. logic AD 1 to 2

Navigation Expert → Diagnostics → Adv.diagn. 1 to 2 → Link. logic AD 1 to 2 (11181–1 to 2)

Prerequisite **Link AD to (→ 214)** = **Digital out AD 1** oder **Digital out AD 2**

Description Select linking logic between the two Advanced Diagnostic Blocks.

Selection
- AND
- OR

Factory setting AND

Sample time 1 to 2

Navigation Expert → Diagnostics → Adv.diagn. 1 to 2 → Sample time 1 to 2 (11187–1 to 2)

Prerequisite **Assign signal (→ 214)** ≠ **None**

Description Specify sampling interval for the calculation.

User entry 1 to 3 600 s

Factory setting 10 s

Calc. type 1 to 2

Navigation Expert → Diagnostics → Adv.diagn. 1 to 2 → Calc. type 1 to 2 (11174–1 to 2)

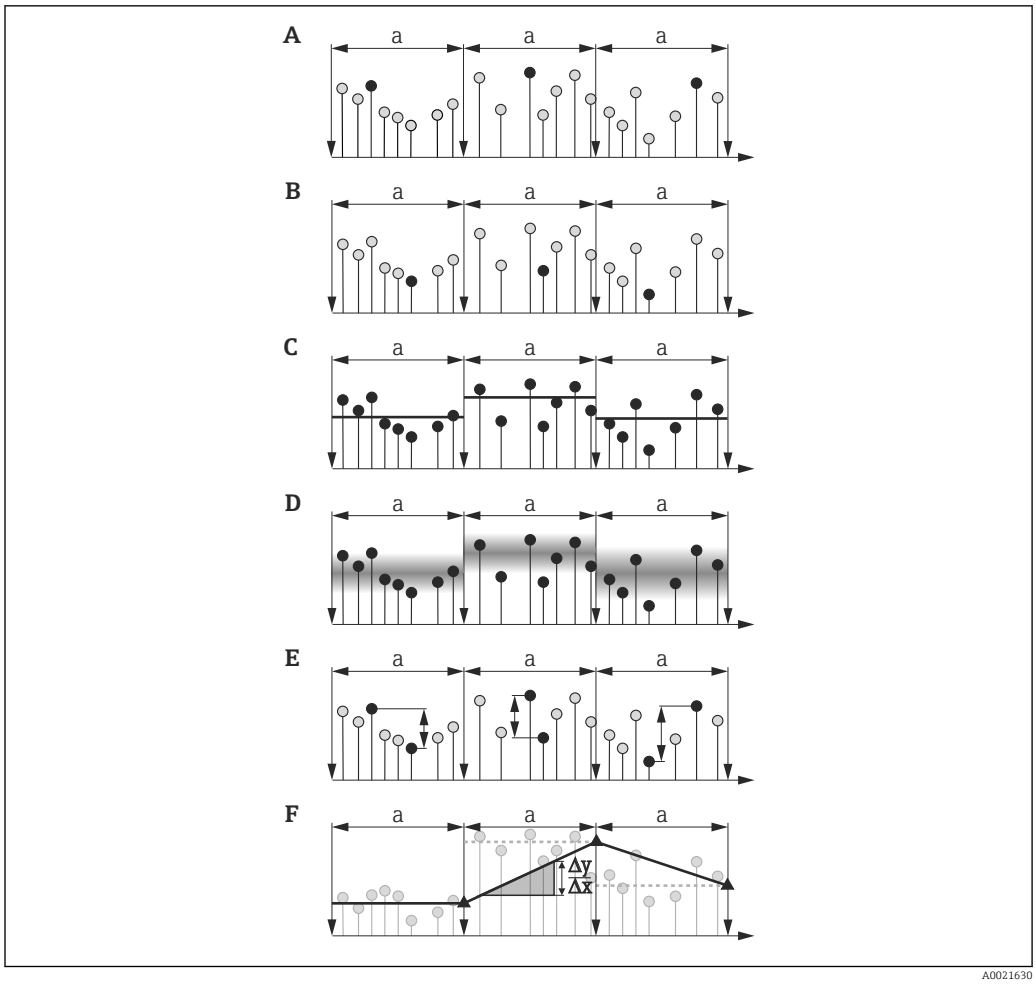
Prerequisite **Assign signal (→ 214)** ≠ **None**

Description Select quantity to be calculated from the measured variable.

Selection
- Off
- Maximum
- Minimum
- Mean
- Std. deviation
- Diff.Max. - Min.
- Slope

Factory setting Off

Additional information



50 *Options of the "Calc. type " parameter*

a Sample time (→ 215)
A "Calc. type " = "Maximum"
B "Calc. type " = "Minimum"
C "Calc. type " = "Mean"
D "Calc. type " = "Std. deviation"
E "Calc. type " = "Diff.Max. - Min."
F "Calc. type " = "Slope"

The calculation is performed based on the sampling interval defined in the **Sample time** parameter (→ 215).

