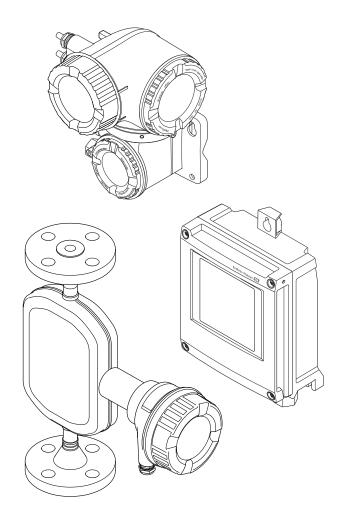
Operating Instructions **Proline Promass A 500 PROFIBUS PA**

Coriolis flowmeter







- Make sure the document is stored in a safe place such that it is always available when working on or with the device.
- To avoid danger to individuals or the facility, read the "Basic safety instructions" section carefully, as well as all other safety instructions in the document that are specific to working procedures.
- The manufacturer reserves the right to modify technical data without prior notice. Your Endress+Hauser sales organization will supply you with current information and updates to this manual.

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1 About this document

1.1 Document function

These Operating Instructions contain all the information required in the various life cycle phases of the device: from product identification, incoming acceptance and storage, to installation, connection, operation and commissioning, through to troubleshooting, maintenance and disposal.

1.2 Symbols

1.2.1 Safety symbols

DANGER

This symbol alerts you to a dangerous situation. Failure to avoid this situation will result in serious or fatal injury.

WARNING

This symbol alerts you to a potentially dangerous situation. Failure to avoid this situation can result in serious or fatal injury.

A CAUTION

This symbol alerts you to a potentially dangerous situation. Failure to avoid this situation can result in minor or medium injury.

NOTICE

This symbol alerts you to a potentially harmful situation. Failure to avoid this situation can result in damage to the product or something in its vicinity.

1.2.2 Electrical symbols

| Symbol | Meaning |
|----------|--|
| | Direct current |
| \sim | Alternating current |
| \sim | Direct current and alternating current |
| <u> </u> | Ground connection A grounded terminal which, as far as the operator is concerned, is grounded via a grounding system. |
| | Potential equalization connection (PE: protective earth) Ground terminals that must be connected to ground prior to establishing any other connections. |
| | The ground terminals are located on the interior and exterior of the device:Interior ground terminal: potential equalization is connected to the supply network.Exterior ground terminal: device is connected to the plant grounding system. |

1.2.3 Communication-specific symbols

| Symbol | Meaning |
|--------|--|
| ((1- | Wireless Local Area Network (WLAN) Communication via a wireless, local network. |

1.2.4 Tool symbols

| Symbol | Meaning |
|--------|---------------------------|
| | Torx screwdriver |
| • | Phillips head screwdriver |
| Ŕ | Open-ended wrench |

1.2.5 Symbols for certain types of information

| Symbol | Meaning |
|---------------|--|
| | Permitted Procedures, processes or actions that are permitted. |
| | Preferred Procedures, processes or actions that are preferred. |
| × | Forbidden Procedures, processes or actions that are forbidden. |
| i | Tip Indicates additional information. |
| | Reference to documentation |
| | Reference to page |
| | Reference to graphic |
| | Notice or individual step to be observed |
| 1., 2., 3 | Series of steps |
| L > | Result of a step |
| ? | Help in the event of a problem |
| | Visual inspection |

1.2.6 Symbols in graphics

| Symbol | Meaning |
|----------------|--------------------------------|
| 1, 2, 3, | Item numbers |
| 1., 2., 3., | Series of steps |
| A, B, C, | Views |
| A-A, B-B, C-C, | Sections |
| EX | Hazardous area |
| X | Safe area (non-hazardous area) |
| ≈➡ | Flow direction |

1.3 Documentation

For an overview of the scope of the associated Technical Documentation, refer to the following:

- *Device Viewer* (www.endress.com/deviceviewer): Enter the serial number from the nameplate
- *Endress+Hauser Operations app*: Enter serial number from nameplate or scan matrix code on nameplate.

The following documentation may be available depending on the device version ordered:

| Document type | Purpose and content of the document |
|--|--|
| Technical Information (TI) | Planning aid for your device The document contains all the technical data on the device and provides an overview of the accessories and other products that can be ordered for the device. |
| Brief Operating Instructions (KA) | Guide that takes you quickly to the 1st measured value The Brief Operating Instructions contain all the essential information from incoming acceptance to initial commissioning. |
| Operating Instructions (BA) | Your reference document These Operating Instructions contain all the information that is required in the various life cycle phases of the device: from product identification, incoming acceptance and storage, to mounting, connection, operation and commissioning, through to troubleshooting, maintenance and disposal. |
| Description of Device Parameters (GP) | Reference for your parameters The document provides a detailed explanation of each individual parameter. The description is aimed at those who work with the device over the entire life cycle and perform specific configurations. |
| Safety Instructions (XA) | Depending on the approval, safety instructions for electrical equipment in hazardous areas are also supplied with the device. The Safety Instructions are a constituent part of the Operating Instructions. Information on the Safety Instructions (XA) that are relevant for the device is provided on the nameplate. |
| Supplementary device-dependent documentation (SD/FY) | Always comply strictly with the instructions in the relevant supplementary documentation. The supplementary documentation is a constituent part of the device documentation. |

1.4 Registered trademarks

PROFIBUS®

Registered trademark of the PROFIBUS Nutzerorganisation e.V. (PROFIBUS User Organization), Karlsruhe, Germany

TRI-CLAMP®

Registered trademark of Ladish & Co., Inc., Kenosha, USA

2 Safety instructions

2.1 Requirements for the personnel

The personnel for installation, commissioning, diagnostics and maintenance must fulfill the following requirements:

- Trained, qualified specialists must have a relevant qualification for this specific function and task.
- Are authorized by the plant owner/operator.
- Are familiar with federal/national regulations.
- Before starting work, read and understand the instructions in the manual and supplementary documentation as well as the certificates (depending on the application).
- ► Follow instructions and comply with basic conditions.

The operating personnel must fulfill the following requirements:

- Are instructed and authorized according to the requirements of the task by the facility's owner-operator.
- ► Follow the instructions in this manual.

2.2 Intended use

Application and media

The measuring instrument described in this manual is intended only for the flow measurement of liquids and gases.

Depending on the version ordered, the measuring instrument can also be used to measure potentially explosive ¹⁾, flammable, toxid and oxidizing media.

Measuring instruments for use in hazardous areas, in hygienic applications, or where there is an increased risk due to pressure, are specially labeled on the nameplate.

To ensure that the measuring instrument is in perfect condition during operation:

- Only use the measuring instrument in full compliance with the data on the nameplate and the general conditions listed in the Operating Instructions and supplementary documentation.
- Using the nameplate, check whether the ordered device is permitted for the intended use in the hazardous area (e.g. explosion protection, pressure vessel safety).
- Use the measuring instrument only for media to which the process-wetted materials are sufficiently resistant.
- ► Keep within the specified pressure and temperature range.
- Keep within the specified ambient temperature range.
- Protect the measuring instrument permanently against corrosion from environmental influences.

Incorrect use

Non-designated use can compromise safety. The manufacturer is not liable for damage caused by improper or non-designated use.

WARNING

Danger of breakage due to corrosive or abrasive fluids and ambient conditions!

- ► Verify the compatibility of the process fluid with the sensor material.
- ► Ensure the resistance of all fluid-wetted materials in the process.
- ► Keep within the specified pressure and temperature range.

¹⁾ Not applicable for IO-Link measuring instruments

NOTICE

Verification for borderline cases:

For special fluids and fluids for cleaning, Endress+Hauser is glad to provide assistance in verifying the corrosion resistance of fluid-wetted materials, but does not accept any warranty or liability as minute changes in the temperature, concentration or level of contamination in the process can alter the corrosion resistance properties.

Residual risks

ACAUTION

Risk of hot or cold burns! The use of media and electronics with high or low temperatures can produce hot or cold surfaces on the device.

Mount suitable touch protection.

WARNING

Danger of housing breaking due to measuring tube breakage!

If a measuring tube ruptures, the pressure inside the sensor housing will rise according to the operating process pressure.

▶ Use a rupture disk.

WARNING

Danger from medium escaping!

For device versions with a rupture disk: medium escaping under pressure can cause injury or material damage.

• Take precautions to prevent injury and material damage if the rupture disk is actuated.

2.3 Workplace safety

When working on and with the device:

• Wear the required personal protective equipment as per national regulations.

2.4 Operational safety

Damage to the device!

- Operate the device in proper technical condition and fail-safe condition only.
- ► The operator is responsible for the interference-free operation of the device.

Modifications to the device

Unauthorized modifications to the device are not permitted and can lead to unforeseeable dangers!

▶ If modifications are nevertheless required, consult with the manufacturer.

Repair

To ensure continued operational safety and reliability:

- Carry out repairs on the device only if they are expressly permitted.
- Observe federal/national regulations pertaining to the repair of an electrical device.
- ► Use only original spare parts and accessories.

2.5 Product safety

This measuring device is designed in accordance with good engineering practice to meet state-of-the-art safety requirements, has been tested, and left the factory in a condition in which it is safe to operate.

It meets general safety standards and legal requirements. It also complies with the EU directives listed in the device-specific EU Declaration of Conformity. The manufacturer confirms this by affixing the CE mark to the device..

2.6 IT security

The manufacturer warranty is valid only if the product is installed and used as described in the Operating Instructions. The product is equipped with security mechanisms to protect it against any inadvertent changes to the settings.

IT security measures, which provide additional protection for the product and associated data transfer, must be implemented by the operators themselves in line with their security standards.

2.7 Device-specific IT security

The device offers a range of specific functions to support protective measures on the operator's side. These functions can be configured by the user and guarantee greater inoperation safety if used correctly. The following list provides an overview of the most important functions:

| Function/interface | Factory setting | Recommendation |
|---|------------------------|---|
| Write protection via hardware write protection switch $\rightarrow \textcircled{B} 11$ | Not enabled | On an individual basis following risk assessment |
| Access code (also applies to web server login or FieldCare connection) $\rightarrow \textcircled{B} 12$ | Not enabled (0000) | Assign a customized access code during commissioning |
| WLAN (order option in display module) | Enabled | On an individual basis following risk assessment |
| WLAN security mode | Enabled (WPA2- PSK) | Do not change |
| WLAN passphrase (Password) → 🗎 12 | Serial number | Assign an individual WLAN passphrase during commissioning |
| WLAN mode | Access point | On an individual basis following risk assessment |
| Web server $\rightarrow \square 12$ | Enabled | On an individual basis following risk assessment |
| Service interface CDI-RJ45 $\rightarrow \square$ 12 | - | On an individual basis following risk assessment |

2.7.1 Protecting access via hardware write protection

Write access to the parameters of the device via the local display, web browser or operating tool (e.g. FieldCare, DeviceCare) can be disabled via a write protection switch (DIP switch on the main electronics module). When hardware write protection is enabled, only read access to the parameters is possible.

Hardware write protection is disabled when the device is delivered $\rightarrow \square$ 156.

2.7.2 Protecting access via a password

Different passwords are available to protect write access to the device parameters or access to the device via the WLAN interface.

- User-specific access code Protect write access to the device parameters via the local display, web browser or operating tool (e.g. FieldCare, DeviceCare). Access authorization is clearly regulated through the use of a user-specific access code.
- WLAN passphrase The network key protects a connection between an operating unit (e.g. notebook or tablet) and the device via the WLAN interface which can be ordered as an option.
- Infrastructure mode
 When the device is operated in infrastructure mode, the WLAN passphrase corresponds to the WLAN passphrase configured on the operator side.

User-specific access code

Write access to the device parameters via the local display, web browser or operating tool (e.g. FieldCare, DeviceCare) can be protected by the modifiable, user-specific access code ($\rightarrow \square$ 155).

When the device is delivered, the device does not have an access code and is equivalent to 0000 (open).

WLAN passphrase: Operation as WLAN access point

A connection between an operating unit (e.g. notebook or tablet) and the device via the WLAN interface ($\rightarrow \bowtie 88$), which can be ordered as an optional extra, is protected by the network key. The WLAN authentication of the network key complies with the IEEE 802.11 standard.

When the device is delivered, the network key is pre-defined depending on the device. It can be changed via the **WLAN settings** submenu in the **WLAN passphrase** parameter ($\rightarrow \triangleq 149$).

Infrastructure mode

A connection between the device and WLAN access point is protected by means of an SSID and passphrase on the system side. Please contact the relevant system administrator for access.

General notes on the use of passwords

- The access code and network key supplied with the device should be changed during commissioning for safety reasons.
- Follow the general rules for generating a secure password when defining and managing the access code and network key.
- The user is responsible for the management and careful handling of the access code and network key.
- For information on configuring the access code or on what to do if you lose the password, for example, see "Write protection via access code" →

 155.

2.7.3 Access via web server

The integrated web server can be used to operate and configure the device via a web browser $\rightarrow \textcircled{B}$ 80. The connection is established via the service interface (CDI-RJ45) or the WLAN interface.

The web server is enabled when the device is delivered. The web server can be disabled via the **Web server functionality** parameter if necessary (e.g., after commissioning).

The device and status information can be hidden on the login page. This prevents unauthorized access to the information.

Detailed information on the device parameters: "Description of device parameters" document .

2.7.4 Access via service interface (CDI-RJ45)

The device can be connected to a network via the service interface (CDI-RJ45). Device-specific functions guarantee the secure operation of the device in a network.

The use of relevant industrial standards and guidelines that have been defined by national and international safety committees, such as IEC/ISA62443 or the IEEE, is recommended.

This includes organizational security measures such as the assignment of access authorization as well as technical measures such as network segmentation.

Transmitters with an Ex de approval may not be connected via the service interface (CDI-RJ45)!

Order code for "Approval transmitter + sensor", options (Ex de): BA, BB, C1, C2, GA, GB, MA, MB, NA, NB BB, C2, GB, MB, NB

3 Product description

The measuring system consists of a transmitter and a sensor. The transmitter and sensor are mounted in physically separate locations. They are interconnected by connecting cables.

3.1 Product design

Two versions of the transmitter are available.

3.1.1 Proline 500 – digital

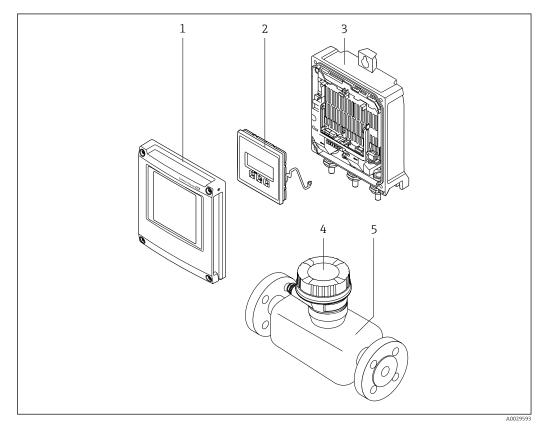
Signal transmission: digital

Order code for "Integrated ISEM electronics", option A "Sensor"

For use in applications not required to meet special requirements due to ambient or operating conditions.

As the electronics are located in the sensor, the device is ideal: For simple transmitter replacement.

- A standard cable can be used as the connecting cable.
- Not sensitive to external EMC interference.



Important components of a measuring device

- *1 Electronics compartment cover*
- 2 Display module
- 3 Transmitter housing
- 4 Sensor connection housing with integrated ISEM electronics: connecting cable connection
- 5 Sensor

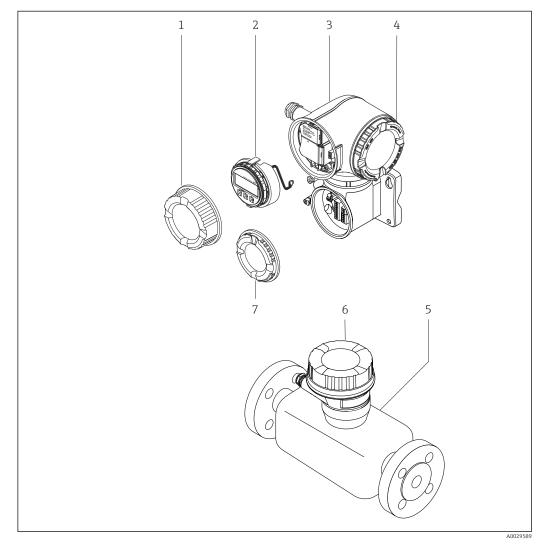
3.1.2 Proline 500

Signal transmission: analog Order code for "Integrated ISEM electronics", option **B** "Transmitter"

For use in applications required to meet special requirements due to ambient or operating conditions.

As the electronics are located in the transmitter, the device is ideal in the event of:

- Strong vibrations at the sensor.
- Sensor operation in underground installations.
- Permanent sensor immersion in water.



- Important components of a measuring device
- 1 Connection compartment cover
- 2 Display module
- *3* Transmitter housing with integrated ISEM electronics
- 4 Electronics compartment cover
- 5 Sensor
- 6 Sensor connection housing: connecting cable connection
- 7 Connection compartment cover: connecting cable connection

4 Incoming acceptance and product identification

4.1 Incoming acceptance

On receipt of the delivery:

- 1. Check the packaging for damage.
 - Report all damage immediately to the manufacturer.
 Do not install damaged components.
- 2. Check the scope of delivery using the delivery note.
- 3. Compare the data on the nameplate with the order specifications on the delivery note.
- **4.** Check the technical documentation and all other necessary documents, e.g. certificates, to ensure they are complete.

If one of the conditions is not satisfied, contact the manufacturer.

4.2 Product identification

The device can be identified in the following ways:

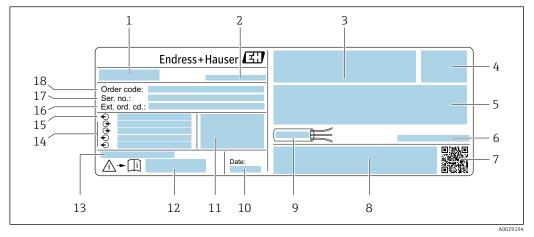
- Nameplate
- Order code with details of the device features on the delivery note
- Enter the serial numbers from the nameplates in the *Device Viewer* (www.endress.com/deviceviewer): all the information about the device is displayed.
- Enter the serial numbers from the nameplates into the *Endress+Hauser Operations app* or scan the DataMatrix code on the nameplate with the *Endress+Hauser Operations app*: all the information about the device is displayed.

For an overview of the scope of the associated Technical Documentation, refer to the following:

- The "Additional standard device documentation" and "Supplementary device-dependent documentation" sections
- The *Device Viewer*: Enter the serial number from the nameplate (www.endress.com/deviceviewer)
- The *Endress+Hauser Operations app*: Enter the serial number from the nameplate or scan the DataMatrix code on the nameplate.

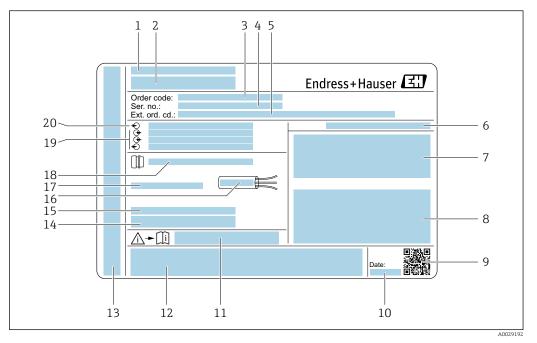
4.2.1 Transmitter nameplate

Proline 500 – digital



- ☑ 3 Example of a transmitter nameplate
- 1 Name of the transmitter
- 2 Manufacturer address/certificate holder
- 3 Space for approvals: Use in hazardous areas
- 4 Degree of protection
- 5 Electrical connection data: available inputs and outputs
- 6 Allowable ambient temperature (T_a)
- 7 2-D matrix code
- 8 Space for approvals and certificates: e.g. CE mark, RCM tick
- 9 Permitted temperature range for cable
- 10 Date of manufacture: year-month
- 11 Firmware version (FW) and device revision (Dev. rev.) from the factory
- 12 Document number of safety-related supplementary documentation
- 13 Space for additional information in the case of special products
- 14 Available inputs and outputs, supply voltage
- 15 Electrical connection data: supply voltage
- 16 Extended order code (Ext. ord. cd.)
- 17 Serial number (Ser. no.)
- 18 Order code

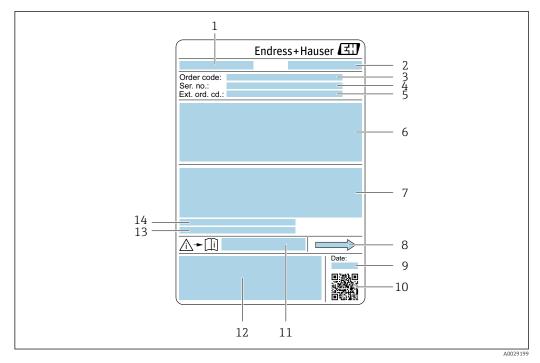
Proline 500



E 4 Example of a transmitter nameplate

- 1 Manufacturer address/certificate holder
- 2 Name of the transmitter
- 3 Order code
- 4 Serial number (Ser. no.)
- 5 Extended order code (Ext. ord. cd.)
- 6 Degree of protection
- 7 Space for approvals: use in hazardous areas
- 8 Electrical connection data: available inputs and outputs
- 9 2-D matrix code
- 10 Date of manufacture: year-month
- 11 Document number of safety-related supplementary documentation
- 12 Space for approvals and certificates: e.g. CE mark, RCM tick
- 13 Space for degree of protection of connection and electronics compartment when used in hazardous areas
- 14 Firmware version (FW) and device revision (Dev. rev.) from the factory
- 15 Space for additional information in the case of special products
- 16 Permitted temperature range for cable
- 17 Allowable ambient temperature (T_a)
- 18 Information on cable gland
- 19 Available inputs and outputs, supply voltage
- 20 Electrical connection data: supply voltage

4.2.2 Sensor nameplate



₽ 5 Example of a sensor nameplate

- Name of the sensor 1
- 2 Manufacturer address/certificate holder
- 3 Order code
- Serial number (Ser. no.) 4
- 5 Extended order code (Ext. ord. cd.)
- 6 Nominal diameter of the sensor; flange nominal diameter/nominal pressure; sensor test pressure; medium temperature range; material of measuring tube and manifold; sensor-specific information: e.g. pressure range of sensor housing, wide-range density specification (special density calibration)
- 7 Approval information for explosion protection, Pressure Equipment Directive and degree of protection
- Flow direction 8
- 9 Date of manufacture: year-month
- 10 2-D matrix code
- Document number of safety-related supplementary documentation 11
- CE mark, RCM-Tick mark 12
- 13 Surface roughness
- Allowable ambient temperature (T_a) 14



Order code

The measuring device is reordered using the order code.

Extended order code

- The device type (product root) and basic specifications (mandatory features) are always listed.
- Of the optional specifications (optional features), only the safety and approvalrelated specifications are listed (e.g. LA). If other optional specifications are also ordered, these are indicated collectively using the **#** placeholder symbol (e.g. **#LA#**).
- If the ordered optional specifications do not include any safety and approval-related specifications, they are indicated by the + placeholder symbol (e.g. XXXXXX-ABCDE +).

| Symbol | Meaning |
|--------|---|
| | WARNING! This symbol alerts you to a dangerous situation. Failure to avoid this situation can result in serious or fatal injury. Please consult the documentation for the measuring instrument to discover the type of potential danger and measures to avoid it. |
| | Reference to documentation Refers to the corresponding device documentation. |
| | Protective ground connection A terminal that must be connected to the ground prior to establishing any other connections. |

4.2.3 Symbols on the device

5 Storage and transport

5.1 Storage conditions

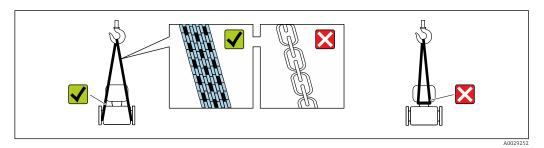
Observe the following notes for storage:

- Store in the original packaging to ensure protection from shock.
- Do not remove protective covers or protective caps installed on process connections. They prevent mechanical damage to the sealing surfaces and contamination in the measuring tube.
- Protect from direct sunlight. Avoid unacceptably high surface temperatures.
- ► Store in a dry and dust-free place.
- ► Do not store outdoors.

Storage temperature $\rightarrow \cong 264$

5.2 Transporting the product

Transport the measuring device to the measuring point in the original packaging.



Do not remove protective covers or caps installed on process connections. They prevent mechanical damage to the sealing surfaces and contamination in the measuring tube.

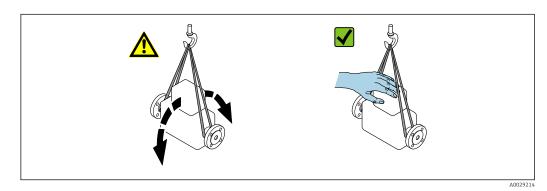
5.2.1 Measuring devices without lifting lugs

WARNING

Center of gravity of the measuring device is higher than the suspension points of the webbing slings.

Risk of injury if the measuring device slips.

- Secure the measuring device against slipping or turning.
- Observe the weight specified on the packaging (stick-on label).



Endress+Hauser

5.2.2 Measuring devices with lifting lugs

Special transportation instructions for devices with lifting lugs

- Only use the lifting lugs fitted on the device or flanges to transport the device.
- The device must always be secured at two lifting lugs at least.

5.2.3 Transporting with a fork lift

If transporting in wood crates, the floor structure enables the crates to be lifted lengthwise or at both sides using a forklift.

5.3 Packaging disposal

All packaging materials are environmentally friendly and 100% recyclable:

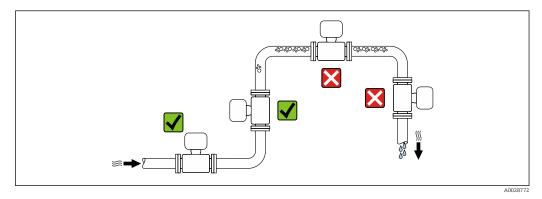
- Outer packaging of device
- Stretch wrap made of polymer in accordance with EU Directive 2002/95/EC (RoHS) Packaging
 - Wood crate treated in accordance with ISPM 15 standard, confirmed by IPPC logo
 - Cardboard box in accordance with European packaging guideline 94/62/EC, recyclability confirmed by Resy symbol
- Transport material and fastening fixtures
 - Disposable plastic pallet
 - Plastic straps
 - Plastic adhesive strips
- Filler material Paper pads

6 Installation

6.1 Mounting requirements

6.1.1 Installation position

Installation point

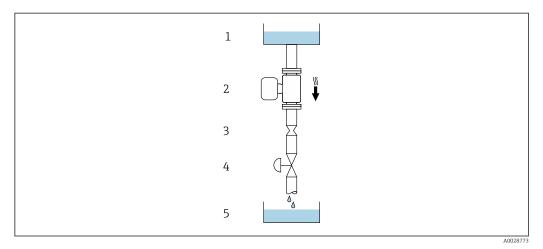


To prevent measuring errors arising from accumulation of gas bubbles in the measuring pipe, avoid the following mounting locations in the piping:

- Highest point of a pipeline.
- Directly upstream of a free pipe outlet in a down pipe.

Installation in down pipes

However, the following installation suggestion allows for installation in an open vertical pipeline. Pipe restrictions or the use of an orifice with a smaller cross-section than the nominal diameter prevent the sensor running empty while measurement is in progress.



🛃 6 Installation in a down pipe (e.g. for batching applications)

- 1 Supply tank
- 2 Sensor
- 3 Orifice plate, pipe restriction
- 4 Valve 5
- Filling vessel

| D | N | Ø orifice plate, | pipe restriction |
|------|------------------------------|------------------|------------------|
| [mm] | [in] | [mm] | [in] |
| 1 | 1/24 | 0.8 | 0.03 |
| 2 | ¹ / ₁₂ | 1.5 | 0.06 |
| 4 | 1/8 | 3.0 | 0.12 |

Orientation

The direction of the arrow on the sensor nameplate helps you to install the sensor according to the flow direction (direction of medium flow through the piping).

| Orientation | | | Recommendation |
|-------------|--|----------|----------------|
| A | Vertical orientation | A0015591 | V 1) |
| В | Horizontal orientation, transmitter at top | A0015589 | 2) |

| Orientation | | | Recommendation |
|-------------|---|----------|------------------------|
| С | Horizontal orientation, transmitter at bottom | A0015590 | № ³⁾ |
| D | Horizontal orientation, transmitter at side | A0015592 | |

- 1) This orientation is recommended to ensure self-draining.
- 2) Applications with low process temperatures may reduce the ambient temperature. To maintain the minimum ambient temperature for the transmitter, this orientation is recommended.
- 3) Applications with high process temperatures may increase the ambient temperature. To maintain the maximum ambient temperature for the transmitter, this orientation is recommended.

If a sensor is installed horizontally with a curved measuring tube, match the position of the sensor to the fluid properties.

Inlet and outlet runs

No special precautions need to be taken for fittings that create turbulence, such as valves, elbows or T-pieces, as long as no cavitation occurs $\rightarrow \cong 24$.



Installation dimensions

For the dimensions and installation lengths of the device, see the "Technical Information" document, "Mechanical construction" section

6.1.2 Environmental and process requirements

Ambient temperature range

| Measuring device | -40 to +60 °C (-40 to +140 °F) Order code for "Test, certificate", option JP: -50 to +60 °C (-58 to +140 °F) |
|--------------------------|---|
| Readability of the local | -20 to $+60$ °C (-4 to $+140$ °F) |
| display | The readability of the display may be impaired at temperatures outside the temperature range. |

P Dependency of ambient temperature on medium temperature $\rightarrow \cong 265$

► If operating outdoors:

Avoid direct sunlight, particularly in warm climatic regions.

Static pressure

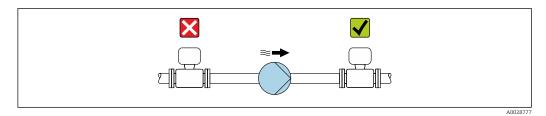
It is important that cavitation does not occur, or that gases entrained in the liquids do not outgas.

Cavitation is caused if the pressure drops below the vapor pressure:

- In liquids that have a low boiling point (e.g. hydrocarbons, solvents, liquefied gases)
- In suction lines
- Ensure the static pressure is sufficiently high to prevent cavitation and outgassing.

For this reason, the following mounting locations are recommended:

- At the lowest point in a vertical pipe
- Downstream from pumps (no danger of vacuum)



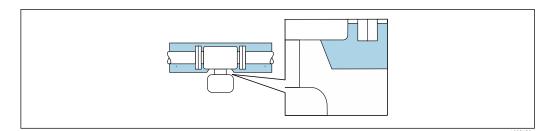
Thermal insulation

In the case of some fluids, it is important to keep the heat radiated from the sensor to the transmitter to a low level. A wide range of materials can be used for the required insulation.

NOTICE

Electronics overheating on account of thermal insulation!

- Recommended orientation: horizontal orientation, sensor connection housing pointing downwards.
- ▶ Do not insulate the sensor connection housing.
- Maximum permissible temperature at the lower end of the sensor connection housing: 80 °C (176 °F)
- Regarding thermal insulation with an exposed extended neck: We advise against insulating the extended neck to ensure optimal heat dissipation.



Thermal insulation with exposed extended neck

Heating

NOTICE

Electronics can overheat due to elevated ambient temperature!

- Observe maximum permitted ambient temperature for the transmitter.
- Depending on the medium temperature, take the device orientation requirements into account.

NOTICE

Danger of overheating when heating

- Ensure that the temperature at the lower end of the transmitter housing does not exceed 80 °C (176 °F).
- Ensure that sufficient convection takes place at the transmitter neck.
- Ensure that a sufficiently large area of the transmitter neck remains exposed. The uncovered part serves as a radiator and protects the electronics from overheating and excessive cooling.
- ➤ When using in potentially explosive atmospheres, observe the information in the device-specific Ex documentation. For detailed information on the temperature tables, see the separate document entitled "Safety Instructions" (XA) for the device.
- Consider the "830 ambient temperature too high" and "832 electronics temperature too high" process diagnostics if overheating cannot be ruled out based on a suitable system design.

Heating options

If a fluid requires that no heat loss should occur at the sensor, users can avail of the following heating options:

- Electrical heating, e.g. with electric band heaters²⁾
- Via pipes carrying hot water or steam
- Via heating jackets

Vibrations

The high oscillation frequency of the measuring tubes ensures that the correct operation of the measuring system is not influenced by plant vibrations.

6.1.3 Special installation instructions

Drainability

When the device is installed in a vertical position, the measuring tube can be drained completely and protected against deposit buildup if the properties of the measured liquid allow this. Furthermore, as only one measuring tube is used the flow is not impeded and the risk of product being retained in the measuring device is reduced to a minimum. The larger internal diameter of the measuring tube ³⁾ also reduces the risk of particles getting trapped in the measuring system. Due to the larger cross-section of the individual measuring tube, the tube is also generally less susceptible to clogging.

Hygienic compatibility

When installing in hygienic applications, please refer to the information in the "Certificates and approvals/hygienic compatibility" section $\rightarrow \cong 275$

Rupture disk

Process-related information: $\rightarrow \square 266$.

²⁾ The use of parallel electric band heaters is generally recommended (bidirectional electricity flow). Particular considerations must be made if a single-wire heating cable is to be used. For additional information, refer to EA01339D "Installation Instructions for Electrical Trace Heating Systems ".

³⁾ Compared with the double-tube design with a similar flow capacity and measuring tubes with a smaller internal diameter

WARNING

Danger from medium escaping!

Medium escaping under pressure can cause injury or material damage.

- Take precautions to prevent danger to persons and damage if the rupture disk is actuated.
- Observe the information on the rupture disk sticker.
- ► Make sure that the function and operation of the rupture disk is not impeded through the installation of the device.
- ▶ Do not remove or damage the rupture disk, drain connection and warning signs.

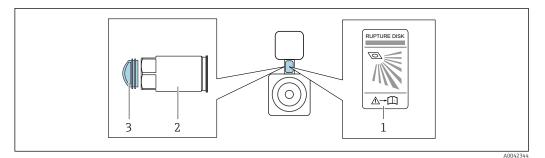
The position of the rupture disk is indicated by an affixed sticker. In versions without a drain connection (order option CU), the sticker is destroyed if the rupture disk is triggered. The disk can therefore be visually monitored.

To allow any escaping medium to drain in a controlled manner, a drain connection is available for the rupture disk integrated in the sensor: order code for "Sensor option", option CU "Drain connection for rupture disk". This connection is intended for a pipe connection with a ¹/₄ "NPT thread and sealed with a grip plug for protection. To guarantee the function of the rupture disk with a drain connection, the drain connection must be connected to the drain system in a hermetically tight manner.

The drain connection is firmly mounted in place by the manufacturer and may not be removed.

It is not possible to use the holder with a measuring device with a drain connection for a rupture disk: order code for "Sensor option", option CU "Drain connection for rupture disk"

It is not possible to use a heating jacket if the drain connection is used: order code for "Sensor option", option CU "Drain connection for rupture disk"



1 Rupture disk label

2 Drain connection for rupture disk with 1/4" NPT internal thread and 17mm width across flats (AF): order code for "Sensor option", option CU, drain connection for rupture disk

3 Transportation guard

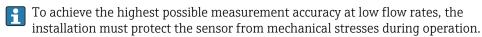
For information on the dimensions, see the "Technical Information" document, "Mechanical construction" section (accessories).

Zero verification and zero adjustment

All measuring instruments are calibrated in accordance with state-of-the-art technology. Calibration takes place under reference conditions $\rightarrow \square$ 260. Therefore, a zero adjustment in the field is generally not required.

Experience shows that zero adjustment is advisable only in special cases:

- To achieve maximum measurement accuracy even with low flow rates.
- Under extreme process or operating conditions (e.g. very high process temperatures or very high-viscosity fluids).
- For gas applications with low pressure



To get a representative zero point, ensure that:

- any flow in the device is prevented during the adjustment
- the process conditions (e.g. pressure, temperature) are stable and representative

Verification and adjustment cannot be carried out if the following process conditions are present:

- Gas pockets Ensure that the system has been sufficiently flushed with the medium. Repeat flushing can help to eliminate gas pockets
- Thermal circulation

In the event of temperature differences (e.g. between the measuring tube inlet and outlet section), induced flow can occur even if the valves are closed due to thermal circulation in the device

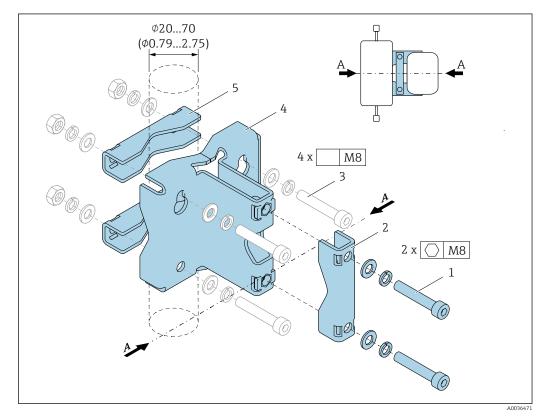
Leaks at the valves

If the valves are not leak-tight, flow is not sufficiently prevented when determining the zero point

If these conditions cannot be avoided, it is advisable to keep the factory setting for the zero point.

Sensor holder

The sensor holder is used to secure the device to a wall, tabletop or pipe (order code for "Accessory enclosed", option PR).



- 1 2 x Allen screw M8 x 50, washer and spring washer A4
- 2 1 x clamp (measuring instrument neck)
- 3 4 x securing screw for wall, tabletop or pipe mounting (not supplied)
- 4 1 x base profile
- 5 2 x clamp (pipe mounting)
- A Measuring instrument central line

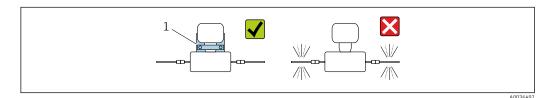
If the holder is used with a measuring instrument fitted with a rupture disk, it is important to ensure that the rupture disk in the neck is not covered over and that the cover of the rupture disk is not damaged.



Strain on pipes!

Excessive strain on an unsupported pipe can cause the pipe to break.

Install the sensor in a sufficiently supported pipe. In addition to the use of the sensor holder, for maximum mechanical stability the sensor can also be supported on the inlet and outlet sides onsite at the installation location with the use of pipe clamps, for example.



1 Sensor holder (Order code for "Accessories enclosed", option PR)

The following mounting versions are recommended for the installation:

Lubricate all threaded joints prior to mounting. The screws for wall, tabletop or pipe mounting are not supplied with the device and must be chosen to suit the individual installation position.

Wall mounting

Screw the sensor holder to the wall with four screws. Two of the four holes to secure the holder are designed to hook into the screws.

Mounting on a table

Screw the sensor holder onto the tabletop with four screws.

Pipe mounting

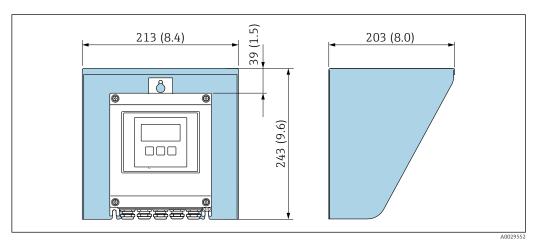
Secure the sensor holder to the pipe with two clamps.

WARNING

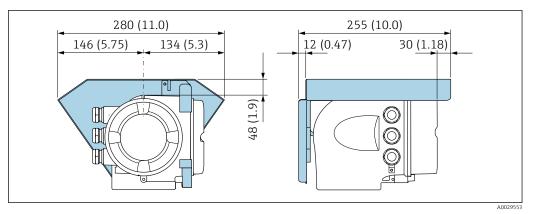
Failure to comply with the specifications for vibration and shock resistance can damage the measuring instrument!

► During operation, transportation and storage, ensure compliance with the specifications for maximum vibration and shock resistance →
⁽¹⁾ 264.

Weather protection cover



Weather protection cover for Proline 500 – digital; engineering unit mm (in)



Weather protection cover for Proline 500; engineering unit mm (in)

6.2 Installing the measuring instrument

6.2.1 Required tools

For transmitter

For mounting on a post:

- Proline 500 digital transmitter
 - Open-ended wrench AF 10
 - Torx screwdriver TX 25
- Proline 500 transmitter
 Open-ended wrench AF 13

For wall mounting: Drill with drill bit Ø 6.0 mm

For sensor

For flanges and other process connections: Use a suitable mounting tool.

6.2.2 Preparing the measuring instrument

- 1. Remove all remaining transport packaging.
- 2. Remove any protective covers or protective caps present from the sensor.
- 3. Remove stick-on label on the electronics compartment cover.

6.2.3 Mounting the measuring device

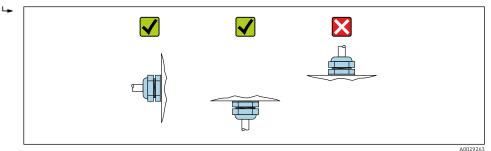
WARNING

Danger due to improper process sealing!

- Ensure that the inside diameters of the gaskets are greater than or equal to that of the process connections and piping.
- Ensure that the seals are clean and undamaged.
- Secure the seals correctly.

1. Ensure that the direction of the arrow on the nameplate of the sensor matches the flow direction of the medium.

2. Install the measuring device or turn the transmitter housing so that the cable entries do not point upwards.



6.2.4 Mounting the transmitter housing: Proline 500 – digital

ACAUTION

Ambient temperature too high!

Danger of electronics overheating and housing deformation.

- Do not exceed the permitted maximum ambient temperature.
- ► If operating outdoors: Avoid direct sunlight and exposure to weathering, particularly in warm climatic regions.

ACAUTION

Excessive force can damage the housing!

• Avoid excessive mechanical stress.

- The transmitter can be mounted in the following ways:
- Post mounting
- Wall mounting

Pipe mounting

Required tools:

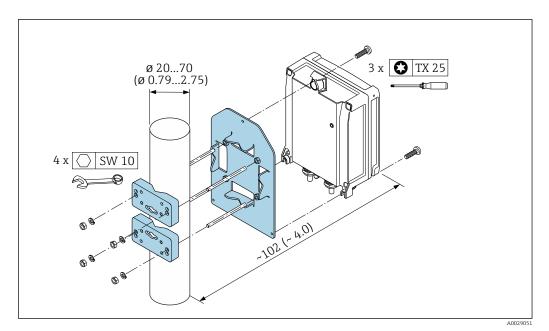
- Open-ended wrench AF 10
- Torx screwdriver TX 25

NOTICE

Excessive tightening torque applied to the fixing screws!

Risk of damaging the plastic transmitter.

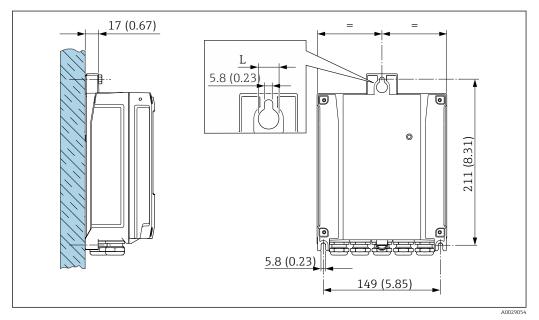
► Tighten the fixing screws as per the tightening torque: 2.5 Nm (1.8 lbf ft)



🖻 10 Unit mm (in)

Wall mounting

Required tools: Drill with drill bit Ø 6.0 mm



■ 11 Engineering unit mm (in)

L Depends on order code for "Transmitter housing"

Order code for "Transmitter housing"

- Option **A**, aluminum, coated: L = 14 mm (0.55 in)
- Option **D**, polycarbonate: L = 13 mm (0.51 in)

1. Drill the holes.

- 2. Insert wall plugs into the drilled holes.
- 3. Screw in the fixing screws slightly.
- 4. Fit the transmitter housing over the fixing screws and mount in place.

5. Tighten the fixing screws.

6.2.5 Mounting the transmitter housing: Proline 500

ACAUTION

Ambient temperature too high!

Danger of electronics overheating and housing deformation.

- Do not exceed the permitted maximum ambient temperature.
- If operating outdoors: Avoid direct sunlight and exposure to weathering, particularly in warm climatic regions.

ACAUTION

Excessive force can damage the housing!

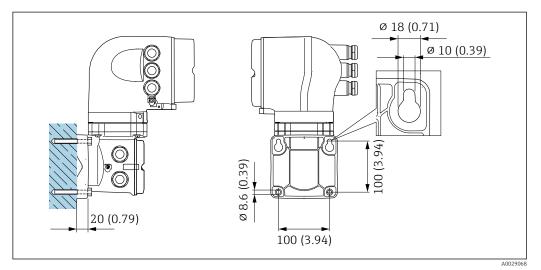
► Avoid excessive mechanical stress.

The transmitter can be mounted in the following ways:

- Post mounting
- Wall mounting

Wall mounting

Required tools Drill with drill bit Ø 6.0 mm



🗷 12 Engineering unit mm (in)

1. Drill the holes.

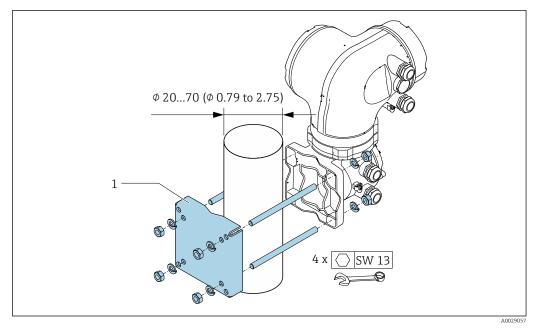
2. Insert wall plugs into the drilled holes.

- 3. Screw in the fixing screws slightly.
- 4. Fit the transmitter housing over the fixing screws and mount in place.

5. Tighten the fixing screws.

Pipe mounting

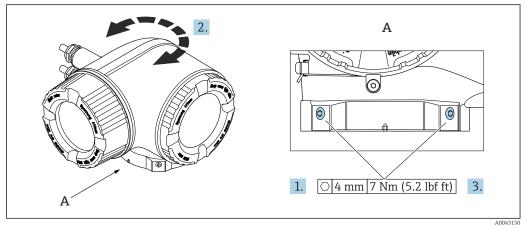
Required tools Open-ended wrench AF 13



🗷 13 Engineering unit mm (in)

6.2.6 Turning the transmitter housing: Proline 500

To provide easier access to the connection compartment or display module, the transmitter housing can be turned.

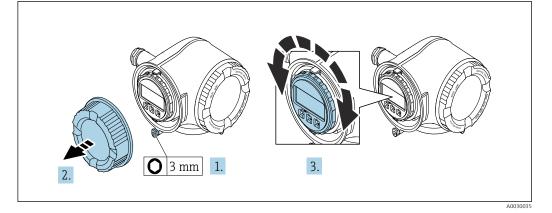


🖻 14 Ex housing

- 1. Loosen the fixing screws.
- 2. Turn the housing to the desired position.
- 3. Tighten the securing screws.

6.2.7 Turning the display module: Proline 500

The display module can be turned to optimize display readability and operability.



- **1.** Depending on the device version: Loosen the securing clamp of the connection compartment cover.
- 2. Unscrew the connection compartment cover.
- 3. Turn the display module to the desired position: max. $8 \times 45^{\circ}$ in each direction.
- 4. Screw on the connection compartment cover.
- **5.** Depending on the device version: Attach the securing clamp of the connection compartment cover.

6.3 Post-installation check

| Is the device undamaged (visual inspection)? | |
|---|--|
| Does the measuring instrument correspond to the measuring point specifications? For example: Process temperature → ²⁶⁵ 265 Pressure (refer to the "Pressure-temperature ratings" section of the "Technical Information" document). Ambient temperature Measuring range | |
| Has the correct orientation for the sensor been selected → [□] 23? According to sensor type According to medium temperature According to medium properties (outgassing, with entrained solids) | |
| Does the arrow on the sensor match the direction of flow of the medium? $\rightarrow \square 23$? | |
| Is the tag name and labeling correct (visual inspection)? | |
| Is the device sufficiently protected from precipitation and direct sunlight? | |
| Are the securing screw and securing clamp tightened securely? | |

7 Electrical connection

WARNING

Live parts! Incorrect work performed on the electrical connections can result in an electric shock.

- Set up a disconnecting device (switch or power-circuit breaker) to easily disconnect the device from the supply voltage.
- ► In addition to the device fuse, include an overcurrent protection unit with max. 10 A in the plant installation.

7.1 Electrical safety

In accordance with applicable national regulations.

7.2 Connecting requirements

7.2.1 Required tools

- For cable entries: use appropriate tool
- For securing clamp: Allen key 3 mm
- Wire stripper
- When using stranded cables: crimper for wire end ferrule
- For removing cables from terminal: flat blade screwdriver \leq 3 mm (0.12 in)

7.2.2 Requirements for connection cable

The connecting cables provided by the customer must fulfill the following requirements.

Protective grounding cable for the outer ground terminal

Conductor cross-section < 2.1 mm² (14 AWG)

The use of a cable lug enables the connection of larger cross-sections.

The grounding impedance must be less than 2 Ω .

Permitted temperature range

- The installation guidelines that apply in the country of installation must be observed.
- The cables must be suitable for the minimum and maximum temperatures to be expected.

Power supply cable (incl. conductor for the inner ground terminal)

Standard installation cable is sufficient.

Signal cable

For custody transfer, all signal lines must be shielded cables (tinned copper braiding, optical coverage \geq 85 %). The cable shield must be connected on both sides.

PROFIBUS PA

Shielded twisted-pair cable. Cable type A is recommended.

See https://www.profibus.com "PROFIBUS Installation Guidelines".

Ethernet-APL

Shielded twisted-pair cable. Cable type A is recommended.
See https://www.profibus.com Ethernet-APL White Paper "

Current output 0 /4 to 20 mA (excluding HART) Standard installation cable is sufficient.

Pulse /frequency /switch output Standard installation cable is sufficient.

Relay output Standard installation cable is sufficient.

Current input 4 to 20 mA Standard installation cable is sufficient.

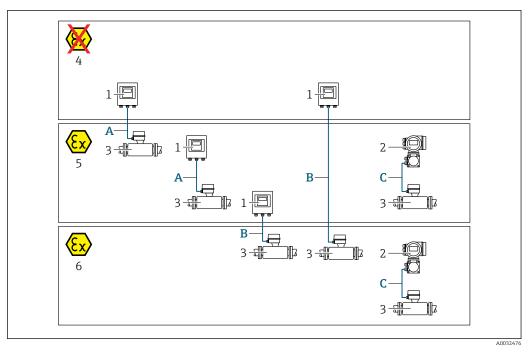
Status input Standard installation cable is sufficient.

Cable diameter

- Cable glands supplied: M20 × 1.5 with cable Ø 6 to 12 mm (0.24 to 0.47 in)
- Spring-loaded terminals: Suitable for strands and strands with ferrules. Conductor cross-section 0.2 to 2.5 mm² (24 to 12 AWG).

