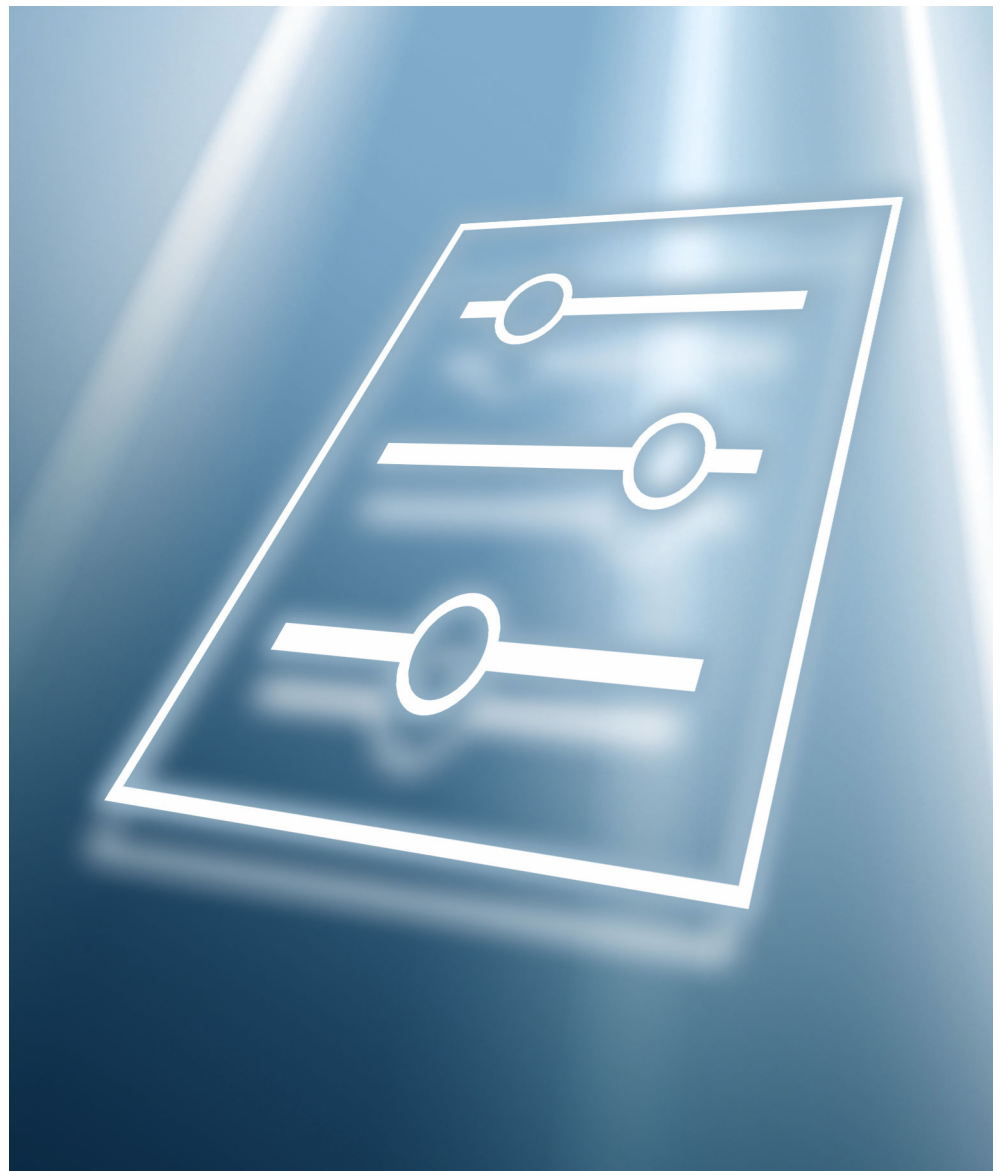


Description of Device Parameters

Micropilot FMR43

HART

Free-space radar



1 About this document

1.1 Document function

The document is part of the Operating Instructions and serves as a reference for parameters.

Tasks that require detailed knowledge of the function of the device:

- Starting up measurements under difficult conditions
- Optimal adjustment of measurements to difficult conditions
- Detailed configuration of communication interface
- Fault diagnosis in difficult cases

1.2 Target group

This document is aimed at specialists who work with the device over the entire life cycle and perform specific configurations.

1.3 Document structure

The document consists of a general part and a specific part.

The structure of the document and its components are explained in the general part (section 1).

The specific part starts with an overview of the device operating menu, which is the focus of this manual.

The description of the device parameters follows the overview of the operating menu. The description is divided into 4 main menus and their submenus.

The 4 main menus:

- Guidance
- Diagnostics
- Application
- System

In the **Description of device parameters** section, the menus, submenus and parameters are displayed in the same way that they are laid out in the menu structure for the operating tool.

An **operating** tool is a piece of software such as FieldCare, for example, which can be used to display and edit the data and parameters stored in the device on a PC or laptop. In contrast to operation via the onsite display, an operating tool offers more options for displaying additional information such as graphics and help text that explain the properties of the parameters.

The submenus that are visible to users depend on the **user role** they are logged in on. This document lists the submenus and parameters that are available to the **Maintenance** user role.

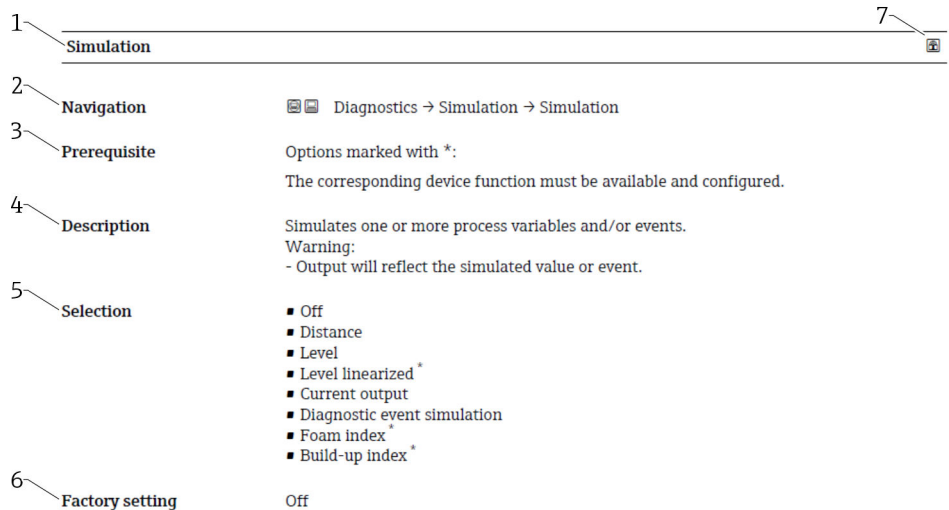
The operating menu is dynamic and adapts the choice of parameters to the selected options.



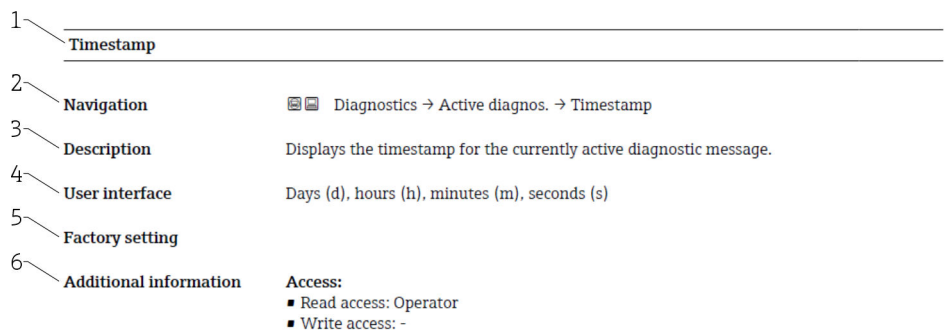
For the operating concept of the operating menu, see the Operating Instructions.

1.4 Elements of parameter descriptions

Parameter descriptions are structured and made up of a number of elements. Depending on the parameter, more or fewer elements may be available. Two examples are provided here for different parameters:



- 1 Name: Parameter designation (Label)
- 2 Navigation: Navigation path to the parameter. The graphics indicate whether the path applies to the onsite display, the operating tool or both.
- 3 Prerequisite: The marked options can only be selected under the condition specified in each case
- 4 Description: Description of the parameter function
- 5 Selection: List of the individual options for the parameter
- 6 Factory setting: Default setting on leaving the factory
- 7 The lock symbol indicates that the parameter is write-protected




- 1 Name: Parameter designation (Label)
- 2 Navigation: Navigation path to the parameter. The graphics indicate whether the path applies to the onsite display, the operating tool or both.
- 3 Description: Description of the parameter function
- 4 User interface: Display value/data of the parameter
- 5 Factory setting: Default setting on leaving the factory
- 6 Additional information:
Read and write access: Information on access rights that users with certain roles have to the parameter


Additional information at the end of the parameter description can refer to, and expand, all elements of the parameter description.


1.5 Symbols

1.5.1 Symbols for certain types of information

Additional information: 


Reference to documentation: 

Operation via local display: 

Operation via operating tool: 

Write-protected parameter: 


1.6 Documentation

 For an overview of the scope of the associated Technical Documentation, refer to the following:

- *Device Viewer* (www.endress.com/deviceviewer): Enter the serial number from the nameplate
- *Endress+Hauser Operations app*: Enter serial number from nameplate or scan matrix code on nameplate.


1.6.1 Standard documentation

Operating Instructions

 The Operating Instructions are available via the Internet: www.endress.com → Download


1.6.2 Supplementary device-dependent documentation
























Special Documentation

 The Special Documentation is available via the Internet: www.endress.com → Download


























2 Overview of the operating menu

Navigation

 Operating tool

Guidance	→  17
▶ Commissioning	→  17
▶ Heartbeat Technology	→  18
▶ Heartbeat Verification	→  19
▶ Loop diagnostics	→  19
▶ Foam detection	→  19
▶ Buildup detection	→  19
▶ Safety mode	→  20
▶ Proof test	→  20
▶ Import / Export	→  20
▶ Compare	→  20
Diagnostics	→  21
▶ Active diagnostics	→  21
Active diagnostics	→  21
Timestamp	→  21
Previous diagnostics	→  22
Timestamp	→  22
Operating time from restart	→  22
Operating time	→  23
▶ Diagnostic list	→  23
▶ Event logbook	→  23
▶ Minimum/maximum values	→  24
Min. level value	→  24

Time min. level	→ 24
Maximum draining speed	→ 24
Counter overfilling	→ 25
Minimum sensor temperature	→ 25
Time min. sensor temperature	→ 25
Minimum terminal voltage	→ 25
Minimum electronics temperature	→ 26
Max. level value	→ 26
Time max. level	→ 26
Maximum filling speed	→ 27
Counter underfilling	→ 27
Maximum sensor temperature	→ 27
Time max. sensor temperature	→ 28
Maximum terminal voltage	→ 28
Maximum electronics temperature	→ 28
Reset min./max.	→ 28
► Simulation	→ 29
Simulation	→ 29
Simulation distance	→ 29
Buildup index	→ 29
Foam index	→ 30
Process variable value	→ 30
Value current output	→ 30
Diagnostic event simulation	→ 30
► Heartbeat Technology	→ 32

► Heartbeat Verification	→  32
Date/time Heartbeat Verification	→  32
Operating time (Verification)	→  32
Verification result	→  33
Status	→  33
► Loop diagnostics	→  33
Rebuild baseline	→  33
Tolerated deviation +/-	→  34
Baseline status	→  34
Loop diagnostics	→  34
Terminal voltage 1	→  35
Clamping voltage lower threshold	→  35
Clamping voltage upper threshold	→  35
806 Event delay	→  35
► Foam detection	→  36
Foam detection	→  36
Foam index	→  36
Foam detec. threshold	→  36
Foam detec. threshold value	→  36
Lower level range limit	→  37
Upper level range limit	→  37
Distance at foam zero adjustment	→  37
0% foam value	→  37
► Buildup detection	→  38
Buildup detection	→  38

	Buildup index	→ 38
	Buildup detection threshold	→ 38
	Buildup detection threshold value	→ 39
	Minimum distance for buildup detection	→ 39
	Maximum distance for buildup detection	→ 39
	0 % buildup value	→ 39
	Area of incoupling	→ 40
	Limit offset for buildup detection	→ 40
▶	Echo curve	→ 40
	Save reference curve	→ 40
	Time reference curve	→ 41
	Reference curve active	→ 41
▶	Diagnostic settings	→ 42
	▶ Properties	→ 42
	941 Diagnostic behavior	→ 42
	941 Event category	→ 42
	Value echo lost	→ 43
	Ramp at echo lost	→ 43
	Delay time echo lost	→ 43
	942 Diagnostic behavior	→ 45
	942 Event category	→ 45

Safety distance	→ 45
Acknowledge alarm	→ 46
► Configuration	→ 46
► Sensor	→ 46
168 Diagnostic behavior	→ 46
168 Event category	→ 46
► Process	→ 47
806 Diagnostic behavior	→ 47
806 Event category	→ 47
941 Diagnostic behavior	→ 48
941 Event category	→ 48
942 Diagnostic behavior	→ 48
942 Event category	→ 49
952 Diagnostic behavior	→ 49
952 Event category	→ 49
Application	→ 50
► Measuring units	→ 50
Level unit	→ 50
Length unit	→ 50
Temperature unit	→ 50
► Measured values	→ 51
Level linearized	→ 51
Level	→ 51
Output current	→ 51
Distance	→ 52

Unfiltered distance	→ 52
Sensor temperature	→ 52
Terminal voltage 1	→ 52
Electronics temperature	→ 53
► Sensor	→ 53
► Basic settings	→ 53
Medium type	→ 53
Application	→ 53
Application	→ 54
Empty calibration	→ 54
Full calibration	→ 55
► Advanced settings	→ 55
Maximum draining speed solid	→ 55
Maximum filling speed solid	→ 56
Maximum draining speed liquid	→ 56
Maximum filling speed liquid	→ 57
Damping output	→ 57
Evaluation sensitivity	→ 58
First echo sensitivity	→ 58
Frequency mode	→ 59
Active map	→ 59
Distance	→ 60
Confirm distance	→ 60
Mapping end point	→ 61
Record map	→ 62












