

# Operating Instructions

## Proservo NMS81

### Tank Gauging





A0023555

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# 1 About this document

## 1.1 Document function

These Operating Instructions contain all the information required in the various life cycle phases of the device: from product identification, incoming acceptance and storage, to installation, connection, operation and commissioning, through to troubleshooting, maintenance and disposal.

## 1.2 Symbols

### 1.2.1 Safety symbols



This symbol alerts you to a dangerous situation. Failure to avoid this situation will result in serious or fatal injury.



This symbol alerts you to a dangerous situation. Failure to avoid this situation can result in serious or fatal injury.



This symbol alerts you to a dangerous situation. Failure to avoid this situation can result in minor or medium injury.



This symbol contains information on procedures and other facts which do not result in personal injury.

### 1.2.2 Electrical symbols



Alternating current



Direct current and alternating current



Direct current



Ground connection

A grounded terminal which, as far as the operator is concerned, is grounded via a grounding system.

#### **Protective earth (PE)**

Ground terminals that must be connected to ground prior to establishing any other connections.

The ground terminals are located on the interior and exterior of the device:

- Interior ground terminal: protective earth is connected to the mains supply.
- Exterior ground terminal: device is connected to the plant grounding system.

### 1.2.3 Tool symbols



Phillips head screwdriver





Flat blade screwdriver



Torx screwdriver



Allen key



Open-ended wrench

#### 1.2.4 Symbols for certain types of information and graphics



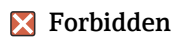
##### **Permitted**

Procedures, processes or actions that are permitted



##### **Preferred**

Procedures, processes or actions that are preferred



##### **Forbidden**

Procedures, processes or actions that are forbidden



##### **Tip**

Indicates additional information



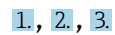
Reference to documentation



Reference to graphic



Notice or individual step to be observed



##### **1., 2., 3.**

Series of steps



Result of a step



Visual inspection



Operation via operating tool



Write-protected parameter

**1, 2, 3, ...**

Item numbers

**A, B, C, ...**

Views



##### **Safety instructions**

Observe the safety instructions contained in the associated Operating Instructions




##### **Temperature resistance of the connection cables**

Specifies the minimum value of the temperature resistance of the connection cables

## 1.3 Documentation

The following documentation types are available in the Downloads area of the Endress+Hauser website ([www.endress.com/downloads](http://www.endress.com/downloads)):

 For an overview of the scope of the associated Technical Documentation, refer to the following:

- *Device Viewer* ([www.endress.com/deviceviewer](http://www.endress.com/deviceviewer)): Enter the serial number from the nameplate
- *Endress+Hauser Operations app*: Enter serial number from nameplate or scan matrix code on nameplate.

### 1.3.1 Technical Information (TI)

#### Planning aid

The document contains all the technical data on the device and provides an overview of the accessories and other products that can be ordered for the device.

### 1.3.2 Brief Operating Instructions (KA)

#### Guide that takes you quickly to the 1st measured value

The Brief Operating Instructions contain all the essential information from incoming acceptance to initial commissioning.

### 1.3.3 Operating Instructions (BA)

The Operating Instructions contain all the information that is required in various phases of the life cycle of the device: from product identification, incoming acceptance and storage, to mounting, connection, operation and commissioning through to troubleshooting, maintenance and disposal.

It also contains a detailed explanation of each individual parameter in the operating menu (except the **Expert** menu). The description is aimed at those who work with the device over the entire life cycle and perform specific configurations.

### 1.3.4 Description of Device Parameters (GP)

The Description of Device Parameters provides a detailed explanation of each individual parameter in the 2nd part of the operating menu: the **Expert** menu. It contains all the device parameters and allows direct access to the parameters by entering a specific code. The description is aimed at those who work with the device over the entire life cycle and perform specific configurations.

### 1.3.5 Safety Instructions (XA)

Depending on the approval, the following Safety Instructions (XA) are supplied with the device. They are an integral part of the Operating Instructions.

 The nameplate indicates the Safety Instructions (XA) that are relevant to the device.

### 1.3.6 Installation instructions (EA)

Installation Instruction are used to replace a faulty unit with a functioning unit of the same type.

## 1.4 Registered trademarks

#### Modbus®

Registered trademark of SCHNEIDER AUTOMATION, INC.

## 2 Basic safety instructions

### 2.1 Requirements for the personnel

The personnel for installation, commissioning, diagnostics and maintenance must fulfill the following requirements:

- ▶ Trained, qualified specialists must have a relevant qualification for this specific function and task.
- ▶ Are authorized by the plant owner/operator.
- ▶ Are familiar with federal/national regulations.
- ▶ Before starting work, read and understand the instructions in the manual and supplementary documentation as well as the certificates (depending on the application).
- ▶ Follow instructions and comply with basic conditions.

The operating personnel must fulfill the following requirements:

- ▶ Are instructed and authorized according to the requirements of the task by the facility's owner-operator.
- ▶ Follow the instructions in this manual.

### 2.2 Intended use

#### **Application and measured materials**

Depending on the version ordered, the measuring device can also measure potentially explosive, flammable, poisonous and oxidizing media.

Measuring devices for use in hazardous areas, in hygienic applications or in applications where there is an increased risk due to process pressure, are labeled accordingly on the nameplate.

To ensure that the measuring device remains in proper condition for the operation time:

- ▶ Only use the measuring device in full compliance with the data on the nameplate and the general conditions listed in the Operating Instructions and supplementary documentation.
- ▶ Check the nameplate to verify if the device ordered can be put to its intended use in the approval-related area (e.g. explosion protection, pressure vessel safety).
- ▶ Use the measuring device only for media against which the process-wetted materials are adequately resistant.
- ▶ If the measuring device is not operated at atmospheric temperature, compliance with the relevant basic conditions specified in the associated device documentation is absolutely essential.
- ▶ Protect the measuring device permanently against corrosion from environmental influences.
- ▶ Observe the limit values in the "Technical Information".

The manufacturer is not liable for damage caused by improper or non-designated use.

#### **Residual risk**

During operation the sensor may assume a temperature near the temperature of the measured material.

Danger of burns due to heated surfaces!

- ▶ For high process temperatures: Install protection against contact in order to prevent burns.

## 2.3 Workplace safety

For work on and with the device:

- ▶ Wear the required personal protective equipment according to federal/national regulations.

## 2.4 Operational safety

Risk of injury!

- ▶ Operate the device only if it is in proper technical condition, free from errors and faults.
- ▶ The operator is responsible for interference-free operation of the device.

### Modifications to the device

Unauthorized modifications to the device are not permitted and can lead to unforeseeable dangers:

- ▶ If modifications are nevertheless required, consult with the manufacturer.

### Repair

To ensure continued operational safety and reliability:

- ▶ Carry out repairs on the device only if they are expressly permitted.
- ▶ Observe federal/national regulations pertaining to the repair of an electrical device.
- ▶ Use only original spare parts and accessories from the manufacturer.

### Hazardous area

To eliminate danger to persons or the facility when the device is used in the hazardous area (e.g. explosion protection):

- ▶ Check the nameplate to verify if the device ordered can be put to its intended use in the hazardous area.
- ▶ Observe the specifications in the separate supplementary documentation that is an integral part of these instructions.

## 2.5 Product safety

This measuring device is designed in accordance with good engineering practice to meet state-of-the-art safety requirements, has been tested, and left the factory in a condition in which it is safe to operate. It meets the general safety standards and legal requirements.

### NOTICE

#### Loss of degree of protection by opening of the device in humid environments

- ▶ If the device is opened in a humid environment, the degree of protection indicated on the nameplate is no longer valid. This may also impair the safe operation of the device.

### 2.5.1 CE mark

The measuring system meets the legal requirements of the applicable EU directives. These are listed in the corresponding EU Declaration of Conformity together with the standards applied.

The manufacturer confirms successful testing of the device by affixing to it the CE mark.

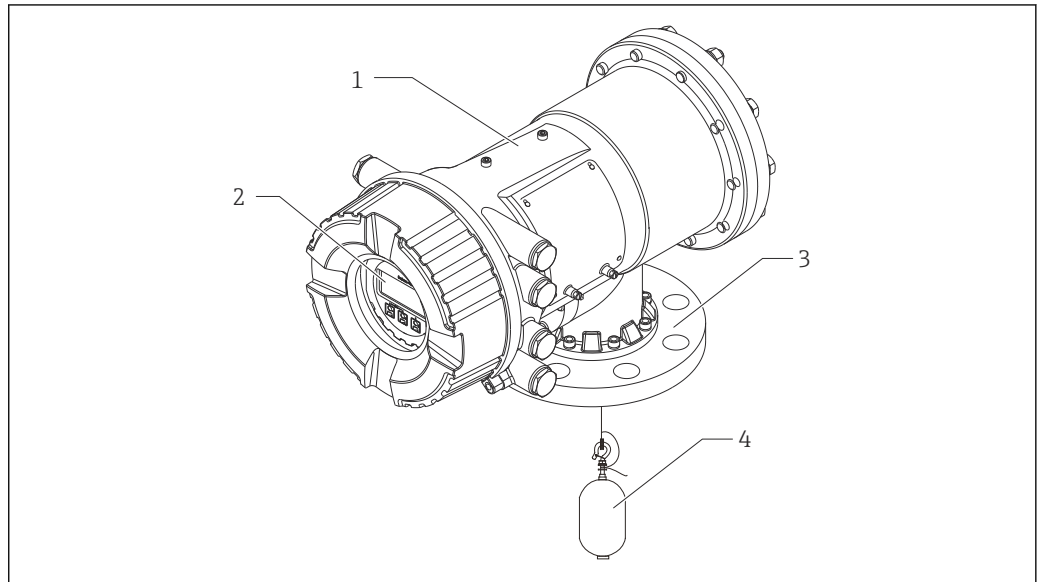
### 2.5.2 EAC conformity

The measuring system meets the legal requirements of the applicable EAC guidelines. These are listed in the corresponding EAC Declaration of Conformity along with the standards applied.

The manufacturer confirms successful testing of the device by affixing to it the EAC mark.

### 3 Product description

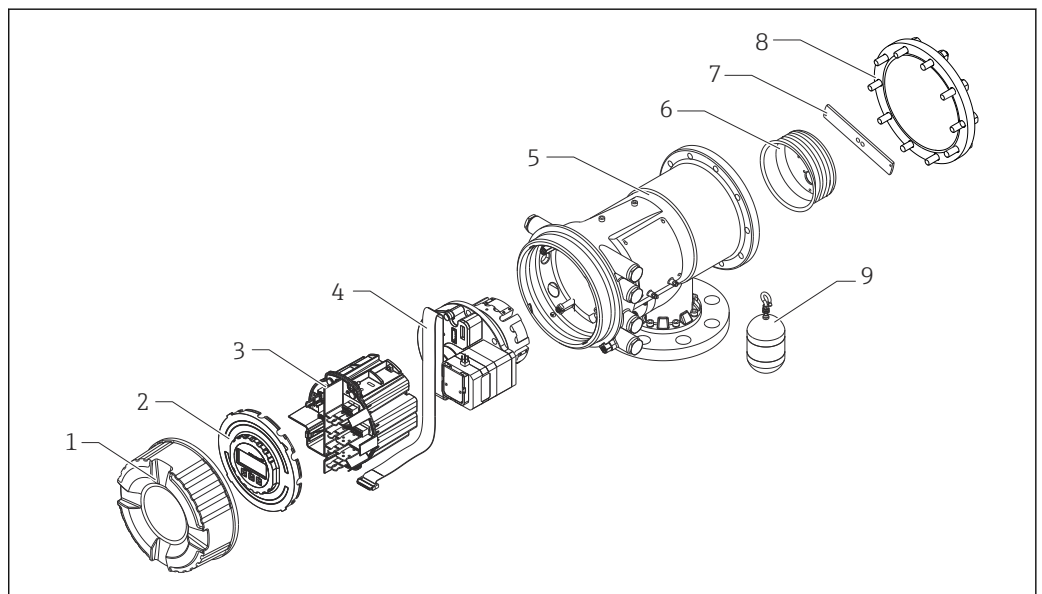
#### 3.1 Product design



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1 Design of Proservo NMS81

- 1 Housing
- 2 Display and operating module (can be operated without opening the cover)
- 3 Process connection (Flange)
- 4 Displacer



A0028666

2 Configuration of NMS81


- 1 Front cover
- 2 Display
- 3 Modules
- 4 Sensor unit (detector unit and cable)
- 5 Housing
- 6 Wire drum
- 7 Bracket
- 8 Housing cover
- 9 Displacer

## 4 Incoming acceptance and product identification

### 4.1 Incoming acceptance

Upon receipt of the goods check the following:


- Are the order codes on the delivery note and the product sticker identical?
- Are the goods undamaged?
- Do the nameplate data match the ordering information on the delivery note?
- If required (see nameplate): Are the Safety Instructions (XA) enclosed?

 If one of these conditions is not satisfied, contact your Endress+Hauser Sales Center.

### 4.2 Product identification

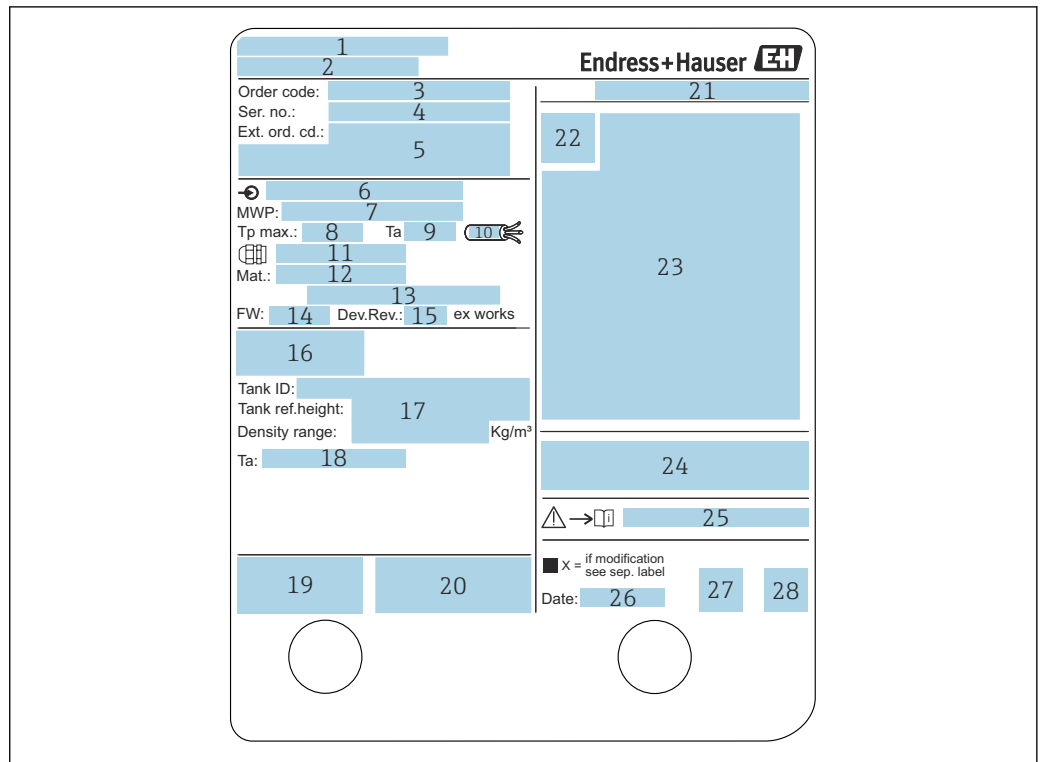
The following options are available for identification of the device:

- Nameplate specifications
- Enter the serial number from the nameplate in the *Device Viewer* ([www.endress.com/deviceviewer](http://www.endress.com/deviceviewer)): all the information about the device and an overview of the Technical Documentation supplied with the device are displayed.
- Enter the serial number on the nameplate into the *Endress+Hauser Operations App* or scan the 2-D matrix code (QR code) on the nameplate with the *Endress+Hauser Operations App*: all the information about the device and the technical documentation pertaining to the device is displayed.

 For an overview of the scope of the associated Technical Documentation, refer to the following:

- *Device Viewer* ([www.endress.com/deviceviewer](http://www.endress.com/deviceviewer)): Enter the serial number from the nameplate
- *Endress+Hauser Operations app*: Enter serial number from nameplate or scan matrix code on nameplate.

### 4.2.1 Nameplate



A0027791

#### 3 Nameplate

- 1 Manufacturer address
- 2 Device name
- 3 Order code
- 4 Serial number
- 5 Extended order code
- 6 Supply voltage
- 7 Maximum process pressure
- 8 Maximum process temperature
- 9 Permitted ambient temperature ( $T_a$ )
- 10 Temperature resistance of cable
- 11 Thread for cable entry
- 12 Material in contact with process
- 13 Not used
- 14 Firmware version
- 15 Device revision
- 16 Metrology certification numbers
- 17 Customized parametrization data
- 18 Ambient temperature range
- 19 CE mark / RCM mark
- 20 Additional information on the device version
- 21 Ingress protection
- 22 Certificate symbol
- 23 Data concerning the Ex approval
- 24 General certificate of approval
- 25 Associated Safety Instructions (XA)
- 26 Manufacturing date
- 27 China RoHS mark
- 28 QR code for the Endress+Hauser Operations App

### 4.2.2 Manufacturer address

Endress+Hauser Yamanashi Co., Ltd.  
 406-0846  
 862-1 Mitsukunugi, Sakaigawa-cho, Fuefuki-shi, Yamanashi

## 4.3 Storage and transport

### 4.3.1 Storage conditions

- Storage temperature: -50 to +80 °C (-58 to +176 °F)
- Store the device in its original packaging.

### 4.3.2 Transport

**⚠ CAUTION**

**Risk of injury**

- ▶ Transport the measuring device to the measuring point in its original packaging.
- ▶ Take into account the mass center of the device in order to avoid unintended tilting.
- ▶ Comply with the safety instructions, transport conditions for devices over 18 kg (39.6 lb) (IEC 61010).


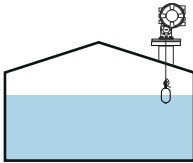

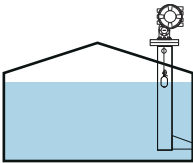

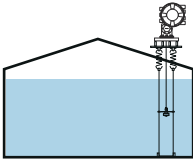


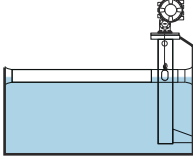



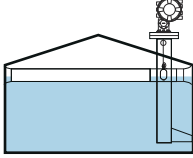



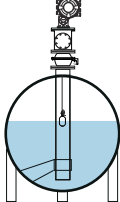



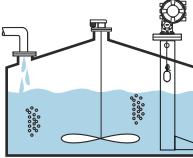

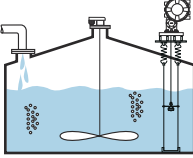



## 5 Installation


### 5.1 Requirements

#### 5.1.1 Type of tanks

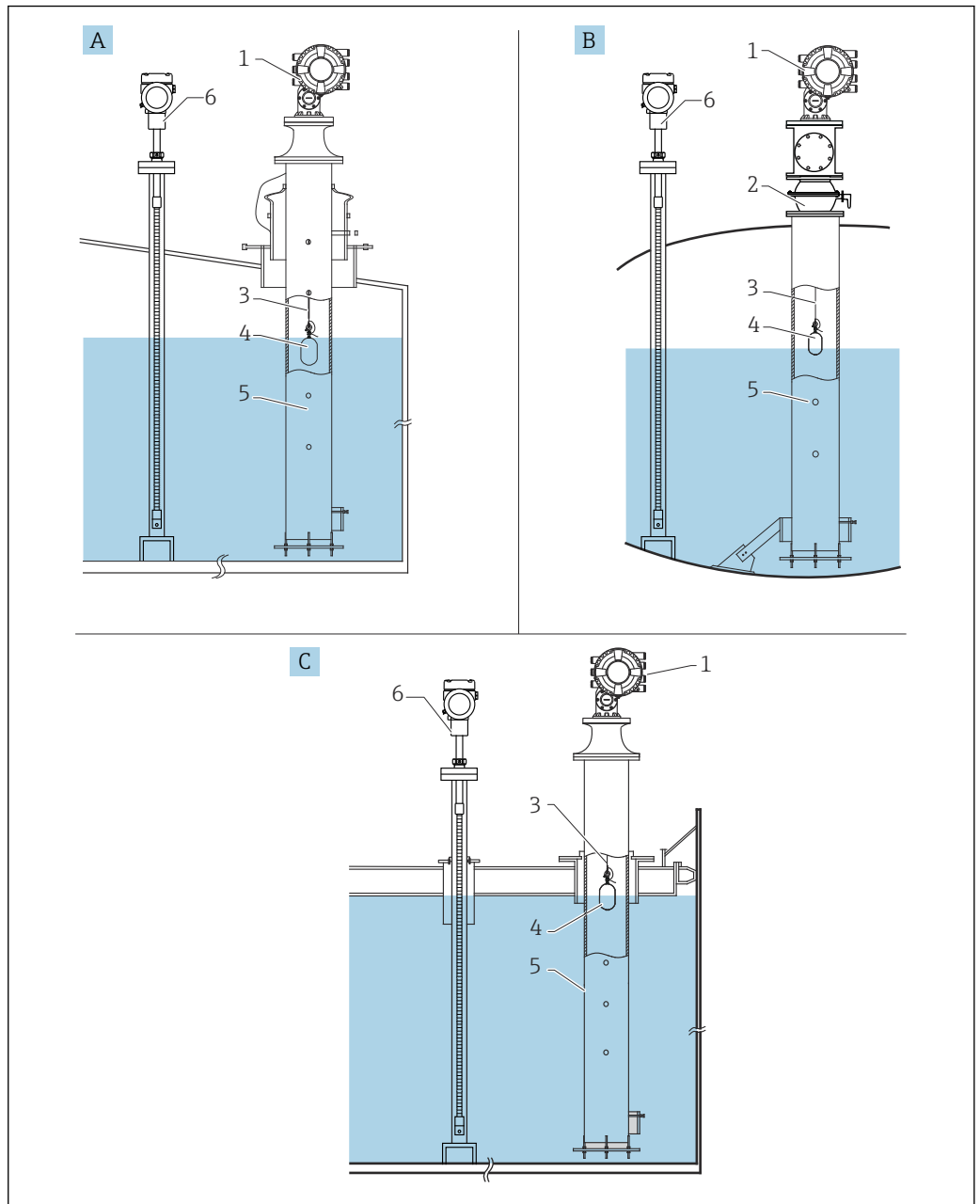
Depending on the type of tank and application, different installation procedures are recommended for NMS8x.

Type of tanks	Without guide system	With stilling well	With guide wires
Fixed roof tank	 	 	 
Floating roof tank		 	
Covered floating roof tank		 	
Pressurized or bullet tank		 	
Tank with agitator or heavy turbulence		 	 

 A stilling well is required in a floating roof tank and a covered floating roof tank.

- Guide wires cannot be installed in a floating roof tank. When the measuring wire is exposed to free space, it may break due to an external shock.
- Installing guide wires is not allowed in pressurized tanks because the wires would prevent closing the valve for replacing the wire, wire drum, or displacer. NMS8x installation position is important for applications without the guide wire system in order to prevent the measuring wire from being broken →  20.

**Typical tank installation**



A0026725

4 Typical tank installation


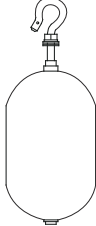
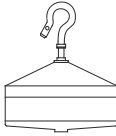

- A Fixed roof tank
- B High pressure tank
- C Floating roof tank with stilling well
- 1 NMS8x
- 2 Ball valve
- 3 Measuring wire
- 4 Displacer
- 5 Stilling well
- 6 Prothermo NMT81

### 5.1.2 Displacer selection guide

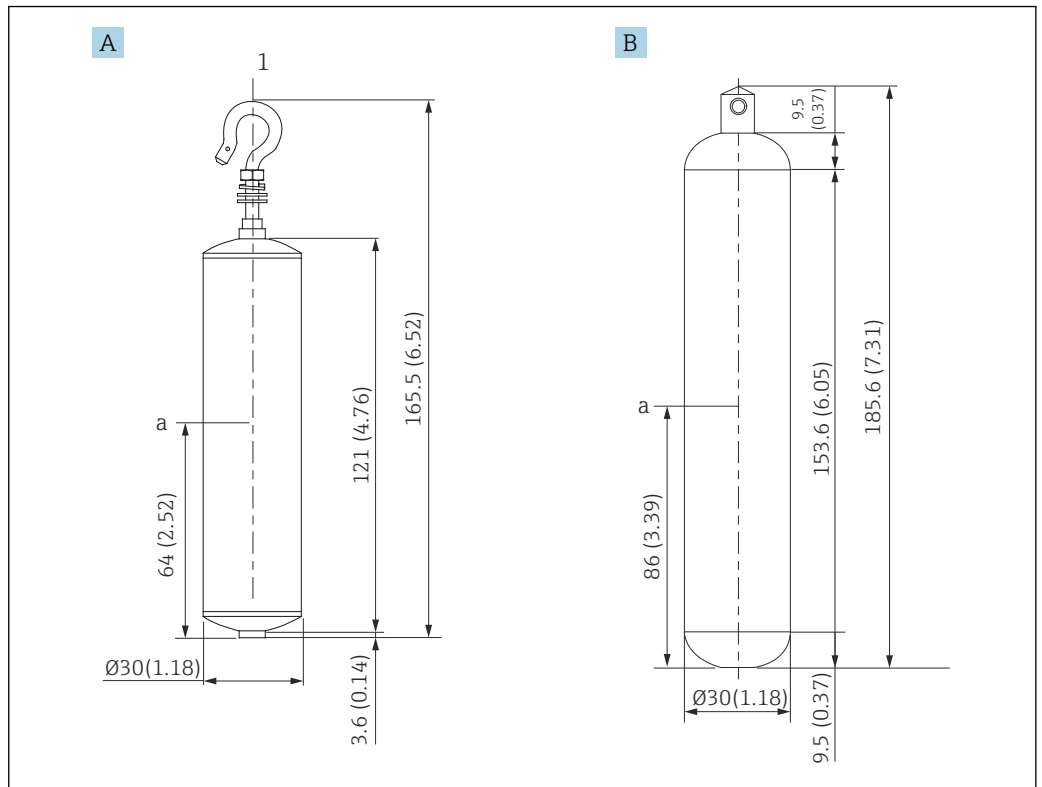
A wide variety of displacers are available to suit different application. Proper displacer selection ensures optimal performance and longevity. The following guidelines will assist you in selecting the most suitable displacer for your application.

#### Displacer types

The following NMS8x displacers are available.

30 mm (1.18 in)	50 mm (1.97 in)	70 mm (2.76 in)	110 mm (4.33 in)
316L/PTFE	316L/AlloyC276/PTFE	316L	316L
			

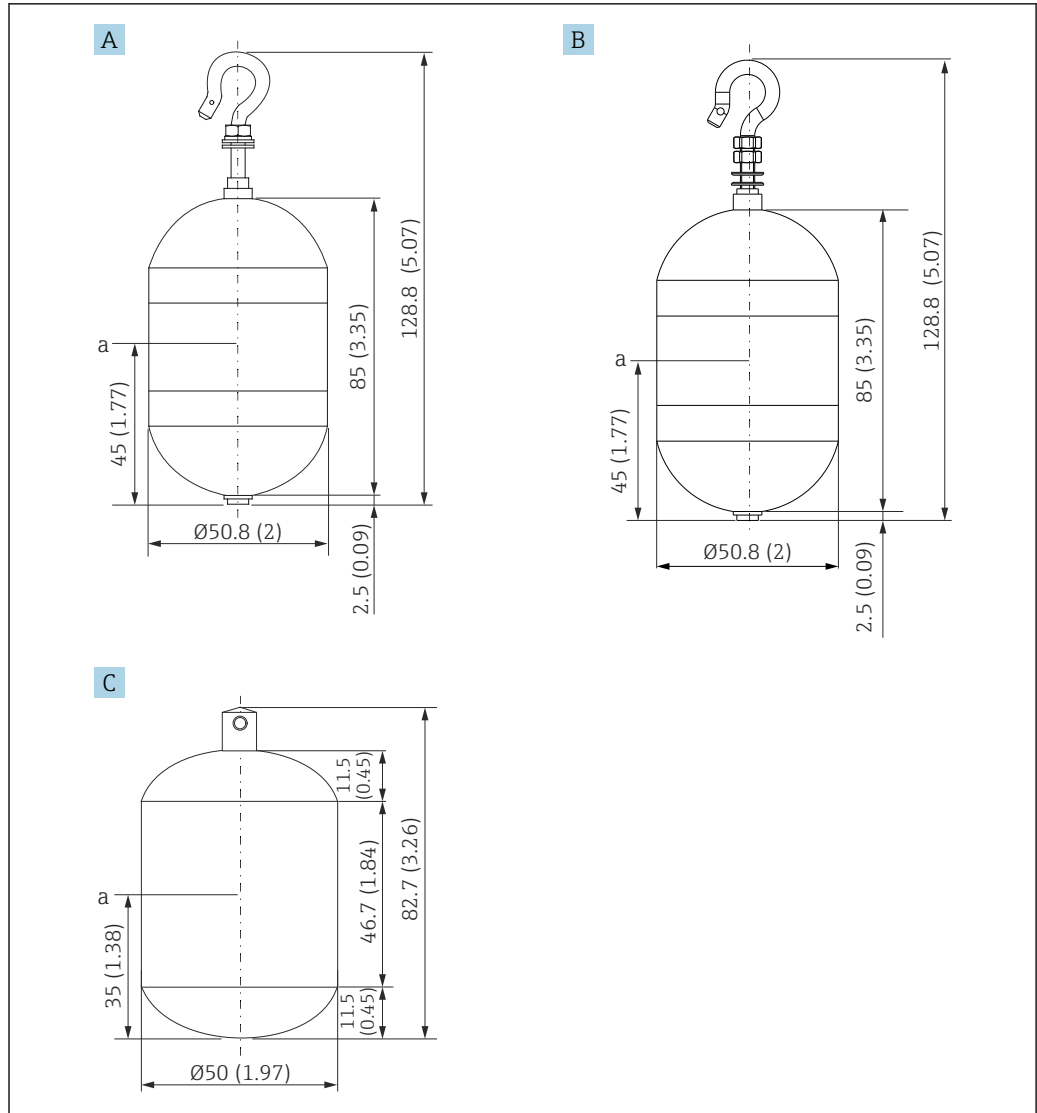
Displacer dimensions



A Ø30 mm (1.18 in) 316L cylindrical displacer  
 B Ø30 mm (1.18 in) PTFE cylindrical displacer  
 a Immersion point

Item	Ø30 mm (1.18 in) 316L cylindrical displacer	Ø30 mm (1.18 in) PTFE cylindrical displacer
Weight (g)	261	250
Volume (ml)	84.3	118
Balance volume (ml)	41.7	59

**i** The weight, volume, and balance volume are individually determined by each displacer and also might vary depending on the values stated above.

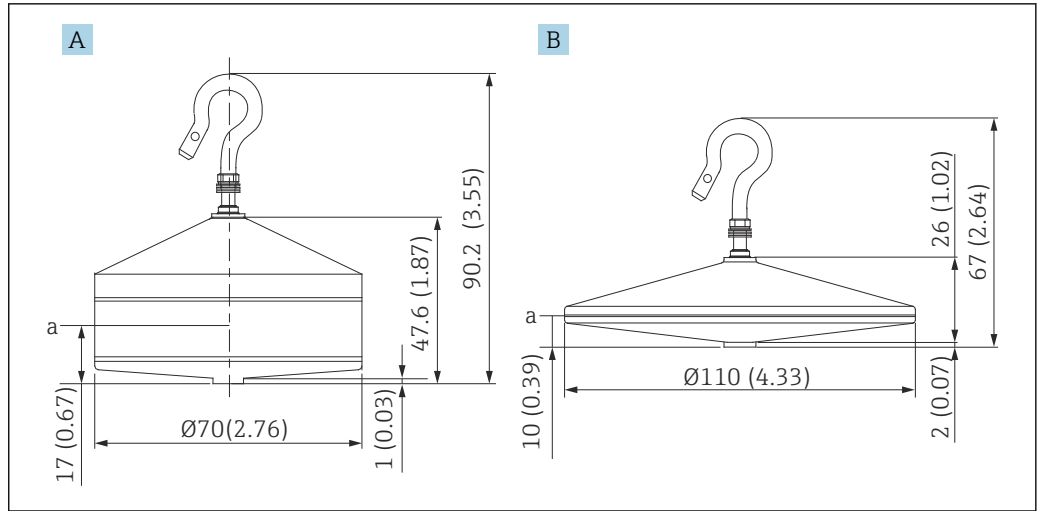


A0029580

- A  $\varnothing 50$  mm (1.97 in) 316L cylindrical displacer
- B  $\varnothing 50$  mm (1.97 in) AlloyC276 cylindrical displacer
- C  $\varnothing 50$  mm (1.97 in) Conductive PTFE cylindrical displacer (Black)
- a Immersion point

Item	$\varnothing 50$ mm (1.97 in) 316L cylindrical displacer	$\varnothing 50$ mm (1.97 in) AlloyC276 cylindrical displacer	$\varnothing 50$ mm (1.97 in) PTFE cylindrical displacer
Weight (g)	253	253	250
Volume (ml)	143	143	118
Balance volume (ml)	70.7	70.7	59

**i** The weight, volume, and balance volume are individually determined by each displacer and also might vary depending on the values stated above.



A0029582

- A Ø70 mm (2.76 in) 316L conical displacer
- B Ø110 mm (4.33 in) 316L conical displacer
- a Immersion point


Item	Ø70 mm (2.76 in) 316L conical displacer	Ø110 mm (4.33 in) 316L conical displacer
Weight (g)	245	223
Volume (ml)	124	108
Balance volume (ml)	52.8	36.3

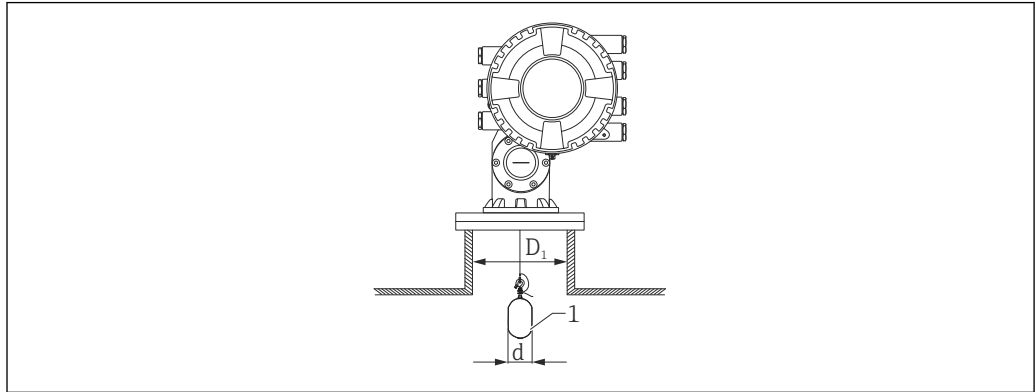
**i** The weight, volume, and balance volume are individually determined by each displacer and also might vary depending on the values stated above.

*Recommended displacer by application*


Application	Product level	Interface level	Density
Viscous liquid	50 mm (1.97 in) PTFE	Not Recommended	Not Recommended
Black oil (e.g. crude oil, heavy oil)	50 mm (1.97 in) 316L 50 mm (1.97 in) PTFE	50 mm (1.97 in) 316L 50 mm (1.97 in) PTFE	50 mm (1.97 in) 316L 50 mm (1.97 in) PTFE
White oil (e.g. gasoline, diesel, heating oil)	50 mm (1.97 in) or 70 mm (2.76 in) 316L	50 mm (1.97 in) or 70 mm (2.76 in) 316L	50 mm (1.97 in) or 70 mm (2.76 in) 316L
Liquefied gas, LPG/LNG	50 mm (1.97 in) or 70 mm (2.76 in) 316L	50 mm (1.97 in) or 70 mm (2.76 in) 316L	50 mm (1.97 in) or 70 mm (2.76 in) 316L
Corrosive liquid	50 mm (1.97 in) AlloyC276 50 mm (1.97 in) PTFE	50 mm (1.97 in) AlloyC276 50 mm (1.97 in) PTFE	50 mm (1.97 in) AlloyC276 50 mm (1.97 in) PTFE

### 5.1.3 Mounting without a guide system

NMS8x is mounted on a nozzle of the tank roof without a guide system. Sufficient clearance inside the nozzle is necessary to allow the displacer to move without hitting the inner walls (for details of  $D$ , →  21).



A0026734

 5 No guide system

$D_1$  Inner diameter of the tank nozzle

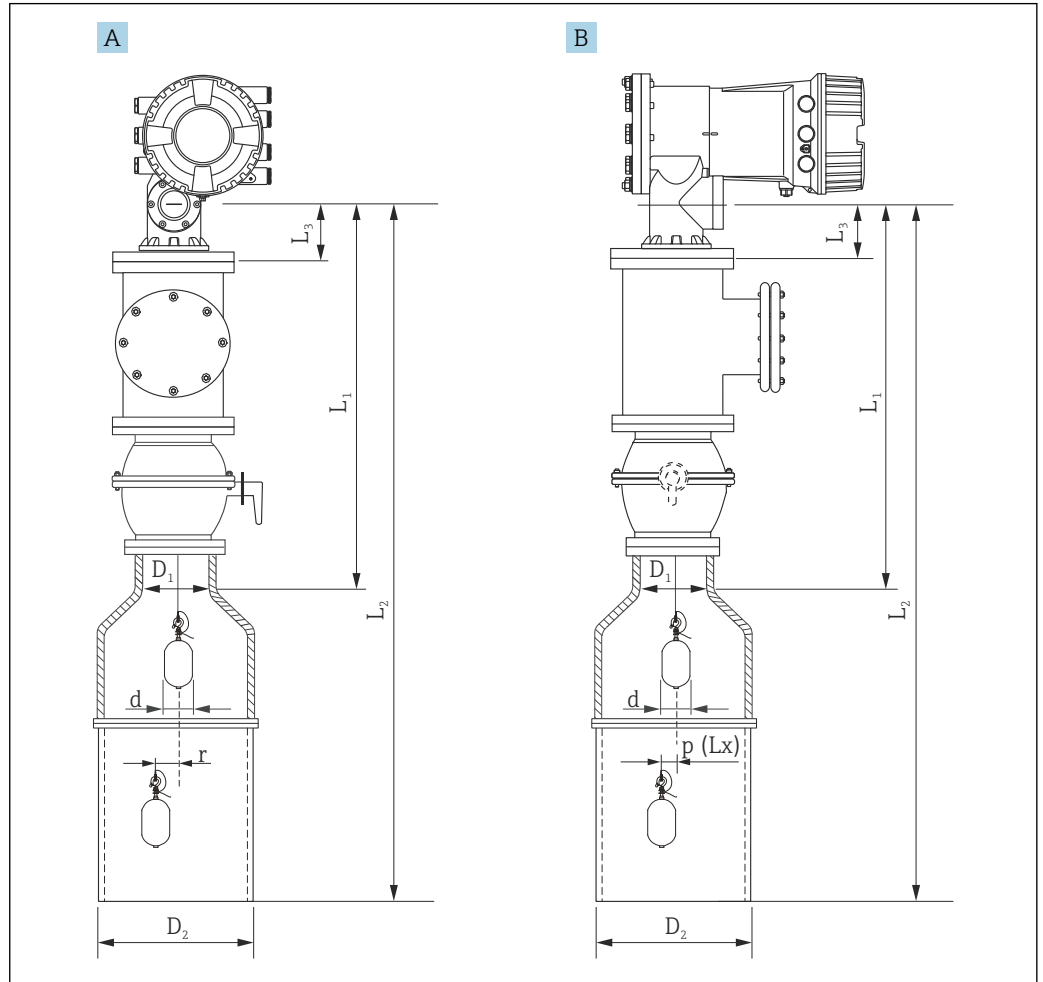
$d$  Diameter of the displacer

1 Displacer



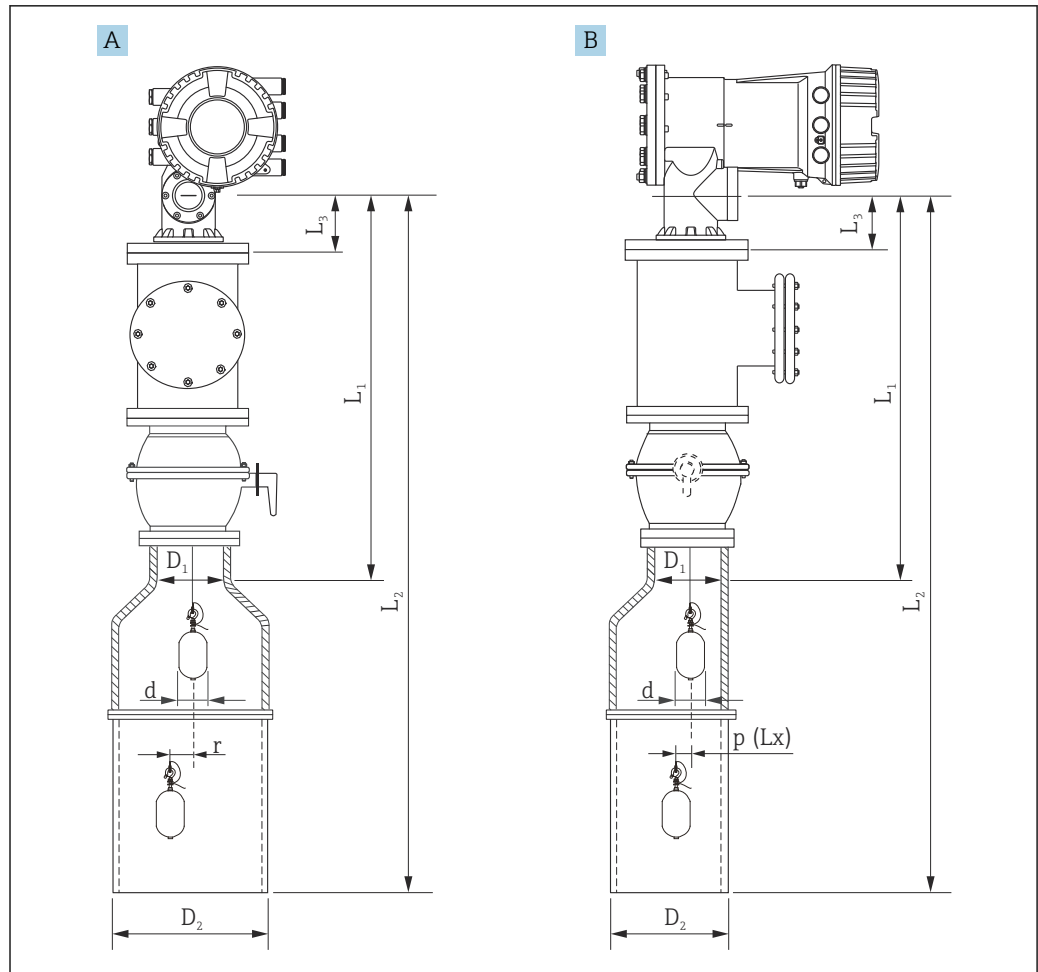
### 5.1.4 Mounting with a stilling well

The stilling well diameter that is required to protect the measuring wire without disturbing its operation varies depending on the tank height. The stilling well could either be of constant diameter, or narrower at its upper part and wider at its lower part. The following figure shows two examples of the latter case, namely a concentric stilling well and an asymmetric stilling well.



6 Mounting with concentric stilling well

- A Front view
- B Side view
- $L_1$  Length from the center of the calibration window to the upper part of the stilling well
- $L_2$  Length from the center of the calibration window to the bottom of the stilling well
- $L_3$  Length from the center of the calibration window to the bottom of the flange
- $D_1$  Diameter of upper part of stilling well
- $D_2$  Diameter of stilling well
- $d$  Diameter of displacer
- $p$  Longitudinal wire position from the center of the flange
- $(Lx)$
- $r$  Radial direction offset



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7 Mounting with asymmetric stilling well

A Front view

B Side view

$L_1$  Length from the center of the calibration window to the upper part of the stilling well

$L_2$  Length from the center of the calibration window to the bottom of the stilling well

$L_3$  Length from the center of the calibration window to the bottom of the flange

$D_1$  Diameter of upper part of stilling well

$D_2$  Diameter of stilling well

$d$  Diameter of displacer

$p$  Longitudinal wire position from the center of the flange

(Lx)

$r$  Radial direction offset

**i**  $L_3$ : length from center of the calibration window to the bottom of the flange built-in NMS8x (77 mm (3.03 in) + flange thickness).

For JIS 10K 150A RF, the flange thickness is 22 mm (0.87 in).

When using an asymmetric stilling well, take into account the lateral shift of the displacer and follow the NMS8x mounting direction as shown in the figure.

To calculate the required stilling well diameters, the formula below should be used. The following tables contain the necessary parameters in order to calculate the dimensions of the stilling well. Be sure to have appropriate dimensions of the stilling well according to each dimension in the table.

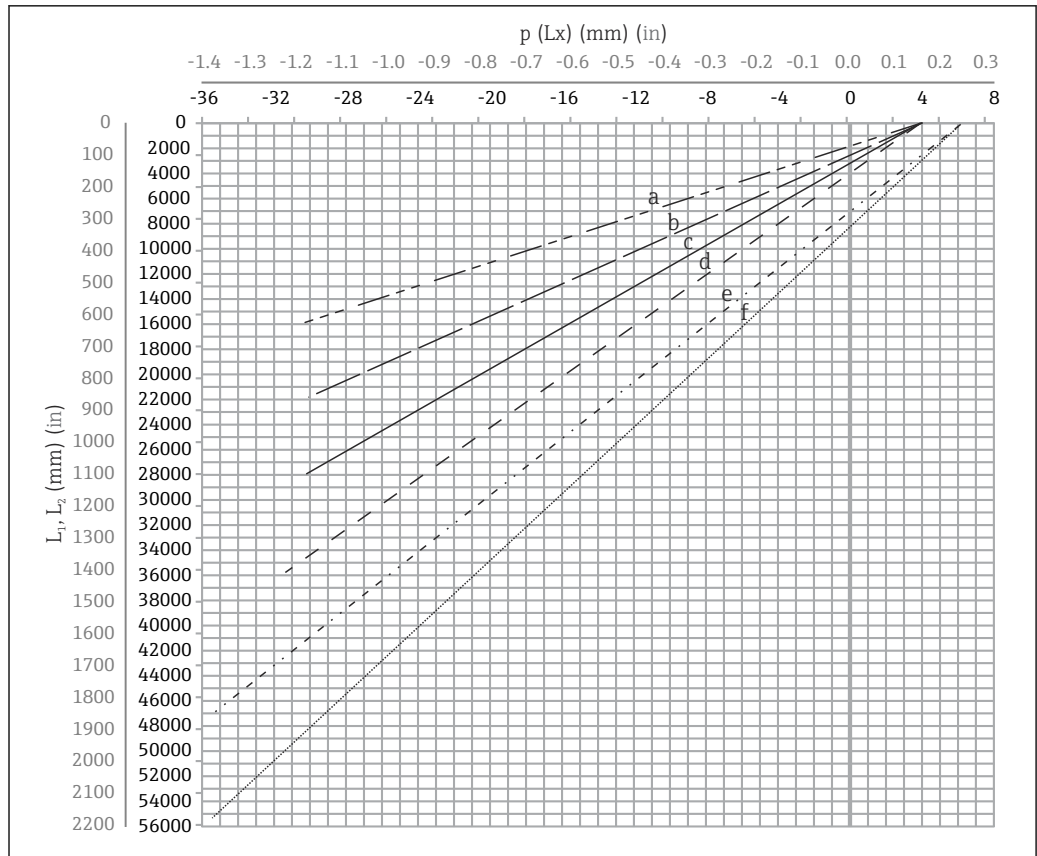
The radial direction offset ( $r$ ) is required for only the 47 m (154.20 ft) and 55 m (180.45 ft) wire drum. For all other drums, the offset is 0 mm/in.

Feature: 110	Description (Measuring range; Wire; Diameter)	NMS80	NMS81	NMS83	r
G1	47 m (154.20 ft); 316L; 0.15 mm (0.00591 in)		☑		6 mm (0.24 in)
H1	55 m (180.45 ft); 316L 0.15 mm (0.00591 in)		☑		6 mm (0.24 in)

Feature: 120	Description (Displacer material; Type)	NMS80	NMS81	NMS83	d
1AA	316L; 30 mm (1.18 in) cylindrical	☑	☑		30 mm (1.18 in)
1AC	316L; 50 mm (1.97 in) cylindrical	☑	☑		50 mm (1.97 in)
1BE	316L; 70 mm (2.76 in) conical	☑	☑		70 mm (2.76 in)
1BJ	316L; 110 mm (4.33 in) conical	☑	☑		110 mm (4.33 in)
2AA	PTFE; 30 mm (1.18 in) cylindrical	☑	☑		30 mm (1.18 in)
2AC	PTFE; 50 mm (1.97 in) cylindrical	☑	☑		50 mm (1.97 in)
3AC	AlloyC276; 50 mm (1.97 in) cylindrical	☑	☑		50 mm (1.97 in)
4AC	316L polished; 50 mm (1.97 in) cylindrical			☑	50 mm (1.97 in)
4AE	316L polished; 70 mm (2.76 in) conical			☑	70 mm (2.76 in)
5AC	PTFE; 50 mm (1.97 in) cylindrical, hygienic white			☑	50 mm (1.97 in)

Parameter	Description
d	Diameter of displacer
p(Lx)	Longitudinal wire position from the center of the flange The value can be determined by using following graph.
r	Radial direction offset
s	Safety factor recommended: 5 mm (0.197 in)

The following graph shows the lateral shift of the displacer depending on the measured distance for the different wire drums.



A0027997

8 Lateral shift of displacer according to measurement range


- a 16 m (A3) (NMS80/NMS81/NMS83)
- b 22 m (C2) (NMS80/NMS81/NMS83)
- c 28 m (D1) (NMS80/NMS81)
- d 36 m (F1) (NMS80/NMS81)
- e 47 m (G1) (NMS81)
- f 55 m (H1) (NMS81)

**Upper diameter of stilling well**

The dimension of  $D_1$  has to be the largest value of the dimensions  $D_{1a}$ ,  $D_{1b}$ ,  $D_{1c}$ , and  $D_{1d}$  according to the following formula.

D <sub>1</sub> Dimension (Example)	D <sub>1x</sub> Dimension		Description	Formula
	Example	Parameter		
>68.1 mm (2.68 in)	68.1 mm (2.68 in)	$D_{1a}$	$D_1$ dimension when the displacer is at the center of the calibration window	$= 2 \times (  p(0)  + d/2 + s )$
	65.6 mm (2.58 in)	$D_{1b}$	$D_1$ dimension when the displacer is at the upper part of the stilling well	$= 2 \times (  p(L_1)  + d/2 + s )$

D <sub>1</sub> Dimension (Example)	D <sub>1x</sub> Dimension		Description	Formula
	Example	Parameter		
	50.9 mm (2.00 in)	D <sub>1c</sub>	D <sub>1</sub> dimension when the displacer is at the bottom of the stilling well	$= 2 \times (  p (L_2)   + s)$
		D <sub>1d</sub>	D <sub>1</sub> dimension when the radial direction offset is considered. This calculation is used only with the 47 m (154.20 ft) wire drum (G1 in Feature110) and 55 m (180.45 ft) (H1 in feature 110)	$= 2 \times (d/2 + r + s)$

 Example: L<sub>1</sub> = 1 000 mm, L<sub>2</sub> = 20 000 mm, d = 50 mm, s = 5.0, 28 m drum


**Lower diameter of stilling well**

The dimension of D<sub>2</sub> has to be the larger value of the dimensions D<sub>1</sub> and D<sub>2b</sub> .

See the table below.


*Concentric pipe*

D <sub>2</sub> Dimension (Example)	D <sub>2x</sub> Dimension		Description	Formula
	Example	Parameter		
>100.9 mm (3.97 in)	68.1 mm (2.68 in)	D <sub>1</sub>	Calculated D <sub>1</sub> value	
	100.9 mm (3.97 in)	D <sub>2b</sub>	D <sub>2</sub> dimension when the displacer is in L <sub>2</sub> length	$= 2 \times (  p (L_2)   + d/2 + s)$

 Example: L<sub>2</sub> = 20 000 mm, d = 50 mm, s = 5.0, 28 m drum

*Asymmetric pipe*

D <sub>2</sub> Dimension (Example)	D <sub>2x</sub> Dimension		Description	Formula
	Example	Parameter		
>84.5 mm (3.33 in)	68.1 mm (2.68 in)	D <sub>1</sub>	Calculated D <sub>1</sub> value	
	84.5 mm (3.33 in)	D <sub>2b</sub>	D <sub>2</sub> dimension that the displacer can pass through (nth groove)	$=  p (L_2)   + d/2 + s + D_1/2$

 Example: L<sub>2</sub> = 20 000 mm, d = 50 mm, s = 5.0, 28 m drum

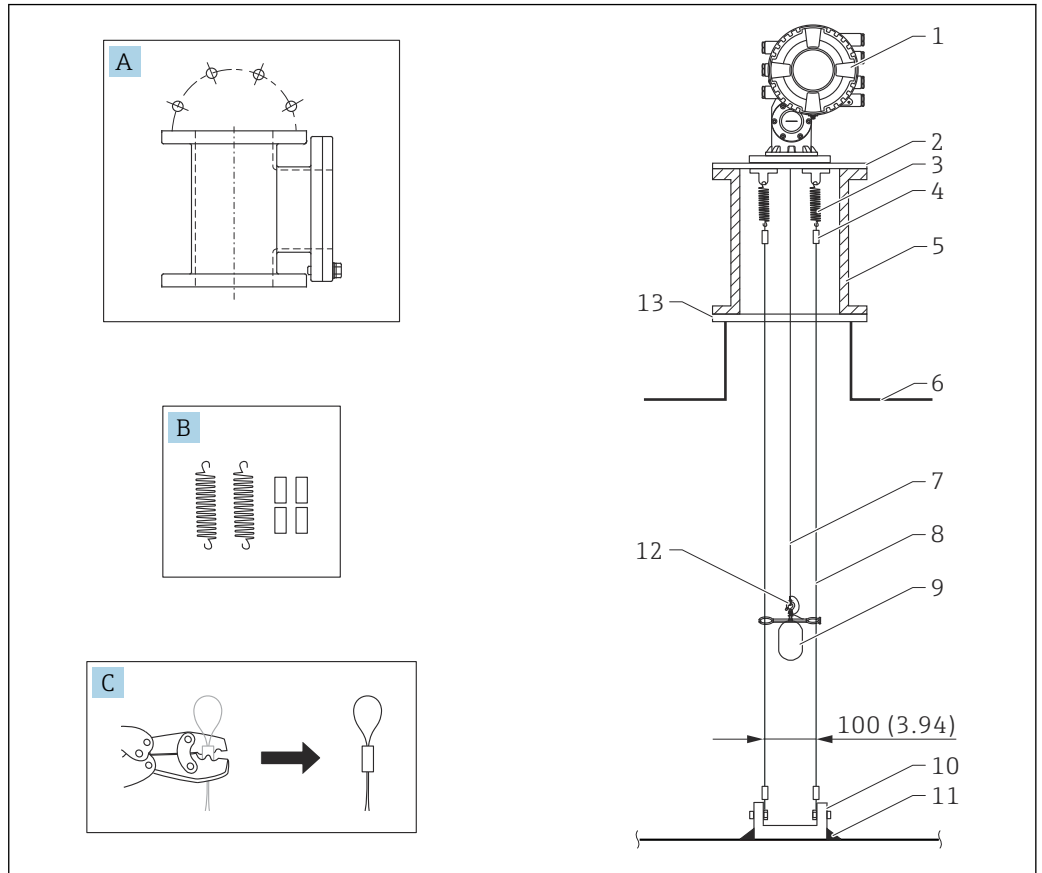
**Recommendations for NMS8x mounting with a stilling well**

Follow the recommendations for mounting NMS8x with a stilling well.

- Keep the pipe connection welds smooth.
- When drilling holes into the pipe, keep the interior surface of the holes clear of metal chips and burrs.
- Coat or paint the interior surface of the pipe to prevent corrosion.
- Keep the pipe as vertical as possible. Check using a plumb bob.
- Install the asymmetric pipe under the valve and align the centers of the NMS8x and the valve.
- Set the center of the lower part of the asymmetric pipe in the direction of the lateral motion.
- Observe the recommendations as per API MPMS chapter 3.1B.
- Confirm grounding between NMS8x and the tank nozzle.

### 5.1.5 Mounting with guide wires

It is also possible to guide the displacer with guide wires to prevent swinging.



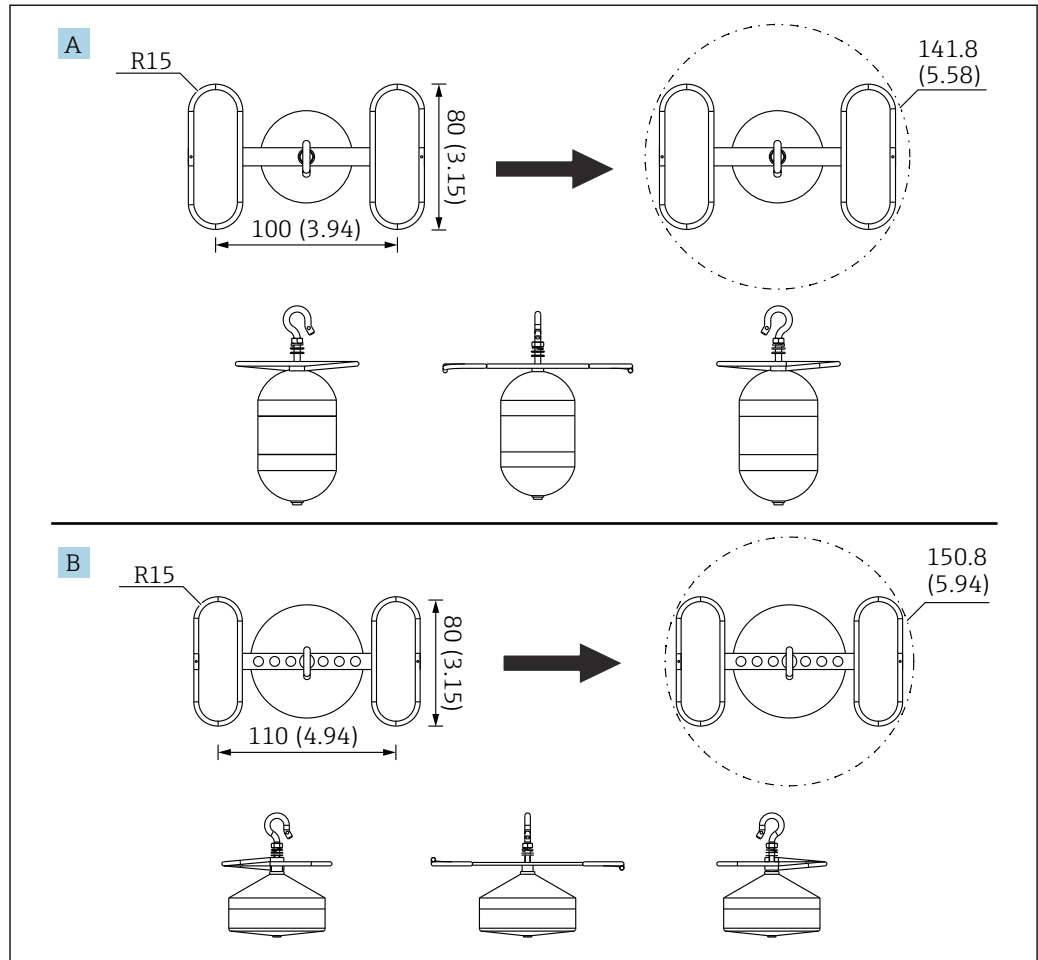
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9 Guide wire; dimensions mm (in)

No.	Description
A	Maintenance chamber
B	Spring and sleeve
C	Crimp tool and guide wire sleeve
1	NMS8x
2	3 to 6" Reducer plate (incl. guide wire option)
3	Spring, 304 (incl. guide wire option)
4	Sleeve, 316 (incl. guide wire option)
5	Maintenance chamber
6	Tank
7	Measuring wire
8	Guide wire, 316 (incl. guide wire option)
9	Displacer with rings (incl. guide wire option)
10	Anchor hook plate, 304 (incl. guide wire option) <ul style="list-style-type: none"> <li>▪ 100 mm (3.94 in) for D50 mm (1.97 in)</li> <li>▪ 110 mm (4.33 in) for D70 mm (2.76 in)</li> </ul>
11	Welding point
12	Wire ring, 316L
13	Flange

**Guide ring dimension**

The dimension of the guide ring is shown below.



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10 Guide ring

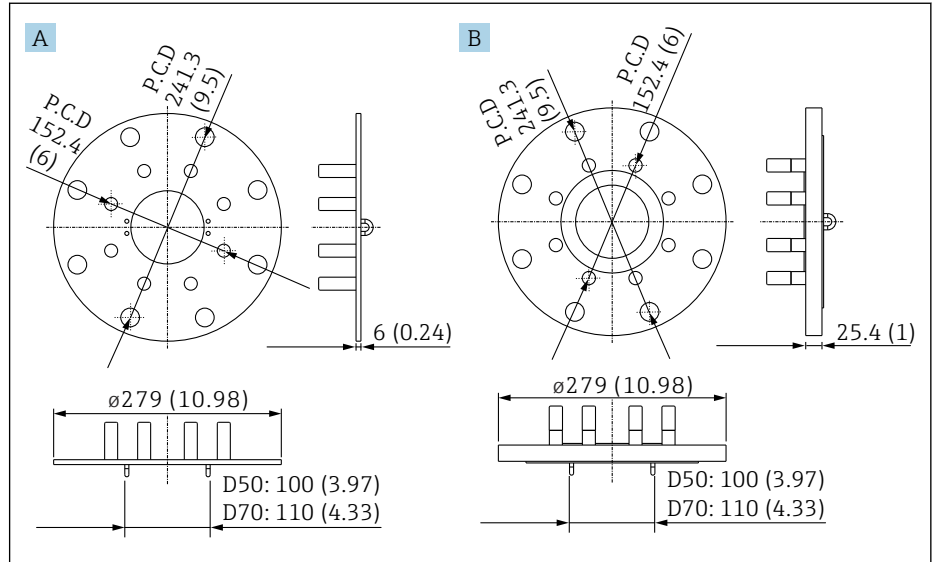
A  $\varnothing 50 \text{ mm}$  (1.97 in) 316L cylindrical displacer

B  $\varnothing 70 \text{ mm}$  (2.76 in) 316L conical displacer



**Guide wire installation procedure**

1. Install NMS8x [1] on the reducer plate [2].
  - ↳ The following dimension shows ASME 3" and 6". The dimensions of JIS, DIN, and JPI vary depending on their specifications.



11 Reducer plate dimension

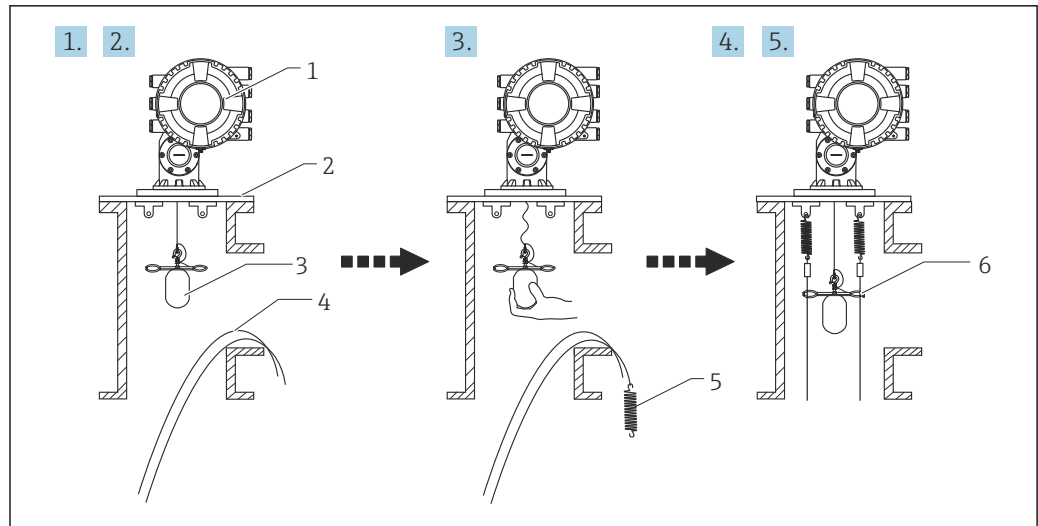
- A Reducer plate for low pressure
- B Reducer plate for middle and high pressure

2. Perform calibration steps (→ 88) before the displacer [3] is attached to the guide wires.
  - ↳ Make sure that the displacer does not touch the guide wires during calibration. This could be done by mounting the NMS8x to the reducer plate prior to fitting the guide wires [4].

**i** Perform calibration steps so that displacer does not touch the guide wires if the guide wires are already installed to the reducer plate.

3. Secure the guide wires to the hooks of the springs [5].
4. Secure the springs to the reducer plate.
5. Put the guide wires through the displacer guide ring [6] and set the displacer.

This completes the guide wire installation procedure.



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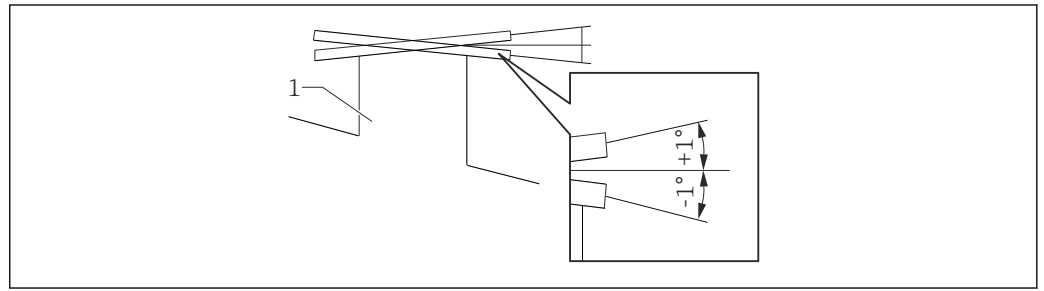
12 Guide wire installation

- 1 NMS8x
- 2 Reducer plate
- 3 Displacer
- 4 Guide wires
- 5 Springs
- 6 Displacer guide ring

### 5.1.6 Flange alignment of NMS8x

Confirm that the size of the nozzle and the flange is matched prior to mounting NMS8x on the tank. The flange size and the rating of NMS8x vary depending on the customer's specifications.

- i** ■ Check the flange size of NMS8x.
- Mount the flange on the top of the tank. The deviation of the flange from the horizontal plane should not exceed +/- 1 degree.
- When mounting NMS8x on a long nozzle, make sure that the displacer does not touch the inner wall of the nozzle.

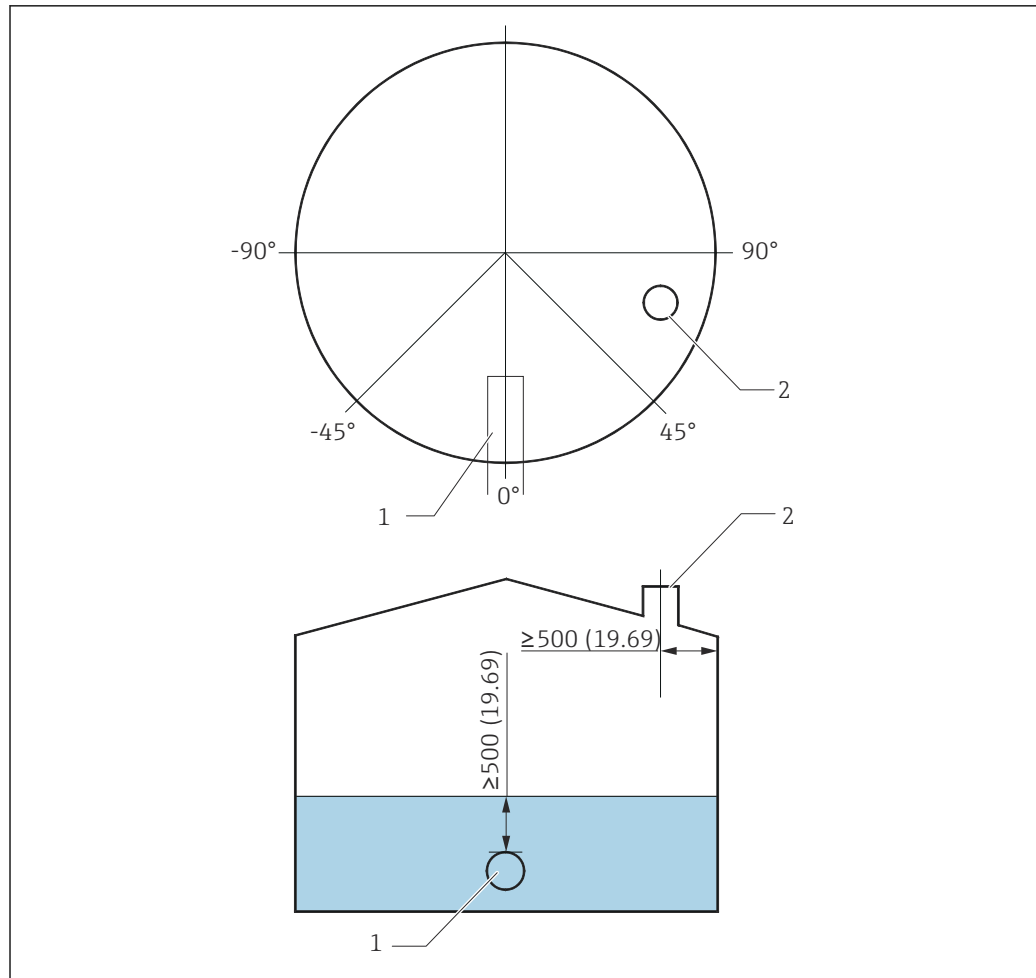


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**i** 13 Allowable inclination of mounting flange

1 Nozzle

- i** When NMS8x is installed without a guide system, follow the recommendations below:
  - Confirm the mounting nozzle is in the sector between 45 and 90 degrees (or -45 and -90 degrees) away from the inlet pipe of the tank. This prevents heavy swinging of the displacer caused by waves or turbulence from the inlet liquid.
  - Confirm the mounting nozzle is 500 mm (19.69 in) or more away from the tank wall.
  - Confirm the minimum measuring level is at 500 mm (19.69 in) or more above the top of the inlet pipe by setting the low stop (for details of low stop setting, → **i** 98). This protects the displacer from direct flow of the inlet liquid.
  - If a stilling well cannot be mounted in the tank due to the shape or condition of the tank, attaching a guide system is recommended. Consult E+H services for further information.



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14 Recommended position for mounting NMS8x and minimum measuring level; dimensions mm (in)

- 1 Inlet pipe  
2 Tank nozzle

- i** Before pouring liquid into the tank, confirm that liquid flowing through the inlet of the pipe will not contact the displacer directly.
- When discharging liquid out of the tank, ensure that the displacer will not get caught in the liquid current and sucked into the outlet pipe.

### 5.1.7 Electrostatic charge

When liquid measured by NMS8x has a conductivity of 1 uS/m or less, it is quasi-nonconductive. In this case, using a stilling well or guide wire is recommended. This diffuses the electrostatic charge on the liquid surface.

## 5.2 Mounting of the device

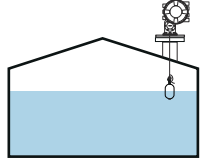
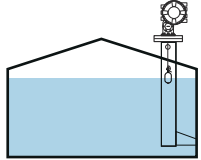
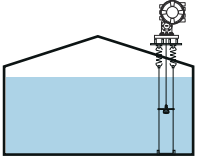
The NMS8x is delivered in two different packing styles depending on the mounting method of the displacer.

- For the all-in-one method, the displacer is mounted on the measuring wire of NMS8x.
- For the displacer shipped separately method, it is necessary to install the displacer on the measuring wire inside NMS8x.