Choice of connecting cable between the transmitter and sensor

Depends on the type of transmitter and the installation zones



- 1 Proline 500 digital transmitter
- 2 Proline 500 transmitter
- 3 Sensor Promass
- 4 Non-hazardous area
- 5 Hazardous area: Zone 2; Class I, Division 2
- 6 Hazardous area: Zone 1; Class I, Division 1
- A Standard cable to 500 digital transmitter →
 ^B 38
 Transmitter installed in the non-hazardous area or hazardous area: Zone 2; Class I, Division 2/sensor
 installed in the hazardous area: Zone 2; Class I, Division 2
- B Standard cable to 500 digital transmitter →
 ^B 39
 Transmitter installed in the hazardous area: Zone 2; Class I, Division 2/sensor installed in the hazardous area:
 Zone 1; Class I, Division 1
- C Signal cable to 500 transmitter → 🗎 41 Transmitter and sensor installed in the hazardous area: Zone 2; Class I, Division 2 or Zone 1; Class I, Division 1

A: Connecting cable between sensor and transmitter: Proline 500 - digital

Standard cable

A standard cable with the following specifications can be used as the connecting cable.

| Design | 4 cores (2 pairs); uninsulated stranded CU wires; pair-stranded with common shield | | |
|---------------------|--|--|--|
| Shield | Tin-plated copper braid, optical cover \geq 85 % | | |
| Loop resistance | Power supply line (+, –): maximum 10Ω | | |
| Cable length | Maximum 300 m (900 ft), see the following table. | | |
| Device plug, side 1 | M12 socket, 5-pin, A-coded. | | |
| Device plug, side 2 | M12 plug, 5-pin, A-coded. | | |
| Pins 1+2 | Connected cores as twisted pair. | | |
| Pins 3+4 | Connected cores as twisted pair. | | |

| Cross-section | Cable length [max.] |
|-------------------------------|---------------------|
| 0.34 mm ² (AWG 22) | 80 m (240 ft) |
| 0.50 mm ² (AWG 20) | 120 m (360 ft) |
| 0.75 mm ² (AWG 18) | 180 m (540 ft) |

| Cross-section | Cable length [max.] | | |
|-------------------------------|---------------------|--|--|
| 1.00 mm ² (AWG 17) | 240 m (720 ft) | | |
| 1.50 mm ² (AWG 15) | 300 m (900 ft) | | |

Optionally available connecting cable

| Design | $2\times2\times0.34$ mm² (AWG 22) PVC cable $^{1)}$ with common shield (2 pairs, uninsulated stranded CU wires; pair-stranded) | | |
|-------------------------------------|--|--|--|
| Flame resistance | According to DIN EN 60332-1-2 | | |
| Oil resistance | According to DIN EN 60811-2-1 | | |
| Shield | Tin-plated copper braid, optical cover \geq 85 % | | |
| Continuous operating temperature | When mounted in a fixed position: –50 to +105 $^\circ$ C (–58 to +221 $^\circ$ F); when cable can move freely: –25 to +105 $^\circ$ C (–13 to +221 $^\circ$ F) | | |
| Available cable length | Fixed: 20 m (60 ft); variable: up to maximum 50 m (150 ft) | | |

1) UV radiation can impair the cable outer sheath. Protect the cable from direct sunshine where possible.

B: Connecting cable between sensor and transmitter: Proline 500 - digital

Standard cable

A standard cable with the following specifications can be used as the connecting cable.

| Design | 4, 6, 8 cores (2, 3, 4 pairs); uninsulated stranded CU wires; pair-stranded with common shield |
|--------------------------------------|--|
| Shielding | Tin-plated copper braid, optical cover \geq 85 % |
| Capacitance C | Maximum 760 nF IIC, maximum 4.2 μF IIB |
| Inductance L | Maximum 26 µH IIC, maximum 104 µH IIB |
| Inductance/resistance ratio (L/R) | Maximum 8.9 $\mu H/\Omega$ IIC, maximum 35.6 $\mu H/\Omega$ IIB (e.g. according to IEC 60079-25) |
| Loop resistance | Power supply line (+, –): maximum 5 Ω |
| Cable length | Maximum 150 m (450 ft), see the following table. |

| Cross-section | Cable length [max.] | Termination |
|--|---------------------|--|
| 2 x 2 x 0.50 mm ² (AWG 20) | 50 m (150 ft) | 2 x 2 x 0.50 mm ² (AWG 20) BN WT YE GN GY |
| | | +, - = 0.5 mm² A, B = 0.5 mm² |
| 3 x 2 x 0.50 mm ² (AWG 20) | 100 m (300 ft) | 3 x 2 x 0.50 mm ² (AWG 20) |
| | | BN WT GY PK YE GN + - A GY + - = 1.0 mm ² A, B = 0.5 mm2 |
| 4 x 2 x 0.50 mm ² | 150 m (450 ft) | 4 x 2 x 0.50 mm ² (AWG 20) |
| (AWG 20) | | BN WT GY PK RD BU + - - - - A B - - - - - - - - - - - - - - |
| | | +, -= 1.5 mm² A, B = 0.5 mm² |

Optionally available connecting cable

| Connecting cable for | Zone 1; Class I, Division 1 |
|------------------------|--|
| Standard cable | $2\times2\times0.5~mm^2$ (AWG 20) PVC cable $^{1)}$ with common shield (2 pairs, pair-stranded) |
| Flame resistance | According to DIN EN 60332-1-2 |
| Oil-resistance | According to DIN EN 60811-2-1 |
| Shielding | Tin-plated copper braid, optical cover \geq 85 % |
| Operating temperature | When mounted in a fixed position: –50 to +105 $^\circ$ C (–58 to +221 $^\circ$ F); when cable can move freely: –25 to +105 $^\circ$ C (–13 to +221 $^\circ$ F) |
| Available cable length | Fixed: 20 m (60 ft); variable: up to maximum 50 m (150 ft) |

1) UV radiation can impair the cable outer sheath. Protect the cable from direct sunshine where possible.

C: Connecting cable between sensor and transmitter: Proline 500

| Design | $6\times0.38\ mm^2$ PVC cable $^{1)}$ with individual shielded cores and common copper shield |
|-------------------------------------|---|
| Conductor resistance | ≤ 50 Ω/km (0.015 Ω/ft) |
| Capacitance: core/shield | ≤ 420 pF/m (128 pF/ft) |
| Cable length (max.) | 20 m (60 ft) |
| Cable lengths (available for order) | 5 m (15 ft), 10 m (30 ft), 20 m (60 ft) |
| Cable diameter | 11 mm (0.43 in) ± 0.5 mm (0.02 in) |
| Continuous operating temperature | Max. 105 °C (221 °F) |

1) UV radiation can impair the cable outer sheath. Protect the cable from direct sunshine where possible.

7.2.3 **Terminal assignment**

Transmitter: supply voltage, input/outputs

The terminal assignment of the inputs and outputs depends on the individual order version of the device. The device-specific terminal assignment is documented on an adhesive label in the terminal cover.

| Supply | voltage | Input/output 1 | | Input/output 2 | | Input/output 3 | | Input/output 4 | |
|--------|---------|--|--------|-------------------|--------|-------------------|--------|-------------------|--------|
| 1 (+) | 2 (-) | 26 (B) | 27 (A) | 24 (+) | 25 (-) | 22 (+) | 23 (-) | 20 (+) | 21 (-) |
| | | Device-specific terminal assignment: adhesive label in terminal cover. | | | | | | | |

Transmitter and sensor connection housing: connecting cable

The sensor and transmitter, which are mounted in separate locations, are interconnected by a connecting cable. The cable is connected via the sensor connection housing and the transmitter housing.

Terminal assignment and connection of the connecting cable:

- Proline 500 digital $\rightarrow \triangleq 44$
- Proline $500 \rightarrow \textcircled{2}51$

7.2.4 Available device plugs



P Device plugs may not be used in hazardous areas!

Order code for "Input; output 1", option GA "PROFIBUS PA"

| Order code for | Cable entry/connection | | | |
|-------------------------|------------------------|---|--|--|
| "Electrical connection" | 2 3 | | | |
| L, N, P, U | Connector M12 × 1 | - | | |

7.2.5 device plug pin assignment

| Pin | | Assignment | Coding | Plug/socket |
|-----|---|---------------|--------|-------------|
| 1 | + | PROFIBUS PA + | А | Plug |
| 2 | | Grounding | | |
| 3 | - | PROFIBUS PA - | | |
| 4 | | Not assigned | | |

7.2.6 Shielding and grounding

Optimal electromagnetic compatibility (EMC) of the fieldbus system can be guaranteed only if the system components and, in particular, the lines are shielded and the shield forms as complete a cover as possible. A shield coverage of 90 % is ideal.

- **1.** To ensure optimal EMC protection, connect the shield to the reference ground as often as possible.
- **2.** For reasons concerning explosion protection, it is recommended that grounding be dispensed with.

To comply with both requirements, there are basically three different types of shielding in the fieldbus system:

- Shielding at both ends
- Shielding at one end on the feed side with capacitance termination at the field device
- Shielding at one end on the feed side

Experience shows that the best results with regard to EMC are achieved in most cases in installations with one-sided shielding on the feed side (without capacitance termination at the field device). Appropriate measures with regard to input wiring must be taken to allow unrestricted operation when EMC interference is present. These measures have been taken into account for this device. Operation in the event of disturbance variables as per NAMUR NE21 is thus guaranteed.

- 1. Observe national installation requirements and guidelines during installation.
- 2. Where there are large differences in potential between the individual grounding points,

connect only one point of the shielding directly to the reference ground.

3. In systems without potential equalization,

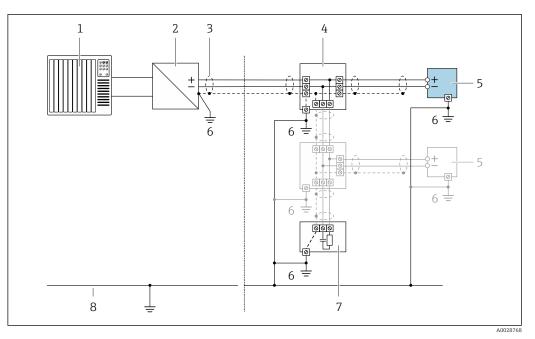
the cable shielding of fieldbus systems should be grounded on one side only, for example at the fieldbus supply unit or at safety barriers.

NOTICE

In systems without potential matching, the multiple grounding of the cable shield causes mains frequency equalizing currents!

Damage to the bus cable shield.

- Only ground the bus cable shield to either the local ground or the protective ground at one end.
- ► Insulate the shield that is not connected.



- 15 Connection example for PROFIBUS PA
- 1 Control system (e.g. PLC)
- 2 PROFIBUS PA segment coupler
- 3 Cable shield: the cable shield must be grounded at both ends to comply with EMC requirements; observe cable specifications
- 4 T-box
- 5 Measuring device
- 6 Local grounding
- 7 Bus terminator
- 8 Potential equalization conductor

7.2.7 Preparing the measuring device

Carry out the steps in the following order:

- 1. Mount the sensor and transmitter.
- 2. Sensor connection housing: Connect connecting cable.
- 3. Transmitter: Connect connecting cable.
- 4. Transmitter: Connect signal cable and cable for supply voltage.

NOTICE

Insufficient sealing of the housing!

Operational reliability of the measuring device could be compromised.

- Use suitable cable glands corresponding to the degree of protection.
- 1. Remove dummy plug if present.
- 2. If the measuring device is supplied without cable glands: Provide suitable cable gland for corresponding connecting cable.
- If the measuring device is supplied with cable glands:
 Observe requirements for connecting cables →
 ⁽²⁾ 36.

7.3 Connecting the measuring instrument: Proline 500 - digital

NOTICE

An incorrect connection compromises electrical safety!

- Only properly trained specialist staff may perform electrical connection work.
- Observe applicable federal/national installation codes and regulations.
- Comply with local workplace safety regulations.
- ► Always connect the protective ground cable ⊕ before connecting additional cables.
- ► When using in potentially explosive atmospheres, observe the information in the device-specific Ex documentation.

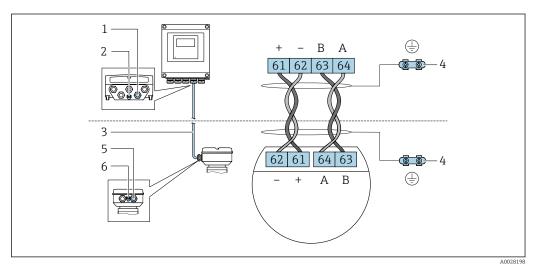
7.3.1 Connecting the connecting cable

WARNING

Risk of damaging electronic components!

- Connect the sensor and transmitter to the same potential equalization.
- Only connect the sensor to a transmitter with the same serial number.

Connecting cable terminal assignment



- 1 Cable entry for cable on transmitter housing
- 2 Protective earth (PE)
- 3 Connecting cable ISEM communication
- 4 Grounding via ground connection; in the version with a device plug, grounding is ensured through the plug itself
- 5 Cable entry for cable or connection of device plug on sensor connection housing
- 6 Protective earth (PE)

Connecting the connecting cable to the sensor connection housing

- Connection via terminals with order code for "Sensor connection housing":
 - Option **A** "Aluminum, coated" $\rightarrow \cong 45$
 - Option **B** "Stainless" $\rightarrow \square 46$
 - Option **L** "Cast, stainless" $\rightarrow \square 45$
- Connection via connectors with order code for "Sensor connection housing": Option C "Ultra-compact hygienic, stainless" $\rightarrow \cong 47$

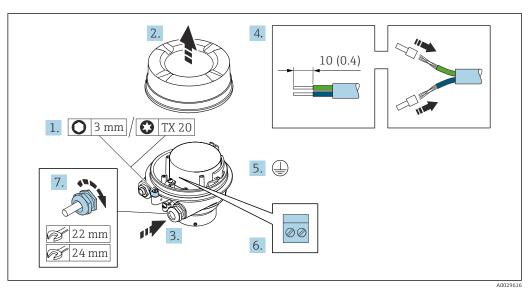
Connecting the connecting cable to the transmitter

The cable is connected to the transmitter via terminals $\rightarrow \implies 48$.

Connecting the sensor connection housing via terminals

For the device version with the order code for "Sensor connection housing":

- Option A "Aluminum coated"
- Option L "Cast, stainless"



- 1. Loosen the securing clamp of the housing cover.
- 2. Unscrew the housing cover.
- **3.** Push the cable through the cable entry. To ensure tight sealing, do not remove the sealing ring from the cable entry.
- 4. Strip the cable and cable ends. In the case of stranded cables, fit ferrules.
- 5. Connect the protective ground.
- 6. Connect the cable in accordance with the connecting cable terminal assignment.
- 7. Firmly tighten the cable glands.
 - └ This concludes the process for connecting the connecting cable.

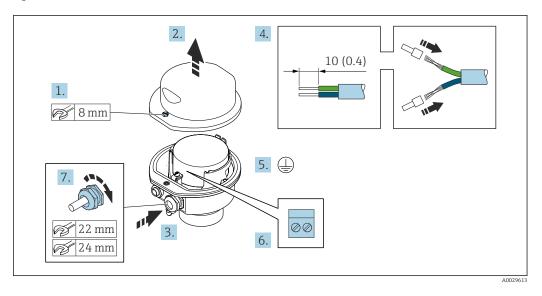
WARNING

Housing degree of protection voided due to insufficient sealing of the housing.

- Screw in the thread on the cover without using any lubricant. The thread on the cover is coated with a dry lubricant.
- 8. Screw on the housing cover.
- 9. Tighten the securing clamp of the housing cover.

Connecting the sensor connection housing via terminals

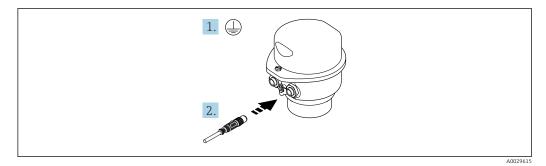
For the device version with the order code for "Sensor connection housing": Option **B** "Stainless"

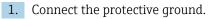


- 1. Release the securing screw of the housing cover.
- 2. Open the housing cover.
- **3.** Push the cable through the cable entry . To ensure tight sealing, do not remove the sealing ring from the cable entry.
- 4. Strip the cable and cable ends. In the case of stranded cables, fit ferrules.
- 5. Connect the protective ground.
- 6. Connect the cable in accordance with the connecting cable terminal assignment.
- 7. Firmly tighten the cable glands.
 - └ This concludes the process for connecting the connecting cable.
- 8. Close the housing cover.
- 9. Tighten the securing screw of the housing cover.

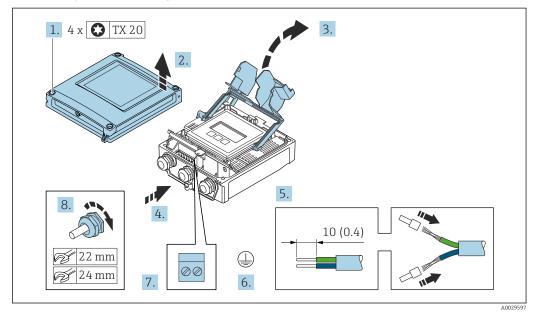
Connecting the sensor connection housing via the connector

For the device version with the order code for "Sensor connection housing": Option **C** "Ultra-compact hygienic, stainless"





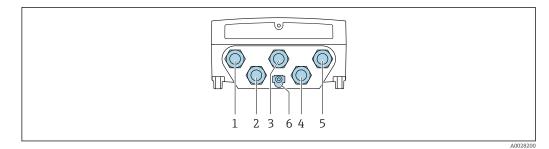
2. Connect the connector.



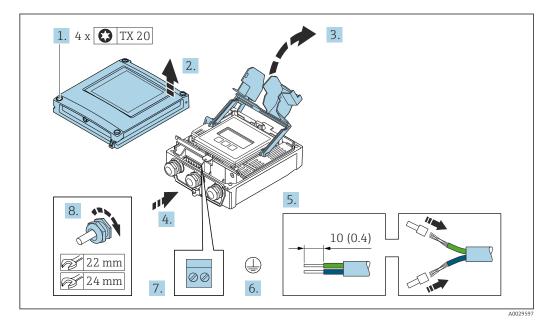
Connecting the connecting cable to the transmitter

- 1. Loosen the 4 fixing screws on the housing cover.
- 2. Open the housing cover.
- 3. Fold open the terminal cover.
- 4. Push the cable through the cable entry. To ensure tight sealing, do not remove the sealing ring from the cable entry.
- 5. Strip the cable and cable ends. In the case of stranded cables, fit ferrules.
- 6. Connect the protective ground.
- **7.** Connect the cable according to the terminal assignment for the connecting cable $\rightarrow \cong 44$.
- 8. Firmly tighten the cable glands.
 - └ The process for connecting the connecting cable is now complete.
- 9. Close the housing cover.
- **10.** Tighten the securing screw of the housing cover.

7.3.2 Connecting the signal cable and the supply voltage cable



- 1 Terminal connection for supply voltage
- 2 Terminal connection for signal transmission, input/output
- 3 Terminal connection for signal transmission, input/output
- 4 Terminal connection for connecting cable between sensor and transmitter
- 5 Terminal connection for signal transmission, input/output; optional: connection for external WLAN antenna
- 6 Protective earth (PE)



- 1. Loosen the 4 fixing screws on the housing cover.
- 2. Open the housing cover.
- 3. Fold open the terminal cover.
- 4. Push the cable through the cable entry. To ensure tight sealing, do not remove the sealing ring from the cable entry.
- 5. Strip the cable and cable ends. In the case of stranded cables, fit ferrules.
- 6. Connect the protective ground.
- 7. Connect the cable according to the terminal assignment.
 - Signal cable terminal assignment: The device-specific terminal assignment is documented on an adhesive label in the terminal cover.
 Supply voltage terminal assignment: Adhesive label in the terminal cover or →
 ⇒ 41.
- 8. Firmly tighten the cable glands.
 - └ This concludes the cable connection process.
- 9. Close the terminal cover.
- **10.** Close the housing cover.

WARNING

Housing degree of protection may be voided due to insufficient sealing of the housing.

• Screw in the screw without using any lubricant.

NOTICE

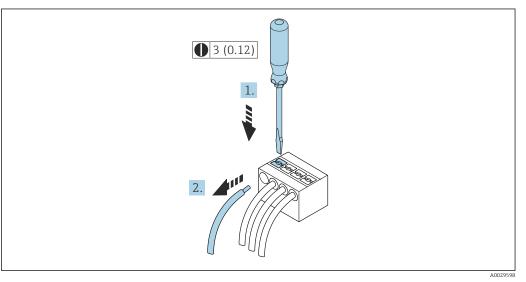
Excessive tightening torque applied to the fixing screws!

Risk of damaging the plastic transmitter.

- Tighten the fixing screws as per the tightening torque: 2.5 Nm (1.8 lbf ft)
- **11.** Tighten the 4 fixing screws on the housing cover.

Removing a cable

To remove a cable from the terminal:



🖻 16 Engineering unit mm (in)

1. Use a flat-blade screwdriver to press down on the slot between the two terminal holes.

2. Remove the cable end from the terminal.

7.4 Connecting the measuring instrument: Proline 500

NOTICE

An incorrect connection compromises electrical safety!

- Only properly trained specialist staff may perform electrical connection work.
- Observe applicable federal/national installation codes and regulations.
- Comply with local workplace safety regulations.
- ► Always connect the protective ground cable ⊕ before connecting additional cables.
- When using in potentially explosive atmospheres, observe the information in the device-specific Ex documentation.

7.4.1 Fitting the connecting cable

WARNING

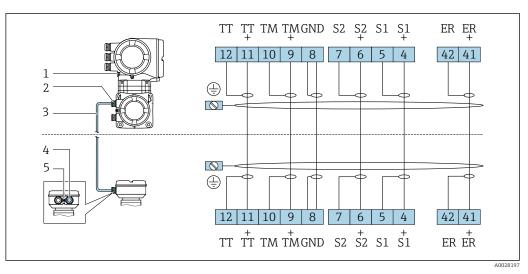
Risk of damaging electronic components!

- Connect the sensor and transmitter to the same potential equalization.
- Only connect the sensor to a transmitter with the same serial number.

Measurement error due to shortening of the connecting cable

The connecting cable is ready for installation and must be used in the length supplied. Shortening the connecting cable can affect the sensor's measurement accuracy.

Connecting cable terminal assignment



- 1 Protective earth (PE)
- 2 Cable entry for connecting cable on transmitter connection housing
- 3 Connecting cable
- 4 Cable entry for connecting cable on sensor connection housing
- 5 Protective earth (PE)

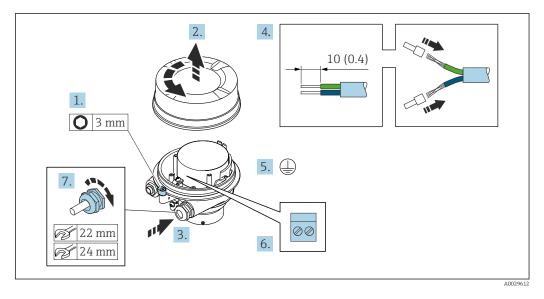
Connecting the connecting cable to the sensor connection housing

Connection via terminals with order code for "Housing":

- Option **A** "Aluminum coated" $\rightarrow \square 52$
- Option **B** "Stainless" \rightarrow 🗎 53

Connecting the sensor connection housing via terminals

For the device version with the order code for "Housing": Option **A** "Aluminum coated"



- 1. Loosen the securing clamp of the housing cover.
- 2. Unscrew the housing cover.
- **3.** Push the cable through the cable entry . To ensure tight sealing, do not remove the sealing ring from the cable entry.
- 4. Strip the cable and cable ends. In the case of stranded cables, fit ferrules.
- 5. Connect the protective ground.
- 6. Connect the cable in accordance with the connecting cable terminal assignment.
- 7. Firmly tighten the cable glands.
 - └ The process for connecting the connecting cable is now complete.

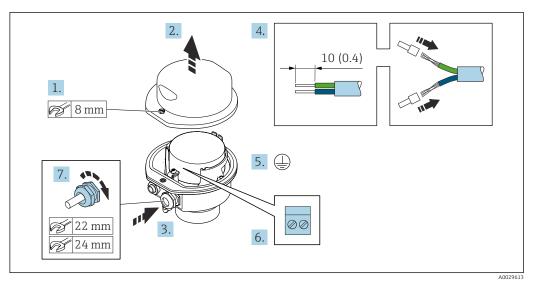
WARNING

Housing degree of protection voided due to insufficient sealing of the housing.

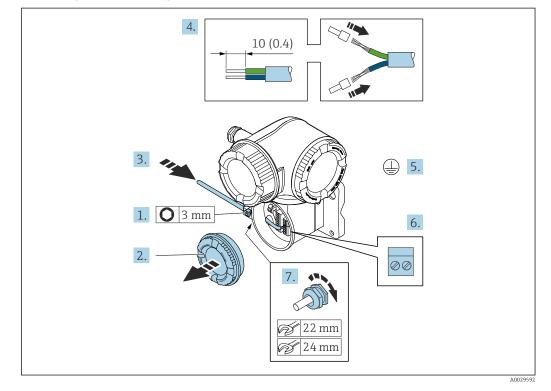
- Screw in the thread on the cover without using any lubricant. The thread on the cover is coated with a dry lubricant.
- 8. Screw on the housing cover.
- **9.** Tighten the securing clamp of the housing cover.

Connecting the sensor connection housing via terminals

For the device version with the order code for "Housing": Option **B** "Stainless"



- 1. Release the securing screw of the housing cover.
- 2. Open the housing cover.
- **3.** Push the cable through the cable entry . To ensure tight sealing, do not remove the sealing ring from the cable entry.
- 4. Strip the cable and cable ends. In the case of stranded cables, fit ferrules.
- 5. Connect the protective ground.
- 6. Connect the cable in accordance with the connecting cable terminal assignment.
- 7. Firmly tighten the cable glands.
 - └ This concludes the process for connecting the connecting cable.
- 8. Close the housing cover.
- 9. Tighten the securing screw of the housing cover.

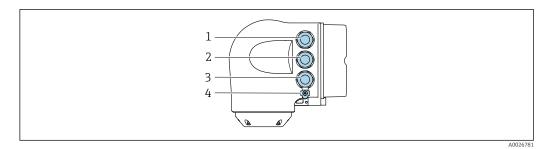


Attaching the connecting cable to the transmitter

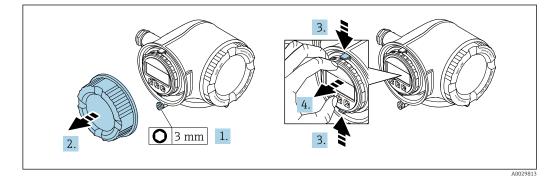
- **1.** Loosen the securing clamp of the connection compartment cover.
- 2. Unscrew the connection compartment cover.
- **3.** Push the cable through the cable entry. To ensure tight sealing, do not remove the sealing ring from the cable entry.
- 4. Strip the cable and cable ends. In the case of stranded cables, also fit ferrules.
- 5. Connect the protective ground.
- 6. Connect the cable in accordance with the connecting cable terminal assignment $\rightarrow \cong 51$.
- 7. Firmly tighten the cable glands.
 - └ This concludes the process for attaching the connecting cable.
- 8. Screw on the connection compartment cover.
- 9. Tighten the securing clamp of the connection compartment cover.
- **10**. After connecting the connecting cable:

Connect the signal cable and the supply voltage cable $\rightarrow \oplus 55$.

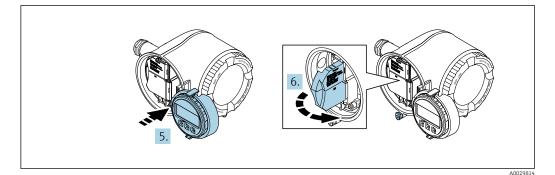
7.4.2 Connecting the signal cable and the supply voltage cable



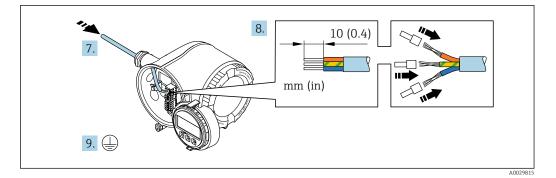
- 1 Terminal connection for supply voltage
- 2 Terminal connection for signal transmission, input/output
- 3 Terminal connection for signal transmission, input/output or terminal connection for network connection via service interface (CDI-RJ45)
- 4 Protective earth (PE)



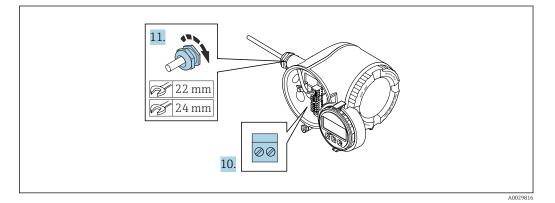
- 1. Loosen the securing clamp of the connection compartment cover.
- 2. Unscrew the connection compartment cover.
- 3. Squeeze the tabs of the display module holder together.
- 4. Remove the display module holder.



- 5. Attach the holder to the edge of the electronics compartment.
- 6. Open the terminal cover.



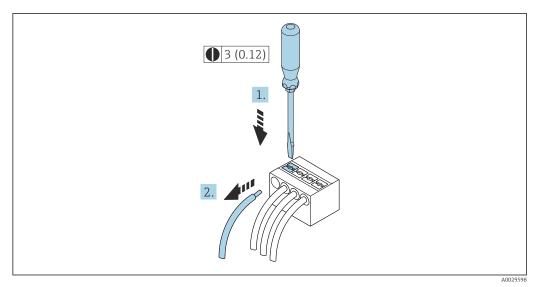
- 7. Push the cable through the cable entry. To ensure tight sealing, do not remove the sealing ring from the cable entry.
- 8. Strip the cable and cable ends. In the case of stranded cables, also fit ferrules.
- 9. Connect the protective ground.



- **10.** Connect the cable according to the terminal assignment.
- **11.** Firmly tighten the cable glands.
 - \blacktriangleright This concludes the cable connection process.
- 12. Close the terminal cover.
- **13.** Fit the display module holder in the electronics compartment.
- **14.** Screw on the connection compartment cover.
- **15.** Secure the securing clamp of the connection compartment cover.

Removing a cable

To remove a cable from the terminal:



🖻 17 Engineering unit mm (in)

- **1.** Use a flat-blade screwdriver to press down on the slot between the two terminal holes.
- 2. Remove the cable end from the terminal.

7.5 Potential equalization

7.5.1 Requirements

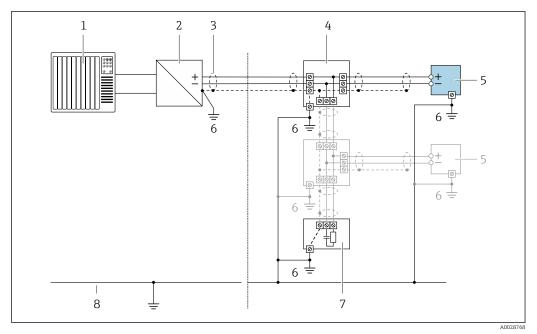
For potential equalization:

- Pay attention to in-house grounding concepts
- Take account of operating conditions, such as the pipe material and grounding
- Connect the medium, sensor and transmitter to the same electric potential
- Use a ground cable with a minimum cross-section of 6 mm² (10 AWG) and a cable lug for potential equalization connections

7.6 Special connection instructions

7.6.1 Connection examples

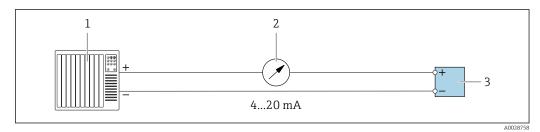
PROFIBUS PA



■ 18 Connection example for PROFIBUS PA

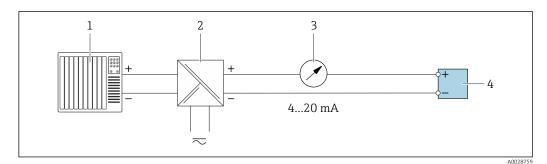
- 1 Control system (e.g. PLC)
- 2 PROFIBUS PA segment coupler
- 3 Cable shield provided at one end. The cable shield must be grounded at both ends to comply with EMC requirements; observe cable specifications
- 4 T-box
- 5 Measuring device
- 6 Local grounding
- 7 Bus terminator
- 8 Potential matching line

Current output 4-20 mA



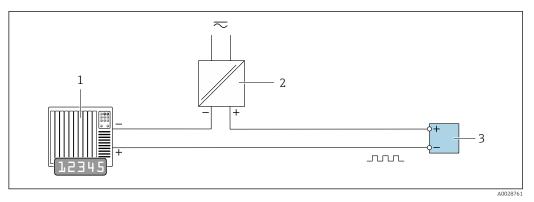
☑ 19 Connection example for 4-20 mA current output (active)

- 1 Automation system with current input (e.g. PLC)
- 2 Analog display unit: observe maximum load
- 3 Transmitter



- ☑ 20 Connection example for 4-20 mA current output (passive)
- *1 Automation system with current input (e.g. PLC)*
- 2 Active barrier for power supply (e.g. RN221N)
- 3 Analog display unit: observe maximum load
- 4 Transmitter

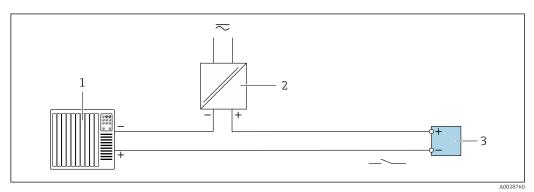
Pulse/frequency output



21 Connection example for pulse/frequency output (passive)

- 1 Automation system with pulse/frequency input (e.g. PLC with 10 k Ω pull-up or pull-down resistor)
- 2 Power supply
- 3 Transmitter: observe input values $\rightarrow \cong 254$

Switch output



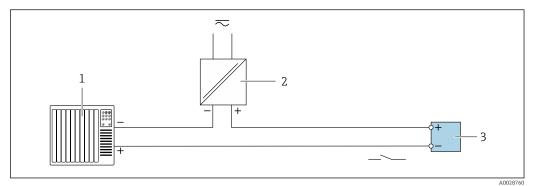
■ 22 Connection example for switch output (passive)

- Automation system with switch input (e.g. PLC with a 10 k Ω pull-up or pull-down resistor)
- 2 Power supply

1

3 Transmitter: observe input values $\rightarrow \cong 254$

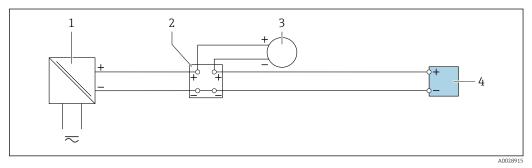
Relay output



■ 23 Connection example for relay output (passive)

- 1 Automation system with relay input (e.g. PLC)
- 2 Power supply
- 3 Transmitter: observe input values $\rightarrow \cong 255$

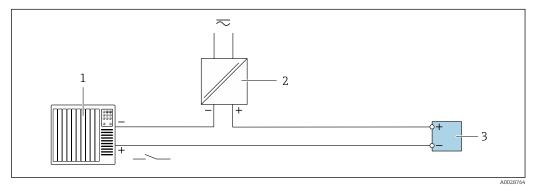
Current input



■ 24 Connection example for 4 to 20 mA current input

- 1 Power supply
- 2 Terminal box
- 3 External measuring device (to read in pressure or temperature, for instance)
- 4 Transmitter

Status input



■ 25 Connection example for status input

- 1 Automation system with status output (e.g. PLC)
- 2 Power supply
- 3 Transmitter

7.7 Hardware settings

7.7.1 Setting the device address

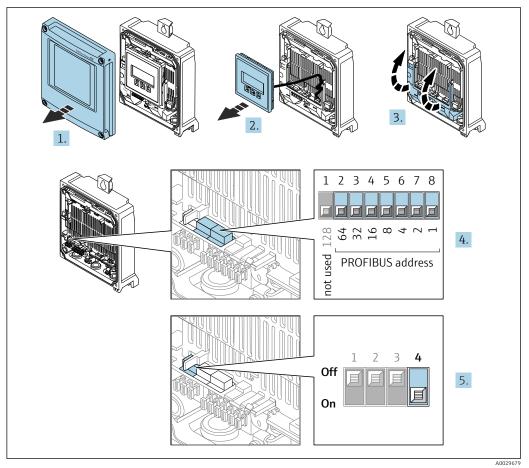
The address must always be configured for a PROFIBUS DP/PA device. The valid address range is between 1 and 126. In a PROFIBUS DP/PA network, each address can only be assigned once. If an address is not configured correctly, the device is not recognized by the master. All measuring devices are delivered from the factory with the device address 126 and with the software addressing method.

Risk of electric shock when opening the transmitter housing.

- Before opening the transmitter housing:
- Disconnect the device from the power supply.

Proline 500 – digital transmitter

Hardware addressing



1. Open the housing cover.

2. Remove the display module.

3. Fold open the terminal cover.

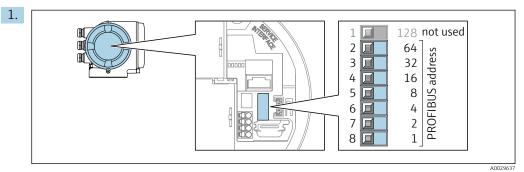
- 4. Set the desired device address using the DIP switches.
- **5.** To switch addressing from software addressing to hardware addressing: set the DIP switch to **On**.
 - └ The change of device address takes effect after 10 seconds. The device is restarted.

Software addressing

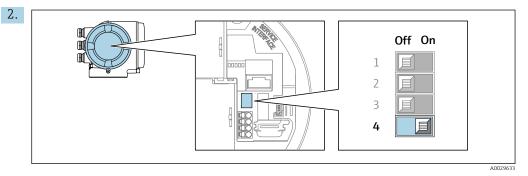
- To switch addressing from hardware addressing to software addressing: set DIP switch No. 4 to **Off**.
 - → The device address set in the **Device address** parameter ($\rightarrow \equiv 113$) takes effect after 10 seconds. The device is restarted.

Proline 500 transmitter

Hardware addressing



Set the desired device address using the DIP switches in the connection compartment.



To switch addressing from software addressing to hardware addressing: set the DIP switch to **On**.

└ The change of device address takes effect after 10 seconds. The device is restarted.

Software addressing

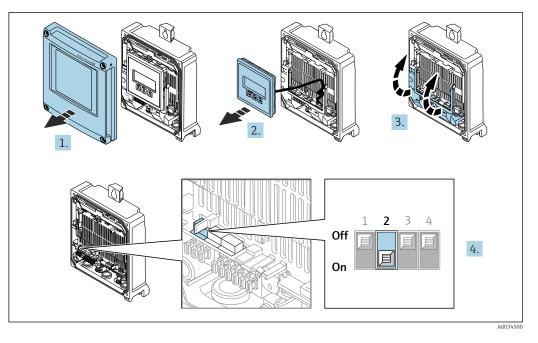
- ► To switch addressing from hardware addressing to software addressing: set DIP switch No. 4 to **Off**.
 - → The device address configured in the **Device address** parameter ($\rightarrow \cong 113$) takes effect after 10 seconds. The device is restarted.

7.7.2 Activating the default IP address

Activating the default IP address by DIP switch: Proline 500 - digital

Risk of electric shock when opening the transmitter housing.

- Before opening the transmitter housing:
- Disconnect the device from the power supply.

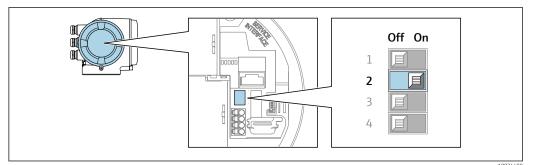


- 1. Loosen the 4 fixing screws on the housing cover.
- 2. Open the housing cover.
- 3. Fold open the terminal cover.
- 4. Set DIP switch no. 2 on the I/O electronics module from $OFF \rightarrow ON$.
- 5. Reassemble the transmitter in the reverse order.
- 6. Reconnect the device to the power supply.
 - └ The default IP address is used once the device is restarted.

Activating the default IP address by DIP switch: Proline 500

Risk of electric shock when opening the transmitter housing.

- Before opening the transmitter housing:
- ► Disconnect the device from the power supply.



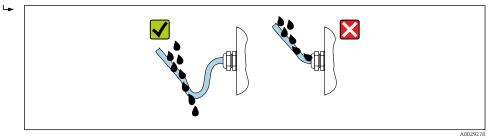
- **1.** Depending on the housing version, loosen the securing clamp or fixing screw of the housing cover.
- 2. Depending on the housing version, unscrew or open the housing cover and disconnect the local display from the main electronics module where necessary .
- **3.** Set DIP switch no. 2 on the I/O electronics module from **OFF** \rightarrow **ON**.
- 4. Reassemble the transmitter in the reverse order.
- 5. Reconnect the device to the power supply.
 - ← The default IP address is used once the device is restarted.

7.8 Ensuring the degree of protection

The measuring instrument fulfills all the requirements for the degree of protection IP66/67, Type 4X enclosure.

To guarantee the degree of protection IP66/67, Type 4X enclosure, carry out the following steps after the electrical connection:

- 1. Check that the housing seals are clean and fitted correctly.
- 2. Dry, clean or replace the seals if necessary.
- **3.** Tighten all housing screws and screw covers.
- 4. Firmly tighten the cable glands.
- 5. To ensure that moisture does not enter the cable entry: Route the cable so that it loops down before the cable entry ("water trap").



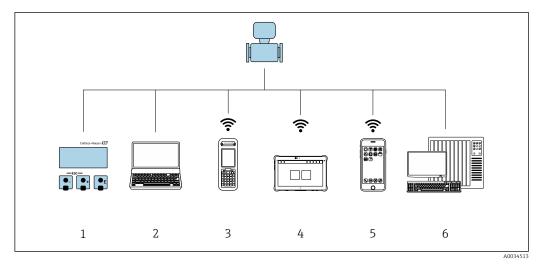
6. The cable glands supplied do not ensure housing protection when not in use. They must therefore be replaced by dummy plugs corresponding to the housing protection.

7.9 Post-connection check

| Are the device and cable undamaged (visual inspection)? | | |
|---|--|--|
| Is the protective earthing established correctly? | | |
| Do the cables used comply with the requirements ? | | |
| Are the installed cables strain-relieved and securely routed? | | |
| Are all cable glands installed, securely tightened and leak-tight? Cable run with "water trap" $\rightarrow \square 64$? | | |
| Is the terminal assignment correct ? | | |
| Are dummy plugs inserted in unused cable entries and have transportation plugs been replaced with dummy plugs? | | |

8 Operation options

8.1 Overview of operation options

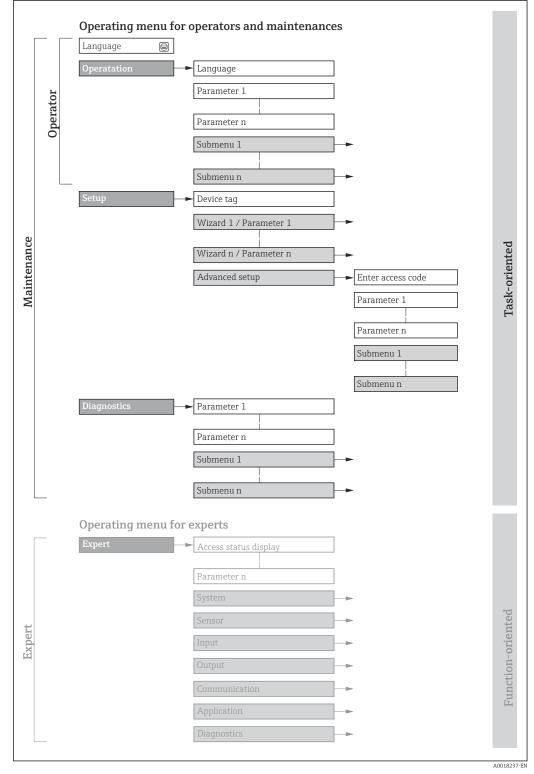


- 1 Local operation via display module
- 2 Computer with web browser or operating tool (e.g. FieldCare, DeviceCare, AMS Device Manager, SIMATIC PDM)
- 3 Field Xpert SFX350 or SFX370
- 4 Field Xpert SMT70
- 5 Mobile handheld terminal
- 6 Automation system (e.g. PLC)

8.2 Structure and function of the operating menu

8.2.1 Structure of the operating menu

For an overview of the operating menu for experts: see the "Description of Device Parameters" document supplied with the device $\rightarrow \cong 279$



Schematic structure of the operating menu

8.2.2 Operating philosophy

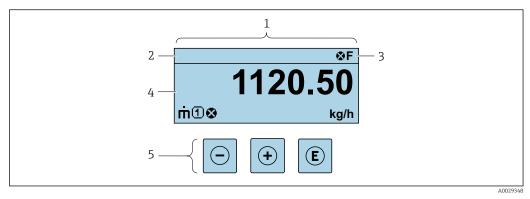
The individual parts of the operating menu are assigned to certain user roles (e.g. operator, maintenance etc.). Each user role contains typical tasks within the device life cycle.

| Menu/pa | arameter | User role and tasks | Content/meaning | |
|-------------|-------------------|---|---|--|
| Language | Task- oriented | Role "Operator", "Maintenance" Tasks during operation: • Configuration of the operational | Defining the operating language Defining the Web server operating language Resetting and controlling totalizers | |
| Operation | | display • Reading measured values | Configuration of the operational display (e.g. display format, display contrast) Resetting and controlling totalizers | |
| Setup | | "Maintenance" role Commissioning: Configuration of the measurement Configuration of the inputs and outputs Configuration of the communication interface | Wizards for fast commissioning: Configuring the system units Configuration of the communication interface Definition of the medium Displaying the I/O configuration Configuring the inputs Configuring the outputs Configuration of the operational display Configuring the low flow cut off Configuring partial and empty pipe detection | |
| | | | Advanced setup For more customized configuration of the measurement (adaptation to special measuring conditions) Configuration of totalizers Configuration of WLAN settings Administration (define access code, reset measuring device) | |
| Diagnostics | | "Maintenance" role Troubleshooting: Diagnostics and elimination of process and device errors Measured value simulation | Contains all parameters for error detection and analyzing process and device errors: Diagnostic list Contains up to 5 currently pending diagnostic messages. Event logbook Contains event messages that have occurred. Device information Contains information for identifying the device Measured values Contains all current measured values. Analog inputs Is used to display the analog input. Data logging submenu with the "Extended HistoROM" order option Storage and visualization of measured values Heartbeat Technology Verification of device functionality on request and documentation of verification results Simulation Used to simulate measured values or output values. | |

| Menu/parameter | | User role and tasks | Content/meaning |
|----------------|----------------------|---|--|
| = | unction- priented | Tasks that require detailed knowledge of the function of the device: Commissioning measurements under difficult conditions Optimal adaptation of the measurement to difficult conditions Detailed configuration of the communication interface Error diagnostics in difficult cases | Contains all of the device parameters and allows direct access to these by means of an access code. The structure of this menu is based on the function blocks of the device: System Contains all higher-level device parameters that do not affect measurement or measured value communication Sensor Configuration of the measurement. Output Configuration of the pulse/frequency/switch output Input Configuration of the status input Output Configuration of the analog current outputs as well as the pulse/frequency and switch output Communication Configuration of the digital communication interface and the Web server Submenus for function blocks (e.g. "Analog Inputs") Configuration of the functions that go beyond the actual measurement (e.g. totalizer) Diagnostics Error detection and analysis of process and device errors and for device simulation and Heartbeat Technology. |

8.3 Access to operating menu via local display

8.3.1 Operational display



1 Operational display

2 Device tag

3 Status area

4 Display range for measured values (up to 4 lines)

5 Operating elements $\rightarrow \square 75$

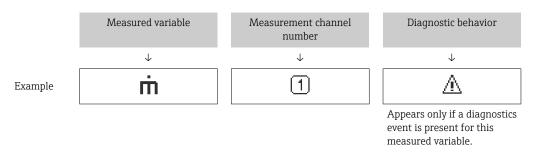
Status area

The following symbols appear in the status area of the operational display at the top right:

- Status signals → 🗎 177
 - **F**: Failure
 - **C**: Function check
 - S: Out of specification
- M: Maintenance required
- Diagnostic behavior $\rightarrow \cong 178$
 - 🛛 🐼: Alarm
- 🕂: Warning
- 🛱: Locking (the device is locked via the hardware)
- •: Communication (communication via remote operation is active)

Display area

In the display area, each measured value is prefaced by certain symbol types for further description:



Measured variables

| Symbol | Meaning |
|--------|---|
| m | Mass flow |
| Ü | Volume flowCorrected volume flow |
| ρ | DensityReference density |
| 4 | Temperature |

The number and display format of the measured variables can be configured via the **Format display** parameter ($\Rightarrow \cong 131$).

Totalizer

| Symb | ol | Meaning | |
|------|----|--|--|
| | Σ | Totalizer The measurement channel number indicates which of the three totalizers is displayed. | |

Input

| Symbol | Meaning |
|--------|--------------|
| Ð | Status input |

Measurement channel numbers

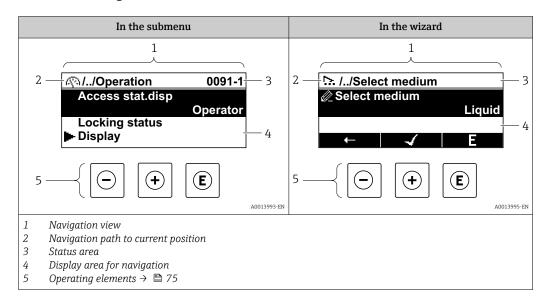
| Symbol | Meaning | |
|--------|--|--|
| 14 | Measurement channel 1 to 4 The measurement channel number is displayed only if more than one channel is present for the same measured variable type (e.g. totalizer 1 to 3). | |

Diagnostic behavior

| Symbol | Meaning | |
|--------|---|--|
| 8 | Alarm Measurement is interrupted. Signal outputs and totalizers assume the defined alarm condition. A diagnostic message is generated. | |
| Δ | Warning Measurement is resumed. The signal outputs and totalizers are not affected. A diagnostic message is generated. | |

The diagnostic behavior pertains to a diagnostic event that is relevant to the displayed measured variable.

