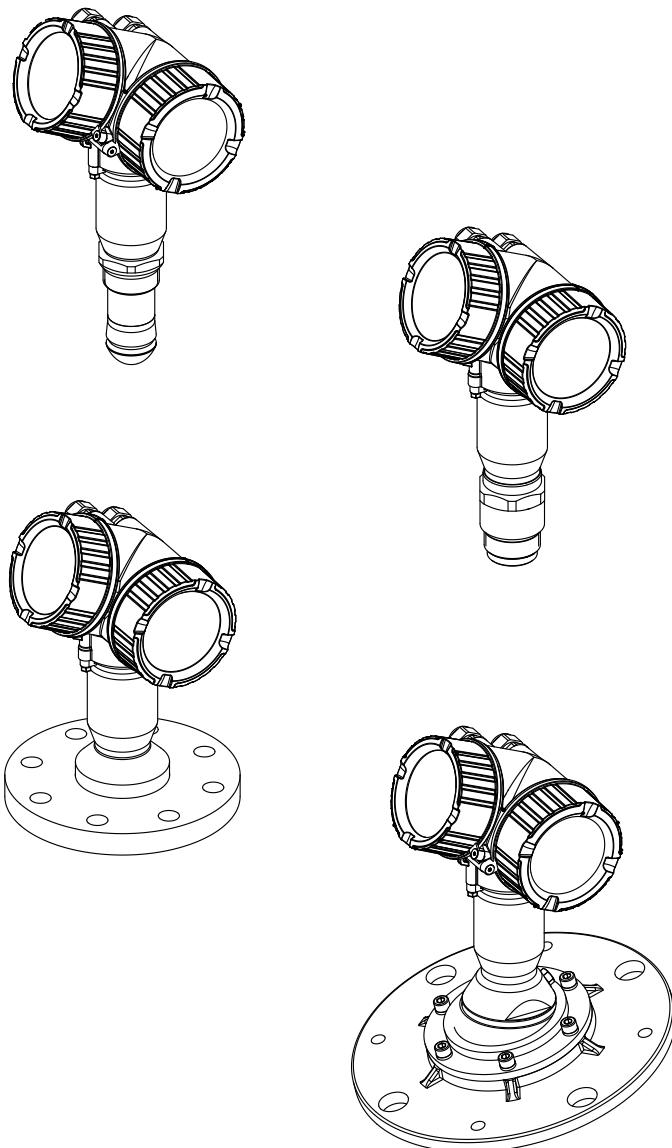


# Description of Device Parameters

## **Micropilot FMR6x**

## **HART**

Free-space radar





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# 1 Important document information

## 1.1 Document function

The document is part of the Operating Instructions and serves as a reference for parameters, providing a detailed explanation of each individual parameter of the operating menu.

## 1.2 Symbols

### 1.2.1 Safety symbols

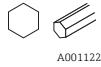
Symbol	Meaning
	<b>DANGER!</b> This symbol alerts you to a dangerous situation. Failure to avoid this situation will result in serious or fatal injury.
	<b>WARNING!</b> This symbol alerts you to a dangerous situation. Failure to avoid this situation can result in serious or fatal injury.
	<b>CAUTION!</b> This symbol alerts you to a dangerous situation. Failure to avoid this situation can result in minor or medium injury.
	<b>NOTE!</b> This symbol contains information on procedures and other facts which do not result in personal injury.

### 1.2.2 Electrical symbols

Symbol	Meaning
$\text{---}$	Direct current
$\sim$	Alternating current
$\overline{\sim}$	Direct current and alternating current
$\perp$	<b>Ground connection</b> A grounded terminal which, as far as the operator is concerned, is grounded via a grounding system.
$\ominus$	<b>Protective ground connection</b> A terminal which must be connected to ground prior to establishing any other connections.
$\triangle$	<b>Equipotential connection</b> A connection that has to be connected to the plant grounding system: This may be a potential equalization line or a star grounding system depending on national or company codes of practice.

### 1.2.3 Tool symbols

Symbol	Meaning
	Torx screwdriver <small>A0013442</small>
	Flat blade screwdriver <small>A0011220</small>

Symbol	Meaning
 A0011219	Cross-head screwdriver
 A0011221	Allen key
 A0011222	Hexagon wrench

#### 1.2.4 Symbols for certain types of information

Symbol	Meaning
	<b>Tip</b> Indicates additional information.
	Reference to documentation
	Reference to page
	Reference to graphic
	Operation via local display
	Operation via operating tool
	Write-protected parameter

#### 1.2.5 Symbols in graphics

Symbol	Meaning
1, 2, 3 ...	Item numbers
A, B, C, ...	Views
A-A, B-B, C-C, ...	Sections

#### 1.2.6 Symbols at the device

Symbol	Meaning
	<b>Safety instructions</b> Observe the safety instructions contained in the associated Operating Instructions.
	<b>Temperature resistance of the connection cables</b> Specifies the minimum value of the temperature resistance of the connection cables.

### 1.3 Terms and abbreviations

Term/abbreviation	Explanation
BA	Document type "Operating Instructions"
KA	Document type "Brief Operating Instructions"
TI	Document type "Technical Information"
SD	Document type "Special Documentation"
XA	Document type "Safety Instructions"
PN	Nominal pressure
MWP	Maximum Working Pressure The MWP can also be found on the nameplate.
ToF	Time of Flight
FieldCare	Scalable software tool for device configuration and integrated plant asset management solutions
DeviceCare	Universal configuration software for Endress+Hauser HART, PROFIBUS, FOUNDATION Fieldbus and Ethernet field devices
DTM	Device Type Manager
DD	Device Description for HART communication protocol
DC	Relative dielectric constant $\epsilon_r$
Operating tool	The term "operating tool" is used in place of the following operating software: FieldCare / DeviceCare, for operation via HART communication and PC
BD	Blocking Distance; no signals are analyzed within the BD.

## 1.4 Registered trademarks

**HART®**

Registered trademark of the HART Communication Foundation, Austin, USA

**KALREZ®, VITON®**

Registered trademark of DuPont Performance Elastomers L.L.C., Wilmington, USA

**TEFLON®**

Registered trademark of E.I. DuPont de Nemours & Co., Wilmington, USA

**TRI CLAMP®**

Registered trademark of Ladish Co. Inc., Kenosha, USA

## 2 Overview of the operating menu



- The following table lists all parameters the "Expert" menu may contain. The page number refers to where a description of the parameter can be found.
- Depending on the device version and parametrization some parameters will not be available in a given situation. For details on the conditions refer to the "Prerequisite" category in the description of the respective parameter.
- The representation essentially corresponds to the menu seen when using an operating tool (e.g. FieldCare). On the local display there may be minor differences in the menu structure. Details are mentioned in the description of the respective submenu.

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Expert

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▶ Display	→  24
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### 3 "Expert" menu

The **Expert** menu contains all parameters of the device. It is structured according to the function blocks of the device.

### 3.1 Description of parameters

Navigation

Expert

#### Direct access


**Navigation**

Expert → Direct access (0106)

**Description**

Enter the access code of a parameter in order to access this parameter directly (i.e. without navigation).

**User entry**

0 to 65 535

**Factory setting**

0

**Additional information**

The direct access code consists of a five digit number and an optional channel code, which specifies an input or output channel, e.g. 00353-2

- Leading zeros need not to be entered.  
Example: You may enter "353" instead of "00353"
- If the channel code is not entered, channel 1 is automatically selected.  
Example: By entering "353" you access the following parameter: Curr.output 1 → Current span (0353)
- In order to access a different channel: Enter the direct access code with the channel code.  
Example: By entering "353-2" you access the following parameter: Curr.output 2 → Current span (0353)

In this document, the direct access code is added in brackets after the parameter name in the *Navigation* category.

Read access	Operator
Write access	Maintenance

---

#### Locking status

**Navigation**

Expert → Locking status (0004)

**Description**

Indicates curr. write protec. with highest prio.

**Additional information**

Read access	Operator
Write access	-

---

#### Access stat.disp

**Navigation**

Expert → Access stat.disp (0091)

**Prerequisite**

The device has a local display.

**Description**

Indicates access authorization to parameter.

**Additional information**

-  The access authorization can be changed via the **Ent. access code** parameter (→ [21](#)).
-  If additional write protection is active, this restricts the current access authorization even further. The write protection status can be viewed via the **Locking status** parameter (→ [20](#)).

Read access	Operator
Write access	-

**Access stat.tool****Navigation**

 Expert → Access stat.tool (0005)

**Description**

Acc.authorization to parameters via operating tool.

**Additional information**

Read access	Operator
Write access	-

-  The access authorization can be changed via the **Ent. access code** parameter (→ [21](#)).
-  If additional write protection is active, this restricts the current access authorization even further. The write protection status can be viewed via the **Locking status** parameter (→ [20](#)).