### 5.2.1 Available installations

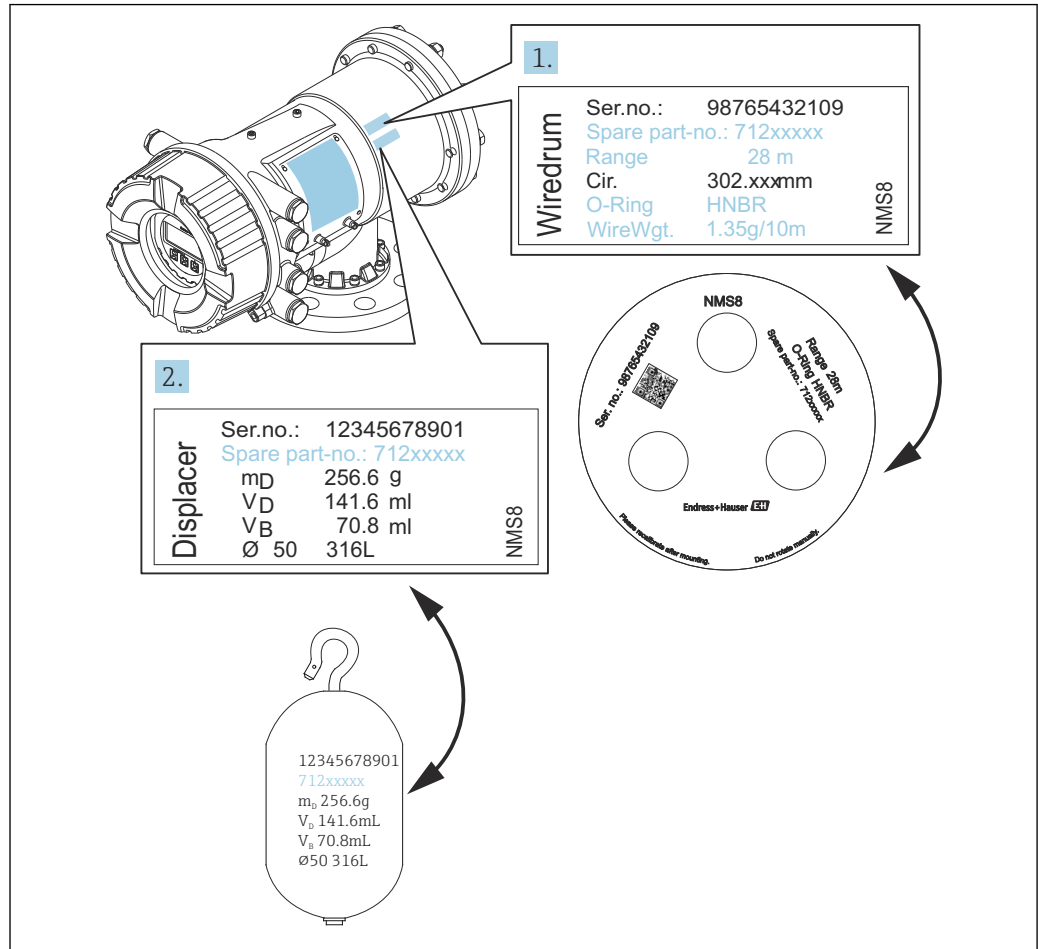
The following installation procedures are available for NMS8x.

- Mounting without guide system
- Mounting with stilling well
- Mounting with guide wire

Mounting options	Without guide system (Free-space mounting)	With stilling well	With guide wire
Type of tanks			
Type of installations	<ul style="list-style-type: none"> <li>■ All-in one</li> <li>■ Displacer shipped separately</li> <li>■ Displacer installation through calibration window</li> </ul>	<ul style="list-style-type: none"> <li>■ All-in one</li> <li>■ Displacer shipped separately</li> <li>■ Displacer installation through calibration window</li> </ul>	Displacer shipped separately

### 5.2.2 Verification of displacer and wire drum

Prior to installation of NMS8x, confirm that the serial numbers of displacer and the wire drum match with those printed to the label attached on the housing.

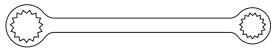
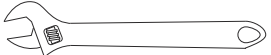

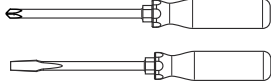
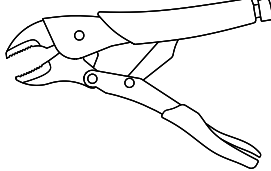




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15 Verification of displacer and wire drum

### 5.2.3 Tools to be required for installation

The following tools are required when installing NMS8x.

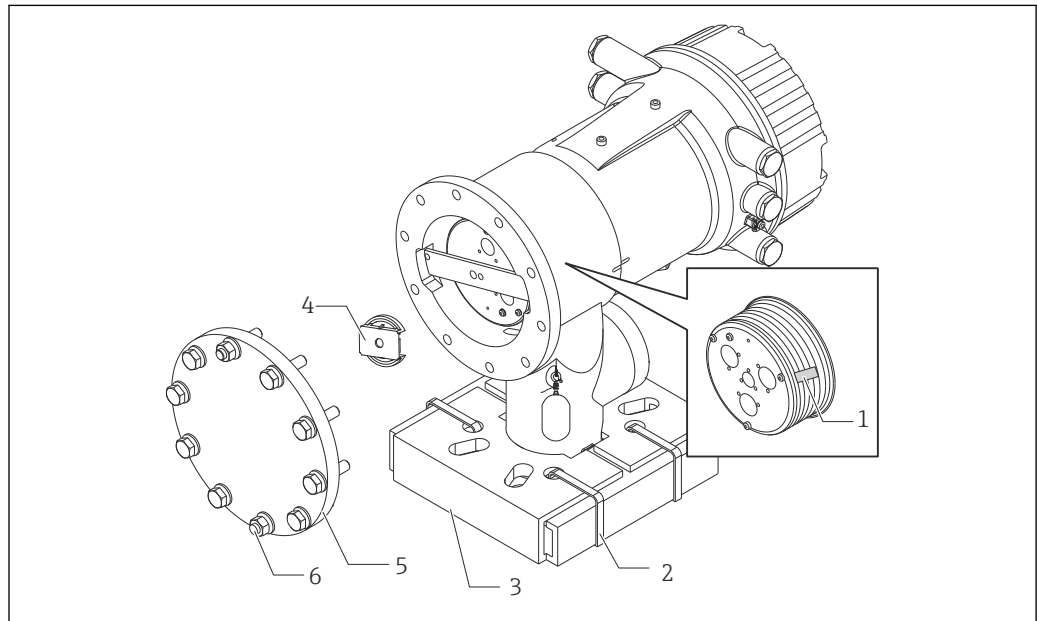
Tools	Figures	Notes
Box end wrench		Use the following size <ul style="list-style-type: none"> <li>▪ 24 mm (0.94 in)</li> <li>▪ 26 mm (1 in)</li> <li>▪ 30 mm (1.2 in)</li> <li>▪ 32 mm (1.3 in)</li> </ul>
Crescent wrench		Use the size of 350 mm (13.78 in)
Allen key		Use the size of 3 mm (0.12 in) or 5 mm (0.17 in)
Screw driver <ul style="list-style-type: none"> <li>▪ Cross-head screwdriver</li> <li>▪ Flat-blade screwdriver</li> </ul>		
Wire cutters or terminal pliers		
Crimp terminal		A: Signal and power supply: 0.2 to 2.5 mm <sup>2</sup> (24 to 13 AWG) <ul style="list-style-type: none"> <li>▪ Ground terminal in the terminal compartment: max. 2.5 mm<sup>2</sup> (13 AWG)</li> <li>▪ Ground terminal at the housing: max. 4 mm<sup>2</sup> (11 AWG)</li> </ul>
Water pump pliers		

### 5.2.4 Installation for all-in-one

The device can be delivered by all-in-one method.

**i** In case of the following specifications, the device cannot be delivered by all-in-one method. Displacer is shipped separately.

- 47 m (154.2 ft) measuring range
- 55 m (180.5 ft) measuring range
- 316L 30 mm (1.18 in) displacer
- 316L 110 mm (4.33 in) displacer
- PTFE 30 mm (1.18 in) displacer
- PTFE 50 mm (1.97 in) displacer
- Guide wire assembly
- Cleaned from oil + grease option
- Internal FEP coated housing




A0027013

**16** Removing packing materials

- 1 Tape
- 2 Fixing band
- 3 Displacer holder
- 4 Wire drum stopper
- 5 Drum housing cover
- 6 Screws and bolts

Procedures	Notes
<ol style="list-style-type: none"> <li>1. Hold the gauge so that it stays horizontal against the flange.</li> <li>2. Cut the fixing bands [2].</li> <li>3. Remove the displacer holder [3] and packing material of the displacer.</li> </ol>	<ul style="list-style-type: none"> <li>▪ Perform these steps before mounting NMS8x on the nozzle.</li> <li>▪ Do not tilt NMS8x after removing the displacer holder.</li> </ul>
<ol style="list-style-type: none"> <li>4. Mount NMS8x on the nozzle .</li> </ol>	<ul style="list-style-type: none"> <li>▪ Make sure that the measuring wire hangs vertically.</li> <li>▪ Confirm that there are no kinks or other defects in the measuring wire.</li> </ul>
<ol style="list-style-type: none"> <li>5. Remove screws and M6 bolts [6] (M10 bolts for stainless steel housing) to remove the drum housing cover [5].</li> </ol>	<p>Be sure not to lose the O-ring and the fixing bolts for the cover of the drum housing.</p>
<ol style="list-style-type: none"> <li>6. Loosen two screws and remove the wire drum stopper [4].</li> </ol>	

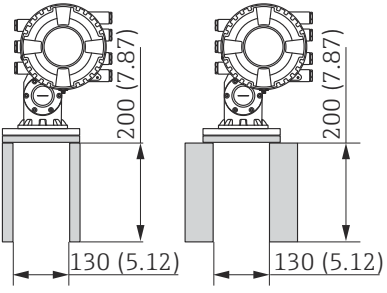
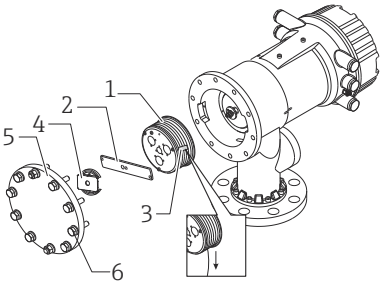
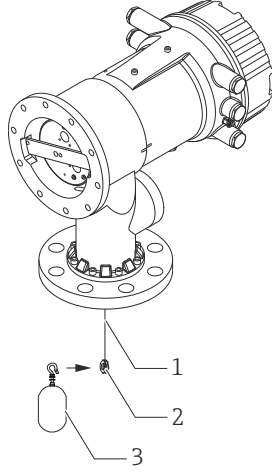


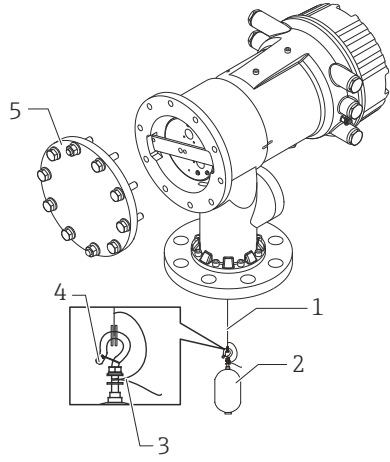
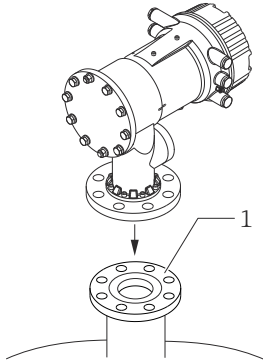
Procedures	Notes
7. Remove the tape [1] from the wire drum carefully.	<ul style="list-style-type: none"><li>■ Remove the tape by hands to avoid damaging the wire drum.</li><li>■ Make sure that the measuring wire is wound so that it fits correctly in the grooves.</li></ul>
8. Mount the drum housing cover.	Confirm that the O-ring is in the drum housing cover.
9. Turn on the power of NMS8x.	 Sensor, reference, and drum calibration steps are not required because they are all performed prior to delivery.

### 5.2.5 Installation for displacer shipped separately method

It is necessary to remove the wire drum from NMS8x, remove the tape on the wire drum, mount the wire drum in the drum housing, and install the displacer on the measuring wire.

Use blocks or a pedestal to secure NMS8x and provide an environment where electrical power can be supplied to NMS8x.

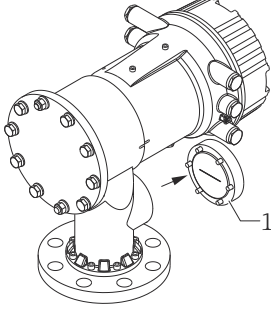
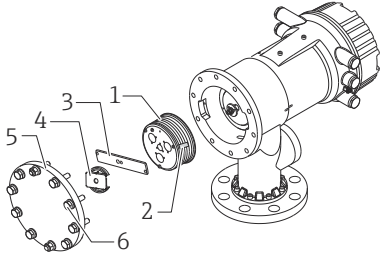
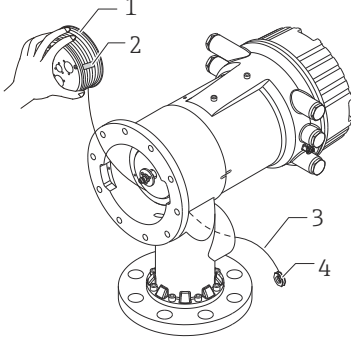
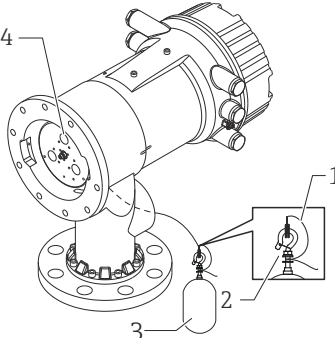
Procedures	Figures
<ol style="list-style-type: none"> <li>1. Secure NMS8x on the blocks or pedestal.</li> <li>2. Confirm that there is enough space under NMS8x.</li> </ol> <p><b>i</b> Be careful not to drop NMS8x.</p>	 <p style="text-align: center;">Dimensions mm (in)</p>
<ol style="list-style-type: none"> <li>3. Remove screws and M6 bolts [6] (M10 bolts for stainless steel housing).</li> <li>4. Remove the wire drum cover [5], wire drum stopper [4], and the bracket [2].</li> <li>5. Remove the wire drum [1] from the drum housing.</li> <li>6. Remove the tape [3] on the wire drum.</li> <li>7. Unwind the measuring wire approximately 250 mm (9.84 in) so that the wire ring is positioned under the flange.</li> <li>8. Mount the wire drum on NMS8x.</li> <li>9. Mount the bracket. <ul style="list-style-type: none"> <li><b>i</b> <ul style="list-style-type: none"> <li>Take special care to not hit the wire drum against the housing due to strong magnet force.</li> <li>Handle the measuring wire with care. It may kink.</li> <li>Be sure that the wire is wound correctly in the grooves.</li> </ul> </li> </ul> </li> </ol>	 <p style="text-align: right; font-size: small;">A0027015</p>
<ol style="list-style-type: none"> <li>10. Hook the displacer [3] on the ring [2]. <ul style="list-style-type: none"> <li><b>i</b> <ul style="list-style-type: none"> <li>Be sure that the wire is wound correctly in the grooves.</li> <li>If not, remove the displacer and the wire drum, and repeat step 7.</li> </ul> </li> </ul> </li> </ol>	 <p style="text-align: right; font-size: small;">A0029115</p>

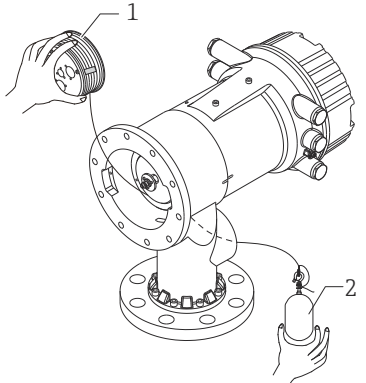




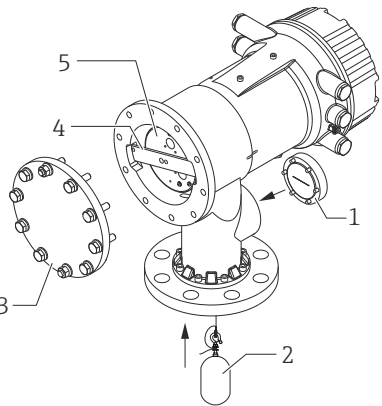
Procedures	Figures
<p>11. Turn on the power of NMS8x.</p> <p>12. Perform sensor calibration</p> <p>13. Secure the displacer [2] to the measuring wire [1] using the securing wire [4].</p> <p>14. Install the ground wire [3] of the displacer (for details of displacer ground wire installation → 42).</p> <p>15. Perform reference calibration.</p> <p>16. Turn off the power.</p> <p>17. Mount the wire drum cover [5].</p> <p><b>i</b> For sensor calibration, → 90                  For reference calibration, → 92.</p>	 <p style="text-align: right;">A0027016</p>
<p>18. Mount NMS8x on the tank nozzle [1].</p> <p>19. Confirm that the displacer does not touch the inner wall of the nozzle.</p> <p>20. Turn on the power.</p> <p>21. Perform drum calibration.</p> <p><b>i</b> For drum calibration, → 93</p>	 <p style="text-align: right;">A0027018</p>

### 5.2.6 Installation through the calibration window

In the case of a 50 mm (1.97 in) diameter displacer, the displacer can be installed through the calibration window.

**i** It is only possible to install the following displacers through the calibration window:  
50 mm 316L, 50 mm AlloyC276, 50 mm PTFE

Procedures	Figures
<p>1. Remove the calibration window cover [1].</p>	 <p style="text-align: right; font-size: small;">A0027019</p>
<p>2. Remove M6 bolts and screws [6] (M10 bolts for stainless steel housing).</p> <p>3. Remove the cover [5], wire drum stopper [4], and the bracket [3].</p> <p>4. Remove the wire drum [1] from the drum housing.</p> <p>5. Remove the tape [2] that is securing the wire.</p> <p><b>i</b> Handle the measuring wire with care. It may kink.</p>	 <p style="text-align: right; font-size: small;">A0029117</p>
<p>6. Holding the wire drum [1] with one hand, unwind the measuring wire [3] approximately 500 mm (19.69 in).</p> <p>7. Secure the wire [3] temporarily with the tape [2].</p> <p>8. Insert the wire ring [4] into the drum housing.</p> <p>9. Pull the wire ring out through the calibration window.</p> <p><b>i</b> Handle the measuring wire with care.</p>	 <p style="text-align: right; font-size: small;">A0027020</p>
<p>10. Insert the wire drum [4] temporarily into the drum housing.</p> <p>11. Hook the displacer [3] on the wire ring.</p> <p>12. Secure the displacer to the measuring wire using the securing wire [2].</p> <p>13. Install the ground wire [1] for the displacer (for details of displacer ground wire installation → 42).</p> <p><b>i</b></p> <ul style="list-style-type: none"> <li>▪ Take special care to not hit the wire drum against the housing due to strong magnet force.</li> <li>▪ Handle the measuring wire with care. It may kink.</li> </ul>	 <p style="text-align: right; font-size: small;">A0027983</p>

Procedures	Figures
<p>14. Remove the wire drum from the drum housing and unwind the measuring wire approximately 500 mm (19.69 in).</p> <p>15. Hold the wire drum [1] up and place the displacer [2] into the calibration window.</p> <p>16. Hold the displacer at the center of the calibration window.</p> <p>17. Hold the other hand (wire drum) up to add tension to the measuring wire in order not to drop the displacer rapidly.</p>	 <p>A0027985</p>
<p>18. Let go of the displacer [2].</p> <p>19. Remove the tape from the wire drum [5].</p> <p>20. Insert the wire drum into the drum housing.</p> <p>21. Mount the bracket [4].</p> <p><b>i</b> Be sure that the wire is wound correctly in the grooves.</p> <p>22. Turn on the power of NMS8x and move the displacer up using the Move displacer →  89 until the wire ring can be seen in the calibration window.</p> <p><b>i</b> <ul style="list-style-type: none"> <li>▪ Confirm that there are no kinks or other defects in the measuring wire.</li> <li>▪ Confirm that the displacer does not touch the inner wall of the nozzle.</li> </ul> </p> <p>23. Perform sensor calibration.</p> <p><b>i</b> For sensor calibration, →  90</p> <p>24. Perform reference calibration.</p> <p><b>i</b> For reference calibration, →  92.</p> <p>25. Mount the drum housing cover [3] and the calibration window cover [1].</p> <p>26. Perform drum calibration.</p> <p><b>i</b> For drum calibration, →  93</p>	 <p>A0027987</p>

### 5.2.7 Displacer ground wire installation

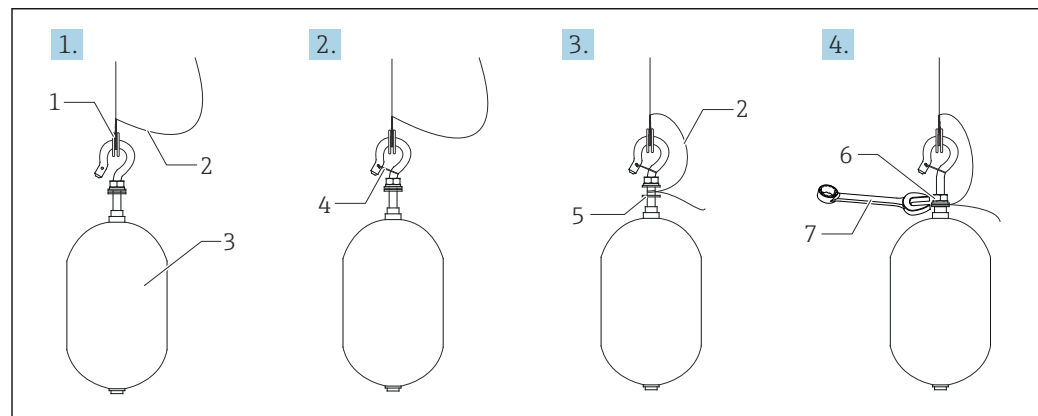
Depending on the application and Ex requirements, electrical grounding of the displacer is required. There are different procedures depending on the displacer type, which are described below.

 For details of displacer installation →  33


#### Standard displacer installation

1. Mount the displacer [3] on the wire ring [1].
2. Wind the securing wire [4] on the wire hook.
3. Wind the ground wire [2] between the washers [5] twice.
  - ↳ If grounding is not required for non-explosion-proof applications, skip this step.
4. Secure the nut [6] with a wrench [7].

This completes the displacer installation procedure.



A0028694

 17 Displacer installation

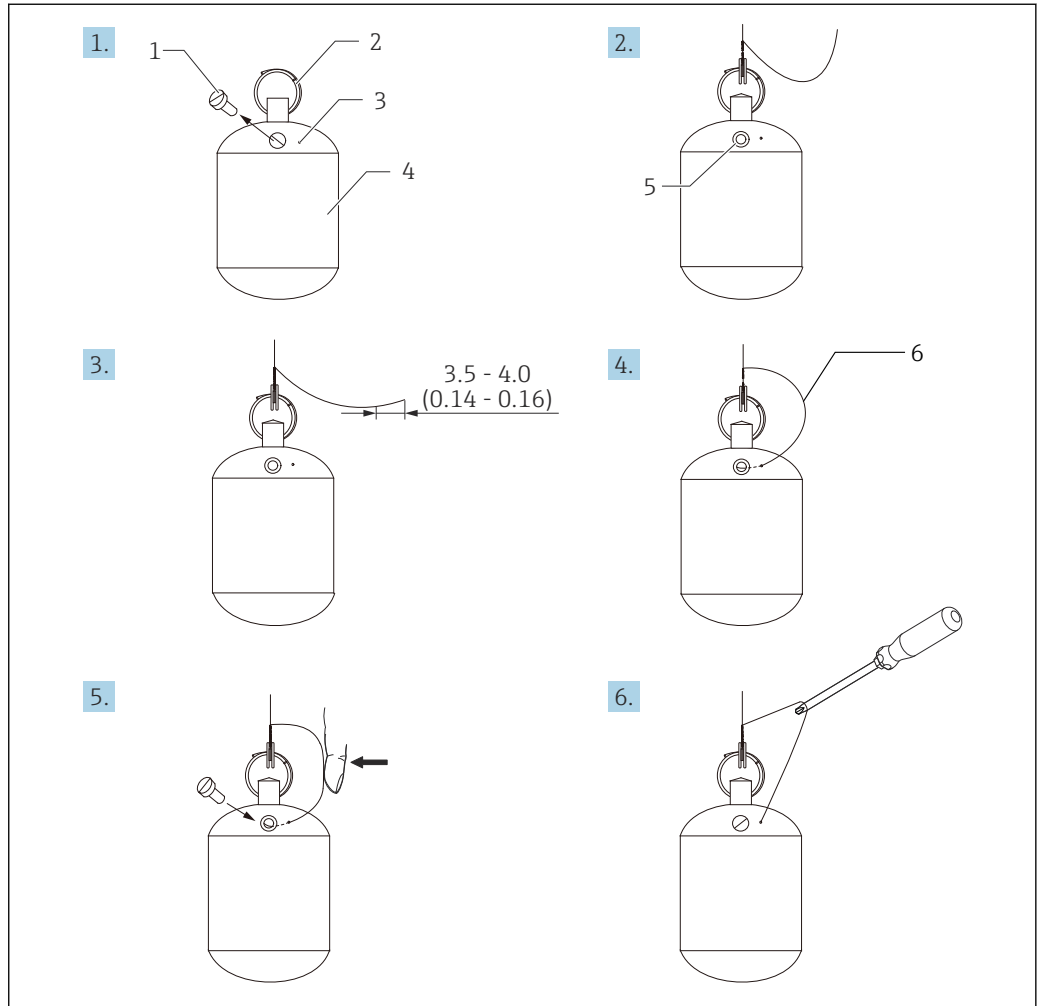
- 1 Wire ring
- 2 Ground wire
- 3 Displacer
- 4 Securing wire
- 5 Washer
- 6 Nut
- 7 Wrench

#### PTFE displacer installation

1. Remove the screw [1] using a flathead screwdriver.
2. Mount the displacer [4] on the Teflon ring [2].
3. Remove the PFA covered wire approximately 3.5 to 4.0 mm (0.14 to 0.16 in) for conductivity.
  - ↳ **PTFE wire:** Install the ground wire [6] onto the displacer from the wire insertion slot [3] until the ground wire touches to the wall of the screw hole [5].
  - SUS wire:** Install the ground wire [6] onto the displacer from the wire insertion slot [3] until the ground wire touches to the wall of the screw hole [5]. Then install the ground wire 10 mm (0.39 in) farther.
4. Install the ground wire [6] onto the displacer from the wire insertion slot [3] until the ground wire contacts to the wall of the screw hole [5].
5. Tighten the screw [1].
  - ↳ Hold the ground wire with finger tips so that the wire does not come out from the slot.

- 6. Lift the displacer using a screwdriver and confirm that the ground wire does not come out from the slot.

This completes the PTFE displacer installation.



18 PTFE displacer installation; dimensions mm (in)

A0028696

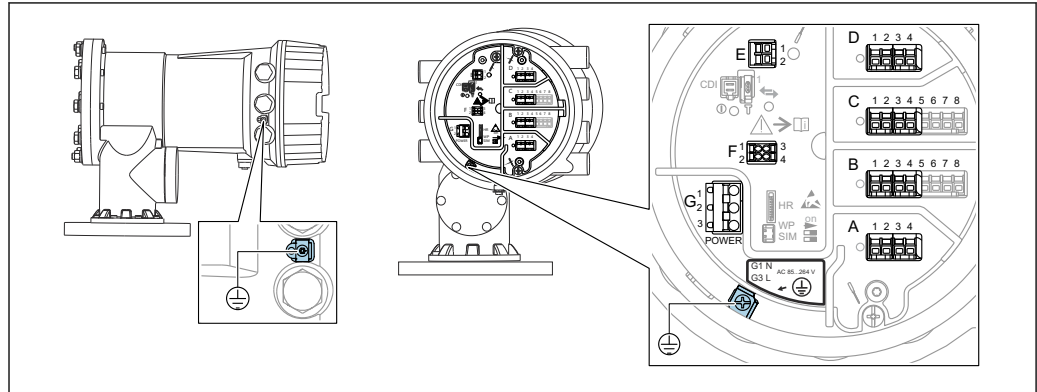
- 1 Screw
- 2 PFA covered ring
- 3 Wire insertion slot
- 4 Displacer
- 5 Screw hole
- 6 Ground wire

### 5.3 Post-installation check

<input type="radio"/>	Is the device undamaged (visual inspection)?
<input type="radio"/>	Does the device conform to the measuring point specifications? For example: <ul style="list-style-type: none"> <li>■ Process temperature</li> <li>■ Process pressure (refer to the chapter on "Material load curves" of the "Technical Information" document)</li> <li>■ Ambient temperature range</li> <li>■ Measuring range</li> </ul>
<input type="radio"/>	Are the measuring point identification and labeling correct (visual inspection)?
<input type="radio"/>	Is the device adequately protected from precipitation and direct sunlight?

## 6 Electrical connection

### 6.1 Terminal assignment



A0027012

19 Terminal compartment (typical example) and ground terminals

#### **i** Housing thread

The threads of the electronics and connection compartment can be coated with an anti-friction coating.

The following applies for all housing materials:

**✗ Do not lubricate the housing threads.**

#### **Terminal area A/B/C/D (slots for I/O modules)**

Module: Up to four I/O modules, depending on the order code

- Modules with four terminals can be in any of these slots.
- Modules with eight terminals can be in slot B or C.

**i** The exact assignment of the modules to the slots is dependent on the device version  
→ 47.

#### **Terminal area E**

Module: HART Ex i/IS interface

- E1: H+
- E2: H-

#### **Terminal area F**

Remote display

- F1:  $V_{CC}$  (connect to terminal 81 of the remote display)
- F2: Signal B (connect to terminal 84 of the remote display)
- F3: Signal A (connect to terminal 83 of the remote display)
- F4: Gnd (connect to terminal 82 of the remote display)

#### **Terminal area G (for High voltage AC power supply and Low voltage AC power supply)**

- G1: N
- G2: not connected
- G3: L

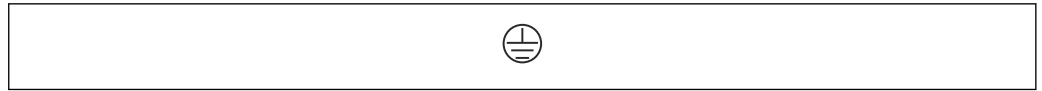
#### **Terminal area G (for Low voltage DC power supply)**

- G1: L-
- G2: not connected
- G3: L+

#### **Terminal area: Protective ground**

Module: Protective ground connection (M4 screw)

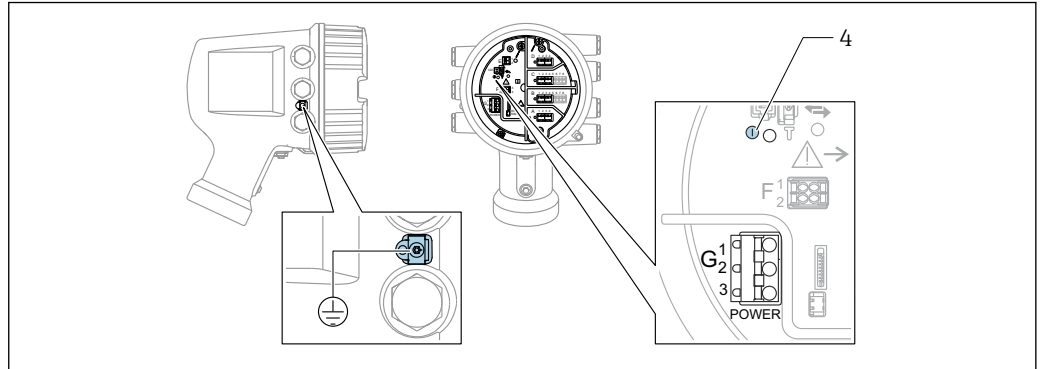




A0018339

20 Terminal area: Protective ground

### 6.1.1 Power supply



A0033413

- G1 N
- G2 not connected
- G3 L
- 4 Green LED: indicates power supply

**i** The supply voltage is also indicated on the nameplate.

#### Supply voltage

##### High voltage AC power supply:

Operational value:

100 to 240 V<sub>AC</sub> (- 15 % + 10 %) = 85 to 264 V<sub>AC</sub> , 50/60 Hz

##### Low voltage AC power supply:

Operational value:

65 V<sub>AC</sub> (- 20 % + 15 %) = 52 to 75 V<sub>AC</sub> , 50/60 Hz

##### Low voltage DC power supply:

Operational value:

24 to 55 V<sub>DC</sub> (- 20 % + 15 %) = 19 to 64 V<sub>DC</sub>

#### Power consumption

Maximum power varies depending on the configuration of the modules. The value shows maximum apparent power, select the applicable cables accordingly. The actual consumed effective power is 12 W.

##### High voltage AC power supply:

28.8 VA

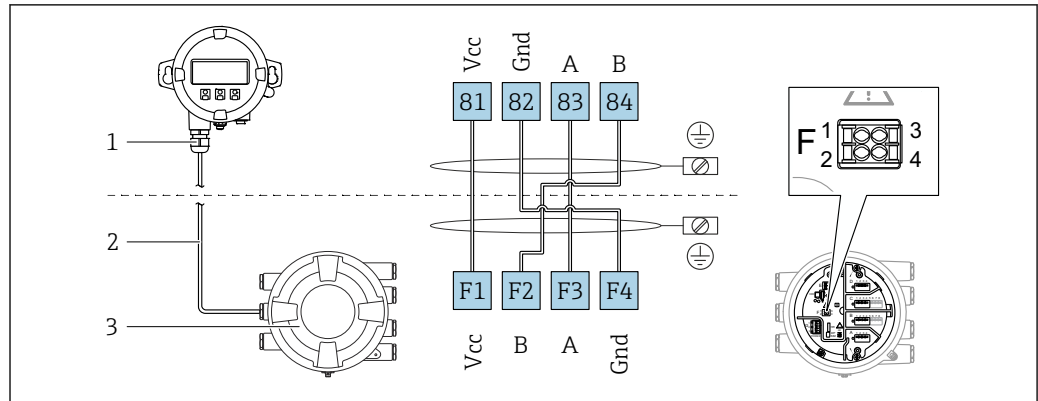
##### Low voltage AC power supply:

21.6 VA

##### Low voltage DC power supply:

13.4 W

### 6.1.2 Remote display and operating module DKX001



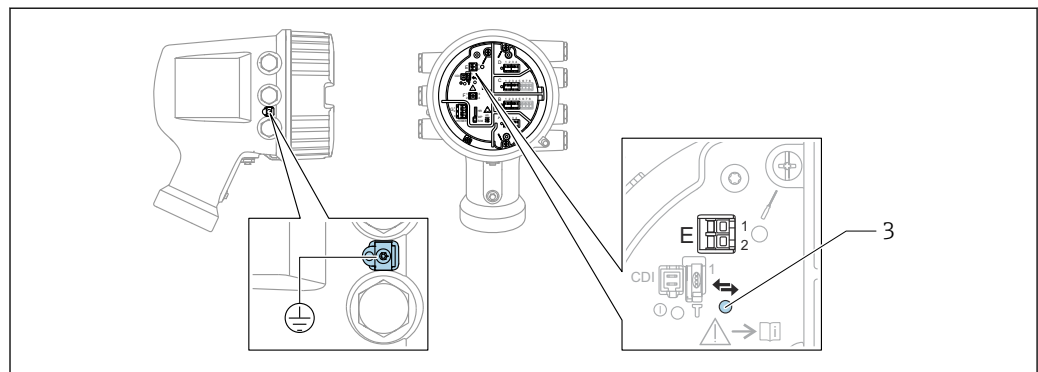
21 Connection of the remote display and operating module DKX001 to the Tank Gauging device (NMR8x, NMS8x or NRF8x)

- 1 Remote display and operating module
- 2 Connecting cable
- 3 Tank Gauging device (NMR8x, NMS8x or NRF8x)

**i** The remote display and operating module DKX001 is available as an accessory. For details refer to SD01763D.

- i**
  - The measured value is indicated on the DKX001 and on the local display and operating module simultaneously.
  - The operating menu cannot be accessed on both modules at the same time. If the operating menu is entered in one of these modules, the other module is automatically locked. This locking remains active until the menu is closed in the first module (back to measured value display).

### 6.1.3 HART Ex i/IS interface



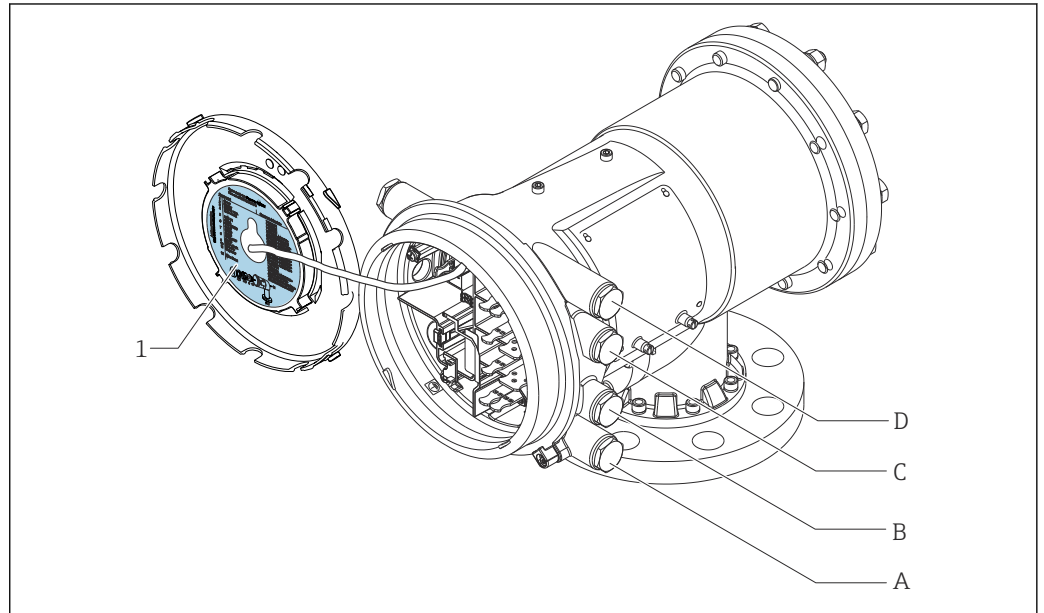
- E1 H+  
E2 H-  
3 Orange LED: indicates data communication

**i** This interface always operates as the main HART master for connected HART slave transmitters. The Analog I/O modules, on the other hand, can be configured as a HART master or slave → 60 → 62.

### 6.1.4 Slots for I/O modules

The terminal compartment contains four slots (A, B, C and D) for I/O modules. Depending on the device version (ordering features 040, 050 and 060) these slots contain different I/O modules. The table below shows which module is located in which slot for a specific device version.

**i** The slot assignment for the device is also indicated on a label attached to the back cover of the display module.



A0030120

- 1 Label showing (among other things) the modules in the slots A to D.
- A Cable entry for slot A
- B Cable entry for slot B
- C Cable entry for slot C
- D Cable entry for slot D

#### List of abbreviations used in table "Primary Output" (040) = "Modbus" (A1)

- O - Ordering feature
- T - Terminal area
- 040 - Primary Output
- 050 - Secondary IO Analog
- 060 - Secondary IO Digital Ex d/XP
- M - Modbus
- D - Digital
- A/XP - Analog Ex d/XP
- A/IS - Analog Ex i/IS

"Primary Output" (O40) = "Modbus" (A1)

O <sup>1)</sup>			T <sup>2)</sup>			
NMx8x - xxxx <u>XX</u> <u>XX</u> <u>XX</u> ... 040 050 060						
040 <sup>3)</sup>	050 <sup>4)</sup>	060 <sup>5)</sup>	A	B	C	D
A1	X0	X0	M	-	-	-
A1	X0	A1	M	-	-	D
A1	X0	A2	M	-	D	D
A1	X0	A3	M	D	D	D
A1	X0	B1	M	M	-	-
A1	X0	B2	M	M	-	D
A1	X0	B3	M	M	D	D
A1	X0	C1	M	V1	-	-
A1	X0	C2	M	V1	-	D
A1	X0	C3	M	V1	D	D
A1	X0	E1	M	W	-	-
A1	X0	E2	M	W	-	D
A1	X0	E3	M	W	D	D
A1	A1	X0	M	A/XP	-	-
A1	A1	A1	M	A/XP	-	D
A1	A1	A2	M	A/XP	D	D
A1	A1	B1	M	M	A/XP	-
A1	A1	B2	M	M	A/XP	D
A1	A1	C1	M	V1	A/XP	-
A1	A1	C2	M	V1	A/XP	D
A1	A1	E1	M	W	A/XP	-
A1	A1	E2	M	W	A/XP	D
A1	A2	X0	M	A/XP	A/XP	-
A1	A2	A1	M	A/XP	A/XP	D
A1	A2	B1	M	A/XP	A/XP	M
A1	A2	C1	M	A/XP	A/XP	V1
A1	A2	E1	M	A/XP	A/XP	W
A1	B1	X0	M	A/IS	-	-
A1	B1	A1	M	A/IS	-	D
A1	B1	A2	M	A/IS	D	D

O <sup>1)</sup>			T <sup>2)</sup>			
NMx8x - xxxx <u>XX</u> <u>XX</u> <u>XX</u> ... 040 050 060						
040 <sup>3)</sup>	050 <sup>4)</sup>	060 <sup>5)</sup>				
A1	B1	B1	M	M	A/IS	-
A1	B1	B2	M	M	A/IS	D
A1	B1	C1	M	V1	A/IS	-
A1	B1	C2	M	V1	A/IS	D
A1	B1	E1	M	W	A/IS	-
A1	B1	E2	M	W	A/IS	D
A1	B2	X0	M	A/IS	A/IS	-
A1	B2	A1	M	A/IS	A/IS	D
A1	B2	B1	M	A/IS	A/IS	M
A1	B2	C1	M	A/IS	A/IS	V1
A1	B2	E1	M	A/IS	A/IS	W
A1	C2	X0	M	A/IS	A/XP	-
A1	C2	A1	M	A/IS	A/XP	D
A1	C2	B1	M	A/IS	A/XP	M
A1	C2	C1	M	A/IS	A/XP	V1
A1	C2	E1	M	A/IS	A/XP	W

- 1) Ordering feature
- 2) Terminal area
- 3) Primary Output
- 4) Secondary IO Analog
- 5) Secondary IO Digital Ex d/XP

**List of abbreviations used in table "Primary Output" (040) = "V1" (B1)**

- O - Ordering feature
- T - Terminal area
- 040 - Primary Output
- 050 - Secondary IO Analog
- 060 - Secondary IO Digital Ex d/XP
- V1 - Sakura V1
- M - Modbus
- W - Whessoe WM550
- D - Digital
- A/XP - Analog Ex d/XP
- A/IS - Analog Ex i/IS

"Primary Output" (040) = "V1" (B1)

O <sup>1)</sup>			T <sup>2)</sup>			
NMx8x - xxxx <u>XX</u> <u>XX</u> <u>XX</u> ... 040 050 060						
040 <sup>3)</sup>	050 <sup>4)</sup>	060 <sup>5)</sup>				
B1	X0	X0	V1	-	-	-
B1	X0	A1	V1	-	-	D
B1	X0	A2	V1	-	D	D
B1	X0	A3	V1	D	D	D
B1	X0	B1	V1	M	-	-
B1	X0	B2	V1	M	-	D
B1	X0	B3	V1	M	D	D
B1	X0	C1	V1	V1	-	-
B1	X0	C2	V1	V1	-	D
B1	X0	C3	V1	V1	D	D
B1	X0	E1	V1	W	-	-
B1	X0	E2	V1	W	-	D
B1	X0	E3	V1	W	D	D
B1	A1	X0	V1	A/XP	-	-
B1	A1	A1	V1	A/XP	-	D
B1	A1	A2	V1	A/XP	D	D
B1	A1	B1	V1	M	A/XP	-
B1	A1	B2	V1	M	A/XP	D
B1	A1	C1	V1	V1	A/XP	-
B1	A1	C2	V1	V1	A/XP	D
B1	A1	E1	V1	W	A/XP	-
B1	A1	E2	V1	W	A/XP	D
B1	A2	X0	V1	A/XP	A/XP	-
B1	A2	A1	V1	A/XP	A/XP	D
B1	A2	B1	V1	A/XP	A/XP	M
B1	A2	C1	V1	A/XP	A/XP	V1
B1	A2	E1	V1	A/XP	A/XP	W
B1	B1	X0	V1	A/IS	-	-
B1	B1	A1	V1	A/IS	-	D
B1	B1	A2	V1	A/IS	D	D

O <sup>1)</sup>			T <sup>2)</sup>			
NMx8x - xxxx <u>XX</u> <u>XX</u> <u>XX</u> ... 040 050 060						
040 <sup>3)</sup>	050 <sup>4)</sup>	060 <sup>5)</sup>				
B1	B1	B1	V1	M	A/IS	-
B1	B1	B2	V1	M	A/IS	D
B1	B1	C1	V1	V1	A/IS	-
B1	B1	C2	V1	V1	A/IS	D
B1	B1	E1	V1	W	A/IS	-
B1	B1	E2	V1	W	A/IS	D
B1	B2	X0	V1	A/IS	A/IS	-
B1	B2	A1	V1	A/IS	A/IS	D
B1	B2	B1	V1	A/IS	A/IS	M
B1	B2	C1	V1	A/IS	A/IS	V1
B1	B2	E1	V1	A/IS	A/IS	W
B1	C2	X0	V1	A/IS	A/XP	-
B1	C2	A1	V1	A/IS	A/XP	D
B1	C2	B1	V1	A/IS	A/XP	M
B1	C2	C1	V1	A/IS	A/XP	V1
B1	C2	E1	V1	A/IS	A/XP	W

- 1) Ordering feature
- 2) Terminal area
- 3) Primary Output
- 4) Secondary IO Analog
- 5) Secondary IO Digital Ex d/XP

**List of abbreviations used in table "Primary Output" (040) = "V1" (B1)**

- O - Ordering feature
- T - Terminal area
- 040 - Primary Output
- 050 - Secondary IO Analog
- 060 - Secondary IO Digital Ex d/XP
- V1 - Sakura V1
- M - Modbus
- W - Whessoe WM550
- D - Digital
- A/XP - Analog Ex d/XP
- A/IS - Analog Ex i/IS

"Primary Output" (O40) = "WM550" (C1)

O <sup>1)</sup>			T <sup>2)</sup>			
NMx8x - xxxx <u>XX</u> <u>XX</u> <u>XX</u> ... 040 050 060						
040 <sup>3)</sup>	050 <sup>4)</sup>	060 <sup>5)</sup>				
C1	X0	X0	W	-	-	-
C1	X0	A1	W	-	-	D
C1	X0	A2	W	-	D	D
C1	X0	A3	W	D	D	D
C1	X0	B1	W	M	-	-
C1	X0	B2	W	M	-	D
C1	X0	B3	W	M	D	D
C1	X0	C1	W	V1	-	-
C1	X0	C2	W	V1	-	D
C1	X0	C3	W	V1	D	D
C1	X0	E1	W	W	-	-
C1	X0	E2	W	W	-	D
C1	X0	E3	W	W	D	D
C1	A1	X0	W	A/XP	-	-
C1	A1	A1	W	A/XP	-	D
C1	A1	A2	W	A/XP	D	D
C1	A1	B1	W	M	A/XP	-
C1	A1	B2	W	M	A/XP	D
C1	A1	C1	W	V1	A/XP	-
C1	A1	C2	W	V1	A/XP	D
C1	A1	E1	W	W	A/XP	-
C1	A1	E2	W	W	A/XP	D
C1	A2	X0	W	A/XP	A/XP	-
C1	A2	A1	W	A/XP	A/XP	D
C1	A2	B1	W	A/XP	A/XP	M
C1	A2	C1	W	A/XP	A/XP	V1
C1	A2	E1	W	A/XP	A/XP	W
C1	B1	X0	W	A/IS	-	-
C1	B1	A1	W	A/IS	-	D
C1	B1	A2	W	A/IS	D	D



O <sup>1)</sup>			T <sup>2)</sup>			
NMx8x - xxxx <u>XX</u> <u>XX</u> <u>XX</u> ... 040 050 060						
040 <sup>3)</sup>	050 <sup>4)</sup>	060 <sup>5)</sup>				
C1	B1	B1	W	M	A/IS	-
C1	B1	B2	W	M	A/IS	D
C1	B1	C1	W	V1	A/IS	-
C1	B1	C2	W	V1	A/IS	D
C1	B1	E1	W	W	A/IS	-
C1	B1	E2	W	W	A/IS	D
C1	B2	X0	W	A/IS	A/IS	-
C1	B2	A1	W	A/IS	A/IS	D
C1	B2	B1	W	A/IS	A/IS	M
C1	B2	C1	W	A/IS	A/IS	V1
C1	B2	E1	W	A/IS	A/IS	W
C1	C2	X0	W	A/IS	A/XP	-
C1	C2	A1	W	A/IS	A/XP	D
C1	C2	B1	W	A/IS	A/XP	M
C1	C2	C1	W	A/IS	A/XP	V1
C1	C2	E1	W	A/IS	A/XP	W

- 1) Ordering feature
- 2) Terminal area
- 3) Primary Output
- 4) Secondary IO Analog
- 5) Secondary IO Digital Ex d/XP

**List of abbreviations used in table "Primary Output" (040) = "V1" (B1)**

- O - Ordering feature
- T - Terminal area
- 040 - Primary Output
- 050 - Secondary IO Analog
- 060 - Secondary IO Digital Ex d/XP
- V1 - Sakura V1
- M - Modbus
- W - Whessoe WM550
- D - Digital
- A/XP - Analog Ex d/XP
- A/IS - Analog Ex i/IS

"Primary Output" (040) = "4-20mA HART Ex d" (E1)

O <sup>1)</sup>			T <sup>2)</sup>			
NMx8x - xxxx <u>XX</u> <u>XX</u> <u>XX</u> ... 040 050 060						
040 <sup>3)</sup>	050 <sup>4)</sup>	060 <sup>5)</sup>				
E1	X0	X0	-	A/XP	-	-
E1	X0	A1	-	A/XP	-	D
E1	X0	A2	-	A/XP	D	D
E1	X0	A3	D	A/XP	D	D
E1	X0	B1	M	A/XP	-	-
E1	X0	B2	M	A/XP	-	D
E1	X0	B3	M	A/XP	D	D
E1	A1	X0	-	A/XP	A/XP	-
E1	A1	A1	-	A/XP	A/XP	D
E1	A1	A2	D	A/XP	A/XP	D
E1	A1	B1	M	A/XP	A/XP	-
E1	A1	B2	M	A/XP	A/XP	D
E1	B1	X0	-	A/XP	A/IS	-
E1	B1	A1	-	A/XP	A/IS	D
E1	B1	A2	D	A/XP	A/IS	D
E1	B1	B1	M	A/XP	A/IS	-
E1	B1	B2	M	A/XP	A/IS	D

- 1) Ordering feature
- 2) Terminal area
- 3) Primary Output
- 4) Secondary IO Analog
- 5) Secondary IO Digital Ex d/XP

List of abbreviations used in table "Primary Output" (040) = "V1" (B1)

- O - Ordering feature
- T - Terminal area
- 040 - Primary Output
- 050 - Secondary IO Analog
- 060 - Secondary IO Digital Ex d/XP
- V1 - Sakura V1
- M - Modbus
- W - Whessoe WM550

- D - Digital
- A/XP - Analog Ex d/XP
- A/IS - Analog Ex i/IS

"Primary Output" (040) = "4-20mA HART Ex i" (H1)

O <sup>1)</sup>			T <sup>2)</sup>			
NMx8x - xxxx <u>XX</u> <u>XX</u> <u>XX</u> ... 040 050 060						
040 <sup>3)</sup>	050 <sup>4)</sup>	060 <sup>5)</sup>				
H1	X0	X0	-	A/IS	-	-
H1	X0	A1	-	A/IS	-	D
H1	X0	A2	-	A/IS	D	D
H1	X0	A3	D	A/IS	D	D
H1	X0	B1	M	A/IS	-	-
H1	X0	B2	M	A/IS	-	D
H1	X0	B3	M	A/IS	D	D
H1	A1	X0	-	A/IS	A/XP	-
H1	A1	A1	-	A/IS	A/XP	D
H1	A1	A2	D	A/IS	A/XP	D
H1	A1	B1	M	A/IS	A/XP	-
H1	A1	B2	M	A/IS	A/XP	D
H1	B1	X0	-	A/IS	A/IS	-
H1	B1	A1	-	A/IS	A/IS	D
H1	B1	A2	D	A/IS	A/IS	D
H1	B1	B1	M	A/IS	A/IS	-
H1	B1	B2	M	A/IS	A/IS	D

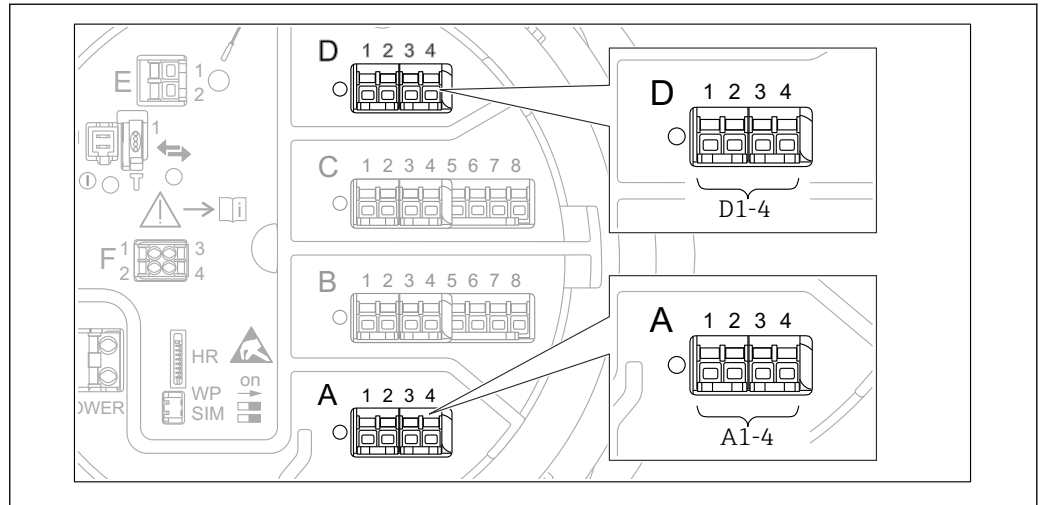
- 1) Ordering feature
- 2) Terminal area
- 3) Primary Output
- 4) Secondary IO Analog
- 5) Secondary IO Digital Ex d/XP

**List of abbreviations used in table "Primary Output" (040) = "V1" (B1)**

- O - Ordering feature
- T - Terminal area
- 040 - Primary Output
- 050 - Secondary IO Analog
- 060 - Secondary IO Digital Ex d/XP
- V1 - Sakura V1

- M - Modbus
- W - Whessoe WM550
- D - Digital
- A/XP - Analog Ex d/XP
- A/IS - Analog Ex i/IS

### 6.1.5 Terminals of the "Modbus" module, "V1" module or "WM550" module



22 Designation of the "Modbus", "V1" or "WM550" modules (examples); depending on the device version these modules may also be in slot B or C.

Depending on the device version, the "Modbus" and/or "V1" or "WM550" module may be in different slots of the terminal compartment. In the operating menu the "Modbus" and "V1" or "WM550" interfaces are designated by the respective slot and the terminals within this slot: **A1-4, B1-4, C1-4, D1-4**.

#### Terminals of the "Modbus" module

Designation of the module in the operating menu: **Modbus X1-4**; (X = A, B, C or D)

- X1<sup>1)</sup>
  - Terminal name: S
  - Description: Cable shielding connected via a capacitor to EARTH
- X2<sup>1)</sup>
  - Terminal name: 0V
  - Description: Common reference
- X3<sup>1)</sup>
  - Terminal name: B-
  - Description: Non-inverting signal line
- X4<sup>1)</sup>
  - Terminal name: A+
  - Description: Inverting signal line

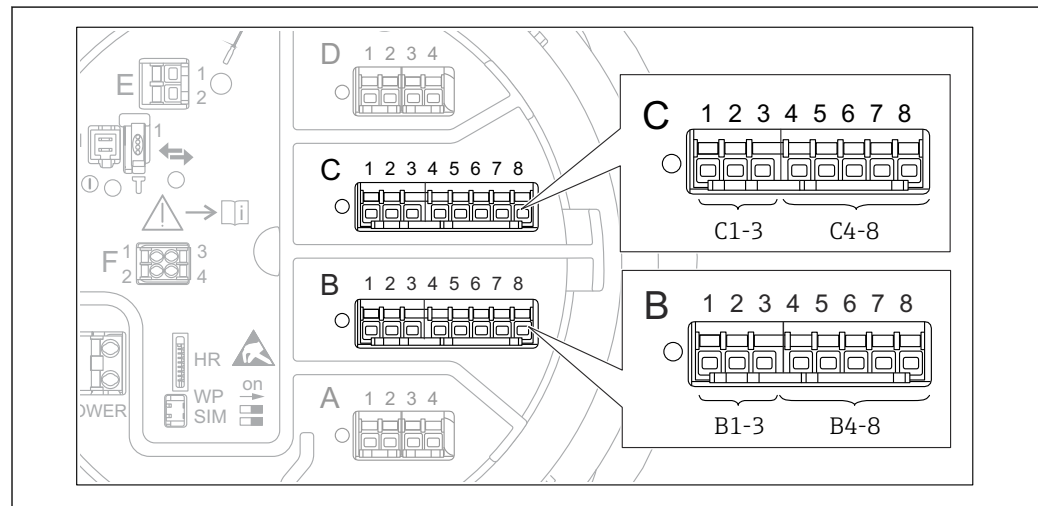
1) Here, "X" stands for one of the slots "A", "B", "C", or "D".

### Terminals of the "V1" and "WM550" module

Designation of the module in the operating menu: **V1 X1-4** or **WM550 X1-4**; (X = A, B, C or D)

- X1 <sup>2)</sup>
  - Terminal name: S
  - Description: Cable shielding connected via a capacitor to EARTH
- X2 <sup>1)</sup>
  - Terminal name: -
  - Description: not connected
- X3 <sup>1)</sup>
  - Terminal name: B-
  - Description: Protocol loop signal -
- X4 <sup>1)</sup>
  - Terminal name: A+
  - Description: Protocol loop signal +

### 6.1.6 Terminals of the "Analog I/O" module (Ex d /XP or Ex i/IS)



A0031168

#### Terminal: B1-3

Function: Analog input or output (configurable)

- Passive usage: → 60
- Active usage: → 62
- Designation in the operating menu:  
Analog I/O B1-3 (→ 227)

#### Terminal: C1-3

Function: Analog input or output (configurable)

- Passive usage: → 60
- Active usage: → 62
- Designation in the operating menu:  
Analog I/O C1-3 (→ 227)

#### Terminal: B4-8



Function: Analog input

- RTD: → 63
- Designation in the operating menu:  
Analog IP B4-8 (→ 221)

2) Here, "X" stands for one of the slots "A", "B", "C", or "D".

**Terminal: C4-8**

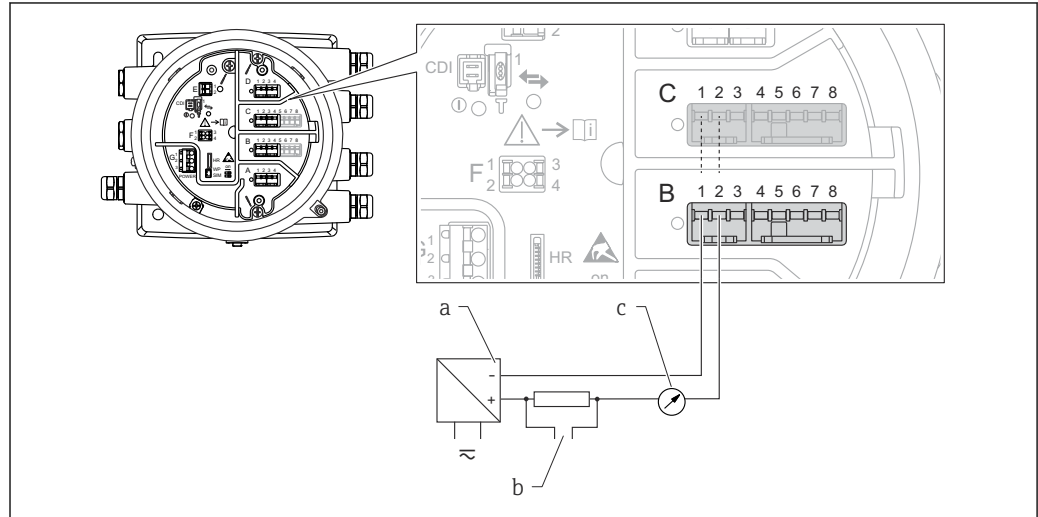
Function: Analog input

- RTD: →  63
- Designation in the operating menu:  
Analog IP C4-8 (→  221)

### 6.1.7 Connection of the "Analog I/O" module for passive usage

- i** In the passive usage the supply voltage for the communication line must be supplied by an external source.
- The wiring must be in accordance with the intended operating mode of the Analog I/O module; see the drawings below.

"Operating mode" = "4..20mA output" or "HART slave +4..20mA output"

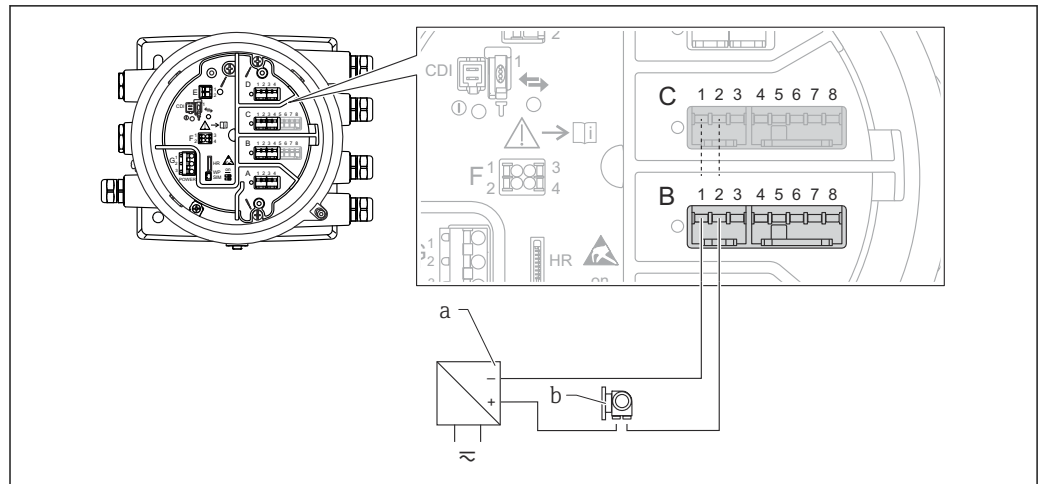


A0027931

23 Passive usage of the Analog I/O module in the output mode

- a Power supply
- b HART signal output
- c Analog signal evaluation

"Operating mode" = "4..20mA input" or "HART master+4..20mA input"



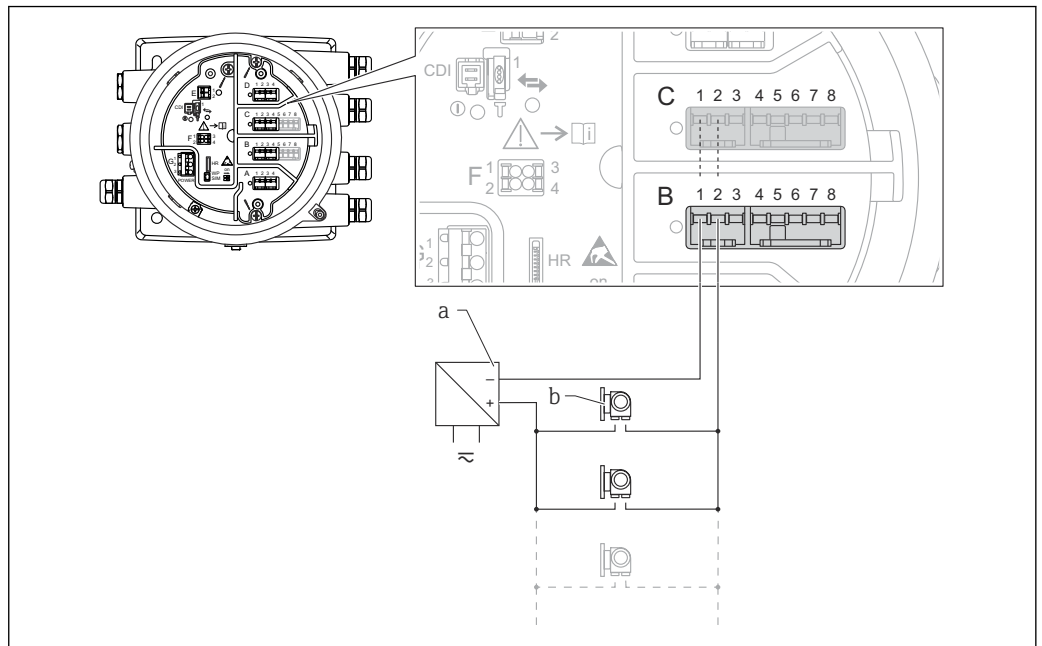
A0027933

24 Passive usage of the Analog I/O module in the input mode

- a Power supply
- b External device with 4...20mA and/or HART signal output



"Operating mode" = "HART master"



A0027934

25 Passive usage of the Analog I/O module in the HART master mode

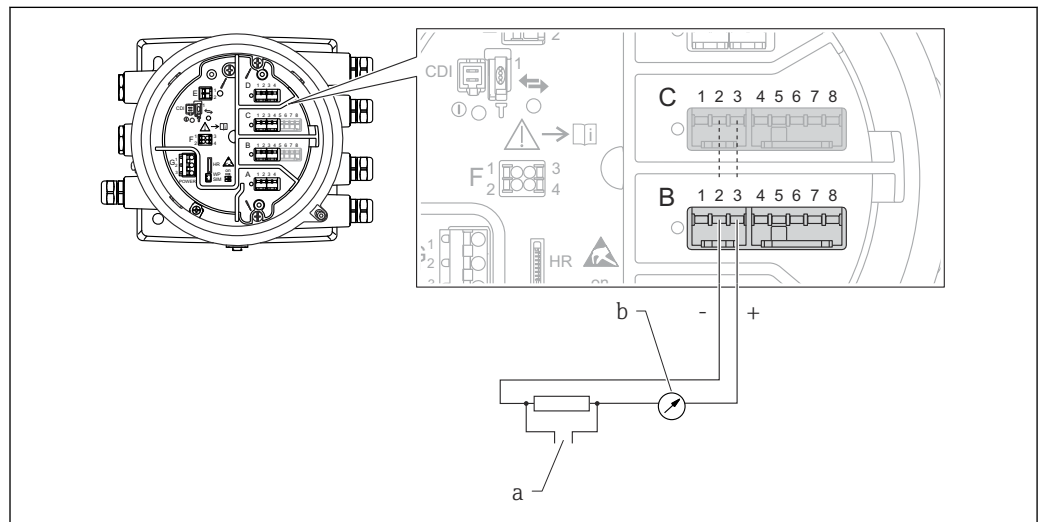
a Power supply

b Up to 6 external devices with HART signal output

### 6.1.8 Connection of the "Analog I/O" module for active usage

- i** In the active usage the supply voltage for the communication line is supplied by the device itself. There is no need of an external power supply.
  - The wiring must be in accordance with the intended operating mode of the Analog I/O module; see the drawings below.
- i** Maximum current consumption of the connected HART devices: 24 mA (i.e. 4 mA per device if 6 devices are connected).
  - Output voltage of the Ex-d module: 17.0 V@4 mA to 10.5 V@22 mA
  - Output voltage of the Ex-ia module: 18.5 V@4 mA to 12.5 V@22 mA

"Operating mode" = "4..20mA output" or "HART slave +4..20mA output"

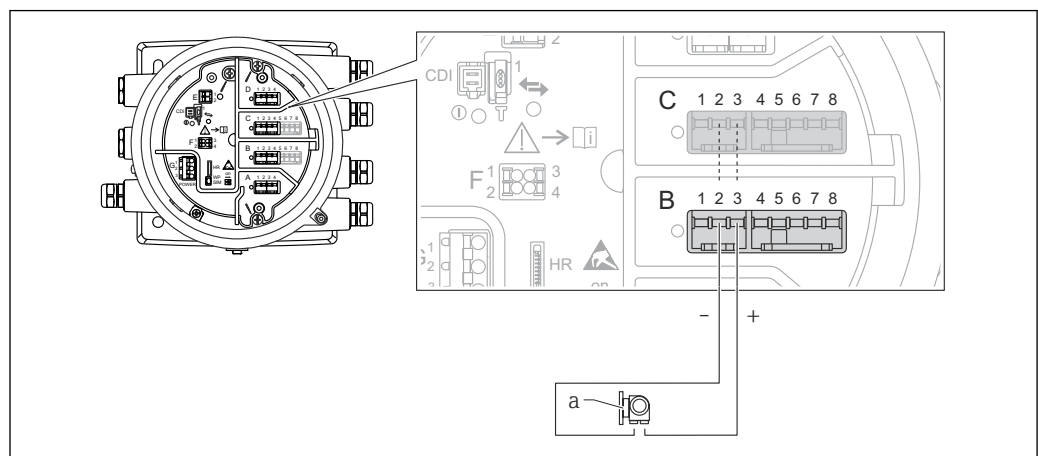


A0027932

26 Active usage of the Analog I/O module in the output mode

- a HART signal output
- b Analog signal evaluation

"Operating mode" = "4..20mA input" or "HART master+4..20mA input"

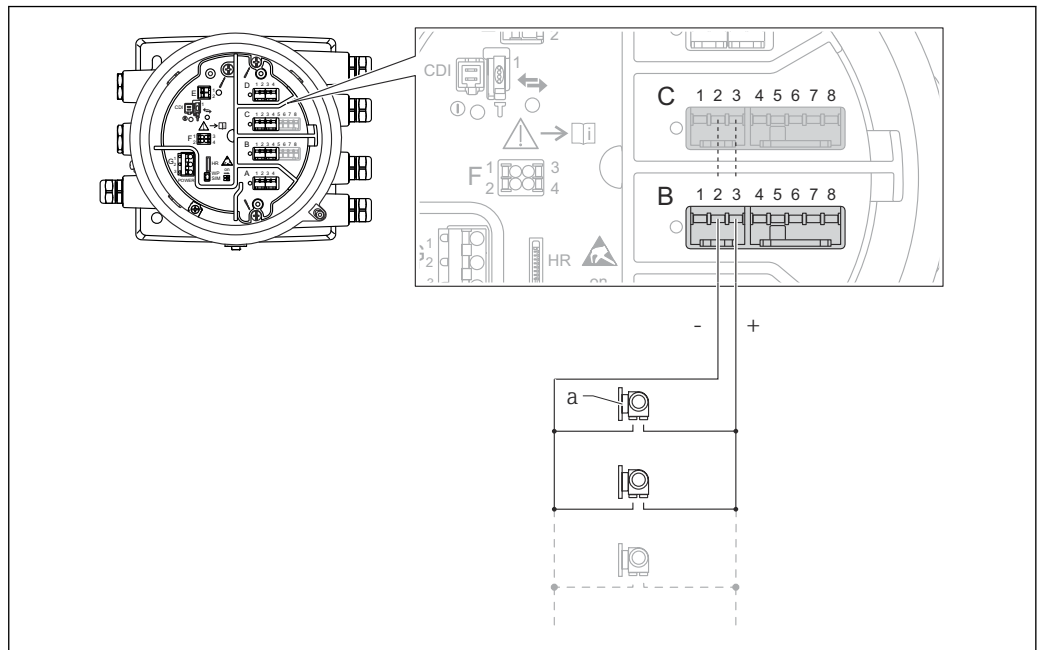


A0027935

27 Active usage of the Analog I/O module in the input mode

- a External device with 4...20mA and/or HART signal output

**"Operating mode" = "HART master"**



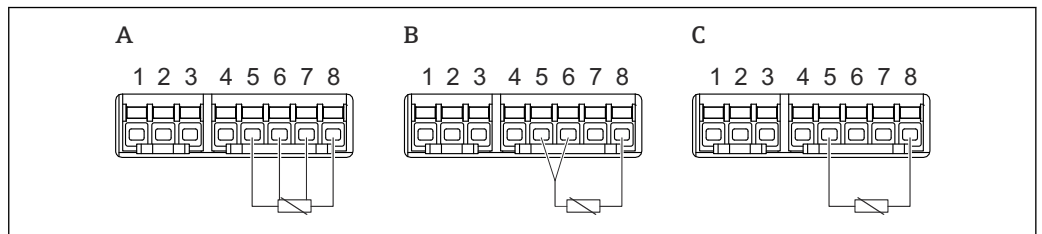
A0027936

28 Active usage of the Analog I/O module in the HART master mode

a Up to 6 external devices with HART signal output

**i** The maximum current consumption for the connected HART devices is 24 mA (i.e. 4 mA per device if 6 devices are connected).