8.3.2 Navigation view



Navigation path

The navigation path to the current position is displayed at the top left in the navigation view and consists of the following elements:

- The display symbol for the menu/submenu (►) or the wizard (\.).
- An omission symbol (/ ../) for operating menu levels in between.
- Name of the current submenu, wizard or parameter

| | Display symbol | Omission symbol | Parameter |
|---------|----------------|-----------------|--------------|
| | \downarrow | \checkmark | \checkmark |
| Example | ► | // | Indication |

For more information about the icons in the menu, refer to the "Display area" section $\rightarrow \cong 71$

Status area

The following appears in the status area of the navigation view in the top right corner:

- In the submenu
 - The direct access code to the parameter (e.g., 0022-1)
- If a diagnostic event is present, the diagnostic behavior and status signal In the wizard
- If a diagnostic event is present, the diagnostic behavior and status signal

For information on the diagnostic behavior and status signal → ☐ 177
 For information on the function and entry of the direct access code → ☐ 77

Display area

Menus

| Symbol | Meaning | |
|--------|---|--|
| Ŵ | Operation Is displayed: In the menu next to the "Operation" selection At the left in the navigation path in the Operation menu | |

| | ې | Setup Is displayed: In the menu next to the "Setup" selection At the left in the navigation path in the Setup menu |
|---|----------------|---|
| (| ર | Diagnosis Is displayed: In the menu next to the "Diagnostics" selection At the left in the navigation path in the Diagnostics menu |
| = | . * | Expert Is displayed: In the menu next to the "Expert" selection At the left in the navigation path in the Expert menu |

Submenus, wizards, parameters

| Symbol | Meaning |
|--------|--|
| • | Submenu |
| ₩. | Wizards |
| Ø | Parameters within a wizard Image: No display symbol exists for parameters in submenus. |

Locking procedure

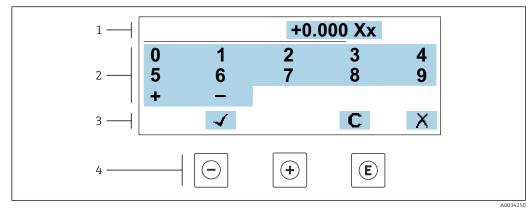
| Symbol | Meaning | |
|--------|--|--|
| Ô | Parameter lockedWhen displayed in front of a parameter name, indicates that the parameter is locked.By a user-specific access codeBy the hardware write protection switch | |

Wizards

| Symbol | Meaning |
|--------------|--|
| - | Switches to the previous parameter. |
| \checkmark | Confirms the parameter value and switches to the next parameter. |
| E | Opens the editing view of the parameter. |

8.3.3 Editing view

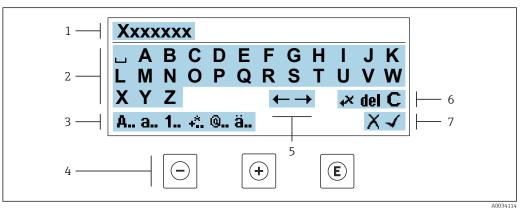
Numeric editor



E 27 For entering values in parameters (e.g. limit values)

- 1 Entry display area
- 2 Input screen
- 3 Confirm, delete or reject entry
- 4 Operating elements

Text editor



■ 28 For entering text in parameters (e.g. device tag)

- 1 Entry display area
- 2 Current input screen
- 3 Change input screen
- 4 Operating elements
- 5 Move entry position
- 6 Delete entry
- 7 Reject or confirm entry

Using the operating elements in the editing view

| Operating ke | y Meaning |
|--------------|---|
| Θ | Minus key Move the entry position to the left. |
| + | Plus key Move the entry position to the right. |

| Operati | Operating key Meaning | |
|---|-----------------------|--|
| Enter key Pressing the key briefly confirms your selection. Pressing the key for 2 s confirms your entry. | | |
| E |)+++ | Escape key combination (press keys simultaneously) Close the editing view without accepting a change. |

Input screens

| Symbol | Meaning |
|----------|---|
| A | Upper case |
| а | Lower case |
| 1 | Numbers |
| +* | Punctuation marks and special characters: = + – * / ² ³ ¹ / ₄ ¹ / ₂ ³ / ₄ () [] < > { } |
| @ | Punctuation marks and special characters: ' "`^. , ; : ? ! % µ ° € \$ £ ¥ § @ # / \ I ~ & _ |
| ä | Umlauts and accents |

Controlling data entries

| Symbol | Meaning |
|--------|---|
| ←→ | Move entry position |
| X | Reject entry |
| 4 | Confirm entry |
| × | Delete character immediately to the left of the entry position |
| del | Delete character immediately to the right of the entry position |
| С | Clear all the characters entered |

8.3.4 Operating elements

| Operating key Meaning | |
|-----------------------|---|
| | Minus key |
| | <i>In menu, submenu</i> Moves the selection bar upwards in a picklist |
| | In wizards Goes to previous parameter |
| | In the text and numeric editor Move the entry position to the left. |
| | Plus key |
| | <i>In menu, submenu</i> Moves the selection bar downwards in a picklist |
| | <i>In wizards</i> Goes to the next parameter |
| | In the text and numeric editor Move the entry position to the right. |
| | Enter key |
| | <i>In the operational display</i> Pressing the key briefly opens the operating menu. |
| E | In menu, submenu Pressing the key briefly: Opens the selected menu, submenu or parameter. Starts the wizard. If help text is open, closes the help text of the parameter. Pressing the key for 2 s in a parameter: If present, opens the help text for the function of the parameter. |
| | In wizards Opens the editing view of the parameter and confirms the parameter value |
| | In the text and numeric editorPressing the key briefly confirms your selection.Pressing the key for 2 s confirms your entry. |
| | Escape key combination (press keys simultaneously) |
| () ++ | In menu, submenu Pressing the key briefly: Exits the current menu level and takes you to the next higher level. If help text is open, closes the help text of the parameter. Pressing the key for 2 s returns you to the operational display ("home position"). |
| | <i>In wizards</i> Exits the wizard and takes you to the next higher level |
| | <i>In the text and numeric editor</i> Exits the Editing view without applying the changes. |
| | Minus/Enter key combination (press and hold down the keys simultaneously) |
| ()+E | If keypad lock is active: Pressing the key for 3 s deactivates the keypad lock. If keypad lock is not active: Pressing the key for 3 s opens the context menu including the option for activating the |
| | keypad lock. |

8.3.5 Opening the context menu

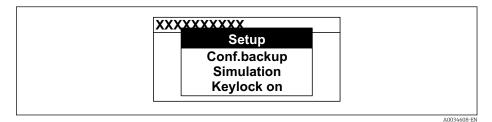
Using the context menu, the user can call up the following menus quickly and directly from the operational display:

- Setup
- Data backup
- Simulation

Calling up and closing the context menu

The user is in the operational display.

- **1.** Press the \Box and \blacksquare keys for longer than 3 seconds.
 - └ The context menu opens.



2. Press \Box + \pm simultaneously.

└ The context menu is closed and the operational display appears.

Calling up the menu via the context menu

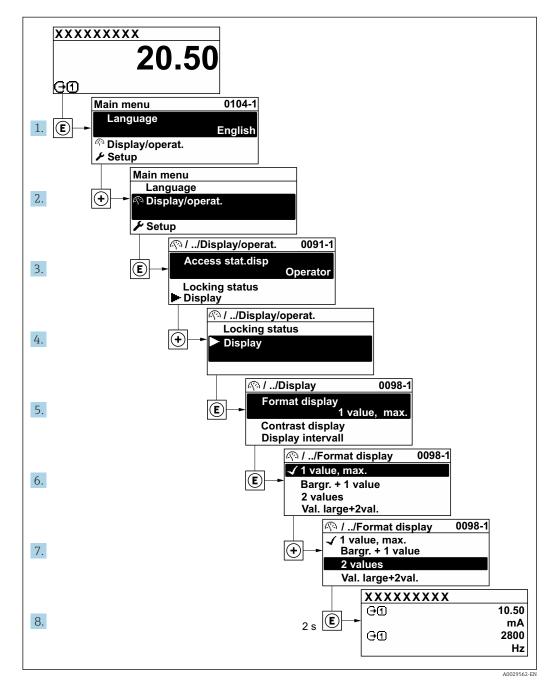
- 1. Open the context menu.
- 2. Press \pm to navigate to the desired menu.
- 3. Press 🗉 to confirm the selection.
 - └ The selected menu opens.

8.3.6 Navigating and selecting from list

Different operating elements are used to navigate through the operating menu. The navigation path is displayed on the left in the header. Icons are displayed in front of the individual menus. These icons are also shown in the header during navigation.

For an explanation of the navigation view with symbols and operating elements $\rightarrow \textcircled{B} 71$

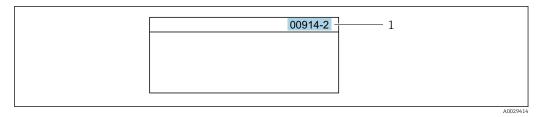
Example: Setting the number of displayed measured values to "2 values"



8.3.7 Calling the parameter directly

A parameter number is assigned to every parameter to be able to access a parameter directly via the onsite display. Entering this access code in the **Direct access** parameter calls up the desired parameter directly.

Navigation path Expert \rightarrow Direct access The direct access code consists of a 5-digit number (at maximum) and the channel number, which identifies the channel of a process variable: e.g. 00914-2. In the navigation view, this appears on the right-hand side in the header of the selected parameter.



1 Direct access code

Note the following when entering the direct access code:

- The leading zeros in the direct access code do not have to be entered. Example: Enter "914" instead of "00914"
- If no channel number is entered, channel 1 is opened automatically.
 Example: Enter 00914 → Assign process variable parameter
- If a different channel is opened: Enter the direct access code with the corresponding channel number.

Example: Enter $00914-2 \rightarrow Assign \ process \ variable$ parameter

For the direct access codes of the individual parameters, see the "Description of Device Parameters" document for the device

8.3.8 Calling up help text

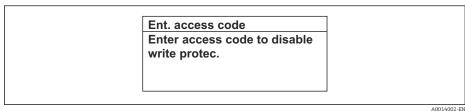
Help text is available for some parameters and can be called up from the navigation view. The help text provides a brief explanation of the parameter function and thereby supports swift and safe commissioning.

Calling up and closing the help text

The user is in the navigation view and the selection bar is on a parameter.

1. Press E for 2 s.

← The help text for the selected parameter opens.



29 Example: Help text for parameter "Enter access code"

- 2. Press \Box + \pm simultaneously.
 - └ The help text is closed.

8.3.9 Changing the parameters

Parameters can be changed via the numeric editor or text editor.

- Numeric editor: Change values in a parameter, e.g. specifications for limit values.
- Text editor: Enter text in a parameter, e.g. tag name.

A message is displayed if the value entered is outside the permitted value range.

| Ent. access code |
|-------------------------------|
| Invalid or out of range input |
| value |
| Min:0 |
| Max:9999 |

For a description of the editing view - consisting of the text editor and numeric editor - with symbols → 🗎 73, for a description of the operating elements → 🗎 75

8.3.10 User roles and related access authorization

The two user roles "Operator" and "Maintenance" have different write access to the parameters if the customer defines a user-specific access code. This protects the device configuration via the local display from unauthorized access $\rightarrow \cong 155$.

Defining access authorization for user roles

An access code is not yet defined when the device is delivered from the factory. Access authorization (read and write access) to the device is not restricted and corresponds to the "Maintenance" user role.

- ► Define the access code.
 - └ The "Operator" user role is redefined in addition to the "Maintenance" user role. Access authorization differs for the two user roles.

Access authorization to parameters: "Maintenance" user role

| Access code status | Read access | Write access |
|--|-------------|-----------------|
| An access code has not yet been defined (factory setting). | V | V |
| After an access code has been defined. | V | ✓ ¹⁾ |

1) The user only has write access after entering the access code.

Access authorization to parameters: "Operator" user role

| Access code status | Read access | Write access |
|--|-------------|--------------|
| After an access code has been defined. | V | _ 1) |

1) Despite the defined access code, certain parameters can always be modified and thus are excluded from the write protection as they do not affect the measurement: write protection via access code $\rightarrow \cong 155$

The user role with which the user is currently logged on is indicated by the **Access status** parameter. Navigation path: Operation → Access status

8.3.11 Disabling write protection via access code

If the B-symbol appears on the local display in front of a parameter, the parameter is write-protected by a user-specific access code and its value cannot be changed at the moment using local operation \rightarrow B 155.

Parameter write protection via local operation can be disabled by entering the user-specific access code in the **Enter access code** parameter via the respective access option.

1. After you press , the input prompt for the access code appears.

2. Enter the access code.

➡ The B -symbol in front of the parameters disappears; all previously writeprotected parameters are now re-enabled.

8.3.12 Enabling and disabling the keypad lock

The keypad lock makes it possible to block access to the entire operating menu via local operation. As a result, it is no longer possible to navigate through the operating menu or change the values of individual parameters. Users can only read the measured values on the operational display.

The keypad lock is switched on and off via the context menu.

Switching on the keypad lock

The keypad lock is switched on automatically:

- If the device has not been operated via the display for > 1 minute.
- Each time the device is restarted.

To activate the keylock manually:

1. The device is in the measured value display.

- Press the \Box and \blacksquare keys for 3 seconds.
- 2. In the context menu select the **Keylock on** option.
 - └ The keypad lock is switched on.

If the user attempts to access the operating menu while the keypad lock is active, the **Keylock on** message appears.

Switching off the keypad lock

- The keypad lock is switched on.
 - Press the \Box and \blacksquare keys for 3 seconds.
 - └ The keypad lock is switched off.

8.4 Access to operating menu via web browser

8.4.1 Function range

With the integrated web server, the device can be operated and configured via a web browser service interface (CDI-RJ45) or WLAN interface. The structure of the operating menu is the same as for the local display. In addition to the measured values, status information on the device is displayed and can be used to monitor device health. Furthermore the device data can be managed and the network parameters can be configured.

A device that has a WLAN interface (can be ordered as an option) is required for the WLAN connection: order code for "Display; operation", option G "4-line, illuminated; touch control + WLAN". The device acts as an Access Point and enables communication by computer or a mobile handheld terminal.

For additional information on the web server, see the Special Documentation for the device. $\rightarrow \cong 279$

8.4.2 Requirements

Computer hardware

| Hardware | Interface | | |
|------------|---|--|--|
| | CDI-RJ45 | WLAN | |
| Interface | The computer must have a RJ45 interface. ¹⁾ | The operating unit must have a WLAN interface. | |
| Connection | Standard Ethernet cable | Connection via Wireless LAN. | |
| Screen | Recommended size: ≥12" (depends on the screen resolution) | | |

1) Recommended cable: CAT5e, CAT6 or CAT7, with shielded plug (e.g. YAMAICHI product; part no. Y-ConProfixPlug63/Prod. ID: 82-006660)

Computer software

| Software | Interface | | |
|--|---|------|--|
| | CDI-RJ45 | WLAN | |
| Recommended operating systems | Microsoft Windows 8 or higher. Mobile operating systems: iOS Android Microsoft Windows XP and Windows 7 is supported. | | |
| Web browsers supported • Microsoft Internet Explorer 8 or higher Microsoft Edge • Mozilla Firefox Google Chrome • Safari | | r | |

Computer settings

| Settings | Interface | | |
|--|--|---|--|
| | CDI-RJ45 | WLAN | |
| User rights | Appropriate user rights (e.g. administrator right settings are necessary (e.g. for adjusting the IP a | | |
| Proxy server settings of the web browser | The web browser setting <i>Use a proxy server for your LAN</i> must be disabled . | | |
| JavaScript | JavaScript must be enabled. | JavaScript must be enabled. | |
| | If JavaScript cannot be enabled: Enter http://192.168.1.212/servlet/ basic.html in the address bar of the web browser. A fully functional but simplified version of the operating menu structure starts in the web browser. | The WLAN display requires JavaScript support. | |
| | When installing a new firmware version: To enable correct data display, clear the temporary memory (cache) under Internet options in the web browser. | | |
| Network connections Only use the active network connections to | | neasuring device. | |
| | Switch off all other network connections such as WLAN for example. | Switch off all other network connections. | |

∏ In the event of connection problems: → \blacksquare 172

Measuring device: Via CDI-RJ45 service interface

| Device | CDI-RJ45 service interface |
|------------------|--|
| Measuring device | The measuring device has an RJ45 interface. |
| Web server | Web server must be enabled; factory setting: ON i For information on enabling the Web server → 86 |

Measuring device: via WLAN interface

| Device | WLAN interface | |
|------------------|--|--|
| Measuring device | The measuring device has a WLAN antenna:Transmitter with integrated WLAN antennaTransmitter with external WLAN antenna | |
| Web server | Web server and WLAN must be enabled; factory setting: ONI For information on enabling the Web server → 86 | |

8.4.3 Connecting the device

Via service interface (CDI-RJ45)

Preparing the measuring device

Proline 500 – digital

- 1. Loosen the 4 fixing screws on the housing cover.
- 2. Open the housing cover.
- **3.** The location of the connection socket depends on the measuring device and the communication protocol.

Connect the computer to the RJ45 plug via the standard Ethernet cable .

Proline 500

- Depending on the housing version: Loosen the securing clamp or fixing screw of the housing cover.
- 2. Depending on the housing version: Unscrew or open the housing cover.
- 3. Connect the computer to the RJ45 plug via the standard Ethernet connecting cable..

Configuring the Internet protocol of the computer

The following information refers to the default Ethernet settings of the device.

IP address of the device: 192.168.1.212 (factory setting)

- 1. Switch on the measuring device.
- **2.** Connect the computer to the RJ45 plug via the standard Ethernet cable $\rightarrow \cong 87$.
- 3. If a 2nd network card is not used, close all the applications on the notebook.
 - ← Applications requiring Internet or a network, such as e-mail, SAP applications, Internet or Windows Explorer.
- 4. Close any open Internet browsers.
- **5.** Configure the properties of the Internet protocol (TCP/IP) as defined in the table:

| IP address | 192.168.1.XXX; for XXX all numerical sequences except: 0, 212 and 255 \rightarrow e.g. 192.168.1.213 | |
|-----------------|--|--|
| Subnet mask | 255.255.255.0 | |
| Default gateway | 192.168.1.212 or leave cells empty | |

Via WLAN interface

Configuring the Internet protocol of the mobile terminal

NOTICE

- If the WLAN connection is lost during the configuration, settings made may be lost.
- ► Make sure that the WLAN connection is not disconnected while configuring the device.

NOTICE

Note the following to avoid a network conflict:

- ► Avoid accessing the measuring device simultaneously from the same mobile terminal via the service interface (CDI-RJ45) and the WLAN interface.
- Only activate one service interface (CDI-RJ45 or WLAN interface).
- ► If simultaneous communication is necessary: configure different IP address ranges, e.g. 192.168.0.1 (WLAN interface) and 192.168.1.212 (CDI-RJ45 service interface).

Preparing the mobile terminal

► Enable WLAN on the mobile terminal.

Establishing a WLAN connection from the mobile terminal to the measuring device

1. In the WLAN settings of the mobile terminal:

Select the measuring device using the SSID (e.g. EH_Promass_500_A802000).

- 2. If necessary, select the WPA2 encryption method.
- 3. Enter the password:
 - Serial number of the measuring device ex-works (e.g. L100A802000).
 - └ The LED on the display module flashes. It is now possible to operate the measuring device with the web browser, FieldCare or DeviceCare.
 - The serial number can be found on the nameplate.
- To ensure the safe and swift assignment of the WLAN network to the measuring point, it is advisable to change the SSID name. It should be possible to clearly assign the new SSID name to the measuring point (e.g. tag name) because it is displayed as the WLAN network.

Terminating the WLAN connection

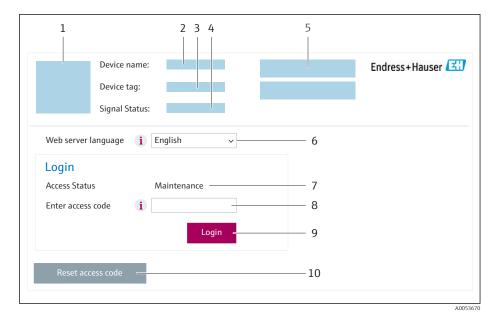
 After configuring the device: Terminate the WLAN connection between the mobile terminal and measuring device.

Starting the web browser

1. Start the web browser on the computer.

2. Enter the IP address of the web server in the address line of the web browser: 192.168.1.212

└ The login page appears.



- 1 Picture of device
- 2 Device name
- 3 Device tag
- 4 Status signal
- 5 Current measured values6 Operating language
- 7 User role
- 8 Access code
- 9 Login
- 10 Reset access code ($\rightarrow \square 152$)

If a login page does not appear, or if the page is incomplete $\rightarrow \square 172$

8.4.4 Logging on

1. Select the preferred operating language for the Web browser.

- 2. Enter the user-specific access code.
- 3. Press **OK** to confirm your entry.

Access code 0000 (factory setting); can be changed by customer

If no action is performed for 10 minutes, the Web browser automatically returns to the login page.

8.4.5 User interface



- 1 Function row
- 2 Local display language
- 3 Navigation area

Header

The following information appears in the header:

- Device name
- Device tag
- Device status with status signal $\rightarrow \square 180$
- Current measured values

Function row

| Functions | Meaning | |
|--------------------|--|--|
| Measured values | Displays the measured values of the device | |
| Menu | Access to the operating menu from the measuring device The structure of the operating menu is the same as for the local display Detailed information on the operating menu structure: Description of Device Parameters | |
| Device status | Displays the diagnostic messages currently pending, listed in order of priority | |
| Data management | Data exchange between computer and measuring device: Device configuration: Load settings from the device (XML format, save configuration) Save settings to the device (XML format, restore configuration) Logbook - Export Event logbook (.csv file) Documents - Export documents: Export backup data record (.csv file, create documentation of the measuring point configuration) Verification report (PDF file, only available with the "Heartbeat Verification" application package) File for system integration - If using fieldbuses, upload device drivers for system integration from the measuring device: PROFIBUS PA: GSD file Firmware update - Flashing a firmware version | |
| Network | Configuration and checking of all the parameters required for establishing the connection to the measuring device:Network settings (e.g. IP address, MAC address)Device information (e.g. serial number, firmware version) | |
| Logout | End the operation and call up the login page | |

Navigation area

The menus, the associated submenus and parameters can be selected in the navigation area.

Working area

Depending on the selected function and the related submenus, various actions can be performed in this area:

- Configuring parameters
- Reading measured values
- Calling up help text
- Starting an upload/download

8.4.6 Disabling the Web server

The Web server of the measuring device can be switched on and off as required using the **Web server functionality** parameter.

Navigation

"Expert" menu \rightarrow Communication \rightarrow Web server

Parameter overview with brief description

| Parameter | Description | Selection |
|--------------------------|-----------------------------------|---|
| Web server functionality | Switch the Web server on and off. | OffHTML OffOn |

Function scope of the "Web server functionality" parameter

| Option | Description | |
|----------|---|--|
| Off | The Web server is completely disabled.Port 80 is locked. | |
| HTML Off | The HTML version of the Web server is not available. | |
| On | The complete Web server functionality is available. JavaScript is used. The password is transferred in an encrypted state. Any change to the password is also transferred in an encrypted state. | |

Enabling the Web server

If the Web server is disabled it can only be re-enabled with the **Web server functionality** parameter via the following operating options:

- Via local display
- Via Bedientool "FieldCare"
- Via "DeviceCare" operating tool

8.4.7 Logging out

Before logging out, perform a data backup via the **Data management** function (upload configuration from device) if necessary.

1. Select the **Logout** entry in the function row.

- └ The home page with the Login box appears.
- 2. Close the Web browser.

3. If no longer needed:

Reset the modified properties of the Internet protocol (TCP/IP) \rightarrow 🗎 82.

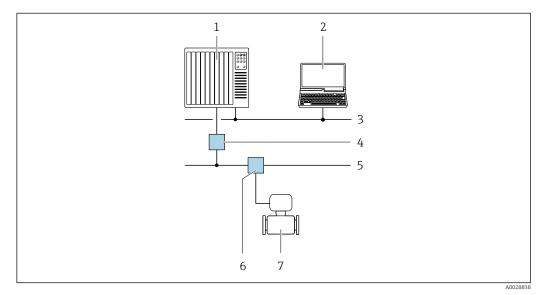
8.5 Access to the operating menu via the operating tool

The structure of the operating menu in the operating tools is the same as for operation via the local display.

8.5.1 Connecting the operating tool

Via PROFIBUS PA network

This communication interface is available in device versions with PROFIBUS PA.



☑ 30 Options for remote operation via PROFIBUS PA network

- 1 Automation system
- 2 Computer with PROFIBUS network card
- 3 PROFIBUS DP network
- 4 Segment coupler PROFIBUS DP/PA
- 5 PROFIBUS PA network
- 6 T-box7 Measuring device

Service interface

Via service interface (CDI-RJ45)

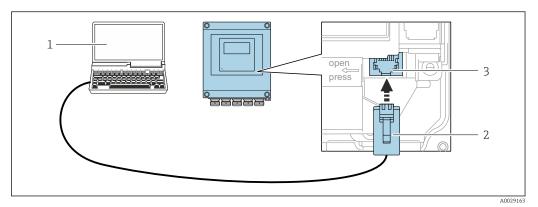
A point-to-point connection can be established to configure the device onsite. With the housing open, the connection is established directly via the service interface (CDI-RJ45) of the device.

An adapter for the RJ45 to the M12 plug is optionally available for the non-hazardous area:

Order code for "Accessories", option NB: "Adapter RJ45 M12 (service interface)"

The adapter connects the service interface (CDI-RJ45) to an M12 plug mounted in the cable entry. The connection to the service interface can be established via an M12 plug without opening the device.

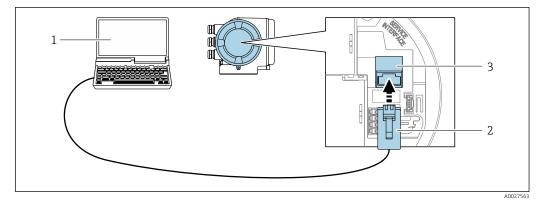
Proline 500 – digital transmitter



☑ 31 Connection via service interface (CDI-RJ45)

- 1 Computer with web browser (e.g. Microsoft Internet Explorer, Microsoft Edge) for accessing the integrated web server or with "FieldCare" operating tool, "DeviceCare" with COM DTM "CDI Communication TCP/IP"
- 2 Standard Ethernet connecting cable with RJ45 plug
- 3 Service interface (CDI-RJ45) of the measuring device with access to the integrated Web server

Proline 500 transmitter

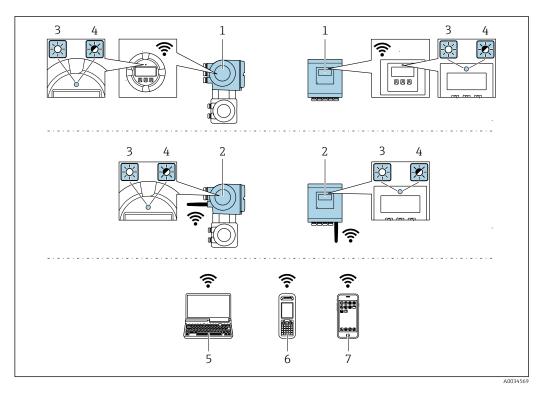


■ 32 Connection via service interface (CDI-RJ45)

- 1 Computer with web browser (e.g. Microsoft Internet Explorer, Microsoft Edge) for accessing the integrated web server or with "FieldCare" operating tool, "DeviceCare" with COM DTM "CDI Communication TCP/IP"
- 2 Standard Ethernet connecting cable with RJ45 plug
- 3 Service interface (CDI-RJ45) of the measuring device with access to the integrated Web server

Via WLAN interface

The optional WLAN interface is available on the following device version: Order code for "Display; operation", option G "4-line, illuminated; touch control + WLAN"



- 1 Transmitter with integrated WLAN antenna
- 2 Transmitter with external WLAN antenna
- 3 LED lit constantly: WLAN reception is enabled on measuring device
- 4 LED flashing: WLAN connection established between operating unit and measuring device
- 5 Computer with WLAN interface and web browser (e.g. Microsoft Internet Explorer, Microsoft Edge) for accessing the integrated device web server or with operating tool (e.g. FieldCare, DeviceCare)
- 6 Mobile handheld terminal with WLAN interface and web browser (e.g. Microsoft Internet Explorer, Microsoft Edge) for accessing the integrated device web server or operating tool (e.g. FieldCare, DeviceCare)
- 7 Smart phone or tablet (e.g. Field Xpert SMT70)

| Function | WLAN: IEEE 802.11 b/g (2.4 GHz) | |
|------------------------------|---|--|
| Encryption | WPA2-PSK AES-128 (in accordance with IEEE 802.11i) | |
| Configurable WLAN channels | 1 to 11 | |
| Degree of protection | IP67 | |
| Available antennas | Internal antenna External antenna (optional) In the event of poor transmission/reception conditions at the place of installation. Only 1 antenna is active at any one time! | |
| Range | Internal antenna: typically 10 m (32 ft) External antenna: typically 50 m (164 ft) | |
| Materials (external antenna) | Antenna: ASA plastic (acrylonitrile styrene acrylate) and nickel-plated brass Adapter: Stainless steel and nickel-plated brass Cable: Polyethylene Plug: Nickel-plated brass Angle bracket: Stainless steel | |

Configuring the Internet protocol of the mobile terminal

NOTICE

If the WLAN connection is lost during the configuration, settings made may be lost.

▶ Make sure that the WLAN connection is not disconnected while configuring the device.

NOTICE

Note the following to avoid a network conflict:

- ► Avoid accessing the measuring device simultaneously from the same mobile terminal via the service interface (CDI-RJ45) and the WLAN interface.
- Only activate one service interface (CDI-RJ45 or WLAN interface).
- ► If simultaneous communication is necessary: configure different IP address ranges, e.g. 192.168.0.1 (WLAN interface) and 192.168.1.212 (CDI-RJ45 service interface).

Preparing the mobile terminal

• Enable WLAN on the mobile terminal.

Establishing a WLAN connection from the mobile terminal to the measuring device

1. In the WLAN settings of the mobile terminal:

Select the measuring device using the SSID (e.g. EH_Promass_500_A802000).

- 2. If necessary, select the WPA2 encryption method.
- 3. Enter the password:
 - Serial number of the measuring device ex-works (e.g. L100A802000).
 - ← The LED on the display module flashes. It is now possible to operate the measuring device with the web browser, FieldCare or DeviceCare.
- The serial number can be found on the nameplate.
- To ensure the safe and swift assignment of the WLAN network to the measuring point, it is advisable to change the SSID name. It should be possible to clearly assign the new SSID name to the measuring point (e.g. tag name) because it is displayed as the WLAN network.

Terminating the WLAN connection

 After configuring the device: Terminate the WLAN connection between the mobile terminal and measuring device.

8.5.2 FieldCare

Function range

FDT-based (Field Device Technology) plant asset management tool from Endress+Hauser. It can configure all smart field units in a system and helps you manage them. By using the status information, it is also a simple but effective way of checking their status and condition.

Access is via:

- PROFIBUS PA protocol $\rightarrow \triangleq 87$
- CDI-RJ45 service interface $\rightarrow \cong 87$
- WLAN interface \rightarrow 🗎 88

Typical functions:

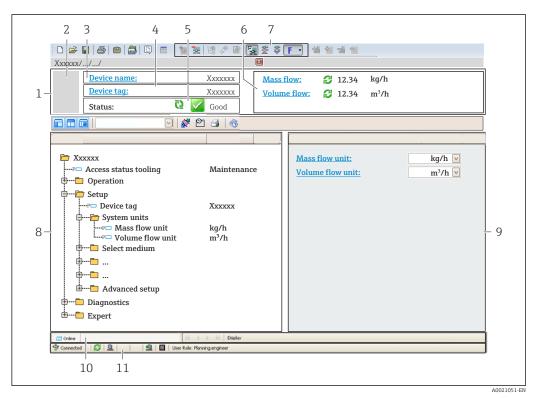
- Transmitter parameter configuration
- Loading and saving of device data (upload/download)
- Documentation of the measuring point
- Visualization of the measured value memory (line recorder) and event logbook
- Operating Instructions BA00027S
 - Operating Instructions BA00059S
 - Source for device description files $\rightarrow \cong 93$

Establishing a connection

- 1. Start FieldCare and launch the project.
- 2. In the network: Add a device.
 - └ The **Add device** window opens.
- 3. Select the **CDI Communication TCP/IP** option from the list and press **OK** to confirm.
- 4. Right-click **CDI Communication TCP/IP** and select the **Add device** option in the context menu that opens.
- 5. Select the desired device from the list and press OK to confirm.

 The CDI Communication TCP/IP (Configuration) window opens.
- 6. Enter the device address in the **IP address** field: 192.168.1.212 and press **Enter** to confirm.
- 7. Establish the online connection to the device.
- Operating Instructions BA00027S
 - Operating Instructions BA00059S

User interface



- 1 Header
- 2 Picture of device
- 3 Device name
- 4 Device tag
- 5 Status area with status signal $\rightarrow \square$ 180
- 6 Display area for current measured values
- 7 Editing toolbar with additional functions such as save/load, event list and create documentation
- 8 Navigation area with operating menu structure
- 9 Work area
- 10 Action area
- 11 Status area

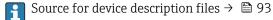
8.5.3 DeviceCare

Function range

Tool for connecting and configuring Endress+Hauser field devices.

The fastest way to configure Endress+Hauser field devices is with the dedicated "DeviceCare" tool. Together with the device type managers (DTMs) it presents a convenient, comprehensive solution.

Innovation brochure IN01047S



8.5.4 SIMATIC PDM

Function range

Standardized, vendor-independent program from Siemens for the operation, configuration, maintenance and diagnosis of intelligent field devices via the PROFIBUS PA protocol.

Source for device description files $\rightarrow \cong$ 93

9 System integration

9.1 Overview of device description files

9.1.1 Current version data for the device

| Firmware version | 01.01.zz | On the title page of the manual On the transmitter nameplate Firmware version Diagnostics → Device information → Firmware version |
|----------------------------------|----------|---|
| Release date of firmware version | 11.2018 | |
| Manufacturer ID | 0x11 | Manufacturer ID Diagnostics → Device information → Manufacturer ID |
| Device type ID | 0x156D | Device type Diagnostics \rightarrow Device information \rightarrow Device type |
| Profile version | 3.02 | |

For an overview of the various firmware versions for the device \rightarrow \cong 243

9.1.2 Operating tools

The suitable device description file for the individual operating tools is listed in the table below, along with information on where the file can be acquired.

| Operating tool via PROFIBUS protocol | Sources for obtaining device descriptions | |
|---|--|--|
| FieldCare | www.endress.com → Downloads area USB stick (contact Endress+Hauser) DVD (contact Endress+Hauser) | |
| DeviceCare | www.endress.com → Downloads area CD-ROM (contact Endress+Hauser) DVD (contact Endress+Hauser) | |
| SIMATIC PDM (Siemens) | www.endress.com → Downloads area | |

9.2 Device master file (GSD)

In order to integrate field devices into a bus system, the PROFIBUS system needs a description of the device parameters, such as output data, input data, data format, data volume and supported transmission rate.

These data are available in the device master file (GSD) which is provided to the PROFIBUS Master when the communication system is commissioned. In addition device bit maps, which appear as icons in the network structure, can also be integrated.

With the Profile 3.02 device master file (GSD) it is possible to exchange field devices made by different manufacturers without having to reconfigure.

Generally speaking, it is possible to use two different GSDs with Profile 3.02 and higher: the manufacturer-specific GSD and the Profile GSD.

• Before configuring, the user must decide which GSD should be used to operate the system.

• The setting can be changed via a Class 2 master.

9.2.1 Manufacturer-specific GSD

This GSD guarantees the unrestricted functionality of the measuring device. Device-specific process parameters and functions are therefore available.

| Manufacturer-specific GSD | ID number | File name |
|---------------------------|-----------|--------------|
| PROFIBUS PA | 0x156D | EH3x156D.gsd |

Use manufacturer-specific GSD

Assignment is performed in the **Ident number selector** parameter via the **Manufacturer** option.

Sources of supply for the manufacturer-specific GSD:

- Export directly from the device via the integrated web server: Data management → Documents → Export GSD file
- Download via the Endress+Hauser website:
 www.endress.com → Download-Area

9.2.2 Profile GSD

Differs in terms of the number of Analog Input blocks (AI) and the measured values. If a system is configured with a Profile GSD, it is possible to exchange devices made by different manufacturers. However, it is essential to ensure that the order of the cyclic process values is correct.

| ID number | Supported blocks | Supported channels |
|-----------|--|---|
| 0x9740 | 1 Analog Input1 Totalizer | Channel Analog Input: volume flowChannel totalizer: volume flow |
| 0x9741 | 2 Analog Input 1 Totalizer | Channel Analog Input 1: volume flow Channel Analog Input 2: mass flow Channel totalizer: volume flow |
| 0x9742 | 3 Analog Input 1 Totalizer | Channel Analog Input 1: volume flow Channel Analog Input 2: mass flow Channel Analog Input 3: corrected volume flow Channel totalizer: volume flow |

Use profile GSD

Assignment is performed in the **Ident number selector** parameter:

- ID number 0x9740: **1 AI, 1 Totalizer (0x9740)** option
- ID number 0x9741: 2 AI, 1 Totalizer (0x9741) option
- ID number 0x9742: **Profile** option

9.3 Compatibility with earlier model

If the device is replaced, the measuring device Promass 500 supports the compatibility of the cyclic data with previous models. It is not necessary to adjust the engineering parameters of the PROFIBUS network with the Promass 500 GSD file.

Earlier models:

- Promass 80PROFIBUS PA
 - ID No.: 1528 (hex)
 - Extended GSD file: EH3x1528.gsd
- Standard GSD file: EH3 1528.gsd
- Promass 83PROFIBUS PA
 - ID No.: 152A (hex)
 - Extended GSD file: EH3x152A.gsd
 - Standard GSD file: EH3 152A.gsd

9.3.1 Automatic identification (factory setting)

The Promass 500 PROFIBUS PA automatically recognizes the measuring device configured in the automation system (Promass 80 PROFIBUS PA or Promass 83 PROFIBUS PA) and makes the same input and output data and measured value status information available for cyclic data exchange.

Automatic identification is set in the **Ident number selector** parameter using the Automatic mode option (factory setting).

9.3.2 Manual setting

The manual setting is made in the **Ident number selector** parameter via the **Promass 80** (0x1528) option or Promass 83 (0x152A) option.

Afterwards the Promass 500 PROFIBUS PA makes the same input and output data and measured value status information available for cyclic data exchange.

- If the Promass 500 PROFIBUS PA is acyclically configured via an operating program (Class 2 master), access is directly via the block structure or the parameters of the measuring device.
- If parameters have been changed in the device to be replaced (Promass 80 PROFIBUS PA or Promass 83 PROFIBUS PA) (parameter setting no longer corresponds to the original factory setting), these parameters must be changed accordingly in the new replacement Promass 500 PROFIBUS PA via an operating program (Class 2 master).

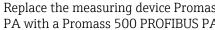
Example

The setting for low flow cut off has been changed from mass flow (factory setting) to corrected volume flow in a Promass 80 PROFIBUS PA currently in operation. This device is now replaced by a Promass 500 PROFIBUS PA.

After replacing the device, the assignment for the low flow cut off must also be changed manually in the Promass 500 PROFIBUS PA, i.e. to corrected volume flow, to ensure the measuring device behaves identically.

9.3.3 Replacing the measuring devices without changing the GSD file or restarting the controller

In the procedure described below, the device can be replaced without interrupting ongoing operation or restarting the controller. However with this procedure the measuring device is not fully integrated!



1. Replace the measuring device Promass 80 PROFIBUS PA or Promass 83 PROFIBUS PA with a Promass 500 PROFIBUS PA.

- 2. Set the device address: The same device address that was set for the Promass 80 or Promass 83 PROFIBUS PA must be used.
- 3. Connect the measuring device Promass 500 PROFIBUS PA.

If the factory setting had been changed on the replaced device (Promass 80 PROFIBUS PA or Promass 83 PROFIBUS PA), the following settings may need to be changed:

- **1**. Configuration of the application-specific parameters.
- 2. Choice of process variables to be transmitted via the **Channel** parameter in the Analog Input or Totalizer function block.
- 3. Setting of the units for the process variables.

9.4 Using the GSD modules of the previous model

In the compatibility mode, all the modules already configured in the automation system are generally supported during cyclic data transmission. However, Promass 500 does not perform further processing for the following modules, i.e. the function is not executed:

- DISPLAY_VALUE
- BATCHING_QUANTITY
- BATCHING_FIX_COMP_QUANTITY

If the device is replaced, the Promass 500 device supports the compatibility of the cyclic data with previous models. It is not necessary to adjust the engineering parameters of the PROFIBUS network with the Promass 500 GSD file.

The diagnostic messages transmitted to the distributed control system with the GSD of the previous model may differ from the diagnostic messages of the device. The diagnostic messages of the device are critical.

9.4.1 Using the CONTROL_BLOCK module in the previous model

If the CONTROL_BLOCK module is used in the previous model, the control variables are processed further if relevant functionalities can be assigned for the Promass 500.

The functions are supported as follows depending on the previous model:

| Control variable | Function | Support |
|-------------------|--------------------------------|---|
| 0 → 2 | Positive zero return: ON | Yes |
| 0 → 3 | Positive zero return: OFF | Yes |
| $0 \rightarrow 4$ | Zero point adjustment: START | Yes |
| 0 → 8 | Measuring mode: UNIDIRECTIONAL | No |
| 0 → 9 | Measuring mode: BIDIRECTIONAL | Cause: The Profile Transducer Block Flow is no longer supported. |
| | | To continue to use the functionality: Use the Totalizer operation mode parameter in the Totalizer function block. |
| 0 → 24 | UNIT TO BUS | No |
| | | Cause: Functionality is no longer required as the unit is adopted automatically. |

Previous model: Promass 80 PROFIBUS PA

| Control variable | Function | Support |
|------------------|---|---|
| 0 → 2 | Positive zero return: ON | Yes |
| 0 → 3 | Positive zero return: OFF | Yes |
| 0 → 4 | Zero point adjustment: START | Yes |
| 0 → 8 | Measuring mode: UNIDIRECTIONAL | No |
| 0 → 9 | Measuring mode: BIDIRECTIONAL | Cause: The Profile Transducer Block Flow is no longer supported. |
| | | To continue to use the functionality: Use the Totalizer operation mode parameter in the Totalizer function block. |
| 0 → 24 | UNIT TO BUS | No |
| | | Cause: Functionality is no longer required as the unit is adopted automatically. |
| 0 → 25 | Advanced diagnostics – Warning mode: ON | No |
| 0 → 26 | Advanced diagnostics – Warning mode: OFF | To continue to use the functionality: The functionalities are offered in the "Heartbeat Technology" application |
| 0 → 70 to 78 | Additional functions: Advanced diagnostics | package. |

Previous model: Promass 83 PROFIBUS PA

9.5 Cyclic data transmission

Cyclic data transmission when using the device master file (GSD).

9.5.1 Block model

The block model shows which input and output data the measuring device makes available for cyclic data exchange. Cyclic data exchange takes place with a PROFIBUS master (Class 1), e.g. a control system.

| Measuring instrument | | | | | Control system |
|----------------------|------------------------------|---------|-----------------------|---------------|----------------|
| | Analog Input block 1 to 8 | → 🖺 99 | Output value AI | ÷ | |
| | | | Output value TOTAL | \rightarrow | |
| | Totalizer block 1 to 3 | → 🖺 100 | Controller SETTOT | ÷ | |
| Flow | | | Configuration MODETOT | ÷ | |
| Block | Analog Output block 1 to 3 | → 🗎 102 | Input values AO | ÷ | PROFIBUS PA |
| | Discrete Input block 1 to 2 | → 🖺 102 | Output values DI | ÷ | |
| | Discrete Output block 1 to 4 | → 🖺 103 | Input values DO | ÷ | |

Defined order of modules

The measuring device works as a modular PROFIBUS slave. In contrast to a compact slave, a modular slave has a variable design and consists of several individual modules. The device master file (GSD) contains a description of the individual modules (input and output data) along with their individual properties.

The modules are permanently assigned to the slots, i.e. when configuring the modules, the order and the arrangement of the modules must be respected.

| Slot | Module | Function block |
|----------|---|------------------------------|
| 1 to 8 | AI | Analog Input block 1 to 8 |
| 9 | TOTAL or SETTOT_TOTAL or T SETTOT_TOTAL or T SETOT_MODETOT_TOTAL T AO AO A DI E | Totalizer block 1 |
| 10 | | Totalizer block 2 |
| 11 | | Totalizer block 3 |
| 12 to 14 | | Analog Output block 1 to 3 |
| 15 to 16 | | Discrete Input block 1 to 2 |
| 17 to 21 | | Discrete Output block 1 to 5 |
| 22 to 23 | AO | Analog Output block 4 to 5 |

To optimize the data throughput rate of the PROFIBUS network, it is advisable to only configure modules that are processed in the PROFIBUS master system. If this results in gaps between the configured modules, these gaps must be assigned to the EMPTY_MODULE.

9.5.2 Description of the modules

The data structure is described from the perspective of the PROFIBUS master:

- Input data: Are sent from the measuring device to the PROFIBUS master.
- Output data: Are sent from the PROFIBUS master to the measuring device.

AI module (Analog Input)

Transmit an input variable from the measuring device to the PROFIBUS master (Class 1).

The selected input variable including its status is cyclically transmitted to the PROFIBUS master (Class 1) via the AI module. The input variable is depicted in the first four bytes in the form of a floating point number as per the IEEE 754 standard. The fifth byte contains standardized status information pertaining to the input variable.

Eight Analog Input blocks are available (slot 1 to 8).

Selection: input variable

| Input variable |
|---|
| Mass flow |
| Volume flow |
| Corrected volume flow |
| Density |
| Reference density |
| Temperature |
| Electronics temperature |
| Oscillation frequency 0 |
| Frequency fluctuation 0 |
| Oscillation damping 0 |
| Tube damping fluctuation 0 |
| Signal asymmetry |
| Exciter current 0 |
| Concentration ¹⁾ |
| Target mass flow ¹⁾ |
| Carrier mass flow ¹⁾ |
| Target volume flow ¹⁾ |
| Carrier volume flow 1) |
| Target corrected volume flow ¹⁾ |
| Carrier corrected volume flow ¹⁾ |
| Carrier tube temperature ²⁾ |
| Oscillation frequency 1 ²⁾ |
| Oscillation amplitude 0 ²⁾ |
| Oscillation amplitude 1 ²⁾ |
| Frequency fluctuation 1 ²⁾ |
| Oscillation damping 1 ²⁾ |
| Tube damping fluctuation 1 ²⁾ |
| Exciter current 1 ²⁾ |
| HBSI ²⁾ |
| Current input 1 |
| Current input 2 |
| Current input 3 |

1) Only available with the Concentration application package

2) Only available with the Heartbeat Verification application package

Factory setting

| Function block | Factory setting |
|----------------|-----------------------|
| AI 1 | Mass flow |
| AI 2 | Volume flow |
| AI 3 | Corrected volume flow |
| AI 4 | Density |
| AI 5 | Mass flow |
| AI 6 | Temperature |
| AI 7 | Mass flow |
| AI 8 | Mass flow |

Data structure

Input data of Analog Input

| Byte 1 | Byte 2 | Byte 3 | Byte 4 | Byte 5 |
|--|--------|--------|--------|--------|
| Measured value: floating point number (IEEE 754) | | | | Status |

TOTAL module

Transmit a totalizer value from the measuring device to the PROFIBUS master (Class 1).

A selected totalizer value, along with the status, is cyclically transmitted to a PROFIBUS Master (Class 1) via the TOTAL module. The totalizer value is depicted in the first four bytes in the form of a floating point number as per the IEEE 754 standard. The fifth byte contains standardized status information pertaining to the totalizer value.

Three Totalizer blocks are available (slot 9 to 11).

Selection: totalizer value

| Input variable |
|---------------------------|
| Mass flow |
| Volume flow |
| Corrected volume flow |
| Target fluid mass flow 1) |
| Carrier mass flow 1) |

1) Only available with the "Concentration" application package

Factory setting

| Function block | Factory setting: TOTAL |
|----------------------|------------------------|
| Totalizer 1, 2 and 3 | Mass flow |

Data structure

Input data of TOTAL

| Byte 1 | Byte 2 | Byte 3 | Byte 4 | Byte 5 |
|--|--------|--------|--------|--------|
| Measured value: floating point number (IEEE 754) | | | | Status |

SETTOT_TOTAL module

The module combination consists of the SET_TOT and TOTAL functions:

- SETTOT: Control the totalizers via the PROFIBUS master.
- TOTAL: Transmit totalizer value incl. status to PROFIBUS master.

Three Totalizer blocks are available (slot 9 to 11).

Selection: control totalizer

| Value SETTOT | Control totalizer |
|--------------|-------------------|
| 0 | Totalize |
| 1 | Reset + hold |
| 2 | Preset + hold |

Factory setting

| Function block | Factory setting: Value SETTOT (meaning) |
|----------------------|---|
| Totalizer 1, 2 and 3 | 0 (totalizing) |

Data structure

Output data of SETTOT

| Byte 1 | |
|--------------------|--|
| Control variable 1 | |

Input data of TOTAL

| Byte 1 | Byte 2 | Byte 3 | Byte 4 | Byte 5 |
|--|--------|--------|--------|--------|
| Measured value: floating point number (IEEE 754) | | | | Status |

SETTOT_MODETOT_TOTAL module

The module combination consists of the SETTOT, MODETOT and TOTAL functions: • SETTOT: Control the totalizers via the PROFIBUS master.

- MODETOT: Configure the totalizers via the PROFIBUS master.
- TOTAL: Transmit totalizer value, along with the status, to the PROFIBUS master.

Three Totalizer blocks are available (slot 9 to 11).

Selection: totalizer configuration

| MODETOT value | Totalizer configuration |
|---------------|---------------------------|
| 0 | Balancing |
| 1 | Balance the positive flow |
| 2 | Balance the negative flow |
| 3 | Stop totalizing |

Factory setting

| | Function block | Factory setting: Value MODETOT (meaning) |
|---|---------------------|--|
| Т | otalizer 1, 2 and 3 | 0 (balancing) |

Data structure

Output data of SETTOT and MODETOT

| Byte 1 | Byte 2 |
|----------------------------|-----------------------------|
| Control variable 1: SETTOT | Control variable 2: MODETOT |

Input data of TOTAL

| Byte 1 | Byte 2 | Byte 3 | Byte 4 | Byte 5 |
|---------|--------------------|------------------|----------|--------|
| Measure | ed value: floating | point number (IE | EEE 754) | Status |

AO module (Analog Output)

Transmit a compensation value from the PROFIBUS master (class 1) to the measuring device.

A compensation value, including the status, is cyclically transmitted from the PROFIBUS master (class 1) to the measuring device via the AO module. The compensation value is depicted in the first four bytes in the form of a floating point number as per the IEEE 754 standard. The fifth byte contains standardized status information pertaining to the compensation value.

Five Analog Output blocks are available (slot 12 to 14, 22 to 23).

Assigned compensation values

A compensation value is permanently assigned to the individual Analog Output blocks.

| Function block | Compensation value |
|----------------|------------------------------------|
| A0 1 | External pressure 1) |
| A0 2 | External temperature ¹⁾ |
| A0 3 | External reference density |
| A0 4 | - |
| A0 5 | - |

1) The compensation values must be transmitted to the device in the SI basic unit



The selection is made via: Expert \rightarrow Sensor \rightarrow External compensation

Data structure

Output data of Analog Output

| Byte 1 | Byte 2 | Byte 3 | Byte 4 | Byte 5 |
|---------|-------------------|------------------|----------|-----------|
| Measure | d value: floating | point number (IE | EEE 754) | Status 1) |

1) Status coding

DI module (Discrete Input)

Transmit discrete input values from the measuring device to the PROFIBUS master (class 1). Discrete input values are used by the measuring device to transmit the state of device functions to the PROFIBUS master (class 1).

The DI module cyclically transmits the discrete input value, including the status, to the PROFIBUS master (class 1). The discrete input value is depicted in the first byte. The second byte contains standardized status information pertaining to the input value.

Two Discrete Input blocks are available (slot 15 to 16).

Selection: device function

| Device function | Factory setting: Status (meaning) | |
|-----------------------------------|---|--|
| Empty pipe detection | 0 (device function not active) | |
| Low flow cut off | • 1 (device function active) | |
| Verification status ¹⁾ | Bit 0: Verification status - Check not done Bit 1: Verification status - Failed Bit 2: Verification status - Busy Bit 3: Verification status - Ready Bit 4: Verification overall result - Failed Bit 5: Verification overall result - Passed Bit 6: Verification overall result - Check not done Bit 7: Not used | |

1) Only available with the Heartbeat Verification application package

Factory setting

| Function block | Factory setting |
|----------------|----------------------|
| DI 1 | Empty pipe detection |
| DI 2 | Low flow cut off |

Data structure

Input data of Discrete Input

| Byte 1 | Byte 2 |
|----------|--------|
| Discrete | Status |

DO module (Discrete Output)

Transmit discrete output values from the PROFIBUS master (class 1) to the measuring device. Discrete output values are used by the PROFIBUS master (class 1) to enable and disable device functions.

The DO module cyclically transmits the discrete output value, including the status, to the measuring device. The discrete output value is depicted in the first byte. The second byte contains standardized status information pertaining to the output value.

Five Discrete Output blocks are available (slot 17 to 21).