Maximum measuring distance	→ 63
Upper blank out	→ 63
Output mode	→ 63
Level limit mode	→ 64
High limit	→ 65
Low limit	→ 65
Level correction	→ 65
► Echo evaluation	→ 66
Tank bottom range	→ 70
Evaluation mode	→ 71
Reset evaluation	→ 71
► Linearization	→ 73
Linearization type	→ 73
Unit after linearization	→ 74
Free text	→ 74
Level linearized	→ 74
Maximum value	→ 75
Diameter	→ 75
Intermediate height	→ 75
Table mode	→ 75
Table number	→ 76
Level	→ 76
Level	→ 76
Customer value	→ 77

Activate table	→ 77
CRC linearization table	→ 77
► Signal information	→ 78
Signal quality	→ 78
Absolute echo amplitude	→ 78
Relative echo amplitude	→ 78
► Current output	→ 79
Assign PV	→ 79
Measuring mode current output	→ 80
Current range output	→ 80
Lower range value output	→ 80
Upper range value output	→ 80
Failure behavior current output	→ 81
Failure current	→ 81
Output current	→ 81
Terminal current	→ 81
► HART output	→ 84
► Configuration	→ 83
HART address	→ 83
HART short tag	→ 83
Device tag	→ 83
No. of preambles	→ 84
Loop current mode	→ 84
► HART output	→ 84
Assign PV	→ 84

Primary variable (PV)	→ 85
Assign SV	→ 85
Secondary variable (SV)	→ 85
Assign TV	→ 86
Tertiary variable (TV)	→ 86
Assign QV	→ 86
Quaternary variable (QV)	→ 87
► Burst configuration 1	→ 87
Burst mode 1	→ 87
Burst command 1	→ 88
Burst variable 0	→ 88
Burst variable 1	→ 89
Burst variable 2	→ 89
Burst variable 3	→ 90
Burst variable 4	→ 90
Burst variable 5	→ 91
Burst variable 6	→ 92
Burst variable 7	→ 92
Burst trigger mode	→ 93
Burst trigger level	→ 93
Min. update period	→ 93
Max. update period	→ 94
► Information	→ 94
Device ID	→ 94
Device type	→ 94

	Device revision	→ 94
	HART short tag	→ 95
	HART revision	→ 95
	HART descriptor	→ 95
	HART message	→ 96
	HART date code	→ 96
System		→ 97
▶ Device management		→ 97
Device tag		→ 97
Locking status		→ 97
Configuration counter		→ 98
Reset device		→ 98
▶ User management		→ 98
User role		→ 98
Password		→ 99
Enter access code		→ 99
Status password entry		→ 99
New password		→ 100
Confirm new password		→ 100
Status password entry		→ 99
Old password		→ 100
New password		→ 100
Confirm new password		→ 100
Status password entry		→ 99
Reset password		→ 100

Status password entry	→ 99
Old password	→ 100
Status password entry	→ 99
▶ Bluetooth configuration	→ 101
Bluetooth activation	→ 101
▶ Display	→ 102
Language	→ 102
Format display	→ 102
Value 1 display	→ 103
Decimal places 1	→ 103
Value 2 display	→ 103
Decimal places 2	→ 104
Rotation display	→ 104
Color scheme	→ 104
▶ Geolocation	→ 105
Process Unit Tag	→ 105
Location Description	→ 105
Longitude	→ 105
Latitude	→ 106
Altitude	→ 106
Location method	→ 106
▶ Information	→ 107
Device name	→ 107
Manufacturer	→ 107
Serial number	→ 107

Order code	→  107
Firmware version	→  108
Hardware version	→  108
Extended order code 1	→  108
Extended order code 2	→  108
Extended order code 3	→  109
Checksum	→  109
► Software configuration	→  113
CRC device configuration	→  113
Activate SW option	→  114
Software option overview	→  114

3 Description of device parameters

3.1 Guidance

The Guidance main menu contains functions which enable users to perform basic tasks swiftly, e.g. commissioning.

These are primarily guided wizards and cross-subject special functions.

Navigation  Guidance

3.1.1 Overview

The **Guidance** menu contains the following submenus and wizards:

- Commissioning
- Heartbeat Technology
 - Heartbeat Verification
 - Loop diagnostics
 - Foam detection
 - Buildup detection
- Safety mode
- Proof test
- Import / Export
- Compare

3.1.2 "Commissioning" wizard

Complete this wizard to commission the device.

For each parameter, enter the appropriate value or select the appropriate option.

NOTE

If you exit the wizard before completing all required parameters, the changes you have made will be saved. For this reason, the device may then be in an undefined state!

In this case, a reset to the default settings is recommended.

[Navigation](#)[Guidance → Commissioning](#)

Parameters for "Commissioning" wizard

The following parameters are configured in this wizard:

■ Device identification

- Device tag
- Device name
- Serial number
- Extended order code 1 ... 3
- Locking status
- HART short tag
- HART date code
- HART descriptor
- HART message
- HART address

■ Measurement adjustments

- Distance unit
- Temperature unit
- Level unit
- Medium type
- Operating mode
- Application
- Empty calibration
- Full calibration
- Level
- Displayed level/distance correct?
- Show possible signals in?
- Distance
- Level
- Is a linearization required?
- Linearization type
- Unit after linearization
- Maximum value
- Diameter
- Level linearized
- Intermediate height
- Diameter
- Level linearized

■ Output settings

- Process variable output current
- Current range output
- Lower range value output
- Upper range value output
- Failure behavior current output
- Failure current
- Loop current mode
- Assign HART variables?

This function comprises several parameters, including the **Assign PV** parameter.


3.1.3 Heartbeat Technology

Heartbeat Technology offers diagnostic functionality through continuous self-monitoring, the transmission of additional measured variables to an external Condition Monitoring system and the in situ verification of measuring instruments in the application.




Special Documentation on Heartbeat Technology is available via the Internet:

www.endress.com → Download

Navigation  Guidance → Heartbeat Techn.


Heartbeat Verification

This wizard is used to start an automatic verification of the device functionality. The results can be documented as a verification report.

Navigation  Guidance → Heartbeat Techn. → Heartbeat Verif.

Loop diagnostics

Using this wizard, changes in the current-voltage loop characteristics (baseline) can be used to detect unwanted installation anomalies such as creep currents caused by terminal corrosion or a deteriorating power supply that can lead to an incorrect 4-20 mA measured value.

Navigation  Guidance → Heartbeat Techn. → Loop diagn.


Foam detection

This wizard configures the automatic foam detection.

Foam detection can be linked to an output variable or status information e.g. to control a sprinkler used to dissolve the foam. It is also possible to monitor the foam increase in a so called foam index. The foam index can also be linked to an output variable and can be shown on the display.

Preparation:

The Foam monitoring initialization should only be done without or less foam.

Navigation  Guidance → Heartbeat Techn. → Foam detection

Buildup detection

This wizard configures the build-up detection.


Basic idea:

The build-up detection can, for example, be linked to a compressed-air system to clean the antenna.

With the build-up monitoring the maintenance cycles can be optimized.

Preparation:

The build-up monitoring initialization should only be done without or less build-up.


Navigation  Guidance → Heartbeat Techn. → Buildup detect.

3.1.4 Safety mode

The write protection guards the device settings against overwriting. In addition, it is recommended for safety applications to confirm the safety relevant device settings. This ensures that the correct values have been entered and downloaded to device.

This input can be used as the confirmation sequence instead of manual checklists. After the safety relevant device settings have been confirmed, the device is marked with the property Safety-locked. This indicates that the safety relevant parameter settings have been checked and evaluated as correct.

To unlock the safety locking the sequence needs to be restarted. The safety locking is deactivated when the safety unlocking code (= safety locking code) is entered.

Navigation  Guidance → Safety mode

3.1.5 Proof test

The proof test will simulate the current output.

The safety function is not guaranteed during proof test. Alternative process control in manual must be taken to ensure process safety.

Note: It is only possible to perform a proof test when the device has no alarm and the hardware write protection switch is off.

Navigation   Guidance → Proof test

3.1.6 Import / Export

Save/Load

- **Save:** The device settings can be saved in a .deh file.
- **Load:** The device settings saved in a .deh file can be written to the device.

Create documentation

- Device documentation can be saved in PDF format under "Create documentation".
- This documentation contains the following general device information:
 - Information on device parameters
 - Information on Linearization
 - Echo curve
 - Event list
 - Diagnostic list

Navigation  Guidance → Import / Export

3.1.7 Compare

Compare datasets

This function can be used to compare the following datasets:

- Data records in the .deh file format from the function Import / Export
- Datasets with the configuration currently in the device

Navigation  Guidance → Compare



3.2 Diagnostics

Navigation   Diagnostics


3.2.1 Active diagnostics

Navigation   Diagnostics → Active diagnos.


Active diagnostics

Navigation	 Diagnostics → Active diagnos. → Active diagnos.
Description	<p>Displays the currently active diagnostic message.</p> <p>If there is more than one pending diagnostic event, the message for the diagnostic event with the highest priority is displayed.</p> <p>The information displayed comprises:</p> <ul style="list-style-type: none"> ■ Symbol for event level ■ Code for diagnostic behavior ■ Operation time of occurrence ■ Event text
User interface	
Factory setting	-
Additional information	<p> Information on what is causing the message, and remedy measures, can be viewed via the I-symbol on the display.</p> <p>Access:</p> <ul style="list-style-type: none"> ■ Read access: Operator ■ Write access: -


Timestamp

Navigation	 Diagnostics → Active diagnos. → Timestamp
Description	Displays the timestamp for the currently active diagnostic message.
User interface	Days (d), hours (h), minutes (m), seconds (s)
Factory setting	
Additional information	<p>Access:</p> <ul style="list-style-type: none"> ■ Read access: Operator ■ Write access: -


Previous diagnostics

Navigation	 Diagnostics → Active diagnos. → Prev.diagnostics
Description	Displays the diagnostic message for the last diagnostic event that has ended.
User interface	
Factory setting	
Additional information	<p>The information displayed comprises:</p> <ul style="list-style-type: none"> ■ Symbol for event level ■ Code for diagnostic behavior ■ Operation time of occurrence ■ Event text <p>The diagnostic message displayed can still be valid.</p> <p>Information on what is causing the message, and remedy measures, can be viewed via the I-symbol on the display.</p> <p>Access:</p> <ul style="list-style-type: none"> ■ Read access: Operator ■ Write access: -

Timestamp


Navigation	 Diagnostics → Active diagnos. → Timestamp
Description	Displays the timestamp of the diagnostic message generated for the last diagnostic event that has ended.
User interface	Days (d), hours (h), minutes (m), seconds (s)
Factory setting	
Additional information	<p>Access:</p> <ul style="list-style-type: none"> ■ Read access: Operator ■ Write access: -

Operating time from restart

Navigation	 Diagnostics → Active diagnos. → Time fr. restart
Description	Indicates how long the device has been in operation since the last time the device was restarted.
User interface	Days (d), hours (h), minutes (m), seconds (s)
Factory setting	

Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Operator ■ Write access: -
-------------------------------	---

Operating time

Navigation	 Diagnostics → Active diagnos. → Operating time
Description	Indicates how long the device has been in operation.
User interface	Days (d), hours (h), minutes (m), seconds (s)
Factory setting	
Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Operator ■ Write access: -


3.2.2 Diagnostic list

Navigation   Diagnostics → Diagnostic list

3.2.3 Event logbook

Navigation   Diagnostics → Event logbook


Clear event list

Navigation	 Diagnostics → Event logbook → Clear event list
Description	Delete all entries of the event list.
Selection	<ul style="list-style-type: none"> ■ Cancel ■ Clear data
Factory setting	Cancel
Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Expert ■ Write access: Expert


3.2.4 Minimum/maximum values

Navigation  Diagnostics → Min/max val.


Min. level value

Navigation	 Diagnostics → Min/max val. → Min. level value
Description	Minimum or maximum measured value by device. Note: This value can be reset via the "Reset min./max." parameter. This value is also reset when device is reset.
User interface	Signed floating-point number
Factory setting	


Time min. level

Navigation	 Diagnostics → Min/max val. → Time min. level
Description	Displays operating time at which the lowest level was measured. Note: This value can be reset via the "Reset min./max. " parameter. This value is also reset when device is reset.
User interface	Days (d), hours (h), minutes (m), seconds (s)
Factory setting	


Maximum draining speed

Navigation	 Diagnostics → Min/max val. → Max. drain speed
Description	Displays highest draining speed measured since the last reset. Note: This value can be reset via the "Reset min./max. " parameter. This value is also reset when device is reset.
User interface	Positive floating-point number
Factory setting	


Counter overfilling

Navigation	 Diagnostics → Min/max val. → Count overfill.
Description	Displays the number of underfills (level < 0 %) or overfills (level > 100 %). Note: This value can be reset via the "Reset min./max. " parameter. This value is also reset when device is reset.
User interface	0 to 65 535
Factory setting	0
Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Operator ■ Write access: -


Minimum sensor temperature

Navigation	 Diagnostics → Min/max val. → Min. sensor temp
Description	Displays lowest or highest sensor temperature measured so far.
User interface	-150 to 200 °C
Factory setting	

Time min. sensor temperature

Navigation	 Diagnostics → Min/max val. → Time min s. temp
Description	Displays operating time at which the lowest sensor temperature was measured so far.
User interface	Days (d), hours (h), minutes (m), seconds (s)
Factory setting	


Minimum terminal voltage

Navigation	 Diagnostics → Min/max val. → Min.term.volt.
Description	Minimum or maximum measured terminal (supply) voltage.
User interface	0.0 to 50.0 V


Factory setting

Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Operator ■ Write access: -
-------------------------------	---


Minimum electronics temperature

Navigation	 Diagnostics → Min/max val. → Min.electr.temp.
Description	Minimum or maximum measured main electronics temperature.
User interface	Signed floating-point number
Factory setting	
Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Operator ■ Write access: -

Max. level value


Navigation	 Diagnostics → Min/max val. → Max. level value
Description	Minimum or maximum measured value by device. Note: This value can be reset via the "Reset min./max." parameter. This value is also reset when device is reset.
User interface	Signed floating-point number
Factory setting	

Time max. level

Navigation	 Diagnostics → Min/max val. → Time max. level
Description	Displays operating time at which the highest level was measured. Note: This value can be reset via the "Reset min./max. " parameter. This value is also reset when device is reset.
User interface	Days (d), hours (h), minutes (m), seconds (s)


Factory setting

Maximum filling speed


Navigation	 Diagnostics → Min/max val. → Max. fill. speed
Description	Displays highest filling speed measured since the last reset. Note: This value can be reset via the "Reset min./max. " parameter. This value is also reset when device is reset.
User interface	Positive floating-point number

Factory setting


Counter underfilling

Navigation	 Diagnostics → Min/max val. → Count underfill.
Description	Displays the number of underfills (level < 0 %) or overfills (level > 100 %). Note: This value can be reset via the "Reset min./max. " parameter. This value is also reset when device is reset.
User interface	0 to 65 535
Factory setting	0


Maximum sensor temperature

Navigation	 Diagnostics → Min/max val. → Max. sensor temp
Description	Displays lowest or highest sensor temperature measured so far.
User interface	-150 to 200 °C
Factory setting	


Time max. sensor temperature

Navigation	 Diagnostics → Min/max val. → Time max s. temp
Description	Displays operating time at which the highest sensor temperature was measured so far.
User interface	Days (d), hours (h), minutes (m), seconds (s)
Factory setting	


Maximum terminal voltage


Navigation	 Diagnostics → Min/max val. → Max.term.voltage
Description	Minimum or maximum measured terminal (supply) voltage.
User interface	0.0 to 50.0 V
Factory setting	

Maximum electronics temperature

Navigation	 Diagnostics → Min/max val. → Max.electr.temp.
Description	Minimum or maximum measured main electronics temperature.
User interface	Signed floating-point number
Factory setting	

Reset min./max.