**Ent. access code****Navigation**

 Expert → Ent. access code (0003)

**Description**

Enter access code to disable write protec.

**User entry**

0 to 9 999

**Additional information**

- For local operation, the customer-specific access code, which has been defined in the **Def. access code** parameter (→ [39](#)), has to be entered.
- If an incorrect access code is entered, the user retains his current access authorization.
- The write protection affects all parameters marked with the -symbol in this document. On the local display, the -symbol in front of a parameter indicates that the parameter is write-protected.
- If no key is pressed for 10 min, or the user switches from the navigation and editing mode back to the measured value display mode, the device automatically locks the write-protected parameters after another 60 s.

 Please contact your Endress+Hauser Sales Center if you lose your access code.

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

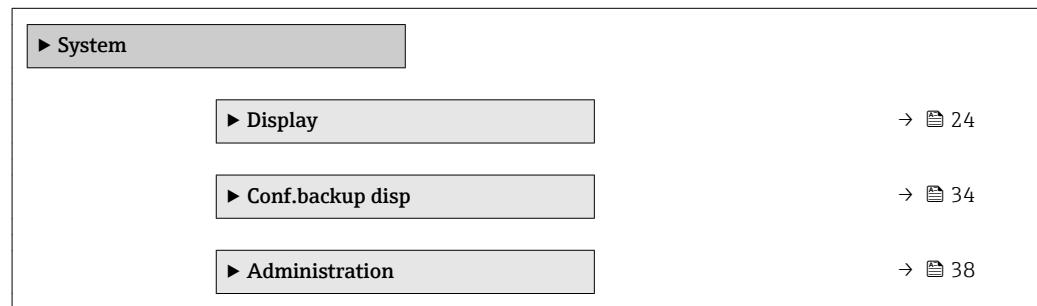
## 3.2 "System" submenu

The **System** submenu contains all general parameters which affect neither the measurement nor the measured value communication.

### 3.2.1 Structure of the submenu

*Navigation*

◀ ▶ Expert → System



### 3.2.2 "Display" submenu

The **Display** submenu is used to configure the representation of measured values on the local display module. Up to four measured values can be allocated to the local display module. Additionally, display characteristics such as the format of numbers, the associated texts or the display contrast can be configured.

 This submenu is only visible if a display module is connected to the device.

#### Structure of the submenu

Navigation

☰ ☰ Expert → System → Display

► Display	
Language	→ ☰ 25
Format display	→ ☰ 25
Value 1 to 4 display	→ ☰ 27
Decimal places 1 to 4	→ ☰ 27
Display interval	→ ☰ 28
Display damping	→ ☰ 28
Header	→ ☰ 28
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Separator	→ ☰ 29
Number format	→ ☰ 30
Dec. places menu	→ ☰ 30
Contrast display	→ ☰ 30
Backlight	→ ☰ 31
Access stat.disp	→ ☰ 31

## Description of parameters

**Navigation**

  Expert → System → Display

### Language

**Navigation**

  Expert → System → Display → Language (0104)

**Description**

Set display language.

**Selection**

- English
- Deutsch \*
- Français \*
- Español \*
- Italiano \*
- Nederlands \*
- Portuguesa \*
- Polski \*
- русский язык(Ru) \*
- Svenska \*
- Türkçe \*
- 中文 (Chinese) \*
- 日本語 (Japanese) \*
- 한국어 (Korean) \*
- Bahasa Indonesia \*
- tiếng Việt (Viet) \*
- čeština (Czech) \*

**Factory setting**

The language selected in feature 500 of the product structure.  
If no language has been selected: **English**

**Additional information**

Read access	Operator
Write access	Operator

### Format display

**Navigation**

  Expert → System → Display → Format display (0098)

**Description**

Select how measured val. are shown on the display.

**Selection**

- 1 value, max.
- Bagr. + 1 value
- 2 values
- Val. large+2val.
- 4 values

**Factory setting**

1 value, max.

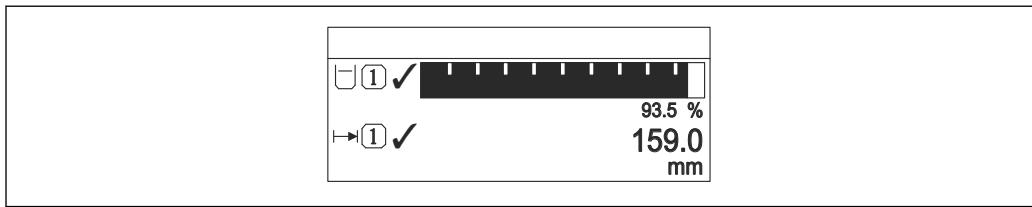
\* Visibility depends on order options or device settings

## Additional information



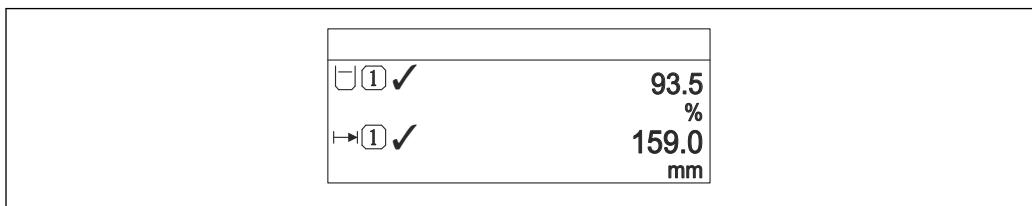
A0019963

■ 1 "Format display" = "1 value, max."



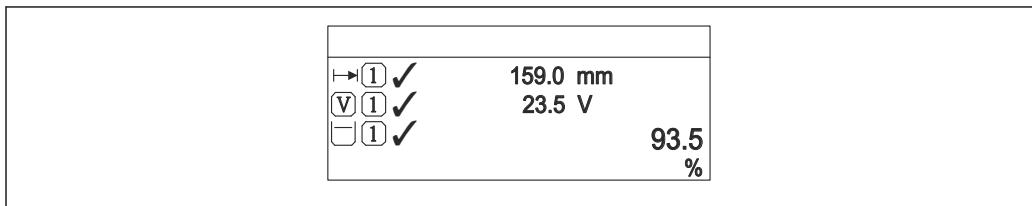
A0019964

■ 2 "Format display" = "Bargr. + 1 value"



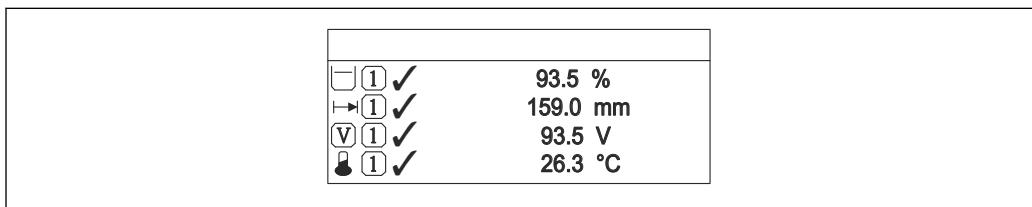
A0019965

■ 3 "Format display" = "2 values"



A0019966

■ 4 "Format display" = "Val. large+2val."



A0019968

■ 5 "Format display" = "4 values"

- i** ■ The **Value 1 to 4 display** → ■ 27 parameters specify which measured values are shown on the display and in which order.
- If more measured values are specified than the current display mode permits, the values alternate on the device display. The display time until the next change is configured in the **Display interval** parameter (→ ■ 28).

Read access	Operator
Write access	Operator

**Value 1 to 4 display**

**Navigation** Expert → System → Display → Value 1 display (0107)

**Description** Select measured value that is shown on the display.

- Selection**
- Level linearized
  - Distance
  - Abs. echo ampl.
  - Relat.echo ampl.
  - Area incoupling
  - Curr.output 1
  - Measur. curr.
  - Curr.output 2 \*
  - Terminal volt.
  - Electronic temp.
  - Analog out. AD 1
  - Analog out. AD 2
  - Analog out. AD 3
  - Analog out. AD 4

- Factory setting**
- Value 1 display: Level linearized
  - Value 2 display: None
  - Value 3 display: None
  - Value 4 display: None

**Additional information**

Read access	Operator
Write access	Maintenance

**Decimal places 1 to 4**

**Navigation** Expert → System → Display → Decimal places 1 (0095)

**Description** This selection does not affect the measurement and calculation accuracy of the device.

- Selection**
- X
  - X.X
  - X.XX
  - X.XXX
  - X.XXXX

- Factory setting** X.XX

**Additional information** The setting does not affect the measuring or computational accuracy of the device.

Read access	Operator
Write access	Maintenance

\* Visibility depends on order options or device settings

---

## Display interval

---

**Navigation**

  Expert → System → Display → Display interval (0096)

**Description**

Time meas. val. are shown if displ. alternates.

