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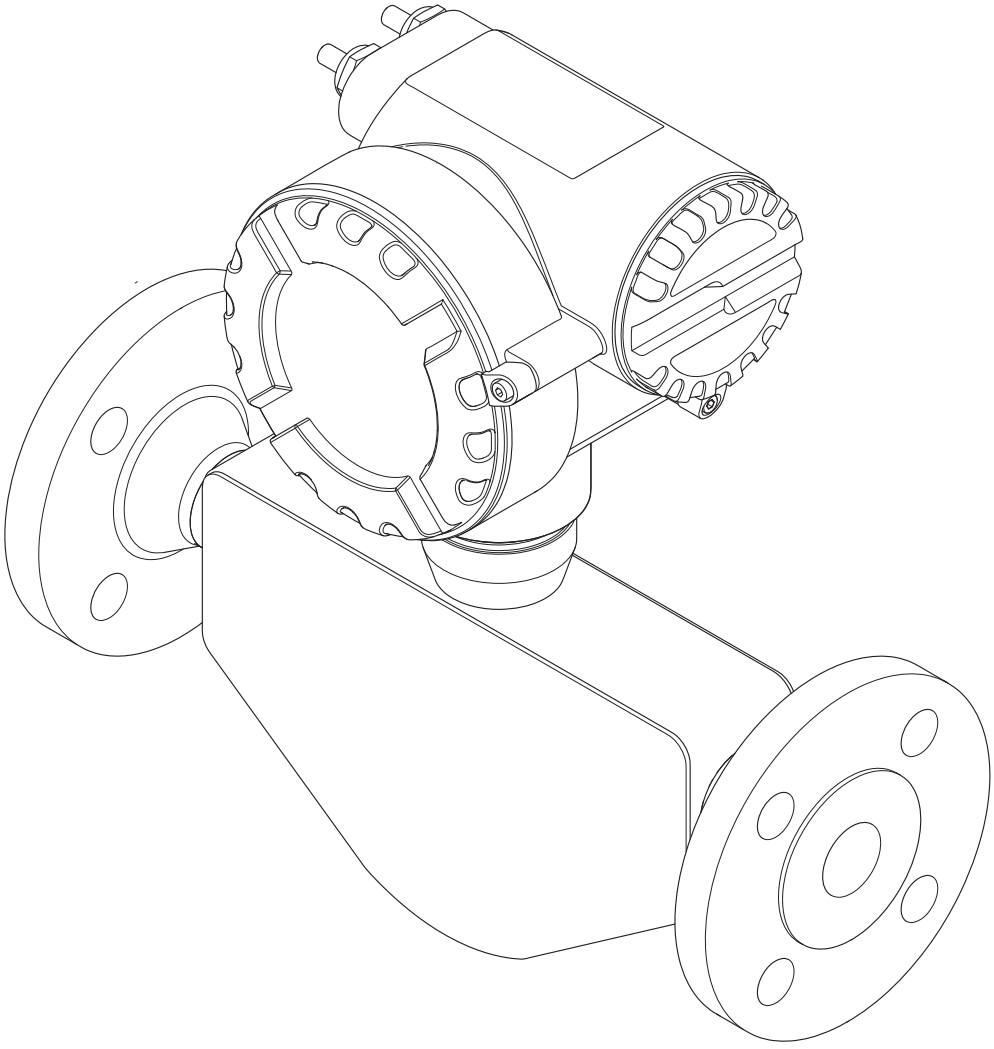
Valid as of version
V 1.01.xx (device software)

Operating Instructions
LPGmass
Modbus RS485

Coriolis flowmeter
For LPG (Liquified Petroleum Gas) applications



Endress+Hauser
People for Process Automation

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1 Safety

1.1 Designated use

The measuring instrument described in these Operating Instructions is to be used for measuring the mass or volume flow of liquified petroleum gas (LPG).
The mass and volume flow measurement of other fluids is also possible, but LPG-specific functions are not applicable.
Resulting from incorrect use or from use other than that designated the operational safety of the measuring devices can be suspended. The manufacturer accepts no liability for damages being produced from this.

1.2 Installation, commissioning and operation

Note the following points:
- Installation, connection to the electricity supply, commissioning and maintenance of the measuring instrument must be carried out by trained, qualified specialists authorized to perform such work by the facility's owner-operator. The specialist must have read and understood these Operating Instructions and must follow the instructions they contain.
- The device must be operated by persons authorized and trained by the facility's owner-operator. Strict compliance with the instructions in the Operating Instructions is mandatory.
- Endress+Hauser will be happy to assist in clarifying the corrosion resistance properties of materials wetted by special fluids, including fluids used for cleaning. However, small changes of temperature, concentration or degree of contamination in the process can result in differences in corrosion resistance. Therefore, Endress+Hauser provides no warranty and assumes no liability with regard to corrosion resistance of fluid wetted materials in any given application. The user is responsible for choosing suitable fluid wetted materials in the process.
- The installer must ensure that the measuring system is correctly wired in accordance with the wiring diagrams. The transmitter must be grounded, except in cases where special protective measures have been taken (e.g. galvanically isolated power supply SELV or PELV).
- The user must attach an external switch for disconnecting the power supply in an emergency. The relationship between this switch and the measuring instrument or part of the system in which the instrument is located must be identified clearly and unambiguously.
- Invariably, local regulations governing the opening and repair of electrical devices apply.

1.3 Operational safety

Note the following points:
- Measuring systems for use in hazardous environments are accompanied by separate "Ex documentation", which is an integral part of these Operating Instructions. Strict compliance with the installation instructions and ratings as stated in this supplementary documentation is mandatory. The symbol on the front of this supplementary Ex documentation indicates the approval and the inspection body (Europe, USA, Canada).
- The housing of the sensor is equipped with an optional rupture disk to prevent the pressure in the housing from increasing. As long as the adhesive label (→ 7) is intact, the rupture disk is also intact.
- The measuring device complies with the general safety requirements in accordance with EN 61010, the EMC requirements of IEC/EN 61326, and NAMUR recommendation NE 21.

- Due to the performance rate in the electronic components, the maximum heating of the outer housing surfaces is 10 °K. When hot media are passed through the measuring tube, the surface temperature of the housing increases. With regard to the sensor, in particular, you should expect temperatures that can be close to the temperature of the medium. If the temperature of the medium is high, ensure staff are protected against burns and scalds.
- The manufacturer reserves the right to modify technical data without prior notice. Your Endress+Hauser distributor will supply you with current information and any updates to these Operating Instructions.
- The sensor housing protects the inner electronics and mechanics and is filled with dry nitrogen. The housing of this sensor does not fulfill any additional secondary containment function. However, 15 bar (217.5 psi) can be specified as a reference value for the pressure loading capacity.
  In case a danger of measuring tube failure exists due to process characteristics, e.g. with corrosive process fluids, this can cause a mechanical overload of the housing which, in turn, can cause breakage of the housing and thus is associated with an increased hazard potential. Thus it is very important to clarify the compatibility of the medium with the measuring tube and to observe the specified maximum process pressure.
  For increased safety, a version with rupture disk (triggering pressure 10 to 15 bar; 145 to 217.5 psi) can be used, which is available for order as a separate option.

1.4 Return

- Do not return a measuring device if you are not absolutely certain that all traces of hazardous substances have been removed, e.g. substances which have penetrated crevices or diffused through plastic.
- Costs incurred for waste disposal and injury (burns, etc.) due to inadequate cleaning will be charged to the owner-operator.
- Please note the measures on → 38

1.5 Notes on safety conventions and icons

The devices are designed to meet state-of-the-art safety requirements, have been tested, and left the factory in a condition in which they are safe to operate. The devices comply with the applicable standards and regulations in accordance with EN 61010 "Protection Measures for Electrical Equipment for Measurement, Control, Regulation and Laboratory Procedures". They can, however, be a source of danger if used incorrectly or for other than the designated use.
Consequently, always pay particular attention to the safety instructions indicated in these Operating Instructions by the following icons:

Warning!
"Warning" indicates an action or procedure which, if not performed correctly, can result in injury or a safety hazard. Comply strictly with the instructions and proceed with care.

Caution!
"Caution" indicates an action or procedure which, if not performed correctly, can result in incorrect operation or destruction of the measuring instrument. Comply strictly with the instructions.

Note!
"Note" indicates an action or procedure which, if not performed correctly, can have an indirect effect on operation or trigger an unexpected response on the part of the device.

2 Identification

The following options are available for identification of the measuring device:
- Nameplate specifications.
- Order code with breakdown of the device features on the delivery note.
- Enter serial numbers from nameplates in *W@M Device Viewer* (www.endress.com/deviceviewer): All information about the measuring device is displayed.

For an overview of the scope of the Technical Documentation provided, refer to the following:
- The chapters "Documentation" → 46.
- The *W@M Device Viewer*: Enter the serial number from the nameplate (www.endress.com/deviceviewer).

Reorder
The measuring device is reordered using the order code.

Extended order code:
- The device type (product root) and basic specifications (mandatory features) are always listed.
- Of the optional specifications (optional features), only the safety and approval-related specifications are listed (e.g. LA). If other optional specifications are also ordered, these are indicated collectively using the # placeholder symbol (e.g. #LA#).
- If the ordered optional specifications do not include any safety and approval-related specifications, they are indicated by the + placeholder symbol (e.g. 8FE**-AACCCAAD2S1+).

2.1 Device designation

The flow measurement system is a compact measuring instrument.

2.1.1 Nameplate of the transmitter

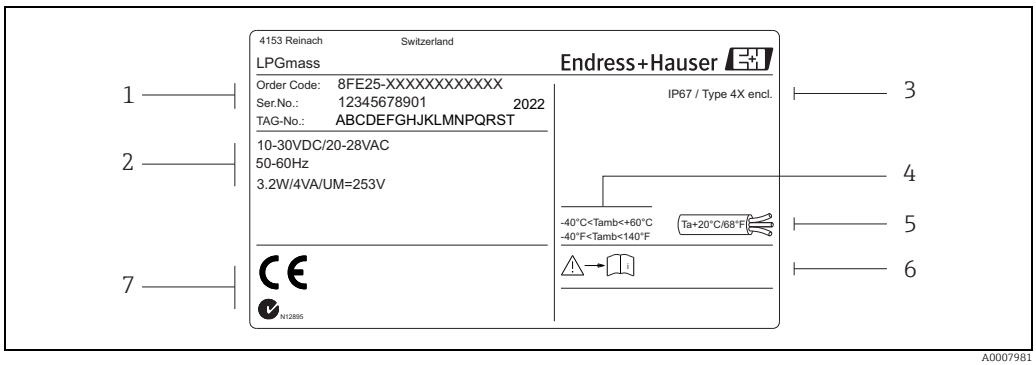


Fig. 1: Nameplate data of the transmitter (example)

1 Order code/serial number: See the specifications on the order confirmation for the meanings of the individual letters and digits
2 Power supply / frequency / power consumption
3 Degree of protection
4 Permitted ambient temperature
5 Cable temperature
6 Please refer to operating instructions / documentation
7 Reserved for additional information on device version (approvals, certificates)

2.1.2 Nameplate of the sensor

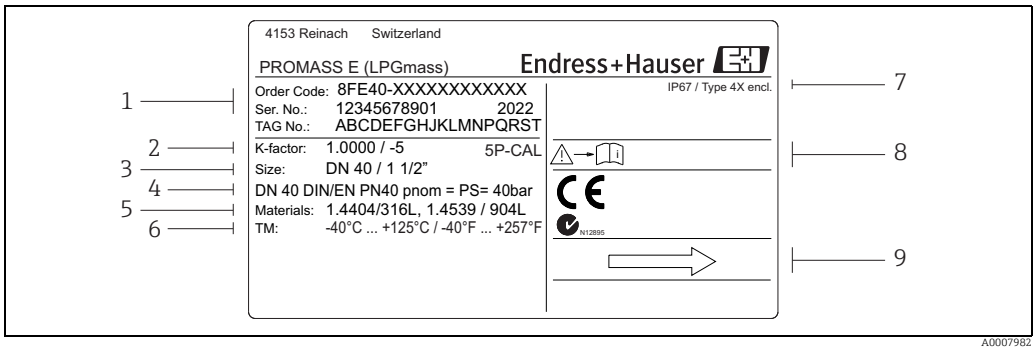


Fig. 2: Nameplate data of the sensor (example)

1 *Order code/serial number: See the specifications on the order confirmation for the meanings of the individual letters and digits*
2 *Calibration factor with zero point; 5P-CAL = with 5-point calibration*
3 *Flange nominal diameter*
4 *Nominal diameter device / Nominal pressure*
5 *Materials*
6 *Max. fluid temperature*
7 *Degree of protection*
8 *Please refer to operating instructions / documentation*
9 *Flow direction*

2.1.3 Additional name plate for approval for custody transfer

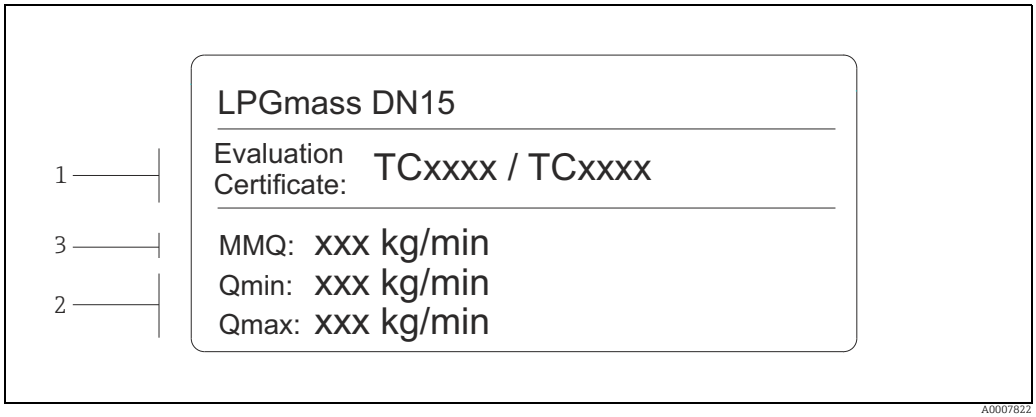


Fig. 3: Additional plate for the approval for custody transfer (example)

1 *Numbers of the evaluation certificates*
2 *Smallest measured quantity*
3 *Flow measuring range Q_{min} to $Q_{max\ in\ kg/min}$*

2.1.4 Nameplate for connections

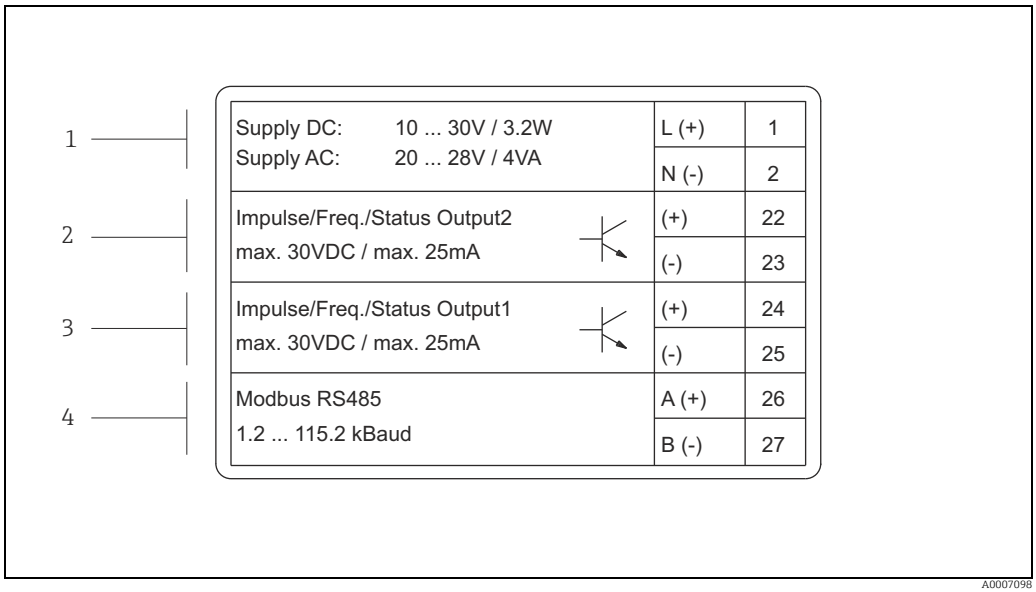


Fig. 4: Nameplate specifications for transmitter connections (example)

1 Terminal assignment for power supply
2 Terminal assignment pulse/frequency/status output
3 Terminal assignment pulse/frequency/status output
4 Terminal assignment Modbus RS485

2.2 Certificates and approvals

The devices are designed in accordance with good engineering practice to meet state-of-the-art safety requirements, have been tested, and left the factory in a condition in which they are safe to operate. The devices comply with the applicable standards and regulations in accordance with EN 61010 "Protection Measures for Electrical Equipment for Measurement, Control, Regulation and Laboratory Procedures".
The measuring system described in these Operating Instructions thus complies with the statutory requirements of the EC Directives. Endress+Hauser confirms successful testing of the device by affixing to it the CE mark.

2.3 Registered trademarks

Modbus®
Registered trademark of the SCHNEIDER AUTOMATION, INC.

Applicator®, FieldCare®, Fieldcheck®, HistoROM™, S-DAT®, T-DAT®
Registered or registration-pending trademarks of the Endress+Hauser Group

3 Incoming acceptance, transport and storage

3.1 Incoming acceptance

On receipt of the goods, check the following points:
- Check the packaging and the contents for damage.
- Check the shipment, make sure nothing is missing and that the scope of supply matches your order.

3.2 Transport

The following instructions apply to unpacking and to transporting the device to its final location:
- Transport the devices in the containers in which they are delivered.
- The covers or caps fitted to the process connections prevent mechanical damage to the sealing faces and the ingress of foreign matter to the measuring tube during transportation and storage. Consequently, do not remove these covers or caps until immediately before installation.

3.3 Storage

Note the following points:
- Pack the measuring device in such a way as to protect it reliably against impact for storage (and transportation). The original packaging provides optimum protection.
- The permitted storage temperature is −40 to +80°C (−40 to +176 °F).
- Do not remove the protective covers or caps on the process connections until you are ready to install the device.
- The measuring device must be protected against direct sunlight during storage in order to avoid unacceptably high surface temperatures.

4 Installation

4.1 Installation conditions

No special measures such as supports are necessary. Design features of the instrument absorb external forces.

4.1.1 Dimensions

All the dimensions and lengths of the sensor and transmitter are provided in the separate documentation entitled "Technical Information" → 46.

4.1.2 Inlet and outlet runs

No special precautions need to be taken for fittings which create turbulence (valves, elbows, T-pieces, etc.), as long as no cavitation occurs.

4.1.3 Vibrations

The high oscillation frequency of the measuring tubes ensures that the correct operation of the measuring system is not influenced by pipe vibrations. Consequently, the sensors require no special measures for attachment.

4.1.4 Limiting flow

For corresponding information, refer to → 39 and → 43.

4.1.5 Special installation instructions

Rupture disk

Make sure that the function and operation of the rupture disk is not impeded through the installation of the device. The position of the rupture disk is indicated on a sticker applied over it. If the rupture disk is triggered, the sticker is destroyed. The disk can therefore be visually monitored. For additional information that is relevant to the process (→ 44).

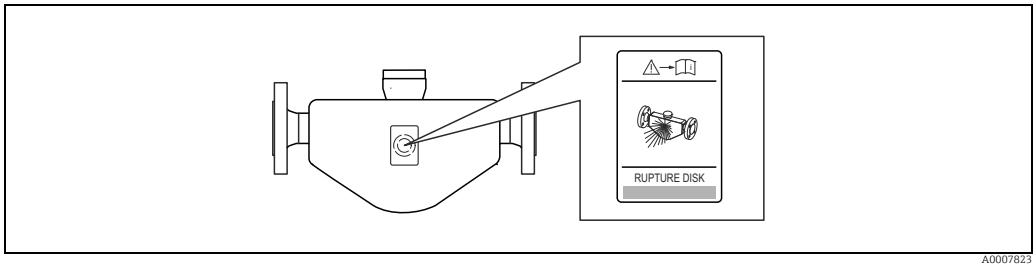


Fig. 5: Additional sign regarding the position of the rupture disk

4.2 Installation

4.2.1 Turning the transmitter housing

The transmitter housing can be rotated counterclockwise continuously up to 360°.

1. Loosen the Allen setscrew (1) partially, but do not unscrew it all the way.
2. Rotate the transmitter housing into the desired position.
3. Tighten the Allen setscrew (1).

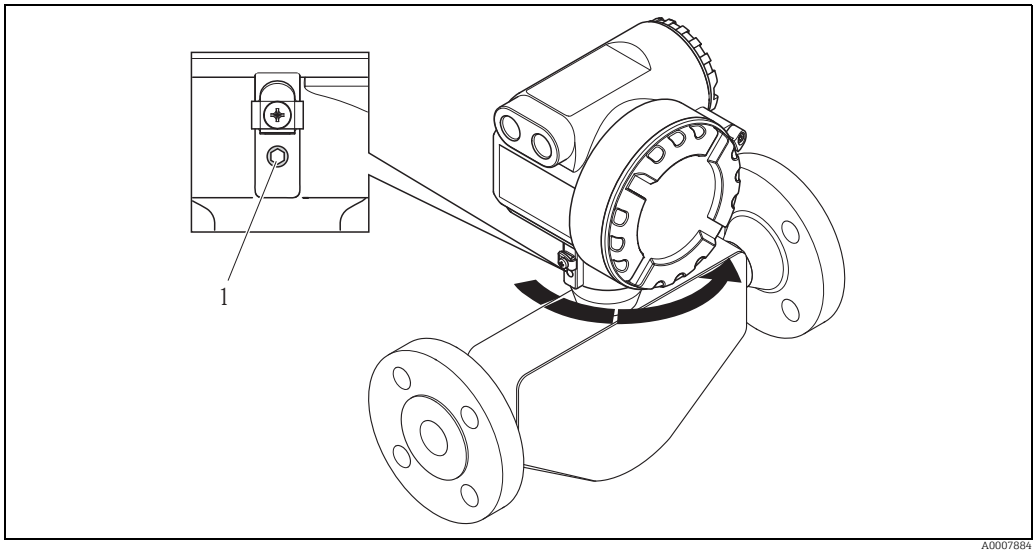


Fig. 6: Rotating the transmitter housing

4.3 Post-installation check

Perform the following checks after installing the measuring device in the pipe:

Device condition and specifications	**Notes**
Is the measuring instrument damaged, particularly the sealing surfaces of the process connection (visual inspection)?	–
Is the adhesive label of the optional rupture disk intact?	→ 🖹 7
Does the device correspond to specifications at the measuring point, including process temperature and pressure, ambient temperature, measuring range, etc.?	→ 🖹 39 ff.
Installation	**Notes**
Do the process connections used correspond to the existing process conditions (pressure, temperature) and the specified seal design on the sensor side?	–
Does the arrow on the sensor nameplate match the direction of flow through the pipe?	–
Are the measuring point number and labeling correct (visual inspection)?	–
Process environment / process conditions	**Notes**
Is the measuring device protected against moisture and direct sunlight?	–

5 Wiring

Warning!
When connecting Ex-certified devices, see the notes and diagrams in the Ex-specific supplement to these Operating Instructions. Please do not hesitate to contact your Endress+Hauser sales office if you have any questions.

5.1 Modbus RS485 cable specifications

Cable data	
Characteristic impedance	120 Ω
Cable capacitance	< 30 pF/m
Core cross-section	> 0.34 mm^2 , corresponds to AWG 22
Cable type	Twisted pairs
Loop-resistance	≤ 110 Ω/km
Shielding	Copper braided shielding or braided shielding and foil shielding

Note the following points for the bus structure:
- All the measuring devices are connected in a bus structure (line).
- The maximum line length (segment length) of the Modbus RS485 system and a transmission rate of 115 200 Baud is 1200 m (4000 ft). The total length of the spurs may not exceed 6.6 m (21.7 ft).
- A maximum of 32 nodes are permitted per segment.
- Each segment is terminated at either end with a terminating resistor.
- The bus length or the number of users can be increased by introducing a repeater.

