

Liquiline pHORP – Revision 4

HART Field Device Specification

Document: E+H Liquiline pHORP LIT-18, Revision 4

Initial release 07-Jan-2015
Current release 04-Apr-2017

SD01325C/07/EN/02.17
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1. Introduction

1.1. Scope

The Endress+Hauser analysis transmitter, model Liquiline pHORP complies with HART protocol revision 7. This document specifies all the device specific features and documents HART protocol implementation details. The functionality of this field device is described sufficiently to allow its proper application in a process and its complete support in HART capable host applications.

1.2. Purpose

This specification is designed to complement the Operating Instructions (BA382) by providing a complete, unambiguous description of this field device from a HART communication perspective.

1.3. Who should use this document?

The specification is designed to be a technical reference for HART capable host application developers, system integrators and knowledgeable end users. It also provides functional specifications (e.g., commands, enumerations and performance requirements) used during field device development, maintenance and testing. This document assumes the reader is familiar with HART protocol requirements and terminology.

1.4. Abbreviations and definitions

| | |
|--------|-------------------------------|
| FSK: | Frequency shift keying |
| HCF: | HART Communication Foundation |
| n. A.: | Not applicable |
| SCS: | Sensor check system |
| NaN: | Not a number |
| ENP: | Electronic nameplate |

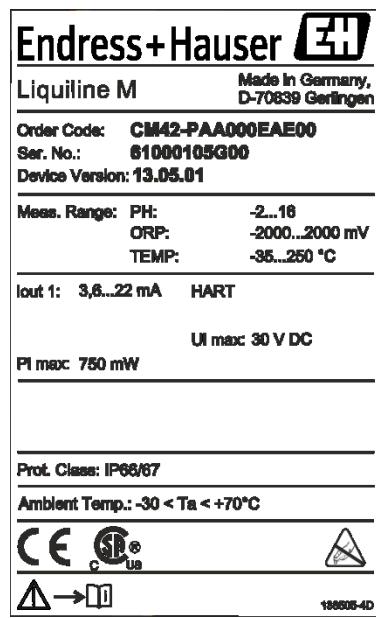
1.5. References

HCF_SPEC-12: HART Smart Communications Protocol Specification. Available from the HCF.
BA00381C + BA00382C: Operating Instructions.

2. Device identification

| | |
|-----------------------------|---|
| Manufacturer name: | Endress+Hauser |
| Model name: | Liquiline pHORP |
| Manufacturer ID code: | 17 (11 _h) |
| Device type code: | 160 (AO _h) |
| Expanded device type code: | 4512 (11A0 _h) |
| HART protocol revision: | 7.5 |
| Device revision: | 4 |
| Number of device variables: | 9 |
| Physical layers supported: | FSK |
| Physical device category: | Transmitter, non DC isolated bus device |

The nameplate is located on the right side of the housing and indicates model name, order code, and serial number of the device. The expanded device type code and device revision are shown on the device's power-up screen.



A nameplate example



Liquiline

3. Product overview

Liquiline pHORP is a robust 2 wire loop powered transmitter for pH/ORP measurement in all process applications.

Different pH or ORP sensors with or without integrated temperature sensor can be connected for different use cases. For more information please refer to the Operating Instructions.

4. Product interfaces

4.1. Process interface

4.1.1. Sensor input channels

Depending on Liquiline version different sensors can be connected to different terminals. Please refer to the Operating Instructions.

4.2. Host interface

Current output 1 terminals are 133 (+) and 134 (-). Liquiline is powered by current output 1. Depending on the Liquiline version current output 2 is present and can be connected by using terminals 233 (+) and 234 (-).

4.2.1. Analog output 1

This output is available in all HART Liquilines. Any of the device variables described in chapter 5 can be assigned to analog output 1. Depending on the selection the output is scaled according to the configured range of the instrument. Analog output 1 corresponds to the HART primary variable. HART communication is supported on this loop, only.

Linear overrange is possible from 3.8 mA to 20.5 mA. Device malfunction can be indicated by error current if selected. Current values are shown in the table below:

| | |
|--|----------------------------|
| Downwards linear over-range: | 3.8 mA |
| Upwards linear over-range: | 20.5 mA |
| Device malfunction indication (detection by software, high): | 21.5 mA |
| Device malfunction indication (detection by software, low): | 3.6 mA |
| Device malfunction indication (detection by hardware): | 22.0 mA |
| Minimum current: | 3.6 mA |
| Maximum current: | 22.0 mA |
| Multidrop current draw: | 4.0 mA (power-up: 22.0 mA) |
| Lift-off Voltage: | 18 V |

4.2.2. Analog output 2

This output is available in certain Liquiline versions, only. Any of the device variables described in chapter 5 can be assigned to analog output 2. HART communication is not supported on this loop.

Linear overrange is possible from 3.8 mA to 20.5 mA. Device malfunction can be indicated by error current if selected. Current values are shown in the table below:

| | |
|--|---------|
| Downwards linear over-range: | 3.8 mA |
| Upwards linear over-range: | 20.5 mA |
| Device warning indication (detection by software): | 21.5 mA |
| Device error indication (detection by hardware): | 22.0 mA |
| Minimum current: | 3.6 mA |
| Maximum current: | 22.0 mA |
| Multidrop current draw: | n. A. |
| Lift-off Voltage: | n. A. |

4.3. Local interfaces, jumpers and switches

4.3.1. Local controls and displays

Liquiline has four buttons, one navigator and a large dot matrix LC display for user interaction. All buttons and the navigator are software controlled. For detailed information refer to the Operating Instructions.

4.3.2. Internal jumpers and switches

There are no controls inside the housing.

5. Device variables

5.1. Device variable 0 - Main process value

The value and the unit of this device variable depend on the present Liquiline operation mode. Not all operation modes are available with all Liquiline versions.

The unit might differ from the unit shown on Liquiline's display.

pH mode:

| | | |
|---------------------------------|------------|------------------------|
| Device variable classification: | Analytical | 81 (51 _h) |
| Device family: | Not used | 250 (FA _h) |
| Device variable unit: | pH | 59 (3B _h) |
| Device variable lower limit: | -2 pH | |
| Device variable upper limit: | 16 pH | |

Raw value and ORP mV mode:

| | | |
|---------------------------------|-------------|------------------------|
| Device variable classification: | EMF/Voltage | 83 (53 _h) |
| Device family: | Not used | 250 (FA _h) |
| Device variable unit: | mV | 36 (24 _h) |
| Device variable lower limit: | -2000 mV | |
| Device variable upper limit: | 2000 mV | |

ORP % mode:

| | | |
|---------------------------------|------------|------------------------|
| Device variable classification: | Analytical | 81 (51 _h) |
| Device family: | Not used | 250 (FA _h) |
| Device variable unit: | % | 57 (39 _h) |
| Device variable lower limit: | -3000 % | |
| Device variable upper limit: | 3000 % | |

rH mode:

| | | |
|---------------------------------|----------|------------------------|
| Device variable classification: | None | 0 (0 _h) |
| Device family: | Not used | 250 (FA _h) |
| Device variable unit: | rH | 247 (F7 _h) |
| Device variable lower limit: | 0 rH | |
| Device variable upper limit: | 70 rH | |

Temperature mode:

| | | |
|---------------------------------|-------------|---|
| Device variable classification: | Temperature | 64 (40 _h) |
| Device family: | Not used | 250 (FA _h) |
| Device variable units: | °C, °F, K | 32, 33, 35 (20 _h , 21 _h , 23 _h) |
| Device variable lower limit: | -50 °C | |
| Device variable upper limit: | 150 °C | |

5.2. Device variable 1 - pH

This value returns the damped temperature compensated pH value.
If the device is not in pH mode this device variable should not be used.

| | | |
|---------------------------------|------------|------------------------|
| Device variable classification: | Analytical | 81 (51 _h) |
| Device family: | Not used | 250 (FA _h) |
| Device variable unit: | pH | 59 (3B _h) |
| Device variable lower limit: | -2 pH | |
| Device variable upper limit: | 16 pH | |

5.3. Device variable 2 - ORP %

This value returns the ORP % value.
If the device is not in ORP mode this device variable should not be used.

| | | |
|---------------------------------|------------|------------------------|
| Device variable classification: | Analytical | 81 (51 _h) |
| Device family: | Not used | 250 (FA _h) |
| Device variable unit: | % | 57 (39 _h) |
| Device variable lower limit: | -3000 % | |
| Device variable upper limit: | 3000 % | |

5.4. Device variable 3 - Raw value

This device variable returns the pH raw value in millivolts.
If the device is not in pH mode this device variable should not be used.

| | | |
|---------------------------------|-------------|------------------------|
| Device variable classification: | EMF/Voltage | 83 (53 _h) |
| Device family: | Not used | 250 (FA _h) |
| Device variable unit: | mV | 36 (24 _h) |
| Device variable lower limit: | -2000 mV | |
| Device variable upper limit: | 2000 mV | |

5.5. Device variable 4 - Temperature

This device variable returns the main process temperature value. This variable will return the real process value if a temperature sensor is present and activated only. If a special temperature is set by the user (e.g. when no temperature sensor is present) the device variable will return that temperature.