Assigned device functions

A device function is permanently assigned to the individual Discrete Output blocks.

| Function block | Device function | Values: control (meaning) |
|----------------|----------------------------------|---|
| DO 1 | Flow override | |
| DO 2 | Zero adjustment | 0 (disable device function) 1 (enable device function) |
| DO 3 | Start verification ¹⁾ | |

| Function block | Device function | Values: control (meaning) |
|----------------|-----------------------------|---|
| DO 4 | Relay output | 0 (non-conductive)1 (conductive) |
| DO 5 | Concentration ²⁾ | Assignment of medium type (see the following table) |

1) Only available with the Heartbeat Verification application package

2) Only available with the Concentration application package

| Assignment of medium type: function block DO 5 | | |
|--|-----------------------------|--|
| 101 | Fructose in water | |
| 102 | Glucose in water | |
| 104 | Hydrogen peroxide in water | |
| 105 | Sucrose in water | |
| 106 | Invert sugar in water | |
| 107 | Nitric acid | |
| 108 | Phosphoric acid | |
| 109 | Potassium hydroxide | |
| 100 | Off | |
| 110 | Sodium hydroxide | |
| 111 | Ethanol in water | |
| 112 | Methanol in water | |
| 113 | Ammonium nitrate in water | |
| 114 | Iron(III) chloride in water | |
| 115 | HFCS42 | |
| 116 | HFCS55 | |
| 117 | HFCS90 | |
| 118 | Original wort | |
| 119 | % mass / % volume | |
| 121 | Coef Set No. 1 | |
| 122 | Coef Set No. 2 | |
| 123 | Coef Set No. 3 | |
| 124 | Hydrochloric acid | |
| 125 | Sulfuric acid | |

Data structure

Output data of Discrete Output

| Byte 1 | Byte 2 |
|----------|--------|
| Discrete | Status |

EMPTY_MODULE module

This module is used to assign empty spaces arising from modules not being used in the slots .

The measuring device works as a modular PROFIBUS slave. In contrast to a compact slave, a modular PROFIBUS slave has a variable design and consists of several individual

modules. The GSD file contains a description of the individual modules along with their individual properties.

The modules are permanently assigned to the slots. When configuring the modules, it is absolutely essential to observe the sequence/arrangement of the modules. Any gaps between the configured modules must be filled with the EMPTY_MODULE.

10 Commissioning

10.1 Post-mounting and post-connection check

Before commissioning the device:

- Make sure that the post-installation and post-connection checks have been performed successfully.
- Checklist for "Post-installation" check→ 🗎 35
- Checklist for "Post-connection" check $\rightarrow \cong 64$

10.2 Switching on the measuring device

- Switch on the device upon successful completion of the post-mounting and postconnection check.
 - ← After a successful startup, the local display switches automatically from the startup display to the operational display.

If nothing appears on the local display or if a diagnostic message is displayed, refer to the section on "Diagnostics and troubleshooting" $\rightarrow \cong 171$.

10.3 Connecting via FieldCare

- For connecting FieldCare $\rightarrow \cong 87$
- For connecting via FieldCare $\rightarrow \cong 91$
- For user interface of FieldCare $\rightarrow \implies 91$

10.4 Configuring the device address via software

In the "Communication" submenu the device address can be set.

Navigation

"Setup" menu \rightarrow Communication \rightarrow Device address

10.4.1 **PROFIBUS** network

At time of delivery, the measuring device has the following factory setting:

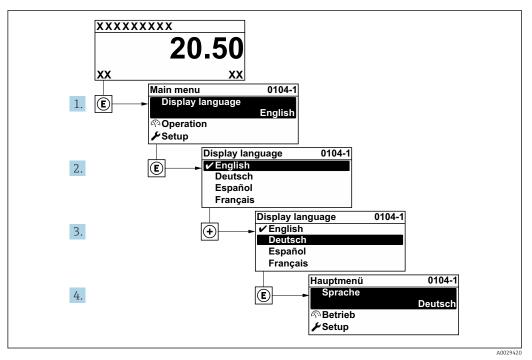
| Device address 126 |
|--------------------|
|--------------------|

• To display the current device address: **Device address** parameter $\rightarrow \implies 113$

• If hardware addressing is active, software addressing is blocked $\rightarrow \square 61$

10.5 Setting the operating language

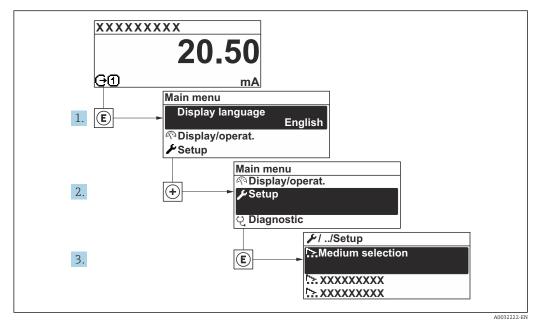
Factory setting: English or ordered local language



■ 33 Taking the example of the local display

10.6 Configuring the measuring instrument

The **Setup** menu with its guided wizards contains all the parameters needed for standard operation.



34 Navigation to "Setup" menu using the example of the local display

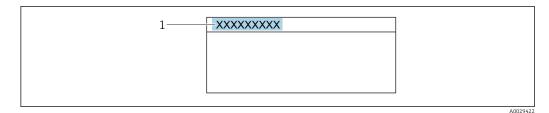
The number of submenus and parameters can vary depending on the device version. Certain submenus and parameters in these submenus are not described in the Operating Instructions. Instead a description is provided in the Special Documentation for the device ("Supplementary documentation").

Navigation "Setup" menu

| 🖌 Setup | | |
|---------|---|-------------|
| | Device tag | → 🖺 109 |
| | ► System units | → 🗎 109 |
| | ► Medium selection | → 🖺 112 |
| | ► Communication | → 🗎 113 |
| | ► Analog inputs | → 🖺 114 |
| | ► I/O configuration | → 🖺 115 |
| | ► Current input 1 to n | → 🖺 116 |
| | ► Status input 1 to n | → 🖺 117 |
| | ► Current output 1 to n | → 🖺 117 |
| | Pulse/frequency/switch output 1 to n | → 🗎 121 |
| | ► Relay output 1 to n | → 🗎 128 |
| | ► Display | → 🖺 130 |
| | ► Low flow cut off | → 🗎 133 |
| | ► Partially filled pipe detection | → 🗎 134 |
| | ► Advanced setup | → 🗎 135 |

10.6.1 Defining the tag name

To enable fast identification of the measuring point within the system, you can enter a unique designation using the **Device tag** parameter and thus change the factory setting.



- 35 Header of the operational display with tag name
- 1 Tag name

Enter the tag name in the "FieldCare" operating tool $\rightarrow \cong 91$

Navigation

"Setup" menu \rightarrow Device tag

Parameter overview with brief description

| Parameter | Description | User entry | Factory setting |
|------------|---|--|-----------------|
| Device tag | Enter the name for the measuring point. | Max. 32 characters, such as letters, numbers or special characters (e.g. @, %, /). | Promass 500 PA |

10.6.2 Setting the system units

In the **System units** submenu the units of all the measured values can be set.

The number of submenus and parameters can vary depending on the device version. Certain submenus and parameters in these submenus are not described in the Operating Instructions. Instead a description is provided in the Special Documentation for the device ("Supplementary documentation").

Navigation

"Setup" menu → System units

| ► System units | |
|--------------------------|------------|
| Mass flow unit | → 🗎 110 |
| Mass unit | → 🗎 110 |
| Volume flow unit | → 🗎 110 |
| Volume unit | → 🗎 110 |
| Corrected volume flow un | it → 🗎 110 |
| Corrected volume unit | → 🗎 110 |
| Density unit | → 🗎 110 |
| Reference density unit | → 🗎 110 |

| Temperature unit |] | → 🖺 111 |
|------------------|---|---------|
| Pressure unit | | → 🖺 111 |

| Parameter | Description | Selection | Factory setting |
|----------------------------|---|------------------|--|
| Mass flow unit | Select mass flow unit. <i>Effect</i> The selected unit applies to: • Output • Low flow cut off • Simulation process variable | Unit choose list | Country-specific: • kg/h • lb/min |
| Mass unit | Select mass unit. | Unit choose list | Country-specific: • kg • lb |
| Volume flow unit | Select volume flow unit. <i>Effect</i> The selected unit applies to: • Output • Low flow cut off • Simulation process variable | Unit choose list | Country-specific: • l/h • gal/min (us) |
| Volume unit | Select volume unit. | Unit choose list | Country-specific: • l • gal (us) |
| Corrected volume flow unit | Select corrected volume flow unit. <i>Effect</i> The selected unit applies to: Corrected volume flow parameter $(\rightarrow \cong 161)$ | Unit choose list | Country-specific: • Nl/h • Sft ³ /min |
| Corrected volume unit | Select corrected volume unit. | Unit choose list | Country-specific: • Nl • Sft ³ |
| Density unit | Select density unit. <i>Effect</i> The selected unit applies to: • Output • Simulation process variable • Density adjustment (Expert menu) | Unit choose list | Country-specific: • kg/l • lb/ft ³ |
| Reference density unit | Select reference density unit. | Unit choose list | Country-specific • kg/Nl • lb/Sft ³ |
| Density 2 unit | Select second density unit. | Unit choose list | Country-specific: • kg/l • lb/ft ³ |

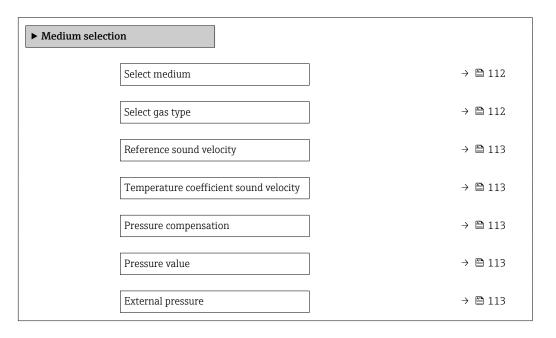
| Parameter | Description | Selection | Factory setting |
|------------------|--|------------------|---|
| Temperature unit | Select temperature unit. <i>Effect</i> The selected unit applies to: • Electronic temperature parameter (6053) • Maximum value parameter (6051) • Minimum value parameter (6052) • Maximum value parameter (6108) • Minimum value parameter (6109) • Maximum value parameter (6029) • Minimum value parameter (6030) • Reference temperature parameter (1816) • Temperature parameter | Unit choose list | Country-specific: • °C • °F |
| Pressure unit | Select process pressure unit. <i>Effect</i> The unit is taken from: Pressure value parameter (→ 🗎 113) External pressure parameter (→ 🖺 113) Pressure value | Unit choose list | Country-specific: • bar a • psi a |

10.6.3 Selecting and setting the medium

The **Select medium** wizard submenu contains parameters that must be configured in order to select and set the medium.

Navigation

"Setup" menu \rightarrow Medium selection



| Parameter | Prerequisite | Description | Selection / User entry / User interface |
|-----------------|--|--|--|
| Select medium | - | Use this function to select the type of medium: "Gas" or "Liquid". Select the "Other" option in exceptional cases in order to enter the properties of the medium manually (e.g. for highly compressive liquids such as sulfuric acid). | LiquidGas |
| Select gas type | In the Medium selection submenu, the Gas option is selected. | Select measured gas type. | Air Ammonia NH3 Argon Ar Sulfur hexafluoride SF6 Oxygen O2 Ozone O3 Nitrogen oxide NOX Nitrogen N2 Nitrous oxide N2O Methane CH4 Hydrogen H2 Helium He Hydrogen chloride HCI Hydrogen sulfide H2S Ethylene C2H4 Carbon dioxide CO2 Carbon monoxide CO Chlorine CI2 Butane C4H10 Propane C3H8 Propylene C3H6 Ethane C2H6 Others |

| Parameter | Prerequisite | Description | Selection / User entry / User interface |
|--|---|--|--|
| Reference sound velocity | In the Select gas type parameter, the Others option is selected. | Enter sound velocity of gas at 0 °C (32 °F). | 1 to 99 999.9999 m/s |
| Reference sound velocity | In the Select medium type parameter, the Others option is selected. | Enter sound velocity of gas at 0 °C (32 °F). | Signed floating-point number |
| Temperature coefficient sound velocity | In the Select gas type parameter, the Others option is selected. | Enter temperature coefficient for the gas sound velocity. | Positive floating point number |
| Temperature coefficient sound velocity | In the Select medium type parameter, the Others option is selected. | Enter temperature coefficient for the gas sound velocity. | Signed floating-point number |
| Pressure compensation | _ | Select pressure compensation type. | Off Fixed value External value Current input 1 * Current input 3 * |
| Pressure value | In the Pressure compensation parameter, the Fixed value option is selected. | Enter process pressure to be used for pressure correction. | Positive floating-point number |
| External pressure | In the Pressure compensation parameter, the External value option or the Current input 1n option is selected. | Shows the external process pressure value. | |

10.6.4 Configuring communication interface

The **Communication** submenu guides you systematically through all the parameters that have to be configured for selecting and setting the communication interface.

Navigation

"Setup" menu \rightarrow Communication

| ► Communication | |
|-----------------|---------|
| Device address | → 🗎 113 |

| Parameter | Description | User entry |
|----------------|-----------------------|------------|
| Device address | Enter device address. | 0 to 126 |

10.6.5 Configuration of the Analog Inputs

The **Analog inputs** submenu guides the user systematically to the individual **Analog input 1 to n** submenu. From here you get to the parameters of the individual analog input.

Navigation

"Setup" menu \rightarrow Analog inputs

| ► Analog inputs | | | |
|-----------------|--------------------|-----------------|---------|
| | ► Analog input 1 t | o n | |
| | | Channel | → 🗎 114 |
| | | PV filter time | → 🗎 114 |
| | | Fail safe type | → 🗎 115 |
| | | Fail-safe value | → 🗎 115 |

| Parameter | Prerequisite | Description | Selection / User entry |
|----------------|--------------|---|---|
| Channel | | Select the process variable. | Mass flow Volume flow Corrected volume flow* Density Reference density* Target mass flow Carrier mass flow* Concentration* Target volume flow* Carrier volume flow* Carrier corrected volume flow* Carrier corrected volume flow* Carrier corrected volume flow* Carrier corrected volume flow* Carrier pipe temperature Carrier pipe temperature* Electronic temperature Oscillation frequency 0 Frequency fluctuation 0* Oscillation damping fluctuation 0* Oscillation damping fluctuation 1* Signal asymmetry* Exciter current 0* Current input 1* |
| PV filter time | - | Specify the time to suppress signal peaks. During the specified time the Analog Input does not respond to an erratic increase in the process variable. | Positive floating-point number |

| Parameter | Prerequisite | Description | Selection / User entry |
|-----------------|--|---|--|
| Fail safe type | - | Select the failure mode. | Fail-safe valueFallback valueOff |
| Fail-safe value | In Fail safe type parameter, the Fail-safe value option is selected. | Specify the values to be output when an error occurs. | Signed floating-point number |

10.6.6 Displaying the I/O configuration

The **I/O configuration** submenu guides the user systematically through all the parameters in which the configuration of the I/O modules is displayed.

Navigation

"Setup" menu \rightarrow I/O configuration

| ► I/O configuration | |
|------------------------------------|---------|
| I/O module 1 to n terminal numbers | → 🗎 115 |
| I/O module 1 to n information | → 🗎 115 |
| I/O module 1 to n type | → 🗎 115 |
| Apply I/O configuration | → 🗎 115 |
| Alteration code | → 🗎 115 |

Parameter overview with brief description

| Parameter | Description | User interface / Selection / User entry |
|------------------------------------|---|--|
| I/O module 1 to n terminal numbers | Shows the terminal numbers used by the I/O module. | Not used 26-27 (I/O 1) 24-25 (I/O 2) |
| I/O module 1 to n information | Shows information of the plugged I/O module. | Not plugged Invalid Not configurable Configurable Profibus PA |
| I/O module 1 to n type | Shows the I/O module type. | Off Current output * Current input * Status input * Pulse/frequency/switch output * Double pulse output * Relay output * |
| Apply I/O configuration | Apply parameterization of the freely configurable I/O module. | NoYes |
| Alteration code | Enter the code in order to change the I/O configuration. | Positive integer |

* Visibility depends on order options or device settings

10.6.7 Configuring the current input

The **"Current input" wizard** guides the user systematically through all the parameters that have to be set for configuring the current input.

Navigation

"Setup" menu \rightarrow Current input

| ► Current input 1 to n | |
|------------------------|---------|
| Terminal number | → 🗎 116 |
| Signal mode | → 🗎 116 |
| 0/4 mA value | → 🗎 116 |
| 20 mA value | → 🗎 116 |
| Current span | → 🗎 116 |
| Failure mode | → 🗎 116 |
| Failure value | → 🗎 116 |

Parameter overview with brief description

| Parameter | Prerequisite | Description | User interface / Selection / User entry | Factory setting |
|-----------------|--|--|---|--|
| Terminal number | - | Shows the terminal numbers used by the current input module. | Not used 24-25 (I/O 2) 20-21 (I/O 4)* | - |
| Signal mode | The measuring device is not approved for use in the hazardous area with type of protection Ex-i. | Select the signal mode for the current input. | Passive Active * | Active |
| 0/4 mA value | - | Enter 4 mA value. | Signed floating-point number | - |
| 20 mA value | - | Enter 20 mA value. | Signed floating-point number | Depends on country and nominal diameter |
| Current span | - | Select current range for process value output and upper/lower level for alarm signal. | 420 mA 420 mA NAMUR 420 mA US 020 mA | Country-specific: • 420 mA NAMUR • 420 mA US |
| Failure mode | - | Define input behavior in alarm condition. | Alarm Last valid value Defined value | - |
| Failure value | In the Failure mode parameter, the Defined value option is selected. | Enter value to be used by the device if input value from external device is missing. | Signed floating-point number | - |

Visibility depends on order options or device settings

10.6.8 Configuring the status input

The **Status input** submenu guides the user systematically through all the parameters that have to be set for configuring the status input.

Navigation

"Setup" menu \rightarrow Status input 1 to n

| ► Status input 1 to n | |
|----------------------------|-----------|
| Assign status input | → 🗎 117 |
| Terminal number | → 🗎 117 |
| Active level |) → 🗎 117 |
| Terminal number |) → 🗎 117 |
| Response time status input |) → 🗎 117 |
| Terminal number |] → 🗎 117 |

Parameter overview with brief description

| Parameter | Description | Selection / User interface / User entry |
|----------------------------|--|---|
| Assign status input | Select function for the status input. | Off Reset totalizer 1 Reset totalizer 2 Reset totalizer 3 Reset all totalizers Flow override |
| Terminal number | Shows the terminal numbers used by the status input module. | Not used 24-25 (I/O 2) 20-21 (I/O 4)* |
| Active level | Define input signal level at which the assigned function is triggered. | HighLow |
| Response time status input | Define the minimum amount of time the input signal level must be present before the selected function is triggered. | 5 to 200 ms |

* Visibility depends on order options or device settings

10.6.9 Configuring the current output

The **Current output** wizard guides you systematically through all the parameters that have to be set for configuring the current output.

Navigation

"Setup" menu → Current output

| ► Current output 1 to n | | |
|-------------------------|--|---------|
| Terminal number | | → 🗎 118 |

| Signal mode | → 🗎 118 |
|------------------------------|---------|
| Assign current output 1 to n | → 🗎 119 |
| Current span | → 🖺 119 |
| 0/4 mA value | → 🗎 119 |
| 20 mA value | → 🗎 119 |
| Fixed current | → 🖺 119 |
| Damping output 1 to n | → 🗎 120 |
| Failure mode | → 🗎 120 |
| Failure current | → 🗎 120 |
| | / 🗏 120 |

| Parameter | Prerequisite | Description | User interface / Selection / User entry | Factory setting |
|-----------------|--------------|---|---|-----------------|
| Terminal number | - | Shows the terminal numbers used by the current output module. | Not used 24-25 (I/O 2) 20-21 (I/O 4)* | - |
| Signal mode | - | Select the signal mode for the current output. | Passive * Active * | Active |

| Parameter | Prerequisite | Description | User interface / Selection / User entry | Factory setting |
|------------------------------|--|--|---|--|
| Assign current output 1 to n | | Select process variable for current output. | Off* Mass flow Volume flow Corrected volume flow* Target mass flow* Carrier mass flow* Carrier volume flow* Carrier volume flow* Carrier corrected colume flow* Carrier corrected volume flow* Concentration* Temperature Carrier pipe temperature* Electronic temperature Oscillation frequency 0 Oscillation amplitude 0* Frequency fluctuation 0 Oscillation damping o* Oscillation damping fluctuation 0 Signal asymmetry* Exciter current 0* HBSI* Pressure* | |
| Current span | - | Select current range for process value output and upper/lower level for alarm signal. | 420 mA NAMUR 420 mA US 420 mA 020 mA Fixed current | Depends on country: • 420 mA NAMUR • 420 mA US |
| 0/4 mA value | In Current span parameter (→ 🖹 119), one of the following options is selected: • 420 mA NAMUR • 420 mA US • 420 mA • 020 mA | Enter 4 mA value. | Signed floating-point number | Depends on country: • 0 kg/h • 0 lb/min |
| 20 mA value | In Current span parameter (→ 🗎 119), one of the following options is selected: • 420 mA NAMUR • 420 mA US • 420 mA • 020 mA | Enter 20 mA value. | Signed floating-point number | Depends on country and nominal diameter |
| Fixed current | The Fixed current option is selected in the Current span parameter ($\rightarrow \square$ 119). | Defines the fixed output current. | 0 to 22.5 mA | 22.5 mA |

| Parameter | Prerequisite | Description | User interface / Selection / User entry | Factory setting |
|-----------------------|---|--|---|-----------------|
| Damping output 1 to n | A process variable is selected in the Assign current output parameter ($\rightarrow \boxdot 119$) and one of the following options is selected in the Current span parameter ($\rightarrow \boxdot 119$): • 420 mA NAMUR • 420 mA US • 420 mA • 020 mA | Set reaction time for output signal to fluctuations in the measured value. | 0.0 to 999.9 s | - |
| Failure mode | A process variable is selected in the Assign current output parameter ($\rightarrow \boxdot 119$) and one of the following options is selected in the Current span parameter ($\rightarrow \boxdot 119$): • 420 mA NAMUR • 420 mA US • 420 mA • 020 mA | Define output behavior in alarm condition. | Min. Max. Last valid value Actual value Defined value | - |
| Failure current | The Defined value option is selected in the Failure mode parameter. | Enter current output value in alarm condition. | 0 to 22.5 mA | 22.5 mA |

10.6.10 Configuring the pulse/frequency/switch output

The **Pulse/frequency/switch output** wizard guides you systematically through all the parameters that can be set for configuring the selected output type.

Navigation

"Setup" menu \rightarrow Advanced setup \rightarrow Pulse/frequency/switch output



Parameter overview with brief description

| Parameter | Description | Selection |
|----------------|---|--|
| Operating mode | Define the output as a pulse, frequency or switch output. | PulseFrequencySwitch |

Configuring the pulse output

Navigation

"Setup" menu \rightarrow Pulse/frequency/switch output

| Pulse/frequency/switch output 1 to n | |
|--|-----------|
| Operating mode |) → 🗎 122 |
| Terminal number |] → 🗎 122 |
| Signal mode |) → 🗎 122 |
| Assign pulse output |) → 🗎 122 |
| Pulse scaling |) → 🗎 122 |
| Pulse width |) → 🗎 122 |
| Failure mode | → 🗎 122 |
| Invert output signal |] → 🗎 122 |

| Parameter overview | with | brief | description |
|--------------------|------|-------|-------------|
|--------------------|------|-------|-------------|

| Parameter | Prerequisite | Description | Selection / User interface / User entry | Factory setting |
|----------------------------|---|---|--|---|
| Operating mode | - | Define the output as a pulse, frequency or switch output. | PulseFrequencySwitch | - |
| Terminal number | - | Shows the terminal numbers used by the PFS output module. | Not used 24-25 (I/O 2) 20-21 (I/O 4)* | - |
| Signal mode | - | Select the signal mode for the PFS output. | PassiveActive | - |
| Assign pulse output 1 to n | The Pulse option is selected in Operating mode parameter. | Select process variable for pulse output. | Off Mass flow Volume flow Corrected volume flow* Target mass flow* Carrier mass flow* Target volume flow* Carrier volume flow* Target corrected volume flow* Carrier corrected volume flow* | - |
| Value per pulse | The Pulse option is selected in the Operating mode parameter ($\rightarrow \bowtie$ 121) and a process variable is selected in the Assign pulse output parameter ($\rightarrow \bowtie$ 122). | Enter measured value at which a pulse is output. | Positive floating point number | Depends on country and nominal diameter |
| Pulse width | The Pulse option is selected in the Operating mode parameter ($\rightarrow \bowtie$ 121) and a process variable is selected in the Assign pulse output parameter ($\rightarrow \bowtie$ 122). | Define time width of the output pulse. | 0.05 to 2 000 ms | - |
| Failure mode | The Pulse option is selected in the Operating mode parameter ($\rightarrow \cong 121$) and a process variable is selected in the Assign pulse output parameter ($\rightarrow \cong 122$). | Define output behavior in alarm condition. | Actual valueNo pulses | - |
| Invert output signal | - | Invert the output signal. | • No • Yes | - |

Configuring the frequency output

Navigation

"Setup" menu \rightarrow Pulse/frequency/switch output

| Pulse/frequency/switch output 1 to n | | |
|---|--|---------|
| Operating mode | | → 🗎 123 |

| Terminal number | | → 🗎 123 |
|--------------------------------------|---|---------|
| Signal mode |] | → 🗎 123 |
| Assign frequency output | | → 🗎 124 |
| Minimum frequency value |] | → 🗎 124 |
| Maximum frequency value | | → 🗎 124 |
| Measuring value at minimum frequency | | → 🗎 124 |
| |] | → 🗎 125 |
| Measuring value at maximum frequency | | 7 🗏 125 |
| Failure mode | | → 🗎 125 |
| Failure frequency | | → 🗎 125 |
| Invert output signal | | → 🗎 125 |

| Parameter | Prerequisite | Description | Selection / User interface / User entry | Factory setting |
|-----------------|--------------|---|---|-----------------|
| Operating mode | - | Define the output as a pulse, frequency or switch output. | PulseFrequencySwitch | - |
| Terminal number | - | Shows the terminal numbers used by the PFS output module. | Not used 24-25 (I/O 2) 20-21 (I/O 4)* | - |
| Signal mode | - | Select the signal mode for the PFS output. | PassiveActive | - |

| Parameter | Prerequisite | Description | Selection / User interface / User entry | Factory setting |
|---|--|--|---|---|
| Assign frequency output | The Frequency option is selected in Operating mode parameter (→ 🗎 121). | Select process variable for frequency output. | Off Mass flow Volume flow Corrected volume flow* Density Reference density* Temperature Pressure Concentration* Target mass flow* Carrier mass flow* Carrier volume flow* Carrier volume flow* Carrier corrected volume flow* Garrier corrected volume flow* Garrier corrected volume flow* Garrier corrected volume flow* HBSI* Exciter current 0 Oscillation damping 0 Oscillation n* Oscillation frequency 0 Frequency fluctuation 0* Oscillation amplitude 0* Signal asymmetry Carrier pipe temperature* Electronic temperature | |
| Minimum frequency value | The Frequency option is selected in the Operating mode parameter ($\rightarrow \supseteq 121$) and a process variable is selected in the Assign frequency output parameter ($\rightarrow \supseteq 124$). | Enter minimum frequency. | 0.0 to 10 000.0 Hz | - |
| Maximum frequency value | The Frequency option is selected in the Operating mode parameter ($\rightarrow \implies 121$) and a process variable is selected in the Assign frequency output parameter ($\rightarrow \implies 124$). | Enter maximum frequency. | 0.0 to 10000.0 Hz | - |
| Measuring value at minimum frequency | The Frequency option is selected in the Operating mode parameter ($\rightarrow \supseteq 121$) and a process variable is selected in the Assign frequency output parameter ($\rightarrow \supseteq 124$). | Enter measured value for minmum frequency. | Signed floating-point number | Depends on country and nominal diameter |

| Parameter | Prerequisite | Description | Selection / User interface / User entry | Factory setting |
|---|--|---|---|---|
| Measuring value at maximum frequency | The Frequency option is selected in the Operating mode parameter ($\rightarrow \supseteq 121$) and a process variable is selected in the Assign frequency output parameter ($\rightarrow \supseteq 124$). | Enter measured value for maximum frequency. | Signed floating-point number | Depends on country and nominal diameter |
| Failure mode | The Frequency option is selected in the Operating mode parameter ($\rightarrow \boxminus 121$) and a process variable is selected in the Assign frequency output parameter ($\rightarrow \boxminus 124$). | Define output behavior in alarm condition. | Actual valueDefined value0 Hz | - |
| Failure frequency | In the Operating mode parameter ($\rightarrow \square$ 121), the Frequency option is selected, in the Assign frequency output parameter ($\rightarrow \square$ 124) a process variable is selected, and in the Failure mode parameter, the Defined value option is selected. | Enter frequency output value in alarm condition. | 0.0 to 12 500.0 Hz | - |
| Invert output signal | - | Invert the output signal. | NoYes | - |

Configuring the switch output

Navigation

"Setup" menu \rightarrow Pulse/frequency/switch output

| Pulse/frequency/switch output 1 to n | |
|---|-----------|
| Operating mode |] → 🗎 126 |
| Terminal number |] → 🗎 126 |
| Signal mode |] → 🗎 126 |
| Switch output function |] → 🗎 127 |
| Assign diagnostic behavior |] → 🗎 127 |
| Assign limit |] → 🗎 127 |
| Assign flow direction check |] → 🗎 127 |
| Assign status |] → 🗎 127 |
| Switch-on value |] → 🗎 127 |
| Switch-off value |] → 🗎 128 |
| Switch-on delay | → 🗎 128 |
| Switch-off delay | → 🗎 128 |
| Failure mode | → 🗎 128 |
| Invert output signal |] → 🗎 128 |

| Parameter | Prerequisite | Description | Selection / User interface / User entry | Factory setting |
|-----------------|--------------|---|---|-----------------|
| Operating mode | - | Define the output as a pulse, frequency or switch output. | PulseFrequencySwitch | - |
| Terminal number | - | Shows the terminal numbers used by the PFS output module. | Not used 24-25 (I/O 2) 20-21 (I/O 4)* | - |
| Signal mode | - | Select the signal mode for the PFS output. | PassiveActive | - |

| Parameter | Prerequisite | Description | Selection / User interface / User entry | Factory setting |
|-----------------------------|---|--|--|---|
| Switch output function | The Switch option is selected in the Operating mode parameter. | Select function for switch output. | Off On Diagnostic behavior Limit Flow direction check Status | - |
| Assign diagnostic behavior | In the Operating mode parameter, the Switch option is selected. In the Switch output function parameter, the Diagnostic behavior option is selected. | Select diagnostic behavior for switch output. | AlarmAlarm or warningWarning | - |
| Assign limit | The Switch option is selected in Operating mode parameter. The Limit option is selected in Switch output function parameter. | Select process variable for limit function. | Mass flow Volume flow Corrected volume flow* Target mass flow* Carrier mass flow* Target volume flow* Carrier volume flow* Carrier corrected volume flow* Target corrected volume flow* Target corrected volume flow* Target corrected volume flow* Carrier correc | - |
| Assign flow direction check | The Switch option is selected in the Operating mode parameter. The Flow direction check option is selected in the Switch output function parameter. | Select process variable for flow direction monitoring. | | - |
| Assign status | The Switch option is selected in Operating mode parameter. The Status option is selected in Switch output function parameter. | Select device status for switch output. | Partially filled pipe detection Low flow cut off Digital output 4[*] | - |
| Switch-on value | The Switch option is selected in the Operating mode parameter. The Limit option is selected in the Switch output function parameter. | Enter measured value for the switch-on point. | Signed floating-point number | Depends on country: • 0 kg/h • 0 lb/min |

| Parameter | Prerequisite | Description | Selection / User interface / User entry | Factory setting |
|----------------------|---|--|---|---|
| Switch-off value | The Switch option is selected in the Operating mode parameter. The Limit option is selected in the Switch output function parameter. | Enter measured value for the switch-off point. | Signed floating-point number | Depends on country: • 0 kg/h • 0 lb/min |
| Switch-on delay | The Switch option is selected in the Operating mode parameter. The Limit option is selected in the Switch output function parameter. | Define delay for the switch-on of status output. | 0.0 to 100.0 s | - |
| Switch-off delay | The Switch option is selected in the Operating mode parameter. The Limit option is selected in the Switch output function parameter. | Define delay for the switch-off of status output. | 0.0 to 100.0 s | - |
| Failure mode | - | Define output behavior in alarm condition. | Actual statusOpenClosed | - |
| Invert output signal | - | Invert the output signal. | NoYes | - |

10.6.11 Configuring the relay output

The **Relay output** wizard guides the user systematically through all the parameters that have to be set for configuring the relay output.

Navigation

"Setup" menu \rightarrow Relay output 1 to n

| ► Relay output 1 to n | |
|-----------------------------|-----------|
| Terminal number | → 🗎 129 |
| Relay output function |) → 🗎 129 |
| Assign flow direction check |) → 🗎 129 |
| Assign limit | → 🗎 129 |
| Assign diagnostic behavior |) → 🗎 129 |
| Assign status | → 🗎 129 |
| Switch-off value | → 🗎 130 |
| Switch-off delay |) → 🗎 130 |

| Switch-on value |) → 🗎 130 |
|------------------------|-----------|
| Switch-on delay |) → 🗎 130 |
| Failure mode |) → 🗎 130 |
| Switch status | → 🗎 130 |
| Powerless relay status | → 🗎 130 |

| Parameter | Prerequisite | Description | User interface / Selection / User entry | Factory setting |
|-----------------------------|--|---|--|-----------------|
| Terminal number | - | Shows the terminal numbers used by the relay output module. | Not used 24-25 (I/O 2) | - |
| Relay output function | - | Select the function for the relay output. | Closed Open Diagnostic behavior Limit Flow direction check Digital Output | _ |
| Assign flow direction check | The Flow direction check option is selected in the Relay output function parameter. | Select process variable for flow direction monitoring. | | - |
| Assign limit | The Limit option is selected in Relay output function parameter. | Select process variable for limit function. | Mass flow Volume flow Corrected volume flow* Target mass flow* Carrier mass flow* Target volume flow* Carrier volume flow* Carrier corrected volume flow* Concentration* Temperature Oscillation damping Pressure Totalizer 1 Totalizer 3 | _ |
| Assign diagnostic behavior | In the Relay output function parameter, the Diagnostic behavior option is selected. | Select diagnostic behavior for switch output. | AlarmAlarm or warningWarning | - |
| Assign status | In the Relay output function parameter, the Digital Output option is selected. | Select device status for switch output. | Partially filled pipe detection Low flow cut off Digital output 4[*] | - |

| Parameter | Prerequisite | Description | User interface / Selection / User entry | Factory setting |
|------------------------|---|---|---|---|
| Switch-off value | The Limit option is selected in the Relay output function parameter. | Enter measured value for the switch-off point. | Signed floating-point number | Depends on country: • 0 kg/h • 0 lb/min |
| Switch-off delay | In the Relay output function parameter, the Limit option is selected. | Define delay for the switch-off of status output. | 0.0 to 100.0 s | - |
| Switch-on value | The Limit option is selected in the Relay output function parameter. | Enter measured value for the switch-on point. | Signed floating-point number | Depends on country: • 0 kg/h • 0 lb/min |
| Switch-on delay | In the Relay output function parameter, the Limit option is selected. | Define delay for the switch-on of status output. | 0.0 to 100.0 s | - |
| Failure mode | - | Define output behavior in alarm condition. | Actual statusOpenClosed | - |
| Switch status | - | Shows the current relay switch status. | Open Closed | - |
| Powerless relay status | - | | Open Closed | - |

10.6.12 Configuring the local display

The **Display** wizard guides you systematically through all the parameters that can configured for configuring the local display.

Navigation

"Setup" menu \rightarrow Display

| ► Display | |
|-----------------------|---------|
| Format display | → 🗎 131 |
| Value 1 display | → 🗎 131 |
| 0% bargraph value 1 | → 🗎 131 |
| 100% bargraph value 1 | → 🗎 131 |
| Value 2 display | → 🗎 131 |
| Value 3 display | → 🗎 132 |
| 0% bargraph value 3 | → 🗎 132 |
| 100% bargraph value 3 | → 🗎 132 |
| Value 4 display | → 🗎 132 |

| Parameter | Prerequisite | Description | Selection / User entry | Factory setting |
|-----------------------|------------------------------|--|--|---|
| Format display | A local display is provided. | Select how measured values are shown on the display. | 1 value, max. size 1 bargraph + 1 value 2 values 1 value large + 2 values 4 values | - |
| Value 1 display | A local display is provided. | Select the measured value that is shown on the local display. | Mass flow Volume flow Corrected volume flow* Density Reference density* Temperature Current output 1* Current output 2* Current output 4* Pressure Totalizer 1 Totalizer 2 Totalizer 3 Concentration* Target mass flow* Carrier mass flow* Carrier volume flow* Carrier corrected volume flow* Carrier corrected volume flow* Carrier corrected volume flow* Carrier corrected volume flow* Carrier current 0 Oscillation damping 0 Oscillation frequency 0 Frequency fluctuation 0* Oscillation amplitude 0* Signal asymmetry Carrier output 1* Current output 2* Current output 3 | |
| 0% bargraph value 1 | A local display is provided. | Enter 0% value for bar graph display. | Signed floating-point number | Country-specific: • 0 kg/h • 0 lb/min |
| 100% bargraph value 1 | A local display is provided. | Enter 100% value for bar graph display. | Signed floating-point number | Depends on country and nominal diameter |
| Value 2 display | A local display is provided. | Select the measured value that is shown on the local display. | For the picklist, see Value 1 display parameter $(\rightarrow \cong 131)$ | _ |

| Parameter | Prerequisite | Description | Selection / User entry | Factory setting |
|-----------------------|---|---|---|---|
| Value 3 display | A local display is provided. | Select the measured value that is shown on the local display. | For the picklist, see Value 1 display parameter $(\rightarrow \cong 131)$ | - |
| 0% bargraph value 3 | A selection was made in the Value 3 display parameter. | Enter 0% value for bar graph display. | Signed floating-point number | Country-specific: • 0 kg/h • 0 lb/min |
| 100% bargraph value 3 | A selection was made in the Value 3 display parameter. | Enter 100% value for bar graph display. | Signed floating-point number | - |
| Value 4 display | A local display is provided. | Select the measured value that is shown on the local display. | For the picklist, see Value 1 display parameter $(\rightarrow \cong 131)$ | - |
| Value 5 display | A local display is provided. | Select the measured value that is shown on the local display. | For the picklist, see Value 1 display parameter $(\rightarrow \square 131)$ | - |
| Value 6 display | A local display is provided. | Select the measured value that is shown on the local display. | For the picklist, see Value 1 display parameter $(\rightarrow \square 131)$ | - |
| Value 7 display | A local display is provided. | Select the measured value that is shown on the local display. | For the picklist, see Value 1 display parameter $(\rightarrow \square 131)$ | - |
| Value 8 display | A local display is provided. | Select the measured value that is shown on the local display. | For the picklist, see Value 1 display parameter $(\rightarrow \cong 131)$ | - |

10.6.13 Configuring the low flow cut off

The **Low flow cut off** wizard systematically guides the user through all the parameters that must be set to configure low flow cut off.

Navigation

"Setup" menu \rightarrow Low flow cut off

| ► Low flow cut off | |
|----------------------------|-----------|
| Assign process variable |) → 🗎 133 |
| On value low flow cutoff |) → 🗎 133 |
| Off value low flow cutoff |) → 🗎 133 |
| Pressure shock suppression |) → 🗎 133 |

Parameter overview with brief description

| Parameter | Prerequisite | Description | Selection / User entry | Factory setting |
|----------------------------|---|--|--|---|
| Assign process variable | - | Select process variable for low flow cut off. | Off Mass flow Volume flow Corrected volume flow * | - |
| On value low flow cutoff | A process variable is selected in the Assign process variable parameter ($\rightarrow \bigoplus 133$). | Enter on value for low flow cut off. | Positive floating- point number | Depends on country and nominal diameter |
| Off value low flow cutoff | A process variable is selected in the Assign process variable parameter ($\rightarrow \cong 133$). | Enter off value for low flow cut off. | 0 to 100.0 % | - |
| Pressure shock suppression | A process variable is selected in the Assign process variable parameter ($\rightarrow \square$ 133). | Enter time frame for signal suppression (= active pressure shock suppression). | 0 to 100 s | - |

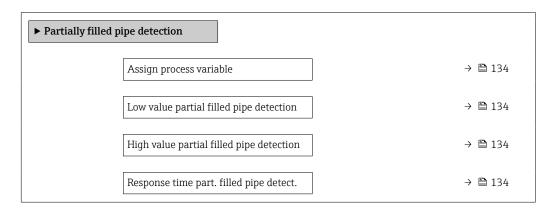
* Visibility depends on order options or device settings

10.6.14 Configuring partially filled pipe detection

The **Partial filled pipe detection** wizard guides you systematically through all parameters that have to be set for configuring the monitoring of the pipe filling.

Navigation

"Setup" menu \rightarrow Partially filled pipe detection

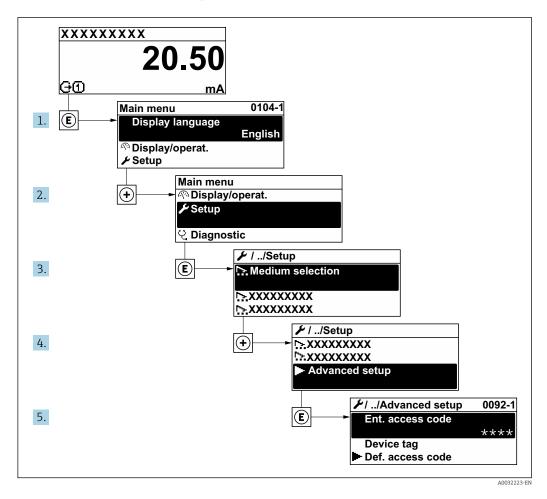


| Parameter | Prerequisite | Description | Selection / User entry | Factory setting |
|--|--|--|--|---|
| Assign process variable | - | Select process variable for partially filled pipe detection. | Off Density Reference density | Density |
| Low value partial filled pipe detection | A process variable is selected in the Assign process variable parameter ($\rightarrow \square$ 134). | Enter lower limit value for deactivating partialy filled pipe detection. | Signed floating-point number | Depends on country: • 200 kg/m ³ • 12.5 lb/ft ³ |
| High value partial filled pipe detection | A process variable is selected in the Assign process variable parameter ($\rightarrow \square$ 134). | Enter upper limit value for deactivating partialy filled pipe detection. | Signed floating-point number | Depends on country: • 6000 kg/m ³ • 374.6 lb/ft ³ |
| Response time part. filled pipe detect. | A process variable is selected in the Assign process variable parameter ($\rightarrow \square$ 134). | Use this function to enter the minimum time (hold time) the signal must be present before diagnostic message S962 "Pipe only partly filled" is triggered in the event of a partially filled or empty measuring pipe. | 0 to 100 s | - |

10.7 Advanced settings

The **Advanced setup** submenu with its submenus contains parameters for specific settings.

Navigation to the "Advanced setup" submenu



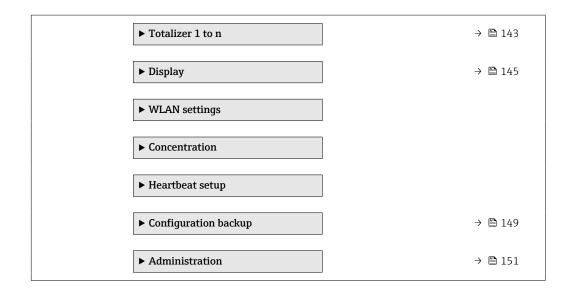
The number of submenus and parameters can vary depending on the device version and the available application packages. These submenus and their parameters are explained in the Special Documentation for the device and not in Operating Instructions.

For detailed information on the parameter descriptions for application packages: Special Documentation for the device $\rightarrow \cong 279$

Navigation

"Setup" menu \rightarrow Advanced setup

| ► Advanced setup | |
|---------------------|---|
| Enter access code | |
| ► Calculated values | → ¹ ³⁶ ¹³⁶ ¹ |
| ► Sensor adjustment | → 137 |

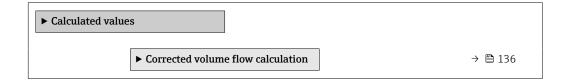


10.7.1 Calculated process variables

The **Calculated values** submenu contains parameters for calculating the corrected volume flow.

Navigation

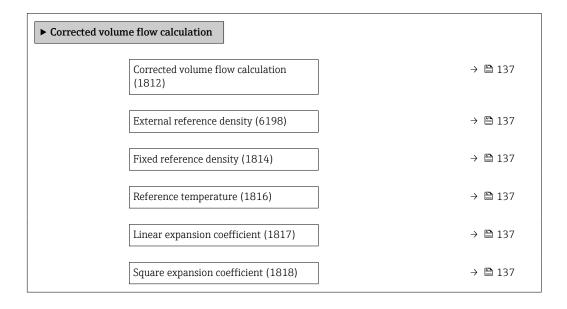
"Setup" menu \rightarrow Advanced setup \rightarrow Calculated values



"Corrected volume flow calculation" submenu

Navigation

"Setup" menu \rightarrow Advanced setup \rightarrow Calculated values \rightarrow Corrected volume flow calculation



| Parameter | Prerequisite | Description | Selection / User interface / User entry | Factory setting |
|-----------------------------------|---|---|---|---|
| Corrected volume flow calculation | - | Select reference density for calculating the corrected volume flow. | Fixed reference density Calculated reference density External reference density Current input 1 * Current input 3 * | - |
| External reference density | - | Shows external reference density. | Floating point number with sign | - |
| Fixed reference density | The Fixed reference density option is selected in the Corrected volume flow calculation parameter parameter. | Enter fixed value for reference density. | Positive floating- point number | - |
| Reference temperature | The Calculated reference density option is selected in the Corrected volume flow calculation parameter parameter. | Enter reference temperature for calculating the reference density. | -273.15 to 99999 °C | Country-specific: • +20 °C • +68 °F |
| Linear expansion coefficient | The Calculated reference density option is selected in the Corrected volume flow calculation parameter parameter. | Enter linear, medium-specific expansion coefficient for calculating the reference density. | Signed floating-point number | - |
| Square expansion coefficient | The Calculated reference density option is selected in the Corrected volume flow calculation parameter parameter. | For media with a non-linear expansion pattern: enter the quadratic, medium-specific expansion coefficient for calculating the reference density. | Signed floating-point number | - |

* Visibility depends on order options or device settings

10.7.2 Carrying out a sensor adjustment

The **Sensor adjustment** submenu contains parameters that pertain to the functionality of the sensor.

Navigation

"Setup" menu \rightarrow Advanced setup \rightarrow Sensor adjustment

| ► Sensor adjustment | |
|------------------------|-----------|
| Installation direction |) → 🗎 138 |
| ► Density adjustment |] |
| ► Zero verification |) → 🗎 141 |
| ► Zero adjustment | → 🗎 142 |

| Parameter | Description | Selection |
|------------------------|---|--|
| Installation direction | Set sign of flow direction to match the direction of the arrow on the sensor. | Flow in arrow directionFlow against arrow direction |

Density adjustment

With density adjustment, a high level of accuracy is achieved only at the point of adjustment and at the relevant density and temperature. However, the accuracy of a density adjustment is only ever as good as the quality of the reference measuring data provided. Therefore it is not a substitute for special density calibration.

Performing density adjustment

- Note the following before performing the adjustment:
 - A density adjustment only makes sense if there is little variation in the operating conditions and the density adjustment is performed under the operating conditions.
 - The density adjustment scales the internally computed density value with a userspecific slope and offset.
 - A 1-point or 2-point density adjustment can be performed.
 - For a 2-point density adjustment, there must be a difference of at least 0.2 kg/l between the two target density values.
 - The reference media must be gas-free or pressurized so that any gas they contain is compressed.
 - The reference density measurements must be performed at the same medium temperature that prevails in the process, as otherwise the density adjustment will not be accurate.
 - The correction resulting from the density adjustment can be deleted with the **Restore original** option.

"1 point adjustment" option

- 1. In the **Density adjustment mode** parameter, select the **1 point adjustment** option and confirm.
- 2. In the **Density setpoint 1** parameter, enter the density value and confirm.
 - In the Execute density adjustment parameter the following options are now available:

Ok **Measure density 1** option Restore original

- 3. Select the **Measure density 1** option and confirm.
- 4. If 100% was reached in the **Progress** parameter on the display and the **Ok** option is displayed in the **Execute density adjustment** parameter, then confirm.
 - In the Execute density adjustment parameter the following options are now available:
 - Ok Calculate
 - Cancel

5. Select the **Calculate** option and confirm.

If the adjustment was completed successfully, the **Density adjustment factor** parameter and the **Density adjustment offset** parameter and the values calculated for them are shown on the display.

"2 point adjustment" option

1. In the **Density adjustment mode** parameter, select the **2 point adjustment** option and confirm.

- 2. In the **Density setpoint 1** parameter, enter the density value and confirm.
- 3. In the **Density setpoint 2** parameter, enter the density value and confirm.
 - In the Execute density adjustment parameter the following options are now available:

Ok Measure density 1 Restore original

- 4. Select the **Measure density 1** option and confirm.
 - In the Execute density adjustment parameter the following options are now available:
 Ok

Measure density 2 Restore original

- 5. Select the **Measure density 2** option and confirm.
 - In the Execute density adjustment parameter the following options are now available:
 - Ok Calculate
 - Cancel

6. Select the **Calculate** option and confirm.

If the **Density adjust failure** option is displayed in the **Execute density adjustment** parameter, call up the options and select the **Cancel** option. The density adjustment is canceled and can be repeated.

If the adjustment was completed successfully, the **Density adjustment factor** parameter and the **Density adjustment offset** parameter and the values calculated for them are shown on the display.

Navigation

"Expert" menu → Sensor → Sensor adjustment → Density adjustment

| ► Density adjustment | |
|----------------------------|-----------|
| Density adjustment mode |) → 🗎 140 |
| Density setpoint 1 | → 🗎 140 |
| Density setpoint 2 | → 🗎 140 |
| Execute density adjustment | → 🗎 140 |
| Progress | → 🗎 140 |
| Density adjustment factor | → 🗎 140 |
| Density adjustment offset | → 🗎 140 |

_

| | i arameter överview with | brief description | |
|-------|--------------------------|-------------------|------|
| neter | Prerequisite | Description | Sele |

Daramotor overview with brief description

| Parameter | Prerequisite | Description | Selection / User entry / User interface | Factory setting |
|----------------------------|--|------------------------------------|---|-----------------|
| Density adjustment mode | - | | 1 point adjustment 2 point adjustment | - |
| Density setpoint 1 | - | | The entry depends on – the unit selected in the Density unit parameter (0555). | |
| Density setpoint 2 | In the Density adjustment mode parameter, the 2 point adjustment option is selected. | | The entry depends on the unit selected in the Density unit parameter (0555). | - |
| Execute density adjustment | _ | | Cancel[*] Busy[*] Ok[*] Density adjust failure[*] Measure density 1[*] Measure density 2[*] Calculate[*] Restore original[*] | _ |
| Progress | - | Shows the progress of the process. | 0 to 100 % | - |
| Density adjustment factor | - | | Signed floating-point number | - |
| Density adjustment offset | - | | Signed floating-point number | - |

Visibility depends on order options or device settings

Zero verification and zero adjustment

All measuring instruments are calibrated in accordance with state-of-the-art technology. Calibration takes place under reference conditions $\rightarrow \square$ 260. Therefore, a zero adjustment in the field is generally not required.