Caution!
The legal EMC requirements are fulfilled **only** when the cable shield is grounded on both sides.

5.2 Connecting the measuring unit

5.2.1 Transmitter connection

Warning!
- Risk of electric shock. Switch off the power supply before opening the device. Do not install or wire the device while it is connected to the power supply. Failure to comply with this precaution can result in irreparable damage to the electronics.
- Risk of electric shock. Connect the protective ground to the ground terminal on the housing before the power supply is applied.
- Compare the specifications on the nameplate with the local supply voltage and frequency. The national regulations governing the installation of electrical equipment also apply.

1. Detach the safety claw (a) and screw the connection compartment cover (b) off of the transmitter housing.
2. Feed the power supply cable (d) and the signal cable (c) through the appropriate cable entries.
3. Carry out the wiring according to the terminal assignment → 14.
4. Screw the connection compartment cover (b) back on the transmitter housing and retighten the safety claw (a).

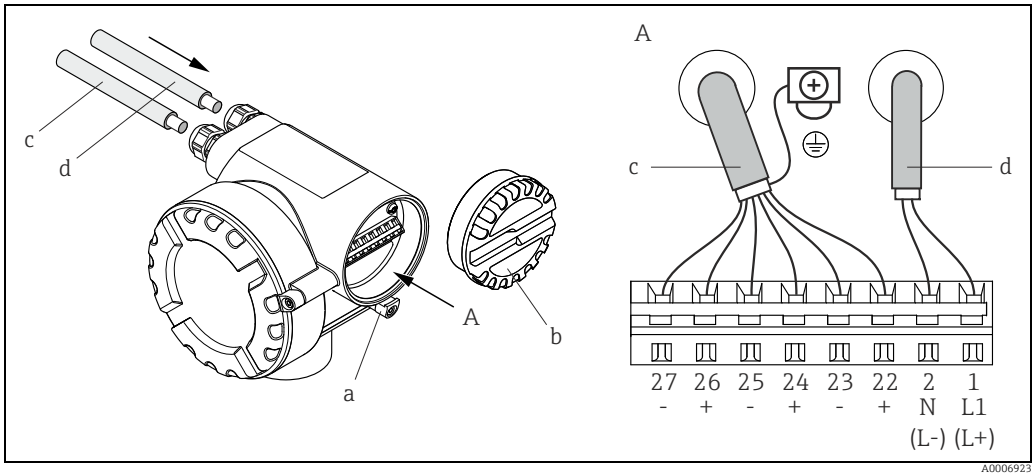


Fig. 7: *Connecting the transmitter; cable cross-section: max. 2.5 mm² (14 AWG)*

A = View A

a = Safety claw

b = Terminal compartment cover

c = Signal cable: terminal Nos. 22 to 27
(shield for Modbus RS485 is mandatory;
shield for pulse, frequency and status outputs is not required, but recommended)

d = Cable for power supply: 20 to 28 V AC, 10 to 30 V DC
Terminal No. 1: L1 for AC, L+ for DC
Terminal No. 2: N for AC, L- for DC

Caution!
- The behavior of the measuring instrument below a supply voltage of 10 VDC is not defined. Correct function can no longer be guaranteed. We recommend switching off the measuring instrument if the supply voltage falls below that specified.
- Operation at a supply voltage of 30 VDC or 28 VAC can destroy the measuring instrument. We recommend limiting the supply voltage to the specified range using corresponding protective elements or other measures.

5.2.2 Terminal assignment

Electrical values for outputs → 📄 39

Order characteristic for "inputs/outputs"	Terminal No. (outputs)		
	22 (+) / 23 (-)	24 (+) / 25 (-)	26 (+) / 27 (–)
Fixed communication boards (permanent assignment)			
N	Pulse/frequency/status output 2	Pulse/frequency/status output 1	Modbus RS485

5.3 Degree of protection

The measuring instrument fulfills all the requirements for IP 67.

Compliance with the following points is mandatory following installation in the field or servicing, in order to ensure that IP 67 protection is maintained:
- The housing seals must be clean and undamaged when inserted into their grooves. The seals must be dried, cleaned or replaced if necessary.
- The housing screws and screw covers must be firmly tightened.
- The cables used for connection must be of the specified outside diameter (8 to 12 mm / 0.32 to 0.47").
- The cable entries must be pulled tight (item **a**, → 🖼 8).
- The cable must loop down ("water trap") before it enters the cable entry (item **b**, → 🖼 8). This arrangement prevents moisture penetrating the entry.

✎ Note!
The cable entries must not point upwards.

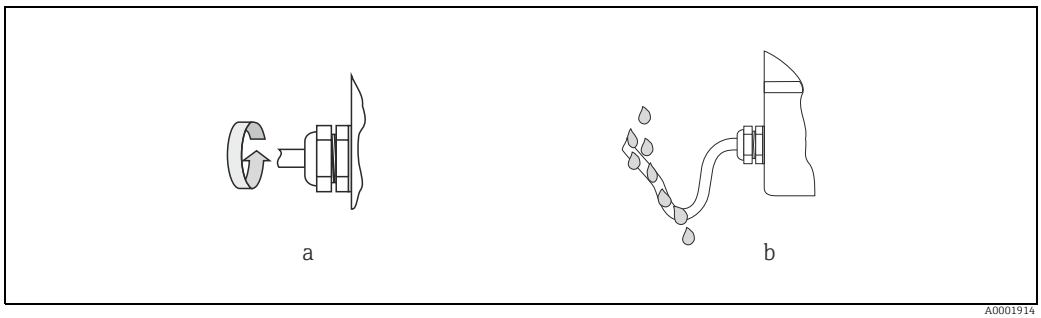


Fig. 8: Installation instructions, cable entries

- Remove all unused cable entries and insert plugs instead.
- Do not remove the grommet from the cable entry.

☝ Caution!
Do not loosen the screws of the sensor housing, as otherwise the degree of protection guaranteed by Endress+Hauser no longer applies.

5.4 Post-connection check

Perform the following checks after completing electrical installation of the measuring device:

Device condition and specifications	Notes
Are cables or the device damaged (visual inspection)?	–
Electrical connection	**Notes**
Does the supply voltage match the specifications on the nameplate? Is the protective ground connected?	20 to 28 V AC (45 to 65 Hz) 10 to 30 V DC
Do the cables comply with the specifications?	→ 🖹 40
Do the cables have adequate strain relief?	–
Are the power supply and signal cables correctly connected?	See the wiring diagram inside the cover of the terminal compartment
Are all screw terminals firmly tightened?	–
Are all cable entries installed, firmly tightened and correctly sealed? Cables looped as "water traps"?	→ 🖹 14
Are all housing covers installed and firmly tightened?	–

6 Operation

6.1 Quick operation guide

You have the following option for configuring and commissioning the device:

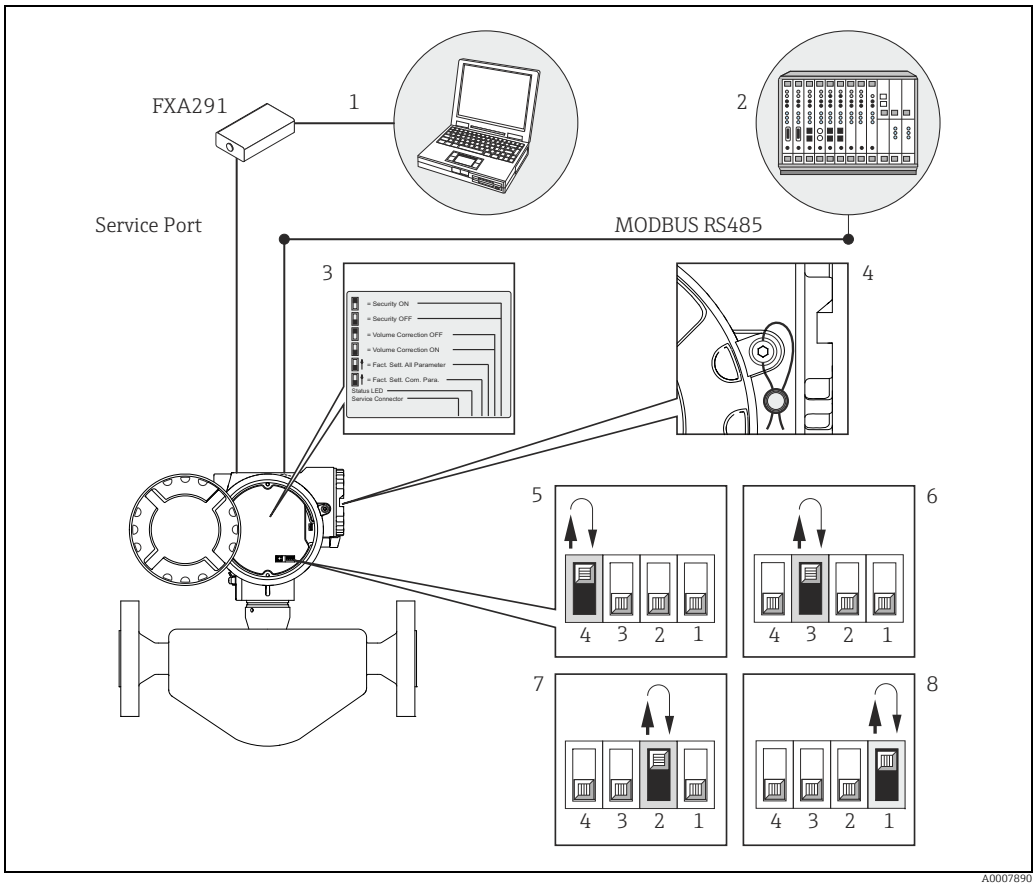


Fig. 9: Method of operating Modbus RS485 devices

1 Configuration/operating program for operating via the service interface FXA291 (e.g. FieldCare)
2 Operation via Modbus RS485 process control system
3 Situation sticker of the various DIP switch positions and their function
4 Option to attach a seal
*5 Operation via device-internal DIP switch (**4**):*
If the DIP switch (4) is pushed upwards, the device restores the factory settings of the communication parameters of the Modbus RS485 (return it afterwards to its original lower position).
*6 Operation via device-internal DIP switch (**3**):*
If the DIP switch (3) is pushed upwards, the device restores the factory settings of all communication parameters of the Modbus RS485 (return it afterwards to its original lower position).
*7 Operation via device-internal DIP switch (**2**):*
If the DIP switch (2) is pushed upwards, the volume flow is calculated with the currently measured density, regardless of the setting configured under "VOLUME CALCULATION". If the DIP switch (2) is pushed back to the lower position, the selection under "VOLUME CALCULATION" again applies → 🖹 84.
*8 Operation via device-internal DIP switch (**1**):*
If the DIP switch (1) is pushed upwards, the device is in secure operation mode. "Secure" means that no write access of any kind is possible. An exception is the totalizer 3. Its parameters also remains writable in the safe operation; that means that it also can be reset in safe operation. If the DIP switch is pushed back to the lower position, write access is enabled once again. This secured/locked operation mode can be used in applications such as legally and metrologically controlled (verified) measuring systems. "CUSTODY TRANSFER MEASUREMENT" → 🖹 52.

Note!
The DIP switches must stay at least two seconds in the desired position, until the appropriate reaction takes place. The parameters can take several minutes to be reset, after which the device restarts. Meanwhile the light emitting diode permanently shines orange. The power supply must not be switched off while the factory settings are being restored.

6.2 Operating option

6.2.1 Customer-specific parameter configuration with the FieldCare

FieldCare is Endress+Hauser's FDT-based plant asset management tool and allows the configuration and diagnosis of intelligent field devices. By using status information, you also have a simple but effective tool for monitoring devices. The Proline flowmeters are accessed via a service interface or via the service interface FXA193.

6.3 Modbus RS485 communication

6.3.1 Modbus RS485 technology

The Modbus is an open, standardized fieldbus system which is deployed in the areas of manufacturing automation, process automation and building automation.

Note!
For detailed information on the Modbus RS485 technology, refer to www.Modbus.org

System architecture

The Modbus RS485 distinguishes between master and slave devices.

- **Master devices**
  Master devices determine the data traffic on the fieldbus system. They can send data without an external request.
- **Slave devices**
  Slave devices do not have their own access rights to the data traffic of the fieldbus system, but send their data only in response to a request from a master.

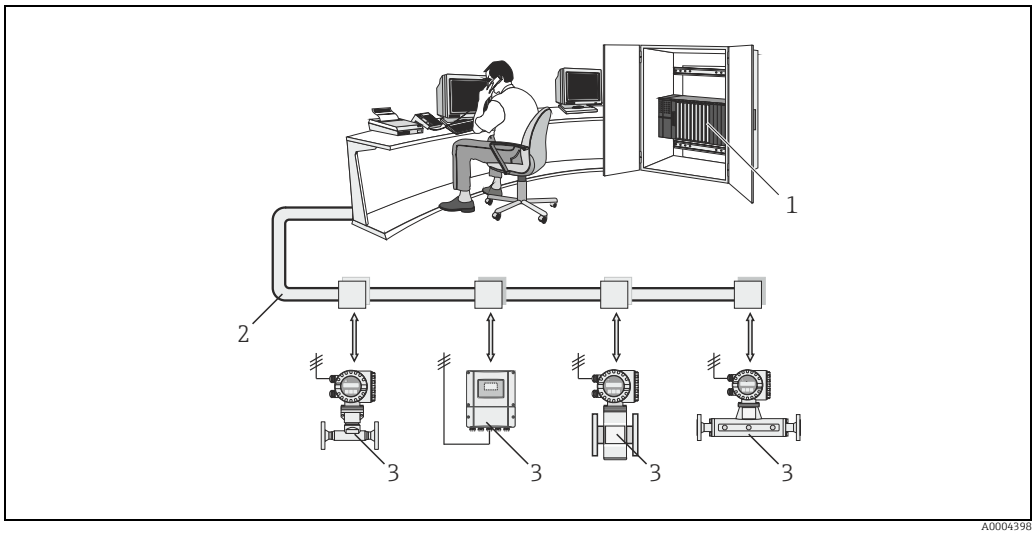


Fig. 10: Modbus RS485 system architecture

1 Modbus master (PLC, etc.)
2 Modbus RS485
3 Modbus slave (measuring devices, etc.)

Master/slave communication

A distinction is made between two methods of communication with regard to master/slave communication via Modbus RS485:

- **Polling (request-response-transaction)**
  The master sends a request telegram to **one** slave and waits for the slave's response telegram. Here, the slave is contacted directly due to its unique bus address (1 to 247).

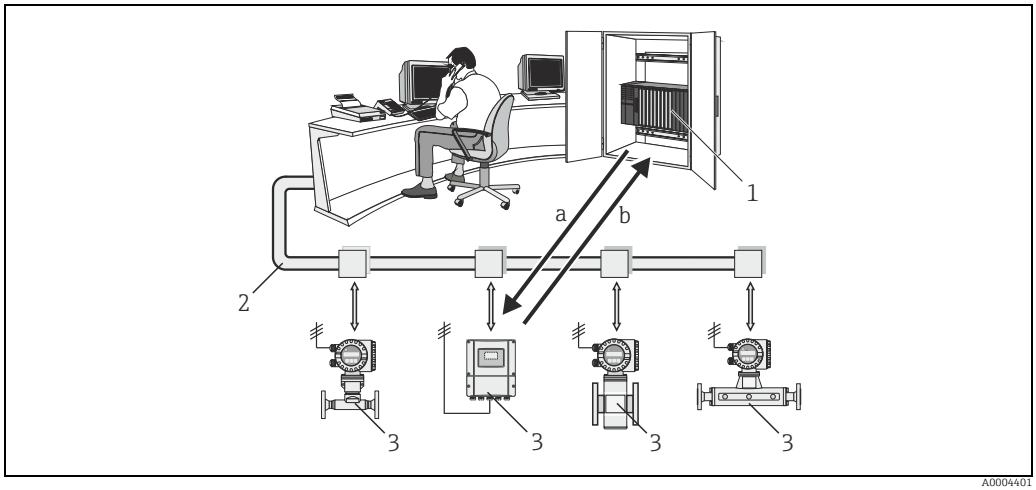


Fig. 11: Modbus RS485 polling data traffic

1 Modbus Master
2 Modbus RS485
3 Modbus Slave
a Request telegram to this slave
b Response telegram to master

- **Broadcast message**
  By means of the global address 0 (broadcast address), the master sends a command to all the slaves in the fieldbus system. The slaves execute the command without reporting back to the master. Broadcast messages are only permitted in conjunction with write function codes.

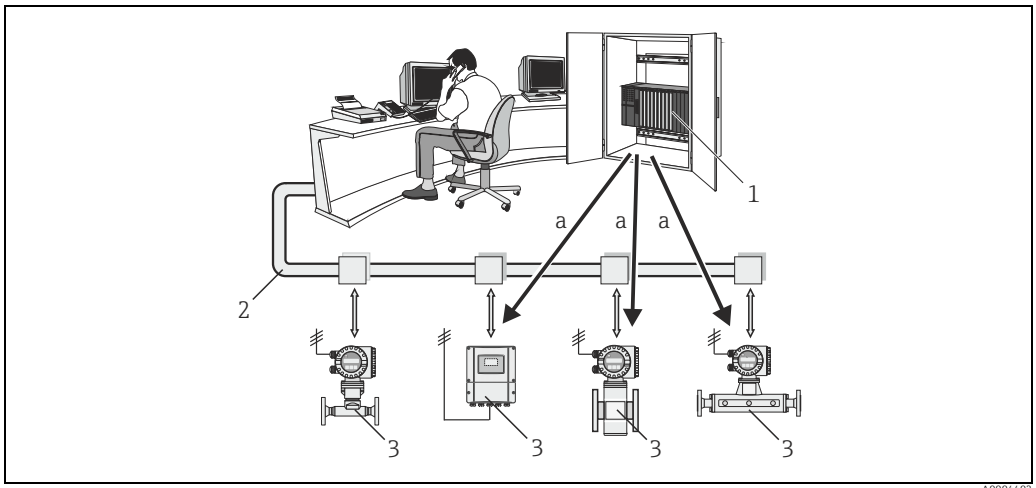


Fig. 12: Modbus RS485 polling data traffic

1 Modbus Master
2 Modbus RS485
3 Modbus Slave
a Broadcast message command to all slaves (request is executed without a response telegram to the master)

6.3.2 Modbus telegram

A request telegram from the master contains the following fields:

Telegram structure:

Slave address	Function code	Data	Check sum

- Slave address
  The slave address can be in an address range from 1 to 247.
  The master talks to all the slaves simultaneously by means of the slave address 0 (broadcast message).
- Function code
  The function code defines which action is to be executed.
  Function codes supported by the measuring device → 📄 20.
- Data
  Depending on the function code, the following values are transmitted in this data field:
  – Register start address (from which the data are transmitted)
  – Number of registers
  – Write/read data
  – Data length
- Check sum (CRC or LRC check)
  The checksum forms the end of the message.

The master can send another message to the slave as soon as it has received an answer to the previous message or once the time-out period set at the master has expired. This time-out period can be specified or modified by the user and depends on the slave response time.

If an error occurs during data transfer or if the slave cannot execute the command from the master, the slave returns an error telegram (exception response) to the master.

The slave response telegram consists of fields that contain the requested data or that confirm that the action requested by the master has been executed. It also contains a checksum.

6.3.3 Modbus function codes

The function code defines which action is to be executed. The measuring device supports the following function codes:

Function code	Name in accordance with Modbus specification	Description
03	READ HOLDING REGISTER	Reads one or more registers of the Modbus slave. 1 to a maximum of 125 consecutive registers (1 register = 2 byte) can be read with a telegram. **Application:** Reading measuring instrument parameters with read and write access.
04	READ INPUT REGISTER	Reads one or more registers of the Modbus slave. 1 to a maximum of 125 consecutive registers (1 register = 2 byte) can be read with a telegram. **Application:** Reading measuring device parameters with read access.
06	WRITE SINGLE REGISTERS	Writing a **single** register with a new value. **Application:** Writes only one measuring device parameter. Note! Function code 16 is used for writing several registers by means of just one telegram.
08	DIAGNOSTICS	Checks the communication connection between the master and slave. All diagnostics codes are supported.
16	WRITE MULTIPLE REGISTERS	Writes several slave registers with a new value. A maximum of 120 consecutive registers can be written with a telegram. **Application:** Writing multiple measuring device parameters.
23	READ/WRITE MULTIPLE REGISTERS	Simultaneous reading and writing of 1 to max. 118 registers in a telegram. Write access is executed before read access. **Application:** Writing and reading multiple measuring device parameters.

Note!
- Broadcast messages are only permitted with function codes 06, 16 and 23.
- The measuring device does not differentiate between function codes 03 and 04. These codes have the same result.

6.3.4 Maximum number of writes

If a nonvolatile device parameter is modified via the PROFIBUS, the change is saved in the DAT of the measuring device.
The number of writes to the DAT is technically restricted to a maximum of 1 million. Attention must be paid to this limit since, if exceeded, it results in data loss and measuring device failure. For this reason, avoid constantly writing nonvolatile device parameters via the Modbus.

6.3.5 Modbus register addresses

Each device parameter has a register address. The master addresses the individual device parameters via this register address.
The register addresses of the individual device parameters can be found in Chapter 12, "Function description", under the parameter description in question.

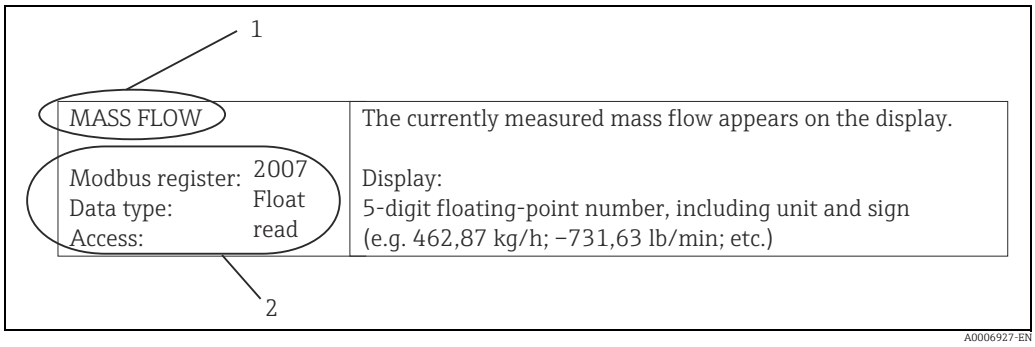


Fig. 13: Example of how a function description is illustrated in the "Description of Instrument functions" manual

1 Name of the function
2 Information on communication via Modbus RS485
– Modbus register (information in decimal numerical format, 1-based)
– Data type: Float, Integer or String
– Possible ways of accessing the function:
read = read access via function codes 03, 04 or 23
write = write access via function codes 06, 16 or 23

Response times

The response time of the measuring device to a request telegram of the Modbus master is typically 5 ms, if no delay of the response telegram is desired, → 72.

Data types

The following data types are supported by the measuring device:

- **FLOAT** (floating-point numbers IEEE 754)
  Data length = 4 bytes (2 registers)

Byte 3	Byte 2	Byte 1	Byte 0
SEEEEEEE (MSB)	EMMMMMMM	MMMMMMMM	MMMMMMMM (LSB)

S = sign
E = exponent
M = mantissa

- **INTEGER**
  Data length = 2 bytes (1 register)

Byte 1	Byte 0
Most significant byte (MSB)	Least significant byte (LSB)

- **STRING**
  Data length = depends on device parameter,
  e.g. illustration of a device parameter with a data length = 8 bytes (4 registers):

Byte 7		to		Byte 0
first byte		to		last byte

Byte transmission sequence

The Modbus specification does not specify the transmission sequence of the bytes. For this reason, it is important to coordinate the addressing method between the master and slave during commissioning. This can be configured in the measuring device by means of the "BYTE ORDER" parameters (see instrument functions, → 📄 73).