The unit might differ from the unit shown on Liquiline's display, i.e. setting Liquiline to °F will not set device variable 4 to °F. Device variable 4 can be set to °F by sending command 53.

| | | |
|---------------------------------|-------------|---|
| Device variable classification: | Temperature | 64 (40 _h) |
| Device family: | Not used | 250 (FA _h) |
| Device variable units: | °C, °F, K | 32, 33, 35 (20 _h , 21 _h , 23 _h) |
| Device variable lower limit: | -50 °C | |
| Device variable upper limit: | 150 °C | |

5.6. Device variable 5 - rH

This value returns the rH value calculated from a pH and mV value.
If the device is not in rH mode this device variable should not be used.

| | | |
|---------------------------------|----------|------------------------|
| Device variable classification: | None | 0 (0 _h) |
| Device family: | Not used | 250 (FA _h) |
| Device variable unit: | rH | 247 (F7 _h) |
| Device variable lower limit: | 0 rH | |
| Device variable upper limit: | 70 rH | |

5.7. Device variable 6 - ORP mV

This value returns the ORP mV value.
If the device is not in ORP mode this device variable should not be used.

| | | |
|---------------------------------|-------------|------------------------|
| Device variable classification: | EMF/Voltage | 83 (53 _h) |
| Device family: | Not used | 250 (FA _h) |
| Device variable unit: | mV | 36 (24 _h) |
| Device variable lower limit: | -2000 mV | |
| Device variable upper limit: | 2000 mV | |

5.8. Device variable 7 - Glass impedance

This value returns the Glass impedance value.
If the device is not in pH mode this device variable should not be used.
This device variable cannot be mapped to PV.

| | | |
|---------------------------------|------------|------------------------|
| Device variable classification: | Resistance | 85 (55 _h) |
| Device family: | Not used | 250 (FA _h) |
| Device variable unit: | MΩ | 170 (AA _h) |
| Device variable lower limit: | 0 MΩ | |
| Device variable upper limit: | 200000 MΩ | |

5.9. Device variable 8 - Reference impedance

This value returns the reference impedance value.
If the device is not in pH mode or reference measurement is not active this device variable should not be used.
This device variable cannot be mapped to PV.

| | | |
|---------------------------------|------------|------------------------|
| Device variable classification: | Resistance | 85 (55 _h) |
| Device family: | Not used | 250 (FA _h) |
| Device variable unit: | kΩ | 163 (A3 _h) |
| Device variable lower limit: | 0 kΩ | |
| Device variable upper limit: | 2000 kΩ | |

5.10. Device variable status

| | |
|----------|---------------------|
| Bit 0: | Not used |
| Bit 1: | Not used |
| Bit 2: | Not used |
| Bit 3: | Not used |
| Bit 5+4: | Limit status |
| | 00: Not limited |
| | 01: Low limited |
| | 10: High limited |
| | 11: Constant |
| Bit 7+6: | Process data status |
| | 00: Bad |
| | 01: Poor accuracy |
| | 10: Manual / fixed |
| | 11: Good |

5.11. Manufacturer specific unit codes

| Code | Code _h | Unit |
|------|-------------------|------|
| 247 | F7 _h | rH |

5.12. Standardized device variables

These device variables have to be present in every HART 7 device.

Standardized device variables cannot be mapped to PV, SV, TV or QV using command 51.

5.12.1. Battery life

This device variable will always return NaN, as Liquiline is not battery powered.

| | | |
|---------------------------------|------------------------|------------------------|
| Device variable number: | 243 (F3 _h) | |
| Device variable classification: | None | 0 (0 _h) |
| Device family: | Not used | 250 (FA _h) |
| Device variable unit: | Not used | 250 (FA _h) |
| Device variable lower limit: | NaN | |
| Device variable upper limit: | NaN | |

5.12.2. Percent range

This device variable returns the PV percentage corresponding to its user set limits. The value will always follow the PV even if the limits are exceeded, or the device is in an error state.

| | | |
|---------------------------------|------------------------|------------------------|
| Device variable number: | 244 (F4 _h) | |
| Device variable classification: | Analytical | 81 (51 _h) |
| Device family: | Not used | 250 (FA _h) |
| Device variable unit: | % | 57 (39 _h) |
| Device variable lower limit: | -1000 % | |
| Device variable upper limit: | 1000 % | |

5.12.3. Loop current

This device variable returns the loop current on current output 1 even if the device is in an error or simulation state.

| | | |
|---------------------------------|------------------------|------------------------|
| Device variable number: | 245 (F5 _h) | |
| Device variable classification: | Current | 84 (54 _h) |
| Device family: | Not used | 250 (FA _h) |
| Device variable unit: | mA | 39 (27 _h) |
| Device variable lower limit: | 0 mA | |
| Device variable upper limit: | 23 mA | |

5.12.4. Primary variable

This device variable returns the primary variable (PV).

| | |
|---------------------------------|------------------------|
| Device variable number: | 246 (F6 _h) |
| Device variable classification: | Depends on PV settings |
| Device family: | Not used |
| Device variable unit: | Depends on PV settings |
| Device variable lower limit: | Depends on PV settings |
| Device variable upper limit: | Depends on PV settings |

5.12.5. Secondary variable

This device variable returns the secondary variable (SV).

| | |
|---------------------------------|------------------------|
| Device variable number: | 247 (F7 _h) |
| Device variable classification: | Depends on SV settings |
| Device family: | Not used |
| Device variable unit: | Depends on SV settings |
| Device variable lower limit: | Depends on SV settings |
| Device variable upper limit: | Depends on SV settings |

5.12.6. Tertiary variable

This device variable returns the tertiary variable (TV).

| | |
|---------------------------------|------------------------|
| Device variable number: | 248 (F8 _h) |
| Device variable classification: | Depends on TV settings |
| Device family: | Not used |
| Device variable unit: | Depends on TV settings |
| Device variable lower limit: | Depends on TV settings |
| Device variable upper limit: | Depends on TV settings |

5.12.7. Quaternary variable

This device variable returns the quaternary variable (QV).

| | |
|---------------------------------|------------------------|
| Device variable number: | 249 (F9 _h) |
| Device variable classification: | Depends on QV settings |
| Device family: | Not used |
| Device variable unit: | Depends on QV settings |
| Device variable lower limit: | Depends on QV settings |
| Device variable upper limit: | Depends on QV settings |

6. Dynamic variables

All 4 dynamic variables (primary variable PV, secondary variable SV, tertiary variable TV and quaternary variable QV) are implemented in Liquiline devices.

6.1. Fixed dynamic variables

There are no fixed dynamic variables.

6.2. Dynamic variables with configurable mapping

PV can be mapped to device variables 0 - 6.

SV, TV and QV can be mapped to any device variable.

Changing the PV dynamic variable will change the current output 1 source, too.

Default mapping:

PV returns the current output 1 source - Device variable 0 - Main process value

SV returns device variable 4 - Temperature

TV returns device variable 3 - Raw value

QV returns device variable 2 - ORP %

7. Status information

7.1. Device status

Bit 0 (01_h, "Primary variable out of limits") is set whenever diagnostic message 404 or 405 is set.
Bit 1 (02_h, "Non-primary variable out of limits") is not used.
Bit 2 (04_h, "Loop current saturated") is set whenever diagnostic message 404 or 405 is set.
Bit 3 (08_h, "Loop current fixed") is set when simulation or multidrop mode or hold is active.
Bit 4 (10_h, "More status available") is set whenever a diagnostic message change is detected. This bit can be reset by user interaction.
Bit 5 (20_h, "Cold start") is set after device reset. It is reset after the first HART communication request.
Bit 6 (40_h, "Configuration changed") is set whenever a persistent parameter was changed. This bit stays set until it is reset by user interaction.
Bit 7 (80_h, "Device malfunction") is set when the present highest priority diagnostic code is classified as F.

7.2. Extended device status

Bit 0 (01_h, "Maintenance required") is set when the present highest priority diagnostic code is classified as M.
Bit 1 (02_h, "Device variable alert") is not used.
Bit 2 (04_h, "Critical power failure") is not used.
Bit 3 (08_h, "Failure") is set when the present highest priority diagnostic code is classified as F.
Bit 4 (10_h, "Out of specification") is set when the present highest priority diagnostic code is classified as S.
Bit 5 (20_h, "Function check") is set when the present highest priority diagnostic code is classified as C.
Bit 6 (40_h) is not used.
Bit 7 (80_h) is not used.

7.3. Standardized status 0

Bit 0 (01_h, "Device variable simulation active") is not used.
Bit 1 (02_h, "Non-volatile memory defect") is not used.
Bit 2 (04_h, "Volatile memory defect") is not used.
Bit 3 (08_h, "Watchdog reset executed") is set when a software exception caused the last device reset. The bit stays set until the next normal device startup.
Bit 4 (10_h, "Power supply conditions out of range") is not used.
Bit 5 (20_h, "Environmental conditions out of range") is set if there is a diagnostic code present marked in column ENV in chapter 7.7.
Bit 6 (40_h, "Electronic defect") is set if there is a diagnostic code present marked in column DEF in chapter 7.7.
Bit 7 (80_h, "Device configuration locked") is set if write protection is enabled or the device is locked using command 71.

7.4. Standardized status 1

Bit 0 (01_h, "Status simulation active") is set when status simulation is set via command 526.
Bit 1 (02_h, "Discrete variable simulation active") is not used.
Bit 2 (04_h, "Event notification overflow") is not used.
Bit 3 (08_h) is not used.
Bit 4 (10_h) is not used.
Bit 5 (20_h) is not used.
Bit 6 (40_h) is not used.
Bit 7 (80_h) is not used.

7.5. Standardized status 2

Standardized status 2 is not used.

7.6. Standardized status 3

Standardized status 3 is not used.