**User entry**

1 to 10 s

**Factory setting**

5 s

**Additional information**

This parameter is only relevant if the number of selected measuring values exceeds the number of values the selected display format can display simultaneously.

Read access	Operator
Write access	Operator

---

## Display damping

---

**Navigation**

  Expert → System → Display → Display damping (0094)

**Description**

Display reaction time to fluctuations of meas.val.

**User entry**

0.0 to 999.9 s

**Factory setting**

0.0 s

**Additional information**

Read access	Operator
Write access	Maintenance

---

## Header

---

**Navigation**

  Expert → System → Display → Header (0097)

**Description**

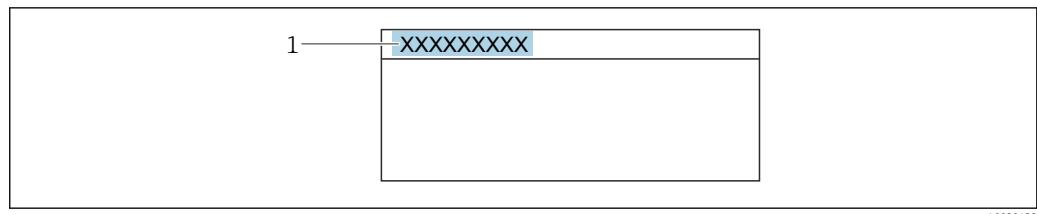
Select display header contents.

**Selection**

- Device tag
- Free text

**Factory setting**

Device tag

**Additional information**

1 Position of the header text on the display

*Meaning of the options***■ Device tag**

Is defined in the **Device tag** parameter (→ 128)

**■ Free text**

Is defined in the **Header text** parameter (→ 29)

Read access	Operator
Write access	Maintenance

**Header text****Navigation**

Expert → System → Display → Header text (0112)

**Prerequisite**

Header (→ 28) = Free text

**Description**

Enter display header text.

**Factory setting**

-----

**Additional information**

The number of characters which can be displayed depends on the characters used.

Read access	Operator
Write access	Maintenance

**Separator****Navigation**

Expert → System → Display → Separator (0101)

**Description**

Select separator for displaying numerical values.

**Selection**

- .
- ,

**Factory setting**

.

**Additional information**

Read access	Operator
Write access	Maintenance

**Number format****Navigation**

Expert → System → Display → Number format (0099)

**Description**

Choose number format for the display.

**Selection**

- Decimal
- ft-in-1/16"

**Factory setting**

Decimal

**Additional information**

The **ft-in-1/16"** option is only valid for distance units.

Read access	Operator
Write access	Maintenance

**Dec. places menu****Navigation**

Expert → System → Display → Dec. places menu (0573)

**Description**

Select number of decimal places for the representation of numbers within the operating menu.

**Selection**

- X
- X.X
- X.XX
- X.XXX
- X.XXXX

**Factory setting**

X.XXX

**Additional information**

- Is only valid for numbers in the operating menu (e.g. **Empty calibr.**, **Full calibr.**), but not for the measured value display. The number of decimal places for the measured value display is defined in the **Decimal places 1 to 4** → 27 parameters.
- The setting does not affect the accuracy of the measurement or the calculations.

Read access	Operator
Write access	Maintenance

**Contrast display****Navigation**

Expert → System → Display → Contrast display (0105)

**Description**

Adjust display contrast setting to ambient cond.

**User entry**

20 to 80 %

**Factory setting**

Dependent on the display.

**Additional information**

Setting the contrast via push-buttons:

- Darker: press the buttons simultaneously.
- Brighter: press the buttons simultaneously.

Read access	Operator
Write access	Operator

---

**Backlight**

---

**Navigation**

Expert → System → Display → Backlight (0111)

**Prerequisite**

The device has the SD03 local display (with optical keys).

**Description**

Switch the local display backlight on and off.

**Selection**

- Disable
- Enable

**Factory setting**

Disable

**Additional information****Meaning of the options****▪ Disable**

Switches the backlight off.

**▪ Enable**

Switches the backlight on.

Regardless of the setting in this parameter the backlight may be automatically switched off by the device if the supply voltage is too low.

Read access	Operator
Write access	Operator

---

**Access stat.disp**

---

**Navigation**

Expert → System → Display → Access stat.disp (0091)

**Prerequisite**

The device has a local display.

**Description**

Indicates access authorization to parameter.

**Additional information**

The access authorization can be changed via the **Ent. access code** parameter (→ 21).

If additional write protection is active, this restricts the current access authorization even further. The write protection status can be viewed via the **Locking status** parameter (→ 20).

<b>Read access</b>	Operator
<b>Write access</b>	-

### 3.2.3 "Conf.backup disp" submenu

 This submenu is only visible if a display module is connected to the device.

All software configurations are initially stored in a memory module (HistoROM) in the housing and are thus permanently connected with the device. As an additional option, the display module contains a backup memory for the device configuration. The transmission of configuration data between these two memory modules is controlled by the **Config. managem.** parameter (→ 35). It provides the following options:

■ **Execute backup**

Saves the current device configuration in the display module.

■ **Restore**

This option can be used to restore a configuration back into the device which has previously been saved in the display module.

■ **Duplicate**

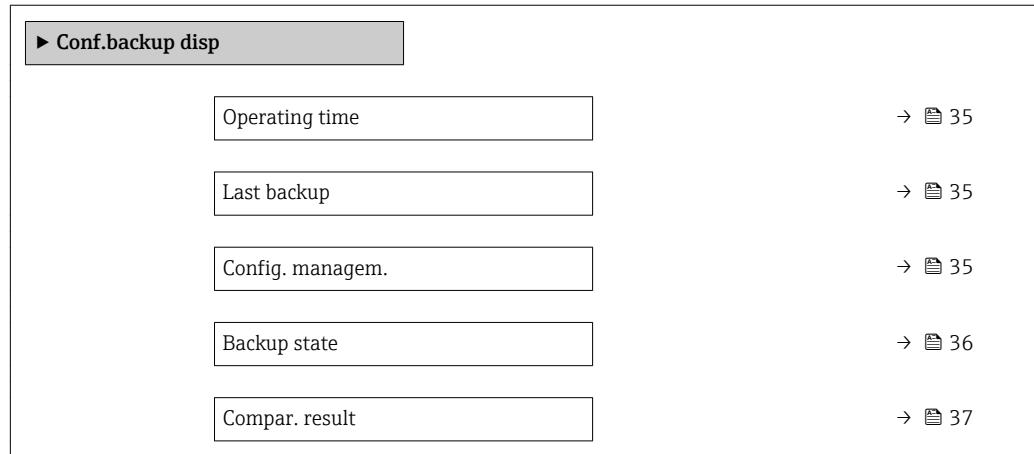
If the configuration has been saved into the display module, the module can be connected to a different device and the configuration can be duplicated to this device. This allows to efficiently configure a number of devices in the same way.

■ **Compare**

The comparison result indicates whether the device configuration has been changed since the last backup.

 If an existing backup is restored to a different device using the **Restore** option, it may occur that some device functionalities are no longer available. Even a reset to the delivery state won't restore the original state in some cases.

In order to transfer the configuration to a different device only the **Duplicate** option should be used.

**Structure of the submenu***Navigation* Expert → System → Conf.backup disp

### Description of parameters

*Navigation*

  Expert → System → Conf.backup disp

#### Operating time

**Navigation**

  Expert → System → Conf.backup disp → Operating time (0652)

**Description**

Indicates how long device has been in operation.

**Additional information**

*Maximum time*

9 999 d ( ≈ 27 years)

Read access	Operator
Write access	-

#### Last backup

**Navigation**

  Expert → System → Conf.backup disp → Last backup (0102)

**Description**

Indicates when last backup was saved to display.

**Additional information**

Read access	Operator
Write access	-

#### Config. managem.



**Navigation**

  Expert → System → Conf.backup disp → Config. managem. (0100)

**Description**

Select action for managing the device data.

**Selection**

- Cancel
- Execute backup
- Restore
- Duplicate
- Compare
- Clear backup

**Factory setting**

Cancel

**Additional information****Meaning of the options****▪ Cancel**

No action is executed and the user exits the parameter.

**▪ Execute backup**

A backup copy of the current device configuration in the HistoROM (built-in in the device) is saved to the display module of the device.

**▪ Restore**

The last backup copy of the device configuration is copied from the display module to the HistoROM of the device.

**▪ Duplicate**

The transmitter configuration is duplicated to another device using the transmitter display module. The following parameters, which characterize the individual measuring point are **not** included in the transmitted configuration:

- HART date code
- HART short tag
- HART message
- HART descriptor
- HART address
- Device tag
- Medium type

**▪ Compare**

The device configuration saved in the display module is compared to the current device configuration of the HistoROM. The result of this comparison is displayed in the **Compar. result** parameter (→ 37).