Navigation	 Diagnostics → Min/max val. → Reset min/max
Description	Resets the drag indicator of the selected process variable.
Selection	<ul style="list-style-type: none"> ■ None ■ Drain/fill speed ■ Level ■ Reset all
Factory setting	None



3.2.5 Simulation

Navigation   Diagnostics → Simulation


Simulation

Navigation	 Diagnostics → Simulation → Simulation
Prerequisite	Selection options marked with *: The corresponding device function must be available and configured.
Description	Simulates one or more process variables and/or events. Warning: Output will reflect the simulated value or event.
Selection	<ul style="list-style-type: none"> ■ Off ■ Distance ■ Level ■ Level linearized * ■ Current output ■ Diagnostic event simulation ■ Foam index * ■ Buildup index *
Factory setting	Off





Simulation distance

Navigation	 Diagnostics → Simulation → Sim distance
Prerequisite	Simulation = Distance (→  52)
User entry	-999 900 to 999 900 mm
Factory setting	

Buildup index

Navigation	 Diagnostics → Simulation → Buildup index
Prerequisite	Simulation = Buildup index
User entry	0 to 100.0 %

* Visibility depends on order options or device settings

Factory setting**Foam index** **Navigation**  Diagnostics → Simulation → Foam index**Prerequisite** Simulation = Foam index (→  36)**User entry** 0 to 100.0 %**Factory setting****Process variable value** **Navigation**  Diagnostics → Simulation → Proc. var. value**Prerequisite** Simulation = Level linearized (→  51)**Description** Defines the value of the selected variable.
The outputs assume values or states according to this value.**User entry** Signed floating-point number**Factory setting****Value current output** **Navigation**  Diagnostics → Simulation → Current output**Prerequisite** Simulation = Current output (→  79)**Description** Defines the value of the simulated output current.**User entry** 3.59 to 23 mA**Factory setting****Diagnostic event simulation** **Navigation**  Diagnostics → Simulation → Diagnostic event**Prerequisite** Simulation = Diagnostic event simulation

Description	Select the diagnostic event to be simulated. Note: To terminate the simulation, select "Off".
Selection	<ul style="list-style-type: none"> ⊗F062 Sensor connection faulty ⊗F151 Sensor electronic failure △M168 Buildup detected △S203 HART Device Malfunction ⊗F204 HART Electronic Defect ⊗F242 Firmware incompatible ⊗F252 Module incompatible ⊗F270 Main electronics defective ⊗F272 Main electronics faulty ⊗F273 Main electronics defective ⊗F282 Data storage inconsistent ⊗F283 Memory content inconsistent △M287 Memory content inconsistent ⊗F388 Electronics and HistoROM defective ⊗F410 Data transfer failed △C412 Processing download △S420 HART Device Configuration Locked △S421 HART Loop Current fixed △C431 Trim required ⊗F435 Linearization faulty ⊗F437 Configuration incompatible △M438 Dataset different △S441 Current output out of range ⊗C484 Failure mode simulation active △C485 Process variable simulation active △C491 Current output simulation active △S495 Diagnostic event simulation active ⊗F538 Configuration Sensor Unit invalid △C585 Simulation distance △C586 Record map ⊗F801 Supply voltage too low △S802 Supply voltage too high ⊗F805 Loop current faulty △M806 Loop diagnostics △M807 No Baseline due to insuf. volt. at 20 mA △S825 Electronics temperature △S826 Sensor temperature out of range △S846 HART Non-Primary Variable Out of Limit △S847 HART Primary Variable Out of Limit


△S848 HART Device Variable Alert
 △S941 Echo lost
 △S942 In safety distance
 △C952 Foam detected
 △S968 Level limited

Factory setting Off


3.2.6 Heartbeat Technology

Navigation  Diagnostics → Heartbeat Techn.

Heartbeat Verification

Navigation  Diagnostics → Heartbeat Techn. → Heartbeat Verif.

Date/time Heartbeat Verification

Navigation  Diagnostics → Heartbeat Techn. → Heartbeat Verif. → Date/time Heartbeat Verification

Description Date and time of last Heartbeat Verification.
 This value is updated with every Heartbeat verification.
 Note:
 If time information is not available, e.g. Heartbeat verification is started from display, '-----' is shown.

User interface Character string comprising numbers, letters and special characters

Factory setting

Operating time (Verification)


Navigation  Diagnostics → Heartbeat Techn. → Heartbeat Verif. → Operating time

Description Value of the operating hours counter at the time of verification.


User interface Days (d), hours (h), minutes (m), seconds (s)

Factory setting

Verification result

Navigation	 Diagnostics → Heartbeat Techn. → Heartbeat Verif. → Verific. result
Description	Result of Heartbeat verification
User interface	<ul style="list-style-type: none"> ▪ Not done ▪ Passed ▪ Failed
Factory setting	


Status

Navigation	 Diagnostics → Heartbeat Techn. → Heartbeat Verif. → Status
Description	Shows the actual status.
User interface	<ul style="list-style-type: none"> ▪ Done ▪ Busy ▪ Failed ▪ Not done
Factory setting	

Loop diagnostics

Navigation   Diagnostics → Heartbeat Techn. → Loop diagn.

Rebuild baseline

Navigation	 Diagnostics → Heartbeat Techn. → Loop diagn. → Reb. baseline
Description	<p>Notice</p> <p>The current output is simulated.</p> <p>Bridge the PLC or take other appropriate measures to prevent an erroneous triggering of alarm messages or changes in the control loop behavior.</p> <p>The baseline should be rebuilt if planned changes have been made in the loop.</p>
Selection	<ul style="list-style-type: none"> ▪ No ▪ Yes
Factory setting	No

Tolerated deviation +/-



Navigation	Diagnostics → Heartbeat Techn. → Loop diagn. → Toler. deviation
Description	A value should be chosen to ensure that normal voltage deviations do not lead to unwanted messages. Default 1.5 V DC
User entry	0.5 to 3.0 V
Factory setting	1.5 V

Baseline status


Navigation	Diagnostics → Heartbeat Techn. → Loop diagn. → Baseline status
Description	"Failed" Means, baseline is not available or creation not possible. "Success" Baseline is available.
User interface	<ul style="list-style-type: none"> ■ Failed ■ Success
Factory setting	Failed

Loop diagnostics




Navigation	Diagnostics → Heartbeat Techn. → Loop diagn. → Loop diagn.
Description	Enable/disable loop diagnostics. Note: If the function is disabled, there is no analysis and no event message.
Selection	<ul style="list-style-type: none"> ■ Disable ■ Enable
Factory setting	Disable


Terminal voltage 1

Navigation	 Diagnostics → Heartbeat Techn. → Loop diagn. → Terminal volt. 1
Description	Shows the current terminal voltage that is applied at the output
User interface	0.0 to 50.0 V
Factory setting	0 V

Clamping voltage lower threshold


Navigation	 Diagnostics → Heartbeat Techn. → Loop diagn. → Lower threshold
User interface	0.0 to 50.0 V
Factory setting	0 V

Clamping voltage upper threshold


Navigation	 Diagnostics → Heartbeat Techn. → Loop diagn. → Upper threshold
User interface	0.0 to 50.0 V
Factory setting	0 V


806 Event delay




Navigation	 Diagnostics → Heartbeat Techn. → Loop diagn. → 806 Event delay
Description	Displays how long the triggering status must be present until an event message is issued. Used to filter out short-term signal interference.
User entry	0 to 60 s
Factory setting	1 s


Foam detection


Navigation  Diagnostics → Heartbeat Techn. → Foam detection


Foam detection 


Navigation	 Diagnostics → Heartbeat Techn. → Foam detection → Foam detection
Selection	<ul style="list-style-type: none"> ■ Off ■ On
Factory setting	Off


Foam index

Navigation	 Diagnostics → Heartbeat Techn. → Foam detection → Foam index
Description	<p>Foam index 0% means: no foam. Foam index 100% means: maximum detectable foam.</p>
User interface	0 to 100 %
Factory setting	0 %

Foam detec. threshold 

Navigation	 Diagnostics → Heartbeat Techn. → Foam detection → Foam threshold
Description	Enter the threshold for the foam detection. As soon as the foam index has reached the preset switching point, an event is triggered.
Selection	<ul style="list-style-type: none"> ■ Sensitive (20%) ■ Middle (40%) ■ Insensitive (80%) ■ User defined (xx%)
Factory setting	Middle (40%)


Foam detec. threshold value 

Navigation	 Diagnostics → Heartbeat Techn. → Foam detection → Foam detect val.
Description	User-defined threshold value for the foam detection.

User entry 0 to 100.0 %

Factory setting 40 %


Lower level range limit

Navigation  Diagnostics → Heartbeat Techn. → Foam detection → LLR limit

Description Assign lower limit of foam monitoring area.

Factory setting 0 %

Upper level range limit

Navigation  Diagnostics → Heartbeat Techn. → Foam detection → ULR limit

Description Assign upper limit of foam monitoring area.

Factory setting 100.0 %

Distance at foam zero adjustment

Navigation  Diagnostics → Heartbeat Techn. → Foam detection → Dist. @zero foam

Description Displays the distance when the 0 % foam value was set.

User entry Signed floating-point number

Factory setting 0 mm

0% foam value


Navigation  Diagnostics → Heartbeat Techn. → Foam detection → 0% foam value

Description Displays the relative echo amplitude when the 0 % foam value was set.


User entry -999 999.9 to 999 999.9 dB

Factory setting 0 dB

Buildup detection

Navigation  Diagnostics → Heartbeat Techn. → Buildup detect.

Buildup detection

Navigation  Diagnostics → Heartbeat Techn. → Buildup detect. → Buildup detect.


Description Activate or deactivate build-up detection.

Selection

- Off
- On

Factory setting Off

Buildup index


Navigation  Diagnostics → Heartbeat Techn. → Buildup detect. → Buildup index

Description Build-up index 0% means: no build-up.
Build-up index 100% means: maximum detectable build-up.

User interface 0 to 100 %

Factory setting 0 %

Buildup detection threshold

Navigation  Diagnostics → Heartbeat Techn. → Buildup detect. → Buildup detec.

Description Enter the threshold for the build-up detection. As soon as the build-up index has reached the preset switching point, an event is triggered.

Selection

- Sensitive (20%)
- Middle (40%)
- Insensitive (80%)
- User defined (xx%)

Factory setting Middle (40%)

Buildup detection threshold value

Navigation	Diagnostics → Heartbeat Techn. → Buildup detect. → Buildup value
Description	User-defined threshold value for the build-up detection.
User entry	0 to 100.0 %
Factory setting	40 %

Minimum distance for buildup detection

Navigation	Diagnostics → Heartbeat Techn. → Buildup detect. → Min dist buildup
Description	Starting point for build-up detection area. Note: Build-up detection requires a minimum distance between the reference point of the measurement and the medium surface.
User entry	-999 900 to 999 900 mm
Factory setting	0 mm

Maximum distance for buildup detection

Navigation	Diagnostics → Heartbeat Techn. → Buildup detect. → Max dist buildup
Description	Endpoint for build-up detection area. Note: Build-up detection requires a minimum distance between the reference point of the measurement and the medium surface.
User entry	-999 900 to 999 900 mm
Factory setting	500 mm

0 % buildup value

Navigation	Diagnostics → Heartbeat Techn. → Buildup detect. → 0 % buildup val
Description	Displays the build up value at 0 % ("Area of incoupling" at 0 % build up). Note: This value is determined automatically in the guided commissioning and can be adjusted manually in the menu later.

User entry Positive floating-point number

Factory setting 0

Area of incoupling


Navigation  Diagnostics → Heartbeat Techn. → Buildup detect. → Area incoupling

Description Ringing integral within the detection area.

User interface Positive floating-point number

Factory setting 0.0

Limit offset for buildup detection

Navigation  Diagnostics → Heartbeat Techn. → Buildup detect. → Offset buildup

User entry -999 999.9 to 999 999.9 dB

Factory setting 10 dB

3.2.7 Echo curve

Navigation   Diagnostics → Echo curve

Save reference curve

Navigation  Diagnostics → Echo curve → Save ref. curve

Description Saves the currently measured echo curve as a reference curve in the device.

Note:

When the guided commissioning is executed the first time, the reference curve is automatically saved at the end.

In the case of manual commissioning (menu), it is recommended to actively save the reference curve immediately after commissioning.


Selection

- Customer reference curve
- Not active


Factory setting

Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Operator ■ Write access: Maintenance
-------------------------------	---

Time reference curve

Navigation	 Diagnostics → Echo curve → Time ref. curve
Description	Displays the timestamp of the recording of the reference curve.
User interface	Days (d), hours (h), minutes (m), seconds (s)
Factory setting	
Additional information	Timestamp of the recording of the reference curve Access: <ul style="list-style-type: none"> ■ Read access: Operator ■ Write access: -


Reference curve active

Navigation	 Diagnostics → Echo curve → Ref.curve active
Description	Displays if a customer reference curve has been stored in the device.
User interface	<ul style="list-style-type: none"> ■ Delivery reference curve available ■ Customer reference curve available
Factory setting	
Additional information	The delivery reference curve is recorded at the factory before delivery. A customer reference curve is recorded as standard at the end of the Guidance → Commissioning . These reference curves can be used for diagnosing problems when troubleshooting. Access: <ul style="list-style-type: none"> ■ Read access: Operator ■ Write access: -



3.2.8 Diagnostic settings

Navigation  Diagnostics → Diag. settings

Properties

Navigation  Diagnostics → Diag. settings → Properties

941 Diagnostic behavior

Navigation   Diagnostics → Diag. settings → Properties → 941 Diag. behav.