The bytes are transmitted depending on the option selected in the specific "BYTE ORDER" parameter:

FLOAT:

	Time transmission sequence			
Selection	**1st**	**2nd**	**3rd**	**4th**
1 – 0 – 3 – 2*	Byte 1 (MMMMMMMM)	Byte 0 (MMMMMMMM)	Byte 3 (SEEEEEEE)	Byte 2 (EMMMMMMM)
0 – 1 – 2 – 3	Byte 0 (MMMMMMMM)	Byte 1 (MMMMMMMM)	Byte 2 (EMMMMMMM)	Byte 3 (SEEEEEEE)
2 – 3 – 0 – 1	Byte 2 (EMMMMMMM)	Byte 3 (SEEEEEEE)	Byte 0 (MMMMMMM)	Byte 1 (MMMMMMM)
3 – 2 – 1 – 0	Byte 3 (SEEEEEEE)	Byte 2 (EMMMMMMM)	Byte 1 (MMMMMMMM)	Byte 0 (MMMMMMMM)

* = Factory setting
S = sign
E = exponent
M = mantissa

INTEGER:

	Time transmission sequence	
Selection	**1st**	**2nd**
1 – 0*	Byte 1 (MSB)	Byte 0 (LSB)
0 – 1	Byte 0 (LSB)	Byte 1 (MSB)

* = Factory setting
MSB = most significant byte
LSB = least significant byte

STRING:
Illustration using the example of a **LPGmass** with a data length of 8 bytes.

Selection	Time transmission sequence							
	1st	2nd	3rd	4th	5th	6th	7th	8th
1 – 0 *	Byte 7 **L**	Byte 6 **P**	Byte 5 **G**	Byte 4 **m**	Byte 3 **a**	Byte 2 **s**	Byte 1 **s**	Byte 0 ↓**
0 – 1	Byte 6 **P**	Byte 7 **L**	Byte 4 **m**	Byte 5 **G**	Byte 2 **s**	Byte 3 **a**	Byte 0 ↓**	Byte 1 **s**

* = Factory setting
** = mandatory termination
MSB = most significant byte
LSB = least significant byte

6.3.6 Modbus error messages

If the Modbus slave detects an error in the request telegram from the master, it sends an error message consisting of the slave address, function code, error code (exception code) and checksum. To indicate that this is an error message, the lead bit of the returned function code is used. The reason for the error is transmitted to the master by means of the exception code. All error codes are supported.

6.3.7 Modbus auto-scan buffer

Function description

The measuring device has a special memory area, known as the auto-scan buffer, for grouping nonconsecutive device parameters. This can be used to flexibly group up to 16 device parameters. The master can talk to this complete data block by means of just one request telegram.

Structure of the auto-scan buffer

The auto-scan buffer consists of the configuration and the data area. In the configuration area, the "Scan List" specifies which device parameters should be grouped. To do so, the corresponding register address is entered into the scan list. Up to 16 device parameters can be grouped. Float and Integer-type device parameters with read and write access are supported.

Scan list		
No.	Modbus configuration Register address (data type = Integer)	Configuration via Configuration program (BASIC FUNCTION → Modbus RS485 →)
1	5001	SCAN LIST REG. 1
2	5002	SCAN LIST REG. 2
3	5003	SCAN LIST REG. 3
4	5004	SCAN LIST REG. 4
5	5005	SCAN LIST REG. 5
6	5006	SCAN LIST REG. 6
7	5007	SCAN LIST REG. 7
8	5008	SCAN LIST REG. 8
9	5009	SCAN LIST REG. 9
10	5010	SCAN LIST REG. 10
11	5011	SCAN LIST REG. 11

Scan list		
No.	**Modbus configuration Register address (data type = Integer)**	**Configuration via Configuration program (BASIC FUNCTION → Modbus RS485 →)**
12	5012	SCAN LIST REG. 12
13	5013	SCAN LIST REG. 13
14	5014	SCAN LIST REG. 14
15	5015	SCAN LIST REG. 15
16	5016	SCAN LIST REG. 16

Access to data via Modbus

The master uses the register addresses 5051 to 5081 to access the data area of the auto-scan buffer. This data area contains the values of the device parameters defined in the scan list. For example, if the register 2007 was entered for mass flow in the scan list by means of the SCAN LIST REG. 1 function, the master can read out the current measured value of the mass flow in register 5051.

Data area				
Parameter value/Measured values		**Access via Modbus register address**	**Data type ***	**Access****
Value of scan list entry No. 1	→	5051	Integer / Float	read/write
Value of scan list entry No. 2	→	5053	Integer / Float	read/write
Value of scan list entry No. 3	→	5055	Integer / Float	read/write
Value of scan list entry No. 4	→	5057	Integer / Float	read/write
Value of scan list entry No. 5	→	5059	Integer / Float	read/write
Value of scan list entry No. 6	→	5061	Integer / Float	read/write
Value of scan list entry No. 7	→	5063	Integer / Float	read/write
Value of scan list entry No. 8	→	5065	Integer / Float	read/write
Value of scan list entry No. 9	→	5067	Integer / Float	read/write
Value of scan list entry No. 10	→	5069	Integer / Float	read/write
Value of scan list entry No. 11	→	5071	Integer / Float	read/write
Value of scan list entry No. 12	→	5073	Integer / Float	read/write
Value of scan list entry No. 13	→	5075	Integer / Float	read/write
Value of scan list entry No. 14	→	5077	Integer / Float	read/write
Value of scan list entry No. 15	→	5079	Integer / Float	read/write
Value of scan list entry No. 16	→	5081	Integer / Float	read/write

* The data type depends on the device parameter entered in the scan list

** The data access depends on the device parameter entered in the scan list. If the device parameter entered supports read and write access, the parameter can also be accessed by means of the data area.

6.3.8 Integer scaling of the measured variables

The current measured variables such as mass flow, density, temperature etc. are usually represented on the side of the Modbus Slaves as floating point numbers after IEEE 754 (single Precision 32 bits). Thus the value of a measured variable occupies in each case two Modbus registers with in each case 16 bits. In order to save storage location on the side of the Modbus Masters and/or time during the data communication, the possibility insists of making on the side of the Modbus Slaves an integer scaling of the measured variables on 16 bits. Then the scaled value occupies only one Modbus register.

In addition for each measured variable a scaling factor K and a scaling offset OS (→ 🖹 76 ff.) is given, which are in each case integer values. The appropriate measured variable X is then scaled as follows on Y (→ 🖹 76).

$$Y = INT((X \cdot K) + (32\,768 - OS))$$

The function INT means that the decimal point portion of the event in the brackets is **cut off** and is not rounded. If the result Y of the scaling is smaller 0 **or** larger than the as the largest possible value defined value Y_{max} (→ 🖹 76), Y_{max} + 1 is transferred.

Example:

Current mass flow X	1.2545 kg/min
Mass flow factor K	100
Mass flow offset OS	32768
Integer scaled mass flow Y	Y = INT((1.2545 · 100) + (32768 – 32768)) = INT(125.45 + 0) = 125

Current mass flow X	– 1.2545 kg/min
Mass flow factor K	100
Mass flow offset OS	0
Integer scaled mass flow Y	Y = INT((–1.2545 · 100) + (32768 – 0)) = INT(–125.45 + 32768) = = INT(32642.55) = 327642

6.3.9 Configuring the device address

The valid device addresses are in the range from 1 to 247. In a Modbus RS485 network, each address can only be assigned once. If an address is not configured correctly, the device is not recognized by the Modbus master. All measuring devices are delivered from the factory with the default device address 247. Configuring the device address → 🖹 72.

7 Commissioning

7.1 Function check

Make sure that all final checks have been completed before you start up your measuring point:
- Checklist for "Post-installation check" → 11
- Checklist for "Post-connection check" → 15

7.2 Switching on the measuring device

Once the installation checks have been successfully completed, it is time to switch on the supply voltage. The device is now operational.
The measuring device performs a number of power on self-tests. Normal measuring mode commences as soon as startup completes.

Note!
If the startup is not successful, depending on the cause, a corresponding message is displayed in the FieldCare operating program, or the status LED flashes correspondingly (→ 32).

7.3 Zero point adjustment

All measuring devices are calibrated with state-of-the-art technology. The zero point obtained in this way is printed on the nameplate. Calibration takes place under reference operating conditions (→ 41). Therefore, a zero point adjustment is generally **not** required.

7.3.1 Preconditions for a zero point adjustment

If you want to carry out a zero point adjustment, note the following points before doing so:
- The calibration can be carried out under stable pressure conditions only.
- The zero point adjustment is carried out a zero flow. This can be achieved, for example, with shutoff valves upstream and/or downstream of the sensor or by using existing valves and gates (→ 14).
  - Normal operation → Valves 1 and 2 open
  - Zero point adjustment *with* process pressure → Valve 1 open / valve 2 closed
  - Zero point adjustment *without* process pressure → Valve 1 open / valve 2 closed
- A zero point adjustment is **not** possible if the function CUSTODY TRANSFER MEASUREMENT is selected or an error message is pending.

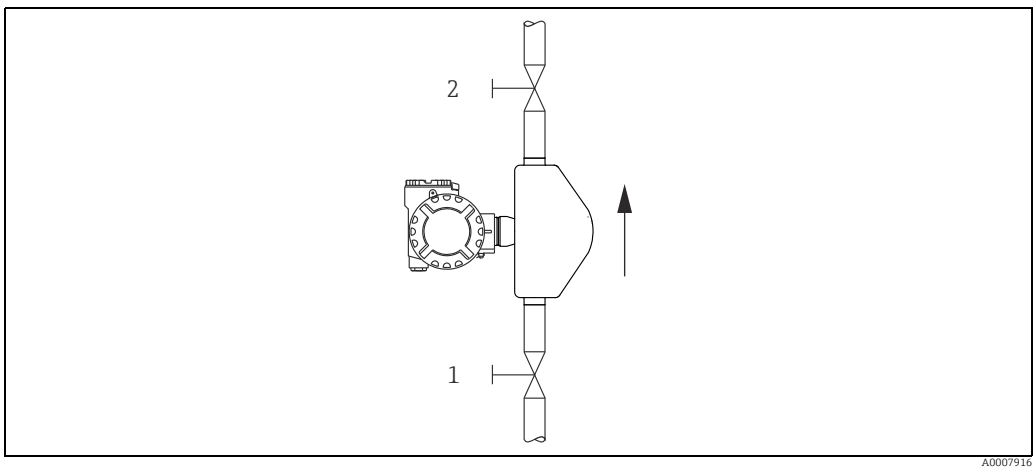


Fig. 14: Zero point adjustment and shut-off valves (1 + 2)

7.3.2 Performing a zero point adjustment

1. Operate the system until operating conditions have settled.
2. Stop the flow (v = 0 m/s).
3. Check the shutoff valves for leaks.
4. Carry out the alignment using the "ZEROPOINT ADJUST" function (→ 82).

7.4 Memory (HistoROM)

At Endress+Hauser, the term HistoROM refers to various types of data storage modules on which process and measuring device data are stored. By unplugging and plugging such modules, device configurations can be duplicated onto other measuring devices, to cite just one example.

7.4.1 HistoROM/T-DAT (sensor and transmitter DAT)

The DAT is an exchangeable data memory in which all sensor-relevant parameters are stored, i.e., diameter, serial number, calibration factor, zero point, and the settings of the transmitter.

8 Maintenance

No special maintenance work is required.

8.1 External cleaning

When cleaning the exterior of measuring devices, always use cleaning agents that do not attack the surface of the housing and the seals.

9 Accessories

Various accessories, which can be ordered with the device or subsequently from Endress+Hauser, are available for the device. Detailed information on the order code in question is available from your local Endress+Hauser sales center or on the product page of the Endress+Hauser website: www.endress.com.

9.1 Device-specific accessories

9.1.1 For the Transmitter

Accessories	Description
Electronics module	Complete plug-in electronics module.

9.2 Service-specific accessories

Accessories	Description
Applicator	Software for selecting and sizing Endress+Hauser measuring devices: ▪ Calculation of all the necessary data for identifying the optimum flowmeter: e.g. nominal diameter, pressure loss, accuracy or process connections ▪ Graphic illustration of the calculation results Administration, documentation and access to all project-related data and parameters over the entire life cycle of a project. Applicator is available: ▪ Via the Internet: https://wapps.endress.com/applicator ▪ On CD-ROM for local PC installation
W@M	Life cycle management for your plant. W@M supports you with a wide range of software applications over the entire process: from planning and procurement, to the installation, commissioning and operation of the measuring devices. All the relevant device information, such as the device status, spare parts and device-specific documentation, is available for every device over the entire life cycle. The application already contains the data of your Endress+Hauser device. Endress+Hauser also takes care of maintaining and updating the data records. W@M is available: ▪ Via the Internet: www.endress.com/lifecyclemanagement ▪ On CD-ROM for local PC installation
Fieldcheck	Tester/simulator for testing flowmeters in the field. When used in conjunction with the "FieldCare" software package, test results can be imported into a database, printed and used for official certification. Contact your Endress+Hauser representative for more information.
FieldCare	FieldCare is Endress+Hauser's FDT-based plant asset management tool and allows the configuration and diagnosis of intelligent field devices. By using status information, you also have a simple but effective tool for monitoring devices. The Proline flowmeters are accessed via a service interface or via the service interface FXA193.
FXA291	Service interface from the measuring device to the PC for operation via FieldCare.

9.3 System components

Accessories	Description
Memograph M graphic display recorder	The Memograph M graphic display recorder provides information on all the relevant process variables. Measured values are recorded correctly, limit values are monitored and measuring points analyzed. The data are stored in the 256 MB internal memory and also on a DSD card or USB stick. Memograph M boasts a modular design, intuitive operation and a comprehensive security concept. The ReadWin® 2000 PC software is part of the standard package and is used for configuring, visualizing and archiving the data captured. The mathematics channels which are optionally available enable continuous monitoring of specific power consumption, boiler efficiency and other parameters which are important for efficient energy management.

10 Troubleshooting

10.1 Self-monitoring

Exceptional states that arise during operation are detected by the flowmeter and corresponding messages are output:

- Via the outputs, depending on the setting (→ 🖹 66, → 🖹 69)
- Via the Modbus interface, depending on the setting (→ 🖹 73)
- Via error messages in the "FieldCare" operating program (→ 🖹 33)
- Via the status LED (→ 🖹 32, visible only when the device is open)

If multiple messages are pending, the one with the highest priority is output.

The message about a status can be assigned to a category as follows:

OFF
- When the status occurs, no message is generated.

Error
- The message belongs to the "Errors" category, meaning that the measuring system cannot continue measuring operation.

Note!
The message belongs to the "Notes" category, meaning that the measuring system may be able to continue measuring operation with restrictions.

10.2 Diagnosis using light emitting diode (LED)

There is a Light Emitting Diode (LED) on the meter electronics board that allows simple fault diagnostics at any time:

- If the status output was not configured to output errors or notes.
- If fault diagnostics are no longer possible via the FieldCare operating program.

⚠ Warning!
Risk of explosion. The electronics compartment may not be opened while there is an explosive atmosphere. This type of fault diagnostics can no longer be carried out in Ex-protected areas.

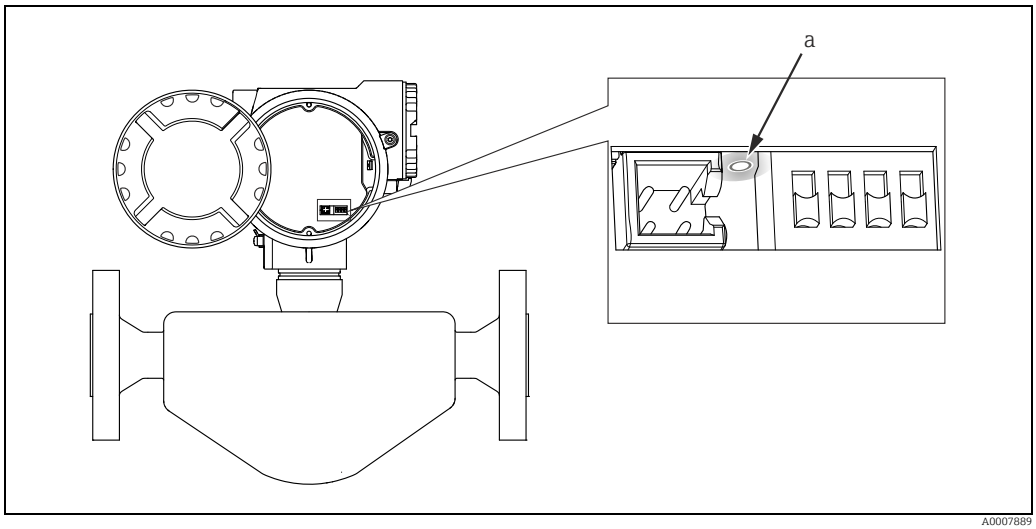


Fig. 15: Fault diagnostics using light emitting diode (a)

Status of light emitting diode (LED)	Status of measuring system
LED illuminated in green	Measuring system OK, creepage is active
LED flashes green (once per second)	Measuring system OK, operation
LED not illuminated	Measuring system no longer working
LED flashes red (three times per second)	– Operation not possible – Error (fault message) pending
LED flashes red/green (once per second)	– Operation possible, but may be limited by application conditions. – Notice message pending
LED flashes red/green (three times per second)	Zero point adjustment running
LED flashes green/orange (approx. 3 seconds long)	Secured/locked operation starts
LED flashes red/orange (approx. 3 seconds long)	Secured/locked operation stops
LED flashes red/(pause)/green (approx. 3 seconds long)	SW update active

10.3 Messages (FieldCare)

No. / error message	Cause	Remedy / spare part
# 001 CRITICAL FAIL		Replace the electronics module (→ 🖹 37). Spare parts: → 🖹 35
# 002 CONFIGURATION FAILURE	Inconsistent parameter configuration	Restore the factory settings.
# 011 AMP HW-EEPROM	Electronics module: Defective EEPROM	Replace the electronics module (→ 🖹 37). Spare parts: → 🖹 35
# 012 AMP SW-EEPROM	Electronics module: Error when accessing the EEPROM	Restore the factory settings.
# 021 HW-FRAM	Electronics module: Faulty FRAM	Replace the electronics module (→ 🖹 37 ff.). Spare parts: → 🖹 35
# 022 SW-FRAM	Electronics module: Error when accessing the FRAM	Contact your Endress+Hauser service organization.
# 031 HW-DAT	Sensor DAT: 1. DAT is defective. 2. DAT is not plugged in or is missing.	1. Replace DAT. Spare parts: → 🖹 35 Check the spare part set number to ensure that the new, replacement DAT is compatible with the meter electronics. 2. Insert the DAT: → 🖹 37
# 032 SW DAT	Sensor: Error when accessing the DAT.	Restore the factory settings.
# 101 STARTUP RUNNING	Measuring instrument is running though the startup procedure.	–
# 355/356 RANGE FRQ.OUT 1/2	Frequency output: The output frequency is out of range.	1. Increase the entered full scale value 2. Reduce flow rate
# 359/360 RANGE PULSE 1/2	Pulse output: Pulse output frequency is out of range.	1. Increase the setting for pulse weighting. 2. Reduce flow rate.
# 379 LOW FREQ.LIM.	The measuring tube oscillation frequency is below the permitted range. Causes: – Measuring tube damaged – Sensor defective or damaged	Contact your Endress+Hauser service organization.
# 380 UPPER FREQUENCY LIMIT	The measuring tube oscillation frequency is above the permitted range. Causes: – Measuring tube damaged – Sensor defective or damaged	Contact your Endress+Hauser service organization.
# 381 MEAS. TEMP. CIRC.SHORT	The temperature sensor on the measuring tube is likely defective.	Check whether the connector of the sensor signal cable is correctly plugged into the electronics module before contacting your Endress+Hauser service organization (→ 🖹 37).
# 382 MEAS. TEMP. CIRC. OPEN		
# 383 CARR.TEMP. CIRC. SHORT	The temperature sensor on the carrier tube is likely defective.	Check whether the connector of the sensor signal cable is correctly plugged into the electronics module before contacting your Endress+Hauser service organization (→ 🖹 37).
# 384 CARR. TEMP. CIRC. OPEN		

No. / error message	Cause	Remedy / spare part
# 387 SEN.ASY.EXCEED	One of the sensor coils (on the inlet or outlet side) is probably defective.	Check whether the connector of the sensor signal cable is correctly plugged into the electronics module before contacting your Endress+Hauser service organization (→ 🖹 37).
# 388 ZP-COMP. INSTABLE	External process conditions	Contact your Endress+Hauser service organization.
# 389 ZP-COMP. LIMIT	–	Contact your Endress+Hauser service organization.
# 390 COMMUNIC.DSP	–	Replace the electronics module.
# 586 OSC.AMPL.LIM	The fluid properties do not allow a continuation of the measurement.	Change or improve process conditions.
# 587 TUBE NOT OSC.	Extreme process conditions exist. The measuring system can therefore not be started. The measuring cell or electronics are defective.	Change or improve process conditions. Replace the electronics module (→ 🖹 37). Spare parts: → 🖹 35
# 692 SIM. MEASURAND	Simulation of measuring variables (e.g. mass flow).	Switch off simulation
# 700 EMPTY PIPE DET. ACTIVE	The density is below the lower limit value defined for the function "EPD VALUE LOW".	Adapt the "EPD" function to the prevailing process conditions.
# 701 EXC.CURR.LIM	The maximum current value for the measuring tube excitation coil has been reached. The instrument continues to work correctly.	This could be cause by liquids contained in the fluid. Change or improve process conditions.
# 702 FLUID INHOM.	The frequency control is not stable because the fluid properties are inhomogenous.	This could be cause by liquids contained in the fluid. Change or improve process conditions.
# 703 FLUID INHOM.	The amplitude control is not stable due to inhomogenous fluid properties.	This could be cause by liquids contained in the fluid. Change or improve process conditions.
# 704 NOISE LIMIT	The failsafe level of the sensor signal is too high.	This could be cause by liquids contained in the fluid. Change or improve process conditions.
# 731 ADJ.ZERO FAIL.	The zero point adjustment is not possible.	Make sure that zero point adjustment is carried out at "zero flow" only (v = 0 m/s) (→ 🖹 26).
# 740 ZEROPOINT ADJ. RUNNING	The zero point adjustment is running.	Wait until the zero point adjustment is finished.
# 800 API TABLE OUT OF RANGE	The density and/or temperature are outside the definition range of API table 53	Change or improve process conditions.
# 801 LOW. PROC. LIMIT TEMP	The temperature has fallen below the lower process limit.	Change the process condition or setting (→ 🖹 89).
# 802 UPP. PROC. LIMIT TEMP	The temperature has exceeded the process limit.	Change the process condition or setting (→ 🖹 89).
# 803 LOW. PROC. LIMIT DENS.	The density has fallen below the lower process limit.	Change the process condition or setting (→ 🖹 89).
# 804 UPP. PROC. LIMIT DENS.	The density has exceeded the upper process limit.	Change the process condition or setting (→ 🖹 89).
# 805 LOW. PROC. LIMIT MASSFLOW	The mass flow has fallen below the lower process limit.	Change the process condition or setting (→ 🖹 89).