Check mode 1 to 2

Navigation Expert → Diagnostics → Adv.diagn. 1 to 2 → Check mode 1 to 2 (11175–1 to 2)

Prerequisite **Assign signal (→ 214) ≠ None**

Description Define check mode for limit monitoring.

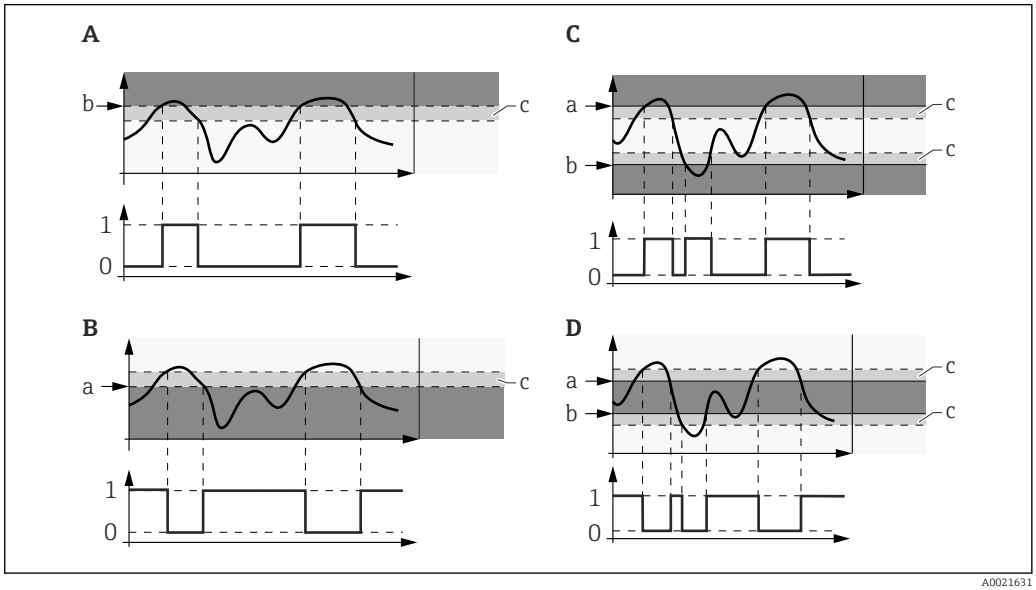
Selection

- Off
- Upper limit
- Lower limit
- In range
- Out of range

Factory setting

Off

Additional information



51 *Limit monitoring in the Advanced Diagnostic Block*

0 Status of digital output: 0 ("INACTIVE")
1 Status of digital output: 1 ("ACTIVE")
a Upper limit (→ 218)
b Lower limit (→ 218)
c Hysteresis (→ 219)
A "Check mode " = "Lower limit"
B "Check mode " = "Upper limit"
C "Check mode " = "In range"
D "Check mode " = "Out of range"

If a calculation has been selected in the **Calc. type** parameter (→ 215), the check does not refer to the assigned measuring variable but to the quantity calculated from it.

Calc. unit 1 to 2

Navigation

Expert → Diagnostics → Adv.diagn. 1 to 2 → Calc. unit 1 to 2 (11188–1 to 2)

Prerequisite

Assign signal (→ 214) ≠ None

Description

Select unit for the calculation.

Selection

Dependent on the following parameters:
- Assign diagnostic signal (→ 214)
- Calculation type (→ 215)

Factory setting
Dependent on the following parameters:
- Assign diagnostic signal (→ 214)
- Calculation type (→ 215)

Upper limit 1 to 2

Navigation
Expert → Diagnostics → Adv.diagn. 1 to 2 → Upper limit 1 to 2 (11182–1 to 2)

Prerequisite
Check mode parameter (→ 216) has one of the following values:
- Upper limit
- In range
- Out of range

Description
Specify upper limit for the limit monitoring.

User entry
Dependent on the following parameters:
- Assign diagnostic signal (→ 214)
- Calculation type (→ 215)

Factory setting
Dependent on the following parameters:
- Assign diagnostic signal (→ 214)
- Calculation type (→ 215)

Lower limit 1 to 2

Navigation
Expert → Diagnostics → Adv.diagn. 1 to 2 → Lower limit 1 to 2 (11184–1 to 2)

Prerequisite
Check mode parameter (→ 216) has one of the following values:
- Lower limit
- In range
- Out of range

Description
Define lower limit for the limit monitoring.

User entry
Dependent on the following parameters:
- Assign diagnostic signal (→ 214)
- Calculation type (→ 215)

Factory setting
Dependent on the following parameters:
- Assign diagnostic signal (→ 214)
- Calculation type (→ 215)

Hysteresis 1 to 2

Navigation Expert → Diagnostics → Adv.diagn. 1 to 2 → Hysteresis 1 to 2 (11178–1 to 2)

Prerequisite **Check mode** parameter (→ 216) has one of the following values:
- Upper limit
- Lower limit
- In range
- Out of range

Description Select hysteresis for the limit monitoring.