Description Defines the behavior of the output in case of an echo loss.

"Last valid value"

Last valid value is kept.

"Ramp at echo lost"

Output value is continuously shifted towards 0% or 100%.

"Value echo lost"

Output assumes a defined value.

"Alarm"



Device generates an alarm.

Selection

- Last valid value
- Ramp at echo lost
- Value echo lost
- Alarm

Factory setting Last valid value

941 Event category

Navigation   Diagnostics → Diag. settings → Properties → 941Event category

Selection

- Failure (F)
- Function check (C)
- Out of specification (S)
- Maintenance required (M)
- No effect (N)

Factory setting Out of specification (S)

Value echo lost



Navigation	Diagnostics → Diag. settings → Properties → Value echo lost
Description	Value of the output in case of an echo loss.
User entry	Signed floating-point number
Factory setting	0 %

Ramp at echo lost



Navigation	Diagnostics → Diag. settings → Properties → Ramp echo lost
Description	Slope of the ramp in the case of an echo loss. Note: If the slope is positive (+), the output increases until it reaches 100%. If the slope is negative (-), the output decreases until it reaches 0%.
User entry	Signed floating-point number
Factory setting	0.0 %/min

Delay echo lost



Navigation	Diagnostics → Diag. settings → Properties → Delay echo lost
Description	Activate or deactivate the delay time in case of echo loss. After an echo loss, the device allows the delay time to pass before the reaction defined in parameter "941 Diagnostic behavior" occurs. This way it can be avoided that temporary disturbances interrupt the measurement unnecessarily.
Selection	<ul style="list-style-type: none"> ■ Off ■ On
Factory setting	On

Delay time echo lost




Navigation	Diagnostics → Diag. settings → Properties → DlyTimeEchoLost
Description	Enter the delay time in case of echo loss. After an echo loss, the device allows the delay time defined here to pass before the reaction defined in parameter "941 Diagnostic behavior" occurs. This way it can be avoided that temporary disturbances interrupt the measurement unnecessarily.

User entry 0 to 99 999.9 s

Factory setting 900 s

Delay time echo jump


Navigation  Diagnostics → Diag. settings → Properties → DlyTimeEchoJump

Description Enter the delay time for the echo jump.

User entry 0 to 99 999.9 s

Factory setting 30 s

Echo lost window right


Navigation  Diagnostics → Diag. settings → Properties → Echo l.win.right

Description Enter the initial width of the extended search window in the direction of decreasing levels.

User entry 0 to 99 900 mm

Factory setting 4 000 mm

Echo lost window left


Navigation  Diagnostics → Diag. settings → Properties → Echo l.win.left

Description Enter the initial width of the extended search window in the direction of increasing levels.

User entry 0 to 99 000 mm

Factory setting 4 000 mm

Draining speed


Navigation  Diagnostics → Diag. settings → Properties → Draining speed

Description Enter the opening speed of the extended search window in the direction of decreasing levels.

User entry Signed floating-point number

Factory setting 60 mm/s

Filling speed



Navigation  Diagnostics → Diag. settings → Properties → Filling speed

Description Enter the opening speed of the extended search window in the direction of increasing levels.

User entry Signed floating-point number

Factory setting 60 mm/s

942 Diagnostic behavior



Navigation   Diagnostics → Diag. settings → Properties → 942 Diag. behav.

Selection

- Off
- Alarm
- Warning
- Self holding

Factory setting Warning

942 Event category


Navigation   Diagnostics → Diag. settings → Properties → 942Event category

Selection

- Failure (F)
- Function check (C)
- Out of specification (S)
- Maintenance required (M)
- No effect (N)

Factory setting Out of specification (S)

Safety distance

Navigation  Diagnostics → Diag. settings → Properties → Safety distance

User entry -200 000 to 125 000 mm

Factory setting 0 mm

Acknowledge alarm



Navigation Diagnostics → Diag. settings → Properties → Acknowl. alarm

Selection

- No
- Yes

Factory setting No

Configuration

Navigation Diagnostics → Diag. settings → Configuration

Sensor

Navigation Diagnostics → Diag. settings → Configuration → Sensor

168 Diagnostic behavior



Navigation Diagnostics → Diag. settings → Configuration → Sensor → 168 Diag. behav.

Description Select event behavior
"Logbook entry only":
no digital or analog transmission of the message
"Warning": Current output unchanged. Message is output digitally (default).
"Alarm": Current output assumes the set alarm current.
Regardless of the setting, the message appears on the display. If the permissible conditions are reached again, the warning is no longer available in the instrument.

Selection

- Off
- Alarm
- Warning
- Logbook entry only

Factory setting Warning

168 Event category




Navigation Diagnostics → Diag. settings → Configuration → Sensor → 168Event category

Description Select category for diagnostic message.


Selection	<ul style="list-style-type: none"> ■ Failure (F) ■ Function check (C) ■ Out of specification (S) ■ Maintenance required (M) ■ No effect (N)
------------------	--

Factory setting	Maintenance required (M)
------------------------	--------------------------

Process

Navigation  Diagnostics → Diag. settings → Configuration → Process

806 Diagnostic behavior


Navigation	 Diagnostics → Diag. settings → Configuration → Process → 806 Diag. behav.
-------------------	---

Description	<p>Select event behavior</p> <p>"Logbook entry only": no digital or analog transmission of the message.</p> <p>"Warning": Current output unchanged. Message is output digitally (default).</p> <p>If the permissible conditions are reached again, the warning is no longer available in the instrument.</p>
--------------------	--

Selection	<ul style="list-style-type: none"> ■ Warning ■ Logbook entry only
------------------	---

Factory setting	Warning
------------------------	---------

806 Event category

Navigation	 Diagnostics → Diag. settings → Configuration → Process → 806Event category
-------------------	--

Description	Select category for diagnostic message.
--------------------	---

Selection	<ul style="list-style-type: none"> ■ Failure (F) ■ Function check (C) ■ Out of specification (S) ■ Maintenance required (M) ■ No effect (N)
------------------	--

Factory setting	Maintenance required (M)
------------------------	--------------------------

941 Diagnostic behavior


Navigation	Diagnostics → Diag. settings → Configuration → Process → 941 Diag. behav.
Description	<p>Defines the behavior of the output in case of an echo loss.</p> <p>"Last valid value" Last valid value is kept.</p> <p>"Ramp at echo lost" Output value is continuously shifted towards 0% or 100%.</p> <p>"Value echo lost" Output assumes a defined value.</p> <p>"Alarm" Device generates an alarm.</p>
Selection	<ul style="list-style-type: none"> ■ Last valid value ■ Ramp at echo lost ■ Value echo lost ■ Alarm
Factory setting	Last valid value

941 Event category


Navigation	Diagnostics → Diag. settings → Configuration → Process → 941Event category
Selection	<ul style="list-style-type: none"> ■ Failure (F) ■ Function check (C) ■ Out of specification (S) ■ Maintenance required (M) ■ No effect (N)
Factory setting	Out of specification (S)

942 Diagnostic behavior


Navigation	Diagnostics → Diag. settings → Configuration → Process → 942 Diag. behav.
Selection	<ul style="list-style-type: none"> ■ Off ■ Alarm ■ Warning ■ Self holding
Factory setting	Warning

942 Event category



Navigation	Diagnostics → Diag. settings → Configuration → Process → 942Event category
Selection	<ul style="list-style-type: none"> ■ Failure (F) ■ Function check (C) ■ Out of specification (S) ■ Maintenance required (M) ■ No effect (N)
Factory setting	Out of specification (S)

952 Diagnostic behavior



Navigation	Diagnostics → Diag. settings → Configuration → Process → 952 Diag. behav.
Description	<p>Select event behavior</p> <p>"Logbook entry only": no digital or analog transmission of the message</p> <p>"Warning": Current output unchanged. Message is output digitally (default).</p> <p>"Alarm": Current output assumes the set alarm current.</p> <p>Regardless of the setting, the message appears on the display. If the permissible conditions are reached again, the warning is no longer available in the instrument.</p>
Selection	<ul style="list-style-type: none"> ■ Off ■ Alarm ■ Warning ■ Logbook entry only
Factory setting	Warning

952 Event category



Navigation	Diagnostics → Diag. settings → Configuration → Process → 952Event category
Description	Select category for diagnostic message.
Selection	<ul style="list-style-type: none"> ■ Failure (F) ■ Function check (C) ■ Out of specification (S) ■ Maintenance required (M) ■ No effect (N)
Factory setting	Out of specification (S)

3.3 Application

Navigation  Application

3.3.1 Measuring units

Navigation  Application → Measuring units

Level unit

Navigation  Application → Measuring units → Level unit

Description Select unit for level measurement.

Selection

<i>SI units</i>	<i>US units</i>
■ %	■ ft
■ m	■ in
■ mm	

Factory setting %

Length unit

Navigation  Application → Measuring units → Length unit

Description Select the length unit for distance measurement.
It is used, e.g., for the basic calibration ("Empty calibration" or "Full calibration").

Selection

<i>SI units</i>	<i>US units</i>
■ mm	■ ft
■ m	■ in

Factory setting mm

Temperature unit

Navigation  Application → Measuring units → Temperature unit

Description Select the temperature unit.

Selection


<i>SI units</i>	<i>US units</i>
■ °C	°F
■ K	

Factory setting °C

3.3.2 Measured values

Navigation   Application → Measured values

Level linearized


Navigation  Application → Measured values → Level linearized

Description Displays the linearized level.

User interface Signed floating-point number

Factory setting 0 %

Level


Navigation  Application → Measured values → Level

Description Displays the actual measured level.

User interface -99 999.9 to 200 000.0 %

Factory setting 0.0 %

Output current


Navigation  Application → Measured values → Output curr.

Description Displays the value currently calculated for the current output


User interface 3.59 to 23 mA

Factory setting 3.59 mA


Distance

Navigation	 Application → Measured values → Distance
Description	Distance from reference point to medium surface. Note: The reference point is specified in the respective Operating Instructions.
User interface	Signed floating-point number
Factory setting	0 mm


Unfiltered distance

Navigation	 Application → Measured values → Unfiltered dist.
Description	Displays the distance from the reference point of the measurement to the medium surface without the influence of the signal filters. Note: The reference point is specified in the respective Operating Instructions.
User interface	Signed floating-point number
Factory setting	0 mm
Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Maintenance ■ Write access: -

Sensor temperature


Navigation	 Application → Measured values → Sensor temp.
Description	Displays the current temperature of the sensor electronics.
User interface	-150 to 200 °C
Factory setting	-150 °C

Terminal voltage 1

Navigation	 Application → Measured values → Terminal volt. 1
Description	Shows the current terminal voltage that is applied at the output

User interface	0.0 to 50.0 V
Factory setting	0 V

Electronics temperature

Navigation	 Application → Measured values → Electronics temp
Description	Displays the current temperature of the main electronics.
User interface	Signed floating-point number
Factory setting	0 °C


3.3.3 Sensor

Navigation   Application → Sensor


Basic settings

Navigation  Application → Sensor → Basic settings

Medium type


Navigation	 Application → Sensor → Basic settings → Medium type
Description	Select whether the measured medium is liquid or solid.
Selection	<ul style="list-style-type: none"> ■ Liquid ■ Solid
Factory setting	Liquid

Application


Navigation	 Application → Sensor → Basic settings → Application
Description	Select application type.

Selection	<ul style="list-style-type: none"> ■ Dosing vessel * ■ Stirred vessel ■ Storage vessel ■ Workbench test
Factory setting	Stirred vessel
Additional information	<ul style="list-style-type: none"> ■ Dosing vessel: Vessel in a dosing application with very fast level change. ■ Stirred vessel: Vessel with agitator. ■ Storage vessel: Vessel for storage with slow level change. ■ Workbench test: All signal filters are deactivated. This mode should only be used for test purposes.

Application


Navigation	 Application → Sensor → Basic settings → Application
Description	Select application type.
Selection	<ul style="list-style-type: none"> ■ Silo ■ Feed hopper * ■ Workbench test
Factory setting	Silo
Additional information	<ul style="list-style-type: none"> ■ Silo: Silo for bulk material (tall and narrow). ■ Feed hopper: Funnel shaped hopper. ■ Workbench test: All signal filters are deactivated. This mode should only be used for test purposes.

Empty calibration


Navigation	 Application → Sensor → Basic settings → Empty calibr.
Description	<p>Enter the distance from the reference point of the measurement to the minimum level (0 %).</p> <p>Note: The reference point is specified in the respective Operating Instructions.</p>
User entry	0 to 125 000 mm
Factory setting	<ul style="list-style-type: none"> ■ 15 000 mm at 80 GHz ■ 10 000 mm at 180 GHz

* Visibility depends on order options or device settings

Full calibration

Navigation	Application → Sensor → Basic settings → Full calibr.
Description	Distance between minimum level (0 %) and maximum level (100 %).
User entry	1 to 125 000 mm
Factory setting	<ul style="list-style-type: none"> ■ 15 000 mm at 80 GHz ■ 10 000 mm at 180 GHz


Advanced settings


Navigation Application → Sensor → Advanced set.