No. / error message	Cause	Remedy / spare part
# 806 UPP. PROC. LIMIT MASSFLOW	The mass flow has exceeded the upper process limit.	Change the process condition or setting (→ 🖹 89).
# 807 LOW. PROC. LIMIT VOLFLOW	The volume flow has fallen below the lower process limit.	Change the process condition or setting (→ 🖹 89).
# 808 UPP. PROC. LIMIT VOLFLOW	The volume flow has exceeded the upper process limit.	Change the process condition or setting (→ 🖹 89).
# 809 CUSTODY TRANSFER MODE STARTED	Custody transfer mode started. The corresponding DIP switches were actuated, → 🖹 17.	–
# 810 CUSTODY TRANSFER MODE EXITED	Custody transfer mode exited. The corresponding DIP switches were actuated, → 🖹 17.	–

10.4 Errors without messages

Symptoms	Rectification
The error cannot be eliminated or another error pattern is present. In these instances, please contact your Endress+Hauser service organization.	The following solutions are possible: **Request the services of an Endress+Hauser service technician** If you request the services of a service technician, please be ready with the following information: – Brief error description – Nameplate data (→ 🖹 6): order code and serial number **Return the devices to Endress+Hauser** Procedures must be carried out before you return a flowmeter to Endress+Hauser for repair or calibration. Please → 🖹 5, → 🖹 38. **Replace the transmitter electronics** Electronics module defective → order spare parts → 🖹 35

10.5 Spare parts

Refer to chapter "Self-monitoring" → 🖹 31 ff. for detailed troubleshooting instructions. The measuring device, moreover, provides additional support in the form of continuous self-diagnosis and storage of error messages that arise.
Fault rectification can entail replacing defective components with tested spare parts. For an overview, refer to → 🖹 33.

10.6 Response of outputs to errors

Failsafe mode of the outputs	
Output	**Failsafe mode**
Frequency output	✎ Note! The failsafe mode of the frequency output can be configured in various ways (→ 🖹 66): FALLBACK VALUE Signal output → 0 Hz HOLD VALUE Last valid value (preceding occurrence of the fault) is output. HIGH VALUE Signal output → maximum possible frequency
Pulse output	✎ Note! The failsafe mode of the pulse output can be configured in various ways (→ 🖹 69): FALLBACK VALUE Signal output → no pulses HOLD VALUE Last valid value (preceding occurrence of the fault) is output. HIGH VALUE Signal output → maximum possible pulse rate
Status output	✎ Note! The assignment of the status of the output can be defined (→ 🖹 71). In the event of fault, note or power supply failure → status output not conductive.
Totalizer	✎ Note! The failsafe mode of the totalizer can be configured in various ways (→ 🖹 57): STOP The totalizers are paused until the error is rectified. HOLD VALUE The totalizers continue to count the flow in accordance with the last valid flow value (before the error occurred).
Modbus RS485	✎ Note! The failsafe mode of the Modbus RS485 output can be configured in various ways (→ 🖹 74): STOP In the event of a fault, the value "NaN" (not a number) is transmitted instead of the current measured value. HOLD VALUE Last valid value (preceding occurrence of the fault) is output.

10.7 Removing and installing the meter electronics

Warning!
- Risk of explosion. The electronics compartment may not be opened while there is an explosive atmosphere.
- Risk of damaging electronic components (ESD protection). Static electricity can damage electronic components or impair their operability.

1. Switch off power supply
2. Remove the cable gland with the Allen screw (1) and insert the cable (2).
3. Remove the securing screw (3) of the protective cover.
4. Push the side snap hooks (2 x item 4) together and pull off the protective cover (5).
5. Unplug the cable connector from the electronics module:
   – Pull off the connector of the sensor signal cable (6) by pulling it forwards.
   – Pull off the connector for the power supply and signal outputs (7) by pulling them upwards.
6. Remove the HistoROM/DAT connector (8).
7. Unscrew the Phillips screws (2 x item 9) and pull out the electronics module (10).
8. Installation is the reverse of the removal procedure.

Caution!
Use only original Endress+Hauser parts.

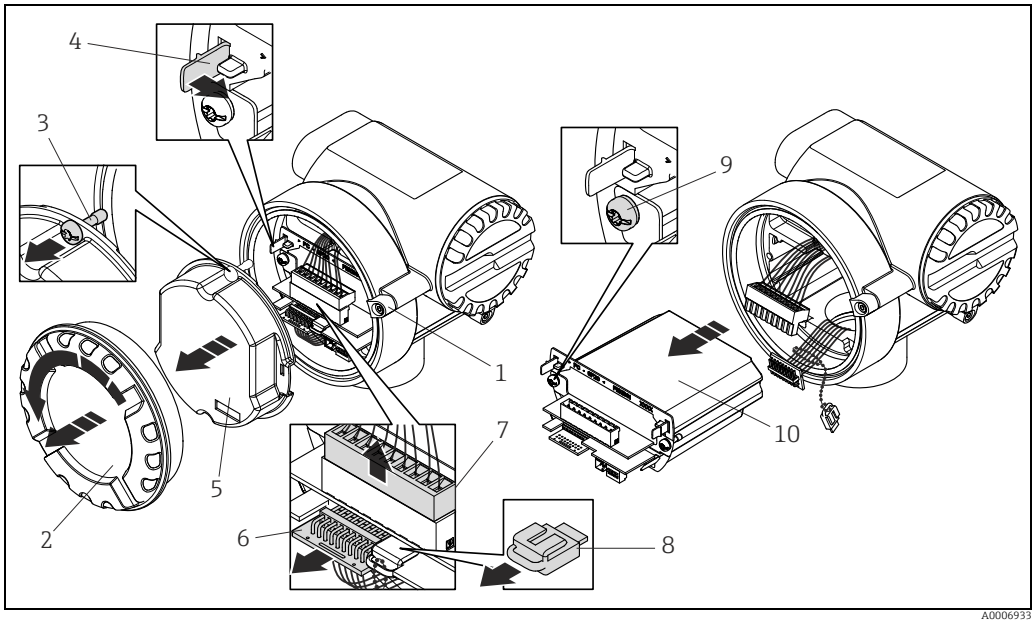


Fig. 16: Removing and installing the meter electronics

1 Allen screw
2 Electronics compartment cover
3 Securing screw of the protective cover
4 Snap hooks, 2 x
5 Protective cover
6 Connector of the sensor signal cable
7 Cable connector for power supply and signal outputs
8 HistoROM/DAT connector
9 Phillips screw, 2 x
10 Electronics module

10.8 Software history

Date	Software version	Changes to software	Operating Instructions
02.2016	1.01.xx	--	71317102 / 15.16
11.2015	1.01.xx	--	71235483 / 14.15
08.2009	1.01.00	▪ Alternative behavior Modbus interpreter ▪ Factory settings ▪ Integer scaled measured variables via Modbus	71123638 / 13.10
12.2006	1.00.00	Original software	71059881 / 07.07

10.9 Return

The measuring device must be returned if repairs or a factory calibration are required, or if the wrong measuring device has been ordered or delivered. According to legal regulations, Endress+Hauser, as an ISO-certified company, is required to follow certain procedures when handling returned products that are in contact with medium.

To ensure swift, safe and professional device returns, please read the return procedures and conditions on the Endress+Hauser website at www.services.endress.com/return-material.

10.10 Disposal

Observe the regulations applicable in your country.

11 Technical data

11.1 Applications

The measuring system is used for mass flow measurement.

11.2 Function and system design

Measuring principle

Mass flow measurement by the Coriolis principle

Measuring system

The measuring system is a compact transmitter consisting of a sensor and a transmitter.

11.3 Input

Measured variable

- Mass flow (proportional to the phase difference between two sensors mounted on the measuring tube which record differences in the pipe oscillation geometry during flow)
- Volume flow (measured from the mass flow and density)
- Fluid density (proportional to the resonance frequency of the measuring tube)
- Fluid temperature (measured with temperature sensors)

Measuring range

Measuring ranges for non-custody transfer operation:

DN		$\dot{m}_{min}$ to $\dot{m}_{max}$	
[mm]	[in]	[kg/h]	[lb/min]
8	⅜"	0 to 2000	0 to 73.50
15	½"	0 to 6500	0 to 238.9
25	1"	0 to 18000	0 to 661.5
40	1 ½"	0 to 45000	0 to 1654

Note!
The values of the corresponding custody transfer certificate apply for custody transfer operation.

Operable flow range

1:100

11.4 Output

Output signal

Pulse / frequency output:

For custody transfer measurement, the two frequency/pulse outputs can be operated in redundant or phase-shifted mode.

- Passive
- Galvanically isolated
- Open Collector
- Max. 30 V DC
- Max. 25 mA
- Frequency output: END VALUE FREQ 100 to 5000 Hz, on/off ratio 1:1
- Pulse output: pulse value and pulse polarity selectable, pulse width configurable (0.1 to 1000 ms)

Status output:

- Passive
- Open Collector
- Max. 30 V DC
- Max. 25 mA

Modbus RS485:

- Modbus device type: slave
- Address range: 1 to 247
- Functions codes supported: 03, 04, 06, 08, 16, 23
- Broadcast: supported with the function codes 06, 16, 23
- Physical interface: RS485 in accordance with standard EIA/TIA-485
- Baud rates supported: 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115200 Baud
- Transmission mode: RTU or ASCII
- Response time = typically 5 ms

Signal on alarm

Pulse / frequency output:

Selectable behavior

Status output:

Selectable behavior

Modbus RS485:

Selectable behavior

Galvanic isolation

All circuits for outputs and power supply are galvanically isolated from each other.

11.5 Power supply

Terminal assignment

→ 14

Supply voltage

24 V DC nominal voltage (10 to 30 V DC)
24 V AC nominal voltage (20 to 28 V AC)

Power consumption

AC: < 4 VA
DC: < 3.2 W

Typical switch-on current at 24 V DC nominal voltage at R_i = 0.1 ΩW of the source.

t [ms]	I [A]
0	10
0.1	8
0.2	7.5
0.5	7
1	6
2	4
5	1.5
10	0.125 (operating current)

Note!
The internal resistance of the source may not exceed R_i = 10 Ω.

Power supply failure

Bridging of at least 20 ms

All measuring cell and measuring point data are maintained

Electrical connections

→ 🖹 12 ff.

Potential equalization

This measuring instrument is suitable for potentially explosive atmospheres; refer to the correspondingly information in the specific Ex-specific supplementary documentation.

Cable entries

Power supply and signal cables (outputs):

- Cable entry M20 x 1.5 (8 to 12 mm / 0.32 to 0.47")
- Threads for cable entries, ½" NPT, G ½"

Cable specifications

Each compatible cable, with a temperature specification at least 20°C (68 °F) higher than the ambient temperature prevailing in the application. We recommend using a cable with a temperature specification of +80°C (176 °F).
For Modbus RS485, refer to → 🖹 12.

11.6 Performance characteristics

Reference operating conditions

- Error limits following ISO 11631
- Water, typically +15 to +45 °C (+59 to +113 °F); 2 to 6 bar (29 to 87 psi)
- Specification as per calibration protocol ±5 °C (±9 °F) and ±2 bar (±30 psi)
- Data on the measured error based on accredited calibration rigs traced back to ISO 17025

To obtain measured errors, use the Applicator sizing tool *Applicator*: → 🖹 29.

Maximum measured error

o.r. = of reading

Mass flow:

±0.2% ± |(zero point stability ÷ measured value) · 100|% o.r.

Volume flow:

±0.3% ± |(zero point stability ÷ measured value) · 100|% o.r.

Zero point stability

DN		Zero point stability	
		[kg/h]	[lb/min]
8	⅜"	0.200	0.007
15	½"	0.650	0.024
25	1"	1.80	0.066
40	1½"	4.50	0.165

Example maximum measured error (mass flow)

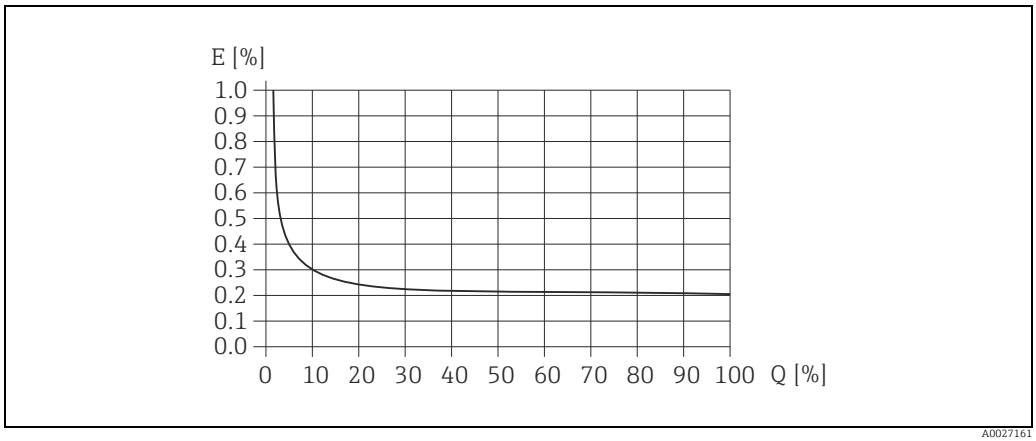


Fig. 17: E = Error: Maximum measured error as % o.r.
Q = Flow rate as %

Calculation example

Given:
- DN 25 (1")
- Mass flow = 5000 kg/h (183,75 lb/min)

Max. measured error:
- ±0,2% ± [(zero point stability ÷ measured value) · 100]% o. r.
- ±0,2% ± 1,80 kg/h (0,066 lb/min) ÷ 5000 kg/h (183,75 lb/min) · 100% = ±0,236% o.r.

Repeatability

o.r. = of reading

Mass flow:

±0.10% ± [½ · (zero point stability ÷ measured value) · 100]% o.r.

Volume flow:

±0.15% ± [½ · (zero point stability ÷ measured value) · 100]% o.r.

Influence of medium temperature

When there is a difference between the temperature for zero point adjustment and the process temperature, the typical measured error is ±0.0003% of the full scale value/°C.

Influence of medium pressure

The following section shows the effect on accuracy of mass flow due to a difference between calibration pressure and process pressure is negligible.

11.7 Installation

Installation instructions	→ 🖹 10 ff.
Inlet and outlet runs	There are no installation requirements regarding inlet and outlet runs.
System pressure	No special precautions regarding the system pressure are required, but observe the safety instructions on → 🖹 4 ff.

11.8 Environment

Ambient temperature range	−40 to +60 °C (−40 to +140 °F) for measuring instrument Install the device at a shady location. Avoid direct sunlight, particularly in warm climatic regions.
Storage temperature	−40 to +80 °C (−40 to +176 °F), preferably at +20 °C (+68 °F)
Degree of protection	Standard: IP 67 (NEMA 4X) for transmitter and sensor
Shock resistance	In accordance with IEC/EN 60068-2-31 and EN 60721 (Class 2M3)
Vibration resistance	In accordance with IEC/EN 60068-2-31 and EN 60721 (Class 2M3)
Electromagnetic compatibility	In accordance with IEC/EN 61326 and NAMUR recommendation NE 21

11.9 Process

Medium temperature range	−40 to +125 °C (−40 to +257 °F)
Medium pressure range (nominal pressure)	Measuring tubes, connector: max. 100 bar (1450 psi) (dependent on process connection)
Pressure-temperature ratings	An overview of the Pressure-temperature ratings for the process connections is provided in the "Technical Information" document.
Rupture disk	To increase the level of safety, a device version with a rupture disk with a triggering pressure of 10 to 15 bar (145 to 217.5 psi) can be used. Special mounting instructions: (→ 🖹 10).
Flow rate	Refer to the information on → 🖹 39 ("Measuring range")
Pressure loss	To calculate the pressure loss, use the *Applicator* sizing tool (→ 🖹 29).

11.10 Mechanical construction

Design / dimensions

The dimensions and lengths of the sensor and transmitter are provided in the separate "Technical Information" document, which can be downloaded as a PDF file from www.endress.com. A list of the available "Technical Information" documents is provided in the "Documentation" section → 📄 46.

Weight

DN in mm (in)	8 (⅜")	15 (½")	25 (1")	40 (1½")
Weight in kg (lb)	6.7 (14.7)	7.2 (15.8)	8.8 (19.4)	13.7 (30.2)

The weights refer to devices with EN/DIN PN 40 flanges.

Material

Transmitter housing

Powder coated die-cast aluminum

Sensor housing, containment

- Acid and alkali-resistant outer surface
- Stainless steel, 1.4301 (304)

Process connections

Stainless steel 1.4404 (316/316L):

Measuring tubes

Stainless steel 1.4539 (904L)

Process connections

- Threaded hygienic connection:
  - DIN 11864-1 form A, DIN 11866 line A
  - DIN 11851
- Clamp:
  - Tri-Clamp, DIN 11866 line C
- Flanges:
  - according to EN 1092-1 (DIN 2501)
  - according to ASME B16.5
  - JIS B2220
- VCO coupling

11.11 Operability

Local display

Display element

Status LED: There is a Light Emitting Diode (LED) on the meter electronics board that allows simple fault diagnostics.

Control elements

Device-internal DIP switch.

Remote operation

Operating via Modbus RS485 and serviceinterface FXA291 (e.g. FieldCare)

11.12 Certificates and approvals

CE mark

The measuring system is in conformity with the statutory requirements of the EC Directives. Endress+Hauser confirms successful testing of the device by affixing to it the CE mark.

C-Tick symbol

The measuring system complies with the EMC requirements of the "Australian Communications and Media Authority (ACMA)".

Ex approval

Information about currently available Ex versions (ATEX, FM, CSA) can be supplied by your Endress+Hauser Sales Center on request. All explosion protection data are given in a separate Ex documentation, which is also available upon request.

Approval for custody transfer

Information about currently available approvals for custody transfer can be supplied by your E+H Sales Center on request.

Modbus certification

The measuring device meets all the requirements of the Modbus/TCP conformity and integration test and has the "Modbus/TCP Conformance Test Policy, Version 2.0". The measuring device has successfully passed all the test procedures carried out and is certified by the "Modbus/TCP Conformance Test Laboratory" of the University of Michigan.

Pressure Equipment Directive

The measuring devices can be ordered with or without PED (Pressure Equipment Directive). If a device with PED is required, this must be ordered explicitly. For devices with nominal diameters less than or equal to DN 25 (1"), this is neither possible nor necessary.

- With the identification PED/G1/III on the sensor nameplate, Endress+Hauser confirms conformity with the "Basic safety requirements" of Appendix I of the Pressure Equipment Directive 97/23/EC.
- Devices with this identification (with PED) are suitable for the following types of fluid:
  - Fluids of Group 1 and 2 with a steam pressure greater than, or smaller and equal to 0.5 bar (7.3 psi)
  - Unstable gases
- Devices without this identification (without PED) are designed and manufactured according to good engineering practice. They correspond to the requirements of Art. 3, Section 3 of the Pressure Equipment Directive 97/23/EC. Their application is illustrated in Diagrams 6 to 9 in Appendix II of the Pressure Equipment Directive 97/23/EC.

Other standards and guidelines

- EN 60529:
  Degrees of protection by housing (IP code)
- EN 61010-1:
  Safety requirements for electrical equipment for measurement, control and laboratory use
- IEC/EN 61326:
  "Emission in accordance with Class A requirements". Electromagnetic compatibility (EMC requirements)
- EN 60721:
  Shock and vibration resistance
- OIML R117-1:
  Requirements for measuring systems for liquids apart from water
- NAMUR NE 21
  Electromagnetic compatibility (EMC) of industrial process and laboratory control equipment

11.13 Accessories/spare parts

→ 🖹 35

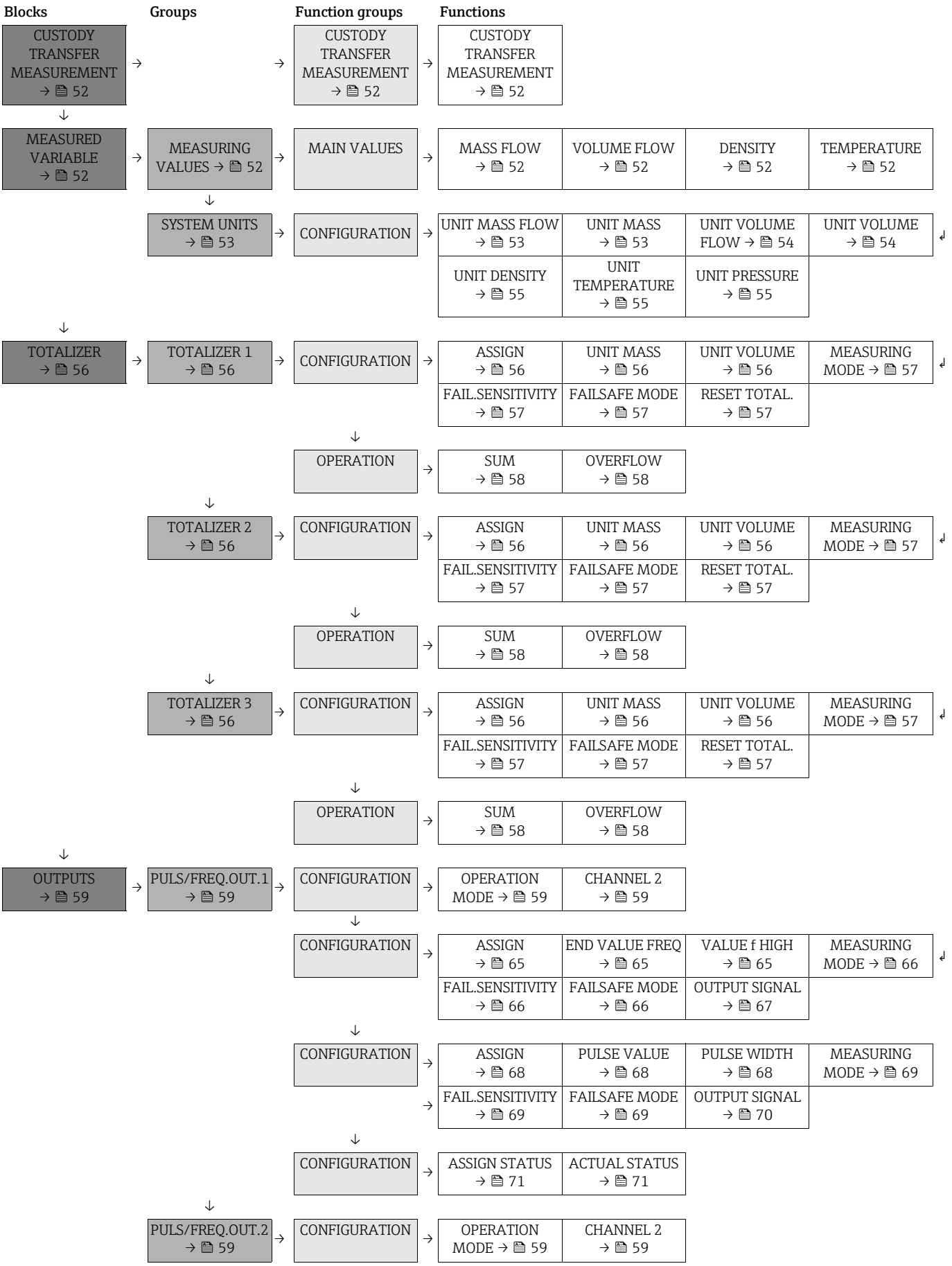
11.14 Documentation

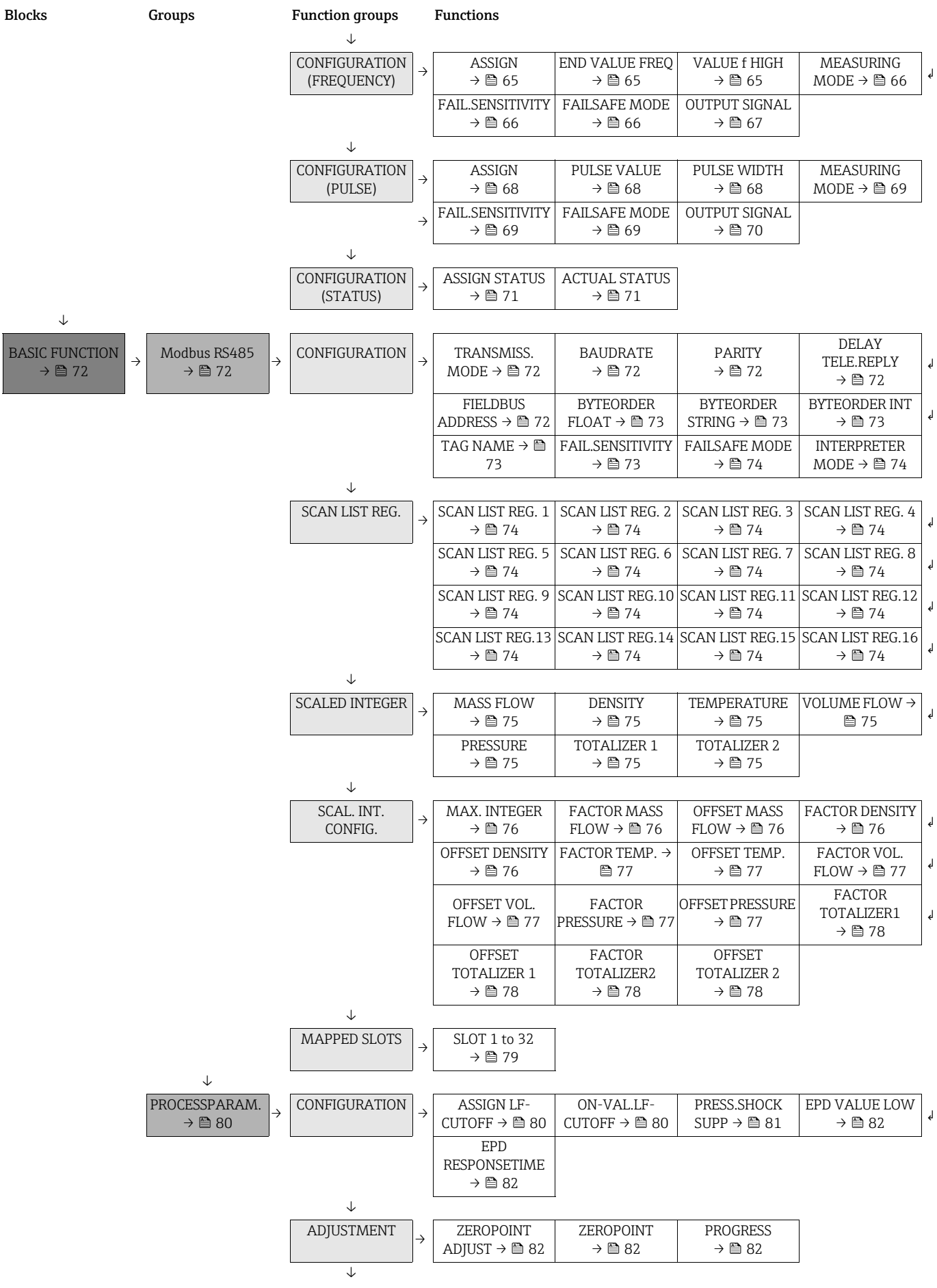
- Flow measuring technology (FA00005D/06)
- Technical Information (TI00080D/06)
- Ex-Supplementary documentation ATEX (II2G): (XA00117D/06)
- Ex-Supplementary documentation FM, CSA (Div. 1): (XA00118D/06)
- Special documentation, Pressure Equipment Directive: (SD00118D/06)

12 Appendix – Instrument functions

This appendix provides detailed descriptions and information about the individual instrument functions. All instrument functions can be selected and configured using the "FieldCare" configuration program from Endress+Hauser and via Modbus RS485 → 17. For measuring instruments with customer-specific parameter configuration, certain values and/or settings may differ from the factory settings listed above.