**6.1.9 Connection of a RTD**



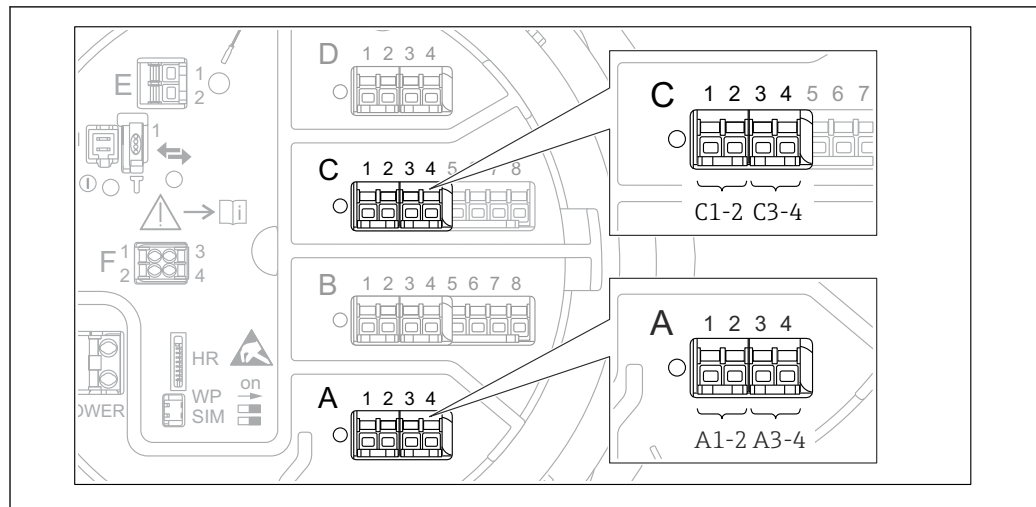
A0026371

A 4-wire RTD connection

B 3-wire RTD connection

C 2-wire RTD connection

### 6.1.10 Terminals of the "Digital I/O" module



A0026424

29 Designation of the digital inputs or outputs (examples)

- Each Digital IO Module provides two digital inputs or outputs.
- In the operating menu each input or output is designated by the respective slot and two terminals within this slot. **A1-2**, for example, denotes terminals 1 and 2 of slot **A**. The same is valid for slots **B**, **C** and **D** if they contain a Digital IO module.
- For each of these pairs of terminals, one of the following operating modes can be selected in the operating menu:
  - Disable
  - Passive Output
  - Passive Input
  - Active Input

## 6.2 Connecting requirements

### 6.2.1 Cable specification

#### Terminals

**Wire cross section 0.2 to 2.5 mm<sup>2</sup> (24 to 13 AWG)**

Use for terminals with function: Signal and power supply

- Spring terminals (NMx8x-xx1...)
- Screw terminals (NMx8x-xx2...)

**Wire cross section max. 2.5 mm<sup>2</sup> (13 AWG)**

Use for terminals with function: Ground terminal in the terminal compartment

**Wire cross section max. 4 mm<sup>2</sup> (11 AWG)**

Use for terminals with function: Ground terminal at the housing

#### Power supply line

Standard device cable is sufficient for the power line.

#### HART communication line

- Standard device cable is sufficient if only the analog signal is used.
- Shielded cable is recommended if using the HART protocol. Observe the grounding concept of the plant.

#### Modbus communication line

- Observe the cable conditions from the TIA-485-A, Telecommunications Industry Association.
- Additional conditions: Use shielded cable.

#### V1 communication line

- 2-wire twisted pair, screened or unscreened cable
- Resistance in one cable:  $\leq 120 \Omega$
- Capacitance between lines:  $\leq 0.3 \mu\text{F}$

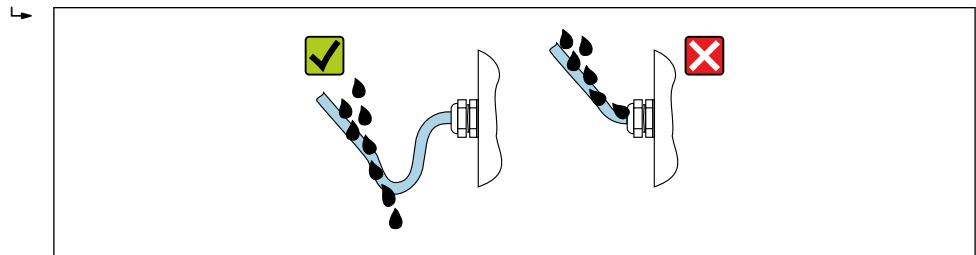
#### WM550 communication line

- 2-wire twisted pair, unscreened cable
- Cross section minimum 0.5 mm<sup>2</sup> (20 AWG)
- Maximum total cable resistance:  $\leq 250 \Omega$
- Cable with low capacitance

### 6.3 Ensuring the degree of protection

To guarantee the specified degree of protection, carry out the following steps after the electrical connection:

1. Check that the housing seals are clean and fitted correctly. Dry, clean or replace the seals if necessary.
2. Tighten all housing screws and screw covers.
3. Firmly tighten the cable glands.
4. To ensure that moisture does not enter the cable entry, route the cable so that it loops down before the cable entry ("water trap").



A0029278


5. Insert blind plugs appropriate for the safety rating of the device (e.g. Ex d/XP).





### 6.4 Post-connection check

<input type="radio"/>	Are cables or the device undamaged (visual inspection)?
<input type="radio"/>	Do the cables comply with the requirements?
<input type="radio"/>	Do the cables have adequate strain relief?
<input type="radio"/>	Are all cable glands installed, firmly tightened and correctly sealed?
<input type="radio"/>	Does the supply voltage match the specifications on the transmitter nameplate?
<input type="radio"/>	Is the terminal assignment correct → 44?
<input type="radio"/>	If required: Is the protective earth connected correctly ?
<input type="radio"/>	If supply voltage is present: Is the device ready for operation and do values appear on the display module?
<input type="radio"/>	Are all housing covers installed and firmly tightened?
<input type="radio"/>	Is the securing clamp tightened correctly?

## 7 Operability

### 7.1 Overview of the operation options

The device is operated via an operating menu (→  68). This menu can be accessed by the following interfaces:

- The display and operating module at the device or the remote display and operating module DKX001 (→  69).
- FieldCare connected through the service interface in the terminal compartment of the device (→  81).
- FieldCare connected through Tankvision Tank Scanner NXA820 (remote operation; →  81).
- FieldCare connected through Commubox FXA195 (→  165) to a HART interface of the device.



Confirm that the servo motor stops before changing parameters for safety use.

## 7.2 Structure and function of the operating menu

Menu	Submenu / parameter	Meaning
<b>Operation</b>	Proservo parameters	Contains parameters to operate Proservo (e.g. Gauge command).
	<b>Level</b>	Shows the measured and calculated level values.
	<b>Temperature</b>	Shows the measured and calculated temperature values.
	<b>Density</b>	Shows the measured and calculated density values.
	<b>Pressure</b>	Shows the measured and calculated pressure values.
	<b>GP values</b>	Shows the general purpose values.
<b>Setup</b>	Standard parameters	Standard commissioning parameters
	<b>Calibration</b>	Calibration of the measurement
	<b>Advanced setup</b>	Contains further parameters and submenus: <ul style="list-style-type: none"> <li>▪ to adapt the device to special measuring conditions.</li> <li>▪ to process the measured value.</li> <li>▪ to configure the signal output.</li> </ul>
<b>Diagnostics</b>	Diagnostic parameters	Indicates: <ul style="list-style-type: none"> <li>▪ The latest diagnostic messages and their timestamps.</li> <li>▪ The operating time (overall time and time since last restart).</li> <li>▪ The time according to the real-time clock.</li> </ul>
	<b>Diagnostic list</b>	Contains up to 5 currently active error messages.
	<b>Device information</b>	Contains information needed to identify the device.
	<b>Simulation</b>	Used to simulate measured values or output values.
	<b>Device check</b>	Contains all parameters needed to check the measurement capability of the device.
<b>Expert</b> <sup>1)</sup> Contains all parameters of the device (including those which are already contained in one of the other menus). This menu is organized according to the function blocks of the device. The parameter of the <b>Expert</b> menu are described in: GP01077G (NMS81)	<b>System</b>	Contains all general device parameters which do not affect the measurement or the communication interface.
	<b>Sensor</b>	Contains all parameters needed to configure the measurement.
	<b>Input/output</b>	Contains submenus to configure the analog and discrete I/O modules and connected HART devices.
	<b>Communication</b>	Contains all parameters needed to configure the digital communication interface.
	<b>Application</b>	Contains submenus to configure <ul style="list-style-type: none"> <li>▪ the tank gauging application</li> <li>▪ the tank calculations</li> <li>▪ the alarms.</li> </ul>



Menu	Submenu / parameter	Meaning
	Tank values	Shows measured and calculated tank values
	Diagnostics	Contains all parameters needed to detect and analyze operational errors.

- 1) On entering the "Expert" menu, an access code is always requested. If a customer specific access code has not been defined, "0000" has to be entered.

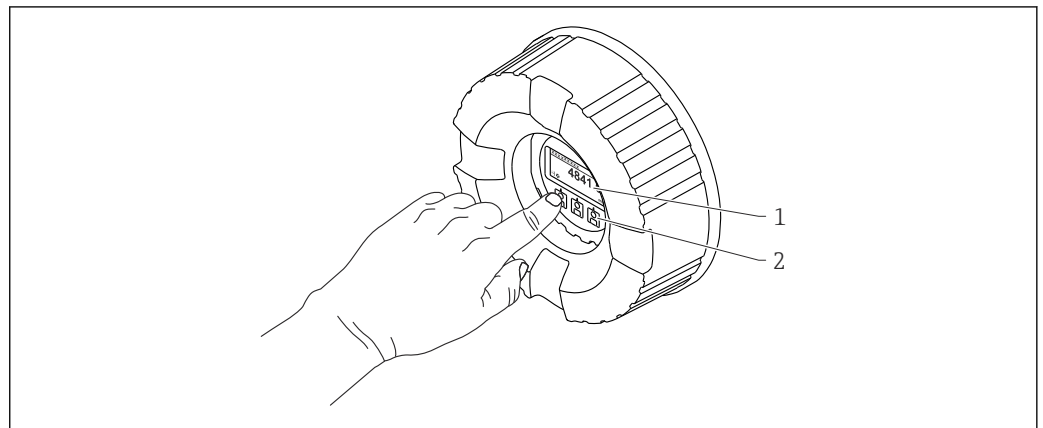
### 7.3 Access to the operating menu via the local or remote display and operating module

- i
  - Operating via the remote display and operating module DKX001 (→ 46) or the local display and operating module at the device are equivalent.
  - The measured value is indicated on the DKX001 and on the local display and operating module simultaneously.
  - The operating menu cannot be accessed on both modules at the same time. If the operating menu is entered in one of these modules, the other module is automatically locked. This locking remains active until the menu is closed in the first module (back to measured value display).

#### 7.3.1 Display and operating elements

The device has an illuminated **liquid crystal display (LCD)** that shows measured and calculated values as well as the device status in the standard view. Other views are used to navigate through the operating menu and to set parameter values.

The device is operated by **three optical keys**, namely "-", "+" and "E". They are actuated when the appropriate field on the protective glass of the front is **lightly** touched with the finger ("touch control").

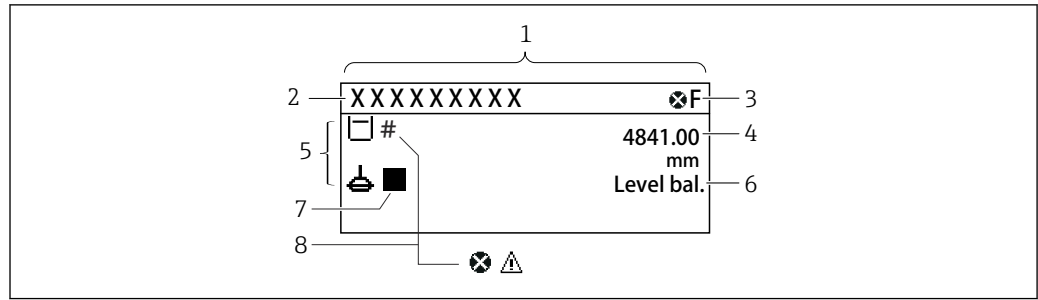


A0028345

i 30 Display and operating elements

- 1 Liquid crystal display (LCD)
- 2 Optical keys; can be operated through the cover glass. If used without the cover glass, lightly place your finger in front of the optical sensor for activation. Do not press hard.

### 7.3.2 Standard view (measured value display)



A0028702

31 Typical appearance of the standard view (measured value display)





























- 1 Display module
- 2 Device tag
- 3 Status area
- 4 Display area for measured values
- 5 Display area for measured value and status symbols
- 6 Gauge status indication
- 7 Gauge status symbol
- 8 Measured value status symbol

#### Status symbols












Symbol	Meaning
<b>F</b> A0013956	<b>"Failure"</b> A device error is present. The measured value is no longer valid.
<b>C</b> A0013959	<b>"Function check"</b> The device is in service mode (e.g. during a simulation).
<b>S</b> A0013958	<b>"Out of specification"</b> The device is operated: <ul style="list-style-type: none"> <li>▪ Outside of its technical specifications (e.g. during startup or a cleaning)</li> <li>▪ Outside of the configuration carried out by the user (e.g. level outside configured span)</li> </ul>
<b>M</b> A0013957	<b>"Maintenance required"</b> Maintenance is required. The measured value is still valid.

#### Measured value symbols





Symbol 1	Symbol 2	Measured value
 A0028148		<ul style="list-style-type: none"> <li>▪ Tank level</li> <li>▪ Measured level</li> <li>▪ Tank level %</li> </ul>
 A0028149		Water level
<b>T</b> A0028528		Liquid temperature
<b>T</b> A0028528	<b>U</b> A0027990	Vapor temperature
<b>T</b> A0028528	<b>A</b> A0027991	Air temperature
 A0027993		<ul style="list-style-type: none"> <li>▪ Tank ullage</li> <li>▪ Tank ullage %</li> </ul>
<b>ρ</b> A0028150		Observed density value

Symbol 1	Symbol 2	Measured value
 A0028150	 A0027991	Average profile density
 A0028151	 A0028141	P1 (bottom)
 A0028151	 A0028142	P2 (middle)
 A0028151	 A0028146	P3 (top)
 A0027992	 A0028141	GP 1 value This is used for an external device.
 A0027992	 A0028142	GP 2 value This is used for an external device.
 A0027992	 A0028146	GP 3 value This is used for an external device.
 A0027992	 A0028147	GP 4 value This is used for an external device.
 A0028149	 A0028529	Upper I/F level
 A0028149	 A0027989	Lower I/F level
 A0028150	 A0028529	Upper density
 A0028150	 A0013957	Middle density
 A0028150	 A0027989	Lower density
 A0028145		Bottom level
 A0027994		Displacer position



Gauge command and gauge status symbols

Symbol 1	Symbol 2	Meaning
 A0028139		Gauge command This shows current command.
 A0028143	 A0028144	Gauge status  : Displacer is unbalanced (Level/Interface not found yet).  : Displacer is balanced (Level/Interface measurement valid).  : Displacer is moving up.  : Displacer is moving down.  : Displacer stopped.
 A0027995	 A0028138	
 A0028140		


*Measured value status symbols*

Symbol	Meaning
 A0012102	<b>Status "Alarm"</b> The measurement is interrupted. The output assumes the defined alarm value. A diagnostic message is generated.
 A0012103	<b>Status "Warning"</b> The device continues measuring. A diagnostic message is generated.
 A0031169	<b>Calibration to regulatory standards disturbed</b> Is displayed in the following situations: <ul style="list-style-type: none"> <li>▪ The write protection switch is OFF. →  79</li> <li>▪ The write protection switch is ON but the level value can currently not be guaranteed because the displacer is not balanced.</li> </ul>

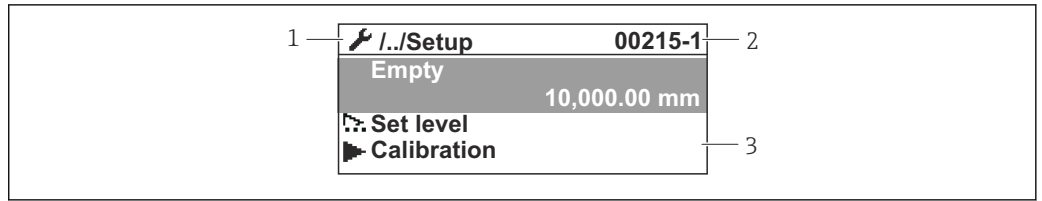
*Locking state symbols*

Symbol	Meaning
 A0011978	<b>Display parameter</b> Marks display-only parameters which cannot be edited.
 A0011979	<b>Device locked</b> <ul style="list-style-type: none"> <li>▪ In front of a parameter name: The device is locked via software and/or hardware.</li> <li>▪ In the header of the measured value screen: The device is locked via hardware.</li> </ul>

*Meaning of the keys in the standard view*

Key	Meaning
 A0028326	<b>Enter key</b> <ul style="list-style-type: none"> <li>▪ Pressing the key briefly opens the operating menu.</li> <li>▪ Pressing the key for 2 s opens the context menu: <ul style="list-style-type: none"> <li>▪ <b>Level</b> (visible if the keylock is inactive): Shows the measured levels.</li> <li>▪ <b>Keylock on</b> (visible if the keylock is inactive): Activates the keylock.</li> <li>▪ <b>Keylock off</b> (visible if the keylock is active): Deactivates the keylock.</li> </ul> </li> </ul>

### 7.3.3 Navigation view



A0047115





32 Navigation view

- 1 Current submenu or wizard
- 2 Quick access code
- 3 Display area for navigation

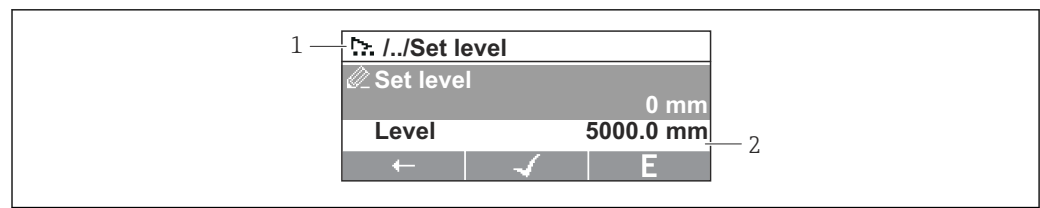
#### Navigation symbols

Symbol	Meaning
 A0011975	<b>Operation</b> Is displayed: <ul style="list-style-type: none"> <li>▪ in the main menu next to the selection <b>Operation</b></li> <li>▪ in the header, if you are in the <b>Operation</b> menu.</li> </ul>
 A0011974	<b>Setup</b> Is displayed: <ul style="list-style-type: none"> <li>▪ in the main menu next to the selection <b>Setup</b></li> <li>▪ in the header, if you are in the <b>Setup</b> menu</li> </ul>
 A0011976	<b>Expert</b> Is displayed: <ul style="list-style-type: none"> <li>▪ in the main menu next to the selection <b>Expert</b></li> <li>▪ in the header, if you are in the <b>Expert</b> menu</li> </ul>
 A0011977	<b>Diagnostics</b> Is displayed: <ul style="list-style-type: none"> <li>▪ in the main menu next to the selection <b>Diagnostics</b></li> <li>▪ in the header, if you are in the <b>Diagnostics</b> menu</li> </ul>
 A0013967	<b>Submenu</b>
 A0013968	<b>Wizard</b>
 A0013963	<b>Parameter locked</b> When displayed in front of a parameter name, indicates that the parameter is locked.


*Meaning of the keys in the navigation view*

Key	Meaning
 <small>A0028324</small>	<b>Minus key</b> Moves the selection bar upwards in a picklist.
 <small>A0028325</small>	<b>Plus key</b> Moves the selection bar downwards in a picklist.
 <small>A0028326</small>	<b>Enter key</b> <ul style="list-style-type: none"> <li>Pressing the key briefly opens the selected menu, submenu or parameter.</li> <li>For parameters: Pressing the key for 2 s opens the help text for the function of the parameter (if present).</li> </ul>
 <small>A0028327</small>	<b>Escape key combination (press keys simultaneously)</b> <ul style="list-style-type: none"> <li>Pressing the keys briefly                             <ul style="list-style-type: none"> <li>Exits the current menu level and takes you to the next higher level.</li> <li>If help text is open, closes the help text of the parameter.</li> </ul> </li> <li>Pressing the keys for 2 s returns you to the measured value display ("standard view").</li> </ul>

**7.3.4 Wizard view**








A0047116

 33 Wizard view on the display module

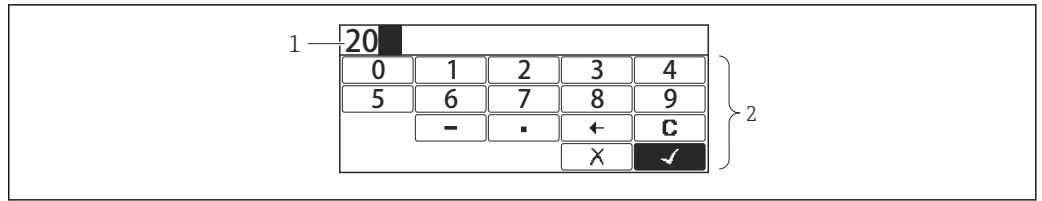
- 1 Current wizard
- 2 Display area for navigation

*Wizard navigation symbols*

Symbol	Meaning
 <small>A0013972</small>	Parameters within a wizard
 <small>A0013978</small>	Switches to the previous parameter.
 <small>A0013976</small>	Confirms the parameter value and switches to the next parameter.
 <small>A0013977</small>	Opens the editing view of the parameter.

 In the wizard view the meaning of the keys is indicated by the navigation symbol directly above the respective key (softkey functionality).








### 7.3.5 Numeric editor







A0028341

34 Numeric editor on the display module

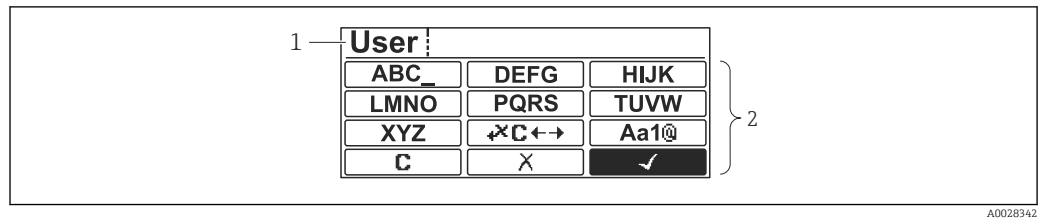
- 1 Display area of the entered value
- 2 Input mask

Symbol	Meaning
 <p>A0013998</p>	Selection of numbers from 0 to 9.
 <p>A0016619</p>	Inserts decimal separator at the input position.
 <p>A0016620</p>	Inserts minus sign at the input position.
 <p>A0013985</p>	Confirms selection.
 <p>A0016621</p>	Moves the input position one position to the left.
 <p>A0013986</p>	Exits the input without applying the changes.
 <p>A0014040</p>	Clears all entered characters.

#### Meaning of the keys in the numeric editor

Key	Meaning
 <p>A0028324</p>	<b>Minus key</b> In the input mask, moves the selection bar to the left (backwards).
 <p>A0028325</p>	<b>Plus key</b> In the input mask, moves the selection bar to the right (forwards).
 <p>A0028326</p>	<b>Enter key</b> <ul style="list-style-type: none"> <li>■ Pressing the key briefly adds the selected number to the current decimal place or carries out the selected action.</li> <li>■ Pressing the key for 2 s confirms the edited parameter value.</li> </ul>
 <p>A0028327</p>	<b>Escape key combination (press keys simultaneously)</b> Closes the text or numeric editor without applying changes.

### 7.3.6 Text editor



A0028342

35 Text editor on the display module

- 1 Display area of the entered text
- 2 Input mask

#### Text editor symbols





Symbol	Meaning
  <small>A0013997</small>	Selection of letters from A to Z
 <small>A0013981</small>	Toggle <ul style="list-style-type: none"> <li>▪ Between upper-case and lower-case letters</li> <li>▪ For entering numbers</li> <li>▪ For entering special characters</li> </ul>
 <small>A0013985</small>	Confirms selection.
 <small>A0013987</small>	Switches to the selection of the correction tools.
 <small>A0013986</small>	Exits the input without applying the changes.
 <small>A0014040</small>	Clears all entered characters.

#### Correction symbols under

 <small>A0013989</small>	Clears all entered characters.
 <small>A0013991</small>	Moves the input position one position to the right.
 <small>A0013990</small>	Moves the input position one position to the left.
 <small>A0013988</small>	Deletes one character immediately to the left of the input position.



### Meaning of the keys in the text editor

Key	Meaning
 A0028324	<b>Minus key</b> In the input mask, moves the selection bar to the left (backwards).
 A0028325	<b>Plus key</b> In the input mask, moves the selection bar to the right (forwards).
 A0028326	<b>Enter key</b> <ul style="list-style-type: none"> <li>▪ Pressing the key briefly               <ul style="list-style-type: none"> <li>▪ Opens the selected group.</li> <li>▪ Carries out the selected action.</li> </ul> </li> <li>▪ Pressing the key for 2 s confirms the edited parameter value.</li> </ul>
 A0028327	<b>Escape key combination (press keys simultaneously)</b> Closes the text or numeric editor without applying changes.

## 7.3.7 Keypad lock

### Automatic keypad lock


Operation via the local display is automatically locked:

- after a start-up or restart of the device.
- if the device has not been operated via the display for > 1 minute.




When attempting to access the operating menu while the keylock is enabled, the **Keylock on** message appears.

### Disabling the keypad lock

1. The keylock is enabled.  
 Press  for at least 2 seconds.  
 ↳ A context menu appears.
2. Select **Keylock off** from the context menu.  
 ↳ The keylock is disabled.

### Manual activation of the keypad lock

After commissioning of the device the keypad lock can be activated manually.


1. The device is in the measured value display.  
 Press  for at least 2 seconds.  
 ↳ A context menu appears.
2. Select **Keylock on** from the context menu.  
 ↳ The keylock is enabled.

## 7.3.8 Access code and user roles


### Meaning of the access code

An access code can be defined in order to distinguish between the following user roles:


User role	Definition
<b>Maintenance</b>	<ul style="list-style-type: none"> <li>▪ Knows the access code.</li> <li>▪ Has write access to all parameters (except service parameters).</li> </ul>
<b>Operator</b>	<ul style="list-style-type: none"> <li>▪ Doesn't know the access code.</li> <li>▪ Has write access to only a few parameters.</li> </ul>



-  The description of parameters states which role is needed at least for read and write access to each parameter.
- The current user role is indicated by the Access status display.
- If the access code is "0000", every user is in the **Maintenance** role. This is the default setting on delivery of the device.

### Defining an access code

1. Navigate to: Setup → Advanced setup → Administration → Define access code → Define access code
2. Enter the intended access code (max. 4 digits).
3. Repeat the same code in the Confirm access code.
  - ↳ The user is in the **Operator** role. The -symbol appears in front of all write-protected parameters.

### Switching to the "Maintenance" role

If the -symbol appears on the local display in front of a parameter, the parameter is write-protected because the user is in the **Operator** role. To switch to the **Maintenance** role, proceed as follows:

1. Press .
  - ↳ The input prompt for the access code appears.
2. Enter the access code.
  - ↳ The user is in the **Maintenance** role. The -symbol in front of the parameters disappears; all previously write-protected parameters are now re-enabled.

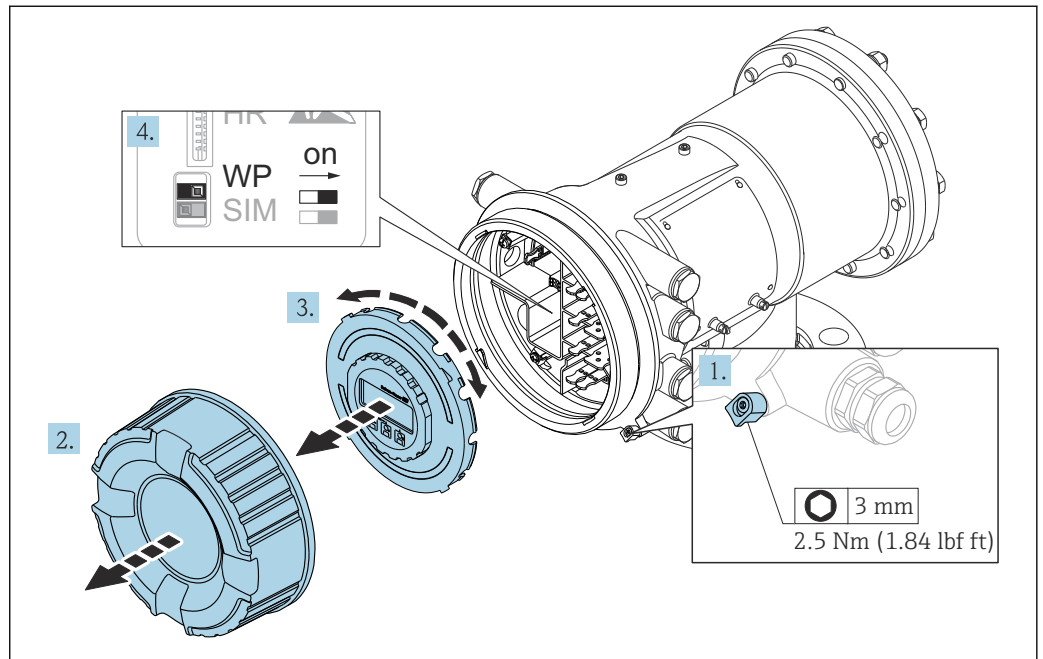
### Switching back to the "Operator" role automatically

The user automatically switches back to the **Operator** role:

- if no key is pressed for 10 minutes in the navigation and editing mode.
- 60 s after going back from the navigation and editing mode to the standard view (measured value display).

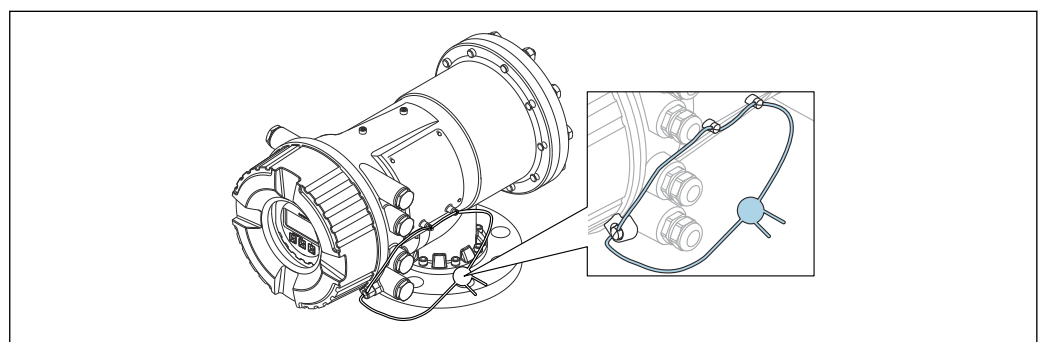
### 7.3.9 Write protection switch

The operating menu can be locked by a hardware switch in the connection compartment. In this locking state W&M related parameters are read only.



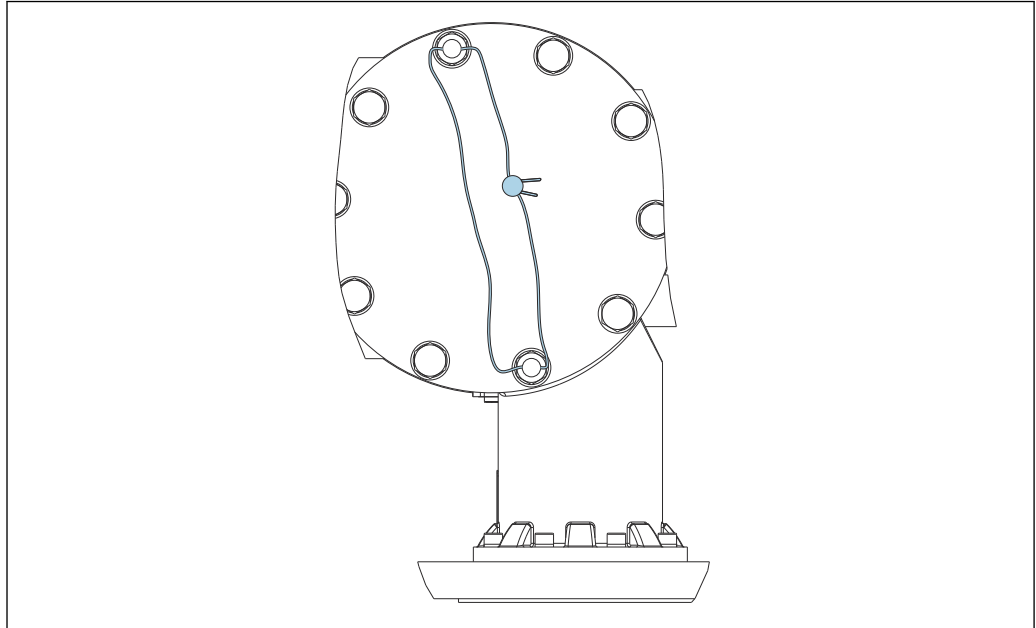
A0028693

- i** The display module can be attached to the edge of the electronics compartment. This makes it easier to access the lock switch.
  - 1. Loosen the securing clamp.
  - 2. Unscrew the housing cover.
  - 3. Pull out the display module with a gentle rotation movement.
  - 4. Using a flat blade screwdriver or a similar tool, set the write protection switch (**WP**) into the desired position. **ON**: operating menu is locked; **OFF**: operating menu is unlocked.
  - 5. Put the display module onto the connection compartment, screw the cover closed and tighten the securing clamp.
- i** To avoid access to the write protection switch, the cover of the connection compartment can be secured by a lead seal.



A0033285

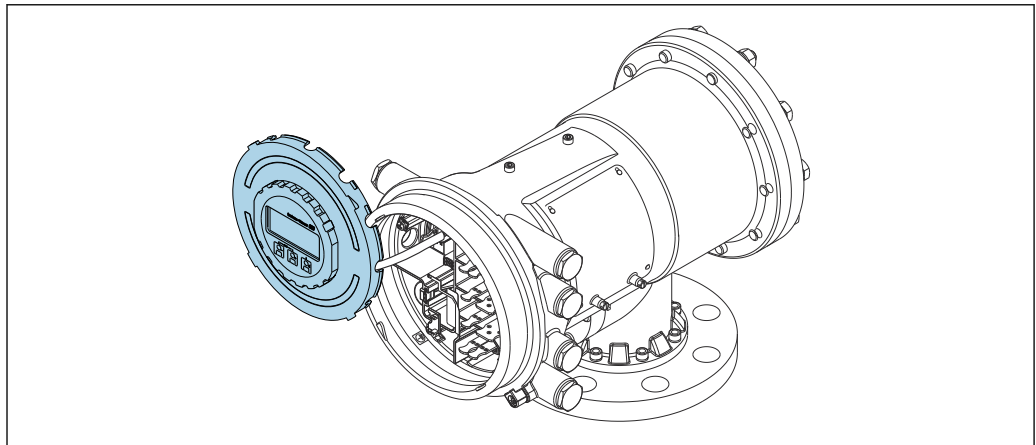
**36** Sealing of the cover of the connection compartment



A0033452

37 Sealing of the rear cover (e.g. NMS81/NMS83)

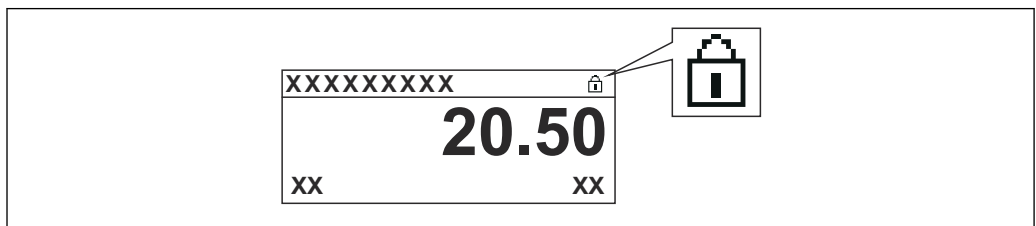
**i** For LNE approval, bolts at built in flange additionally must be secured by a lead seal.



A0028695

38 NMS81: Display module attached to the edge of the terminal compartment

**Indication of the locking state**



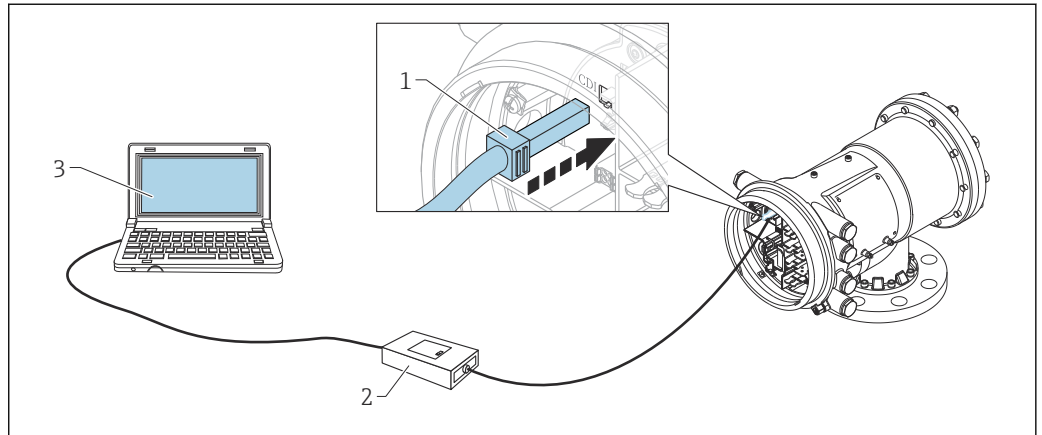
A0015870

39 Write protection symbol in the header of the display

Write protection via locking switch is indicated as follows:

- **Locking status** (→ **212**) = **Hardware locked**
- **🔒** appears in the header of the display.

## 7.4 Access to the operating menu via the service interface and FieldCare



A0026993

40 Operation via service interface

- 1 Service interface (CDI = Endress+Hauser Common Data Interface)
- 2 Commubox FXA291
- 3 Computer with "FieldCare" operating tool and "CDI Communication FXA291" COM DTM

### **i** The "Save/Restore" function

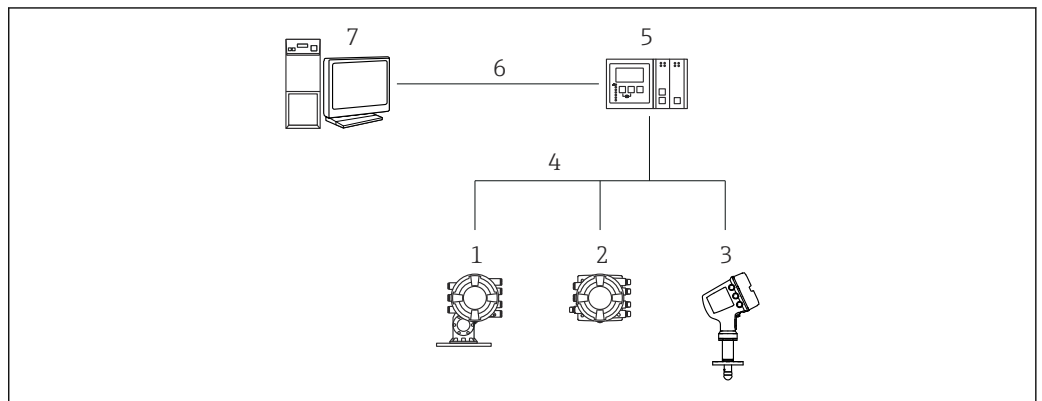
After a device configuration has been saved to a computer and restored to the device using the **Save/Restore** function of FieldCare, the device must be restarted by the following setting:

**Setup** → **Advanced setup** → **Administration** → **Device reset** = **Restart device**.

This ensures correct operation of the device after the restore.

## 7.5 Access to the operating menu via Tankvision Tank Scanner NXA820 and FieldCare

### 7.5.1 Wiring scheme



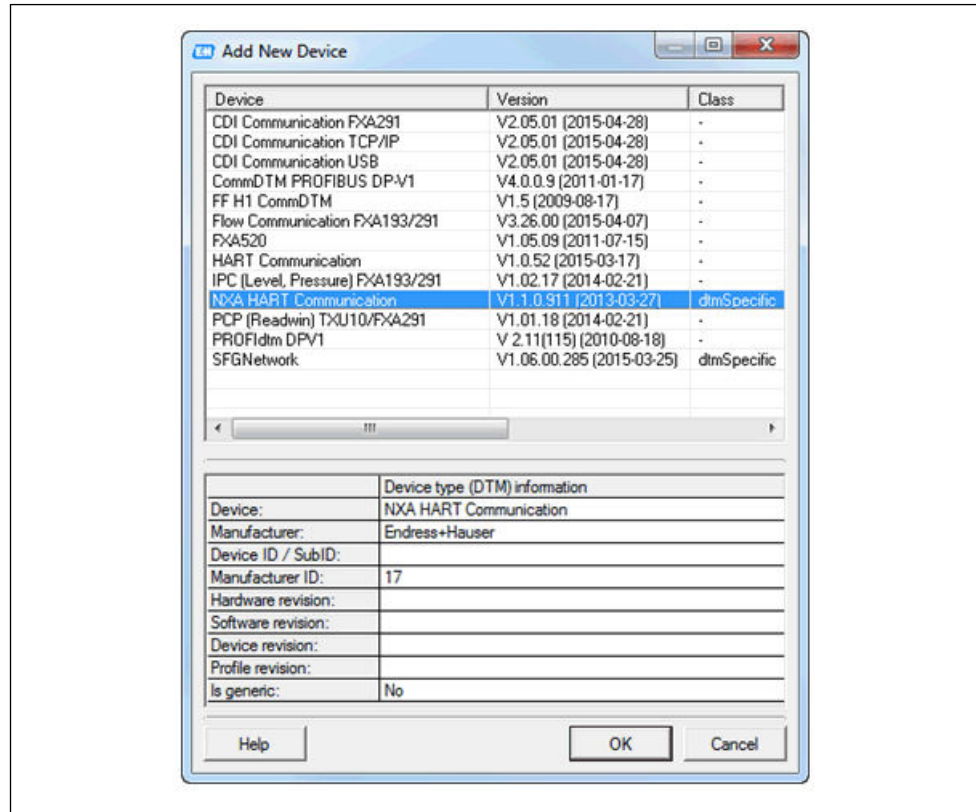
A0025621

41 Connection of Tank Gauging devices to FieldCare via the Tankvision Tank Scanner NXA820

- 1 Proservo NMS8x
- 2 Tankside Monitor NRF81
- 3 Micropilot NMR8x
- 4 Field protocol (e.g. Modbus, V1)
- 5 Tankvision Tank Scanner NXA820
- 6 Ethernet
- 7 Computer with FieldCare installed

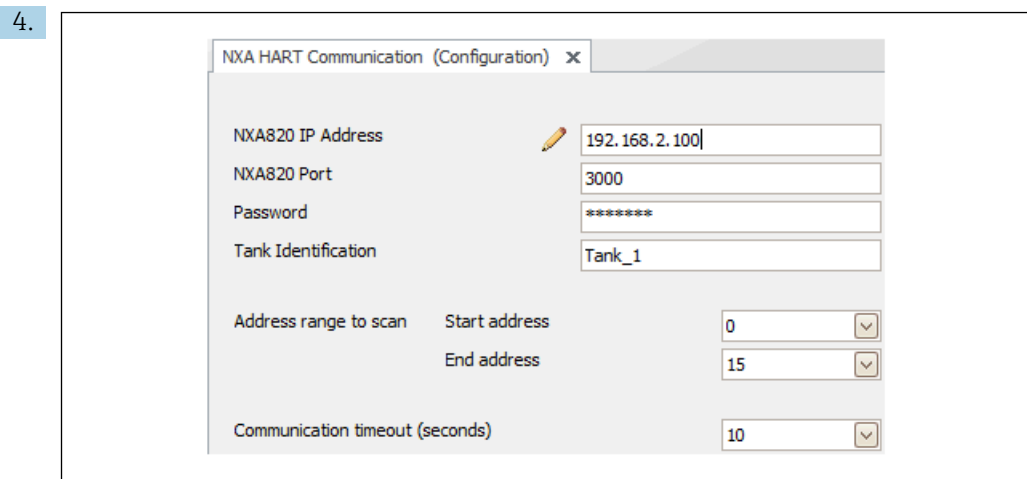
## 7.5.2 Establishing the connection between FieldCare and the device

1. Make sure the **HART CommDTM NXA** is installed and update the DTM catalogue if required.
2. Create a new project in FieldCare.
- 3.



A0028515

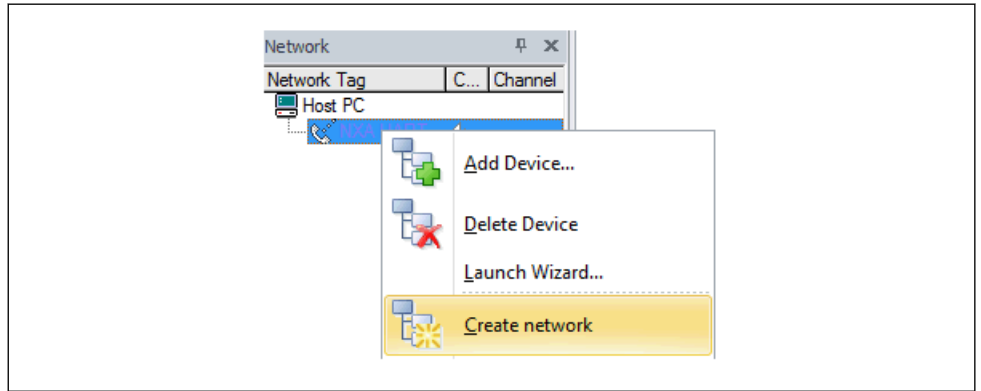
Add a new device: **NXA HART Communication**



A0028516

Open the configuration of the DTM and enter the required data (IP address of the NXA820; "Password" = "hart"; "Tank identification" only with NXA V1.05 or higher)

5.

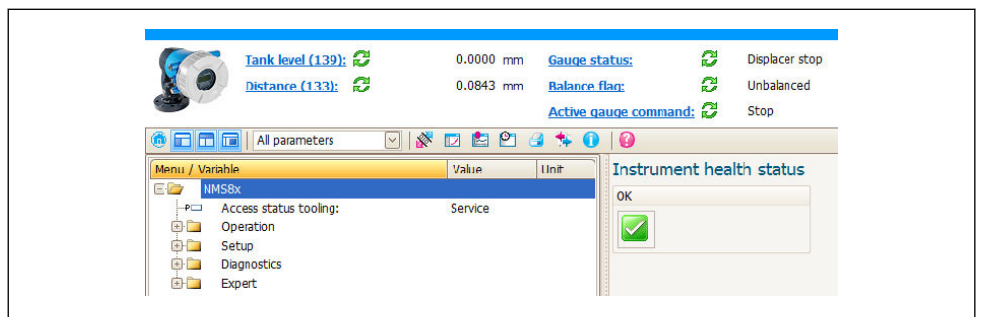


A0028517

Select **Create network** from the context menu.

↳ The device is detected and the DTM is assigned.

6.



A0032427

↳ The device can be configured.



**The "Save/Restore" function**

After a device configuration has been saved to a computer and restored to the device using the **Save/Restore** function of FieldCare, the device must be restarted by the following setting:

**Setup → Advanced setup → Administration → Device reset = Restart device.**

This ensures correct operation of the device after the restore.

## 8 System integration

### 8.1 Overview of the Device Description files (DTM)

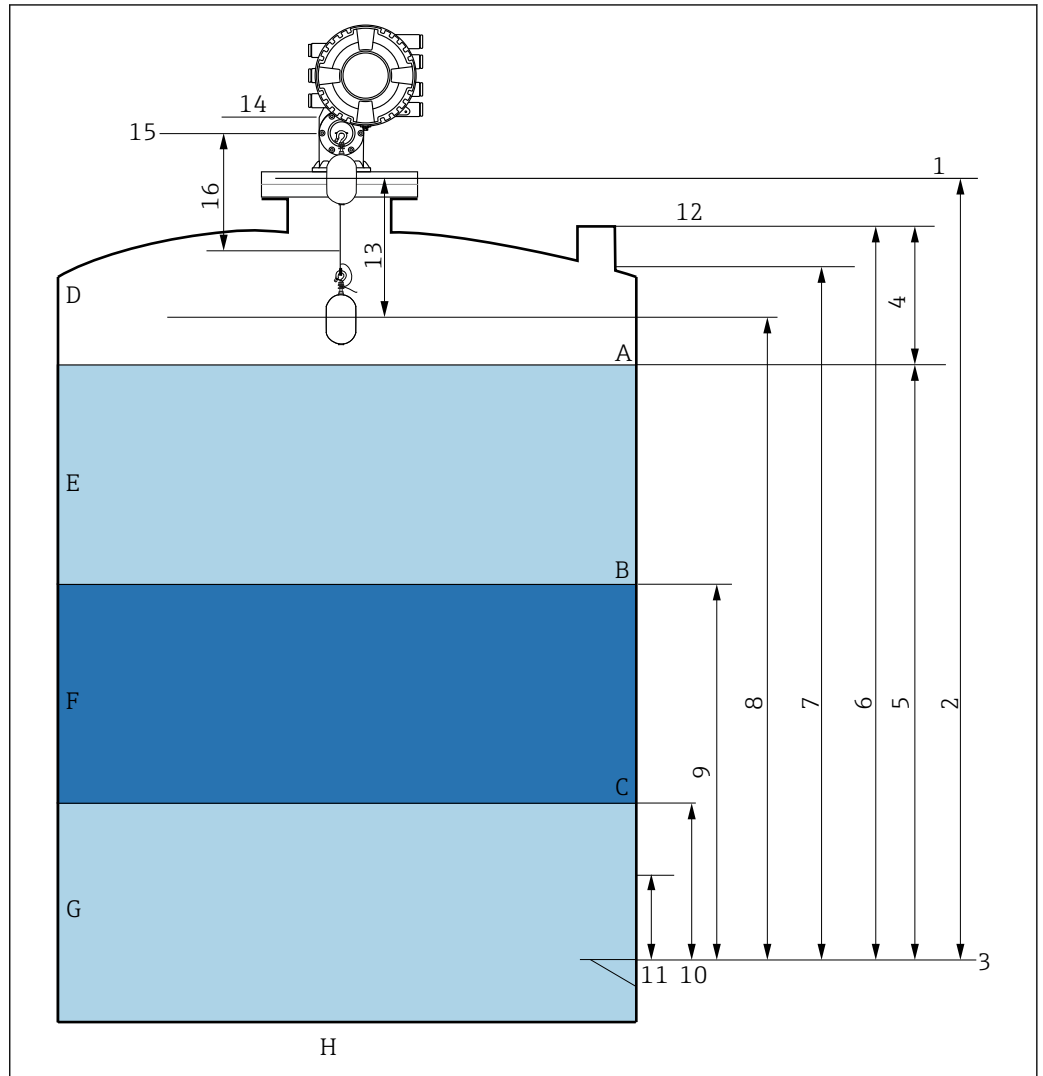
To integrate the device via HART into FieldCare, a Device Description file (DTM) according to the following specification is required:

Manufacturer ID	0x11
Device type (NMS8x)	0x112D
HART specification	7.0
DD files	For information and files see: <a href="http://www.endress.com">www.endress.com</a>



## 9 Commissioning

### 9.1 Terms related to tank measurement



42 Terms concerning NMS8x installation (e.g. NMS81)

- A Liquid level
- B Upper interface
- C Lower interface
- D Gas phase
- E Upper phase
- F Middle phase
- G Lower phase
- H Tank bottom
- 1 Gauge reference height
- 2 Empty
- 3 Datum plate
- 4 Tank ullage
- 5 Tank level
- 6 Tank reference height
- 7 High stop level (Adjustable)
- 8 Displacer position
- 9 Upper interface level
- 10 Lower interface level
- 11 Low stop level (Adjustable)
- 12 Dipping reference
- 13 Distance


- 14 Mechanical stop
- 15 Reference position
- 16 Slow hoist zone

## 9.2 Initial settings

Depending on NMS8x specification, some of the initial settings described below may not be required.


### 9.2.1 Setting the display language

#### Setting the display language via the display module

1. While in the standard view (→  70), press "E". If required, select **Keylock off** from the context menu and press "E" again.
  - ↳ The Language appears.
2. Open the Language and select the display language.

#### Setting the display language via an operating tool (e.g. FieldCare)

1. Navigate to: Setup → Advanced setup → Display → Language
2. Select the display language.

 This setting only affects the language on the display module. To set the language in the operating tool use the language setting functionality of FieldCare or DeviceCare, respectively.

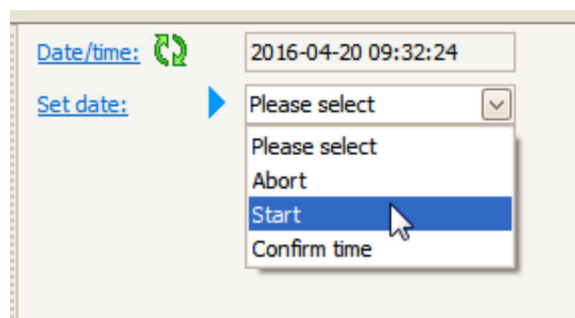
### 9.2.2 Setting the real-time clock

#### Setting the real-time clock via the display module

1. Navigate to: Setup → Advanced setup → Date / time → Set date
2. Use the following parameters to set the real-time clock to the current date and time:  
**Year, Month, Day, Hour, Minutes.**





#### Setting the real-time clock via an operating tool (e.g. FieldCare)

1. Navigate to: Setup → Advanced setup → Date / time
- 2.







Go to the Set date and select the Start.

3.

Date/time:		2016-04-20 09:34:25
Set date:	 	Please select 
Year:		2016
Month:		4
Day:		20
Hour:		9
Minute:		34

Use the following parameters to set the date and time: **Year, Month, Day, Hour, Minutes.**

4.

Date/time:		2016-04-20 09:35:49
Set date:	 	Please select 
Year:		
Month:		
Day:		
Hour:		9
Minute:		34

The dropdown menu for 'Set date' is open, showing the following options: Please select, Abort, Start, and Confirm time. A mouse cursor is pointing at the 'Confirm time' option.

Go to the Set date and select the Confirm time.

↳ The real-time clock is set to the current date and time.

## 9.3 Calibration

After installing or replacing NMS8x or its parts (sensor module, detector unit, wire drum, or measuring wire), Perform the following calibrations in this order.

1. Sensor calibration
2. Reference calibration
3. Drum calibration

All calibration steps may not be required, depending on whether the device is being installed, adjusted, or replaced (see the table below).

Type of installation/replacement		Calibration step		
		1. Sensor calibration	2. Reference calibration	3. Drum calibration
All-in one		Not required	Not required	Not required
Displacer shipped separately		Required	Required	Required
Displacer installation through calibration window		Required	Required	Required
Replacement/ maintenance	Wire drum	Required	Required	Required
	Displacer	Not required	Required	Required
	Sensor module/ Detector unit	Required	Required	Required

### 9.3.1 Verification of displacer and wire drum

Prior to installation of NMS8x, confirm that all of the following data of the displacer and the wire drum on the nameplate match with those programmed into the device.

#### Parameters to be confirmed

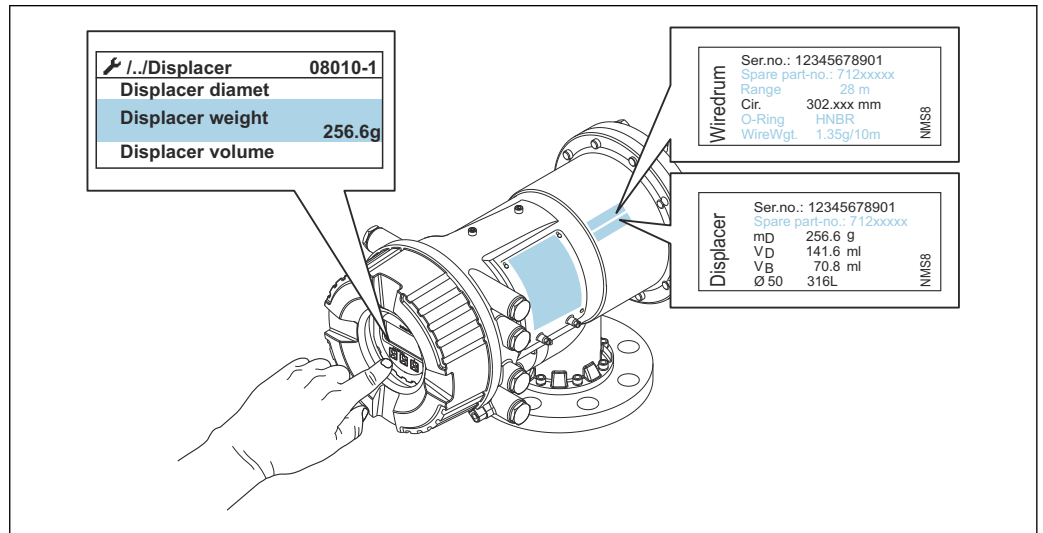
Parameters	Navigate to:
Displacer diameter	Setup → Advanced setup → Sensor config → Displacer → Displacer diameter
Displacer weight	Setup → Advanced setup → Sensor config → Displacer → Displacer weight
Displacer volume	Setup → Advanced setup → Sensor config → Displacer → Displacer volume
Displacer balance volume	Setup → Advanced setup → Sensor config → Displacer → Displacer balance volume
Drum circumference	Setup → Advanced setup → Sensor config → Wire drum
Wire weight	Expert → Sensor → Sensor config → Wire drum → Wire weight

## Data verification

### Data verification procedure

1. Check the displacer diameter, weight, volume, and balance volume for the Displacer diameter, the Displacer weight, the Displacer volume, and the Displacer balance volume.
2. Check the drum circumference and wire weight for the Drum circumference and Wire weight.

This completes the data verification procedure.



43 Data verification

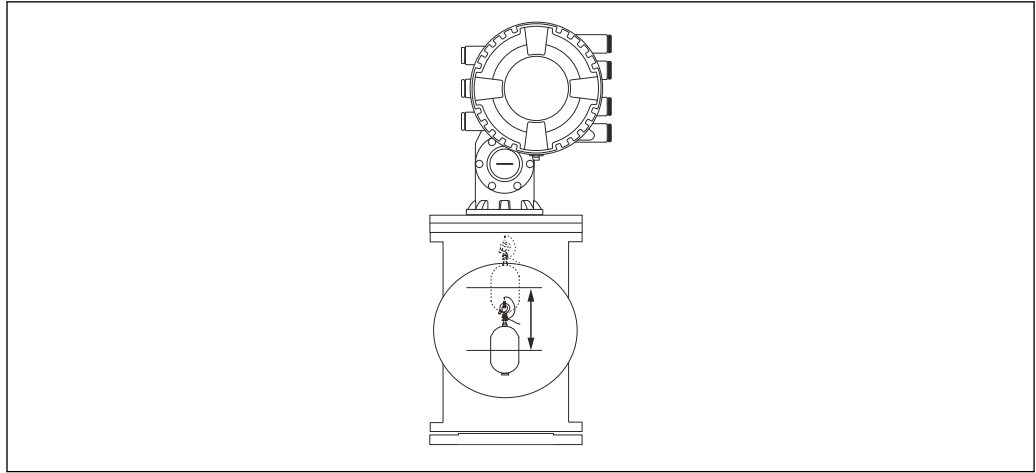
A0028697

### 9.3.2 Move displacer

The move displacer operation is optional and can be used to change the current position of the displacer in order to perform the calibration steps more easily.

1. Make sure that the wire drum stopper has been removed.
2. Navigate to: Setup → Calibration → Move displacer → Move distance
3. Input the relative moving distance for the Move distance.
4. Select the Move down or the Move up
5. Select the **Yes**.

This completes move displacer commands procedure.



A0029119

44 Move displacer

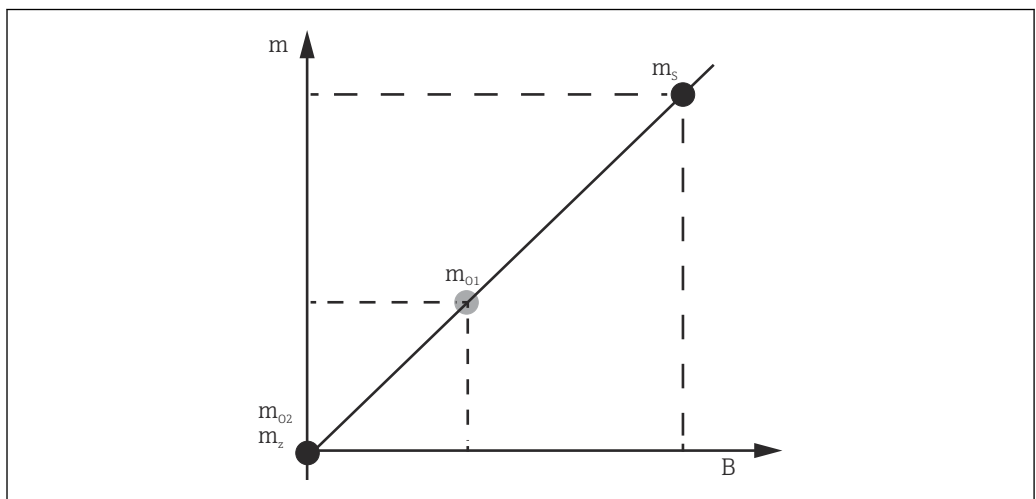
### 9.3.3 Sensor calibration

Sensor calibration adjusts the weight measurement of the detector unit. The calibration consists of three steps as follows.

- ADC zero calibration
- ADC offset calibration
- ADC span calibration

For the ADC offset weight calibration, either 0 g or an offset weight (0 to 100 g) can be used.

**i** Using an offset weight other than 0 g is recommended for density measurement.











A0029472

45 Concept of sensor calibration

- $m$  Weight of displacer  
 $B$  Binary value of AD-Converter  
 $m_s$  Span weight  
 $m_{o1}$  Offset weight in case of 0 to 100 g (50 g is recommended.)  
 $m_{o2}$  Offset weight in case of 0 g  
 $m_z$  Zero weight

Calibration procedure

Step	Using displacer	Using offset weight	Description
1.	 A0028000	 A0028000	<ul style="list-style-type: none"> <li>▪ Navigate to: Setup → Calibration → Sensor calibration → Sensor calibration</li> <li>▪ Input the offset weight for the Offset weight used in step 3 (0.0 g in case of using the displacer only).</li> <li>▪ Input the value for the Span weight used in step 4 (weight of displacer indicated on nameplate).</li> </ul>
2.	 A0027999	 A0028001	<ul style="list-style-type: none"> <li>▪ Hold up or remove the displacer.</li> <li>▪ Select <input checked="" type="checkbox"/> for next parameter.</li> <li>▪ Measuring zero weight is shown on the display.</li> <li>▪ Wait until the Zero calibration shows the Finished and calibration status shows Idle.</li> </ul> <p><b>i</b> When the displacer is being held up, do not release it until this step is completed.</p>
3.	 A0027999	 A0028002	<ul style="list-style-type: none"> <li>▪ Confirm that the Offset calibration shows the Place offset weight.</li> <li>▪ Hold up the displacer or attach the offset weight.</li> <li>▪ Select <input checked="" type="checkbox"/> for next parameter.</li> <li>▪ Measuring offset weight is shown on the display.</li> <li>▪ Wait until the Offset calibration shows the Finished and Calibration status shows Idle.</li> </ul> <p><b>i</b> When the displacer is being held up, do not release it until this step is completed.</p>
4.	 A0028000	 A0028000	<ul style="list-style-type: none"> <li>▪ Release the displacer or mount it on the measuring ring if an offset weight was used in the previous step.</li> <li>▪ Select <input checked="" type="checkbox"/> for next parameter.</li> <li>▪ Measuring span weight is shown on the display.</li> <li>▪ Confirm that the Span calibration shows the Finished and Calibration status shows Idle.</li> <li>▪ Select the Next.</li> <li>▪ Confirm that the Sensor calibration shows the Finished and Calibration status shows Idle.</li> </ul> <p>This completes sensor calibration procedure.</p> <p><b>i</b> Do not swing the displacer and keep it in as stable a position as possible.</p>

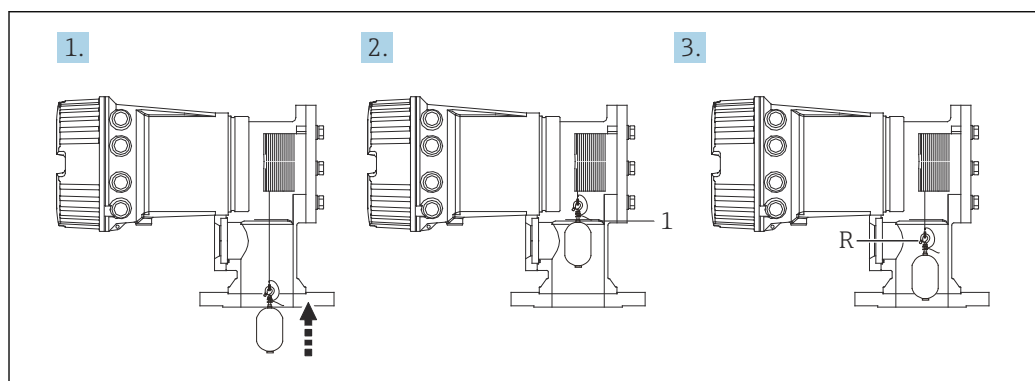
### 9.3.4 Reference calibration

#### Reference calibration procedure

The reference calibration defines the zero distance position of the displacer from the mechanical stop.

1. Navigate to: Setup → Calibration → Reference calibration → Reference calibration
2. Select the Start
3. Check the reference position (e.g. 70 mm (2.76 in)).  
↳ The reference position is preset prior to delivery.
4. Confirm that the displacer is correctly attached to the measuring wire.
5. The reference calibration starts automatically.

This completes the reference calibration.



A0029121

46 Reference calibration sequence

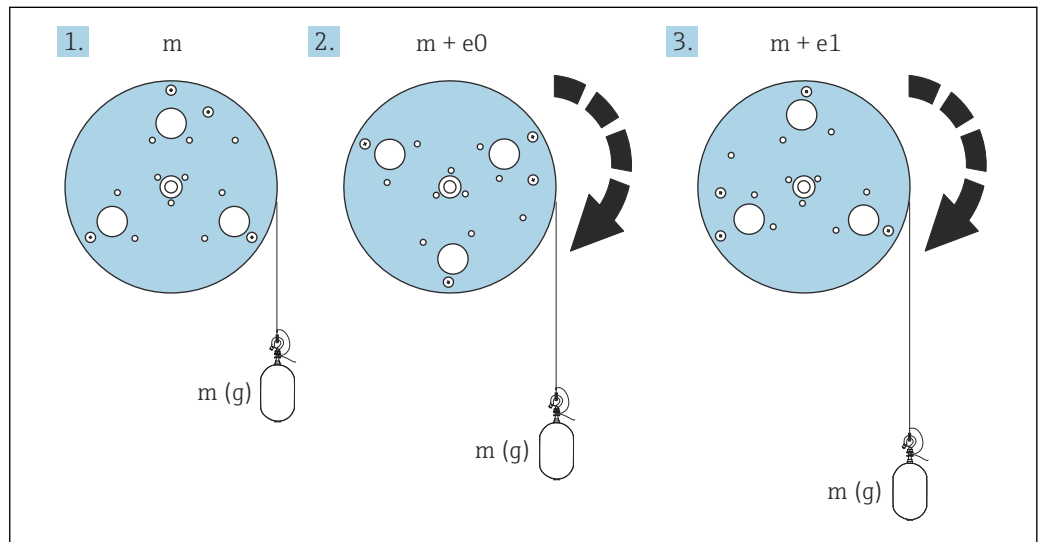
- 1 Mechanical stop  
R Reference position



### 9.3.5 Drum calibration

#### Drum table

As shown in the following illustration, a weight measurement error ( $e_0$  and  $e_1$ ) occurs depending of the stop position of the wire drum, even if the same weight is measured. To perform the weight measurement more accurately, a drum table for correcting the error due to the stop position of the wire drum has been measured and saved into the device at the factory. Because of individual differences of the values, the wire drum is measured for all devices. It is not necessary to know about this drum table for operation.



47 Measurement weight

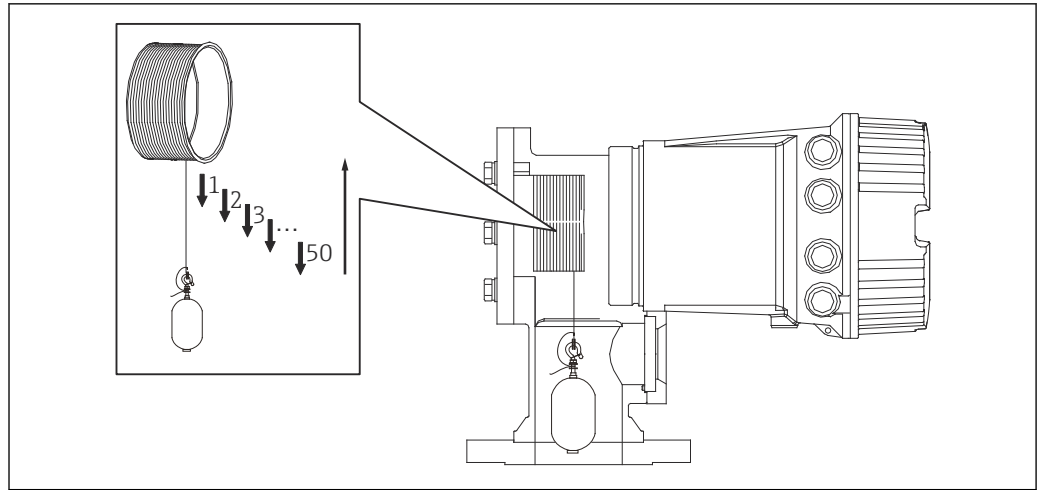
$e$  Error  
 $m$  Weight

#### Calibration procedure

1. Navigate to: Setup → Calibration → Drum calibration → Drum calibration
2. Ensure a distance of 500 mm (19.69 in) or more from the bottom of the displacer to the liquid level.
3. Confirm that the displacer weight is correct for the Set high weight.
4. Select the Start.
  - ↳ The drum calibration starts automatically.  
The drum calibration records fifty points which will take approximately eleven minutes.
5. Select the No as usual for the Make low table.
  - ↳ To make a low table for special applications, select the **Yes** and use 50 g weight.