7.7. Additional device status - command 48

Bits not described below are set to 0.

| Bit | Byte | Bit2 | 524 index | Liquiline diagnostic message | Status | Code | ENV | DEF |
|-----|------|------|-----------|-------------------------------|--------|------|-----|-----|
| 0 | 0 | 0 | 8 | Temp. sensor failure | F | 3 | X | |
| 1 | 0 | 1 | 9 | Scanning sensor | C | 4 | | |
| 2 | 0 | 2 | 10 | Sensor initialization | C | 10 | | |
| 3 | 0 | 3 | 11 | Sensor no communication | F | 11 | X | |
| 4 | 0 | 4 | 12 | Sensor failure | F | 12 | X | |
| 5 | 0 | 5 | 13 | Wrong sensor type | F | 13 | | |
| 6 | 0 | 6 | 14 | Invalid sensor data | C | 14 | | |
| 7 | 0 | 7 | 15 | Sensor supply bad | F | 104 | | |
| 8 | 1 | 0 | 16 | Temp offset upper limit | F | 119 | | |
| 9 | 1 | 1 | 17 | Temp offset lower limit | F | 120 | | |
| 10 | 1 | 2 | 18 | Invalid TAG group | F | 127 | | |
| 11 | 1 | 3 | 19 | Invalid TAG | F | 128 | | |
| 12 | 1 | 4 | 20 | Sensor change aborted | C | 129 | | |
| 13 | 1 | 5 | 21 | Calibration active | C | 130 | | |
| 14 | 1 | 6 | 22 | PV not stable | M | 131 | | |
| 15 | 1 | 7 | 23 | Temperature not stable | M | 132 | | |
| 16 | 2 | 0 | 24 | Zero pnt. too high alarm | M | 134 | X | |
| 17 | 2 | 1 | 25 | Zero pnt. too high warning | M | 135 | | |
| 18 | 2 | 2 | 26 | Zero pnt. too low warning | M | 136 | | |
| 19 | 2 | 3 | 27 | Zero pnt. too low alarm | M | 137 | X | |
| 20 | 2 | 4 | 28 | Slope too low alarm | M | 138 | X | |
| 21 | 2 | 5 | 29 | Slope too low warning | M | 139 | | |
| 22 | 2 | 6 | 30 | Leakage current alarm | F | 140 | X | |
| 23 | 2 | 7 | 31 | Leakage current warn | M | 145 | | |
| 24 | 3 | 0 | 32 | Operating time alarm | M | 172 | X | |
| 25 | 3 | 1 | 33 | Oper.time >80°C alarm | M | 173 | X | |
| 26 | 3 | 2 | 34 | Oper.time >100°C alarm | M | 174 | X | |
| 27 | 3 | 3 | 35 | Cal. expired alarm | M | 180 | X | |
| 28 | 3 | 4 | 36 | SIP, CIP, autoclaving alarm | M | 181 | X | |
| 29 | 3 | 5 | 37 | Operating time warning | M | 182 | | |
| 30 | 3 | 6 | 38 | Oper.time >80°C warn | M | 183 | | |
| 31 | 3 | 7 | 39 | Oper.time >100°C warn | M | 184 | | |
| 32 | 4 | 0 | 40 | Cal. expired warning | M | 190 | | |
| 33 | 4 | 1 | 41 | SIP, CIP, autoclaving warning | M | 191 | | |
| 34 | 4 | 2 | 42 | Wrong transmitter type | F | 203 | X | |
| 35 | 4 | 3 | 43 | Simulation active | C | 215 | | |
| 36 | 4 | 4 | 44 | Current output not available | F | 218 | X | |
| 37 | 4 | 5 | 45 | Power supply bad | C | 219 | X | |
| 38 | 4 | 6 | 46 | Meas. value out of range | S | 322 | X | |
| 39 | 4 | 7 | 47 | Comm. module defect | F | 380 | X | |

| | | | | | | | |
|-----|----|---|-----|----------------------------------|----|-----|---|
| 40 | 5 | 0 | 48 | Comm. module incompl. | F | 381 | X |
| 41 | 5 | 1 | 49 | Lower limit current output | S | 404 | |
| 42 | 5 | 2 | 50 | Upper limit current output | S | 405 | |
| 43 | 5 | 3 | 51 | SETUP active | OK | 406 | |
| 44 | 5 | 4 | 52 | Diag. active | OK | 407 | |
| 45 | 5 | 5 | 53 | Calibration aborted | M | 408 | |
| 46 | 5 | 6 | 54 | Sensor change | C | 409 | |
| 47 | 5 | 7 | 55 | Device open | M | 501 | |
| 112 | 14 | 0 | 120 | Device alarm | F | 513 | X |
| 113 | 14 | 1 | 121 | Device warning | M | 514 | X |
| 114 | 14 | 2 | 122 | Logbook 20 % remain | S | 530 | |
| 115 | 14 | 3 | 123 | Logbook full | S | 531 | |
| 116 | 14 | 4 | 124 | Calibration timer expired | M | 532 | |
| 117 | 14 | 5 | 125 | PV upper limit alarm | F | 810 | X |
| 118 | 14 | 6 | 126 | PV lower limit alarm | F | 811 | X |
| 119 | 14 | 7 | 127 | Temperature out of range | F | 812 | X |
| 120 | 15 | 0 | 128 | PV upper limit warning | M | 840 | |
| 121 | 15 | 1 | 129 | PV lower limit warning | M | 841 | |
| 136 | 17 | 0 | 144 | Glass impedance alarm | F | 100 | X |
| 137 | 17 | 1 | 145 | Ref. impedance alarm | F | 101 | X |
| 138 | 17 | 2 | 146 | Glass imp. too low alarm | F | 102 | X |
| 139 | 17 | 3 | 147 | Ref. imp. too low alarm | F | 103 | X |
| 140 | 17 | 4 | 148 | Glass impedance warning | M | 106 | |
| 141 | 17 | 5 | 149 | Ref. impedance warning | M | 107 | |
| 142 | 17 | 6 | 150 | Glass imp. too low warning | M | 111 | |
| 143 | 17 | 7 | 151 | Ref. imp. too low warning | M | 112 | |
| 144 | 18 | 0 | 152 | SCC electrode cond. bad | M | 142 | X |
| 145 | 18 | 1 | 153 | SCC electrode sufficient | M | 148 | |
| 146 | 18 | 2 | 154 | Operating point too high alarm | M | 153 | X |
| 147 | 18 | 3 | 155 | Operating point too high warning | M | 154 | |
| 148 | 18 | 4 | 156 | Operating point too low warning | M | 155 | |
| 149 | 18 | 5 | 157 | Operating point too low alarm | M | 156 | X |
| 150 | 18 | 6 | 158 | Oper.time <-300mV alarm | M | 175 | X |
| 151 | 18 | 7 | 159 | Oper.time >300mV alarm | M | 176 | X |
| 152 | 19 | 0 | 160 | Delta slope alarm | M | 177 | X |
| 153 | 19 | 1 | 161 | Delta zero alarm | M | 178 | X |
| 154 | 19 | 2 | 162 | Delta oper.point alarm | M | 179 | X |
| 155 | 19 | 3 | 163 | Oper.time <-300mV warn | M | 185 | |
| 156 | 19 | 4 | 164 | Oper.time >300mV warn | M | 186 | |
| 157 | 19 | 5 | 165 | Delta slope warning | C | 238 | |
| 158 | 19 | 6 | 166 | Delta zero warning | C | 239 | |
| 159 | 19 | 7 | 167 | Delta oper.point warning | C | 240 | |
| 160 | 20 | 0 | 168 | Glass imp. too high alarm | M | 318 | X |
| 161 | 20 | 1 | 169 | Ref. imp. too high alarm | M | 319 | X |

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| | | | | | | |
|-----|----|---|-----|-----------------------------|---|-------|
| 162 | 20 | 2 | 170 | Glass imp. too high warning | M | 320 |
| 163 | 20 | 3 | 171 | Ref. imp. too high warning | M | 321 |
| 164 | 20 | 4 | 172 | PCS Alarm | F | 802 X |
| 165 | 20 | 5 | 173 | Sensor deactivated | F | 770 |

8. Supported commands

It is not suggested to use HART at command level directly.

Endress+Hauser provides device descriptions (DD) and device type managers (DTM) for a variety of control systems.

8.1. Read unique identifier - 0 (00_h)

This command reads fundamental information about the connected device.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|-------|-------------|---|
| 0 | Unsigned-8 | 254 |
| 1-2 | Enum | Expanded device type |
| 3 | Unsigned-8 | Minimum request preambles |
| 4 | Unsigned-8 | Universal command revision |
| 5 | Unsigned-8 | Device revision |
| 6 | Unsigned-8 | Software revision |
| 7 | Unsigned-8 | Hardware revision / Physical signaling code |
| 8 | Bits | Flags |
| 9-11 | Unsigned-24 | Device ID |
| 12 | Unsigned-8 | Minimum response preambles |
| 13 | Unsigned-8 | Maximum number of device variables |
| 14-15 | Unsigned-16 | Configuration change counter |
| 16 | Bits | Extended field device status |
| 17-18 | Enum | Manufacturer identification code |
| 19-20 | Enum | Private label distributor code |
| 21 | Enum | Device profile |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.2. Read primary variable - 1 (01_h)

This command reads the primary variable (PV). The primary variable is given by the source of the current output 1. The PV is one of the device variables described in chapter 5. Supported units can be found in chapter 5.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|--------|-----------------------|
| 0 | Enum | Primary variable unit |
| 1-4 | Float | Primary variable |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.3. Read loop current and percent of range - 2 (02_h)

This command reads the loop current and the percent of range of current output 1.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|--------|----------------------|
| 0-3 | Float | Loop current [mA] |
| 4-7 | Float | Percent of range [%] |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.4. Read dynamic variables and loop current - 3 (03_h)

This command reads the loop current and up to four predefined dynamic variables. Every dynamic variable corresponds to one device variable. Supported units can be found in chapter 5.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|-------|--------|--------------------------|
| 0-3 | Float | Loop current [mA] |
| 4 | Enum | Primary variable unit |
| 5-8 | Float | Primary variable |
| 9 | Enum | Secondary variable unit |
| 10-13 | Float | Secondary variable |
| 14 | Enum | Tertiary variable unit |
| 15-18 | Float | Tertiary variable |
| 19 | Enum | Quaternary variable unit |
| 20-23 | Float | Quaternary variable |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.5. Write polling address - 6 (06_h)

This command writes the polling address and the loop current mode. The polling address can be set at the Liquiline operating panel, too (“Setup/General settings/Bus address”).