**▪ Clear backup**

The backup copy of the device configuration is deleted from the display module of the device.

**i** While this action is in progress, the configuration cannot be edited via the local display and a message on the processing status appears on the display.

**i** If an existing backup is restored to a different device using the **Restore** option, it may occur that some device functionalities are no longer available. In some cases even a device reset will not restore the original status.

In order to transmit a configuration to a different device, the **Duplicate** option should always be used.

Read access	Operator
Write access	Maintenance

---

**Backup state****Navigation**

Expert → System → Conf.backup disp → Backup state (0121)

**Description**

Displays which backup action is currently in progress.

**Additional information**

Read access	Operator
Write access	-

---

**Compar. result**

---

**Navigation**

 Expert → System → Conf.backup disp → Compar. result (0103)

**Description**

Comp. between present device data and disp. backup.

**Additional information****Meaning of the display options****■ Set. identical**

The current device configuration of the HistoROM is identical to the backup copy in the display module.

**■ Set. not ident.**

The current device configuration of the HistoROM is not identical to the backup copy in the display module.

**■ No backup**

There is no backup copy of the device configuration of the HistoROM in the display module.

**■ Backup corrupt**

The current device configuration of the HistoROM is corrupt or not compatible with the backup copy in the display module.

**■ Check not done**

The device configuration of the HistoROM has not yet been compared to the backup copy in the display module.

**■ Dataset incomp.**

The data sets are incompatible and can not be compared.

 To start the comparison, set **Config. managem.** (→  35) = **Compare**.

 If the transmitter configuration has been duplicated from a different device by **Config. managem.** (→  35) = **Duplicate**, the new device configuration in the HistoROM is only partially identical to the configuration stored in the display module: Sensor specific properties (e.g. the mapping curve) are not duplicated. Thus, the result of the comparison will be **Set. not ident.**.

Read access	Operator
Write access	-

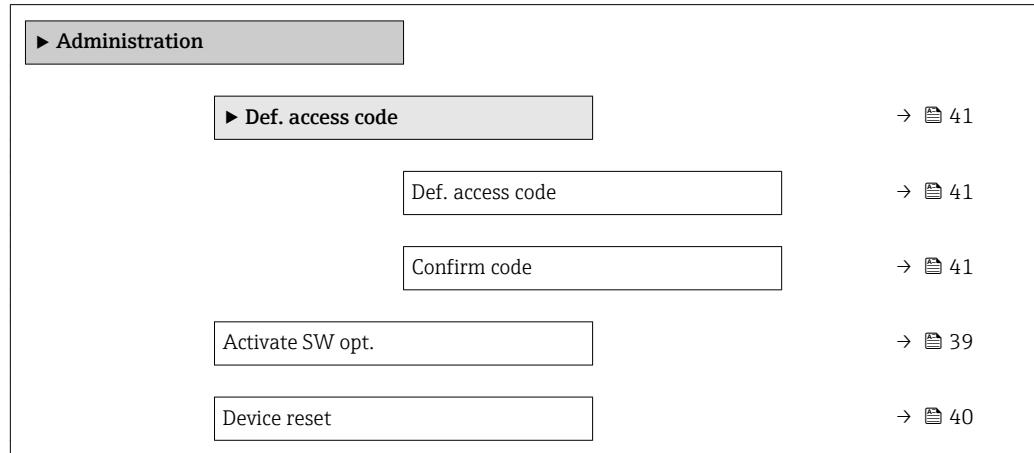
### 3.2.4 "Administration" submenu

The **Administration** submenu contains all parameters for the management of the device. Its structure depends on the user interface:

#### Structure of the submenu on the local display

Navigation

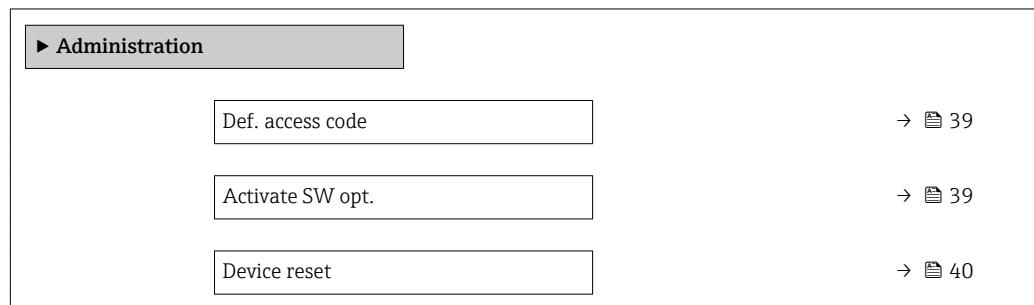
☰ Expert → System → Administration



#### Structure of the submenu in an operating tool

Navigation

☰ Expert → System → Administration



## Description of parameters

*Navigation*



Expert → System → Administration

### Def. access code



**Navigation** Expert → System → Administration → Def. access code (0093)

**Description** Define release code for write access to parameters.

**User entry** 0 to 9 999

**Factory setting** 0

**Additional information**

- If the factory setting is not changed or 0 is defined as the access code, the parameters are not write-protected and the configuration data of the device can then always be modified. The user is logged on in the *Maintenance* role.
- The write protection affects all parameters marked with the symbol in this document. On the local display, the symbol in front of a parameter indicates that the parameter is write-protected.
- Once the access code has been defined, write-protected parameters can only be modified if the access code is entered in the **Ent. access code** parameter (→ 21).
- Please contact your Endress+Hauser Sales Center if you lose your access code.
- For display operation: The new access code is only valid after it has been confirmed in the **Confirm code** parameter (→ 41).

Read access	Operator
Write access	Maintenance

### Activate SW opt.



**Navigation** Expert → System → Administration → Activate SW opt. (0029)

**Description** Enter code to unlock specific software options.

**User entry** Positive integer

**Factory setting** 0

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Device reset****Navigation**

Expert → System → Administration → Device reset (0000)

**Description**

Reset device configuration to a defined state.

**Selection**

- Cancel
- To fact.defaults
- To delivery set.
- Of customer set.
- To transd.def.
- Restart device

**Factory setting**

Cancel

**Additional information****Meaning of the options**

- **Cancel**  
No action
- **To fact.defaults**  
All parameters are reset to the order-code specific factory setting.
- **To delivery set.**  
All parameters are reset to the delivery setting. The delivery setting may differ from the factory default if customer specific settings have been ordered.  
This option is only visible if customer specific settings have been ordered.
- **Of customer set.**  
All customer parameters are reset to their factory setting. Service parameters, however, remain unchanged.
- **To transd.def.**  
Every measurement-related parameter is reset to its factory setting. Service parameters and communication-related parameters, however, remain unchanged.
- **Restart device**  
The restart resets every parameter which is stored in the volatile memory (RAM) to the factory setting (e.g. measured value data). The device configuration remains unchanged.

Read access	Operator
Write access	Maintenance

**"Def. access code" wizard***Navigation*

Expert → System → Administration → Def. access code

**Def. access code****Navigation**

Expert → System → Administration → Def. access code → Def. access code

**Description**

→ 39

**Confirm code****Navigation**

Expert → System → Administration → Def. access code → Confirm code

**Description**

Confirm the entered access code.

**User entry**

0 to 9 999

**Factory setting**

0

**Additional information**

Read access	Operator
Write access	Maintenance

### 3.3 "Sensor" submenu

The **Sensor** submenu contains all parameters related to the measurement and the sensor settings.

#### 3.3.1 Structure of the submenu

*Navigation*

☰ ☰ Expert → Sensor

► Sensor	
Distance unit	→ ☰ 43
Temperature unit	→ ☰ 43
Tank type	→ ☰ 43
Bin type	→ ☰ 44
Max drain liquid	→ ☰ 44
Max. fill liquid	→ ☰ 45
Max.drain solid	→ ☰ 46
Max. fill. solid	→ ☰ 46
► Medium	→ ☰ 48
► Level	→ ☰ 52
► Linearization	→ ☰ 65
► Information	→ ☰ 74
► Distance	→ ☰ 78
► Sensor diag.	→ ☰ 83
► Safety sett.	→ ☰ 89
► Mapping	→ ☰ 98
► Tank bottom eval	→ ☰ 104
► Echo tracking	→ ☰ 106

### 3.3.2 Description of parameters

Navigation

Expert → Sensor



#### Distance unit

Navigation Expert → Sensor → Distance unit (0551)

Description Used for the basic calibration (Empty / Full).

Selection	SI units	US units
■ mm	■ ft	
■ m	■ in	

Factory setting m

Additional information	Read access	Operator
	Write access	Maintenance



#### Temperature unit

Navigation Expert → Sensor → Temperature unit (0557)

Description Used to display the electronics temperature.