This completes drum calibration procedure.

**i** To cancel any calibration, press  $\square + \oplus$  simultaneously. If the drum calibration is canceled while making the new table, the old table remains effective. If making a new table fails due to an obstruction, NMS8x will not accept the new table and shows an error message.



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48 Making drum table

### 9.3.6 Commissioning check

This procedure is to confirm that all calibration steps have been completed appropriately.

The commissioning check starts at the position where the previous drum calibration was performed. Perform drum calibration if the reference position was changed.

When skipping the drum calibration, it is necessary to ensure that there are no obstructions or interfering objects prior to the commissioning check.

The commissioning check has a total of eleven steps as follows.

The check items for the commissioning check should be performed in the following order.

- The displacer weight at the first point is within the threshold (within the specified value: 5 g (0.01 lb)).
- Ten points out of fifty, when the previous drum table was created, are selected and compared with the result of the current weight table and detected weight will be confirmed.
- Confirm the displacer weight is within the threshold (within specified value: 5 g (0.01 lb)) at each point.

If the displacer weight exceeds the threshold in the ten steps, the commissioning check stops and the gauge status changes to Stop.

To continue the level measurement, perform the gauge command.

The following three items are confirmed in the last step.

- The difference of the neighboring two points is within the threshold (within the specified value: 2 g (0.004 lb)).
- Peak-to-peak of the compensation value in the drum table is within 20 g (0.04 lb).
- The maximum compensation value in the drum table is within 40 g (0.09 lb).












Overtension is not confirmed during execution of the commissioning check.

Prior to drum calibration, ensure that there is nothing interfering with where the previous drum calibration was performed.

1. Navigate to: Diagnostics → Device check → Commissioning check → Commissioning check
2. Select the Start.
  - ↳ Executing is shown on the verify drum table.
3. Select the Start.
4. Confirm that the Commissioning check shows the Finished.
5. Confirm that the Result drum check is passed.

This completes the commissioning check procedure.

## 9.4 Configuring the measuring device

Configuration task		Description
Configuring the level and interface measurement	Setting density	→  96
	Setting tank height	→  97
	Setting high and low stop	→  98
Level calibration	Setting for open tank with liquid	→  99
	Setting for open tank without liquid	→  100
	Setting for closed tank	→  101
	Setting process condition	→  103
Configuring the density measurement	Setting spot density	→  104
	Setting tank profile	→  106
	Setting interface profile	→  107
	Setting manual profile	→  108

### 9.4.1 Configuring the level and interface measurement

The level measurement is to measure the position where the displacer is balanced (immersion point) in the liquid. When the liquid surface level changes, the displacer continuously follows the position to measure the liquid level. To define the appropriate level measurement, the following settings are required prior to operation.

The interface measurement can determine the interface between different liquids in a tank (e.g. water and oil). Up to two different interfaces can be determined within a maximum of three phases in a tank.

#### Setting the density of application

Density values for three liquid phases are set as follows prior to delivery.

- Upper density: 800 kg/m<sup>3</sup>
- Middle density: 1 000 kg/m<sup>3</sup>
- Lower density: 1 200 kg/m<sup>3</sup>

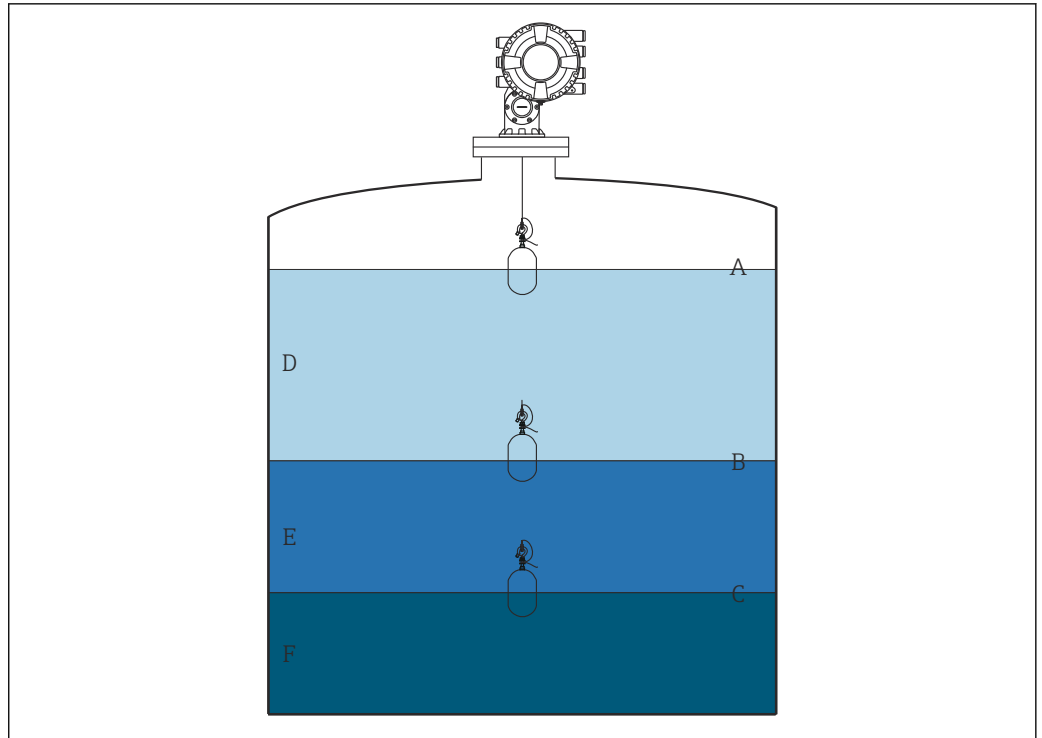
Change the data to reflect the actual density values. For tanks with only one liquid phase, set the upper density. For tanks with two or three phases, set middle and bottom densities as well.

Number of phases	Parameters to be set
1 phase	Upper density
2 phases	Upper/middle density
3 phases	Upper/middle/lower density

 When performing an interface measurement, the minimum density difference between phases should be at least 100 kg/m<sup>3</sup>.

#### Setting the density

1. Navigate to: Setup → Upper density , Setup → Middle density and Setup → Lower density
2. Input the value to Upper, Middle, and Lower densities accordingly.



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#### 49 Tank configuration

- A Liquid level
- B Upper interface
- C Lower interface
- D Upper phase (density)
- E Middle phase (density)
- F Lower phase (density)

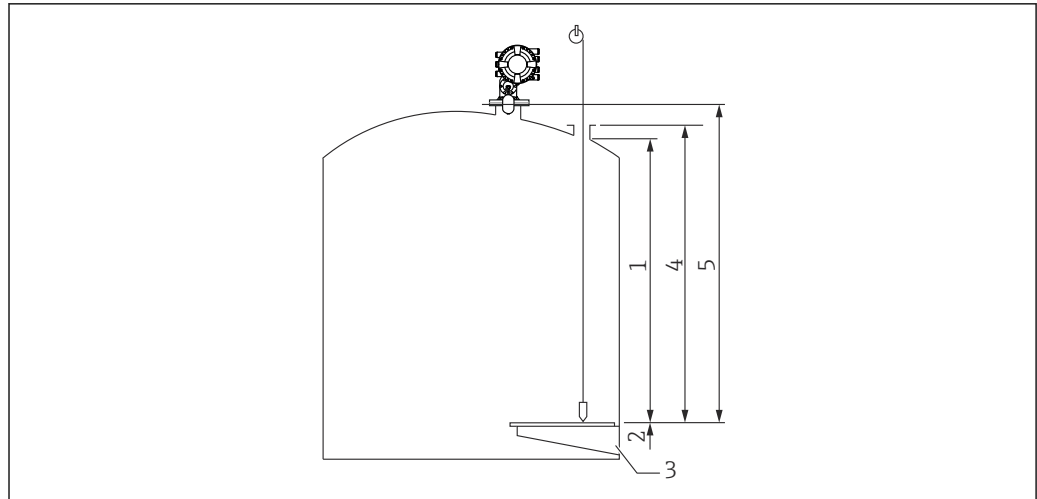
### Setting the tank height

To measure the tank level correctly, the tank reference height and empty (distance from reference point to datum plate) must be set in advance.

- i
  - Tank reference height: Set by the customer to represent the height of the tank. Distance between the dipping reference and the datum plate. Used for percentage calculation and as reference for the ullage level.
  - Empty: Distance between the zero point of device and datum plate. Empty is automatically adjusted by the Set level.
  - Refer to Level calibration for details how to determine the empty parameter accurately. → 99

### Setting the tank reference height and empty

1. Navigate to: Setup → Empty
2. Input the empty value.
3. Navigate to: Setup → Tank reference height
4. Input the value of tank reference height.



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#### 50 Tank height

- 1 High stop
- 2 Low stop
- 3 Datum plate
- 4 Tank reference height
- 5 Empty

### Setting the high stop and low stop

The high stop and low stop determine the highest and lowest points of displacer movement. Set these data to the desired actual upper and lower limit values.

**i** If the displacer should be able to determine a tank bottom that is below the datum plate, set the low stop to a negative value. To make sure that the displacer travels up to the reference position, set the high stop to a value greater than or equal to empty.

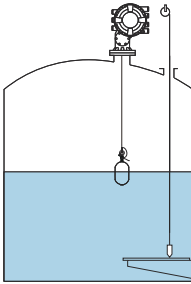
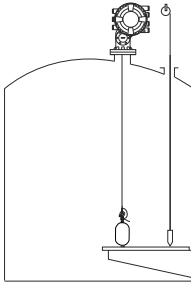
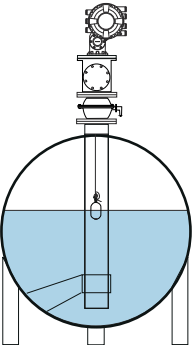
### High stop and low stop setting procedure

1. Navigate to: Setup → High stop level
2. Input the actual value for high stop.
3. Navigate to: Setup → Low stop level
4. Input the actual value for low stop.

This completes upper and lower stop setting procedure.

### 9.4.2 Level calibration


The following table shows the most likely options for setting the level calibration.

Open tank with liquid	Open tank without liquid	Closed tank
		

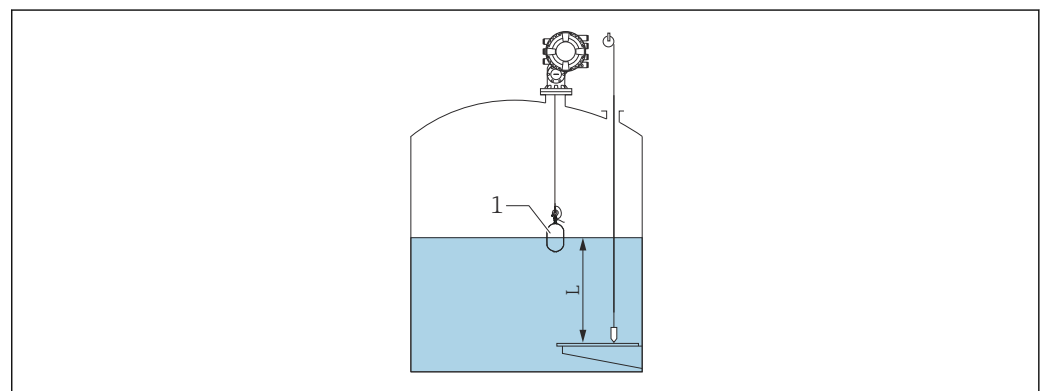
#### Setting for an open tank with liquid

##### Level setting procedure

1. Navigate to: Setup → Gauge command
2. Select the Level for the Gauge command.
  - ↳ The displacer automatically searches for the point where it balances.
3. Wait until the displacer is balanced on the liquid.
4. Perform dipping to determine the liquid level (L) in the tank.
5. Navigate to: Setup → Set level
6. Input the determined level value for the Set level.

 The Set level adjusts the Empty to reflect the new level value.

This completes setting for open tank with liquid procedure.



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 51 Set level for opened tank

- 1 Displacer
- L Measured value

### Setting for an open tank without liquid

If there is no liquid in the tank, the following procedure can be used to set the tank bottom or datum plate to 0 mm for the tank level.

#### Level setting procedure

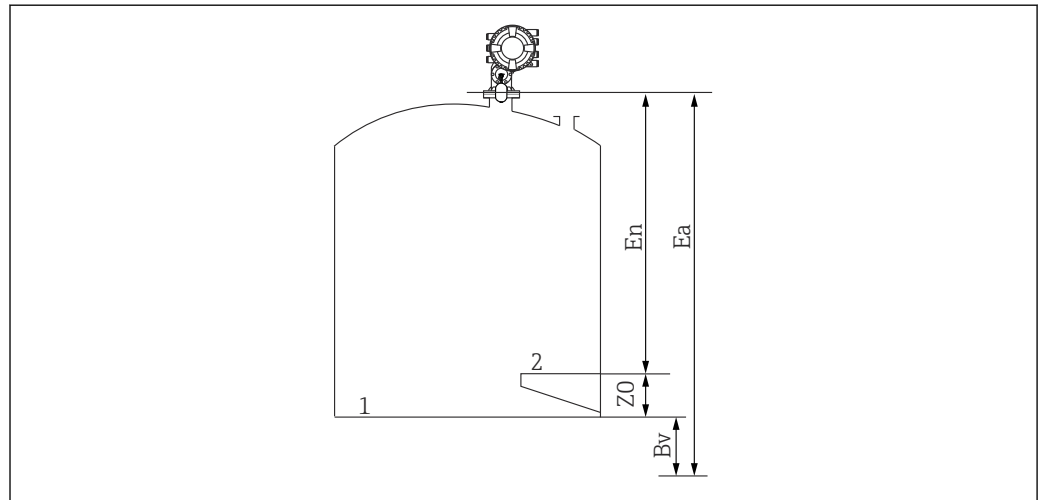
1. Navigate to: Operation → Gauge command → Gauge command
2. Select the Bottom level to measure the tank bottom.
3. Navigate to: Operation → One-time command status
4. Wait until the Finished is shown.
5. Navigate to: Operation → Level → Bottom level
6. Read the Bottom level (Bv).
7. Navigate to: Setup → Empty
8. Read the actual empty value (Ea).
9. Calculate the new empty value using following formula.  
↳  $E_n = E_a - B_v - Z_0$
10. Input the calculated value for the Empty.  
↳

Example:  $E_a = 28\text{m}$ ,  $B_v = 10.5\text{m}$ ,  $Z_0 = 0.5\text{m}$   
 $E_n = 28\text{m} - 10.5\text{m} = 17\text{m}$

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- i** The parameter  $Z_0$  defines the distance between the desired 0mm level value and the physical tank bottom (if displacer measures the datum plate,  $Z_0 = 0\text{ mm}$  (0 in)).
- Bottom level operation considers the immersion depth of the displacer in the measurement.

This completes the level setting for open tank without liquid procedure.



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**52** Open tank without liquid

- 1 Tank bottom
- 2 Datum plate
- $E_a$  Initial empty setting
- $B_v$  Initial bottom level
- $E_n$  New empty
- $Z_0$  Distance from tank bottom to datum plate

- i** It is recommended to repeating the level calibration when there is liquid in the tank (→ 99).



### Setting for a closed tank

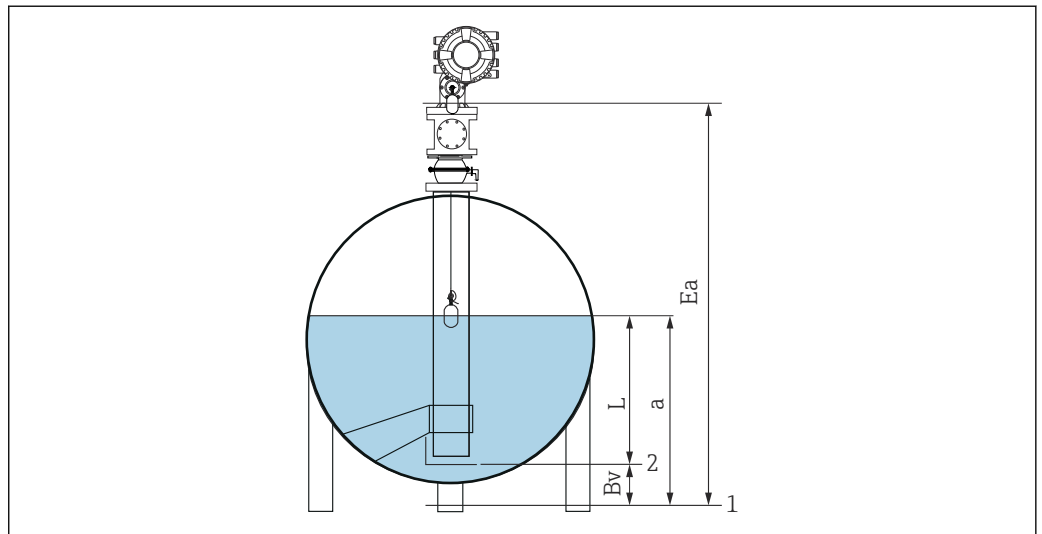
For tanks that cannot be hand-dipped, follow the procedure shown below.

#### Level setting procedure

1. Navigate to: Operation → Gauge command → Gauge command
2. Select the Bottom level to measure the tank bottom.
  - ↳ NMS8x measures the tank bottom and returns to level if the post gauge command is set to level (default).
3. Navigate to: Operation → One-time command status
4. Wait until the Finished is shown.
5. Navigate to: Operation → Level → Bottom level
6. Read the bottom value (Bv).
7. Navigate to: Operation → Level → Tank level (a)
8. Calculate the level value (L) by using following formula.
  - ↳  $L = a - Bv$
9. Navigate to: Setup → Set level
10. Input the value L for the Set level.

This completes the level setting procedure.

**i** If the datum plate is not zero (e.g. Z mm), adjust the set level value (L) by subtracting Z from the value L ( $L = a - Bv - Z$ ).



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**53** Closed tank for NMS80 and NMS81

- 1 Initial zero level position
- 2 Datum plate
- Ea Initial setting of Empty
- Bv Bottom level
- a Tank level
- L Set level value

### Setting for a closed tank without datum plate

For tanks that cannot be hand-dipped and have no datum plates, follow the procedure shown below.

#### Procedure for setting level by empty

In cases where a manual dip cannot be carried out and there are no flat datum plates to reference the bottom, empty can be used instead of set level. In this particular case, empty needs to be adjusted as it is not the gauge reference height but the displacer immersion depth.

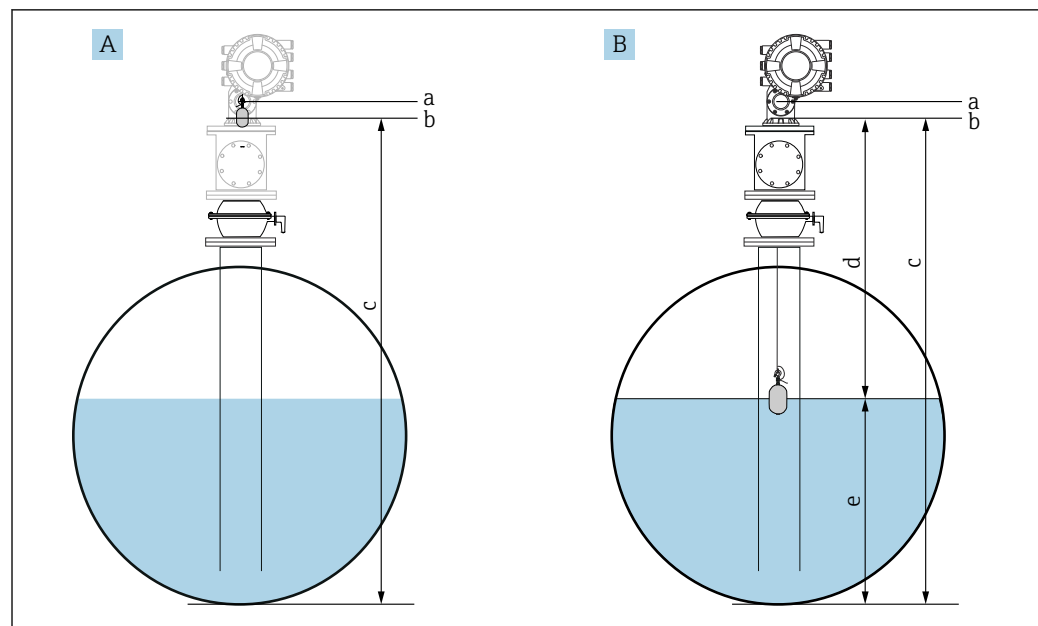
Level is automatically calculated by the following formula.

#### Empty - Distance = Level

The absolute value of distance is updated according to the displacer movement and level can be determined.

1. Navigate to: Setup → Empty
2. Set empty to be the displacer immersion depth.
3. Navigate to: Setup → Gauge command
4. Select the **Level** for the Gauge command parameter.
  - ↳ The displacer automatically searches for the point where it balances.
5. Wait until the displacer is balanced on the liquid surface.

This completes the level setting procedure.




54 Level setting in case of empty (NMS80/81)

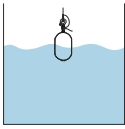
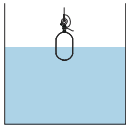
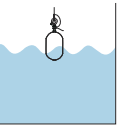
- A Set empty  
 B How level is determined  
 a Reference position  
 b Gauge reference height  
 c Empty  
 d Distance  
 e Level

### Selecting the process condition

The process condition is used to adjust the device to the application. By changing this parameter, several balancing parameters are adjusted automatically to make setup easier.

1. Navigate to: Setup → Process condition
2. Select an appropriate condition for the Process condition.

 The default setting of the process condition varies depending on your order.

Parameter name	Process condition		
Parameter setting	Universal	Calm surface	Turbulent surface
Description			
	Provides reliable results in various applications and for various liquids.	For storage tanks with a calm surface and focus on highest accuracy measurement.	For applications where the surface is turbulent.

### 9.4.3 Configuring the density measurement

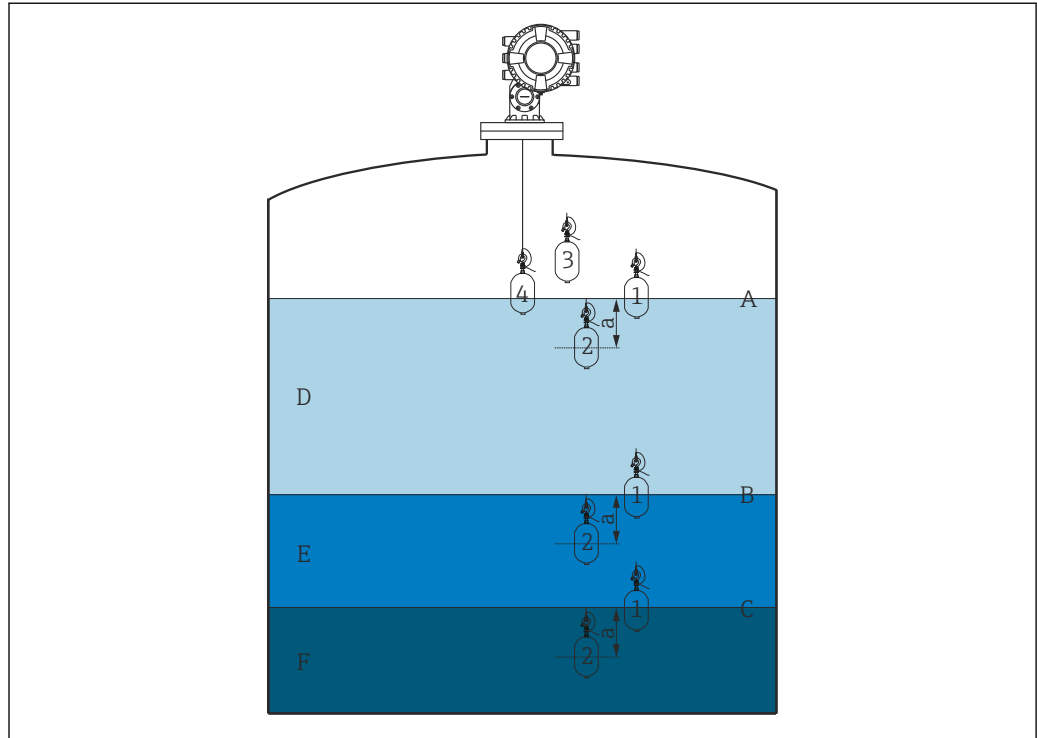
The density measurement is performed to confirm and maintain the quality of the liquid.

The density measurement is largely divided into two methods as shown below.

Density methods	Gauge command	Description
Spot density	Upper density Middle density Lower density	One spot density measurement for designated layer <ul style="list-style-type: none"> <li>▪ Upper density is for upper layer.</li> <li>▪ Middle density is for middle layer.</li> <li>▪ Lower density is for lower layer.</li> </ul>
Profile density	Tank profile	Profile between the bottom of the tank and the level position <ul style="list-style-type: none"> <li>▪ Normal mode</li> <li>▪ Compensation mode</li> </ul>
	Interface profile	Profile between the upper interface (I/F) and the level position <ul style="list-style-type: none"> <li>▪ Normal mode</li> <li>▪ Compensation mode</li> </ul>
	Manual profile	Profile between the desired start point and the level position <ul style="list-style-type: none"> <li>▪ Normal mode</li> <li>▪ Compensation mode</li> </ul>

### Spot density measurement

Three different spot density gauge commands are available as shown below.



55 Spot density (The numbers show the order of displacer movement.)

- A Liquid level
- B Upper interface
- C Lower interface
- D Upper density
- E Middle density
- F Lower density
- a Submersion depth

The submersion depth (a) is set to 150 mm (5.91 in) prior to delivery. To change the submersion depth, perform the following steps.

1. Navigate to: Setup → Advanced setup → Sensor config → Spot density → Submersion depth
2. Input the desired value for the Submersion depth.

#### Setting the spot density

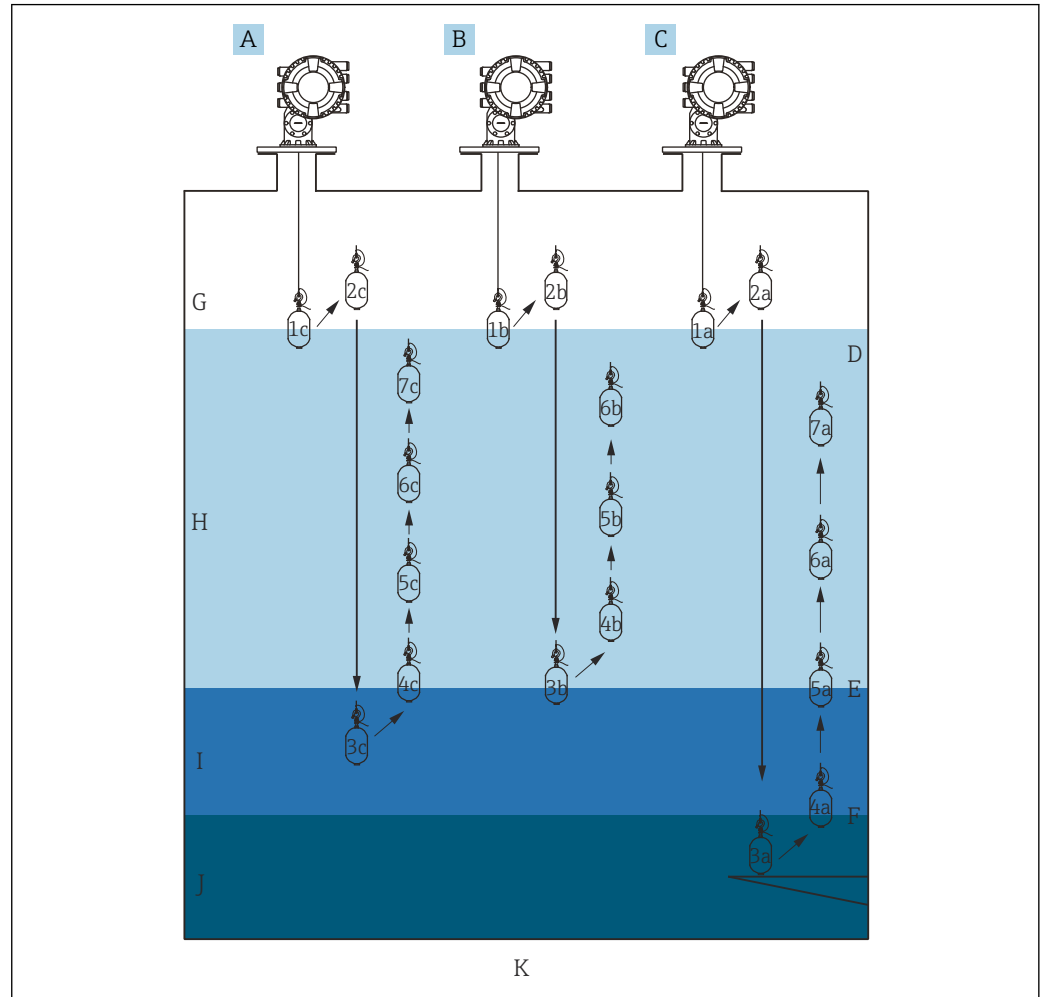
1. Navigate to: Operation → Gauge command → Gauge command
2. Select the Upper density, the Middle density, or the Lower density for the Gauge command.
3. Verify that the value that was examined in a laboratory and the actual value that was measured in the tank are the same or within an allowable range.
4. Adjust the value if necessary.
  - ↳ Navigate to: Setup → Advanced setup → Sensor config → Spot density  
Select the Upper density offset, the Middle density offset, and the Lower density offset and input the desired values for each offset.

This completes the setting spot density procedure.

**Profile density measurement**

Profile density has three gauge commands as shown below.

**i** NMS8x measures a density profile according to a defined interval of up to 50 points.



**56** Overview of profile density (1a, 2a, 3a...show the order of displacer movements.)

- A Manual profile
- B Interface profile
- C Tank profile
- D Liquid level
- E Upper interface
- F Lower interface
- G Gas phase
- H Upper density
- I Middle density
- J Lower density
- K Tank bottom

**i** Density measurement has two types of modes.

- Normal measure mode: Profile points are measured at exactly configured positions.
- Compensation mode: Profile points are measured at multiples of the wire drum circumference to further improve accuracy.

Select normal mode as usual. However, when selecting compensation mode, NMS8x automatically adjusts the measurement positions to where the density measurement can be the most accurate.

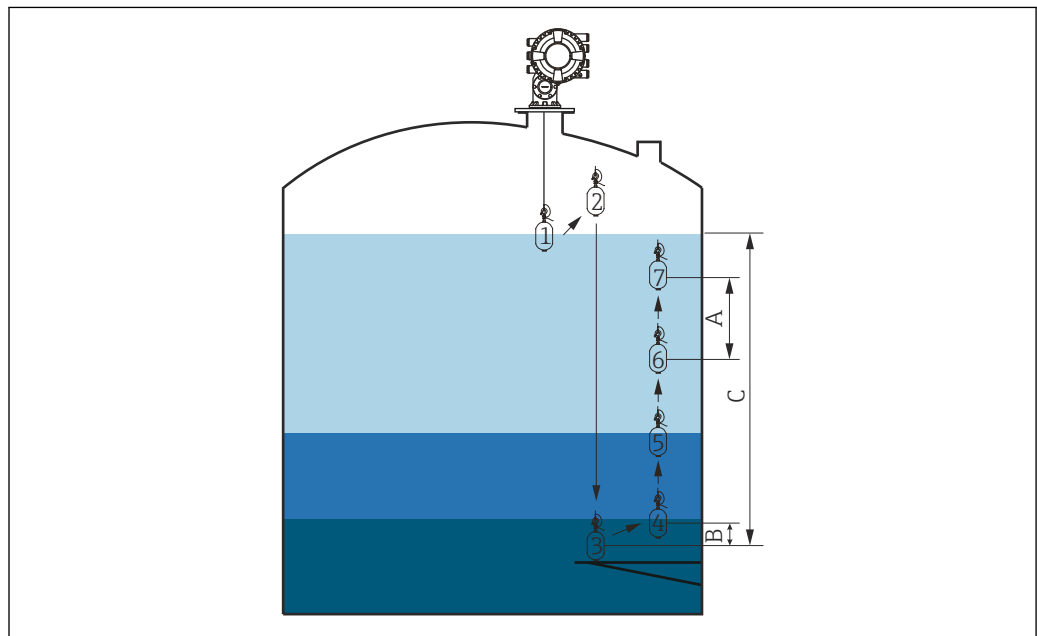
## Tank profile measurement

### Setting tank profile procedure

The tank profile operation measures a profile starting at the physical tank bottom up to the liquid level.

1. Navigate to: Setup → Advanced setup → Sensor config → Profile density → Profile density offset distance
2. Input the desired value for the Profile density offset distance.
  - ↳ The value of the profile density offset distance defines the distance between the start point (datum plate or bottom of the tank) and the first measurement point.
3. Navigate to: Setup → Advanced setup → Sensor config → Profile density → Profile density interval
4. Input the desired value for the Profile density interval.
5. Set Tank profile in the Gauge command to start measurement.

This completes the setting tank profile procedure.



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57 Tank profile movement (The numbers show the order of the displacer movement.)

- A Profile density interval
- B Profile density offset distance
- C Datum plate
- D Tank profile range

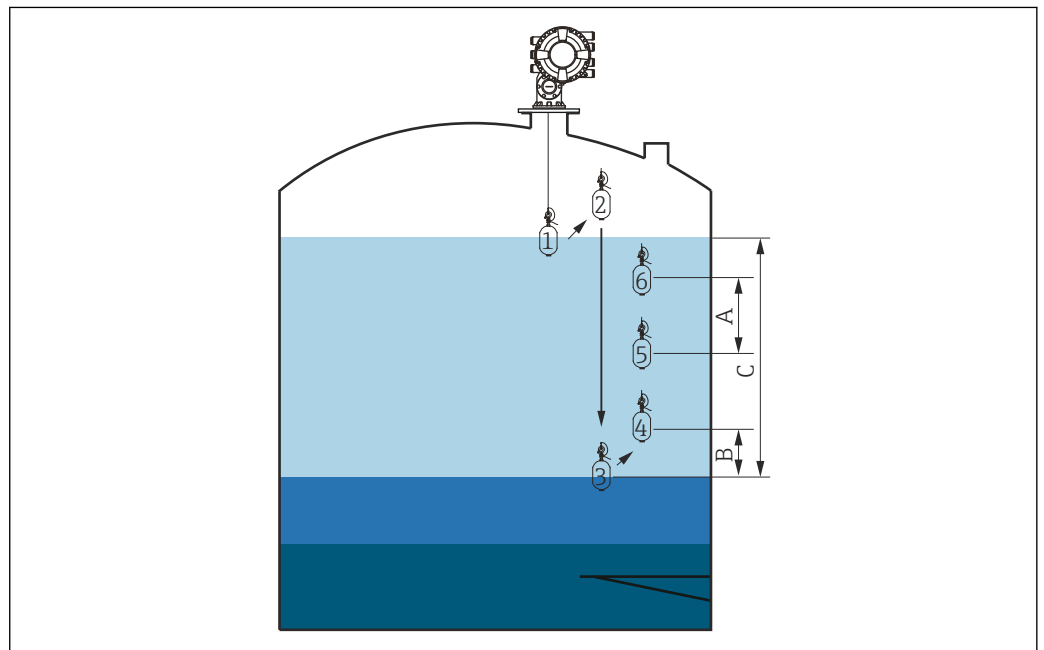
## Interface profile measurement

### Setting interface profile procedure

The interface profile operation measures a profile starting at the upper interface level up to the liquid level.

1. Navigate to: Setup → Advanced setup → Sensor config → Profile density → Profile density offset distance
2. Input the desired value for the Profile density offset distance.
  - ↳ The value of the profile density offset distance defines the distance between the start point (upper interface) and the first measurement point.
3. Navigate to: Setup → Advanced setup → Sensor config → Profile density → Profile density interval
4. Input the desired value for the Profile density interval.
5. Set Interface profile in the Gauge command to start measurement.

This completes the setting interface profile procedure.



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58 Interface profile movement (The numbers show the order of the displacer movement.)

- A Profile density interval
- B Profile density offset distance
- C Tank profile range

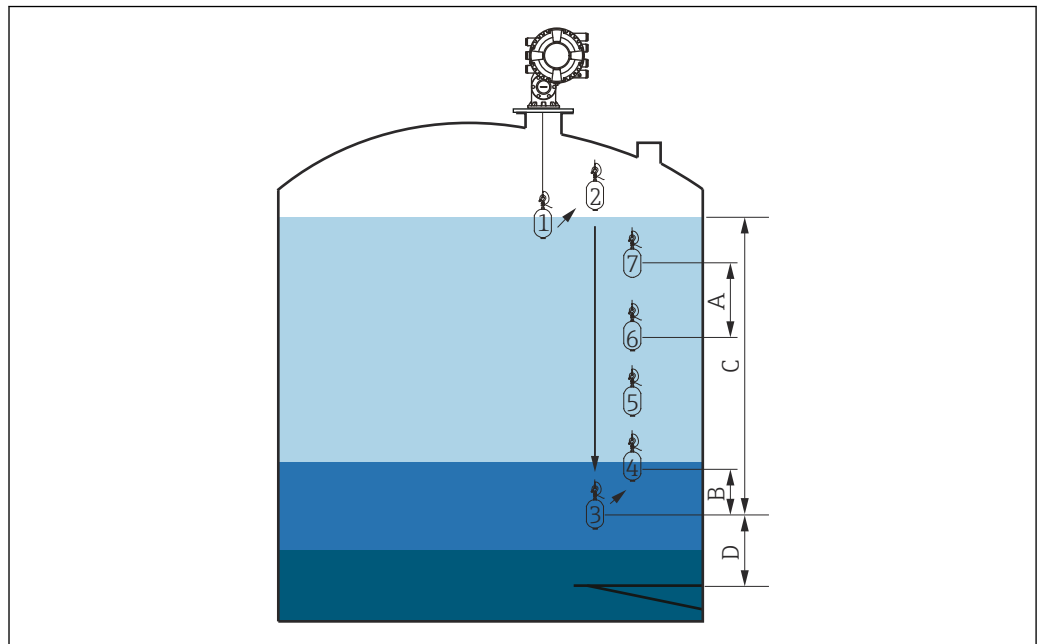
## Manual profile measurement

### Setting manual profile procedure

The manual profile operation measures a profile starting at a manually specified level up to the liquid level.

1. Navigate to: Setup → Advanced setup → Sensor config → Profile density → Manual profile level
2. Input the desired value for the Manual profile level.
3. Navigate to: Setup → Advanced setup → Sensor config → Profile density → Profile density offset distance
  - ↳ For the manual profile, the level offset can be set to 0 so that the first point can be measured at the manual profile level.
4. Input the desired value for the Profile density offset distance.
  - ↳ The value of the profile density offset distance defines the distance between the start point (manual profile) and the first measurement point.
5. Navigate to: Setup → Advanced setup → Sensor config → Profile density → Profile density interval
6. Input the desired value for the Profile density interval.
7. Set Manual profile in the Gauge command to start measurement.

This completes the setting manual profile.




















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59 Manual profile movement (The numbers show the order of the displacer movement.)

- A Profile density interval
- B Profile density offset distance
- C Manual profile range
- D Manual profile level

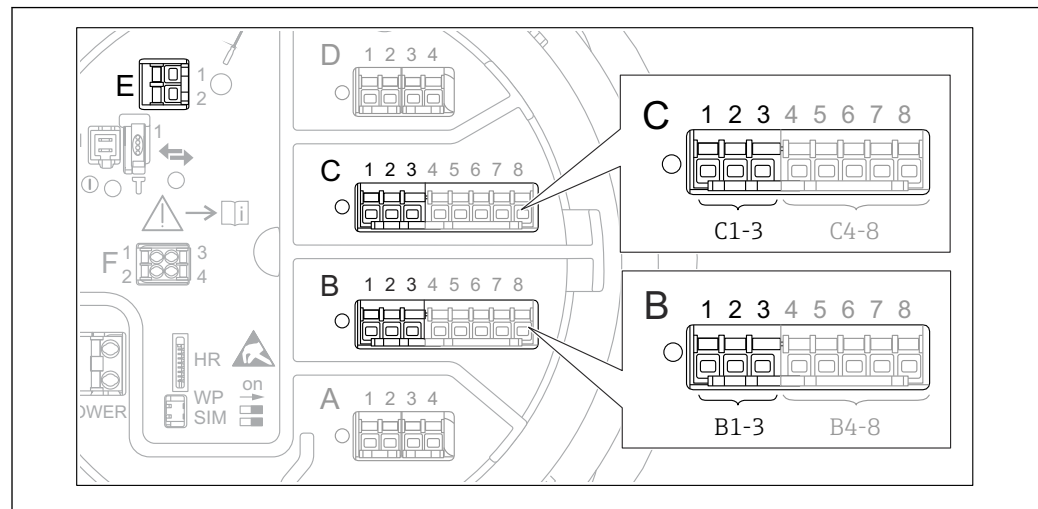


## 9.5 Configuring the tank gauging application

<b>Configuration of the inputs:</b>	<b>Description</b>
HART inputs	→  110
NMT532/539/81 connected via HART	→  112
4-20mA inputs	→  114
RTD input	→  115
Digital inputs	→  117
<b>Configuration of the data processing in the device:</b>	<b>Description</b>
Linking input values to tank variables	→  118
Tank calculation: Direct Level Measurement	→  119
Tank calculation: Hybrid Tank Measurement System (HTMS)	→  120
Tank calculation: Correction of the Hydrostatic Tank Deformation (HyTD)	→  121
Tank calculation: Thermal Tank Shell Correction (CTSh)	→  122
Alarms (limit evaluation)	→  126
<b>Configuration of the signal output:</b>	<b>Description</b>
4-20mA output	→  127
HART slave + 4-20mA output	→  128
Modbus	→  129
V1	→  130
Digital outputs	→  131
WM550	→  130

## 9.5.1 Configuration of the HART inputs

### Connecting and addressing HART devices



60 Possible terminals for HART loops

- B Analog I/O module in slot B (availability depending on device version → 47)  
 C Analog I/O module in slot C (availability depending on device version → 47)  
 E HART Ex is output (available in all device versions)

**i** HART devices must be configured and given a unique HART address in the range from 1 to 15 via their own user interface before they are connected to the Proservo NMS8x<sup>3)</sup>. Make sure they are connected as defined by the terminal assignment → 58. Devices with an address larger than 15 are not recognized by the Proservo.

#### Slot B or C: Setting the operating mode of the Analog I/O module



**i** This section is not relevant for the HART Ex is output (Slot E). This output always functions as a HART master for the connected HART slaves.

If HART devices are connected to an Analog I/O module (slot B or C in the terminal compartment), this module must be configured as follows:






1. Navigate to the submenu of the respective Analog I/O module: Setup → Advanced setup → Input/output → Analog I/O X1-3
2. Go to the Operating mode (→ 227).
3. If only one HART device is connected to this loop:  
 Select the HART master+4..20mA input. In this case the 4-20mA signal can be used in addition to the HART signal. For the configuration of the 4-20mA input:  
 → 114.
4. If up to 6 HART devices are connected to this loop:  
 Select the HART master.

3) The current software does not support HART devices with address 0 (zero).

### Defining the type of measured value

-  This setting can be skipped for a connected Prothermo NMT53x and NMT8x as the type of measured value is automatically recognized by the Proservo NMS8x in this case.
- 
  - The measured values can only be used in the system if the unit of the assigned HART variable fits the type of measured value. The HART variable assigned to **Output temperature**, for example, has to be in °C or °F.
  - A HART variable with unit "%" cannot be used for **Output level**. Instead, the HART variable must be in mm, m, ft or in.

The type of measured value must be specified for each HART variable (PV, SV, TV and QV). To do so, proceed as follows:

1. Navigate to: Setup → Advanced setup → Input/output → HART devices
  - ↳ There is a submenu for each connected HART device.
2. For each device go to the corresponding submenu.
3. If the device measures a pressure:
  - Go to the Output pressure (→  217) and specify which of the four HART variables contains the measured pressure. Only a HART variable with a pressure unit may be selected.
4. If the device measures a density:
  - Go to the Output density (→  217) and specify which of the four HART variables contains the measured density. Only a HART variable with a density unit may be selected.
5. If the device measures a temperature:
  - Go to the Output temperature (→  218) and specify which of the four HART variables contains the measured temperature. Only a HART variable with a temperature unit may be selected.
6. If the device measures the vapor temperature:
  - Go to the Output vapor temperature (→  218) and specify which of the four HART variables contains the measured vapor temperature. Only a HART variable with a temperature unit may be selected.
7. If the device measures a level:
  - Go to the Output level (→  219) and specify which of the four HART variables contains the measured level. Only a HART variable with a level unit (not "%") may be selected.

### Disconnecting HART devices

When a HART device is disconnected from the device, it must also be logically removed as follows:

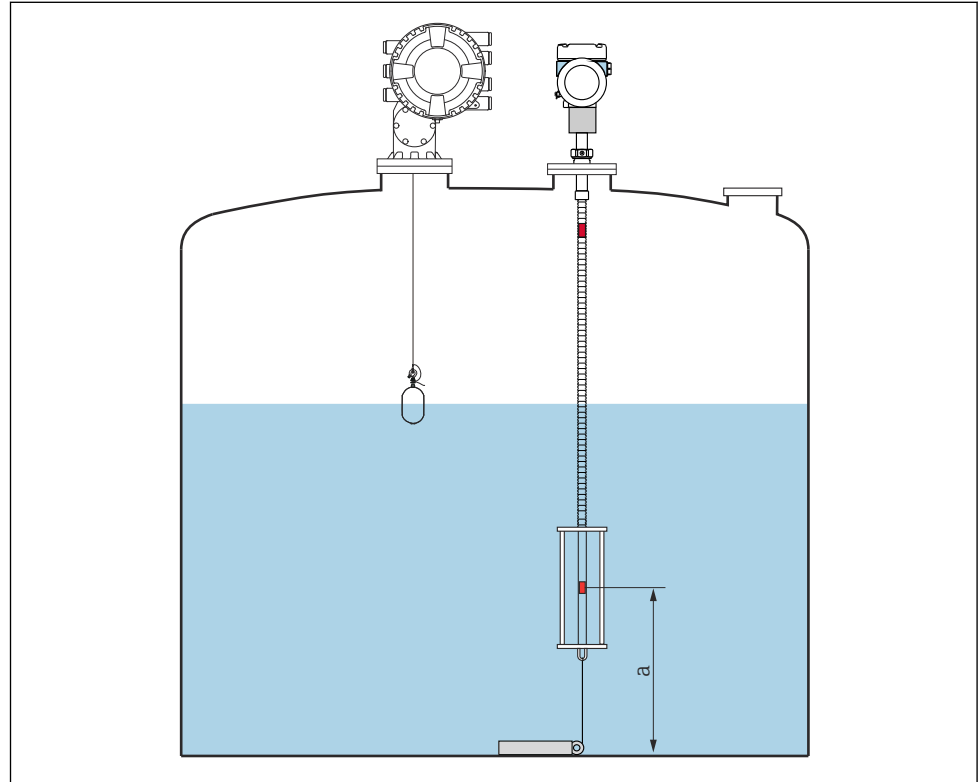
1. Navigate to Setup → Advanced setup → Input/output → HART devices → Forget device → Forget device
2. Select the HART device to be removed.

-  This procedure is also necessary if a defective device is exchanged.

### 9.5.2 Configuration of a connected Prothermo temperature transmitter

If a Prothermo NMT532, NMT539 or NMT8x temperature transmitter is connected via HART, it can be configured as follows:

1. Navigate to: Expert → Input/output → HART devices → HART Device(s) → NMT device config; here, **HART Device(s)** is the name of the connected Prothermo.
2. Go to the Configure device? and select **Yes**.
- 3.



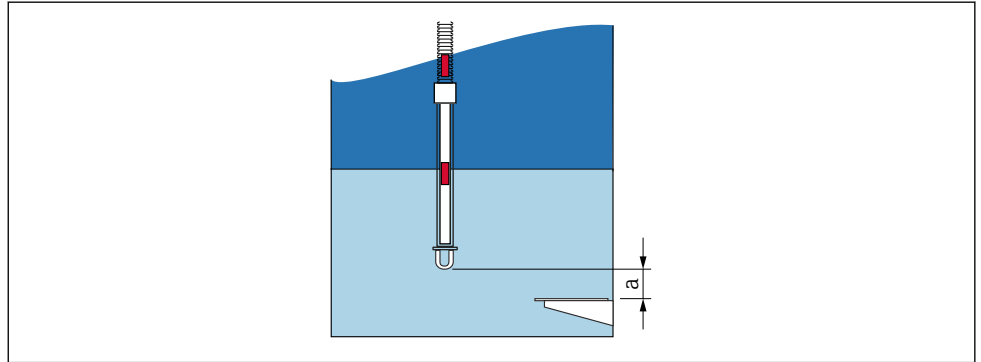
61 Prothermo NMT53x: Position of the bottom temperature element

*a* Distance from bottom temperature element to zero reference (tank bottom or datum plate).

To configure a **Prothermo NMT53x**: Go to the Bottom point and enter the position of the bottom temperature element (see picture above).

- ↳ The value entered into the Bottom point in the Tank Gauging device is handed over to the Bottom point in the connected Prothermo NMT53x.

4.



A0047111

62 Prothermo NMT8x: Distance between the physical end of the probe and the zero level value

*a* Distance between the physical end of the probe and the zero level value in the tank (tank bottom or datum plate).

To configure a **Prothermo NMT8x**: Go to the Bottom point and enter the distance between the physical end of the probe and the zero level value in the tank (tank bottom or datum plate).

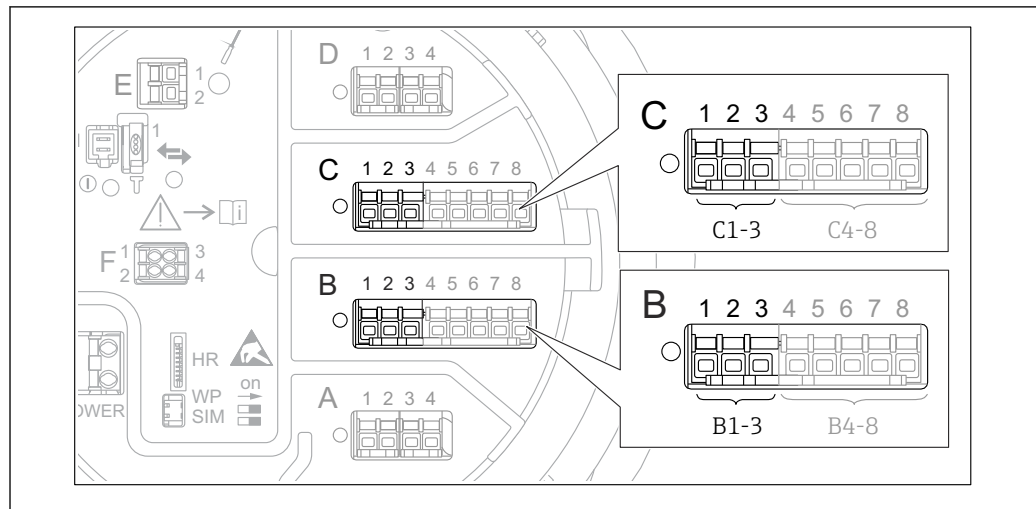
↳ The value entered into the Bottom point in the Tank Gauging device is handed over to the End of probe to zero distance in the connected Prothermo NMT8x.



To check the temperatures measured by the individual elements, go to the following submenu: Operation → Temperature → NMT element values → Element temperature

There is a Element temperature X for each element of the Prothermo.

### 9.5.3 Configuration of the 4-20mA inputs

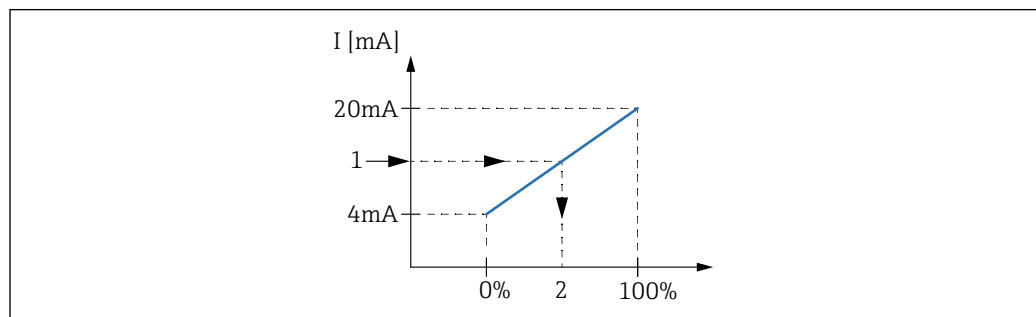


A0032464

63 Possible locations of the Analog I/O modules, which can be used as a 4-20mA input. The order code of the device determines which of these modules is actually present → 47.

For each Analog I/O module to which a 4-20mA device is connected, proceed as follows:

1. Make sure the 4-20mA devices are connected as defined by the terminal assignment → 58.
2. Navigate to the submenu of the respective Analog I/O module: Setup → Advanced setup → Input/output → Analog I/O X1-3
3. Go to the Operating mode (→ 227) and select **4..20mA input** or **HART master +4..20mA input**.
4. Go to the Process value (→ 234) and specify which process variable is transmitted by the connected device.
5. Go to the Analog input 0% value (→ 233) and define which value of the process variable corresponds to an input current of 4 mA (see diagram below).
6. Go to the Analog input 100% value (→ 233) and define which value of the process variable corresponds to an input current of 20 mA (see diagram below).
7. Go to the Process value (→ 234) and check whether the indicated value matches the actual value of the process variable.



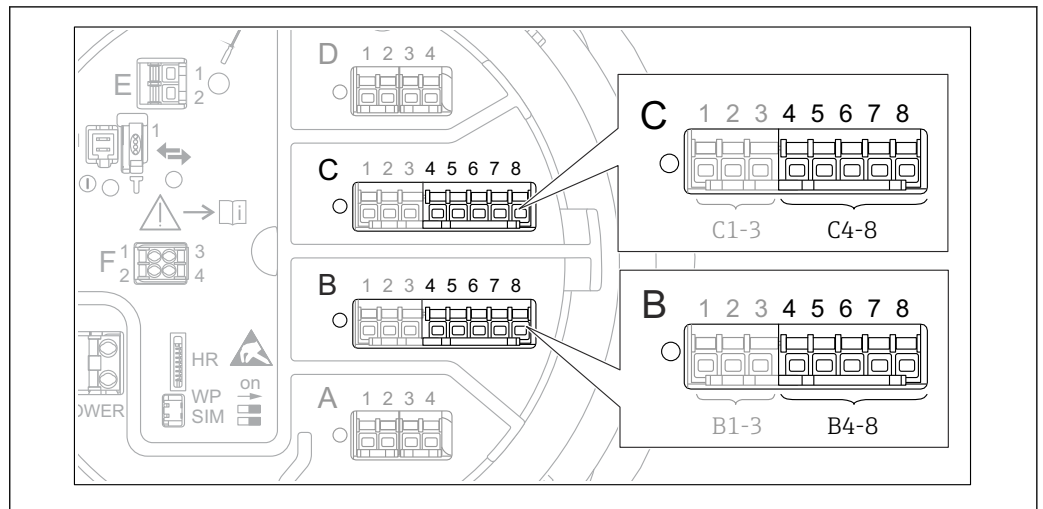
A0029264

64 Scaling of the 4-20mA input to the process variable

- 1 Input value in mA
- 2 Process value

**i** The **Analog I/O** submenu contains additional parameters for a more detailed configuration of the Analog Input. For a description refer to : → 227

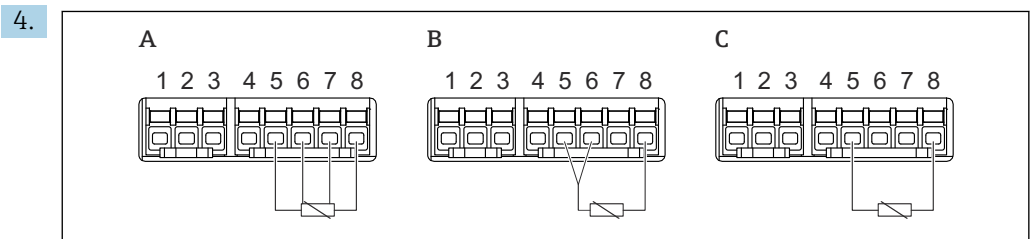
### 9.5.4 Configuration of a connected RTD



A0032465

65 Possible locations of the Analog I/O modules, to which an RTD can be connected. The order code of the device determines which of these modules is actually present → 47.

1. Make sure the RTD is connected as defined by the terminal assignment → 63.
2. Navigate to the submenu of the respective Analog I/O module: Setup → Advanced setup → Input/output → Analog IP X4-8.
3. Go to the RTD type (→ 221) and specify the type of the connected RTD.



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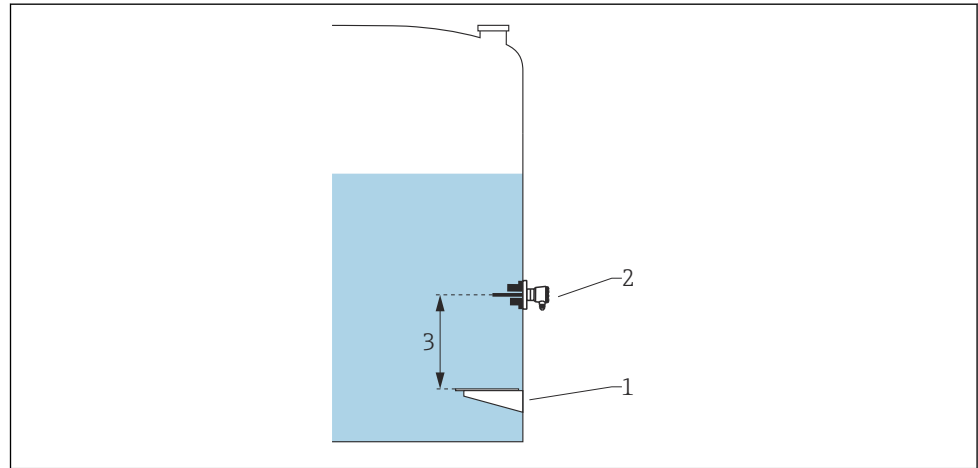
66 RTD connection types

- A 4 wire RTD connection
- B 3 wire RTD connection
- C 2 wire RTD connection


Go to the RTD connection type (→ 222) and specify the type of connection of the RTD (2-, 3- or 4-wire).


5. Go to the Input value (→ 224) and check whether the indicated temperature matches the actual temperature.
6. Go to the Minimum probe temperature (→ 224) and specify the minimum approved temperature of the connected RTD.
7. Go to the Maximum probe temperature (→ 225) and specify the maximum approved temperature of the connected RTD.

8.



A0042773

- 1 Datum plate
- 2 RTD
- 3 Probe position (→  225)

Go to the Probe position (→  225) and enter the mounting position of the RTD (measured from the datum plate).

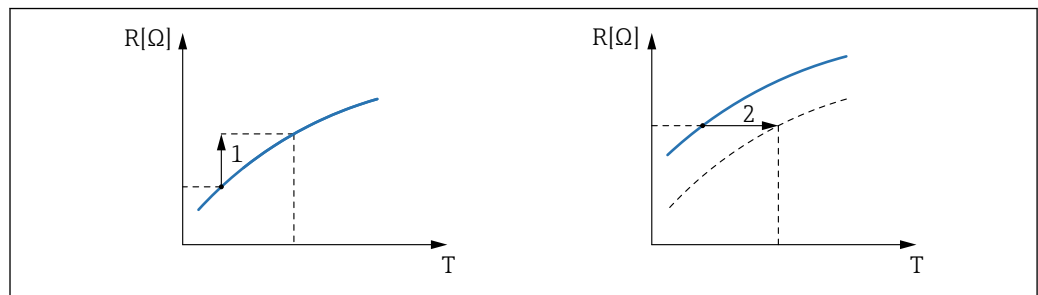
- ↳ This parameter, in conjunction with the measured level, determines whether the measured temperature refers to the product or to the gas phase.

### Offset for resistance and/or temperature



An offset for the resistance or the temperature can be defined in the following submenu: Expert → Input/output → Analog IP X4-8.

- **Ohms offset** is added to the measured resistance before the calculation of the temperature.
- **Temperature offset after conversion** is added to the measured temperature.

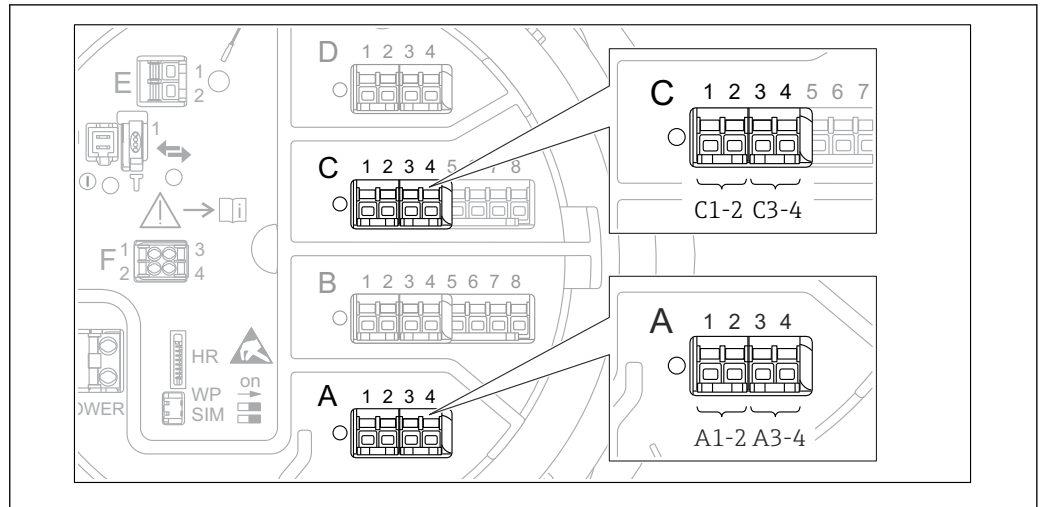


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- 1 Ohms offset
- 2 Temperature offset after conversion



### 9.5.5 Configuration of the digital inputs



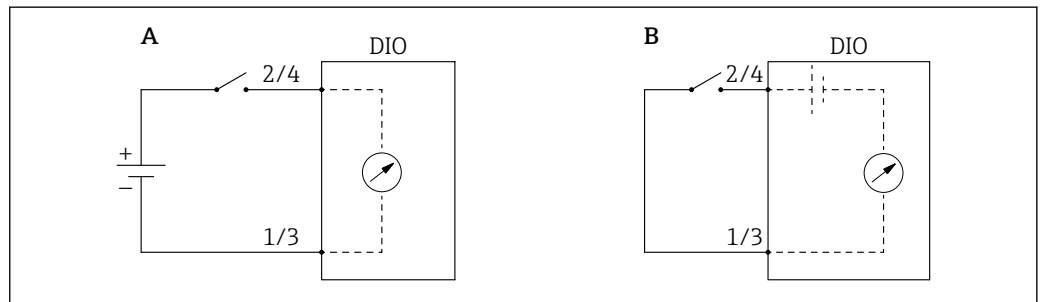
A0026424

67 Possible locations of the Digital I/O modules (examples); the order code defines the number and location of digital input modules → 47.

There is a **Digital Xx-x** submenu for each digital I/O module of the device. "X" designates the slot in the terminal compartment, "x-x" the terminals within this slot. The most important parameters of this submenu are **Operating mode** and **Contact type**.

#### The Operating mode

Setup → Advanced setup → Input/output → Digital Xx-x → Operating mode



A0029262

A "Operating mode" = "Input passive"  
 B "Operating mode" = "Input active"

#### Meaning of the options

- **Input passive**

The DIO module measures the voltage provided by an external source. Depending on the status of the external switch, this voltage is 0 at the input (switch open) or exceeds a certain limit voltage (switch closed). These two states represent the digital signal.

- **Input active**



The DIO module provides a voltage and uses it to detect whether the external switch is open or closed.

#### The Contact type

Setup → Advanced setup → Input/output → Digital Xx-x → Contact type

This parameter determines how the state of the external switch is mapped to the internal states of the DIO module:


State of the external switch	Internal state of the DIO module	
	Contact type = Normally open	Contact type = Normally closed
Open	Inactive	Active
Closed	Active	Inactive
<b>Behavior in special situations:</b>		
During start-up	Unknown	Unknown
Fault in measurement	Error	Error

-  The internal state of the Digital Input can be transferred to a Digital Output or can be used to control the measurement.
- The **Digital Xx-x** submenu contains additional parameters for a more detailed configuration of the Digital Input. For a description refer to →  237.

### 9.5.6 Linking input values to tank variables

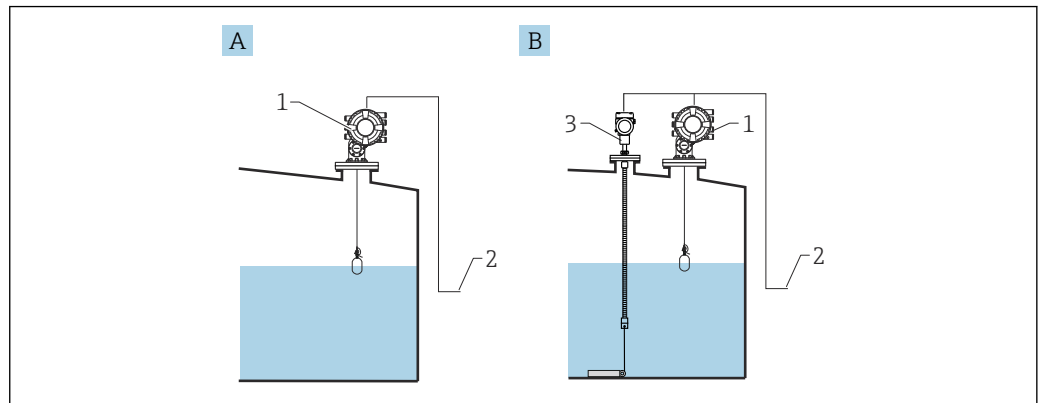
Measured values must be linked to tank variables before they can be used in the Tank Gauging application. This is done by defining the source of each tank variable in the following parameters:

Tank variable	Parameter defining the source of this variable
Product level	<ul style="list-style-type: none"> <li>▪ Setup → Level source</li> <li>▪ Setup → Advanced setup → Application → Tank configuration → Level → Level source</li> </ul>
Bottom water level	Setup → Advanced setup → Application → Tank configuration → Level → Water level source
Average or spot temperature of the product	<ul style="list-style-type: none"> <li>▪ Setup → Liquid temp source</li> <li>▪ Setup → Advanced setup → Application → Tank configuration → Temperature → Liquid temp source</li> </ul>
Temperature of the air surrounding the tank	Setup → Advanced setup → Application → Tank configuration → Temperature → Air temperature source
Temperature of the vapor above the product	Setup → Advanced setup → Tank configuration → Temperature → Vapor temp source
Density of the product	Setup → Advanced setup → Application → Tank configuration → Density → Observed density source
Bottom pressure (P1)	Setup → Advanced setup → Application → Tank configuration → Pressure → P1 (bottom) source
Top pressure (P3)	Setup → Advanced setup → Application → Tank configuration → Pressure → P3 (top) source

-  Depending on the application not all these parameters will be relevant in a given situation.

### 9.5.7 Tank calculation: Direct level measurement

If no tank calculation is configured, level and temperature are measured directly.



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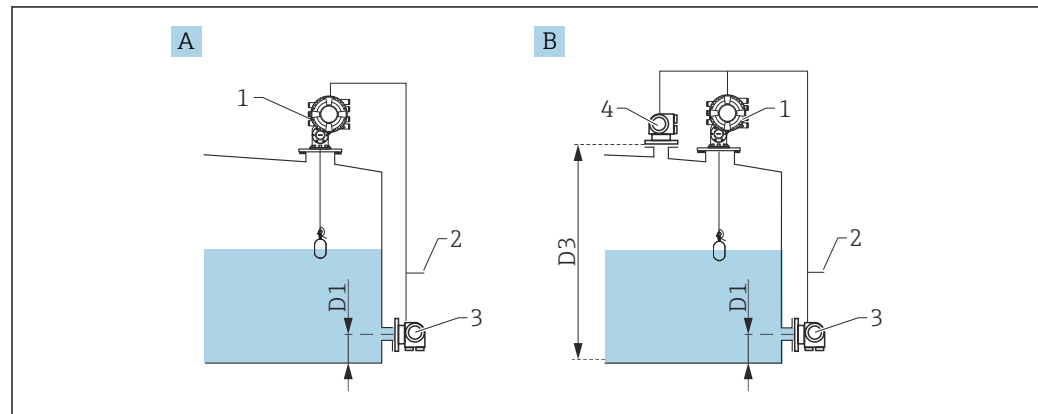
- A Direct level measurement (without temperature)  
 B Direct level and temperature measurement  
 1 NMS8x  
 2 To inventory management system  
 3 Temperature transmitter

1. Navigate to: "Setup → Level source" and specify from which device the level is obtained.
2. If a temperature transmitter is connected:  
 Navigate to: "Setup → Liquid temp source" and specify from which device the temperature is obtained.

## 9.5.8 Tank calculation: Hybrid tank measurement system (HTMS)

HTMS uses level and pressure measurements to calculate the density of the medium.

**i** In non-atmospheric (i.e. pressurized) tanks it is recommended to use the **HTMS P1+P3** mode. Two pressure sensors are required in this case. In atmospheric (i.e. unpressurized) tanks the **HTMS P1** with only one pressure sensor is sufficient.



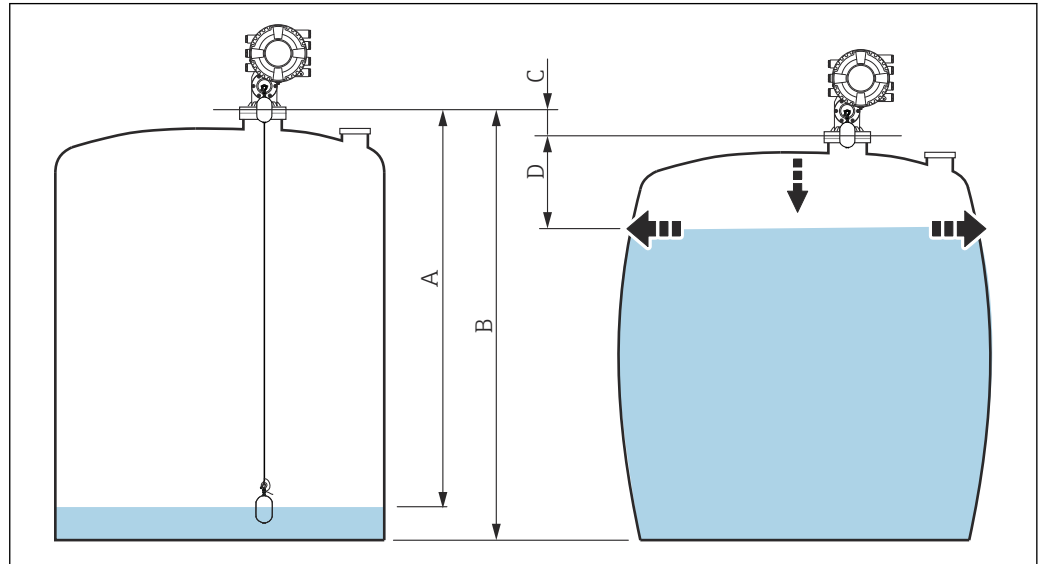
A0029277

- A The "HTMS P1" measurement mode  
 B The "HTMS P1+P3" measurement mode  
 D1 P1 position  
 D3 P3 position  
 1 NMS8x  
 2 To inventory management system  
 3 Pressure sensor (bottom)  
 4 Pressure sensor (top)

1. Navigate to Setup → Advanced setup → Application → Tank configuration → Level
2. Go to **Level source** (→ 📄 201) and specify from which device the level is obtained.
3. Navigate to Setup → Advanced setup → Application → Tank configuration → Pressure
4. Go to **P1 (bottom) source** (→ 📄 278) and specify from which device the bottom pressure (P1) is obtained.
5. If a top pressure transmitter (P3) is connected:  
 Go to **P3 (top) source** (→ 📄 280) and specify from which device the top pressure (P3) is obtained.
6. Navigate to: Setup → Advanced setup → Application → Tank calculation → HTMS
7. Go to **HTMS mode** (→ 📄 295) and specify the HTMS mode.
8. Navigate to Setup → Advanced setup → Application → Tank configuration → Density
9. Go to **Observed density source** (→ 📄 276) and select **HTMS**.
10. Use the other parameters of the HTMS to configure the calculation. For a detailed description: → 📄 293

### 9.5.9 Tank calculation: Hydrostatic Tank Deformation (HyTD)

Hydrostatic Tank Deformation can be used to compensate the vertical movement of the Gauge Reference Height (GRH) due to bulging of the tank shell caused by the hydrostatic pressure exerted by the liquid stored in the tank. The compensation is based on a linear approximation obtained from manual hand dips at several levels divided over the full range of the tank.