12.1 Display of function matrix

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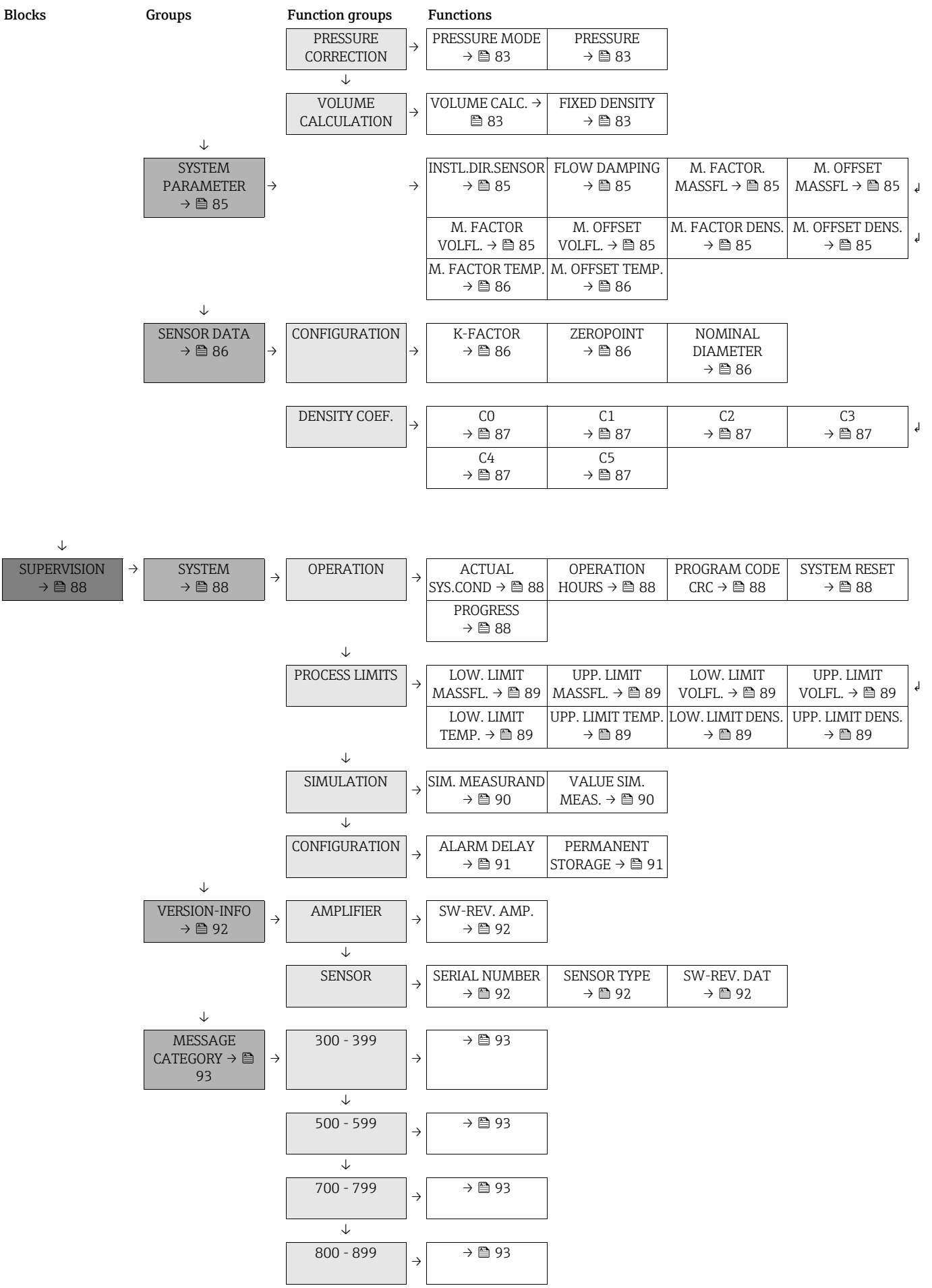
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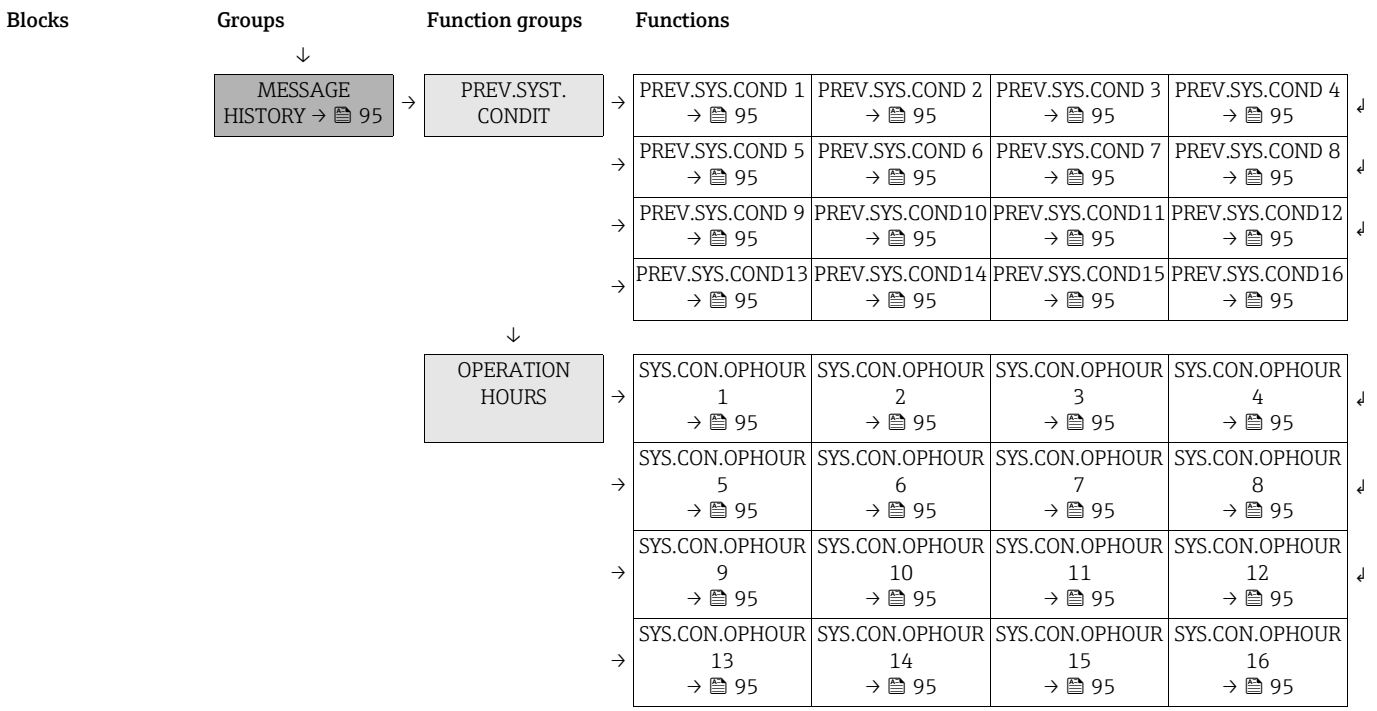
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12.2 Block "CUSTODY TRANSFER MEASUREMENT"

12.2.1 Group "CUSTODY TRANSFER MEASUREMENT"

CUSTODY TRANSFER MEASUREMENT → CUSTODY TRANSFER MEASUREMENT

Function description CUSTODY TRANSFER MEASUREMENT →CUSTODY TRANSFER MEASUREMENT	
Note! **Switching takes place using a hardware switch. For detailed information about the function of the hardware switch, refer to → 16.**	
CUSTODY TRANSFER MEASUREMENT **Modbus register:** 7551 **Data type:** Integer **Access:** Read	Displays whether secured/locked operation mode is active. Display: 0 = OFF 1 = ON **Factory setting:** OFF

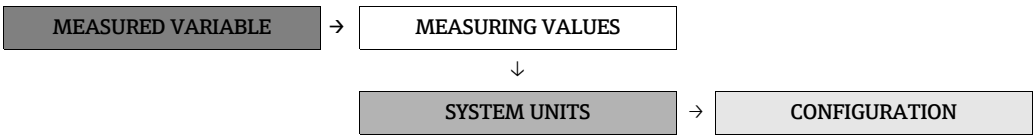
12.3 Block "MEASURED VARIABLE"

12.3.1 Group "MEASURING VALUES"

MEASURED VARIABLE → MEASURING VALUES → MAIN VALUES

Function description MEASURED VARIABLE → MEASURING VALUES → HAMAIN VALUES	
Note! **The engineering units of all the measured variables shown here can be set in the "SYSTEM UNITS" group.**	
MASS FLOW **Modbus register:** 2007 **Data type:** Float **Access:** Read	The currently measured mass flow appears on the display.
VOLUME FLOW **Modbus register:** 2009 **Data type:** Float **Access:** Read	The calculated volume flow appears on the display. The volume flow is calculated from the mass flow and the density → 84.
DENSITY **Modbus register:** 2013 **Data type:** Float **Access:** Read	The currently measured density or its specific gravity appears on the display.
TEMPERATURE **Modbus register:** 2017 **Data type:** Float **Access:** Read	The currently measured temperature appears on the display.

12.3.2 Group "SYSTEM UNITS"



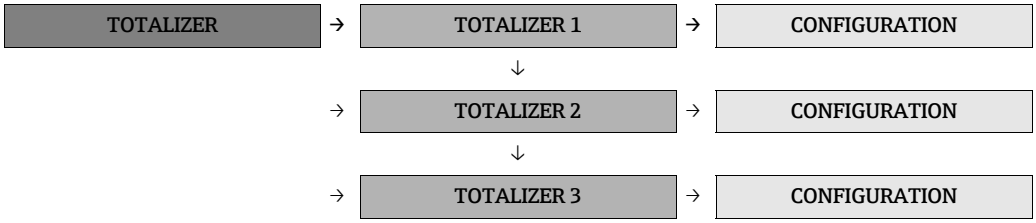
Function description MEASURED VARIABLE → SYSTEM UNITS	
UNIT MASS FLOW Modbus register: 2101 Data type: Integer Access: read/ write	For selecting the desired unit for the mass flow (mass/time). **Options:** Metric: 0 to 3 = gram → g/s; g/min; g/h; g/day 4 to 7 = kilogram → kg/s; kg/min; kg/h; kg/day 8 to 11 = ton → t/s; t/min; t/h; t/day US: 12 to 15 = ounce → oz/s; oz/min; oz/h; oz/day 16 to 19 = pound → lb/s; lb/min; lb/h; lb/day 20 to 23 = ton → ton/s; ton/min; ton/h; ton/day **Factory setting:** Country-dependent (kg/min or lb/min)
UNIT MASS Modbus register: 2102 Data type: Integer Access: read/ write	For selecting the desired unit for the mass. **Options:** 0; 1; 2 = metric → g; kg; t 3; 4; 5 = US → oz; lb; ton **Factory setting:** Country-dependent (kg or lb) ✎ Note! The unit of the totalizers is independent of your choice here. The unit for each totalizer is selected separately for the totalizer in question.

Function description MEASURED VARIABLE → SYSTEM UNITS	
UNIT VOLUME FLOW Modbus register: 2103 Data type: Integer Access: read/ write	For selecting the desired unit for the volume flow (volume/time). **Options:** Metric: 0 to 3 = cubic centimeter → cm3/s; cm3/min; cm3/h; cm3/day 4 to 7 = cubic decimeter → dm3/s; dm3/min; dm3/h; dm3/day 8 to 11 = cubic meter → m3/s; m3/min; m3/h; m3/day 12 to 15 = milliliter → ml/s; ml/min; ml/h; ml/day 16 to 19 = liter → l/s; l/min; l/h; l/day 20 to 23 = hectoliter → hl/s; hl/min; hl/h; hl/day 24 to 27 = megaliter → Ml/s; Ml/min; Ml/h; Ml/day US: 28 to 31 = cubic centimeter → cc/s; cc/min; cc/h; cc/day 32 to 35 = acre foot → af/s; af/min; af/h; af/day 36 to 39 = cubic foot → ft3/s; ft3/min; ft3/h; ft3/day 40 to 43 = fluid ounce → oz f/s; oz f/min; oz f/h; oz f/day 44 to 47 = gallon → gal/s; gal/min; gal/h; gal/day 52 to 55 = barrel (normal fluids: 31.5 gal/bbl) → bbl/s; bbl/min; bbl/h; bbl/day 56 to 59 = barrel (beer: 36.0 gal/bbl) → bbl/s; bbl/min; bbl/h; bbl/day 60 to 63 = barrel (petrochemicals: 42.0 gal/bbl) → bbl/s; bbl/min; bbl/h; bbl/day 64 to 67 = Barrel (filling tanks: 55.0 gal/bbl) → bbl/s; bbl/min; bbl/h; bbl/day Imperial: 68 to 71 = gallon → gal/s; gal/min; gal/h; gal/day 76 to 79 = barrel (beer: 36.0 gal/bbl) → bbl/s; bbl/min; bbl/h; bbl/day 80 to 83 = Barrel (petrochemicals: 34.97 gal/bbl) → bbl/s; bbl/min; bbl/h; bbl/day **Factory setting:** Country-dependent (l/min or US gal/min)
UNIT VOLUME Modbus register: 2104 Data type: Integer Access: read/ write	For selecting the desired unit for the volume. **Options:** Metric: 0 to 6 = cm3; dm3; m3; ml; l; hl; Ml US: 7 to 16 = cc; af; ft3; oz f; gal; bbl (normal fluids); bbl (beer); bbl (petrochemicals); bbl (filling tanks); Imperial: 17; 19; 20 = gal; bbl (beer); bbl (petrochemicals) **Factory setting:** Country-dependent (l or US gal) ✎ Note! The unit of the totalizers is independent of your choice here. The unit for each totalizer is selected separately for the totalizer in question.

Function description MEASURED VARIABLE → SYSTEM UNITS	
UNIT DENSITY Modbus register: 2107 Data type: Integer Access: read/ write	For selecting the desired unit for the density. **Options:** Metric: 0 to 10 = g/cm3; g/cc; kg/dm3; kg/l; kg/m3; SD 4 °C, SD 15 °C, SD 20 °C; SG 4 °C, SG 15 °C, SG 20 °C US: 11 to 16 = lb/ft3; lb/gal; lb/bbl (normal fluids); lb/bbl (beer); lb/bbl (petrochemicals); lb/bbl (filling tanks) Imperial: 17 to 19 = lb/gal; lb/bbl (beer); lb/bbl (petrochemicals) **Factory setting:** Country-dependent (kg/l or g/cc) ✎ Note! SD = Specific Density, SG = Specific Gravity The specific density is the ratio of fluid density to water density (at water temperature = 4, 15, 20 °C (39, 59, 68 °F).
UNIT TEMPERATURE Modbus register: 2109 Data type: Integer Access: read/ write	For selecting the desired unit for the temperature. **Options:** 0 = °C (Celsius) 1 = K (Kelvin) 2 = °F (Fahrenheit) **Factory setting:** Country-dependent (°C or °F)
UNIT PRESSURE Modbus register: 2130 Data type: Integer Access: read/ write	For selecting the desired unit for the pressure. **Options:** 0 = bara 1 = barg 2 = psia 3 = psig **Factory setting:** Country-dependent (barg or psig)

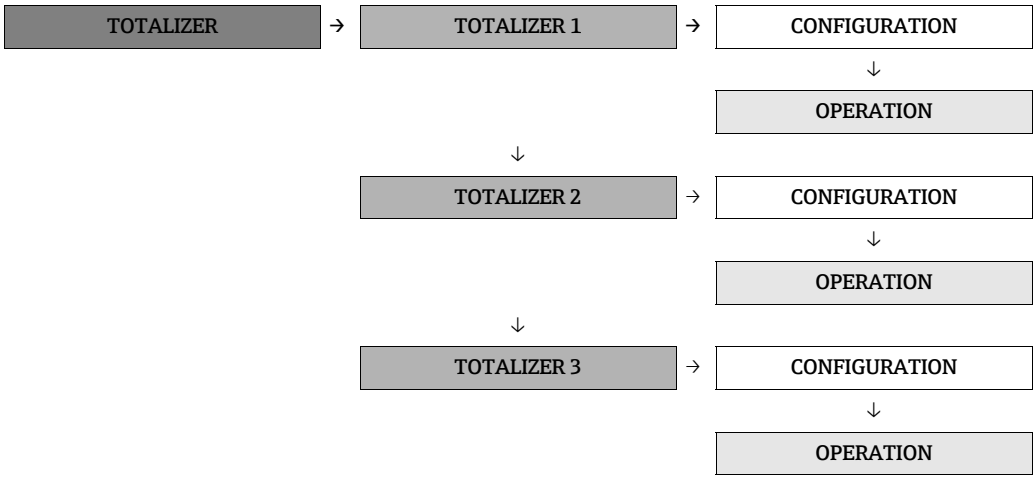
12.4 Block "TOTALIZER"

12.4.1 Group "TOTALIZER (1 to 3)"



Function description TOTALIZER → TOTALIZER 1 to 3 → CONFIGURATION	
✎ Note! The function descriptions below apply to totalizers 1 to 3; the totalizers are independently configurable.	
ASSIGN Modbus register: Totalizer 1 2601 Totalizer 2 2801 Totalizer 3 3001 Data type: Integer Access: read/ write	For assigning a measured variable to the totalizer in question. **Options:** 0 = OFF 1 = MASS FLOW 2 = VOLUME FLOW **Factory setting:** MASS FLOW ✎ Note! Selecting 0 = OFF or switching between options resets the totalizer to 0.
UNIT MASS Modbus register: Totalizer 1 2602 Totalizer 2 2802 Totalizer 3 3002 Data type: Integer Access: read/ write	For selecting the unit for the measured variable assigned in the function ASSIGN. **Options:** Metric: 0 to 2 = g; kg; t US: 3 to 5 = oz; lb; ton **Factory setting:** Country-dependent (kg or lb)
UNIT VOLUME Modbus register: Totalizer 1 2603 Totalizer 2 2803 Totalizer 3 3003 Data type: Integer Access: read/ write	For selecting the unit for the measured variable assigned in the function ASSIGN. **Options:** Metric: 0 to 6 = cm3; dm3; m3; ml; l; hl; Ml US: 7 to 16 = cc; af; ft3; oz f; gal; bbl (normal fluids); bbl (beer); bbl (petrochemicals); bbl (filling tanks) Imperial: 17; 19; 20 = gal; bbl (beer); bbl (petrochemicals) **Factory setting:** Country-dependent (l or gal)

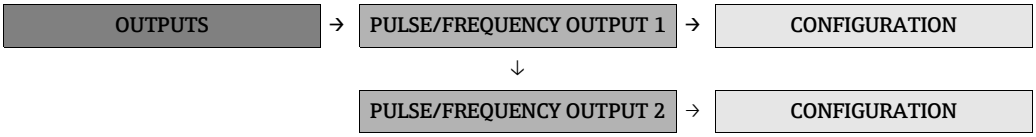
Function description TOTALIZER → TOTALIZER 1 to 3 → CONFIGURATION	
MEASURING MODE Modbus register: Totalizer 1 2605 Totalizer 2 2805 Totalizer 3 3005 Data type: Integer Access: read/ write	For selecting how the totalizer should operate. **Options:** 0 = BIDIRECTIONAL Positive and negative flow components are measured. 1 = FORWARD Only positive flow components are measured. 2 = REVERSE Only negative flow components are measured. **Factory setting:** 1 = FORWARD
FAIL.SENSITIVITY Modbus register: Totalizer 1 2615 Totalizer 2 2815 Totalizer 3 3015 Data type: Integer Access: read/ write	Defines the status categories to which the totalizer reacts. **Options:** 0 = OFF The totalizer does not react to any status. 1 = WARNING The totalizer reacts to warnings. 2 = ERRORS The totalizer reacts to errors. 3 = ERRORS AND WARN. The totalizer reacts to errors and warnings. **Factory setting:** ERRORS
FAILSAFE MODE Modbus register: Totalizer 1 2606 Totalizer 2 2806 Totalizer 3 3006 Data type: Integer Access: read/ write	Defines how the totalizer behaves when a status occurs of the category to which the totalizer is configured to react. **Options:** 0 = STOP The totalizer remains at a stop. 1 = HOLD VALUE The totalizer resumes counting with the last value before the status occurred. **Factory setting:** STOP
RESET TOTAL. Modbus register: Totalizer 1 2608 Totalizer 2 2808 Totalizer 3 3008 Data type: Integer Access: read/ write	Resets the total and the overflow of the totalizer n (1 to 3) to zero. **Options:** 0 = CANCEL 1 = START



Function description TOTALIZER 1 to 3 →OPERATION	
Note! The following function descriptions apply to totalizers 1 to 3.	
SUM Modbus register: Totalizer 1 2610 Totalizer 2 2810 Totalizer 3 3010 Data type: Float Access: Read	Displays the total for the totalizer's measured variable aggregated since the last reset.
OVERFLOW Modbus register: Totalizer 1 2612 Totalizer 2 2812 Totalizer 3 3012 Data type: Float Access: Read	Displays the totalized measured variable of the totalizer since the last reset above 10^7 in the selected unit.

