Operating Instructions
Prosonic S FMU90 HART

Level measurement
Alternating pump control
Rake control

HART
COMMUNICATION PROTOCOL

Endress+Hauser

People for Process Automation
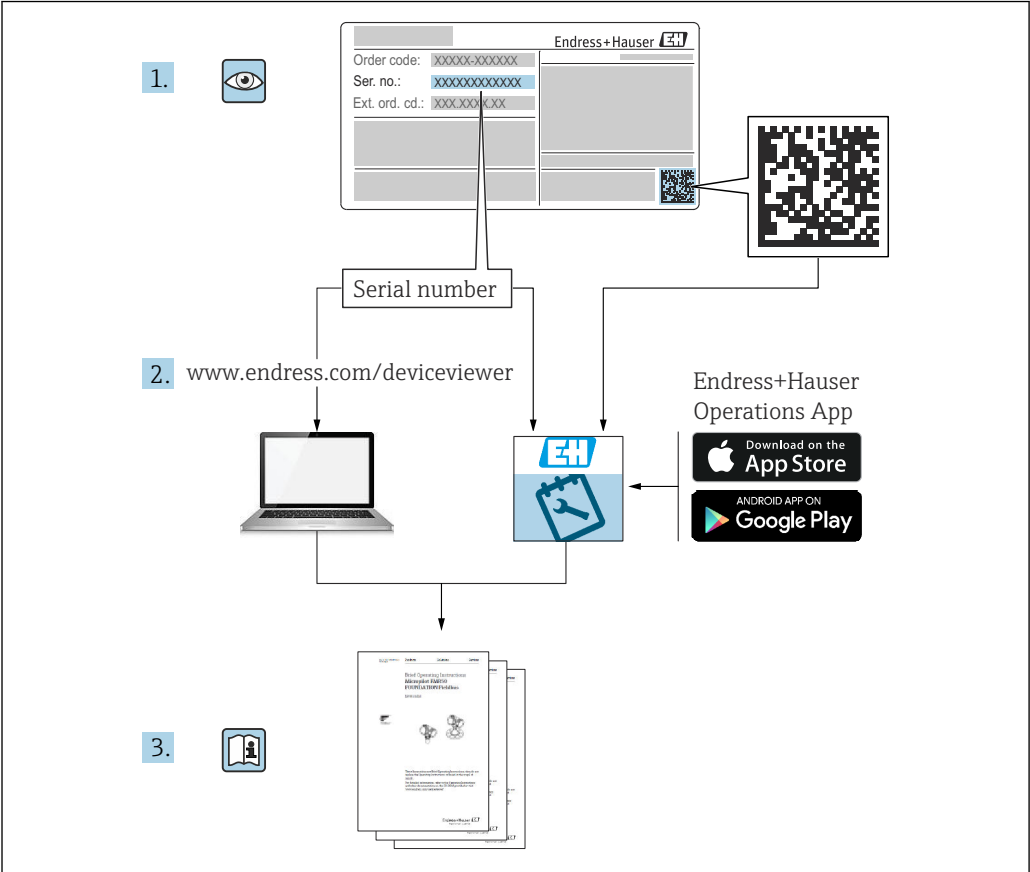
A0023555

Table of contents

1   Important document information

1.1   Document function

These Operating Instructions provide all of the information that is required in various
phases of the life cycle of the device including:
- Product identification
- Incoming acceptance
- Storage
- Installation
- Connection
- Operation
- Commissioning
- Troubleshooting
- Maintenance
- Disposal

1.2   Symbols used

1.2.1   Safety symbols

⚠ DANGER

This symbol alerts you to a dangerous situation. Failure to avoid this situation will result in
serious or fatal injury.

⚠ WARNING

This symbol alerts you to a dangerous situation. Failure to avoid this situation can result in
serious or fatal injury.

⚠ CAUTION

This symbol alerts you to a dangerous situation. Failure to avoid this situation can result in
minor or medium injury.

NOTICE

This symbol contains information on procedures and other facts which do not result in
personal injury.

1.2.2   Electrical symbols

∿

Alternating current

≂

Direct current and alternating current

⎓

Direct current

⏚

Ground connection

A grounded terminal which, as far as the operator is concerned, is grounded via a
grounding system.

⏚ **Protective earth (PE)**

Ground terminals that must be connected to ground prior to establishing any other
connections.

The ground terminals are located on the interior and exterior of the device:
- Interior ground terminal: protective earth is connected to the mains supply.
- Exterior ground terminal: device is connected to the plant grounding system.

1.2.3   Tool symbols

Phillips head screwdriver

Flat blade screwdriver

Torx screwdriver

Allen key

Open-ended wrench

1.2.4   Symbols for certain types of information and graphics

Permitted
Procedures, processes or actions that are permitted

Preferred
Procedures, processes or actions that are preferred

Forbidden
Procedures, processes or actions that are forbidden

Tip
Indicates additional information

Reference to documentation

Reference to graphic

▶
Notice or individual step to be observed

1. , 2. , 3.
Series of steps

↳
Result of a step

Visual inspection

Operation via operating tool

Write-protected parameter

1, 2, 3, ...
Item numbers

A, B, C, ...
Views

⚠ → 📖 **Safety instructions**
Observe the safety instructions contained in the associated Operating Instructions

Temperature resistance of the connection cables
Specifies the minimum value of the temperature resistance of the connection cables

1.3   Documentation

The following documentation types are available in the Downloads area of the Endress +Hauser website (www.endress.com/downloads):

For an overview of the scope of the associated Technical Documentation, refer to the following:
- *W@M Device Viewer* (www.endress.com/deviceviewer): Enter the serial number from nameplate
- *Endress+Hauser Operations App*: Enter the serial number from the nameplate or scan the 2D matrix code (QR code) on the nameplate

1.3.1   Technical Information (TI)

Planning aid
The document contains all the technical data on the device and provides an overview of the accessories and other products that can be ordered for the device.

1.3.2   Brief Operating Instructions (KA)

Guide that takes you quickly to the 1st measured value
The Brief Operating Instructions contain all the essential information from incoming acceptance to initial commissioning.

1.3.3   Safety Instructions (XA)

Depending on the approval, the following Safety Instructions (XA) are supplied with the device. They are an integral part of the Operating Instructions.

The nameplate indicates the Safety Instructions (XA) that are relevant to the device.

1.4   Registered trademarks

HART®
Registered trademark of the FieldComm Group, Austin, Texas, USA

2 Basic safety instructions

2.1 Designated use

Prosonic S FMU90 is a transmitter for ultrasonic sensors FDU90, FDU91, FDU91F, FDU92, FDU93 and FDU95. To support existing installations, the following sensors can also be connected: FDU80, FDU80F, FDU81, FDU81F, FDU82, FDU83, FDU84, FDU85, FDU86, FDU96.

Typical measuring tasks
- Level measurement in tanks and silos
- Conveyor belt
- Limit detection
- (Alternating) pump control, rake control

2.2 Installation, commissioning and operation

The device is designed to meet state-of-the-art safety requirements and complies with applicable standards and EC regulations. However, if it is used improperly or for applications for which it is not intended, application-related hazards may arise, e.g. product overflow due to incorrect installation or configuration. Installation, electrical connection, commissioning, operation and maintenance of the measuring system must therefore be carried out exclusively by trained specialists authorized to perform such work by the system operator. Technical personnel must have read and understood these Operating Instructions and must adhere to them. Modifications and repairs to the device may only be carried out if they are expressly permitted in the Operating Instructions.

2.3 Operational safety and process safety

Alternative monitoring measures must be taken to ensure operational safety and process safety during configuration, testing and maintenance work on the device.

2.3.1 Hazardous area

When using the measuring system in hazardous areas, the applicable national standards must be observed. The device is accompanied by separate "Ex documentation", which is an integral part of these Operating Instructions. The installation specifications, connection values and safety instructions listed in this supplementary documentation must be observed.

- Ensure that the technical personnel is sufficiently trained.
- Comply with the metrological and safety-related requirements for the measuring point.

The transmitter may only be mounted in suitable areas. Sensors with an approval for hazardous areas may be connected to transmitters that do not have an Ex approval.
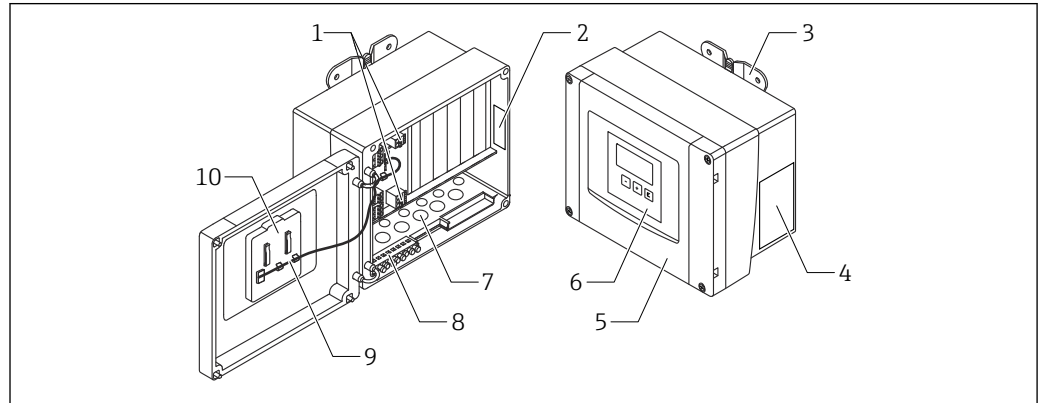
⚠ WARNING

Explosion Hazard
▶ Do not connect FDU83, FDU84, FDU85 and FDU86 sensors with an ATEX, FM, or CSA certificate to the Prosonic S transmitter.

3   Product description

3.1   Product layout: polycarbonate field housing

ℹ️ **Valid for:**
Order code 030 (housing, material)
Option 1 (PC field mounting, IP66 NEMA4x)

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🔲 *1   Parts of the Prosonic S in the polycarbonate field housing*

1   Terminals
2   Device designation and identification
3   Housing bracket
4   Nameplate
5   Cover of terminal compartment
6   Display and operating module
7   Precut openings for cable entries
8   Grounding terminal block
9   Display cable
10   Brief Operating Instructions

3.2   Product layout: aluminum field housing

ℹ️ **Valid for:**
Order code 030 (housing, material)
Option 3 (aluminum field mounting, IP66 NEMA4x)
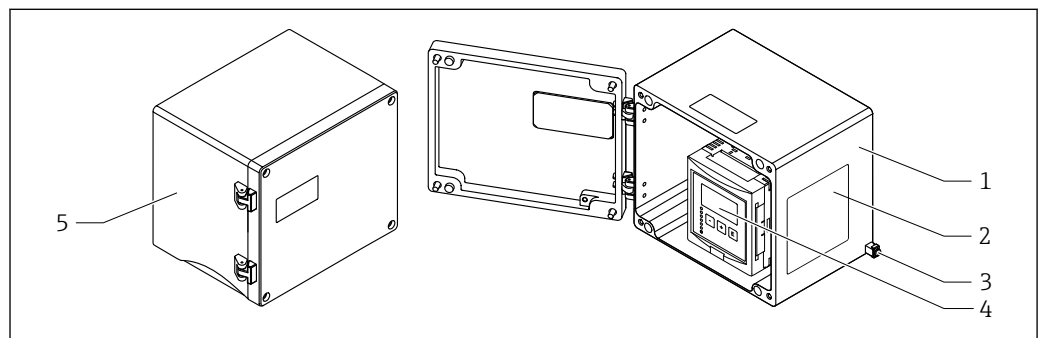
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🔲 *2   Parts of the Prosonic S in the aluminum field housing*

1   Aluminum field housing, open
2   Nameplate
3   Terminal for potential equalization (protective ground)
4   Display and operating module
5   Aluminum field housing, closed

3.3   Product layout: DIN rail housing

Valid for:
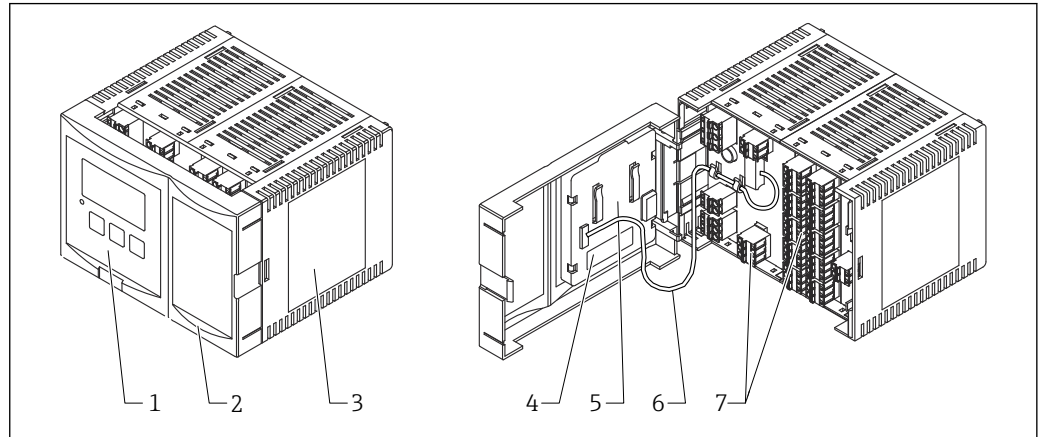Order code 030 (housing, material)
Option 2 (DIN rail mounting PBT, IP20)

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3   Parts of the Prosonic S in the DIN rail housing

1   Display and operating module
2   Cover of terminal compartment
3   Nameplate
4   Device designation and identification
5   Brief Operating Instructions
6   Display cable
7   Terminals

One possible version of the DIN rail housing is illustrated in the graphic above. The housing may be narrower or wider depending on the device version.

3.4   Product layout: remote display and operating module for cabinet door and panel mounting

Valid for:
Order code 040 (operation)
Option E (illuminated display + keypad, 96x96, panel mounting, IP65 at front)
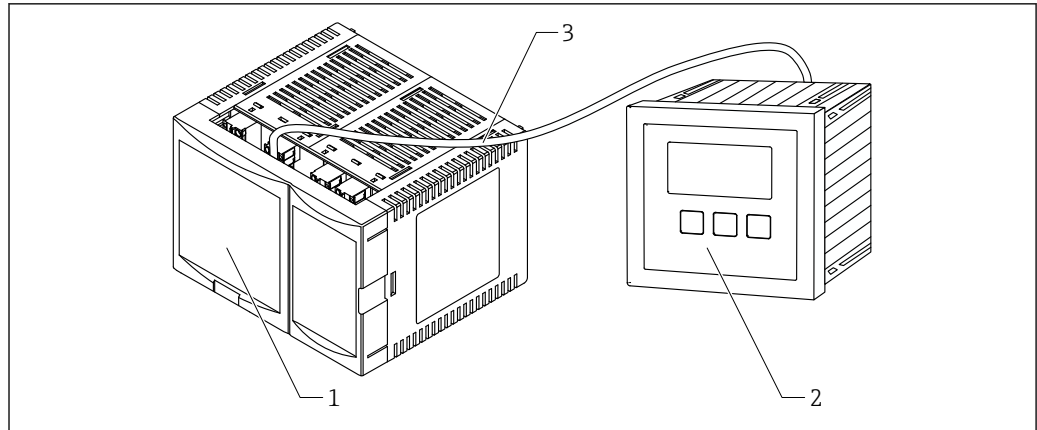
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⊡ 4   Parts of the Prosonic S with remote display and operating module

1   DIN rail housing without display and operating module
2   Remote display and operating module for mounting in a cabinet
3   The cable (3m [9.8 ft]) is supplied

One possible version of the DIN rail housing is illustrated in the graphic above. The housing may be narrower or wider depending on the device version.

4   Incoming acceptance and product identification

4.1   Incoming acceptance

Check the following during goods acceptance:
• Are the order codes on the delivery note and the product label identical?
• Are the goods undamaged?
• Do the data on the nameplate match the ordering information on the delivery note?
• If required (see nameplate): are the Safety Instructions (XA) provided?

ℹ️   If one of these conditions is not met, please contact your Endress+Hauser sales office.

4.2   Product identification

The following options are available for the identification of the measuring device:
• Nameplate specifications
• Order code with breakdown of the device features on the delivery note
• Enter the serial number on the nameplate into *W@M Device Viewer*
  (www.endress.com/deviceviewer): all the information about the measuring device is
  displayed.
• Enter the serial number on the nameplate into the *Endress+Hauser Operations App* or
  scan the 2-D matrix code (QR code) on the nameplate with the *Endress+Hauser
  Operations App*: all the information about the measuring device is displayed.

4.2.1   Nameplate
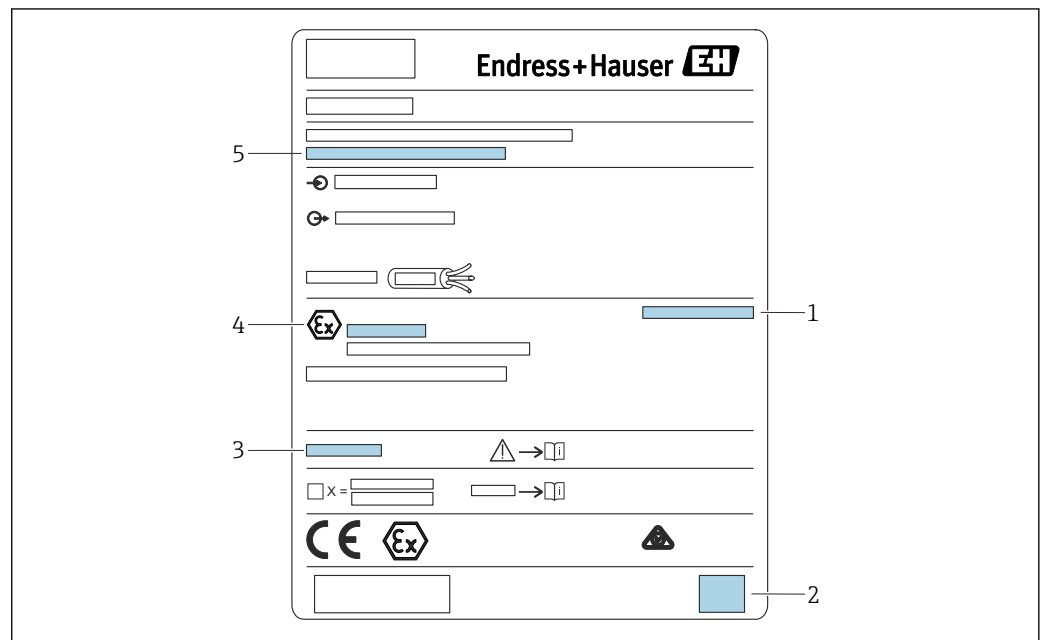
5   Nameplate

1   Degree of protection
2   2-D matrix code (QR code)
3   Reference to additional safety-related documentation
4   Identification marking according to ATEX Directive 2014/34/EC and type of protection
5   Serial number

4.3   Storage, transport

- Pack the device so that it is protected against impact for storage and transportation. The original packaging provides optimum protection.
- Permitted storage temperature: −40 to +60 ℃ (−40 to 140 ℉)

5 Installation

5.1 Mounting the polycarbonate field housing

Valid for:
Order code 030 (housing, material)
Option 1 (PC field mounting, IP66 NEMA4x)

5.1.1 Installation conditions

Dimensions of polycarbonate field housing
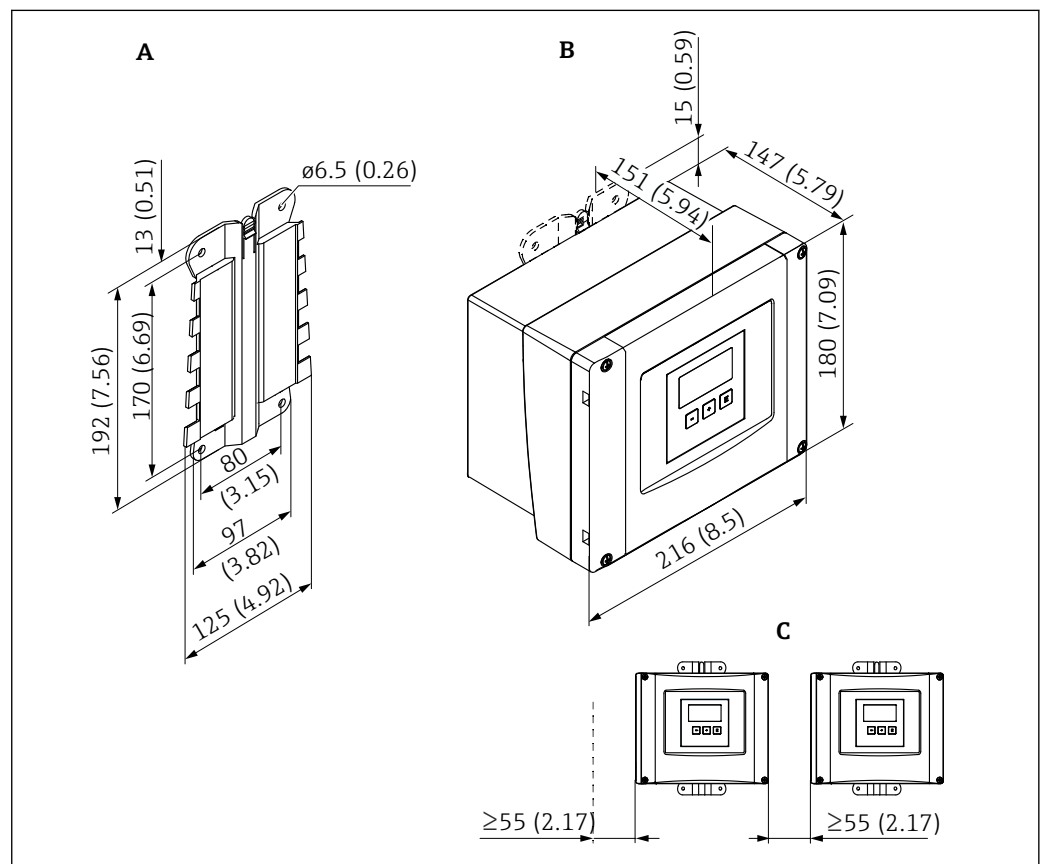
⚏ 6 *Dimensions of Prosonic S with polycarbonate field housing. Unit of measurement mm (in)*

A   Housing bracket (supplied), can also be used as a drilling template
B   Polycarbonate field housing
C   Minimum mounting clearance

Mount the housing bracket on a level surface so that it cannot become warped or bent. Otherwise it may be difficult or impossible to mount the polycarbonate field housing.

Mounting location

• Shaded location, protected from direct sunlight. Use a weather protection cover if necessary.
• If mounting outdoors: use a surge arrester.
• Altitude: install at a maximum altitude of 2 000 m (6 560 ft) over MSL
• Minimum clearance to the left: 55 mm (2.17 in); the housing cover cannot be opened otherwise.

5.1.2   Mounting the device

Wall mounting

- The housing bracket supplied can also be used as a drilling template.
- Mount the housing bracket on a level surface so that it cannot become warped or bent.
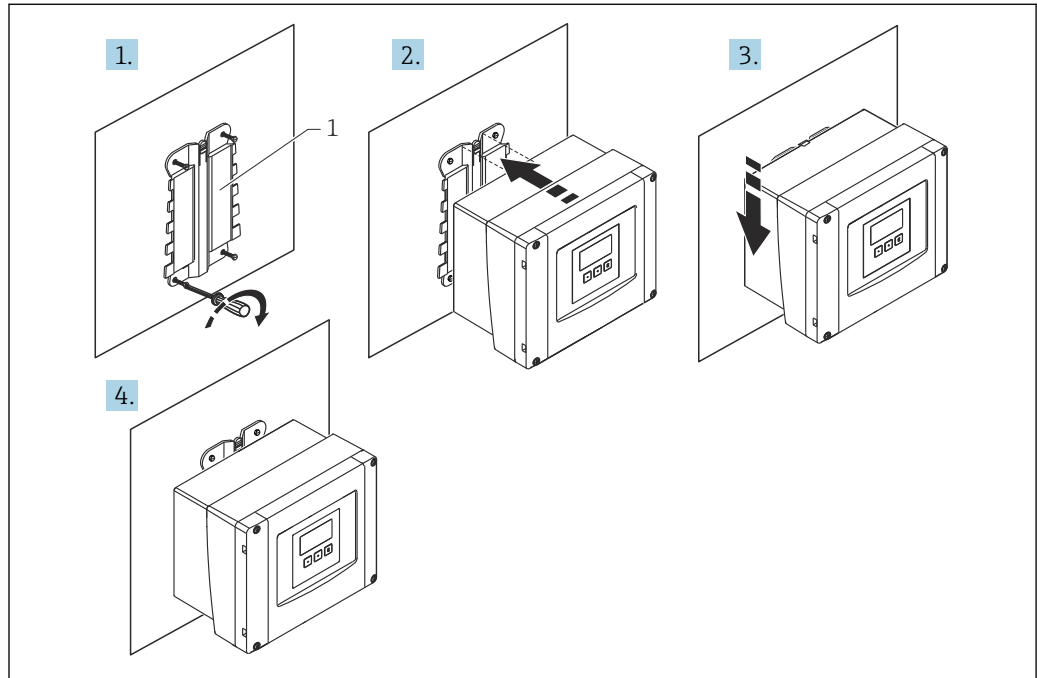
 7   Wall-mounted polycarbonate field housing

1   Housing bracket (supplied)

Post mounting
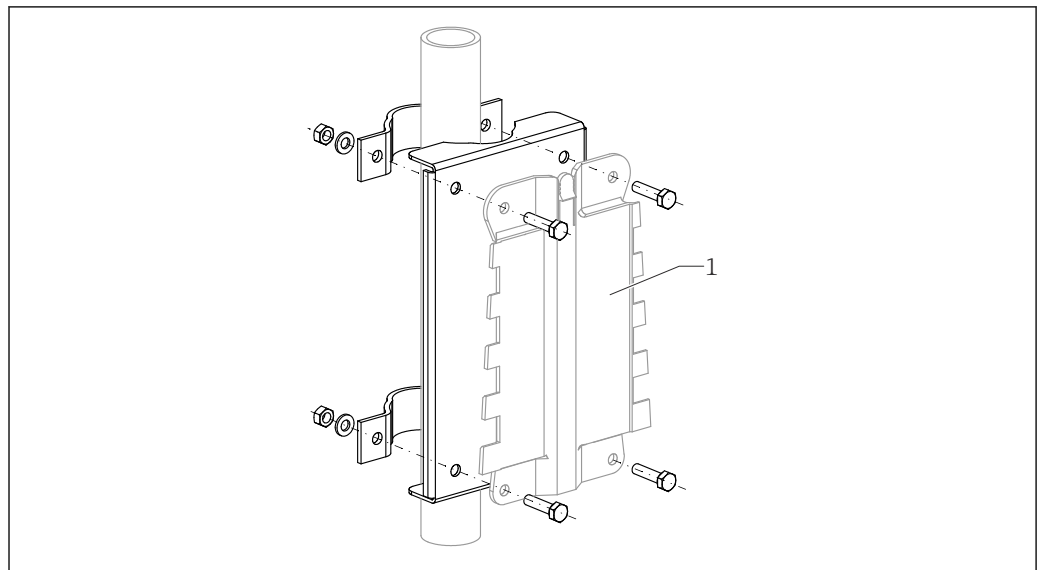
 8   Mounting plate for mounting the polycarbonate field housing on a post

1   Housing bracket (supplied)

5.2   Mounting the aluminum field housing

Valid for:

Order code 030 (housing, material)
Option 3 (aluminum field mounting, IP66 NEMA4x)

5.2.1   Installation conditions

Dimensions of the aluminum field housing
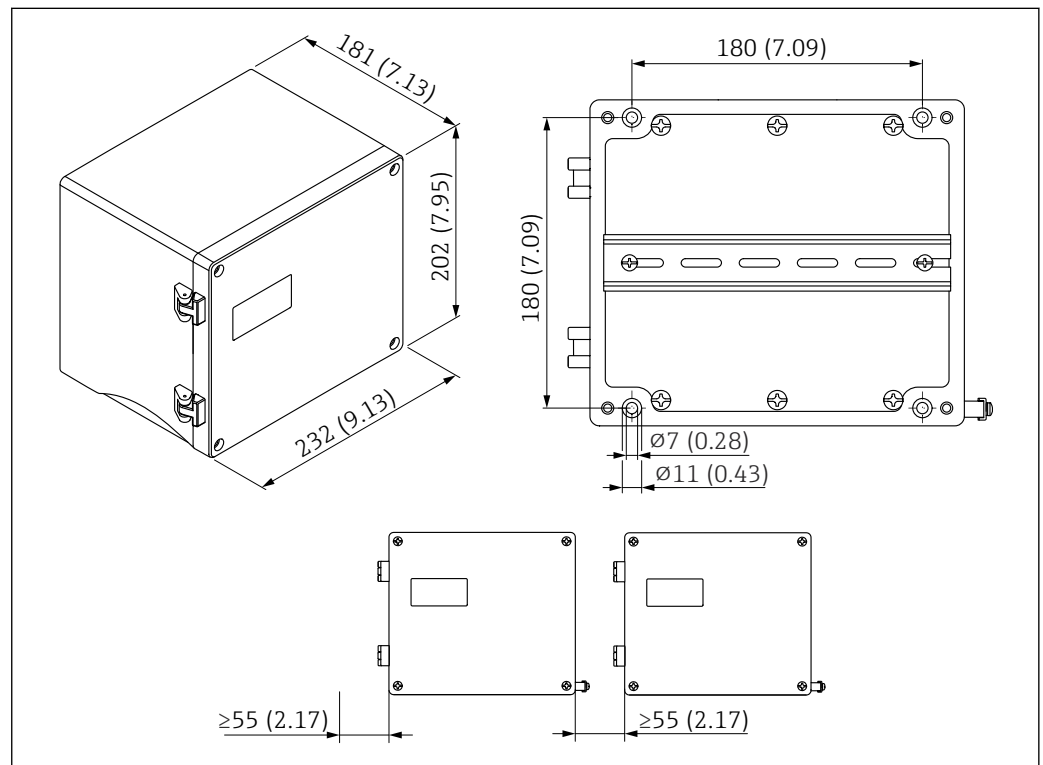
🖾 *9   Dimensions of Prosonic S with aluminum field housing. Unit of measurement mm (in)*

Mounting location

- Shaded location, protected from direct sunlight
- If mounting outdoors: use a surge arrester
- Altitude: install at a maximum altitude of 2 000 m (6 560 ft) over MSL
- Minimum clearance to the left: 55 mm (2.17 in); the housing cover cannot be opened otherwise

5.2.2   Mounting the device
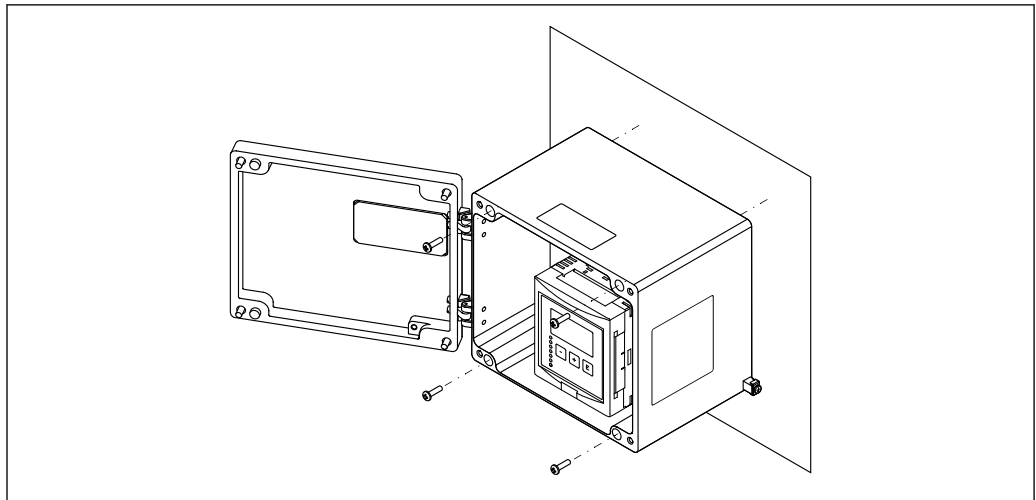
A0033331

☒ *10   Wall-mounted aluminum field housing*

5.3   Mounting the DIN rail housing

Valid for:
Order code 030 (housing, material)
Option 2 (DIN rail mounting PBT, IP20)

⚠ WARNING

The DIN rail housing meets protection class IP06.