A0030164

68 Correction of the hydrostatic tank deformation (HyTD)


- A "Distance" (tank nearly empty)
- B Gauge Reference Height (GRH)
- C HyTD correction value
- D "Distance" (tank filled)





The Correction of the Hydrostatic Tank Deformation is configured in the HyTD  
(→ 285)

### 9.5.10 Tank calculation: Thermal tank shell correction (CTSh)

CTSh (correction for the thermal expansion of the tank shell) compensates for effects on the Gauge Reference Height (GRH) and on the expansion or contraction of the measuring wire due to temperature effects on the tank shell or stilling well. The temperature effects are separated into two parts, respectively affecting the 'dry' and 'wetted' part of the tank shell or stilling well. The correction function is based on thermal expansion coefficients of steel and insulation factors for both the 'dry' and 'wet' parts of the wire and the tank shell. The temperatures used for the correction can be selected from on manual or measured values.

-  This correction is recommended for the following situations:
- if the operating temperature deviates considerably from the temperature during calibration ( $\Delta T > 10\text{ }^{\circ}\text{C}$  (18 °F))
  - for extremely high tanks
  - for refrigerated, cryogenic or heated applications

-  As the use of this correction will influence the innage level reading, it is recommended to ensure the manual hand dip and level verification procedures are being conducted correctly before enabling this correction method.

-  This mode cannot be used in conjunction with HTG because the level is not measured relative to the gauge reference height with HTG.

### 9.5.11 Configuration of the level reference check (LRC) function

For tanks where a manual dipping cannot be performed the level gauge can be verified by means of the LRC function.

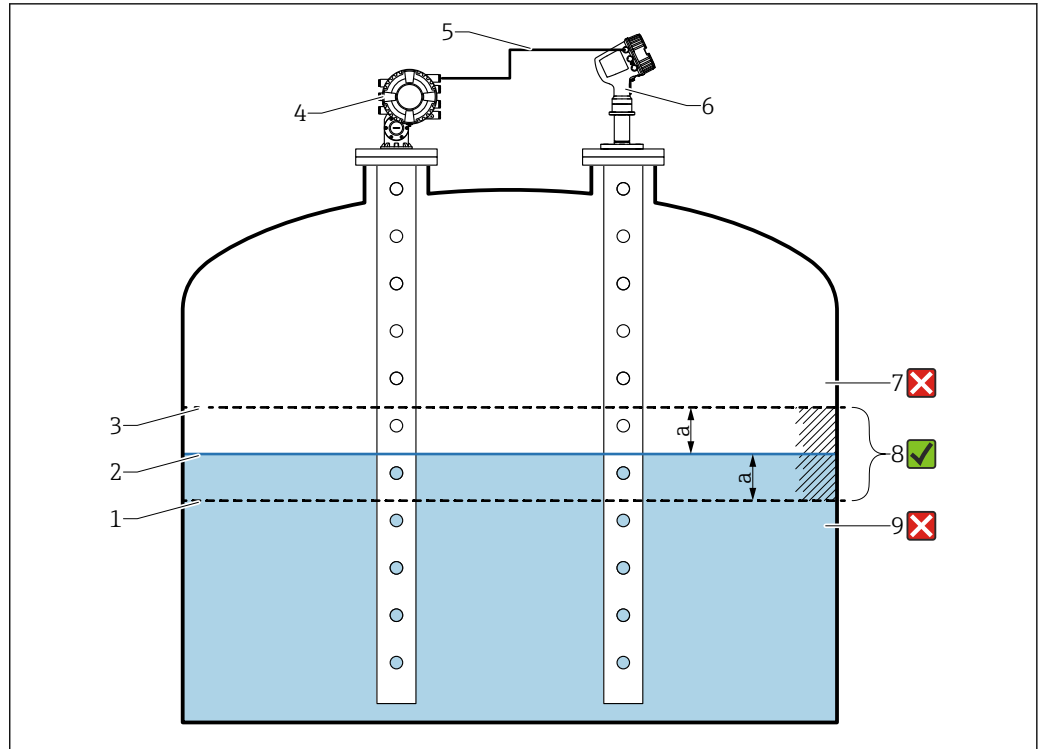
-  This reference check is recommended for liquefied gas applications.

There are different options for this function:

- LRC with reference level
- LRC with reference switch

#### LRC with reference level

The radar device compares its own level reading with the level reading of another level gauge (e.g. Proservo NMS8x). Based on a configurable deviation value (**Allowed difference** parameter), a continuous check is performed.



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69 Application example with Proservo NMS8x

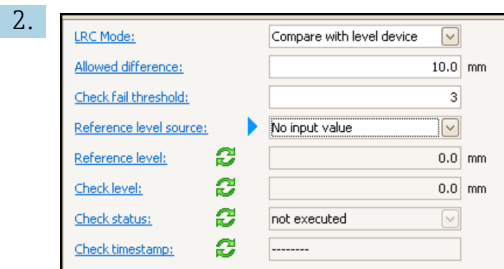
- 1 Lower limit of deviation value "a" as configured in radar level gauge
- 2 Reference value: Measured level as provided by level gauge Proservo NMS8x
- 3 Upper limit of deviation
- 4 Proservo NMS8x provides the reference value
- 5 Level gauges are interconnected via HART interface
- 6 Radar level gauge with configured deviation value "a" for "Allowed difference" parameter
- 7 The measured level is greater than reference value plus deviation value "a". Level value is not verified
- 8 The measured level is within or equal to the limits defined by the deviation value "a". Level value is verified
- 9 The measured level is less than reference value minus deviation value "a". Level value is not verified

Properties

- Frequency: The reference check is performed continuously every 60 seconds.
- Tolerance: Via the **Check fail threshold** parameter, a configurable number of failures is allowed before the status switches to failed.
- Connection: The level reference device is connected via an optional HART I/O board.

Configuration of LRC with reference level

1. Navigate to Diagnostics → LRC → LRC 1 to 2



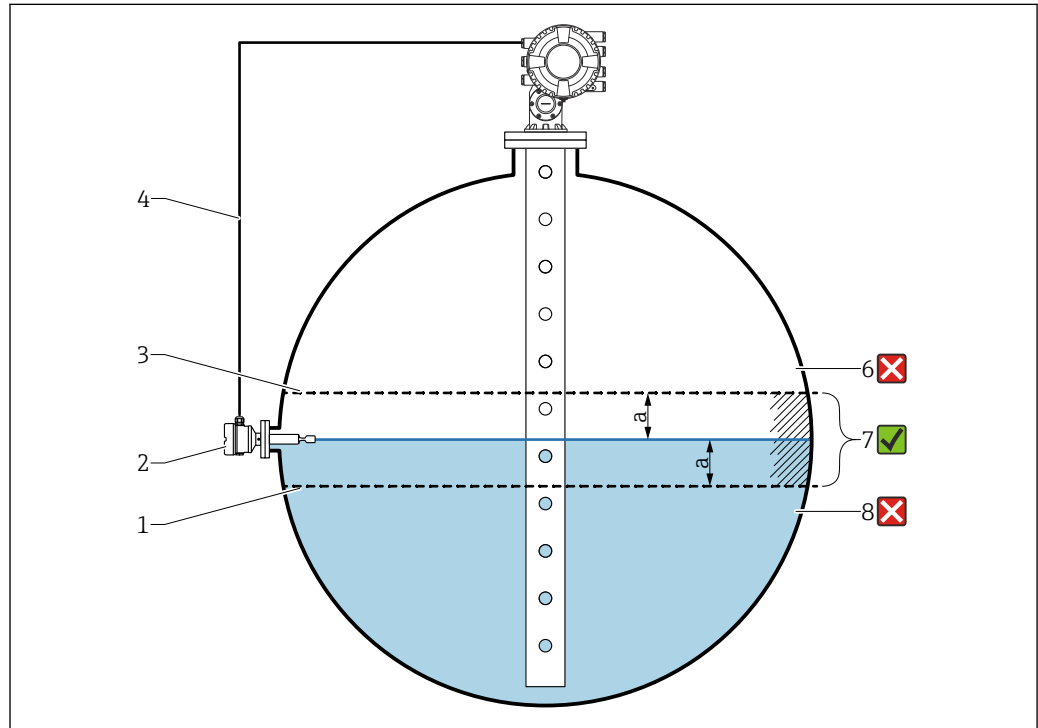
Go to the **LRC Mode** parameter and select the **Compare with level device** option.

3. Go to the **Allowed difference** parameter and specify the value for the allowed difference between the tank level and the reference.

4. Go to the **Check fail threshold** parameter and set the tolerated amount of failures before an alarm is triggered. As the reference check is performed continuously every 60 seconds, this resembles the number of minutes until an alarm is triggered.
5. Go to the **Reference level source** parameter and define the source for the reference level.

### LRC with reference switch

A level switch (e.g. Liquiphant FTLx) can be mounted within the tank. The check can be performed continuously, each time the level switch is activated or deactivated. The measured level should remain within a configurable deviation.



A0054210

#### 70 Application example with level switch

- 1 Lower limit of deviation value "a" as configured in radar level gauge
- 2 Reference value: The switching point of an installed level switch represents the reference value for verification
- 3 Upper limit of deviation
- 4 Level switch and level gauge are interconnected via a digital I/O board
- 5 Radar level gauge with configured deviation value "a" for "Allowed difference" parameter
- 6 The measured level is greater than reference value plus deviation value "a": Level value is not verified
- 7 The measured level is within or equal to the limits defined by the deviation value "a": Level value is verified
- 8 The measured level is less than reference value minus deviation value "a": Level value is not verified

#### Properties

- Modes: The device can be set to monitor the switching point while filling or draining the tank.
- Connection: The level switch is connected via a digital I/O board.

#### Configuration of LRC with reference switch

1. Navigate to Diagnostics → LRC → LRC 1 to 2



2.

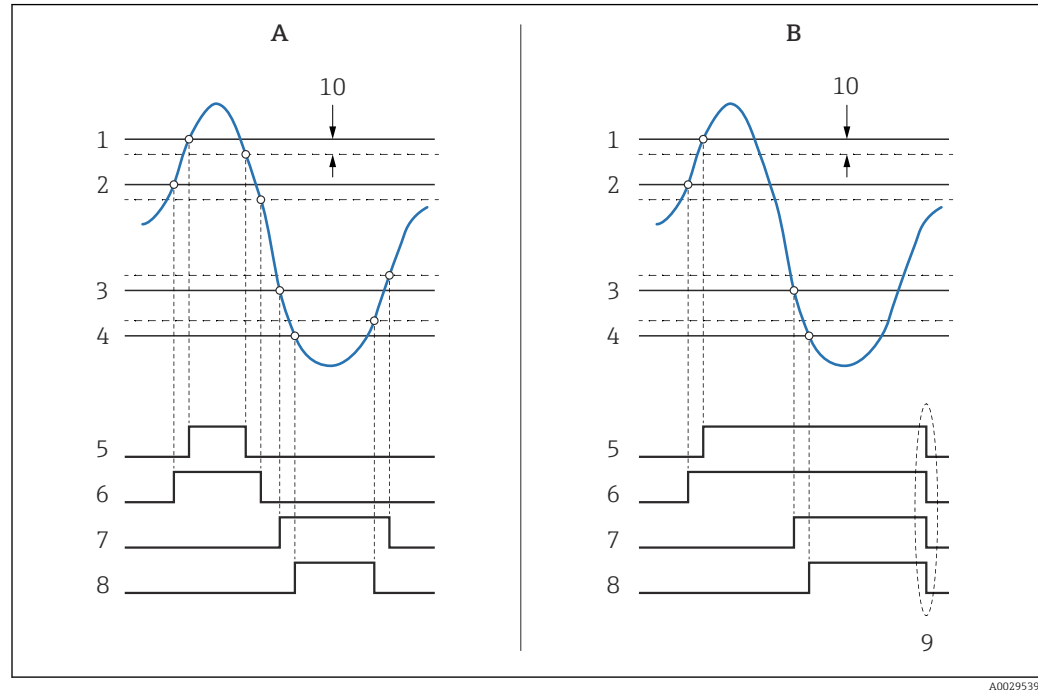
LRC Mode:	Compare with level switch
Allowed difference:	10.0 mm
Reference switch source:	None
Reference switch mode:	Inactive -> Active
Reference switch level:	17740.0 mm
Reference switch state:	Unknown
Check level:	0.0 mm
Check status:	not executed
Check timestamp:	-----

Go to the **LRC Mode** parameter and select the **Compare with level switch** option.

3. Go to the **Allowed difference** parameter and specify the value for the allowed difference between the tank level and the reference.
4. Go to the **Reference switch source** parameter and select the source for the reference switch.
5. Go to the **Reference switch mode** parameter. Select the **Active -> Inactive** option to define the switch direction for the reference check to be executed when the switch status changes from **Active** to **Inactive**. Or select the **Inactive -> Active** option to define the switch direction for the reference check to be executed when the switch status changes from **Inactive** to **Active**.
6. Go to the **Reference switch level** parameter and enter the position of the reference switch by entering a value with a unit of length. This parameter depends on the choice made for the **Distance unit** parameter.
  - ↳ This defines the position of the reference switch as level.

### 9.5.12 Configuration of the alarms (limit evaluation)

A limit evaluation can be configured for up to 4 tank variables. The limit evaluation issues an alarm if the value exceeds an upper limit or falls below a lower limit, respectively. The limit values can be defined by the user.



71 Principle of the limit evaluation

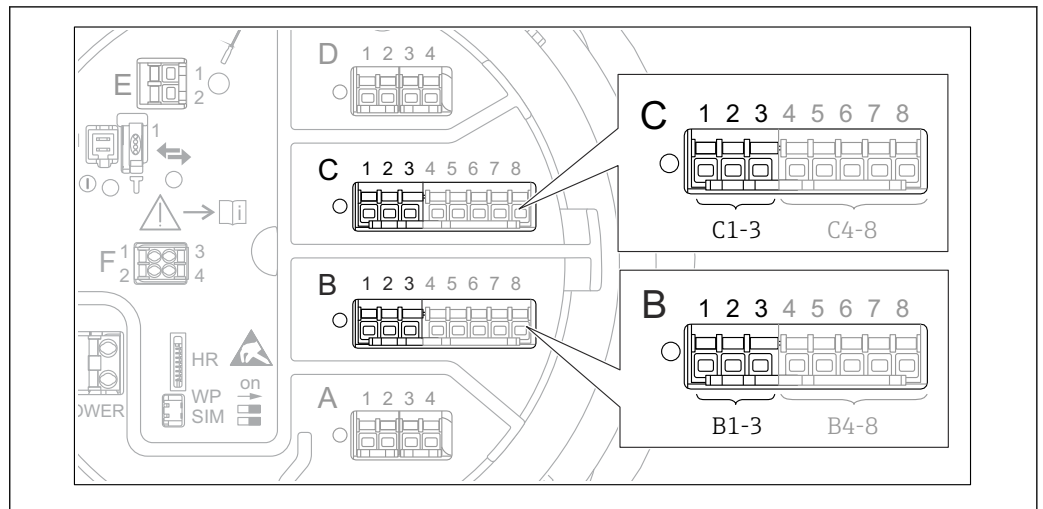
- A Alarm mode = On
- B Alarm mode = Latching
- 1 HH alarm value
- 2 H alarm value
- 3 L alarm value
- 4 LL alarm value
- 5 HH alarm
- 6 H alarm
- 7 L alarm
- 8 LL alarm
- 9 "Clear alarm" = "Yes" or power off-on
- 10 Hysteresis

The limit evaluation is configured in the **Alarm 1 to 4** submenus.

Navigation path: Setup → Advanced setup → Alarm → Alarm 1 to 4

- i** For **Alarm mode = Latching** all alarms remain active until the user selects **Clear alarm = Yes** or the power is switched off and on.
- i** Make sure to also configure the parameter **Hysteresis** accordingly, depending on tank variable and unit used.

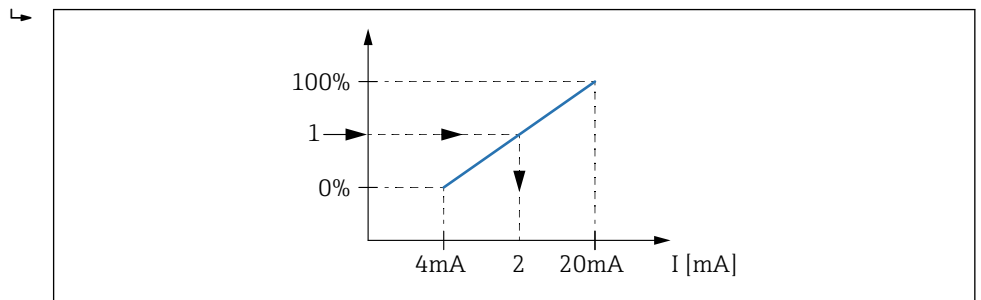
### 9.5.13 Configuration of the 4-20mA output



72 Possible locations of the Analog I/O modules, which can be used as a 4-20mA output. The order code of the device determines which of these modules is actually present → 47.

Each Analog I/O module of the device can be configured as a 4...20mA analog output. To do so, proceed as follows:

1. Navigate to: Setup → Advanced setup → Input/output → Analog I/O X1-3.
2. Go to the Operating mode and select **4..20mA output** or **HART slave +4..20mA output**<sup>4)</sup>.
3. Go to the Analog input source and select the tank variable which is to be transmitted via the 4...20mA output.
4. Go to the 0 % value and enter the value of the selected tank variable which will be mapped to 4 mA.
5. Go to the 100 % value and enter the value of the selected tank variable which will be mapped to 20 mA.



73 Scaling of the tank variable to the output current

- 1 Tank variable
- 2 Output current

- i** After startup of the device, as long as the assigned tank variable is not yet available, the output current assumes the defined error value.
- i** The Analog I/O contains more parameters which can be used for a more detailed configuration of the analog output. For a description see → 227

4) "HART slave +4..20mA output" means that the Analog I/O module serves as a HART slave which cyclically sends up to four HART variables to a HART master. For the configuration of the HART output: → 128

### 9.5.14 Configuration of the HART slave + 4 to 20 mA output

If **Operating mode = HART slave +4..20mA output** has been selected for an Analog I/O module, it serves as a HART slave which sends up to four HART variables to a HART master.

**i** The 4 to 20 mA signal can be used in this case, too. For its configuration: → 127

#### Standard case: PV = 4 to 20 mA signal

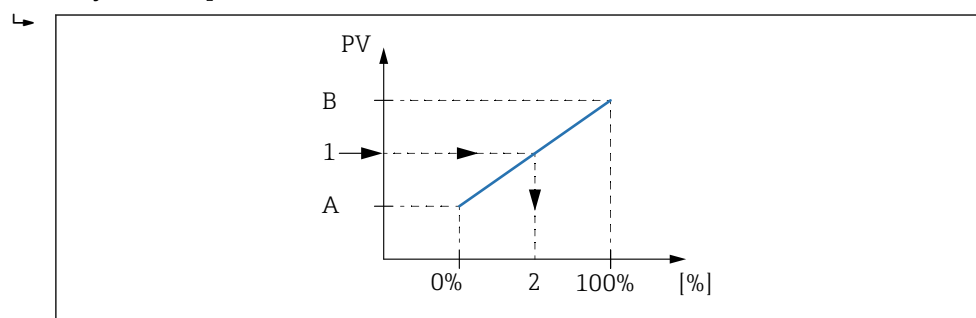
By default, the Primary Variable (PV) is identical to the tank variable transmitted by the 4-20mA output. To define the other HART variables and to configure the HART output in more detail, proceed as follows:

1. Navigate to: Setup → Advanced setup → Communication → HART output → Configuration
2. Go to the System polling address and set the HART slave address of the device.
3. Use the following parameters to assign tank variables to the second to fourth HART variable: **Assign SV**, **Assign TV**, **Assign QV**.
  - ↳ The four HART variables are transmitted to a connected HART Master.

#### Special case: PV ≠ 4 to 20 mA signal

In exceptional cases it might be required that the Primary Variable (PV) transmits a different tank variable than the 4-20mA output. This is configured as follows.

1. Navigate to: Setup → Advanced setup → Communication → HART output → Configuration
2. Go to the PV source and select **Custom**.
  - ↳ The following additional parameters appear in the submenu: **Assign PV**, **0 % value**, **100 % value** and **PV mA selector**.
3. Go to the Assign PV and select the tank variable to be transmitted as the Primary Variable (PV).
4. Use the **0 % value** and **100 % value** parameters to define a range for the PV. The Percent of range indicates the percentage for the actual value of the PV. It is included in the cyclical output to the HART master.



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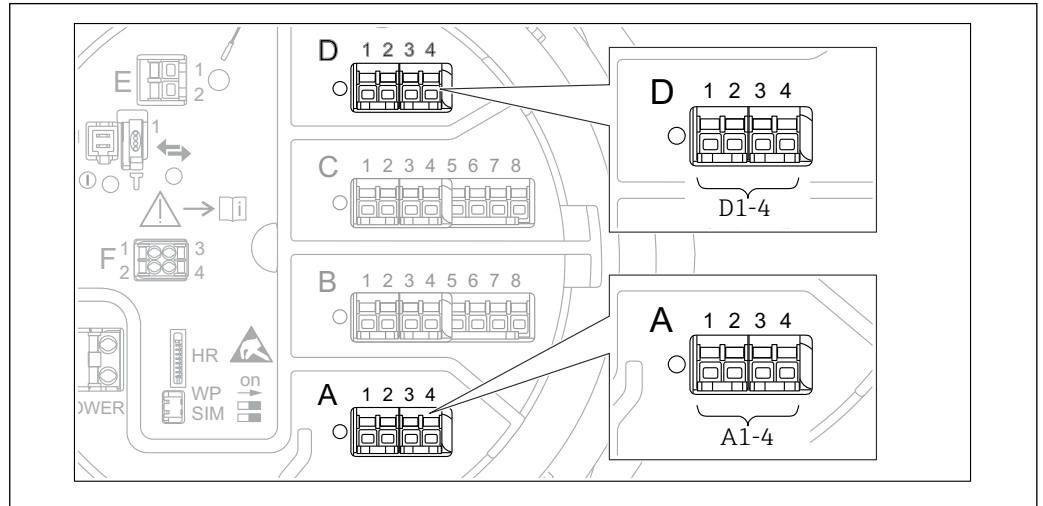
74 *Scaling of the tank variable to the percentage*

- A 0 % value
- B 100 % value
- 1 Primary variable (PV)
- 2 Percent of range

5. Use the PV mA selector to define whether the output current of an Analog I/O module is to be included in the cyclical HART output.

- i** After startup of the device, as long as the assigned tank variable is not yet available, the output current assumes the defined error value.
- i** The PV mA selector does not influence the output current at the terminals of the Analog I/O module. It only defines whether the value of this current is part of the HART output or not.

### 9.5.15 Configuration of the Modbus output



A0031200

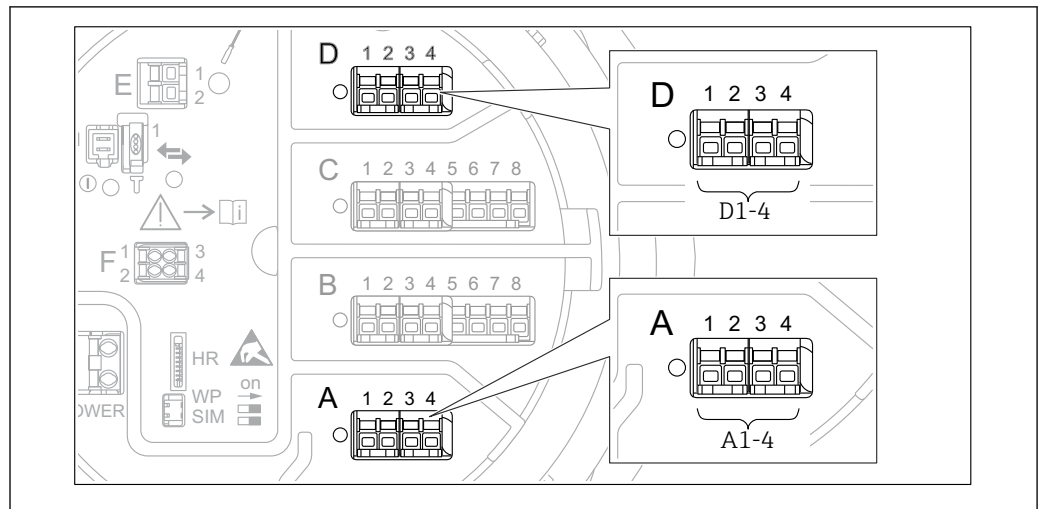
**75** Possible locations of the Modbus modules (examples); depending on the device version these modules may also be in slot B or C → **47**.

The Proservo NMS8x acts as a Modbus slave. Measured or calculated tank values are stored in registers which can be requested by a Modbus master.

The following submenu is used to configure the communication between the device and the Modbus master:

Setup → Advanced setup → Communication → Modbus X1-4 → Configuration (→ **248**)

### 9.5.16 Configuration of the V1 output



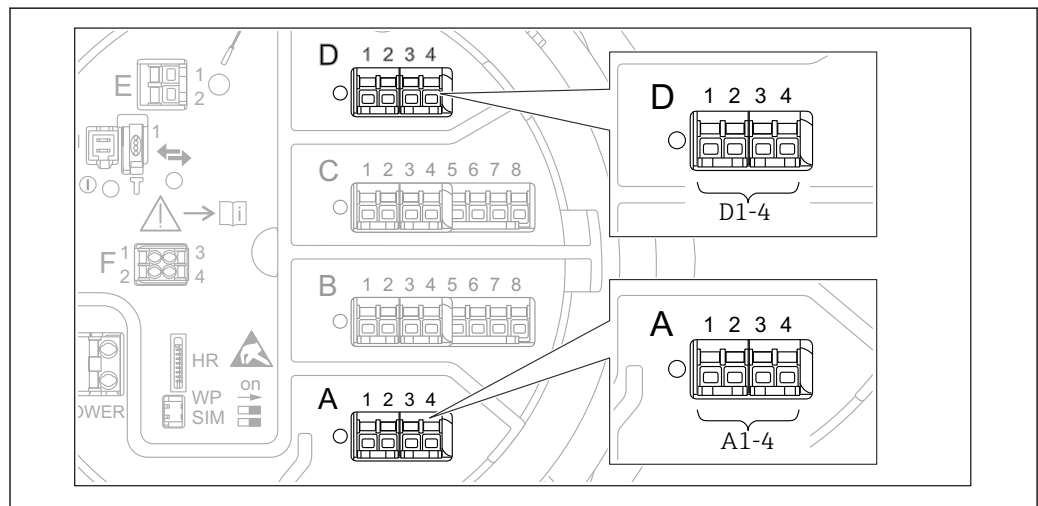
A0031200

- 76 Possible locations of the V1 modules (examples); depending on the device version these modules may also be in slot B or C → 47.

The following submenus are used to configure the V1 communication between the device and the control system:

- Setup → Advanced setup → Communication → V1 X1-4 → Configuration → 251
- Setup → Advanced setup → Communication → V1 X1-4 → V1 input selector → 254

### 9.5.17 Configuration of the WM550 output



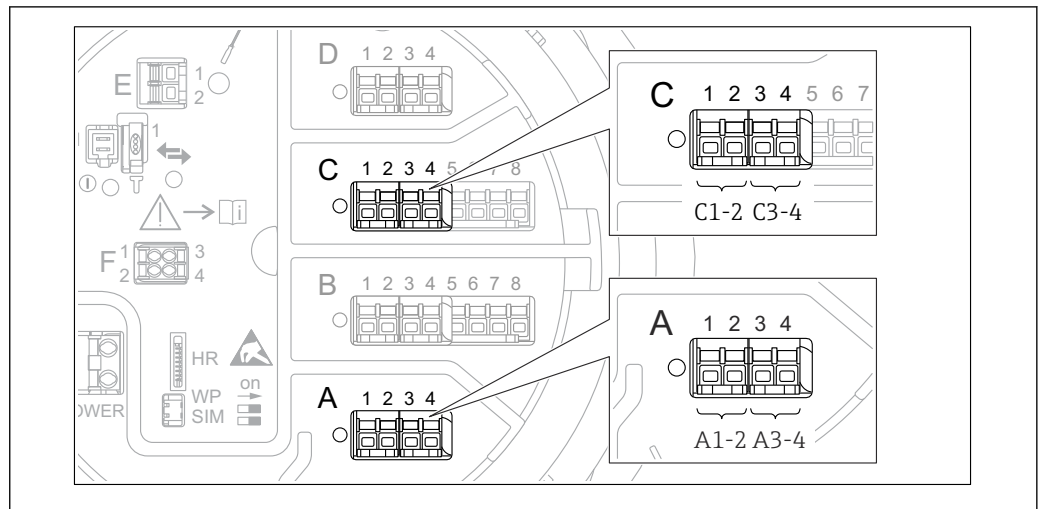
A0031200

- 77 Possible locations of the WM550 modules (examples); depending on the device version these modules may also be in slot B or C → 47.

The following submenus are used to configure the WM550 communication between the device and the control system:

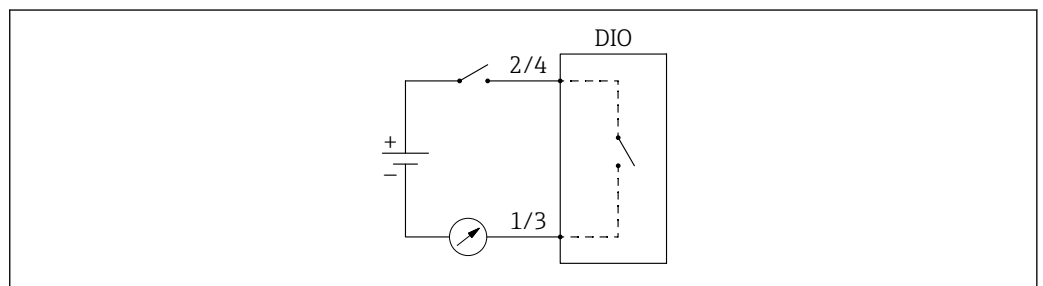
- Setup → Advanced setup → Communication → WM550 X1-4 → Configuration → 247
- Setup → Advanced setup → Communication → WM550 X1-4 → WM550 input selector → 256

### 9.5.18 Configuration of the digital outputs



A0026424

78 Possible locations of the Digital I/O modules (examples); the order code defines the number and location of Digital I/O modules → 47.



A0033029

79 Usage of the Digital I/O module as a digital output

There is a **Digital Xx-x** submenu for each digital I/O module of the device. "X" designates the slot in the terminal compartment, "x-x" the terminals within this slot. The most important parameters of this submenu are **Operating mode**, **Digital input source** and **Contact type**.



A digital output can be used to

- output the state of an alarm (if an alarm has been configured → 126)
- transmit the status of a digital input (if a digital input has been configured → 117)


To configure a digital output, proceed as follows:

1. Navigate to Setup → Advanced setup → Input/output → Digital Xx-x, where Xx-x designates the digital I/O module to be configured.
2. Go to the Operating mode and select the Output passive.
3. Go to the Digital input source and select the alarm or digital input to be transmitted.
4. Go to the Contact type and select how the internal state of the alarm or digital input is to be mapped to the digital output (see table below).


<ul style="list-style-type: none"> <li>▪ State of the alarm</li> <li>▪ Internal state of the digital input</li> </ul>	Switching state of the digital output	
	Contact type = Normally open	Contact type = Normally closed
Inactive	Open	Closed
Active	Closed	Open

-  For SIL applications, **Contact type** is automatically set to **Normally closed** by the device when starting the SIL confirmation procedure.
- In case of a power supply failure, the switching state is always "open", irrespective of the selected option.
- The Digital Xx-x contains additional parameters for a more detailed configuration of the Digital Input. For a description refer to →  237.

## 9.6 Advanced settings



For a more detailed configuration of the signal inputs, the tank calculations and the signal outputs refer to the Advanced setup (→  212).

## 9.7 Simulation

To check the correct configuration of the device and of the control system, it is possible to simulate different situations (measured values, diagnostic messages etc.). See the Simulation (→  342) for details.

## 9.8 Protecting settings from unauthorized access

There are two possibilities to protect the settings from unauthorized access:

- By an access code (→  78)
  - This locks the access via the display and operating module.
- By the protection switch (→  79)
  - This locks the access to weight and mesure (W&M)-related parameters by any user interface (display and operating module, FieldCare, other configuration tools).



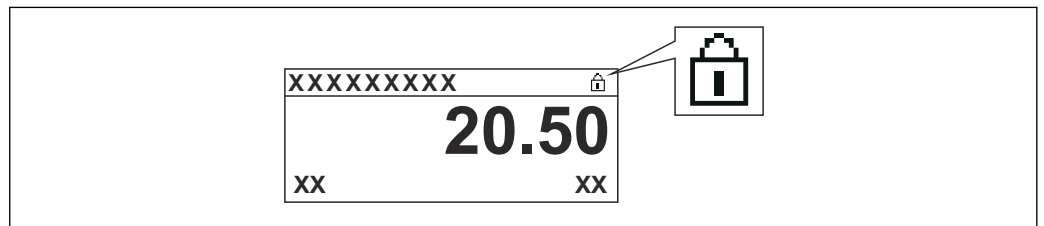
## 10 Operation

### 10.1 Reading off the device locking status

Depending on the locking state of the device some operations may be locked. The current locking status is indicated at: Setup → Advanced setup → Locking status. The following table summarizes the different locking statuses:

Locking status	Meaning	Unlocking procedure
Hardware locked	The device is locked by the write-protection switch in the terminal compartment.	→  79
SIL locked	The device is in SIL-locked mode.	Detailed information on this topic see SIL Safety manual
CT active - all parameters	The weight and measure (W&M) mode is active.	→  79
WHG locked	The device is in WHG-locked mode.	Detailed information on this topic see SIL Safety manual
Temporarily locked	Write access to the parameters is temporarily lock due to device-internal processing (e.g. data upload/download, reset). Once the internal processing has been completed, the parameters can be changed again.	Wait for completion of the device-internal processing.

A locking is indicated by the write protection symbol in the header of the display:



A0015870

### 10.2 Reading off measured values

Tank values can be read off in the following submenus:

- Operation → Level
- Operation → Temperature
- Operation → Density
- Operation → Pressure

## 10.3 Gauge commands

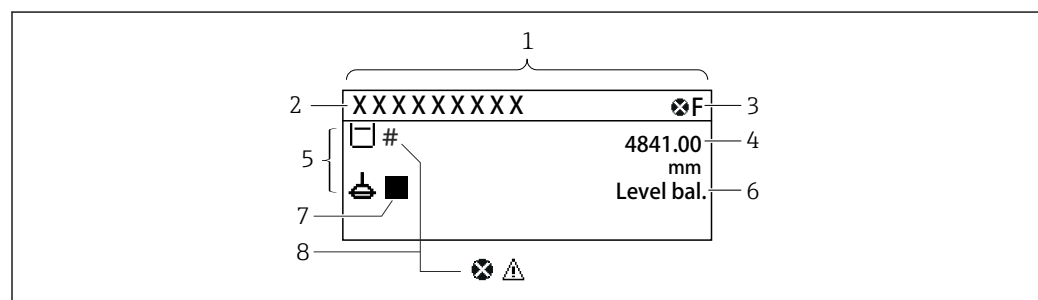
### 10.3.1 Overview of available device functions

Gauge commands are mainly divided into two categories.

- Continuous gauge command
- One-time gauge command (non-continuous)

**i** One-time gauge commands have a defined end state. After a one-time gauge command is completed, another gauge command is executed which is defined by the Post gauge command. If **Post gauge command** is set to **None**, the operation will stop.

The gauge command can be chosen by navigating to Operation → Gauge command. The status of the gauge command execution is shown in the Gauge status. The gauge status is displayed on the home screen by default.



A0028702

**80** Typical appearance of the standard view (measured value display)


- 1 Display module
- 2 Device tag
- 3 Status area
- 4 Display area for measured values
- 5 Display area for measured value and status symbols
- 6 Gauge status indication
- 7 Gauge status symbol
- 8 Measured value status symbol

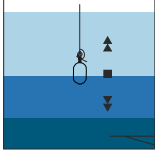
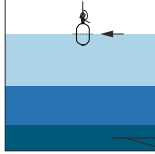
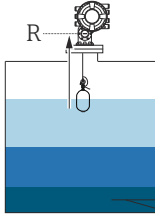
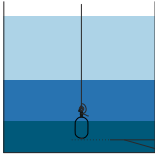
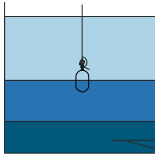
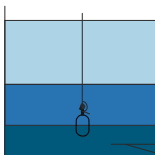
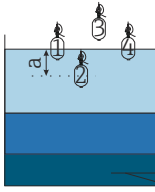
For details of status symbols → **69**

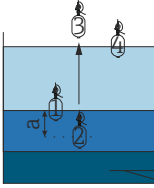
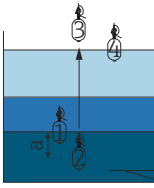

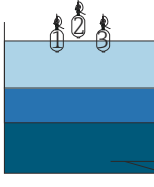
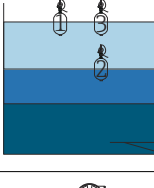

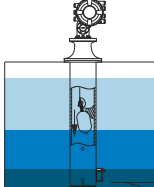
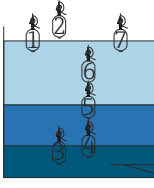
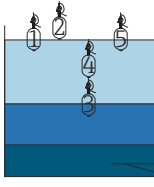
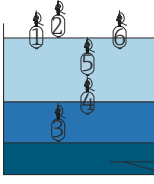
When a one-time gauge command is executed, additional information is shown in the One-time command status in the operation menu.


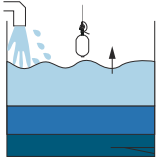

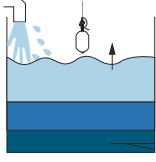
### 10.3.2 Descriptions of gauge commands

The following table shows the available gauge commands and functions of NMS8x.

 The numbers in the figures show the sequence of displacer movement.

Gauge command	Descriptions		Post gauge command
Stop	Displacer stops.		Not available
Level	The displacer searches for the liquid level surface and balances there.		Not available
Up	The displacer moves up to the reference position.	 <i>R Reference position</i>	Not available
Bottom level	The displacer searches for the tank bottom. After determining the bottom value, the post gauge command is executed.		Customer setting value
Upper I/F level	The displacer searches for the upper interface level and balances there.		Not available
Lower I/F level	The displacer searches for the lower interface level and balances there.		Not available
Upper density	NMS8x performs a spot density measurement in the upper phase of the tank. After completing the measurement, the post gauge command is executed.	 <i>a Immersion depth</i>	Customer setting value

Gauge command	Descriptions		Post gauge command
Middle density	NMS8x performs a spot density measurement in the middle phase of the tank. After completing the measurement, the post gauge command is executed.	 <p data-bbox="1002 501 1187 533"><i>a</i> Immersion depth</p>	Customer setting value
Lower density	NMS8x performs a spot density measurement in the lower phase of the tank. After completing measurement, the post gauge command is executed.	 <p data-bbox="1002 763 1187 795"><i>a</i> Immersion depth</p>	Customer setting value
Repeatability	<p>The displacer moves upwards from the liquid. After that, the displacer returns to the level measurement. This can be used for a function check.</p> <p> This gauge command should only be executed if the current gauge command is level.</p>		Level
Water dip	The displacer searches for the upper interface level. After balancing on the liquid, the post gauge command is executed.		Customer setting value
Release overtension	<p>When the displacer hits any obstacle in the tank and gets stuck (Error message: Overtension) this command will release the tension on the wire by moving down a short distance.</p> <p> During an overtension error, no other gauge command will be executed.</p>		Stop
Tank profile	Density profile measurement of the tank (tank bottom to level)		Customer setting value
Interface profile	Density profile measurement of the upper interface (upper I/F level to level)		Customer setting value
Manual profile	Density profile measurement from a manually set position to level		Customer setting value

Gauge command	Descriptions		Post gauge command
Level standby	<p>The displacer moves to a set position and stays there until the tank level reaches this position. After that, gauge command is changed back to level.</p> <p> This function can be used when supplying or discharging liquid.</p>		Level
Offset standby	<p>The displacer moves upwards for the distance which is set from the current position and stays there until the tank level reaches this position. After that, gauge command is changed back to level.</p> <p> This function can be used when supplying or discharging liquid.</p>		Level

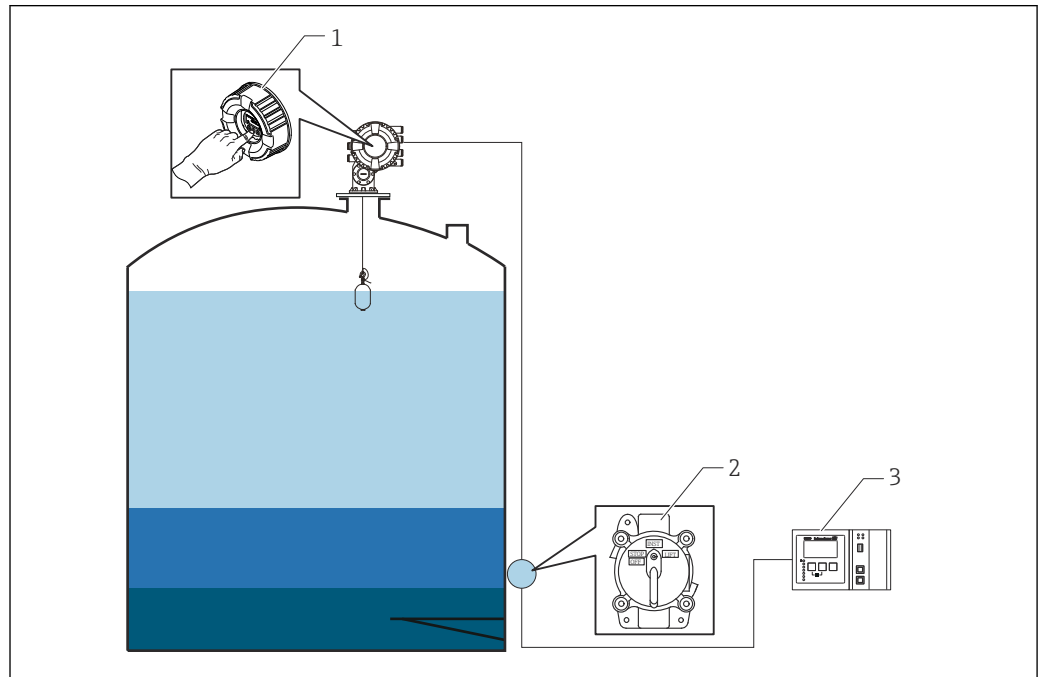
### 10.3.3 Sources for gauge commands

Gauge commands can be sent via various sources.

- Displays or CDI (e.g. FieldCare)
- Digital input (e.g. control switch)
- Fieldbus (Modbus, V1, HART)

The last received gauge command via any sources will be executed as usual.

**i** During calibration, gauge commands are not accepted from any sources.



- 1 Display operation
- 2 Digital input (e.g. control switch)
- 3 Tankvision

#### Gauge command priorities

The priority of the gauge command for NMS8x is very simple. The last received gauge command via any sources will be executed to take of the former gauge command. However the priority varies depending on the devices. When replacing the device with the NMS8x, check the priorities shown below.

#### NOTICE

##### Undesired gauge command will be executed.

If the setting is not changed, an undesired gauge command will be executed (e.g. Level command via Fieldbus would overwrite Stop command for maintenance.).

- If the system has been automatically or semi-automatically programmed for operation, maintenance or other purposes, the setting should be changed corresponding to use.

#### Proservo NMS8x

By display		From digital input		From Fieldbus	
Command	Priority	Command	Priority	Command	Priority
Level	1	Level	1	Level	1
Interface	1	Interface	1	Interface	1
Tank bottom	1	Tank bottom	1	Tank bottom	1

By display		From digital input		From Fieldbus	
Spot density	1	Spot density	1	Spot density	1
Profile density	1	Profile density	1	Profile density	1
Up	1	Up	1	Up	1
Stop	1	Stop	1	Stop	1

### Proservo NMS5/NMS7

By display		From NRF560		From digital input		From Fieldbus	
Command	Priority	Command	Priority	Command	Priority	Command	Priority
Level	4	Level	4	Level	4	Level	4
Interface	2	Interface	3	Interface	1	Interface	4
Tank bottom	2	Tank bottom	3	N/A	N/A	Tank bottom	4
Spot density	2	Spot density	3	N/A	N/A	Spot density	4
Profile density	2	Profile density	3	N/A	N/A	Profile density	4
Up	2	Up	3	Up	1	Up	4
Stop	2	Stop	3	Stop	1	Stop	4

### Servo level gauge TGM5

By display		From NRF560		From DRM9700		From digital input		From Fieldbus	
Command	Priority	Command	Priority	Command	Priority	Command	Priority	Command	Priority
Level	4	Level	4	Level	4	Level	4	Level	4
Interface	2	Interface	3	N/A	N/A	N/A	N/A	Interface	4
Tank bottom	2	Tank bottom	3	N/A	N/A	N/A	N/A	Tank bottom	4
Spot density	2	Spot density	3	N/A	N/A	N/A	N/A	Spot density	4
Profile density	2	Profile density	3	N/A	N/A	N/A	N/A	Profile density	4
Up	2	Up	3	Up	1	Up	1	Up	4
Stop	2	Stop	3	N/A	N/A	Stop	1	Stop	4

### Servo level gauge TGM4000

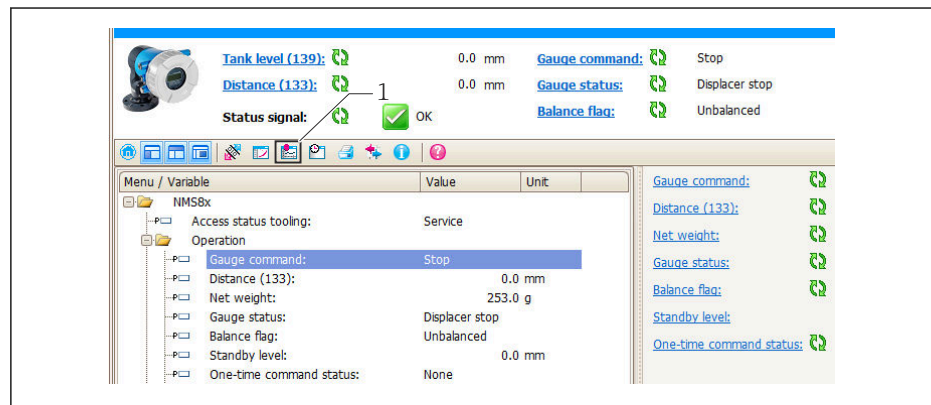
By display		From DRM9700		From digital input		From Fieldbus	
Command	Priority	Command	Priority	Command	Priority	Command	Priority
Level	4	Level	4	Level	4	Level	4
Interface	2	Interface	1	N/A	N/A	Interface	4
Tank bottom	2	N/A	N/A	N/A	N/A	Tank bottom	4
Spot density	2	N/A	N/A	N/A	N/A	Spot density	4
Profile density	2	N/A	N/A	N/A	N/A	Profile density	4
Up	2	Up	1	Up	1	Up	4
Stop	2	Stop	N/A	Stop	1	Stop	4

## 10.4 Confirmation of drum and density tables via FieldCare

### 10.4.1 Drum table in FieldCare

The drum table is measured at up to 50 points spaced at equal intervals through one turn. The drum table has two tables called the High table (weight: 250 g) and the Low table (weight: 50 g) and they can be checked as a graph by clicking the following icons in FieldCare.

1. Open the table by clicking on the table icon.
  - ↳ The graphical table is shown.

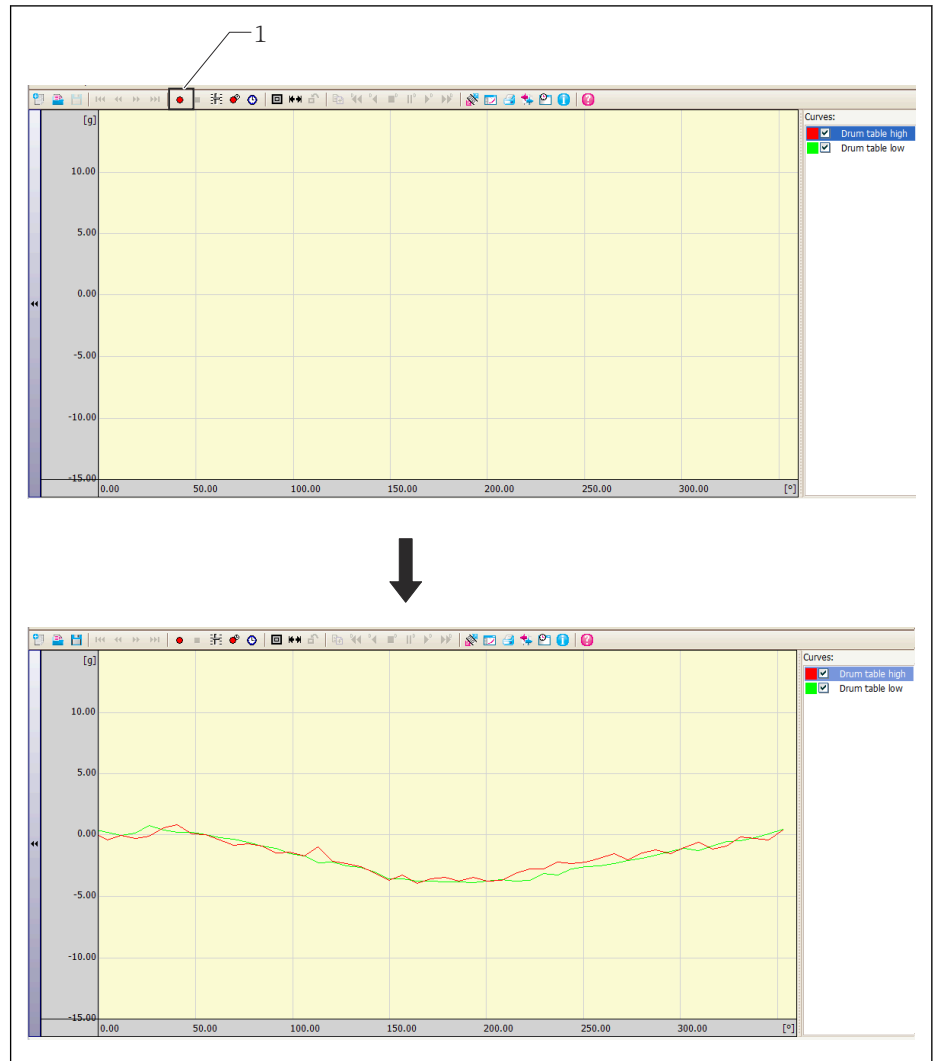


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- 1 Table icon; calls up the table.



2. Press the read curve icon.
  - ↳ The drum table high and low is shown.



1 Read curve

This completes the drum table confirmation.

- i** When a reference calibration is executed, the saved data of the drum table will be discarded and all weights will show 0 g. When a drum calibration is executed, the saved drum table will be updated.

### 10.4.2 Density table

When the profile command is executed, a density profile is obtained and saved. There are three types of profile as follows.

- Tank profile
- Interface profile
- Manual profile

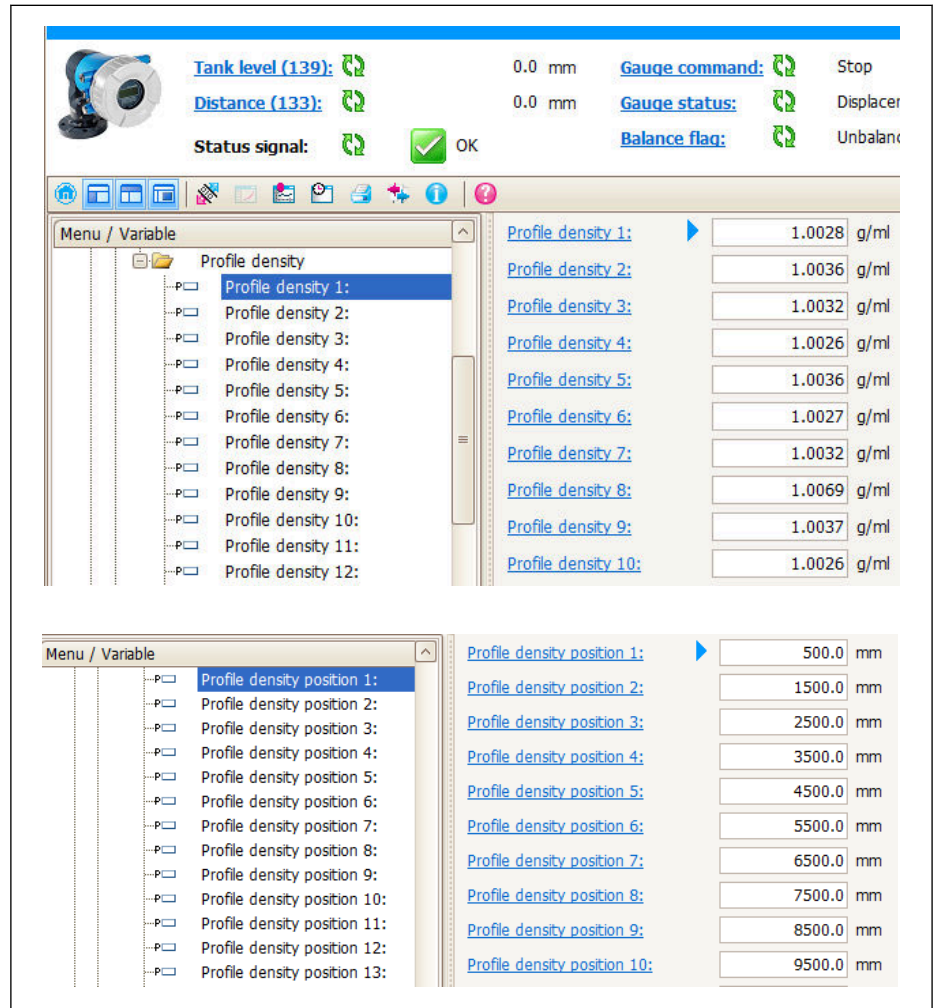
Profile data of up to 50 points can be obtained and saved. For details of the profile command settings, refer to the Operating Instructions (BA) of the respective device.

### 10.4.3 Density table in FieldCare

Saved data of the density profile can be confirmed in FieldCare in two ways as follows.

#### Density confirmation at main menu of FieldCare

1. Navigate to: Operation → Density → Profile density → Profile density 1 to 50
  - ↳ The profile density for each point is shown.
2. Navigate to: Operation → Density → Profile density → Profile density position 1 to 50
  - ↳ The profile density position is shown.



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This completes the confirmation procedure at the main menu of FieldCare.


# 11 Diagnostics and troubleshooting

## 11.1 General trouble shooting

### 11.1.1 General errors

Error	Possible cause	Remedial action
Device does not respond.	Supply voltage not connected.	Connect the correct voltage.
	The cables do not contact the terminals properly.	Ensure electrical contact between the cable and the terminal.
Values on the display invisible	The plug of the display cable is not connected correctly.	Connect the plug correctly.
	Display is defective.	Replace display.
	Display contrast too low.	Set Setup → Advanced setup → Display → Contrast display to a value $\geq 60\%$ .
"Communication error" is indicated on the display when starting the device or connecting the display	Electromagnetic interference	Check grounding of the device.
	Broken display cable or display plug.	Exchange display.
CDI communication does not work.	Wrong setting of the COM port on the computer.	Check the setting of the COM port on the computer (e.g. FieldCare) and change it if necessary.
Device measures incorrectly.	Parametrization error	Check and adjust parameterization.

### 11.1.2 Measurement specific errors

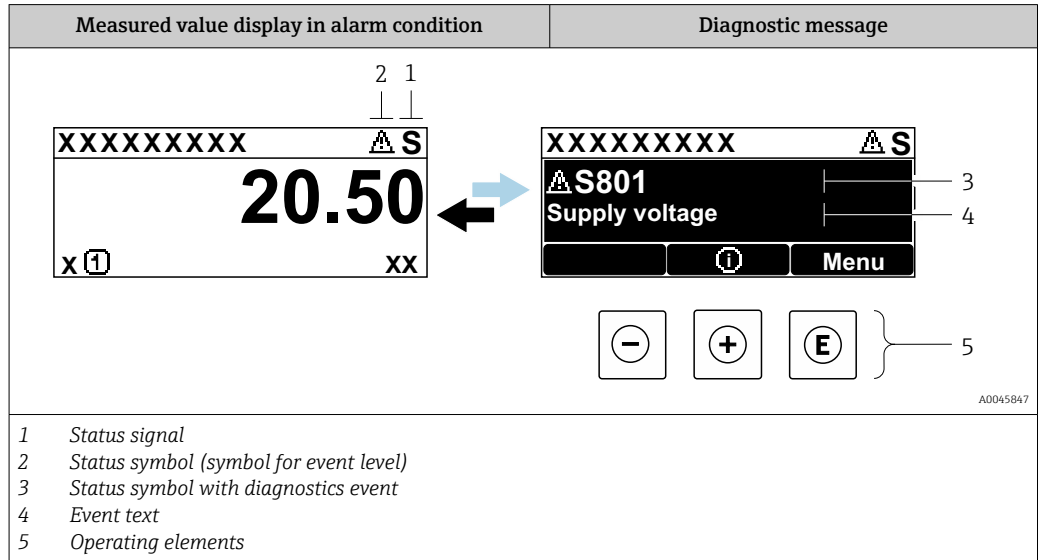
Error	Possible case	Remedy
Displacer not balancing	No water in the tank	
	Liquid surface unstable	Change Process condition.
	Incorrect density setting	Check density setting.
Displacer not traveling to reference position	High stop level	Check gauge status.
	Over tension	Check gauge status and gauge command.  The function, Release overtension, can only be performed.
Displacer not measuring the bottom level	Low stop level	Check gauge status.
	Under tension	Check gauge status.
	Bottom detection weight wrong	Check Bottom detection weight in Service mode.
Gauge status not working under the following levels. <ul style="list-style-type: none"> <li>▪ Upper/lower interface</li> <li>▪ Middle/lower density</li> <li>▪ IF (Interface) profile</li> <li>▪ Water dip</li> </ul>	Those setting of Upper, Middle, and Lower density are set to same value.	Upper density < Middle density < Lower density The difference of value 0.2 g/ml or more is required for setting as follows. <e.g> <ul style="list-style-type: none"> <li>▪ 0.8 g/ml</li> <li>▪ 1.0 g/ml</li> <li>▪ 1.2 g/ml</li> </ul>
After turning on the power, the previous gauge command is not effective.	Digital input gauge status is effective.	Check the Digital input mapping.

Error	Possible case	Remedy
Invalid level setting	Gauge command of Balanced is not valid when Set level was issued.	Check the gauge command and set level again.
Invalid liquid temperature	Incorrect liquid temperature source	Check Liquid temp source.
	HART device disconnected	Check HART device
Invalid vapor temperature	Incorrect liquid temperature source	Check Liquid temp source.
	HART device disconnected	Check HART device
Invalid liquid level	Incorrect water level source	Check Water level source
	HART device disconnected	Check HART device
Status is not SIL mode	The status of Gauge command is not on Level mode.	Check gauge command is on Level.
	Incorrect AIO parameter setting	Check the Operating mode, 4 to 20 mA output
		Check the Use for SIL is valid.
	Incorrect DIO parameter setting	Check the Operating mode, Output passive.
		Check the Contact type is Normally closed.
		Check the Use for SIL is valid.

## 11.2 Diagnostic information on local display

### 11.2.1 Diagnostic message

Faults detected by the self-monitoring system of the measuring device are displayed as a diagnostic message in alternation with the measured value display.



### Status signals

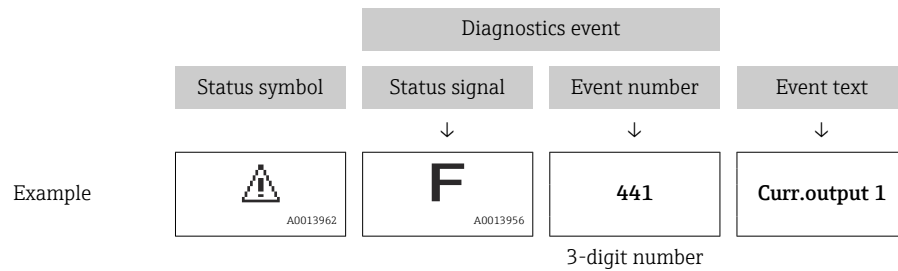
<b>F</b> <small>A0013956</small>	<b>"Failure"</b> A device error is present. The measured value is no longer valid.
<b>C</b> <small>A0013959</small>	<b>"Function check"</b> The device is in service mode (e.g. during a simulation or a warning).
<b>S</b> <small>A0013958</small>	<b>"Out of specification"</b> The device is operated: <ul style="list-style-type: none"> <li>▪ Outside of its technical specifications (e.g. during startup or a cleaning)</li> <li>▪ Outside of the configuration carried out by the user (e.g. level outside configured span)</li> </ul>
<b>M</b> <small>A0013957</small>	<b>"Maintenance required"</b> Maintenance is required. The measured value is still valid.


### Status symbol (symbol for event level)

 <small>A0013961</small>	<b>"Alarm" status</b> The measurement is interrupted. The signal outputs take on the defined alarm condition. A diagnostic message is generated.
 <small>A0013962</small>	<b>"Warning" status</b> The device continues to measure. A diagnostic message is generated.



### Diagnostics event and event text

The fault can be identified using the diagnostics event. The event text helps you by providing information about the fault. In addition, the corresponding symbol is displayed before the diagnostics event.

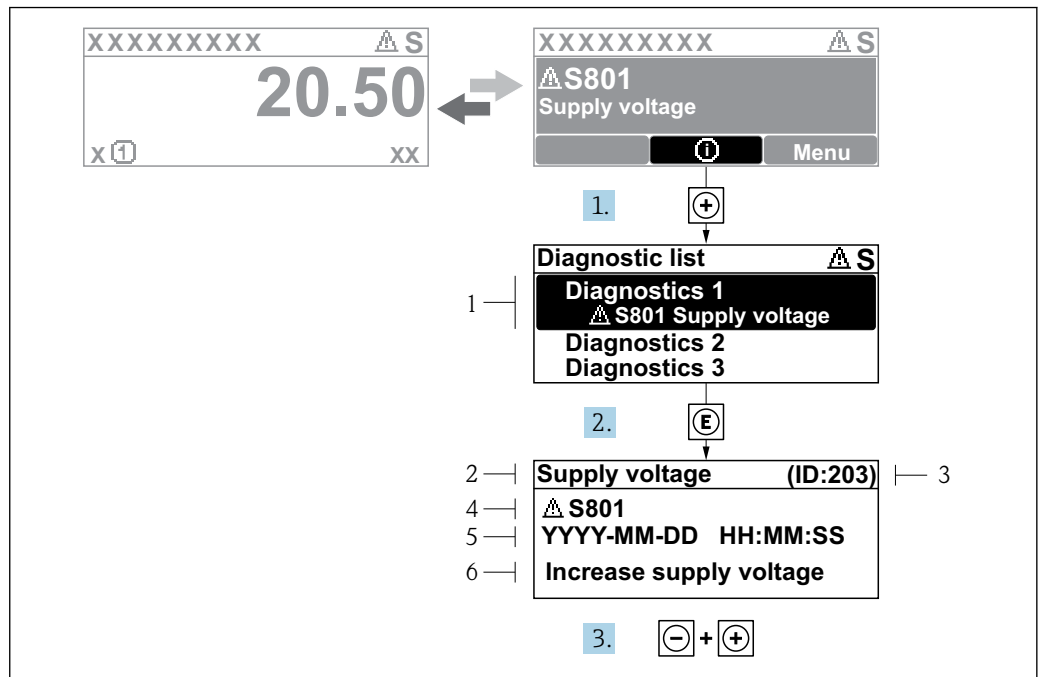


If two or more diagnostic messages are pending simultaneously, only the message with the highest priority is shown. Additional pending diagnostic messages can be shown in **Diagnostic list** submenu (→  338).

### Operating elements

Operating functions in menu, submenu	
 A0013970	<b>Plus key</b> Opens the message about the remedial measures.
 A0013952	<b>Enter key</b> Opens the operating menu.

### 11.2.2 Calling up remedial measures



81 Message for remedial measures

A0045845

- 1 Diagnostic information
- 2 Short text
- 3 Service ID
- 4 Diagnostic behavior with diagnostic code
- 5 Operation time of occurrence
- 6 Remedial measures

A diagnostic message appears in the standard view (measured value display).

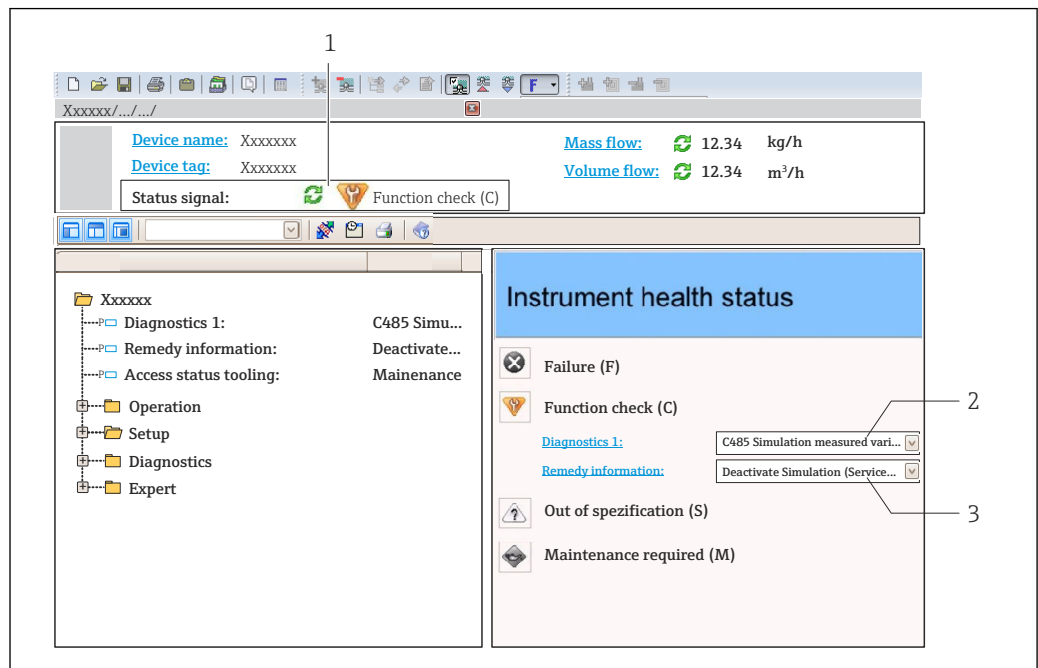
1. Press **+** (**i** symbol).  
↳ The **Diagnostic list** submenu opens.
2. Select the desired diagnostic event with **+** or **-** and press **⏏**.  
↳ The message for the remedial measures for the selected diagnostic event opens.
3. Press **-** + **+** simultaneously.  
↳ The message for the remedial measures closes.

The user is in the **Diagnostics** menu at an entry for a diagnostics event, e.g. in the **Diagnostic list** submenu or in the **Previous diagnostics**.

1. Press **⏏**.  
↳ The message for the remedial measures for the selected diagnostic event opens.
2. Press **-** + **+** simultaneously.  
↳ The message for the remedial measures closes.

### 11.3 Diagnostic information in FieldCare

Any faults detected by the measuring device are displayed on the home page of the operating tool once the connection has been established.



- 1 Status area with status signal
- 2 Diagnostic information
- 3 Remedial measures with Service ID

**i** Furthermore, diagnostic events that have occurred can be viewed in the Diagnostic list.

#### 11.3.1 Status signals

The status signals provide information on the state and reliability of the device by categorizing the cause of the diagnostic information (diagnostic event).

Symbol	Meaning
 <small>A0017271</small>	<b>Failure</b> A device error has occurred. The measured value is no longer valid.
 <small>A0017278</small>	<b>Function check</b> The device is in service mode (e.g. during a simulation or a warning).
 <small>A0017277</small>	<b>Out of specification</b> The device is operated outside its technical specification limits (e.g. outside the process temperature range)
 <small>A0017276</small>	<b>Maintenance required</b> Maintenance is required. The measured value is still valid.

**i** The status signals are categorized in accordance with VDI/VDE 2650 and NAMUR Recommendation NE 107.



### 11.3.2 Calling up remedy information

Remedy information is provided for every diagnostic event to ensure that problems can be rectified quickly:

- On the home page  
Remedy information is displayed in a separate field below the diagnostics information.
- In the **Diagnostics** menu  
Remedy information can be called up in the working area of the user interface.

The user is in the **Diagnostics** menu.

1. Call up the desired parameter.
2. On the right in the working area, mouse over the parameter.
  - ↳ A tool tip with remedy information for the diagnostic event appears.