12.5 Block "OUTPUTS"

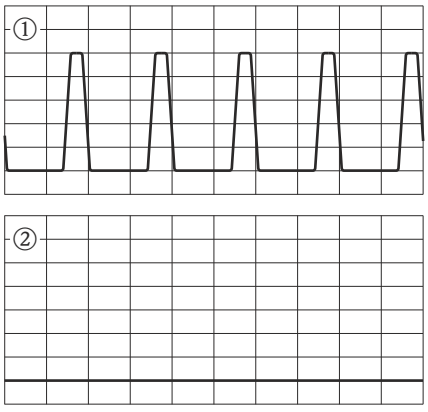
12.5.1 Group "PULSE/FREQUENCY OUTPUTS (1 to 2)"



Function description OUTPUTS → PULSE/FREQUENCY OUTPUT 1 to 2 → CONFIGURATION	
OPERATION MODE Modbus register: Pulse/freq. output 1 3201 Pulse/freq. output 2 3401 Data type: Integer Access: read/ write	Configuration of the output as a pulse, frequency or status output. The functions available in this function group vary, depending on which option you select here. **Options:** 0 = PULSE 1 = FREQUENCY 2 = STATUS 3 = OFF **Factory setting:** Pulse/frequency output 1: PULSE Pulse/frequency output 2: PULSE
CHANNEL 2 Modbus register: Pulse/freq. output 1 3255 Pulse/freq. output 2 3455 Data type: Integer Access: read/ write	Selection for output of the assigned measured variable on PULS/FREQ.OUT. 2 **Options:** 0 = OFF = no output 1 = REDUNDANCY 0° = repeated output without time delay 2 = REDUNDANCY 90° = repeated output with time delay of one-half of a pulse width 3 = REDUNDANCY 180° = repeated output with time delay of an entire pulse width 4 = PHASE SHIFT 0° = repeated output without phase shift 5 = PHASE SHIFT 90° = repeated output with 90° phase shift 6 = PHASE SHIFT 180° = repeated output with 180° phase shift **Factory setting:** OFF ✎ Note! ▪ REDUNDANCY 0°, REDUNDANCY 90° and REDUNDANCY 180° can be selected in PULSE mode of operation only. ▪ PHASE SHIFT 0°, PHASE SHIFT 90° and PHASE SHIFT 180° can be selected in PULSE and FREQUENCY modes of operation.

✎ Note!
The options selected in the functions MODE OF OPERATION and CHANNEL 2, and the resulting effects on the two pulse/frequency/status outputs, are illustrated on the following pages using examples.

Function description OUTPUTS → PULSE/FREQUENCY OUTPUT 1 to 2 → CONFIGURATION	
Descriptions of pulse/frequency/ status outputs	There are two pulse/frequency/status outputs, which can be operated **independent** or **dependent** of each other. In PULSE and FREQUENCY modes, flow measurement values can be output; in STATUS mode, statuses can be output. For example, the first pulse/frequency/status output can be used as the pulse output for mass flow, and the second pulse/frequency/status output can be used as the status output for the system status. If, for custody transfer reasons or due to the function of the downstream totalizer counter, a measured value must be output redundantly or phase-shifted, a logical pulse/frequency/status output assigns both physical outputs (selection with parameter CHANNEL 2). The other pulse/frequency/ status output is then switched off, regardless of its mode of operation. The parameter CHANNEL 2 is used to select the mode of the measured value output on the second channel. A distinction is made between the redundant pulse output REDUNDANCY in PULSE mode of operation and PHASE SHIFT in PULSE or FREQUENCY mode. Redundant pulse output means that a pulse in the first channel must always be followed by a corresponding pulse in the second channel. On the contrary, the phase shift relates to the period length of the output signal of the logically first channel. The following applies for the examples below: ▪ Wiring of pulse/frequency/status output 1 24 V DC via 1 kW pull-up at terminal 24 (+), terminal 25 (-) at ground, Signal tapped at terminal 24 (+) ▪ Wiring of pulse/frequency/status output 2 24 V DC via 1 kW pull-up at terminal 22 (+), terminal 23 (-) at ground, Signal tapped at terminal 22 (+)
Example 1 (in metric units)	Mass flow = +3600 kg/h

Parameter	IFS ouput ①	IFS output ②
OPERATION MODE	Pulse	Status
2. CHANNEL	Off	-
ASSIGN	Mass flow	Fault
MEASURING MODE	Bidirectional	-
PULSE VALUE	0,001 kg	-
PULSE WIDTH	0,25 ms	-
SIGNAL FORM	Passive positive	-
Output signal: Pulse with 0,25 ms length Pulse rate = (3600 kg/h) / 0,001 kg = 1 kHz Gauge 0 V DC, because no error status active		

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Function description
OUTPUTS → PULSE/FREQUENCY OUTPUT 1 to 2 → CONFIGURATION

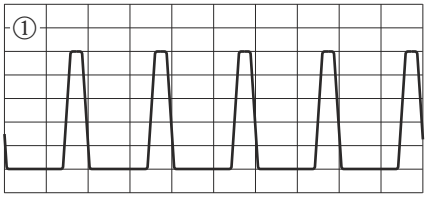
Example 2
(in metric units)

Mass flow = +3600 kg/h

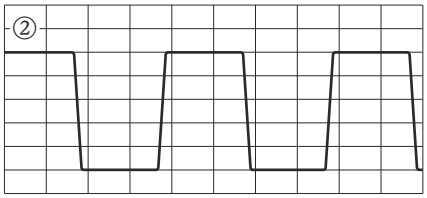
Parameter	IFS output ①	IFS output ②
OPERATION MODE	Pulse	Frequency
2. CHANNEL	Off	Off
ASSIGN	Mass flow	Mass flow
MEASURING MODE	Bidirectional	Bidirectional
PULSE VALUE	0,001 kg	-
PULSE WIDTH	0,25 ms	-
SIGNAL FORM	Passive positive	Passive positive
END VALUE	-	36000 kg/h
END VALUE FREQ.	-	5 kHz

Output signal:

Pulse with
0,25 ms length
Pulse rate =
(3600 kg/h) / 0,001 kg
= 1 kHz



Frequency f =
(3600 kg/h) /
(36000 kg /h) x
5 kHz = 500 Hz



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Example 3
(in metric units)

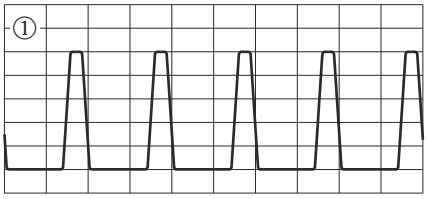
Mass flow = +3600 kg/h

Parameter	IFS output ①	IFS output ②
OPERATION MODE	Pulse	Off*
2ND CHANNEL	Redundancy 90°	-
ASSIGN	Mass flow	-
MEASURING MODE	Bidirectional	-
PULSE VALUE	0,001 kg	-
PULSE WIDTH	0,25 ms	-
SIGNAL FORM	Passive positive	-

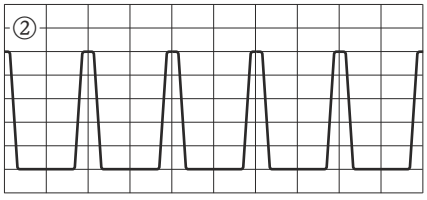
* because 2ND CHANNEL on IFS 1 is set to Redundancy 90°.

Output signal:

Pulse with
0,25 ms length
Pulse rate =
(3600 kg/h) / 0,001 kg
= 1 kHz



Pulse with
0,25 ms length
Pulse rate =
(3600 kg/h) / 0,001 kg
= 1 kHz, **lagging** half a
pulse width, because
mass flow is **positive**



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Function description
OUTPUTS → PULSE/FREQUENCY OUTPUT 1 to 2 → CONFIGURATION

Example 4
(in metric units)

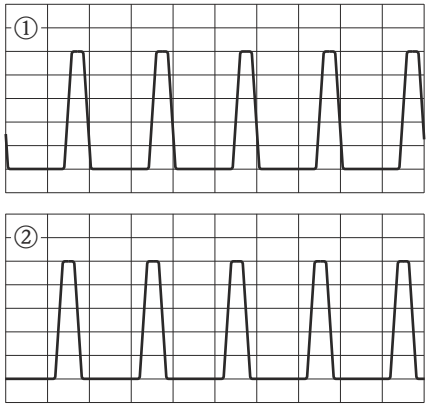
Mass flow = −3600 kg/h

Parameter	IFS output ①	IFS output ②
OPERATION MODE	Pulse	Off *
2ND CHANNEL	Redundancy 90°	-
ASSIGN	Mass flow	-
MEASURING MODE	Bidirectional	-
PULSE VALUE	0,001 kg	-
PULSE WIDTH	0,25 ms	-
SIGNAL FORM	Passive positive	-
* because 2ND CHANNEL on IFS 1 is set to Redundancy 90°.		

Output signal:

Pulse with
0,25 ms length
Pulse rate =
(3600 kg/h) / 0,001 kg
= 1 kHz

Pulse with
0,25 ms length
Pulse rate =
(3600 kg/h) / 0,001 kg
= 1 kHz, **advanced** half
a pulse width,
because mass flow is
negative



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Example 5
(in metric units)

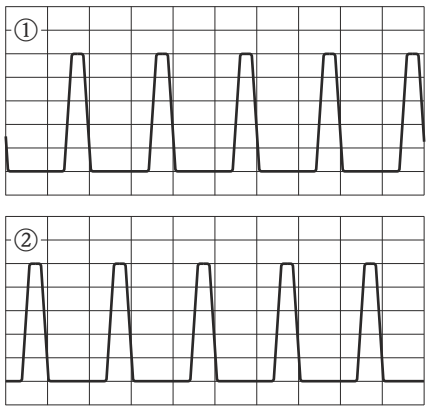
Mass flow = +3600 kg/h

Parameter	IFS output ①	IFS output ②
OPERATION MODE	Pulse	Off *
2ND CHANNEL	Phase shift 180°	-
ASSIGN	Mass flow	-
MEASURING MODE	Bidirectional	-
PULSE VALUE	0,001 kg	-
PULSE WIDTH	0,25 ms	-
SIGNAL FORM	Passive positive	-
* because 2ND CHANNEL on IFS 1 is set to Phase shift 180°.		

Output signal:

Pulse with
0,25 ms length
Pulse rate =
(3600 kg/h) / 0,001 kg
= 1 kHz

Pulse with
0,25 ms length
Pulse rate =
(3600 kg/h) / 0,001 kg
= 1 kHz, phase-shift
180°.



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Function description
OUTPUTS → PULSE/FREQUENCY OUTPUT 1 to 2 → CONFIGURATION

Example 6
(in metric units)

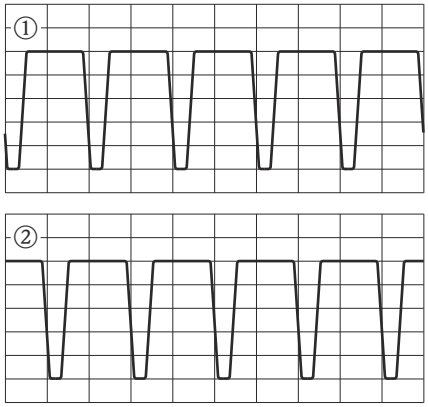
Mass flow = +3600 kg/h

Parameter	IFS output ①	IFS output ②
OPERATION MODE	Pulse	Off *
2ND CHANNEL	Phase shift 180°	-
ASSIGN	Mass flow	-
MASURING MODE	Bidirectional	-
PULSE VALUE	0,001 kg	-
PULSE WIDTH	0,25 ms	-
SIGNAL FORM	Passive negative	-
* because 2ND CHANNEL on IFS 1 is set to Phase shift 180°		

Output signal:

Pulse with
0,25 ms length
Pulse rate =
(3600 kg/h) / 0,001 kg
= 1 kHz

Pulse with
0,25 ms length
Pulse rate =
(3600 kg/h) / 0,001 kg
= 1 kHz, phase-shift
180°.



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Example 7
(in metric units)

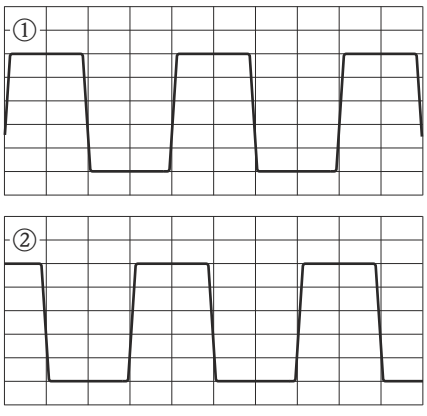
Mass flow = +3600 kg/h

Parameter	IFS output ①	IFS output ②
OPERATION MODE	Off *	Frequency
2ND CHANNEL	-	Phase shift 90°
ASSIGN	-	Mass flow
MEASURING MODE	-	Bidirectional
SIGNAL FORM	-	Passive negative
END VALUE	-	36000 kg/h
END VALUE FREQ.	-	5 kHz
* because 2ND CHANNEL on IFS 2 is set to Phase shift 90°		

Output signal:

Frequency f =
(3600 kg/h)/
(36000 kg/h) x 5 kHz
= 500 Hz, **lagging** 90°,
because mass flow is
positive

Frequency f =
(3600 kg/h)/
(36000 kg/h) x 5 kHz
= 500 Hz



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Function description
OUTPUTS → PULSE/FREQUENCY OUTPUT 1 to 2 → CONFIGURATION

Example 8
(in metric units)

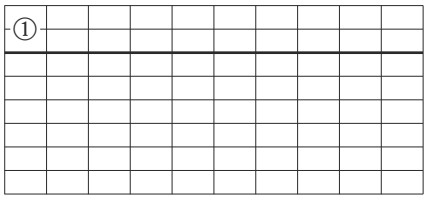
Mass flow = +3600 kg/h*

Parameter	IFS output ①	IFS output ②
OPERATION MODE	Status	Frequency
2ND CHANNEL	-	Off
ASSIGN	Fault	Mass flow
MEASURING MODE	-	Bidirectional
SIGNAL FORM	-	Passive positive
END VALUE	-	36000 kg/h
END VALUE FREQ.	-	5 kHz
FAIL SAFE MODE	-	Max. value
FAULT SENSITIVITY	-	Fault

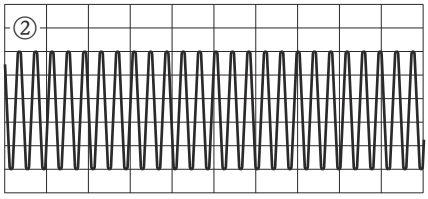
* but error condition #587 is active

Output signal:

Gauge 24 V DC, because fail safe mode is active



Frequency f = 5 kHz, because highly possible end value frequency



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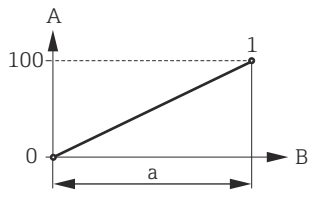
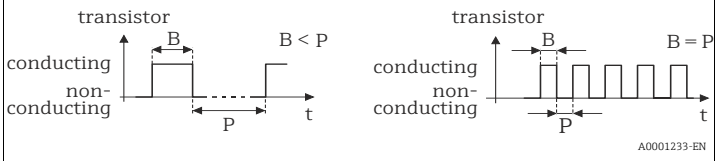
Function description OUTPUTS → PULSE/FREQUENCY OUTPUTS 1 to 2 → CONFIGURATION (frequency)	
ASSIGN Modbus register: Pulse/freq. output 1 3202 Pulse/freq. output 2 3402 Data type: Integer Access: read/ write	Assign a measured variable to the output. ✎ Note! Function is not available unless the FREQUENCY setting was selected in the OPERATION MODE function. **Options:** 0 = OFF 2 = MASS FLOW 5 = VOLUME FLOW **Factory setting:** MASS FLOW
END VALUE FREQ Modbus register: Pulse/freq. output 1 3205 Pulse/freq. output 2 3405 Data type: Float Access: read/ write	For defining an end value frequency for the frequency output. Assign the corresponding measured value to the measuring range in the function VALUE f HIGH (see below). ✎ Note! Function is not available unless the FREQUENCY setting was selected in the OPERATION MODE function. **User input:** 5-digit fixed-point number: 100 to 5000 Hz **Factory setting:** 1000 Hz Example: ▪ VALUE f HIGH = 1000 kg/h, end value frequency = 1000 Hz: i.e. a frequency of 1000 Hz is output at a flow of 1000 kg/h. ▪ VALUE f HIGH = 3600 kg/h, end value frequency = 5000 Hz: i.e. a frequency of 5000 Hz is output at a flow of 3600 kg/h. ✎ Note! In the FREQUENCY operating mode, the output signal is symmetrical (on/off ratio = 1:1).
VALUE f HIGH Modbus register: Pulse/freq. output 1 3209 Pulse/freq. output 2 3409 Data type: Float Access: read/ write	In this function, a value is assigned to the END VALUE FREQ. Determine the desired span by defining VALUE f HIGH. ✎ Note! Function is not available unless the FREQUENCY setting was selected in the OPERATION MODE function. **User input:** Floating-point number **Factory setting:** Depends on nominal diameter  A0007114 *Fig. 18: Behavior of frequency output* a = Span A = Frequency [%] B = Measured variable (amount) 1 = VALUE f HIGH (END VALUE FREQ) ✎ Note! A value greater than VALUE f HIGH cannot be output; otherwise, a message is generated (#355/#356). We recommend providing reserve capacity during parameter configuration.

Function description OUTPUTS → PULSE/FREQUENCY OUTPUTS 1 to 2 → CONFIGURATION (frequency)	
MEASURING MODE Modbus register: Pulse/freq. output 1 3211 Pulse/freq. output 2 3411 Data type: Integer Access: read/ write	Use this function to define the measuring mode for the frequency output. ✎ Note! Function available only if PULSE or FREQUENCY has been selected in the MODE OF OPERATION function. **Options:** 0 = FORWARD 1 = BIDIRECTIONAL 3 = REVERSE **Factory setting:** FORWARD **Description of the individual options:** FORWARD Only positive flow rates are output. Negative flow rates are cut off. If the output is again on the second PULS/FREQ.OUT., the time delay or phase shift is lagging. BIDIRECTIONAL Positive and negative flow rates are output. Only the amount of the flow is relevant for generating the pulses or frequency. If the output is again at the second PULS/FREQ.OUT., the time delay or phase shift is lagging if the flow rate is positive and leading if the flow rate is negative. REVERSE Only negative flow rates are output. Positive flow rates are cut off. If the output is again on the second PULS/FREQ.OUT., the time delay or phase shift is leading.
FAIL.SENSITIVITY Modbus register: Pulse/freq. output 1 3256 Pulse/freq. output 2 3456 Data type: Integer Access: read/ write	Defines the message categories to which the output reacts. **Options:** 0 = OFF = The output does not react to any status. 1 = WARNING = The output reacts to warnings. 2 = ERRORS = The output reacts to errors. 3 = ERRORS AND WARN. = The output reacts to errors and warnings **Factory setting:** ERRORS
FAILSAFE MODE Modbus register: Pulse/freq. output 1 3215 Pulse/freq. output 2 3415 Data type: Integer Access: read/ write	Defines how the PULS/FREQ.OUT. behaves when a message occurs of the category to which the PULS/FREQ.OUT. is configured to react. ✎ Note! Function is not available unless the FREQUENCY setting was selected in the OPERATION MODE function. **Options:** 0 = FALLBACK VALUE (Output is 0 Hz) 2 = HOLD VALUE (Measured value display on the basis of the last measured value preceding occurrence of the status) 4 = HIGH VALUE (Output of the highest possible pulse rate or frequency) **Factory setting:** FALLBACK VALUE ✎ Note! If OFF is not selected for CHANNEL 2, the failsafe mode of channel 2 is as follows: 1st channel / 2nd channel FALLBACK VALUE / HIGH VALUE HOLD VALUE / HOLD VALUE HIGH VALUE / FALLBACK VALUE A0007100-EN

Function description OUTPUTS → PULSE/FREQUENCY OUTPUTS 1 to 2 → CONFIGURATION (frequency)	
OUTPUT SIGNAL Modbus register: Pulse/freq. output 1 3212 Pulse/freq. output 2 3412 Data type: Integer Access: read/ write	Use this function to select the polarity of the output signal. ✎ Note! Function is not available unless the FREQUENCY setting was selected in the OPERATION MODE function. **Options:** 0 = PASSIVE/POSITIVE 1 = PASSIVE/NEGATIVE **Factory setting:** PASSIVE/POSITIVE **Description of the individual options:** PASSIVE/POSITIVE The output transistor is **nonconductive** during the first half of the period of the output signal and **conductive** during the second half of the period. PASSIVE/NEGATIVE The output transistor is **conductive** during the first half of the period of the output signal and**nonconductive** during the second half of the period.

Function description OUTPUTS → PULSE/FREQUENCY OUTPUTS 1 to 2 → CONFIGURATION (pulse)	
ASSIGN Modbus register: Pulse/freq. output 1 3223 Pulse/freq. output 2 3423 Data type: Integer Access: read/ write	Assign a measured variable to the output. ✎ Note! Function is not available unless the PULSE setting was selected in the OPERATION MODE function. **Options:** 0 = OFF 2 = MASS FLOW 5 = VOLUME FLOW **Factory setting:** VOLUME FLOW
PULSE VALUE Modbus register: Pulse/freq. output 1 3224 Pulse/freq. output 2 3424 Data type: Float Access: read/ write	Use this function to define the flow at which a pulse is triggered. These pulses can be totaled by an external totalizer, and the total flow quantity since measuring started can be registered in this way. ✎ Note! Function is not available unless the PULSE setting was selected in the OPERATION MODE function. **User input:** Floating-point number **Factory setting:** Depends on nominal diameter
PULSE WIDTH Modbus register: Pulse/freq. output 1 3226 Pulse/freq. output 2 3426 Data type: Float Access: read/ write	Use this function to enter the pulse width of the output pulse. ✎ Note! Function is not available unless the PULSE setting was selected in the OPERATION MODE function. **User input:** 0.1 to 1000 ms **Factory setting:** 1 ms Pulse output is always with the pulse width (B) entered in this function. The pauses (P) between the individual pulses are automatically configured. However, they must at least correspond to the pulse width (B = P).  *Fig. 19: Pulse Width* B = Pulse width entered (the illustration applies to positive pulses) P = Pauses between the individual pulses ✎ Note! When entering the pulse width, select a value that can still be processed by an external totalizer (e.g. mechanical totalizer, PLC, etc.). ☝ Caution! If the pulse rate resulting from the entered pulse value (see above) and the current flow rate is too large to maintain the selected pulse width (the pause interval P is smaller than the entered pulse width B), a message is generated (# 359/360).