If the housing is damaged, there is a risk of electric shock at live parts.

▶ Install the device in a stable cabinet.

5.3.1   Installation conditions
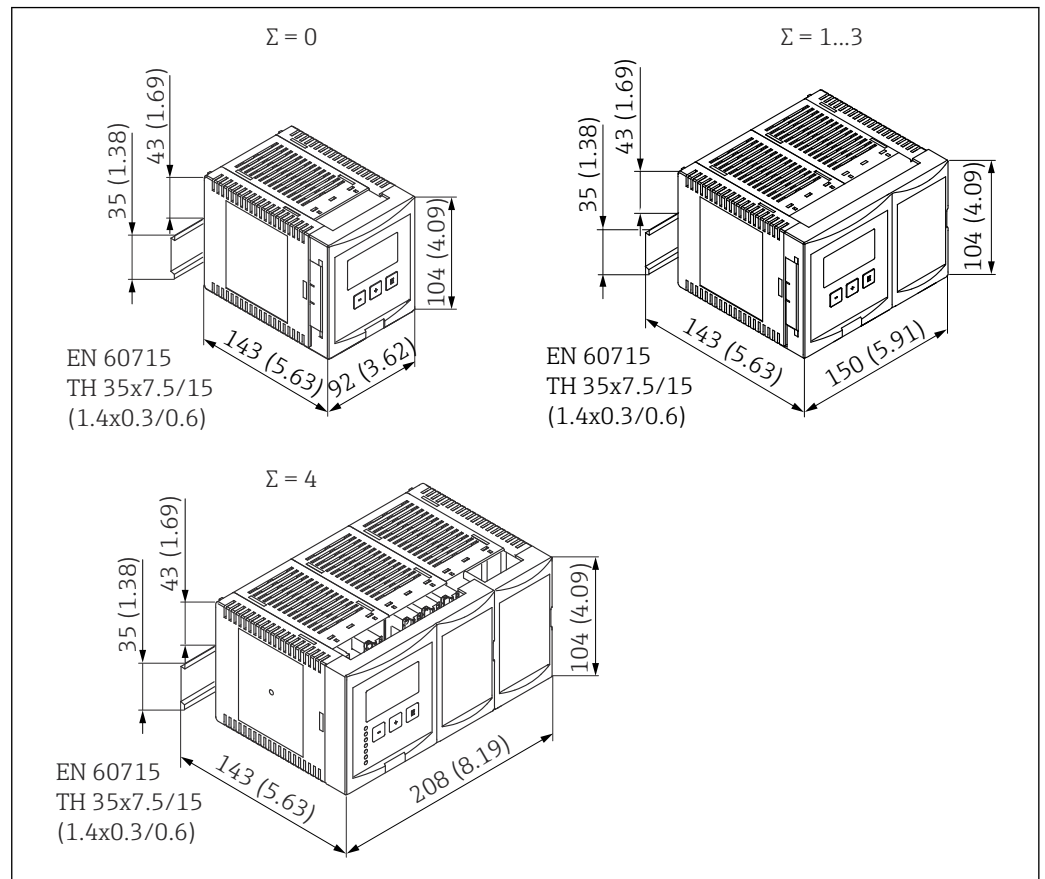
Dimensions

⊞ *11   Dimensions of Prosonic S with DIN rail housing; Σ: number of additional connection modules. Unit of measurement mm (in)*

Mounting location

- In cabinet outside hazardous areas
- At a sufficient distance from high-voltage electric cables, motor cables, contactors or frequency converters
- Altitude: install at a maximum altitude of 2 000 m (6 560 ft) over MSL
- Minimum clearance to the left: 10 mm (0.4 in); the housing cover cannot be opened otherwise.

5.3.2 Mounting the device

A0032559
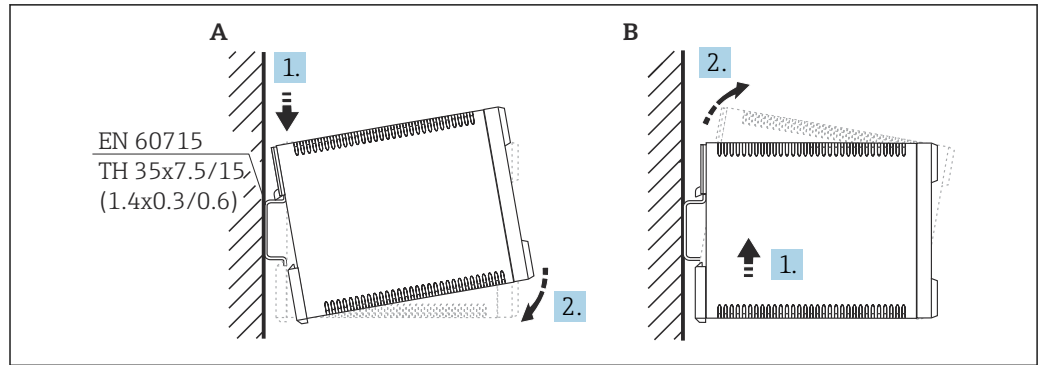
⊠ *12   Mounting/disassembling the DIN rail housing. Unit of measurement mm (in)*

A   Installation
B   Disassembly

5.4 Installation of the remote display and operating module

ℹ️ Valid for:
Order code 040 (operation)
Option E (illuminated display + keypad, 96x96, panel mounting, IP65 at front)

5.4.1 Mounting methods

Mounting in appropriate installation opening

A0032560
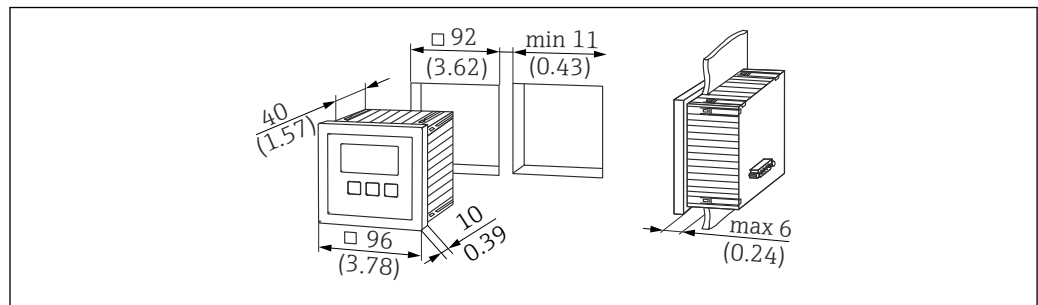
⊠ *13   Opening for remote display and operating module. Unit of measurement mm (in)*

Mounting in remote display of Prosonic FMU860/861/862

- This mounting method is suitable if FMU9x replaces the FMU86x predecessor model (both with a remote display module).
- Order number for adapter plate: 52027441
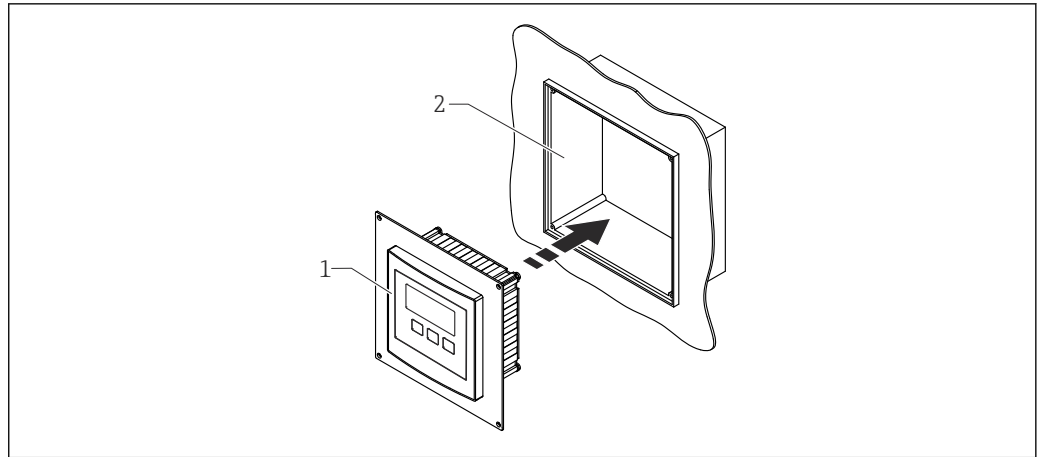
🖼 *14   Mounting in remote display of FMU860/861/862*

1   Remote display of Prosonic S with adapter plate
2   Opening of remote display of the FMU860/861/862

5.4.2   Mounting the device

Scope of delivery

- Display and operating module 96 x 96 mm (3.78 x 3.78 in)
- 4 retainers with nuts and screws
- Connecting cable (3 m (9.8 ft)) to connect to the transmitter (pre-terminated with suitable connectors)

Installation instructions
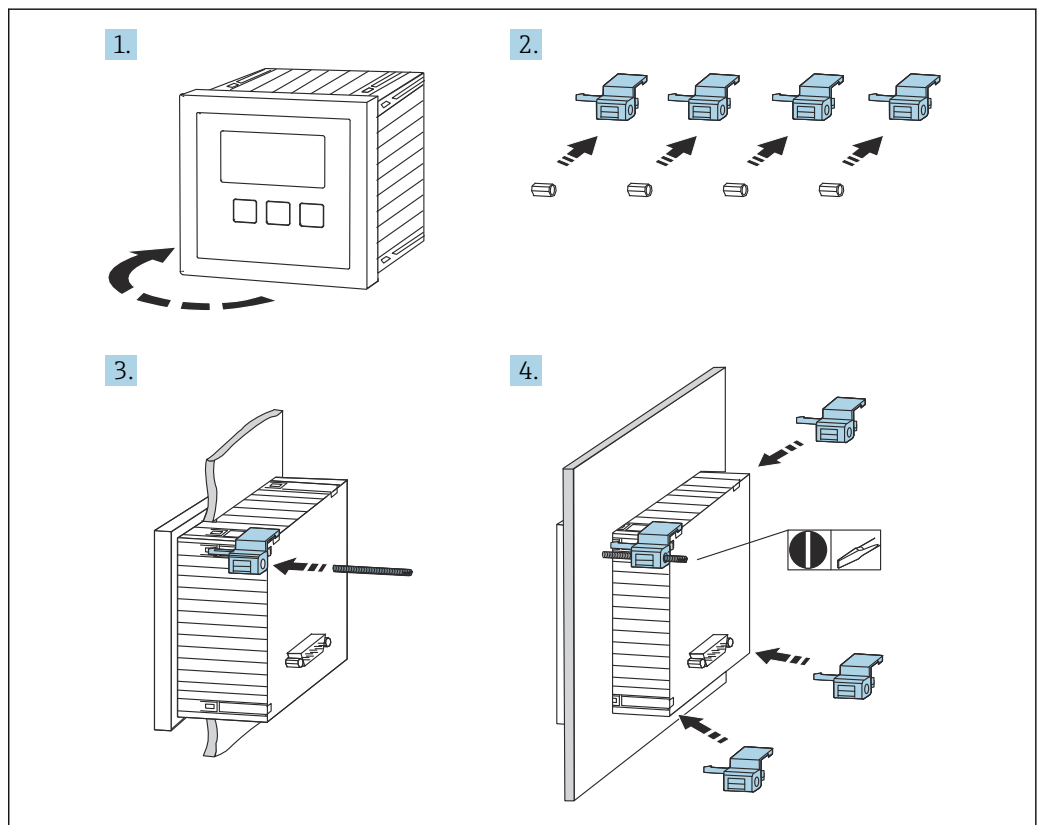
🖼 *15   Installation of the remote display and operating module*

5.5   Mounting the sensors

📖 Further information and the documentation currently available can be found on the Endress+Hauser website: www.endress.com → Downloads.

Sensor documentation:
- TI01469F (FDU90)
- TI01470F (FDU91)
- TI01471F (FDU91F)
- TI01472F (FDU92)
- TI01473F (FDU93)
- TI01474F (FDU95)

Sensors FDU80/80F/81/81F/82/83/84/85/86/96 can no longer be ordered. The Prosonic S transmitter can still be connected if the sensors are already installed.

5.6   Post-installation check

Perform the following checks after mounting the device:

❑ Is the device undamaged (visual inspection)?

❑ Does the device match the measuring point specifications such as process temperature, process pressure, ambient temperature, measuring range etc.?

❑ If provided: are the measuring point number and labeling correct?

❑Is the measuring device adequately protected against precipitation and direct sunlight?

❑ In the case of the field housing: are the cable glands tightened correctly?

❑ Is the device firmly seated on the DIN rail/is the device correctly mounted on the field housing bracket (visual inspection)?

❑ Are the cover screws on the connection compartment cover of the field housing tightened securely (visual inspection)?

6   Electrical connection

6.1   Connection conditions

6.1.1   Cable specification

- **Conductor cross-section**: 0.2 to 2.5 mm² (26 to 14 AWG)
- **Wire sleeve cross-section**: 0.25 to 2.5 mm² (24 to 14 AWG)
- **Min. stripping length**: 10 mm (0.39 in)

6.2   Connecting the device

6.2.1   Terminal compartment of polycarbonate field housing

Valid for:
Order code 030 (housing, material)
Option 1 (PC field mounting, IP66 NEMA4x)

Access to terminal compartment

A0034895
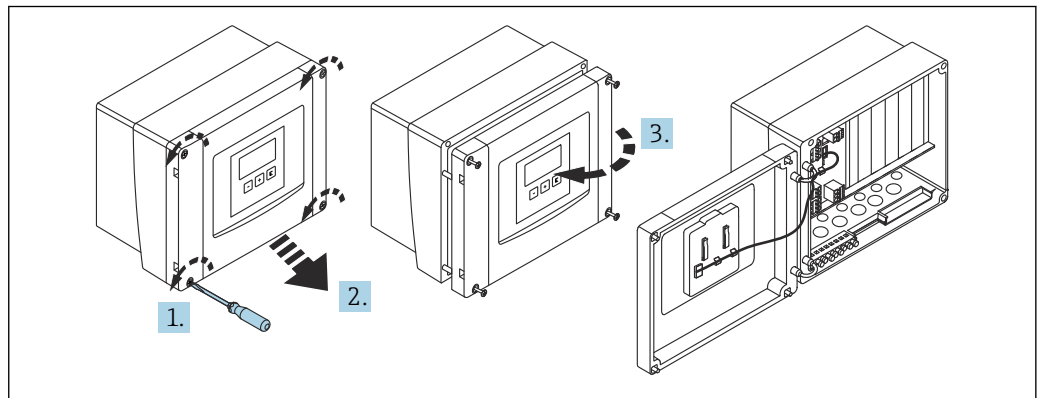
🖼 *16   Access to terminal compartment in polycarbonate field housing*

A0034896
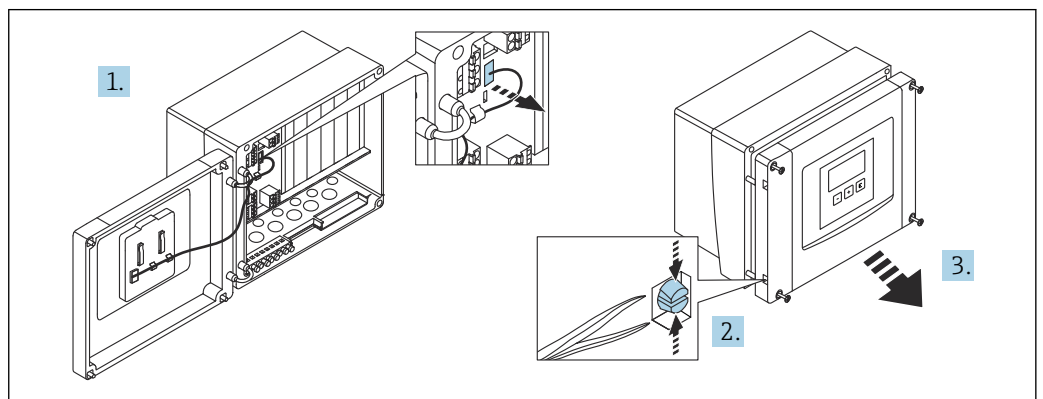
🖼 *17   For easier wiring, remove the cover from the field housing*

Cable entries

Precut openings on the bottom of the housing for the following cable entries:
- M20x1.5 (10 openings)
- M16x1.5 (5 openings)
- M25x1.5 (1 opening)

Use a suitable tool to cut out the openings.

6.2.2 Terminal compartment of aluminum field housing

ℹ️ **Valid for:**
Order code 030 (housing, material)
Option 3 (aluminum field mounting, IP66 NEMA4x)

⚠️ **WARNING**

To ensure explosion protection:
▸ Ensure that all the terminals are located in the field housing. (Exception: terminal for protective ground on the outside of the field housing).
▸ Connect the housing to the local ground potential (PML).
▸ To route the cables, only use cable glands that meet the explosion protection requirements at the place of operation.

Access to terminal compartment
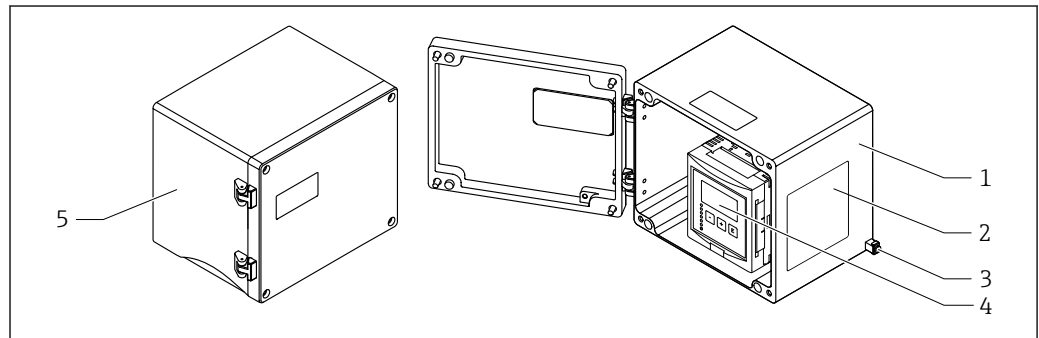
A0033256

⊞ *18   Access to terminal compartment in aluminum field housing*

1   Aluminum field housing, open
2   Nameplate
3   Terminal for protective ground
4   Display and operating module
5   Aluminum field housing, closed

Cable entries

- 12 M20x1.5 openings for cable entries are located on the bottom of the field housing.
- To establish the electrical connection: guide the cables through the cable entries and into the housing. The electrical connection is then established in the same way as in the DIN rail housing.

6.2.3 Terminal compartment of DIN rail housing

ℹ️ **Valid for:**
Order code 030 (housing, material)
Option 2 (DIN rail mounting PBT, IP20)

Access to terminal compartment
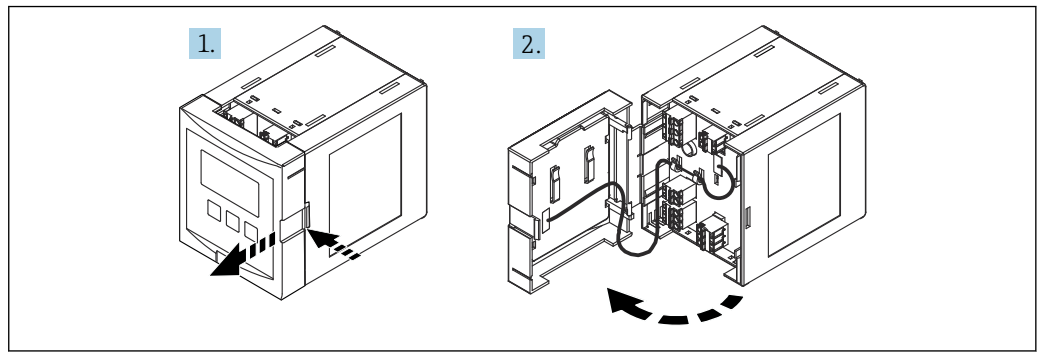
🖼 19   Access to terminal compartment: single DIN rail housing unit
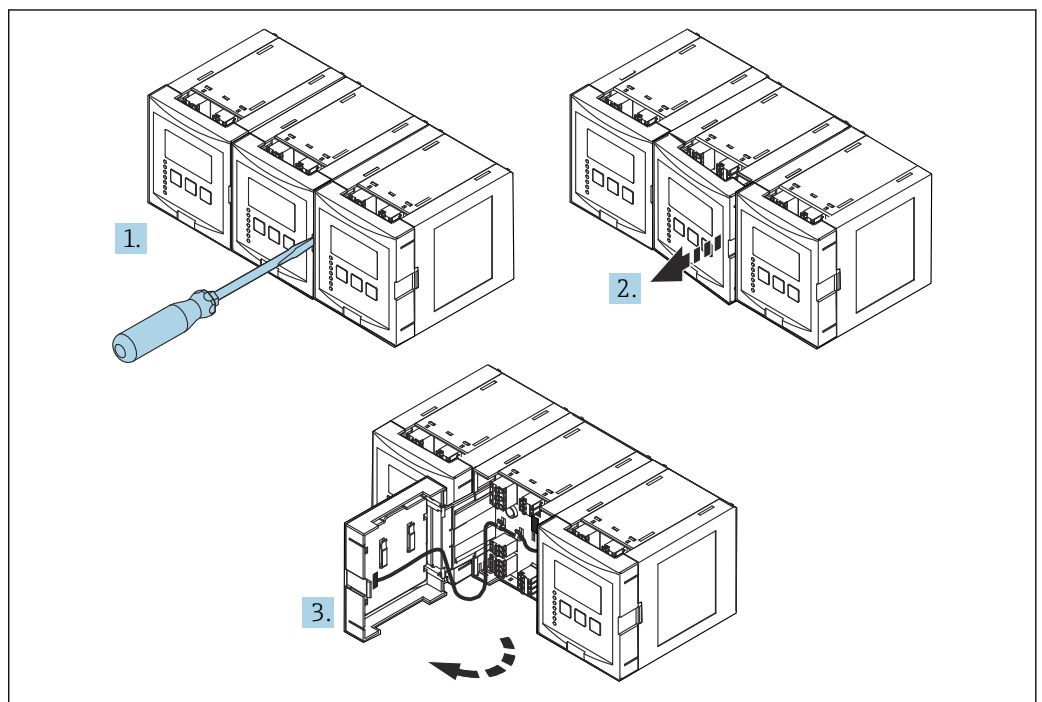
🖼 20   Access to terminal compartment: several DIN rail housing units mounted side by side

6.2.4   Terminal assignment

Terminal type

Prosonic S has plug-in spring terminals. Rigid conductors or flexible conductors with ferrules can be inserted directly into the terminal without using the lever, and create a contact automatically.

Terminal areas

- **Basic terminal area (A)**
  Found on all device versions
- **Terminal area for additional inputs and outputs (B)**
  Found on the following device versions:
  - FMU90 - *****2******
  - FMU90 - *******2****
- **Terminal area for relays (C)**
  Found on the following device versions:
  - FMU90 - ******3*****
  - FMU90 - ******6*****
- **Terminal area for switch inputs and temperature inputs (D)**
  Found on the following device version:
  FMU90 - ********B***
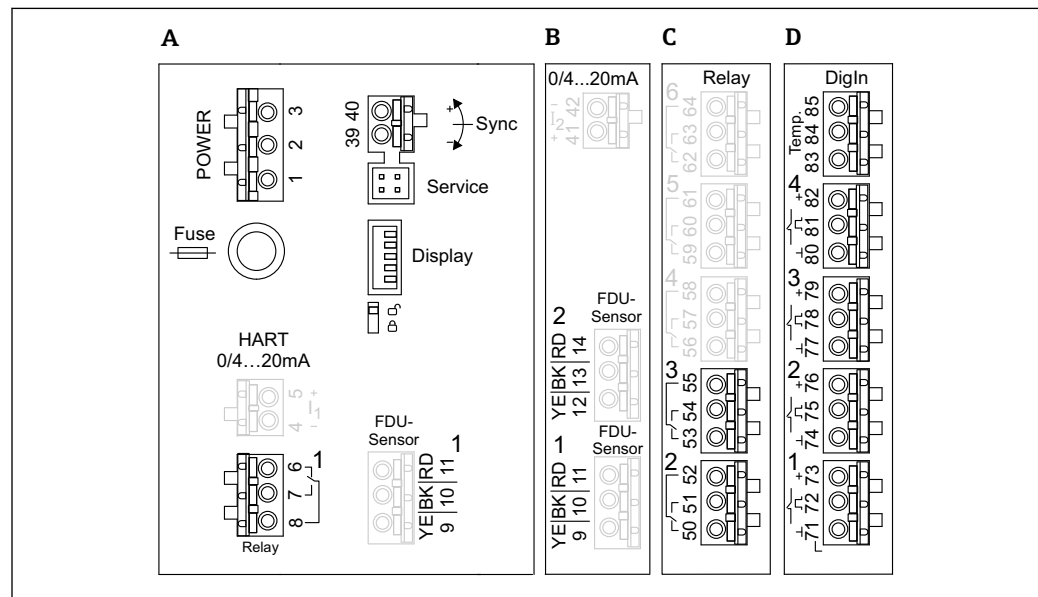
A0035301

🖼 *21   Terminal areas; the terminals shown in gray are not available in every device version*

A   Basic terminal area
B   Optional terminal area for two sensors
C   Optional terminal area for up to five relays
D   Optional terminal area for up to four external switches and one external temperature sensor

ℹ️ The relay switching states shown on the terminal area refer to the de-energized state.

Terminals for power supply (AC version)

Terminal area A
- Terminal 1: L (90 to 253 V_{AC})
- Terminal 2: N
- Terminal 3: potential equalization
- Fuse: 400 mA T

Terminals for power supply (DC version)

Terminal area A
- Terminal 1: L+ (10.5 to 32 V_{DC})
- Terminal 2: L-
- Terminal 3: potential equalization
- Fuse: 2AT

Terminals for analog outputs

Terminal area A
Terminals 4, 5: analog output 1 (0/4 to 20mA, HART)

Terminal area B
Terminals 41, 42: analog output 2 (0/4 to 20mA)

Terminals for relays

Terminal area A
Terminals 6, 7, 8: relay 1

Terminal area C
- Terminals 50, 51, 52: relay 2
- Terminals 53, 54, 55: relay 3
- Terminals 56, 57, 58: relay 4
- Terminals 59, 60, 61: relay 5
- Terminals 62, 63, 64: relay 6

Terminals for level inputs

Terminal area A
Sensor 1 (for device version with one sensor input)
- Terminal 9: yellow sensor wire
- Terminal 10: black sensor wire (cable shield)
- Terminal 11: red sensor wire

Terminal area B
- Sensor 1 (for device version with two sensor inputs)
  - Terminal 9: yellow sensor wire
  - Terminal 10: black sensor wire (cable shield)
  - Terminal 11: red sensor wire
- Sensor 2 (for device version with two sensor inputs)
  - Terminal 12: yellow sensor wire
  - Terminal 13: black sensor wire (cable shield)
  - Terminal 14: red sensor wire

Terminals for synchronization

Terminal area A
Terminals 39, 40: synchronization of multiple Prosonic S transmitters

Terminals for switch inputs

Terminal area D
- Terminals 71, 72, 73: external switch 1
- Terminals 74, 75, 76: external switch 2
- Terminals 77, 78, 79: external switch 3
- Terminals 80, 81, 82: external switch 4

Terminals for temperature input

Terminal area D
Terminals 83, 84, 85:
- Pt100
- Omnigrad S TR61 (Endress+ Hauser)

Other elements on the terminal areas

Terminal area A
- **Display**
  Connection of the display or the remote display and operating module
- **Service**
  Service interface; for connection of a PC/notebook via Commubox FXA291
- 🔓
  Write protection switch: locks the device to prevent modifications to the configuration.

6.3   Special connection instructions

6.3.1   Connecting the power supply

⚠️ **CAUTION**

To guarantee electrical safety:
▶ Fix the power supply cables securely in place when installing so they are permanently connected to the electrical installations for the building.
▶ When connecting to the public mains, install a mains switch for the device such that it is within easy reach of the device. Mark the power switch as a disconnector for the device (IEC/EN61010).
▶ For the 90-253VAC version: connect potential equalization
▶ Switch off the supply voltage before connecting.