## 11.4 Overview of the diagnostic messages

Diagnostic number	Short text	Remedy instructions	Status signal [from the factory]	Diagnostic behavior [from the factory]
<b>Diagnostic of sensor</b>				
102	Sensor incompatible error	1. Restart device 2. Contact service	F	Alarm
150	Detector error	1. Restart device 2. Check electrical connections of detector 3. Replace detector unit	F	Alarm
151	Sensor electronic failure	Replace sensor electronic module	F	Alarm
<b>Diagnostic of electronic</b>				
242	Software incompatible	1. Check software 2. Flash or change main electronic module	F	Alarm
252	Modules incompatible	1. Check if correct electronic module is plugged 2. Replace electronic module	F	Alarm
261	Electronic modules	1. Restart device 2. Check electronic modules 3. Change I/O module or main electronics	F	Alarm
262	Module connection	1. Check module connections 2. Replace electronic modules	F	Alarm
270	Main electronics failure	Replace main electronics	F	Alarm
271	Main electronics failure	1. Restart device 2. Change main electronic module	F	Alarm
272	Main electronics failure	Restart device	F	Alarm
272	Main electronics failure	1. Restart device 2. Contact service	F	Alarm
273	Main electronics failure	1. Emergency operation via display 2. Change main electronics	F	Alarm
275	I/O module failure	1. Restart device 2. Change I/O module	F	Alarm
276	I/O module faulty	1. Restart device 2. Change I/O module	F	Alarm
282	Data storage	1. Restart device 2. Contact service	F	Alarm
283	Memory content	1. Transfer data or reset device 2. Contact service	F	Alarm
284	Detector SW update in progress	Firmware update active, please wait!	F	Alarm
311	Electronics failure	Maintenance required! 1. Do not perform reset 2. Contact service	M	Warning
333	System recovery required	HW change detected System configuration recovery required Go to menu on device and perform recovery	F	Alarm

Diagnostic number	Short text	Remedy instructions	Status signal [from the factory]	Diagnostic behavior [from the factory]
334	System recovery failure	HW changed, system recovery failure. Return to factory	F	Alarm
381	Displacer distance invalid	1. Calibrate sensor 2. Restart device 3. Replace sensor electronics	F	Alarm
382	Sensor communication	1. Check connection of sensor electronics 2. Restart device 3. Replace sensor electronics	F	Alarm
<b>Diagnostic of configuration</b>				
400	AIO simulation output	Deactivate simulation AIO output	C	Warning
401	DIO simulation output	Deactivate simulation DIO output	C	Warning
403	Calibration AIO	1. Restart device 2. Change I/O module	F	Alarm
404	Calibration AIP	1. Restart device 2. Change I/O module	F	Alarm
405	COMM timeout DIO 1 to 8	1. Check wiring 2. Change I/O module	F	Alarm
406	IOM offline	1. Check wiring 2. Change I/O module	F	Alarm
407	COMM timeout AIO 1 to 2	1. Check wiring 2. Change I/O module	F	Alarm
408	Invalid range AIO 1 to 2	1. Check device configuration. 2. Check wiring.	C	Warning
409	RTD temp out of range 1 to 2	1. Check electronic modules 2. Change I/O or main electronic module	C	Warning
410	Data transfer	1. Retry data transfer 2. Check connection	F	Alarm
411	Hart device 1 to 15 has malfunction	1. Check HART device 2. Change HART device	F	Alarm <sup>1)</sup>
412	Processing download	Download active, please wait	C	Warning
413	NMT 1 to 15: element is open or short	1. Check NMT wiring connection 2. Replace NMT	C	Warning
415	Hart device 1 to 15 offline	1. Check HART device 2. Change HART device	C	Warning
416	Warning occurred for HART device 1 to 15	Check connected HART device	M	Warning
434	Real time clock defective	Replace main electronics	C	Warning
436	Date/time incorrect	Check date and time settings.	M	Warning
437	Configuration incompatible	1. Restart device 2. Contact service	F	Alarm
438	Dataset	1. Check dataset file 2. Check device configuration 3. Up- and download new configuration	M	Warning
441	AIO 1 to 2 current output alarm	1. Check process 2. Check current output settings	F	Alarm

Diagnostic number	Short text	Remedy instructions	Status signal [from the factory]	Diagnostic behavior [from the factory]
442	AIO 1 to 2 current output warning	1. Check process 2. Check current output settings	C	Warning
443	AIO 1 to 2 Input not HART compatible	Change PV source or AIO input source.	C	Warning
484	Failure mode simulation	Deactivate simulation	C	Alarm
495	Diagnostic event simulation	Deactivate simulation	C	Warning
500	AIO C1-3 source no longer valid	Change input source	C	Warning
501	Level source no longer valid	Change input source	C	Warning
502	GP1 source no longer valid	Change input source	C	Warning
503	GP2 source no longer valid	Change input source	C	Warning
504	GP3 source no longer valid	Change input source	C	Warning
505	GP4 source no longer valid	Change input source	C	Warning
506	Water level source no longer valid	Change input source	C	Warning
507	Liquid temp source no longer valid	Change input source	C	Warning
508	Vapor temperatur source no longer valid	Change input source	C	Warning
509	Air temperature source no longer valid	Change input source	C	Warning
510	P1 source no longer valid	Change input source	C	Warning
511	P2 source no longer valid	Change input source	C	Warning
512	P3 source no longer valid	Change input source	C	Warning
513	Upper density source no longer valid	Change input source	C	Warning
514	Middle density source no longer valid	Change input source	C	Warning
515	Lower density source no longer valid	Change input source	C	Warning
516	Gauge command source no longer valid	Change input source	C	Warning
517	Gauge status source no longer valid	Change input source	C	Warning
518	Average density source no longer valid	Change input source	C	Warning
519	Upper interface source no longer valid	Change input source	C	Warning
520	Lower interface source no longer valid	Change input source	C	Warning
521	Bottom level source no longer valid	Change input source	C	Warning
522	Displacer position source not valid	Change input source	C	Warning
523	Distance source no longer valid	Change input source	C	Warning
524	Balance flag source no longer valid	Change input source	C	Warning

Diagnostic number	Short text	Remedy instructions	Status signal [from the factory]	Diagnostic behavior [from the factory]
525	One time cmd source no longer valid	Change input source	C	Warning
526	Alarm 1 to 4 source no longer valid	Change input source	C	Warning
527	AIO B1-3 source no longer valid	Change input source	C	Warning
528	CTSh	1. Check device configuration. 2. Check wiring.	C	Warning
529	HTG	1. Check device configuration. 2. Check wiring.	C	Warning
530	HTMS	1. Check device configuration. 2. Check wiring.	C	Warning
531	HyTD correction value	1. Check device configuration. 2. Check wiring.	C	Warning
532	HART output: PV source not valid	Change input source	C	Warning
533	HART output: SV source not valid	Change input source	C	Warning
534	HART output: QV source not valid	Change input source	C	Warning
535	HART output: TV source not valid	Change input source	C	Warning
536	Display: source no longer valid	Change input source	C	Warning
537	Trend: source no longer valid	Change input source	C	Warning
538	HART output: PV mA source not valid	Change input source	C	Warning
539	Modbus 1-4 SP source invalid	Set valid SP input selector	C	Warning
540	V1 1-4 SP source invalid	Set valid SP input selector	C	Warning
541	Modbus 1-4 alarm source invalid	Set valid alarm input selector	C	Warning
542	V1 1-4 alarm source invalid	Set valid alarm input selector	C	Warning
543	Modbus 1-4 analog source invalid	Set valid analog input selector	C	Warning
544	V1 1-4 analog source invalid	Set valid analog input selector	C	Warning
545	Modbus 1-4 user value source invalid	Set valid user value input selector	C	Warning
546	Modbus 1-4 discrete value source invalid	Set valid user discrete input selector	C	Warning
547	V1 1-4 user value source invalid	Set valid user value input selector	C	Warning
548	V1 1-4 discrete value source invalid	Set valid user discrete input selector	C	Warning
549	Modbus 1-4 percent source invalid	Set valid percentage input selector	C	Warning
550	V1 1-4 percent source invalid	Set valid percentage input selector	C	Warning

Diagnostic number	Short text	Remedy instructions	Status signal [from the factory]	Diagnostic behavior [from the factory]
560	Calibration mandatory	1. Carry out weight calibration 2. Carry out reference calibration 3. Carry out drum calibration	C	Alarm
564	DIO B1-2 source no longer valid	Change input source	C	Warning
565	DIO B3-4 source not valid	Change input source	C	Warning
566	DIO C1-2 source no longer valid	Change input source	C	Warning
567	DIO C3-4 source no longer valid	Change input source	C	Warning
568	DIO D1-2 source no longer valid	Change input source	C	Warning
569	DIO D3-4 source no longer valid	Change input source	C	Warning
572	LRC 1 to 2 not possible	1. Check device configuration. 2. Check wiring.	C	Warning
585	Simulation distance	Deactivate simulation	C	Warning
586	Record map	Recording of mapping please wait	C	Warning
598	DIO A1-2 source no longer valid	Change input source	C	Warning
599	DIO A3-4 source no longer valid	Change input source	C	Warning
<b>Diagnostic of process</b>				
801	Energy too low	Increase supply voltage	S	Warning
803	Current loop	1. Check device configuration. 2. Check wiring.	F	Alarm
803	Current loop 1 to 2		M	Warning
803	Current loop		C	Warning
825	System temperature	1. Check ambient temperature 2. Check process temperature	S	Warning
825	System temperature		F	Alarm
826	Sensor temperature	1. Check ambient temperature 2. Check process temperature	S	Warning
826	Sensor temperature		F	Alarm
844	Process value out of specification	1. Check process value 2. Check application 3. Check sensor	S	Warning <sup>1)</sup>
844	Process value out of specification		S	Warning
901	Level held	Normal state while Dip Freeze is turned on, otherwise check configuration	S	Warning
903	Current loop 1 to 2	1. Check device configuration. 2. Check wiring.	F	Alarm
904	Digital output 1 to 8	1. Check device configuration. 2. Check wiring.	F	Alarm
941	Echo lost	1. Check process value 2. Check application 3. Check sensor	S	Warning

Diagnostic number	Short text	Remedy instructions	Status signal [from the factory]	Diagnostic behavior [from the factory]
942	In safety distance	1. Check level 2. Check safety distance 3. Reset self holding	S	Warning
943	In blocking distance	Reduced accuracy Check level	S	Warning
950	Advanced diagnostics	Maintain your diagnostic event	M	Warning
961	Alarm 1 to 4 HighHigh	1. Check alarm source 2. Check configuration settings	C	Warning
962	Alarm 1 to 4 High	1. Check alarm source 2. Check configuration settings	C	Warning
963	Alarm 1 to 4 Low	1. Check alarm source 2. Check configuration settings	C	Warning
964	Alarm 1 to 4 LowLow	1. Check alarm source 2. Check configuration settings	C	Warning
965	Alarm 1 to 4 HighHigh	1. Check alarm source 2. Check configuration settings	F	Alarm
966	Alarm 1 to 4 High	1. Check alarm source 2. Check configuration settings	F	Alarm
967	Alarm 1 to 4 Low	1. Check alarm source 2. Check configuration settings	F	Alarm
968	Alarm 1 to 4 LowLow	1. Check alarm source 2. Check configuration settings	F	Alarm
970	Overtension	1. Check displacer and process conditions 2. Release overtension	C	Alarm
971	Undertension	Check displacer and process.	C	Alarm
974	LRC 1 to 2 failed	1. Check process value 2. Check application 3. Check sensor	C	Warning

1) Diagnostic behavior can be changed.



The parameters No.941, 942, and 943 are only used for NMR8x and NRF81.




## 11.5 Diagnostic list

In the Diagnostic list submenu, up to 5 currently pending diagnostic messages can be displayed. If more than 5 messages are pending, the messages with the highest priority are shown on the display.

### Navigation path

Diagnostics → Diagnostic list


### Calling up and closing the remedial measures

1. Press .
  - ↳ The message for the remedial measures for the selected diagnostic event opens.
2. Press  +  simultaneously.
  - ↳ The message about the remedial measures closes.

## 11.6 Reset measuring device

To reset the device to a defined state use the Device reset (→  333).

## 11.7 Device information

Information on the device (order code, hardware and software version of the individual modules etc.) can be found in the Device information (→  339).

## 11.8 Firmware history

Date	Software version	Modifications	Documentation (NMS81)		
			Operating Instructions	Description of Parameters	Technical Information
04.2016	01.00.zz	Original software	BA01459G/00/EN/01.16	GP01077G/00/EN/01.16	TI01249G/00/EN/01.16
12.2016	01.02.zz	Bugfixes and improvements	BA01459G/00/EN/02.17	GP01077G/00/EN/01.17	TI01249G/00/EN/02.17
07.2018	01.03.zz	Software update	BA01459G/00/EN/04.18	GP01077G/00/EN/02.18	TI01249G/00/EN/04.18
10.2020	01.04.zz	Software update	BA01459G/00/EN/05.20	GP01077G/00/EN/03.18	TI01249G/00/EN/05.20
09.2022	01.06.zz	Software update	BA01459G/00/EN/06.22	GP01077G/00/EN/04.22	TI01249G/00/EN/06.22
10.2023	01.07.zz	Software update	BA01459G/00/EN/ 07.23-00		TI01249G/00/EN/07.23-00



## 12 Maintenance

### 12.1 Maintenance tasks

No special maintenance work is required.

#### 12.1.1 Exterior cleaning

When cleaning the exterior of measuring devices, always use cleaning agents that do not attack the surface of the housing or the seals.

### 12.2 Endress+Hauser services

Endress+Hauser offers a wide variety of services for maintenance such as recalibration, maintenance service or device tests.



Your Endress+Hauser Sales Center can provide detailed information on the services.

## 13 Repair

### 13.1 General information on repairs

#### 13.1.1 Repair concept

The Endress+Hauser repair concept assumes that the devices have a modular design and that repairs can be done by the Endress+Hauser service or specially trained customers.

Spare parts are contained in suitable kits. They contain the related replacement instructions.

For more information on service and spare parts, contact the Service Department at Endress+Hauser.

#### 13.1.2 Repairs to Ex-approved devices

##### **WARNING**

##### **Incorrect repair can compromise electrical safety!**



Explosion hazard!

- ▶ Only specialist personnel or the manufacturer's service team may carry out repairs on Ex-certified devices in accordance with national regulations.
- ▶ Relevant standards and national regulations on hazardous areas, safety instructions and certificates must be observed.
- ▶ Only use original spare parts from the manufacturer.
- ▶ Please note the device designation on the nameplate. Only identical parts may be used as replacements.
- ▶ Carry out repairs according to the instructions.
- ▶ Only the manufacturer's service team is permitted to modify a certified device and convert it to another certified version.

#### 13.1.3 Replacement of a device or electronic module

After a complete device or the electronic mainboard has been replaced, the parameters can be downloaded into the instrument again via FieldCare.

Condition: The configuration of the old device has been saved to the computer via FieldCare.

 If an electronic module of the sensor or other parts of the sensor have been replaced, the servo calibration must be repeated. Refer to →  88.

##### **The "Save/Restore" function**

After a device configuration has been saved to a computer and restored to the device using the **Save/Restore** function of FieldCare, the device must be restarted by the following setting:

**Setup** → **Advanced setup** → **Administration** → **Device reset** = **Restart device**.

This ensures correct operation of the device after the restore.

## 13.2 Spare parts


Some interchangeable measuring device components are listed on an overview sign in the connection compartment cover.

The spare part overview sign contains the following information:

- A list of the most important spare parts for the measuring device, including their ordering information.
- The URL for the *W@M Device Viewer* ([www.endress.com/deviceviewer](http://www.endress.com/deviceviewer)):  
All the spare parts for the measuring device, along with the order code, are listed here and can be ordered. If available, users can also download the associated Installation Instructions.

## 13.3 Endress+Hauser services

Endress+Hauser offers a wide range of services.

-  Your Endress+Hauser Sales Center can provide detailed information on the services.

## 13.4 Return

The requirements for safe device return can vary depending on the device type and national legislation.

1. Refer to the web page for information:  
<http://www.endress.com/support/return-material>  
↳ Select the region.
2. Return the device if repairs or a factory calibration are required, or if the wrong device was ordered or delivered.

## 13.5 Disposal

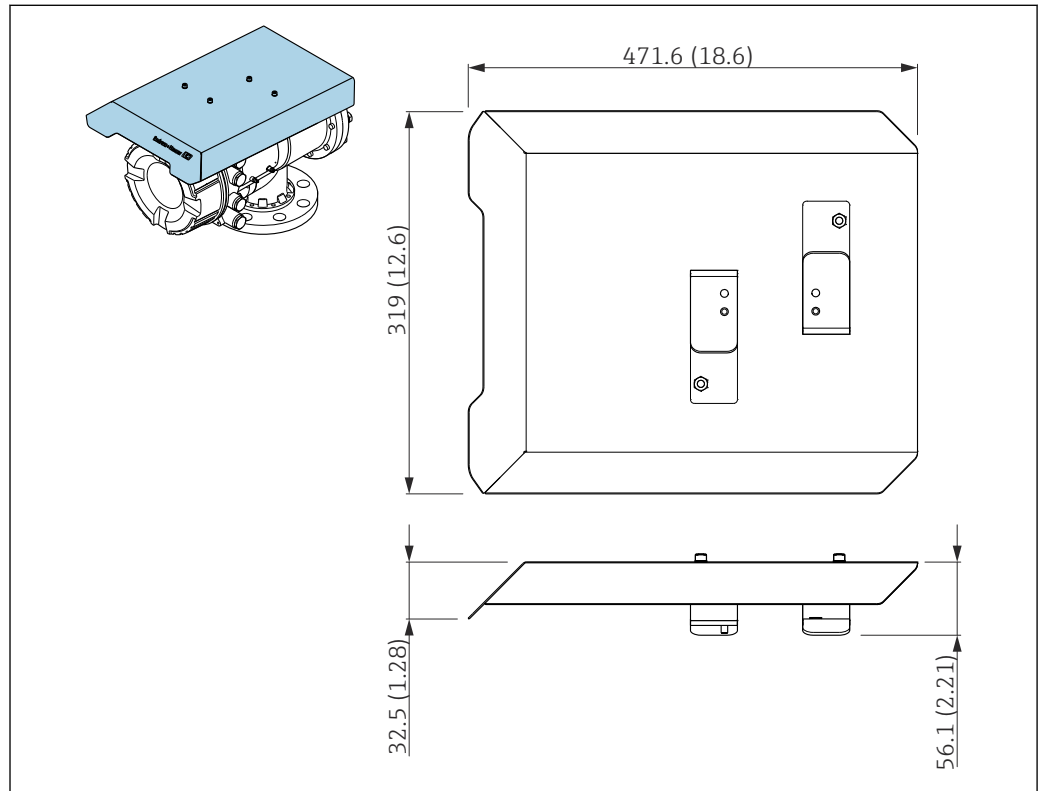


If required by the Directive 2012/19/EU on waste electrical and electronic equipment (WEEE), the product is marked with the depicted symbol in order to minimize the disposal of WEEE as unsorted municipal waste. Do not dispose of products bearing this marking as unsorted municipal waste. Instead, return them to the manufacturer for disposal under the applicable conditions.

## 14 Accessories

### 14.1 Device-specific accessories

#### 14.1.1 Weather protection cover



A0033572

82 Weather protection cover; dimensions: mm (in)

#### Materials

- Protection cover and mounting brackets

Material

316L (1.4404)

- Screws and washers

Material

A4



- The weather protection cover can be ordered together with the device:  
Ordering feature 620 "Accessory Enclosed", option PA "Weather Protection Cover")
- It can also be ordered as an accessory:  
Order code: 71305035 (for NMS8x)

### 14.1.2 Maintenance chamber

A maintenance chamber is recommended for use with tank level gauges in order to allow maintenance (removing the 70 mm (2.76 in) displacer or larger), while the tank is in service. Contact your Endress+Hauser Sales Center if necessary.

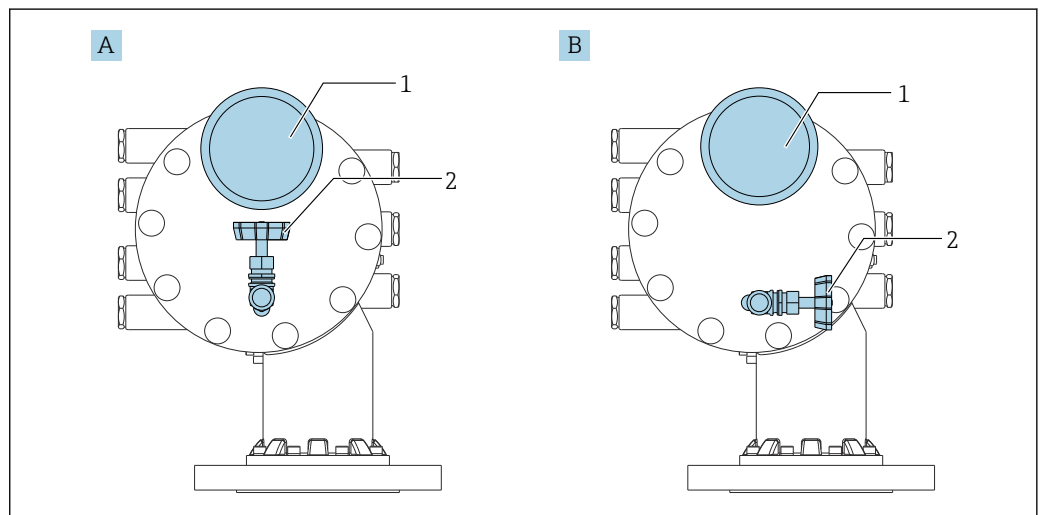
### 14.1.3 Ball valve

Ball valves are recommended for use with tank level gauges in order to allow maintenance such as removing displacers while tank is in service. Contact your Endress+Hauser Sales Center if necessary.

### 14.1.4 Control switch

A control switch is used for field mounted tank gauges. This provides additional gauge operation contact switching in order to control the gauge's operation, such as hoisting up the displacer. Contact your Endress+Hauser Sales Center if necessary.

### 14.1.5 Relief valve and pressure gauge



83 Mounting position of relief valve and pressure gauge

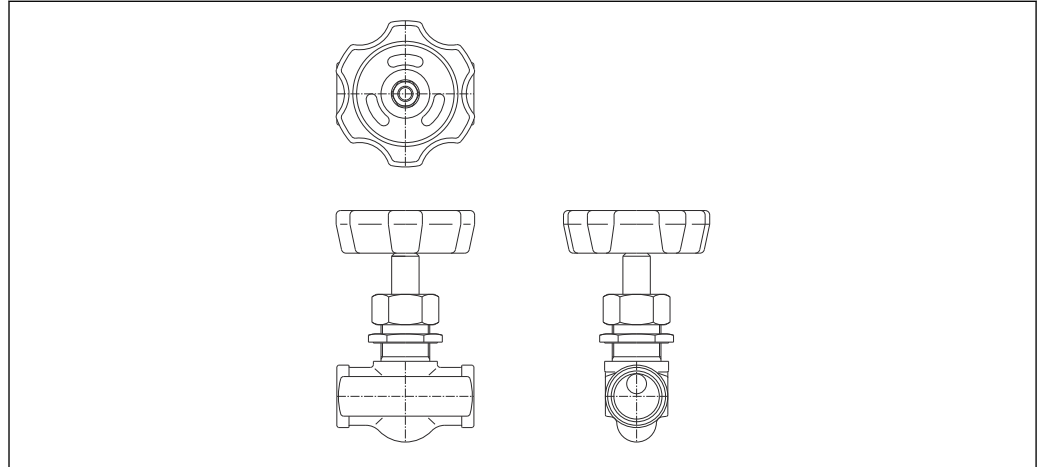
- A Standard version
- B 90 °-degree rotation (optional)
- 1 Pressure gauge
- 2 Relief valve

### Relief valve

A relief valve is used to release pressure inside the housing of NMS8x before maintenance.

Process temperature:  $-20$  to  $150$  °C ( $-4$  to  $302$  °F)

**i** Contact your Endress+Hauser Sales Center when applying pressure in an ammonia atmosphere.



A0028881

**84** Relief valve

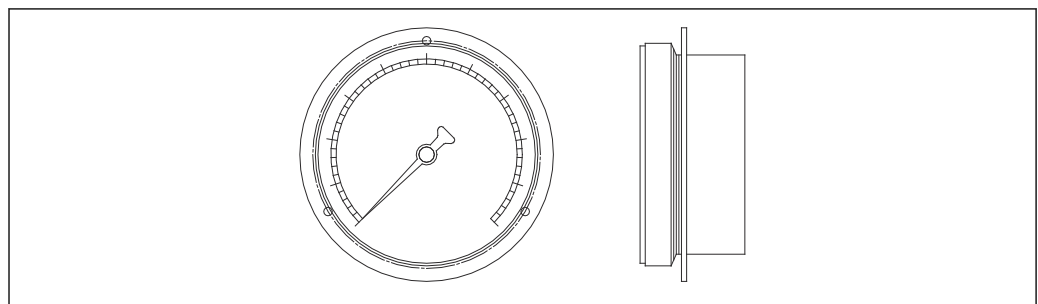
### Pressure gauge

A pressure gauge is used to check process pressure inside the housing. The range of the scale for the pressure gauge varies depending on the pressure.

- Low pressure: 0 to 1 MPa
- High pressure: 0 to 4 MPa

Process temperature:  $-5$  to  $45$  °C ( $23$  to  $113$  °F)

**i** Contact your Endress+Hauser Sales Center when applying pressure in an ammonia atmosphere.



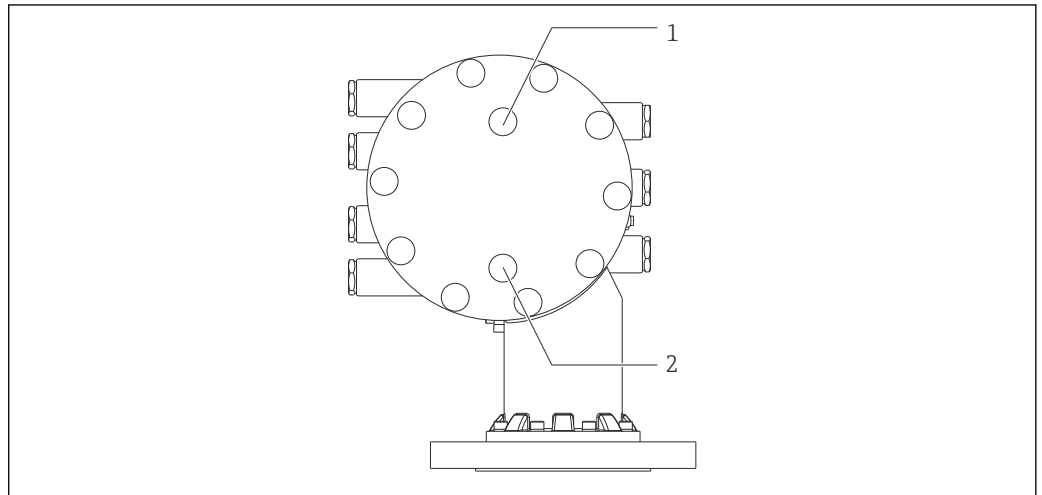
A0028882

**85** Pressure gauge

### 14.1.6 Cleaning nozzle and gas purging nozzle

A cleaning nozzle used for washing inside housing is especially recommended for F&B or alcohol applications.

A gas purging nozzle used for purging gas inside the housing is especially recommended for a nitrogen blanket for petrochemical or chemical applications.



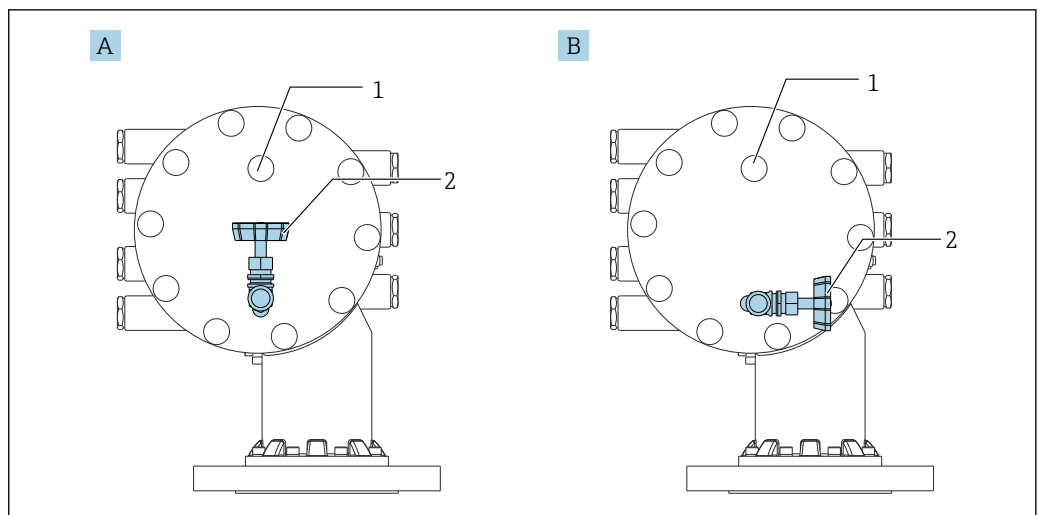
A0028883

86 Holes for cleaning nozzle and gas purging nozzle

- 1 Cleaning nozzle
- 2 Gas purging nozzle

### 14.1.7 Other combinations for relief valve, pressure gauge, cleaning nozzle, and gas purging nozzle

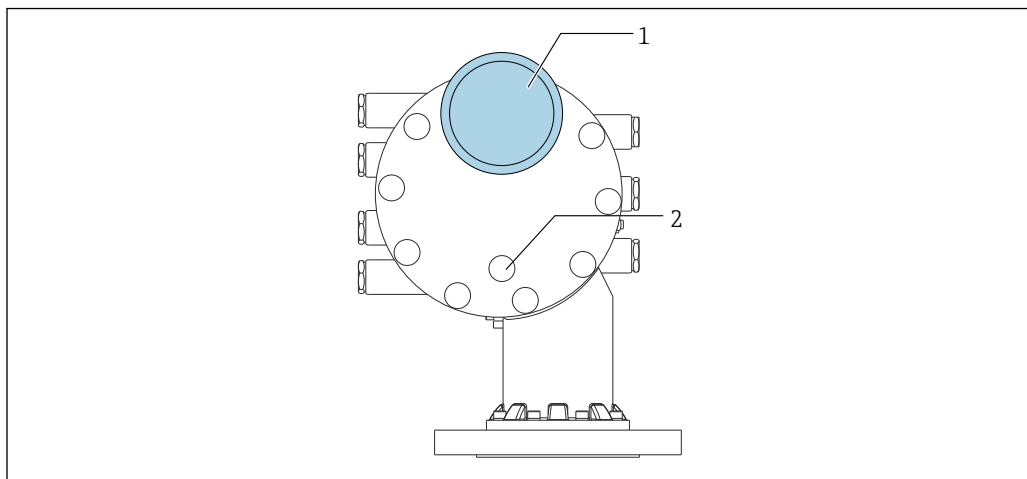
#### Cleaning nozzle and relief valve



A0051204

87 Cleaning nozzle and relief valve

- A Standard version
- B 90 °-degree rotation (optional)
- 1 Cleaning nozzle
- 2 Relief valve

**Pressure gauge and gas purging nozzle**

A0051271

88 Pressure gauge and gas purging nozzle

1 Pressure gauge

2 Gas purging nozzle



## 14.2 Communication-specific accessories

### WirelessHART adapter SWA70

- Is used for the wireless connection of field devices
- The WirelessHART adapter can be easily integrated into field devices and existing infrastructures, offers data protection and transmission safety and can be operated in parallel with other wireless networks

 For details, see Operating Instructions BA00061S

### Gauge Emulator, Modbus to BPM

- Using the protocol converter, it is possible to integrate a field device into a host system even if the field device does not know the communication protocol of the host system. Eliminates vendor lock-in for field devices.
- Field communication protocol (field device): Modbus RS485
- Host communication protocol (host system): Enraf BPM
- 1 measuring device per Gauge Emulator
- Separate power supply: 100 to 240 V<sub>AC</sub>, 50 to 60 Hz, 0.375 A, 15 W
- Several approvals for the hazardous area

### Gauge Emulator, Modbus to TRL/2

- Using the protocol converter, it is possible to integrate a field device into a host system even if the field device does not know the communication protocol of the host system. Eliminates vendor lock-in for field devices.
- Field communication protocol (field device): Modbus RS485
- Host communication protocol (host system): Saab TRL/2
- 1 measuring device per Gauge Emulator
- Separate power supply: 100 to 240 V<sub>AC</sub>, 50 to 60 Hz, 0.375 A, 15 W
- Several approvals for the hazardous area

## 14.3 Service-specific accessories


### Commubox FXA195 HART

For intrinsically safe HART communication with FieldCare via the USB interface

 For details, see "Technical Information" TI00404F

### Commubox FXA291

Connects Endress+Hauser field devices with a CDI interface (= Endress+Hauser Common Data Interface) and the USB port of a computer or laptop  
Order number: 51516983

 For details, see "Technical Information" TI00405C


### DeviceCare SFE100

Configuration tool for HART, PROFIBUS and FOUNDATION Fieldbus field devices  
DeviceCare is available for download at [www.software-products.endress.com](http://www.software-products.endress.com). You need to register in the Endress+Hauser software portal to download the application.

 Technical Information TI01134S

### FieldCare SFE500

FDT-based plant asset management tool  
It can configure all smart field units in your system and helps you manage them. By using the status information, it is also a simple but effective way of checking their status and condition.

 Technical Information TI00028S

## 14.4 System components

### RIA15

Compact process display unit with very low voltage drop for universal use to display 4 to 20 mA/HART signals



Technical Information TI01043K

### **Tankvision Tank Scanner NXA820 / Tankvision Data Concentrator NXA821 / Tankvision Host Link NXA822**

Inventory Management System with completely integrated software for operation via standard web browser



Technical Information TI00419G

## 15 Operating menu

- i
📄 : Navigation path for operating module at the device
- 📄 : Navigation path for operating tool (e.g. FieldCare)
- 🔒 : Parameter can be locked via software locking


























### 15.1 Overview of the operating menu



























- i
📄 This section lists the parameters of the following menus:
  - ➔ 📄 180) Operation
  - ➔ 📄 197) Setup
  - ➔ 📄 335) Diagnostics
- For the **Expert** menu refer to the "Description of Device Parameters" (GP) of the respective device.
- Depending on the device version and parametrization some parameters will not be available in a given situation. For details refer to the "Prerequisite" category in the description of the respective parameter.
- The representation essentially corresponds to the menu in an operating tool (e.g. FieldCare). On the local display there may be minor differences in the menu structure. Details are mentioned in the description of the respective submenu.


























Navigation

📄 📄 Operating tool

<b>Operation</b>	➔ <span style="font-size: 0.8em;">📄</span> 180
Gauge command	➔ <span style="font-size: 0.8em;">📄</span> 180
Distance	➔ <span style="font-size: 0.8em;">📄</span> 180
Net weight	➔ <span style="font-size: 0.8em;">📄</span> 181
Gauge status	➔ <span style="font-size: 0.8em;">📄</span> 181
Balance flag	➔ <span style="font-size: 0.8em;">📄</span> 181
Standby level	➔ <span style="font-size: 0.8em;">📄</span> 181
Offset standby distance	➔ <span style="font-size: 0.8em;">📄</span> 182
One-time command status	➔ <span style="font-size: 0.8em;">📄</span> 183
▶ <b>Level</b>	➔ <span style="font-size: 0.8em;">📄</span> 183
Dip Freeze	➔ <span style="font-size: 0.8em;">📄</span> 183
Tank level	➔ <span style="font-size: 0.8em;">📄</span> 184
Tank Level %	➔ <span style="font-size: 0.8em;">📄</span> 184
Tank ullage	➔ <span style="font-size: 0.8em;">📄</span> 184
Tank ullage %	➔ <span style="font-size: 0.8em;">📄</span> 185

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



















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Reference switch level	→  350
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Check status	→  351
Check timestamp	→  351

## 15.2 "Operation" menu

The **Operation** menu (→  180) shows the most important measured values and allows to issue a gauge command.


Navigation   Operation

---

### Gauge command

---

**Navigation**

 Operation → Gauge command

**Description**

Gauge operation command to choose the measurement mode of the device.

**Selection**

- Stop \*
- Level
- Up \*
- Bottom level \*
- Upper I/F level \*
- Lower I/F level \*
- Upper density \*
- Middle density \*
- Lower density \*
- Repeatability \*
- Water dip \*
- Release overtension \*
- Tank profile \*
- Interface profile \*
- Manual profile \*
- Level standby \*
- Offset standby \*

**Factory setting**

Stop

**Additional information**

Read access	Operator
Write access	Maintenance

---

### Distance

---

**Navigation**

 Operation → Distance

**Description**

Shows measured distance from reference position.

**Additional information**

Read access	Operator
Write access	-

---

\* Visibility depends on order options or device settings



---

**Net weight**


---

**Navigation**  Operation → Net weight

**Description** Shows the corrected weight data from the detector, as compensated by the drum table, This weight is used for measurement.

**Additional information**

Read access	Operator
Write access	-

---

**Gauge status**


---

**Navigation**  Operation → Gauge status

**Description** Indicates the current status of the device gauge command.

**Additional information**

Read access	Operator
Write access	-

---

**Balance flag**


---

**Navigation**  Operation → Balance flag

**Description** Indicates the validity of the Measurement. If balanced, corresponding Value (Liquid Level, Upper Interface, Lower Interface, Tank Bottom ) is updated.


**Additional information**

Read access	Operator
Write access	-

---

**Standby level**


---



**Navigation**  Operation → Standby level

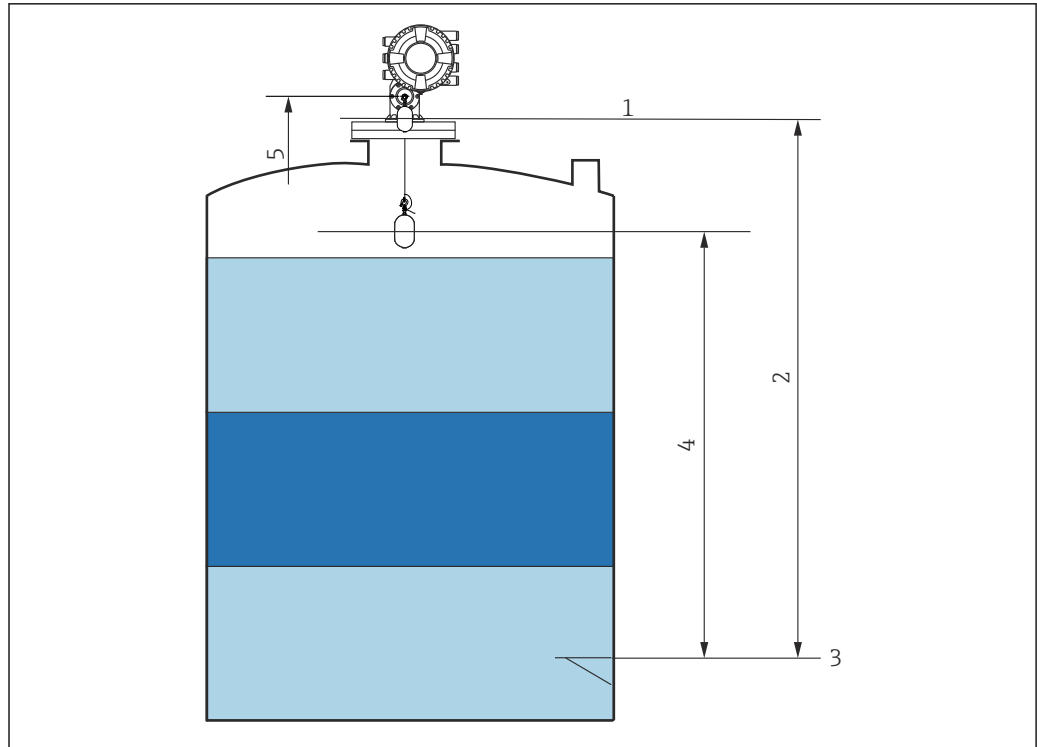
**Description** Defines the position in the tank where the displacer waits for the liquid level to rise during standby level gauge command.

**User entry** -999 999.9 to 999 999.9 mm

**Factory setting** 0 mm

**Additional information**

Read access	Operator
Write access	Maintenance



A0055643

89 Displacer waiting for the liquid level to rise during standby level gauge command

- 1 Gauge reference height
- 2 Empty
- 3 Datum plate
- 4 Standby level (→ 181)
- 5 Reference position

---

**Offset standby distance**

---

**Navigation**

☰☰ Operation → Offset distance

**Description**

Defines the distance from the current position where the displacer waits for the liquid level to rise during offset standby gauge command.

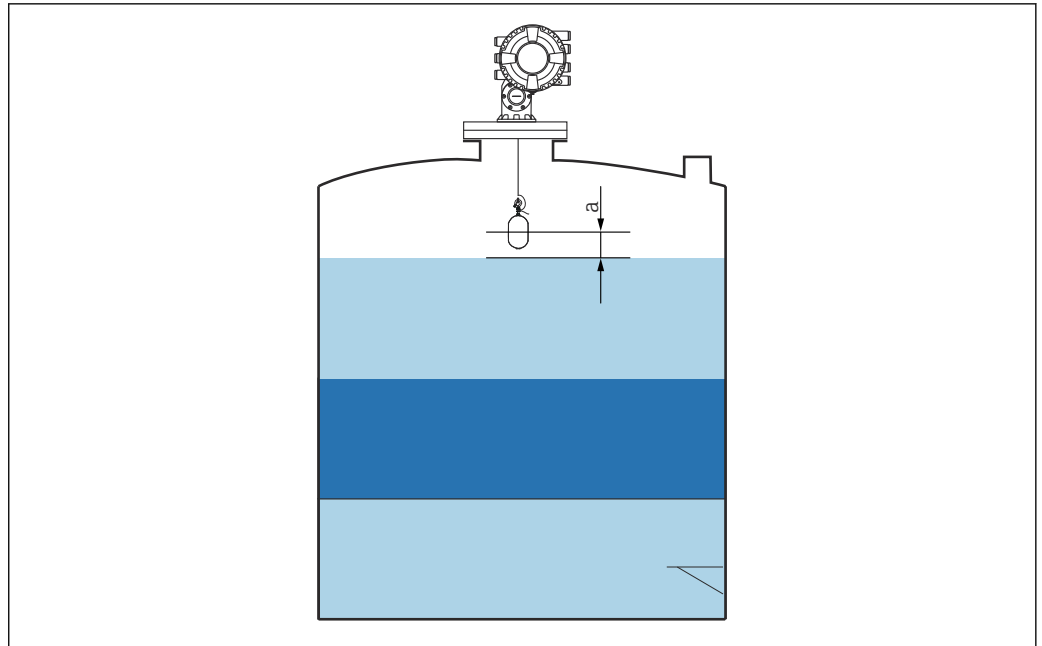
**User entry**

0 to 999 999.9 mm

**Factory setting**

500 mm

**Additional information**



A0051202

90 a: Offset standby distance

**One-time command status**

**Navigation**

☰☰ Operation → One-time Cmd

**Description**

Indicates the status of the last executed one-time gauge command.

**Additional information**

Read access	Operator
Write access	-

**Additional information**

📘 One-time command is available for all gauge commands, excepting Level, Stop, Up, and Interface.

**15.2.1 "Level" submenu**

Navigation ☰☰ Operation → Level

**Dip Freeze**



**Navigation**


☰☰ Operation → Level → Dip Freeze

**Description**

If activated the level values are frozen and a warning is shown.

**Selection**                    ■ Off  
                                      ■ On

**Factory setting**            Off

**Additional information**     This function can be used when performing a manual dipping in the same stilling well or nozzle where the radar device is mounted.

## Tank level

**Navigation**                 Operation → Level → Tank level

**Description**                Shows the distance from the zero position (tank bottom or datum plate) to the product surface.

**Additional information**

Read access	Operator
Write access	-

## Tank Level %

**Navigation**                 Operation → Level → Tank Level %

**Description**                Shows the level as a percentage of the full measuring range.

**Additional information**

Read access	Operator
Write access	-

## Tank ullage

**Navigation**                 Operation → Level → Tank ullage

**Description**                Shows the remaining empty space in the tank.

**Additional information**

Read access	Operator
Write access	-

**Tank ullage %**

**Navigation**

 Operation → Level → Tank ullage %

**Description**

Shows the remaining empty space in percentage related to parameter tank reference height.

**Additional information**

Read access	Operator
Write access	-

**Upper interface level**

**Navigation**

 Operation → Level → Upper I/F level

**Description**

Shows measured interface level from zero position (tank bottom or datum plate). Value is updated when device generates a valid Interface measurement.

**Additional information**

Read access	Maintenance
Write access	-

**Upper interface level timestamp**

**Navigation**

 Operation → Level → Up I/F timestamp

**Description**

Shows timestamp for the last measured upper interface level.

**Additional information**

Read access	Operator
Write access	-

**Lower interface level**

**Navigation**

 Operation → Level → Lower I/F level

**Description**

Shows measured interface level from zero position (tank bottom or datum plate). Value is updated when device generates a valid interface measurement.


**Additional information**

Read access	Maintenance
Write access	-

---

**Lower interface level timestamp**


---

**Navigation**  Operation → Level → LowI/F timestamp

**Description** Shows timestamp of the last measured lower interface level.

**Additional information**

Read access	Operator
Write access	-

---

**Bottom level**


---

**Navigation**  Operation → Level → Bottom level

**Description** Shows the bottom level.

**Additional information**

Read access	Operator
Write access	-

---

**Bottom level timestamp**


---

**Navigation**  Operation → Level → BotLev timestamp

**Description** Shows the timestamp for measured bottom level.

**Additional information**

Read access	Operator
Write access	-

---

**Water level**


---

**Navigation**  Operation → Level → Water level

**Description** Shows the bottom water level.


**Additional information**

Read access	Operator
Write access	-

---

**Measured level**


---

**Navigation**  Operation → Level → Measured level

**Description** Shows the measured level without any correction from the tank calculations.

**Additional information**

Read access	Operator
Write access	-

---

**Distance**


---

**Navigation**  Operation → Level → Distance

**Description** Shows measured distance from reference position.

**Additional information**

Read access	Operator
Write access	-

---

**Displacer position**


---

**Navigation**  Operation → Level → Displacer pos

**Description** Shows the displacer position.

**Additional information**

Read access	Operator
Write access	-


## 15.2.2 "Temperature" submenu

*Navigation*  Operation → Temperature

---

**Air temperature**


---

**Navigation**  Operation → Temperature → Air temp.


**Description** Shows the air temperature.

**Additional information**

Read access	Operator
Write access	-

### Liquid temperature

**Navigation**

 Operation → Temperature → Liquid temp.

**Description**


Shows the average or spot temperature of the measured liquid.

**Additional information**

Read access	Operator
Write access	-

### Vapor temperature

**Navigation**

 Operation → Temperature → Vapor temp.


**Description**


Shows the measured vapor temperature.

**Additional information**

Read access	Operator
Write access	-

**"NMT element values" submenu**

 This submenu is only visible if a Prothermo NMT is connected.

*Navigation*  Operation → Temperature → NMT elem. values

*"Element temperature" submenu*

*Navigation*  Operation → Temperature → NMT elem. values → Element temp.

### Element temperature 1 to 24

**Navigation**

 Operation → Temperature → NMT elem. values → Element temp. → Element temp 1 to 24

**Description**


Shows the temperature of an element in the NMT.

**Additional information**

Read access	Operator
Write access	-



*"Element position" submenu*

*Navigation*            Operation → Temperature → NMT elem. values → Element position

**Element position 1 to 24**

**Navigation**            Operation → Temperature → NMT elem. values → Element position → Element pos. 1 to 24

**Description**      Shows the position of the selected element in the NMT.

**Additional information**

Read access	Operator
Write access	-

**15.2.3 "Density" submenu**

*Navigation*             Operation → Density


**Observed density**

**Navigation**             Operation → Density → Observed density



**Description**      Calculated density of the product.

**Additional information**

Read access	Operator
Write access	-

 This value is calculated from different measured variables depending on the selected calculation method.

**Observed density temperature**

**Navigation**             Operation → Density → Obs. dens. temp.

**Description**      Corresponding temperature of measured density. Can be used for reference density calculation.

**User interface**      Signed floating-point number

**Factory setting**      0 °C

**Vapor density****Navigation** Operation → Density → Vapor density**Description** Defines the density of the gas phase in the tank.**User entry** 0.0 to 500.0 kg/m<sup>3</sup>**Factory setting** 1.2 kg/m<sup>3</sup>**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

**Air density****Navigation** Operation → Density → Air density**Description** Defines the density of the air surrounding the tank.**User entry** 0.0 to 500.0 kg/m<sup>3</sup>**Factory setting** 1.2 kg/m<sup>3</sup>**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

**Measured upper density****Navigation** Operation → Density → Meas upper dens.**Description** Shows the density of the upper phase.**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	-



**Upper density timestamp****Navigation** Operation → Density → UpDens timestamp**Description** Shows timestamp of the last measured upper density.

**Additional information**

Read access	Operator
Write access	-

**Measured middle density**

**Navigation**

  Operation → Density → Meas middle dens

**Description**


Density of the middle phase.

**Additional information**

Read access	Operator
Write access	-

**Middle Density Timestamp**

**Navigation**

  Operation → Density → MidDensTimestamp

**Description**

Shows the timestamp of the last measured middle density.

**Additional information**

Read access	Operator
Write access	-

**Measured lower density**

**Navigation**

  Operation → Density → Meas lower dens.

**Description**

Density of the lower phase.

**Additional information**

Read access	Maintenance
Write access	-

**Lower density timestamp**

**Navigation**

  Operation → Density → LowerDensTimestp

**Description**

Shows timestamp of last measured lower density.

**Additional information**

Read access	Operator
Write access	-

---

**Profile point**


---

**Navigation**  Operation → Density → Profile point

**Description** Shows actual number of Density Points measured so far in current operation, and the total Number of Points after Density Profile Operation is complete.

**Additional information**

Read access	Operator
Write access	-

---

**Profile average density**


---

**Navigation**  Operation → Density → Profile avg dens

**Description** Shows the average density calculated after a profile density measurement is complete.


**Additional information**

Read access	Operator
Write access	-

---

**Profile density timestamp**


---


**Navigation**  Operation → Density → Profil dens time

**Description** Shows the timestamp when the last average density profile was finished.


**Additional information**

Read access	Operator
Write access	-

**"Profile density" submenu**

*Navigation*            Operation → Density → Profile density

**Profile density 0 to 49**


**Navigation**            Operation → Density → Profile density → Profile dens 0 to 49

**Description**      Shows the density measurement at the corresponding profile density position.

**Additional information**

Read access	Operator
Write access	-

**Profile density position 0 to 49**

**Navigation**            Operation → Density → Profile density → Profile pos 0 to 49

**Description**      Shows the position where the corresponding density was measured.



**Additional information**

Read access	Operator
Write access	-

**15.2.4 "Pressure" submenu**

*Navigation*             Operation → Pressure

**P1 (bottom)**

**Navigation**             Operation → Pressure → P1 (bottom)

**Description**      Shows the pressure at the tank bottom.


**Additional information**

Read access	Operator
Write access	-

---

**P3 (top)**

---

**Navigation** Operation → Pressure → P3 (top)**Description**

Shows the pressure (P3) at the top transmitter.

**Additional information**

Read access	Operator
Write access	-

### 15.2.5 "GP values" submenu

Navigation  Operation → GP values

---

#### GP 1 to 4 name

---

**Navigation**  Operation → GP values → GP 1 name

**Description** Defines the label associated with the respective GP value.

**User entry** Character string comprising numbers, letters and special characters (15)

**Factory setting** GP Value 1

**Additional information**

Read access	Operator
Write access	Maintenance

---

#### GP Value 1

---

**Navigation**  Operation → GP values → GP Value 1

**Description** Displays the value that will be used as general purpose value.


**Additional information**

Read access	Operator
Write access	-

---

#### GP Value 2

---

**Navigation**  Operation → GP values → GP Value 2

**Description** Displays the value that will be used as general purpose value.


**Additional information**

Read access	Operator
Write access	-

---

#### GP Value 3

---

**Navigation**  Operation → GP values → GP Value 3

**Description** Displays the value that will be used as general purpose value.

**Additional information**

Read access	Operator
Write access	-

---

**GP Value 4**

---

**Navigation** Operation → GP values → GP Value 4**Description**


Displays the value that will be used as general purpose value.

**Additional information**

Read access	Operator
Write access	-





## 15.3 "Setup" menu

Navigation   Setup

---

### Device tag



---

<b>Navigation</b>	  Setup → Device tag				
<b>Description</b>	Enter a unique name for the measuring point to identify the device quickly within the plant.				
<b>User entry</b>	Character string comprising numbers, letters and special characters (32)				
<b>Factory setting</b>	NMS8x				
<b>Additional information</b>	<table border="1"> <tr> <td>Read access</td> <td>Operator</td> </tr> <tr> <td>Write access</td> <td>Maintenance</td> </tr> </table>	Read access	Operator	Write access	Maintenance
Read access	Operator				
Write access	Maintenance				




---

### Units preset


---

<b>Navigation</b>	  Setup → Units preset				
<b>Description</b>	Defines a set of units for length, pressure and temperature.				
<b>Selection</b>	<ul style="list-style-type: none"> <li>■ mm, bar, °C</li> <li>■ m, bar, °C</li> <li>■ mm, PSI, °C</li> <li>■ ft, PSI, °F</li> <li>■ ft-in-16, PSI, °F</li> <li>■ ft-in-8, PSI, °F</li> <li>■ Customer value</li> </ul>				
<b>Factory setting</b>	mm, bar, °C				
<b>Additional information</b>	<table border="1"> <tr> <td>Read access</td> <td>Operator</td> </tr> <tr> <td>Write access</td> <td>Maintenance</td> </tr> </table>	Read access	Operator	Write access	Maintenance
Read access	Operator				
Write access	Maintenance				

If the **Customer value** option is selected, the units are defined in the following parameters. In any other case these are read-only parameters used to indicate the respective unit:

- Distance unit (→  326)
- Pressure unit (→  327)
- Temperature unit (→  327)

---

**Upper density**



---

**Navigation**   Setup → Upper density

**Description** Sets the density of the upper phase of the liquid.


**User entry** 50 to 2 000 kg/m<sup>3</sup>

**Factory setting** 800 kg/m<sup>3</sup>

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Middle density**



---

**Navigation**   Setup → Middle density

**Description** Sets Density of Middle Phase in the Tank if three Phases are available. Otherwise used for the Lower Phase in the Tank if two Phases are available.


**User entry** 50 to 2 000 kg/m<sup>3</sup>

**Factory setting** 1 000 kg/m<sup>3</sup>

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Lower density**



---

**Navigation**   Setup → Lower density

**Description** Sets the density of the lower Phase in the tank if three phases are available.

**User entry** 50 to 2 000 kg/m<sup>3</sup>

**Factory setting** 1 200 kg/m<sup>3</sup>

**Additional information**

Read access	Operator
Write access	Maintenance

**Gauge command**



**Navigation** Setup → Gauge command

**Description** Gauge operation command to choose the measurement mode of the device.

- Selection**
- Stop \*
  - Level
  - Up \*
  - Bottom level \*
  - Upper I/F level \*
  - Lower I/F level \*
  - Upper density \*
  - Middle density \*
  - Lower density \*
  - Repeatability \*
  - Water dip \*
  - Release overtension \*
  - Tank profile \*
  - Interface profile \*
  - Manual profile \*
  - Level standby \*
  - Offset standby \*

**Factory setting** Stop

**Additional information**

Read access	Operator
Write access	Maintenance

**Process condition**



**Navigation** Setup → Process cond.

**Description** Select the liquid condition of the tank.


- Selection**
- Universal
  - Calm surface
  - Turbulent surface

**Factory setting** Universal

**Additional information** For W&M, setting to option **Calm surface** is recommended.

Read access	Operator
Write access	Maintenance

\* Visibility depends on order options or device settings

**Empty** 

**Navigation**   Setup → Empty

**Description** Distance from reference point to zero position (tank bottom or datum plate).

**User entry** 0 to 10 000 000 mm

**Factory setting** Dependent on the device version

**Additional information**

Read access	Operator
Write access	Maintenance

 The reference point is the reference line of the calibration window.

**Tank reference height** 

**Navigation**   Setup → Tank ref height

**Description** Defines the distance from the dipping reference point to the zero position (tank bottom or datum plate).

**User entry** 0 to 10 000 000 mm

**Factory setting** Dependent on the device version

**Additional information**

Read access	Operator
Write access	Maintenance

**Tank level**

**Navigation**   Setup → Tank level

**Description** Shows the distance from the zero position (tank bottom or datum plate) to the product surface.

**Additional information**

Read access	Operator
Write access	-

**Set level**



**Navigation**

Setup → Set level

**Description**

If the level measured by the device does not match the actual level obtained by a manual dip, enter the correct level into this parameter.

**User entry**

0 to 10 000 000 mm

**Factory setting**

0 mm

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

The device adjusts the **Empty** parameter (→ 200) according to the entered value, such that the measured level will match the actual level.

**Level source**



**Navigation**

Setup → Level source

**Description**

Defines the source of the level value.

**Selection**

- No input value
- HART device 1 ... 15 level
- Level SR\*
- Level\*
- Displacer position\*
- AIO B1-3 value\*
- AIO C1-3 value\*
- AIP B4-8 value\*
- AIP C4-8 value\*

**Factory setting**

Dependent on the device version

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

**High stop level**



**Navigation**

Setup → High stop level

**Description**

Position of the displacer high stop as measured from defined zero position (tank bottom or datum plate).

\* Visibility depends on order options or device settings

**User entry** -999 999.9 to 999 999.9 mm

**Factory setting** 20 000 mm

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

---

**Low stop level** 

**Navigation**   Setup → Low stop level

**Description** Position of the displacer low stop as measured from defined zero position (tank bottom or datum plate).

**User entry** -999 999.9 to 999 999.9 mm

**Factory setting** 0 mm

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

---

**Distance**


**Navigation**   Setup → Distance

**Description** Shows measured distance from reference position.

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	-

---

**Liquid temp source** 

**Navigation**   Setup → Liq temp source

**Description** Defines source from which the liquid temperature is obtained.

**Selection**

- Manual value
- HART device 1 ... 15 temperature
- AIO B1-3 value
- AIO C1-3 value
- AIP B4-8 value
- AIP C4-8 value

**Factory setting** Manual value

**Additional information**


Read access	Operator
Write access	Maintenance

### 15.3.1 "Calibration" submenu

Read access	Maintenance
-------------	-------------

Navigation  Setup → Calibration


#### "Move displacer" wizard

Navigation  Setup → Calibration → Move displacer

---

#### Move distance

---

Navigation  Setup → Calibration → Move displacer → Move distance

Description Up or down movement of displacer in mm.

User entry 0 to 999 999.9 mm

Factory setting 0 mm


Additional information

Read access	Operator
Write access	Maintenance

---

#### Distance

---

Navigation  Setup → Calibration → Move displacer → Distance

Description Shows measured distance from reference position.


Additional information

Read access	Operator
Write access	-

---

#### Move displacer

---

Navigation  Setup → Calibration → Move displacer → Move displacer

Selection

- Stop
- Move down
- Move up

Factory setting Stop





**Additional information**

Read access	Operator
Write access	Maintenance

**Motor status**

**Navigation**

  Setup → Calibration → Move displacer → Motor status

**Description**

Shows the current moving Direction of the Motor.

**Additional information**

Read access	Operator
Write access	-

**Move displacer**



**Navigation**

  Setup → Calibration → Move displacer → Move displacer

**Selection**

- No
- Yes

**Factory setting**


No


**Additional information**

Read access	Operator
Write access	Maintenance

**"Sensor calibration" wizard**

*Navigation*  Setup → Calibration → Sensor cal.


**Sensor calibration** 


**Navigation**  Setup → Calibration → Sensor cal. → Sensor cal.

**Description** This sequence calibrates the sensor of the servo.

**Additional information**

Read access	Operator
Write access	Maintenance

**Offset weight** 

**Navigation**  Setup → Calibration → Sensor cal. → Offset wgt.

**Description** Sets the weight that is used for the lower point sensor calibration. Changing the value will delete the calibration data.


**User entry** 0 to 150 g

**Factory setting** Dependent on the device version

**Additional information**

Read access	Operator
Write access	Maintenance

 For density measurement application, it is recommended to apply 50 g.

**Span weight** 

**Navigation**  Setup → Calibration → Sensor cal. → Span wgt.

**Description** Sets the weight that is used for the middle point sensor calibration. Changing the value will delete the calibration data.

**User entry** 10 to 999.9 g

**Factory setting** Dependent on the device version

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Zero calibration**

---

**Navigation**

Setup → Calibration → Sensor cal. → Zero calibration

**Description**

In this step the sensor calibration zero weight will be done.

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Calibration status**

---

**Navigation**

Setup → Calibration → Sensor cal. → Status

**Description**

Gives feedback on the latest status of the calibration process.

**Additional information**

Read access	Operator
Write access	-

---

**Offset calibration**

---

**Navigation**

Setup → Calibration → Sensor cal. → Offset cal.

**Description**

In this step the sensor calibration with offset weight will be done.

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Span calibration**

---

**Navigation**

Setup → Calibration → Sensor cal. → Span calibration


**Description**


In this step the sensor calibration with span weight will be done.


**Additional information**

Read access	Operator
Write access	Maintenance

**"Reference calibration" wizard**

*Navigation*  Setup → Calibration → Reference cal.


**Reference calibration** 


**Navigation**  Setup → Calibration → Reference cal. → Reference cal.

**Description** This sequence will move the displacer to the mechanical stop and set the reference position.

**Additional information**

Read access	Operator
Write access	Maintenance

**Reference position** 

**Navigation**  Setup → Calibration → Reference cal. → Ref. position


**Description** Defines in mm, during reference calibration, the distance between mechanical stop inside the drum housing and the middle of the wire ring.


**User entry** 0 to 9 999.9 mm

**Factory setting** Dependent on the device version

**Additional information**

Read access	Operator
Write access	Maintenance

**Progress** 

**Navigation**  Setup → Calibration → Reference cal. → Progress

**Description** Gives feedback on the latest status of the reference calibration process.


**Additional information**

Read access	Operator
Write access	Maintenance

---

**Calibration status**

---

**Navigation** Setup → Calibration → Reference cal. → Status**Description**

Gives feedback on the latest status of the calibration process.


**Additional information**

Read access	Operator
Write access	-

**"Drum calibration" wizard**

*Navigation*  Setup → Calibration → Drum cal.

---

**Drum calibration** 


**Navigation**  Setup → Calibration → Drum cal. → Drum cal.


**Description** This sequence will perform a drum calibration.

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

---

**Set high weight** 

**Navigation**  Setup → Calibration → Drum cal. → Set high weight

**Description** High weight that is used for a drum calibration (normally it is the displacer weight).


**User entry** 10 to 999.9 g


**Factory setting** Dependent on the device version

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

---

**Make drum table** 

**Navigation**  Setup → Calibration → Drum cal. → Make drum table


**Description** This will perform a drum calibration.

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

---

**Drum table point**

**Navigation**  Setup → Calibration → Drum cal. → Drum table point



**Description** Shows the currently measured point of the drum calibration. Maximum number of measured points is 50.

**Additional information**

Read access	Operator
Write access	-

**Calibration status**

**Navigation**

  Setup → Calibration → Drum cal. → Status

**Description**

Gives feedback on the latest status of the calibration process.



**Additional information**

Read access	Operator
Write access	-

**Make low table**



**Navigation**

  Setup → Calibration → Drum cal. → Make low table

**Description**

For additional accuracy it is possible to perform a second drum calibration with low weight. Choose "Yes" or "No" to start/stop calibration.

**Selection**

- No
- Yes

**Factory setting**

No



**Additional information**

Read access	Operator
Write access	Maintenance

**Set low weight**



**Navigation**

  Setup → Calibration → Drum cal. → Set low weight

**Description**

Set weight for additional drum calibration sequence.

**User entry**

10 to 999.9 g

**Factory setting**

Dependent on the device version

**Additional information**


Read access	Operator
Write access	Maintenance

### 15.3.2 "Advanced setup" submenu

Navigation  Setup → Advanced setup

#### Locking status

**Navigation**

 Setup → Advanced setup → Locking status

**Description**

Indicates the type of locking.

"Hardware locked" (HW)

The device is locked by the "WP" switch on the main electronics module. To unlock, set the switch into the OFF position.

"WHG locked" (SW)

Unlock the device by entering the appropriate access code in "Enter access code".

"SIL locked" (SW)

Unlock the device by entering the appropriate access code in "Enter access code".

"Temporarily locked" (SW)

The device is temporarily locked by processes in the device (e.g. data upload/download, reset). The device will automatically be unlocked after completion of these processes.

**Additional information**

Read access	Operator
Write access	-

#### User role

**Navigation**

 Setup → Advanced setup → User role

**Description**


Shows the access authorization to the parameters via the operating tool

**Additional information**

Read access	Operator
Write access	-

#### Enter access code

**Navigation**

 Setup → Advanced setup → Ent. access code

**Description**


Enter access code to disable write protection of parameters.

**Additional information**


Read access	Operator
Write access	Operator




**"Input/output" submenu**

*Navigation*       Setup → Advanced setup → Input/output

*"HART devices" submenu*

*Navigation*       Setup → Advanced setup → Input/output → HART devices

**Number of devices**


**Navigation**       Setup → Advanced setup → Input/output → HART devices → Number devices


**Description**      Shows the number of devices on the HART bus.

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	-


*"HART Device(s)" submenu*

 There is a **HART Device(s)** submenu for each HART slave device found on the HART loop.

*Navigation*  Setup → Advanced setup → Input/output → HART devices → HART Device(s)

**Device name**

**Navigation**

 Setup → Advanced setup → Input/output → HART devices → HART Device(s) → Device name

**Description**


Shows the name of the transmitter.

**Additional information**

Read access	Operator
Write access	-

**Polling address**

**Navigation**

 Setup → Advanced setup → Input/output → HART devices → HART Device(s) → Polling address

**Description**


Shows the polling address of the transmitter.

**Additional information**

Read access	Operator
Write access	-

**Device tag**

**Navigation**

 Setup → Advanced setup → Input/output → HART devices → HART Device(s) → Device tag

**Description**

Shows the device tag of the transmitter.

**Additional information**

Read access	Operator
Write access	-

**Operating mode**



<b>Navigation</b>	Setup → Advanced setup → Input/output → HART devices → HART Device(s) → Operating mode				
<b>Prerequisite</b>	Not available if the HART device is a Prothermo NMT.				
<b>Description</b>	Selection of the operation mode PV only or PV,SV,TV,QV. Devines which values are polled from the connected HART Device.				
<b>Selection</b>	<ul style="list-style-type: none"> <li>■ PV only</li> <li>■ PV,SV,TV &amp; QV</li> <li>■ Level <sup>5)</sup></li> <li>■ Measured level <sup>5)</sup></li> </ul>				
<b>Factory setting</b>	PV,SV,TV & QV				
<b>Additional information</b>	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="width: 50%; padding: 2px;">Read access</td> <td style="padding: 2px;">Operator</td> </tr> <tr> <td style="padding: 2px;">Write access</td> <td style="padding: 2px;">Maintenance</td> </tr> </table>	Read access	Operator	Write access	Maintenance
Read access	Operator				
Write access	Maintenance				

**Communication status**

<b>Navigation</b>	Setup → Advanced setup → Input/output → HART devices → HART Device(s) → Comm. status				
<b>Description</b>	Shows the operating status of the transmitter.				
<b>User interface</b>	<ul style="list-style-type: none"> <li>■ Operating normally</li> <li>■ Device offline</li> </ul>				
<b>Additional information</b>	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="width: 50%; padding: 2px;">Read access</td> <td style="padding: 2px;">Operator</td> </tr> <tr> <td style="padding: 2px;">Write access</td> <td style="padding: 2px;">-</td> </tr> </table>	Read access	Operator	Write access	-
Read access	Operator				
Write access	-				

**Status signal**


<b>Navigation</b>	Setup → Advanced setup → Input/output → HART devices → HART Device(s) → Status signal
<b>Description</b>	Indicates the current device status in accordance with VDI/VDE 2650 and NAMUR Recommendation NE 107.
<b>User interface</b>	<ul style="list-style-type: none"> <li>■ OK</li> <li>■ Failure (F)</li> <li>■ Function check (C)</li> <li>■ Out of specification (S)</li> </ul>

5) only visible if the connected device is a Micropilot

- Maintenance required (M)
- ---
- No effect (N)
- ---

Factory setting ---

**#blank# ( HART PV - designation dependent on device)**


**Navigation**  Setup → Advanced setup → Input/output → HART devices → HART Device(s) → #blank#


**Description** Shows the first HART variable (PV).

**Additional information**

Read access	Operator
Write access	-

**#blank# (HART SV - designation dependent on device)**

**Navigation**  Setup → Advanced setup → Input/output → HART devices → HART Device(s) → #blank#


**Prerequisite** For HART devices other than NMT: **Operating mode** (→  215) = PV,SV,TV & QV

**Description** Shows the second HART variable (SV).

**Additional information**

Read access	Operator
Write access	-

**#blank# (HART TV - designation dependent on device)**

**Navigation**  Setup → Advanced setup → Input/output → HART devices → HART Device(s) → #blank#


**Prerequisite** For HART devices other than NMT: **Operating mode** (→  215) = PV,SV,TV & QV

**Description** Shows the third HART variable (TV).

**Additional information**

Read access	Operator
Write access	-

**#blank# (HART QV - designation dependent on device)**

**Navigation**  Setup → Advanced setup → Input/output → HART devices → HART Device(s) → #blank#

**Prerequisite** For HART devices other than NMT: **Operating mode** (→  215) = PV,SV,TV & QV


**Description** Shows the fourth HART variable (QV).

**Additional information**

Read access	Operator
Write access	-

**Output pressure**



**Navigation**  Setup → Advanced setup → Input/output → HART devices → HART Device(s) → Output pressure

**Prerequisite** Not available for Micropilot S FMR5xx, Prothermo NMT53x and Prothermo NMT8x. In these cases the measured variables are allocated automatically.

**Description** Defines which HART variable is the pressure.

- Selection**
- No value
  - Primary variable (PV)
  - Secondary variable (SV)
  - Tertiary variable (TV)
  - Quaternary variable (QV)


**Factory setting** No value

**Additional information**

Read access	Operator
Write access	Maintenance

**Output density**



**Navigation**  Setup → Advanced setup → Input/output → HART devices → HART Device(s) → Output density

**Prerequisite** Not available for Micropilot S FMR5xx, Prothermo NMT53x and Prothermo NMT8x. In these cases the measured variables are allocated automatically.

**Description** Defines which HART variable is the density.

- Selection**
- No value
  - Primary variable (PV)
  - Secondary variable (SV)
  - Tertiary variable (TV)
  - Quaternary variable (QV)

**Factory setting** No value

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Output temperature**



**Navigation**

Setup → Advanced setup → Input/output → HART devices → HART Device(s) → Output temp.

**Prerequisite**

Not available for Micropilot S FMR5xx, Prothermo NMT53x and Prothermo NMT8x. In these cases the measured variables are allocated automatically.

**Description**

Defines which HART variable is the temperature.

**Selection**

- No value
- Primary variable (PV)
- Secondary variable (SV)
- Tertiary variable (TV)
- Quaternary variable (QV)

**Factory setting**

No value

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Output vapor temperature**



**Navigation**

Setup → Advanced setup → Input/output → HART devices → HART Device(s) → Output vapor tmp

**Prerequisite**

Not available for Micropilot S FMR5xx, Prothermo NMT53x and Prothermo NMT8x. In these cases the measured variables are allocated automatically.

**Description**

Defines which HART variable is the vapor temperature.

**Selection**

- No value
- Primary variable (PV)
- Secondary variable (SV)
- Tertiary variable (TV)
- Quaternary variable (QV)

**Factory setting**

No value

**Additional information**

Read access	Operator
Write access	Maintenance

**Output level**



**Navigation**

Setup → Advanced setup → Input/output → HART devices → HART Device(s) → Output level

**Prerequisite**

Not available for Micropilot S FMR5xx, Prothermo NMT53x and Prothermo NMT8x. In these cases the measured variables are allocated automatically.

**Description**

Defines which HART variable is the level.

**Selection**

- No value
- Primary variable (PV)
- Secondary variable (SV)
- Tertiary variable (TV)
- Quaternary variable (QV)

**Factory setting**



No value


**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

"Forget device" wizard

Read access	Maintenance
-------------	-------------


 This submenu is only visible if **Number of devices** (→  213) ≥ 1.