Function description OUTPUTS → PULSE/FREQUENCY OUTPUTS 1 to 2 → CONFIGURATION (pulse)	
MEASURING MODE Modbus register: Pulse/freq. output 1 3228 Pulse/freq. output 2 3428 Data type: Integer Access: read/ write	Use this function to define the measuring mode for the pulse output. ✎ Note! Function available only if PULSE or FREQUENCY has been selected in the MODE OF OPERATION function. **Options:** 0 = FORWARD 1 = BIDIRECTIONAL 3 = REVERSE **Factory setting:** FORWARD **Description of the individual options:** BALANCE Positive and negative flow rates are output. Only the amount of the flow is relevant for generating the pulses or frequency. If the output is again at the second PULS/FREQ.OUT., the time delay or phase shift is lagging if the flow rate is positive and leading if the flow rate is negative. FORWARD Only positive flow rates are output. Negative flow rates are cut off. If the output is again on the second PULS/FREQ.OUT., the time delay or phase shift is lagging. REVERSE Only negative flow rates are output. Positive flow rates are cut off. If the output is again on the second PULS/FREQ.OUT., the time delay or phase shift is leading.
FAIL.SENSITIVITY Modbus register: Pulse/freq. output 1 3254 Pulse/freq. output 2 3454 Data type: Integer Access: read/ write	Defines the message categories to which the output reacts. **Options:** 0 = OFF = The output does not react to any status. 1 = WARNING = The output reacts to warnings. 2 = ERRORS = The output reacts to errors. 3 = ERRORS AND WARN. = The output reacts to warnings and messages **Factory setting:** ERRORS
FAILSAFE MODE Modbus register: Pulse/freq. output 1 3230 Pulse/freq. output 2 3430 Data type: Integer Access: read/ write	Defines how the PULS/FREQ.OUT. behaves when a message occurs of the category to which the PULS/FREQ.OUT. is configured to react. ✎ Note! Function is not available unless the PULSE setting was selected in the OPERATION MODE function. **Options:** 0 = FALLBACK VALUE Output is 0 Hz. 2 = HOLD VALUE Measured value display on the basis of the last measured value preceding occurrence of the message. 4 = HIGH VALUE Output of the highest possible pulse rate or frequency. **Factory setting:** FALLBACK VALUE ✎ Note! If OFF is not selected for CHANNEL 2, the failsafe mode of channel 2 is as follows: 1st channel / 2nd channel FALLBACK VALUE / HIGH VALUE HOLD VALUE / HOLD VALUE HIGH VALUE / FALLBACK VALUE A0007100-EN

Function description OUTPUTS → PULSE/FREQUENCY OUTPUTS 1 to 2 → CONFIGURATION (pulse)	
OUTPUT SIGNAL Modbus register: Pulse/freq. output 1 3229 Pulse/freq. output 2 3429 Data type: Integer Access: read/ write	Use this function to select the polarity of the output signal. ✎ Note! Function is not available unless the PULSE setting was selected in the OPERATION MODE function. **Options:** 0 = PASSIVE/POSITIVE 1 = PASSIVE/NEGATIVE **Factory setting:** PASSIVE/POSITIVE **Description of the individual options:** PASSIVE/POSITIVE The output transistor is **nonconductive** during the first half of the output of a pulse and **conductive** otherwise. PASSIVE/NEGATIVE The output transistor is **conductive** during the first half of the output of a pulse and **nonconductive** otherwise.

Function description OUTPUTS →PULSE/FREQUENCY OUTPUTS 1 to 2 →CONFIGURATION (status)	
ASSIGN STATUS Modbus register: Pulse/freq. output 1 3236 Pulse/freq. output 2 3436 Data type: Integer Access: read/ write	Use this function to assign a switching function to the status output. ✎ Note! Function is not available unless the STATUS setting was selected in the OPERATION MODE function. **Options:** 0 = OFF → nonconductive 1 = ON → conductive 2 = ERROR → nonconductive if error message is present 3 = WARNING → nonconductive if warning message is present 4 = ERROR AND WARN. → nonconductive if error or warning message is present 6 = FLOW DIRECTION → conductive if flow rate is positive and nonconductive if flow rate is negative **Factory setting:** ERRORS
ACTUAL STATUS Modbus register: 3248 Data type: Integer Access: read/ write	Use this function to check the current status of the status output. ✎ Note! Function is not available unless the STATUS setting was selected in the OPERATION MODE function. **Display:** 0 = NON CONDUCTIVE 1 = CONDUCTIVE

12.6 Block "BASIC FUNCTION"

12.6.1 Group "Modbus RS485"

BASIC FUNCTION → Modbus RS485 → CONFIGURATION

Function description BASIC FUNCTION →Modbus RS485 → CONFIGURATION	
TRANSMISS. MODE Modbus register: 4913 Data type: Integer Access: read/ write	For selecting the data transfer mode. **Options:** 0 = RTU 1 = ASCII **Factory setting:** RTU
BAUDRATE Modbus register: 4912 Data type: Integer Access: read/ write	For selecting the baud rate. **Options:** 0 = 1200 BAUD 1 = 2400 BAUD 2 = 4800 BAUD 3 = 9600 BAUD 4 = 19200 BAUD 5 = 38400 BAUD 6 = 57600 BAUD 7 = 115200 BAUD **Factory setting:** 19200 BAUD
PARITY Modbus register: 4914 Data type: Integer Access: read/ write	For selecting whether no parity bit or an even or uneven parity bit should be transmitted. **Options:** 0 = EVEN 1 = ODD 2 = NONE/STOP BITS 2 **Factory setting:** EVEN
DELAY TELE. REPLY Modbus register: 4916 Data type: Float Access: read/ write	For entering a minimum delay time after which the measuring device replies to the request telegram of the Modbus master. This allows communication to be adapted to slow Modbus RS485 masters. **User input:** 0 to 1000 ms **Factory setting:** 10 ms
FIELDBUS ADDRESS Modbus register: 4910 Data type: Integer Access: read/ write	For entering the device address. **User input:** 1 to 247 **Factory setting:** 247

Function description BASIC FUNCTION →Modbus RS485 → CONFIGURATION	
BYTEORDER FLOAT Modbus register: 4924 Data type: Integer Access: read/ write	Select the transmission sequence of bytes for the data type Float. **Options:** 0 = 0 - 1 - 2 - 3 1 = 3 - 2 - 1 - 0 2 = 2 - 3 - 0 - 1 3 = 1 - 0 - 3 - 2 **Factory setting:** 1 - 0 - 3 - 2 Note! ▪ The transmission sequence must suit the Modbus master. ▪ For more information, refer to the keyword "Byte transmission sequence", → 22.
BYTEORDER STRING Modbus register: 4922 Data type: Integer Access: read/ write	Select the transmission sequence of bytes for the data type String. **Options:** 0 = 0 - 1 1 = 1 - 0 **Factory setting:** 1 - 0 Note! ▪ The transmission sequence must suit the Modbus master. ▪ For more information, refer to the keyword "Byte transmission sequence", → 22.
BYTEORDER INT Modbus register: 4923 Data type: Integer Access: read/ write	Select the transmission sequence of bytes for the data type Integer. **Options:** 0 = 0 - 1 1 = 1 - 0 **Factory setting:** 1 - 0 Note! ▪ The transmission sequence must suit the Modbus master. ▪ For more information, refer to the keyword "Byte transmission sequence", → 22.
TAG NAME Modbus register: 4901 Data type: String (16) Access: read/ write	For entering a tag name for the measuring device. **User input:** max. 15-character text, permissible: A-Z, 0-9, +, -, punctuation marks **Factory setting:** "_ _ _ _ _ _ _ _ _ _ _ _ _ _ _ _" (No text) Note! For the Modbus, the input must end with the termination (binary null).
FAIL.SENSITIVITY Modbus register: 4921 Data type: Integer Access: read/ write	Defines the message categories to which the data transmission reacts. **Options:** 0 = OFF = The data transmission does not react to any messages. 1 = WARNING = The data transmission reacts to warnings. 2 = ERRORS = The data transmission reacts to errors. 3 = ERRORS AND WARN. = The data transmission reacts to errors and warnings **Factory setting:** ERRORS

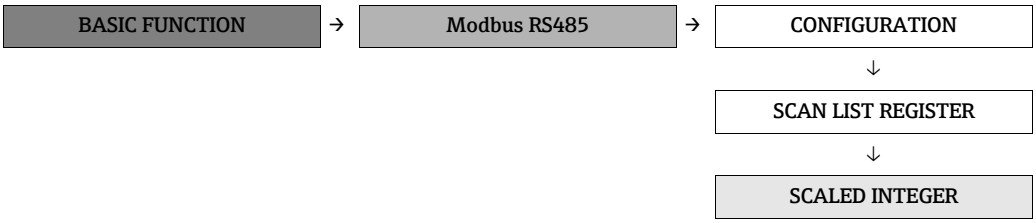
Function description BASIC FUNCTION →Modbus RS485 → CONFIGURATION	
FAILSAFE MODE Modbus register: 4920 Data type: Integer Access: read/ write	Defines how the measured value output behaves when a message occurs of the category to which it is configured to react. **Options:** 0 = STOP = The data transmission returns "NaN" 1 = HOLD VALUE = The data transmission returns the last value before the message occurred. **Factory setting:** STOP
INTERPRETER MODE Modbus Register: 4925 Datentyp: Integer Access: read/ write	Defines how the interpreter of telegram receipt behaves. **Options:** 0 = STANDARD = Behavior in accordance with Modbus standard, i.e. the two last received bytes are the check sum CRC16. 1 = IGNORE SURPLUS BYTES = the two bytes for the check sum CRC16 are determined from the telegram length which can be expected, if possible from the function code. Surplus bytes at the end of the actual telegram are ignored. This behavior does not correspond to the Modbus standard. **Factory setting:** STANDARD ✎ Note! The selection has only a meaning in the RTU mode. In the ASCII mode the equipment always behaves in accordance with the Modbus standard.

BASIC FUNCTION → Modbus RS485 → CONFIGURATION

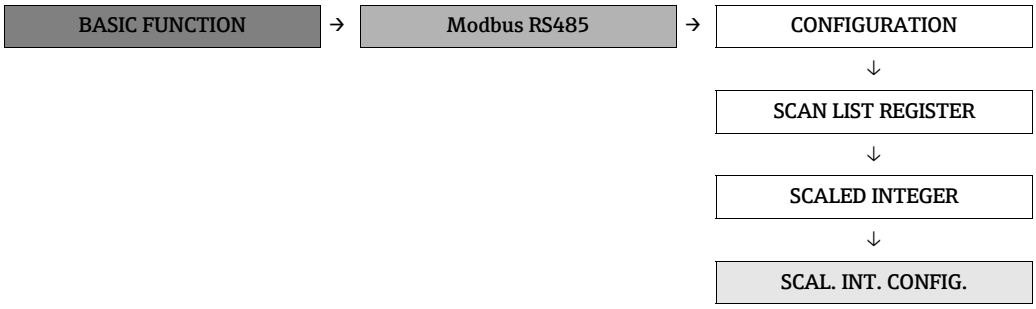
↓

SCAN LIST REGISTER

Function description BASIC FUNCTION → PROCESSPARAMETER → SCAN LIST REGISTER	
SCAN LIST REGISTER 1 TO 16 Modbus register: SCAN LIST REG. 1 5001 SCAN LIST REG. 2 5002 SCAN LIST REG. 3 5003 SCAN LIST REG. 4 5004 SCAN LIST REG. 5 5005 SCAN LIST REG. 6 5006 SCAN LIST REG. 7 5007 SCAN LIST REG. 8 5008 SCAN LIST REG. 9 5009 SCAN LIST REG. 10 5010 SCAN LIST REG. 11 5011 SCAN LIST REG. 12 5012 SCAN LIST REG. 13 5013 SCAN LIST REG. 14 5014 SCAN LIST REG. 15 5015 SCAN LIST REG. 16 5016 Data type: Integer Access: read/ write	By entering the register address (1-based), up to 16 device parameters can be grouped in the auto-scan buffer where they are assigned to the scan list registers 1 to 16. The data of the device parameters assigned here are read out via the register addresses 5051 to 5081. **User input:** 1 to 65535 **Factory setting:** 1



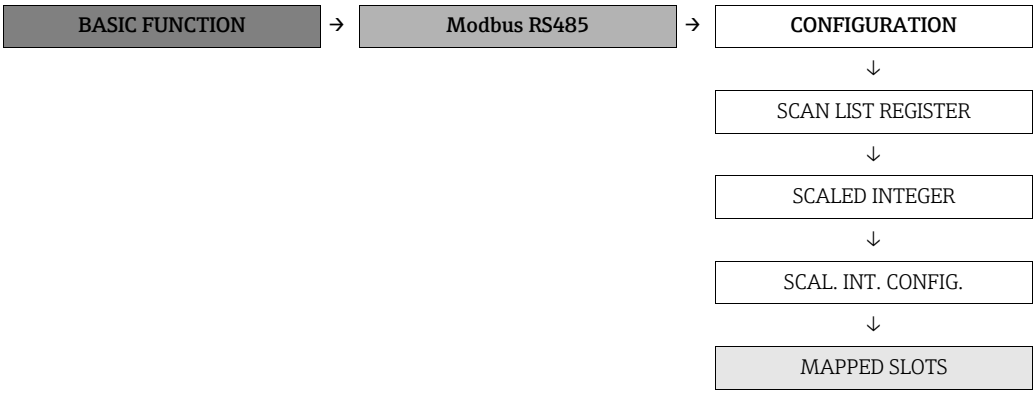
Function description BASIC FUNCTION → PROCESSPARAMETER → SCALED INTEGER	
MASS FLOW Modbus register: 2 Data type: Integer Access: read	This function shows the current measured mass flow as scaled integer. ✎ Note! Details for scaling → 🖹 25.
DENSITY Modbus register: 3 Data type: Integer Access: read	This function shows the current measured density as scaled integer. ✎ Note! Details for scaling → 🖹 25.
TEMPERATURE Modbus register: 4 Data type: Integer Access: read	This function shows the current measured temperature as scaled integer. ✎ Note! Details for scaling → 🖹 25.
VOLUME FLOW Modbus register: 5 Data type: Integer Access: read	This function shows the calculated volume flow as scaled integer. ✎ Note! Details for scaling → 🖹 25.
PRESSURE Modbus register: 7 Data type: Integer Access: read	This function shows the adjusted pressure as scaled integer. ✎ Note! Details for scaling → 🖹 25.
TOTALIZER Modbus register: TOTALIZER 1: 8 TOTALIZER 2: 9 Data type: Integer Access: read	This function shows the value of the totalizer as scaled integer. ✎ Note! The totalizer 1 must be assigned on mass flow, the totalizer 2 on volume flow. Details for scaling → 🖹 25.



Function description BASIC FUNCTION → PROCESSPARAMETER → SCALED INTEGER CONFIGURATION	
MAX. INTEGER Modbus register: 18 Data type: Integer Access: read/ write	Input of the general maximum integer value for the scaling. **User input:** 0 to 65534 **Factory settings:** 65534 ✎ Note! Details for scaling → 🖹 25.
FACTOR MASS FLOW Modbus register: 29 Data type: Integer Access: read/ write	Input of the factor of the scaled integer for the mass flow. **User input:** 0 to 65535 **Factory settings:** 1 ✎ Note! Details for scaling → 🖹 25.
OFFSET MASS FLOW Modbus register: 19 Data type: Integer Access: read/ write	Input of the offset of thed scaled integer for the mass flow. **User input:** 0 to 65536 **Factory setting:** 32768 ✎ Note! Details for scaling → 🖹 25.
FACTOR DENSITY Modbus register: 30 Data type: Integer Access: read/ write	Input of the factor of the scaled integer for the density. **User input:** 0 to 65536 **Factory setting:** 1 ✎ Note! Details for scaling → 🖹 25.
OFFSET DENSITY Modbus register: 20 Data type: Integer Access: read/ write	Input of the offset of the scaled integer for the density. **User input:** 0 to 65535 **Factory setting:** 32768 ✎ Note! Details for scaling → 🖹 25.

Function description BASIC FUNCTION → PROCESSPARAMETER → SCALED INTEGER CONFIGURATION	
FACTOR TEMPERATURE Modbus register: 31 Data type: Integer Access: read/ write	Input of the factor of the scaled integer for the temperature. **User input:** 0 to 65536 **Factory setting:** 1 ✎ Note! Details for scaling → 🖹 25.
OFFSET TEMPERATURE Modbus register: 21 Data type: Integer Access: read/ write	Input of the offset of the scaled integer for the temperature. **User input:** 0 to 65535 **Factory setting:** 32736 ✎ Note! Details for scaling → 🖹 25.
FACTOR VOLUME FLOW Modbus register: 32 Data type: Integer Access: read/ write	Input of the factor of the scaled integer for the volume flow. **User input:** 0 to 65536 **Factory setting:** 1 ✎ Note! Details for scaling → 🖹 25.
OFFSET VOLUME FLOW Modbus register: 22 Data type: Integer Access: read/ write	Input of the offset of the scaled integer for the volume flow. **User input:** 0 to 65535 **Factory setting:** 32738 ✎ Note! Details for scaling → 🖹 25.
FACTOR PRESSURE Modbus register: 34 Data type: Integer Access: read/ write	Input of the factor of the scaled integer for the pressure. **User input:** 0 to 65536 **Factory setting:** 1 ✎ Note! Details for scaling → 🖹 25.
OFFSET PRESSURE Modbus register: 24 Data type: Integer Access: read/ write	Input of the offset of the scaled integer for the pressure. **User input:** 0 to 65535 **Factory setting:** 32738 ✎ Note! Details for scaling → 🖹 25.

Function description BASIC FUNCTION → PROCESSPARAMETER → SCALED INTEGER CONFIGURATION	
FACTOR TOTALIZER Modbus register: 35 Data type: 36 Access: Integer read/ write	Input of the factor of the scaled integer for the totalizer status. **User input:** 0 to 65536 **Factory setting:** 1 ✎ Note! The totalizer 1 must be assigned on mass flow, the totalizer 2 on volume flow. Details for scaling → 🖹 25.
OFFSET TOTALIZER Modbus register: 25 Data type: 26 Access: Integer read/ write	Input of the offset of the scaled integer for the totalizer status. **User input:** 0 to 65535 **Factory setting:** 32738 ✎ Note! The totalizer 1 must be assigned on mass flow, the totalizer 2 on volume flow. Details for scaling → 🖹 25.

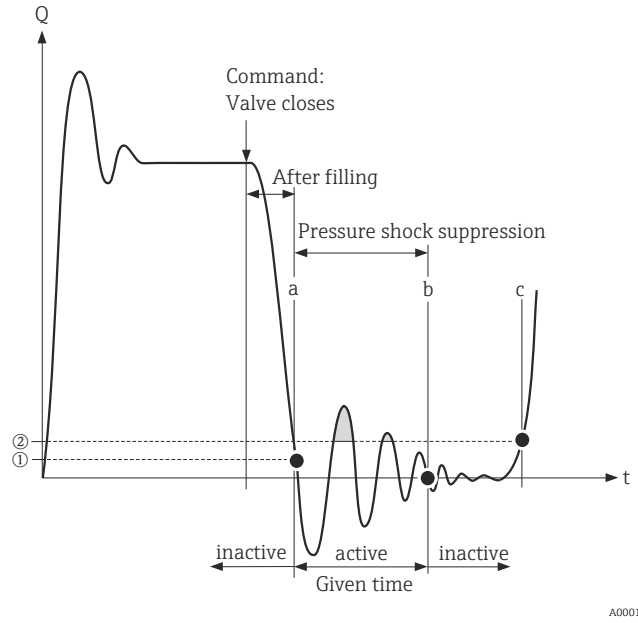


Function description BASIC FUNCTION → PROCESSPARAMETER → SCALED INTEGER CONFIGURATION	
SLOT 1 to 32 Modbus register: Slot 1: 655 Slot 2: 656 Slot 3: 657 Slot 4: 658 Slot 5: 659 Slot 6: 660 Slot 7: 661 Slot 8: 662 Slot 9: 663 Slot 10: 664 Slot 11: 665 Slot 12: 666 Slot 13: 667 Slot 14: 668 Slot 15: 669 Slot 16: 670 Slot 17: 671 Slot 18: 672 Slot 19: 673 Slot 20: 674 Slot 21: 675 Slot 22: 676 Slot 23: 677 Slot 24: 678 Slot 25: 679 Slot 26: 680 Slot 27: 681 Slot 28: 682 Slot 29: 683 Slot 30: 684 Slot 31: 685 Slot 32: 686 Data type: Integer Access: read/ write	By the input of the register address (based on 0) up to 32 equipment parameters can be grouped. The readout of the data is made by the register addresses 687/688 for Slot 1, 689/690 for Slot 2 etc. up to 749/750 for Slot 32. **User input:** 0 to 65535 **Factory setting:** 0 ✎ Note! For the readout of the data always two registers are reserved, if the value has the data type floating POINT and thus two registers occupied.

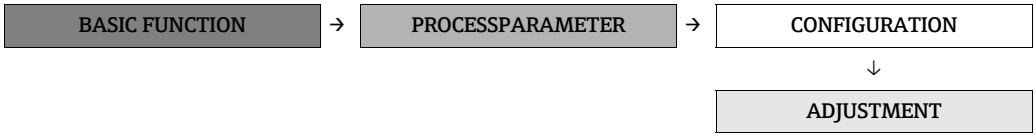
12.6.2 Group "PROCESSPARAMETER"

BASIC FUNCTION → PROCESSPARAMETER → CONFIGURATION

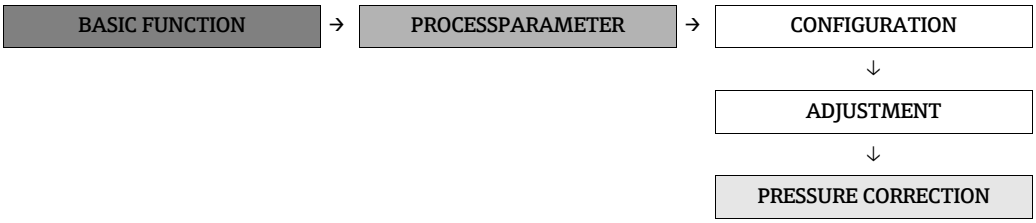
Function description BASIC FUNCTION → PROCESSPARAMETER → CONFIGURATION	
ASSIGN LF-CUTOFF Modbus register: 5101 Data type: Integer Access: read/ write	Use this function to assign the measured variable to which the low flow cut off pertains. **Options:** 1 = MASS FLOW 2 = VOLUME FLOW **Factory setting:** MASS FLOW
ON-VAL.LF-CUTOFF Modbus register: 5138 Data type: Float Access: read/ write	Use this function to assign a value to the switch-on point for low flow cut off. Low flow cut off is active if the value entered is not equal to 0. **User input:** Floating-point number **Factory setting:** Depends on nominal diameter ✎ Note! The low flow cut-off value is implicitly 150% of the on-value. Thus the low flow cut-off has a hysteresis.