Connection of the power supply in the polycarbonate field housing

ℹ️ **Valid for:**
Order code 030 (housing, material)
Option 1 (PC field mounting, IP66 NEMA4x)
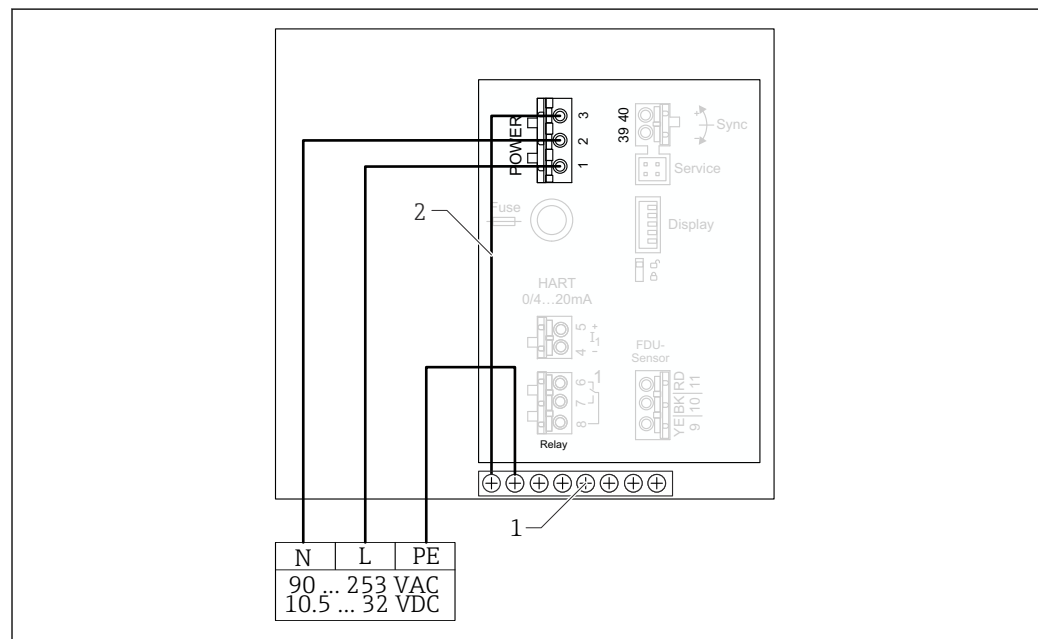
A0035934

🖼 *22   Connection of the power supply in the polycarbonate field housing*

1   Terminal block in field housing for potential equalization
2   Potential equalization; wired on delivery

Connection of the power supply in the aluminum field housing

ℹ **Valid for:**
Order code 030 (housing, material)
Option 3 (aluminum field mounting, IP66 NEMA4x)

⚠️ **WARNING**

Shock Hazard and Explosion Hazard
▸ Connect the aluminum field housing to the potential earth (PE) and/or the local
ground potential (PML) via the protective ground terminal.

🖾 *23   Connection of the power supply in the aluminum field housing*

1   Potential equalization in aluminum field housing; wired on delivery
2   Protective ground terminal strip (with contact to DIN rail)
3   Protective ground terminal on outside of field housing
4   Power supply

Connection of the power supply in the DIN rail housing

ℹ **Valid for:**
Order code 030 (housing, material)
Option 2 (DIN rail mounting PBT, IP20)
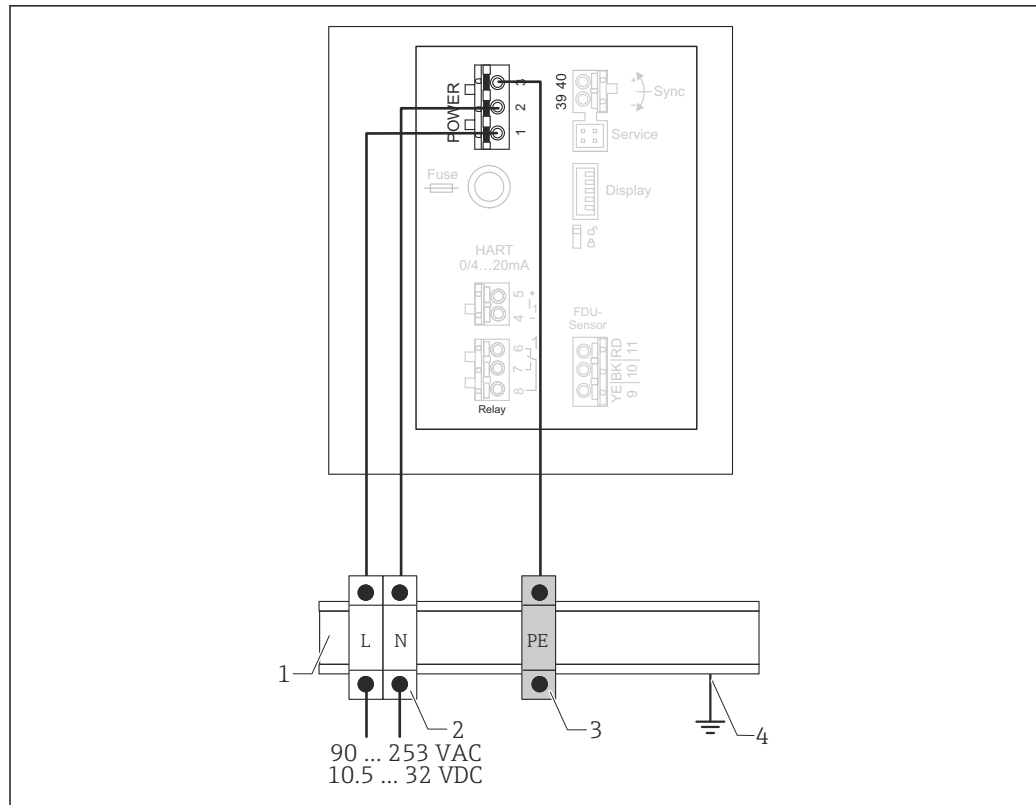
⊠ 24   Connection of the power supply in the DIN rail housing
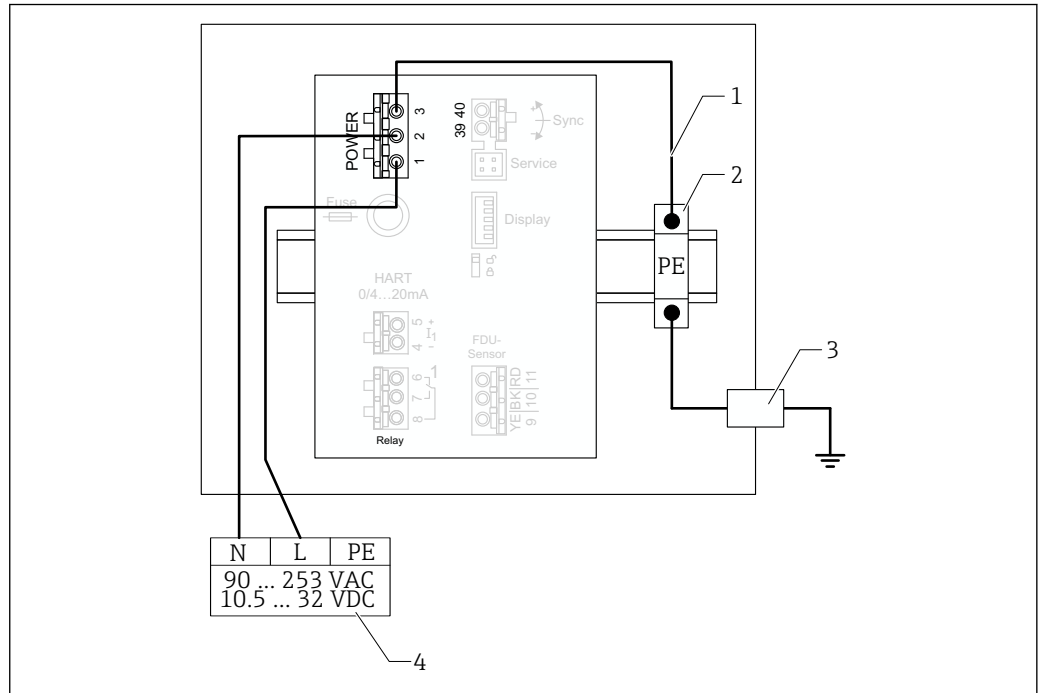
1   Metal DIN rail in cabinet
2   Terminal strip (no contact to DIN rail)
3   Protective ground terminal strip (with contact to DIN rail)
4   Grounding via DIN rail

6.3.2   Sensor connection

⚠ CAUTION

Inadequate potential equalization can compromise electrical safety
▶ Connect the yellow/green protective ground of the FDU91F, FDU93 and FDU95 sensors to local potential equalization after a **maximum distance of 30 m (98 ft)**. The can be done in a terminal box, at the transmitter or in the cabinet.

NOTICE

Interference signals may cause malfunctions
▶ Do not route the sensor cables parallel to high-voltage electric power lines or near frequency converters.

NOTICE

A damaged cable shield may cause malfunctions
▶ For pre-terminated cables: connect the black wire (shield) to the "BK" terminal.
▶ For extension cables: twist the shield and connect to the "BK" terminal.

⚠ WARNING

Explosion Hazard
▶ Do not connect FDU83, FDU84, FDU85 and FDU86 sensors with an ATEX, FM, or CSA certificate to the FMU90 or FMU95 transmitters.
▶ For the sensors FDU91F/93/95/96 and FDU83/84/85/86: connect the ground cable (GNYE) to local potential equalization after a maximum distance of 30 m (98 ft). This can be done in the terminal box or at the transmitter or in the cabinet if the distance to the sensor does not exceed 30 m (98 ft).

NOTICE

The evaluation electronics and their direct connections (display/service connector, service interface etc.) are galvanically isolated from the power supply and the communication signals, and are connected to the potential of the sensor electronics.
▶ Pay attention to the potential difference in the case of grounded sensors.
▶ If removing the jacket of the sensor cable, take the longest required cable length into consideration.

Further information and the documentation currently available can be found on the Endress+Hauser website: www.endress.com → Downloads.
Sensor documentation:
- TI01469F (FDU90)
- TI01470F (FDU91)
- TI01471F (FDU91F)
- TI01472F (FDU92)
- TI01473F (FDU93)
- TI01474F (FDU95)

Sensors FDU80/80F/81/81F/82/83/84/85/86/96 can no longer be ordered. The Prosonic S transmitter can still be connected if the sensors are already installed.

Connection diagram for FDU9x → FMU90
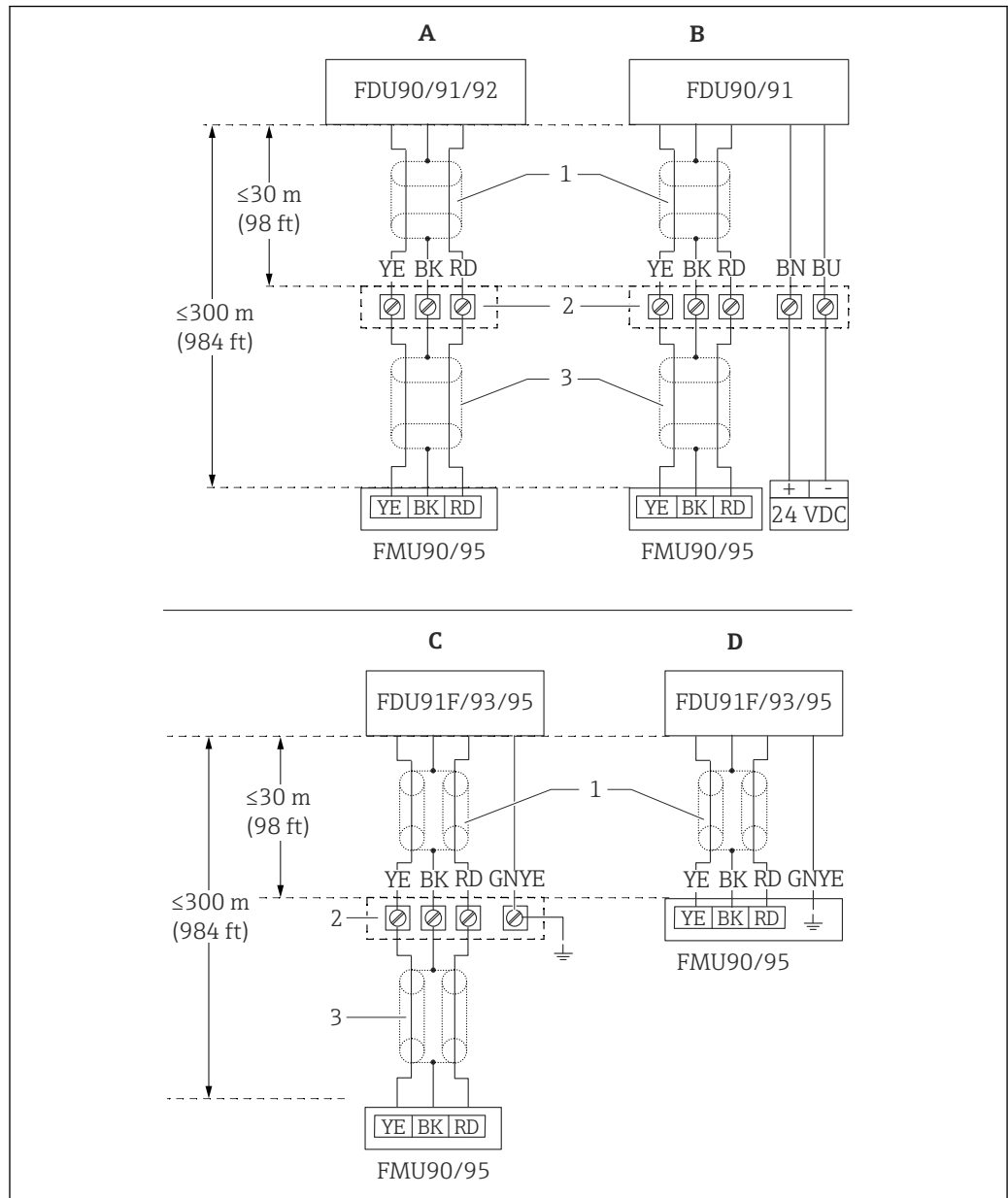
⊠ 25   Connection diagram for sensors FDU9x; YE: yellow, BK: black; RD: red; BU: blue; BN: brown; GNYE: green/yellow

A   Without sensor heater
B   With sensor heater
C   Grounding at terminal box
D   Grounding at transmitter FMU90
1   Shielding of sensor cable
2   Terminal box
3   Shielding of extension cable

Potential equalization of metallic sensors in polycarbonate field housing

ℹ️ Valid for:
Order code 030 (housing, material)
Option 1 (PC field mounting, IP66 NEMA4x)

Valid for the following sensors
- FDU91F
- FDU93
- FDU95

These sensors are no longer available but can be connected to the Prosonic S in existing installations.
- FDU96
- FDU83
- FDU84
- FDU85
- FDU86

🖾 *26   Potential equalization of metallic sensors in polycarbonate field housing*

1   Terminal block in field housing for potential equalization
2   Potential equalization; wired on delivery.

Potential equalization of metallic sensors in aluminum field housing

ℹ️ **Valid for:**
Order code 030 (housing, material)
Option 3 (field mounting, aluminum, IP66 NEMA4x)

Valid for the following sensors
- FDU91F
- FDU93
- FDU95

These sensors are no longer available but can be connected to the Prosonic S in existing installations.
- FDU96
- FDU83
- FDU84
- FDU85
- FDU86

27   Potential equalization of metallic sensors in aluminum field housing

1   *Potential equalization in the field housing; wired on delivery*
2   *Protective ground terminal strip (with contact to DIN rail)*
3   *Protective ground terminal on outside of field housing*
4   *Power supply*

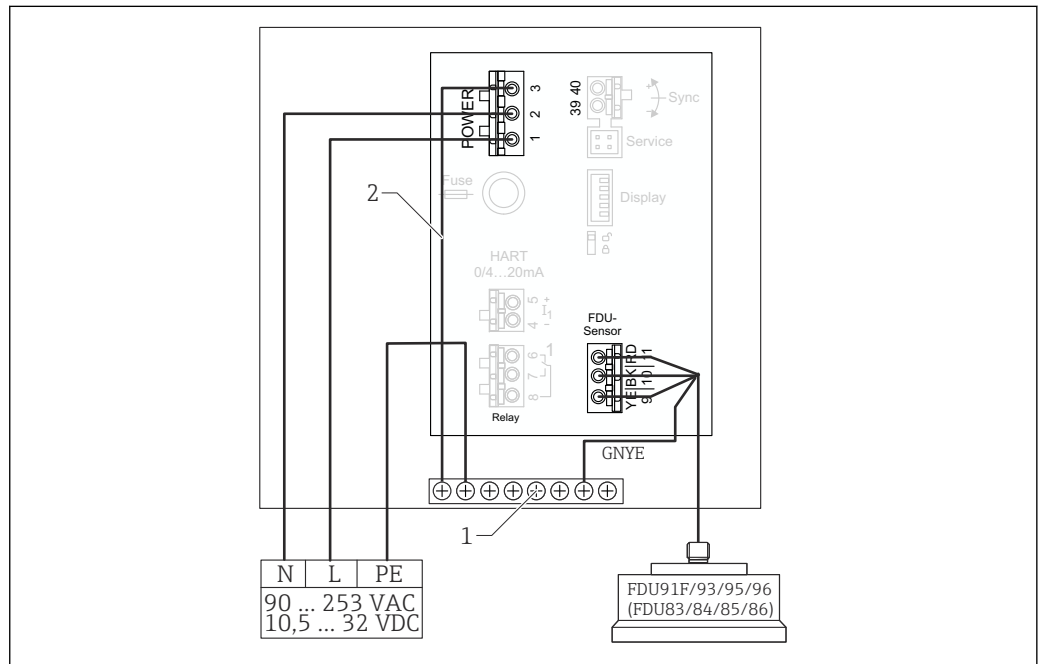**Potential equalization of metallic sensors in DIN rail housing**

Valid for:
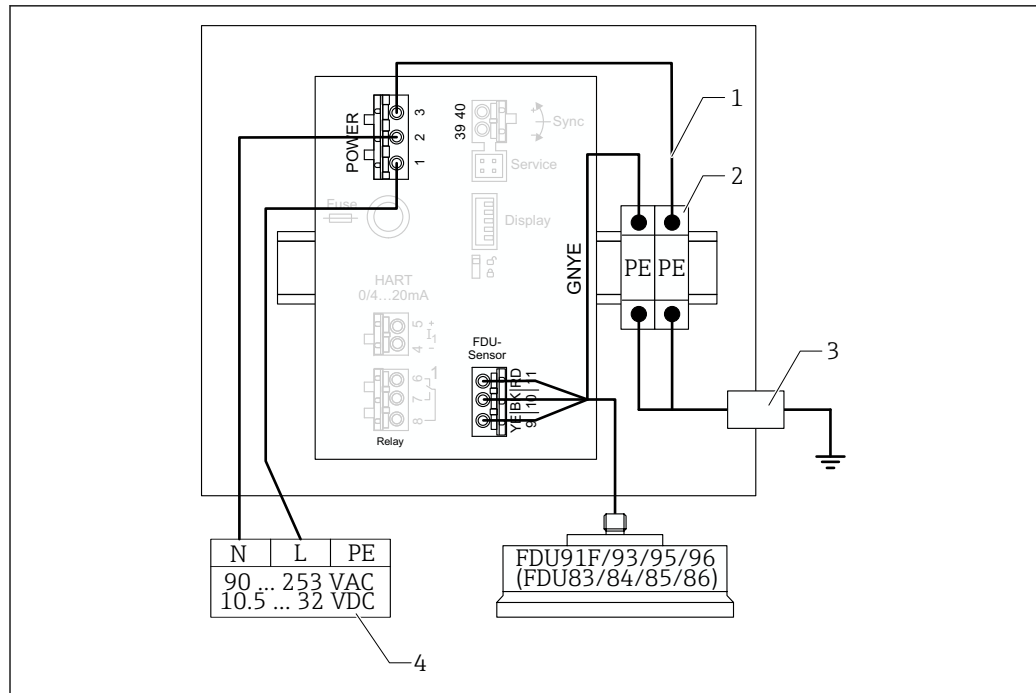Order code 030 (housing, material)
Option 2 (DIN rail mounting PBT, IP20)

Valid for the following sensors
- FDU91F
- FDU93
- FDU95

These sensors are no longer available but can be connected to the Prosonic S in existing installations.
- FDU96
- FDU83
- FDU84
- FDU85
- FDU86
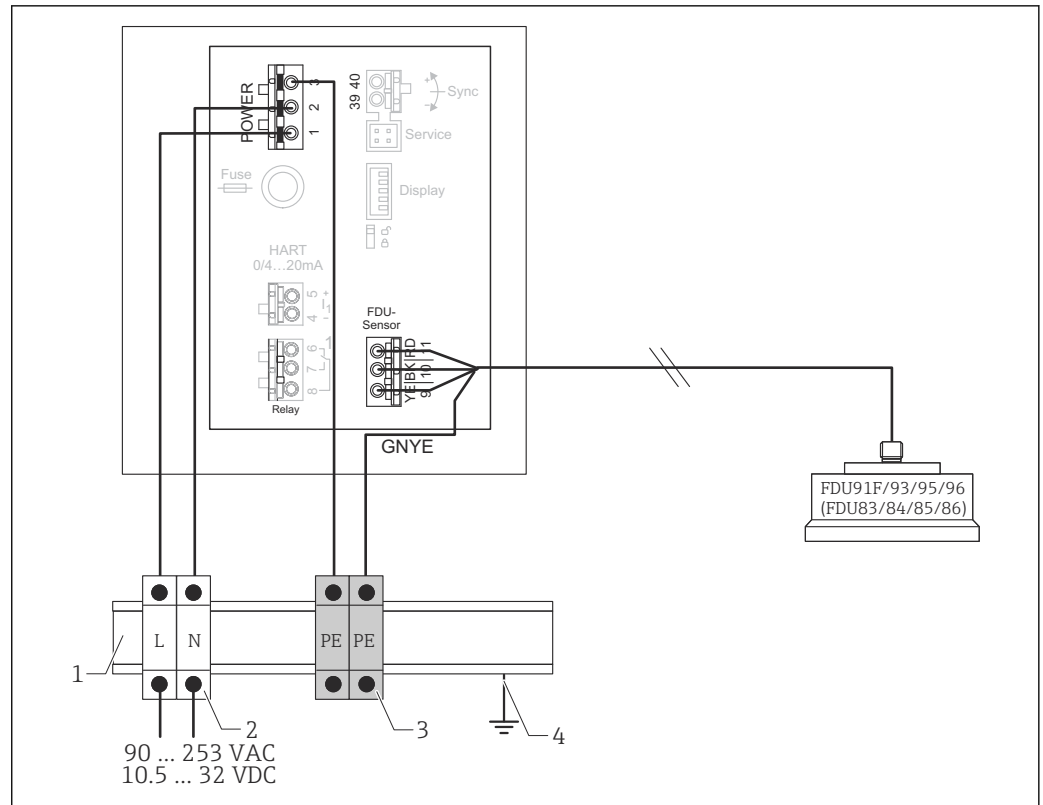
⊠ *28   Potential equalization of metallic sensors in DIN rail housing*

1   Metal DIN rail in cabinet
2   Terminal strip (no contact to DIN rail)
3   Protective ground terminal strip (with contact to DIN rail)
4   Grounding via DIN rail

6.3.3   Sensor extension cable

⚠ WARNING

Explosion Hazard
▸ Use a terminal box to connect the extension cable.
▸ If the terminal box is installed in hazardous areas, comply with applicable national requirements.

Extension cable specifications

- **Maximum total length (sensor cable + extension cable)**
  300 m (984 ft)
- **Number of wires**
  As per connection diagram
- **Shielding**
  One shielding braid for the YE wire and one for the RD wire (no foil shield)
- **Cross-section**
  0.75 to 2.5 mm^2 (18 to 14 AWG)
- **Resistance**
  Max. 8 Ω per wire
- **Capacitance, wire to shield**
  Max. 60 nF
- **Protective ground (for FDU91F/93/95)**
  May not be within the shielding.

ℹ Suitable connection cables are available from Endress+Hauser (→ ▤ 92).

6.3.4 Shortening the sensor cable

NOTICE

Damaged wires or no return conductor may cause malfunctions

▸ Do not damage the wires when removing the insulation.

▸ After shortening the cable, twist the shielding metal braiding and connect it to the "BK" terminal.

▸ If the cable has a protective ground (GNYE), do **not** connect the protective ground to the cable shield.
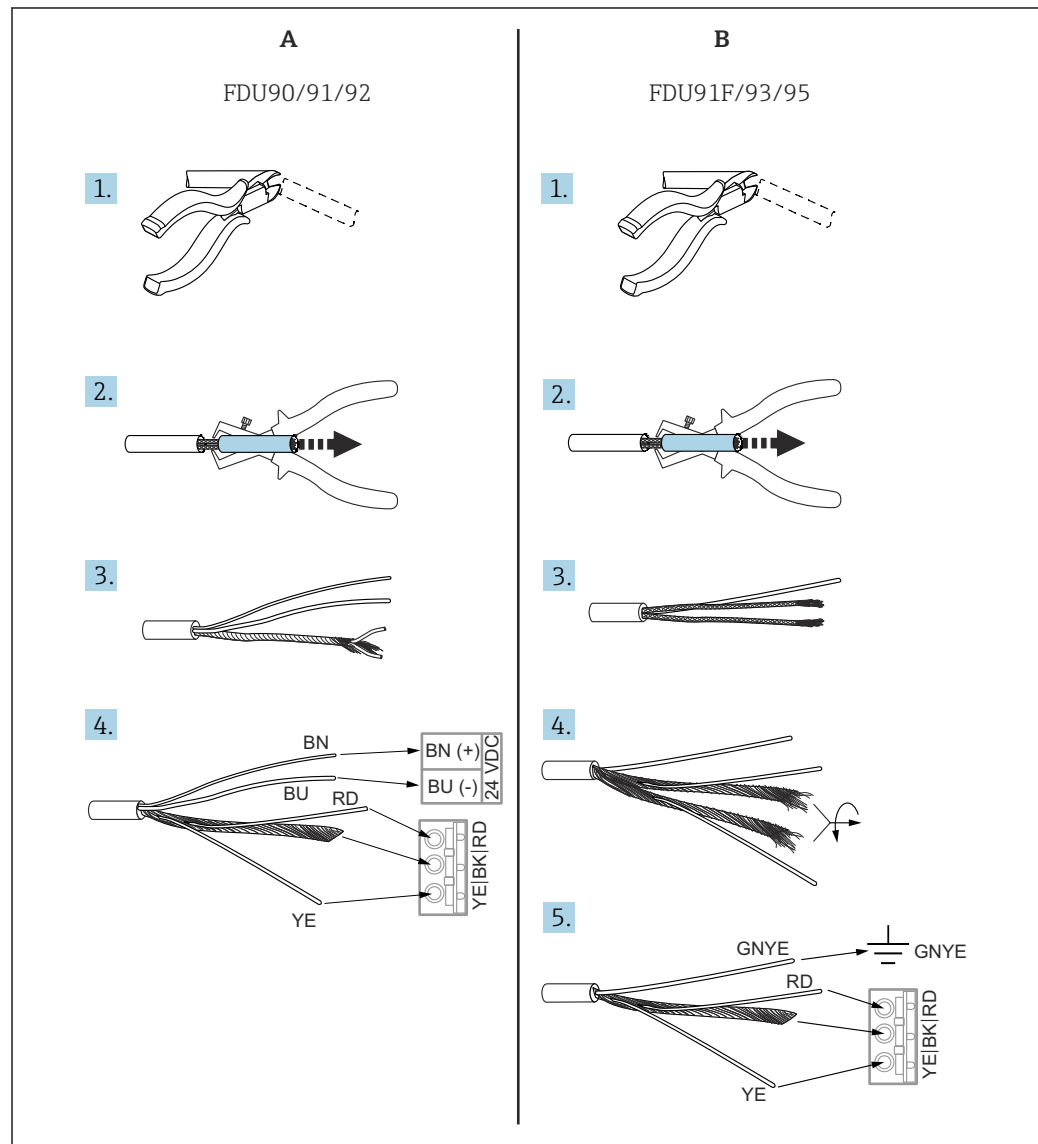
🖼 29   Shortening the sensor cable

A   FDU90/91/92 sensors
B   FDU91F/93/95 sensors

ℹ️ The "BU" (blue) and "BN" (brown) wires are only provided on sensors with a heater.

6.3.5 Connection of the sensor heater

ℹ️ **Valid for FDU90/FDU91:**
Order code 035 (heater)
Option B (connection to 24VDC)

Technical data for sensor heater

- **Supply voltage**
  24 $V_{DC}\pm10$ %
- **Residual ripple**
  < 100 mV
- **Current consumption**
  250 mA per sensor

ℹ **Temperature compensation with sensor heater**
If the sensor heater is used, connect an external temperature sensor to correct the sound time-of-flight and assign this temperature sensor to the sensor.

Connection of the sensor heater in the polycarbonate field housing

ℹ **Valid for:**
Order code 030 (housing, material)
Option 1 (PC field mounting, IP66 NEMA4x)

A0032574
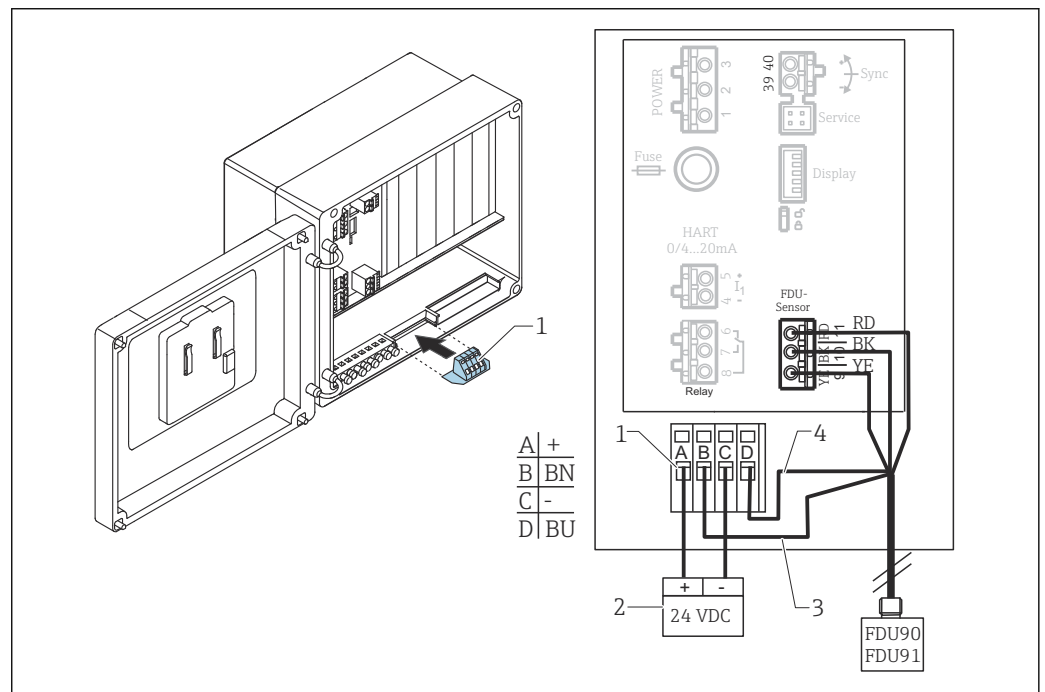
☑ *30   Connection of the sensor heater in the polycarbonate field housing*

1   Terminal module for sensor heater (included in the delivery for the sensors concerned)
2   External power supply unit
3   Brown wire (BN)
4   Blue wire (BU)

Connection of the sensor heater in the aluminum field housing

ℹ **Valid for:**
Order code 030 (housing, material)
Option 3 (field mounting, aluminum, IP66 NEMA4x)

⚠ WARNING

Explosion Hazard

▶ Install the power supply unit outside the hazardous area.
▶ Use a cable that meets the requirements of the zone in which the aluminum field housing is installed.
▶ Connect the sensor heater inside the aluminum field housing (or another explosion-proof housing) to the power supply. To do so, install additional terminal blocks on the DIN rail in the housing.
▶ Prior to opening the aluminum field housing: switch off the power supply to the sensor heater.