*Navigation*  Setup → Advanced setup → Input/output → HART devices → Forget device

---

**Forget device**



**Navigation**  Setup → Advanced setup → Input/output → HART devices → Forget device → Forget device

**Description** With this function an offline device can be deleted from the device list.

- Selection**
- HART Device 1 \*
  - HART Device 2 \*
  - HART Device 3 \*
  - HART Device 4 \*
  - HART Device 5 \*
  - HART Device 6 \*
  - HART Device 7 \*
  - HART Device 8 \*
  - HART Device 9 \*
  - HART Device 10 \*
  - HART Device 11 \*
  - HART Device 12 \*
  - HART Device 13 \*
  - HART Device 14 \*
  - HART Device 15 \*
  - None

**Factory setting** None

**Additional information**

Read access	Operator
Write access	Maintenance

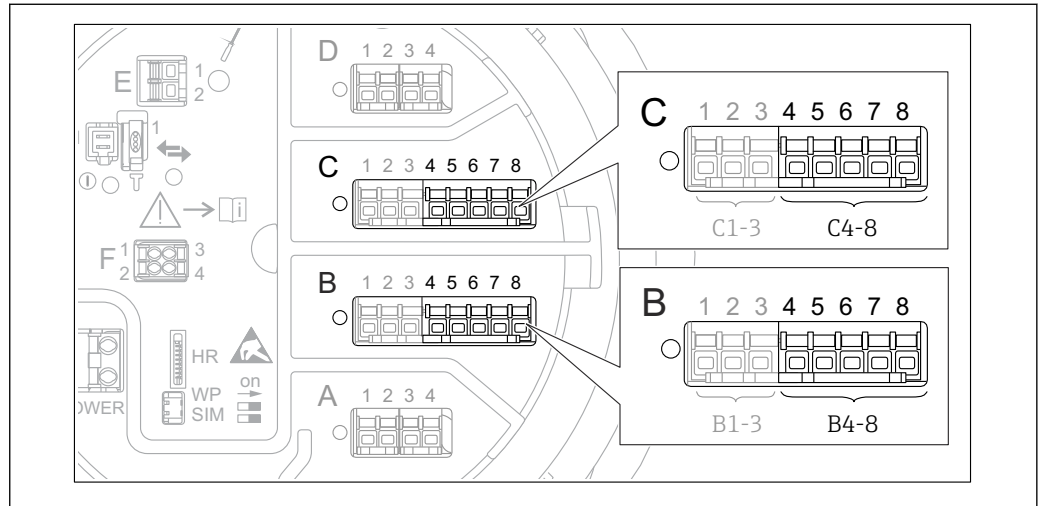
---

\* Visibility depends on order options or device settings



"Analog IP" submenu

**i** There is a **Analog IP** submenu for each Analog I/O module of the device. This submenu refers to terminals 4 to 8 of this module (the analog input). They are primarily used to connect an RTD. For terminals 1 to 3 (analog input or output) refer to → 227.



91 Terminals for the "Analog IP" submenu ("B4-8" or "C4-8", respectively)

Navigation Setup → Advanced setup → Input/output → Analog IP

Operating mode

Navigation Setup → Advanced setup → Input/output → Analog IP → Operating mode

Description Defines the operating mode of the analog input.

- Selection
- Disabled
  - RTD temperature input
  - Gauge power supply

Factory setting Disabled

Additional information

Read access	Operator
Write access	Maintenance

RTD type

Navigation Setup → Advanced setup → Input/output → Analog IP → RTD type

Prerequisite **Operating mode** (→ 221) = **RTD temperature input**

Description Defines the type of the connected RTD.

- Selection**
- Cu50 (w=1.428, GOST)
  - Cu53 (w=1.426, GOST)
  - Cu90; 0°C (w=1.4274, GOST)
  - Cu100; 25°C (w=1.4274, GOST)
  - Cu100; 0°C(w=1.4274, GOST)
  - Pt46 (w=1.391, GOST)
  - Pt50 (w=1.391, GOST)
  - Pt100(385) (a=0.00385, IEC751)
  - Pt100(389) (a=0.00389, Canadian)
  - Pt100(391) (a=0.003916, JIS1604)
  - Pt100 (w=1.391, GOST)
  - Pt500(385) (a=0.00385, IEC751)
  - Pt1000(385) (a=0.00385, IEC751)
  - Ni100(617) (a=0.00617, DIN43760)
  - Ni120(672) (a=0.00672, DIN43760)
  - Ni1000(617) (a=0.00617, DIN43760)

**Factory setting** Pt100(385) (a=0.00385, IEC751)

**Additional information**

Read access	Operator
Write access	Maintenance

**Thermocouple type**



**Navigation** Setup → Advanced setup → Input/output → Analog IP → Thermocouple typ

**Description** Defines the type of the connected thermocouple.

- Selection**
- N type
  - B type
  - C type
  - D type
  - J type
  - K type
  - L type
  - L GOST type
  - R type
  - S type
  - T type
  - U type

**Factory setting** N type

**RTD connection type**



**Navigation** Setup → Advanced setup → Input/output → Analog IP → RTD connect type

**Prerequisite** **Operating mode (→ 221) = RTD temperature input**

**Description** Defines the connection type of the RTD.

**Selection**

- 4 wire RTD connection
- 2 wire RTD connection
- 3 wire RTD connection

**Factory setting** 4 wire RTD connection

**Additional information**

Read access	Operator
Write access	Maintenance

**Process value**

**Navigation**  Setup → Advanced setup → Input/output → Analog IP → Process value

**Prerequisite** **Operating mode (→  221) ≠ Disabled**


**Description** Shows the measured value received via the analog input.


**Additional information**

Read access	Operator
Write access	-

**Process variable**



**Navigation**  Setup → Advanced setup → Input/output → Analog IP → Process variable

**Prerequisite** **Operating mode (→  221) ≠ RTD temperature input**

**Description** Determines type of measured value.

**Selection**

- Level linearized
- Temperature
- Pressure
- Density

**Factory setting** Level linearized

**Additional information**

Read access	Operator
Write access	Maintenance

**0 % value**



**Navigation**  Setup → Advanced setup → Input/output → Analog IP → 0 % value

**Prerequisite** **Operating mode (→  221) = 4..20mA input**

**Description** Defines the value represented by a current of 4mA.


**User entry** Signed floating-point number

**Factory setting** 0 mm

**Additional information**

Read access	Operator
Write access	Maintenance

---

**100 % value** 

**Navigation**   Setup → Advanced setup → Input/output → Analog IP → 100 % value

**Prerequisite** **Operating mode (→  221) = 4..20mA input**

**Description** Defines the value represented by a current of 20mA.

**User entry** Signed floating-point number



**Factory setting** 0 mm

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Input value**

**Navigation**   Setup → Advanced setup → Input/output → Analog IP → Input value


**Prerequisite** **Operating mode (→  221) ≠ Disabled**



**Description** Shows the value received via the analog input.


**Additional information**

Read access	Operator
Write access	-

---

**Minimum probe temperature** 

**Navigation**   Setup → Advanced setup → Input/output → Analog IP → Min. probe temp

**Prerequisite** **Operating mode (→  221) = RTD temperature input**

**Description** Minimum approved temperature of the connected probe.  
If the temperature falls below this value, the W&M status will be "invalid".

**User entry** -213 to 927 °C

**Factory setting** -100 °C

**Additional information**

Read access	Operator
Write access	Maintenance

**Maximum probe temperature**



**Navigation**

Setup → Advanced setup → Input/output → Analog IP → Max. probe temp

**Prerequisite**

**Operating mode** (→ 221) = **RTD temperature input**

**Description**

Maximum approved temperature of the connected probe. If the temperature rises above this value, the W&M status will be "invalid".

**User entry** -213 to 927 °C

**Factory setting** 250 °C

**Additional information**

Read access	Operator
Write access	Maintenance

**Probe position**



**Navigation**

Setup → Advanced setup → Input/output → Analog IP → Probe position

**Prerequisite**

**Operating mode** (→ 221) = **RTD temperature input**

**Description**

Position of the temperature probe, measured from zero position (tank bottom or datum plate). This parameter, in conjunction with the measured level, determines whether the temperature probe is still covered by the product. If this is no longer the case, the status of the temperature value will be "invalid".

**User entry** -5 000 to 30 000 mm

**Factory setting** 5 000 mm

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Damping factor**


**Navigation** Setup → Advanced setup → Input/output → Analog IP → Damping factor

**Prerequisite** **Operating mode (→ 221) ≠ Disabled**

**Description** Defines the damping constant (in seconds).

**User entry** 0 to 999.9 s

**Factory setting** 0 s

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Gauge current**

**Navigation** Setup → Advanced setup → Input/output → Analog IP → Gauge current

**Prerequisite** **Operating mode (→ 221) = Gauge power supply**

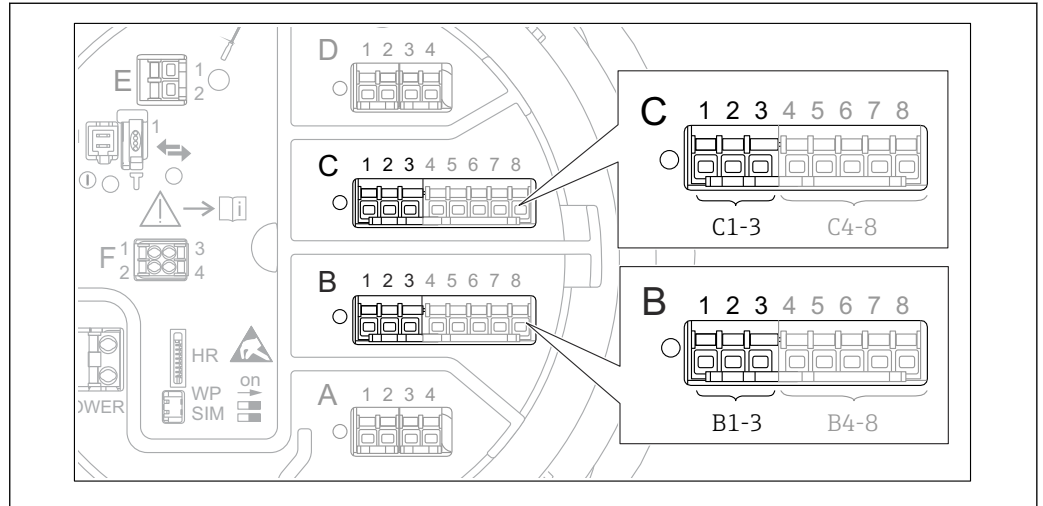
**Description** Shows the current on the power supply line for the connected device.

**Additional information**

Read access	Operator
Write access	-

"Analog I/O" submenu

**i** There is a **Analog I/O** submenu for each Analog I/O module of the device. This submenu refers to terminals 1 to 3 of this module (an analog input or output). For terminals 4 to 8 (always an analog input) refer to → 221.



92 Terminals for the "Analog I/O" submenu ("B1-3" or "C1-3", respectively)

Navigation Setup → Advanced setup → Input/output → Analog I/O

Operating mode

**Navigation** Setup → Advanced setup → Input/output → Analog I/O → Operating mode

**Description** Defines the operating mode of the analog I/O module.

- Selection**
- Disabled
  - 4..20mA input
  - HART master+4..20mA input
  - HART master
  - 4..20mA output
  - HART slave +4..20mA output


**Factory setting** Disabled

**Additional information**

Read access	Operator
Write access	Maintenance


Meaning of the options


Operating mode (→ 227)	Direction of signal	Type of signal
Disabled	-	-
4..20mA input	Input from 1 external device	Analog (4...20mA)
HART master+4..20mA input	Input from 1 external device	<ul style="list-style-type: none"> <li>■ Analog (4...20mA)</li> <li>■ HART</li> </ul>
HART master	Input from up to 6 external devices	HART

Operating mode (→  227)	Direction of signal	Type of signal
4...20mA output	Output to higher-level unit	Analog (4...20mA)
HART slave +4...20mA output	Output to higher-level unit	<ul style="list-style-type: none"> <li>■ Analog (4...20mA)</li> <li>■ HART</li> </ul>

Depending on the terminals used, the Analog I/O module is used in the passive or active mode.

Mode	Terminals of the I/O module		
	1	2	3
Passive (power supply from external source)	-	+	not used
Active (power supplied by the device itself)	not used	-	+

-  In the active mode the following conditions must be met:
- Maximum current consumption of the connected HART devices: 24 mA (i.e. 4 mA per device if 6 devices are connected).
  - Output voltage of the Ex-d module: 17.0 V@4 mA to 10.5 V@22 mA
  - Output voltage of the Ex-ia module: 18.5 V@4 mA to 12.5 V@22 mA

**Current span** 

**Navigation**   Setup → Advanced setup → Input/output → Analog I/O → Current span

**Prerequisite** **Operating mode** parameter (→  227) ≠ **Disabled** option or **HART master** option

**Description** Defines the current range for the measured value transmission.

- Selection**
- 4...20 mA NE (3.8...20.5 mA)
  - 4...20 mA US (3.9...20.8 mA)
  - 4...20 mA (4...20.5 mA)
  - Fixed value\*

**Factory setting** 4...20 mA NE (3.8...20.5 mA)

**Additional information**

Read access	Operator
Write access	Maintenance

*Meaning of the options*


Option	Current range for process variable	Minimum value	Lower alarm signal level	Upper alarm signal level	Maximum value
4...20 mA (4...20.5 mA)	4 to 20.5 mA	3.5 mA	< 3.6 mA	> 21.95 mA	22.6 mA
4...20 mA NE (3.8...20.5 mA)	3.8 to 20.5 mA	3.5 mA	< 3.6 mA	> 21.95 mA	22.6 mA

\* Visibility depends on order options or device settings



Option	Current range for process variable	Minimum value	Lower alarm signal level	Upper alarm signal level	Maximum value
4...20 mA US (3.9...20.8 mA)	3.9 to 20.8 mA	3.5 mA	< 3.6 mA	> 21.95 mA	22.0 mA
Fixed current	Constant current, defined in the <b>Fixed current</b> parameter (→ ⓘ 229).				

 In the case of an error, the output current assumes the value defined in the **Failure mode** parameter (→ ⓘ 230).

**Fixed current** 

**Navigation**  Setup → Advanced setup → Input/output → Analog I/O → Fixed current

**Prerequisite** **Current span (→ ⓘ 228) = Fixed current**


**Description** Defines the fixed output current.


**User entry** 4 to 22.5 mA

**Factory setting** 4 mA

**Additional information**

Read access	Operator
Write access	Maintenance

**Analog input source** 

**Navigation**  Setup → Advanced setup → Input/output → Analog I/O → Analog source

**Prerequisite**

- **Operating mode (→ ⓘ 227) = 4..20mA output or HART slave +4..20mA output**
- **Current span (→ ⓘ 228) ≠ Fixed current**

**Description** Defines the process variable transmitted via the AIO.

- Selection**
- None
  - Tank level
  - Tank level %
  - Tank ullage
  - Tank ullage %
  - Measured level
  - Distance
  - Displacer position
  - Water level
  - Upper interface level
  - Lower interface level
  - Bottom level
  - Tank reference height
  - Liquid temperature
  - Vapor temperature

- Air temperature
- Observed density value
- Average profile density <sup>6)</sup>
- Upper density
- Middle density
- Lower density
- P1 (bottom)
- P2 (middle)
- P3 (top)
- GP 1 ... 4 value
- AIO B1-3 value <sup>6)</sup>
- AIO B1-3 value mA <sup>6)</sup>
- AIO C1-3 value <sup>6)</sup>
- AIO C1-3 value mA <sup>6)</sup>
- AIP B4-8 value <sup>6)</sup>
- AIP C4-8 value <sup>6)</sup>
- Element temperature 1 ... 24 <sup>6)</sup>
- HART device 1...15 PV <sup>6)</sup>
- HART device 1 ... 15 PV mA <sup>6)</sup>
- HART device 1 ... 15 PV % <sup>6)</sup>
- HART device 1 ... 15 SV <sup>6)</sup>
- HART device 1 ... 15 TV <sup>6)</sup>
- HART device 1 ... 15 QV <sup>6)</sup>

**Factory setting**

Tank level

**Additional information**

Read access	Operator
Write access	Maintenance

**Failure mode**



**Navigation**

Setup → Advanced setup → Input/output → Analog I/O → Failure mode

**Prerequisite**

**Operating mode (→ 227) = 4..20mA output or HART slave +4..20mA output**

**Description**

Defines the output behavior in case of an error.

**Selection**

- Min.
- Max.
- Last valid value
- Actual value
- Defined value

**Factory setting**

Max.

**Additional information**

Read access	Operator
Write access	Maintenance

<sup>6)</sup> Visibility depends on order options or device settings

**Error value**



**Navigation** Setup → Advanced setup → Input/output → Analog I/O → Error value

**Prerequisite** **Failure mode (→ 230) = Defined value**

**Description** Defines the output value in case of an error.

**User entry** 3.4 to 22.6 mA

**Factory setting** 22 mA

**Additional information**

Read access	Operator
Write access	Maintenance

**Input value**

**Navigation** Setup → Advanced setup → Input/output → Analog I/O → Input value

**Prerequisite**

- **Operating mode (→ 227) = 4..20mA output or HART slave +4..20mA output**
- **Current span (→ 228) ≠ Fixed current**

**Description** Shows the input value of the analog I/O module.

**Additional information**

Read access	Operator
Write access	-

**0 % value**



**Navigation** Setup → Advanced setup → Input/output → Analog I/O → 0 % value

**Prerequisite**

- **Operating mode (→ 227) = 4..20mA output or HART slave +4..20mA output**
- **Current span (→ 228) ≠ Fixed current**

**Description** Value corresponding to an output current of 0% (4mA).

**User entry** Signed floating-point number

**Factory setting** 0 Unitless

**Additional information**

Read access	Operator
Write access	Maintenance

100 % value 🔒

- Navigation** 🔍📄 Setup → Advanced setup → Input/output → Analog I/O → 100 % value
- Prerequisite** 
  - **Operating mode** (→ 📄 227) = **4..20mA output** or **HART slave +4..20mA output**
  - **Current span** (→ 📄 228) ≠ **Fixed current**
- Description** Value corresponding to an output current of 100% (20mA).
- User entry** Signed floating-point number
- Factory setting** 0 Unitless

**Additional information**

Read access	Operator
Write access	Maintenance

Input value %

- Navigation** 🔍📄 Setup → Advanced setup → Input/output → Analog I/O → Input value %
- Prerequisite** 
  - **Operating mode** (→ 📄 227) = **4..20mA output** or **HART slave +4..20mA output**
  - **Current span** (→ 📄 228) ≠ **Fixed current**
- Description** Shows the output value as a percentage of the complete 4...20mA range.

**Additional information**

Read access	Operator
Write access	-

Output value

- Navigation** 🔍📄 Setup → Advanced setup → Input/output → Analog I/O → Output value
- Prerequisite** **Operating mode** (→ 📄 227) = **4..20mA output** or **HART slave +4..20mA output**
- Description** Shows the output value in mA.

**Additional information**

Read access	Operator
Write access	-

**Process variable**



**Navigation** Setup → Advanced setup → Input/output → Analog I/O → Process variable

**Prerequisite** **Operating mode (→ 227) = 4..20mA input or HART master+4..20mA input**

**Description** Defines the type of measuring variable.

- Selection**
- Level linearized
  - Temperature
  - Pressure
  - Density

**Factory setting** Level linearized

**Additional information**

Read access	Operator
Write access	Maintenance

**Analog input 0% value**



**Navigation** Setup → Advanced setup → Input/output → Analog I/O → AI 0% value

**Prerequisite** **Operating mode (→ 227) = 4..20mA input or HART master+4..20mA input**

**Description** Value corresponding to an input current of 0% (4mA).

**User entry** Signed floating-point number

**Factory setting** 0 mm

**Additional information**

Read access	Operator
Write access	Maintenance

**Analog input 100% value**



**Navigation** Setup → Advanced setup → Input/output → Analog I/O → AI 100% value

**Prerequisite** **Operating mode (→ 227) = 4..20mA input or HART master+4..20mA input**

**Description** Value corresponding to an input current of 100% (20mA).

**User entry** Signed floating-point number

**Factory setting** 0 mm

**Additional information**

Read access	Operator
Write access	Maintenance

**Error event type****Navigation**

Setup → Advanced setup → Input/output → Analog I/O → Error event type

**Prerequisite**

**Operating mode (→ 227) ≠ Disabled or HART master**

**Description**

Defines the type of event message (alarm/warning) in case of an error or output out of range in the analog I/O module.

**Selection**

- None
- Warning
- Alarm

**Factory setting**

Warning

**Additional information**

Read access	Operator
Write access	Maintenance

**Process value****Navigation**

Setup → Advanced setup → Input/output → Analog I/O → Process value

**Prerequisite**

**Operating mode (→ 227) = 4..20mA input or HART master+4..20mA input**

**Description**

Shows the input value scaled to customer units.

**Additional information**

Read access	Operator
Write access	-

**Input value in mA****Navigation**

Setup → Advanced setup → Input/output → Analog I/O → Input val. in mA

**Prerequisite**

**Operating mode (→ 227) = 4..20mA input or HART master+4..20mA input**

**Description**



Shows the input value in mA.

**Additional information**


Read access	Operator
Write access	-

**Input value percent**

**Navigation**

  Setup → Advanced setup → Input/output → Analog I/O → Input value [%]

**Prerequisite**

**Operating mode** (→  227) = **4..20mA input** or **HART master+4..20mA input**

**Description**

Shows the input value as a percentage of the complete 4...20mA current range.



**Additional information**

Read access	Operator
Write access	-


**Damping factor**



**Navigation**

  Setup → Advanced setup → Input/output → Analog I/O → Damping factor

**Prerequisite**

**Operating mode** (→  227) ≠ **Disabled** or **HART master**

**Description**

Defines the damping constant (in seconds).

**User entry**

0 to 999.9 s

**Factory setting**

0 s

**Additional information**

Read access	Operator
Write access	Maintenance


**Used for SIL/WHG**



**Navigation**

  Setup → Advanced setup → Input/output → Analog I/O → Used for SIL/WHG

**Prerequisite**

- **Operating mode** (→  227) = **4..20mA output** or **HART slave +4..20mA output**
- The device has a SIL approval.

**Description**

Determines whether the discrete I/O module is in SIL/WHG mode.

**Selection**

- Enabled
- Disabled

**Factory setting**

Disabled

**Additional information**


Read access	Operator
Write access	Maintenance

---


**Expected SIL/WHG chain**

---

**Navigation**

 Setup → Advanced setup → Input/output → Analog I/O → SIL/WHG chain

**Prerequisite**

- **Operating mode (→  227) = 4..20mA output or HART slave +4..20mA output**
- The device has a SIL approval.

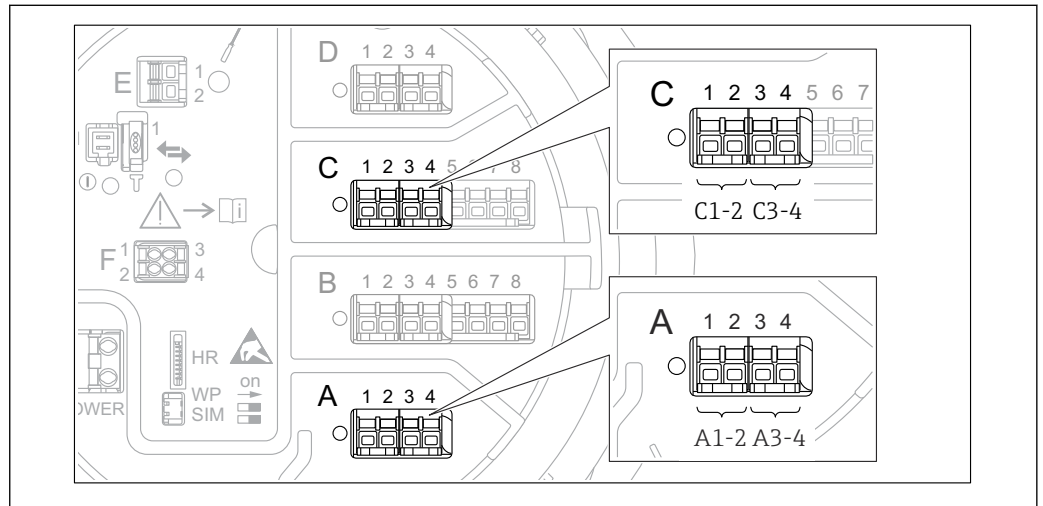
**Additional information**

Read access	Operator
Write access	-



*"Digital Xx-x" submenu*

- i
  - In the operating menu, each digital input or output is designated by the respective slot of the terminal compartment and two terminals within this slot. **A1-2**, for example, denotes terminals 1 and 2 of slot **A**. The same is valid for slots **B**, **C** and **D** if they contain a Digital IO module.
  - In this document, **Xx-x** designates any of these submenus. The structure of all these submenus is the same.



93 Designation of the digital inputs or outputs (examples)

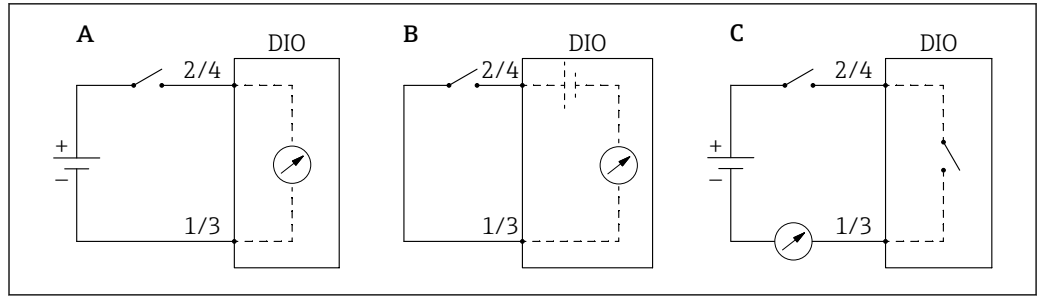
Navigation Setup → Advanced setup → Input/output → Digital Xx-x

**Operating mode**



<b>Navigation</b>	Setup → Advanced setup → Input/output → Digital Xx-x → Operating mode
<b>Description</b>	Defines the operating mode of the discrete I/O module.
<b>Selection</b>	<ul style="list-style-type: none"> <li>▪ Disabled</li> <li>▪ Output passive</li> <li>▪ Input passive</li> <li>▪ Input active</li> </ul>
<b>Factory setting</b>	Disabled

**Additional information**



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94 Operating modes of the Digital I/O module

- A Input passive
- B Input active
- C Output passive

**Digital input source**



**Navigation**

Setup → Advanced setup → Input/output → Digital Xx-x → Digital source

**Prerequisite**

Operating mode (→ 237) = Output passive

**Description**

Defines which device state is indicated by the digital output.

**Selection**

- None
- Balance flag
- Alarm x any
- Alarm x High
- Alarm x HighHigh
- Alarm x High or HighHigh
- Alarm x Low
- Alarm x LowLow
- Alarm x Low or LowLow
- Digital Xx-x
- Primary Modbus x
- Secondary Modbus x

**Factory setting**

None

**Additional information**

**Meaning of the options**

- **Alarm x any, Alarm x High, Alarm x HighHigh, Alarm x High or HighHigh, Alarm x Low, Alarm x LowLow, Alarm x Low or LowLow**

The digital output indicates if the selected alarm is currently active. The alarms themselves are defined in the **Alarm 1 to 4** submenus.

- **Digital Xx-x**<sup>7)</sup>

The digital signal present at the digital input **Xx-x** is passed through to the digital output.

- **Modbus A1-4 Discrete x**
- **Modbus B1-4 Discrete x**
- **Modbus C1-4 Discrete x**
- **Modbus D1-4 Discrete x**


The digital value written by the Modbus Master device to the **Modbus discrete x** parameter<sup>8)</sup> is passed to the digital output. For details refer to Special Documentation SD02066G.

**Input value**

**Navigation**

 Setup → Advanced setup → Input/output → Digital Xx-x → Input value

**Prerequisite**

**Operating mode (→  237) = "Input passive" option or "Input active" option**

**Description**

Shows the digital input value.


**Additional information**

Read access	Operator
Write access	-


**Contact type**



**Navigation**

 Setup → Advanced setup → Input/output → Digital Xx-x → Contact type

**Prerequisite**

**Operating mode (→  237) ≠ Disabled**

**Description**


Determines the switching behavior of the input or output.

**Selection**

- Normally open
- Normally closed

**Factory setting**

Normally open

7) Only present if "Operating mode (→  237)" = "Input passive" or "Input active" for the respective Digital I/O module.

8) Expert → Communication → Modbus Xx-x → Modbus discrete x

**Output simulation**



**Navigation**

Setup → Advanced setup → Input/output → Digital Xx-x → Output sim

**Prerequisite**

**Operating mode** (→ 237) = **Output passive**

**Description**

Sets the output to a specific simulated value.

**Selection**

- Disable
- Simulating active
- Simulating inactive
- Fault 1
- Fault 2

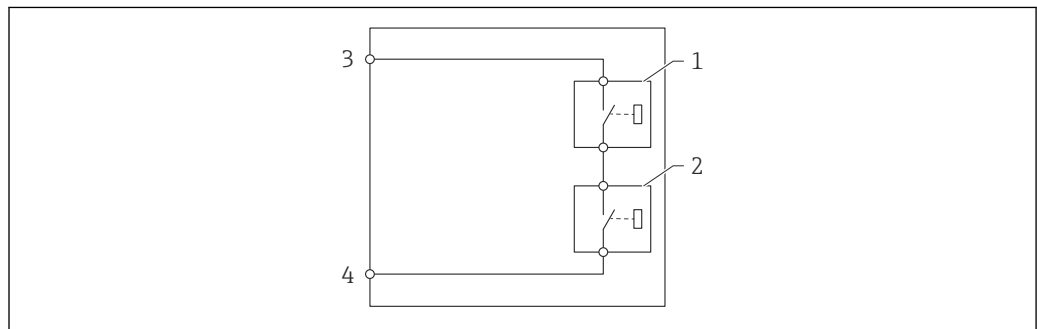
**Factory setting**

Disable

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

The digital output consists of two relays connected in series:



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95 The two relays of a digital output

1/2 The relays

3/4 The terminals of the digital output


The switching state of these relays is defined by the **Output simulation** parameter as follows:

Output simulation	State of relay 1	State of relay 2	Expected result on the terminals of the I/O module
Simulating active	Closed	Closed	Closed
Simulating inactive	Open	Open	Open
Fault 1	Closed	Open	Open
Fault 2	Open	Closed	Open

**i** The **Fault 1** and **Fault 2** options can be used to check the correct switching behavior of the two relays.

**Output value**

**Navigation**  Setup → Advanced setup → Input/output → Digital Xx-x → Output values


**Prerequisite** **Operating mode (→  237) = Output passive**


**Description** Shows the digital output value.

**Additional information**

Read access	Operator
Write access	-

**Readback value**

**Navigation**  Setup → Advanced setup → Input/output → Digital Xx-x → Readback value

**Prerequisite** **Operating mode (→  237) = Output passive**


**Description** Shows the value read back from the output.

**Additional information**


Read access	Operator
Write access	-

**Used for SIL/WHG**



**Navigation**  Setup → Advanced setup → Input/output → Digital Xx-x → Used for SIL/WHG

**Prerequisite**

- **Operating mode (→  237) = Output passive**
- The device has a SIL certificate.

**Description** Determines whether the discrete I/O module is in SIL/WHG mode.

**Selection**

- Enabled
- Disabled

**Factory setting** Disabled


**Additional information**

Read access	Operator
Write access	Maintenance

---

**Expected SIL/WHG chain**


---


**Navigation** Setup → Advanced setup → Input/output → Digital C3-4 → SIL/WHG chain**Prerequisite****Operating mode (→  237) = Output passive****Additional information**

Read access	Service
Write access	-

*"Digital input mapping" submenu*

Navigation  Setup → Advanced setup → Input/output → DI mapping

**Digital input source 1** 

**Navigation**  Setup → Advanced setup → Input/output → DI mapping → Digital source 1


**Description** Selects the source of digital input #1 (for gauge command).


- Selection**
- None
  - Digital A1-2 \*
  - Digital A3-4 \*
  - Digital B1-2 \*
  - Digital B3-4 \*
  - Digital C1-2 \*
  - Digital C3-4 \*
  - Digital D1-2 \*
  - Digital D3-4 \*

**Factory setting** None

**Additional information**

Read access	Operator
Write access	Maintenance

**Digital input source 2** 

**Navigation**  Setup → Advanced setup → Input/output → DI mapping → Digital source 2

**Description** Selects the source of digital input #2 (for gauge command).

- Selection**
- None
  - Digital A1-2 \*
  - Digital A3-4 \*
  - Digital B1-2 \*
  - Digital B3-4 \*
  - Digital C1-2 \*
  - Digital C3-4 \*
  - Digital D1-2 \*
  - Digital D3-4 \*

**Factory setting** None

**Additional information**

Read access	Operator
Write access	Maintenance

\* Visibility depends on order options or device settings

**Gauge command 0**



**Navigation** Setup → Advanced setup → Input/output → DI mapping → Gauge command 0

**Prerequisite** **Digital input source 1 (→ 243) ≠ None**

**Description** Gauge command assigned to digital input combination 0 (DI2=0, DI1=0).

- Selection**
- Stop \*
  - Level
  - Up \*
  - Bottom level \*
  - Upper I/F level \*
  - Lower I/F level \*
  - Upper density \*
  - Middle density \*
  - Lower density \*
  - Repeatability \*
  - Water dip \*
  - Release overtension \*
  - Tank profile \*
  - Interface profile \*
  - Manual profile \*
  - Level standby \*
  - Offset standby \*

**Factory setting** Level

**Additional information**

Read access	Operator
Write access	Maintenance

**Gauge command 1**



**Navigation** Setup → Advanced setup → Input/output → DI mapping → Gauge command 1

**Prerequisite** **Digital input source 1 (→ 243) ≠ None**

**Description** Gauge command assigned to digital input combination 1 (DI2=0, DI1=1).

- Selection**
- Stop \*
  - Level
  - Up \*
  - Bottom level \*
  - Upper I/F level \*
  - Lower I/F level \*
  - Upper density \*
  - Middle density \*
  - Lower density \*
  - Repeatability \*
  - Water dip \*

\* Visibility depends on order options or device settings



- Release overtension \*
- Tank profile \*
- Interface profile \*
- Manual profile \*
- Level standby \*
- Offset standby \*

**Factory setting**

Up

**Additional information**

Read access	Operator
Write access	Maintenance

**Gauge command 2**



**Navigation**

Setup → Advanced setup → Input/output → DI mapping → Gauge command 2

**Prerequisite**

- **Digital input source 1** (→ 243) ≠ None
- **Digital input source 2** (→ 243) ≠ None

**Description**

Gauge command assigned to digital Input combination 2 (DI2=1, DI1=0).

**Selection**

- Stop \*
- Level
- Up \*
- Bottom level \*
- Upper I/F level \*
- Lower I/F level \*
- Upper density \*
- Middle density \*
- Lower density \*
- Repeatability \*
- Water dip \*
- Release overtension \*
- Tank profile \*
- Interface profile \*
- Manual profile \*
- Level standby \*
- Offset standby \*

**Factory setting**

Stop

**Additional information**

Read access	Operator
Write access	Maintenance

\* Visibility depends on order options or device settings

**Gauge command 3**



**Navigation** Setup → Advanced setup → Input/output → DI mapping → Gauge command 3

**Prerequisite**

- Digital input source 1 (→ 243) ≠ None
- Digital input source 2 (→ 243) ≠ None

**Description** Gauge command assigned to digital input combination 3 (DI2=1, DI1=1).

**Selection**

- Stop \*
- Level
- Up \*
- Bottom level \*
- Upper I/F level \*
- Lower I/F level \*
- Upper density \*
- Middle density \*
- Lower density \*
- Repeatability \*
- Water dip \*
- Release overtension \*
- Tank profile \*
- Interface profile \*
- Manual profile \*
- Level standby \*
- Offset standby \*

**Factory setting** Upper I/F level

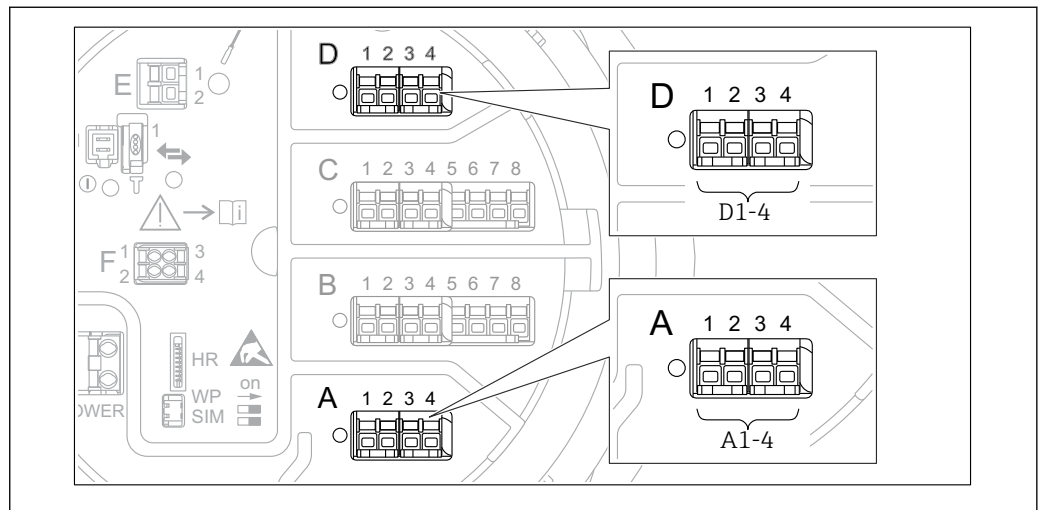
**Additional information**

Read access	Operator
Write access	Maintenance

\* Visibility depends on order options or device settings

**"Communication" submenu**

This menu contains a submenu for each digital communication interface of the device. The communication interfaces are designated by "X1-4" where "X" specifies the slot in the terminal compartment and "1-4" the terminals within this slot.



96 Designation of the "Modbus", "V1" or "WM550" modules (examples); depending on the device version these modules may also be in slot B or C.

Navigation Setup → Advanced setup → Communication

*"Modbus X1-4", "V1 X1-4" and "WM550 X1-4" submenu*

This submenu is only present for devices with **MODBUS** and/or **V1** and/or **"WM550" option** communication interface. There is one submenu of this type for each communication interface.

Navigation Setup → Advanced setup → Communication → Modbus X1-4

Navigation Setup → Advanced setup → Communication → V1 X1-4

Navigation Setup → Advanced setup → Communication → WM550 X1-4

**Communication interface protocol**

Navigation Setup → Advanced setup → Communication → Modbus X1-4 / V1 X1-4 / WM550 X1-4 → Commu I/F protoc


Description Shows the type of communication protocol.

**Additional information**

Read access	Operator
Write access	-

*"Configuration" submenu*


This submenu is only present for devices with a **MODBUS** communication interface.


*Navigation*       Setup → Advanced setup → Communication → Modbus X1-4 → Configuration

---

**Baudrate** 

---

**Navigation**       Setup → Advanced setup → Communication → Modbus X1-4 → Configuration → Baudrate

**Prerequisite**      **Communication interface protocol (→  247) = MODBUS**

**Description**      Defines the baud rate of the communication.

- Selection**
- 600 BAUD
  - 1200 BAUD
  - 2400 BAUD
  - 4800 BAUD
  - 9600 BAUD \*
  - 19200 BAUD \*

**Factory setting**      9600 BAUD


**Additional information**


Read access	Operator
Write access	Maintenance

---

**Parity** 

---

**Navigation**       Setup → Advanced setup → Communication → Modbus X1-4 → Configuration → Parity

**Prerequisite**      **Communication interface protocol (→  247) = MODBUS**

**Description**      Defines the parity of the Modbus communication.

- Selection**
- Odd
  - Even
  - None / 1 stop bit
  - None / 2 stop bits

**Factory setting**      None / 1 stop bit

**Additional information**

Read access	Operator
Write access	Maintenance

---

\* Visibility depends on order options or device settings

**Modbus address**



**Navigation** Setup → Advanced setup → Communication → Modbus X1-4 → Configuration → Device ID

**Prerequisite** **Communication interface protocol (→ 247) = MODBUS**

**Description** Defines the Modbus address of the device.

**User entry** 1 to 247

**Factory setting** 1

**Additional information**

Read access	Operator
Write access	Maintenance

**Float swap mode**



**Navigation** Setup → Advanced setup → Communication → Modbus X1-4 → Configuration → Float swap mode

**Prerequisite** **Communication interface protocol (→ 247) = MODBUS**

**Description** Sets the format of how the floating point value is transferred on Modbus.

- Selection**
- Normal 3-2-1-0
  - Swap 0-1-2-3
  - WW Swap 1-0-3-2
  - WW Swap 2-3-0-1

**Factory setting** Swap 0-1-2-3

**Additional information**

Read access	Operator
Write access	Maintenance

**Bus termination**



**Navigation** Setup → Advanced setup → Communication → Modbus X1-4 → Configuration → Bus termination

**Prerequisite** **Communication interface protocol (→ 247) = MODBUS**

**Description** Activates or deactivates the bus termination at the device. Should only be activated on the last device in a loop.

- Selection**
- Off
  - On


**Factory setting**                      Off

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance


*"Configuration" submenu*

This submenu is only present for devices with a **V1** communication interface.


*Navigation*       Setup → Advanced setup → Communication → V1 X1-4 → Configuration



---

**Communication interface protocol variant** 

<b>Navigation</b>	 Setup → Advanced setup → Communication → V1 X1-4 → Configuration → Protocol variant				
<b>Description</b>	Determines which variant of the V1 protocol is used.				
<b>User interface</b>	<ul style="list-style-type: none"> <li>■ None</li> <li>■ V1*</li> </ul>				
<b>Factory setting</b>	None				
<b>Additional information</b>	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="width: 50%;">Read access</td> <td>Operator</td> </tr> <tr> <td>Write access</td> <td>Maintenance</td> </tr> </table>	Read access	Operator	Write access	Maintenance
Read access	Operator				
Write access	Maintenance				

---

**V1 address** 

<b>Navigation</b>	 Setup → Advanced setup → Communication → V1 X1-4 → Configuration → V1 address				
<b>Prerequisite</b>	<b>Communication interface protocol variant (→  251) = V1</b>				
<b>Description</b>	Identifier of the device for the V1 communication.				
<b>User entry</b>	0 to 99				
<b>Factory setting</b>	1				
<b>Additional information</b>	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="width: 50%;">Read access</td> <td>Operator</td> </tr> <tr> <td>Write access</td> <td>Maintenance</td> </tr> </table>	Read access	Operator	Write access	Maintenance
Read access	Operator				
Write access	Maintenance				

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\* Visibility depends on order options or device settings

**V1 address**



**Navigation** Setup → Advanced setup → Communication → V1 X1-4 → Configuration → V1 address

**Prerequisite** **Communication interface protocol variant (→ 251)**

**Description** Identifier of the previous device for V1 communication.

**User entry** 0 to 255

**Factory setting** 1

**Additional information**

Read access	Operator
Write access	Maintenance

**Level mapping**



**Navigation** Setup → Advanced setup → Communication → V1 X1-4 → Configuration → Level mapping

**Prerequisite** **Communication interface protocol (→ 247) = V1**

**Description** Determines the transmittable range of levels.

**Selection**

- +ve
- +ve & -ve

**Factory setting** +ve

**Additional information**

Read access	Operator
Write access	Maintenance

In V1, the level is always represented by a number in the range from 0 to 999 999. This number corresponds to a level as follows:

*"Level mapping" = "+ve"*

Number	Corresponding level
0	0.0 mm
999 999	99 999.9 mm

*"Level mapping" = "+ve & -ve"*

Number	Corresponding level
0	0.0 mm
500 000	50 000.0 mm



Number	Corresponding level
500 001	-0.1 mm
999 999	-49 999.9 mm

**Line impedance**



**Navigation** Setup → Advanced setup → Communication → V1 X1-4 → Configuration → Line impedance

**Prerequisite** **Communication interface protocol (→ 247) = V1**

**Description** Adjusts the impedance of the communication line.

**User entry** 0 to 15

**Factory setting** 15

**Additional information**

Read access	Operator
Write access	Maintenance

The line impedance affects the voltage difference between a logical 0 and a logical 1 on the message of the device to the bus. The default setting is suitable for most applications.

**Compatibility mode**



**Navigation** Setup → Advanced setup → Communication → Modbus Xx-x / V1 Xx-x → Configuration → Comp. mode

**Description** Defines the compatibility mode.

**Selection**

- Nxx5xx
- Nxx8x

**Factory setting** Nxx8x

**Additional information** In **NMS5x** mode: Only values which have also existed on NMS5x Gauge status are output on the bus.

In **NMS8x** mode: All Gauge status are available at this parameter.


Read access	Operator
Write access	Maintenance

*"V1 input selector" submenu*


This submenu is only present for devices with a **V1** communication interface.

*Navigation*       Setup → Advanced setup → Communication → V1 X1-4 → V1 input select.

---

**Alarm 1 input source** 

---

**Navigation**       Setup → Advanced setup → Communication → V1 X1-4 → V1 input select. → Alarm1 input src

**Description**      Determines which discrete value will be transmitted as V1 alarm 1 status.

- Selection**
- None
  - Alarm 1-4 any
  - Alarm 1-4 HighHigh
  - Alarm 1-4 High or HighHigh
  - Alarm 1-4 High
  - Alarm 1-4 Low
  - Alarm 1-4 Low or LowLow
  - Alarm 1-4 LowLow

**Factory setting**      None


**Additional information**

Read access	Operator
Write access	Maintenance

---

**Alarm 2 input source** 

---

**Navigation**       Setup → Advanced setup → Communication → V1 X1-4 → V1 input select. → Alarm2 input src

**Description**      Determines which discrete value will be transmitted as V1 alarm 2 status.

- Selection**
- None
  - Alarm 1-4 any
  - Alarm 1-4 HighHigh
  - Alarm 1-4 High or HighHigh
  - Alarm 1-4 High
  - Alarm 1-4 Low
  - Alarm 1-4 Low or LowLow
  - Alarm 1-4 LowLow

**Factory setting**      None

**Additional information**

Read access	Operator
Write access	Maintenance

**Value percent selector**



**Navigation**      Setup → Advanced setup → Communication → V1 X1-4 → V1 input select. → Value % select

**Description**      Selects which value shall be transmitted as a 0..100% value in the V1 Z0/Z1 message.

- Selection**
- None
  - Tank level %
  - Tank ullage %
  - AIO B1-3 value % \*
  - AIO C1-3 value % \*

**Factory setting**      None

**Additional information**

Read access	Operator
Write access	Maintenance

*"Configuration" submenu*

This submenu is only present for devices with a **"WM550" option** communication interface.

*Navigation*      Setup → Advanced setup → Communication → WM550 X1-4 → Configuration

**Baudrate**



**Navigation**      Setup → Advanced setup → Communication → WM550 X1-4 → Configuration → Baudrate

**Prerequisite**      **Communication interface protocol (→ 247) = "WM550" option**

**Description**      Defines the baud rate of the WM550 communication.

- Selection**
- 600 BAUD
  - 1200 BAUD
  - 2400 BAUD
  - 4800 BAUD

**Factory setting**      2400 BAUD

**Additional information**

Read access	Operator
Write access	Maintenance

\* Visibility depends on order options or device settings

---

**WM550 address**

---



<b>Navigation</b>	Setup → Advanced setup → Communication → WM550 X1-4 → Configuration → WM550 address
<b>Description</b>	Describes the WM550 address of the device.
<b>User entry</b>	0 to 63
<b>Factory setting</b>	1

---

**Software ID**

---



<b>Navigation</b>	Setup → Advanced setup → Communication → WM550 X1-4 → Configuration → Software ID
<b>Prerequisite</b>	<b>Communication interface protocol (→  247) = "WM550" option</b>
<b>Description</b>	Defines content for WM550 Task 32. Detailed information on content for WM550 Task 32, Special Documentation SD02567G.
<b>User entry</b>	0 to 9999
<b>Factory setting</b>	2000

*"WM550 input selector" submenu*

This submenu is only present for devices with a **"WM550" option** communication interface.

*Navigation* Setup → Advanced setup → Communication → WM550 X1-4 → WM550 inp select

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**Discrete 1 selector**

---



<b>Navigation</b>	Setup → Advanced setup → Communication → WM550 X1-4 → WM550 inp select → Discrete 1select
<b>Description</b>	Determines the input source which is transferred as Alarm bit [n] value in the corresponding WM550 tasks.
<b>Selection</b>	<ul style="list-style-type: none"> <li>▪ None</li> <li>▪ <b>Balance flag</b> optionVisibility depends on order options or device settings</li> <li>▪ Alarm 1...4 any</li> <li>▪ Alarm 1...4 HighHigh</li> </ul>

- Alarm 1...4 High or HighHigh
- Alarm 1...4 High
- Alarm 1...4 Low
- Alarm 1...4 Low or LowLow
- Alarm 1...4 LowLow
- Digital Xx-x

**Factory setting**

None


**Additional information**

Read access	Operator
Write access	Maintenance


*"HART output" submenu*


*Navigation*       Setup → Advanced setup → Communication → HART output

*"Configuration" submenu*

*Navigation*       Setup → Advanced setup → Communication → HART output  
→ Configuration

---

**System polling address** 

**Navigation**       Setup → Advanced setup → Communication → HART output → Configuration  
→ Polling address

**Description**      Device address for HART communication.

**User entry**      0 to 63

**Factory setting**      15

**Additional information**

Read access	Operator
Write access	Maintenance

---

**No. of preambles** 

**Navigation**       Setup → Advanced setup → Communication → HART output → Configuration → No.  
of preambles

**Description**      Defines the number of preambles in the HART telegram.


**User entry**      5 to 20

**Factory setting**      5

**Additional information**

Read access	Operator
Write access	Maintenance

---

**PV source** 

**Navigation**       Setup → Advanced setup → Communication → HART output → Configuration → PV  
source

**Description**      Decides, if the PV configuration is according to an analog output (HART slave) or  
customized (in case of HART tunneling only).

- Selection**
- AIO B1-3 \*
  - AIO C1-3 \*
  - Custom

**Factory setting** Custom

**Additional information**

Read access	Maintenance
Write access	Maintenance

---

**Assign PV**



**Navigation** Setup → Advanced setup → Communication → HART output → Configuration → Assign PV

**Prerequisite** PV source (→ 258) = Custom

**Description** Assign a measured variable to the primary dynamic variable (PV).  
 Additional information:  
 The assigned measured variable is also used by the current output.

- Selection**
- None
  - Tank level
  - Tank ullage
  - Measured level
  - Distance
  - Displacer position
  - Water level
  - Upper interface level
  - Lower interface level
  - Bottom level
  - Tank reference height
  - Liquid temperature
  - Vapor temperature
  - Air temperature
  - Observed density value
  - Average profile density
  - Upper density
  - Middle density
  - Lower density
  - P1 (bottom)
  - P2 (middle)
  - P3 (top)
  - GP 1 value
  - GP 2 value
  - GP 3 value
  - GP 4 value

**Factory setting** Tank level

---

\* Visibility depends on order options or device settings

**Additional information**

Read access	Operator
Write access	Maintenance

 The **Measured level** option doesn't contain a unit. If a unit is needed, select the **Tank level** option.

**0 % value****Navigation**

 Setup → Advanced setup → Communication → HART output → Configuration → 0 % value

**Prerequisite**

**PV source = Custom**

**Description**

0% value of the primary variable (PV).

**User entry**

Signed floating-point number

**Factory setting**

0 mm

**Additional information**

Read access	Operator
Write access	Maintenance

**100 % value****Navigation**

 Setup → Advanced setup → Communication → HART output → Configuration → 100 % value

**Prerequisite**

**PV source = Custom**

**Description**

100% value of the primary variable (PV).

**User entry**

Signed floating-point number

**Factory setting**

0 mm

**Additional information**

Read access	Operator
Write access	Maintenance

**PV mA selector****Navigation**

 Setup → Advanced setup → Communication → HART output → Configuration → PV mA selector

**Prerequisite**

**PV source = Custom**



**Description** Assigns a current to the primary HART variable (PV).


- Selection**
- None
  - AIO B1-3 value mA \*
  - AIO C1-3 value mA \*

**Factory setting** None

**Additional information**

Read access	Operator
Write access	Maintenance

**Primary variable (PV)**


**Navigation**  Setup → Advanced setup → Communication → HART output → Configuration → Primary var (PV)

**Description** Shows the current measured value of the primary dynamic variable (PV)

**Additional information**

Read access	Operator
Write access	-

**Percent of range**

**Navigation**  Setup → Advanced setup → Communication → HART output → Configuration → Percent of range


**Description** Shows the value of the primary variable (PV) as a percentage of the defined 0% to 100% range.

**Additional information**

Read access	Operator
Write access	-

**Assign SV**



**Navigation**  Setup → Advanced setup → Communication → HART output → Configuration → Assign SV

**Description** Assign a measured variable to the second dynamic variable (SV).

- Selection**
- None
  - Tank level
  - Tank ullage

\* Visibility depends on order options or device settings

- Measured level
- Distance
- Displacer position
- Water level
- Upper interface level
- Lower interface level
- Bottom level
- Tank reference height
- Liquid temperature
- Vapor temperature
- Air temperature
- Observed density value
- Average profile density
- Upper density
- Middle density
- Lower density
- P1 (bottom)
- P2 (middle)
- P3 (top)
- GP 1 value
- GP 2 value
- GP 3 value
- GP 4 value

**Factory setting**

Liquid temperature

**Additional information**

Read access	Operator
Write access	Maintenance


 The **Measured level** option doesn't contain a unit. If a unit is needed, select the **Tank level** option.

---

**Secondary variable (SV)**

---

**Navigation**

 Setup → Advanced setup → Communication → HART output → Configuration → Second.var(SV)

**Prerequisite**

**Assign SV (→  261) ≠ None**

**Description**

Shows the current measured value of the secondary dynamic variable (SV)

**Additional information**

Read access	Operator
Write access	-

**Assign TV**



**Navigation** Setup → Advanced setup → Communication → HART output → Configuration → Assign TV

**Description** Assign a measured variable to the tertiary dynamic variable (TV).

- Selection**
- None
  - Tank level
  - Tank ullage
  - Measured level
  - Distance
  - Displacer position
  - Water level
  - Upper interface level
  - Lower interface level
  - Bottom level
  - Tank reference height
  - Liquid temperature
  - Vapor temperature
  - Air temperature
  - Observed density value
  - Average profile density
  - Upper density
  - Middle density
  - Lower density
  - P1 (bottom)
  - P2 (middle)
  - P3 (top)
  - GP 1 value
  - GP 2 value
  - GP 3 value
  - GP 4 value

**Factory setting** Water level

**Additional information**

Read access	Operator
Write access	Maintenance

The **Measured level** option doesn't contain a unit. If a unit is needed, select the **Tank level** option.

**Tertiary variable (TV)**

**Navigation** Setup → Advanced setup → Communication → HART output → Configuration → Tertiary var(TV)

**Prerequisite** **Assign TV** (→ 263) ≠ **None**

**Description** Shows the current measured value of the tertiary (third) dynamic variable (TV)

**Additional information**

Read access	Operator
Write access	-

**Assign QV**



**Navigation**

Setup → Advanced setup → Communication → HART output → Configuration → Assign QV

**Description**

Assign a measured variable to the quaternary dynamic variable (QV).

**Selection**

- None
- Tank level
- Tank ullage
- Measured level
- Distance
- Displacer position
- Water level
- Upper interface level
- Lower interface level
- Bottom level
- Tank reference height
- Liquid temperature
- Vapor temperature
- Air temperature
- Observed density value
- Average profile density
- Upper density
- Middle density
- Lower density
- P1 (bottom)
- P2 (middle)
- P3 (top)
- GP 1 value
- GP 2 value
- GP 3 value
- GP 4 value

**Factory setting**

Observed density value

**Additional information**

Read access	Operator
Write access	Maintenance

The **Measured level** option doesn't contain a unit. If a unit is needed, select the **Tank level** option.

**Quaternary variable (QV)**

**Navigation**

☰☰ Setup → Advanced setup → Communication → HART output → Configuration  
→ Quaterna.var(QV)

**Prerequisite**

**Assign QV (→ ☰ 264) ≠ None**

**Description**


Shows the current measured value of the quaternary (fourth) dynamic variable (QV)


**Additional information**

Read access	Operator
Write access	-

*"Information" submenu*

Navigation  Setup → Advanced setup → Communication → HART output → Information

**HART short tag** 

**Navigation**  Setup → Advanced setup → Communication → HART output → Information → HART short tag


**Description** Defines the short tag for the measuring point.  
 Maximum length: 8 characters  
 Allowed characters: A-Z, 0-9, certain special characters


**User entry** Character string comprising numbers, letters and special characters (8)

**Factory setting** NMS8x

**Additional information**

Read access	Operator
Write access	Maintenance

**Device tag** 

**Navigation**  Setup → Advanced setup → Communication → HART output → Information → Device tag

**Description** Enter a unique name for the measuring point to identify the device quickly within the plant.


**User entry** Character string comprising numbers, letters and special characters (32)

**Factory setting** NMS8x

**Additional information**

Read access	Operator
Write access	Maintenance

**HART descriptor** 

**Navigation**  Setup → Advanced setup → Communication → HART output → Information → HART descriptor

**Description** Enter description for the measuring point

**User entry** Character string comprising numbers, letters and special characters (16)

**Factory setting** NMS8x

**Additional information**

Read access	Operator
Write access	Maintenance

**HART message**



**Navigation**

Setup → Advanced setup → Communication → HART output → Information → HART message

**Description**

Use this function to define a HART message which is sent via the HART protocol when requested by the master.

Maximum length: 32 characters

Allowed characters: A-Z, 0-9, certain special characters

**User entry**

Character string comprising numbers, letters and special characters (32)

**Factory setting**

NMS8x

**Additional information**

Read access	Operator
Write access	Maintenance

**HART date code**



**Navigation**

Setup → Advanced setup → Communication → HART output → Information → HART date code

**Description**

Enter date of the last configuration change. Use this format yyyy-mm-dd

**User entry**

Character string comprising numbers, letters and special characters (10)


**Factory setting**

2009-07-20

**Additional information**

Read access	Operator
Write access	Maintenance


**"Application" submenu**

Navigation  Setup → Advanced setup → Application


*"Tank configuration" submenu*


Navigation  Setup → Advanced setup → Application → Tank config

*"Level" submenu*

Navigation  Setup → Advanced setup → Application → Tank config → Level

---

**Level source** 

**Navigation**  Setup → Advanced setup → Application → Tank config → Level → Level source

**Description** Defines the source of the level value.

- Selection**
- No input value
  - HART device 1 ... 15 level
  - Level SR\*
  - Level\*
  - Displacer position\*
  - AIO B1-3 value\*
  - AIO C1-3 value\*
  - AIP B4-8 value\*
  - AIP C4-8 value\*


**Factory setting** Dependent on the device version

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Empty** 

**Navigation**  Setup → Advanced setup → Application → Tank config → Level → Empty

**Description** Distance from reference point to zero position (tank bottom or datum plate).

**User entry** 0 to 10 000 000 mm

**Factory setting** Dependent on the device version

---

\* Visibility depends on order options or device settings



**Additional information**

Read access	Operator
Write access	Maintenance

 The reference point is the reference line of the calibration window.

**Tank reference height**



**Navigation**

 Setup → Advanced setup → Application → Tank config → Level → Tank ref height

**Description**

Defines the distance from the dipping reference point to the zero position (tank bottom or datum plate).

**User entry**

0 to 10 000 000 mm

**Factory setting**

Dependent on the device version

**Additional information**

Read access	Operator
Write access	Maintenance

**Tank level**

**Navigation**

 Setup → Advanced setup → Application → Tank config → Level → Tank level

**Description**

Shows the distance from the zero position (tank bottom or datum plate) to the product surface.

**Additional information**

Read access	Operator
Write access	-

**Set level**



**Navigation**

 Setup → Advanced setup → Application → Tank config → Level → Set level

**Description**

If the level measured by the device does not match the actual level obtained by a manual dip, enter the correct level into this parameter.

**User entry**


0 to 10 000 000 mm

**Factory setting**


0 mm

**Additional information**

Read access	Operator
Write access	Maintenance

The device adjusts the **Empty** parameter (→  200) according to the entered value, such that the measured level will match the actual level.

---

**Water level source** 

---

**Navigation**   Setup → Advanced setup → Application → Tank config → Level → Water level src

**Description** Defines the source of the bottom water level.


- Selection**
- Manual value
  - Bottom level
  - HART device 1 ... 15 level
  - AIO B1-3 value
  - AIO C1-3 value
  - AIP B4-8 value
  - AIP C4-8 value

**Factory setting** Manual value

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Manual water level** 

---

**Navigation**   Setup → Advanced setup → Application → Tank config → Level → Man. water level

**Prerequisite** **Water level source (→  270) = Manual value**

**Description** Defines the manual value of the bottom water level.

**User entry** -2 000 to 5 000 mm

**Factory setting** 0 mm



**Additional information**

Read access	Operator
Write access	Maintenance

---

**Water level**

---

**Navigation**   Setup → Advanced setup → Application → Tank config → Level → Water level


**Description** Shows the bottom water level.

**Additional information**

Read access	Operator
Write access	-

*"Temperature" submenu*

Read access	Maintenance
-------------	-------------

Navigation  Setup → Advanced setup → Application → Tank config → Temperature

**Liquid temp source** 

**Navigation**  Setup → Advanced setup → Application → Tank config → Temperature → Liq temp source


**Description** Defines source from which the liquid temperature is obtained.


- Selection**
- Manual value
  - HART device 1 ... 15 temperature
  - AIO B1-3 value
  - AIO C1-3 value
  - AIP B4-8 value
  - AIP C4-8 value


**Factory setting** Manual value

**Additional information**

Read access	Operator
Write access	Maintenance

**Manual liquid temperature** 

**Navigation**  Setup → Advanced setup → Application → Tank config → Temperature → Man. liquid temp

**Prerequisite** **Liquid temp source (→  202) = Manual value**

**Description** Defines the manual value of the liquid temperature.


**User entry** -50 to 300 °C

**Factory setting** 25 °C

**Additional information**

Read access	Operator
Write access	Maintenance

**Liquid temperature**

**Navigation**  Setup → Advanced setup → Application → Tank config → Temperature → Liquid temp.

**Description** Shows the average or spot temperature of the measured liquid.

**Additional information**

Read access	Operator
Write access	-

**Air temperature source**



**Navigation**  Setup → Advanced setup → Application → Tank config → Temperature → Air temp. source

**Description** Defines source from which the air temperature is obtained.

- Selection**
- Manual value
  - HART device 1 ... 15 temperature
  - AIO B1-3 value
  - AIO C1-3 value
  - AIP B4-8 value
  - AIP C4-8 value


**Factory setting** Manual value

**Additional information**

Read access	Operator
Write access	Maintenance

**Manual air temperature**



**Navigation**  Setup → Advanced setup → Application → Tank config → Temperature → Manual air temp.

**Prerequisite** **Air temperature source (→  273) = Manual value**

**Description** Defines the manual value of the air temperature.

**User entry** -50 to 300 °C

**Factory setting** 25 °C

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Air temperature**


---

**Navigation**  Setup → Advanced setup → Application → Tank config → Temperature → Air temp.

**Description** Shows the air temperature.


**Additional information**

Read access	Operator
Write access	-

---

**Vapor temp source**


---



**Navigation**  Setup → Advanced setup → Application → Tank config → Temperature → Vapor temp src

**Description** Defines the source from which the vapor temperature is obtained.

**Selection**

- Manual value
- HART device 1 ... 15 vapor temp
- AIO B1-3 value
- AIO C1-3 value
- AIP B4-8 value
- AIP C4-8 value

**Factory setting**

Manual value


**Additional information**

Read access	Operator
Write access	Maintenance

---

**Manual vapor temperature**


---



**Navigation**  Setup → Advanced setup → Application → Tank config → Temperature → Man. vapor temp.

**Prerequisite** **Vapor temp source (→  274) = Manual value**

**Description** Defines the manual value of the vapor temperature.

**User entry** -50 to 300 °C

**Factory setting** 25 °C

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Vapor temperature**

---

**Navigation**

 Setup → Advanced setup → Application → Tank config → Temperature → Vapor temp.


**Description**


Shows the measured vapor temperature.

**Additional information**

Read access	Operator
Write access	-

"Density" submenu

Navigation  Setup → Advanced setup → Application → Tank config → Density

Observed density source 

**Navigation**  Setup → Advanced setup → Application → Tank config → Density → Density source

**Description** Determines how the density is obtained.


- Selection**
- HTG \*
  - HTMS \*
  - Average profile density \*
  - Upper density
  - Middle density
  - Lower density

**Factory setting** Dependent on the device version

**Additional information**

Read access	Operator
Write access	Maintenance


Observed density

**Navigation**  Setup → Advanced setup → Application → Tank config → Density → Observed density

**Description** Shows the measured or calculated density.

**Additional information**

Read access	Operator
Write access	-

Air density 

**Navigation**  Setup → Advanced setup → Application → Tank config → Density → Air density

**Description** Defines the density of the air surrounding the tank.

**User entry** 0.0 to 500.0 kg/m<sup>3</sup>

**Factory setting** 1.2 kg/m<sup>3</sup>

\* Visibility depends on order options or device settings



**Additional information**

Read access	Operator
Write access	Maintenance

**Vapor density**



**Navigation**

Setup → Advanced setup → Application → Tank config → Density → Vapor density

**Description**

Defines the density of the gas phase in the tank.

**User entry**

0.0 to 500.0 kg/m<sup>3</sup>

**Factory setting**


1.2 kg/m<sup>3</sup>

**Additional information**

Read access	Operator
Write access	Maintenance

*"Pressure" submenu*

Navigation  Setup → Advanced setup → Application → Tank config → Pressure

**P1 (bottom) source** 

**Navigation**  Setup → Advanced setup → Application → Tank config → Pressure → P1 (bot) source

**Description** Defines the source of the bottom pressure (P1).

- Selection**
- Manual value
  - HART device 1 ... 15 pressure
  - AIO B1-3 value
  - AIO C1-3 value
  - AIP B4-8 value
  - AIP C4-8 value

**Factory setting** Manual value

**Additional information**

Read access	Operator
Write access	Maintenance


**P1 (bottom)**


**Navigation**  Setup → Advanced setup → Application → Tank config → Pressure → P1 (bottom)

**Description** Shows the pressure at the tank bottom.

**Additional information**

Read access	Operator
Write access	-

**P1 (bottom) manual pressure** 

**Navigation**  Setup → Advanced setup → Application → Tank config → Pressure → P1 (bot) manual

**Prerequisite** **P1 (bottom) source** (→  278) = **Manual value**

**Description** Defines the manual value of the bottom pressure (P1).

**User entry** -1.01325 to 25 bar

**Factory setting** 0 bar

**Additional information**

Read access	Operator
Write access	Maintenance

**P1 position**



**Navigation**

Setup → Advanced setup → Application → Tank config → Pressure → P1 position

**Description**

Defines the position of the bottom pressure transmitter (P1), measured from zero position (tank bottom or datum plate).

**User entry**

-10 000 to 100 000 mm

**Factory setting**

5 000 mm

**Additional information**

Read access	Operator
Write access	Maintenance

**P1 offset**



**Navigation**

Setup → Advanced setup → Application → Tank config → Pressure → P1 offset

**Description**

Offset for the bottom pressure (P1).  
The offset is added to the measured pressure prior to any tank calculation.

**User entry**

-25 to 25 bar

**Factory setting**

0 bar

**Additional information**

Read access	Operator
Write access	Maintenance

**P1 absolute / gauge**



**Navigation**

Setup → Advanced setup → Application → Tank config → Pressure → P1 absolut/  
gauge

**Description**

Defines whether the connected pressure transmitter measures an absolute or a gauge pressure.

**Selection**

- Absolute
- Gauge

**Factory setting**

Gauge

**Additional information**

Read access	Operator
Write access	Maintenance

**P3 (top) source****Navigation**

Setup → Advanced setup → Application → Tank config → Pressure → P3 (top) source

**Description**

Defines the source of the top pressure (P3).

**Selection**

- Manual value
- HART device 1 ... 15 pressure
- AIO B1-3 value
- AIO C1-3 value
- AIP B4-8 value
- AIP C4-8 value

**Factory setting**

Manual value

**Additional information**

Read access	Operator
Write access	Maintenance

**P3 (top)****Navigation**

Setup → Advanced setup → Application → Tank config → Pressure → P3 (top)

**Description**

Shows the pressure (P3) at the top transmitter.

**Additional information**

Read access	Operator
Write access	-

**P3 (top) manual pressure****Navigation**

Setup → Advanced setup → Application → Tank config → Pressure → P3 (top) manual

**Prerequisite**

**P3 (top) source** (→ 280) = **Manual value**

**Description**

Defines the manual value of the top pressure (P3).

**User entry**

-1.01325 to 25 bar

**Factory setting**

0 bar

**Additional information**

Read access	Operator
Write access	Maintenance

**P3 position**



**Navigation**

Setup → Advanced setup → Application → Tank config → Pressure → P3 position

**Description**

Defines the position of the top pressure transmitter (P3), measured from zero position (tank bottom or datum plate).

**User entry**

0 to 100 000 mm

**Factory setting**

20 000 mm

**Additional information**

Read access	Operator
Write access	Maintenance

**P3 offset**



**Navigation**

Setup → Advanced setup → Application → Tank config → Pressure → P3 offset

**Description**

Offset for the top pressure (P3).  
The offset is added to the measured pressure prior to any tank calculation.

**User entry**

-25 to 25 bar

**Factory setting**

0 bar

**Additional information**

Read access	Operator
Write access	Maintenance

**P3 absolute / gauge**



**Navigation**

Setup → Advanced setup → Application → Tank config → Pressure → P3 absolut/  
gauge

**Description**

Defines whether the connected pressure transmitter measures an absolute or a gauge pressure.

**Selection**

- Absolute
- Gauge

**Factory setting**

Gauge

**Additional information**

Read access	Operator
Write access	Maintenance

**Ambient pressure**



**Navigation**

Setup → Advanced setup → Application → Tank config → Pressure → Ambient pressure

**Description**

Defines the manual value of the ambient pressure.

**User entry**

0 to 2.5 bar


**Factory setting**

1 bar

**Additional information**

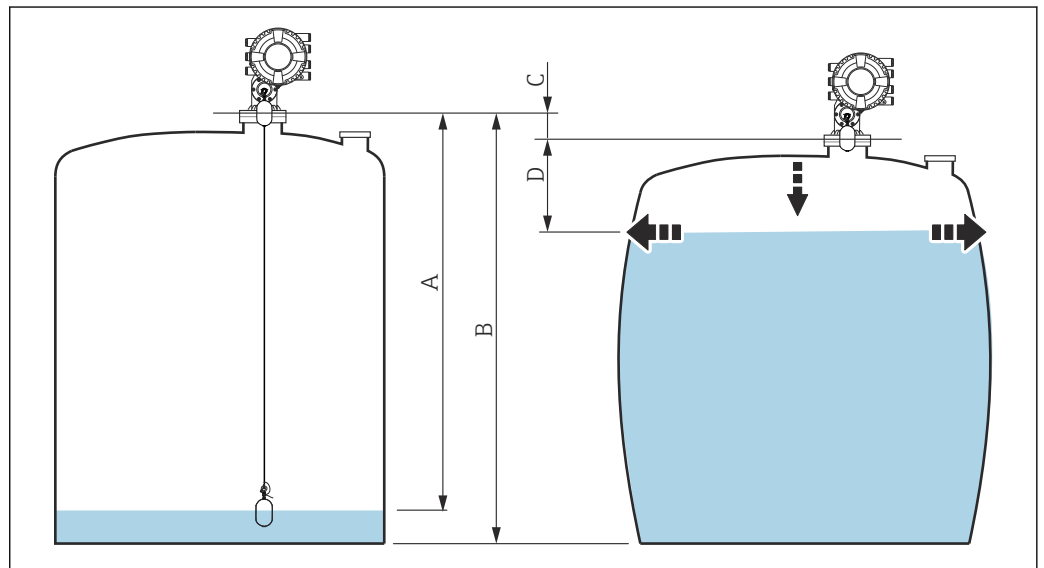
Read access	Operator
Write access	Maintenance

*"Tank calculation" submenu*


Navigation  Setup → Advanced setup → Application → Tank calculation

*"HyTD" submenu**Overview*

Hydrostatic Tank Deformation can be used to compensate the vertical movement of the Gauge Reference Height (GRH) due to bulging of the tank shell caused by the hydrostatic pressure exerted by the liquid stored in the tank. The compensation is based on a linear approximation obtained from manual hand dips at several levels distributed over the full range of the tank.



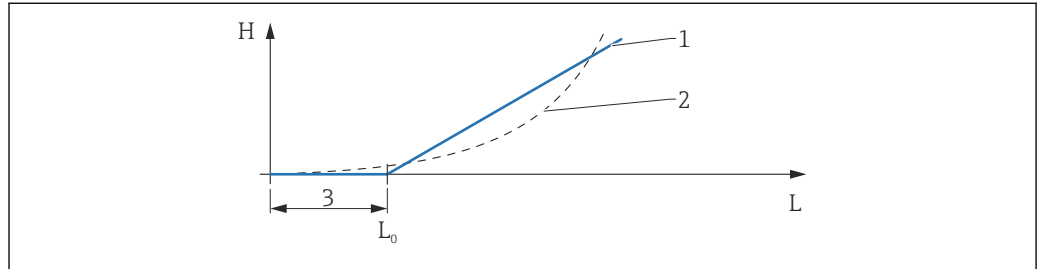
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 97 Correction of the hydrostatic tank deformation (HyTD)

- A "Distance" (level below  $L_0$  → "HyTD correction value" = 0)
- B Gauge Reference Height (GRH)
- C HyTD correction value
- D "Distance" (level above  $L_0$  → "HyTD correction value" > 0)

*Linear approximation of the HyTD correction*

The real amount of deformation varies non-linearly with the level due to the construction of the tank. However, as the correction values are typically small compared to the measured level, a simple straight line method can be used with good results.