Selection	SI units	US units
■ °C	■ °F	
■ K	■ °R	

Factory setting °C

Additional information	Read access	Operator
	Write access	Maintenance



#### Tank type

Navigation Expert → Sensor → Tank type (12519)

Prerequisite Medium type (→ 49) = Liquid

Description Optimizes the signal filters for the respective tank type. Note: 'Workbench test' deactivates all filters. This option should exclusively be used for tests.

**Selection**

- Open channel
- Sphere
- Storage vessel
- Vessel standard
- Vessel w. agitat
- Workbench test

**Factory setting**

Vessel standard

**Additional information**

 **Workbench test** deactivates all filters. This option is intended for tests only.

 Depending on the antenna some of the options mentioned above may not be available or there may be additional options.

Read access	Operator
Write access	Maintenance

**Bin type****Navigation**
  Expert → Sensor → Bin type (12535)
**Prerequisite****Medium type (→  49) = Solid****Description**

Optimizes the signal filters for the respective bin type. Note: 'Workbench test' deactivates all filters. This option should exclusively be used for tests.

**Selection**

- Buffer silo fast
- Bin/ Pile
- Crusher / belt
- Silo
- Workbench test

**Factory setting**

Silo

**Additional information**

 **Workbench test** deactivates all filters. This option is intended for tests only.

Read access	Operator
Write access	Maintenance

**Max drain liquid****Navigation**
  Expert → Sensor → Max drain liquid (12531)
**Prerequisite****Tank type (→  43) = Liquid****Description**

Select expected maximum draining speed.

**Selection**

- Slow < 1cm /min
- Medium <10cm/min
- Standard <1m/min
- Fast < 2m /min
- Very fast > 2m/m
- No filter / test

**Factory setting**

Depending on the **Tank type** parameter (→  43)

**Additional information**

By selecting the maximum expected filling and draining speed the signal evaluation is automatically optimized for the process.

-  The filling and draining speeds can be set separately as the filling and draining procedures may be different.
-  With the **No filter / test** option all signal evaluation filters are deactivated. This option should exclusively be used for tests.
-  **Max. drain liquid** is preset by **Tank type**. It can, however, be adjusted to the process in the vessel at any time. If **Tank type** is changed again, it may be necessary to repeat the fine adjustment.

Read access	Operator
Write access	Maintenance

**Max. fill liquid****Navigation**

 Expert → Sensor → Max. fill liquid (12532)

**Prerequisite**

**Medium type** (→  49) = **Liquid**

**Description**

Select expected maximum filling speed.

**Selection**

- Slow < 1cm /min
- Medium <10cm/min
- Standard <1m/min
- Fast < 2m /min
- Very fast > 2m/m
- No filter / test

**Factory setting**

Depending on the **Tank type** parameter (→  43)

**Additional information**

By selecting the maximum expected filling and draining speed the signal evaluation is automatically optimized for the process.

-  The filling and draining speeds can be set separately as the filling and draining procedures may be different.
-  With the **No filter / test** option all signal evaluation filters are deactivated. This option should exclusively be used for tests.
-  **Max. fill liquid** is preset by **Tank type**. It can, however, be adjusted to the process in the vessel at any time. If **Tank type** is changed again, it may be necessary to repeat the fine adjustment.

Read access	Operator
Write access	Maintenance

**Max.drain solid****Navigation**

Expert → Sensor → Max.drain solid (12533)

**Prerequisite****Medium type (→ 49) = Solid****Description**

Select maximum expecte draining speed.

**Selection**

- Very slow<0.5m/h
- Slow < 1m /h
- Standard < 2m /h
- Medium < 4m /h
- Fast < 8m /h
- Very fast >8m/h
- No filter / test

**Factory setting**

No filter / test

**Additional information**

By specifying the maximum filling and draining speed the signal evaluation is automatically optimized for the process.

The filling and draining speed can be set separately as filling and draining may be different processes.

When selecting the **No filter / test** option all filters of the signal evaluation are deactivated. This option is intended for tests only.

Read access	Operator
Write access	Maintenance

**Max. fill. solid****Navigation**

Expert → Sensor → Max. fill. solid (12534)

**Prerequisite****Medium type (→ 49) = Solid****Description**

Select expected maximum filling speed.

**Selection**

- Very slow<0.5m/h
- Slow < 1m /h
- Standard < 2m /h
- Medium < 4m /h
- Fast < 8m /h
- Very fast >8m/h
- No filter / test

**Factory setting**

No filter / test

**Additional information**

By specifying the maximum filling and draining speed the signal evaluation is automatically optimized for the process.

 The filling and draining speed can be set separately as filling and draining may be different processes.

 When selecting the **No filter / test** option all filters of the signal evaluation are deactivated. This option is intended for tests only.

Read access	Operator
Write access	Maintenance

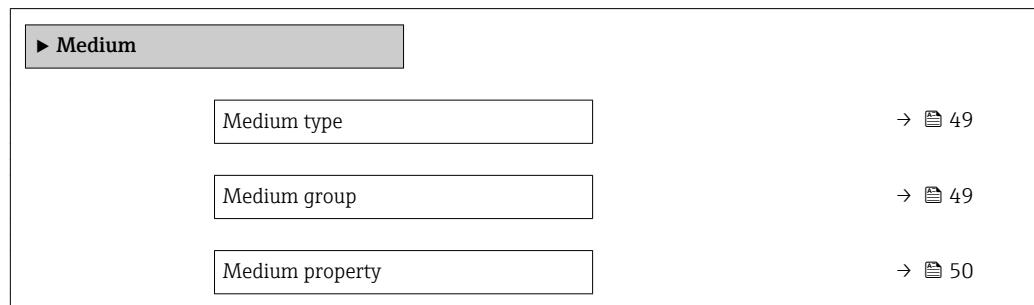
### 3.3.3 "Medium" submenu

The **Medium** submenu is used to specify the relevant properties of the measured medium.

#### Structure of the submenu

*Navigation*

☰ ☰ Expert → Sensor → Medium



**Description of parameters***Navigation* Expert → Sensor → Medium**Medium type****Navigation** Expert → Sensor → Medium → Medium type (12527)**Description**

Specify medium type.

**User interface**

- Liquid
- Solid

**Factory setting**

- Liquid
- Liquid
- Solid

**Additional information**

 This parameter determines the value of several other parameters and strongly influences the complete signal evaluation. Therefore, it is strongly recommended **not to change** the factory setting.

Read access	Operator
Write access	Service

**Medium group****Navigation** Expert → Sensor → Medium → Medium group (12528)**Prerequisite****Medium type** (→  49) = Liquid**Description**

Select medium group.

**Selection**

- Others
- Water based DC>4

**Factory setting**

Others

**Additional information**

This parameter roughly specifies the dielectric constant (DC) of the medium. For a more detailed definition of the DC use the **Medium property** parameter (→  50).

The **Medium group** parameter (→ 49) presets the **Medium property** parameter (→ 50) as follows:

Medium group (→ 49)	Medium property (→ 50)
Others	Unknown
Water based DC>4	DC 4 ... 7

- i** The **Medium property** parameter (→ 50) can be changed subsequently. However, when doing so, the **Medium group** parameter (→ 49) retains its value. Only the **Medium property** is relevant for the signal evaluation.
- i** The measuring range may be reduced for small dielectric constants. For details refer to the Technical Information (TI) of the respective device.

Read access	Operator
Write access	Maintenance

## Medium property



### Navigation

Expert → Sensor → Medium → Medium property (12529)

### Description

Specify relative dielectric constant  $\epsilon_r$  of the medium.

### Selection

- Unknown
- DC 1.4 ... 1.6
- DC 1.6 ... 1.9
- DC 1.9 ... 2.5
- DC 2.5 ... 4
- DC 4 ... 7
- DC 7 ... 15
- DC > 15

### Factory setting

Depending on the **Medium type** (→ 49) and **Medium group** (→ 49) parameters.