A0033332
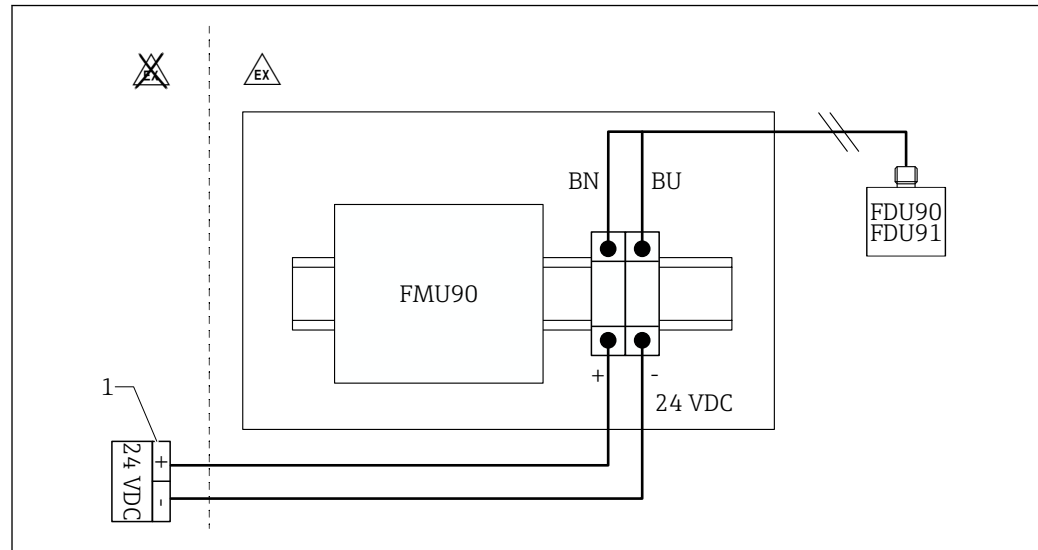
⊠ 31   *Connection of the sensor heater in the aluminum field housing*

1   External power supply unit
BN   Brown wire
BU   Blue wire

Connection of the sensor heater in the DIN rail housing

ℹ **Valid for:**
Order code 030 (housing, material)
Option 2 (DIN rail mounting PBT, IP20)

The supply voltage must be provided in the cabinet, e.g. via a terminal block:
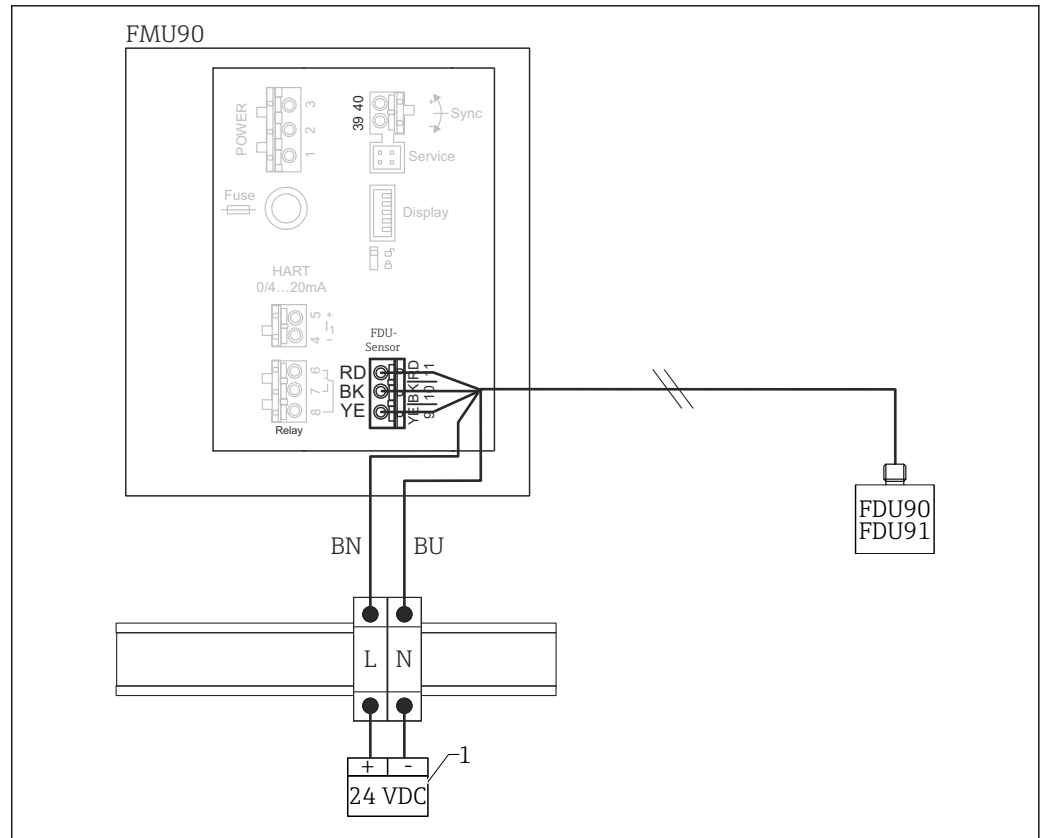
32 *Connection of the sensor heater via a metal DIN rail in the cabinet*

1 *External power supply unit*
BN *Brown wire*
BU *Blue wire*

6.3.6   Synchronization terminal

Using the GSD files

The synchronization terminal must be used if the sensor cables of several transmitters are routed in parallel. As a result of synchronization, a transmitter cannot receive signals while another transmitter is transmitting signals. This prevents transmission and reception signals from mutually influencing one another.

Number of transmitters that can be synchronized

- 20 (in the case of FMU90/FMU95)
- 10 (if synchronizing FMU90/FMU95 with FMU86x)

Procedure if synchronizing more than 20 transmitters

- Form groups with a maximum of 20 transmitters.
- For transmitters within a group, the sensor cables can run in parallel.
- The sensor cables of different groups must be separated from one another.

Cable specification for synchronization

- **Max. length**
  10 m (33 ft) between the individual transmitters
- **Cross-section**
  2 x 0.75 to 2.5 mm² (18 to 14 AWG)
- **Cable shield**
  Required for cables > 1 m (3.3 ft); ground the shield.

Synchronization wiring diagram
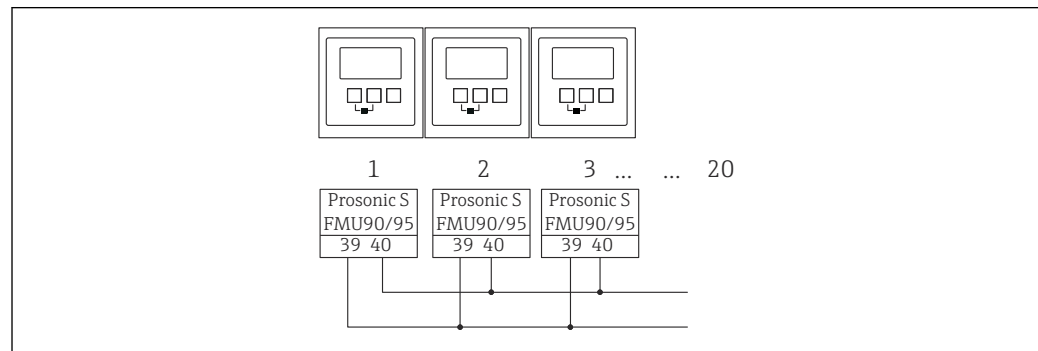
🔲 *33   Synchronization of multiple FMU90/FMU95 transmitters*
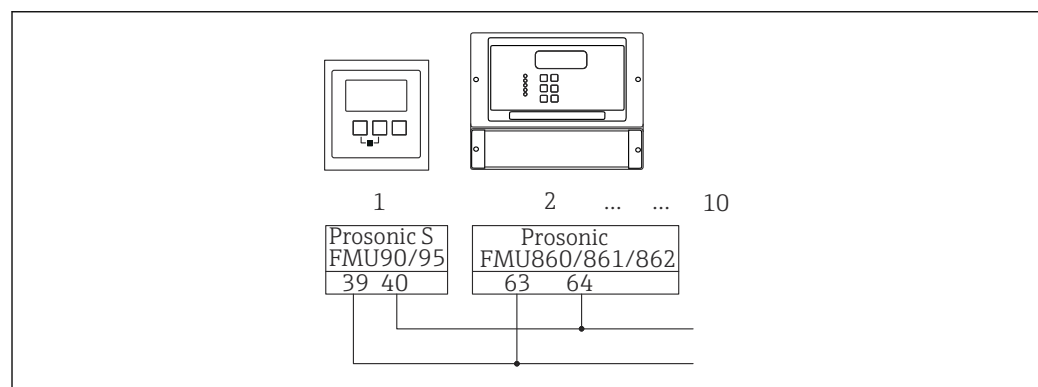
🔲 *34   Synchronization of FMU90/FMU95 with FMU86x*

6.3.7   Connection of external switches

ℹ **Valid for:**
Order code 090 (additional input)
Option B (4 x point level switch + 1 x temperature)
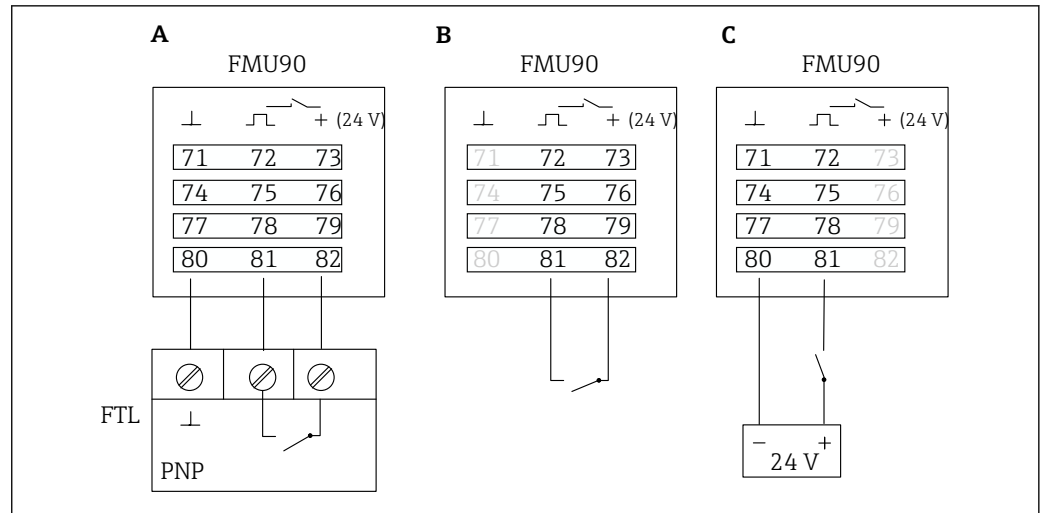
35   Connection of external switches

A   Liquiphant connection
B   Connection of external switches (passive)
C   Connection of external switches (active)

Inputs for external switches

- External switch 1
  - $0 \triangleq$ < 8 V or 72 and 73 interconnected
  - $1 \triangleq$ > 16 V or 72 and 73 not interconnected
- External switch 2
  - $0 \triangleq$ < 8 V or 75 and 76 interconnected
  - $1 \triangleq$ > 16 V or 75 and 76 not interconnected
- External switch 3
  - $0 \triangleq$ < 8 V or 78 and 79 interconnected
  - $1 \triangleq$ > 16 V or 78 and 79 not interconnected
- External switch 4
  - $0 \triangleq$ < 8 V or 81 and 82 interconnected
  - $1 \triangleq$ > 16 V or 81 and 82 not interconnected

Maximum short-circuit current

24 V at 20 mA

6.3.8   Connection of a Pt100 temperature sensor

Valid for:
Order code 090 (additional input)
Option B (4 x point level switch + 1 x temperature)

⚠ WARNING

Explosion Hazard
It is not permitted to connect a Pt100 sensor in hazardous areas.
▸ In hazardous areas, use an Omnigrad S TR61 with an appropriate approval certificate.
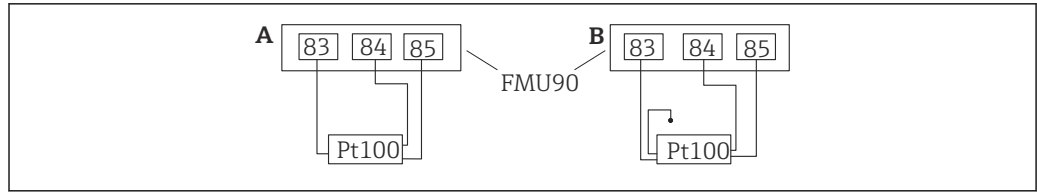
▣ 36   Connection of a Pt100 temperature sensor

A   Pt100 with 3-wire connection
B   Pt100 with 4-wire connection (one connector is not used)

The use of a 2-wire connection is not permitted due to insufficient measuring accuracy.

After connecting the sensor
Assign the temperature sensor to an ultrasonic sensor via the operating menu:
Sensor management → Sensor management → US sensor N → Temperature measurement = External temperature

6.3.9   Connection of the Omnigrad S TR61 temperature sensor

Valid for:
Order code 090 (additional input)
Option B (4 x point level switch + 1 x temperature)

Connection of the Omnigrad S TR61 temperature sensor outside hazardous areas
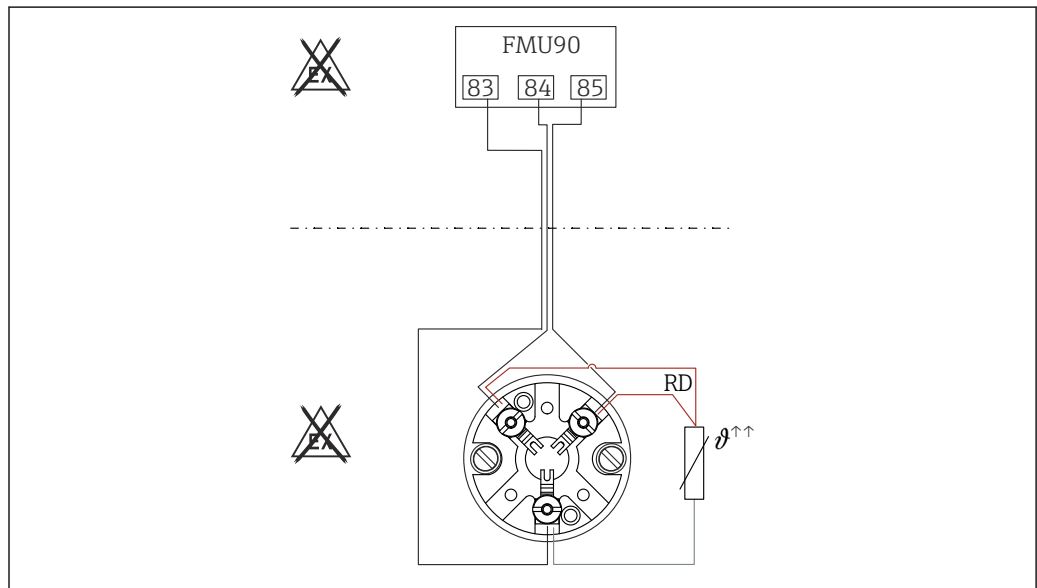
▣ 37   Connection of the Omnigrad S TR61 outside hazardous areas

RD   Wire color = red

Omnigrad S models suitable for connection
TR61-A…

Additional information
Technical Information TI01029T

After connecting the sensor
Assign the temperature sensor to an ultrasonic sensor via the operating menu:
Sensor management → Sensor management → US sensor N → Temperature measurement = External temperature

Connection of the Omnigrad S TR61 temperature sensor in hazardous areas
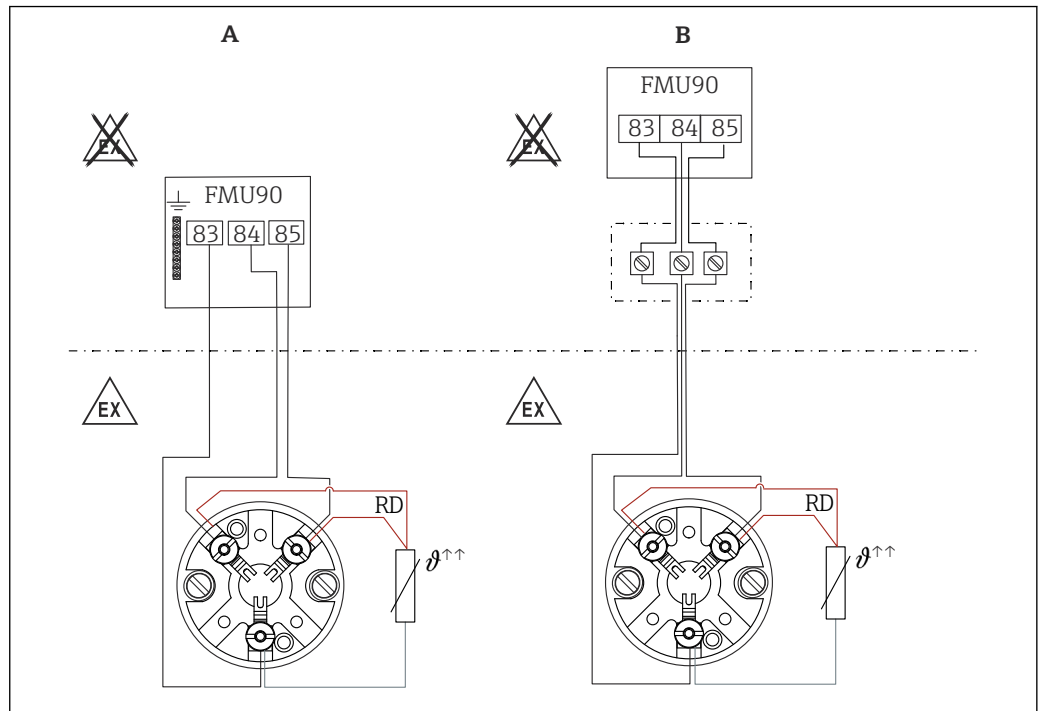
38   Connection of the Omnigrad S TR61 in hazardous areas

A   Temperature sensor in hazardous area
B   Temperature sensor in hazardous area, with connection at terminal box
RD   Wire color = red

Omnigrad S models suitable for connection
Depends on the approval required:
- TR61-E***********
- TR61-H***********
- TR61-M***********
- TR61-N***********
- TR61-R***********
- TR61-S***********
- TR61-2***********
- TR61-3***********

Additional information
- Technical Information TI01029T
- Ex documentation (XA) supplied with the TR61. This is an integral part of the documentation. The installation specifications, connection data and safety instructions listed in this supplementary documentation must be observed.

After connecting the sensor
Assign the temperature sensor to an ultrasonic sensor via the operating menu:
Sensor management → Sensor management → US sensor N → Temperature measurement = External temperature

6.3.10   Connecting the remote display and operating module

Valid for:
Order code 040 (operation)
Option E (illuminated display + keypad, 96x96, panel mounting, IP65 at front)
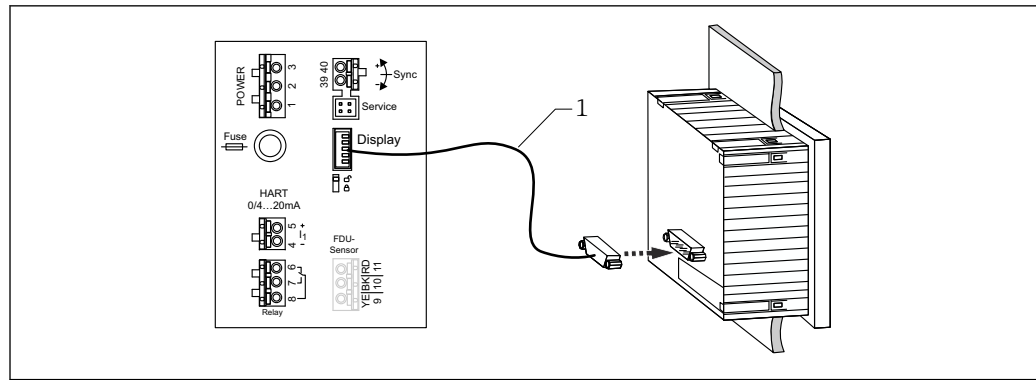
A0034903

🖾 *39   Connection of the remote display and operating module*

1   Pre-terminated connecting cable 3 m (9.8 ft) with display plug (supplied)

Minimum diameter for cable entry

20 mm (0.79 in)

6.3.11   Post-connection check

❏ Is the terminal assignment correct?

For field housing (polycarbonate/aluminum):

❏ Are the cable glands tight?

❏ Is the housing cover securely closed?

For aluminum field housing:

❏ Is the housing connected to protective ground (PE) and/or the local ground potential (PML)?

If the power supply is switched on:

❏ Is the LED for the operating state lit green?

❏ If a display module is attached: does anything appear on the screen?

7 Operating options

7.1 Structure and function of the operating menu

7.1.1 Submenus and parameter sets

Parameters that belong together are grouped into one parameter set in the operating menu. Each parameter set is identified by a five-digit code.
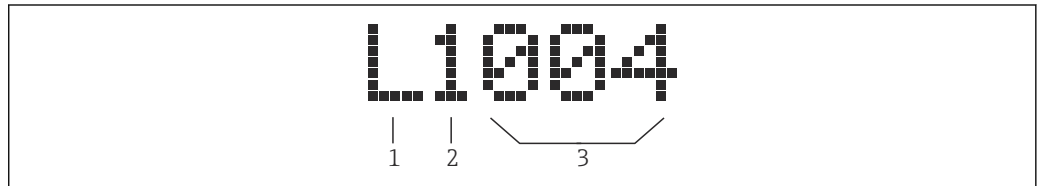
40   Identification of the parameter sets:

1   Submenu
2   Number of the associated input or output (for multi-channel devices)
3   Number of the parameter set within the submenu

7.1.2 Types of parameter

Read-only parameters

- Symbol:
- Cannot be edited.

Editable parameters

- Symbol:
- Can be opened for editing by pressing .

7.2   Access to the operating menu via the local display

7.2.1   Display and operating elements

Elements of the display and operating module

A0034921
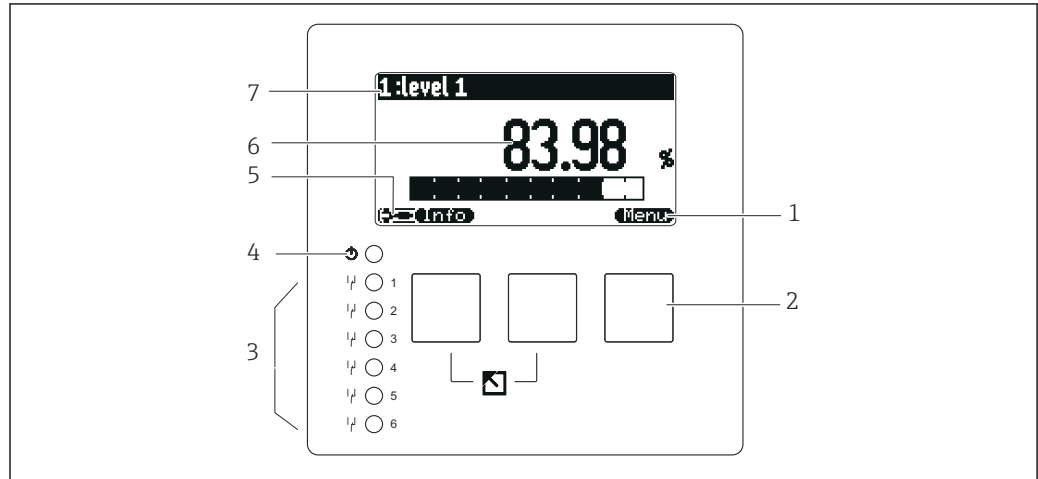
1   Soft key symbols
2   Keys
3   Light emitting diodes to indicate the relay switching states
4   LED to indicate the operational state
5   Display symbol
6   Parameter value with unit (here: primary value)
7   Name of displayed parameter

Symbols for operating state

- ▭▭▭
  User operating state:
  User parameters can be edited. Service parameters cannot be edited.
- ▭▭▭
  Diagnostics operating state:
  Service interface is connected.
- ▭▭▭
  Service operating state:
  User parameters and service parameters can be edited.
- ▭▭▭
  Locked operating state:
  All parameters are locked and cannot be edited.

Symbols indicating the editing state of the current parameter

- ▭▭▭
  Read-only parameter
  The parameter **cannot** be edited in the current device operating state.
- ▭▭▭
  Editable parameter
  The parameter can be edited.

Scroll symbols

⏬ ⏫

Scroll list available

Is displayed if the picklist contains more options than can be shown on the display. All the options in the list can be displayed by pressing ◼◼◻ or ◻◼◼ repeatedly.

Navigation in the envelope curve display (select the "Cyclic" display format)

- ◀◀
  Move left
- ▶▶
  Move right
- ◀▶
  Zoom in
- ▶◀
  Zoom out

LED for operating state

- **Lit green**
  Normal operation; no errors detected
- **Flashes red**
  Warning: an error has been detected, but measurement continues. The reliability of the measured value cannot be guaranteed.
- **Lit red**
  Alarm: an error has been detected. Measurement is interrupted. The measured value adopts the value specified by the user ("Output on alarm").
- **Off**
  No supply voltage.

Light emitting diodes for relays

- **Lit yellow**
  Relay energized
- **Off**
  Relay de-energized (quiescent state)

Keys (soft key operation)

The current key function is indicated by soft key symbols above the key.

- ◼◼◻
  Moves the selection bar downwards in a picklist.
- ◻◼◼
  Moves the selection bar upwards in a picklist.
- ◼◼◻
  - Opens the selected submenu, parameter set or parameter.
  - Confirms the edited parameter value.
- ◼◼◻
  Goes to the previous parameter set within the submenu.
- ◼◻◼
  Goes to the next parameter set within the submenu.
- ◼✓◼
  Selects the option in a picklist which is currently marked by the selection bar.
- ◼➕◼
  Increases the selected digit of an alphanumeric parameter.
- ◼➖◼
  Decreases the selected digit of an alphanumeric parameter.

- ▪ **⬛⬛▪⬛**
  - Opens the list of errors which are currently detected.
  - If a warning is present, the symbol flashes.
  - If an alarm is present, the symbol is displayed permanently.
- ▪ **⬛⬛⬛**
  Displays the next page of measured values (only available if several pages of measured values have been defined; see the "Display" menu).
- ▪ **Info**
  Opens the "Shortcut" menu, which contains the most important read-only parameters.
- ▪ **Menu**
  Opens the main menu from where you can access **all** the device parameters.

General key combinations
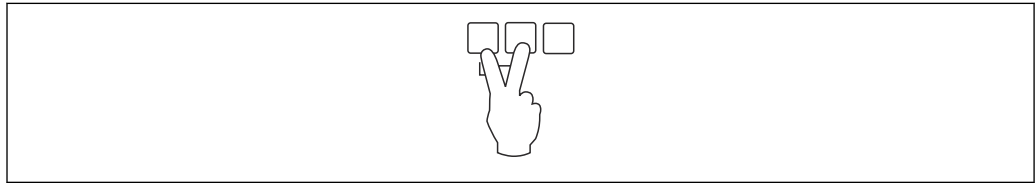
🔲 *41   Escape*
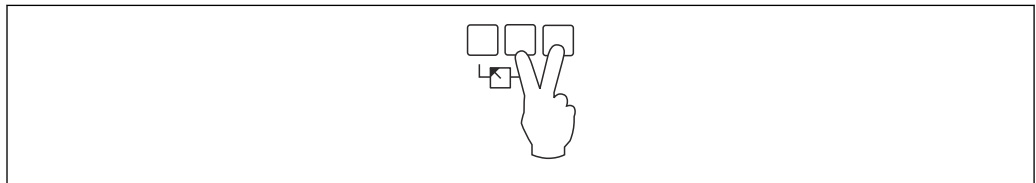
🔲 *42   Increase contrast*
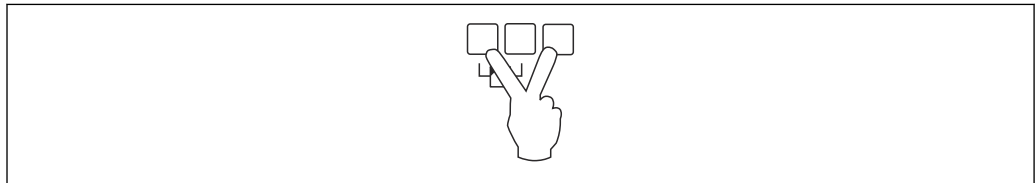
🔲 *43   Reduce contrast*
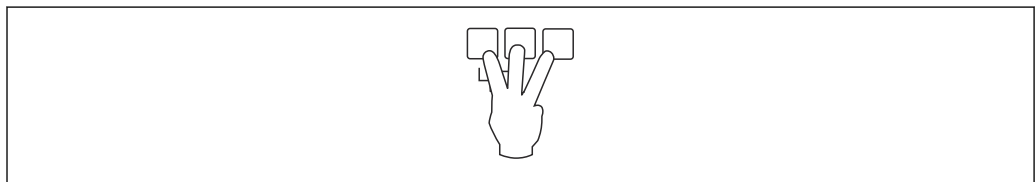
🔲 *44   Locking*

7.2.2   Calling the operating menu from a standard screen (measured value display)

- **Left button ("Info") : shortcut menu**
  Provides fast access to the most important parameters:
  - Daily counter
  - Tag marking
  - Envelope curve
  - Language
  - Device information
  - Password/reset
- **Middle key: current errors**
  If the self-monitoring system detects one or more errors, the soft key symbol appears above the middle key. When the button is pressed, a list of all the errors currently pending is displayed.
- **Right key ("Menu"): main menu**
  Contains all the parameters of the device, subdivided into submenus and parameter sets.