Experience shows that zero adjustment is advisable only in special cases:

- To achieve maximum measurement accuracy even with low flow rates.
- Under extreme process or operating conditions (e.g. very high process temperatures or very high-viscosity fluids).
- For gas applications with low pressure

To achieve the highest possible measurement accuracy at low flow rates, the installation must protect the sensor from mechanical stresses during operation.

To get a representative zero point, ensure that:

- any flow in the device is prevented during the adjustment
- the process conditions (e.g. pressure, temperature) are stable and representative

Zero verification and zero adjustment cannot be performed if the following process conditions are present:

• Gas pockets Ensure that the system has been sufficiently flushed with the medium. Repeat flushing can help to eliminate gas pockets

- Thermal circulation In the event of temperature differences (e.g. between the measuring tube inlet and outlet section), induced flow can occur even if the valves are closed due to thermal circulation in the device
- Leaks at the valves
 - If the valves are not leak-tight, flow is not sufficiently prevented when determining the zero point

If these conditions cannot be avoided, it is advisable to keep the factory setting for the zero point.

Zero point verification

The zero point can be verified with the **Zero verification** wizard.

Navigation

"Setup" menu \rightarrow Advanced setup \rightarrow Sensor adjustment \rightarrow Zero verification

| ► Zero verification | 1 | |
|---------------------|-------------------------------|---------|
| | Process conditions | → 🗎 141 |
| | Progress | → 🗎 141 |
| | Status | → 🗎 142 |
| | Additional information | → 🗎 142 |
| | Recommendation: | → 🗎 142 |
| | Root cause | → 🗎 142 |
| | Abort cause | → 🗎 142 |
| | Zero point measured | → 🗎 142 |
| | Zero point standard deviation | → 🗎 142 |

| Parameter | Description | Selection / User interface | Factory setting |
|--------------------|---------------------------------------|--|-----------------|
| Process conditions | Ensure process conditions as follows. | Tubes are completely filled Process operational pressure applied No-flow conditions (closed valves) Process and ambient temperatures stable | - |
| Progress | Shows the progress of the process. | 0 to 100 % | - |

| Parameter | Description | Selection / User interface | Factory setting |
|-------------------------------|--|---|-----------------|
| Zero point adjustment status | | BusyZero point adjust failureOk | - |
| Additional information | Indicate whether to display additional information. | HideShow | - |
| Recommendation: | Indicates whether an adjustment is recommended. Only recommended if the measured zero point deviates significantly from the current zero point. | Do not adjust zero pointAdjust zero point | - |
| Abort cause | Indicates why the wizard was aborted. | Check process conditions!A technical issue has occurred | - |
| Root cause | Shows the diagnostic and remedy. | Zero point too high. Ensure no-flow. Zero point is unstable. Ensure no-flow. Fluctuation high. Avoid 2- phase medium. | - |
| Zero point measured | Shows the zero point measured for the adjustment. | Signed floating-point number | - |
| Zero point standard deviation | Shows the standard deviation of the zero point measured. | Positive floating-point number | - |

Zero adjust

The zero point can be adjusted with the **Zero adjustment** wizard.

- A zero point verification should be performed before a zero adjustment.
 - The zero point can also be adjusted manually: Expert \rightarrow Sensor \rightarrow Calibration

Navigation

"Setup" menu \rightarrow Advanced setup \rightarrow Sensor adjustment \rightarrow Zero adjustment

| ► Zero adjustment | |
|------------------------------------|-----------|
| Process conditions |] → 🗎 143 |
| Progress |) → 🗎 143 |
| Status |) → 🗎 143 |
| Root cause |) → 🗎 143 |
| Abort cause |) → 🗎 143 |
| Root cause |) → 🗎 143 |
| Reliability of measured zero point | → 🗎 143 |
| Additional information |) → 🗎 143 |
| Reliability of measured zero point |) → 🗎 143 |

| Z | Zero point measured | | 143 |
|---|-------------------------------|---|-------|
| Z | Zero point standard deviation | ÷ | 🗎 143 |
| S | elect action | ÷ | 🖺 143 |

| Parameter | Description | Selection / User interface | Factory setting |
|--|---|--|-----------------|
| Process conditions | Ensure process conditions as follows. | Tubes are completely filled Process operational pressure applied No-flow conditions (closed valves) Process and ambient temperatures stable | - |
| Progress | Shows the progress of the process. | 0 to 100 % | - |
| Zero point adjustment status | | Busy Zero point adjust failure Ok | - |
| Abort cause | Indicates why the wizard was aborted. | Check process conditions! A technical issue has occurred | - |
| Root cause | Shows the diagnostic and remedy. | Zero point too high. Ensure no-flow. Zero point is unstable. Ensure no-flow. Fluctuation high. Avoid 2- phase medium. | - |
| Reliability of measured zero point | Indicates the reliability of the zero point measured. | Not doneGoodUncertain | - |
| Additional information Indicate whether to display addition information. | | HideShow | - |
| Zero point measured Shows the zero point measured for the adjustment. | | Signed floating-point number | - |
| Zero point standard deviation Shows the standard deviation of the zero point measured. | | Positive floating-point number | - |
| Select action Select the zero point value to apply. | | Keep current zero point Apply zero point measured Apply factory zero point * | - |

* Visibility depends on order options or device settings

10.7.3 Configuring the totalizer

In the **"Totalizer 1 to n" submenu**, you can configure the specific totalizer.

Navigation

"Setup" menu \rightarrow Advanced setup \rightarrow Totalizer 1 to n

| ► Totalizer 1 to n | | | |
|--------------------|----------------------|-----|---------|
| [| Assign process varia | ble | → 🖺 144 |

| Unit totalizer |] | → 🖺 144 |
|--------------------------|-----|---------|
| Totalizer operation mode |] + | → 🖺 144 |
| Control Totalizer 1 to n |] + | → 🖺 144 |
| Failure mode |] - | → 🖺 144 |

| Parameter | Description | Selection | Factory setting |
|--------------------------|---|---|-----------------------------------|
| Assign process variable | Select process variable for totalizer. | Mass flow Volume flow Corrected volume flow* Target mass flow* Carrier mass flow* Target volume flow* Carrier volume flow* Target corrected volume flow* Carrier corrected volume flow* | - |
| Unit totalizer | Select the unit for the process variable of the totalizer. | Unit choose list | Country-specific: • kg • lb |
| Control Totalizer 1 to n | Control the totalizer value. | Totalize Reset + hold Preset + hold | - |
| Totalizer operation mode | Select totalizer calculation mode. | Net flow total Forward flow total Reverse flow total Last valid value | - |
| Failure mode | Define the totalizer behavior in the event of a device alarm. | StopActual valueLast valid value | - |

* Visibility depends on order options or device settings

10.7.4 Carrying out additional display configurations

In the **Display** submenu you can set all the parameters associated with the configuration of the local display.

Navigation

"Setup" menu \rightarrow Advanced setup \rightarrow Display

| ► Display | |
|-----------------------|-----------|
| Format display |] → 🗎 146 |
| Value 1 display |] → 🖹 146 |
| 0% bargraph value 1 |] → 🗎 146 |
| 100% bargraph value 1 |) → 🗎 146 |
| Decimal places 1 |] → 🗎 147 |
| Value 2 display |) → 🗎 147 |
| Decimal places 2 |) → 🗎 147 |
| Value 3 display |) → 🗎 147 |
| 0% bargraph value 3 |] → 🗎 147 |
| 100% bargraph value 3 |] → 🗎 147 |
| Decimal places 3 |) → 🗎 147 |
| Value 4 display |] → 🗎 147 |
| Decimal places 4 |] → 🗎 147 |
| Display language |] → 🗎 147 |
| Display interval |] → 🗎 147 |
| Display damping |] → 🗎 148 |
| Header |] → 🗎 148 |
| Header text |] → 🗎 148 |
| Separator |] → 🗎 148 |
| Backlight |] → 🗎 148 |

| Parameter | Prerequisite | Description | Selection / User entry | Factory setting |
|-----------------------|------------------------------|--|--|---|
| Format display | A local display is provided. | Select how measured values are shown on the display. | 1 value, max. size 1 bargraph + 1 value 2 values 1 value large + 2 values 4 values | - |
| Value 1 display | A local display is provided. | Select the measured value that is shown on the local display. | Mass flow Volume flow Corrected volume flow* Density Reference density* Temperature Current output 1* Current output 2* Current output 4* Pressure Totalizer 1 Totalizer 1 Totalizer 3 Concentration* Target mass flow* Carrier mass flow* Carrier volume flow* Carrier volume flow* Carrier corrected volume flow* Carrier corrected volume flow* Carrier corrected volume flow* Carrier corrected volume flow Carrier current 0 Oscillation damping 0 Oscillation frequency 0 Frequency of Frequency of Carrier pipe temperature Electronic temperature Current output 1* Current output 1* Current output 2* | |
| 0% bargraph value 1 | A local display is provided. | Enter 0% value for bar graph display. | Signed floating-point number | Country-specific: • 0 kg/h • 0 lb/min |
| 100% bargraph value 1 | A local display is provided. | Enter 100% value for bar graph display. | Signed floating-point number | Depends on country and nominal diameter |

| Parameter | Prerequisite | Description | Selection / User entry | Factory setting |
|-----------------------|--|---|---|--|
| Decimal places 1 | A measured value is specified in the Value 1 display parameter. | Select the number of decimal places for the display value. | x x.x x.xx x.xxx x.xxx x.xxxx | - |
| Value 2 display | A local display is provided. | Select the measured value that is shown on the local display. | For the picklist, see Value 1 display parameter $(\rightarrow \cong 131)$ | - |
| Decimal places 2 | A measured value is specified in the Value 2 display parameter. | Select the number of decimal places for the display value. | x x.x x.xx x.xxx x.xxx x.xxxx | - |
| Value 3 display | A local display is provided. | Select the measured value that is shown on the local display. | For the picklist, see Value 1 display parameter $(\rightarrow \square 131)$ | - |
| 0% bargraph value 3 | A selection was made in the Value 3 display parameter. | Enter 0% value for bar graph display. | Signed floating-point number | Country-specific: • 0 kg/h • 0 lb/min |
| 100% bargraph value 3 | A selection was made in the Value 3 display parameter. | Enter 100% value for bar graph display. | Signed floating-point number | - |
| Decimal places 3 | A measured value is specified in the Value 3 display parameter. | Select the number of decimal places for the display value. | x x.x x.xx x.xxx x.xxx x.xxxx | - |
| Value 4 display | A local display is provided. | Select the measured value that is shown on the local display. | For the picklist, see Value 1 display parameter $(\rightarrow \cong 131)$ | - |
| Decimal places 4 | A measured value is specified in the Value 4 display parameter. | Select the number of decimal places for the display value. | x x.x x.xx x.xxx x.xxx x.xxxx | - |
| Display language | A local display is provided. | Set display language. | English Deutsch* Français* Español* Italiano* Nederlands* Portuguesa* Polski* pyccкий язык (Russian)* Svenska* Türkçe* 中文 (Chinese)* 日本語 (Japanese)* 한국어 (Korean)* tiếng Việt (Vietnamese)* čeština (Czech)* | English (alternatively, the ordered language is preset in the device) |
| Display interval | A local display is provided. | Set time measured values are shown on display if display alternates between values. | 1 to 10 s | - |

| Parameter | Prerequisite | Description | Selection / User entry | Factory setting |
|-----------------|---|--|---|-----------------|
| Display damping | A local display is provided. | Set display reaction time to fluctuations in the measured value. | 0.0 to 999.9 s | - |
| Header | A local display is provided. | Select header contents on local display. | Device tag Free text | - |
| Header text | The Free text option is selected in the Header parameter. | Enter display header text. | Max. 12 characters, such as letters, numbers or special characters (e.g. @, %, /) | - |
| Separator | A local display is provided. | Select decimal separator for displaying numerical values. | . (point), (comma) | . (point) |
| Backlight | One of the following conditions is met: • Order code for "Display; operation", option F "4-line, illum.; touch control" • Order code for "Display; operation", option G "4-line, illum.; touch control +WLAN" | Switch the local display backlight on and off. | DisableEnable | - |

* Visibility depends on order options or device settings

10.7.5 WLAN configuration

The **WLAN Settings** submenu guides the user systematically through all the parameters that have to be set for the WLAN configuration.

Navigation

"Setup" menu \rightarrow Advanced setup \rightarrow WLAN settings

| ► WLAN settings | |
|------------------|-----------|
| WLAN IP address |) → 🗎 149 |
| Security type |] → 🗎 149 |
| WLAN passphrase |] → 🗎 149 |
| Assign SSID name |] → 🗎 149 |
| SSID name |] → 🗎 149 |
| Apply changes |] → 🗎 149 |

| Parameter | Prerequisite | Description | User entry / Selection | Factory setting |
|------------------|--|---|---|--|
| WLAN IP address | - | Enter IP address of the device WLAN interface. | 4 octet: 0 to 255 (in the particular octet) | - |
| Network security | - | Select the security type of the WLAN network. | Unsecured WPA2-PSK EAP-PEAP with MSCHAPv2* EAP-PEAP MSCHAPv2 no server authentic.* EAP-TLS* | - |
| WLAN passphrase | The WPA2-PSK option is selected in the Security type parameter. | Enter the network key (8 to 32 characters). The network key supplied with the device should be changed during commissioning for security reasons. | 8 to 32-digit character string comprising numbers, letters and special characters (without spaces) | Serial number of the measuring device (e.g. L100A802000) |
| Assign SSID name | - | Select which name will be used for SSID: device tag or user- defined name. | Device tagUser-defined | - |
| SSID name | The User-defined option is selected in the Assign SSID name parameter. The WLAN access point option is selected in the WLAN mode parameter. | Enter the user-defined SSID name (max. 32 characters). The user-defined SSID name may only be assigned once. If the SSID name is assigned more than once, the devices can interfere with one another. | Max. 32-digit character string comprising numbers, letters and special characters | EH_device designation_last 7 digits of the serial number (e.g. EH_Promass_500_A 802000) |
| Apply changes | - | Use changed WLAN settings. | CancelOk | _ |

* Visibility depends on order options or device settings

10.7.6 Configuration management

After commissioning, you can save the current device configurationor restore the previous device configuration. The device configuration is managed via the **Configuration management** parameter.

Navigation

"Setup" menu \rightarrow Advanced setup \rightarrow Configuration backup

| ► Configuration backup | |
|--------------------------|-----------|
| Operating time | → 🗎 150 |
| Last backup |) → 🗎 150 |
| Configuration management |) → 🗎 150 |

| Backup state | → 🗎 150 |
|-------------------|---------|
| Comparison result | → 🗎 150 |

| Parameter | Description | User interface / Selection |
|--------------------------|--|---|
| Operating time | Indicates how long the device has been in operation. | Days (d), hours (h), minutes (m) and seconds (s) |
| Last backup | Shows when the last data backup was saved to HistoROM backup. | Days (d), hours (h), minutes (m) and seconds (s) |
| Configuration management | Select action for managing the device data in the HistoROM backup. | Cancel Execute backup Restore * Compare * Clear backup data |
| Backup state | Shows the current status of data saving or restoring. | None Backup in progress Restoring in progress Delete in progress Compare in progress Restoring failed Backup failed |
| Comparison result | Comparison of current device data with HistoROM backup. | Settings identical Settings not identical No backup available Backup settings corrupt Check not done Dataset incompatible |

* Visibility depends on order options or device settings

Function scope of the "Configuration management" parameter

| Options | Description |
|-------------------|---|
| Cancel | No action is executed and the user exits the parameter. |
| Execute backup | A backup copy of the current device configuration is saved from the HistoROM backup to the memory of the device. The backup copy includes the transmitter data of the device. |
| Restore | The last backup copy of the device configuration is restored from the device memory to the device's HistoROM backup. The backup copy includes the transmitter data of the device. |
| Compare | The device configuration saved in the device memory is compared with the current device configuration of the HistoROM backup. |
| Clear backup data | The backup copy of the device configuration is deleted from the memory of the device. |

📔 HistoROM backup

A HistoROM is a "non-volatile" device memory in the form of an EEPROM.

While this action is in progress, the configuration cannot be edited via the local display and a message on the processing status appears on the display.

10.7.7 Using parameters for device administration

The **Administration** submenu systematically guides the user through all the parameters that can be used for device administration purposes.

Navigation

 $"Setup" menu \rightarrow Advanced setup \rightarrow Administration$

| ► Administration | |
|----------------------|---------|
| ► Define access code | → 🗎 151 |
| ► Reset access code | → 🗎 151 |
| Device reset | → 🗎 152 |

Using the parameter to define the access code

Navigation

"Setup" menu \rightarrow Advanced setup \rightarrow Administration \rightarrow Define access code

| ► Define access code | |
|----------------------|-----------|
| Define access code | → 🗎 151 |
| Confirm access code |) → 🗎 151 |

Parameter overview with brief description

| Parameter | Description | User entry |
|---------------------|---|---|
| Define access code | Restrict write-access to parameters to protect the configuration of the device against unintentional changes. | Max. 16-digit character string comprising numbers, letters and special characters |
| Confirm access code | | Max. 16-digit character string comprising numbers, letters and special characters |

Using the parameter to reset the access code

Navigation

"Setup" menu \rightarrow Advanced setup \rightarrow Administration \rightarrow Reset access code

| ► Reset access code | | |
|---------------------|---|-------|
| Operating time | → | 🗎 152 |
| Reset access code | → | 152 |

| Parameter | Description | User interface / User entry |
|-------------------|--|---|
| Operating time | Indicates how long the device has been in operation. | Days (d), hours (h), minutes (m) and seconds (s) |
| Reset access code | Reset access code to factory settings. For a reset code, contact your Endress+Hauser service organization. | Character string comprising numbers, letters and special characters |
| | The reset code can only be entered via: • Web browser • DeviceCare, FieldCare (via CDI-RJ45 service interface) • Fieldbus | |

Using the parameter to reset the device

Navigation

 $\texttt{"Setup"} \texttt{menu} \rightarrow \texttt{Advanced setup} \rightarrow \texttt{Administration}$

Parameter overview with brief description

| Parameter | Description | Selection |
|--------------|---|--|
| Device reset | Reset the device configuration - either entirely or in part - to a defined state. | Cancel To delivery settings Restart device Restore S-DAT backup * |

* Visibility depends on order options or device settings

10.8 Simulation

Via the **Simulation** submenu, it is possible to simulate various process variables in the process and the device alarm mode and verify downstream signal chains (switching valves or closed-control loops). The simulation can be performed without a real measurement (no flow of medium through the device).

Navigation

"Diagnostics" menu \rightarrow Simulation

| ► Simulation | |
|------------------------------------|-----------|
| Assign simulation process variable |) → 🗎 153 |
| Process variable value |) → 🗎 153 |
| Status input simulation |) → 🗎 154 |
| Input signal level |) → 🖺 154 |
| Current input 1 to n simulation |) → 🗎 154 |
| Value current input 1 to n | → 🗎 154 |

| Current output 1 to n simulation |] | → 🗎 153 |
|------------------------------------|---|---------|
| Value current output 1 to n |] | → 🖺 153 |
| Frequency output simulation 1 to n |] | → 🗎 154 |
| Frequency value 1 to n |] | → 🗎 154 |
| Pulse output simulation 1 to n |] | → 🖺 154 |
| Pulse value 1 to n |] | → 🖺 154 |
| Switch output simulation 1 to n |] | → 🗎 154 |
| Switch status 1 to n |] | → 🖺 154 |
| Relay output 1 to n simulation |] | → 🗎 154 |
| Switch status 1 to n |] | → 🗎 154 |
| Device alarm simulation |] | → 🗎 154 |
| Diagnostic event category |] | → 🗎 154 |
| Diagnostic event simulation | | → 🗎 154 |
| | - | |

| Parameter | Prerequisite | Description | Selection / User entry |
|------------------------------------|---|---|--|
| Assign simulation process variable | - | Select a process variable for the simulation process that is activated. | Off Mass flow Volume flow Corrected volume flow* Target mass flow* Carrier mass flow* Carrier volume flow* Carrier volume flow* Target corrected volume flow* Carrier corrected volume flow* <l< td=""></l<> |
| Process variable value | A process variable is selected in the Assign simulation process variable parameter ($\rightarrow \square$ 153). | Enter the simulation value for the selected process variable. | Depends on the process variable selected |
| Current output 1 to n simulation | - | Switch the simulation of the current output on and off. | OffOn |
| Value current output 1 to n | In the Current output 1 to n simulation parameter, the On option is selected. | Enter the current value for simulation. | 3.59 to 22.5 mA |

| Parameter | Prerequisite | Description | Selection / User entry |
|------------------------------------|--|--|---|
| Frequency output simulation 1 to n | In the Operating mode parameter, the Frequency option is selected. | Switch the simulation of the frequency output on and off. | OffOn |
| Frequency value 1 to n | In the Frequency output simulation 1 to n parameter, the On option is selected. | Enter the frequency value for the simulation. | 0.0 to 12 500.0 Hz |
| Pulse output simulation 1 to n | In the Operating mode parameter, the Pulse option is selected. | Set and switch off the pulse output simulation. For Fixed value option: Pulse width parameter (→ ¹ 122) defines the pulse width of the pulses output. | Off Fixed value Down-counting value |
| Pulse value 1 to n | In the Pulse output simulation 1 to n parameter, the Down-counting value option is selected. | Enter the number of pulses for simulation. | 0 to 65 535 |
| Switch output simulation 1 to n | In the Operating mode parameter, the Switch option is selected. | Switch the simulation of the switch output on and off. | OffOn |
| Switch status 1 to n | - | Select the status of the status output for the simulation. | Open Closed |
| Relay output 1 to n simulation | - | Switch simulation of the relay output on and off. | OffOn |
| Switch status 1 to n | The On option is selected in the Switch output simulation 1 to n parameter parameter. | Select status of the relay output for the simulation. | Open Closed |
| Device alarm simulation | - | Switch the device alarm on and off. | OffOn |
| Diagnostic event category | - | Select a diagnostic event category. | SensorElectronicsConfigurationProcess |
| Diagnostic event simulation | - | Select a diagnostic event to simulate this event. | Off Diagnostic event picklist (depends on the category selected) |
| Current input 1 to n simulation | - | Switch simulation of the current input on and off. | OffOn |
| Value current input 1 to n | In the Current input 1 to n simulation parameter, the On option is selected. | Enter the current value for simulation. | 0 to 22.5 mA |
| Status input simulation | - | Switch simulation of the status input on and off. | OffOn |
| Input signal level | In the Status input simulation parameter, the On option is selected. | Select the signal level for the simulation of the status input. | HighLow |

Visibility depends on order options or device settings

10.9 Protecting settings from unauthorized access

The following write protection options exist in order to protect the configuration of the measuring device from unintentional modification:

- Protect access to parameters via access code $\rightarrow \cong 155$
- Protect access to local operation via key locking $\rightarrow \cong 80$
- Protect access to measuring device via write protection switch \rightarrow 🗎 156

10.9.1 Write protection via access code

The effects of the user-specific access code are as follows:

- Via local operation, the parameters for the measuring device configuration are writeprotected and their values can no longer be changed.
- Device access is protected via the Web browser, as are the parameters for the measuring device configuration.
- Device access is protected via FieldCare or DeviceCare (via CDI-RJ45 service interface), as are the parameters for the measuring device configuration.

Defining the access code via the local display

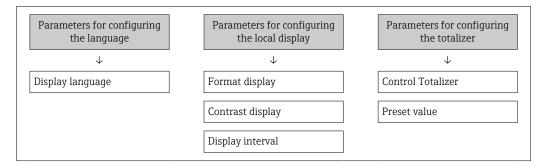
- **1.** Navigate to the **Define access code** parameter ($\rightarrow \square$ 151).
- 2. Maximum of 16-digit character string comprising numbers, letters and special characters as the access code.
- 3. Enter the access code again in the **Confirm access code** parameter (→ 🗎 151) to confirm.
 - └ The B symbol appears in front of all write-protected parameters.

P • Disabling parameter write protection via access code $\rightarrow \square$ 79.

- If the access code is lost: Resetting the access code $\rightarrow \cong 156$.
- The user role with which the user is currently logged in is displayed in **Access status** parameter.
 - Navigation path: Operation → Access status
 - User roles and their access rights $\rightarrow \cong 79$
- The device automatically locks the write-protected parameters again if a key is not pressed for 10 minutes in the navigation and editing view.
- The device locks the write-protected parameters automatically after 60 s if the user skips back to the operational display mode from the navigation and editing view.

Parameters which can always be modified via the local display

Certain parameters that do not affect the measurement are excepted from parameter write protection via the local display. Despite the user-specific access code, they can always be modified, even if the other parameters are locked.



Defining the access code via the web browser

- **1.** Navigate to the **Define access code** parameter ($\rightarrow \square 151$).
- 2. Define a 16-digit (max.) numeric code as the access code.

- **3.** Enter the access code again in the **Confirm access code** parameter ($\rightarrow \implies 151$) to confirm.
 - └ The web browser switches to the login page.
- Disabling parameter write protection via access code \rightarrow 🗎 79.
 - If the access code is lost: Resetting the access code $\rightarrow \cong 156$.
 - The **Access status** parameter shows which user role the user is currently logged in with.
 - Navigation path: Operation → Access status
 - User roles and their access rights \rightarrow \bigcirc 79

If no action is performed for 10 minutes, the web browser automatically returns to the login page.

Resetting the access code

If you misplace the user-specific access code, it is possible to reset the code to the factory setting. A reset code must be entered for this purpose. The user-specific access code can then be defined again afterwards.

Via Web browser, FieldCare, DeviceCare (via CDI-RJ45 service interface), fieldbus

You can only obtain a reset code from your local Endress+Hauser service organization. The code must be calculated explicitly for every device.

- 1. Note down the serial number of the device.
- 2. Read off the **Operating time** parameter.
- **3.** Contact the local Endress+Hauser service organization and tell them the serial number and the operating time.
 - └ Get the calculated reset code.
- **4.** Enter the reset code in the **Reset access code** parameter ($\rightarrow \triangleq 152$).
 - → The access code has been reset to the factory setting **0000**. It can be redefined $\rightarrow \triangleq 155$.
- For IT security reasons, the calculated reset code is only valid for 96 hours from the specified operating time and for the specific serial number. If you cannot return to the device within 96 hours, you should either increase the operating time you read out by a few days or switch off the device.

10.9.2 Write protection via write protection switch

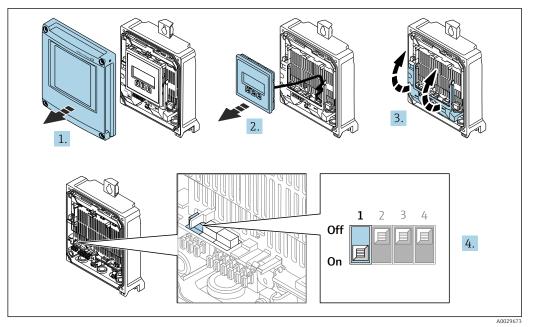
Unlike parameter write protection via a user-specific access code, this allows the user to lock write access to the entire operating menu - apart from the **"Contrast display" parameter**.

The parameter values are now read only and cannot be edited any more (exception **"Contrast display" parameter**):

- Via local display
- Via PROFIBUS PA protocol

Proline 500 – digital

Enable/disable write protection



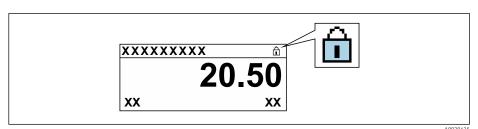
- 1. Open the housing cover.
- 2. Remove the display module.

3. Fold open the terminal cover.

4. Enable or disable write protection:

Setting the write protection (WP) switch on the main electronics module to the **ON** position enables hardware write protection/setting to **OFF** (factory setting) disables hardware write protection.

In the Locking status parameter, the Hardware locked option is displayed
 → ■ 159. When hardware write protection is enabled, the
 symbol appears in the header of the measured value display and in the navigation view in front of the parameters.



- 5. Insert the display module.
- 6. Close the housing cover.

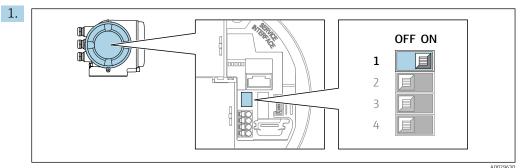
7. NOTICE

Excessive tightening torque applied to the fixing screws! Risk of damaging the plastic transmitter.

► Tighten the fixing screws as per the tightening torque: 2.5 Nm (1.8 lbf ft)

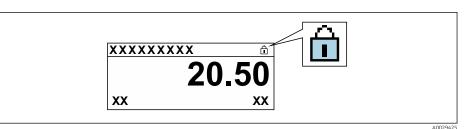
Tighten the fixing screws.

Proline 500



Setting the write protection (WP) switch on the main electronics module to the **ON** position enables hardware write protection.

→ In the Locking status parameter, the Hardware locked option is displayed
 → ⇒ 159. In addition, on the local display the
 B symbol appears in front of the parameters in the header of the operational display and in the navigation view.



- 2. Setting the write protection (WP) switch on the main electronics module to the **OFF** position (factory setting) disables hardware write protection.
 - ► No option is displayed in the Locking status parameter → <a>Pmin 159. On the local display, the <a>Pmin symbol disappears from in front of the parameters in the header of the operational display and in the navigation view.

11 Operation

11.1 Reading off the device locking status

Device active write protection: Locking status parameter

Operation \rightarrow Locking status

Function scope of the "Locking status" parameter

| Options | Description |
|--------------------|--|
| None | The access authorization displayed in the Access status parameter applies $\rightarrow \square$ 79. Only appears on local display. |
| Hardware locked | The DIP switch for hardware locking is activated on the PCB board. This locks write access to the parameters (e.g. via local display or operating tool) $\rightarrow \square$ 156. |
| Temporarily locked | Write access to the parameters is temporarily locked on account of internal processes running in the device (e.g. data upload/download, reset, etc.). Once the internal processing has been completed, the parameters can be changed once again. |

11.2 Adjusting the operating language

Petailed information:

- To configure the operating language $\rightarrow extsf{B} extsf{106}$
- For information on the operating languages supported by the measuring device $\rightarrow \ \ \cong \ 271$

11.3 Configuring the display

Detailed information:

- On the basic settings for the local display $\rightarrow \square 130$
- On the advanced settings for the local display $\rightarrow \cong 145$

11.4 Reading off measured values

With the **Measured values** submenu, it is possible to read all the measured values.

Navigation

"Diagnostics" menu \rightarrow Measured values

| ► Measured values | | | |
|-------------------|-------------------|-----|---------|
| ► M | easured variables | - | → 🖺 160 |
| ► In | put values |] - | → 🖺 163 |
| ► Ou | itput values |] - | → 🖺 164 |
| ► To | talizer 1 to n |] - | → 🖺 143 |

11.4.1 "Measured variables" submenu

The **Measured variables** submenu contains all the parameters needed to display the current measured values for each process variable.

Navigation

"Diagnostics" menu \rightarrow Measured values \rightarrow Measured variables

| ► Measured variables | |
|-------------------------------|-----------|
| Mass flow |] → 🗎 160 |
| Volume flow |] → 🗎 160 |
| Corrected volume flow |) → 🗎 161 |
| Density |) → 🗎 161 |
| Reference density | → 🗎 161 |
| Temperature |] → 🗎 161 |
| Pressure |] → 🗎 161 |
| Concentration |] → 🖹 161 |
| Target mass flow |] → 🗎 161 |
| Carrier mass flow |] → 🗎 161 |
| Target corrected volume flow |) → 🗎 161 |
| Carrier corrected volume flow |) → 🗎 162 |
| Target volume flow | → 🗎 162 |
| Carrier volume flow |] → 🗎 162 |

Parameter overview with brief description

| Parameter | Prerequisite | Description | User interface |
|-------------|--------------|--|---------------------------------|
| Mass flow | - | Displays the mass flow that is currently measured. Dependency The unit is taken from: Mass flow unit parameter (→ 	≧ 110) | Signed floating-point number |
| Volume flow | - | Displays the volume flow that is currently calculated. Dependency The unit is taken from the Volume flow unit parameter ($\rightarrow \cong 110$). | Signed floating-point number |

| Parameter | Prerequisite | Description | User interface |
|------------------------------|---|--|---------------------------------|
| Corrected volume flow | - | Displays the corrected volume flow that is currently calculated. Dependency The unit is taken from: Corrected volume flow unit parameter $(\rightarrow \cong 110)$ | Signed floating-point number |
| Density | - | Shows the density currently measured. <i>Dependency</i> The unit is taken from the Density unit parameter ($\rightarrow \cong 110$). | Signed floating-point number |
| Reference density | - | Displays the reference density that is currently calculated. <i>Dependency</i> The unit is taken from: Reference density unit parameter (→ 🗎 110) | Signed floating-point number |
| Temperature | - | Shows the medium temperature currently measured. <i>Dependency</i> The unit is taken from: Temperature unit parameter ($\rightarrow \cong 111$) | Signed floating-point number |
| Pressure value | - | Displays either a fixed or external pressure value. Dependency The unit is taken from the Pressure unit parameter ($\rightarrow \cong$ 111). | Signed floating-point number |
| Concentration | For the following order code: Order code for "Application package", option ED "Concentration" The software options currently enabled are displayed in the Software option overview parameter. | Displays the concentration that is currently calculated. <i>Dependency</i> The unit is taken from the Concentration unit parameter. | Signed floating-point number |
| Target mass flow | With the following conditions: Order code for "Application package", option ED "Concentration" Image: The software options currently enabled are displayed in the software option overview parameter. | Displays the mass flow that is currently measured for the target medium. <i>Dependency</i> The unit is taken from: Mass flow unit parameter ($\rightarrow \square$ 110) | Signed floating-point number |
| Carrier mass flow | With the following conditions: Order code for "Application package", option ED "Concentration" Image: Concentration and the software options currently enabled are displayed in the software option overview parameter. | Displays the mass flow of the carrier medium that is currently measured. <i>Dependency</i> The unit is taken from: Mass flow unit parameter ($\rightarrow \square$ 110) | Signed floating-point number |
| Target corrected volume flow | With the following conditions: Order code for "Application package", option ED "Concentration" The Ethanol in water option or %mass / %volume option is selected in the Liquid type parameter. The software options currently enabled are displayed in the Software option overview parameter. | Displays the corrected volume flow that is currently measured for the target fluid. Dependency The unit is taken from the Volume flow unit parameter ($\rightarrow \cong 110$). | Signed floating-point number |

| Parameter | Prerequisite | Description | User interface |
|-------------------------------|--|---|---------------------------------|
| Carrier corrected volume flow | With the following conditions: Order code for "Application package", option ED "Concentration" In the Liquid type parameter, the Ethanol in water option or %mass / %volume option is selected. | Displays the corrected volume flow currently measured for the carrier fluid. <i>Dependency</i> The unit is taken from the Volume flow unit parameter ($\rightarrow \square$ 110). | Signed floating-point number |
| | The software options currently enabled are displayed in the Software option overview parameter. | | |
| Target volume flow | With the following conditions: Order code for "Application package", option ED "Concentration" The Ethanol in water option or %mass / %volume option is selected in the Liquid type parameter. The %vol option is selected in the Concentration unit parameter. | Displays the volume flow currently measured for the target medium. <i>Dependency</i> The unit is taken from the Volume flow unit parameter ($\rightarrow \square$ 110). | Signed floating-point number |
| | The software options currently enabled are displayed in the Software option overview parameter. | | |
| Carrier volume flow | With the following conditions: Order code for "Application package", option ED "Concentration" The Ethanol in water option or %mass / %volume option is selected in the Liquid type parameter. The %vol option is selected in the Concentration unit parameter. | Displays the volume flow currently measured for the carrier medium. <i>Dependency</i> The unit is taken from the Volume flow unit parameter ($\rightarrow \cong 110$). | Signed floating-point number |
| | The software options currently enabled are displayed in the Software option overview parameter. | | |

11.4.2 Totalizer

The **Totalizer** submenu contains all the parameters needed to display the current measured values for every totalizer.

Navigation

"Diagnostics" menu \rightarrow Measured values \rightarrow Totalizer

| ► Totalizer | | |
|-------------|--------------------------------|--|
| | Assign process variable 1 to n | |
| | Totalizer 1 to n value | |
| | Totalizer 1 to n status | |
| | Totalizer 1 to n status (Hex) | |

| Parameter | Prerequisite | Description | Selection / User entry / User interface |
|-------------------------------|---|---|---|
| Assign process variable | _ | Select process variable for totalizer. | Mass flow Volume flow Corrected volume flow* Target mass flow* Carrier mass flow* Target volume flow* Carrier volume flow* Target corrected volume flow* Carrier corrected volume flow* |
| Totalizer value 1 to n | One of the following options is selected in the Assign process variable parameter: • Volume flow • Mass flow • Corrected volume flow • Total mass flow • Condensate mass flow • Energy flow • Heat flow difference | Displays the current totalizer counter value. | Signed floating-point number |
| Totalizer status 1 to n | - | Displays the current totalizer status. | GoodUncertainBad |
| Totalizer status (Hex) 1 to n | In Target mode parameter, the Auto option is selected. | Displays the current status value (hex) of the totalizer. | 0 to 0xFF |

* Visibility depends on order options or device settings

11.4.3 "Input values" submenu

The Input values submenu guides you systematically to the individual input values.

Navigation

"Diagnostics" menu \rightarrow Measured values \rightarrow Input values

| ► Input values | |
|------------------------|---------|
| ► Current input 1 to n | → 🗎 163 |
| ► Status input 1 to n | → ● 164 |

Input values of current input

The **Current input 1 to n** submenu contains all the parameters needed to display the current measured values for every current input.

Navigation

"Diagnostics" menu \rightarrow Measured values \rightarrow Input values \rightarrow Current input 1 to n

| ► Current input 1 to n | |
|-------------------------|-----------|
| Measured values 1 to n |] → 🗎 164 |
| Measured current 1 to n |] → 🗎 164 |

Parameter overview with brief description

| Parameter | Description | User interface |
|-------------------------|--|------------------------------|
| Measured values 1 to n | Displays the current input value. | Signed floating-point number |
| Measured current 1 to n | Displays the current value of the current input. | 0 to 22.5 mA |

Input values of status input

The **Status input 1 to n** submenu contains all the parameters needed to display the current measured values for every status input.

Navigation

"Diagnostics" menu \rightarrow Measured values \rightarrow Input values \rightarrow Status input 1 to n



Parameter overview with brief description

| Parameter | Description | User interface |
|--------------------|---------------------------------------|------------------------------------|
| Value status input | Shows the current input signal level. | HighLow |

11.4.4 Output values

The **Output values** submenu contains all the parameters needed to display the current measured values for every output.

Navigation

"Diagnostics" menu \rightarrow Measured values \rightarrow Output values

| ► Output values | | |
|-----------------|-------------------|---------|
| ► Curre | ent output 1 to n | → 🗎 165 |

| ► Pulse 1 to r | e/frequency/switch output n | → 🗎 165 |
|-------------------|--------------------------------|---------|
| ► Relay | y output 1 to n | → 🗎 166 |

Output values of current output

The **Value current output** submenu contains all the parameters needed to display the current measured values for every current output.

Navigation

"Diagnostics" menu \rightarrow Measured values \rightarrow Output values \rightarrow Value current output 1 to n

| ► Current output 1 to n | |
|-------------------------|-----------|
| Output current 1 to n |) → 🗎 165 |
| Measured current 1 to n | → 🗎 165 |

Parameter overview with brief description

| Parameter | Description | User interface |
|------------------|---|-----------------|
| Output current 1 | Displays the current value currently calculated for the current output. | 3.59 to 22.5 mA |
| Measured current | Displays the current value currently measured for the current output. | 0 to 30 mA |

Output values for pulse/frequency/switch output

The **Pulse/frequency/switch output 1 to n** submenu contains all the parameters needed to display the current measured values for every pulse/frequency/switch output.

Navigation

"Diagnostics" menu \rightarrow Measured values \rightarrow Output values \rightarrow Pulse/frequency/switch output 1 to n

| Pulse/frequency/switch output 1 to n | |
|---|---------|
| Output frequency 1 to n | → 🗎 166 |
| Pulse output 1 to n | → 🗎 166 |
| Switch status 1 to n | → 🗎 166 |

| Parameter | Prerequisite | Description | User interface |
|-------------------------|---|---|---|
| Output frequency 1 to n | In the Operating mode parameter, the Frequency option is selected. | Displays the value currently measured for the frequency output. | 0.0 to 12 500.0 Hz |
| Pulse output 1 to n | The Pulse option is selected in the Operating mode parameter parameter. | Displays the pulse frequency currently output. | Positive floating-point number |
| Switch status 1 to n | The Switch option is selected in the Operating mode parameter. | Displays the current switch output status. | Open Closed |

Output values for relay output

The **Relay output 1 to n** submenu contains all the parameters needed to display the current measured values for every relay output.

Navigation

"Diagnostics" menu \rightarrow Measured values \rightarrow Output values \rightarrow Relay output 1 to n

| ► Relay output 1 to n | |
|---------------------------|-----------|
| Switch status | → 🗎 166 |
| Switch cycles |) → 🗎 166 |
| Max. switch cycles number | → 🗎 166 |

Parameter overview with brief description

| Parameter | Description | User interface |
|---------------------------|---|---|
| Switch status | Shows the current relay switch status. | Open Closed |
| Switch cycles | Shows number of all performed switch cycles. | Positive integer |
| Max. switch cycles number | Shows the maximal number of guaranteed switch cycles. | Positive integer |

11.5 Adapting the measuring device to the process conditions

The following are available for this purpose:

- Basic settings using the Setup menu ($\rightarrow \implies 107$)
- Advanced settings using the Advanced setup submenu ($\rightarrow \implies 135$)

11.6 Performing a totalizer reset

The totalizers are reset in the **Operation** submenu: Control Totalizer

Function range of "Control Totalizer " parameter

| Options | Description |
|---------------|--|
| Totalize | The totalizer is started. |
| Reset + hold | The totaling process is stopped and the totalizer is reset to 0. |
| Preset + hold | The totaling process is stopped and the totalizer is set to its defined start value from the Preset value 1 to n parameter. |

Navigation

"Operation" menu \rightarrow Totalizer handling

| ► Totalizer handling | | |
|--------------------------|---------|--|
| Control Totalizer 1 to n | → 🗎 167 | |
| Preset value 1 to n | → 🗎 167 | |
| Reset all totalizers | → 🗎 167 | |

Parameter overview with brief description

| Parameter | Prerequisite | Description | Selection / User entry |
|--------------------------|--|--------------------------------------|---|
| Control Totalizer 1 to n | - | Control the totalizer value. | TotalizeReset + holdPreset + hold |
| Preset value 1 to n | In the Assign process variable parameter one of the following options is selected: • Volume flow • Mass flow • Corrected volume flow • Total mass flow • Condensate mass flow • Energy flow • Heat flow difference | Specify start value for totalizer. | Signed floating-point number |
| Reset all totalizers | - | Reset all totalizers to 0 and start. | CancelReset + totalize |

11.7 Displaying the measured value history

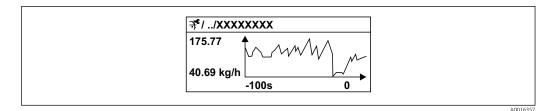
The **Extended HistoROM** application package must be enabled in the device (order option) for the **Data logging** submenu to appear. This contains all the parameters for the measured value history.

Pata logging is also available via:

- Plant Asset Management Tool FieldCare →
 ⁽¹⁾
 ⁽²⁾
 ⁽²⁾
- Web browser

Function range

- A total of 1000 measured values can be stored
- 4 logging channels
- Adjustable logging interval for data logging
- Measured value trend for each logging channel displayed in the form of a chart



S 36 Chart of a measured value trend

- x-axis: depending on the number of channels selected displays 250 to 1000 measured values of a process variable.
- y-axis: displays the approximate measured value span and constantly adapts this to the ongoing measurement.

If the length of the logging interval or the assignment of the process variables to the channels is changed, the content of the data logging is deleted.

Navigation

"Diagnostics" menu \rightarrow Data logging

| ► Data logging | |
|-------------------------|-----------|
| Assign channel 1 |] → 🗎 169 |
| Assign channel 2 |] → 🗎 169 |
| Assign channel 3 |] → 🗎 169 |
| Assign channel 4 |] → 🗎 169 |
| Logging interval |] → 🗎 169 |
| Clear logging data |] → 🖺 169 |
| Data logging |] → 🗎 170 |
| Logging delay |] → 🗎 170 |
| Data logging control |] → 🗎 170 |
| Data logging status |] → 🗎 170 |
| Entire logging duration |] → 🗎 170 |
| ► Display channel 1 |] |
| ► Display channel 2 |] |
| ► Display channel 3 |] |
| ► Display channel 4 |] |

| Parameter | Prerequisite | Description | Selection / User entry / User interface |
|--------------------|--|---|---|
| Assign channel 1 | The Extended HistoROM application package is available. | Assign process variable to logging channel. | Off Mass flow Volume flow Corrected volume flow* Density Reference density* Temperature Oscillation amplitude* Current output 1* Current output 2* Current output 4* Pressure Concentration* Target mass flow* Carrier volume flow* Carrier volume flow* Carrier corrected volume flow* Carrier corrected volume flow* Carrier corrected volume flow* Carrier corrected volume flow* Carrier current 0 Oscillation amplitude* HBSI* Exciter current 0 Oscillation damping 0 Oscillation frequency 0 Oscillation amplitude* Frequency fluctuation 0* Oscillation amplitude* Frequency fluctuation 0* Oscillation amplitude 1* Signal asymmetry Carrier pipe temperature* Electronic temperature |
| Assign channel 2 | The Extended HistoROM application package is available. The software options currently enabled are displayed in the Software option overview parameter. | Assign a process variable to logging channel. | For the picklist, see Assign channel 1 parameter (→ 🗎 169) |
| Assign channel 3 | The Extended HistoROM application package is available. The software options currently enabled are displayed in the Software option overview parameter. | Assign a process variable to logging channel. | For the picklist, see Assign channel 1 parameter (→ 🗎 169) |
| Assign channel 4 | The Extended HistoROM application package is available. The software options currently enabled are displayed in the Software option overview parameter. | Assign a process variable to logging channel. | For the picklist, see Assign channel 1 parameter (→ 🗎 169) |
| Logging interval | The Extended HistoROM application package is available. | Define the logging interval for data logging. This value defines the time interval between the individual data points in the memory. | 0.1 to 3 600.0 s |
| Clear logging data | The Extended HistoROM application package is available. | Clear the entire logging data. | CancelClear data |

| Parameter | Prerequisite | Description | Selection / User entry / User interface |
|-------------------------|--|--|--|
| Data logging | - | Select the type of data logging. | OverwritingNot overwriting |
| Logging delay | In the Data logging parameter, the Not overwriting option is selected. | Enter the time delay for measured value logging. | 0 to 999 h |
| Data logging control | In the Data logging parameter, the Not overwriting option is selected. | Start and stop measured value logging. | NoneDelete + startStop |
| Data logging status | In the Data logging parameter, the Not overwriting option is selected. | Displays the measured value logging status. | DoneDelay activeActiveStopped |
| Entire logging duration | In the Data logging parameter, the Not overwriting option is selected. | Displays the total logging duration. | Positive floating-point number |

* Visibility depends on order options or device settings

12 Diagnostics and troubleshooting

12.1 General troubleshooting

For local display

| Error | Possible causes | Remedial action |
|---|---|--|
| Local display is dark, but signal output is within the valid range | The cable of the display module is not plugged in correctly. | Insert the plug correctly into the main electronics module and display module. |
| Local display dark and no output signals | Supply voltage does not match the voltage specified on the nameplate. | Apply the correct supply voltage $\rightarrow \textcircled{B} 55 \rightarrow \textcircled{B} 49.$ |
| Local display dark and no output signals | Supply voltage has incorrect polarity. | Reverse polarity of supply voltage. |
| Local display dark and no output signals | No contact between connecting cables and terminals. | Ensure electrical contact between the cable and the terminal. |
| Local display dark and no output signals | Terminals are not plugged into the I/O electronics module correctly. Terminals are not plugged into the main electronics module correctly. | Check terminals. |
| Local display dark and no output signals | I/O electronics module is defective. Main electronics module is defective. | Order spare part $\rightarrow \square 245$. |
| Local display dark and no output signals | The connector between the main electronics module and display module is not plugged in correctly. | Check the connection and correct if necessary. |
| Local display cannot be read, but signal output is within the valid range | Display is set too bright or too dark. | Set the display brighter by simultaneously pressing + E. Set the display darker by simultaneously pressing + E. |
| Local display is dark, but signal output is within the valid range | Display module is defective. | Order spare part $\rightarrow \square$ 245. |
| Backlighting of local display is red | Diagnostic event with "Alarm" diagnostic behavior has occurred. | Take remedial measures → 🗎 185 |
| Text on local display appears in a language that cannot be understood. | The selected operating language cannot be understood. | Press □ + |
| Message on local display: "Communication Error" "Check Electronics" | Communication between the display module and the electronics is interrupted. | Check the cable and the connector between the main electronics module and display module. Order spare part → |

For output signals

| Error | Possible causes | Remedial action |
|---|--|---|
| Signal output outside the valid range | Main electronics module is defective. | Order spare part $\rightarrow \square$ 245. |
| Device shows correct value on local display, but signal output is incorrect, though in the valid range. | Parameter configuration error | Check and adjust parameter configuration. |
| Device measures incorrectly. | Configuration error or device is operated outside the application. | Check and correct parameter configuration. Observe limit values specified in the "Technical Data". |

For access

| Fault | Possible causes | Remedial action | |
|---|--|---|--|
| Write access to parameters is not possible. | Hardware write protection is enabled. | Set the write protection switch on the main electronics module to the OFF position $\rightarrow \cong 156$. | |
| Write access to parameters is not possible. Current user role has limited access authorization. | | Check user role → 79. Enter correct customer-specific access code ⇒ 79. | |
| Connection via PROFIBUS PA is not possible. | Device plug is incorrectly connected. | Check the pin assignment of the device plugs . | |
| Connection via PROFIBUS PA is not possible. | PROFIBUS PA cable is incorrectly terminated. | Check the terminating resistor . | |
| Unable to connect to the web server. | Web server is disabled. | Using the "FieldCare" or "DeviceCare" operating tool, check whether the web server of the device is enabled, and enable it if necessary $\rightarrow \cong 86$. | |
| | The Ethernet interface on the PC is incorrectly configured. | Check the properties of the Internet protocol (TCP/IP) → | |
| Unable to connect to the web server. | The IP address on the PC is incorrectly configured. | Check the IP address: 192.168.1.212 $\rightarrow \cong 82$ | |
| Unable to connect to the web server. | WLAN access data are incorrect. | Check WLAN network status. Log on to the device again using WLAN access data. Check that WLAN is enabled on the measuring instrument and operating unit → 82. | |
| | WLAN communication is disabled. | - | |
| Unable to connect to web server, FieldCare or DeviceCare. | WLAN network is not available. | Check if WLAN reception is present: LED or display module is lit blue. Check if WLAN connection is enabled: LED display module flashes blue. Switch on instrument function. | |
| Network connection not present or unstable | WLAN network is weak. | Operating unit outside reception range: Check network status on operating unit. To improve network performance, use an external WLAN antenna. | |
| | Parallel WLAN and Ethernet communication | Check network settings. Temporarily enable only the WLAN as an interface. | |
| Web browser frozen and operation no longer possible | Data transfer is active. | Wait until data transfer or current action is finished. | |
| | Connection lost | Check cable connection and power supply. Refresh the web browser and restart if necessary. | |
| Display of web browser content is difficult to read or incomplete. | Web browser version used is not optimal. | Use correct web browser version → | |
| | Unsuitable view settings. | Change the font size/display ratio of the Web browser. | |
| Incomplete or no display of content in the web browser | JavaScript is not enabled. JavaScript cannot be enabled. | Enable JavaScript. Enter http://XXX.XXX.X.XX/servlet/ basic.html as the IP address. | |

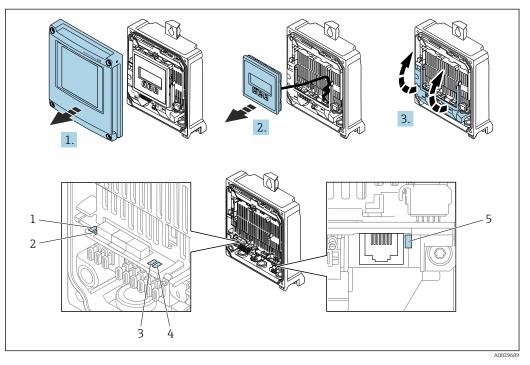
| Fault | Possible causes | Remedial action |
|--|--|--|
| Operation with FieldCare or DeviceCare via service interface CDI-RJ45 (port 8000) is not possible. | Firewall of the PC or network is blocking communication. | Depending on the settings of the firewall used on the PC or in the network, the firewall must be adapted or disabled to allow FieldCare/ DeviceCare access. |
| Flashing the firmware with FieldCare or DeviceCare via service interface CDI-RJ45 (port 8000 or TFTP ports) is not possible. | Firewall of the PC or network is blocking communication. | Depending on the settings of the firewall used on the PC or in the network, the firewall must be adapted or disabled to allow FieldCare/ DeviceCare access. |

12.2 Diagnostic information via light emitting diodes

12.2.1 Transmitter

Proline 500 – digital

Different LEDs in the transmitter provide information on the device status.