Request data bytes

| Byte | Format | Description |
|------|------------|------------------------------|
| 0 | Unsigned-8 | Polling address |
| 1 | Enum | Loop current mode (optional) |

Response data bytes

| Byte | Format | Description |
|------|------------|-------------------|
| 0 | Unsigned-8 | Polling address |
| 1 | Enum | Loop current mode |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid address |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 12 | Error | Invalid mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

Loop current mode

Disabled: 0
Enabled: 1

8.6. Read loop configuration - 7 (07_h)

This command reads the loop current and the polling address.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|------------|-------------------|
| 0 | Unsigned-8 | Polling address |
| 1 | Enum | Loop current mode |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.7. Read dynamic variable classification - 8 (08_h)

This command reads the classification associated with the dynamic variables. Reading the classification is necessary to select the correct unit code table. Supported units and classification codes can be found in chapter 5.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|------------|------------------------------------|
| 0 | Unsigned-8 | Primary variable classification |
| 1 | Unsigned-8 | Secondary variable classification |
| 2 | Unsigned-8 | Tertiary variable classification |
| 3 | Unsigned-8 | Quaternary variable classification |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.8. Read device variables with status - 9 (09_h)

This command reads up to four device variables with their status. If more than 4 device variables are requested only the first four are returned and response code 30 is set.

Request data bytes

| Byte | Format | Description |
|------|------------|---|
| 0 | Unsigned-8 | Slot 0: Device variable code |
| 1 | Unsigned-8 | Slot 1: Device variable code (optional) |
| 2 | Unsigned-8 | Slot 2: Device variable code (optional) |
| 3 | Unsigned-8 | Slot 3: Device variable code (optional) |
| 4 | Unsigned-8 | Slot 4: Device variable code (optional) |
| 5 | Unsigned-8 | Slot 5: Device variable code (optional) |
| 6 | Unsigned-8 | Slot 6: Device variable code (optional) |
| 7 | Unsigned-8 | Slot 7: Device variable code (optional) |

Response data bytes

| Byte | Format | Description |
|----------|------------|--|
| 0 | Bits | Extended device status |
| 1 | Unsigned-8 | Slot 0: Device variable code |
| 2 | Enum | Slot 0: Device variable classification |
| 3 | Enum | Slot 0: Device variable unit |
| 4-7 | Float | Slot 0: Device variable value |
| 8 | Bits | Slot 0: Device variable status |
| 9 | Unsigned-8 | Slot 1: Device variable code |
| 10 | Enum | Slot 1: Device variable classification |
| 11 | Enum | Slot 1: Device variable unit |
| 12-15 | Float | Slot 1: Device variable value |
| 16 | Bits | Slot 1: Device variable status |
| 17 | Unsigned-8 | Slot 2: Device variable code |
| 18 | Enum | Slot 2: Device variable classification |
| 19 | Enum | Slot 2: Device variable unit |
| 20-23 | Float | Slot 2: Device variable value |
| 24 | Bits | Slot 2: Device variable status |
| 25 | Unsigned-8 | Slot 3: Device variable code |
| 26 | Enum | Slot 3: Device variable classification |
| 27 | Enum | Slot 3: Device variable unit |
| 28-31 | Float | Slot 3: Device variable value |
| 32 | Bits | Slot 3: Device variable status |
| 33-36(*) | Time | Data time stamp |

(*) Timestamp is always present, even if less than 4 device variables were requested. Its position is always at the end of the frame. Timestamp is in format 1/32 ms since midnight (Unsigned-32).

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |
| 30 | Warning | Command response truncated |

8.9. Read unique identifier associated with tag - 11 (0B_h)

This command reads fundamental information about the connected device.
The device will not respond to this command unless the short tag matches.

Request data bytes

| Byte | Format | Description |
|------|--------------|-------------|
| 0-5 | Packed ASCII | Tag |

Response data bytes

| Byte | Format | Description |
|-------|-------------|---|
| 0 | Unsigned-8 | 254 |
| 1-2 | Enum | Expanded device type |
| 3 | Unsigned-8 | Minimum request preambles |
| 4 | Unsigned-8 | Universal command revision |
| 5 | Unsigned-8 | Device revision |
| 6 | Unsigned-8 | Software revision |
| 7 | Unsigned-8 | Hardware revision / Physical signaling code |
| 8 | Bits | Flags |
| 9-11 | Unsigned-24 | Device ID |
| 12 | Unsigned-8 | Minimum response preambles |
| 13 | Unsigned-8 | Maximum number of device variables |
| 14-15 | Unsigned-16 | Configuration change counter |
| 16 | Bits | Extended field device status |
| 17-18 | Enum | Manufacturer identification code |
| 19-20 | Enum | Private label distributor code |
| 21 | Enum | Device profile |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.10. Read message - 12 (0C_h)

This command reads the message.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|--------------|-------------|
| 0-23 | Packed ASCII | Message |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.11. Read tag, descriptor and date - 13 (0D_h)

This command reads the short tag, descriptor and the date.
The short HART tag is completely separated from the long tag.
The short tag can be read and written via HART only.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|-------|--------------|-------------|
| 0-5 | Packed ASCII | Short tag |
| 6-17 | Packed ASCII | Descriptor |
| 18-20 | Unsigned-24 | Date |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.12. Read primary variable transducer information - 14 (0E_h)

This command reads the serial number, limits and the minimum span for the primary variable transducer. The serial number is always 0. As there is no minimum span, this value is set to NaN.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|-------|-------------|---------------------------------|
| 0-2 | Unsigned-24 | Transducer serial number |
| 3 | Enum | Transducer limits and span unit |
| 4-7 | Float | Upper transducer limit |
| 8-11 | Float | Lower transducer limit |
| 12-15 | Float | Minimum transducer span |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.13. Read device information - 15 (0F_h)

This command reads additional information of the device.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|-------|------------|---------------------------|
| 0 | Enum | PV alarm selection code |
| 1 | Enum | PV transfer function code |
| 2 | Enum | PV range value unit |
| 3-6 | Float | PV upper range value |
| 7-10 | Float | PV lower range value |
| 11-14 | Float | PV damping value [s] |
| 15 | Enum | Write protect code |
| 16 | Unsigned-8 | Reserved |
| 17 | Enum | PV analog channel flags |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.14. Read final assembly number - 16 (10_h)

This command reads the final assembly number of the device.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|-------------|-----------------------|
| 0-2 | Unsigned-24 | Final assembly number |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.15. Write message - 17 (11_h)

This command writes the message.

Request data bytes

| Byte | Format | Description |
|------|--------------|-------------|
| 0-23 | Packed ASCII | Message |

Response data bytes

| Byte | Format | Description |
|------|--------------|-------------|
| 0-23 | Packed ASCII | Message |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.16. Write tag, descriptor and date - 18 (12_h)

This command writes the short tag, descriptor and the date.

The short HART tag is completely separated from the long tag. The short tag can be read and written via HART only.

Request data bytes

| Byte | Format | Description |
|-------|--------------|-------------|
| 0-5 | Packed ASCII | Short tag |
| 6-17 | Packed ASCII | Descriptor |
| 18-20 | Unsigned-24 | Date |

Response data bytes

| Byte | Format | Description |
|-------|--------------|-------------|
| 0-5 | Packed ASCII | Short tag |
| 6-17 | Packed ASCII | Descriptor |
| 18-20 | Unsigned-24 | Date |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.17. Write final assembly number - 19 (13_h)

This command writes the final assembly number.

Request data bytes

| Byte | Format | Description |
|------|-------------|-----------------------|
| 0-2 | Unsigned-24 | Final assembly number |

Response data bytes

| Byte | Format | Description |
|------|-------------|-----------------------|
| 0-2 | Unsigned-24 | Final assembly number |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.18. Read long tag - 20 (14_h)

This command reads the long tag.

The long HART tag corresponds to the Liquiline tag shown on the display and in the setup menu (“Setup/General settings/TAG number”). This tag can be edited via HART and the local operating panel.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|---------|-------------|
| 0-31 | Latin-1 | Long tag |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.19. Read unique identifier associated with long tag - 21 (15_h)

This command reads fundamental information about the connected device.
The device will not respond to this command unless the long tag matches.

Request data bytes

| Byte | Format | Description |
|------|---------|-------------|
| 0-31 | Latin-1 | Tag |

Response data bytes

| Byte | Format | Description |
|-------|-------------|---|
| 0 | Unsigned-8 | 254 |
| 1-2 | Enum | Expanded device type |
| 3 | Unsigned-8 | Minimum request preambles |
| 4 | Unsigned-8 | Universal command revision |
| 5 | Unsigned-8 | Device revision |
| 6 | Unsigned-8 | Software revision |
| 7 | Unsigned-8 | Hardware revision / Physical signaling code |
| 8 | Bits | Flags |
| 9-11 | Unsigned-24 | Device ID |
| 12 | Unsigned-8 | Minimum response preambles |
| 13 | Unsigned-8 | Maximum number of device variables |
| 14-15 | Unsigned-16 | Configuration change counter |
| 16 | Bits | Extended field device status |
| 17-18 | Enum | Manufacturer identification code |
| 19-20 | Enum | Private label distributor code |
| 21 | Enum | Device profile |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.20. Write long tag - 22 (16_h)

This command writes the long tag.