8   System integration
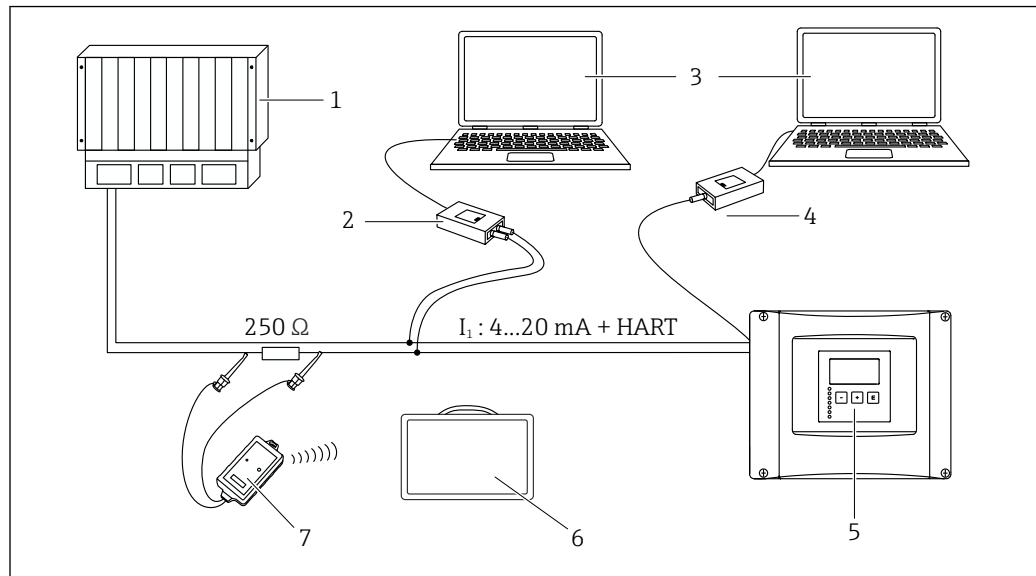
⊞ 45   HART system integration

1   PLC, API
2   Commubox FXA195 (USB), HART protocol
3   DeviceCare/FieldCare
4   Commubox FXA291 (service interface)
5   Display and operating module on Prosonic S (if available)
6   Field Xpert SMT70/SMT77
7   VIATOR Bluetooth modem with connecting cable

9   Commissioning

9.1   Preparatory steps

9.1.1   Resetting to factory settings (Reset)

NOTICE

A reset may negatively impact the measurement.

▶ Perform a new basic setup after resetting the device.

Using the reset function

It is always advisable to reset the device if you want to use a device with an unknown history.

Effects of a reset

- All the parameters are reset to the factory setting.
- Linearization is disabled. If a linearization table is present it is not deleted, however, and can be reactivated if necessary.
- Interference echo suppression (mapping) is disabled. The mapping curve is not deleted, however, and can be reactivated if necessary.

Effect on a 5-point linearization protocol

With the creation of a 5-point linearity protocol, the measuring system (FDU9x sensor and FMU9x transmitter) is adjusted and the measuring accuracy is optimized for the specified range.

The **Zero distance** service parameter is fine-adjusted for this adjustment. Following a reset, this parameter must be re-configured in the Service menu according to the data indicated on the 5-point linearity protocol for the FDU9x sensor. Please contact Endress+Hauser customer service for this purpose.

Performing the reset

1. Navigate to **Device properties** → **Password/reset** → **Reset**.
2. Enter "333".

9.2   Switching on the measuring device

Parameters that need to be configured when the device is switched on for the first time

- **Language**
  Select the language of the display.
- **Length unit**
  Select the unit of length in which the distance is measured.
- **Temperature unit**
  Select the unit for the sensor temperature.
- **Operating mode**
  The possible options depend on the device version and installation environment.
- **Controls**
  Choose whether pump control or rake control should be configured.

9.3 Configuring the measuring device

9.3.1 Parameter set "LVL N sensor sel."

Navigation
Level → Level (LVL) N → Basic setup → LVL N sensor sel.

Parameter
- **Input**
  Assign a sensor to the channel.
- **Sensor selection**
  Specify the sensor type.
  Select the **Automatic** option for FDU9x sensors.
  Select the **Manual** option for FDU8x sensors.
- **Detected**
  Only displayed if **Sensor selection** = **Automatic**
  Displays the sensor type detected automatically.

9.3.2 Parameter set "LVL N appl. para."

Navigation
Level → Level (LVL) N → Basic setup → LVL N app. para.

Parameter
- **Tank shape**
  Select the applicable option.
- **Medium property**
  If the medium cannot be clearly assigned to any of the categories, select the **Unknown** option.
- **Process conditions**
  For liquid applications that do not fall into any other category, select the **Standard liq.** option.
  For bulk solid applications that do not fall into any other category, select the **Standard solid** option.
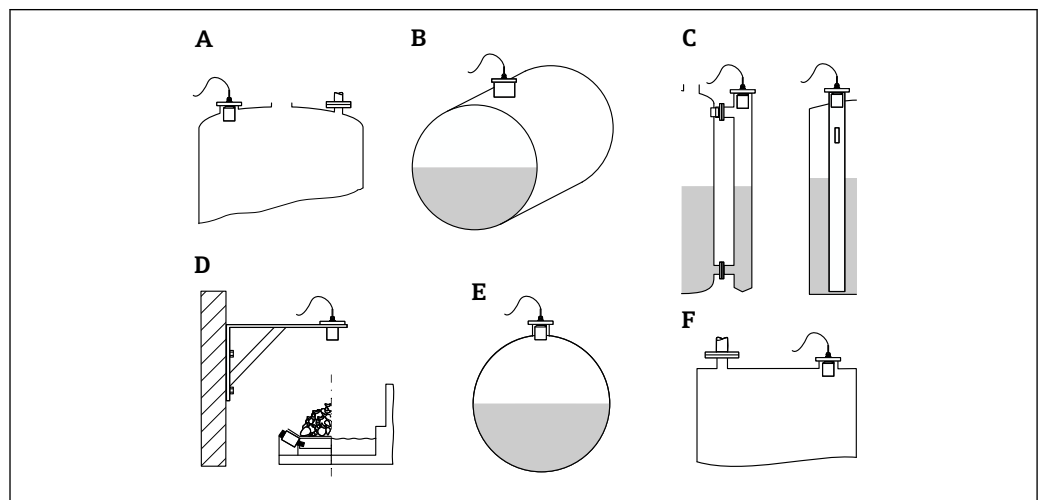
🖾 46   *Tank shape*

A   Dome ceiling
B   Horizontal cylindrical
C   Bypass/stilling well
D   No ceiling
E   Sphere
F   Flat ceiling

9.3.3   Parameter set "LVL N empty cal."
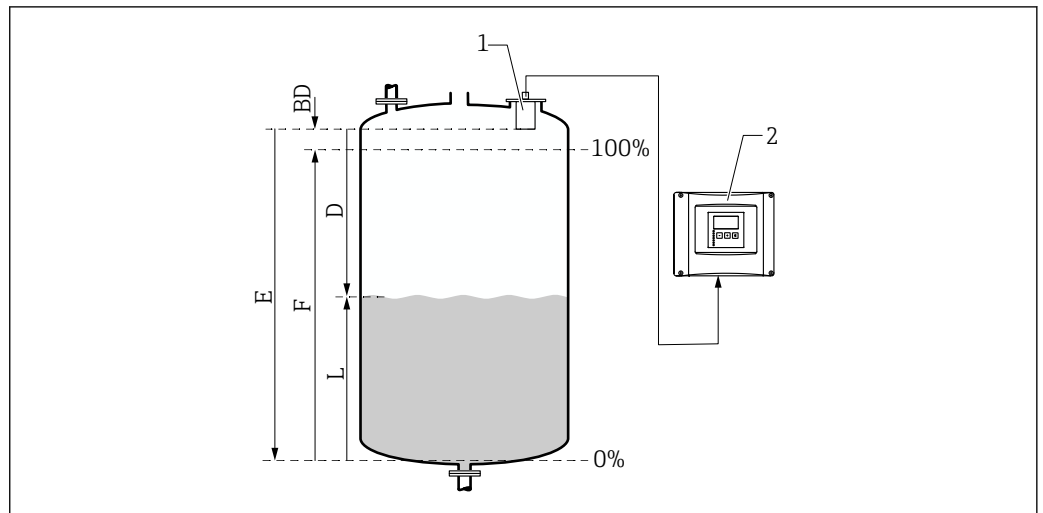
47   Empty and full calibration for level measurement

1   FDU9x sensor
2   FMU90/FMU95 transmitter
BD   Blocking distance
D   Distance between sensor membrane and product surface
E   Empty E
F   Full F
L   Level

Navigation
Level → Level (LVL) N → Basic setup → LVL N empty cal.

Parameter "Empty E"
Specify the distance E from the reference point of the sensor to the minimum level (zero point). The zero point should not be lower than the point where the ultrasonic wave hits the bottom of the tank.

9.3.4   Parameter set "LVL N full cal."

Navigation
Level → Level (LVL) N → Basic setup → LVL N full cal.

Parameter
• **Full F**
  Specify the span F (the distance from the minimum level to the maximum level).
  F may not project into the blocking distance BD of the sensor.
• **Blocking distance**
  Indicates the blocking distance BD of the sensor.

9.3.5   Parameter set "LVL N unit"

Navigation
Level → Level (LVL) N → Basic setup → LVL N unit

Parameter

- **Unit level**

  Select the level unit.

  The level is output in this unit if linearization is not performed.

- **Level N**

  Displays the level F currently measured (from the zero point to the surface of the product) in the selected unit.

- **Sensor**

  Displays the distance D currently measured between the sensor membrane (reference point of the measurement) and the surface of the product.
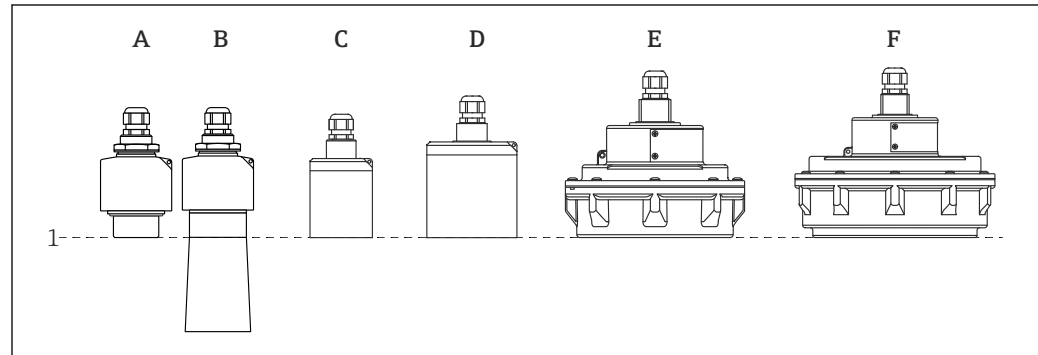
1   Reference point of measurement
A   FDU90 without flooding protection tube
B   FDU90 with flooding protection tube
C   FDU91/FDU91F
D   FDU92
E   FDU93
F   FDU95

9.3.6   Parameter set "LVL N Linearisat."
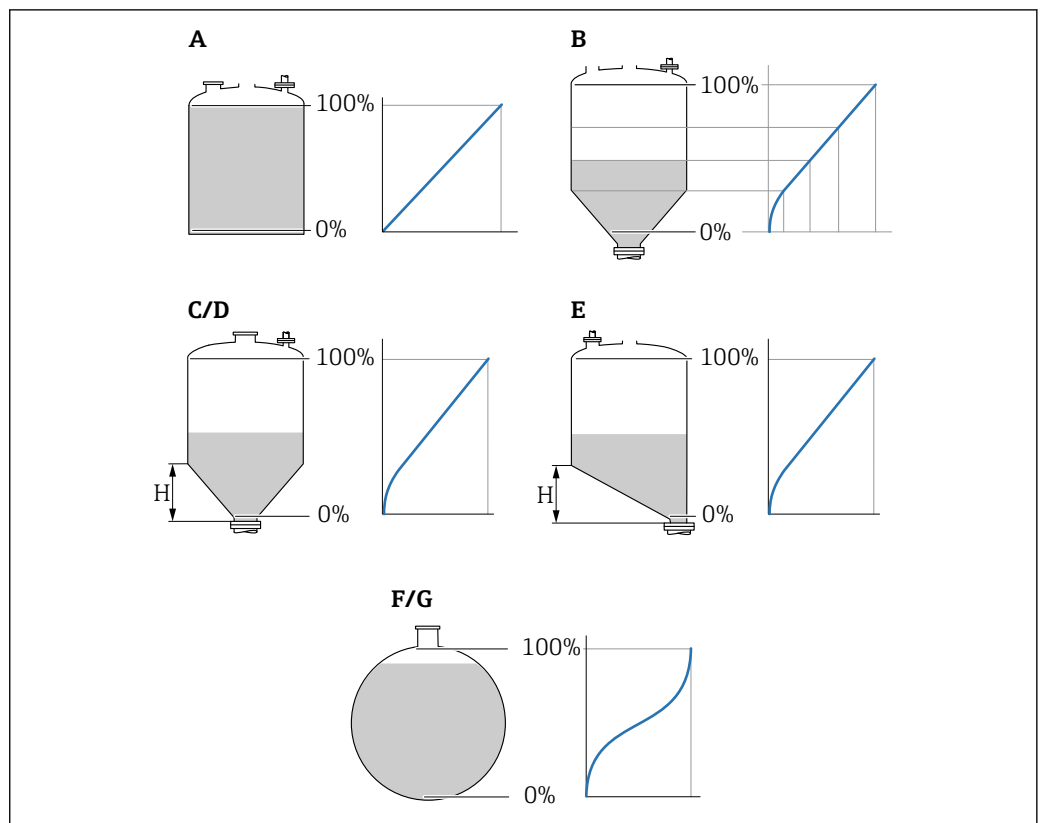
🖻 *48   Types of linearization*

A   None
B   Table
C   Pyramid bottom
D   Conical bottom
E   Angled bottom
F   Sphere
G   Horizontal cylindrical
H   Intermediate height

Navigation
Level → Level (LVL) N → Basic setup → LVL N Linearisat.

Parameter
- **Type**
  Select the type of linearization (see above)
- **Customer unit**
  Specify the unit for the linearized value.
- **Max. scale**
  Specify the maximum vessel content (100 %) in the selected customer unit.
  Not displayed if **Type** = **Table**.
  If **Type** = **Horizontal cyl.** or **Sphere**, the **Max. scale** must always refer to a completely full tank.
- **Diameter**
  Only displayed if **Type** = **Horizontal cyl.** or **Sphere**.
  Specify the diameter D of the tank.
- **Intermediate height (H)**
  Only displayed if **Type** = **Angled bottom**, **Pyramid bottom** or **Conical bottom**
  Specify the intermediate height H of the vessel (see above).

- **Edit**
  Only displayed if **Type** = **Table**.
  Opens the **Edit** parameter set to enter the linearization table.
- **Status table**
  Activates or deactivates the linearization table.
- **Mode**
  Specifies whether the linearization refers to the level or the ullage.

9.3.7   Table editor

Linearization table conditions:
- Up to 32 "Level to volume" value pairs.
- Monotonically increasing or decreasing. (The monotonicity is checked when the table is activated).
- Once entered, must be activated by the **Status table** parameter.

A0040751

A   Line number
B   Column for level
C   Column for values

1. Press [keys] to jump to the next line.

2. Press [keys] to jump to the previous line.

3. Press [keys] to open the selected line for editing.

A0040752

A   Line number
B   Column for level
C   Column for values

1. Press [keys] or [keys] to navigate inside the table.

2. Press [keys] or [keys] to navigate inside the column with the line numbers.

3. Press [keys] to delete the entire line, insert or move a line.

Press **Escape** to return to the previous step.
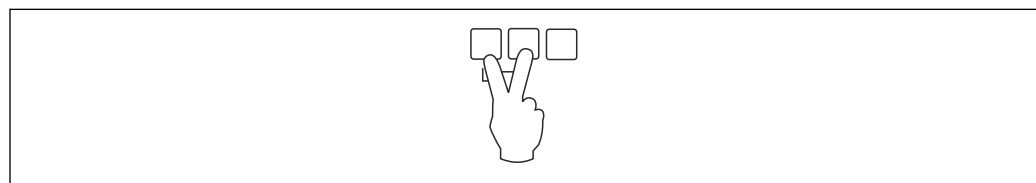
A0032709

9.3.8   Parameter set "Check value"

ℹ️ • This parameter set starts inference echo suppression (mapping).
 • To record all the interference echoes, perform mapping at the minimum level possible (ideally with an empty vessel).
 • If it is not possible to empty the vessel during commissioning, record preliminary mapping when the vessel is partially filled. Repeat mapping when the level reaches approximately 0 % for the first time.
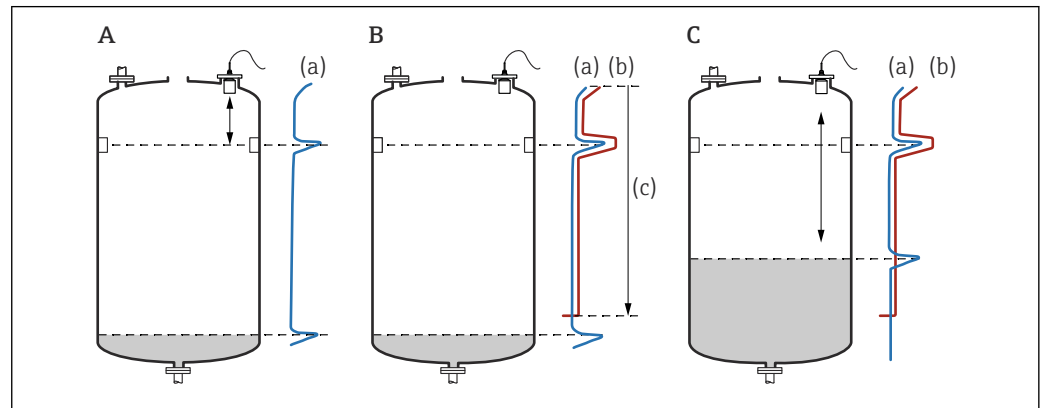
🖾 49   Operating principle of the interference echo suppression (mapping) function

A   The echo curve (a) contains an interference echo and the level echo. Without mapping, the interference echo would also be evaluated. This is not desired.
B   Mapping generates the mapping curve (b). This suppresses all the echoes that are inside the range of mapping (c).
C   Afterwards, only echoes that are higher than the mapping curve are evaluated. The interference echo is below the mapping curve and is therefore ignored (not evaluated).

Navigation
Level → Level (LVL) N → Basic setup → LVL N check value

Parameter
• **Actual distance**
 Displays the distance D currently measured between the sensor membrane and the surface of the product.
• **Check distance**
 Compare the distance displayed with the actual value and enter the result of the comparison. Based on the entry, the device automatically determines the range of mapping.
 • **Distance = ok**
  The displayed distance and actual distance match.
  → Continue with the parameter set **LVL N dist. map.**.
 • **Dist. too small**
  The displayed distance is smaller than the actual distance.
  → Continue with the parameter set **LVL N dist. map.**.
 • **Dist. too big**
  The displayed distance is larger than the actual distance.
  → Mapping is not possible.
  → Setup for sensor N ends.
 • **Dist. unknown**
  Actual distance is unknown.
  → Mapping is not possible.
  → Setup for sensor N ends.
 • **Manual**
  The range of mapping is to be defined manually.
  → Continue with the parameter set **LVL N dist. map.**.

9.3.9 Parameter set "LVL N dist. map."

Navigation
Level → Level (LVL) N → Basic setup → LVL N dist. map.

Parameter
• **Actual distance**
 Displays the distance D currently measured between the sensor membrane and the surface of the product.
• **Range of mapping**
 Specifies the range, starting from the sensor membrane, in which mapping is performed.
   • If **Check distance** = **Distance = Ok** or **Dist. too small**:
     Confirm the preset value.
   • If **Check distance** = **Manual**:
     Enter the desired mapping range.
• **Start mapping**
 Select **Yes** to start recording the mapping curve.
 → The **LVL N status** parameter set appears.
 → If the displayed distance is still too small: keep recording mapping curves until the displayed distance and the actual distance match.
• **Status**
 Specifies the mapping status:
   • **Enable map**
     The mapping curve is taken into consideration during signal evaluation.
   • **Disable map**
     The mapping curve is not taken into consideration during signal evaluation but remains stored in the device.
   • **Delete map**
     The mapping curve is deleted.

9.3.10 Parameter set "US sensor N"

ℹ️ For multi-channel devices: disable unused sensor inputs in the **US sensor N** parameter set.

Navigation
Sensor management → FDU sensor N → Sensor operation

Parameter "Sensor operation"
Switch sensor N on or off.

9.4 Advanced settings

9.4.1 Flooding detection for FDU90

ℹ️ This section only applies to FDU90 sensors with a flooding protection tube.

1. Navigate to: **Safety settings → Safety distance → Saf. dist. sen N**

2.
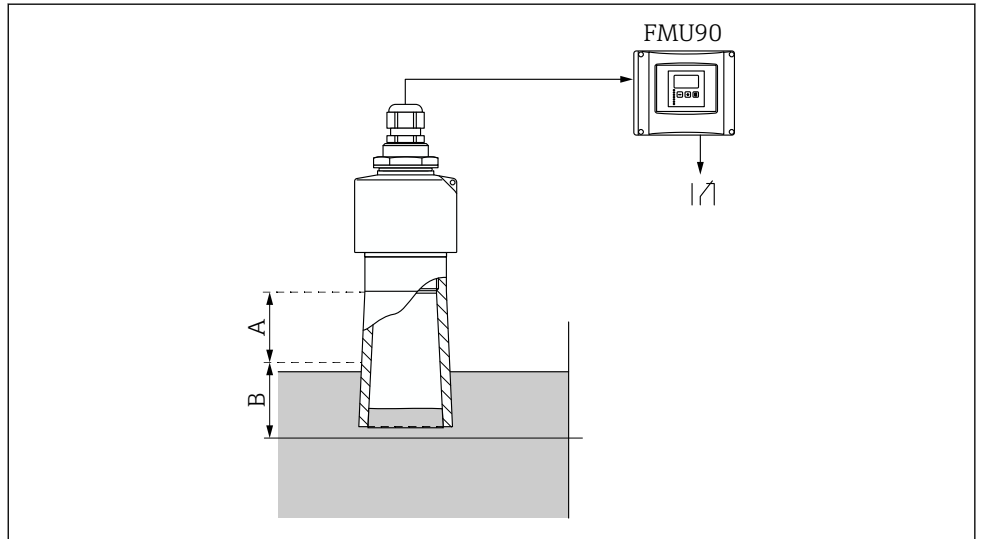
◉ 50   Use of the flooding protection tube for FDU90

A   Blocking distance FDU90: 70 mm (2.8 in)
B   Safety distance to be entered: 40 mm (1.6 in)

Enter 40 mm (1.6 in). With this setting, the safety distance ends just below the flooding protection tube.

3. Navigate to: **Relay/controls → Relay configurat. → Relay allocation**

4. Select a relay.
   ↳ The selected relay is used for the flooding alarm.

5. Navigate to: **Relay/controls → Relay configurat. → Relay N → Function**

6. Select **Alarm/diagnost. → Diagnostics**.

7. Switch to the **Allocation M** parameter

8. Select the **Level in safety distance sensor N** option.
   ↳ The selected relay is de-energized as soon as the level enters the safety distance.

9.4.2   Configuring the local display

Type of visualization
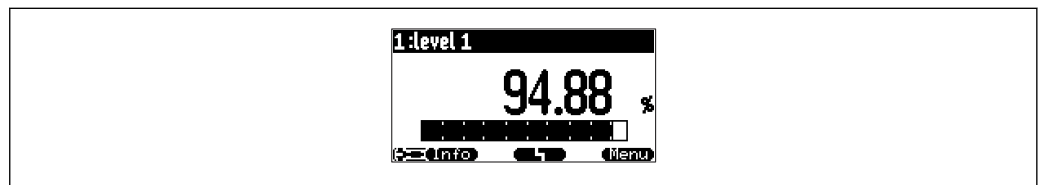
◉ 51   "Type" = "1x value+bargr."
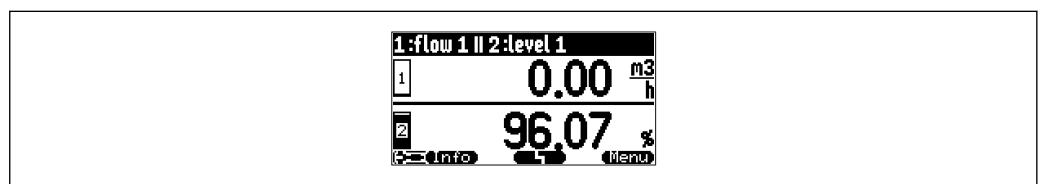
◉ 52   "Type" = "2x value+bargr."
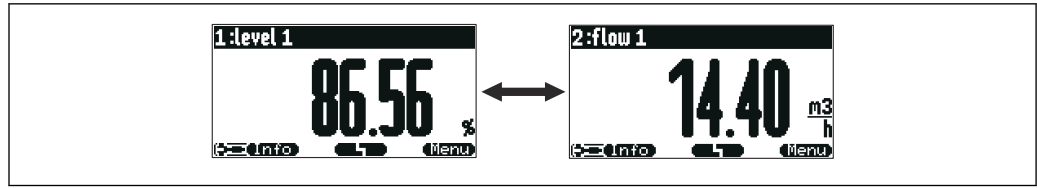
⊠ *53   "Type" = "value max size". The different values are displayed cyclically in maximum size.*
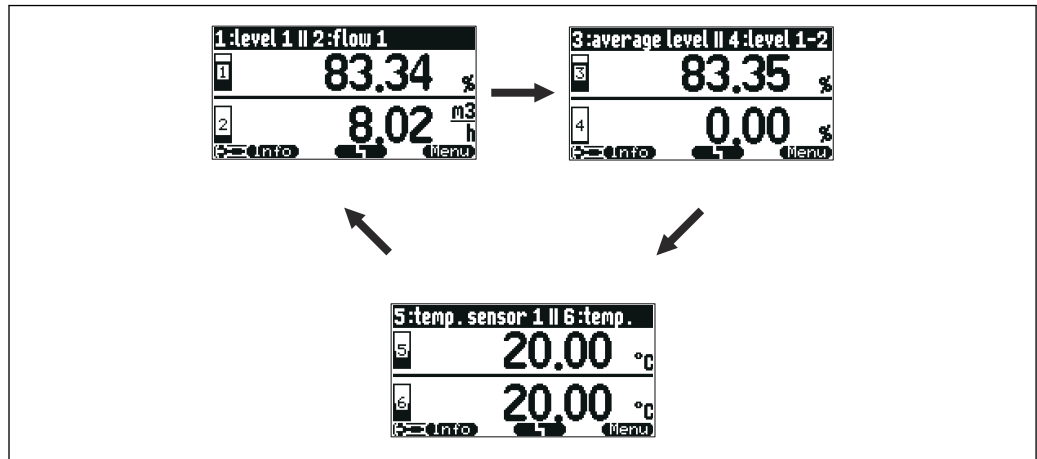
⊠ *54   "Type" = "alter.3x2 val.". Up to six values can be displayed. These values are spread over three pages with two values on each. These pages are displayed cyclically.*

ℹ️ Press ▭▭ in the main display screen to change to the next value immediately.

Configuration of the type of visualization

1. Navigate to the parameter set **Display → Display**.

2. Select the type of visualization in the **Type** parameter (see above).

3. For **Type** = **Value max size** or **Alter. 5x2 val.**:
    In the **Time** parameter, specify the time after which the next screen is displayed.

4. In the **Value 1** to **Value N** parameters, select a measured value to be displayed.

5. In the **Customized text 1** to **Customized text N** parameters, enter a text string to be displayed with the values.
    ↳ The specified text string is displayed if **Customized text** = **Yes** (see below).

Configuration of the display format

1. Navigate to the parameter set: **Display → Display format**.

2. In the **Format** parameter, select the number format for length data.

3. In the **No. of decimals** parameter, specify the number of decimal places that are displayed.

4. In the **Sep. character** parameter, specify whether a comma or dot is used as the decimal separator.

5. In the **Customized text** parameter, specify whether **Customized text 1** to **Customized text N** (see above) is used and displayed on the screen.