User entry Dependent on the following parameters:
- Assign diagnostic signal (→ 214)
- Calculation type (→ 215)

Factory setting Dependent on the following parameters:
- Assign diagnostic signal (→ 214)
- Calculation type (→ 215)

Maximum value 1 to 2

Navigation Expert → Diagnostics → Adv.diagn. 1 to 2 → Maximum value 1 to 2 (11183–1 to 2)

Prerequisite **Assign signal (→ 214) ≠ None**

Description Indicates the maximum value the assigned measuring variable has obtained in the past (drag indicator).

Minimum value 1 to 2

Navigation Expert → Diagnostics → Adv.diagn. 1 to 2 → Minimum value 1 to 2 (11185–1 to 2)

Prerequisite **Assign signal (→ 214) ≠ None**

Description Indicates minimum value the assigned measuring variable has obtained in the past (drag indicator).

Reset min/max 1 to 2

Navigation Expert → Diagnostics → Adv.diagn. 1 to 2 → Reset min/max 1 to 2 (11186–1 to 2)

Prerequisite **Assign signal (→ 214) ≠ None**

Description Reset drag indicators (**Maximum value (→ 219)** and/or **Minimum value (→ 219)**).

Selection
- Off
- Reset max.
- Reset min.
- Reset min/max

Factory setting Off

Stat. AD event 1 to 2

Navigation Expert → Diagnostics → Adv.diagn. 1 to 2 → Stat. AD event 1 to 2 (11176–1 to 2)

Prerequisite **Assign signal (→ 214) ≠ None**

Description Assign a category according to NAMUR NE107 to the event of the Advanced Diagnostic Block.

Selection
- Failure (F)
- Mainten. req.(M)
- Funct. check (C)
- Out of spec. (S)

Factory setting Mainten. req.(M)

Evt behaviour 1 to 2

Navigation Expert → Diagnostics → Adv.diagn. 1 to 2 → Evt behaviour 1 to 2 (11177–1 to 2)

Prerequisite **Assign signal (→ 214) ≠ None**

Description Assign an event behavior to the event of the Advanced Diagnostic Block.

Selection
- Off
- Alarm
- Warning
- Logbook only

Factory setting Warning

Alarm delay 1 to 2

Navigation Expert → Diagnostics → Adv.diagn. 1 to 2 → Alarm delay 1 to 2 (11171–1 to 2)

Prerequisite **Assign signal (→ 214) ≠ None**

Description Define alarm delay for the Advanced Diagnostic Block.

User entry 0.0 to 3 600.0 s

Factory setting 10.0 s

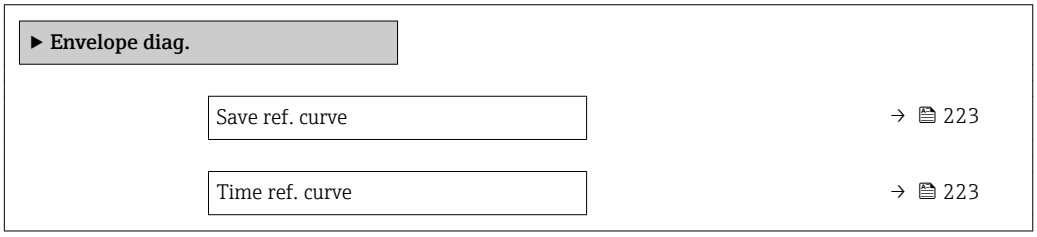
4.7.12 "Envelope diag." submenu

After the configuration of the measurement it is recommended to record the current envelope curve as a reference curve. The reference curve can be used later for diagnostic purposes. To record the reference curve use the **Save ref. curve** parameter (→ 223).

The reference curve can only be displayed in the envelope curve diagram of FieldCare after it has been loaded from the device into FieldCare. This is performed by the "Load Reference Curve" function in FieldCare:

Structure of the submenu

Navigation Expert → Diagnostics → Envelope diag.



Description of parameters

Navigation Expert → Diagnostics → Envelope diag.

Save ref. curve

Navigation
Expert → Diagnostics → Envelope diag. → Save ref. curve (1218)
Expert → Diagnostics → Envelope diag. → Save ref. curve (1218)

Description
Save current envelope curve as reference curve.

Selection
- No
- Yes

Factory setting
No

Additional information
Meaning of the options
- No
  No action
- Yes
  The current envelope curve is saved as reference curve.

Time ref. curve

Navigation
Expert → Diagnostics → Envelope diag. → Time ref. curve (1232)
Expert → Diagnostics → Envelope diag. → Time ref. curve (1232)

Description
Indicates at which time the existing reference curve has been recorded.

Index

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