The long HART tag corresponds to the Liquiline tag shown on the display and in the setup menu (“Setup/General settings/TAG number”). This tag can be edited via HART and the local operating panel.

Request data bytes

| Byte | Format | Description |
|------|---------|-------------|
| 0-31 | Latin-1 | Long tag |

Response data bytes

| Byte | Format | Description |
|------|---------|-------------|
| 0-31 | Latin-1 | Long tag |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.21. Read device variable - 33 (21_h)

This command reads up to 4 device variables.

Request data bytes

| Byte | Format | Description |
|------|------------|---|
| 0 | Unsigned-8 | Slot 0: Device variable code |
| 1 | Unsigned-8 | Slot 1: Device variable code (optional) |
| 2 | Unsigned-8 | Slot 2: Device variable code (optional) |
| 3 | Unsigned-8 | Slot 3: Device variable code (optional) |

Response data bytes

| Byte | Format | Description |
|-------|------------|-------------------------------|
| 0 | Unsigned-8 | Slot 0: Device variable code |
| 1 | Enum | Slot 0: Device variable unit |
| 2-5 | Float | Slot 0: Device variable value |
| 6 | Unsigned-8 | Slot 1: Device variable code |
| 7 | Enum | Slot 1: Device variable unit |
| 8-11 | Float | Slot 1: Device variable value |
| 12 | Unsigned-8 | Slot 2: Device variable code |
| 13 | Enum | Slot 2: Device variable unit |
| 14-17 | Float | Slot 2: Device variable value |
| 18 | Unsigned-8 | Slot 3: Device variable code |
| 19 | Enum | Slot 3: Device variable unit |
| 20-23 | Float | Slot 3: Device variable value |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |

8.22. Write primary variable damping value - 34 (22_h)

This command writes the primary variable damping value.

This value can also be set using the Liquiline local operating panel (“Setup/Sensor pH/Damping”).

Request data bytes

| Byte | Format | Description |
|------|--------|------------------------------------|
| 0-3 | Float | Primary variable damping value [s] |

Response data bytes

| Byte | Format | Description |
|------|--------|------------------------------------|
| 0-3 | Float | Primary variable damping value [s] |

Command specific response codes

| Code | Class | Description |
|------|---------|-------------------------------|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 8 | Warning | Set to nearest possible value |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.23. Write primary variable range values - 35 (23_h)

This command defines the relationship between the loop current and the primary variable. These values can also be set using the Liquiline local operating panel ("Setup/Current output/Current output 1/Low value" and "Setup/Current output/Current output 1/Upper value").

Request data bytes

| Byte | Format | Description |
|------|--------|------------------------------------|
| 0 | Enum | Range value unit |
| 1-4 | Float | Upper range value (value at 20 mA) |
| 5-8 | Float | Lower range value (value at 4 mA) |

Response data bytes

| Byte | Format | Description |
|------|--------|------------------------------------|
| 0 | Enum | Range value unit |
| 1-4 | Float | Upper range value (value at 20 mA) |
| 5-8 | Float | Lower range value (value at 4 mA) |

Command specific response codes

| Code | Class | Description |
|------|---------|---|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 9 | Error | Lower range value too high |
| 10 | Error | Lower range value too low |
| 11 | Error | Upper range value too high |
| 12 | Error | Upper range value too low |
| 13 | Error | Upper and lower range value out of limits |
| 14 | Warning | Span too small |
| 16 | Error | Access restricted |
| 18 | Error | Invalid units code |
| 32 | Error | Busy |

8.24. Set primary variable upper range value - 36 (24_h)

As soon as this command is issued, the present primary variable value is copied into the upper range value. The upper range can be set below the lower range.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |
| 7 | Error | In write protect mode |
| 9 | Error | Applied process too high |
| 10 | Error | Applied process too low |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.25. Set primary variable lower range value - 37 (25_h)

As soon as this command is issued, the present primary variable value is copied into the lower range value. At the same time, the upper range will be shifted to keep the span constant. The lower range can be set above the upper range.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |
| 7 | Error | In write protect mode |
| 9 | Error | Applied process too high |
| 10 | Error | Applied process too low |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.26. Reset configuration changed flag - 38 (26_h)

This command will reset one of the configuration changed flags, depending on the sending master. If the configuration change counter value is sent, the device will check it versus the current counter value. If both match, the configuration changed flag will be reset.

Request data bytes

| Byte | Format | Description |
|------|-------------|---|
| 0-1 | Unsigned-16 | Configuration change counter (optional) |

Response data bytes

| Byte | Format | Description |
|------|-------------|------------------------------|
| 0-1 | Unsigned-16 | Configuration change counter |

Command specific response codes

| Code | Class | Description |
|------|---------|---------------------------------------|
| 0 | Success | No command specific errors |
| 7 | Error | In write protect mode |
| 9 | Error | Configuration change counter mismatch |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.27. Set simulation current - 40 (28_h)

This command sets a certain fixed current on current output 1 (current simulation).

To disable simulation mode a value of 0.0 has to be set.

The simulation mode and the current value can also be set using the Liquiline local operating panel ("Diag/Service/Simulation/Current output 1").

Simulation values in the range from 3.6 to 21.5 mA are valid.

Request data bytes

| Byte | Format | Description |
|------|--------|--------------------------|
| 0-3 | Float | Fixed current value [mA] |

Response data bytes

| Byte | Format | Description |
|------|--------|--------------------------|
| 0-3 | Float | Fixed current value [mA] |

Command specific response codes

| Code | Class | Description |
|------|---------|--|
| 0 | Success | No command specific errors |
| 3 | Error | Passed parameter too large |
| 4 | Error | Passed parameter too small |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 11 | Error | Loop current not active (multidrop mode) |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.28. Perform self-test - 41 (29_h)

This command answers the request, only. It is implemented for compatibility reasons.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.29. Reset device - 42 (2A_h)

This command triggers a reset. Liquiline will need about 30 seconds to initialize and to be back online.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |
| 16 | Error | Access restricted |

8.30. Write primary variable unit - 44 (2C_h)

This command selects the unit in which the primary variable and its range will be returned. Possible units depending on different operating modes are listed in chapter 5.

Request data bytes

| Byte | Format | Description |
|------|--------|-----------------------|
| 0 | Enum | Primary variable unit |

Response data bytes

| Byte | Format | Description |
|------|--------|-----------------------|
| 0 | Enum | Primary variable unit |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.31. Trim loop current zero - 45 (2D_h)

Command 45 and 46 can do a recalibration of the current output 1 loop.

These commands will not overwrite the factory current output calibration, but do a second user calibration. To restore the original values a "Factory default" in the Liquiline diagnostics menu has to be executed or command 45 with value 0.0 mA has to be sent.

Command 45 recalibrates the lower range of the current output.

Before sending command 45 command 40 with a value of 4 mA has to be sent.

The value to be sent with command 45 must be measured with an external ampere meter.

Request data bytes

| Byte | Format | Description |
|------|--------|---------------------------------------|
| 0-3 | Float | Externally measured loop current [mA] |

Response data bytes

| Byte | Format | Description |
|------|--------|-------------------|
| 0-3 | Float | Loop current [mA] |

Command specific response codes

| Code | Class | Description |
|------|---------|--|
| 0 | Success | No command specific errors |
| 3 | Error | Passed parameter too large |
| 4 | Error | Passed parameter too small |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 9 | Error | Incorrect loop current mode or value |
| 11 | Error | Loop current not active (multidrop mode) |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.32. Trim loop current gain - 46 (2E_h)

Command 45 and 46 can do a recalibration of the current output 1 loop.

These commands will not overwrite the factory current output calibration, but do a second user calibration. To restore the original values a "Factory default" in the Liquiline diagnostics menu has to be executed or command 45 with value 0.0 mA has to be sent.

Command 46 recalibrates the upper range of the current output.

Before sending command 46 command 40 with a value of 20 mA has to be sent.

The value to be sent with command 46 must be measured with an external ampere meter.

Request data bytes

| Byte | Format | Description |
|------|--------|---------------------------------------|
| 0-3 | Float | Externally measured loop current [mA] |

Response data bytes

| Byte | Format | Description |
|------|--------|-------------------|
| 0-3 | Float | Loop current [mA] |

Command specific response codes

| Code | Class | Description |
|------|---------|--|
| 0 | Success | No command specific errors |
| 3 | Error | Passed parameter too large |
| 4 | Error | Passed parameter too small |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 9 | Error | Incorrect loop current mode or value |
| 11 | Error | Loop current not active (multidrop mode) |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.33. Read additional status - 48 (30_h)

This command returns device status information not included in the response code or device status byte.

A description of the single bits meanings can be found in chapter 7.7.

If data is included when sending command 48 this data is checked versus the current device status. If all data matches the “more status available” flag is reset.