Configuration of back to home time

1. Navigate to **Display → Back to home → Back to home**

2. Specify the time after which the onsite display returns to home (measured value display).

9.4.3   Configuring the limit value relay

Limit type = "Standard" or "Tendency/speed"

A0036325
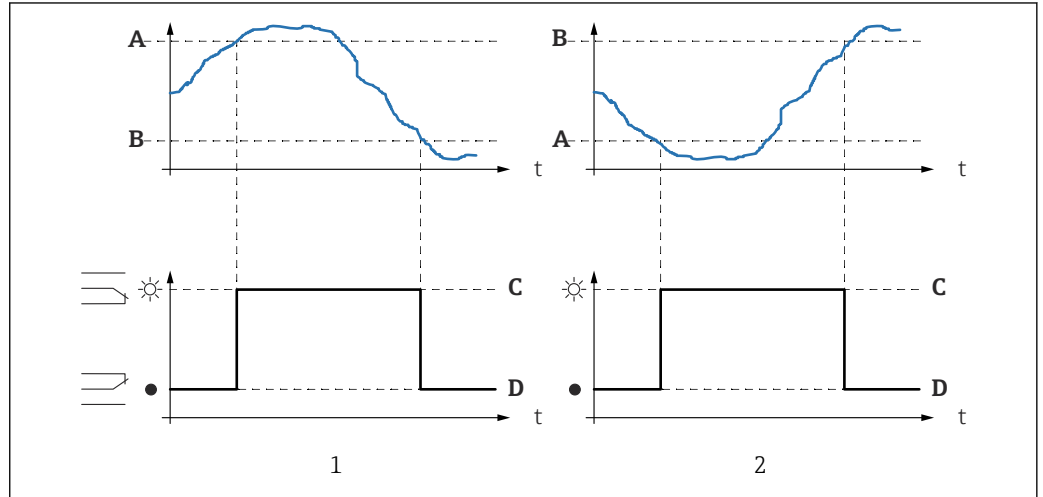
🖼 *55   Parameters for "Limit type" = "Standard" or "Tendency/speed"*

1   "Switch-on point" > "Switch-off point"
2   "Switch-off point" > "Switch-on point"
A   Switch-on point
B   Switch-off point
C   Relay energized
D   Relay de-energized

Limit type = "Inband" or "Out of band"
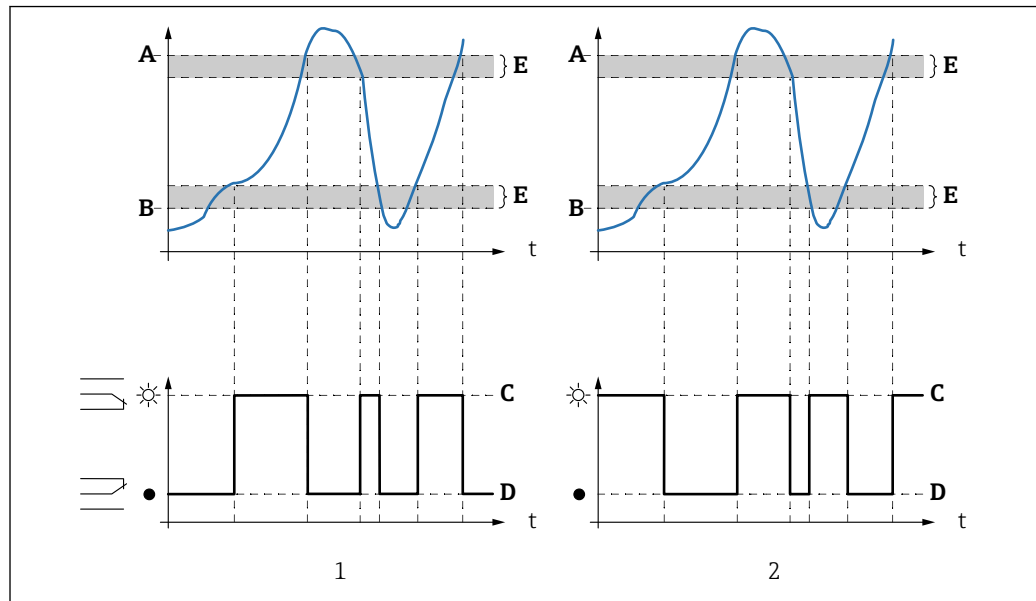
⊠ *56   Parameters for "Limit type" = "Inband" or "Out of band"*

1   "Limit type" = "Inband"
2   "Limit type" = "Out of band"
A   Upper switchpt.
B   Lower switchpt.
C   Relay energized
D   Relay de-energized
E   Hysteresis

Configuration of the limit relay

1. Navigate to the parameter set **Relay/controls → Relay configurat. → Relay N**

2. In the **Function** parameter, select the **Limit** option.
   ↳ The **Function** picklist is displayed.

3. Select the variable to which the limit value refers.

4. In the **Limit type** parameter, select the appropriate limit type (see above).

5. For **Limit type** = **Standard**:
   In the **Switch-on point** parameter, specify the switch-on point.

6. For **Limit type** = **Standard**:
   In the **Switch-off point** parameter, specify the switch-off point.

7. For **Limit type** = **Tendency/speed**:
   In the **Switch on/min** parameter, specify the switch-on point for the speed of change.

8. For **Limit type** = **Tendency/speed**:
   In the **Switch off/min** parameter, specify the switch-off point for the speed of change.

9. For **Limit type** = **Inband** or **Out of band**
   In the **Upper switchpt.** parameter, specify the upper switch point.

10. For **Limit type** = **Inband** or **Out of band**
    In the **Lower switchpt.** parameter, specify the lower switch point.

11. For **Limit type** = **Inband** or **Out of band**
    In the **Hysteresis** parameter, specify the hysteresis for the switch points.

12. In the **Switch delay** parameter, specify the switch delay for the relay.
    ↳ The relay only switches when the limit value has been exceeded for the length of time specified here.

13. In the **Invert** parameter, specify whether the switching direction of the relay is to be inverted in relation to the defined behavior.

14. In the **Error handling** parameter, specify the behavior of the relay if an error occurs.

9.4.4   Configuring the alarm or diagnostics relay

1. Navigate to: **Relay/controls** → **Relay configurat.** → **Relay N**

2. In the **Function** parameter, select the **Alarm/diagnost.** option.
   ↳ The **Function** picklist is displayed.

3. Specify whether the relay indicates an alarm (**Alarm relay** option) or up to two user-definable device states (**Diagnostic** option).

4. For **Function** = **Diagnostic**
   In the **Allocation 1** and **Allocation 2** parameters, select the device states that are to be indicated by the relays.

5. In the **Invert** parameter, specify whether the switching direction of the relay is to be inverted in relation to the defined behavior.

9.4.5   Configuring standard pump control

This section applies to devices with standard pump control:
- FMU90-*1**********
- FMU90-*2**********

Aim of pump control

Activation and deactivation of pumps depending on the measured level

Control function if multiple pumps are used

- **Limit control**
  The number of pumps that are switched on depends solely on the current level and on the switch-on and switch-off points of the pumps concerned.
- **Pump rate control**
  The switch-on and switch-off points are identical for all the pumps. The number of pumps that are switched on is controlled in such a way that - depending on the level - a desired pump rate (level change per time) is reached.

Configuration of the pump control system (function: Limit control)

1. Navigate to **Relay/controls** → **Pump control N**.

2. In the **Reference** parameter, select the level according to which the pumps are to be controlled.

3. In the **Number of pumps** parameter, specify how many pumps are involved in pump control. One relay must be available on the FMU90 for each pump.

4. In the **Function** parameter, select the **Limit control** option.

5. For each pump:
   Select the **Pump M** parameter.
   ↳ The **Pump M/control N** parameter set opens for the configuration of pump M.

6.

A0036679
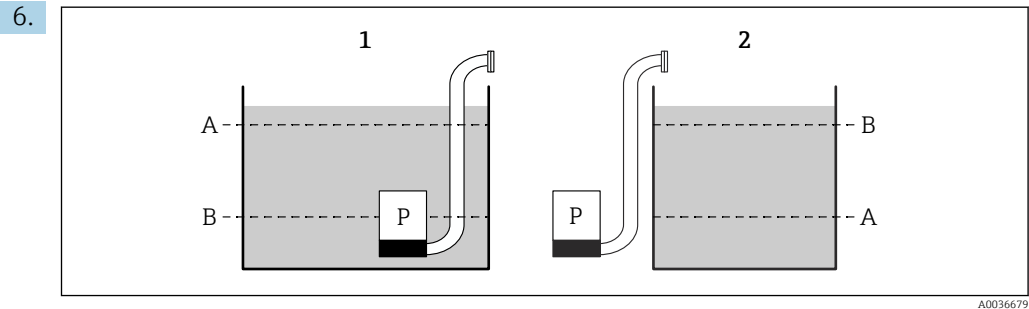
🔲 *57   Switch-on point and switch-off point for limit control*

1   Pump empties a vessel: switch-on point > switch-off point
2   Pump fills a vessel: switch-off point > switch-on point
A   Switch-on point
B   Switch-off point

Set the **Switch-on point** and **Switch-off point** parameters according to the diagram above.

7. In the **Switch-on delay** parameter, set the switch-on delay for the pump in question. Define different switch-on delays for different pumps. This ensures that several pumps are not switched on simultaneously.

8. In the **Alternate** parameter, specify whether the pump should be included in alternating pump control.
   ↳ In alternating pump control, the switch points do not apply for the individual pump. If a pump has to be switched on due to the current level of the medium, the device automatically selects the pump that has been used the least.

9. In the **Crust reduction** parameter, enter a suitable fluctuation value for the switch points.
   ↳ The position of the switch points varies statistically with the specified margin of fluctuation. This helps prevent the formation of buildup at the switch points.

10.

🖾 58   Effect of "Backlash interval" and "Backlash time"

A   Switch-on point
B   Switch-off point
C   Pump on
D   Pump off
E   Backlash interval
F   Backlash time

If, for example, you want to empty a pump chamber at regular intervals for a period of time that extends beyond the switch-off point, proceed as follows:

In the **Backlash interval** parameter, specify the time after which extended pumping should occur. In the **Backlash time** parameter, specify the duration of this extended pumping procedure.

11. In the **Error handling** parameter, define how the pump relay responds when an error occurs.

12. In the **Relay allocation** parameter, assign a relay to the pump that has just been configured.

    ↳ The **Relay K** parameter set appears.

13. In the **Relay K → Function** parameter, select the **Pump M/control N** option.

    ↳ Pump M is now controlled via relay K.

14. In the **Invert** parameter, specify whether the switching direction of the relay should be inverted in relation to the defined behavior.

    ↳ The pump is fully configured. Continue with the next pump.

Configuration of the pump control system (function: Pump rate control)
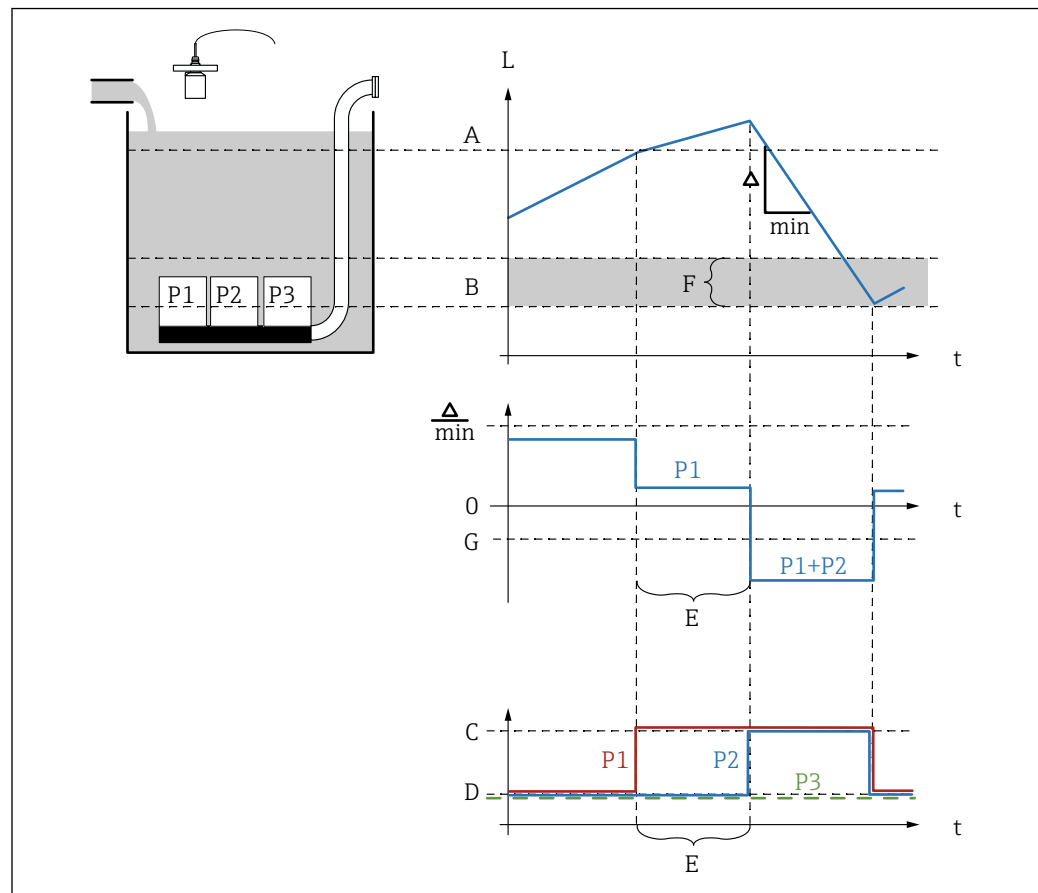
🖾 *59   Operating principle of pump rate control*

A   Switch-on point
B   Switch-off point
C   Pump on
D   Pump off
E   Hook up interval
F   Switch on border
G   Min. pump rate/min

1. Navigate to **Relay/controls → Pump control N**.

2. In the **Reference** parameter, select the level according to which the pumps are to be controlled.

3. In the **Number of pumps** parameter, specify how many pumps are involved in pump control. One relay must be available on the FMU90 for each pump.

4. In the **Function** parameter, select the **Rate control** option.

5. In the **Switch-on point** and **Switch-off point** parameters, specify the switch points for pump rate control.

6. In the **Min. pump rate** parameter, specify the desired minimum pump rate. (Positive values: filling, negative values: emptying).

7. In the **Crust reduction** parameter, enter a suitable fluctuation value for the switch points.
   - ↳ The position of the switch points varies statistically with the specified margin of fluctuation. This helps prevent the formation of buildup at the switch points.

8. In the **Switch on border** parameter, specify the limit level for switching on an additional pump.
   - ↳ If the distance between the current level and the switch-off point is smaller than the switch-on border, no additional pumps are switched on even if the desired pump rate has not yet been reached.

9. In the **Hook up interval** parameter, specify the time after which an additional pump is switched on.

10. In the **Alternate** parameter, specify whether the pumps should be switched on in an alternating manner.
    - ↳ With alternating pump control, when the device has to switch on an additional pump it automatically selects the pump that has been used the least.

11. For each pump:
    Select the **Pump M** parameter.
    - ↳ The **Pump M/control N** parameter set opens for the configuration of pump M.

12. In the **Switch-on delay** parameter, set the switch-on delay for the pump in question.

13.
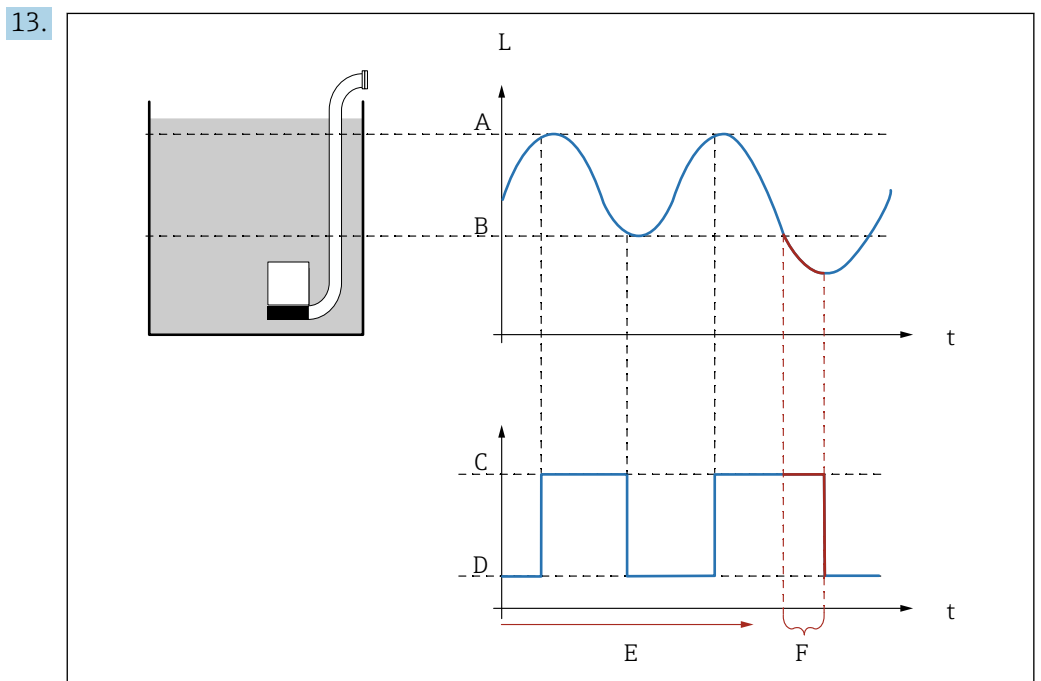
A0036678

🖾 *60   Effect of "Backlash interval" and "Backlash time"*

A   *Switch-on point*
B   *Switch-off point*
C   *Pump on*
D   *Pump off*
E   *Backlash interval*
F   *Backlash time*

If, for example, you want to empty a pump chamber at regular intervals for a period of time that extends beyond the switch-off point, proceed as follows:

In the **Backlash interval** parameter, specify the time after which extended pumping should occur. In the **Backlash time** parameter, specify the duration of this extended pumping procedure.

14. In the **Error handling** parameter, define how the pump relay responds when an error occurs.

15. In the **Relay allocation** parameter, assign a relay to the pump that has just been configured.
    - ↳ The **Relay K** parameter set appears.

16. In the **Relay K → Function** parameter, select the **Pump M/control N** option.
    ↳ Pump M is now controlled via relay K.

17. In the **Invert** parameter, specify whether the switching direction of the relay should be inverted in relation to the defined behavior.
    ↳ The pump is fully configured. Continue with the next pump.

9.4.6 Configuring advanced pump control

This section applies to devices with advanced pump control:
- FMU90-*3**********
- FMU90-*4**********

Aim of pump control

Activation and deactivation of pumps depending on the measured level

Control function if multiple pumps are used

- **Limit single**
  One pump, at the very maximum, is switched on at any one time. If a new pump has to be switched on due to the current level of the medium, the pump that is currently in operation is switched off.
- **Limit parallel**
  Several pumps can be in operation simultaneously. The number of pumps that are switched on depends solely on the current level and on the switch-on and switch-off points of the pumps concerned.
- **Pump rate control**
  The switch-on and switch-off points are identical for all the pumps. The number of pumps that are switched on is controlled in such a way that a desired pump rate (level change per time) is reached.

Configuration of the pump control system (function: "Limit single" or "Limit parallel")

1. Navigate to: **Relay/controls → Pump control N → Basic setup → Pump control N**

2. In the **Reference** parameter, select the level according to which the pumps are to be controlled.

3. In the **Number of pumps** parameter, specify how many pumps are involved in pump control. One relay must be available on the FMU90 for each pump.

4. If the last pump in the group is to act as a standby pump:
   In the **Standby pump** parameter, select the **Yes** option.
   ↳ As soon as the failure of a pump is reported to the Prosonic S via a digital input, the standby pump takes over from the faulty pump.

5. To reset pump control:
   In the **Reset** parameter, select the **Yes** option.
   ↳ Pump error messages are reset when a reset is performed. The reset does not affect the configuration of the pump control.

6. In the **Function** parameter, select the **Limit single** or **Limit parallel** option.

7. In the **Load control** parameter, specify the criterion for controlling the relative load on the pumps (fixed pump sequence, time of use of the individual pumps or number of starts of the individual pumps).

8. For each pump:
   Select the **Pump M** parameter.
   ↳ The parameter set opens for the configuration of pump M.

9.

A0036679
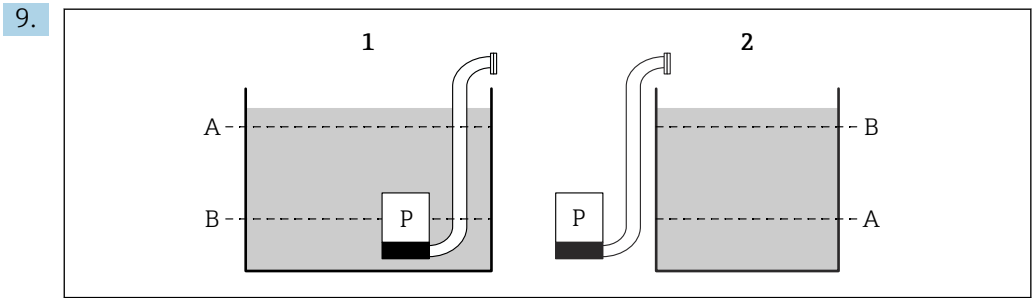
☒ *61*   *Switch-on point and switch-off point for limit control*

1   *Pump empties a vessel: switch-on point > switch-off point*
2   *Pump fills a vessel: switch-off point > switch-on point*
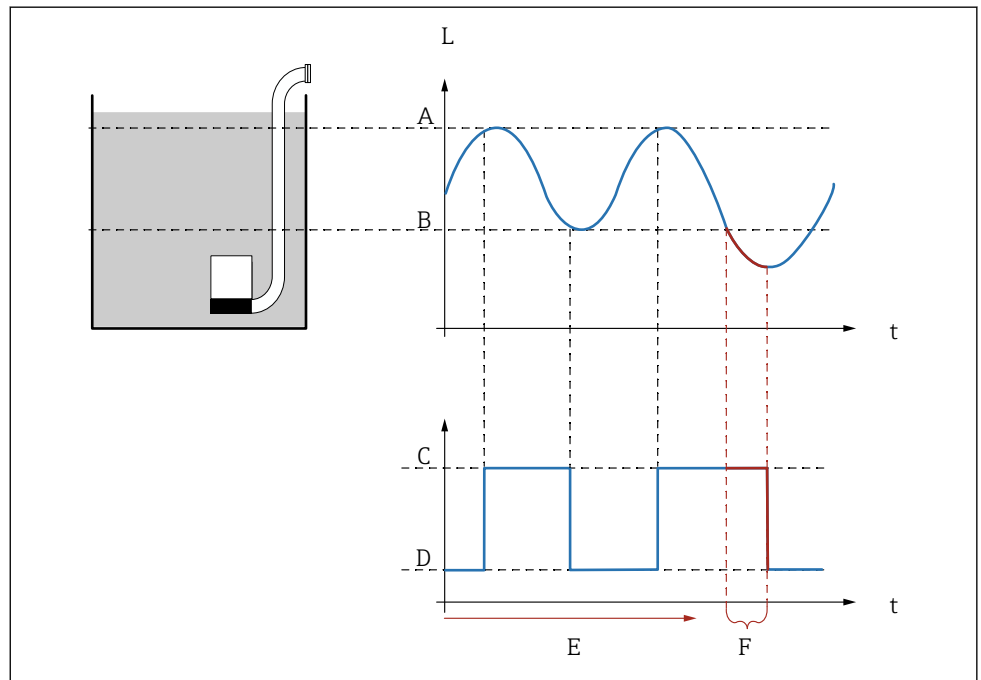*A*   *Switch-on point*
B   *Switch-off point*

Set the **Switch-on point** and **Switch-off point** parameters according to the diagram above.

10. In the **Switch-on delay** parameter, set the switch-on delay for the pump in question. Define different switch-on delays for different pumps. This ensures that several pumps are not switched on simultaneously.

11. In the **Alternate** parameter, specify whether the pump should be included in alternating pump control.
    ↳ In alternating pump control, the switch points do not apply for the individual pump. If a pump has to be switched on due to the current level of the medium, the device automatically selects the pump that has been used the least (according to the criterion selected in the **Load control** parameter).

12. For **Load control** = **Time of use** or **Starts**:
    In the **Degree of use** parameter, specify the desired percentage time of use of the pump. The total degree of usage of all pumps participating in alternating pump control must be 100 %.

13. For **Load control** = **Starts + time**
    In the **Max. use time** parameter, specify the maximum amount of time the pump remains switched on once it has started.

14. In the **Crust reduction** parameter, enter a suitable fluctuation value for the switch points.
    ↳ The position of the switch points varies statistically with the specified margin of fluctuation. This helps prevent the formation of buildup at the switch points.

15.
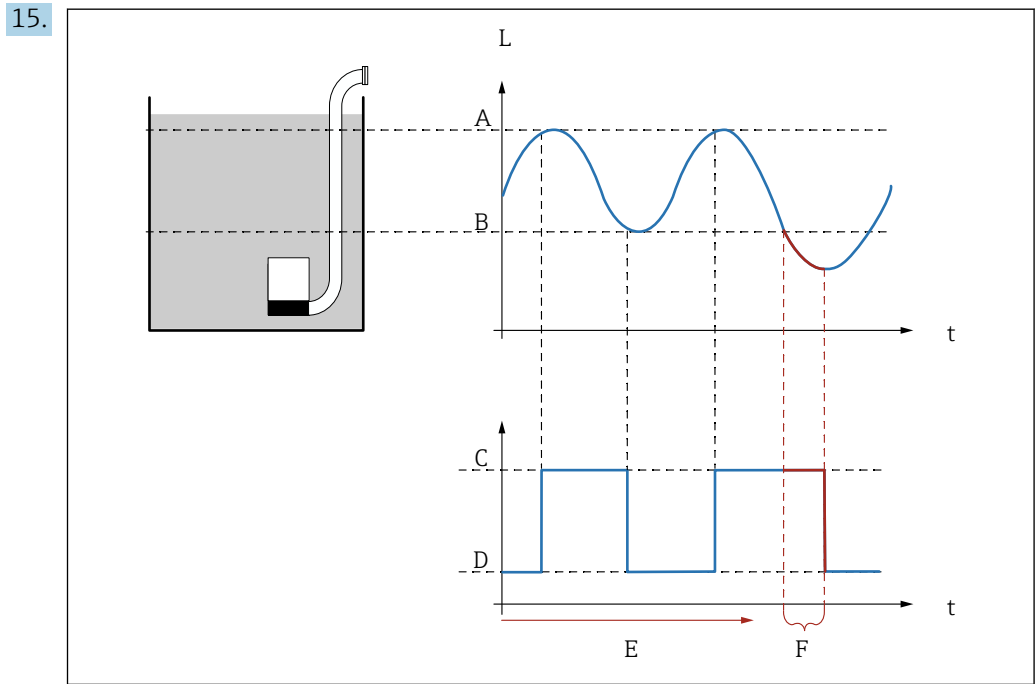
🖼 *62   Effect of "Backlash interval" and "Backlash time"*

A   *Switch-on point*
B   *Switch-off point*
C   *Pump on*
D   *Pump off*
E   *Backlash interval*
F   *Backlash time*

If, for example, you want to empty a pump chamber at regular intervals for a period of time that extends beyond the switch-off point, proceed as follows:

In the **Backlash interval** parameter, specify the time after which extended pumping should occur. In the **Backlash time** parameter, specify the duration of this extended pumping procedure.

16. In the **Error handling** parameter, define how the pump relay responds when an error occurs.

17. In the **Pump feedback** parameter, specify the switch input via which the pump sends feedback to the Prosonic S.

18. In the **Feedback delay** parameter, specify the time frame within which feedback from the pump is required after the pump has started. Take the start delay of the relay into consideration here. Minimum value for the feedback delay: "number of pumps" x "start delay relay"

  ↳ Feedback after this time is not taken into consideration.

19. In the **Feedb. meaning** parameter, specify the meaning of the pump feedback (confirms a pump start or reports a pump failure).

20. In the **Relay allocation** parameter, assign a relay to the pump that has just been configured.

  ↳ The **Relay K** parameter set appears.

21. In the **Relay K → Function** parameter, select the **Pump M/control N** option.

  ↳ Pump M is now controlled via relay K.

22. In the **Invert** parameter, specify whether the switching direction of the relay should be inverted in relation to the defined behavior.

  ↳ The pump is fully configured. Continue with the next pump.

Configuration of the pump control system (function: Pump rate control)

🖾 63   *Operating principle of pump rate control*

A   Switch-on point
B   Switch-off point
C   Pump on
D   Pump off
E   Hook up interval
F   Switch on border
G   Min. pump rate/min

1. Navigate to: **Relay/controls → Pump control N → Basic setup → Pump control N**

2. In the **Reference** parameter, select the level according to which the pumps are to be controlled.

3. In the **Number of pumps** parameter, specify how many pumps are involved in pump control. One relay must be available on the FMU90 for each pump.

4. If the last pump in the group is to act as a standby pump:
   In the **Standby pump** parameter, select the **Yes** option.
   ↳ As soon as the failure of a pump is reported to the Prosonic S via a digital input, the standby pump takes over from the faulty pump.

5. To reset pump control:
   In the **Reset** parameter, select the **Yes** option.
   ↳ Pump error messages are reset when a reset is performed. The reset does not affect the configuration of the pump control.

6. In the **Function** parameter, select the **Rate control** option.

7. In the **Load control** parameter, specify the criterion for controlling the relative load on the pumps (fixed pump sequence, time of use of the individual pumps or number of starts of the individual pumps).

8. In the **Switch-on point** and **Switch-off point** parameters, specify the switch points for pump rate control.

9. In the **Min. pump rate** parameter, specify the desired minimum pump rate. (Positive values: filling, negative values: emptying).

10. In the **Hook up interval** parameter, specify the time after which an additional pump is switched on.

11. In the **Switch on border** parameter, specify the limit level for switching on an additional pump.
    ↳ If the distance between the current level and the switch-off point is smaller than the switch-on border, no additional pumps are switched on even if the desired pump rate has not yet been reached.

12. In the **Alternate** parameter, specify whether the pumps should be switched on in an alternating manner.
    ↳ In alternating pump control, the switch points do not apply for the individual pump. If a pump has to be switched on due to the current level of the medium, the device automatically selects the pump that has been used the least (according to the criterion selected in the **Load control** parameter).

13. In the **Crust reduction** parameter, enter a suitable fluctuation value for the switch points.
    ↳ The position of the switch points varies statistically with the specified margin of fluctuation. This helps prevent the formation of buildup at the switch points.

14. For each pump:
    Select the **Pump M** parameter.
    ↳ The **Pump M/control N** parameter set opens for the configuration of pump M.

15. In the **Switch-on delay** parameter, set the switch-on delay for the pump in question.

16. For **Load control** = **Time of use** or **Starts**:
    In the **Degree of use** parameter, specify the desired percentage time of use of the pump. The total degree of usage of all pumps participating in alternating pump control must be 100 %.

17. For **Load control** = **Starts + time**
    In the **Max. use time** parameter, specify the maximum amount of time the pump remains switched on once it has started.

18.

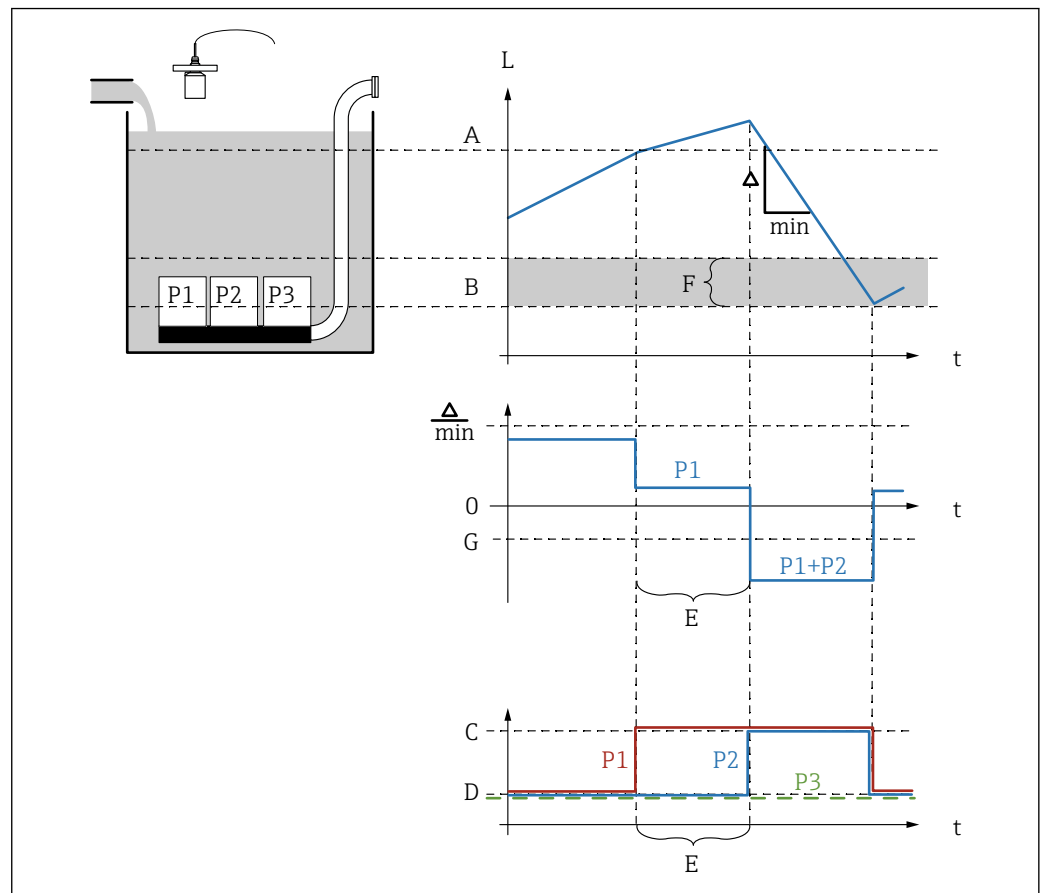🖻 64   *Effect of "Backlash interval" and "Backlash time"*

A   Switch-on point
B   Switch-off point
C   Pump on
D   Pump off
E   Backlash interval
F   Backlash time

If, for example, you want to empty a pump chamber at regular intervals for a period of time that extends beyond the switch-off point, proceed as follows:

In the **Backlash interval** parameter, specify the time after which extended pumping should occur. In the **Backlash time** parameter, specify the duration of this extended pumping procedure.