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98 Calculation of the HyTD correction

- 1 Linear correction according to "Deformation factor (→ 286)"
- 2 Real correction
- 3 Starting level (→ 285)
- L Measured level (→ 187)
- H HyTD correction value (→ 285)

*Calculation of the HyTD correction*

$$L \leq L_0 \Rightarrow C_{HyTD} = 0$$

$$L > L_0 \Rightarrow C_{HyTD} = - (L - L_0) \times D$$

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<b>L</b>	Measured level
<b>L<sub>0</sub></b>	Starting level
<b>C<sub>HyTD</sub></b>	HyTD correction value
<b>D</b>	Deformation factor



*Description of parameters*

*Navigation*       Setup → Advanced setup → Application → Tank calculation → HyTD

**HyTD correction value**

**Navigation**       Setup → Advanced setup → Application → Tank calculation → HyTD → HyTD corr. value

**Description**      Shows the correction value from the Hydrostatic Tank Deformation.

**Additional information**

Read access	Operator
Write access	-

**HyTD mode**



**Navigation**       Setup → Advanced setup → Application → Tank calculation → HyTD → HyTD mode

**Description**      Activates or deactivates the calculation of the Hydrostatic Tank Deformation.

**Selection**       No  
 Yes


**Factory setting**      No

**Additional information**

Read access	Operator
Write access	Maintenance

**Starting level**



**Navigation**       Setup → Advanced setup → Application → Tank calculation → HyTD → Starting level

**Description**      Defines the starting level for the Hydrostatic Tank Deformation. Levels below this value are not corrected.

**User entry**      0 to 5 000 mm

**Factory setting**      500 mm

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Deformation factor**

---

**Navigation**

Setup → Advanced setup → Application → Tank calculation → HyTD → Deform factor

**Description**

Defines the deformation factor for the HyTD (change of device position per change of level).

**User entry**

-1.0 to 1.0 %

**Factory setting**

0.2 %




**Additional information**

Read access	Operator
Write access	Maintenance

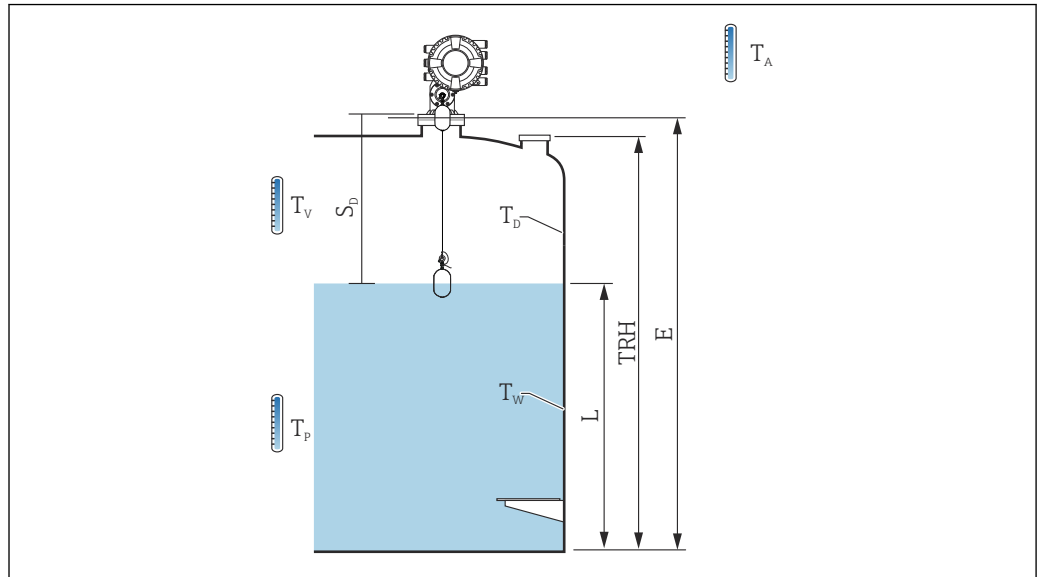
### "CTSh" submenu

#### Overview

CTSh (correction for the thermal expansion of the tank shell) compensates for effects on the Gauge Reference Height (GRH) and on the expansion or contraction of the measuring wire due to temperature effects on the tank shell or stilling well. The temperature effects are separated into two parts, respectively affecting the 'dry' and 'wetted' part of the tank shell or stilling well. The correction function is based on thermal expansion coefficients of steel and insulation factors for both the 'dry' and 'wet' parts of the wire and the tank shell. The temperatures used for the correction can be selected from on manual or measured values.

-  This correction is recommended for the following situations:
  - if the operating temperature deviates considerably from the temperature during calibration ( $\Delta T > 10\text{ °C}$  (18 °F))
  - for extremely high tanks
  - for refrigerated, cryogenic or heated applications
-  As the use of this correction will influence the innage level reading, it is recommended to ensure the manual hand dip and level verification procedures are being conducted correctly before enabling this correction method.
-  This mode cannot be used in conjunction with HTG because the level is not measured relative to the gauge reference height with HTG.

*CTSh: Calculation of the wall temperature*



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99 Parameters for the CTSh calculation

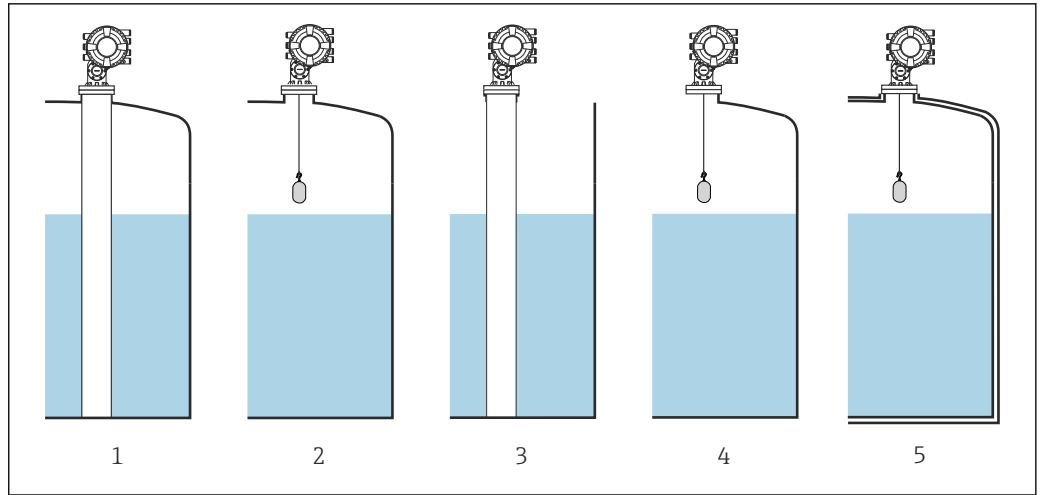
$T_W$	Temperature of the wetted part of the tank shell
$T_D$	Temperature of the dry part of the tank shell
$T_P$	Product temperature
$T_V$	Vapor temperature (in the tank)
$T_A$	Ambient temperature (atmosphere surrounding the tank)
$S_d$	Measured distance (Empty to Level)
<b>TRH</b>	Tank reference height
<b>E</b>	Empty
<b>L</b>	Level

*CTSh: Calculation of the wall temperature*

Depending on the parameters **Covered tank** (→ 290) and **Stilling well** (→ 291), the temperatures  $T_W$  of the wetted and  $T_D$  of the dry part of the tank wall are calculated as follows:

Covered tank (→ 290)	Stilling well (→ 291)	$T_W$	$T_D$
Covered	Yes <sup>1)</sup>	$T_P$	$T_V$
	No	$(7/8) T_P + (1/8) T_A$	$(1/2) T_V + (1/2) T_A$
Open top	Yes	$T_P$	$T_A$
	No	$(7/8) T_P + (1/8) T_A$	$T_A$

1) This option is also valid for insulated tanks without a stilling well. This is due to the temperature inside and outside of the tank shell being the same due to the insulation of the tank.



- 1 Covered tank (→ 290) = Covered; Stilling well (→ 291) = Yes
- 2 Covered tank (→ 290) = Covered; Stilling well (→ 291) = No
- 3 Covered tank (→ 290) = Open top; Stilling well (→ 291) = Yes
- 4 Covered tank (→ 290) = Open top; Stilling well (→ 291) = No
- 5 Insulated tank: Covered tank (→ 290) = Open top; Stilling well (→ 291) = Yes

*CTSh: Calculation of the correction*


$$C_{CTSh} = \alpha_{\text{tank}} (TRH - L)(T_D - T_{\text{cal}}) + \alpha_{\text{tank}} L (T_W - T_{\text{cal}}) - \alpha_{\text{wire}} S_D (T_V - T_{\text{cal}})$$

<b>TRH</b>	Tank reference height
<b>L</b>	Level
<b>T<sub>D</sub></b>	Temperature of the dry part of the tank shell (calculated from T <sub>P</sub> , T <sub>V</sub> and T <sub>A</sub> )
<b>T<sub>W</sub></b>	Temperature of the wetted part of the tank shell (calculated from T <sub>P</sub> , T <sub>V</sub> and T <sub>A</sub> )
<b>T<sub>cal</sub></b>	Temperature at which the measurement has been calibrated
<b>α<sub>tank</sub></b>	Linear expansion coefficient of tank
<b>α<sub>wire</sub></b>	Linear expansion coefficient of wire
<b>C<sub>CTSh</sub></b>	CTSh correction value

*Description of parameters*

**Navigation**  Setup → Advanced setup → Application → Tank calculation → CTSh

**CTSh correction value**

**Navigation**  Setup → Advanced setup → Application → Tank calculation → CTSh → CTSh corr value

**Description** Shows the CTSh correction value.

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	-

**CTSh mode**



**Navigation**  Setup → Advanced setup → Application → Tank calculation → CTSh → CTSh mode

**Description** Activates or deactivates the CTSh.

- Selection**
- No
  - Yes
  - With wire \*
  - Only wire \*

**Factory setting** No

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

**Covered tank**



**Navigation**  Setup → Advanced setup → Application → Tank calculation → CTSh → Covered tank

**Description** Determines whether the tank is covered.

- Selection**
- Open top
  - Covered


**Factory setting** Open top

\* Visibility depends on order options or device settings

**Additional information**

Read access	Operator
Write access	Maintenance

 The **Covered** option is only valid for fixed tank roofs. For a floating roof select **Open top**.

**Stilling well** 

**Navigation**

  Setup → Advanced setup → Application → Tank calculation → CTSh → Stilling well

**Description**

Determines whether the device is mounted on a stilling well.

**Selection**


- No
- Yes

**Factory setting**



No

**Additional information**

Read access	Operator
Write access	Maintenance

**Calibration temperature** 

**Navigation**

  Setup → Advanced setup → Application → Tank calculation → CTSh → Calibration temp

**Description**

Specify temperature at which the measurement has been calibrated.

**User entry**


-50 to 250 °C

**Factory setting**



25 °C

**Additional information**

Read access	Operator
Write access	Maintenance

**Linear expansion coefficient** 

**Navigation**

  Setup → Advanced setup → Application → Tank calculation → CTSh → Linear exp coeff

**Description**

Defines the linear expansion coefficient of the tank shell material.

**User entry**

0 to 100 ppm

**Factory setting**

15 ppm

**Additional information**

Read access	Operator
Write access	Maintenance

**Wire expansion coefficient****Navigation**

Setup → Advanced setup → Application → Tank calculation → CTSh → Wire exp coeff

**Description**

Defines the expansion coefficient of the wire material of the drum. Value is programmed in factory.

**User entry**

0 to 100 ppm

**Factory setting**

15 ppm

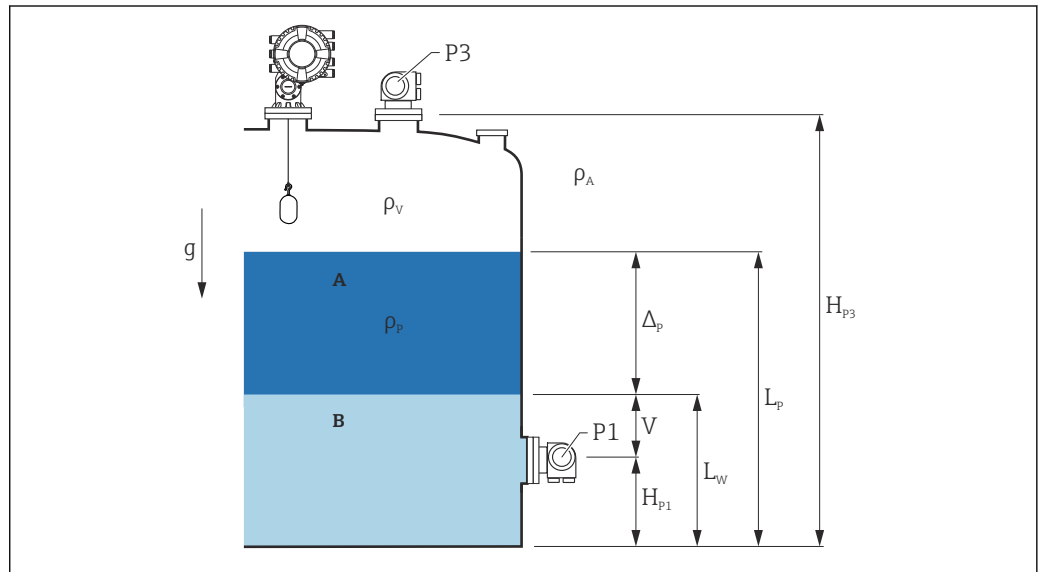


"HTMS" submenu

Overview

The Hybrid Tank Measurement System (HTMS) is a method to calculate the density of a product in a tank based on both a (top mounted) level and at least one (bottom mounted) pressure measurement. An additional pressure sensor can be installed at the top of the tank to provide information about the vapor pressure and to make the density calculation more accurate. The calculation method also takes into account a possible level of water at the bottom of the tank to make density calculations as accurate as possible.

HTMS parameters



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
100 HTMS parameters


- A Product
- B Water


Parameter	Navigation path
P1 (Bottom pressure)	Setup → Advanced setup → Tank configuration → Pressure → P1 (bottom)
$H_{P1}$ (Position of P1 transmitter)	Setup → Advanced setup → Tank configuration → Pressure → P1 position
P3 (Top pressure)	Setup → Advanced setup → Tank configuration → Pressure → P3 (top)
$H_{P3}$ (Position of P3 transmitter)	Setup → Advanced setup → Tank configuration → Pressure → P3 position
$\rho_p$ (Density of the product <sup>1)</sup> )	<ul style="list-style-type: none"> <li>■ Measured value: Setup → Advanced setup → Calculation → HTMS → Density value</li> <li>■ User-defined value: Setup → Advanced setup → Calculation → HTMS → Manual upper density</li> </ul>
$\rho_v$ (Vapor density)	Expert → Application → Tank configuration → Density → Vapor density
$\rho_A$ (Ambient air temperature)	Setup → Advanced setup → Tank configuration → Density → Air density
g (Local gravity)	Expert → Application → Tank Calculation → Local gravity
$L_p$ (Level of the product)	Operation → Tank level
$L_w$ (Bottom water level)	Operation → Water level
$V = L_w - H_{P1}$	
$\Delta_p = L_p - L_w = L_p - V - H_{P1}$	

1) Depending on the situation this parameter is measured or a user-defined value is used.

*HTMS modes*

Two HTMS modes can be selected in the **HTMS mode** parameter (→  295). The mode determines whether one or two pressure values are used. Depending on the selected mode a number of additional parameters are required for the calculation of the product density.

 The **HTMS P1+P3** option must be used in pressurized tanks in order to compensate for the pressure of the vapor phase.

HTMS mode (→  295)	Measured variables	Required additional parameters	Calculated variables
HTMS P1	<ul style="list-style-type: none"> <li>▪ P<sub>1</sub></li> <li>▪ L<sub>p</sub></li> </ul>	<ul style="list-style-type: none"> <li>▪ g</li> <li>▪ H<sub>p1</sub></li> <li>▪ L<sub>w</sub> (optional)</li> </ul>	ρ <sub>p</sub>
HTMS P1+P3	<ul style="list-style-type: none"> <li>▪ P<sub>1</sub></li> <li>▪ P<sub>3</sub></li> <li>▪ L<sub>p</sub></li> </ul>	<ul style="list-style-type: none"> <li>▪ ρ<sub>v</sub></li> <li>▪ ρ<sub>a</sub></li> <li>▪ g</li> <li>▪ H<sub>p1</sub></li> <li>▪ H<sub>p3</sub></li> <li>▪ L<sub>w</sub> (optional)</li> </ul>	ρ <sub>p</sub> (more precise calculation for pressurized tanks)

*Minimum level*

The density of the product can only be calculated if the product has a minimum thickness :


$$\Delta_p \geq \Delta_{p, \min}$$

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This is equivalent to the following condition for the product level:

$$L_p - V \geq \Delta_{p, \min} + H_{p1} = L_{\min}$$


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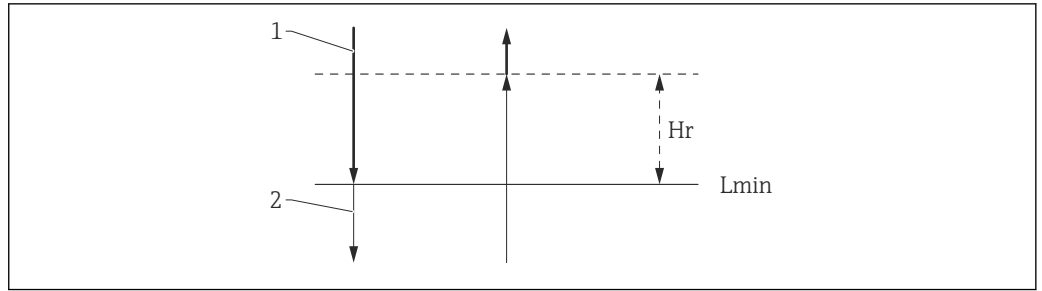
L<sub>min</sub> is defined in the **Minimum level** parameter (→  296). As can be seen from the formula it always must be bigger than H<sub>p1</sub>.

If L<sub>p</sub> - V falls below this limit, the density is calculated as follows:

- If a previous calculated value is available, this value will be kept as long as no new calculation is possible.
- If no value was previously calculated, the manual value (defined in the **Manual upper density** parameter) will be used.

*Hysteresis*

The level of the product in a tank is not constant but slightly varies, due for example to filling disturbances. If the level oscillates around the changeover level (**Minimum level** (→  296)), the algorithm will constantly switch between calculating the value and holding the previous result. To avoid this effect a positional hysteresis is defined around the changeover point.



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101 HTMS hysteresis

- 1 Value calculated
- 2 Value held/manual
- $L_{min}$  Minimum level (→ 296)
- $H_r$  Hysteresis (→ 297)

Description of parameters

Navigation Setup → Advanced setup → Application → Tank calculation → HTMS

HTMS mode

<b>Navigation</b>	Setup → Advanced setup → Application → Tank calculation → HTMS → HTMS mode				
<b>Description</b>	Defines the HTMS mode. Depending on the mode one or two pressure transmitters are used.				
<b>Selection</b>	<ul style="list-style-type: none"> <li>■ HTMS P1</li> <li>■ HTMS P1+P3</li> </ul>				
<b>Factory setting</b>	HTMS P1				
<b>Additional information</b>	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="padding: 2px;">Read access</td> <td style="padding: 2px;">Operator</td> </tr> <tr> <td style="padding: 2px;">Write access</td> <td style="padding: 2px;">Maintenance</td> </tr> </table>	Read access	Operator	Write access	Maintenance
Read access	Operator				
Write access	Maintenance				

Meaning of the options

- HTMS P1  
Only a bottom pressure transmitter (P1) is used.
- HTMS P1+P3  
A bottom (P1) and top (P3) pressure transmitter are used. This option should be selected for pressurized tanks.

Manual density

<b>Navigation</b>	Setup → Advanced setup → Application → Tank calculation → HTMS → Manual density
<b>Description</b>	Defines the manual density.

**User entry** 0 to 3 000 kg/m<sup>3</sup>

**Factory setting** 800 kg/m<sup>3</sup>

**Additional information**

<b>Read access</b>	Maintenance
<b>Write access</b>	Maintenance

---

**Density value**

---

**Navigation**  Setup → Advanced setup → Application → Tank calculation → HTMS → Density value

**Description** Shows the calculated product density.

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	-

---

**Minimum level**

---



**Navigation**  Setup → Advanced setup → Application → Tank calculation → HTMS → Min. level

**Description** Defines the minimum product level for a HTMS calculation.  
If Lp - V falls below the limit defined in this parameter, the density retains its last value or the manual value is used instead.

**User entry** 0 to 20 000 mm

**Factory setting** 7 000 mm

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

---

**Minimum pressure**

---



**Navigation**  Setup → Advanced setup → Application → Tank calculation → HTMS → Minimum pressure

**Description** Defines the minimum pressure for a HTMS calculation.  
If the pressure P1 (or the difference P1 - P3) falls below the limit defined in this parameter, the density retains its last value or the manual value is used instead.

**User entry** 0 to 100 bar

**Factory setting** 0.1 bar

**Additional information**

Read access	Operator
Write access	Maintenance

**Safety distance**



**Navigation**

Setup → Advanced setup → Application → Tank calculation → HTMS → Safety distance

**Description**

Defines the minimum level which must be present above the bottom pressure sensor before its signal is used for the calculation.

**User entry**

0 to 10 000 mm

**Factory setting**

2 000 mm

**Additional information**

Read access	Operator
Write access	Maintenance

**Hysteresis**



**Navigation**

Setup → Advanced setup → Application → Tank calculation → HTMS → Hysteresis

**Description**

Defines the hysteresis for the HTMS calculation. Prevents constant switching if the level is near the switch-over point.

**User entry**

0 to 2 000 mm

**Factory setting**

50 mm

**Additional information**

Read access	Operator
Write access	Maintenance

**Water density**



**Navigation**

Setup → Advanced setup → Application → Tank calculation → HTMS → Water density

**Description**

Density of the water in the tank.

**User entry**

Signed floating-point number

**Factory setting**

1 000 kg/m<sup>3</sup>

**Additional information**

















Read access	Operator
Write access	Maintenance



*"Alarm" submenu*

*Navigation*       Setup → Advanced setup → Application → Alarm

*"Alarm" submenu*

*Navigation*       Setup → Advanced setup → Application → Alarm → Alarm


<b>▶ Alarm</b>	
Alarm mode	→  299
Error value	→  300
Alarm value source	→  301
Alarm value	→  302
HH alarm value	→  302
H alarm value	→  302
L alarm value	→  303
LL alarm value	→  303
HH alarm	→  303
H alarm	→  304
HH+H alarm	→  304
L alarm	→  304
LL alarm	→  304
LL+L alarm	→  305
Any error	→  305
Clear alarm	→  305

Alarm hysteresis	→  306
Damping factor	→  306

**Alarm mode**



**Navigation**

  Setup → Advanced setup → Application → Alarm → Alarm → Alarm mode

**Description**

Defines the alarm mode of the selected alarm.

**Selection**

- Off
- On
- Latching


**Factory setting**

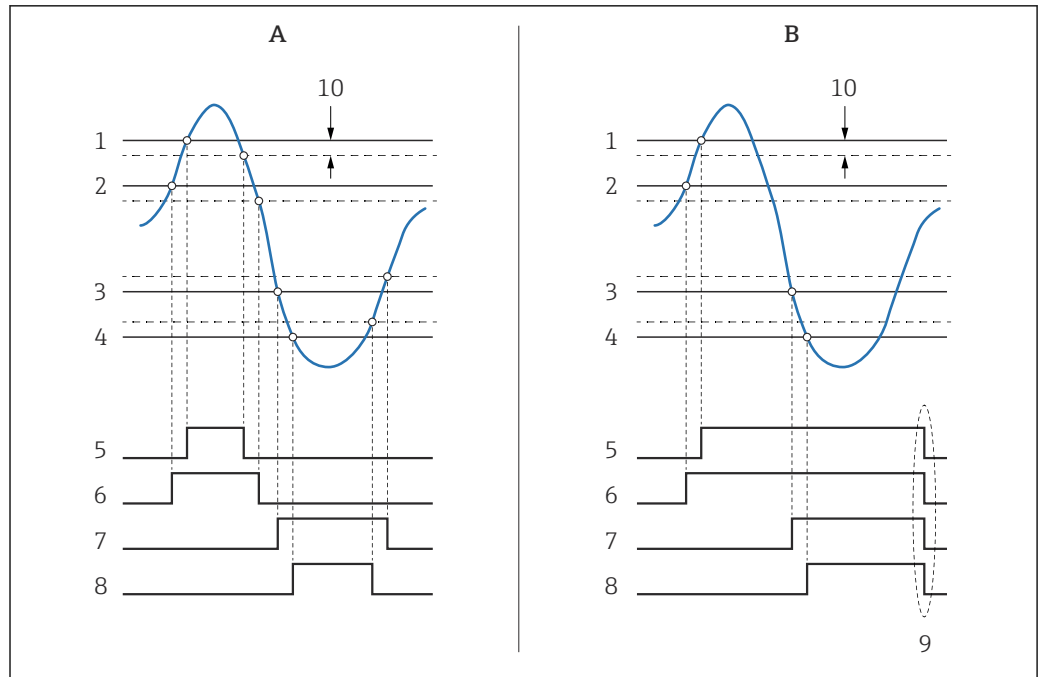
Off

**Additional information**

Read access	Operator
Write access	Maintenance

*Meaning of the options*

- **Off**  
No alarms are generated.
- **On**  
An alarm disappears if the alarm condition is no longer present (taking into consideration the hysteresis).
- **Latching**  
All alarms remain active until the user selects **Clear alarm** (→  305) = **Yes** or the power is switched off and on.



A0029539

102 Principle of the limit evaluation

- A Alarm mode (→ 299) = On
- B Alarm mode (→ 299) = Latching
- 1 HH alarm value (→ 302)
- 2 H alarm value (→ 302)
- 3 L alarm value (→ 303)
- 4 LL alarm value (→ 303)
- 5 HH alarm (→ 303)
- 6 H alarm (→ 304)
- 7 L alarm (→ 304)
- 8 LL alarm (→ 304)
- 9 "Clear alarm (→ 305)" = "Yes" or power off-on
- 10 Hysteresis (→ 306)

Error value



Navigation

Setup → Advanced setup → Application → Alarm → Alarm → Error value

Prerequisite

Alarm mode (→ 299) ≠ Off

Description

Defines the alarm to be issued if the input value is invalid.

Selection

- No alarm
- HH+H alarm
- H alarm
- L alarm
- LL+L alarm
- All alarms

Factory setting

All alarms

Additional information

Read access	Operator
Write access	Maintenance



**Alarm value source**



**Navigation** Setup → Advanced setup → Application → Alarm → Alarm → Alarm source

**Prerequisite** **Alarm mode (→ 299) ≠ Off**

**Description** Determines the process variable to be monitored.


- Selection**
- Tank level
  - Liquid temperature
  - Vapor temperature
  - Water level
  - P1 (bottom)
  - P2 (middle)
  - P3 (top)
  - Observed density value
  - Volume
  - Flow velocity
  - Volume flow
  - Vapor density
  - Middle density
  - Upper density
  - Correction
  - Tank level %
  - GP 1...4 value
  - Measured level
  - P3 position
  - Tank reference height
  - Local gravity
  - P1 position
  - Manual density
  - Tank ullage
  - Average profile density
  - Lower density
  - Upper interface level
  - Lower interface level
  - Bottom level
  - Displacer position
  - HART device 1...15 PV
  - HART device 1...15 SV
  - HART device 1...15 TV
  - HART device 1...15 QV
  - HART device 1...15 PV mA
  - HART device 1...15 PV %
  - Element temperature 1...24
  - AIO B1-3 value
  - AIO C1-3 value
  - AIP B4-8 value
  - AIP C4-8 value
  - None


**Factory setting** None

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

**Alarm value**

**Navigation**  Setup → Advanced setup → Application → Alarm → Alarm → Alarm value

**Prerequisite** **Alarm mode (→  299) ≠ Off**

**Description** Shows the current value of the process variable being monitored.

**User interface** Signed floating-point number


**Factory setting** 0 None


**Additional information**

Read access	Operator
Write access	-

**HH alarm value**



**Navigation**  Setup → Advanced setup → Application → Alarm → Alarm → HH alarm value

**Prerequisite** **Alarm mode (→  299) ≠ Off**

**Description** Defines the high-high(HH) limit value.

**User entry** Signed floating-point number


**Factory setting** 0 None

**Additional information**

Read access	Operator
Write access	Maintenance

**H alarm value**



**Navigation**  Setup → Advanced setup → Application → Alarm → Alarm → H alarm value

**Prerequisite** **Alarm mode (→  299) ≠ Off**

**Description** Defines the high(H) limit value.

**User entry** Signed floating-point number

**Factory setting** 0 None

**Additional information**

Read access	Operator
Write access	Maintenance

**L alarm value**



**Navigation** Setup → Advanced setup → Application → Alarm → Alarm → L alarm value

**Prerequisite** **Alarm mode (→ 299) ≠ Off**

**Description** Defines the low limit value.

**User entry** Signed floating-point number

**Factory setting** 0 None

**Additional information**

Read access	Operator
Write access	Maintenance

**LL alarm value**



**Navigation** Setup → Advanced setup → Application → Alarm → Alarm → LL alarm value

**Prerequisite** **Alarm mode (→ 299) ≠ Off**

**Description** Defines the low-low(LL) limit value.

**User entry** Signed floating-point number

**Factory setting** 0 None

**Additional information**

Read access	Operator
Write access	Maintenance

**HH alarm**

**Navigation** Setup → Advanced setup → Application → Alarm → Alarm → HH alarm

**Prerequisite** **Alarm mode (→ 299) ≠ Off**

**Description** Shows whether an HH alarm is currently active.

**Additional information**


Read access	Operator
Write access	-

---

**H alarm**


---

**Navigation**  Setup → Advanced setup → Application → Alarm → Alarm → H alarm

**Prerequisite** **Alarm mode (→  299) ≠ Off**

**Description** Shows whether an H alarm is currently active.


**Additional information**


Read access	Operator
Write access	-

---

**HH+H alarm**


---

**Navigation**  Setup → Advanced setup → Application → Alarm → Alarm → HH+H alarm

**Prerequisite** **Alarm mode (→  299) ≠ Off**

**Description** Shows whether an HH or H alarm is currently active.

**Additional information**

Read access	Operator
Write access	-

---

**L alarm**


---

**Navigation**  Setup → Advanced setup → Application → Alarm → Alarm → L alarm

**Prerequisite** **Alarm mode (→  299) ≠ Off**

**Description** Shows whether an L alarm is currently active.


**Additional information**

Read access	Operator
Write access	-

---

**LL alarm**


---

**Navigation**  Setup → Advanced setup → Application → Alarm → Alarm → LL alarm

**Prerequisite** **Alarm mode (→  299) ≠ Off**

**Description** Shows whether an LL alarm is currently active.


**Additional information**

Read access	Operator
Write access	-

**LL+L alarm****Navigation**

  Setup → Advanced setup → Application → Alarm → Alarm → LL+L alarm

**Prerequisite**

**Alarm mode (→  299) ≠ Off**



**Description**

Shows whether an LL or L alarm is currently active.


**Additional information**

Read access	Operator
Write access	-

**Any error****Navigation**

  Setup → Advanced setup → Application → Alarm → Alarm → Any error

**Prerequisite**

**Alarm mode (→  299) ≠ Off**

**Description**

Show whether any alarm is currently active.

**User interface**

- Unknown
- Inactive
- Active
- Error

**Factory setting**

Unknown

**Additional information**

Read access	Operator
Write access	-

**Clear alarm****Navigation**

  Setup → Advanced setup → Application → Alarm → Alarm → Clear alarm

**Prerequisite**

**Alarm mode (→  299) = Latching**

**Description**

Deletes an alarm which is still active although the alarm condition is no longer present.

**Selection**

- No
- Yes

**Factory setting**

No

**Additional information**

Read access	Operator
Write access	Maintenance

**Alarm hysteresis**



**Navigation**

Setup → Advanced setup → Application → Alarm → Alarm → Alarm hysteresis

**Prerequisite**

**Alarm mode** (→ 299) ≠ Off

**Description**

Defines the hysteresis for the limit values. The hysteresis prevents constant changes of the alarm state if the level is near one of the limit values.

**User entry**

Signed floating-point number

**Factory setting**

0.001

**Additional information**

Read access	Maintenance
Write access	Maintenance

**Damping factor**



**Navigation**

Setup → Advanced setup → Application → Alarm → Alarm → Damping factor

**Description**

Defines the damping constant (in seconds).

**User entry**

0 to 999.9 s


**Factory setting**


0 s

**Additional information**

Read access	Operator
Write access	Maintenance

**"Safety settings" submenu**

Navigation  Setup → Advanced setup → Safety settings

**Output out of range** 

**Navigation**  Setup → Advanced setup → Safety settings → Output out range


**Description** Selection of behavior between Alarm or Last valid value when displacer reached HighStoplevel, LowStopLevel or ReferencePosition.

- Selection**
- Last valid value
  - Alarm
  - None


**Factory setting** Last valid value

**Additional information**

Read access	Operator
Write access	Maintenance

**Output out of range** 

**Navigation**  Setup → Advanced setup → Safety settings → Output out range


**Description** Selection of behavior when displacer reached **High stop level** (→  201), **Low stop level** or **Reference position**.

- Selection**
- Last valid value
  - Alarm
  - None

**Factory setting** Last valid value

**Additional information**

Read access	Operator
Write access	Maintenance

**High stop level** 

**Navigation**  Setup → Advanced setup → Safety settings → High stop level

**Description** Position of the displacer high stop as measured from defined zero position (tank bottom or datum plate).

**User entry** -999 999.9 to 999 999.9 mm

**Factory setting** Dependent on the device version

**Additional information**

Read access	Operator
Write access	Maintenance

**Low stop level****Navigation**

Setup → Advanced setup → Safety settings → Low stop level

**Description**

Position of the displacer low stop as measured from defined zero position (tank bottom or datum plate).

**User entry**

-999 999.9 to 999 999.9 mm

**Factory setting**

0 mm

**Additional information**

Read access	Operator
Write access	Maintenance

**Slow hoist zone****Navigation**

Setup → Advanced setup → Safety settings → Slow hoist zone

**Description**

Defines the interval in millimeters, measured down from the Reference Position, in which the Displacer reduces moving speed.

**User entry**

10 to 999 999.9 mm

**Factory setting**

70 mm

**Additional information**

Read access	Operator
Write access	Maintenance

**Overtension weight****Navigation**

Setup → Advanced setup → Safety settings → Overtension wgt

**Description**

Sets the minimum Weight in grams when Overtension Alarm will be set.

**User entry**

100 to 999.9 g

**Factory setting**

350 g



**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

**Undertension weight**



**Navigation**

Setup → Advanced setup → Safety settings → Undertension wgt

**Description**

Defines the undertension error weight. Undertension error will be issued if displacer weight is below this value longer than 7 seconds.

**User entry**

0 to 300 g


**Factory setting**

10 g


**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

**"Sensor config" submenu**


*Navigation*       Setup → Advanced setup → Sensor config

---

**Post gauge command** 

---

**Navigation**

 Setup → Advanced setup → Sensor config → Post gauge cmd

**Description**

Defines the gauge command that will be executed after a one-time gauge command has finished.

**Selection**

- Stop
- Level
- Up
- Upper I/F level
- Lower I/F level
- None

**Factory setting**


Level

**Additional information**

Read access	Operator
Write access	Maintenance

*"Displacer" submenu*

Navigation  Setup → Advanced setup → Sensor config → Displacer

**Displacer type** 

**Navigation**  Setup → Advanced setup → Sensor config → Displacer → Displacer type

**Description** Chooses the type of displacer used.


- Selection**
- Custom diameter
  - Diameter 30 mm
  - Diameter 50 mm
  - Diameter 70 mm
  - Diameter 110 mm

**Factory setting** Dependent on the device version

**Additional information**

Read access	Operator
Write access	Maintenance

**Displacer diameter** 

**Navigation**  Setup → Advanced setup → Sensor config → Displacer → Displacer diamet

**Prerequisite** **Displacer type (→  311) = Custom diameter**

**Description** Sets the diameter of the cylindrical part of displacer.


**User entry** 0 to 999.9 mm

**Factory setting** See label on the device.

**Additional information**

Read access	Operator
Write access	Maintenance

**Displacer weight** 

**Navigation**  Setup → Advanced setup → Sensor config → Displacer → Displacer weight

**Description** Set the weight of the displacer in air. Indicated on the displacer in grams.

**User entry** 10 to 999.9 g

**Factory setting** See label on the device.

**Additional information**

Read access	Operator
Write access	Maintenance

**Displacer volume****Navigation**

Setup → Advanced setup → Sensor config → Displacer → Displacer volume

**Description**

Displacer volume indicated on displacer in milliliter.

**User entry**

10 to 999.9 ml

**Factory setting**

See label on the device.

**Additional information**

Read access	Operator
Write access	Maintenance

**Displacer balance volume****Navigation**

Setup → Advanced setup → Sensor config → Displacer → Balance volume

**Description**

Defines the balance volume of the displacer as the lower part of displacer immersed in liquid. Units in milliliters. Indicated on displacer.

**User entry**

10 to 999.9 ml

**Factory setting**

See label on the device.

**Additional information**

Read access	Operator
Write access	Maintenance

**Displacer height****Navigation**

Setup → Advanced setup → Sensor config → Displacer → Displacer height

**Description**

Sets the displacer height in mm. Used for density measurement as minimum distance between last profile point and liquid level.

**User entry**

10 to 300 mm

**Factory setting**

Dependent on the device version

**Additional information**

Read access	Operator
Write access	Maintenance

**Immersion depth**



**Navigation**                      Setup → Advanced setup → Sensor config → Displacer → Immersion depth

**Description**                      Defines distance (mm) from displacer bottom to balancing line defined by balanced volume. Value is needed for correct bottom level measurement.

**User entry**                        0 to 99.9 mm

**Factory setting**                      Dependent on the device version


**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance


*"Wiredrum" submenu*

Navigation  Setup → Advanced setup → Sensor config → Wiredrum

---

**Drum circumference** 

---

**Navigation**  Setup → Advanced setup → Sensor config → Wiredrum → Drum circumfer

**Description** Sets the circumference of the wire drum. Indicated in Label.


**User entry** 100 to 999.9 mm

**Factory setting** See label on the device.


**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

---

**Wire weight** 

---

**Navigation**  Setup → Advanced setup → Sensor config → Wiredrum → Wire weight

**Description** Defines the weight of the measuring wire in g/10m. Indicated on Label.

**User entry** 0 to 999.9 g


**Factory setting** See label on the device.


**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

*"Spot density" submenu*

Navigation  Setup → Advanced setup → Sensor config → Spot density

**Upper density offset** 

**Navigation**  Setup → Advanced setup → Sensor config → Spot density → Up dens. offset


**Description** Defines an offset value which is added to the measured upper density value.


**User entry** -999.99 to 999.99 kg/m<sup>3</sup>

**Factory setting** 0 kg/m<sup>3</sup>

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

**Middle density offset** 

**Navigation**  Setup → Advanced setup → Sensor config → Spot density → Mid dens. offset


**Description** Defines an Offset Value which is added to the measured Middle Density Value.


**User entry** -999.99 to 999.99 kg/m<sup>3</sup>

**Factory setting** 0 kg/m<sup>3</sup>

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

**Lower density offset** 

**Navigation**  Setup → Advanced setup → Sensor config → Spot density → Low dens. offset

**Description** Defines an offset value which is added to the measured lower density value.

**User entry** -999.99 to 999.99 kg/m<sup>3</sup>

**Factory setting** 0 kg/m<sup>3</sup>

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

---

**Submersion depth**

---

**Navigation**

Setup → Advanced setup → Sensor config → Spot density → Submersion depth

**Description**

Sets the displacer submersion depth (mm) for spot density operations.

**User entry**

50 to 99 999.9 mm

**Factory setting**


150 mm

**Additional information**

Read access	Operator
Write access	Maintenance




*"Profile density" submenu*

Navigation  Setup → Advanced setup → Sensor config → Profile density

---

**Density measurement mode** 

---

**Navigation**  Setup → Advanced setup → Sensor config → Profile density → Density mode


**Description** In normal measure mode, measures at specified positions. In compensation mode measures using next integer value of drum turns to improve accuracy.

- Selection**
- Normal measure mode
  - Compensation mode

**Factory setting** Normal measure mode

**Additional information**


Read access	Operator
Write access	Maintenance

 In normal mode, measures spot densities at requested positions. In compensations mode the Proservo measures the spot densities at multiples of the wiredrum circumference (e.g. every ~ 150 mm (5.91 in))

---

**Manual profile level** 

---

**Navigation**  Setup → Advanced setup → Sensor config → Profile density → Man profile lvl

**Description** Sets the level position in the tank where the manual profile density operation starts.

**User entry** -999 999.9 to 999 999.9 mm

**Factory setting** 1 000 mm


**Additional information**

Read access	Operator
Write access	Maintenance

---

**Profile density offset distance** 

---

**Navigation**  Setup → Advanced setup → Sensor config → Profile density → Dens offset dist

**Description** Profile density offset distance [mm] is the distance between start point and first measurement point.

**User entry** 0 to 999 999.9 mm

**Factory setting** 500 mm

**Additional information**

Read access	Operator
Write access	Maintenance

**Profile density interval**



**Navigation**

Setup → Advanced setup → Sensor config → Profile density → Density interval

**Description**

Sets the interval between two measurement points in profile density operation.

**User entry**

1 to 100 000 mm

**Factory setting**

1 000 mm

**Additional information**

Read access	Operator
Write access	Maintenance

**Profile density offset**



**Navigation**

Setup → Advanced setup → Sensor config → Profile density → Prof dens offset

**Description**

Defines an offset value which is added to the measured profile density value.

**User entry**

-999.99 to 999.99 kg/m<sup>3</sup>

**Factory setting**

0 kg/m<sup>3</sup>

**Additional information**

Read access	Operator
Write access	Maintenance

**"Display" submenu**


This menu is only visible if the device has a local display.

*Navigation*       Setup → Advanced setup → Display

---

**Language**

---

**Navigation**       Setup → Advanced setup → Display → Language

**Prerequisite**      The device has a local display.

**Description**      Set display language.

- Selection**
- English
  - Deutsch
  - русский язык (Russian)
  - 日本語 (Japanese)
  - Español
  - 中文 (Chinese)

**Factory setting**      English


**Additional information**

Read access	Operator
Write access	Operator

---

**Format display**

---

**Navigation**       Setup → Advanced setup → Display → Format display

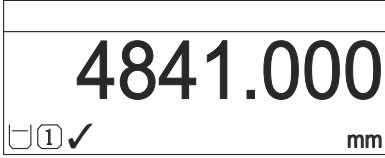
**Prerequisite**      The device has a local display.

**Description**      Select how measured values are shown on the display.

- Selection**
- 1 value, max. size
  - 1 bargraph + 1 value
  - 2 values
  - 1 value large + 2 values
  - 4 values

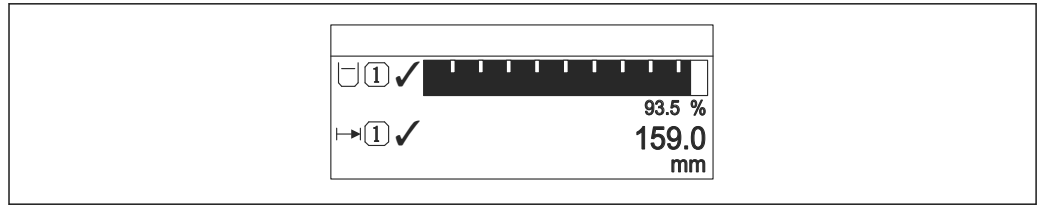
**Factory setting**      2 values

**Additional information**



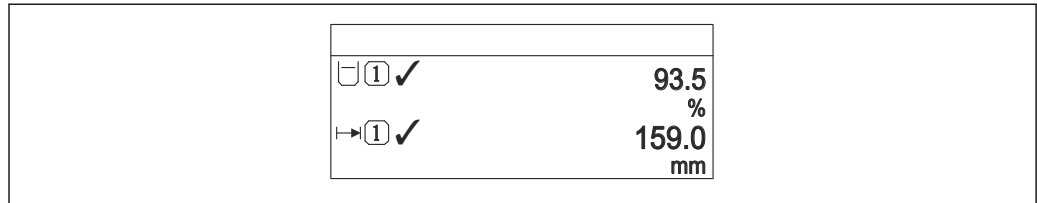
 103 "Format display" = "1 value, max. size"

A0019963



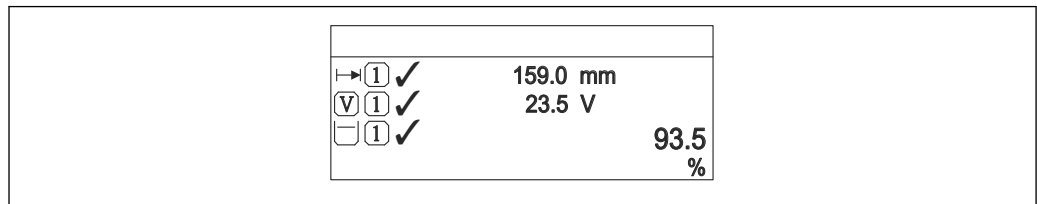
A0019964

104 "Format display" = "1 bargraph + 1 value"



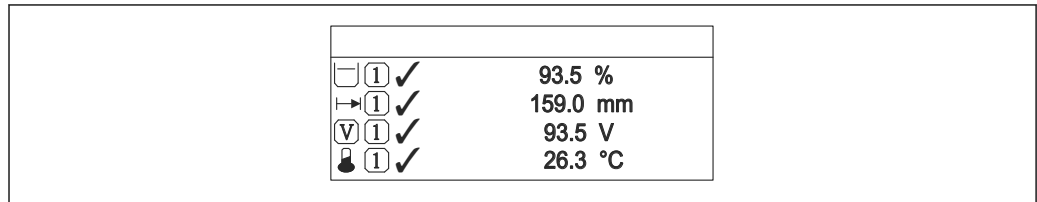
A0019965

105 "Format display" = "2 values"



A0019966

106 "Format display" = "1 value large + 2 values"



A0019968

107 "Format display" = "4 values"

Read access	Operator
Write access	Operator

- The **Value 1 to 4 display** (→ 320) parameters specify which measured values are shown on the display and in which order.
- If more measured values are specified than the current display mode permits, the values alternate on the device display. The display time until the next change is configured in the **Display interval** parameter (→ 323).

Value 1 to 4 display



Navigation

Setup → Advanced setup → Display → Value 1 display

Prerequisite

The device has a local display.

**Description** Select the measured value that is shown on the local display.

- Selection**
- None <sup>9)</sup>
  - Tank level
  - Measured level
  - Level linearized
  - Tank level %
  - Water level <sup>9)</sup>
  - Liquid temperature <sup>9)</sup>
  - Vapor temperature <sup>9)</sup>
  - Air temperature <sup>9)</sup>
  - Tank ullage
  - Tank ullage %
  - Observed density value <sup>9)</sup>
  - P1 (bottom) <sup>9)</sup>
  - P2 (middle) <sup>9)</sup>
  - P3 (top) <sup>9)</sup>
  - GP 1 value <sup>9)</sup>
  - GP 2 value <sup>9)</sup>
  - GP 3 value <sup>9)</sup>
  - GP 4 value <sup>9)</sup>
  - Gauge command <sup>9)</sup>
  - Gauge status <sup>9)</sup>
  - AIO B1-3 value <sup>9)</sup>
  - AIO B1-3 value mA <sup>9)</sup>
  - AIO B1-3 value % <sup>9)</sup>
  - AIO C1-3 value <sup>9)</sup>
  - AIO C1-3 value mA <sup>9)</sup>
  - AIO C1-3 value % <sup>9)</sup>
  - AIP B4-8 value <sup>9)</sup>
  - AIP B4-8 value mA <sup>9)</sup>
  - AIP B4-8 value % <sup>9)</sup>
  - AIP C4-8 value <sup>9)</sup>
  - AIP C4-8 value mA <sup>9)</sup>
  - AIP C4-8 value % <sup>9)</sup>

**Factory setting** Depending on device version

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Decimal places 1 to 4**



**Navigation** Setup → Advanced setup → Display → Decimal places 1

**Prerequisite** The device has a local display.


**Description** This selection does not affect the measurement and calculation accuracy of the device.

---

<sup>9)</sup> not available for the **Value 1 display** parameter


- Selection**
- X
  - X.X
  - X.XX
  - X.XXX
  - X.XXXX



**Factory setting** x.x

**Additional information**  The setting does not affect the measuring or computational accuracy of the device.

Read access	Operator
Write access	Maintenance

---

**Separator** 

**Navigation**   Setup → Advanced setup → Display → Separator

**Prerequisite** The device has a local display.

**Description** Select decimal separator for displaying numerical values.

- Selection**
- .
  - ,



**Factory setting** .

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Number format** 

**Navigation**   Setup → Advanced setup → Display → Number format

**Prerequisite** The device has a local display.


**Description** Choose number format for the display.

- Selection**
- Decimal
  - ft-in-1/16"

**Factory setting** Decimal

**Additional information**

Read access	Operator
Write access	Maintenance

 The **ft-in-1/16"** option is only valid for distance values.

**Header**



**Navigation** Setup → Advanced setup → Display → Header

**Prerequisite** The device has a local display.

**Description** Select header contents on local display.

**Selection**

- Device tag
- Free text

**Factory setting** Device tag

**Additional information**

Read access	Operator
Write access	Maintenance

**Meaning of the options**

- **Device tag**  
The header contents is defined in the **Device tag** parameter (→ 197).
- **Free text**  
The header contents is defined in the **Header text** parameter (→ 323).

**Header text**



**Navigation** Setup → Advanced setup → Display → Header text

**Prerequisite** **Header** (→ 323) = **Free text**

**Description** Enter display header text.

**User entry** Character string comprising numbers, letters and special characters (11)

**Factory setting** TG-Platform

**Additional information**

Read access	Operator
Write access	Maintenance

**Display interval**

**Navigation** Setup → Advanced setup → Display → Display interval

**Description** Set time measured values are shown on display if display alternates between values.

**User entry** 1 to 10 s

**Factory setting** 5 s

**Additional information**

This parameter is only relevant if the number of selected measuring values exceeds the number of values the selected display format can display simultaneously.

Read access	Operator
Write access	Operator

**Display damping****Navigation**

Setup → Advanced setup → Display → Display damping

**Prerequisite**

The device has a local display.

**Description**

Set display reaction time to fluctuations in the measured value.

**User entry**

0.0 to 999.9 s

**Factory setting**

0.0 s

**Additional information**

Read access	Operator
Write access	Maintenance

**Backlight****Navigation**

Setup → Advanced setup → Display → Backlight

**Prerequisite**

The device has a local display.

**Description**

Switch the local display backlight on and off.

**Selection**

- Disable
- Enable

**Factory setting**

Enable

**Additional information**

Read access	Operator
Write access	Operator

**Contrast display****Navigation**

Setup → Advanced setup → Display → Contrast display

**Prerequisite**

The device has a local display.

**Description**

Adjust local display contrast setting to ambient conditions (e.g. lighting or reading angle)




**User entry**                    20 to 80 %

**Factory setting**            30 %


**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Operator

**"System units" submenu**

Navigation  Setup → Advanced setup → System units

**Units preset** 

**Navigation**  Setup → Advanced setup → System units → Units preset

**Description** Defines a set of units for length, pressure and temperature.




- Selection**
- mm, bar, °C
  - m, bar, °C
  - mm, PSI, °C
  - ft, PSI, °F
  - ft-in-16, PSI, °F
  - ft-in-8, PSI, °F
  - Customer value

**Factory setting** mm, bar, °C


**Additional information**

Read access	Operator
Write access	Maintenance

If the **Customer value** option is selected, the units are defined in the following parameters. In any other case these are read-only parameters used to indicate the respective unit:

- Distance unit (→  326)
- Pressure unit (→  327)
- Temperature unit (→  327)

**Distance unit** 


**Navigation**  Setup → Advanced setup → System units → Distance unit

**Description** Select distance unit.

- Selection**
- |  |  |
|--|--|
| <p><i>SI units</i></p> <ul style="list-style-type: none"> <li>■ m</li> <li>■ mm</li> <li>■ cm</li> </ul> | <p><i>US units</i></p> <ul style="list-style-type: none"> <li>■ ft</li> <li>■ in</li> <li>■ ft-in-16</li> <li>■ ft-in-8</li> </ul> |
|--|--|

**Factory setting** mm

**Additional information**

Read access	Operator
Write access	Maintenance (if <b>Units preset</b> (→  197) = <b>Customer value</b> )

**Pressure unit**



**Navigation**

Setup → Advanced setup → System units → Pressure unit

**Selection**

*SI units*

- bar
- Pa
- kPa
- MPa
- mbar a

*US units*

- psi

*Other units*

- inH2O
- inH2O (68°F)
- ftH2O (68°F)
- mmH2O
- mmHg

**Factory setting**

bar

**Additional information**

Read access	Operator
Write access	Maintenance (if <b>Units preset</b> (→  197) = <b>Customer value</b> )

**Temperature unit**



**Navigation**

Setup → Advanced setup → System units → Temperature unit

**Description**

Select temperature unit.

**Selection**

*SI units*

- °C
- K

*US units*

- °F
- °R

**Factory setting**

°C

**Additional information**

Read access	Operator
Write access	Maintenance (if <b>Units preset</b> (→  197) = <b>Customer value</b> )

**Density unit**



**Navigation**

Setup → Advanced setup → System units → Density unit

**Description**

Select density unit.

**Selection**

*SI units*

- g/cm<sup>3</sup>
- g/ml
- g/l
- kg/l
- kg/dm<sup>3</sup>
- kg/m<sup>3</sup>

*US units*

- lb/ft<sup>3</sup>
- lb/gal (us)
- lb/in<sup>3</sup>
- STon/yd<sup>3</sup>


*Other units*

- °API
- SGU


**Factory setting**

kg/m<sup>3</sup>


**Additional information**

Read access	Operator
Write access	Maintenance (if Units preset (→  197) = Customer value)

**"Date / time" submenu**

*Navigation*       Setup → Advanced setup → Date / time

**Date/time**

**Navigation**       Setup → Advanced setup → Date / time → Date/time


**Description**      Displays the device internal real time clock.

**Additional information**

Read access	Operator
Write access	-

**Set date**



**Navigation**       Setup → Advanced setup → Date / time → Set date

**Description**      Controls the setting of the real-time clock.

**Selection**

- Please select
- Abort
- Start
- Confirm time

**Factory setting**      Please select

**Additional information**

Read access	Operator
Write access	Maintenance

**Meaning of the options**

- **Please select**  
Prompts the user to select an action.
- **Abort**  
Discards the entered date and time.
- **Start**  
Starts the setting of the real time clock.
- **Confirm time**  
Sets the real-time clock to the entered date and time.

**Year**



**Navigation**       Setup → Advanced setup → Date / time → Year

**Prerequisite**      Set date (→  329) = Start

**Description** Enter the current year.

**User entry** 2 016 to 2 079

**Factory setting** 2 016


**Additional information**


Read access	Operator
Write access	Maintenance

---

**Month** 

---

**Navigation**  Setup → Advanced setup → Date / time → Month

**Prerequisite** **Set date (→  329) = Start**

**Description** Enter the current month.

**User entry** 1 to 12

**Factory setting** 1

**Additional information**


Read access	Operator
Write access	Maintenance

---

**Day** 

---

**Navigation**  Setup → Advanced setup → Date / time → Day

**Prerequisite** **Set date (→  329) = Start**

**Description** Enter the current day.

**User entry** 1 to 31

**Factory setting** 1

**Additional information**


Read access	Operator
Write access	Maintenance

---

**Hour** 

---

**Navigation**  Setup → Advanced setup → Date / time → Hour

**Prerequisite** **Set date (→  329) = Start**

**Description** Enter the current hour.

**User entry** 0 to 23

**Factory setting** 0

**Additional information**

Read access	Operator
Write access	Maintenance

---

## Minute



**Navigation** Setup → Advanced setup → Date / time → Minute

**Prerequisite** Set date (→ 329) = Start

**Description** Enter the current minute.


**User entry** 0 to 59


**Factory setting** 0

**Additional information**


Read access	Operator
Write access	Maintenance


**"SIL confirmation" wizard**

-  The **SIL confirmation** wizard is only available for devices with SIL or WHG approval (Feature 590: "Additional Approval", option LA: "SIL" or LC: "WHG overflow prevention" ) which are currently **not** in the SIL- or WHG-locked state.
- The **SIL confirmation** wizard is required to lock the device according to SIL or WHG. For details refer to the "Functional Safety Manual" of the respective device, which describes the locking procedure and the parameters of this wizard.

*Navigation*       Setup → Advanced setup → SIL confirmation


**"Deactivate SIL/WHG" wizard**


-  The **Deactivate SIL/WHG** wizard is only available for devices with SIL or WHG approval (Feature 590: "Additional Approval", option LA: "SIL" or LC: "WHG overflow prevention" ) which are currently in the SIL- or WHG-locked state.
- The **Deactivate SIL/WHG** wizard is required to undo the locking of the device according to SIL or WHG. For details refer to the "Functional Safety Manual" of the respective device, which describes the locking procedure and the parameters of this wizard.

*Navigation*       Setup → Advanced setup → Deactiv. SIL/WHG



**"Administration" submenu**

Navigation  Setup → Advanced setup → Administration

**Define access code** 

**Navigation**  Setup → Advanced setup → Administration → Def. access code






**Description** Define release code for write access to parameters.


**User entry** 0 to 9999

**Factory setting** 0

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

-  If the factory setting is not changed or 0 is defined as the access code, the parameters are not write-protected and the configuration data of the device can then always be modified. The user is logged on in the *Maintenance* role.
-  The write protection affects all parameters marked with the  symbol in this document.
-  Once the access code has been defined, write-protected parameters can only be modified if the access code is entered in the **Enter access code** parameter (→  212).

**Device reset** 

**Navigation**   Setup → Advanced setup → Administration → Device reset

**Description** Reset the device configuration - either entirely or in part - to a defined state

**Selection**

- Cancel
- To factory defaults
- Restart device

**Factory setting** Cancel

**Additional information**

**Meaning of the options**

- **Cancel**  
No action
- **To factory defaults**  
All parameters are reset to the order-code specific factory setting.
- **Restart device**  
The restart resets every parameter which is stored in the volatile memory (RAM) to the factory setting (e.g. measured value data). The device configuration remains unchanged.

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

## 15.4 "Diagnostics" menu

Navigation   Diagnostics

---

### Actual diagnostics

---

**Navigation**   Diagnostics → Actual diagnos.


**Description** Displays the currently active diagnostic message.  
 If there is more than one pending diagnostic event, the message for the diagnostic event with the highest priority is displayed.


**Additional information**

Read access	Operator
Write access	-

The display consists of:

- Symbol for event behavior
- Code for diagnostic behavior
- Operating time of occurrence
- Event text

 If several messages are active at the same time, the messages with the highest priority is displayed.

 Information on what is causing the message, and remedy measures, can be viewed via the ⓘ symbol on the display.

---

### Timestamp

---

**Navigation**   Diagnostics → Timestamp

**Description** Displays the timestamp for the currently active diagnostic message.

**Additional information**

Read access	Operator
Write access	-

---

### Previous diagnostics

---

**Navigation**   Diagnostics → Prev.diagnostics


**Description** Displays the diagnostic message for the last diagnostic event that has ended.



**Additional information**

Read access	Operator
Write access	-

The display consists of:

- Symbol for event behavior
- Code for diagnostic behavior
- Operating time of occurrence
- Event text

 If several messages are active at the same time, the messages with the highest priority is displayed.

 Information on what is causing the message, and remedy measures, can be viewed via the  symbol on the display.

### Timestamp

**Navigation**   Diagnostics → Timestamp

**Description** Displays the timestamp of the diagnostic message generated for the last diagnostic event that has ended.

**Additional information**

Read access	Operator
Write access	-

### Operating time from restart

**Navigation**   Diagnostics → Time fr. restart

**Description** Indicates how long the device has been in operation since the last time the device was restarted.

**Additional information**

Read access	Operator
Write access	-

### Operating time

**Navigation**   Diagnostics → Operating time

**Description** Indicates how long the device has been in operation.

**Additional information**

Read access	Operator
Write access	-

---

**Date/time**

---

**Navigation** Diagnostics → Date/time**Description**

Displays the device internal real time clock.

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	-


### 15.4.1 "Diagnostic list" submenu

*Navigation*  Diagnostics → Diagnostic list

---

#### Diagnostics 1 to 5

---

**Navigation**  Diagnostics → Diagnostic list → Diagnostics 1 to 5

**Description** Displays the currently active diagnostic message with the highest priority.

**Additional information** The display consists of:

- Symbol for event behavior
- Code for diagnostic behavior
- Operating time of occurrence
- Event text

---

#### Timestamp 1 to 5

---

**Navigation**  Diagnostics → Diagnostic list → Timestamp 1 to 5

**Description** Timestamp of the diagnostic message.

### 15.4.2 "Device information" submenu

Navigation  Diagnostics → Device info

---

#### Device tag

---

**Navigation**  Diagnostics → Device info → Device tag

**Description** Shows the device tag.

**User interface** Character string comprising numbers, letters and special characters

**Factory setting** - none -

**Additional information**

Read access	Operator
Write access	-

---

#### Serial number

---

**Navigation**  Diagnostics → Device info → Serial number

**Description** The serial number is a unique alphanumeric code identifying the device. It is printed on the nameplate. In combination with the Operations app it allows to access all device related documentation.


**Additional information**

Read access	Operator
Write access	-

---

#### Firmware version

---

**Navigation**  Diagnostics → Device info → Firmware version

**Description** Displays the device firmware version installed.


**Additional information**

Read access	Operator
Write access	-

---

**Firmware CRC**


---

**Navigation**   Diagnostics → Device info → Firmware CRC

**Description** Result of the cyclic redundancy check of the firmware.

**Additional information**

Read access	Operator
Write access	-

---

**Weight and measures configuration CRC**


---

**Navigation**   Diagnostics → Device info → W&M config CRC

**Description** Result of the cyclic redundancy check of the weights and measure relevant parameters.

**Additional information**

Read access	Operator
Write access	-

---

**Device name**


---

**Navigation**   Diagnostics → Device info → Device name

**Description** Use this function to display the device name. It can also be found on the nameplate.

**Additional information**

Read access	Operator
Write access	-

---

**Order code**


---



**Navigation**   Diagnostics → Device info → Order code

**Description** Shows the device order code.

**Additional information**

Read access	Operator
Write access	Service



---

**Extended order code 1 to 3**

---

**Navigation**

Diagnostics → Device info → Ext. order cd. 1

**Description**

Display the three parts of the extended order code.

**User interface**

Character string comprising numbers, letters and special characters

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Service

The extended order code indicates the selected option of all ordering features and thus uniquely identifies the device.

### 15.4.3 "Simulation" submenu

Read access	Maintenance
-------------	-------------

Navigation  Diagnostics → Simulation

---

#### Device alarm simulation

**Navigation**  Diagnostics → Simulation → Dev. alarm sim.

**Description** Switch the device alarm on and off.

**Selection**

- Off
- On


**Factory setting** Off

**Additional information**

Read access	Operator
Write access	Maintenance

---

#### Diagnostic event simulation

**Navigation**  Diagnostics → Simulation → Diagnostic event


**Description** Select a diagnostic event to simulate this event.

**Selection** The diagnostic events of the device

**Factory setting** Off

**Additional information**

Read access	Operator
Write access	Maintenance

 To terminate the simulation, select **Off**.

---

#### Simulation distance on

**Navigation**  Diagnostics → Simulation → Sim distance on

**Description** Switches the distance simulation on or off.


**Selection**

- Off
- On


**Factory setting** Off

**Additional information**

Read access	Operator
Write access	Maintenance

**Simulation distance** 

**Navigation**   Diagnostics → Simulation → Sim distance

**Prerequisite** **Simulation distance on (→  342) = On**


**Description** Defines the distance value to be simulated.



**User entry** Signed floating-point number

**Factory setting** 0 mm

**Additional information**

Read access	Operator
Write access	Maintenance

**Current output N simulation** 

**Navigation**   Diagnostics → Simulation → Curr.outp N sim.

**Prerequisite**

- The device has an Anlog I/O module.
- **Operating mode (→  227) = 4..20mA output or HART slave +4..20mA output**

**Description** Switches the simulation of the current on or off.


**Selection**

- Off
- On


**Factory setting** Off

**Additional information**

Read access	Operator
Write access	Maintenance

**Simulation value** 

**Navigation**   Diagnostics → Simulation → Simulation value

**Prerequisite** **Current output simulation (→  343) = On**

**Description** Defines the current to be simulated.

**User entry** 3.4 to 23 mA

**Factory setting** The current at the time the simulation was started.

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance


### 15.4.4 "Device check" submenu

*Navigation*       Diagnostics → Device check

---

#### Result drum check

---


**Navigation**       Diagnostics → Device check → Result drum chk


**Description**      Gives feedback on the latest status of the commissioning check.

**Additional information**

Read access	Operator
Write access	-

**"Commissioning check" wizard**

*Navigation*  Diagnostics → Device check → Commission check

**Commissioning check** 

**Navigation**  Diagnostics → Device check → Commission check → Commission check

**Description** This sequence supports checking of the hardware on sensor side and correct installation of the sensor.

**Additional information**

Read access	Operator
Write access	Maintenance

**Result drum check**


**Navigation**  Diagnostics → Device check → Commission check → Result drum chk

**Description** Gives feedback on the latest status of the commissioning check.

**Additional information**

Read access	Operator
Write access	-

**Step X / 11**

**Navigation**  Diagnostics → Device check → Commission check → Step X / 11

**Description** Indicates which step of the commissioning check is currently running.

**Additional information**

Read access	Operator
Write access	-

### 15.4.5 "LRC 1 to 2" submenu

 Configuration of the level reference check (LRC) function →  122

*Navigation*        Diagnostics → LRC → LRC 1 to 2

---

#### LRC Mode

---

**Navigation**        Diagnostics → LRC → LRC 1 to 2 → LRC Mode

**Description**      Activates or deactivates one of the level reference check (LRC) modes.

**Selection**

- Off
- Compare with level device
- Compare with level switch
- Measure reference point \*

**Factory setting**      Off

**Additional information**



Read access	Operator
Write access	Maintenance

**Additional information**      The option of the Measure reference point is not available for NMS8x.

---

#### Allowed difference

---

**Navigation**        Diagnostics → LRC → LRC 1 to 2 → Allowed diff.

**Description**      Defines the allowed difference between the tank level and the reference.

**User entry**      1 to 1 000 mm

**Factory setting**      10 mm

**Additional information**

Read access	Operator
Write access	Maintenance

---

\* Visibility depends on order options or device settings

**Check fail threshold**



**Navigation**

Diagnostics → LRC → LRC 1 to 2 → Fail threshold

**Description**

Defines how many minutes the comparison has to fail before the check is failed. Note: Only for mode "Compare with level device".

**User entry**

1 to 60

**Factory setting**

3

**Additional information**

Read access	Operator
Write access	Maintenance

**Reference level source**



**Navigation**

Diagnostics → LRC → LRC 1 to 2 → Reference source

**Description**

Defines the source for the reference level. Note: Only for mode "Compare with level device".

**Selection**

- No input value
- HART device 1 level \*
- HART device 2 level \*
- HART device 3 level \*
- HART device 4 level \*
- HART device 5 level \*
- HART device 6 level \*
- HART device 7 level \*
- HART device 8 level \*
- HART device 9 level \*
- HART device 10 level \*
- HART device 11 level \*
- HART device 12 level \*
- HART device 13 level \*
- HART device 14 level \*
- HART device 15 level \*

**Factory setting**

No input value

**Additional information**

Read access	Operator
Write access	Maintenance

\* Visibility depends on order options or device settings



**Reference switch source**



<b>Navigation</b>	Diagnostics → LRC → LRC 1 to 2 → Reference source				
<b>Description</b>	Defines the source for the reference switch. Note: Only for mode "Compare with level switch".				
<b>Selection</b>	<ul style="list-style-type: none"> <li>■ None</li> <li>■ Digital A1-2</li> <li>■ Digital A3-4</li> <li>■ Digital B1-2</li> <li>■ Digital B3-4</li> <li>■ Digital C1-2</li> <li>■ Digital C3-4</li> <li>■ Digital D1-2</li> <li>■ Digital D3-4</li> </ul>				
<b>Factory setting</b>	None				
<b>Additional information</b>	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="width: 50%;">Read access</td> <td>Operator</td> </tr> <tr> <td>Write access</td> <td>Maintenance</td> </tr> </table>	Read access	Operator	Write access	Maintenance
Read access	Operator				
Write access	Maintenance				

**Reference switch mode**



<b>Navigation</b>	Diagnostics → LRC → LRC 1 to 2 → Ref. switch mode				
<b>Description</b>	Defines the switch direction for which the reference check is executed. Note: Only for mode "Compare with level switch".				
<b>Selection</b>	<ul style="list-style-type: none"> <li>■ Active -&gt; Inactive</li> <li>■ Inactive -&gt; Active</li> </ul>				
<b>Factory setting</b>	Active -> Inactive				
<b>Additional information</b>	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="width: 50%;">Read access</td> <td>Operator</td> </tr> <tr> <td>Write access</td> <td>Maintenance</td> </tr> </table>	Read access	Operator	Write access	Maintenance
Read access	Operator				
Write access	Maintenance				

**Reference level**

<b>Navigation</b>	Diagnostics → LRC → LRC 1 to 2 → Reference level
<b>Description</b>	Shows the current reference level. Note: Only for mode "Compare with level device".
<b>User interface</b>	Signed floating-point number
<b>Factory setting</b>	0 mm

**Additional information**

Read access	Operator
Write access	-

**Reference switch level****Navigation**

Diagnostics → LRC → LRC 1 to 2 → Reference level

**Description**

Defines the position of the reference switch as level. Note: Only for mode "Compare with level switch".

**User entry**

0 to 10 000.00 mm

**Factory setting**

0 mm

**Additional information**

Read access	Operator
Write access	Maintenance

**Reference switch state****Navigation**

Diagnostics → LRC → LRC 1 to 2 → Ref.switch state

**Description**

Shows the current state of the reference switch (e.g. "active"). Note: Only for mode "Compare with level switch".

**User interface**

- Unknown
- Inactive
- Active
- Error

**Factory setting**

Unknown

**Additional information**

Read access	Operator
Write access	-

**Check level****Navigation**

Diagnostics → LRC → LRC 1 to 2 → Check level

**Description**

Shows the tank level at which the reference check has been executed.

**User interface**

Signed floating-point number


**Factory setting**

0 mm

**Additional information**

Read access	Operator
Write access	Development

**Check status****Navigation**

 Diagnostics → LRC → LRC 1 to 2 → Check status

**Description**

Shows the status of the reference check execution (e.g. "passed").

**User interface**

- not executed
- Passed
- Failed
- Not possible

**Factory setting**

not executed

**Additional information**

Read access	Operator
Write access	Development

**Check timestamp****Navigation**

 Diagnostics → LRC → LRC 1 to 2 → Check timestamp

**Description**

Shows the timestamp at which the reference check has been executed.

**User interface**

Character string comprising numbers, letters and special characters

**Factory setting****Additional information**

Read access	Operator
Write access	-

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