Function description BASIC FUNCTION → PROCESSPARAMETER → CONFIGURATION	
PRESS.SHOCK SUPP Modbus register: 5140 Data type: Float Access: read/ write	The closure of a valve can cause brief but severe movements of the fluid which the measuring system registers. For this reason, the measuring device is equipped with pressure shock suppression (= short-term signal suppression) which can eliminate system-related "disruptions". Note! Note that pressure shock suppression cannot be used unless the low flow cut off is active, (see function ON-VAL.LF-CUTOFF → 80). Use this function to define the time span for active pressure shock suppression. **Activation of the pressure shock suppression** Pressure shock suppression is activated after the flow falls below the switch-on point of the low flow cut off (see point a in graphic). When pressure shock suppression is activated, the flow is set to null. **Deactivation of the pressure shock suppression** The pressure shock suppression is deactivated after the time interval, set in this function, has passed (see point b in graphic). The actual flow value is not displayed and output until the specified time interval for the pressure shock suppression has passed and the flow exceeds the switch-off point of the low flow cut off (see point c in the graphic).  *Fig. 20: Pressure shock suppression* ① *On-value (creepage)* ② *Off-value (creepage)* *a Active when value falls below the on-value of the low flow cut off* *b Deactivated after specified time expires* *c Flow values are again used to calculate the pulses* ■ *Suppressed values* *Q Flow* **User input:** 0.00 to 10.0 s **Factory setting:** 0.00 s

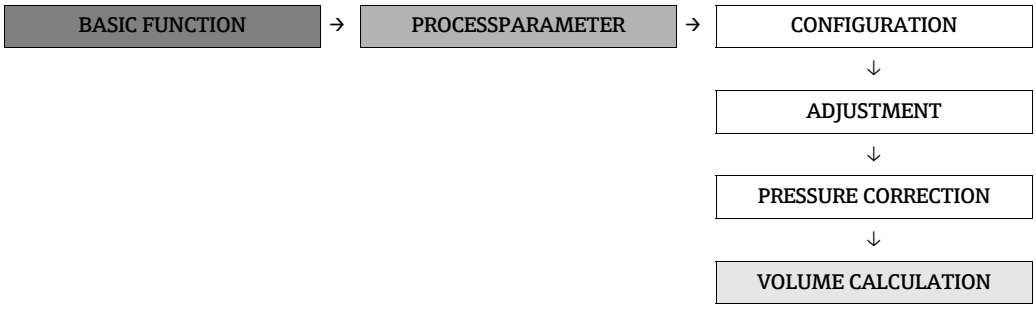
Function description BASIC FUNCTION → PROCESSPARAMETER → CONFIGURATION	
EPD VALUE LOW Modbus register: 5110 Data type: Float Access: read/ write	Use this function to set a lower threshold for the measured density value. If the value falls below this threshold, the measuring tube is considered empty. Message #700 appears. **User input:** Floating-point number **Factory setting:** 0 kg/l or 0 g/cc
EPD RESPONSETIME Modbus register: 5108 Data type: Float Access: read/ write	Use this function to define a time span for which the activation criterion for an error has to be satisfied without interruption before the function is activated. **User input:** 0 to 100 s **Factory setting:** 1.0 s



Function description BASIC FUNCTION → PROCESSPARAMETER → ADJUSTMENT	
ZEROPOINT ADJUST Modbus register: 5121 Data type: Integer Access: read/ write	This function enables a zero point adjustment to be carried out. The new zero point determined by the measuring system is adopted by the function ZERO POINT. **Options:** 0 = CANCEL 1 = START 2 = ERRORS **Factory setting:** CANCEL Caution! Before carrying this out, please refer to the detailed description of the procedure for a zero point adjustment → 26.
ZEROPOINT Modbus register: 7527 Data type: Float Access: read/ write	This function shows the current zero point correction value for the sensor. **Display:** max. 5-digit number: –99999 to +99999 **Factory setting:** Depends on calibration
PROGRESS Modbus register: 6797 Data type: Integer Access: read/ write	Displays the progress of a zero point adjustment as a percentage of the duration. **Display:** 0 to 100%



Function description BASIC FUNCTION → PROCESSPARAMETER → PRESSURE CORRECTION	
PRESSURE MODE Modbus register: 5184 Data type: Integer Access: read/ write	Use this function to configure an automatic pressure correction. In this way, the effect of a pressure deviation between the calibration and process pressures on the measured error for mass flow is compensated for (see the chapter on "Performance characteristics", → 🖹 41). **Options:** 0 = OFF 1 = ON (a fixed process pressure for pressure correction is specified). **Factory setting:** OFF ✎ Note! Measuring cells in which the pressure has only a negligible effect on the accuracy do not need this correction.
PRESSURE Modbus register: 5185 Data type: Float Access: read/ write	Use this function to enter the value for the process pressure which should be used during pressure correction. ✎ Note! Function is not available unless the ON selection was selected in the PRESSURE MODE function. **User input:** Floating-point number



Function description BASIC FUNCTION → PROCESSPARAMETER → VOLUME CALCULATION	
VOLUME CALCULATION Modbus register: 5052 Data type: Integer Access: read/ write	Use this function to select the type of volume calculation. **Options:** 0 = MEASURED DENSITY (the density measured by the device is used) 1 = FIXED DENSITY (a fixed density is specified, e.g. if the fluid is known) 2 = API TABLE (the density is taken from API table 53; the basis is the density and temperature measured by the device) **Factory setting:** MEASURED DENSITY ✎ Note! For setting the corresponding DIP switch → 🖹 16.
FIXED DENSITY Modbus register: 5130 Data type: Float Access: read/ write	Use this function to specify a fixed density of the fluid. **User input:** Floating-point number ✎ Note! This function is not available unless FIXED DENSITY was selected in the VOLUME CALCULATION function.

12.6.3 Group "SYSTEM PARAMETER"

BASIC FUNCTION → SYSTEM PARAMETER → CONFIGURATION

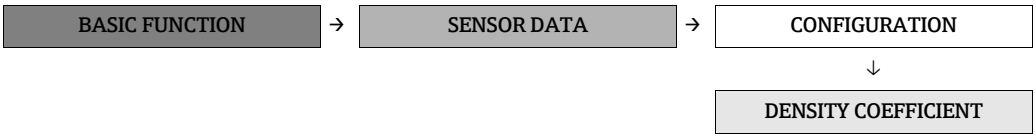
Function description BASIC FUNCTION → SYSTEM PARAMETER → CONFIGURATION	
☝ Caution! The settings configured under these functions allow the calibration officer to adjust the respective measuring values. Once the device is sealed, these settings can no longer be changed. Modifying these values in non-custody transfer mode may result in false measurements and thus is not recommended.	
INSTL.DIR. SENSOR Modbus register: 5501 Data type: Integer Access: read/write	Use this function to reverse the sign of the flow direction, if necessary. **Options:** 0 = FORWARD (flow in direction of arrow) 1 = REVERSE (flow opposite to direction of arrow) **Factory setting:** NORMAL
FLOW DAMPING Modbus register: 5510 Data type: Float Access: read/write	For setting the damping of the mass flow measured value. It can be used to reduce the spread. The reaction time of the measuring device increases with every increase in the damping. The damping acts on all functions and outputs of the measuring device. **User input:** 0 to 100 s **Factory setting:** 0 s
M. FACTOR MASS FLOW Modbus register: 5519 Data type: Float Access: read/write	Use this function to enter the factor for adjustment of the mass flow. **User input:** Floating-point number **Factory setting:** 1
M. OFFSET MASSFL Modbus register: 5521 Data type: Float Access: read/write	Use this function to enter the offset for adjustment of the mass flow. **User input:** Floating-point number **Factory setting:** 0
M. FACTOR VOLUME FLOW Modbus register: 5523 Data type: Float Access: read/write	Use this function to enter the factor for adjustment of the volume flow. **User input:** Floating-point number **Factory setting:** 1
M. OFFSET VOLFL. Modbus register: 5525 Data type: Float Access: read/write	Use this function to enter the offset for adjustment of the volume flow. **User input:** Floating-point number **Factory setting:** 0
M. FACTOR DENS. Modbus register: 5527 Data type: Float Access: read/write	Use this function to enter the factor for adjustment of the density. **User input:** Floating-point number **Factory setting:** 1
M. OFFSET DENS. Modbus register: 5529 Data type: Float Access: read/write	Use this function to enter the offset for adjustment of the density. **User input:** Floating-point number **Factory setting:** 0

Function description BASIC FUNCTION → SYSTEM PARAMETER → CONFIGURATION	
M. FACTOR TEMP. Modbus register: 5531 Data type: Float Access: read/write	Use this function to enter the factor for adjustment of the temperature. **User input:** Floating-point number **Factory setting:** 1 ✎ Note! The entered value corresponds to the absolute temperature in Kelvin. Example: - Current temperature = 26.85 °C corresponds to 300 Kelvin - Thus if a value of 1.01 is entered, the temperature changes to 303 Kelvin, corresponding to 29.85 °C.
M. OFFSET TEMP. Modbus register: 5533 Data type: Float Access: read/write	Use this function to enter the offset for adjustment of the temperature. **User input:** Floating-point number **Factory setting:** 0 ✎ Note! The unit of the entered value is always Kelvin. Example: - Current temperature = 26.85 °C corresponds to 300 Kelvin - Thus if a value of 1 is entered, the temperature changes to 301 Kelvin, corresponding to 27.85 °C.

12.6.4 Group "SENSOR DATA"

BASIC FUNCTION → SENSOR DATA → CONFIGURATION

Function description BASIC FUNCTION → SENSOR DATA → CONFIGURATION	
K-FACTOR Modbus register: 7513 Data type: Float Access: Read	This function shows the calibration factor for the sensor.
ZEROPOINT Modbus register: 7527 Data type: Float Access: read/ write	Shows the zero point for the sensor.
NOMINAL DIAMETER Modbus register: 7525 Data type: Integer Access: Read	This function shows the nominal diameter for the sensor. **Display:** 6 = DN 08 or 5/16" 8 = DN 15 or ½" 11 = DN 25 or 1" 14 = DN 40 or 1½"



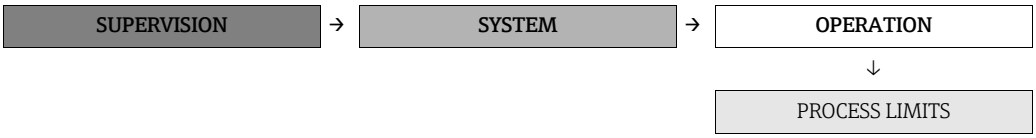
Function description BASIC FUNCTION → SENSOR DATA → DENSITY COEFFICIENT	
C0 Modbus register: 7501 Data type: Float Access: Read	Displays the density coefficient C0.
C1 Modbus register: 7503 Data type: Float Access: Read	Displays the density coefficient C1.
C2 Modbus register: 7505 Data type: Float Access: Read	Displays the density coefficient C2.
C3 Modbus register: 7507 Data type: Float Access: Read	Displays the density coefficient C3.
C4 Modbus register: 7509 Data type: Float Access: Read	Displays the density coefficient C4.
C5 Modbus register: 7511 Data type: Float Access: Read	Displays the density coefficient C5.

12.7 Block "SUPERVISION"

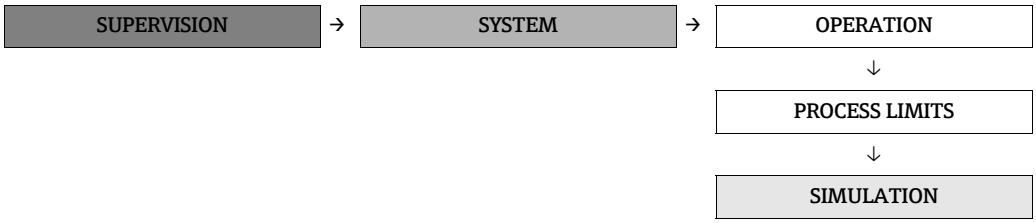
12.7.1 Group "SYSTEM"

SUPERVISION → SYSTEM → OPERATION

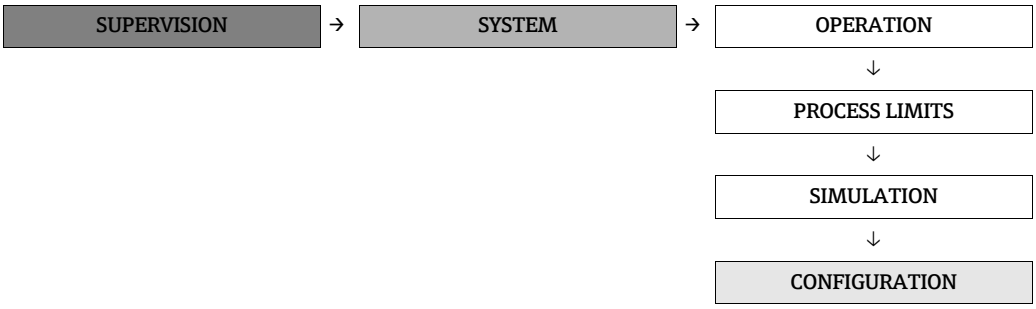
Function description SUPERVISION → SYSTEM → OPERATION	
ACTUAL SYS.COND Modbus register: 6801 Data type: Integer Access: Read	Displays the present system condition. **Display:** 0 = "SYSTEM OK" or Displays the message with the highest priority. ✎ Note! The number of the message is output via Modbus RS485, → 🖹 33.
OPERATION HOURS Modbus register: 6810 Data type: Float Access: Read	The operating hours of the device appear on the display. **Display:** ▪ Hours of operation < 10 hours → display format = 0:00:00 (hr:min:sec) ▪ Hours of operation 10 to 10,000 hours → display format = 0000:00 (hr:min) ▪ Hours of operation > 10,000 hours → display format = 000000 (hr)
PROGRAM CODE CRC Modbus register: 8933 Data type: String Access: Read	Display of the CRC checksum of the program code. ✎ Note! The CRC checksum of the program code is cyclically recalculated to check its consistency.
SYSTEM RESET Modbus register: 6817 Data type: Integer Access: read/ write	Use this function to perform a reset of the measuring system. **Options:** 0 = CANCEL 1 = RESTART SYSTEM (restart without interrupting power supply) 2 = RESET DELIVERY **Factory setting:** CANCEL ✎ Note! The parameters can take several minutes to be reset, after which the device restarts. The power supply must not be switched off while the factory settings are being restored.
PROGRESS Modbus register: 6797 Data type: Integer Access: Read	Displays the progress of restoring the default values. **Display:** 0 to 100%



Function description SUPERVISION → SYSTEM → PROCESS LIMITS	
LOW. LIMIT MASSFL. Modbus register: 6781 Data type: Float Access: read/write	Use this function to enter the lower process limit for the mass flow. If value falls below this limit, message #805 is output. **User input:** Floating-point number **Factory setting:** depends on nominal diameter and country
UPP. LIMIT MASSFL. Modbus register: 6783 Data type: Float Access: read/write	Use this function to enter the upper process limit for the mass flow. If value exceeds this limit, message #806 is output. **User input:** Floating-point number **Factory setting:** Depends on nominal diameter and country
LOW. LIMIT VOLFL. Modbus register: 6785 Data type: Float Access: read/write	Use this function to enter the lower process limit for the volume flow. If value falls below this limit, message #807 is output. **User input:** Floating-point number **Factory setting:** Depends on nominal diameter and country
UPP. LIMIT VOLFL. Modbus register: 6787 Data type: Float Access: read/write	Use this function to enter the upper process limit for the volume flow. If value exceeds this limit, message #808 is output. **User input:** Floating-point number **Factory setting:** Depends on nominal diameter and country
LOW. LIMIT TEMP. Modbus register: 6789 Data type: Float Access: read/write	Use this function to enter the lower process limit for the temperature. If value falls below this limit, message #801 is output. **User input:** Floating-point number **Factory setting:** −55°C or −67°F
UPP. LIMIT TEMP. Modbus register: 6791 Data type: Float Access: read/write	Use this function to enter the upper process limit for the temperature. If value exceeds this limit, message #802 is output. **User input:** Floating-point number **Factory setting:** +130°C or +266°F
LOW. LIMIT DENS. Modbus register: 6793 Data type: Float Access: read/write	Use this function to enter the lower process limit for the pressure. If value falls below this limit, message #803 is output. **User input:** Floating-point number **Factory setting:** 0 kg/l or 0 g/cc
UPP. LIMIT DENS. Modbus register: 6795 Data type: Float Access: read/write	Use this function to enter the upper process limit for the density. If value exceeds this limit, message #804 is output. **User input:** Floating-point number **Factory setting:** 4 kg/l or 4 g/cc



Function description SUPERVISION → SYSTEM → SIMULATION	
SIM. MEASURAND Modbus register: 6813 Data type: Integer Access: read/ write	Use this function to set the inputs, outputs and totalizers to their corresponding defined flow-response modes in order to check whether they respond correctly. During this time, message #692, "SIM. MEASURAND", appears on the display. **Options:** 0 = OFF 1 = MASS FLOW 2 = VOLUME FLOW 4 = DENSITY 6 = TEMPERATURE **Factory setting:** OFF Caution! ▪ The measuring device cannot be used for measuring while this simulation is in progress. ▪ The setting is not saved in the event of a power failure.
VALUE SIM. MEAS. Modbus register: 6814 Data type: Float Access: read/ write	For entering a user-selectable value (e.g. 30 kg/min) to check the associated functions in the device itself and downstream signal loops. Note! This function is not available unless the function SIM. MEASURAND is active. **User input:** Floating-point number Caution! The setting is not saved in the event of a power failure.



Function description SUPERVISION → SYSTEM → CONFIGURATION	
ALARM DELAY Modbus register: 6808 Data type: Float Access: read/ write	Enter a time span for which the criteria for an error have to be satisfied without interruption before a message is generated. **User input:** 0 to 100 s (in one-second increments) **Factory setting:** 0 s Caution! If this function is activated, fault and notice messages are delayed by the time corresponding to the setting before being transmitted to the higher-order controller (process controller, etc.). It is therefore imperative to check in advance in order to make sure whether a delay of this nature could affect the safety requirements of the process. If fault and notice messages may not be delayed, a value of 0 seconds must be entered here.
PERMANENT STORAG Modbus register: 6907 Data type: Integer Access: read/ write	Enter whether permanent storage of all parameters in the DAT has been switched on or off. **Options:** 0 = OFF 1 = ON **Factory setting:** ON **Description of the individual options:** OFF Changes of settings are not stored permanently. After a power failure, the settings are the same as they were before OFF was selected. This function is recommended if a setting is frequently changed via Modbus, as the number of write actions to the DAT allowed is limited to 1,000,000. ON Every change of the settings is stored permanently. After selecting ON, the measuring instrument carries out a restart and then has the same settings as before OFF was selected.

12.7.2 Group "VERSION-INFO"

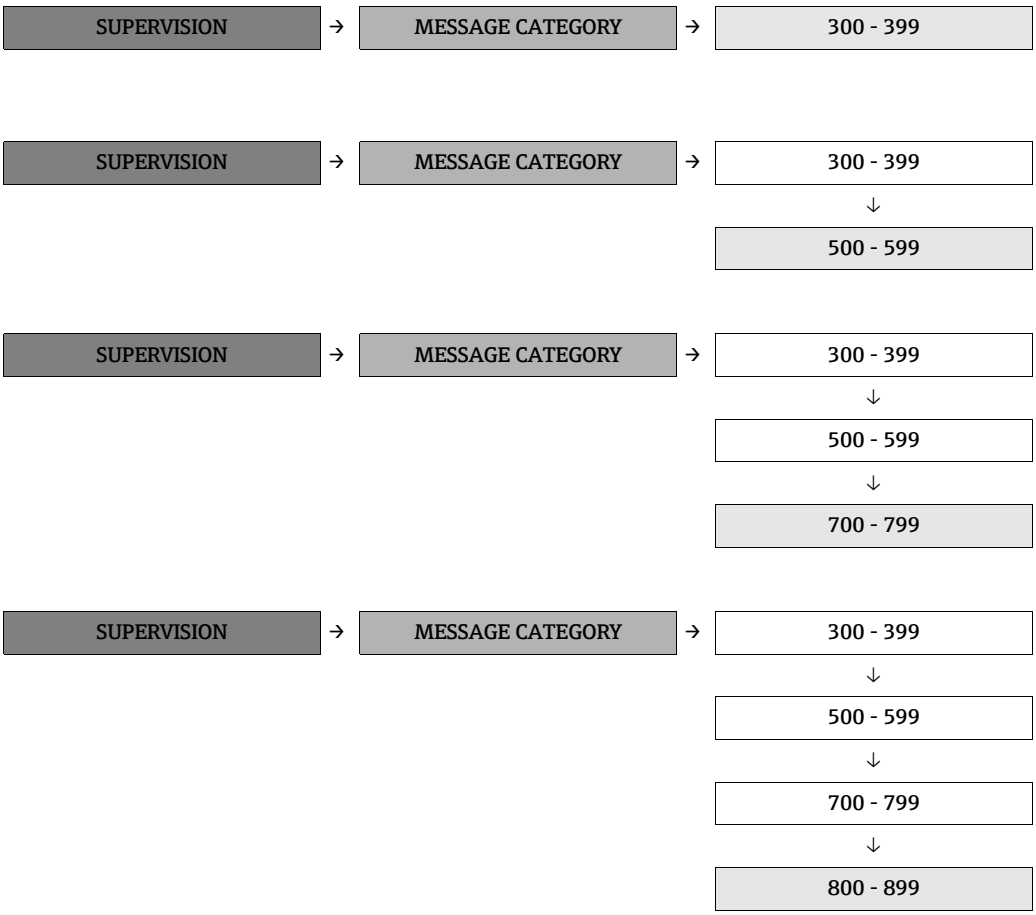
SUPERVISION → VERSION-INFO → AMPLIFIER

Function description SUPERVISION → VERSION-INFO → AMPLIFIER	
SOFTWARE REVISION AMPLIFIER Modbus register: 7039 Data type: String Access: (16) Read	Use this function to view the software revision number of the amplifier.

SUPERVISION → VERSION-INFO → AMPLIFIER
↓
SENSOR

Function description SUPERVISION → VERSION-INFO → SENSOR	
SERIAL NUMBER Modbus register: 7003 Data type: String Access: (16) Read	The serial number of the device appears on the display.
SENSOR TYPE Modbus register: 7012 Data type: String Access: (16) Read	The sensor type appears on the display.
SOFTWARE REVISION DAT Modbus register: 7021 Data type: String Access: (16) Read	Use this function to view the software revision number of the software used to program the DAT.

12.7.3 Group "MESSAGE CATEGORY"



Function description SUPERVISION → MESSAGE CATEGORY → 300 to 899	
300 to 899 Modbus register: 355 10038 356 10039 358 10041 359 10042 360 10043 361 10044 362 10045 379 10026 380 10027 381 10028 382 10029 383 10030 384 10031 385 10032 386 10033 387 10034 388 10070 389 10071 586 10035 587 10036	Set the category of a message. **Options:** 0 = OFF = No status is activated. 1 = WARNING = The status in the "Warning" category. 2 = ERROR = The status is in the "Error" category. **Factory setting:** 300 to 399 = ERROR 500 to 599 = ERROR 700 to 799 = Note 800 = Note 801 to 899 = OFF (continued on next page)

Function description SUPERVISION → MESSAGE CATEGORY → 300 to 899		
700	10050	
701	10046	
702	10047	
703	10048	
704	10049	
705	10037	
706	10051	
707	10052	
708	10053	
709	10054	
710	10055	
800	10056	
801	10057	
802	10058	
803	10059	
804	10060	
805	10061	
806	10062	
807	10063	
808	10064	
809	10065	
810	10066	
Data type:	Integer	
Access:	read/ write	

12.7.4 Group "MESSAGE HISTORY"

SUPERVISION → MESSAGE HISTORY → PREVIOUS SYSTEM CONDITIONS

Function description SUPERVISION→ MESSAGE HISTORY → PREVIOUS SYSTEM CONDITIONS	
PREV.SYS.COND n Modbus register: Fault/notice message: 1 6842 2 6843 3 6844 4 6845 5 6846 6 6847 7 6848 8 6849 9 6850 10 6851 11 6852 12 6853 13 6854 14 6855 15 6856 16 6857 Data type: Integer Access: Read	Displays the last 16 messages to occur. ✎ Note! For more information, refer to the keyword "System or process error messages."

SUPERVISION → MESSAGE HISTORY → PREVIOUS SYSTEM CONDITIONS
↓
OPERATION HOURS

Function description SUPERVISION → MESSAGE HISTORY → OPERATION HOURS	
SYS.CON.OP HOUR n Modbus register: 1 8901 2 8903 3 8905 4 8907 5 8909 6 8911 7 8913 8 8915 9 8917 10 8919 11 8921 12 8923 13 8925 14 8927 15 8929 16 8931 Data type: Float Access: Read	This displays the status of the operating hours counter at which a message has occurred. **Display:** ▪ Status of operating hours < 10 hours → display format = 0:00:00 (hr:min:sec) ▪ Status of operating hours 10 to 10,000 hours → display format = 0000:00 (hr:min) ▪ Status of operating hours > 10,000 hours → display format = 000000 (hr)

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