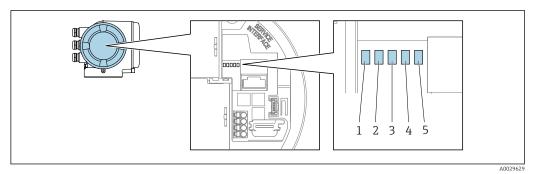
- 1 Supply voltage
- 2 Device status
- 3 Not used
- 4 Communication
- 5 Service interface (CDI) active, Ethernet Link/Activity
- 1. Open the housing cover.
- 2. Remove the display module.
- 3. Fold open the terminal cover.

| LED | | Color | Meaning |
|-----|-----------------------|-----------------------|---|
| 1 | Supply voltage | Off | Supply voltage is off or too low. |
| | | Green | Supply voltage is OK. |
| 2 | Device status (normal | Off | Firmware error |
| | operation) | Green | Device status is OK. |
| | | Flashing green | Device is not configured. |
| | | Flashing red | A diagnostic event with "Warning" diagnostic behavior has occurred. |
| | | Red | A diagnostic event with "Alarm" diagnostic behavior has occurred. |
| | | Flashing red or green | The device restarts. |
| 2 | Device status (during | Flashes red slowly | If $>$ 30 seconds: problem with the boot loader. |
| | start-up) | Flashes red quickly | If > 30 seconds: compatibility problem when reading the firmware. |
| 3 | Not used | - | - |

| LED | | Color | Meaning |
|-----|--------------------------|-----------------|---|
| 4 | Communication | Off | Device does not receive any Profibus data. |
| | | White | Device receives Profibus data. |
| 5 | Service interface (CDI), | Off | Not connected or no connection established. |
| | Ethernet Link/Activity | Yellow | Connected and connection established. |
| | | Flashing yellow | Service interface active. |

Proline 500

Different LEDs in the transmitter provide information on the device status.



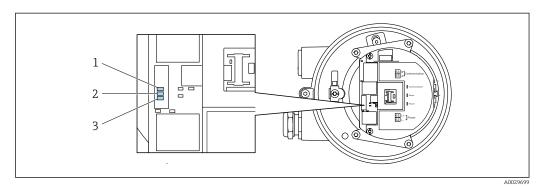
- 1 2 Supply voltage
- Device status
- 3 Not used
- Communication
- 4 5 Service interface (CDI) active, Ethernet Link/Activity

| LED | | Color | Meaning |
|-----|--------------------------|-----------------------|---|
| 1 | Supply voltage | Off | Supply voltage is off or too low. |
| | | Green | Supply voltage is OK. |
| 2 | Device status (normal | Off | Firmware error |
| | operation) | Green | Device status is OK. |
| | | Flashing green | Device is not configured. |
| | | Red | A diagnostic event with "Alarm" diagnostic behavior has occurred. |
| | | Flashing red | A diagnostic event with "Warning" diagnostic behavior has occurred. |
| | | Flashing red or green | The device restarts. |
| 2 | Device status (during | Flashes red slowly | If $>$ 30 seconds: problem with the boot loader. |
| | start-up) | Flashes red quickly | If > 30 seconds: compatibility problem when reading the firmware. |
| 3 | Not used | - | - |
| 4 | Communication | Off | Device does not receive any Profibus data. |
| | | White | Device receives Profibus data. |
| 5 | Service interface (CDI), | Off | Not connected or no connection established. |
| | Ethernet Link/Activity | Yellow | Connected and connection established. |
| | | Flashing yellow | Service interface active. |

12.2.2 Sensor connection housing

Proline 500 – digital

Various light emitting diodes (LED) on the ISEM electronics unit (intelligent sensor electronics module) in the sensor connection housing provide information about the device status.



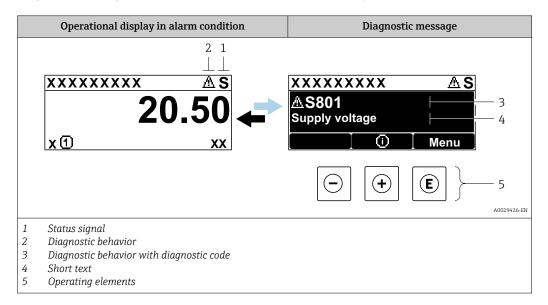
- 1 Communication
- 2 Device status
- 3 Supply voltage

| LED | | Color | Meaning |
|-------------------------|-----------------------|---------------------|---|
| 1 | Communication | White | Communication active. |
| 2 Device status (normal | Red | Error | |
| | operation) | Flashing red | Warning |
| | Device status (during | Flashes red slowly | If > 30 seconds: problem with the boot loader. |
| | start-up) | Flashes red quickly | If > 30 seconds: compatibility problem when reading the firmware. |
| 3 | Supply voltage | Green | Supply voltage is ok. |
| | | Off | Supply voltage is off or too low. |

Diagnostic information on local display 12.3

12.3.1 **Diagnostic message**

Faults detected by the self-monitoring system of the measuring device are displayed as a diagnostic message in alternation with the operational display.



If two or more diagnostic events are pending simultaneously, only the message of the diagnostic event with the highest priority is shown.

Other diagnostic events that have occurred can be displayed in the **Diagnostics** menu:

- Via parameter $\rightarrow \cong 237$
- Via submenus →
 ⁽²⁾ 237

Status signals

The status signals provide information on the state and reliability of the device by categorizing the cause of the diagnostic information (diagnostic event).



The status signals are categorized according to VDI/VDE 2650 and NAMUR Recommendation NE 107: F = Failure, C = Function Check, S = Out of Specification, M = Maintenance Required

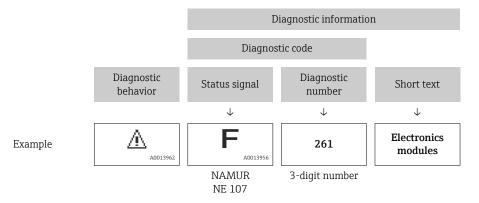
| Symbol | Meaning |
|--------|--|
| F | Failure A device error has occurred. The measured value is no longer valid. |
| С | Function check The device is in service mode (e.g. during a simulation). |
| S | Out of specification The device is being operated: Outside its technical specification limits (e.g. outside the process temperature range) |
| М | Maintenance required Maintenance is required. The measured value remains valid. |

Diagnostic behavior

| Symbol | Meaning |
|--------|---|
| * | Alarm Measurement is interrupted. Signal outputs and totalizers assume the defined alarm condition. A diagnostic message is generated. |
| Δ | Warning Measurement is resumed. The signal outputs and totalizers are not affected. A diagnostic message is generated. |

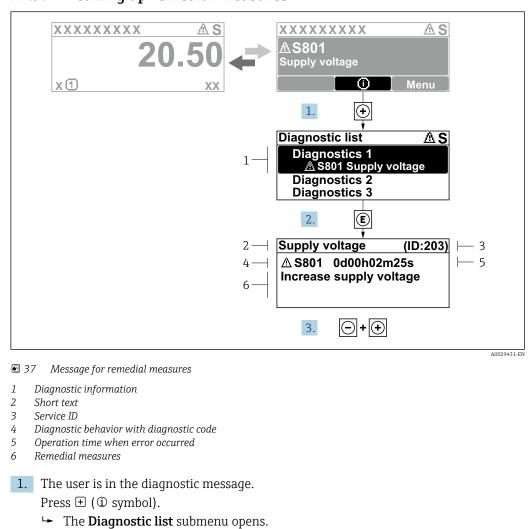
Diagnostic information

The fault can be identified using the diagnostic information. The short text helps you by providing information about the fault. In addition, the corresponding symbol for the diagnostic behavior is displayed in front of the diagnostic information on the local display.



Operating elements

| Operating key | Meaning |
|---------------|--|
| + | Plus key In menu, submenu Opens the message about the remedial measures. |
| E | Enter key In menu, submenu Opens the operating menu. |



12.3.2 Calling up remedial measures

- 2. Select the desired diagnostic event with \pm or \Box and press $\mathbb E$.
 - \blacktriangleright The message about the remedial measures opens.
- 3. Press = + \pm simultaneously.
 - └ The message about the remedial measures closes.

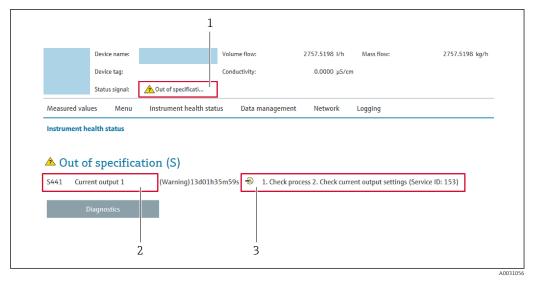
The user is in the **Diagnostics** menu at an entry for a diagnostics event, e.g. in the **Diagnostic list** submenu or **Previous diagnostics** parameter.

- 1. Press E.
 - └ The message for the remedial measures for the selected diagnostic event opens.
- 2. Press + + simultaneously.
 - \blacktriangleright The message for the remedial measures closes.

12.4 Diagnostic information in the web browser

12.4.1 Diagnostic options

Any faults detected by the measuring device are displayed in the Web browser on the home page once the user has logged on.



- 1 Status area with status signal
- 2 Diagnostic information
- 3 Remedial measures with service ID

In addition, diagnostic events which have occurred can be shown in the **Diagnostics** menu:

- Via parameter →
 ⁽¹⁾ 237
- Via submenu → 🗎 237

Status signals

The status signals provide information on the state and reliability of the device by categorizing the cause of the diagnostic information (diagnostic event).

| Symbol | Meaning |
|------------|--|
| \otimes | Failure A device error has occurred. The measured value is no longer valid. |
| | Function check The device is in service mode (e.g. during a simulation). |
| <u>^</u> | Out of specification The device is being operated: Outside its technical specification limits (e.g. outside the process temperature range) |
| \bigcirc | Maintenance required Maintenance is required. The measured value remains valid. |

The status signals are categorized in accordance with VDI/VDE 2650 and NAMUR Recommendation NE 107.

12.4.2 Calling up remedy information

Remedy information is provided for every diagnostic event to ensure that problems can be rectified quickly. These measures are displayed in red along with the diagnostic event and the related diagnostic information.

12.5 Diagnostic information in FieldCare or DeviceCare

12.5.1 Diagnostic options

Any faults detected by the measuring device are displayed on the home page of the operating tool once the connection has been established.

| D 📽 🖬 🍜 🕋 🖾 🗅 📖 🏻 🛬 Xxxxxx/// | : 💽 (1 < 1) (1 | š \$ F • i d d d d d |
|--|---------------------------------------|--|
| Device name: XXXXXXX Device tag: XXXXXXX Status signal: | Function check | Mass flow: ₽ 12.34 kg/h Volume flow: ₽ 12.34 m³/h (C) |
| Xxxxxx Xxxxxxx Xxxxxx Xxxx | C485 Simu Deactivate Mainenance | Instrument health status Image: Second status < |

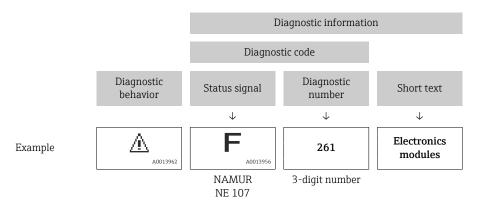
- 1 Status area with status signal \rightarrow \square 177
- 2 Diagnostic information $\rightarrow \square 178$
- 3 Remedial measures with service ID

In addition, diagnostic events which have occurred can be shown in the **Diagnostics** menu:

- Via parameter $\rightarrow \cong 237$
- Via submenu → 🗎 237

Diagnostic information

The fault can be identified using the diagnostic information. The short text helps you by providing information about the fault. In addition, the corresponding symbol for the diagnostic behavior is displayed in front of the diagnostic information on the local display.



12.5.2 Calling up remedy information

Remedy information is provided for every diagnostic event to ensure that problems can be rectified quickly:

- On the home page
- Remedy information is displayed in a separate field below the diagnostics information.
- In the **Diagnostics** menu

Remedy information can be called up in the working area of the user interface.

The user is in the **Diagnostics** menu.

1. Call up the desired parameter.

- 2. On the right in the working area, mouse over the parameter.
 - └ A tool tip with remedy information for the diagnostic event appears.

12.6 Adapting the diagnostic information

12.6.1 Adapting the diagnostic behavior

Each item of diagnostic information is assigned a specific diagnostic behavior at the factory. The user can change this assignment for specific diagnostic information in the **Diagnostic behavior** submenu.

Diagnostic behavior in accordance with Specification PROFIBUS PA Profile 3.02, Condensed Status.

Expert \rightarrow System \rightarrow Diagnostic handling \rightarrow Diagnostic behavior

| F//Diagn. behaviorDiagnostic no.442Diagnostic no.443 | 0658-1 Warning | |
|--|-------------------|-------------|
| | J | A0019179-EN |

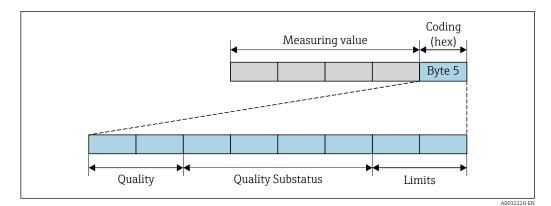
Available diagnostic behaviors

The following diagnostic behaviors can be assigned:

| Diagnostic behavior | Description |
|---------------------|---|
| Alarm | The device stops measurement. The totalizers assume the defined alarm condition. A diagnostic message is generated. |
| Warning | The device continues to measure. Measured value output via PROFIBUS and totalizers are not affected. A diagnostic message is generated. |
| Logbook entry only | The device continues to measure. The diagnostic message is only displayed in the Event logbook submenu (Event list submenu) and is not displayed in alternating sequence with the operational display. |
| Off | The diagnostic event is ignored, and no diagnostic message is generated or entered. |

Displaying the measured value status

If the Analog Input, Digital Input and Totalizer function blocks are configured for cyclic data transmission, the device status is coded as per PROFIBUS PA Profile 3.02 Specification and transmitted along with the measured value to the PROFIBUS Master (Class 1) via the coding byte (byte 5). The coding byte is split into three segments: Quality, Quality Substatus and Limits.



☑ 38 Structure of the coding byte

The content of the coding byte depends on the configured failure mode in the individual function block. Depending on which failure mode has been configured, status information in accordance with PROFINET PA Profile Specification 4 is transmitted to the PROFIBUS master (Class 1) via the coding byte status information.

Determining the measured value status and device status via the diagnostic behavior

When the diagnostic behavior is assigned, this also changes the measured value status and device status for the diagnostic information. The measured value status and device status depend on the choice of diagnostic behavior and on the group in which the diagnostic information is located.

The diagnostic information is grouped as follows:

- Diagnostic information pertaining to the sensor: diagnostic number 000 to 199 $\rightarrow \cong 183$
- Diagnostic information pertaining to the electronics: diagnostic number 200 to 399 $\rightarrow \ \textcircled{}$ 184
- Diagnostic information pertaining to the configuration: diagnostic number 400 to 599 \rightarrow B 184
- Diagnostic information pertaining to the process: diagnostic number 800 to 999 $\rightarrow \ \textcircled{}$ 184

Depending on the group in which the diagnostic information is located, the following measured value status and device status are firmly assigned to the particular diagnostic behavior:

| Diagnostic behavior | M | leasured value st | Device diagnosis | | |
|---------------------|---------|-------------------------|------------------|---------------------|-------------------------|
| (configurable) | Quality | Quality Substatus | Coding (hex) | Category (NE107) | (fixed assignment) |
| Alarm | BAD | Maintenance alarm | 0x24 to 0x27 | F (Failure) | Maintenance alarm |
| Warning | GOOD | Maintenance demanded | 0xA8 to 0xAB | M (Maintenance) | Maintenance demanded |
| Logbook entry only | GOOD | ok | 0x80 to 0x8E | _ | _ |
| Off | 0000 | UK | UXUU LU UXUE | | |

Diagnostic information pertaining to the sensor: diagnostic number 000 to 199

Diagnostic information pertaining to the electronics: diagnostic number 200 to 399

Diagnostic number 200 to 301, 303 to 399

| Discussion | N | leasured value st | Dovice discussion | | | |
|---------------------------------------|---------|----------------------|-------------------|---------------------|--|--|
| Diagnostic behavior (configurable) | Quality | Quality Substatus | Coding (hex) | Category (NE107) | Device diagnostics (fixed assignment) | |
| Alarm | BAD | Maintenance | 0x24 to 0x27 | F | Maintenance | |
| Warning | DAD | alarm | 0.24 10 0.27 | (Failure) | alarm | |
| Logbook entry only | GOOD | COOD | - 1- | 000 +- 005 | | |
| Off | GOOD | ok | 0x80 to 0x8E | _ | _ | |

Diagnostic information 302

| Diagnostic behavior | N | leasured value st | Device diagnostics | | |
|---------------------|---------|-----------------------------------|--------------------|---------------------|--------------------|
| (configurable) | Quality | Quality Substatus | Coding (hex) | Category (NE107) | (fixed assignment) |
| Alarm | BAD | Function check, local override | 0x24 to 0x27 | С | Function check |
| Warning | GOOD | Function check | 0xBC to 0xBF | _ | - |

Data logging continues when Heartbeat Verification is started. The signal outputs and totalizers are not affected.

- Signal status: Function check
- Choice of diagnostic behavior: alarm or warning (factory setting)

When the Heartbeat Verification is started, data logging is interrupted, the last valid measured value is output and the totalizer counter is stopped.

Diagnostic information pertaining to the configuration: diagnostic number 400 to 599

| Diagnostic behavior | M | leasured value sta | Device diagnosis | | | |
|---------------------|---------------|----------------------|------------------|--------------------------------|------------------------------|--|
| (configurable) | Quality | Quality Substatus | Coding (hex) | Category (NE107) | (fixed assignment) | |
| Alarm | BAD | Process related | 0x28 to 0x2B | F (Failure) | Invalid process condition | |
| Warning | UNCERTA IN | Process related | 0x78 to 0x7B | S (Out of specification) | Invalid process condition | |
| Logbook entry only | GOOD | 000 | ok | 0x80 to 0x8E | _ | |
| Off | GOOD | UK | UXOU IU UXOL | _ | | |

Diagnostic information pertaining to the process: diagnostic number 800 to 999

| Diagnostic behavior | M | Device diagnosis | | | |
|---------------------|---------------|----------------------|-----------------|--------------------------------|------------------------------|
| (configurable) | Quality | Quality Substatus | Coding (hex) | Category (NE107) | (fixed assignment) |
| Alarm | BAD | Process related | 0x28 to 0x2B | F (Failure) | Invalid process condition |
| Warning | UNCERTA IN | Process related | 0x78 to 0x7B | S (Out of specification) | Invalid process condition |

| Diagnostis hohovior | N | leasured value sta | Device diagnosis | | |
|---------------------------------------|---------|----------------------|------------------|---------------------|--|
| Diagnostic behavior (configurable) | Quality | Quality Substatus | Coding (hex) | Category (NE107) | Device diagnosis (fixed assignment) |
| Logbook entry only | GOOD | ok | 0x80 to 0x8E | _ | _ |
| Off | GOOD | UK | UXOU LU UXOE | - | _ |

12.7 Overview of diagnostic information

• The amount of diagnostic information and the number of measured variables affected increase if the measuring device has one or more application packages.

• All of the measured variables affected in the entire Promass instrument family are always listed under "Measured variables affected". The measured variables available for the device in question depend on the device version. When assigning the measured variables to the device functions, for example to the individual outputs, all of the measured variables available for the device version in question are available for selection.

In the case of some items of diagnostic information, the diagnostic behavior can be changed. Adapting the diagnostic information $\rightarrow \square$ 182

12.7.1 Diagnostic of sensor

| | Diagnostic in | nformation | Remedy instructions | |
|-----|---|-------------------|--|--|
| No. | Sh | ort text | | |
|)22 | Temperature sensor defective | | 1. Check or replace sensor electronic module (ISEM) | |
| | Measured variable status | | If available: Check connection cable between sensor and transmitter Replace sensor | |
| | Quality | Bad | | |
| | Quality substatus | Maintenance alarm | | |
| | Coding (hex) | 0x24 to 0x27 | | |
| | Status signal | F | | |
| | Diagnostic behavior | Alarm | | |
| | Influenced measured variables | | | |
| | Oscillation amplitude 1 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Carrier corrected volume flow Carrier corrected volume flow Concentration Oscillation damping 1 Density Oil density Dynamic viscosity Empty pipe detection option GSV flow | | ptionOscillation damping fluctuation 1Oscillation damping fluctuation 2Frequency fluctuation 1Frequency fluctuation 2Target mass flowCarrier volume flowTarget volume flowTemp. compensated dynamic viscosityTemp. compensated kinematic viscosityTemperatureNot 1StatusOil volume flowOil volume flowWater volume flowWater cut | |

| | Diagnostic i | nformation | Remedy instructions |
|-----|--|--|---|
| No. | Sh | ort text | |
| 046 | Sensor limit exceeded | | 1. Inspect sensor |
| | Measured variable status [fro | m the factory] ¹⁾ | 2. Check process condition |
| | Quality | Good | |
| | Quality substatus | Maintenance demanded | |
| | Coding (hex) | 0xA8 to 0xAB | |
| | Status signal | S | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variable | S | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Carrier corrected volume flow Concentration Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature Empty pipe detection option GSV flow GSV flow alternative | v NSV flow NSV flow alternativ External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density | ptionOscillation damping fluctuation 1Oscillation damping fluctuation 2Frequency fluctuation 1Frequency fluctuation 2Target mass flowCarrier volume flowCarrier volume flowTarget volume flowTemp. compensated dynamic viscosityTemp. compensated kinematic viscosityTemperatureccy 1Statuscy 2Volume flowOil volume flowWater volume flowWater cut |

| | Diagnostic | information | Remedy instructions |
|-----|--|-------------------|--|
| No. | Short text | | |
| 062 | Sensor connection faulty | | 1. Check or replace sensor electronic module (ISEM) |
| | Measured variable status | | 2. If available: Check connection cable between sensor and transmitter 3. Replace sensor |
| | Quality | Bad | |
| | Quality substatus | Maintenance alarm | |
| | Coding (hex) | 0x24 to 0x27 | _ |
| | Status signal | F | |
| | Diagnostic behavior Alarm | | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Carrier corrected volume flow Carrier corrected volume flow Concentration Oscillation damping 1 Density Oil density Oscillation frequ Dynamic viscosity Sensor electronic temperature (ISEM) Empty pipe detection option GSV flow | | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Status Oil volume flow Volume flow Water volume flow Water cut |

| | Diagnostic in | formation | Remedy instructions |
|-----|---|--|---|
| No. | Sho | ort text | |
| 063 | Exciter current faulty | | 1. Check or replace sensor electronic module (ISEM) |
| | Measured variable status | | If available: Check connection cable between sensor and transmitter Replace sensor |
| | Quality I | Bad | |
| | Quality substatus | Maintenance alarm | |
| | Coding (hex) | 0x24 to 0x27 | |
| | Status signal S | S | |
| | Diagnostic behavior | Alarm | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature Empty pipe detection option GSV flow | NSV flow NSV flow alternat External pressure Exciter current 1 Exciter current 2 Oscillation frequent Oscillation frequent S&W volume flow Reference density | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Oil volume flow Oil volume flow Water volume flow Water cut |

| | Diagnostic inf | ormation | Remedy instructions |
|-----|--|---|---|
| No. | Shor | rt text | |
|)82 | Data storage | | 1. Check module connections |
| | Measured variable status | | 2. Contact service |
| | Quality B | ad | |
| | Quality substatus N | laintenance alarm | |
| | Coding (hex) 0: | x24 to 0x27 | |
| | Status signal F | | |
| | Diagnostic behavior A | larm | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature Empty pipe detection option | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density a Corrected volume fi | Oscillation damping fluctuation 1 Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Target volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Cy 1 Volume flow Water volume flow Water cut |

| Diagnostic information | | | Remedy instructions |
|------------------------|--|---|--|
| No. | Shor | rt text | |
| 083 | Memory content | | 1. Restart device |
| | Measured variable status | | Restore HistoROM S-DAT backup ('Device reset' parameter) Replace HistoROM S-DAT |
| | Quality B | ad | - |
| | Quality substatus N | Naintenance alarm | |
| | Coding (hex) 0: | x24 to 0x27 | |
| | Status signal F | | |
| | Diagnostic behavior A | larm | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature Empty pipe detection option | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequent Oscillation frequent S&W volume flow Reference density a Corrected volume flow | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Cy 1 Volume flow Water volume flow Water cut |

| | Diagnostic info | ormation | Remedy instructions |
|-----|--|---|--|
| No. | Shor | rt text | |
| 140 | Sensor signal asymmetrical Measured variable status [from the factory] 1) | | 1. Check or replace sensor electronic module (ISEM) |
| | | | If available: Check connection cable between sensor and transmitter Replace sensor |
| | Quality Ba | ad | • |
| | Quality substatus M | laintenance alarm | |
| | Coding (hex) | x24 to 0x27 | |
| | Status signal S | | |
| | Diagnostic behavior A | larm | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature 6 Empty pipe detection option | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density a Corrected volume flow | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Cy 1 Volume flow Water volume flow Water cut |

| | Diagnostic i | nformation | Remedy instructions |
|-----|--|--|---|
| No. | Sł | nort text | |
| 144 | Measuring error too high | | 1. Check or change sensor |
| | Measured variable status [fro | om the factory] ¹⁾ | 2. Check process conditions |
| | Quality | Bad | |
| | Quality substatus | Maintenance alarm | |
| | Coding (hex) | 0x24 to 0x27 | |
| | Status signal | F | |
| | Diagnostic behavior | Alarm | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Carrier corrected volume flow Concentration Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature Empty pipe detection option GSV flow GSV flow alternative | w NSV flow NSV flow alternati External pressure Exciter current 1 Exciter current 2 Oscillation frequer S&W volume flow re (ISEM) Reference density | ptionOscillation damping fluctuation 1Oscillation damping fluctuation 2Frequency fluctuation 1Frequency fluctuation 2Target mass flowCarrier volume flowCarrier volume flowTarget volume flowTemp. compensated dynamic viscosityTemp. compensated kinematic viscosityTemperaturestatusvolume flowOil volume flowOil volume flowWater volume flowWater cut |

12.7.2 Diagnostic of electronic

| | Diagnostic infe | ormation | | Remedy instructions |
|-----|---|---|--|---|
| No. | Shor | rt text | | |
| 01 | Device failure | | 1. Restart device | |
| | Measured variable status | | 2. Contact service | |
| | Quality Ba | ad | | |
| | Quality substatus M | laintenance alarm | | |
| | Coding (hex) 02 | x24 to 0x27 | | |
| | Status signal F | | | |
| | Diagnostic behavior A | larm | | |
| | Influenced measured variables | | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature 6 | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off of Mass flow Oil mass flow Oil mass flow Water mass flow Water mass flow HBSI NSV flow NSV flow NSV flow alternative Exciter current 1 Exciter current 2 Oscillation frequent Oscillation frequent S&W volume flow Reference density a Corrected volume f | ption re cy 1 cy 2 alternative | Oil corrected volume flow Water corrected volume flow Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Volume flow Oil volume flow Water volume flow Water cut |

| Diagnostic information | | | Remedy instructions |
|------------------------|---|---|---|
| No. | Shor | rt text | |
| 42 | Software incompatible | | 1. Check software |
| | Measured variable status | | 2. Flash or change main electronics module |
| | Quality Ba | ad | |
| | Quality substatus M | Naintenance alarm | |
| | Coding (hex) 02 | x24 to 0x27 | |
| | Status signal F | | |
| | Diagnostic behavior A | larm | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density a Corrected volume flow | Oscillation damping fluctuation 1 Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Ve Temp. compensated dynamic viscosity Temperature Status Cy 1 Volume flow Water volume flow Water cut |

| | Diagnostic ir | nformation | Remedy instructions |
|-----|---|--|---|
| No. | She | ort text | |
| 252 | Modules incompatible Measured variable status | | 1. Check electronic modules |
| | | | Check if correct modules are available (e.g. NEx, Ex) Replace electronic modules |
| | Quality | Bad | |
| | Quality substatus | Maintenance alarm | |
| | Coding (hex) | 0x24 to 0x27 | |
| | Status signal | F | |
| | Diagnostic behavior | Alarm | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature | Water mass flow HBSI NSV flow NSV flow alternati External pressure Exciter current 1 Exciter current 2 Oscillation frequer Oscillation frequer S&W volume flow Reference density e (ISEM) | y Oscillation damping fluctuation 1 ption Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Carrier volume flow Target volume flow ve Temp. compensated dynamic viscosity Temp. compensated kinematic viscosity Temperature Status Volume flow ucy 1 Volume flow water volume flow Water cut alternative Water cut |

| Sensor electronic temperature (ISEM) Empty pipe detection option | |
|---|--|
| | |

| | Diagnostic | information | Remedy instructions |
|-----|--|---|---|
| No. | 2 | Short text | |
| 252 | Modules incompatible Measured variable status | | 1. Check if correct electronic modul is plugged |
| | | | 2. Replace electronic module |
| | Quality | Bad | |
| | Quality substatus | Maintenance alarm | |
| | Coding (hex) | 0x24 to 0x27 | |
| | Status signal | F | |
| | Diagnostic behavior | Alarm | |
| | Influenced measured variab | les | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density | Dynamic viscosity Sensor electronic ti Empty pipe detect Kinematic viscosity Low flow cut off o Mass flow HBSI External pressure Exciter current 1 Exciter current 2 Oscillation frequent | ion optionOscillation damping fluctuation 1Oscillation damping fluctuation 2ptionFrequency fluctuation 1Frequency fluctuation 2Target mass flowTemp. compensated dynamic viscosityTemperaturecy 1Status |

| | Diagnostic inf | formation | Remedy instructions | |
|-----|---|---|--|--|
| No. | Shor | rt text | | |
| 262 | Sensor electronic connection faulty Measured variable status | | 1. Check or replace connection cable between sensor electronic module | |
| | | | (ISEM) and main electronics 2. Check or replace ISEM or main electronics | |
| | Quality Ba | ad | | |
| | Quality substatus M | Naintenance alarm | | |
| | Coding (hex) 02 | x24 to 0x27 | | |
| | Status signal F | | | |
| | Diagnostic behavior A | larm | | |
| | Influenced measured variables | | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density a Corrected volume flow | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Cy 1 Volume flow Water volume flow Water cut | |

| | Diagnostic inf | ormation | Remedy instructions |
|-----|---|---|---|
| No. | Shor | rt text | |
| 270 | Main electronic failure | | Change main electronic module |
| | Measured variable status | | |
| | Quality Ba | ad | |
| | Quality substatus M | laintenance alarm | |
| | Coding (hex) 02 | x24 to 0x27 | |
| | Status signal F | | |
| | Diagnostic behavior A | larm | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density a Corrected volume fi | Oscillation damping fluctuation 1 Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Target volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Cy 1 Volume flow Water volume flow Water cut |

| Diagnostic information | | | Remedy instructions |
|------------------------|--|---|--|
| No. | Sh | ort text | |
| 271 | Main electronic failure | | 1. Restart device |
| | Measured variable status | | 2. Change main electronic module |
| | Quality | Bad | |
| | Quality substatus | Maintenance alarm | |
| | Coding (hex) | 0x24 to 0x27 | |
| | Status signal | F | |
| | Diagnostic behavior | Alarm | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Sensor electronic temperature | v • Water mass flow • HBSI • NSV flow • NSV flow alternati • External pressure • Exciter current 1 • Exciter current 2 • Oscillation frequent • Oscillation frequent • S&W volume flow • Reference density • re (ISEM) | Oscillation damping fluctuation 1 Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Volume flow Volume flow Water volume flow Water cut |

| | Diagnostic inf | formation | | Remedy instructions |
|-----|---|---|--|---|
| No. | Shor | rt text | | |
| 272 | Main electronic failure | | 1. Restart device | |
| | Measured variable status | | 2. Contact service | |
| | Quality Ba | ad | | |
| | Quality substatus M | Naintenance alarm | | |
| | Coding (hex) 02 | x24 to 0x27 | | |
| | Status signal F | | | |
| | Diagnostic behavior A | larm | | |
| | Influenced measured variables | | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature 4 | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequence Oscillation frequence S&W volume flow Reference density a Corrected volume flow | ption re cy 1 cy 2 alternative | Oil corrected volume flow Water corrected volume flow Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Volume flow Oil volume flow Water volume flow Water cut |

| | Diagnostic inf | formation | | Remedy instructions |
|-----|---|--|--|---|
| No. | Sho | rt text | | |
| 273 | Main electronic failure | | Change electronic | |
| | Measured variable status | | | |
| | Quality B | Bad | | |
| | Quality substatus N | Naintenance alarm | | |
| | Coding (hex) | 0x24 to 0x27 | | |
| | Status signal F | | | |
| | Diagnostic behavior A | Alarm | | |
| | Influenced measured variables | | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Sensor electronic temperature Empty pipe detection option | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density a Corrected volume f | ption re cy 1 cy 2 llternative | Oil corrected volume flow Water corrected volume flow Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Volume flow Oil volume flow Water volume flow Water cut |

| | Diagnostic | information | Remedy instructions |
|-----|--|--|---|
| No. | Short text | | |
| 275 | I/O module 1 to n defective | | Change I/O module |
| | Measured variable status | | |
| | Quality | Bad | |
| | Quality substatus | Maintenance alarm | |
| | Coding (hex) | 0x24 to 0x27 | |
| | Status signal | F | - |
| | Diagnostic behavior | Alarm | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density | Dynamic viscosity Sensor electronic te Empty pipe detect Kinematic viscosity Low flow cut off op Mass flow HBSI External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen | tion optionOscillation damping fluctuation 1yOscillation damping fluctuation 2optionFrequency fluctuation 1Frequency fluctuation 2Target mass flowTemp. compensated dynamic viscosityTemp. compensated kinematic viscosityTemperatureStatus |

| Diagnostic information | | | | Remedy instructions |
|------------------------|--|---|--|---|
| 0. | 2 | Short text | | |
| 76 | I/O module 1 to n faulty | | 1. Restart device | |
| | Measured variable status | | 2. Change I/O module | |
| | Quality | Bad | | |
| | Quality substatus | Maintenance alarm | | |
| | Coding (hex) | 0x24 to 0x27 | | |
| | Status signal | F | | |
| | Diagnostic behavior | Alarm | | |
| | Influenced measured variab | les | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flot Carrier corrected volume flot Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 | Empty pipe deternation Kinematic viscos Low flow cut off Mass flow | etemperature (ISEM) ection option ity option e ency 1 ency 2 | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temprature Status Volume flow |

Density

Corrected volume flow

Diagnostic information Remedy instructions No. Short text 283 Memory content 1. Reset device 2. Contact service Measured variable status Bad Quality Maintenance alarm Quality substatus 0x24 to 0x27 Coding (hex) F Status signal Diagnostic behavior Alarm Influenced measured variables Oscillation amplitude 1 GSV flow Oil corrected volume flow • Oscillation amplitude 2 GSV flow alternative Water corrected volume flow Kinematic viscosity Oscillation damping fluctuation 1 Signal asymmetry Oscillation damping fluctuation 2 Carrier mass flow Low flow cut off option Carrier pipe temperature Mass flow Frequency fluctuation 1 Oil mass flow Frequency fluctuation 2 Target corrected volume flow Carrier corrected volume flow Water mass flow Target mass flow Concentration HBSI Carrier volume flow Measured values 1 NSV flow Target volume flow • Temp. compensated dynamic viscosity Measured values 2. NSV flow alternative Measured values 3 External pressure Temp. compensated kinematic viscosity Oscillation damping 1 • Exciter current 1 Temperature Oscillation damping 2 • Exciter current 2 Status Density Oscillation frequency 1 Volume flow Oil density Oscillation frequency 2 Oil volume flow Water density S&W volume flow Water volume flow Dynamic viscosity Water cut

- Reference density
- Reference density alternative
- Corrected volume flow

Endress+Hauser

Sensor electronic temperature (ISEM)

Empty pipe detection option

| Diagnostic information | | | Remedy instructions |
|------------------------|---|---|--|
| о. | Shor | rt text | |
|)2 | Device verification active | | Device verification active, please wait. |
| | Measured variable status [from | the factory] ¹⁾ | |
| | Quality G | ood | |
| | Quality substatus Fi | unction check | |
| | Coding (hex) 02 | xBC to 0xBF | |
| | Status signal C | | |
| | Diagnostic behavior W | Varning | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequent Oscillation frequent S&W volume flow Reference density Corrected volume flow | Oscillation damping fluctuation 1 Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Volume flow Volume flow Water volume flow Water cut |

| | Diagno | ostic information | Remedy instructions |
|----|-------------------------------|-------------------|---|
| o. | | Short text | |
| 33 | | | 1. Apply I/O module configuration (parameter 'Apply I/O configuration') |
| | Measured variable status | | 2. Afterwards reload device description and check wiring |
| | Quality | Bad | |
| | Quality substatus | Maintenance alarm | |
| | Coding (hex) | 0x24 to 0x27 | |
| | Status signal | M | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | - | | |

| | Diagnostic inf | formation | | Remedy instructions |
|-----|--|---|--|---|
| No. | Sho | ort text | | |
| 311 | Electronic failure | | 1. Do not reset device | |
| | Measured variable status | | 2. Contact service | |
| | Quality B | Bad | | |
| | Quality substatus N | Maintenance alarm | | |
| | Coding (hex) 0 | 0x24 to 0x27 | | |
| | Status signal N | N | | |
| | Diagnostic behavior V | Warning | | |
| | Influenced measured variables | | • | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature Empty pipe detection option | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow HBSI NSV flow NSV flow alternative Exciter current 1 Exciter current 2 Oscillation frequent Oscillation frequent S&W volume flow Reference density Corrected volume flow | ption ve cy 1 cy 2 alternative | Oil corrected volume flow Water corrected volume flow Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Volume flow Oil volume flow Water volume flow Water cut |

| Diagnostic information | | nformation | Remedy instructions |
|------------------------|---|--|--|
| No. | Sh | ort text | |
| 332 | Writing in HistoROM backup failed | | Replace user interface board |
| | Measured variable status | | Ex d/XP: replace transmitter |
| | Quality | Bad | _ |
| | Quality substatus | Maintenance alarm | - |
| | Coding (hex) | 0x24 to 0x27 | - |
| | Status signal | F | |
| | Diagnostic behavior | Alarm | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature Empty pipe detection option GSV flow GSV flow alternative | NSV flow NSV flow alternat External pressure Exciter current 1 Exciter current 2 Oscillation freque Oscillation freque S&W volume flow Reference density | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temp. compensated kinematic viscosity Temperature Status Volume flow Oil volume flow Water volume flow Water cut |

| | Diagnostic | information | Remedy instructions |
|-----|--|--|--|
| No. | S | Short text | |
| 361 | I/O module 1 to n faulty Measured variable status | | 1. Restart device |
| | | | Check electronic modules Change I/O Modul or main electronics |
| | Quality | Bad | |
| | Quality substatus | Maintenance alarm | |
| | Coding (hex) | 0x24 to 0x27 | |
| | Status signal | F | |
| | Diagnostic behavior | Alarm | |
| | Influenced measured variab | les | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density | Dynamic viscosity Sensor electronic t Empty pipe detect Kinematic viscosity Low flow cut off o Mass flow HBSI External pressure Exciter current 1 Exciter current 2 Oscillation frequent Oscillation frequent | ion optionOscillation damping fluctuation 1Oscillation damping fluctuation 2ptionFrequency fluctuation 1Frequency fluctuation 2Target mass flowTemp. compensated dynamic viscosityTemp. compensated kinematic viscosityTemperaturecy 1Status |

| | Diagnostic inf | formation | Remedy instructions |
|-----|---|--|--|
| No. | Sho | rt text | |
| 372 | Sensor electronic (ISEM) faulty | | 1. Restart device |
| | Measured variable status | | Check if failure recurs Replace sensor electronic module (ISEM) |
| | Quality B | Bad | |
| | Quality substatus N | Naintenance alarm | |
| | Coding (hex) 0 | 0x24 to 0x27 | |
| | Status signal F | · | |
| | Diagnostic behavior A | Alarm | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Sensor electronic temperature Empty pipe detection option | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density a Corrected volume flow | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Cy 1 Volume flow Water volume flow Water cut |

| Diagnostic information | | ormation | Remedy instructions |
|------------------------|---|---|---|
| o. | Sho | rt text | |
| 73 | Sensor electronic (ISEM) faulty | | 1. Transfer data or reset device |
| | Measured variable status | | 2. Contact service |
| | Quality B | ad | |
| | Quality substatus N | laintenance alarm | |
| | Coding (hex) 0: | x24 to 0x27 | |
| | Status signal F | | |
| | Diagnostic behavior A | larm | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Sensor electronic temperature Empty pipe detection option | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density a Corrected volume flow | Oscillation damping fluctuation 1 Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Ve Temp. compensated dynamic viscosity Temperature Status Cy 1 Volume flow Water volume flow Water cut |

| | Diagnostic | information | Remedy instructions | | |
|-----|---|--|---|--|--|
| No. | Short text | | | | |
| 374 | Sensor electronic (ISEM) fault | y | 1. Restart device | | |
| | Measured variable status [fr | om the factory] ¹⁾ | Check if failure recurs Replace sensor electronic module (ISEM) | | |
| | Quality | Bad | | | |
| | Quality substatus Maintenance ala | Maintenance alarm | | | |
| | Coding (hex) | 0x24 to 0x27 | | | |
| | Status signal | S | | | |
| | Diagnostic behavior | Warning | | | |
| | Influenced measured variables | | | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Concentration Oscillation damping 1 Oscillation damping 2 Density Dynamic viscosity Sensor electronic temperature | Empty pipe detect Kinematic viscosity Low flow cut off of Mass flow HBSI External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen Reference density | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Temp. compensated dynamic viscosity Temp. compensated kinematic viscosity Temperature | | |

| Diagnostic information | | formation | Remedy instructions |
|------------------------|--|-------------------|--|
| No. | Sho | ort text | |
| 375 | I/O- 1 to n communication failed | | 1. Restart device |
| | Measured variable status | | Check if failure recurs Replace module rack inclusive electronic modules |
| | Quality E | Bad | |
| | Quality substatus N | Maintenance alarm | |
| | Coding (hex) | 0x24 to 0x27 | |
| | Status signal F | 7 | |
| | Diagnostic behavior A | Alarm | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Empty pipe det Oscillation amplitude 2 GSV flow Signal asymmetry GSV flow alternative viscos Carrier mass flow Kinematic viscos Carrier orrected volume flow Carrier corrected volume flow Carrier corrected volume flow Carrier corrected volume flow Carrier corrected volume flow Carrier ass flow Carrier viscos Carrier corrected volume flow Oil mass flow Concentration Water mass flow Measured values 1 Measured values 2 NSV flow Measured values 3 Oscillation damping 1 External pressure Oscillation damping 2 Exciter current 2 Density Oscillation freque Water density Oscillation freque Dynamic viscosity | | Corrected volume flow Ve Oil corrected volume flow Water corrected volume flow Volution damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Target volume flow Temp. compensated dynamic viscosity Temperature cy 1 |

| | Diagnostic inf | formation | | Remedy instructions |
|-----|--|---|--|---|
| lo. | Sho | rt text | | |
| 82 | Data storage | | 1. Insert T-DAT | |
| | Measured variable status | | 2. Replace T-DAT | |
| | Quality B | ad | | |
| | Quality substatus N | Naintenance alarm | | |
| | Coding (hex) 0 | x24 to 0x27 | | |
| | Status signal F | | | |
| | Diagnostic behavior A | larm | | |
| | Influenced measured variables | | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature Empty pipe detection option | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density a Corrected volume fi | ption re cy 1 cy 2 alternative | Oil corrected volume flow Water corrected volume flow Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Volume flow Oil volume flow Water volume flow Water cut |

| | Diagnostic information | | Remedy instructions | |
|-----|--|-------------------|---|--|
| No. | Short text | | | |
| 383 | Memory content | | 1. Restart device | |
| | Measured variable status | | 2. Delete T-DAT via 'Reset device' parameter 3. Replace T-DAT | |
| | Quality B | Bad | | |
| | Quality substatus N | Maintenance alarm | | |
| | Coding (hex) 0 | 0x24 to 0x27 | | |
| | Status signal F | 7 | | |
| | Diagnostic behavior A | Alarm | | |
| | Influenced measured variables | | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Exciter current 1 Density Oscillation frequet Water density Oscillation frequet Saw volume flow | | Corrected volume flow Oil corrected volume flow Water corrected volume flow Water corrected volume flow Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Cy 1 | |

| Diagnostic information | | nformation | Remedy instructions |
|------------------------|---|--|---|
| Io. | Short text | | |
| 87 | HistoROM backup failed | | Contact service organization |
| | Measured variable status | | |
| | Quality | Bad | |
| | Quality substatus | Maintenance alarm | |
| | Coding (hex) | 0x24 to 0x27 | |
| | Status signal | F | |
| | Diagnostic behavior | Alarm | |
| | Influenced measured variable | S | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature | v • Water mass flow • HBSI • NSV flow • NSV flow alternativ • External pressure • Exciter current 1 • Exciter current 2 • Oscillation frequent • Oscillation frequent • S&W volume flow • Reference density • re (ISEM) | y Oscillation damping fluctuation 1 ption Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Ve Temp. compensated dynamic viscosity Temp. compensated kinematic viscosity Temp. compensated kinematic viscosity Temperature Status Noty 1 Volume flow Water volume flow Water cut alternative |

12.7.3 Diagnostic of configuration

| | Diagnostic | information | Remedy instructions |
|-----|--|--|--|
| No. | Short text | | |
| 330 | Flash file invalid | | 1. Update firmware of device |
| | Measured variable status | | 2. Restart device |
| | Quality | Bad | |
| | Quality substatus | Maintenance alarm | |
| | Coding (hex) | 0x24 to 0x27 | |
| | Status signal | М | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variable | les | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density | Dynamic viscosity Sensor electronic to Empty pipe detect Kinematic viscosity Low flow cut off of Mass flow HBSI External pressure Exciter current 1 Exciter current 2 Oscillation frequent Oscillation frequent | ion optionOscillation damping fluctuation 1Oscillation damping fluctuation 2ptionFrequency fluctuation 1Frequency fluctuation 2Target mass flowTemp. compensated dynamic viscosityTemp. compensated kinematic viscosityTemperaturecy 1Status |

| | Diagnostic inf | formation | Remedy instructions |
|-----|---|---|--|
| No. | Shor | rt text | |
| 331 | Firmware update failed | | 1. Update firmware of device |
| | Measured variable status | | 2. Restart device |
| | Quality Ba | ad | |
| 1 | Quality substatus M | laintenance alarm | |
| | Coding (hex) | x24 to 0x27 | |
| | Status signal F | | |
| | Diagnostic behavior W | Varning | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature 4 | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density a Corrected volume flow | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Cy 1 Volume flow Water volume flow Water cut |

| | Diagnostic inf | formation | | Remedy instructions |
|-----|--|--|--|---|
| No. | Sho | ort text | | |
| 410 | Data transfer | | 1. Check connection | |
| | Measured variable status | | 2. Retry data transfer | |
| | Quality E | Bad | | |
| | Quality substatus N | Maintenance alarm | | |
| | Coding (hex) | 0x24 to 0x27 | | |
| | Status signal F | 7 | | |
| | Diagnostic behavior A | Alarm | | |
| | Influenced measured variables | | 1 | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature Empty pipe detection option | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density a Corrected volume flow | ption re cy 1 cy 2 alternative | Oil corrected volume flow Water corrected volume flow Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Volume flow Oil volume flow Water volume flow Water cut |

| | Diagnostic information | | Remedy instructions | |
|-----|--|--|---|--|
| No. | Short text | | | |
| 412 | Processing download | | Download active, please wait | |
| | Measured variable status | | | |
| | Quality | Uncertain | | |
| | Quality substatus I | Initial value | | |
| | Coding (hex) | 0x4C to 0x4F | | |
| | Status signal 0 | C | | |
| | Diagnostic behavior | Warning | | |
| | Influenced measured variables | 5 | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature Empty pipe detection option | HBSI NSV flow NSV flow alternati External pressure Exciter current 1 Exciter current 2 Oscillation frequent Oscillation frequent S&W volume flow Reference density Reference density | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Volume flow Volume flow Water volume flow Water cut | |

| | Diagno | ostic information | Remedy instructions |
|-----|-------------------------------|-------------------|---------------------|
| No. | | Short text | |
| 431 | Trim 1 to n | | Carry out trim |
| | Measured variable status | | |
| | Quality | Good | |
| | Quality substatus | Function check | |
| | Coding (hex) | OxBC to OxBF | |
| | Status signal | С | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | - | | |

| Diagnostic information | | | Remedy instructions | |
|------------------------|--|--|--|---|
| No. | Sho | ort text | | |
| 437 | Configuration incompatible | | 1. Restart device | |
| | Measured variable status | | 2. Contact service | |
| | Quality B | Bad | | |
| | Quality substatus N | Maintenance alarm | | |
| | Coding (hex) 0 | 0x24 to 0x27 | | |
| | Status signal F | 1 | | |
| | Diagnostic behavior A | Alarm | | |
| | Influenced measured variables | | 1 | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature Empty pipe detection option | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density a Corrected volume for | ption re cy 1 cy 2 alternative | Oil corrected volume flow Water corrected volume flow Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Volume flow Oil volume flow Water volume flow Water cut |

| | Diagnostic in | iformation | Remedy instructions | |
|-----|---|---|--|--|
| No. | Short text | | | |
| 438 | Dataset | | 1. Check data set file | |
| | Measured variable status | | Check device configuration Up- and download new configuration | |
| | Quality | Uncertain | | |
| | Quality substatus | Maintenance demanded | | |
| | Coding (hex) | 0x68 to 0x6B | | |
| | Status signal | М | | |
| | Diagnostic behavior | Warning | | |
| | Influenced measured variables | | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature | Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequent Oscillation frequent S&W volume flow Reference density Reference density | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Cy 1 Volume flow Water volume flow Water cut | |

| Diagnostic information | | | Remedy instructions |
|------------------------|---|----------------|--|
| No. | | Short text | |
| 441 | Current output 1 to n | | Check process Check current output settings |
| | Measured variable status [from the factory] ¹⁾ | | |
| | Quality | Good | |
| | Quality substatus | Function check | |
| | Coding (hex) | 0xBC to 0xBF | |
| | Status signal | S | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | - | | |

| Diagnostic information | | | Remedy instructions |
|------------------------|---|----------------|--|
| | | Short text | |
| Fre | Frequency output 1 to n | | Check process Check frequency output settings |
| Me | Measured variable status [from the factory] ¹⁾ | | |
| Qua | ıality | Good | |
| Qua | uality substatus | Function check | |
| Coc | oding (hex) | OxBC to OxBF | |
| Sta | atus signal | S | |
| Die | agnostic behavior | Warning | |

| | Diagno | stic information | Remedy instructions |
|-----|---|------------------|--|
| No. | | Short text | |
| 443 | Pulse output 1 to n | | Check process Check pulse output settings |
| | Measured variable status [from the factory] ¹⁾ | | |
| | Quality | Good | |
| | Quality substatus | Function check | |
| | Coding (hex) | 0xBC to 0xBF | |
| | Status signal | S | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | - | | |

1) Diagnostic behavior can be changed. This causes the overall status of the measured variable to change.

| | Diagno | stic information | Remedy instructions | | |
|-----|---|------------------|---|--|--|
| No. | | Short text | | | |
| 444 | Current input 1 to n | | Check process Check current input settings | | |
| | Measured variable status [from the factory] 1) | | | | |
| | Quality | Good | | | |
| | Quality substatus | Function check | | | |
| | Coding (hex) | 0xBC to 0xBF | | | |
| | Status signal | S | | | |
| | Diagnostic behavior | Warning | | | |
| | Influenced measured variables | | | | |
| | Measured values 1 Measured values 2 Measured values 3 | | | | |

| | Diagnos | tic information | | | Remedy instructions |
|-----|--|-------------------------------|--|--|--|
| No. | | Short text | | | |
| 453 | Flow override Measured variable status | | | Deactivate flow override | |
| | | | | | |
| | Quality | Good | | | |
| | Quality substatus | Function check | ζ. | | |
| | Coding (hex) | 0xBC to 0xBF | | | |
| | Status signal | С | | | |
| | Diagnostic behavior | Warning | | | |
| | Influenced measured variables | | | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume Carrier corrected volume Carrier corrected volume Concentration Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temper Empty pipe detection op GSV flow | flow flow rature (ISEM) | Kinematic viscosity Low flow cut off of Mass flow Oil mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density a Corrected volume f Oil corrected volume | ption ve ncy 1 ncy 2 alternative Flow | Water corrected volume flow Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Volume flow Oil volume flow Water volume flow Water cut |

| | Diagnos | stic information | Remedy instructions |
|-----|---|-------------------|---------------------------------------|
| No. | | Short text | |
| 463 | Analog input 1 to n selecti | on invalid | 1. Check module/channel configuration |
| | Measured variable status | | 2. Check I/O module configuration |
| | Quality | Bad | |
| | Quality substatus | Maintenance alarm | |
| | Coding (hex) | 0x24 to 0x27 | |
| | Status signal | F | |
| | Diagnostic behavior | Alarm | |
| | Influenced measured var | iables | |
| | Measured values 1 Measured values 2 Measured values 3 | | |

| | Diagno | stic information | Remedy instructions |
|-----|-------------------------------|------------------|------------------------|
| No. | | Short text | |
| 482 | FB not Auto/Cas | | Set Block in AUTO mode |
| | Measured variable status | | |
| | Quality | Good | |
| | Quality substatus | Ok | |
| | Coding (hex) | 0x80 to 0x83 | |
| | Status signal | F | |
| | Diagnostic behavior | Alarm | |
| | Influenced measured variables | | 1 |
| | - | | |

| | Diagnostic information | | | Remedy instructions |
|-----|---|--|---|--|
| No. | S | hort text | | |
| 484 | Failure mode simulation | | Deactivate simulation | |
| | Measured variable status | | | |
| | Quality | Bad | | |
| | Quality substatus | Function check | | |
| | Coding (hex) | 0x3C to 0x3F | | |
| | Status signal | С | | |
| | Diagnostic behavior | Alarm | | |
| | Influenced measured variables | | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperatu Empty pipe detection option GSV flow GSV flow alternative | w NSV flow NSV flow alternati External pressure Exciter current 1 Exciter current 2 Oscillation frequen S&W volume flow re (ISEM) Reference density | ption ve cy 1 cy 2 alternative low | Water corrected volume flow Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Volume flow Oil volume flow Water volume flow Water cut |

| | Diagnostic information | | | Remedy instructions | |
|-----|--|-----------------------------------|---|--|--|
| No. | | Short text | | | |
| 485 | Measured variable simulation | | | Deactivate simulation | |
| | Measured variable status | | | | |
| | Quality | Good | | | |
| | Quality substatus | Function check | : | | |
| | Coding (hex) | 0xBC to 0xBF | | | |
| | Status signal | С | | | |
| | Diagnostic behavior | Warning | | | |
| | Influenced measured variables | | | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume Carrier corrected volume Concentration Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic tempe Empty pipe detection of GSV flow | e flow e flow rature (ISEM) | Kinematic viscosity Low flow cut off o Mass flow Oil mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 1 Exciter current 2 Oscillation frequent Oscillation frequent S&W volume flow Reference density a Corrected volume flow | ption ve ncy 1 ncy 2 alternative clow | Water corrected volume flow Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Volume flow Oil volume flow Water volume flow Water cut |

| | Diagno | ostic information | Remedy instructions |
|-----|---|-------------------|-----------------------|
| No. | | Short text | |
| 486 | Current input 1 to n simulation | | Deactivate simulation |
| | Measured variable status | | |
| | Quality | Good | |
| | Quality substatus | Function check | |
| | Coding (hex) | OxBC to OxBF | |
| | Status signal | С | |
| | Diagnostic behavior | Warning | |
| | Influenced measured var | riables | |
| | Measured values 1 Measured values 2 Measured values 3 | | |

| | Diagnos | stic information | Remedy instructions |
|-----|----------------------------------|------------------|-----------------------|
| No. | | Short text | |
| 491 | Current output 1 to n simulation | | Deactivate simulation |
| | Measured variable status | | |
| | Quality | Good | |
| | Quality substatus | Function check | |
| | Coding (hex) | OxBC to OxBF | |
| | Status signal | C | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | - | | |

| n frequency output 1 variable status | Short text t 1 to n Good | Deactivate simulation frequency output |
|--|--------------------------------|--|
| l variable status | | Deactivate simulation frequency output |
| | Good | |
| | Good | |
| | | |
| ~ | Function check | |
| | 0xBC to 0xBF | |
| nal | С | |
| c behavior | Warning | |
| d measured varia | bles | |
| | nal c behavior | nal C |

| | Diagnosti | c information | Remedy instructions |
|-----|---|----------------|------------------------------------|
| No. | Short text | | |
| 493 | Simulation pulse output 1 to n Measured variable status | | Deactivate simulation pulse output |
| | | | |
| | Quality | Good | |
| Ī | Quality substatus | Function check | |
| | Coding (hex) | 0xBC to 0xBF | |
| | Status signal | C | |
| | Diagnostic behavior | Warning | |
| | Influenced measured varial | bles | |
| | - | | |

| | Diagnos | tic information | Remedy instructions |
|-----|-------------------------------|-----------------|-------------------------------------|
| No. | Short text | | |
| 494 | Switch output simulation 1 | to n | Deactivate simulation switch output |
| | Measured variable status | | |
| | Quality | uality Good | |
| | Quality substatus | Function check | |
| | Coding (hex) | 0xBC to 0xBF | |
| | Status signal | С | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | - | | |

| | Diagnos | stic information | Remedy instructions |
|-----|-------------------------------|------------------|-----------------------|
| No. | Short text | | |
| 495 | Diagnostic event simulation | n | Deactivate simulation |
| | Measured variable status | | |
| | Quality | Good | |
| | Quality substatus | Ok | |
| | Coding (hex) | 0x80 to 0x83 | |
| | Status signal | C | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | _ | | |

| | Diagno | ostic information | Remedy instructions |
|-----|-------------------------------|-------------------|------------------------------------|
| No. | | Short text | |
| | Status input simulation | | Deactivate simulation status input |
| | Measured variable status | | |
| | Quality | Good | |
| | Quality substatus | Function check | - |
| | Coding (hex) | OxBC to OxBF | |
| | Status signal | С | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | - | | |

| Diagnostic information | | Remedy instructions |
|------------------------|--------------|-----------------------|
| | Short text | |
| Simulation block outp | ut | Deactivate simulation |
| Measured variable s | tatus | |
| Quality | Good | |
| Quality substatus | Ok | |
| Coding (hex) | 0x80 to 0x83 | |
| Status signal | С | |
| Diagnostic behavior | Warning | |

| | Diagnostic | information | Remedy instructions |
|-----|---|----------------|--|
| No. | S | hort text | |
| 520 | I/O 1 to n hardware configuration invalid | | 1. Check I/O hardware configuration |
| | Measured variable status | | Replace wrong I/O module Plug the module of double pulse output on correct slot |
| | Quality | Bad | |
| | Quality substatus | Function check | |
| | Coding (hex) | 0x3C to 0x3F | |
| | Status signal | F | |
| | Diagnostic behavior | Alarm | |
| | Influenced measured variables | | |
| | - | | |

| | Diagnostic information | | Remedy instructions |
|-----|---|----------------|--|
| No. | : | Short text | |
| 528 | Concentration settings faulty | | 1. Check concentration settings |
| | Measured variable status | | 2. Check input values e.g. pressure, temperature |
| | Quality | Bad | |
| | Quality substatus | Function check | |
| | Coding (hex) | 0x3C to 0x3F | |
| | Status signal | S | |
| | Diagnostic behavior | Alarm | |
| | Influenced measured variables | | |
| | Carrier mass flow Target corrected volume flot Carrier corrected volume flot Concentration | | Target volume flowVolume flow |

| | Diagnostic | information | Remedy instructions |
|-----|---|----------------|--|
| No. | 5. Short text | | |
| 529 | Concentration settings faulty | | 1. Check concentration settings |
| | Measured variable status | | 2. Check input values e.g. pressure, temperature |
| | Quality | Bad | |
| | Quality substatus | Function check | |
| | Coding (hex) | 0x3C to 0x3F | |
| | Status signal | S | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | Carrier mass flow Density Target corrected volume flow Carrier corrected volume flow Concentration Carrier volume flow | | Target volume flowVolume flow |

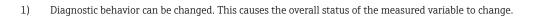
| | Diagnostic information | | Remedy instructions |
|-----|-------------------------------|----------------|----------------------------------|
| No. | | Short text | |
| 537 | 5 | | 1. Check IP addresses in network |
| | Measured variable status | | 2. Change IP address |
| | Quality | Good | |
| | Quality substatus | Function check | |
| | Coding (hex) | 0xBC to 0xBF | |
| | Status signal | F | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | - | | |

| | Diagnostic information | | Remedy instructions |
|-----|-------------------------------|----------------|-------------------------------------|
| No. | | Short text | |
| 594 | Relay output simulation | | Deactivate simulation switch output |
| | Measured variable status | | 1 |
| | Quality | Good | - |
| | Quality substatus | Function check | |
| | Coding (hex) | OxBC to OxBF | |
| | Status signal | С | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | - | | |

12.7.4 Diagnostic of process

| | Diagnostic information | | Remedy instructions |
|----|-------------------------------|-----------------|----------------------|
| o. | | Short text | |
|)3 | Current loop | | 1. Check wiring |
| Ī | Measured variable status | | 2. Change I/O module |
| ŀ | Quality | Bad | |
| | Quality substatus | Process related | |
| | Coding (hex) | 0x28 to 0x2B | |
| | Status signal | F | |
| | Diagnostic behavior | Alarm | |
| Ī | Influenced measured variables | | |
| | _ | | |

| | Diagnosti | c information | Remedy instructions |
|-----|---|--|--|
| No. | Short text | | |
| 830 | Sensor temperature too high | | Reduce ambient temp. around the sensor housing |
| | Measured variable status [from the factory] ¹⁾ | | |
| | Quality | Uncertain | |
| | Quality substatus | Process related | |
| | Coding (hex) | 0x78 to 0x7B | - |
| | Status signal | S | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume fl Carrier corrected volume fl Carrier corrected volume fl Concentration Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperaties Empty pipe detection opting GSV flow GSV flow alternative | low NSV flow NSV flow alternat External pressure Exciter current 1 Exciter current 2 Oscillation freque S&W volume flow Reference density | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Notatus Notatus Oil volume flow Water volume flow Water cut |



| | Diagnostic information | | Remedy instructions |
|-----|--|---|--|
| No. | Short text | | |
| 831 | Sensor temperature too low | | Increase ambient temp. around the sensor housing |
| | Measured variable status [fro | om the factory] ¹⁾ | |
| | Quality | Uncertain | |
| | Quality substatus | Process related | |
| | Coding (hex) | 0x78 to 0x7B | |
| | Status signal | S | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Carrier corrected volume flow Concentration Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature Empty pipe detection option GSV flow GSV flow alternative | w NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequent S&W volume flow re (ISEM) Reference density | ptionOscillation damping fluctuation 1Oscillation damping fluctuation 2Frequency fluctuation 1Frequency fluctuation 2Target mass flowCarrier volume flowCarrier volume flowTarget volume flowTemp. compensated dynamic viscosityTemp. compensated kinematic viscosityTemperaturecy 1Statuscy 2Volume flowOil volume flowWater volume flowWater cut |

| Diagnostic information | | formation | Remedy instructions |
|------------------------|---|--|--|
| lo. | Sho | ort text | |
| 32 | Electronic temperature too high | | Reduce ambient temperature |
| | Measured variable status [from | n the factory] ¹⁾ | |
| | Quality E | Bad | |
| | Quality substatus P | Process related | |
| | Coding (hex) | 0x28 to 0x2B | |
| | Status signal S | | |
| | Diagnostic behavior V | Warning | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature | GSV flow GSV flow alternative Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow Water mass flow WSV flow NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density a Corrected volume flow | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Status Volume flow Water volume flow Water cut |

| Diagnostic information | | ormation | Remedy instructions |
|------------------------|---|--|--|
| No. | Shor | rt text | |
| 333 | Electronic temperature too low Measured variable status [from the factory] ¹⁾ | | Increase ambient temperature |
| | | | |
| | Quality Ba | ad | |
| | Quality substatus Pr | rocess related | |
| | Coding (hex) 02 | x28 to 0x2B | |
| | Status signal S | | |
| | Diagnostic behavior W | Varning | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature (| GSV flow GSV flow alternativ Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Oil mass flow Water mass flow Water mass flow HBSI NSV flow NSV flow alternativ External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density a Corrected volume f | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Target volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Cy 1 Volume flow Water volume flow Water cut |

| | Diagnostic information | | Remedy instructions |
|-----|---|--|--|
| No. | Sh | ort text | |
| 834 | Process temperature too high | | Reduce process temperature |
| | Measured variable status [fro | m the factory] ¹⁾ | |
| | Quality | Uncertain | |
| | Quality substatus | Process related | |
| | Coding (hex) | 0x78 to 0x7B | |
| | Status signal | S | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature Empty pipe detection option GSV flow GSV flow alternative | v NSV flow NSV flow alternativ External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density | ptionOscillation damping fluctuation 1Oscillation damping fluctuation 2Frequency fluctuation 1Frequency fluctuation 2Target mass flowCarrier volume flowCarrier volume flowTarget volume flowTemp. compensated dynamic viscosityTemp. compensated kinematic viscosityTemperaturecy 1Statuscy 2Volume flowOil volume flowWater volume flowWater cut |

| | Diagnostic | information | Remedy instructions |
|-----|--|--|---|
| No. | Short text | | |
| 835 | Process temperature too low | | Increase process temperature |
| | Measured variable status [fro | om the factory] ¹⁾ | |
| | Quality | Uncertain | |
| | Quality substatus | Process related | |
| | Coding (hex) | 0x78 to 0x7B | |
| | Status signal | S | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Carrier corrected volume flow Concentration Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature Empty pipe detection option GSV flow GSV flow alternative | w NSV flow NSV flow alternati External pressure Exciter current 1 Exciter current 2 Oscillation frequen S&W volume flow re (ISEM) Reference density | ptionOscillation damping fluctuation 1Oscillation damping fluctuation 2Frequency fluctuation 1Frequency fluctuation 2Target mass flowCarrier volume flowCarrier volume flowTarget volume flowTemp. compensated dynamic viscosityTemp. compensated kinematic viscosityTemperaturestatusvolume flowOil volume flowOil volume flowWater volume flowWater cut |

| | Diagnostic i | nformation | Remedy instructions |
|-----|---|---|---|
| No. | Short text | | |
| 842 | Process limit | | Low flow cut off active! |
| | Measured variable status [fro | om the factory] ¹⁾ | 1. Check low flow cut off configuration |
| | Quality | Uncertain | |
| | Quality substatus | Process related | |
| | Coding (hex) | 0x78 to 0x7B | |
| | Status signal | S | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature Empty pipe detection option GSV flow GSV flow alternative | w NSV flow NSV flow alternat External pressure Exciter current 1 Exciter current 2 Oscillation frequen S&W volume flow re (ISEM) Reference density | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Yolume flow Oil volume flow Water volume flow Water cut |

| | Diagnostic | information | Remedy instructions |
|-----|--|--|---|
| No. | b. Short text | | |
| 862 | Partly filled pipe | | 1. Check for gas in process |
| | Measured variable status [from the factory] ¹⁾ | | 2. Adjust detection limits |
| | Quality | Bad | |
| | Quality substatus | Process related | |
| | Coding (hex) | 0x28 to 0x2B | |
| | Status signal | S | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | Carrier mass flow Target corrected volume flo Carrier corrected volume flo Concentration Density Oil density Water density Dynamic viscosity Empty pipe detection optice GSV flow GSV flow alternative Kinematic viscosity Low flow cut off option | w • Water mass flow • HBSI • NSV flow • NSV flow alternativ • External pressure • S&W volume flow | Status Status Volume flow Oil volume flow Water volume flow Water cut he flow |

| | Diagnostic info | ormation | Remedy instructions |
|-----|---|--|--|
| No. | Short text | | |
| 882 | Input signal Measured variable status | | 1. Check input configuration |
| | | | 2. Check external device or process conditions |
| | Quality Ba | ad | |
| | Quality substatus M | laintenance alarm | |
| | Coding (hex) 02 | x24 to 0x27 | |
| | Status signal F | | |
| | Diagnostic behavior A | larm | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Measured values 1 Measured values 2 Measured values 3 Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Sensor electronic temperature 6 Empty pipe detection option | GSV flow GSV flow alternativ Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Water mass flow Water mass flow HBSI NSV flow NSV flow alternativ External pressure Exciter current 1 Exciter current 2 Oscillation frequention Oscillation frequention S&W volume flow Reference density a Corrected volume flow | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Cy 1 Volume flow Water volume flow Water cut |

| | Diagnostic information | | | Remedy instructions |
|-----|---|---|---|--|
| No. | Sho | ort text | | |
| 910 | Tubes not oscillating | | 1. Check electronic | |
| | Measured variable status | | 2. Inspect sensor | |
| | Quality B | Bad | | |
| | Quality substatus N | Maintenance alarm | | |
| | Coding (hex) 0 | 0x24 to 0x27 | | |
| | Status signal F | 7 | | |
| | Diagnostic behavior A | Alarm | | |
| | Influenced measured variables | | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature Empty pipe detection option GSV flow GSV flow alternative | Kinematic viscosity Low flow cut off op Mass flow Oil mass flow Water mass flow Water mass flow HBSI NSV flow NSV flow alternative External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density a Corrected volume f Oil corrected volume | ption re cy 1 cy 2 llternative low | Water corrected volume flow Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Carrier volume flow Target volume flow Temp. compensated dynamic viscosity Temperature Status Volume flow Oil volume flow Water volume flow Water cut |

| | Diagnostic information | | Remedy instructions |
|-----|--|---|---|
| No. | Short text | | |
| 912 | Medium inhomogeneous | | 1. Check process cond. |
| | Measured variable status [from the factory] ¹⁾ | | 2. Increase system pressure |
| | Quality | Uncertain | |
| | Quality substatus | Process related | |
| | Coding (hex) | 0x78 to 0x7B | |
| | Status signal | S | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flor Carrier corrected volume flor Concentration Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature GSV flow GSV flow alternative | w NSV flow NSV flow alternativ External pressure Exciter current 1 Exciter current 2 Oscillation frequen S&W volume flow re (ISEM) Reference density | optionOscillation damping fluctuation 1Oscillation damping fluctuation 2Frequency fluctuation 1Frequency fluctuation 2Target mass flowCarrier volume flowCarrier volume flowTarget volume flowTemp. compensated dynamic viscosityTemp. compensated kinematic viscosityTemperaturecy 1Statuscy 2Volume flowOil volume flowWater volume flowWater cut |

| Diagnostic information | | formation | Remedy instructions |
|------------------------|--|---|--|
| No. | Short text | | |
| 913 | Medium unsuitable Measured variable status [from the factory] ¹⁾ | | 1. Check process conditions |
| | | | 2. Check electronic modules or sensor |
| | Quality | Uncertain | |
| | Quality substatus | Process related | |
| | Coding (hex) | 0x78 to 0x7B | |
| | Status signal Status St | S | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | 3 | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Concentration Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature Empty pipe detection option GSV flow GSV flow alternative | NSV flow alternation External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density | ptionOscillation damping fluctuation 1Oscillation damping fluctuation 2Frequency fluctuation 1Frequency fluctuation 2Target mass flowCarrier volume flowCarrier volume flowTarget volume flowTemp. compensated dynamic viscosityTemp. compensated kinematic viscosityTemperaturecy 1Statuscy 2Volume flowOil volume flowWater volume flowWater cut |

| | Diagnost | ic information | Remedy instructions |
|-----|--|--|--|
| No. | Short text | | |
| 941 | API temperature out of spec | ification | 1. Check process temperature with selected API commodity group |
| | Measured variable status | | 2. Check API related parameters |
| | Quality | Bad | |
| | Quality substatus | Maintenance alarm | |
| | Coding (hex) | 0x24 to 0x27 | |
| | Status signal | S | |
| | Diagnostic behavior | Alarm | |
| | Influenced measured variables | | |
| | Oil density Water density GSV flow GSV flow alternative Mass flow Oil mass flow | Water mass flow NSV flow NSV flow alternati External pressure S&W volume flow Reference density and the second secon | Oil volume flowWater volume flow |

| | Diagnos | tic information | Remedy instructions |
|-----|-------------------------------|-------------------|--|
| No. | | Short text | |
| 942 | | | 1. Check process density with selected API commodity group |
| | Measured variable status | | 2. Check API related parameters |
| | Quality | Bad | |
| | Quality substatus | Maintenance alarm | |
| | Coding (hex) | 0x24 to 0x27 | |
| | Status signal | S | |
| | Diagnostic behavior | Alarm | |
| | Influenced measured variables | | |
| | Mass flow | | |

| | Diagnosti | c information | Remedy instructions |
|-----|--|--|---|
| No. | Short text | | |
| 943 | 3 API pressure out of specification | | 1. Check process pressure with selected API commodity group |
| | Measured variable status | | 2. Check API related parameters |
| | Quality | Bad | |
| | Quality substatus | Maintenance alarm | |
| | Coding (hex) | 0x24 to 0x27 | |
| | Status signal | S | |
| | Diagnostic behavior | Alarm | |
| | Influenced measured variables | | |
| | Oil density Water density GSV flow GSV flow alternative Mass flow Oil mass flow | Water mass flow NSV flow NSV flow alternative External pressure S&W volume flow Reference density and the second sec | Oil volume flowWater volume flow |

| | Diagnostic | information | Remedy instructions | |
|-----|---|---|---|--|
| No. | Short text | | | |
| 944 | Monitoring failed | | Check process conditions for Heartbeat Monitoring | |
| | Measured variable status [fr | om the factory] ¹⁾ | | |
| | Quality | Bad | | |
| | Quality substatus | Maintenance alarm | | |
| | Coding (hex) | 0x24 to 0x27 | | |
| | Status signal | S | | |
| | Diagnostic behavior | Warning | | |
| | Influenced measured variables | | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Concentration Oscillation damping 1 Oscillation damping 2 Density Dynamic viscosity Sensor electronic temperature | Empty pipe detect Kinematic viscosity Low flow cut off o Mass flow HBSI External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen Reference density | Oscillation damping fluctuation 1 Oscillation damping fluctuation 2 Frequency fluctuation 1 Frequency fluctuation 2 Target mass flow Temp. compensated dynamic viscosity Temp. compensated kinematic viscosity Temperature | |

| | Diagnostic | information | Remedy instructions |
|-----|---|--|--|
| No. | Short text | | |
| 948 | Oscillation damping too high | | Check process conditions |
| | Measured variable status [fr | om the factory] ¹⁾ | |
| | Quality | Uncertain | |
| | Quality substatus | Process related | |
| | Coding (hex) | 0x78 to 0x7B | |
| | Status signal | S | |
| | Diagnostic behavior | Warning | |
| | Influenced measured variables | | |
| | Oscillation amplitude 1 Oscillation amplitude 2 Signal asymmetry Carrier mass flow Carrier pipe temperature Target corrected volume flow Carrier corrected volume flow Carrier corrected volume flow Concentration Oscillation damping 1 Oscillation damping 2 Density Oil density Water density Dynamic viscosity Sensor electronic temperature GSV flow GSV flow alternative | w NSV flow NSV flow alternativ External pressure Exciter current 1 Exciter current 2 Oscillation frequen Oscillation frequen S&W volume flow Reference density | optionOscillation damping fluctuation 1Oscillation damping fluctuation 2Frequency fluctuation 1Frequency fluctuation 2Target mass flowCarrier volume flowCarrier volume flowTarget volume flowTemp. compensated dynamic viscosityTemperaturecy 1Statuscy 2Volume flowOil volume flowWater volume flowUternativeWater cut |

12.8 Pending diagnostic events

The **Diagnostics** menu allows the user to view the current diagnostic event and the previous diagnostic event separately.

To call up the measures to rectify a diagnostic event:

- Via local display $\rightarrow \square 179$
- Via web browser $\rightarrow \square 180$
- Via "FieldCare" operating tool →
 ■ 181
- Via "DeviceCare" operating tool $\rightarrow \implies 181$

Other pending diagnostic events can be displayed in the **Diagnostic list** submenu $\rightarrow \cong 237$.

Navigation

"Diagnostics" menu

| Ċ Diagnostics | |
|-----------------------------|-----------|
| Actual diagnostics |] → 🗎 237 |
| Previous diagnostics |] → 🗎 237 |
| Operating time from restart |) → 🗎 237 |
| Operating time |] → 🗎 237 |

Parameter overview with brief description

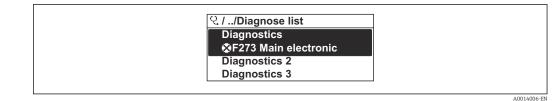
| Parameter | Prerequisite | Description | User interface |
|-----------------------------|--|--|--|
| Actual diagnostics | A diagnostic event has occurred. | Shows the current occured diagnostic event along with its diagnostic information. | Symbol for diagnostic behavior, diagnostic code and short message. |
| | | If two or more messages occur simultaneously, the message with the highest priority is shown on the display. | |
| Previous diagnostics | Two diagnostic events have already occurred. | Shows the diagnostic event that occurred prior to the current diagnostic event along with its diagnostic information. | Symbol for diagnostic behavior, diagnostic code and short message. |
| Operating time from restart | - | Shows the time the device has been in operation since the last device restart. | Days (d), hours (h), minutes (m) and seconds (s) |
| Operating time | - | Indicates how long the device has been in operation. | Days (d), hours (h), minutes (m) and seconds (s) |

12.9 Diagnostics list

Up to 5 currently pending diagnostic events can be displayed in the **Diagnostic list** submenu along with the associated diagnostic information. If more than 5 diagnostic events are pending, the events with the highest priority are shown on the display.

Navigation path

Diagnostics \rightarrow Diagnostic list



■ 39 Using the example of the local display

To call up the measures to rectify a diagnostic event:

- Via local display $\rightarrow \square 179$
- Via web browser $\rightarrow \square$ 180
- Via "DeviceCare" operating tool $\rightarrow \implies 181$

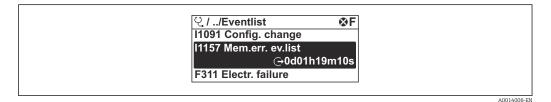
12.10 Event logbook

12.10.1 Reading out the event logbook

A chronological overview of the event messages that have occurred is provided in the **Events list** submenu.

Navigation path

Diagnostics menu → **Event logbook** submenu → Events list



☑ 40 Using the example of the local display

- A maximum of 20 event messages can be displayed in chronological order.
- If the **Extended HistoROM** application package (order option) is enabled in the device, the event list can contain up to 100 entries.

The event history includes entries for:

- Diagnostic events $\rightarrow \square 185$
- Information events $\rightarrow \cong 239$

In addition to the operating time when the event occurred, each event is also assigned a symbol that indicates whether the event has occurred or is finished:

- Diagnostics event
 - $\overline{\mathfrak{O}}$: Occurrence of the event
 - 🕒: End of the event
- Information event

 \oplus : Occurrence of the event

To call up the measures to rectify a diagnostic event:

- Via local display $\rightarrow \square 179$
- Via web browser $\rightarrow \implies 180$
- Via "FieldCare" operating tool $\rightarrow \square$ 181
- Via "DeviceCare" operating tool $\rightarrow \implies 181$

For filtering the displayed event messages $\rightarrow \cong 239$

12.10.2 Filtering the event logbook

Using the **Filter options** parameter you can define which category of event message is displayed in the **Events list** submenu.

Navigation path

Diagnostics \rightarrow Event logbook \rightarrow Filter options

Filter categories

- All
- Failure (F)
- Function check (C)
- Out of specification (S)
- Maintenance required (M)
- Information (I)

12.10.3 Overview of information events

Unlike a diagnostic event, an information event is displayed in the event logbook only and not in the diagnostic list.

| Info number | Info name |
|-------------|--|
| I1000 | (Device ok) |
| I1079 | Sensor changed |
| 11089 | Power on |
| I1090 | Configuration reset |
| I1091 | Configuration changed |
| I1092 | HistoROM backup deleted |
| I1111 | Density adjust failure |
| I1137 | Electronic changed |
| I1151 | History reset |
| I1155 | Reset electronic temperature |
| I1156 | Memory error trend |
| I1157 | Memory error event list |
| I1184 | Display connected |
| I1209 | Density adjustment ok |
| I1221 | Zero point adjust failure |
| I1222 | Zero point adjustment ok |
| I1256 | Display: access status changed |
| I1278 | I/O module reset detected |
| I1335 | Firmware changed |
| I1361 | Web server: login failed |
| I1397 | Fieldbus: access status changed |
| I1398 | CDI: access status changed |
| I1444 | Device verification passed |
| I1445 | Device verification failed |
| I1447 | Record application reference data |
| I1448 | Application reference data recorded |
| I1449 | Recording application ref. data failed |
| I1450 | Monitoring off |

| Info number | Info name |
|-------------|--|
| I1451 | Monitoring on |
| I1457 | Measured error verification failed |
| I1459 | I/O module verification failed |
| I1460 | HBSI verification failed |
| I1461 | Sensor verification failed |
| I1462 | Sensor electronic module verific. failed |
| I1512 | Download started |
| I1513 | Download finished |
| I1514 | Upload started |
| I1515 | Upload finished |
| I1618 | I/O module 2 replaced |
| I1619 | I/O module 3 replaced |
| I1621 | I/O module 4 replaced |
| I1622 | Calibration changed |
| I1624 | Reset all totalizers |
| I1625 | Write protection activated |
| I1626 | Write protection deactivated |
| I1627 | Web server: login successful |
| I1628 | Display: login successful |
| I1629 | CDI: login successful |
| I1631 | Web server access changed |
| I1632 | Display: login failed |
| I1633 | CDI: login failed |
| I1634 | Reset to factory settings |
| I1635 | Reset to delivery settings |
| I1636 | Fieldbus address reset |
| I1639 | Max. switch cycles number reached |
| I1649 | Hardware write protection activated |
| I1650 | Hardware write protection deactivated |
| I1712 | New flash file received |
| I1725 | Sensor electronic module (ISEM) changed |
| I1726 | Configuration backup failed |

12.11 Resetting the measuring device

The entire device configuration or some of the configuration can be reset to a defined state with the **Device reset** parameter ($\rightarrow \implies 152$).

12.11.1 Function range of "Device reset" parameter

| Options | Description |
|----------------------|--|
| Cancel | No action is executed and the user exits the parameter. |
| To delivery settings | Every parameter for which a customer-specific default setting was ordered is reset to the customer-specific value. All other parameters are reset to the factory setting. |

| Options | Description |
|----------------------|---|
| Restart device | The restart resets every parameter with data stored in volatile memory (RAM) to the factory setting (e.g. measured value data). The device configuration remains unchanged. |
| Restore S-DAT backup | Restores the data that is saved on the S-DAT. Additional information: This function can be used to resolve the memory issue "083 Memory content inconsistent" or to restore the S-DAT data when a new S-DAT has been installed. This option is displayed only in an alarm condition. |

12.12 Device information

The **Device information** submenu contains all parameters that display different information for device identification.

Navigation

"Diagnostics" menu \rightarrow Device information

| ► Device information | |
|-------------------------------|---------|
| Device tag | → 🗎 241 |
| Serial number | → 🗎 241 |
| Firmware version | → 🗎 242 |
| Device name | → 🗎 242 |
| Order code | → 🗎 242 |
| Extended order code 1 | → 🗎 242 |
| Extended order code 2 | → 🗎 242 |
| Extended order code 3 | → 🗎 242 |
| ENP version | → 🗎 242 |
| PROFIBUS ident number | → 🗎 242 |
| Status PROFIBUS Master Config | → 🗎 242 |
| | |

Parameter overview with brief description

| Parameter | Description | User interface | Factory setting |
|---------------|--|--|-----------------|
| Device tag | Shows name of measuring point. | Max. 32 characters, such as letters, numbers or special characters (e.g. @, %, /). | Promass 500 PA |
| Serial number | Shows the serial number of the measuring device. | Max. 11-digit character string comprising letters and numbers. | - |

| Parameter | Description | User interface | Factory setting | | |
|-------------------------------|--|--|-----------------|--|--|
| Firmware version | Shows the device firmware version installed. | installed. Character string in the format xx.yy.zz | | | |
| Device name | Shows the name of the transmitter. The name can be found on the nameplate of the transmitter. | Promass 300/500 | - | | |
| Order code | Shows the device order code. Character string composed of letters, numbers and certain punctuation marks (e.g. /). Image: Character string composed of the sensor and transmitter in the "Order code" field. Character string composed of letters, numbers and certain punctuation marks (e.g. /). | | | | |
| Extended order code 1 | Shows the 1st part of the extended order code. The extended order code can also be found on the nameplate of the sensor and transmitter in the "Ext. ord. cd." field. | Character string | _ | | |
| Extended order code 2 | Shows the 2nd part of the extended order code. The extended order code can also be found on the nameplate of the sensor and transmitter in the "Ext. ord. cd." field. | | - | | |
| Extended order code 3 | Shows the 3rd part of the extended order code. Character string - Image: The extended order code can also be found on the nameplate of the sensor and transmitter in the "Ext. ord. cd." field. - | | - | | |
| ENP version | Shows the version of the electronic nameplate (ENP). | Character string | - | | |
| PROFIBUS ident number | Displays the PROFIBUS identification 0 to FFFF 0x156D number. 0 0 0 | | 0x156D | | |
| Status PROFIBUS Master Config | Displays the status of the PROFIBUS Master configuration. | ActiveNot active | - | | |

| Release date | Firmware version | Order code for "Firmware version" | Firmware Changes | Documentation type | Documentation |
|-----------------|---------------------|--|---|---------------------------|----------------------|
| 08.2016 | 01.00.zz | Option 72 | Original firmware | Operating Instructions | BA01869D/06/EN/01.18 |
| 11.2018 | 01.01.zz | Option 68 | Concentration update Local display - enhanced performance and data entry via text editor Optimized keypad lock for local display Web server feature update Support for trend data function Heartbeat function enhanced to include detailed results (page 3/4 of the report) Device configuration as PDF (parameter log, similar to FDT print) Network capability of Ethernet (service) interface Comprehensive Heartbeat feature update Local display - support for WLAN infrastructure mode Implementation of reset code | Operating Instructions | BA01869D/06/EN/02.18 |

12.13 Firmware history



🛐 It is possible to flash the firmware to the current version or the previous version using the service interface.

For the compatibility of the firmware version with the previous version, the installed device description files and operating tools, observe the information about the device in the "Manufacturer's information" document.

The manufacturer's information is available:

- In the Download Area of the Endress+Hauser web site: www.endress.com \rightarrow Downloads
- Specify the following details:
- Product root: e.g. 8A5B

The product root is the first part of the order code: see the nameplate on the device.

- Text search: Manufacturer's information
- Media type: Documentation Technical Documentation

13 Maintenance

13.1 Maintenance work

No special maintenance work is required.

13.1.1 Exterior cleaning

When cleaning the exterior of measuring devices, always use cleaning agents that do not attack the surface of the housing or the seals.

13.1.2 Internal cleaning

Observe the following points for CIP and SIP cleaning:

- Use only cleaning agents to which the process-wetted materials are adequately resistant.
- Observe the maximum permitted medium temperature for the measuring device .

13.2 Measuring and test equipment

Endress+Hauser offers a variety of measuring and testing equipment, such as Netilion or device tests.

Your Endress+Hauser Sales Center can provide detailed information on the services.

List of some of the measuring and testing equipment: \rightarrow 🗎 249

13.3 Endress+Hauser services

Endress+Hauser offers a wide variety of services for maintenance such as recalibration, maintenance service or device tests.

Your Endress+Hauser Sales Center can provide detailed information on the services.

14 Repair

14.1 General notes

14.1.1 Repair and conversion concept

The Endress+Hauser repair and conversion concept provides for the following:

- The measuring devices have a modular design.
- Spare parts are grouped into logical kits with the associated Installation Instructions.
- Repairs are carried out by Endress+Hauser Service or by appropriately trained customers.
- Certified devices can only be converted to other certified devices by Endress+Hauser Service or at the factory.

14.1.2 Notes for repair and conversion

For repair and conversion of a measuring device, observe the following notes:

- ► Use only original Endress+Hauser spare parts.
- Carry out the repair according to the Installation Instructions.
- Observe the applicable standards, federal/national regulations, Ex documentation (XA) and certificates.
- Document all repairs and conversions and enter the details in Netilion Analytics.

14.2 Spare parts

Device Viewer (www.endress.com/deviceviewer):

All the spare parts for the measuring device, along with the order code, are listed here and can be ordered. If available, users can also download the associated Installation Instructions.

P Measuring device serial number:

- Is located on the nameplate of the device.
- Can be read out via the Serial number parameter (→
 ^(→) 241) in the Device information submenu.

14.3 Endress+Hauser services

Endress+Hauser offers a wide range of services.

Your Endress+Hauser Sales Center can provide detailed information on the services.

14.4 Return

The requirements for safe device return can vary depending on the device type and national legislation.

1. Refer to the web page for information:

https://www.endress.com/support/return-material

- → Select the region.
- 2. If returning the device, pack the device in such a way that it is reliably protected against impact and external influences. The original packaging offers the best protection.

14.5 Disposal

If required by the Directive 2012/19/EU on waste electrical and electronic equipment (WEEE), the product is marked with the depicted symbol in order to minimize the disposal of WEEE as unsorted municipal waste. Do not dispose of products bearing this marking as unsorted municipal waste. Instead, return them to the manufacturer for disposal under the applicable conditions.

14.5.1 Removing the measuring device

1. Switch off the device.

WARNING

Danger to persons from process conditions!

- Beware of hazardous process conditions such as pressure in the measuring device, high temperatures or aggressive media.
- 2. Carry out the mounting and connection steps from the "Mounting the measuring device" and "Connecting the measuring device" sections in reverse order. Observe the safety instructions.

14.5.2 Disposing of the measuring device

WARNING

Danger to personnel and environment from fluids that are hazardous to health.

Ensure that the measuring device and all cavities are free of fluid residues that are hazardous to health or the environment, e.g. substances that have permeated into crevices or diffused through plastic.

Observe the following notes during disposal:

- Observe valid federal/national regulations.
- Ensure proper separation and reuse of the device components.

15 Accessories

Various accessories, which can be ordered with the device or subsequently from Endress +Hauser, are available for the device. Detailed information on the order code in question is available from your local Endress+Hauser sales center or on the product page of the Endress+Hauser website: www.endress.com.

15.1 Device-specific accessories

15.1.1 For the transmitter

| Accessories | Description | |
|---|---|--|
| Transmitter • Proline 500 – digital • Proline 500 | Transmitter for replacement or storage. Use the order code to define the following specifications: • Approvals • Output • Input • Display/operation • Housing • Software • Proline 500 - digital transmitter: Order number: 8X5BXX-******A • Proline 500 transmitter: Order number: 8X5BXX-******B | |
| | Proline 500 transmitter for replacement: It is essential to specify the serial number of the current transmitter when ordering. On the basis of the serial number, the device-specific data (e.g. calibration factors) of the replaced device can be used for the new transmitter. | |
| | Proline 500 – digital transmitter: Installation Instructions EA01151D Proline 500 transmitter: Installation Instructions EA01152D | |
| External WLAN antenna | External WLAN antenna with 1.5 m (59.1 in) connecting cable and two angle brackets. Order code for "Accessory enclosed", option P8 "Wireless antenna wide area". Inte external WLAN antenna is not suitable for use in hygienic applications. Additional information regarding the WLAN interface → 🗎 88. Order number: 71351317 Installation Instructions EA01238D | |
| Pipe mounting set | Pipe mounting set for transmitter. Image: Proline 500 - digital transmitter Order number: 71346427 Image: Image: Proline 500 transmitter Order number: 71346428 | |
| Weather protection cover Transmitter • Proline 500 – digital • Proline 500 | Is used to protect the measuring device from the effects of the weather: e.g. rainwater, excess heating from direct sunlight. Proline 500 - digital transmitter Order number: 71343504 Proline 500 transmitter Order number: 71343505 Installation Instructions EA01191D | |

| Display guard Proline 500 – digital | Is used to protect the display against impact or scoring, for example from sand in desert areas. Order number: 71228792 Installation Instructions EA01093D |
|--|--|
| Connecting cable Proline 500 – digital Sensor – Transmitter | The connecting cable can be ordered directly with the measuring device (order code for "Cable, sensor connection) or as an accessory (order number DK8012). The following cable lengths are available: order code for "Cable, sensor connection" • Option B: 20 m (65 ft) • Option E: User-configurable up to max. 50 m • Option F: User-configurable up to max. 165 ft • Maximum possible cable length for a Proline 500 – digital connecting cable: 300 m (1000 ft) |
| Connecting cables Proline 500 Sensor – Transmitter | The connecting cable can be ordered directly with the measuring device (order code for "Cable, sensor connection") or as an accessory (order number DK8012). The following cable lengths are available: order code for "Cable, sensor connection" • Option 1: 5 m (16 ft) • Option 2: 10 m (32 ft) • Option 3: 20 m (65 ft) • Possible cable length for a Proline 500 connecting cable: max. 20 m (65 ft) |

15.1.2 For the sensor

| Accessories | Description |
|----------------|--|
| Heating jacket | Is used to stabilize the temperature of the fluids in the sensor. Water, water vapor and other non-corrosive liquids are permitted for use as fluids. |
| | If using oil as a heating medium, please consult with Endress+Hauser. |
| | If ordered together with the measuring device: |
| | Order code for "Accessory enclosed" |
| | Option RB "Heating jacket, G 1/2" female thread" |
| | Option RD "Heating jacket, NPT 1/2" female thread" |
| | If ordered subsequently: |
| | Use the order code with the product root DK8003. |
| | Special Documentation SD02173D |
| Sensor holder | For wall, tabletop and pipe mounting. |
| | Order number: 71392563 |

| Accessories | Description | |
|-------------|--|--|
| Applicator | Software for selecting and sizing Endress+Hauser measuring instruments: Choice of measuring instruments for industrial requirements Calculation of all the necessary data for identifying the optimum flowmeter: e.g. nominal diameter, pressure loss, flow velocity and measurement accuracy. Graphic display of the calculation results Determination of the partial order code, administration, documentation and access to all project-related data and parameters over the entire life cycle of a project. Applicator is available: | |
| | Via the Internet: https://portal.endress.com/webapp/applicator | |
| Netilion | lloT ecosystem: Unlock knowledge With the Netilion IIoT ecosystem,Endress+Hauser allows you to optimize your plant performance, digitize workflows, share knowledge, and enhance collaboration. Drawing upon decades of experience in process automation, Endress+Hauser offers the process industry an IIoT ecosystem designed to effortlessly extract insights from data. These insights allow process optimization, leading to increased plant availability, efficiency, and reliability - ultimately resulting in a more profitable plant. www.netilion.endress.com | |
| FieldCare | FDT-based plant asset management tool from Endress+Hauser. It can configure all intelligent field units in your system and helps you manage them. By using the status information, it is also a simple but effective way of checking their status and condition. Operating Instructions BA00027S and BA00059S | |
| DeviceCare | Tool to connect and configure Endress+Hauser field devices. | |

15.2 Service-specific accessories

15.3 System components

| Accessories | Description |
|-------------------------------------|---|
| Memograph M graphic data manager | The Memograph M graphic data manager provides information on all the relevant measured variables. Measured values are recorded correctly, limit values are monitored and measuring points analyzed. The data are stored in the 256 MB internal memory and also on a SD card or USB stick. |
| | Technical Information TI00133R Operating Instructions BA00247R |
| Cerabar M | The pressure transmitter for measuring the absolute and gauge pressure of gases, steam and liquids. It can be used to read in the operating pressure value. |
| | Technical Information TI00426P and TI00436P Operating Instructions BA00200P and BA00382P |
| Cerabar S | The pressure transmitter for measuring the absolute and gauge pressure of gases, steam and liquids. It can be used to read in the operating pressure value. |
| ITEMP | The temperature transmitters can be used in all applications and are suitable for the measurement of gases, steam and liquids. They can be used to read in the medium temperature. |

16 Technical data

16.1 Application

The measuring device is intended only for the flow measurement of liquids and gases.

Depending on the version ordered, the measuring device can also measure potentially explosive, flammable, poisonous and oxidizing media.

To ensure that the device remains in proper operating condition for its service life, use the measuring device only for media against which the process-wetted materials are sufficiently resistant.

16.2 Function and system design

| Measuring principle | Mass flow measurement based on the Coriolis measuring principle |
|---------------------|---|
| Measuring system | The measuring system consists of a transmitter and a sensor. The transmitter and sensor are mounted in physically separate locations. They are interconnected by connecting cables. |
| | For information on the structure of the measuring instrument $\rightarrow \ \ 14$ |

Input 16.3

| Measured variable | Direct measured variables |
|-------------------|---|
| | Mass flowDensityTemperature |
| | Calculated measured variables |
| | Volume flowCorrected volume flowReference density |
| Measuring range | Measuring range for liquids |

Measuring range

Measuring range for liquids

| DN | | Measuring range full scal | e values $\dot{m}_{min(F)}$ to $\dot{m}_{max(F)}$ |
|------|------------------|---------------------------|---|
| [mm] | [in] | [kg/h] | [lb/min] |
| 1 | 1/ ₂₄ | 0 to 20 | 0 to 0.735 |
| 2 | 1/ ₁₂ | 0 to 100 | 0 to 3.675 |
| 4 | 1⁄8 | 0 to 450 | 0 to 16.54 |

Measuring range for gases

The full scale value depends on the density and the sound velocity of the gas used. The full scale value can be calculated with the following formulas:

 $\dot{m}_{max(G)} = (\rho_G \cdot (c_G/m) \cdot d_i^2 \cdot (\pi/4) \cdot 3600 \cdot n)$

| m _{max(G)} | Maximum full scale value for gas [kg/h] |
|---------------------|---|
| ρ _G | Gas density in [kg/m ³] at operating conditions |
| C _G | Sound velocity (gas) [m/s] |
| d _i | Measuring tube internal diameter [m] |
| π | Pi |
| n = 1 | Number of measuring tubes |
| m = 2 | For all gases except pure H2 and He gas |
| m = 3 | For pure H2 and He gas |

Recommended measuring range

Flow limit \rightarrow 266

Operable flow range

Over 1000 : 1.

Flow rates above the preset full scale value do not override the electronics unit, with the result that the totalizer values are registered correctly.

Input signal

External measured values

To increase the measurement accuracy of certain measured variables or to calculate the corrected volume flow for gases, the automation system can continuously write different measured values to the measuring instrument:

- Operating pressure to increase measurement accuracy (Endress+Hauser recommends the use of a pressure measuring device for absolute pressure, e.g. Cerabar M or Cerabar S)
- Medium temperature to increase measurement accuracy (e.g. iTEMP)
- Reference density for calculating the corrected volume flow for gases

Various pressure and temperature measuring devices can be ordered from Endress +Hauser: see "Accessories" section $\rightarrow \textcircled{B}$ 249

It is recommended to read in external measured values to calculate the corrected volume flow.

Current input

The measured values are written from the automation system to the measuring device via the current input $\rightarrow \cong 252$.

Digital communication

The measured values are written by the automation system via PROFIBUS PA.