### Additional information

*Dependence on "Medium type" and "Medium group"*

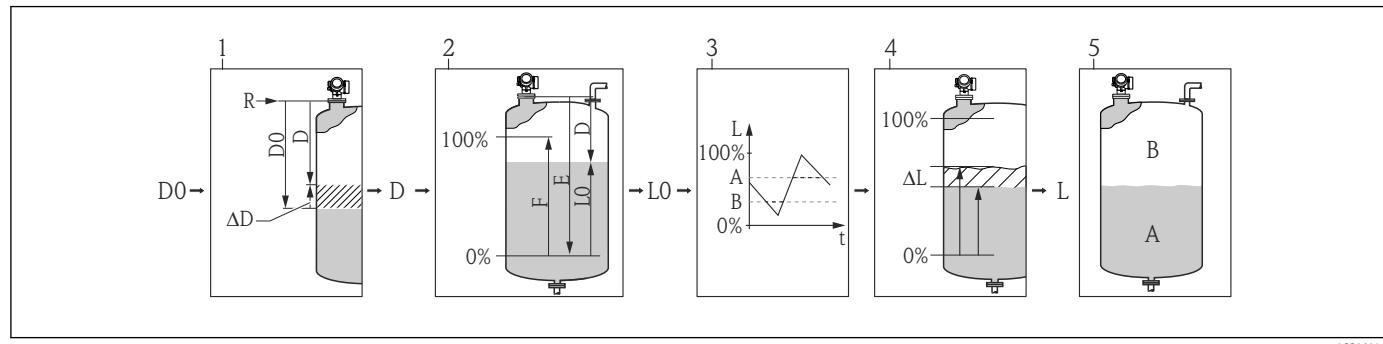
Medium type (→ 49)	Medium group (→ 49)	Medium property (→ 50)
Solid		Unknown
Liquid	Water based DC>4	DC 4 ... 7
	Others	Unknown

- i** For dielectric constants (DC values) of many media commonly used in various industries refer to:
  - the Endress+Hauser DC manual (CP01076F)
  - the Endress+Hauser "DC Values App" (available for Android and iOS)

Read access	Operator
Write access	Maintenance

### 3.3.4 "Level" submenu

The **Level** submenu (→ 52) is used to configure the calculation of the level from the measured distance.



A0016141

6 Calculation of the level from the measured distance

- 1 Correction of the measured distance
- 2 Level calculation
- 3 Level limitation
- 4 Correction of the level
- 5 Definition of the output value: Level (A) or Ullage (B)

## Structure of the submenu

Navigation

☰ ☰ Expert → Sensor → Level

▶ Level	
Empty calibr.	→ ☰ 53
Full calibr.	→ ☰ 54
Tank/silo height	→ ☰ 55
Level unit	→ ☰ 56
Output mode	→ ☰ 57
Distance offset	→ ☰ 57
Distance	→ ☰ 58
Level limit mode	→ ☰ 59
High limit	→ ☰ 60
Low limit	→ ☰ 61
Level correction	→ ☰ 61
Level	→ ☰ 61
Level linearized	→ ☰ 62

### Description of parameters

Navigation

Diagram Expert → Sensor → Level

#### Empty calibr.



Navigation

Diagram Expert → Sensor → Level → Empty calibr. (2343)

Description

Distance between process connection and minimum level (0%).

User entry

Depending on the antenna

Factory setting

Depending on the antenna

Additional information

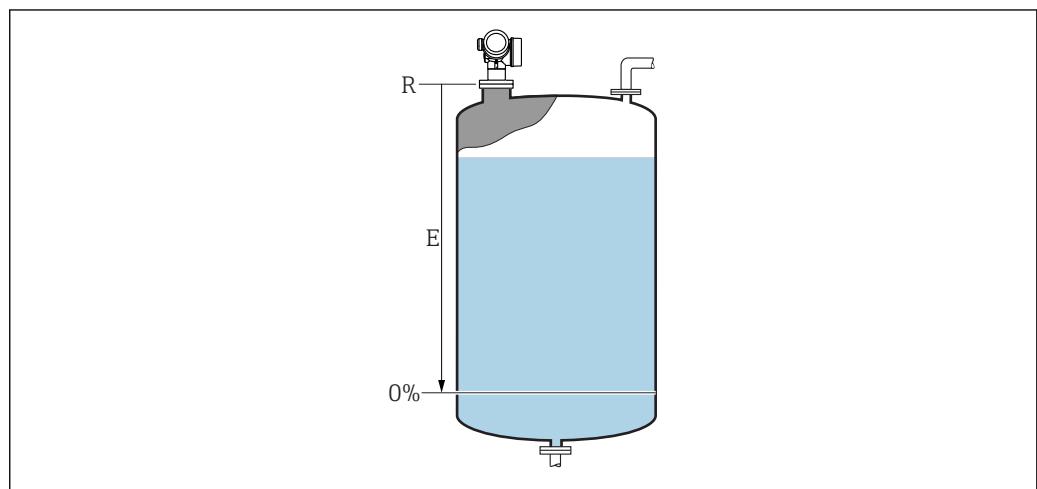


Diagram 7 Empty calibr. (E) for level measurements in liquids

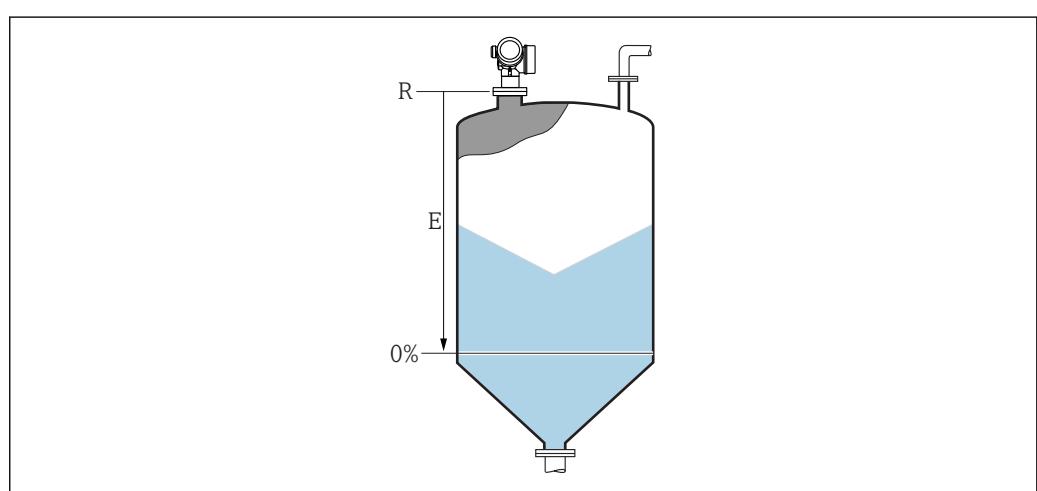


Diagram 8 Empty calibr. (E) for level measurements in bulk solids.

The measuring range starts at the point at which the radar beam hits the tank or silo bottom. In the case of dished boiler ends or conical outlets levels below this point can not be measured.

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

**Full calibr.****Navigation**

Diagram Expert → Sensor → Level → Full calibr. (2308)

**Description**

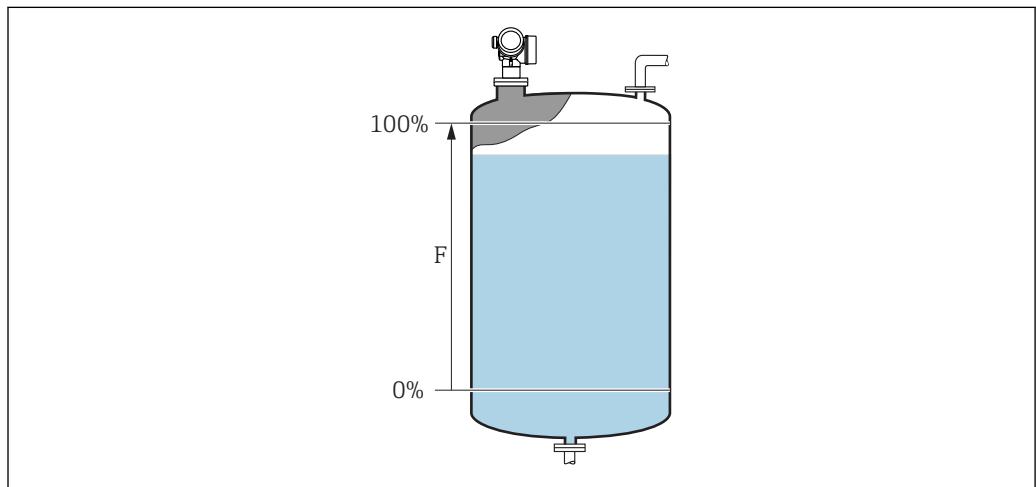
Distance between minimum level (0%) and maximum level (100%).