Request data bytes

| Byte | Format | Description |
|-------|--------|-------------------------------------|
| 0-5 | Bits | See chapter 7.7 (optional) |
| 6 | Bits | Extended device status (optional) |
| 7 | Bits | Device operating mode (optional) |
| 8 | Bits | Standardized status 0 (optional) |
| 9 | Bits | Standardized status 1 (optional) |
| 10 | Bits | Analog channel saturated (optional) |
| 11 | Bits | Standardized status 2 (optional) |
| 12 | Bits | Standardized status 3 (optional) |
| 13 | Bits | Analog channel fixed (optional) |
| 14-24 | Bits | See chapter 7.7 (optional) |

Response data bytes

| Byte | Format | Description |
|-------|--------|--------------------------|
| 0-5 | Bits | See chapter 7.7 |
| 6 | Bits | Extended device status |
| 7 | Bits | Device operating mode |
| 8 | Bits | Standardized status 0 |
| 9 | Bits | Standardized status 1 |
| 10 | Bits | Analog channel saturated |
| 11 | Bits | Standardized status 2 |
| 12 | Bits | Standardized status 3 |
| 13 | Bits | Analog channel fixed |
| 14-24 | Bits | See chapter 7.7 |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.34. Read dynamic variable assignments - 50 (32_h)

This command returns the mapping between device and dynamic variables (see chapter 6.2).

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|------------|---|
| 0 | Unsigned-8 | Device variable assigned to primary variable |
| 1 | Unsigned-8 | Device variable assigned to secondary variable |
| 2 | Unsigned-8 | Device variable assigned to tertiary variable |
| 3 | Unsigned-8 | Device variable assigned to quaternary variable |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.35. Write dynamic variable assignments - 51 (33_h)

This command sets the mapping between device and dynamic variables (see chapter 6.2).

Request data bytes

| Byte | Format | Description |
|------|------------|--|
| 0 | Unsigned-8 | Device variable to assign to primary variable |
| 1 | Unsigned-8 | Device variable to assign to secondary variable |
| 2 | Unsigned-8 | Device variable to assign to tertiary variable |
| 3 | Unsigned-8 | Device variable to assign to quaternary variable |

Response data bytes

| Byte | Format | Description |
|------|------------|---|
| 0 | Unsigned-8 | Device variable assigned to primary variable |
| 1 | Unsigned-8 | Device variable assigned to secondary variable |
| 2 | Unsigned-8 | Device variable assigned to tertiary variable |
| 3 | Unsigned-8 | Device variable assigned to quaternary variable |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.36. Write device variable unit - 53 (35_h)

This command selects the unit in which a certain device variable and its range will be returned. Possible units depending on different operating modes are listed in chapter 5.

Request data bytes

| Byte | Format | Description |
|------|------------|----------------------|
| 0 | Unsigned-8 | Device variable code |
| 1 | Enum | Device variable unit |

Response data bytes

| Byte | Format | Description |
|------|------------|----------------------|
| 0 | Unsigned-8 | Device variable code |
| 1 | Enum | Device variable unit |

Command specific response codes

| Code | Class | Description |
|------|---------|------------------------------|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 11 | Error | Invalid device variable code |
| 12 | Error | Invalid unit code |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.37. Read device variable information - 54 (36_h)

This command reads more information about a device variable.

Device variable transducer serial number and family classification are not supported and will return 0.

Request data bytes

| Byte | Format | Description |
|------|------------|----------------------|
| 0 | Unsigned-8 | Device variable code |

Response data bytes

| Byte | Format | Description |
|-------|-------------|---------------------------------|
| 0 | Unsigned-8 | Device variable code |
| 1-3 | Unsigned-24 | Transducer serial number |
| 4 | Enum | Transducer limits and span unit |
| 5-8 | Float | Upper transducer limit |
| 9-12 | Float | Lower transducer limit |
| 13-16 | Float | Damping value [s] |
| 17-20 | Float | Minimum span |
| 21 | Enum | Device variable classification |
| 22 | Enum | Device variable family |
| 23-26 | Time | Acquisition period |
| 27 | Bits | Device variable properties |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |

8.38. Write number of response preambles - 59 (3B_h)

This command sets the number of response preambles.

Request data bytes

| Byte | Format | Description |
|------|------------|------------------------------|
| 0 | Unsigned-8 | Number of response preambles |

Response data bytes

| Byte | Format | Description |
|------|------------|------------------------------|
| 0 | Unsigned-8 | Number of response preambles |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 3 | Error | Passed parameter too large |
| 4 | Error | Passed parameter too small |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.39. Lock device - 71 (47_h)

This command locks the device to one HART master and prevents changes from the other master and the operating panel.

If the device is locked by this command, the local operating panel does not respond to any user action.

A key icon appears in the status bar on the top of the display.

If a permanent lock was set and the device loses power, the lock will be set again as soon as the first HART frame is detected. If a permanent lock has to be reset, the HART master the lock was set with has to be used. If this is not possible then Liquiline has to be restarted without HART communication and a factory default has to be executed.

“Lock all” prevents any master from writing. Then any master can reset the lock, though.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| 0 | Enum | Lock code |

Response data bytes

| Byte | Format | Description |
|------|--------|-------------|
| 0 | Enum | Lock code |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |
| 10 | Error | Invalid lock code |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

Lock code

Unlock: 0

Lock temporary: 1

Lock permanent: 2

Lock all: 3

8.40. Squawk - 72 (48_h)

This command can be used to invert the display of Liquiline.

If no data byte is sent with the command the display is reset to normal condition after 10 seconds.
This command can be used to identify a certain device in large installations.

Request data bytes

| Byte | Format | Description |
|------|--------|------------------------|
| 0 | Enum | Squawk code (optional) |

Response data bytes

| Byte | Format | Description |
|------|--------|-------------|
| 0 | Enum | Squawk code |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

Squawk code

| | |
|-------------|---|
| Off: | 0 |
| On: | 1 |
| 10 seconds: | 2 |

8.41. Find device - 73 (49_h)

The device will not respond to this command unless the user sets “Setup/General settings/Bus find response” to “on”.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|-------|-------------|---|
| 0 | Unsigned-8 | 254 |
| 1-2 | Enum | Expanded device type |
| 3 | Unsigned-8 | Minimum request preambles |
| 4 | Unsigned-8 | Universal command revision |
| 5 | Unsigned-8 | Device revision |
| 6 | Unsigned-8 | Software revision |
| 7 | Unsigned-8 | Hardware revision / Physical signaling code |
| 8 | Bits | Flags |
| 9-11 | Unsigned-24 | Device ID |
| 12 | Unsigned-8 | Minimum response preambles |
| 13 | Unsigned-8 | Maximum number of device variables |
| 14-15 | Unsigned-16 | Configuration change counter |
| 16 | Bits | Extended field device status |
| 17-18 | Enum | Manufacturer identification code |
| 19-20 | Enum | Private label distributor code |
| 21 | Enum | Device profile |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.42. Read lock device state - 76 (4C_h)

This command reads the current state of the device lock.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|--------|-------------|
| 0 | Bits | Lock state |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

Lock state

| | |
|---------------------------|---|
| Locked: | 1 |
| Permanent: | 2 |
| Locked by primary master: | 4 |
| All locked: | 8 |

8.43. Set real time clock - 89 (59_h)

This command sets the real time clock of Liquiline or determines the roundtrip time for setting the real time clock.

Request data bytes

| Byte | Format | Description |
|------|-------------|---------------|
| 0 | Enum | Time set code |
| 1-3 | Date | Date to set |
| 4-7 | Time | Time to set |
| 8-9 | Unsigned-16 | Always 0 |

Response data bytes

| Byte | Format | Description |
|------|--------|----------------|
| 0 | Enum | Time set code |
| 1-3 | Date | Liquiline date |
| 4-7 | Time | Liquiline time |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid time set code |
| 3 | Error | Passed parameter too large |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 9 | Error | Invalid date |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

Time set code

Read receive time: 0

Write date and time: 1

Time is in format 1/32 ms since midnight (Unsigned-32).

Date is in format day, month, (year -1900) (Unsigned-24).

8.44. Read real time clock - 90 (5A_h)

This command reads the current date and time from Liquiline.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|-------|--------|-------------------------|
| 0-2 | Date | Liquiline date |
| 3-6 | Time | Liquiline time |
| 7-9 | Date | Date clock was last set |
| 10-13 | Time | Time clock was last set |
| 14 | Bits | Flags |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

Flags

Nonvolatile clock: 1

Clock uninitialized: 2

8.45. Read communication statistics - 95 (5F_h)

This command reads the current communication statistics. The counters roll over to 0 if they reach their maximum. This will happen about once a day, assuming one communication per second.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|-------------|----------------------------------|
| 0-1 | Unsigned-16 | Number of HART requests received |
| 2-3 | Unsigned-16 | Number of HART responses sent |
| 4-5 | Unsigned-16 | Always 0 |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.46. Write primary variable alarm code - 100 (64_h)

This command will set the current output 1 behavior if condensed status is “F”.
 The parameters “Setup/General settings/Alarms/Alarm message/Alarm active” and
 “Setup/General settings/Alarms/Alarm message/Alarm value” will be set accordingly.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------------------|
| 0 | Enum | PV alarm selection code |

Response data bytes

| Byte | Format | Description |
|------|--------|-------------------------|
| 0 | Enum | PV alarm selection code |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

Alarm selection code

High (fixed 21.5 mA): 0
 Low (fixed 3.6 mA): 1
 Hold last value: 239 (EF_h)

8.47. Read parameter group - 140 (8C_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|------------|-------------|
| 0 | Unsigned-8 | Group index |

Response data bytes

| Byte | Format | Description |
|------|----------------|-----------------|
| 0 | Unsigned-8 | Group index |
| 1-n | Unsigned-8 [] | Parameter group |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |

8.48. Set diagnostic code behavior - 150 (96_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|-------------|------------------------------------|
| 0-1 | Unsigned-16 | Diagnostic code |
| 2 | Unsigned-8 | Extended device status code to set |

Response data bytes

| Byte | Format | Description |
|------|-------------|-----------------------------|
| 0-1 | Unsigned-16 | Diagnostic code |
| 2 | Unsigned-8 | Extended device status code |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.49. Read diagnostic code behavior - 151 (97_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|-------------|-----------------|
| 0-1 | Unsigned-16 | Diagnostic code |