Current input 0/4 to 20 mA

| Current input | 0/4 to 20 mA (active/passive) |
|--------------------------|---|
| Current span | 4 to 20 mA (active) 0/4 to 20 mA (passive) |
| Resolution | 1 μΑ |
| Voltage drop | Typically: 0.6 to 2 V for 3.6 to 22 mA (passive) |
| Maximum input voltage | ≤ 30 V (passive) |
| Open-circuit voltage | < 28.8 V (active) |
| Possible input variables | PressureTemperatureDensity |

Status input

| Maximum input values | DC -3 to 30 V If status input is active (ON): R_i >3 kΩ |
|----------------------|--|
| Response time | Configurable: 5 to 200 ms |
| Input signal level | Low signal: DC -3 to +5 V High signal: DC 12 to 30 V |
| Assignable functions | Off Reset the individual totalizers separately Reset all totalizers Flow override |

16.4 Output

Output signal

PROFIBUS PA

| PROFIBUS PA | In accordance with EN 50170 Volume 2, IEC 61158-2 (MBP), galvanically isolated |
|--------------------------|--|
| Data transmission | 31.25 kbit/s |
| Current consumption | 10 mA |
| Permitted supply voltage | 9 to 32 V |
| Bus connection | With integrated reverse polarity protection |

Current output 4 to 20 mA

| Signal mode | Can be set to: • Active • Passive |
|----------------------------------|--|
| Current range | Can be set to: • 4 to 20 mA NAMUR • 4 to 20 mA US • 4 to 20 mA • 0 to 20 mA (only if the signal mode is active) • Fixed current |
| Maximum output values | 22.5 mA |
| Open-circuit voltage | DC 28.8 V (active) |
| Maximum input voltage | DC 30 V (passive) |
| Load | 0 to 700 Ω |
| Resolution | 0.38 μΑ |
| Damping | Configurable: 0 to 999.9 s |
| Assignable measured variables | Mass flow Volume flow Corrected volume flow Density Reference density Temperature Electronics temperature Oscillation frequency 0 Oscillation damping 0 Signal asymmetry Exciter current 0 The range of options increases if the measuring device has one or more application packages. |

Current output 4 to 20 mA Ex i passive

| Order code | "Output; input 2" (21), "Output; input 3" (022): Option C: current output 4 to 20 mA Ex i passive |
|-----------------------|--|
| Signal mode | Passive |
| Current range | Can be set to: • 4 to 20 mA NAMUR • 4 to 20 mA US • 4 to 20 mA • Fixed current |
| Maximum output values | 22.5 mA |
| Maximum input voltage | DC 30 V |

| Load | 0 to 700 Ω |
|----------------------------------|---|
| Resolution | 0.38 μΑ |
| Damping | Configurable: 0 to 999 s |
| Assignable measured variables | Mass flow Volume flow Corrected volume flow Density Reference density Temperature Electronics temperature Oscillation frequency 0 Oscillation damping 0 Signal asymmetry Exciter current 0 Im The range of options increases if the measuring device has one or more application packages. |

Pulse/frequency/switch output

| Function | Can be configured as pulse, frequency or switch output | |
|-------------------------------|--|--|
| Version | Open collector | |
| | Can be set to: | |
| | ActivePassive | |
| | Passive Passive NAMUR | |
| | | |
| | Ex-i, passive | |
| Maximum input values | DC 30 V, 250 mA (passive) | |
| Open-circuit voltage | DC 28.8 V (active) | |
| Voltage drop | For 22.5 mA: \leq DC 2 V | |
| Pulse output | | |
| Maximum input values | DC 30 V, 250 mA (passive) | |
| Maximum output current | 22.5 mA (active) | |
| Open-circuit voltage | DC 28.8 V (active) | |
| Pulse width | Configurable: 0.05 to 2 000 ms | |
| Maximum pulse rate | 10 000 Impulse/s | |
| Pulse value | Configurable | |
| Assignable measured variables | Mass flowVolume flow | |
| | Corrected volume flow | |
| | The range of options increases if the measuring device has one or more application packages. | |
| Frequency output | Frequency output | |
| Maximum input values | DC 30 V, 250 mA (passive) | |
| Maximum output current | 22.5 mA (active) | |
| Open-circuit voltage | DC 28.8 V (active) | |
| Output frequency | Configurable: end value frequency 2 to 10000 Hz(f $_{max}$ = 12500 Hz) | |
| Damping | Configurable: 0 to 999.9 s | |
| Pulse/pause ratio | 1:1 | |

| Assignable measured variables | Mass flow Volume flow Corrected volume flow Density Reference density Temperature Electronics temperature Oscillation frequency 0 Oscillation damping 0 Signal asymmetry Exciter current 0 In range of options increases if the measuring device has one or more application packages. |
|----------------------------------|--|
| Switch output | |
| Maximum input values | DC 30 V, 250 mA (passive) |
| Open-circuit voltage | DC 28.8 V (active) |
| Switching behavior | Binary, conductive or non-conductive |
| Switching delay | Configurable: 0 to 100 s |
| Number of switching cycles | Unlimited |
| Assignable functions | Disable On Diagnostic behavior Limit Mass flow Volume flow Corrected volume flow Density Reference density Temperature Totalizer 1-3 Flow direction monitoring Status Partially filled pipe detection Low flow cut off The range of options increases if the measuring device has one or more application packages. |

Relay output

| Function | Switch output |
|--------------------|---|
| Version | Relay output, galvanically isolated |
| Switching behavior | Can be set to: • NO (normally open), factory setting • NC (normally closed) |

| Maximum switching capacity (passive) | DC 30 V, 0.1 A AC 30 V, 0.5 A |
|--------------------------------------|--|
| Assignable functions | Disable On Diagnostic behavior Limit Mass flow Volume flow Corrected volume flow Density Reference density Temperature Totalizer 1-3 Flow direction monitoring Status Partially filled pipe detection Low flow cut off The range of options increases if the measuring device has one or more application packages. |

User-configurable input/output

One specific input or output is assigned to a user-configurable input/output (configurable I/O) during device commissioning.

The following inputs and outputs are available for assignment:

- Choice of current output: 4 to 20 mA (active), 0/4 to 20 mA (passive)
- Pulse/frequency/switch output
- Choice of current input: 4 to 20 mA (active), 0/4 to 20 mA (passive)
- Status input

Signal on alarm

Depending on the interface, failure information is displayed as follows:

PROFIBUS PA

| Status and alarm messages | Diagnostics in accordance with PROFIBUS PA Profile 3.02 |
|---|---|
| Failure current FDE (Fault Disconnection Electronic) | 0 mA |

Current output 0/4 to 20 mA

4 to 20 mA

| Choose from: 4 to 20 mA in accordance with NAMUR recommendation NE 43 4 to 20 mA in accordance with US Min. value: 3.59 mA Max. value: 22.5 mA Definable value between: 3.59 to 22.5 mA Actual value |
|--|
| Last valid value |

0 to 20 mA

| Failure mode | Choose from: |
|--------------|---|
| | Maximum alarm: 22 mA Definable value between: 0 to 20.5 mA |
| | |

Pulse/frequency/switch output

| Pulse output | |
|------------------|---|
| Fault mode | Choose from: • Actual value • No pulses |
| Frequency output | |
| Fault mode | Choose from: • Actual value • 0 Hz • Definable value between: 2 to 12 500 Hz |
| Switch output | |
| Fault mode | Choose from: • Current status • Open • Closed |

Relay output

| Failure mode | Choose from: |
|--------------|------------------------------------|
| | Current status |
| | Open |
| | Closed |

Local display

| Plain text display | With information on cause and remedial measures |
|--------------------|---|
| Backlight | Red lighting indicates a device error. |



Status signal as per NAMUR recommendation NE 107

Interface/protocol

- Via digital communication:
 - PROFIBUS PA
- Via service interface CDI-RJ45 service interface
 - WLAN interface

| Plain text display | With information on cause and remedial measures |
|--------------------|---|
|--------------------|---|

Web browser

| Plain text display | With information on cause and remedial measures |
|--------------------|---|
|--------------------|---|

Light emitting diodes (LED)

| Status information | Status indicated by various light emitting diodes | | |
|--------------------|---|--|--|
| | The following information is displayed depending on the device version: Supply voltage active Data transmission active Device alarm/error has occurred | | |
| | Diagnostic information via light emitting diodes $\rightarrow \square 174$ | | |

| Low flow cut off | The switch points for low flow cut off are user-selectable. | | | |
|------------------------|--|---|--|--|
| Galvanic isolation | The outputs are galvanically isolated: • from the power supply • from one another • from the potential equalization (PE) terminal | | | |
| protocol-specific data | Manufacturer ID | 0x11 | | |
| | Ident number | 0x156D | | |
| | Profile version | 3.02 | | |
| | Device description files (GSD, DTM, DD) | Information and files under: • https://www.endress.com/download On the device product page: PRODUCTS → Product Finder → Links • https://www.profibus.com | | |
| | Supported functions | Identification & Maintenance Simplest device identification on the part of the control system and nameplate PROFIBUS upload/download Reading and writing parameters is up to ten times faster with PROFIBU upload/download Condensed status Simplest and self-explanatory diagnostic information by categorizing diagnostic messages that occur | | |
| | Configuration of the device address | DIP switches on the I/O electronics module Local display Via operating tools (e.g. FieldCare) | | |
| | Compatibility with earlier model | If the device is replaced, the measuring device Promass 500 supports the compatibility of the cyclic data with previous models. It is not necessary to adjust the engineering parameters of the PROFIBUS network with the Promass 500 GSD file. | | |
| | | Earlier models: Promass 80 PROFIBUS PA ID No.: 1528 (hex) Extended GSD file: EH3x1528.gsd Standard GSD file: EH3_1528.gsd Promass 83 PROFIBUS PA ID No.: 152A (hex) Extended GSD file: EH3x152A.gsd Standard GSD file: EH3_152A.gsd | | |
| | System integration | Information regarding system integration → Cyclic data transmission Block model Description of the modules | | |

16.5 Power supply

| Terminal assignment | $\rightarrow 	riangleq 41$ |
|------------------------|----------------------------|
| Available device plugs | → 🗎 41 |
| Available device plugs | → 🗎 42 |

| Supply voltage | Order code Terminal voltage Frequency rate | | | Frequency range |
|-----------------------------------|---|-------------------------|-------------------|-----------------------------------|
| | Option D | DC 24 V | ±20% | - |
| | Option E | AC 100 to 240 V | / -15+10% | 50/60 Hz |
| | Ontion I | DC 24 V | ±20% | - |
| | Option I | AC 100 to 240 V | 7 -15+10% | 50/60 Hz |
| Power consumption | Transmitter | | | |
| | Max. 10 W (active pov | ver) | | |
| | switch-on current | Max. 36 A (<5 ms) as pe | er NAMUR Recom | nmendation NE 21 |
| Current consumption | Transmitter | | | |
| | Max. 400 mA (24 V) Max. 200 mA (110 V) | | 0/60 Hz) | |
| Power supply failure | Totalizers stop at the last value measured. Depending on the device version, the configuration is retained in the device memory or in the pluggable data memory (HistoROM DAT). Error messages (incl. total operated hours) are stored. | | | |
| Overcurrent protection element | The device must be operated with a dedicated circuit breaker, as it does not have an ON/OFF switch of its own. The circuit breaker must be easy to reach and labeled accordingly. Permitted nominal current of the circuit breaker: 2 A up to maximum 10 A. | | | |
| Electrical connection | $\bullet \rightarrow \cong 44$ $\bullet \rightarrow \boxtimes 51$ | | | |
| Potential equalization | → 🖹 57 | | | |
| Terminals | Spring-loaded terminals: Suitable for strands and strands with ferrules. Conductor cross-section 0.2 to 2.5 mm ² (24 to 12 AWG). | | | |
| Cable entries | Cable gland: M20 × 1.5 with cable Ø 6 to 12 mm (0.24 to 0.47 in) Thread for cable entry: NPT ¹/₂" G ¹/₂" M20 Device plug for digital communication: M12 | | | |
| Cable specification | → 🗎 36 | | | |
| Overvoltage protection | Mains voltage fluctuation | s → | ₿ 259 | |
| | Overvoltage category | Ov | ervoltage categor | y II |
| | Short-term, temporary ov | ervoltage Be | tween cable and g | ground up to 1200 V, for max. 5 s |
| | Long-term, temporary ove | ervoltage Be | tween cable and g | ground up to 500 V |

| Reference operating conditions | Error limits based on ISO 11631 Water +15 to +45 °C (+59 to +113 °F) 2 to 6 bar (29 to 87 psi) Data as indicated in the calibration protocol Accuracy based on accredited calibration rigs according to ISO 17025 | | |
|--------------------------------|--|--|------------|
| | 5 | rs, use the <i>Applicator</i> sizing tool | |
| Maximum measurement error | o.r. = of reading; $1 \text{ g/cm}^3 = 1 \text{ kg/l}$; T = medium temperature | | |
| | Base accuracy | | |
| | Design fundamentals → [●] 263 | | |
| | Mass flow and volume flow (li | auids) | |
| | ±0.10 % o.r. | quite) | |
| | Mass flow (gases) | | |
| | ±0.35 % o.r. | | |
| | Density (liquids) | | |
| | Under reference conditions | Standard density calibration ¹⁾ | Wide-range |

16.6 Performance characteristics

| Under reference conditions | Standard density calibration ¹⁾ | Wide-range Density specification ^{2) 3)} |
|----------------------------|--|--|
| [g/cm ³] | [g/cm³] | [g/cm³] |
| ±0.0005 | ±0.001 | ±0.002 |

1) For devices with the order code "Measuring tube material, wetted surface", option HB "Alloy C22, high pressure, not polished", the standard density calibration ± 0.002 g/cm³

2) Valid range for special density calibration: 0 to 2 g/cm³, +5 to +80 °C (+41 to +176 °F)

3) order code for "Application package", option EE "Special density"

Temperature

±0.5 °C ± 0.005 · T °C (±0.9 °F ± 0.003 · (T – 32) °F)

Zero point stability

Standard version: order code for "Measuring tube mat., wetted surface", option BB, BF, HA, SA

| DN | | Zero point stability | |
|------|------------------------------|----------------------|----------|
| [mm] | [in] | [kg/h] | [lb/min] |
| 1 | 1/24 | 0.0005 | 0.000018 |
| 2 | ¹ / ₁₂ | 0.0025 | 0.00009 |
| 4 | 1/8 | 0.0100 | 0.00036 |

| DN | | Zero point stability | |
|------|------------------------------|----------------------|-----------|
| [mm] | [in] | [kg/h] | [lb/min] |
| 1 | 1/24 | 0.0008 | 0.0000288 |
| 2 | ¹ / ₁₂ | 0.0040 | 0.000144 |
| 4 | 1/8 | 0.0160 | 0.000576 |

High-pressure version: order code for "Measuring tube mat., wetted surface", option HB

Flow values

Flow values as turndown parameters depending on nominal diameter.

SI units

| DN | 1:1 | 1:10 | 1:20 | 1:50 | 1:100 | 1:500 |
|------|--------|--------|--------|--------|--------|--------|
| [mm] | [kg/h] | [kg/h] | [kg/h] | [kg/h] | [kg/h] | [kg/h] |
| 1 | 20 | 2 | 1 | 0.4 | 0.2 | 0.04 |
| 2 | 100 | 10 | 5 | 2 | 1 | 0.2 |
| 4 | 450 | 45 | 22.5 | 9 | 4.5 | 0.9 |

US units

| DN | 1:1 | 1:10 | 1:20 | 1:50 | 1:100 | 1:500 |
|--------|----------|----------|----------|----------|----------|----------|
| [inch] | [lb/min] | [lb/min] | [lb/min] | [lb/min] | [lb/min] | [lb/min] |
| 1/24 | 0.735 | 0.074 | 0.037 | 0.015 | 0.007 | 0.001 |
| 1/12 | 3.675 | 0.368 | 0.184 | 0.074 | 0.037 | 0.007 |
| 1/8 | 16.54 | 1.654 | 0.827 | 0.331 | 0.165 | 0.033 |

Accuracy of outputs

The outputs have the following base accuracy specifications.

Current output

| Accuracy ±5 µ |
|---------------|
|---------------|

Pulse/frequency output

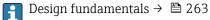
o.r. = of reading

| Accuracy | Max. ± 50 ppm o.r. (over the entire ambient temperature range) |
|----------|--|
|----------|--|

Repeatability

o.r. = of reading; $1 \text{ g/cm}^3 = 1 \text{ kg/l}$; T = medium temperature

Base repeatability



Mass flow and volume flow (liquids) ± 0.05 % o.r.

| | Mass flow (gases) ±0.15 % o.r. | | | |
|------------------------------------|---|--|--|--|
| | Density (liquids) $\pm 0.00025 \text{ g/cm}^3$ | | | |
| | <i>Temperature</i> ±0.25 °C ± 0.0025 · T °C (±0.45 °F ± 0.0015 · (T−32) °F) | | | |
| Response time | The response time depends on the configuration (damping). | | | |
| Influence of ambient temperature | Current output | | | |
| temperature | Temperature coefficient Max. 1 µA/°C | | | |
| | Pulse/frequency output | | | |
| | Temperature coefficient No additional effect. Included in accuracy. | | | |
| Influence of medium temperature | Mass flow o.f.s. = of full scale value If there is a difference between the temperature during zero adjustment and the process temperature, the additional measurement error of the sensors is typically $\pm 0.0002 \ \% o.f.s./^{\circ}C \ (\pm 0.0001 \ \% o.f.s./^{\circ}F).$ The influence is reduced when the zero adjustment is performed at process temperature. Density If there is a difference between the density calibration temperature and the process temperature, the measurement error of the sensors is typically $\pm 0.00005 \ g/cm^{3}/^{\circ}C \ (\pm 0.000025 \ g/cm^{3}/^{\circ}F).$ Field density adjustment is possible. Wide-range density specification (special density calibration) If the process temperature is outside the valid range ($\rightarrow \cong 260$) the measurement error is $\pm 0.00005 \ g/cm^{3}/^{\circ}C \ (\pm 0.000025 \ g/cm^{3}/^{\circ}F)$ | | | |
| | $1 Field density adjustment, for example at +20 °C (+68 °F) \\ 2 Special density calibration \\ 1 Speci$ | | | |

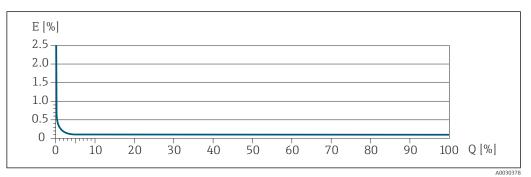
Influence of mediumA difference between the calibration pressure and process pressure does not affect
accuracy.

| Influence of process density | If there is a difference in density between the calibration density and the process density, the measurement error for the measured density is typically: ±0.6% for nominal diameter DN 4 (¹/₂₄ in) ±1.4% for nominal diameter DN 2 (¹/₁₂ in) ±2.0% for nominal diameter DN 1 (¹/₁₂ in) and for devices with order code for "Measuring tube material, wetted surface:", option HB "Alloy C22, high pressure, not polished" A field density adjustment is possible. | | | | |
|------------------------------|--|---|--|--|--|
| Design fundamentals | o.r. = of reading, o.f.s. = of full scale value BaseAccu = base accuracy in % o.r., BaseRepeat = base repeatability in % o.r. MeasValue = measured value; ZeroPoint = zero point stability | | | | |
| | Calculation of the maximum measured error as a function of the flow rate | | | | |
| | Flow rate | Maximum measured error in % o.r. | | | |
| | $\geq \frac{\text{ZeroPoint}}{\text{BaseAccu}} \cdot 100$ | 2 ± BaseAccu | | | |
| | < ZeroPoint BaseAccu · 100 | $\pm \frac{\text{ZeroPoint}}{\text{MeasValue}} \cdot 100$ | | | |

Calculation of the maximum repeatability as a function of the flow rate

| Flow rate | Maximum repeatability in % o.r. |
|---|---|
| $\geq \frac{\frac{1}{2} \cdot \text{ZeroPoint}}{\text{BaseRepeat}} \cdot 100$ | ± BaseRepeat |
| A002133 | A0021340 |
| $< \frac{\frac{1}{2} \cdot \text{ZeroPoint}}{\text{BaseRepeat}} \cdot 100$ | $\pm \frac{1}{2} \cdot \frac{\text{ZeroPoint}}{\text{MeasValue}} \cdot 100$ |
| A0021336 | A0021337 |

Example of maximum measurement error



E Maximum measurement error in % o.r. (example)

Q Flow rate in % of maximum full scale value

16.7 Mounting

Mounting requirements $\rightarrow \cong 22$

| Ambient temperature range | $\rightarrow \blacksquare 24$ | | | | |
|------------------------------|---|--|--|--|--|
| | Temperature tables | | | | |
| | Observe the interdependencies between the permitted ambient and fluid temperatures when operating the device in hazardous areas. | | | | |
| | For detailed information on the temperature tables, see the separate document entitled "Safety Instructions" (XA) for the device. | | | | |
| Storage temperature | | | | | |
| Climate class | DIN EN 60068-2-38 (test Z/AD) | | | | |
| Relative humidity | The device is suitable for use outdoors and indoors with a relative humidity of 4 to 95 %. | | | | |
| Operating height | According to EN 61010-1 ≤ 2 000 m (6 562 ft) > 2 000 m (6 562 ft) with additional overvoltage protection (e.g. Endress+Hauser HAW Series) | | | | |
| Degree of protection | Transmitter | | | | |
| | IP66/67, Type 4X enclosure, suitable for pollution degree 4 When the housing is open: IP20, Type 1 enclosure, suitable for pollution degree 2 Display module: IP20, Type 1 enclosure, suitable for pollution degree 2 | | | | |
| | Sensor | | | | |
| | IP66/67, Type 4X enclosure, suitable for pollution degree 4 When the housing is open: IP20, Type 1 enclosure, suitable for pollution degree 2 | | | | |
| | Optional | | | | |
| | Order code for "Sensor options", option CM "IP69 | | | | |
| | External WLAN antenna | | | | |
| | IP67 | | | | |
| Shock and vibration | Vibration sinusoidal, in accordance with IEC 60068-2-6 | | | | |
| resistance | Sensor • 2 to 8.4 Hz, 3.5 mm peak • 8.4 to 2 000 Hz, 1 g peak | | | | |
| | Transmitter • 2 to 8.4 Hz, 7.5 mm peak • 8.4 to 2 000 Hz, 2 g peak | | | | |
| | Vibration broad-band random, according to IEC 60068-2-64 | | | | |
| | Sensor | | | | |
| | ■ 10 to 200 Hz, 0.003 g ² /Hz | | | | |
| | 200 to 2 000 Hz, 0.001 g²/Hz Total: 1.54 g rms | | | | |

16.8 Environment

| | Transmitter • 10 to 200 Hz, 0.01 g ² /Hz • 200 to 2 000 Hz, 0.003 g ² /Hz • Total: 2.70 g rms |
|--|--|
| | Shock half-sine, according to IEC 60068-2-27 |
| | Sensor 6 ms 30 g Transmitter 6 ms 50 g |
| | Rough handling shocks according to IEC 60068-2-31 |
| Internal cleaning | CIP cleaningSIP cleaning |
| | Options Oil- and grease-free version for wetted parts, without declaration Order code for "Service", option HA $^{\rm 4)}$ |
| Mechanical load | Transmitter housing and sensor connection housing: Protect against mechanical effects, such as shock or impact Do not use as a ladder or climbing aid |
| Electromagnetic compatibility (EMC) | As per IEC/EN 61326 and NAMUR Recommendation 21 (NE 21) As per IEC/EN 61000-6-2 and IEC/EN 61000-6-4 |
| | Details are provided in the Declaration of Conformity. |
| | This unit is not intended for use in residential environments and cannot guarantee adequate protection of the radio reception in such environments. |
| | 16.9 Process |
| Medium temperature range | –50 to +205 °C (–58 to +401 °F) |
| Pressure-temperature ratings | For an overview of the pressure-temperature ratings for the process connections, see the Technical Information |
| Sensor housing | The sensor housing is filled with dry nitrogen gas and protects the electronics and mechanics inside. |
| | If a measuring tube fails (e.g. due to process characteristics like corrosive or abrasive fluids), the fluid will initially be contained by the sensor housing. |
| | In the event of a tube failure, the pressure level inside the sensor housing will rise according to the operating process pressure. If the user judges that the sensor housing burst pressure does not provide an adequate safety margin, the device can be fitted with a rupture disk. This prevents excessively high pressure from forming inside the sensor housing. Therefore, the use of a rupture disk is strongly recommended in applications |

⁴⁾ The cleaning refers to the measuring instrument only. Any accessories supplied are not cleaned.

involving high gas pressures, and particularly in applications in which the process pressure is greater than 2/3 of the sensor housing burst pressure.

High-pressure devices are always fitted with a rupture disk: order code for "Measuring tube mat., wetted surface", option HB

Burst pressure of the sensor housing

If the device is fitted with a rupture disk (order code for "Sensor option", option CA "Rupture disk"), the rupture disk trigger pressure is decisive .

The sensor housing burst pressure refers to a typical internal pressure which is reached prior to mechanical failure of the sensor housing and which was determined during type testing. The corresponding type test declaration can be ordered with the device (order code for "Additional approval", option LN "Sensor housing burst pressure, type test").

| D | N | Sensor housing burst pressure | | |
|------|------|-------------------------------|---------|--|
| [mm] | [in] | [bar] | [psi] | |
| 1 | 1/24 | 220 | 3 190 | |
| 2 | 1/12 | 140 | 2 0 3 0 | |
| 4 | 1⁄8 | 105 | 1520 | |

For information on the dimensions: see the "Mechanical construction" section of the "Technical Information" document

Rupture disk To increase the level of safety, a device version with a rupture disk with a trigger pressure of 10 to 15 bar (145 to 217.5 psi)can be used (order code for "Sensor option", option CA "rupture disk").

Drain connection for rupture disk

To allow any escaping medium to drain in a controlled manner in the event of an error, an optional drain connection can be ordered in addition to the rupture disk.

The function of the rupture disk is not compromised in any way.

Flow limit

Select the nominal diameter by optimizing between the required flow range and permissible pressure loss.

For an overview of the full scale values for the measuring range, see the "Measuring range" section $\rightarrow \cong 251$

- The minimum recommended full scale value is approx. 1/20 of the maximum full scale value
- In most applications, 20 to 50 % of the maximum full scale value can be considered ideal
- A low full scale value must be selected for abrasive media (such as liquids with entrained solids): flow velocity < 1 m/s (< 3 ft/s).
- For gas measurement the following rules apply:
 - The flow velocity in the measuring tubes should not exceed half the sound velocity (0.5 Mach).
 - The maximum mass flow depends on the density of the gas: formula
 - To calculate the flow limit, use the Applicator sizing tool $\rightarrow \square 249$

Pressure loss

To calculate the pressure loss, use the Applicator sizing tool $\rightarrow \cong 249$

System pressure

→ 🖺 24

16.10 Mechanical construction

| Design, dimensions | For the dimensions and installation lengths of the device, see the "Technical |
|--------------------|---|
| | Information" document, "Mechanical construction" section |

Weight

All values (weight exclusive of packaging material) refer to devices with VCO couplings.

Transmitter Proline 500 – digital polycarbonate: 1 (kg (3.1 lbs))

- Proline 500 digital polycarbonate: 1.4 kg (3.1 lbs)
- Proline 500 digital aluminum: 2.4 kg (5.3 lbs)
- Proline 500 aluminum: 6.5 kg (14.3 lbs)
- Proline 500 cast, stainless: 15.6 kg (34.4 lbs)

Sensor

Sensor with aluminum connection housing version:

Weight in SI units

| DN [mm] | Weight [kg] |
|---------|-------------|
| 1 | 2.75 |
| 2 | 4.3 |
| 4 | 6.15 |

Weight in US units

| DN [in] | Weight [lbs] |
|---------|--------------|
| 1/24 | 6 |
| 1/12 | 9 |
| 1/8 | 14 |

Materials

Transmitter housing

Housing of Proline 500 – digital transmitter

Order code for "Transmitter housing":

- Option A "Aluminum coated": aluminum, AlSi10Mg, coated
- Option **D** "Polycarbonate": polycarbonate

Housing of Proline 500 transmitter

Order code for "Transmitter housing":

- Option A "Aluminum coated": aluminum, AlSi10Mg, coated
- Option L "Cast, stainless": cast, stainless steel, 1.4409 (CF3M) similar to 316L

Window material

Order code for "Transmitter housing":

- Option A "Aluminum, coated": glass
- Option **D** "Polycarbonate": plastic
- Option L "Cast, stainless": glass

Fastening components for mounting on a post

- Screws, threaded bolts, washers, nuts: stainless A2 (chrome-nickel steel)
- Metal plates: stainless steel, 1.4301 (304)

Sensor connection housing

Order code for "Sensor connection housing":

- Option A "Aluminum coated": aluminum, AlSi10Mg, coated
- Option B "Stainless": Stainless steel 1.4301 (304)
- Option C "Ultra-compact, stainless": Stainless steel 1.4301 (304)
- Option L "Cast, stainless": 1.4409 (CF3M) similar to 316L

Cable entries/cable glands

| Cable entries and adapters | Material |
|--|--------------------------------|
| Cable gland M20 × 1.5 | Plastic |
| Adapter for cable entry with female thread G ¹/₂" Adapter for cable entry with female thread NPT ¹/₂" | Nickel-plated brass |
| Only available for certain device versions: Order code for "Transmitter housing": Option A "Aluminum, coated" Option D "Polycarbonate" Order code for "Sensor connection housing": Proline 500 - digital: Option A "Aluminum coated" Option B "Stainless" Proline 500: Option B "Stainless" | |
| Adapter for device plug | Stainless steel, 1.4404 (316L) |
| Device plug for digital communication: Only available for certain device versions . Device plug for connecting cable: A device plug is always used for the device version, order code for "Sensor connection housing", option C (ultra- compact, hygienic, stainless). | |

Device plug

| Electrical | connection | Material |
|------------|------------|---|
| Plug M12: | x1 | Socket: Stainless steel, 1.4404 (316L) Contact housing: Polyamide Contacts: Gold-plated brass |

Connecting cables

UV rays can impair the cable outer sheath. Protect the cable from exposure to sun as much as possible.

Connecting cable for sensor - Proline 500 – digital transmitter PVC cable with copper shield

Connecting cable for sensor - Proline 500 transmitter

PVC cable with copper shield

Sensor housing

- Acid and alkali-resistant outer surface
- Stainless steel, 1.4404 (316L)

Measuring tubes

Order code for "Measuring tube mat., wetted surface", option BB, BF, SA

Stainless steel, 1.4435 (316/316L)

Order code for "Measuring tube mat., wetted surface", option HA, HB, HC, HD Alloy C22, 2.4602 (UNS N06022)

Process connections

Order code for "Measuring tube mat., wetted surface", option SA

| VCO coupling | Stainless steel, 1.4404 (316/316L) |
|--|------------------------------------|
| G¼", G½" female thread | Stainless steel, 1.4404 (316/316L) |
| NPT¼", NPT½" female thread | Stainless steel, 1.4404 (316/316L) |
| Tri-Clamp½" | Stainless steel, 1.4435 (316L) |
| Fixed flange EN 1092-1, ASME B16.5, JIS B2220 | Stainless steel, 1.4404 (316/316L) |

Order code for "Measuring tube mat., wetted surface", option BB, BF

| VCO coupling | Stainless steel, 1.4404 (316/316L) |
|----------------------------|------------------------------------|
| Tri-Clamp ¹ /2" | Stainless steel, 1.4435 (316L) |

Order code for "Measuring tube mat., wetted surface", option HC, HD

| VCO coupling | Alloy C22, 2.4602 (UNS N06022) |
|--------------|--------------------------------|
| Tri-Clamp½" | Alloy C22, 2.4602 (UNS N06022) |

Order code for "Measuring tube mat., wetted surface", option HA

| VCO coupling | Alloy C22, 2.4602 (UNS N06022) |
|---|---|
| G¼", G½" female thread | Alloy C22, 2.4602 (UNS N06022) |
| NPT¼", NPT½" female thread | Alloy C22, 2.4602 (UNS N06022) |
| Fixed flange EN 1092-1, ASME B16.5, JIS B2220 | Alloy C22, 2.4602 (UNS N06022) |
| Lap joint flange EN 1092-1, ASME B16.5, JIS B2220 | Stainless steel, 1.4301 (F304), wetted parts Alloy C22, 2.4602 (UNS N06022) |

Order code for "Measuring tube mat., wetted surface", option HB (high-pressure option)

| 1 | VCO coupling | Alloy C22, 2.4602 (UNS N06022) |
|---|------------------------|--------------------------------|
| (| G¼", G½" female thread | Alloy C22, 2.4602 (UNS N06022) |

| NPT¼", NPT½" female thread | Alloy C22, 2.4602 (UNS N06022) |
|--|--|
| Fixed flange EN 1092-1, ASME B16.5, JIS B2220 | Stainless steel, 1.4404 (316/316L); Alloy C22, 2.4602 (UNS N06022) |

Process connections→ 🖺 270

Seals

Welded process connections without internal seals

Accessories

Sensor holder

Stainless steel, 1.4404 (316L)

Heating jacket

- Heating jacket housing: stainless steel, 1.4571 (316Ti)
- NPT adapter ½": stainless steel, 1.4404 (316)
- G¹/₂" adapter: stainless steel, 1.4404

Protective cover

Stainless steel, 1.4404 (316L)

External WLAN antenna

- Antenna: ASA plastic (acrylonitrile styrene acrylate) and nickel-plated brass
- Adapter: Stainless steel and nickel-plated brass
- Cable: Polyethylene
- Plug: Nickel-plated brass
- Angle bracket: Stainless steel

Process connections

- Fixed flange connections:
 - EN 1092-1 (DIN 2501) flange
 - EN 1092-1 (DIN 2512N) flange
 - ASME B16.5 flange
 - JIS B2220 flange
- Clamp connections:
 - Tri-Clamp (OD tubes), DIN 11866 series C
- VCO connections: 4-VCO-4
- Internal thread:
 - Cylindrical internal thread BSPP (G) in accordance with ISO 228-1
 - NPT
- Process connection materials → 🖺 269

Surface roughness

All data refer to parts in contact with the medium.

The following surface roughness categories can be ordered:

| Category | Method | Option(s) order code "Measuring tube mat., wetted surface" |
|--|-------------------------------------|---|
| Not polished | - | HA, HB, SA |
| Ra \leq 0.76 µm (30 µin) ¹⁾ | Mechanically polished ²⁾ | BB, HC |
| Ra \leq 0.38 µm (15 µin) ¹⁾ | Mechanically polished ²⁾ | BF, HD |

1) Ra according to ISO 21920

2) Except for inaccessible welds between pipe and manifold

16.11 User interface

| Languages | Can be operated in the following languages: Via local operation English, German, French, Spanish, Italian, Dutch, Portuguese, Polish, Russian, Turkish, Chinese, Japanese, Korean, Vietnamese, Czech, Swedish Via web browser English, German, French, Spanish, Italian, Dutch, Portuguese, Polish, Russian, Turkish, Chinese, Japanese, Vietnamese, Czech, Swedish Via "FieldCare", "DeviceCare" operating tool: English, German, French, Spanish, Italian, Chinese, Japanese |
|------------------|---|
| Onsite operation | Via display module Features: Order code for "Display; operation", option F "4-line, illuminated, graphic display; touch control" Order code for "Display; operation", option G "4-line, illuminated, graphic display; touch control + WLAN" Information about WLAN interface → 88 |
| | |

- ☑ 41 Operation with touch control
- 1 Proline 500 digital
- 2 Proline 500

A002823

Display elements

- 4-line, illuminated, graphic display
- White background lighting; switches to red in event of device errors
- Format for displaying measured variables and status variables can be individually configured

Operating elements

- External operation via touch control (3 optical keys) without opening the housing: \pm , \Box , Ξ
- Operating elements also accessible in the various zones of the hazardous area

| Remote operation | → 🗎 87 |
|-------------------|--------|
| Service interface | → 🗎 87 |

Supported operating tools

Different operating tools can be used for local or remote access to the measuring device. Depending on the operating tool used, access is possible with different operating units and via a variety of interfaces.

| Supported operating tools | Operating unit | Interface | Additional information |
|---------------------------|--|---|--|
| Web browser | Notebook, PC or tablet with Web browser | CDI-RJ45 service interfaceWLAN interface | Special Documentation for device $\rightarrow \cong 279$ |
| DeviceCare SFE100 | Notebook, PC or tablet with Microsoft Windows system | CDI-RJ45 service interfaceWLAN interfaceFieldbus protocol | → 🗎 249 |
| FieldCare SFE500 | Notebook, PC or tablet with Microsoft Windows system | CDI-RJ45 service interface WLAN interface Fieldbus protocol | → 🗎 249 |
| Field Xpert | SMT70/77/50 | All fieldbus protocols WLAN interface Bluetooth CDI-RJ45 service interface | Operating Instructions BA01202S Device description files: Use update function of handheld terminal |
| SmartBlue app | Smartphone or tablet with iOs or Android | WLAN | → 🗎 249 |

Other operating tools based on FDT technology with a device driver such as DTM/ iDTM or DD/EDD can be used for device operation. These operating tools are available from the individual manufacturers. Integration into the following operating tools, among others, is supported:

- FactoryTalk AssetCentre (FTAC) from Rockwell Automation → www.rockwellautomation.com
- Process Device Manager (PDM) from Siemens → www.siemens.com
- Field Device Manager (FDM) from Honeywell → www.process.honeywell.com
- FieldMate from Yokogawa → www.yokogawa.com
- PACTWare → www.pactware.com

The related device description files are available: www.endress.com \rightarrow Download Area

Web server

| | With the integrated web server, the device can be operated and configured via a web browser service interface (CDI-RJ45) or WLAN interface. The structure of the operating menu is the same as for the local display. In addition to the measured values, status information on the device is displayed and can be used to monitor device health. Furthermore the device data can be managed and the network parameters can be configured. |
|-----------------------------|--|
| | A device that has a WLAN interface (can be ordered as an option) is required for the WLAN connection: order code for "Display; operation", option G "4-line, illuminated; touch control + WLAN". The device acts as an Access Point and enables communication by computer or a mobile handheld terminal. |
| | Supported functions Data exchange between the operating unit (such as a notebook, for example,) and measuring instrument: Upload the configuration from the measuring instrument (XML format, configuration backup) Save the configuration to the measuring instrument (XML format, restore configuration) Export event list (.csv file) Export parameter settings (.csv file or PDF file, document the measuring point configuration) Export the Heartbeat Technology verification report (PDF file, only available with the Heartbeat Verification → 🖺 277 application package) Flash firmware version for device firmware upgrade, for example Download driver for system integration Visualize up to 1000 saved measured values (only available with the Extended |
| HistoROM data management | HistoROM application package → ⁽¹⁾ 277) The measuring device features HistoROM data management. HistoROM data management comprises both the storage and import/export of key device and process data, making operation and servicing far more reliable, secure and efficient. |
| | When the device is delivered, the factory settings of the configuration data are stored as a backup in the device memory. This memory can be overwritten with an updated data record, for example after commissioning. |

Additional information on the data storage concept

There are different types of data storage units in which device data are stored and used by the device:

| | HistoROM backup | T-DAT | S-DAT |
|------------------|---|--|---|
| Available data | Event logbook, e.g. diagnostic events Parameter data record backup Device firmware package Driver for system integration for exporting via web server, e.g.: GSD for PROFIBUS PA | Measured value logging ("Extended HistoROM" order option) Current parameter data record (used by firmware at run time) Indicator (minimum/maximum values) Totalizer value | Sensor data: e.g. nominal diameter Serial number Calibration data Device configuration (e.g. SW options, fixed I/O or multi I/O) |
| Storage location | Fixed on the user interface PC board in the connection compartment | Can be plugged into the user interface PC board in the connection compartment | In the sensor plug in the transmitter neck part |

Data backup

Automatic

- The most important device data (sensor and transmitter) are automatically saved in the DAT modules
- If the transmitter or measuring device is replaced: once the T-DAT containing the previous device data has been exchanged, the new measuring device is ready for operation again immediately without any errors
- If the sensor is replaced: once the sensor has been replaced, new sensor data are transferred from the S-DAT in the measuring device and the measuring device is ready for operation again immediately without any errors
- If exchanging the electronics module (e.g. I/O electronics module): Once the electronics module has been replaced, the software of the module is compared against the current device firmware. The module software is upgraded or downgraded where necessary. The electronics module is available for use immediately afterwards and no compatibility problems occur.

Manual

Additional parameter data record (complete parameter settings) in the integrated device memory HistoROM backup for:

Data backup function

Backup and subsequent restoration of a device configuration in the device memory HistoROM backup

 Data comparison function Comparison of the current device configuration with the device configuration saved in the device memory HistoROM backup

Data transmission

Manual

- Transfer of a device configuration to another device using the export function of the specific operating tool, e.g. with FieldCare, DeviceCare or Web server: to duplicate the configuration or to store in an archive (e.g. for backup purposes)
- Transmission of the drivers for system integration via Web server, e.g.: GSD for PROFIBUS PA

Event list

Automatic

- Chronological display of up to 20 event messages in the events list
- If the **Extended HistoROM** application package (order option) is enabled: up to 100 event messages are displayed in the events list along with a time stamp, plain text description and remedial measures
- The events list can be exported and displayed via a variety of interfaces and operating tools e.g. DeviceCare, FieldCare or Web server

Data logging

Manual

If the **Extended HistoROM** application package (order option) is enabled:

- Recording of 1 to 4 channels of up to 1000 measured values (up to 250 measured values per channel)
- User configurable recording interval
- Export the measured value log via a variety of interfaces and operating tools e.g. FieldCare, DeviceCare or web server

| 16.12 Certificates and approvals |
|--|
| Current certificates and approvals for the product are available at <u>www.endress.com</u> on the relevant product page: |
| 1. Select the product using the filters and search field. |
| 2. Open the product page. |
| 3. Select Downloads . |
| The device meets the legal requirements of the applicable EU Directives. These are listed in the corresponding EU Declaration of Conformity along with the standards applied. |
| Endress+Hauser confirms successful testing of the device by affixing to it the CE mark. |
| The device meets the legal requirements of the applicable UK regulations (Statutory Instruments). These are listed in the UKCA Declaration of Conformity along with the designated standards. By selecting the order option for UKCA marking, Endress+Hauser confirms a successful evaluation and testing of the device by affixing the UKCA mark. |
| Contact address Endress+Hauser UK: Endress+Hauser Ltd. |
| Floats Road Manchester M23 9NF |
| United Kingdom |
| www.uk.endress.com |
| The measuring system meets the EMC requirements of the "Australian Communications and Media Authority (ACMA)". |
| 3-A approval Only measuring instruments with the order code for "Additional approval", option LP "3A" have 3-A approval. The 3-A approval refers to the measuring instrument. |
| When installing the measuring instrument, ensure that no liquid can accumulate on |
| the outside of the measuring instrument. |
| A remote display module must be installed in accordance with the 3-A Standard. Accessories (e.g. heating jacket, weather protection cover, wall holder unit) must be installed in accordance with the 3-A Standard. |
| Each accessory can be cleaned. Disassembly may be necessary under certain circumstances. |
| • FDA |
| Food Contact Materials Regulation (EC) 1935/2004 Observe the special installation instructions |
| |
| PROFIBUS interface |
| The measuring device is certified and registered by the PNO (PROFIBUS Nutzerorganisation e.V./PROFIBUS User Organization). The measuring system meets all the requirements of the following specifications: • Certified according to PA Profile 3.02 • The device can also be operated with certified devices of other manufacturers |
| |

| Radio approval | The measuring device has radio approval. | | | | | |
|--------------------------|---|--|--|--|------------------------------------|---|
| | For detailed information on the radio approval, see the Special Documentation $\rightarrow \cong 279$ | | | | | |
| Additional certification | CRN approval | | | | | |
| | Some device versions have CRN approval. A CRN-approved process connection with a CSA approval must be ordered for a CRN-approved device. | | | | | |
| | Tests and ce | ertificates | | | | |
| | Technology verification report Radiographic testing ASME B31.3 NFS (RT), process connection, weld seam, Heartbeat Technology verification report Radiographic testing ASME VIII Div.1 (RT), process connection, weld seam, Heartbeat Technology verification report Radiographic testing NORSOK M-601 (RT), process connection, weld seam, Heartbeat Technology verification report Radiographic testing ISO 10675-1 ZG1 (DR), process connection, weld seam, Heartbeat Technology verification report Radiographic testing ASME B31.3 NFS (DR), process connection, weld seam, Heartbeat Technology verification report Radiographic testing ASME B31.3 NFS (DR), process connection, weld seam, Heartbeat Technology verification report Radiographic testing ASME VIII Div.1 (DR), process connection, weld seam, Heartbeat Technology verification report Radiographic testing ASME VIII Div.1 (DR), process connection, weld seam, Heartbeat Technology verification report Radiographic testing NORSOK M-601 (DR), process connection, weld seam, Heartbeat Technology verification report | | | | | |
| | Radiograph | hic testing NORSC | 0KM-601 (DR), | process connect | tion, weld seam | n, Heartbeat |
| | Radiograph Technology Testing of we | hic testing NORSC | 0KM-601 (DR), | - | tion, weld seam | n, Heartbeat |
| | Radiograph Technology | hic testing NORSC y verification repo | 0K M-601 (DR), ort | - | tion, weld seam NORSOK M-601 | |
| | Radiograph Technology Testing of we | hic testing NORSC y verification repo elded connections | OK M-601 (DR), ort Test sta ASME | andard ASME | NORSOK | Process |
| | Radiograph Technology Testing of we Option | hic testing NORSC y verification repo elded connections ISO 10675-1 AL1 | OK M-601 (DR), ort Test sta ASME | andard ASME | NORSOK | Process connection |
| | Radiograph Technology <i>Testing of we</i> Option KE | hic testing NORSC y verification repo elded connections ISO 10675-1 AL1 | OK M-601 (DR), ort Test sta ASME | andard ASME | NORSOK | Process connection RT |
| | Radiograph Technology Testing of we Option KE KI | hic testing NORSC y verification repo elded connections ISO 10675-1 AL1 | OK M-601 (DR), ort Test sta ASME | andard ASME VIII Div.1 | NORSOK | Process connection RT RT |
| | Radiograph Technology <i>Testing of we</i> Option KE KI KN | hic testing NORSC y verification repo elded connections ISO 10675-1 AL1 | OK M-601 (DR), ort Test sta ASME | andard ASME VIII Div.1 | NORSOK M-601 | Process connection RT RT RT RT |
| | Radiograph Technology Testing of we Option KE KI KN KS | hic testing NORSC y verification repo elded connections ISO 10675-1 AL1 x | OK M-601 (DR), ort Test sta ASME | andard ASME VIII Div.1 | NORSOK M-601 | Process connection RT RT RT RT RT |
| | Radiograph Technology <i>Testing of we</i> Option KE KI KN KS K5 | hic testing NORSC y verification repo elded connections ISO 10675-1 AL1 x | OK M-601 (DR), ort Test sta ASME B31.3 NFS x | andard ASME VIII Div.1 | NORSOK M-601 | Process connection RT RT RT RT RT DR |
| | Radiograph Technology <i>Testing of we</i> Option KE KI KN KS K5 K6 K6 KB KB KB KB KB KB | hic testing NORSC y verification repo elded connections ISO 10675-1 AL1 x | OK M-601 (DR), ort Test sta ASME B31.3 NFS x | andard ASME VIII Div.1 X | NORSOK M-601 | Process connection RT RT RT RT RT DR DR DR |
| | Radiograph Technology <i>Testing of we</i> Option KE KI KN KS K5 K6 K7 | hic testing NORSC y verification repo elded connections ISO 10675-1 AL1 x x | DK M-601 (DR), ort Test sta ASME B31.3 NFS x x | andard ASME VIII Div.1 x x DR = Digital radiog | NORSOK M-601 | Process connection RT RT RT RT RT RT DR DR DR DR |

Safety requirements for electrical equipment for measurement, control and laboratory use - general requirements

■ EN 61326-1/-2-3

EMC requirements for electrical equipment for measurement, control and laboratory use

NAMUR NE 21

Electromagnetic compatibility (EMC) of industrial process and laboratory control equipment

 NAMUR NE 32 Data retention in the event of a power failure in field and control instruments with microprocessors

NAMUR NE 43
 Standardization of the signal level for the breakdown information of digital transmitters with analog output signal.

• NAMUR NE 53

Software of field devices and signal-processing devices with digital electronics

NAMUR NE 105 Specifications for integrating fieldbus devices in engineering tools for field devices
NAMUR NE 107

- Self-monitoring and diagnosis of field devices
- NAMUR NE 131 Requirements for field devices for standard applications
- NAMUR NE 132

Coriolis mass meter

- ETSI EN 300 328
- Guidelines for 2.4 GHz radio components.

• EN 301489 Electromagnetic compatibility and radio spectrum matters (ERM).

16.13 Application packages

| | Many different application packages are available to enhance the functionality of the device. Such packages might be needed to address safety aspects or specific application requirements. |
|--------------------------|--|
| | The application packages can be ordered with the device or subsequently from Endress+Hauser. Detailed information on the order code in question is available from your local Endress+Hauser sales center or on the product page of the Endress+Hauser website: www.endress.com. |
| | Detailed information on the application packages: Special Documentation $\rightarrow \cong 279$ |
| Diagnostic functionality | Order code for "Application package", option EA "Extended HistoROM" |
| | Comprises extended functions concerning the event log and the activation of the measured value memory. |
| | Event log: Memory volume is extended from 20 message entries (standard version) to up to 100 entries. |
| | Data logging (line recorder): Memory capacity for up to 1000 measured values is activated. 250 measured values can be output via each of the 4 memory channels. The recording interval can be defined and configured by the user. Measured value logs can be accessed via the local display or operating tool e.g. FieldCare, DeviceCare or Web server. |
| | For detailed information, see the Operating Instructions for the device. |

Heartbeat Technology

Order code for "Application package", option EB "Heartbeat Verification + Monitoring"

| | Traceable verification results on request, including a report. Simple testing process via local operation or other operating interfaces. Clear measuring point assessment (pass/fail) with high test coverage within the framework of manufacturer specifications. Extension of calibration intervals according to operator's risk assessment. |
|-----------------|---|
| | Heartbeat Monitoring Continuously supplies data, which are characteristic of the measuring principle, to an external condition monitoring system for the purpose of preventive maintenance or process analysis. These data enable the operator to: Draw conclusions - using these data and other information - about the impact process influences (e.g. corrosion, abrasion, buildup etc.) have on the measuring performance over time. Schedule servicing in time. Monitor the process or product quality, e.g. gas pockets . |
| | For detailed information, see the Special Documentation for the device. |
| Concentration | Order code for "Application package", option ED "Concentration" |
| measurement | Calculation and outputting of fluid concentrations. |
| | The measured density is converted to the concentration of a substance of a binary mixture using the "Concentration" application package: Choice of predefined fluids (e.g. various sugar solutions, acids, alkalis, salts, ethanol etc.). Common or user-defined units ("Brix, "Plato, % mass, % volume, mol/l etc.) for standard applications. |
| | Concentration calculation from user-defined tables. For detailed information, see the Special Documentation for the device. |
| Special density | Order code for "Application package", option EE "Special density" |
| | Many applications use density as a key measured value for monitoring quality or controlling processes. The measuring instrument measures the density of the fluid as standard and makes this value available to the control system. |
| | The "Special Density" application package offers high-precision density measurement over a wide density and temperature range particularly for applications subject to varying process conditions. |
| | For detailed information, see the Operating Instructions for the device. |

16.14 Accessories

Heartbeat Verification

Overview of accessories available to order \rightarrow \cong 247



For an overview of the scope of the associated Technical Documentation, refer to the following:

- *Device Viewer* (www.endress.com/deviceviewer): Enter the serial number from the nameplate
- *Endress+Hauser Operations app*: Enter serial number from nameplate or scan matrix code on nameplate.

| Standard documentation | Brief operating instructions |
|------------------------|------------------------------|
| | brief operating motifactions |

Brief Operating Instructions for the sensor

| Measuring instrument | Documentation code |
|----------------------|--------------------|
| Proline Promass A | KA01282D |

Brief Operating Instructions for the transmitter

| Measuring device | Documentation code |
|-----------------------|--------------------|
| Proline 500 – digital | KA01392D |
| Proline 500 | KA01391D |

Technical information

| Measuring device | Documentation code |
|------------------|--------------------|
| Promass A 500 | TI01375D |

Description of device parameters

| Measuring instrument | Documentation code |
|----------------------|--------------------|
| Promass 500 | GP01061D |

Supplementary devicedependent documentation

Safety instructions

Safety instructions for electrical equipment for hazardous areas.

Special documentation

| Contents | Documentation code |
|---|--------------------|
| Information on the Pressure Equipment Directive | SD01614D |
| Radio approvals for WLAN interface for A309/A310 display module | SD01793D |
| Web server | SD01668D |
| Heartbeat Technology | SD01705D |
| Concentration measurement | SD01711D |

Installation instructions

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| Installation instructions for spare part sets and accessories | Access the overview of all the available spare part sets via <i>Device Viewer</i> → ⁽¹⁾ 245 Accessories available for order with Installation Instructions → ⁽²⁾ 247 |

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