**User entry**

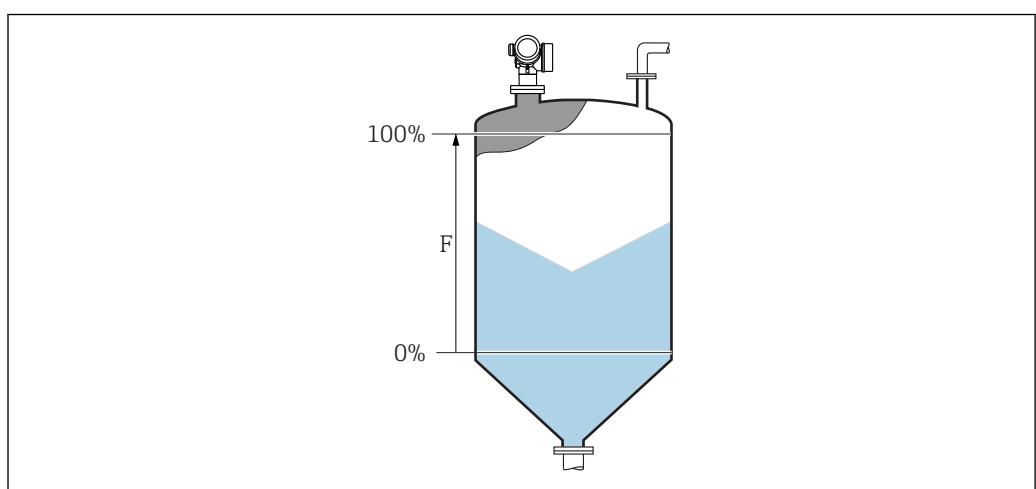
Depending on the antenna

**Factory setting**

Depending on the antenna

**Additional information**

■ 9 Full calibr. (F) for level measurements in liquids



■ 10 Full calibr. (F) for level measurements in bulk solids

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

**Tank/silo height****Navigation**

Expert → Sensor → Level → Tank/silo height (12403)

**Description**

Total height of the tank or silo (measured from the process connection)

**User entry**

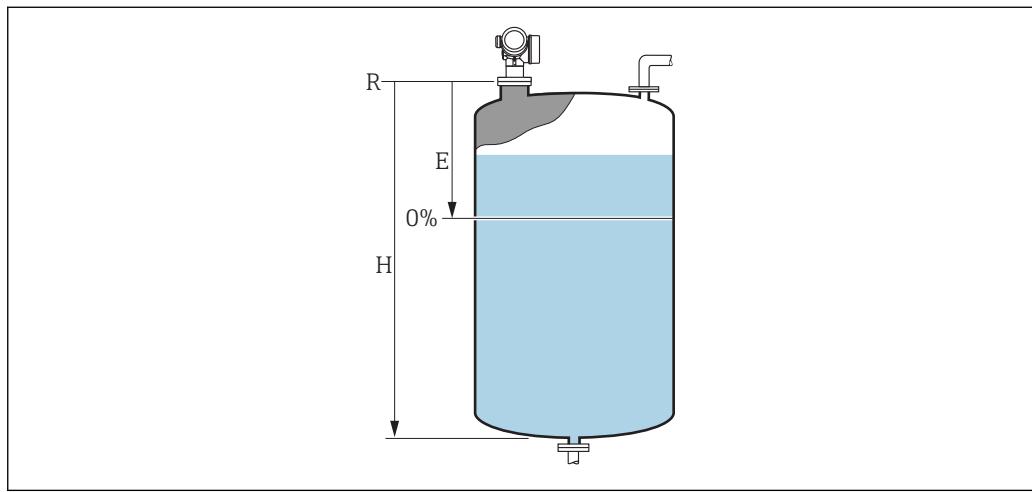
-999.9999 to 999.9999 m

**Factory setting**

Empty calibration (→ [53](#))

**Additional information**

If the parametrized measuring range differs significantly from the tank or silo height, it is recommended to enter the tank or silo height. Example: Continuous level monitoring in the upper third of a tank or silo.

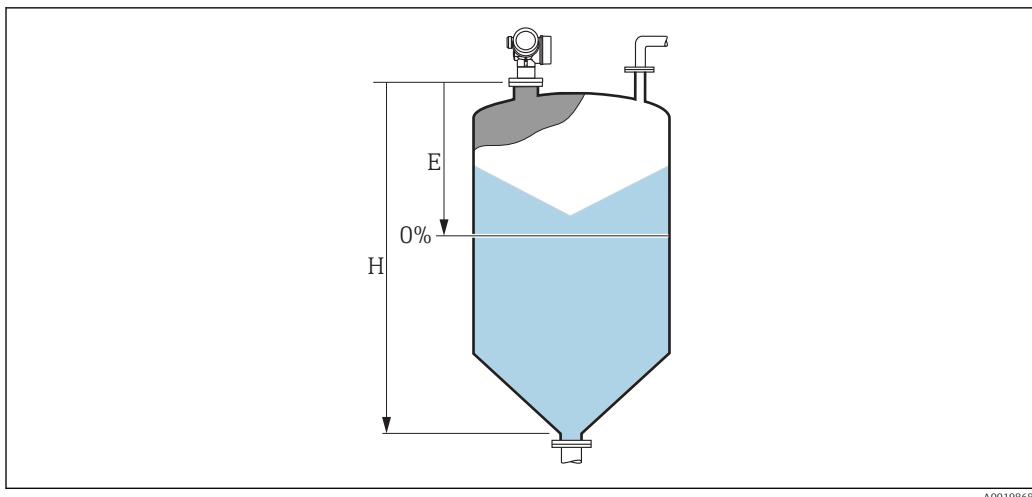


A0019867

11 "Tank/silo height" parameter for measurements in liquids

E Empty calibr. (→ [53](#))

H Tank/silo height (→ [55](#))



12 "Tank/silo height" parameter for measurements in bulk solids

E Empty calibr. (→ 53)

H Tank/silo height (→ 55)

For tanks with conical outlet, **Tank/silo height** should not be changed as in this type of applications **Empty calibr.** (→ 53) is usually **not** much less-than the tank or silo height.

Read access	Operator
Write access	Maintenance

## Level unit



### Navigation

Expert → Sensor → Level → Level unit (0576)

### Description

Select level unit.

### Selection

SI units	US units
▪ %	▪ ft
▪ m	▪ in
▪ mm	

### Factory setting

%

### Additional information

The level unit may differ from the distance unit defined in the **Distance unit** parameter (→ 43):

- The unit defined in the **Distance unit** parameter is used for the basic calibration (**Empty calibr.** (→ 53) and **Full calibr.** (→ 54)).
- The unit defined in the **Level unit** parameter is used to display the (unlinearized) level.

Read access	Operator
Write access	Maintenance

**Output mode****Navigation**

Expert → Sensor → Level → Output mode (2317)

**Description**

Select output mode.

**Selection**

- Ullage
- Level linearized

**Factory setting**

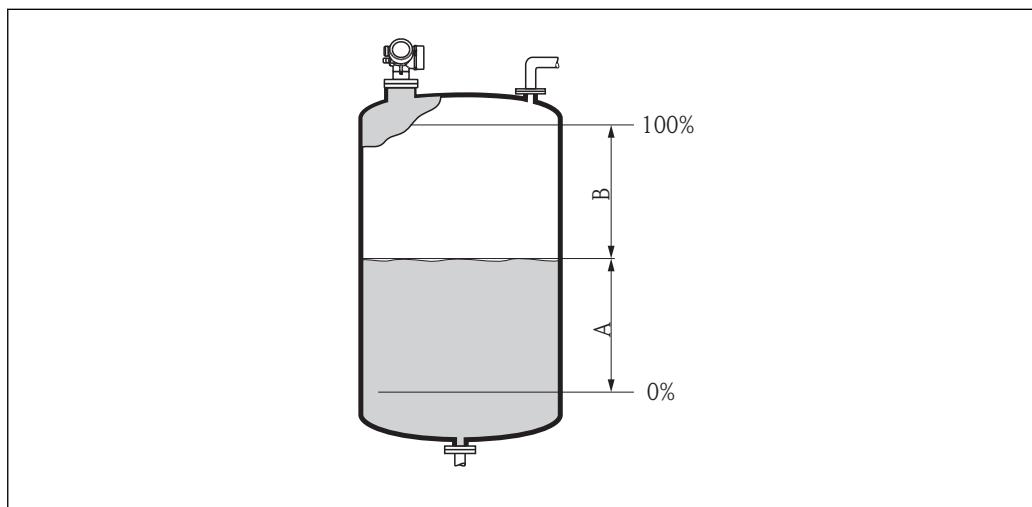
Level linearized

**Additional information****Meaning of the options****■ Ullage**

The remaining space in the tank or silo is indicated.

**■ Level linearized**

The level is indicated (more precisely: the linearized value if a linearization has been activated).



13 Definition of the "Output mode (→ 57)" parameter

A Level linearized

B Ullage

The **Ullage** option is not available for **Lineariz. type (→ 66) = Table**.

Read access	Operator
Write access	Maintenance

**Distance offset****Navigation**

Expert → Sensor → Level → Distance offset (2309)

**Description**

Specify distance offset.