Response data bytes

| Byte | Format | Description |
|------|-------------|-----------------------------|
| 0-1 | Unsigned-16 | Diagnostic code |
| 2 | Unsigned-8 | Extended device status code |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |

8.50. Set logbook control - 160 (A0_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|-------------|--------------------|
| 0 | Unsigned-8 | Transfer ID number |
| 1 | Unsigned-8 | Access type |
| 2 | Unsigned-8 | Attribute |
| 3-6 | Unsigned-32 | Data |

Response data bytes

| Byte | Format | Description |
|------|-------------|--------------------|
| 0 | Unsigned-8 | Transfer ID number |
| 1 | Unsigned-8 | Access type |
| 2 | Unsigned-8 | Attribute |
| 3-6 | Unsigned-32 | Data |
| 7 | Unsigned-8 | Status |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.51. Read logbook data - 161 (A1_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|-------------|--------------------|
| 0 | Unsigned-8 | Transfer ID number |
| 1 | Unsigned-8 | Access type |
| 2 | Unsigned-8 | Status |
| 3-43 | Unsigned-32 | Data |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.52. Read extended communication statistics - 170 (AA_h)

This command reads the current extended communication statistics of Liquiline. The counters roll over to 0 if they reach their maximum.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|-------|-------------|----------------------------------|
| 0-3 | Unsigned-32 | Number of HART requests received |
| 4-7 | Unsigned-32 | Number of HART responses sent |
| 8-11 | Unsigned-32 | Number of parity errors |
| 12-15 | Unsigned-32 | Number of framing errors |
| 16-19 | Unsigned-32 | Number of overrun errors |
| 20-23 | Unsigned-32 | Number of overflow errors |
| 24-27 | Unsigned-32 | Number of checksum errors |
| 28-31 | Unsigned-32 | Number of busies |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.53. Write parameter - 211 (D3_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|----------------|-----------------|
| 0-1 | Unsigned-16 | Parameter ID |
| 2 | Unsigned-8 | Parameter set |
| 3-n | Unsigned-8 [] | Parameter value |

Response data bytes

| Byte | Format | Description |
|------|----------------|-----------------|
| 0-1 | Unsigned-16 | Parameter ID |
| 2 | Unsigned-8 | Parameter set |
| 3-n | Unsigned-8 [] | Parameter value |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.54. Write parameter attribute - 212 (D4_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|----------------|-----------------|
| 0-1 | Unsigned-16 | Parameter ID |
| 2 | Unsigned-8 | Parameter set |
| 3-6 | Unsigned-32 | Attribute code |
| 7-n | Unsigned-8 [] | Parameter value |

Response data bytes

| Byte | Format | Description |
|------|----------------|-----------------|
| 0-1 | Unsigned-16 | Parameter ID |
| 2 | Unsigned-8 | Parameter set |
| 3-6 | Unsigned-32 | Attribute code |
| 7-n | Unsigned-8 [] | Parameter value |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.55. Read parameter - 213 (D5_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|-------------|---------------|
| 0-1 | Unsigned-16 | Parameter ID |
| 2 | Unsigned-8 | Parameter set |

Response data bytes

| Byte | Format | Description |
|------|----------------|-----------------|
| 0-1 | Unsigned-16 | Parameter ID |
| 2 | Unsigned-8 | Parameter set |
| 3-n | Unsigned-8 [] | Parameter value |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |

8.56. Read parameter attribute - 214 (D6_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|-------------|----------------|
| 0-1 | Unsigned-16 | Parameter ID |
| 2 | Unsigned-8 | Parameter set |
| 3-6 | Unsigned-32 | Attribute code |

Response data bytes

| Byte | Format | Description |
|------|----------------|-----------------|
| 0-1 | Unsigned-16 | Parameter ID |
| 2 | Unsigned-8 | Parameter set |
| 3-6 | Unsigned-32 | Attribute code |
| 7-n | Unsigned-8 [] | Parameter value |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |
| 16 | Error | Access restricted |

8.57. Read float parameter - 215 (D7_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|-------------|---------------|
| 0-1 | Unsigned-16 | Parameter ID |
| 2 | Unsigned-8 | Parameter set |

Response data bytes

| Byte | Format | Description |
|------|-------------|-----------------|
| 0-1 | Unsigned-16 | Parameter ID |
| 2 | Unsigned-8 | Parameter set |
| 3 | Unsigned-8 | Unit table |
| 4 | Unsigned-8 | Unit |
| 5-8 | Float | Parameter value |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |
| 16 | Error | Access restricted |

8.58. Write float parameter - 216 (D8_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|-------------|-------------------|
| 0-1 | Unsigned-16 | Parameter ID |
| 2 | Unsigned-8 | Parameter set |
| 3 | Unsigned-8 | Unit table number |
| 4 | Unsigned-8 | Unit |
| 5-8 | Float | Parameter value |

Response data bytes

| Byte | Format | Description |
|------|-------------|-------------------|
| 0-1 | Unsigned-16 | Parameter ID |
| 2 | Unsigned-8 | Parameter set |
| 3 | Unsigned-8 | Unit table number |
| 4 | Unsigned-8 | Unit |
| 5-8 | Float | Parameter value |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.59. Reset device - 217 (D9_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|------------|-------------|
| 0 | Unsigned-8 | Reset code |

Response data bytes

| Byte | Format | Description |
|------|------------|-------------|
| 0 | Unsigned-8 | Reset code |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.60. Read software version - 226 (E2_h)

This command reads the software version.

Request data bytes

| Byte | Format | Description |
|------|------------|-------------------------|
| 0 | Unsigned-8 | Module index (always 0) |

Response data bytes

| Byte | Format | Description |
|------|------------|-------------------------|
| 0 | Unsigned-8 | Module index |
| 1-16 | Latin-1 | Software version string |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |

8.61. Read serial number - 227 (E3_h)

This command reads the serial number.

Request data bytes

| Byte | Format | Description |
|------|------------|-------------------------|
| 0 | Unsigned-8 | Module index (always 0) |

Response data bytes

| Byte | Format | Description |
|------|------------|----------------------|
| 0 | Unsigned-8 | Module index |
| 1-16 | Latin-1 | Serial number string |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |

8.62. Read extended order code - 228 (E4_h)

This command reads the extended order code. As the device does not support the extended order code the normal order code is returned.

Request data bytes

| Byte | Format | Description |
|------|------------|------------------|
| 0 | Unsigned-8 | Index (always 0) |

Response data bytes

| Byte | Format | Description |
|------|------------|-------------------|
| 0 | Unsigned-8 | Index |
| 1-20 | Latin-1 | Order code string |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |

8.63. Write serial number - 229 (E5_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|------------|----------------------|
| 0 | Unsigned-8 | Module index |
| 1-16 | Latin-1 | Serial number string |

Response data bytes

| Byte | Format | Description |
|------|------------|----------------------|
| 0 | Unsigned-8 | Module index |
| 1-16 | Latin-1 | Serial number string |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.64. Write extended order code - 230 (E6_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|------------|-------------------|
| 0 | Unsigned-8 | Module index |
| 1-20 | Latin-1 | Order code string |

Response data bytes

| Byte | Format | Description |
|------|------------|-------------------|
| 0 | Unsigned-8 | Module index |
| 1-20 | Latin-1 | Order code string |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.65. Check device status - 231 (E7_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|------------|--------------|
| 0 | Unsigned-8 | Module index |

Response data bytes

| Byte | Format | Description |
|------|-------------|--------------------------------------|
| 0 | Unsigned-8 | Module index |
| 1 | Unsigned-8 | Device status |
| 2-3 | Unsigned-16 | Number of the highest priority error |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |

8.66. Write service code - 232 (E8_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|-------------|---------------------|
| 0-1 | Unsigned-16 | Service access code |

Response data bytes

| Byte | Format | Description |
|------|-------------|---------------------|
| 0-1 | Unsigned-16 | Service access code |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.67. Read order code - 233 (E9_h)

This command reads the order code.

Request data bytes

| Byte | Format | Description |
|------|------------|-------------------------|
| 0 | Unsigned-8 | Module index (always 0) |

Response data bytes

| Byte | Format | Description |
|------|------------|-------------------|
| 0 | Unsigned-8 | Module index |
| 1-20 | Latin-1 | Order code string |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |

8.68. Read ENP version - 234 (EA_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|------------|-------------------------|
| 0 | Unsigned-8 | Module index (always 0) |

Response data bytes

| Byte | Format | Description |
|------|------------|--------------------|
| 0 | Unsigned-8 | Module index |
| 1-16 | Latin-1 | ENP version string |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |

8.69. Write order code - 235 (EB_h)

This command is for Endress+Hauser internal use, only.

Request data bytes

| Byte | Format | Description |
|------|------------|-------------------------|
| 0 | Unsigned-8 | Module index (always 0) |
| 1-20 | Latin-1 | Order code string |

Response data bytes

| Byte | Format | Description |
|------|------------|-------------------|
| 0 | Unsigned-8 | Module index |
| 1-20 | Latin-1 | Order code string |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.70. Read startup behavior - 236 (EC_h)

This command reads the startup behavior of Liquiline.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|-------|-------------|---|
| 0-3 | Float | Minimal startup voltage [V] |
| 4-7 | Float | Startup current [mA] |
| 8-9 | Unsigned-16 | Time until HART communication possible [s] |
| 10-13 | Float | Minimal operating voltage [V] |
| 14-17 | Float | Multidrop current [mA] |
| 18-19 | Unsigned-16 | Time until measurement values are present [s] |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.71. Read device location - 516 (0204_h)

This command reads the location of Liquiline. Content has to be set by user using command 517.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|--------|----------------------------|
| 0-3 | Float | Latitude [°]. N = +, S = - |
| 4-7 | Float | Longitude [°] E = +, W = - |
| 8 | Enum | Location method/quality |
| 9-12 | Float | Altitude [m] |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.72. Write device location - 517 (0205_h)

This command writes the device location.