19.   In the **Error handling** parameter, define how the pump relay responds when an error occurs.

20.   In the **Pump feedback** parameter, specify the switch input via which the pump sends feedback to the Prosonic S.

21.   In the **Feedback delay** parameter, specify the time frame within which feedback from the pump is required after the pump has started. Take the start delay of the relay into consideration here. Minimum value for the feedback delay: "number of pumps" x "start delay relay"

↳   Feedback after this time is not taken into consideration.

22.   In the **Feedback meaning** parameter, specify the meaning of the pump feedback.

23.   In the **Relay allocation** parameter, assign a relay to the pump that has just been configured.

↳   The **Relay K** parameter set appears.

24.   In the **Relay K → Function** parameter, select the **Pump M/control N** option.

↳   Pump M is now controlled via relay K.

25.   In the **Invert** parameter, specify whether the switching direction of the relay should be inverted in relation to the defined behavior.

↳   The pump is fully configured. Continue with the next pump.

9.4.7   Configuring rake control

Operating principle of the rake control function

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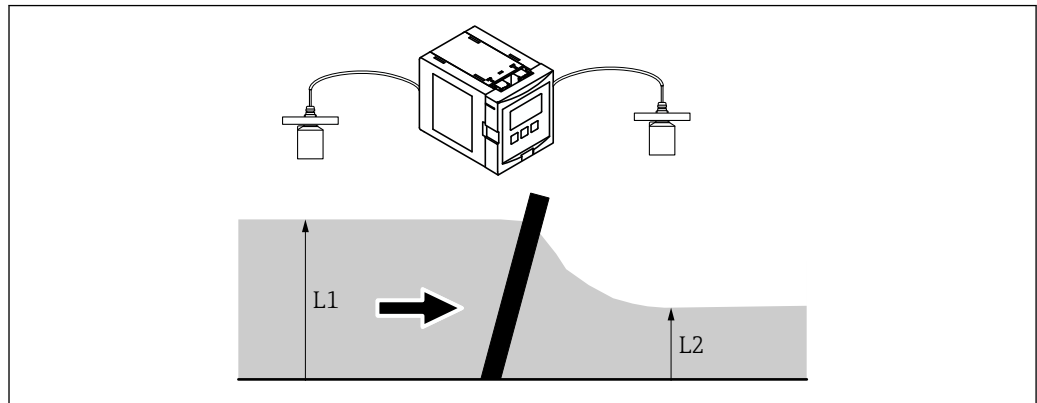
🖼 *65   Operating principle of the rake control function*

- The rake control function uses two levels, namely L_1 and L_2. If the downstream level L_2 is significantly smaller than the upstream level L_1, this is an indication that the rake is clogged.
- Detected rake clogging is output via a relay. This can be used to activate cleaning by the rake.

Configuration of the rake control function

1. Navigate to: **Relay/controls** → **Rake control** → **Rake control**

2. In the **Upstream water** parameter, select the level signal L_1.

3. In the **Downstream water** parameter, select the level signal L_2.

4. In the **Function** parameter, specify whether the difference or the ratio of L_1 to L_2 is evaluated.

5. For **Function** = **Difference**:
    In the **Switch-on point** and **Switch-off point** parameters, enter suitable limit values for the difference $L_1 - L_2$.
    ↳ The rake contamination relay is energized if $L_1 - L_2$ exceeds the switch-on point. The rake contamination relay is de-energized if $L_1 - L_2$ drops below the switch-off point.

6. For **Function** = **Ratio**:
    In the **Switch-on point** and **Switch-off point** parameters, enter suitable limit values for the ratio L_2/L_1.
    ↳ The rake contamination relay is energized if L_2/L_1 drops below the switch-on point. The rake contamination relay is de-energized if L_1/L_2 exceeds the switch-off point.

7. In the **Switch delay** parameter, enter a suitable value so that rake cleaning is not activated unnecessarily in the event of brief fluctuations of the L_1 or L_2 value.

8. In the **Error handling** parameter, define how the rake control relay responds when an error occurs.

9. In the **Relay allocation** parameter, assign a relay to rake control.
    ↳ The **Relay N** parameter set appears.

10. In the **Relay N** → **Function** parameter, select the **Rake control** option.

11. In the **Invert** parameter, specify whether the switching direction of the relay should be inverted in relation to the defined behavior.

9.4.8 Configuring the current outputs

Assigning a measured value to the current output

1. Navigate to: **Output/calculat.** → **Current output N** → **Allocat./calculat.** → **Allocat. curr. N**

2. In the **Output** parameter, specify which value is output via the current output.
   ↳ The **Output current** parameter displays the latest output current.

Extended calibration of the current output

1. Navigate to: **Output/calculat.** → **Current output N** → **Extended calibr.** → **Mode current N**

2.
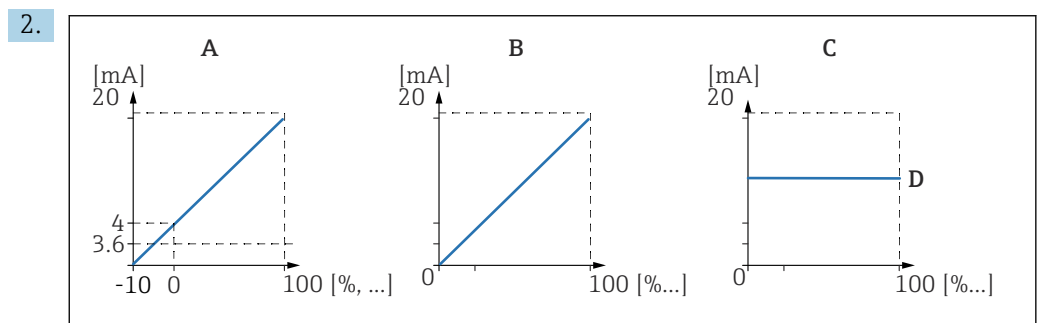
▣ 66   *Current span*

A   4 to 20 mA
B   0 to 20 mA
C   Fix. current HART
D   mA value

In the **Current span** parameter, select the current range to which the measured value (0 % to 100 %) will be mapped. If the **Fix. current** option is selected, the measured value is only transmitted via the HART signal.

3. For **Current span** = **Fix. current HART**:

   In the **mA value** parameter, specify the value of the fixed current.

4.
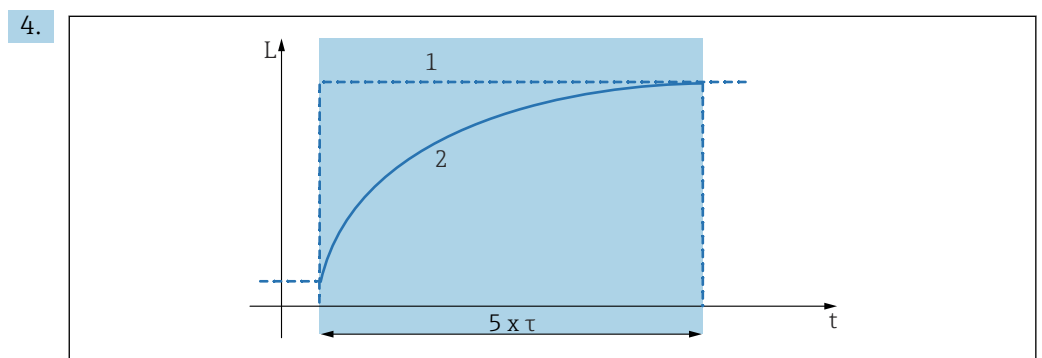
▣ 67   *Output damping*

1   Measured value
2   Output current

In the **Output damping** parameter, define the attenuation constant τ used to attenuate the output signal.

5.
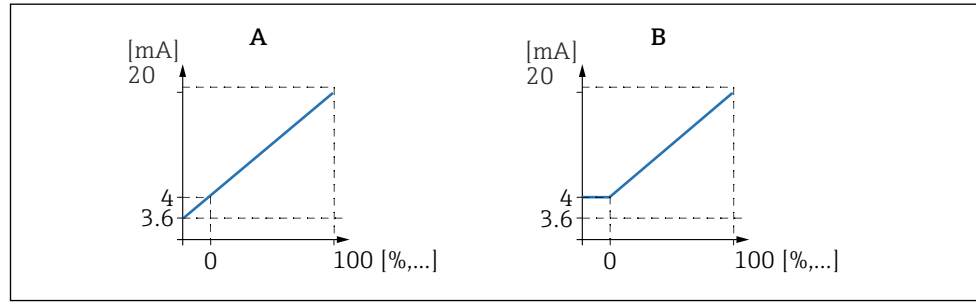
⊠ 68   4mA threshold (only for current span = 4 to 20 mA)

A   4mA threshold off
B   4mA threshold on

For **Current span** = **4-20 mA**:

In the **4-mA threshold** parameter, switch the lower threshold limit for the current on or off.

↳ When the 4-mA threshold is switched on, the minimum current is 4 mA even if the measured value is lower.

6.
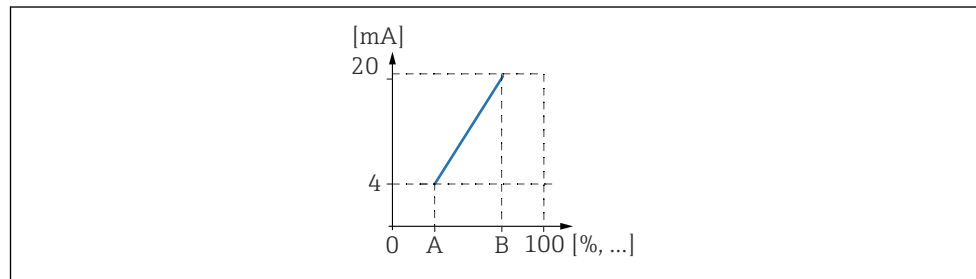
⊠ 69   Operating principle of the current turn down

A   Turn down 0/4mA
B   Turn down 20mA

In the **Curr. turn down** parameter, specify whether the current turn down is switched on or off.

↳ The current turn down spreads the level signal. Without the current turn down, the entire level range (0 % to 100 %) is mapped to the current range. When the current turn down function is switched on, a section of the level range (defined by the **Turn down 0/4mA value** and the **Turn down 20mA value**) is mapped to the current range.

7. For **Curr. turn down** = **On**:

   In the **Turn down 0/4mA value** parameter, specify the measured value at which the current is 0 mA or 4 mA.

8. For **Curr. turn down** = **On**:

   In the **Turn down 20mA value** parameter, specify the measured value at which the current is 20 mA.

9.4.9   Configuring the HART signal

This section only applies to current output 1. The first HART variable (PV) always corresponds to the measured value which is also assigned to the current. The other HART variables can be defined in the **HART settings** submenu.

1. Navigate to: **Output/calculat.** → **Current output N** → **HART settings** → **HART settings**

2. In the **HART address** parameter, specify the HART address of the device.
   ↳ If the address is set to 0, the measured value is also output via the current value. For addresses 1 - 15, the output current is constant. The measured value is then only output via the HART signal.

3. In the **No. of preambles** parameter, specify the number of preambles for the HART protocol.

4. In the **Measured value N** parameter (N = 2 - 4), specify which measured value is output via the HART variable.

5. In the **Output damping N** parameter (N = 2 -4), specify the attenuation constant for the HART variable.

9.5   Simulation

9.5.1   Level or volume simulation

Navigation
Level → Level N → Simulation

Parameter
- **Simulation**
  Select the variable to be simulated (level or volume)
- **Sim. level value**
  Only displayed if **Simulation** = **Sim. level**
  Enter the level to be simulated. The linearization and the output signal follow this value.
- **Sim. volume value**
  Only displayed if **Simulation** = **Sim. volume**
  Enter the volume to be simulated. The output signal follows this value.

9.5.2   Current simulation

Navigation
Output/calculat. → Current output N → Simulation

Parameter
- **Simulation**
  Switch simulation on or off.
- **Simulation value**
  Only available if **Simulation** = **On**.
  Specify the current to be simulated. The current output adopts this value.

9.6   Protecting settings from unauthorized access

9.6.1   Software locking

Locking

1. Navigate to **Device properties** → **Password/reset** → **Code**.

2. Enter a number ≠ 100.
   ↳ The device is locked; no entries can be made.

Unlocking

▶ If an attempt is made to change a parameter, the device jumps to **Password/reset**. Enter "**100**".
   ↳ Entries can be made again.

9.6.2 Keypad lock

Locking

▶ Press all three keys simultaneously.
  ↳ The device is locked; no entries can be made. The [⊙▭] symbol appears on the display.

Unlocking

▶ If an attempt is made to change a parameter, the device jumps to **Password/reset**. **Key-locked** is displayed in the **Status** parameter.
  Press all three keys simultaneously.
  ↳ Entries can be made again.

9.6.3 Hardware locking
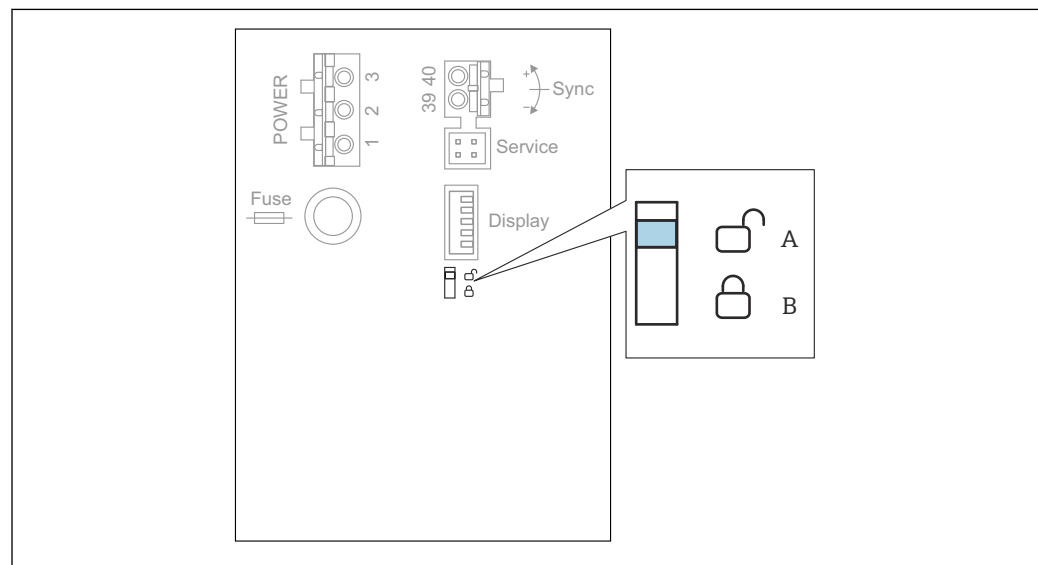
🖂 *70   Hardware locking*

A   Unlocked
B   Locked

A write protection switch, which can be used to lock the device against parameter changes, is located on the basic terminal area in the terminal compartment. When the device is locked the [⊙▭] symbol is shown on the display.

9.6.4 Displaying the locking status

Navigation
Device properties → Password/reset → Status

Display options

- **Unlocked**

  All parameters (apart from Service parameters) can be edited.
- **Code locked**

  The device has been locked via the operating menu. It can only be unlocked again by entering the access code in the **Device settings** → **Password/reset** → **Code** parameter.
- **Key-locked**

  The device has been locked via the operating keys. It can only be unlocked again by pressing all three keys simultaneously.
- **Switch-locked**

  The device has been locked via the write protection switch in the terminal compartment. It can only be unlocked again using this switch.

10 Diagnostics and troubleshooting

10.1 General troubleshooting

10.1.1 Calibration error

Measured value incorrect

Check the **Actual distance** parameter.
- The **Actual distance** is incorrect:
  - For measurements in a bypass or ultrasound guide pipe:
    Set the appropriate option in the **LVL N appl. param.** parameter set.
  - Perform interference echo suppression (mapping) (**LVL N check value** parameter set).
- The **Actual distance** is correct:
  - Check the **Empty E** and **Full F** parameters and correct them if necessary.
  - Check linearization and correct it if necessary.

No change of measured value on filling/emptying

- Perform interference echo suppression (mapping).
- Clean sensor.
- Select a better installation position for the sensor (to avoid interference echoes).

If the surface is turbulent, the measured value jumps sporadically to higher levels

- Perform interference echo suppression (mapping).
- Set the **Process cond.** parameter to **Turb. surface** or **Add. agitator**.
- Select another installation position and/or a larger sensor.

During filling/emptying, the measured value drops sporadically.

- Set the **Tank shape** parameter to **Dome ceiling** or **Horizontal cyl.**
- Avoid a central mounting position for the sensor.
- If possible, use a stilling well/ultrasound guide pipe.

Echo loss (error E xx 641)

- Check all the application parameters (**LVL N appl. param.** parameter set)
- Select another installation position and/or a larger sensor.
- Align the sensor so that it is parallel to the surface of the product (particularly for bulk solids applications).

10.1.2 Checking the signal in the envelope curve display

Aim of the envelope curve display

The measuring signal can be checked with the envelope curve display. From the envelope curve, it is possible to see if interference echoes are present and if these echoes are completely suppressed by the interference echo suppression (mapping) function.

Envelope curve on the display module

To call the envelope curve display:

1. Navigate to **System informat.** → **Envelope curve**.

2. For devices with several sensors:
   Select the sensor whose envelope curve is to be displayed.

3. Select which type of curve is to be displayed: envelope curve, floating average curve (FAC), mapping curve.

4. Select the display format: **single curve** or **cyclic**.
   ↳ The envelope curve display now appears:
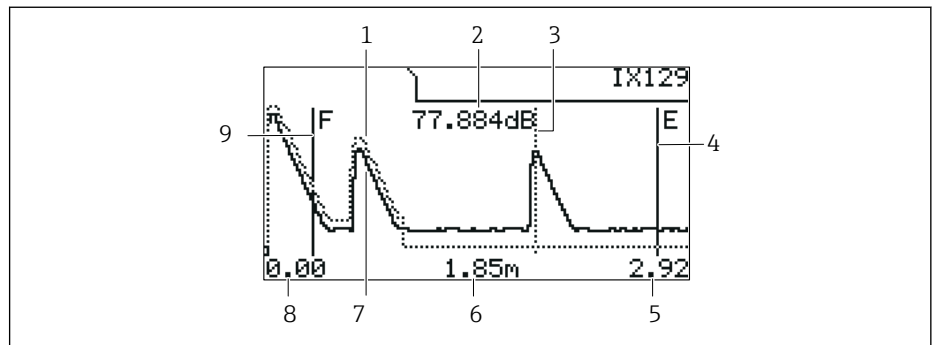
🔲 71   *Envelope curve on the local display*

1   Mapping curve (dotted line)
2   Echo quality of the evaluated echo (i.e. distance of the peak of the echo from the floating average curve)
3   Marking for the evaluated echo
4   Marking for empty calibration E
5   Right limit of the display range
6   Distance of the evaluated echo (measured from the reference point of the sensor)
7   Envelope curve (solid line)
8   Left limit of the display range
9   Marking for full calibration F

Scaling the envelope curve display

1. Press the left or middle key.
   ↳ The ◀▶ or ▶◀ symbol appears in the top right-hand corner of the chart.

2. To zoom in: press the middle key.

3. To zoom out: press the left key.

Moving the envelope curve horizontally

1. Press the right key.
   ↳ The ◀◀ or ▶▶ symbol appears in the top right-hand corner of the chart.

2. To move the screen to the right, press the middle key.

3. To move the screen to the left, press the left key.

Quitting the envelope curve display

▶ Press all three keys simultaneously.

Envelope curve display in FieldCare/DeviceCare

A0036420

1. Click **F** (functions) on the menu bar.

2. Select the sensor whose envelope curve is to be displayed.

3. To display a single curve, click the **Read curve** button.

4. To display the curves cyclically, press the **Cyclic read** button.

5. In the **Curves** window, select which type of curve is to be displayed: envelope curve, floating average curve (FAC), mapping curve.

10.2   Overview of diagnostic information

10.2.1   Error signal

Displaying errors that occur during commissioning or operation:
- **Onsite display**:
  - Error symbol
  - Error code
  - Error description
- **Current output**, depends on the **Output on alarm → Output N** parameter:
  - **Min (3.6 mA)**: –10 %, 3.6 mA
  - **Max (22 mA)** : 110 %, 22 mA
  - **Hold**: the last value is held.
  - **User specific**: defined in the **Output value N** parameter.
- **Operating menu**:
  System informat. → Error list → Actual error

10.2.2   List of the last errors

Operating menu:
System informat. → Error list → Last error

10.2.3   Types of error

Alarm (A)

▊▊▊▊▊ lit permanently.

The value of the output signal is defined by the **Output on alarm → Output N** parameter:
- **Min (3.6 mA)**: –10 %, 3.6 mA
- **Max (22 mA)** : 110 %, 22 mA
- **Hold**: the last value is held.
- **User specific**: defined in the **Output value N** parameter.

The operating status LED flashes red. An error message is displayed.

Warning (W)

▊▊▊▊▊ flashes.

- The device continues to measure.
- The operating status LED flashes red.
- An error message is displayed.

10.2.4   Error codes

Meaning of the error codes

- **Digit 1:**
  Type of error
  - A: alarm
  - W: warning
  - E: error (the error behavior is defined by the user.)
- **Digits 2 and 3:**
  Input or output channel
  "**00**" means that the error does not refer to a specific channel.
- **Digits 4 to 6:**
  Error code according to the following table

List of error codes

- **A 00 100**
  Software version does not suit hardware version.
- **A 00 101**
  Checksum error
  → Total reset and recalibration
- **A 00 102**
  Checksum error
  → Total reset and recalibration
- **W 00 103**
  Initializing - please wait
  → If the message does not disappear after a few seconds, replace the electronics.
- **A 00 106**
  Downloading - please wait
  → Wait for the download to finish.
- **A 00 110**
  Checksum error
  → Total reset and recalibration
- **A 00 111/112/114/115**
  Electronics defect
  - → Switch off device and switch it on again.
  - → If the error persists: call Endress+Hauser Service.
- **A 00 116**
  Download error
  → Repeat download.
- **A 00 117**
  Hardware after change not identified
- **A 0x 121**
  Current output 01 or 02 not calibrated
  → Call Endress+Hauser Service.
- **A 00 125**
  Electronics defect
  → Replace electronics.
- **A 00 152**
  Checksum error
  → Perform total reset and recalibration.
- **W 00 153**
  Initializing
  → If the message does not disappear after a few seconds, replace the electronics.
- **A 00 155**
  Electronics defect
  → Replace electronics.
- **A 00 164**
  Electronics defect
  Replace electronics.
- **A 00 171**
  Electronics defect
  Replace electronics.
- **A 00 180**
  Synchronization failure
  → Check synchronization connection.
- **A 00 183**
  Not supported hardware
  - → Check whether the printed circuit boards installed match the order code for the device.
  - → Call Endress+Hauser Service.
- **A 0x 231**
  Sensor 01 or 02 defect - check connection
  → Check that the sensor is connected correctly.

- **A 00 250**
  Faulty external temperature sensor
  → Check temperature sensor.
- **A 0x 281**
  Temperature readings sensor 01 or 02 defect - check connection
  → Check that the sensor is connected correctly.
- **W 0x 501**
  No sensor selected for input 01 or 02
  → Select sensor (**Level** or **Flow** menu).
- **A 0x 502**
  Sensor 01 or 02 not recognized
  → Enter sensor type manually (**Level** or **Flow** menu, **Basic setup** submenu).
- **A 00 511**
  No factory calibration available
- **A 0x 512**
  Recording of mapping
  → Wait for the mapping to finish.
- **W 01 521**
  New sensor 01 or 02 recognized
- **W 01 601**
  Linearization curve steps incorrect level 01 or 02
  → Enter linearization again (**Level** menu).
- **W 0x 602/603**
  Linearization curve steps incorrect flow 01 or 02
  → Enter linearization again (**Flow** menu).
- **A 0x 604**
  Calibration level 01 or 02 failure
  → Correct calibration (**Level** menu).
- **A 0x 605/606**
  Calibration flow 01 or 02 failure
  → Correct calibration (**Flow** menu).
- **W 0x 611**
  Less than 2 linearization points for level 01 or 02
  → Enter additional linearization points (**Level** menu).
- **W 0x 612/613**
  Less than 2 linearization points for flow 01 or 02
  → Enter additional linearization points (**Flow** menu).
- **W 0x 620**
  Pulse value too small relay 01 - 06
  → Check counting unit (**Flow** menu, **Flow counter** submenu).
- **E 0x 641**
  No usable echo sensor 01 or 02
  → Check basic setup for the sensor (**Level** or **Flow** menu).
- **A 0x 651**
  Level in safety distance sensor 01 or 02 risk overfill
  The error disappears as soon as the level is no longer in the safety distance.
  → If necessary, activate the **Reset self holding** function (**Safety settings** menu).
- **E 0x 661**
  Sensor 01 or 02 temperature too high (max. temp. exceeded at sensor)
- **W 0x 682**
  Current 01 or 02 out of range
  - → Perform basic setup.
  - → Check linearization.
- **W 0x 691**
  Noise filling detected sensor 01 or 02
- **W 00 692**
  Backwater detected (with active backwater detection)
- **W 00 693**
  Dirt detected (with active dirt detection)

- **W 0x 70y**
  Operating hours alarm pump y PST x
  → Reset operating hours (**Op.hour alarm** submenu).
- **W 0x 71y**
  Failure pump y PST x
  → Check pump 1. After rectifying the pump error, reset the pump controller or switch
  the device off and on again.
- **W 00 801**
  Simulation level on
  → Switch off level simulation (**Level** menu).
- **W 0x 802**
  Simulation sensor 01 or 02 on
  → Switch off simulation.
- **W 0x 803/804**
  Simulation flow on
  → Switch off simulation (**Flow** menu).
- **W 01 805**
  Simulation current 01 on
  → Switch off simulation (**Outputs/calculations** menu).
- **W 02 806**
  Simulation current 02 on
  → Switch off simulation (**Outputs/calculations** menu).
- **W 0x 807**
  Simulation relay 01 - 06 on
  → Switch off simulation.
- **W 0x 808**
  Sensor 01 or 02 off
  → Switch on sensor (**Sensor management** menu).
- **W 0x 809**
  Current D/A adjustment active
- **A 00 820-832**
  Different units for the calculation of mean value/total/difference or rake control.
  → Check units in the corresponding basic setups (**Level** or **Flow** menu).

10.3   Firmware history

- **V01.00.00 (12.2005)**
  Original software
  BA00288F/00/en/12.05
- **V01.00.02 (06.2006)**
  Limit relay function revised
  BA00288F/00/en/12.05
- **V02.00.00 (04.2007)**
  New option: binary inputs (e.g. to record external limit values or pump, motor and switch
  positions)
  BA00288F/00/en/10.07
- **V02.01.00 (07.2009)**
  Introduction of FDU90 sensor
  BA00288F/00/en/07.09
- **V02.01.01 (02.2010)**
  Introduction of temperature plausibility
  BA00288F/00/en/07.09

- **V01.02.03 (05.2011)**
  Improved temperature plausibility; flow counter limit; troubleshooting
  BA00288F/00/en/07.09
- **V01.02.05 (08.2014)**
  Continuous improvement
  BA00288F/00/en/13.12
- **V01.02.06 (04.2016)**
  Continuous improvement
  BA00288F/00/en/14.17

11   Maintenance

No special maintenance work is required.

11.1   Exterior cleaning

When cleaning the exterior, always use cleaning agents that do not corrode the surface of the housing and the seals.

12 Repair

12.1 General information

12.1.1 The Endress+Hauser repair concept

Under the Endress+Hauser repair concept, the measuring devices have a modular design and customers are able to undertake repairs themselves. For more information on service and spare parts, please contact your Endress+Hauser sales representative.

12.1.2 Repair of Ex-certified devices

- Only specialist personnel or Endress+Hauser-Service can carry out repairs to Ex certified devices.
- Comply with the prevailing standards, national Ex-area regulations, Safety Instructions (XA) and certificates.
- Use only original Endress+Hauser spare parts.
- When ordering spare parts, check the device designation on the nameplate. Only identical parts may be used as replacements.
- Carry out repairs according to the instructions. On completion of the repair, carry out the routine test specified for the device.
- A certified device may be converted to another certified device version by Endress +Hauser Service only.
- Document all repairs and modifications.

12.1.3 Replacing a device or electronics module

After an entire device or an electronics module has been replaced, the parameters can be downloaded to the device again via the communication interface. For this, the data must have been uploaded to the PC beforehand using the "FieldCare" software. You can continue measuring without performing a new calibration. Only a linearization and interference echo suppression need to be performed again.

12.1.4 Replacing the sensor

Check the following parameters after replacing the sensor:
- **Empty E**
- **Full F**
- **Check distance** (mapping)

Afterwards, measurement can resume without further restrictions.

12.2 Spare parts

All the spare parts for the measuring device, along with the order code, are listed in the *W@M Device Viewer* (www.endress.com/deviceviewer) and can be ordered. If available, users can also download the associated Installation Instructions.

12.3 Return

The requirements for safe device return can vary depending on the device type and national legislation.