Maximum draining speed solid

Navigation	Application → Sensor → Advanced set. → Max.drain solid
Description	<p>By selecting the maximum expected filling and draining speed the signal evaluation is automatically optimized for the process.</p> <p>Note: The filling and draining speeds can be set separately as the filling and draining procedures may be different.</p> <p>Note: With the 'No filter / test' option all signal evaluation filters are deactivated. This option should exclusively be used for tests.</p>
Selection	<ul style="list-style-type: none"> ■ No filter / test * ■ Very fast > 1000 mm (40 in)/min * ■ Fast < 1000 mm (40 in)/min * ■ Standard < 500 mm (20 in)/min * ■ Medium < 100 mm (4 in)/min * ■ Slow < 50 mm (2 in)/min * ■ Very slow < 10 mm (0.4 in)/min *
Factory setting	No filter / test

* Visibility depends on order options or device settings

Maximum filling speed solid	
Navigation	 Application → Sensor → Advanced set. → Max. fill. solid
Description	<p>By selecting the maximum expected filling and draining speed the signal evaluation is automatically optimized for the process.</p> <p>Note: The filling and draining speeds can be set separately as the filling and draining procedures may be different.</p> <p>Note: With the 'No filter / test' option all signal evaluation filters are deactivated. This option should exclusively be used for tests.</p>
Selection	<ul style="list-style-type: none"> ■ No filter / test * ■ Very fast > 1000 mm (40 in)/min * ■ Fast < 1000 mm (40 in)/min * ■ Standard < 500 mm (20 in)/min * ■ Medium < 100 mm (4 in)/min * ■ Slow < 50 mm (2 in)/min * ■ Very slow < 10 mm (0.4 in)/min *
Factory setting	No filter / test

Maximum draining speed liquid	
Navigation	 Application → Sensor → Advanced set. → Max drain liquid
Description	<p>By selecting the maximum expected filling and draining speed the signal evaluation is automatically optimized for the process.</p> <p>Note: The filling and draining speeds can be set separately as the filling and draining procedures may be different.</p> <p>Note: With the 'No filter / test' option all signal evaluation filters are deactivated. This option should exclusively be used for tests.</p>
Selection	<ul style="list-style-type: none"> ■ No filter / test * ■ Very fast > 60 mm (2.4 in)/sec * ■ Fast < 60 mm (2.4 in)/sec * ■ Standard < 20 mm (0.8 in)/sec * ■ Medium < 5 mm (0.2 in)/sec * ■ Slow < 1 mm (0.04 in)/sec *
Factory setting	No filter / test

* Visibility depends on order options or device settings

Maximum filling speed liquid


Navigation	Application → Sensor → Advanced set. → Max. fill liquid
Description	<p>By selecting the maximum expected filling and draining speed the signal evaluation is automatically optimized for the process.</p> <p>Note: The filling and draining speeds can be set separately as the filling and draining procedures may be different.</p> <p>Note: With the 'No filter / test' option all signal evaluation filters are deactivated. This option should exclusively be used for tests.</p>
Selection	<ul style="list-style-type: none"> ■ No filter / test * ■ Very fast > 60 mm (2.4 in)/sec * ■ Fast < 60 mm (2.4 in)/sec * ■ Standard < 20 mm (0.8 in)/sec * ■ Medium < 5 mm (0.2 in)/sec * ■ Slow < 1 mm (0.04 in)/sec *
Factory setting	No filter / test

Damping output


Navigation	Application → Sensor → Advanced set. → Damping out.
Description	<p>The damping is effective before the measured value is further processed, i.e., before the following processes:</p> <ul style="list-style-type: none"> - Scaling - Limit value monitoring - Forwarding to display - Forwarding to Analog Input Block <p>Note: The Analog Input Block has its own "Damping" parameter. In the measurement chain, only one of the two attenuation parameters shall have a value other than 0. Otherwise, the signal will be attenuated several times.</p>
User entry	0.0 to 1200.0 s
Factory setting	0.0 s

* Visibility depends on order options or device settings

Evaluation sensitivity
**Navigation**

Application → Sensor → Advanced set. → Evaluation sens.

Description

Selection of the evaluation sensitivity

Options to select from:

- "Low"

Interferers but also small level signals are not recognized. The weighting curve is located high.

- "Medium"

The weighting curve is in a medium region.

- "High"

Small level signals but also interferers can be reliably detected. The weighting curve is located low.

Selection

- Low
- Medium
- High

Factory setting

Medium

First echo sensitivity
**Navigation**

Application → Sensor → Advanced set. → First echo sens.

Description

This parameter describes the band for First Echo evaluation.

Is measured / calculated down from the peak of the current level echo.

Options to select from:

"Low"

The band for the first echo evaluation is very narrow. The evaluation stays longer at the found echo respectively does not jump to the next Echo or distortion signal.

"Medium"

The band for the first echo evaluation has an average width.

"High"

The band for the first echo evaluation is broad. The evaluation jumps earlier to the next echo or distortion signal.

Selection

- Low
- Medium
- High

Factory setting

Medium

Frequency mode



Navigation	Application → Sensor → Advanced set. → Frequency mode
Description	Displays the device-specific measurement configuration.
Selection	<ul style="list-style-type: none"> ■ Mode 1 * ■ Mode 2 * ■ Mode 3 * ■ Mode 4 * ■ Mode 5 * ■ Mode 6 * ■ Mode 7 * ■ Mode 8 * ■ Mode 9 * ■ Mode 10 *
Factory setting	<ul style="list-style-type: none"> ■ Mode 1 at 80 GHz ■ Mode 9 at 180 GHz
Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Maintenance ■ Write access: Maintenance

Active map



Navigation	Application → Sensor → Advanced set. → Active map
Description	Select the mapping curve that is to be active. Alternatively, the option "No map" can be selected.
Selection	<ul style="list-style-type: none"> ■ Factory map ■ Customer map ■ No map
Factory setting	Factory map
Additional information	<ul style="list-style-type: none"> ■ Factory map: The device activates the mapping curve recorded in the factory. This curve cannot be edited or deleted. ■ Customer map: If a customer map has been recorded, this can be activated in order to minimize distortions in the application. This curve can be edited. ■ No map


* Visibility depends on order options or device settings

Distance


Navigation	 Application → Sensor → Advanced set. → Distance
Description	Distance from reference point to medium surface. Note: The reference point is specified in the respective Operating Instructions.
User interface	Signed floating-point number
Factory setting	0 mm


Confirm distance



Navigation	 Application → Sensor → Advanced set. → Confirm distance
Description	State whether the measured distance and the actual distance are the same.
Selection	<ul style="list-style-type: none"> ▪ Modify map ▪ Distance ok ▪ Distance unknown ▪ Level <=0
Factory setting	Distance unknown
Additional information	<ul style="list-style-type: none"> ▪ Modify map: To be selected if the range of mapping is to be defined manually in the Mapping end point parameter. ▪ Distance ok: To be selected if the measured distance matches the actual distance. The device does not perform a mapping. ▪ Distance unknown: To be selected if the actual distance is unknown. A mapping cannot be performed in this case. ▪ Level <=0: To be selected if the tank is completely empty. The device records a mapping covering the complete measuring range.

Mapping start point



Navigation	 Application → Sensor → Advanced set. → Map. start point
Description	Enter the initial distance for the mapping.
User entry	-999 900 to 999 900 mm
Factory setting	-250 mm
Additional information	Access: <ul style="list-style-type: none"> ▪ Read access: Expert ▪ Write access: Expert

Mapping end point


Navigation	Application → Sensor → Advanced set. → Map. end point
Description	Defines up to which distance the new mapping has to be recorded. Remark: Make sure the level signal is not covered by the mapping.
User entry	0.1 to 125 mm
Factory setting	1 200 mm

Map gap


Navigation	Application → Sensor → Advanced set. → Map gap
Description	Enter the distance between the defined and the actual end of the map.
User entry	0 to 100 000 mm
Factory setting	<ul style="list-style-type: none"> ■ 190 mm at 80 GHz ■ 153 mm at 180 GHz
Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Expert ■ Write access: Expert

End of mapping


Navigation	Application → Sensor → Advanced set. → End of mapping
Description	Define the behavior of the mapping curve at the end of the map.
Selection	<ul style="list-style-type: none"> ■ Adjustable ■ Last map value
Factory setting	Adjustable
Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Expert ■ Write access: Expert

End map. ampl. 

Navigation  Application → Sensor → Advanced set. → End map. ampl.

Description Enter the minimum amplitude of the mapping curve.


User entry -99 999.0 to 99 999.0 dB

Factory setting -100 dB

Additional information **Access:**

- Read access: Expert
- Write access: Expert

Mapping overlay time 

Navigation  Application → Sensor → Advanced set. → Map overlay time


Description Enter the duration for which a map is recorded. During this time, the largest amplitude values that occur are overlapped.


User entry 0 to 1 200 s

Factory setting 5 s

Additional information **Access:**

- Read access: Expert
- Write access: Expert

Record map 

Navigation  Application → Sensor → Advanced set. → Record map

Selection

- No
- Overlay map
- Delete cust map

Factory setting No

Additional information

- No
- Overlay map: The new map is generated by overlaying the old map and the current envelope curve.
- Delete cust map: The complete map (if one exists) is deleted.

Maximum measuring distance


Navigation	Application → Sensor → Advanced set. → Max. meas. dist.
Description	<p>If the preset measuring range differs significantly from the maximum measuring distance, it is recommended to enter the maximum measuring distance here.</p> <p>Example: Continuous level monitoring in the upper third of a tank/silo.</p> <p>Note: For tanks or silos with a conical outlet, this parameter should not be changed, as in this type of applications Empty calibration is usually not much smaller than the tank/silo height.</p>
User entry	0 to 125 000 mm
Factory setting	20 000 mm

Upper blank out


Navigation	Application → Sensor → Advanced set. → Upper blank out
Description	<p>Displays the distance from the reference point to slightly above the maximum level (100 %).</p> <p>The value is calculated by the device to suppress signals in this range. The value can also be adjusted manually.</p> <p>Note: No evaluation takes place in the upper blank out area.</p>
User entry	0 to 125 000 mm
Factory setting	0 mm

Output mode


Navigation	Application → Sensor → Advanced set. → Output mode
Description	<p>Select output mode between:</p> <p>Ullage: Displays the remaining ullage.</p> <p>or</p> <p>Level linearized: Display the measured level.</p> <p>Note: If linearization has been activated, the linearized level is displayed here.</p>
Selection	<ul style="list-style-type: none"> ■ Ullage ■ Level linearized

Factory setting Level linearized

L max. drain speed

Navigation  Application → Sensor → Advanced set. → L max draining


Description Enter the maximum draining speed.

User entry 0.0 to 50 000.0 %/min

Factory setting 0.0 %/min

Additional information **Access:**
 ■ Read access: Expert
 ■ Write access: Expert

L max. fill speed

Navigation  Application → Sensor → Advanced set. → L max.fill speed

Description Enter the maximum filling speed.

User entry 0.0 to 50 000.0 %/min

Factory setting 0.0 %/min

Additional information **Access:**
 ■ Read access: Expert
 ■ Write access: Expert

Level limit mode

Navigation  Application → Sensor → Advanced set. → Level limit mode

Description Determines whether the output value is limited by an upper or lower limit (or by both).

Selection ■ Off
 ■ Low limit
 ■ High limit
 ■ Low and High Limit

Factory setting Low limit

High limit



Navigation	Application → Sensor → Advanced set. → High limit
Description	Defines the upper limit of the output value.
User entry	Signed floating-point number
Factory setting	0 %

Low limit



Navigation	Application → Sensor → Advanced set. → Low limit
Description	Defines the lower limit of the output value.
User entry	-200 000.0 to 200 000.0 %
Factory setting	0.0 %

Level correction



Navigation	Application → Sensor → Advanced set. → Level correction
Description	Value is added to the measured level to compensate for a constant level error. Level correction > 0: The level is increased by this value. Level correction < 0: The level is decreased by this value.
User entry	-200 000.0 to 200 000.0 %
Factory setting	0.0 %

Antenna zero distance



Navigation	Application → Sensor → Advanced set. → Ant. zero dist.
Description	Displays the zero point adjustment of the antenna at state of delivery. Note: This parameter is adjusted to the device at the factory and should not be changed.
User entry	0 to 10 000 mm


Factory setting 230 mm

Additional information **Access:**
 ■ Read access: Expert
 ■ Write access: Expert

Echo evaluation

Navigation  Application → Sensor → Advanced set. → Echo evaluation

Echo curve statistic

Navigation  Application → Sensor → Advanced set. → Echo evaluation → Ec. curve stat.

Description Activate or deactivate the weighted echo curve statistics.

Selection
 ■ Off
 ■ On

Factory setting On

Additional information **Access:**
 ■ Read access: Expert
 ■ Write access: Expert

Echo curve statistics up

Navigation  Application → Sensor → Advanced set. → Echo evaluation → EC. stat. up

Description Enter the number of measuring cycles to define the weighting of the last echo curve for ascending signals.

User entry 0 to 30

Factory setting 2

Additional information **Access:**
 ■ Read access: Expert
 ■ Write access: Expert

Echo curve statistic down



Navigation	Application → Sensor → Advanced set. → Echo evaluation → ECS in down
Description	Enter the number of measuring cycles to define the weighting of the last echo curve for descending signals.
User entry	0 to 30
Factory setting	3
Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Expert ■ Write access: Expert

Echo curve smoothing



Navigation	Application → Sensor → Advanced set. → Echo evaluation → EC. smoothing
Description	Enter window width for echo curve smoothing.
User entry	0 to 9 900 mm
Factory setting	35 mm
Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Expert ■ Write access: Expert

Weighting curve offset



Navigation	Application → Sensor → Advanced set. → Echo evaluation → WgthCurveOffset
Description	Enter offset of the weighting curve.
User entry	-9 999.0 to 9 999.0 dB
Factory setting	14 dB
Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Expert ■ Write access: Expert

Window size weighting curve



Navigation	Application → Sensor → Advanced set. → Echo evaluation → WindowWgthCurve
Description	Enter width of the weighting curve window.
User entry	0 to 9 900 mm
Factory setting	<ul style="list-style-type: none">■ 800 mm at 80 GHz■ 427 mm at 180 GHz
Additional information	Access: <ul style="list-style-type: none">■ Read access: Expert■ Write access: Expert

Maximum value weighting curve



Navigation	Application → Sensor → Advanced set. → Echo evaluation → MaxValWghtCurve
Description	Enter maximum amplitude of the weighting curve.
User entry	-9 999.0 to 9 999.0 dB
Factory setting	100 dB
Additional information	Access: <ul style="list-style-type: none">■ Read access: Expert■ Write access: Expert

First echo band



Navigation	Application → Sensor → Advanced set. → Echo evaluation → First echo band
Description	Enter width of the first echo band.
User entry	0.0 to 100.0 dB
Factory setting	10 dB
Additional information	Access: <ul style="list-style-type: none">■ Read access: Expert■ Write access: Expert

DSC Mode



Navigation	Application → Sensor → Advanced set. → Echo evaluation → DSC Mode
Description	Select DSC mode.
Selection	<ul style="list-style-type: none"> ■ Off ■ Manual ■ Auto
Factory setting	Manual
Additional information	<ul style="list-style-type: none"> ■ Off: The signal control is deactivated. ■ Manual: The signal control is activated with a fixed value. ■ Auto: The signal control operates automatically. <p>Access:</p> <ul style="list-style-type: none"> ■ Read access: Expert ■ Write access: Expert