Request data bytes

| Byte | Format | Description |
|------|--------|----------------------------|
| 0-3 | Float | Latitude [°]. N = +, S = - |
| 4-7 | Float | Longitude [°] E = +, W = - |
| 8 | Enum | Location method/quality |
| 9-12 | Float | Altitude [m] |

Response data bytes

| Byte | Format | Description |
|------|--------|----------------------------|
| 0-3 | Float | Latitude [°]. N = +, S = - |
| 4-7 | Float | Longitude [°] E = +, W = - |
| 8 | Enum | Location method/quality |
| 9-12 | Float | Altitude [m] |

Command specific response codes

| Code | Class | Description |
|------|---------|--------------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid location method |
| 3 | Error | Latitude or longitude to large |
| 4 | Error | Latitude or longitude to small |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

Location method

| | |
|---------------------------|---|
| No fix: | 0 |
| GPS or SPS fix: | 1 |
| Differential GPS fix: | 2 |
| PPS fix: | 3 |
| RTK fixed solution: | 4 |
| RTK float solution: | 5 |
| Estimated dead reckoning: | 6 |
| Manual input mode: | 7 |
| Simulation mode: | 8 |

8.73. Read location description - 518 (0206_h)

This command reads the location description.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|---------|----------------------|
| 0-31 | Latin-1 | Location description |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.74. Write location description - 519 (0207_h)

This command writes the location description.

Request data bytes

| Byte | Format | Description |
|------|---------|----------------------|
| 0-31 | Latin-1 | Location description |

Response data bytes

| Byte | Format | Description |
|------|---------|----------------------|
| 0-31 | Latin-1 | Location description |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.75. Read process unit tag - 520 (0208_h)

This command reads the process unit tag.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|---------|------------------|
| 0-31 | Latin-1 | Process unit tag |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |

8.76. Write process unit tag - 521 (0209_h)

This command writes the process unit tag.

Request data bytes

| Byte | Format | Description |
|------|---------|------------------|
| 0-31 | Latin-1 | Process unit tag |

Response data bytes

| Byte | Format | Description |
|------|---------|------------------|
| 0-31 | Latin-1 | Process unit tag |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.77. Read condensed status mapping array - 523 (020B_h)

This command reads the status mapping array or a part of it.

The status mapping array determines the devices behavior depending on the highest priority diagnostic message.

The default mapping can be found in chapter 7.7.

No more than 84 status maps can be read at once.

Request data bytes

| Byte | Format | Description |
|------|------------|---|
| 0 | Unsigned-8 | Starting status map index (see chapter 7.7) |
| 1 | Unsigned-8 | Number of entries to read |

Response data bytes

| Byte | Format | Description |
|--------------|------------|-------------------------------------|
| 0 | Unsigned-8 | Actual starting status map index |
| 1 | Unsigned-8 | Number of entries actually returned |
| 2 (bits 0-3) | Enum | First status map code |
| 2 (bits 4-7) | Enum | Second status map code |
| 3 (bits 0-3) | Enum | Third status map code |
| ... | Enum | Remaining status map codes |

Command specific response codes

| Code | Class | Description |
|------|---------|-------------------------------|
| 0 | Success | No command specific errors |
| 5 | Error | Too few data bytes received |
| 8 | Warning | Set to nearest possible value |

8.78. Write condensed status mapping array - 524 (020C_h)

This command writes the status mapping array or a part of it.

The status mapping array determines the devices behavior depending on the highest priority diagnostic message.

The default mapping can be found in chapter 7.7.

Only index 8 - 55 and 120 - 172 can be changed.

At least 2 status maps must be written.

Request data bytes

| Byte | Format | Description |
|--------------|------------|---|
| 0 | Unsigned-8 | Starting status map index (see chapter 7.7) |
| 1 | Unsigned-8 | Number of entries to write |
| 2 (bits 0-3) | Enum | First status map code |
| 2 (bits 4-7) | Enum | Second status map code |
| 3 (bits 0-3) | Enum | Third status map code |
| ... | Enum | Remaining status map codes |

Response data bytes

| Byte | Format | Description |
|--------------|------------|-------------------------------------|
| 0 | Unsigned-8 | Actual starting status map index |
| 1 | Unsigned-8 | Number of entries actually returned |
| 2 (bits 0-3) | Enum | First status map code |
| 2 (bits 4-7) | Enum | Second status map code |
| 3 (bits 0-3) | Enum | Third status map code |
| ... | Enum | Remaining status map codes |

Command specific response codes

| Code | Class | Description |
|------|---------|--|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 8 | Warning | Set to nearest possible value |
| 9 | Error | Starting status map index must be even |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

Condensed status mapping code

| | |
|----|---|
| N: | 0 |
| M: | 1 |
| F: | 3 |
| S: | 4 |
| C: | 5 |

8.79. Reset condensed status map - 525 (020D_h)

This command restores the condensed status map factory settings.

Request data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Response data bytes

| Byte | Format | Description |
|------|--------|-------------|
| None | | |

Command specific response codes

| Code | Class | Description |
|------|---------|----------------------------|
| 0 | Success | No command specific errors |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

8.80. Write status simulation - 526 (020E_h)

This command enables or disables status simulation.

Request data bytes

| Byte | Format | Description |
|------|--------|------------------------|
| 0 | Enum | Status simulation mode |

Response data bytes

| Byte | Format | Description |
|------|--------|------------------------|
| 0 | Enum | Status simulation mode |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

Status simulation mode

| | |
|-----------|---|
| Disabled: | 0 |
| Enabled: | 1 |

8.81. Simulate status bit - 527 (020F_h)

This command sets or resets a specific status bit (see chapter 7.7) while simulation mode is enabled.

Request data bytes

| Byte | Format | Description |
|------|------------|------------------------------|
| 0 | Unsigned-8 | Index of bit to be simulated |
| 1 | Enum | Simulated value code |

Response data bytes

| Byte | Format | Description |
|------|------------|------------------------------|
| 0 | Unsigned-8 | Index of bit to be simulated |
| 1 | Enum | Simulated value code |

Command specific response codes

| Code | Class | Description |
|------|---------|-----------------------------|
| 0 | Success | No command specific errors |
| 2 | Error | Invalid selection |
| 5 | Error | Too few data bytes received |
| 7 | Error | In write protect mode |
| 16 | Error | Access restricted |
| 32 | Error | Busy |

Simulated value

Reset: 0
Set: 1

9. Performance

9.1. Sampling rates

All sensors sample: ≥1 per second

All device variables digital value calculation: ≥1 per second

All analog outputs update: ≥1 per second

9.2. Power-up

On power-up, the transmitter has to initialize itself, which takes up to 30 seconds. During this period, the device will not respond to HART commands.

As soon as the measurement screen appears on the display, Liquiline is ready to communicate via HART, no matter if there are errors present or not.

Fixed current and simulation modes are cancelled by power loss.

9.3. Reset

Command 42 ("Device Reset") causes the device to reset. The resulting restart is identical to the normal power up sequence.

9.4. Self-test

This field device does not support a self-test.

9.5. Command response times

Minimum: 0 ms

Typical: 50 ms

Maximum: 200 ms

9.6. Busy and delayed response

The Liquiline will respond with "busy" status whenever the requested action occupies the CPU for more than 200 ms.

Delayed response mechanism is not used.

9.7. Long messages

The largest data field can be 44 bytes.

9.8. Nonvolatile memory

The device's configuration parameters are saved into a flash memory. New data is written to this memory by a special flash handler. Data will not be saved immediately on execution of a write command, but with a short delay or at power loss.

9.9. Operating modes

Fixed current mode is implemented, using command 40. This mode is cleared by power or reset.

9.10. Write protection

Write protection can be set on Liquiline's operating panel "Setup/General settings/Bus write protection". When write protection is enabled all HART write commands will be blocked and return response code 7. Write protection has no influence on the local operating panel.

9.11. Burst mode

Liquiline does not support burst mode.

9.12. Catch device variable

Liquiline does not support device variable catching.

10. Annex A: Capability checklist

| | |
|---------------------------------------|--|
| Manufacturer, model and revision: | Endress+Hauser Liquiline pHORP rev. 4 |
| Device type: | Transmitter |
| HART revision: | 7 |
| Device description available: | Yes |
| Number and type of sensors: | 1 or 2 pH/redox sensors, 1 temperature sensor (optional) |
| Number and type of actuators: | 0 |
| Number and type of host side signals: | 2x 4 20 mA analog |
| Number of device variables: | 7.5 |
| Number of dynamic variables: | 4 |
| Mappable dynamic variables: | Yes / 4 |
| Number of common practice commands: | 35 |
| Number of device specific commands: | 24 |
| Bits of additional device status: | 108 |
| Alternative operating modes: | No |
| Burst mode: | No |
| Write protection: | Yes |
| Condensed status: | Yes |

11. Annex B: Default configuration

Please refer to the Operating Instructions.

12. Annex C: Revision history

Rev. 1, 07-Jan-2015: Initial revision
Rev. 2, 07-Aug-2015: Added device variables 7 and 8.
Rev. 3, 31-May-2016: Fixed additional device status table
Rev. 4, 04-Apr-2017 Added bits to additional status

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