1. Refer to the website for more information:
   http://www.endress.com/support/return-material

2. Return the device if repairs or a factory calibration are required, or if the wrong device was ordered or delivered.

12.4   Disposal

Observe the following notes during disposal:
- Observe valid federal/national regulations.
- Ensure proper separation and reuse of the device components.

13   Accessories

13.1   Communication-specific accessories

13.1.1   Commubox FXA195 HART

- For intrinsically safe HART communication with FieldCare or DeviceCare via the USB interface
- Additional information: Technical Information TI00404F

13.1.2   Commubox FXA291

- Connects the CDI interface (Common Data Interface) of Endress+Hauser devices with the USB port of a computer.
- Order number: 51516983
- Additional information: Technical Information TI00405C

13.2   Device-specific accessories

13.2.1   Weather protection cover for polycarbonate field housing
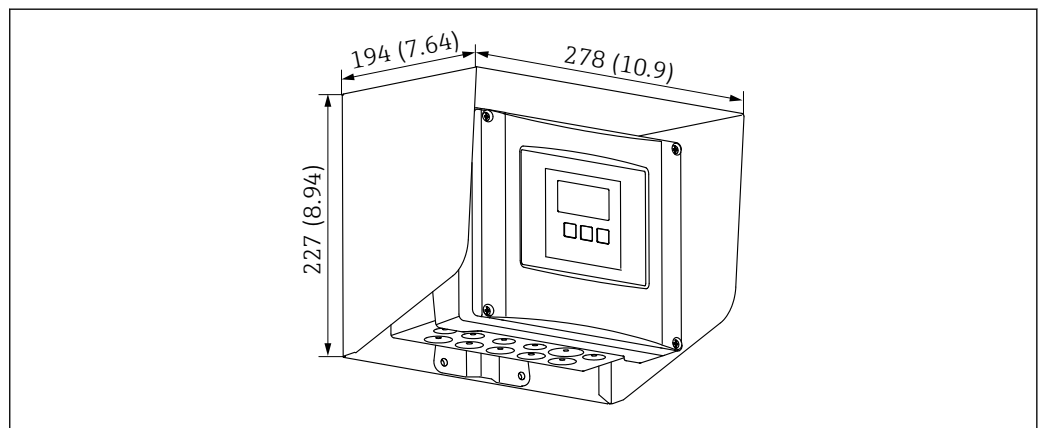
🖾 *72   Weather protection cover for polycarbonate field housing. Unit of measurement mm (in)*

- Material: 316Ti (1.4571)
- Mounting and fixing: using the Prosonic S housing bracket
- Order number: 52024477

13.2.2 Mounting plate for polycarbonate field housing
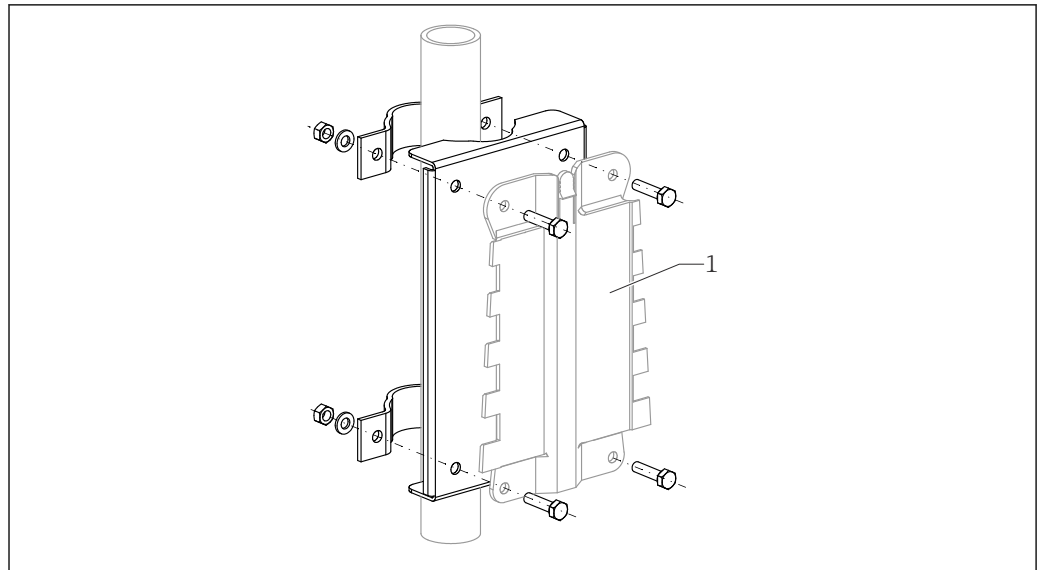
A0034923

🖾 *73 Mounting plate for polycarbonate field housing*

- Compatible with the Prosonic S housing bracket
- Pipe diameter: 25 to 50 mm (1 to 2 in)
- Dimensions: 210 x 110 mm (8.27 x 4.33 in)
- Material: 316Ti (1.4571)
- Mounting accessories: fastening clips, screws and nuts are supplied.
- Order number: 52024478

Mounting frame, short
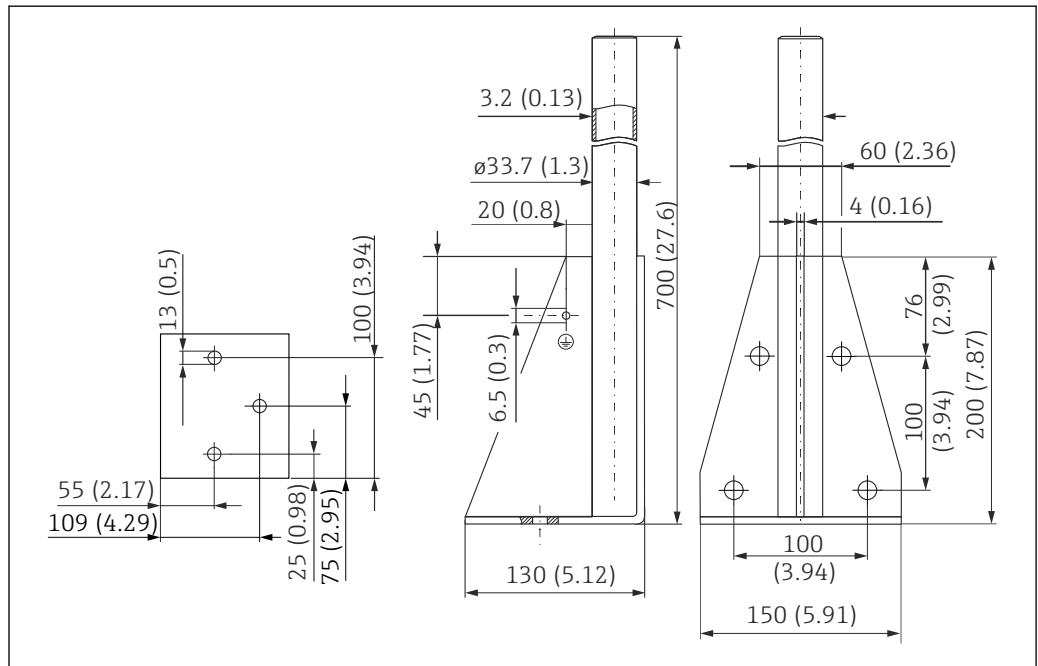
A0037799

🖾 *74 Dimensions of mounting frame, short. Unit of measurement mm (in)*

Weight:
3.2 kg (7.06 lb)

Material
316L (1.4404)

Order number
71452327

Mounting frame, long
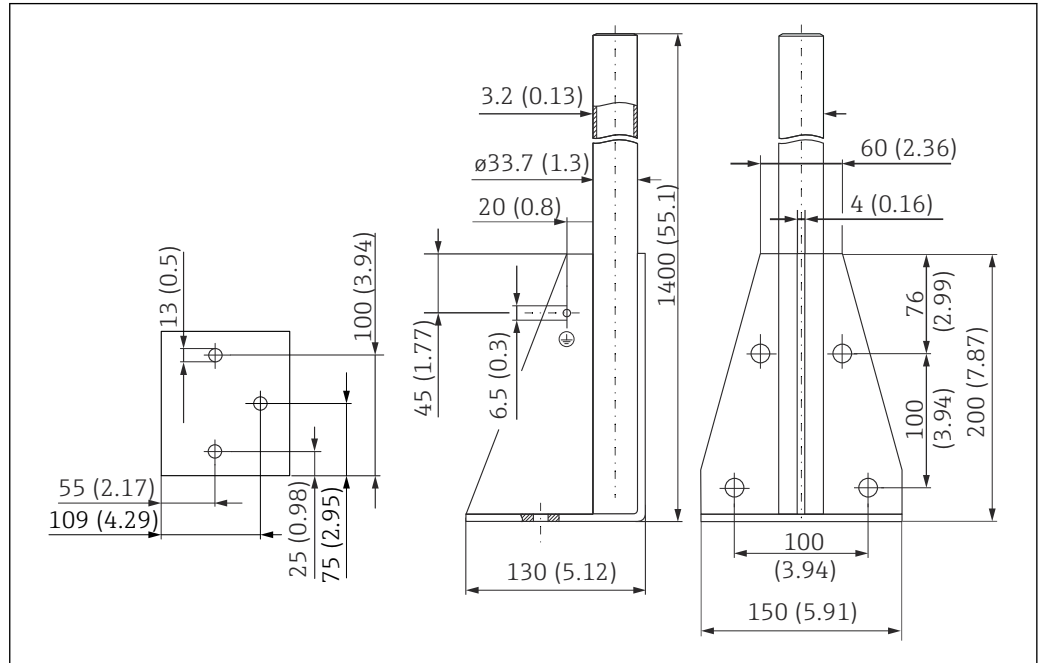
⊠ *75   Dimensions of mounting frame, long. Unit of measurement mm (in)*

Weight:
4.9 kg (10.08 lb)

Material
316L (1.4404)

Order number
71452326

13.2.3 Adapter plate for remote display
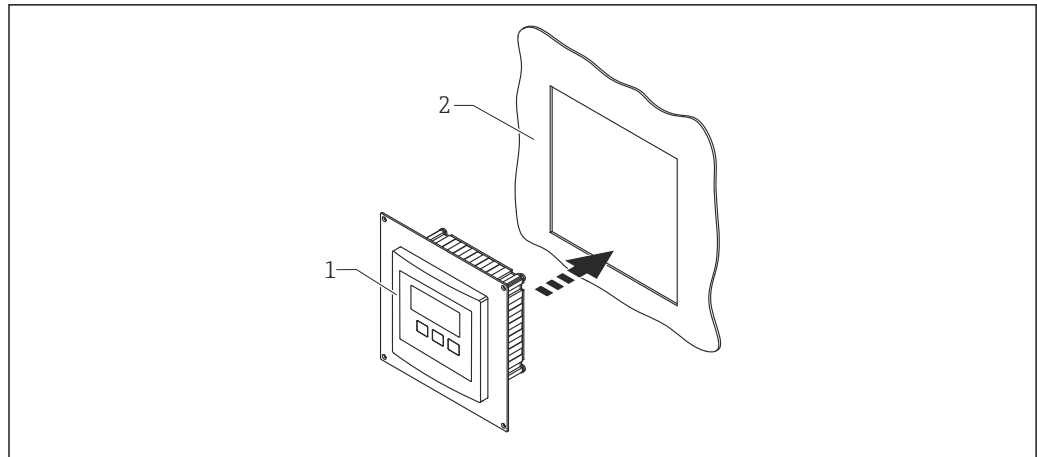
🖾 76   Use of adapter plate

1   Remote display of Prosonic S FMU9x with adapter plate
2   Installation opening of the remote display of the FMU86x predecessor transmitter

To mount the remote display of the Prosonic S FMU9x in the housing of the larger remote display of the FMU86x predecessor
• Dimensions: 144 x 144 mm (5.7 x 5.7 in)
• Order number: 52027441

13.2.4 HAW562 surge arrester

Reduces residual voltages from upstream lightning arresters; limits surges induced or generated in the system
Additional information: Technical Information TI01012K

13.2.5 Extension cables for sensors

• Maximum permissible total length (sensor cable + extension cable): 300 m (984 ft)
• The sensor cable and extension cable are the same type of cable.

FDU90/FDU91 without sensor heater
• Cable type: LiYCY 2x(0.75)
• Material: PVC
• Ambient temperature:
• Order number: 71027742

FDU90/FDU91 with sensor heater
• Cable type: LiYY 2x(0.75)D+2x0.75
• Material: PVC
• Ambient temperature:−40 to +105 ℃ (−40 to +221 ℉)
• Order number: 71027746

FDU92
• Cable type: LiYCY 2x(0.75)
• Material: PVC
• Ambient temperature:−40 to +105 ℃ (−40 to +221 ℉)
• Order number: 71027742

FDU91F/FDU93/FDU95
• Cable type: LiYY 2x(0.75)D+1x0.75
• Material: PVC
• Ambient temperature:−40 to +105 ℃ (−40 to +221 ℉)
• Order number: 71027743

FDU95
- Cable type: Li2G2G 2x(0.75)D+1x0.75
- Material: silicone
- Ambient temperature:–40 to +150 ℃ (–40 to +302 ℉)
- Order number: 71027745

13.2.6   Temperature sensor Omnigrad S TR61
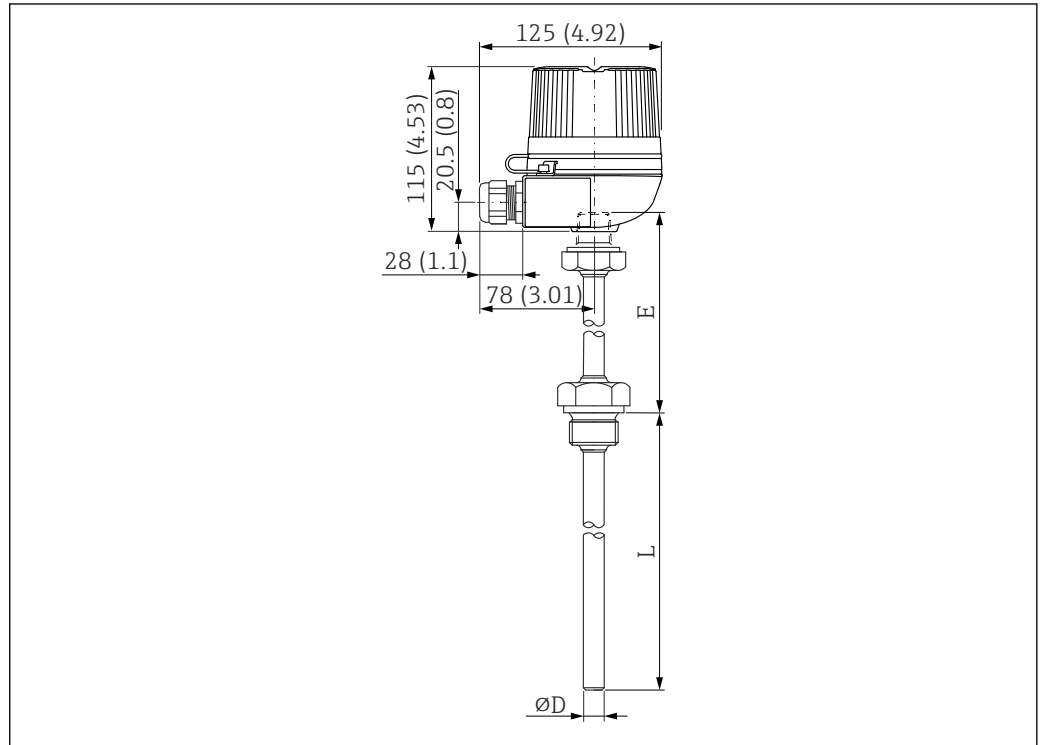
🖼 *77   Structure of the Omnigrad S TR61; dimensions: mm (in)*

- **Replacement for FMT131-R* (non-hazardous area)**
  TR61-ABAD0BHSCC2B
- **Replacement for FMT131-J* (ATEX II 2G EEx m II T6/T5)**
  TR61-EBAD0BHSCC2B
- Additional information: Technical Information TI01029T

14 Operating menu

14.1 Menu "Level → Level (LVL N)"

14.1.1 Submenu "Basic setup"

Parameter set L1003 "LVL N sensor sel."
- Input
- Sensor selection
- Detected

Parameter set L1004 "LVL N appl. param."
- Tank shape
- Medium property
- Process conditions

Parameter set L1005 "LVL N empty cal."
Empty E

Parameter set L 1006 "LVL N full cal."
- Full F
- Blocking distance

Parameter set L1007 "LVL N unit"
- Unit level
- Level N
- Distance

Parameter set L1008 "LVL N linearisat."
- Type
- Customer unit
- Customized text
- Max. scale
- Diameter
- Intermediate height (H)
- Mode
- Edit
- Status table

Parameter set L100B "LVL N check value"
- Act. distance N
- Check distance

Parameter set L100B "LVL N dist. map."
- Act. distance N
- Range of mapping
- Start mapping
- Status

Parameter set L100C "LVL N status"
- Level N
- Act. distance N
- Status

14.1.2 Submenu "Extended calibr."

Parameter set L1016 "LVL N dist. map."
- Act. distance N
- Range of mapping
- Start mapping
- Status

Parameter set L1017 "LVL N check value"
Correction

Parameter set L1018 "LVL N correction"
Offset

Parameter set L1020 "LVL N blocking distance"
Blocking distance

Parameter set L1019 "LVL N limitation"
- Limitation
- Upper limit
- Lower limit

Parameter set L1020/L1021 "LVL N ext. input M"
Only for devices with additional digital inputs (FMU90********B***)
- Input M
- Function
- Value

14.1.3 Submenu "Simulation"

Parameter set L1022 "LVL N simulation"
- Simulation
- Sim. level value
- Sim. volume value

14.2 Menu "Safety settings"

Parameter set AX101 "Output on alarm"
- Output N
- Output value N

Parameter set AX102 "Outp. echo loss"
- Level N
- Ramp level N
- Value level N
- Flow N
- Value flow N

Parameter set AX103 "Delay echo loss"
Delay Sensor N

Parameter set AX104 "Safety distance"
Saf. dist.sen N

Parameter set AX105 "In safety dist."
- In saf. dist.s N
- Reset sen N

Parameter set AX107 "React. high temp."
- Overtemp. sen. N
- Max. temp. sen. N

Parameter set A0000 "Defect temp. sen."
Def. temp. sen. N

Parameter set A0000 "Relay delay"
Start delay relay

14.3 Menu "Relay/controls"

14.3.1 Submenu "Pump control N" (standard - limit control)

Valid for:
- FMU90-*1**********
- FMU90-*2**********

Parameter set R1300 "Pump control N"
- Reference
- Number of pumps

Parameter set R1301 "Pump control N"
Function = Limit control

Parameter set R1302 "Pump control N"
Pump M

Parameter set R1303 "Pump M /control N"
- Switch-on point
- Switch-off point
- Switch-on delay
- Alternate
- Crust reduction

Parameter set R1304 "Pump M /control N"
- Backlash interval
- Backlash time
- Failure mode

Parameter set R1306 "Relay allocation → Relay K"
- Function
- Invert

14.3.2 Submenu "Pump control N" (standard - pump rate control)

Valid for:
- FMU90-*1**********
- FMU90-*2**********

Parameter set R1300 "Pump control N"
- Reference
- Number of pumps

Parameter set R1301 "Pump control N"
Function = Pump rat. contr.

Parameter set R13A3 "Pump control N"
- Switch-on point
- Switch-off point
- Min. pump rate/min
- Crust reduction
- Switch on border
- Hook up interval
- Alternate

Parameter set R13A2 "Pump control N"
Pump M

Parameter set R13A3 "Pump M / control N"
- Switch-on delay
- Backlash interval
- Backlash time
- Failure mode

Parameter set R13A6 "Relay allocation → Relay K"
- Function
- Invert

14.3.3 Submenu "Pump control N → Basic setup" (extended - limit control)

Valid for:
- FMU90-*3**********
- FMU90-*4**********

Navigation to the submenu:
Relay/controls → Pump control N → Basic setup

Parameter set R1401 "Pump control N"
- Reference
- Number of pumps
- Standby pump
- Reset

Parameter set R1402 "Pump control N"
- Function = Limit single/limit parallel
- Load control

Parameter set R1403 "Pump control N"
Pump M

Parameter set R1404 "Pump M /control N"
- Switch-on point
- Switch-off point
- Switch-on delay
- Alternate
- Degree of use
- Max. use time
- Crust reduction

Parameter set R1405 "Pump M /control N"
- Backlash interval
- Backlash time
- Failure mode

Parameter set R1406 "Pump M /control N"
- Pump feedback
- Feedback delay
- Feedb. meaning

Parameter set R1408 "Relay allocation → Relay K"
- Function
- Invert

14.3.4 Submenu "Pump control N → Basic setup" (extended - pump rate control)

Valid for:
- FMU90-*3**********
- FMU90-*4**********

Navigation to the submenu:
Relay/controls → Pump control N → Basic setup

Parameter set R1401 "Pump control N"
- Reference
- Number of pumps
- Standby pump
- Reset

Parameter set R1402 "Pump control N"
- Function = Pump rat. contr.
- Load control

Parameter set R1504 "Pump control N"
- Switch-on point
- Switch-off point
- Min. pump rate/min
- Hook up interval
- Switch on border
- Alternate
- Crust reduction

Parameter set R1505 "Pump control N"
Pump M

Parameter set R1505 "Pump M /control N"
- Switch-on delay
- Degree of use
- Max. use time

Parameter set R1506 "Pump M /control N"
- Backlash interval
- Backlash time
- Failure mode

Parameter set R1507 "Pump M /control N"
- Pump feedback
- Feedback delay
- Meaning of the feedback

Parameter set R1509 "Relay allocation → Relay K"
- Function
- Invert

14.3.5   Submenu "Pump control N → Storm function"

Valid for:
- FMU90-*3**********
- FMU90-*4**********

Navigation to the submenu:
Relay/controls → Pump control N → Storm function

Parameter set R1601 "Storm function N"
- Storm function
- Switch-on point
- Switch-off point
- Storm time

14.3.6   Submenu "Pump control N → Function test"

Valid for:
- FMU90-*3**********
- FMU90-*4**********

Navigation to the submenu:
Relay/controls → Pump control N → Function test

Parameter set R1602 "Function test N"
- Function test
- Max. downtime
- Max. test time
- Switch-on point
- Switch-off point

14.3.7   Submenu "Pump control N → Flush control"

Valid for:
- FMU90-*3**********
- FMU90-*4**********

Navigation to the submenu:
Relay/controls → Pump control N → Flush control

Parameter set R1603 "Flush control N"
- Flush control
- Pump cycles
- Flush cycles
- Flush time
- Flush delay

Parameter set R1605 "Relay allocation → Relay M"
- Function
- Invert

14.3.8   Submenu "Pump control N → Tariff control"

Valid for:
- FMU90-*3******B***
- FMU90-*4******B***

Navigation to the submenu:
Relay/controls → Pump control N → Tariff control

Parameter set R1607 "Tariff control N"
- Tariff control
- Tariff input

Parameter set R1608 "Tariff control N"
Pump M

Parameter set R1619 "Tariff ctrl N/pump M"
- Switch-on point
- Switch-on tariff
- Switch-off point
- Switch-off tariff

14.3.9   Submenu "Pump control N → Pump data"

Valid for:
- FMU90-*3**********
- FMU90-*4**********

Navigation to the submenu:
Relay/controls → Pump control N → Pump data → Pump M

Parameter set R1611 "Pump dat. P M"
- Operating hours
- Reset op. hours
- Total op. hours
- Number of starts
- Starts per h

- Backlash starts
- Reset backlstart
- Last run time

14.3.10 Submenu "Pump control N → Op. hours alarm"

Valid for:
- FMU90-*3**********
- FMU90-*4**********

Navigation to the submenu:
Relay/controls → Pump control N → Op. hours alarm

Parameter set R1612 "Op. hours alarm"
- Op. hours alarm
- Alarm delay

Parameter set R1613 "Op. hours alarm"
Pump M

Parameter set R1613 "Op. hours alarm N P M"
- Operating hours
- Max. op. hours

Parameter set R1615 "Relay allocation → Relay K"
- Function
- Invert

14.3.11 Submenu "Pump control N → Pump alarm"

Valid for:
- FMU90-*3******B***
- FMU90-*4******B***

Navigation to the submenu:
Relay/controls → Pump control N → Pump alarm

Parameter set R1617 "Pump alarm N"
- Pump alarm
- Waiting time

Parameter set R1619 "Relay allocation → Relay K"
- Function
- Invert

14.3.12 Submenu "Rake control"

Parameter set R1200 "Rake control"
- Upstream water
- Downstream water
- Function

Parameter set R1201 "Rake control"
- Switch-on point
- Switch-off point

Parameter set R1202 "Rake control"
- Switching delay
- Failure mode

Parameter set R2204 "Relay allocation → Relay N"
- Function
- Invert

14.3.13 Submenu "Relay configurat. → Relay N" (function: limit)

Parameter set R1203 "Relay N"
- Function → Limit → Limit XXX
- Limit type
- Switch-on point
- Switch-off point
- Switch on/min.
- Switch off/min.
- Upper switchpt.
- Low switch point
- Hysteresis

Parameter set R1204 "Relay N"
- Switch delay
- Invert
- Failure mode

14.3.14 Submenu "Relay configurat. → Relay N" (function: time pulse)

Parameter set R2103 "Relay N"
- Function → Time pulse
- Pulse width
- Pulse time

Parameter set R2104 "Relay N"
- Invert
- Failure mode

14.3.15 Submenu "Relay configurat. → Relay N" (function: counting pulse)

Parameter set R1203 "Relay N"
- Function → Counting pulse → Pulse flow N
- Counter unit
- Pulse value
- Pulse width

Parameter set R1205 "Relay N"
- Pulse counter
- Overflow x 10^7
- Reset counter
- Start counter
- Stop counter

Parameter set R1204 "Relay N"
- Invert
- Failure mode

14.3.16 Submenu "Relay configurat. → Relay N" (function: alarm/ diagnost.)

Parameter set R2103 "Relay N"
- Function → Alarm/diagnost.
  - Alarm relay
  - Diagnostics
  - Backw. alarm
  - Dirt alarm
- Allocation M

Parameter set R2104 "Relay N"
Invert

14.3.17 Submenu "Relay simulation"

Parameter set R2106 "Relay N"
• Simulation
• Simulation value

14.4 Menu "Output/calculat. → Current output N"

14.4.1 Submenu "Allocat./calculat."

Parameter set O1201 "Allocat. curr. N"
• Output
• Output current

14.4.2 Submenu "Extended calibr."

Parameter set OX202 "Mode current N"
• Current span
• mA value
• Output damping
• 4mA threshold
• Curr. turn down
• Turn down 0/4mA
• Turn down 20mA

14.4.3 Submenu "HART settings"

Only for current output 1

Parameter set O1203 "HART settings"
• HART address
• No. of preambles
• Short TAG HART

Parameter set O2205/O3206/O4207 "Add. HART value M"
• Measured value M
• Output damping M

14.4.4 Submenu "Simulation"

Parameter set O1204 "Current output N"
• Simulation
• Simulation value

14.5 Overview of the "Device properties" menu

14.5.1 Submenu "Operating param."

Parameter set D1101 "Distance unit"
Distance unit

Parameter set D110B "Temperature unit"
Temperature unit

Parameter set D110C "Operating mode"
Operating mode

Parameter set D110D "Controls"
Controls

14.5.2 Submenu "Tag marking"

Parameter set D1102 "Tag marking"
- Output N
- Device marking

14.5.3 Submenu "Language"

Parameter set D1103 "Language"
Language

14.5.4 Submenu "Password/reset"

Parameter set D1104 "Password/reset"
- Reset
- Code
- Status

14.6 Menu "System informat."

14.6.1 Submenu "Device information"

Parameter set IX101 "Device family"
Device family

Parameter set IX102 "Device name"
Device name

Parameter set IX103 "Device marking"
Device marking

Parameter set IX105 "Serial no."
Serial number

Parameter set IX106 "Software version"
Software version

Parameter set IX107 "Dev. rev."
Dev. rev.

Parameter set IX108 "DD version"
DD version

14.6.2 Submenu "In/output info"

Parameter set IX108 "Level N"
- Input
- Sensor selection
- Detected

Parameter set IX109 "Flow N"
- Input
- Sensor selection
- Detected

Parameter set IX10A "Current output N"
Output

Parameter set IX10B "Relay N"
Function

14.6.3   Submenu "Trend display → Trend output N"

Parameter set IX10F Trend output N
Time interval

14.6.4   Submenu "Min/max values"

Parameter set IX302 "Level → Level (LVL) N"
- Max. value
- Min. Value
- Reset

Parameter set IX302 "Flow → Flow N"
- Max. value
- Min. Value
- Reset

Parameter set IX302 "Temperature → Temperature sen. N"
- Max. value
- Min. Value

14.6.5   Submenu "Envelope curve"

Parameter set IX126 "En. curve sen. N"
- Plot settings (choice of displayed curves)
- Plot settings (choice between an individual curve and cyclic presentation)

14.6.6   Submenu "Error list"

Parameter set E1002 "Actual error"
- 1:
- 2:
- ...

Parameter set E1003 "Last error"
- 1:
- 2:
- ...

14.6.7   Submenu "Diagnostics"

Parameter set E1403 "Operating hours"
Operating hours

Parameter set E1404 "Actual distance"
Act. distance N

Parameter set E1405 "Act. meas. value"
- Level N
- Flow N

Parameter set E1405 "Application par."
Sensor N

Parameter set E1406 "Echo quality sen."
Echo quality N

14.7   Menu "Display"

Parameter set DX202 "Display"
• Type
• Value N
• Customized text N

Parameter set DX201 "Display format"
• Format
• No. of decimals
• Sep. character
• Customized text

Parameter set DX200 "Back to home"
Back to home

14.8 Menu "Sensor management"

14.8.1 Submenu "Sensor management → FDU sensor → Sensor management"

Parameter set D1019 "Input"
FDU sensor N

Parameter set D1106 "US sensor N"
• Sensor operation
• Sensor priority
• Detected
• Sensor selection
• Detection window

Parameter set D1107 "US sensor N"
• Temp. measurement
• Ext. send ctrl.
• Input
• Distance

14.8.2 Submenu "Sensor management → FDU sensor → Ext. temp. sensor"

Parameter set D1020 "Ext. temp. sensor"
• Sensor type
• Temperature unit

Parameter set D1021 "Ext. temp. sensor"
• Max. value
• Min. Value
• Actual value
• Reset

Parameter set D1022 "Ext. temp. sensor"
• Failure mode
• Value at warning

14.8.3 Submenu "Sensor management → FDU sensor → External digin"

Parameter set D1025 "Ext. digin N"
• Invert
• Value

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