DSC Factor




Navigation	Application → Sensor → Advanced set. → Echo evaluation → DSC Factor
Description	Displays the actual factor for signal control.
User entry	0 to 1
Factory setting	0.75
Additional information	<p>Access:</p> <ul style="list-style-type: none"> ■ Read access: Expert ■ Write access: Expert


Actual DSC Factor

Navigation	Application → Sensor → Advanced set. → Echo evaluation → ActualDSCFactor
Description	Displays the actual factor for signal control.
User interface	0 to 1
Factory setting	0
Additional information	<p>Access:</p> <ul style="list-style-type: none"> ■ Read access: Expert ■ Write access: -


Tank bottom range 

Navigation	 Application → Sensor → Advanced set. → Echo evaluation → TB range
Description	Determines the range in which the physical bottom echo is searched for. The bottom range extends downwards and starts at level 0 % "Empty calibration". It ends at the entered value. Note: If the level 0 % "Empty calibration" is far above the physical bottom, the bottom range starts at the entered "Maximum measuring distance".
User entry	0 to 312 500 mm
Factory setting	15 000 mm


Min. amplitude TBD 

Navigation	 Application → Sensor → Advanced set. → Echo evaluation → Min. ampl. TBD
Description	Enter the minimum amplitude for tank bottom detection.
User entry	-99 to 9 999.0 dB
Factory setting	10 dB
Additional information	Access: <ul style="list-style-type: none"> ▪ Read access: Expert ▪ Write access: Expert


Lower level area 

Navigation	 Application → Sensor → Advanced set. → Echo evaluation → Lower level area
Description	Enter lower level area. In this defined range, the first echo band is lowered to the weighting curve.
User entry	0 to 125 000 mm
Factory setting	400 mm
Additional information	Access: <ul style="list-style-type: none"> ▪ Read access: Expert ▪ Write access: Expert


Evaluation mode


Navigation	 Application → Sensor → Advanced set. → Echo evaluation → Evaluation mode
Description	Defines the evaluation mode for the echo tracking.
Selection	<ul style="list-style-type: none"> ■ FlexTracking ■ FlexTracking - Weak signals ■ FixTracking ■ FixTracking - Weak signals
Factory setting	FlexTracking
Additional information	<ul style="list-style-type: none"> ■ FlexTracking: This is the standard setting with a self-correcting evaluation. If the device detects a more probable level signal than the currently evaluated signal, the device automatically corrects the evaluation after a preset time has elapsed. An evaluation below the map generally does not take place. ■ FlexTracking - Weak signals: Like FlexTracking, additionally the level signal is also tracked under the map. In case of bad signal conditions (small DC value, strongly turbulent surfaces...) this evaluation mode can bring additional stability. ■ FixTracking: This evaluation mode is optimized for applications with frequently changing, unwanted level jumps. As long as the evaluated echo is present, it is evaluated as a valid level echo. An evaluation below the map generally does not take place. ■ FixTracking - Weak signals: Like FixTracking, additionally the level signal is also tracked under the map. In case of bad signal conditions (small DC value, strongly turbulent surfaces...) this evaluation mode can bring additional stability.

Reset evaluation


Navigation	 Application → Sensor → Advanced set. → Echo evaluation → Reset evaluation
Description	Restarts level determination.
Selection	<ul style="list-style-type: none"> ■ Reset done ■ Yes
Factory setting	Reset done

Window size tracking


Navigation	 Application → Sensor → Advanced set. → Echo evaluation → Wind.size track.
User entry	0 to 20 500 mm
Factory setting	<ul style="list-style-type: none"> ■ 250 mm at 80 GHz ■ 213 mm at 180 GHz

Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Expert ■ Write access: Expert
-------------------------------	--

Debug parameter index


Navigation	 Application → Sensor → Advanced set. → Echo evaluation → Debug parm. idx
-------------------	--

User entry	0 to 65 535
-------------------	-------------

Factory setting	2
------------------------	---

Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Expert ■ Write access: Expert
-------------------------------	--

Debug array index



Navigation	 Application → Sensor → Advanced set. → Echo evaluation → Debug array indx
-------------------	---

User entry	0 to 255
-------------------	----------

Factory setting	0
------------------------	---

Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Expert ■ Write access: Expert
-------------------------------	--

Status



Navigation	 Application → Sensor → Advanced set. → Echo evaluation → Status
-------------------	---

User entry	0 to 255
-------------------	----------


Factory setting	0
------------------------	---

Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Expert ■ Write access: Expert
-------------------------------	--

Debug value

Navigation	 Application → Sensor → Advanced set. → Echo evaluation → Debug value
User interface	Signed floating-point number
Factory setting	4.0
Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Expert ■ Write access: Expert

Debug value integer32


Navigation	 Application → Sensor → Advanced set. → Echo evaluation → Debug val. int32
User interface	Positive integer
Factory setting	0
Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Expert ■ Write access: Expert

Linearization


Navigation  Application → Sensor → Linearization

Linearization type




Navigation	 Application → Sensor → Linearization → Lineariz. type
Description	Select type of linearization.
Selection	<ul style="list-style-type: none"> ■ None ■ Linear ■ Table ■ Pyramid bottom ■ Conical bottom ■ Angled bottom ■ Horizontal cylinder ■ Sphere
Factory setting	None


Unit after linearization 

Navigation	 Application → Sensor → Linearization → Unit lineariz.																																										
Description	<p>Defines the unit of the linearized value.</p> <p>Note: The selected unit is only used to be indicated on the display. The measured value is not transformed according to the selected unit.</p> <p>Note: If "Free text" is selected, an additional parameter "Free text" appears in which the designation of the unit can be defined.</p>																																										
Selection	<table> <thead> <tr> <th><i>SI units</i></th> <th><i>US units</i></th> <th><i>Imperial units</i></th> </tr> </thead> <tbody> <tr> <td>▪ STon</td> <td>▪ lb</td> <td>impGal</td> </tr> <tr> <td>▪ t</td> <td>▪ UsGal</td> <td></td> </tr> <tr> <td>▪ kg</td> <td>▪ ft³</td> <td></td> </tr> <tr> <td>▪ cm³</td> <td>▪ ft</td> <td></td> </tr> <tr> <td>▪ dm³</td> <td>▪ in</td> <td></td> </tr> <tr> <td>▪ m³</td> <td></td> <td></td> </tr> <tr> <td>▪ hl</td> <td></td> <td></td> </tr> <tr> <td>▪ l</td> <td></td> <td></td> </tr> <tr> <td>▪ %</td> <td></td> <td></td> </tr> <tr> <td>▪ mm</td> <td></td> <td></td> </tr> <tr> <td>▪ m</td> <td></td> <td></td> </tr> <tr> <td colspan="3"><i>Custom-specific units</i></td> </tr> <tr> <td colspan="3">Free text</td> </tr> </tbody> </table>	<i>SI units</i>	<i>US units</i>	<i>Imperial units</i>	▪ STon	▪ lb	impGal	▪ t	▪ UsGal		▪ kg	▪ ft ³		▪ cm ³	▪ ft		▪ dm ³	▪ in		▪ m ³			▪ hl			▪ l			▪ %			▪ mm			▪ m			<i>Custom-specific units</i>			Free text		
<i>SI units</i>	<i>US units</i>	<i>Imperial units</i>																																									
▪ STon	▪ lb	impGal																																									
▪ t	▪ UsGal																																										
▪ kg	▪ ft ³																																										
▪ cm ³	▪ ft																																										
▪ dm ³	▪ in																																										
▪ m ³																																											
▪ hl																																											
▪ l																																											
▪ %																																											
▪ mm																																											
▪ m																																											
<i>Custom-specific units</i>																																											
Free text																																											
Factory setting	%																																										

Free text 

Navigation	 Application → Sensor → Linearization → Free text
User entry	Character string comprising numbers, letters and special characters (32)
Factory setting	Free text

Level linearized

Navigation	 Application → Sensor → Linearization → Level linearized
Description	Displays the linearized level.
User interface	Signed floating-point number
Factory setting	0 %

Maximum value



Navigation	Application → Sensor → Linearization → Maximum value
Description	Linearized value corresponding to a level of 100 %.
User entry	-200 000 to 200 000.0 %
Factory setting	100.0 %

Diameter



Navigation	Application → Sensor → Linearization → Diameter
Description	Diameter of the spherical tank or horizontal cylinder tank.
User entry	0.001 to 125 000 mm
Factory setting	When the Empty calibration function is performed, the value in the Diameter parameter is automatically configured. Although manual adjustment of the value is possible here, changing the diameter does not affect the Empty calibration function.

Intermediate height



Navigation	Application → Sensor → Linearization → Intermed. height
Description	Height of the pyramid, conical or angled bottom
User entry	0 to 125 000 mm
Factory setting	0 mm

Table mode



Navigation	Application → Sensor → Linearization → Table mode
Description	<p>Defines the editing mode of the linearization table.</p> <p>Note:</p> <p>DeviceCare and FieldCare contain a graphical tool for the easy creation of a linearization table.</p> <p>Device Care: "Additional functions" -> "Linearization table"</p> <p>FieldCare: "Device Operation" -> "Device Functions" -> "Additional functions" -> "Linearization table"</p>

Selection	<ul style="list-style-type: none"> ■ Manual ■ Semiautomatic * ■ Clear table ■ Sort table *
Factory setting	Manual
Additional information	<ul style="list-style-type: none"> ■ Manual: Enter the level and the associated linearized value manually for each table point. ■ Semiautomatic: The level is measured by the device for each table point. Enter the associated linearized value manually. ■ Clear table: Deletes the existing linearization table. ■ Sort table: Rearranges the linearization points into an ascending order.

Table number


Navigation	Application → Sensor → Linearization → Table number
Description	Enter or change the table point.
User entry	1 to 32
Factory setting	1

Level


Navigation	Application → Sensor → Linearization → Level
Description	Enter level value of the table point (value before linearization).
User entry	Signed floating-point number
Factory setting	0 %

Level

Navigation	Application → Sensor → Linearization → Level
Description	Displays measured level (value before linearization). This value is transmitted to the table.
User interface	Signed floating-point number
Factory setting	0.0 %

* Visibility depends on order options or device settings

Customer value



Navigation	Application → Sensor → Linearization → Customer value
Description	Enter linearized value for the table point.
User entry	Signed floating-point number
Factory setting	0 %

Activate table



Navigation	Application → Sensor → Linearization → Activate table
Description	<p>Activate or deactivate table. The table can only be activated if the table values:</p> <ul style="list-style-type: none"> - are present in at least 2 value pairs - do not exceed the sensor limits - represent a function which is monotonically ascending or descending
Selection	<ul style="list-style-type: none"> ■ Disable ■ Enable
Factory setting	Disable

CRC linearization table

Navigation	Application → Sensor → Linearization → CRC lin. table
Description	CRC checksum based on the current parameter settings of the linearization table. Can be used to detect changes in the parameter settings.
User interface	0 to 65 535
Factory setting	0

Signal information

Navigation  Application → Sensor → Signal inform.

Signal quality

Navigation  Application → Sensor → Signal inform. → Signal quality

Description Displays the quality of the evaluated level signal.

User interface

- Strong
- Medium
- Weak
- No signal

Factory setting Strong

Absolute echo amplitude


Navigation  Application → Sensor → Signal inform. → Abs. echo ampl.

Description Shows the absolute amplitude of the evaluated level signal.

User interface -150.0 to 32.0 dB

Factory setting 0.0 dB

Relative echo amplitude


Navigation  Application → Sensor → Signal inform. → Relat.echo ampl.

Description Shows the relative amplitude (i.e. the distance to the evaluation curve) of the evaluated level signal.

User interface 0.0 to 150.0 dB

Factory setting 0.0 dB


Sensor cycle time

Navigation  Application → Sensor → Signal inform. → Sens. cycle time



Description Displays the cycle time of the measurement.

User interface	0 to 65 535 ms
Factory setting	0 ms
Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Expert ■ Write access: -


Actual IF gain

Navigation	 Application → Sensor → Signal inform. → Actual IF gain
Description	Displays the actual gain of the intermediate frequency.
User interface	0 to 1 000
Factory setting	0
Additional information	Access: <ul style="list-style-type: none"> ■ Read access: Expert ■ Write access: -

3.3.4 Current output

Navigation   Application → Curr.output

Assign PV

Navigation	 Application → Curr.output → Assign PV
Description	Assign a measured variable to the primary dynamic variable (PV). Additional information: The assigned measured variable is also used by the current output.
Selection	<ul style="list-style-type: none"> ■ Level linearized ■ Distance
Factory setting	Level linearized

Measuring mode current output


Navigation	Application → Curr.output → Output mode
Description	Select curve of current output.
Selection	<ul style="list-style-type: none"> ■ Standard ■ Inverse
Factory setting	Standard

Current range output


Navigation	Application → Curr.output → Current range
Description	<p>Defines the current range used to transmit the measured or calculated value. In brackets are indicated the “low saturation value” and the “high saturation value”. If Measured value ≤ “low saturation”, the output current is set to “low saturation”. If Measured value ≥ “high saturation”, the output current is set to “high saturation”.</p> <p>Note: Currents below 3.6 mA or above 21.5 mA can be used to signal an alarm.</p>
Selection	<ul style="list-style-type: none"> ■ 4...20 mA (4...20.5 mA) ■ 4...20 mA NE (3.8...20.5 mA) ■ 4...20 mA US (3.9...20.8 mA)
Factory setting	4...20 mA NE (3.8...20.5 mA)

Lower range value output


Navigation	Application → Curr.output → Low.range outp
Description	Depending on which variable has been selected as "Process variable output current", define the related lower (4 mA) and upper range values (20 mA).
User entry	Signed floating-point number
Factory setting	0.0 %

Upper range value output


Navigation	Application → Curr.output → Upp.range outp
Description	Depending on which variable has been selected as "Process variable output current", define the related lower (4 mA) and upper range values (20 mA).

User entry Signed floating-point number

Factory setting 100.0 %

Failure behavior current output

Navigation  Application → Curr.output → Failure behav.

Description Defines which current the output assumes in the case of an error.
 Min: < 3.6 mA
 Max: >21.5 mA
 Note: The hardware DIP Switch for alarm current has priority over software setting.

Selection

- Min.
- Max.

Factory setting Min.

Failure current

Navigation  Application → Curr.output → Failure current

Description Enter current output value in alarm condition

User entry 21.5 to 23 mA

Factory setting 22.5 mA

Output current

Navigation  Application → Curr.output → Output curr.

Description Displays the value currently calculated for the current output

User interface 3.59 to 23 mA

Factory setting 3.59 mA

Terminal current

Navigation  Application → Curr.output → Terminal curr.

Description Shows the current value of the current output which is currently measured

User interface 0 to 30 mA

Factory setting 0 mA

4 mA trim value

Navigation  Application → Curr.output → 4 mA trim value

Description Enter the trim value for the 4 mA current output.

Note:
Simulation must be active.

User entry 3 to 5 mA

Factory setting 4 mA

Additional information **Access:**

- Read access: Expert
- Write access: Expert

20 mA trim value

Navigation  Application → Curr.output → 20 mA trim value

Description Enter the trim value for the 20 mA current output.

Note:
Simulation must be active.


User entry 18 to 22 mA

Factory setting 20 mA

Additional information **Access:**

- Read access: Expert
- Write access: Expert


3.3.5 HART output

Navigation  Application → Curr.output


Configuration

Navigation  Application → HART output → Configuration


HART address

Navigation	 Application → HART output → Configuration → HART address
Description	Enter the address to exchange data via the HART protocol.
User entry	0 to 63
Factory setting	0


HART short tag

Navigation	 Application → HART output → Configuration → HART short tag
Description	Defines the short tag for the measuring point. Maximum length: 8 characters Allowed characters: A-Z, 0-9, certain special characters
User entry	Character string comprising numbers, letters and special characters (8)
Factory setting	SHORTTAG


Device tag

Navigation	 Application → HART output → Configuration → Device tag
Description	Enter a unique name for the measuring point to identify the device quickly within the plant.
User entry	Character string comprising numbers, letters and special characters (32)
Factory setting	43

No. of preambles 

Navigation	 Application → HART output → Configuration → No. of preambles
Description	Defines the number of preambles in the HART telegram
User entry	5 to 20
Factory setting	5


Loop current mode 

Navigation	 Application → HART output → Configuration → Loop curr mode
Description	If Loop current mode is disabled, Multi-drop communication mode is activated. Multi-drop is a HART digital communication mode where multiple devices may share the same pair of wires for power and communications. In this mode the output current is fixed.
Selection	<ul style="list-style-type: none"> ■ Disable ■ Enable
Factory setting	Enable


HART output

Navigation   Application → HART output → HART output

Assign PV 


Navigation	 Application → HART output → HART output → Assign PV
Description	Assign a measured variable to the primary dynamic variable (PV). Additional information: The assigned measured variable is also used by the current output.
Selection	<ul style="list-style-type: none"> ■ Level linearized ■ Distance
Factory setting	Level linearized

Primary variable (PV)


Navigation	 Application → HART output → HART output → Primary var (PV)
Description	Shows the current measured value of the primary dynamic variable (PV)
User interface	Signed floating-point number
Factory setting	100.0 %

Assign SV






Navigation	 Application → HART output → HART output → Assign SV
Description	Assign a measured variable to the second dynamic variable (SV).
Selection	<ul style="list-style-type: none"> ■ Level linearized ■ Distance ■ Terminal voltage * ■ Electronics temperature ■ Sensor temperature ■ Absolute echo amplitude ■ Relative echo amplitude ■ Area of incoupling ■ Buildup index * ■ Buildup detected * ■ Foam index * ■ Foam detected * ■ Percent of range ■ Loop current ■ Terminal current * ■ Not used
Factory setting	Distance



Secondary variable (SV)

Navigation	 Application → HART output → HART output → Second.var(SV)
Description	Shows the current measured value of the secondary dynamic variable (SV)
User interface	0 to 410.10498687664 mm
Factory setting	0 mm

* Visibility depends on order options or device settings

Assign TV 	
Navigation	 Application → HART output → HART output → Assign TV
Description	Assign a measured variable to the tertiary dynamic variable (TV).
Selection	<ul style="list-style-type: none"> ■ Level linearized ■ Distance ■ Terminal voltage * ■ Electronics temperature ■ Sensor temperature ■ Absolute echo amplitude ■ Relative echo amplitude ■ Area of incoupling ■ Buildup index * ■ Buildup detected * ■ Foam index * ■ Foam detected * ■ Percent of range ■ Loop current ■ Terminal current * ■ Not used
Factory setting	Absolute echo amplitude

Tertiary variable (TV)	
Navigation	 Application → HART output → HART output → Tertiary var(TV)
Description	Shows the current measured value of the tertiary (third) dynamic variable (TV)
User interface	-150.0 to 0.0 deciBel
Factory setting	-150.0 deciBel


Assign QV 	
Navigation	 Application → HART output → HART output → Assign QV
Description	Assign a measured variable to the quaternary dynamic variable (QV).
Selection	<ul style="list-style-type: none"> ■ Level linearized ■ Distance ■ Terminal voltage * ■ Electronics temperature ■ Sensor temperature ■ Absolute echo amplitude

* Visibility depends on order options or device settings

- Relative echo amplitude
- Area of incoupling
- Buildup index^{*}
- Buildup detected^{*}
- Foam index^{*}
- Foam detected^{*}
- Percent of range
- Loop current
- Terminal current^{*}
- Not used

Factory setting Relative echo amplitude

Quaternary variable (QV)


Navigation  Application → HART output → HART output → Quaterna.var(QV)

Description Shows the current measured value of the quaternary (fourth) dynamic variable (QV)


User interface -150.0 to 0.0 deciBel

Factory setting -150.0 deciBel

Burst configuration

Navigation   Application → HART output → Burst config. 1

Burst mode



Navigation  Application → HART output → Burst config. 1 → Burst mode 1



Description Switch HART burst mode for burst message on

Selection ■ Off
 ■ On

Factory setting Off

* Visibility depends on order options or device settings

Burst command		
Navigation		Application → HART output → Burst config. 1 → Burst command 1
Description	Select the HART command that is sent to the HART master	
Selection	<ul style="list-style-type: none"> ■ Primary variable (PV) ■ Loop Current and Percent of Range ■ Dynamic Variables ■ Device variables with status ■ Device variables ■ Additional device status 	
Factory setting	Loop Current and Percent of Range	

Burst variable 0		
Navigation		Application → HART output → Burst config. 1 → Burst variable 0
Description	For HART command 9 and 33, assign a HART device variable or process variable to burst variable	
Selection	<ul style="list-style-type: none"> ■ Level linearized ■ Distance ■ Electronics temperature ■ Sensor temperature ■ Absolute echo amplitude ■ Relative echo amplitude ■ Area of incoupling ■ Buildup index[*] ■ Buildup detected[*] ■ Foam index[*] ■ Foam detected[*] ■ Terminal voltage[*] ■ Terminal current[*] ■ Percent of range ■ Loop current ■ Primary variable (PV) ■ Secondary variable (SV) ■ Tertiary variable (TV) ■ Quaternary variable (QV) ■ Not used 	
Factory setting	Level linearized	

* Visibility depends on order options or device settings

Burst variable 1**Navigation**

Application → HART output → Burst config. 1 → Burst variable 1

Description

For HART command 9 and 33, assign a HART device variable or process variable to burst variable

Selection

- Level linearized
- Distance
- Electronics temperature
- Sensor temperature
- Absolute echo amplitude
- Relative echo amplitude
- Area of incoupling
- Buildup index *
- Buildup detected *
- Foam index *
- Foam detected *
- Terminal voltage *
- Terminal current *
- Percent of range
- Loop current
- Primary variable (PV)
- Secondary variable (SV)
- Tertiary variable (TV)
- Quaternary variable (QV)
- Not used

Factory setting

Level linearized

Burst variable 2**Navigation**

Application → HART output → Burst config. 1 → Burst variable 2

Description

For HART command 9 and 33, assign a HART device variable or process variable to burst variable

Selection


- Level linearized
- Distance
- Electronics temperature
- Sensor temperature
- Absolute echo amplitude
- Relative echo amplitude
- Area of incoupling
- Buildup index *
- Buildup detected *
- Foam index *
- Foam detected *
- Terminal voltage *
- Terminal current *
- Percent of range

* Visibility depends on order options or device settings

- Loop current
- Primary variable (PV)
- Secondary variable (SV)
- Tertiary variable (TV)
- Quaternary variable (QV)
- Not used

Factory setting Level linearized

Burst variable 3


Navigation  Application → HART output → Burst config. 1 → Burst variable 3

Description For HART command 9 and 33, assign a HART device variable or process variable to burst variable

- Selection**
- Level linearized
 - Distance
 - Electronics temperature
 - Sensor temperature
 - Absolute echo amplitude
 - Relative echo amplitude
 - Area of incoupling
 - Buildup index^{*}
 - Buildup detected^{*}
 - Foam index^{*}
 - Foam detected^{*}
 - Terminal voltage^{*}
 - Terminal current^{*}
 - Percent of range
 - Loop current
 - Primary variable (PV)
 - Secondary variable (SV)
 - Tertiary variable (TV)
 - Quaternary variable (QV)
 - Not used

Factory setting Level linearized

Burst variable 4

Navigation  Application → HART output → Burst config. 1 → Burst variable 4

Description For HART command 33, assign a HART device variable or process variable to burst variable

- Selection**
- Level linearized
 - Distance
 - Electronics temperature

* Visibility depends on order options or device settings

- Sensor temperature
- Absolute echo amplitude
- Relative echo amplitude
- Area of incoupling
- Buildup index^{*}
- Buildup detected^{*}
- Foam index^{*}
- Foam detected^{*}
- Terminal voltage^{*}
- Terminal current^{*}
- Percent of range
- Loop current
- Primary variable (PV)
- Secondary variable (SV)
- Tertiary variable (TV)
- Quaternary variable (QV)
- Not used

Factory setting Not used

Burst variable 5



Navigation Application → HART output → Burst config. 1 → Burst variable 5

Description For HART command 33, assign a HART device variable or process variable to burst variable

- Selection**
- Level linearized
 - Distance
 - Electronics temperature
 - Sensor temperature
 - Absolute echo amplitude
 - Relative echo amplitude
 - Area of incoupling
 - Buildup index^{*}
 - Buildup detected^{*}
 - Foam index^{*}
 - Foam detected^{*}
 - Terminal voltage^{*}
 - Terminal current^{*}
 - Percent of range
 - Loop current
 - Primary variable (PV)
 - Secondary variable (SV)
 - Tertiary variable (TV)
 - Quaternary variable (QV)
 - Not used

Factory setting Not used

* Visibility depends on order options or device settings

Burst variable 6**Navigation**

Application → HART output → Burst config. 1 → Burst variable 6

Description

For HART command 33, assign a HART device variable or process variable to burst variable

Selection

- Level linearized
- Distance
- Electronics temperature
- Sensor temperature
- Absolute echo amplitude
- Relative echo amplitude
- Area of incoupling
- Buildup index^{*}
- Buildup detected^{*}
- Foam index^{*}
- Foam detected^{*}
- Terminal voltage^{*}
- Terminal current^{*}
- Percent of range
- Loop current
- Primary variable (PV)
- Secondary variable (SV)
- Tertiary variable (TV)
- Quaternary variable (QV)
- Not used

Factory setting

Not used

Burst variable 7**Navigation**

Application → HART output → Burst config. 1 → Burst variable 7

Description

For HART command 33, assign a HART device variable or process variable to burst variable

Selection


- Level linearized
- Distance
- Electronics temperature
- Sensor temperature
- Absolute echo amplitude
- Relative echo amplitude
- Area of incoupling
- Buildup index^{*}
- Buildup detected^{*}
- Foam index^{*}
- Foam detected^{*}
- Terminal voltage^{*}
- Terminal current^{*}
- Percent of range
- Loop current
- Primary variable (PV)

* Visibility depends on order options or device settings

- Secondary variable (SV)
- Tertiary variable (TV)
- Quaternary variable (QV)
- Not used

Factory setting Not used

Burst trigger mode

Navigation  Application → HART output → Burst config. 1 → Trigger mode


Description Select the event that triggers the burst message

Selection

- Continuous
- Window^{*}
- Rising^{*}
- Falling^{*}
- On change

Factory setting Continuous

Burst trigger level


Navigation  Application → HART output → Burst config. 1 → Trigger level

Description Enter the burst trigger value that determines together with the option selected in "Burst trigger mode" parameter the time of burst message

User entry Signed floating-point number

Factory setting 2.0E-38

Min. update period

Navigation  Application → HART output → Burst config. 1 → Min. upd. per.

Description Enter the minimum time span between two burst responses of one burst message

User entry Positive integer

Factory setting 1 000 ms

* Visibility depends on order options or device settings

Max. update period



Navigation	Application → HART output → Burst config. 1 → Max. upd. per.
Description	Enter the maximum time span between two burst responses of one burst message
User entry	Positive integer
Factory setting	2 000 ms

Information

Navigation Application → HART output → Information

Device ID

Navigation	Application → HART output → Information → Device ID
Description	Shows the device ID for identifying the device in a HART network
User interface	Positive integer
Factory setting	123 456

Device type

Navigation	Application → HART output → Information → Device type
Description	Displays the device type with which the device is registered with the HART FieldComm Group.
User interface	0 to 65 535
Factory setting	4 550


Device revision

Navigation	Application → HART output → Information → Device revision
Description	Displays the device revision with which the device is registered with the HART FieldComm Group.

User interface 0 to 255

Factory setting 1

HART short tag

Navigation  Application → HART output → Information → HART short tag

Description Defines the short tag for the measuring point.


Maximum length: 8 characters

Allowed characters: A-Z, 0-9, certain special characters

User entry Character string comprising numbers, letters and special characters (8)

Factory setting SHORTTAG

HART revision


Navigation  Application → HART output → Information → HART revision

Description Displays the revision of the HART protocol for the device.

User interface 5 to 7

Factory setting 7

HART descriptor

Navigation  Application → HART output → Information → HART descriptor

Description Use this function to define a description for the measuring point.

Maximum length: 16 characters

Allowed characters: A-Z, 0-9, certain special characters

User entry Character string comprising numbers, letters and special characters (16)

Factory setting 43

HART message

**Navigation**

Application → HART output → Information → HART message

Description

Use this function to define a HART message which is sent via the HART protocol when requested by the master.

Maximum length: 32 characters

Allowed characters: A-Z, 0-9, certain special characters

User entry

Character string comprising numbers, letters and special characters (32)

Factory setting

43

HART date code

**Navigation**

Application → HART output → Information → HART date code

Description

Enter date of the last configuration change. Use this format yyyy-mm-dd

User entry

Character string comprising numbers, letters and special characters (10)

Factory setting


2009-07-20


3.4 System

Navigation  System


3.4.1 Device management

Navigation  System → Device manag.


Device tag	
-------------------	---

Navigation	 System → Device manag. → Device tag
Description	Enter a unique name for the measuring point to identify the device quickly within the plant.
User entry	Character string comprising numbers, letters and special characters (32)
Factory setting	43

Locking status	
-----------------------	--


Navigation	 System → Device manag. → Locking status
Description	<p>Indicates the type of locking.</p> <p>"Safety locked" (SW) Unlock the device by entering the appropriate access code in "Enter safety unlocking code".</p> <p>"Temporarily locked" (SW) The device is temporarily locked by processes in the device (e.g. data upload/download, reset). The device will automatically be unlocked after completion of these processes.</p>
User interface	<ul style="list-style-type: none"> ■ Safety locked ■ Temporarily locked

Configuration counter

Navigation	 System → Device manag. → Config. counter
Description	<p>Displays the counter for changes to the device parameters.</p> <p>Additional information:</p> <ul style="list-style-type: none"> - If the value for a static parameter is changed when optimizing or configuring the parameter, the counter is incremented by 1. This is to enable tracking different parameter versions. - When multiple parameters are changed simultaneously, e.g. when loading parameters into the device from an external source such as FieldCare, the counter may display a higher value. The counter cannot be reset, nor is it reset to a default value on performing a device reset. - Once the counter has reached the value 65535, it restarts at 0.
User interface	0 to 65 535
Factory setting	0

Reset device




Navigation	 System → Device manag. → Reset device
Description	Reset the device configuration - either entirely or in part - to a defined state
Selection	<ul style="list-style-type: none"> ■ Cancel ■ To fieldbus defaults ** ■ To factory defaults * ■ To delivery settings * ■ Restart device
Factory setting	Cancel

3.4.2 User management

Navigation  System → User manag.

User role

Navigation	 System → User manag. → User role
Description	Shows the access authorization to the parameters via the operating tool

** Visibility depends on communication


* Visibility depends on order options or device settings

User interface

- Operator
- Maintenance
- Expert
- Production
- Development

Factory setting Maintenance

Password

Navigation  System → User manag. → Password

Description Enter the password for the "Maintenance" user role to get access to the functionality of this role.

User entry Character string comprising numbers, letters and special characters (16)

Factory setting

Enter access code



Navigation  System → User manag. → Ent. access code

Description For authorized service personnel only.

User entry 0 to 9999

Factory setting 0

Status password entry

Navigation   System → User manag. → Status pw entry



Description Use this function to display the status of the password verification.

User interface

- -----
- Wrong password
- Password rule violated
- Password accepted
- Permission denied
- Confirm PW mismatch
- Reset password accepted
- Invalid user role
- Wrong sequence of entry

Factory setting -----

New password 

Navigation   System → User manag. → New password

Description Define the new "Maintenance" password.
A new password is valid after it has been confirmed within the "Confirm new password" parameter.
Any valid password consists of 4 to 16 characters and can contain letters and numbers.

User entry Character string comprising numbers, letters and special characters (16)

Factory setting

Confirm new password 

Navigation   System → User manag. → Confirm password

Description Enter the new password again to confirm.

User entry Character string comprising numbers, letters and special characters (16)

Factory setting


Reset password

Navigation  System → User manag. → Reset password

Description Enter a code to reset the current "Maintenance" password.
The code is delivered by your local support.

User entry Character string comprising numbers, letters and special characters (16)

Factory setting

Old password 


Navigation   System → User manag. → Old password

Description Enter the current password, to subsequently change the existing password.

User entry Character string comprising numbers, letters and special characters (16)

Factory setting


Status password entry

Navigation	 System → User manag. → Status pw entry
Description	Use this function to display the status of the password verification.
User interface	<ul style="list-style-type: none"> ■ ----- ■ Wrong password ■ Password rule violated ■ Password accepted ■ Permission denied ■ Confirm PW mismatch ■ Reset password accepted ■ Invalid user role ■ Wrong sequence of entry
Factory setting	-----

3.4.3 Bluetooth configuration

Navigation  System → Bluetooth conf.


Bluetooth activation

Navigation	 System → Bluetooth conf. → Bluetooth active
Description	If Bluetooth is deactivated, it can only be reactivated via the display or the operating tool. Reactivating via the SmartBlue app is not possible.
Selection	<ul style="list-style-type: none"> ■ Disable ■ Enable
Factory setting	Enable


3.4.4 Display

Navigation  System → Display

Language

Navigation	 System → Display → Language
Description	Set display language
Selection	<ul style="list-style-type: none"> ■ English ■ Deutsch * ■ Français * ■ Español * ■ Italiano * ■ Nederlands * ■ Portuguesa * ■ Polski * ■ русский язык (Russian) * ■ Svenska * ■ Türkçe * ■ 中文 (Chinese) * ■ 日本語 (Japanese) * ■ 한국어 (Korean) * ■ Bahasa Indonesia * ■ čeština (Czech) *
Factory setting	English

Format display

Navigation	 System → Display → Format display
Description	Select how measured values are shown on the display
Selection	<ul style="list-style-type: none"> ■ 1 value, max. size ■ Bargraph ■ 2 values
Factory setting	1 value, max. size

* Visibility depends on order options or device settings

Value 1 display



Navigation	System → Display → Value 1 display
Description	Select the measured value that is shown on the local display
Selection	<ul style="list-style-type: none"> ■ Level linearized ■ Distance ■ Absolute echo amplitude ■ Relative echo amplitude ■ Area of incoupling ■ Current output ■ Buildup index * ■ Foam index * ■ Terminal voltage ■ Electronics temperature ■ Sensor temperature ■ Unfiltered distance
Factory setting	Level linearized

Decimal places 1



Navigation	System → Display → Decimal places 1
Description	This selection does not affect the measurement and calculation accuracy of the device.
Selection	<ul style="list-style-type: none"> ■ x ■ x.X ■ x.XX ■ x.XXX ■ x.XXXX
Factory setting	x.XX

Value 2 display




Navigation	System → Display → Value 2 display
Description	Select the measured value that is shown on the local display
Selection	<ul style="list-style-type: none"> ■ None ■ Level linearized ■ Distance ■ Absolute echo amplitude ■ Relative echo amplitude ■ Area of incoupling

* Visibility depends on order options or device settings

- Buildup index^{*}
- Foam index^{*}
- Terminal voltage
- Electronics temperature
- Sensor temperature
- Current output
- Unfiltered distance

Factory setting Distance

Decimal places 2

Navigation  System → Display → Decimal places 2

Description This selection does not affect the measurement and calculation accuracy of the device.

- Selection**
- x
 - x.x
 - x.xx
 - x.xxx
 - x.xxxx

Factory setting x

Rotation display

Navigation  System → Display → Rotation display

Description Select rotation angle of the display text to optimize local display readability.

- Selection**
- Auto
 - 0 degree
 - 90 degree
 - 180 degree
 - 270 degree

Factory setting 0 degree

Color scheme

Navigation  System → Display → Color scheme

Description Select the preferred color scheme.


* Visibility depends on order options or device settings

Selection	<ul style="list-style-type: none"> ▪ Light ▪ Dark
Factory setting	Dark


3.4.5 Geolocation

Navigation  System → Geolocation


Process Unit Tag

Navigation	 System → Geolocation → Process Unit Tag
Description	Enter the process unit in which the device is installed.
User entry	Character string comprising numbers, letters and special characters (32)
Factory setting	Process Unit Tag


Location Description

Navigation	 System → Geolocation → Location Descr.
Description	Use this function to enter a description of the location so that the device can be located in the plant.
User entry	Character string comprising numbers, letters and special characters (32)
Factory setting	somewhere


Longitude

Navigation	 System → Geolocation → Longitude
Description	Use this function to enter the longitude coordinates that describe the device location.
User entry	-180 to 180 °
Factory setting	0 °


Latitude 

Navigation	 System → Geolocation → Latitude
Description	Use this function to enter the latitude coordinates that describe the device location.
User entry	-90 to 90 °
Factory setting	0 °

Altitude 

Navigation	 System → Geolocation → Altitude
Description	Use this function to enter the altitude data that describe the device location.
User entry	Signed floating-point number
Factory setting	0 m


Location method 

Navigation	 System → Geolocation → Location method
Description	Use this function to select the data format for specifying the geographic location. The codes for specifying the location are based on the US National Marine Electronics Association (NMEA) Standard NMEA 0183.
Selection	<ul style="list-style-type: none"> ■ No fix ■ GPS or Standard Positioning Service fix ■ Differential GPS fix ■ Precise positioning service (PPS) fix ■ Real Time Kinetic (RTK) fixed solution ■ Real Time Kinetic (RTK) float solution ■ Estimated dead reckoning ■ Manual input mode ■ Simulation Mode
Factory setting	No fix


3.4.6 Information

Navigation   System → Information


Device name

Navigation	 System → Information → Device name
Description	Use this function to display the device name. It can also be found on the nameplate.
User interface	Character string comprising numbers, letters and special characters
Factory setting	43


Manufacturer

Navigation	 System → Information → Manufacturer
Description	Displays the manufacturer.
User interface	Character string comprising numbers, letters and special characters
Factory setting	Endress+Hauser

Serial number

Navigation	 System → Information → Serial number
Description	The serial number is a unique alphanumeric code identifying the device. It is printed on the nameplate. In combination with the Operations app it allows to access all device related documentation.
User interface	Character string comprising numbers, letters and special characters
Factory setting	AAFFFFAAFFF

Order code

Navigation	 System → Information → Order code
Description	Shows the device order code.

User interface Character string comprising numbers, letters and special characters

Factory setting - none -

Firmware version

Navigation  System → Information → Firmware version

Description Displays the device firmware version installed.

User interface Character string comprising numbers, letters and special characters

Factory setting 01.00

Hardware version

Navigation  System → Information → Hardware version

User interface Character string comprising numbers, letters and special characters

Factory setting 01.00.00

Extended order code 1

Navigation  System → Information → Ext. order cd. 1

Description The extended order code is an alphanumeric code containing all information to identify the device and its options.

User interface Character string comprising numbers, letters and special characters

Extended order code 2

Navigation  System → Information → Ext. order cd. 2

Description The extended order code is an alphanumeric code containing all information to identify the device and its options.

User interface Character string comprising numbers, letters and special characters

Factory setting -

Extended order code 3



Navigation	System → Information → Ext. order cd. 3
Description	The extended order code is an alphanumeric code containing all information to identify the device and its options.
User interface	Character string comprising numbers, letters and special characters
Factory setting	-


XML build number

Navigation	System → Information → XML build no.
User interface	Positive integer
Factory setting	134

Checksum

Navigation	System → Information → Checksum
Description	Checksum for Firmware version.
User interface	Positive integer
Factory setting	0


3.4.7 Additional information

Navigation  System → Additional info


Sensor

Navigation  System → Additional info → Sensor


Serial number

Navigation	 System → Additional info → Sensor → Serial number
Description	Shows the serial number of the module
User interface	Character string comprising numbers, letters and special characters
Factory setting	AAFFFAAFF


Firmware version

Navigation	 System → Additional info → Sensor → Firmware version
Description	Displays the firmware version of the module.
User interface	Positive integer
Factory setting	0


Build no. software

Navigation	 System → Additional info → Sensor → Build no. softw.
Description	Shows the build number of the module firmware
User interface	0 to 65 535
Factory setting	0

Hardware version

Navigation	 System → Additional info → Sensor → Hardware version
Description	Displays the hardware version of the module.
User interface	Character string comprising numbers, letters and special characters
Factory setting	- none -


Checksum

Navigation	 System → Additional info → Sensor → Checksum
Description	Checksum for Firmware version.
User interface	Positive integer
Factory setting	0


Electronics

Navigation   System → Additional info → Electronics

Serial number


Navigation	 System → Additional info → Electronics → Serial number
Description	Shows the serial number of the module
User interface	Character string comprising numbers, letters and special characters
Factory setting	AAFFFFAAFF

Firmware version

Navigation	 System → Additional info → Electronics → Firmware version
Description	Displays the firmware version of the module.
User interface	Positive integer

Factory setting 0

Build no. software

Navigation  System → Additional info → Electronics → Build no. softw.

Description Shows the build number of the module firmware

User interface 0 to 65 535

Factory setting 0

Hardware version



Navigation  System → Additional info → Electronics → Hardware version

Description Displays the hardware version of the module.

User interface Character string comprising numbers, letters and special characters

Factory setting - none -

Display/Bluetooth

Navigation   System → Additional info → Displ./Bluetooth

Serial number


Navigation  System → Additional info → Displ./Bluetooth → Serial number

Description Shows the serial number of the module


User interface Character string comprising numbers, letters and special characters

Factory setting AAAAAFAAFF


Firmware version

Navigation	 System → Additional info → Displ./Bluetooth → Firmware version
Description	Displays the firmware version of the module.
User interface	Positive integer
Factory setting	0

Build no. software

Navigation	 System → Additional info → Displ./Bluetooth → Build no. softw.
Description	Shows the build number of the module firmware
User interface	0 to 65 535
Factory setting	0


Hardware version

Navigation	 System → Additional info → Displ./Bluetooth → Hardware version
Description	Displays the hardware version of the module.
User interface	Character string comprising numbers, letters and special characters
Factory setting	- none -

3.4.8 Software configuration

Navigation   System → Softw. config.


CRC device configuration

Navigation	 System → Softw. config. → CRC device conf.
Description	CRC device configuration based on current settings of safety relevant parameters. The CRC device configuration is unique and can be used to detect changes in safety relevant parameter settings.

User interface 0 to 65 535

Factory setting 65 535

Activate SW option

Navigation  System → Softw. config. → Activate SW opt.

Description Enter the application package code or code of another re-ordered functionality to enable it

User entry Positive integer

Factory setting 0

Software option overview

Navigation  System → Softw. config. → SW option overv.

Description Shows all enabled software options

User interface

- WHG
- Heartbeat Verification
- Heartbeat Monitoring *
- Bluetooth

* Visibility depends on order options or device settings



www.addresses.endress.com