**User entry**

-200 to 200 m

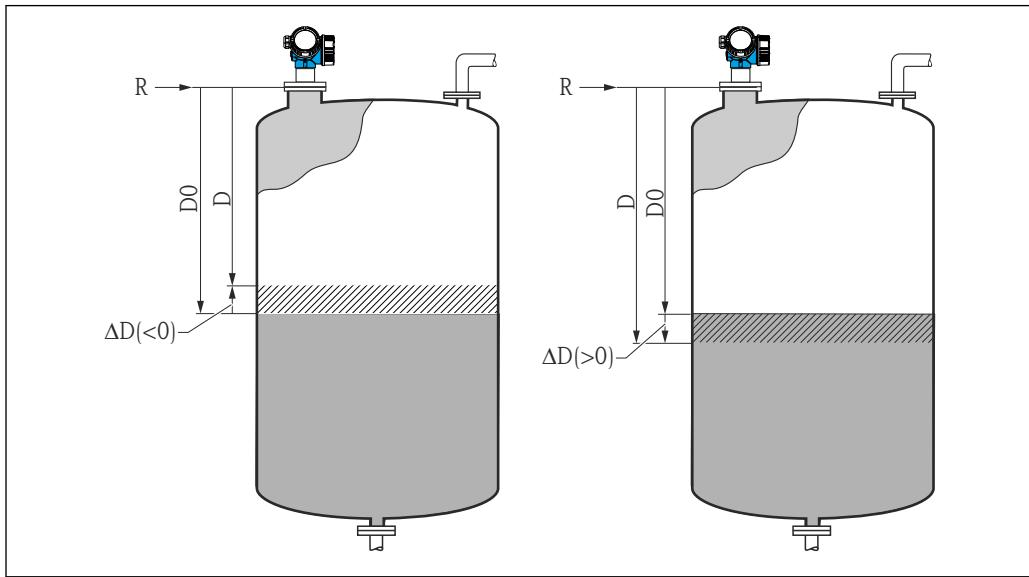
**Factory setting**

0 m

**Additional information**

The value specified in this parameter is added to the measured distance between the reference point of the measurement and the level echo.

- Positive values increase the distance and thus decrease the level.
- Negative values decrease the distance and thus increase the level.



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14 Effect of "Distance offset" (→ 57)"

$\Delta D$  Distance offset

$D_0$  Measured distance

$D$  Corrected distance (is used to calculate the level)

$R$  Reference point



- The value entered in this parameter changes the distance input into the level block and thus influences the measured level.
- The distance without offset is displayed in the following parameters:
  - Setup → Distance (1124)
  - Expert → Sensor → Distance → Distance (1124)
  - Expert → Sensor → Mapping → Distance (1124)
- The distance with offset is displayed in the following parameters:
  - Expert → Sensor → Level → Distance (2231)

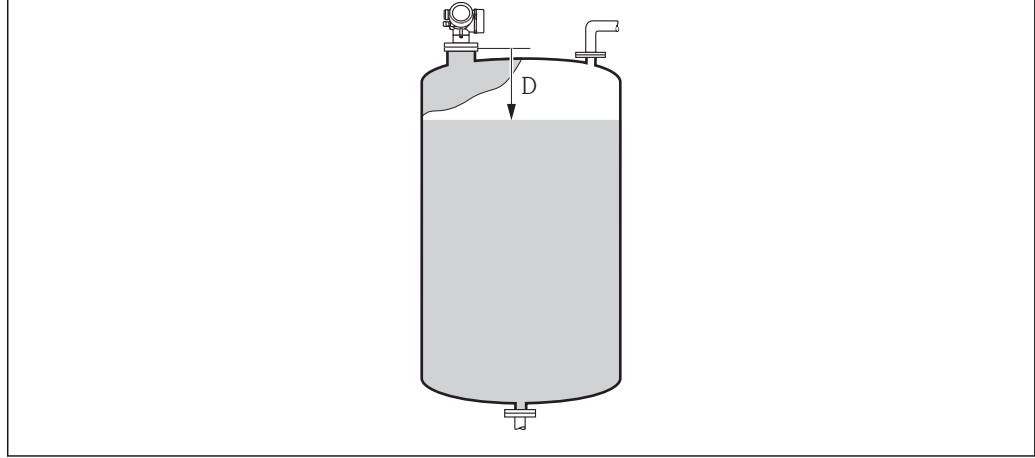
Read access	Operator
Write access	Maintenance

**Distance****Navigation**

Expert → Sensor → Level → Distance (2231)

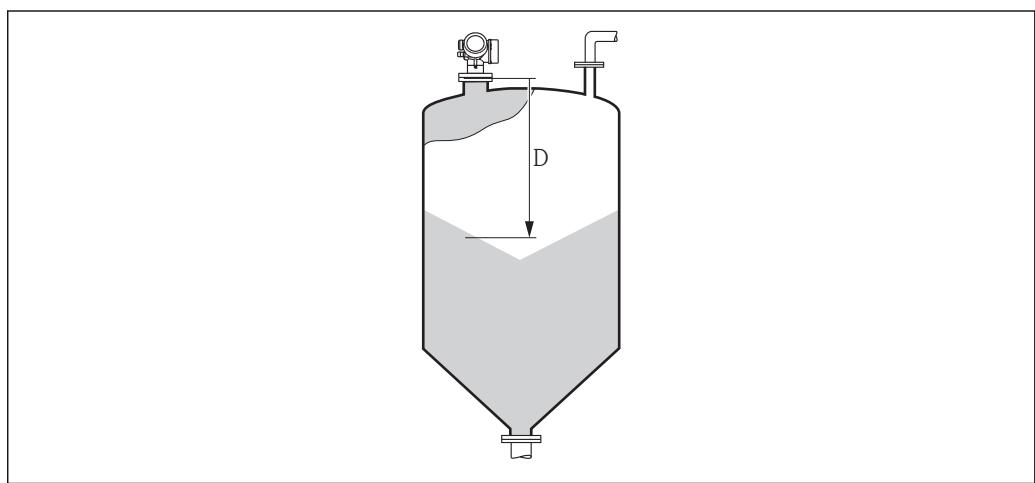
**Description**

Displays the measured distance  $D$  from the reference point (lower edge of the flange or threaded connection) to the level. The **Distance offset** parameter (→ 57) is included in the displayed value.

**Additional information**

A0019483

图 15 Distance for level measurements



A0019485

图 16 Distance for bulk solid measurements

**i** The unit is defined by the **Distance unit** parameter (→ 图 43).

Read access	Operator
Write access	-

**Level limit mode****Navigation**

图 16 Expert → Sensor → Level → Level limit mode (2314)

**Description**

Select the type of level limitation.

**Selection**

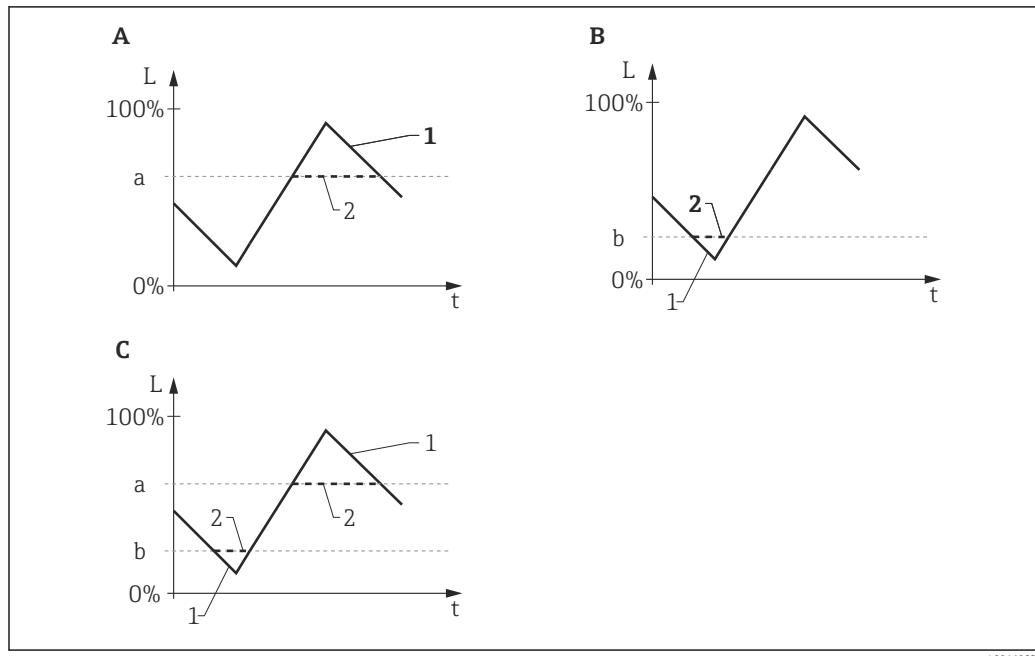
- Off
- Low limit
- High limit
- Low + High Limit

**Factory setting**

Low limit

**Additional information**

The parameter determines to which direction the level is limited. The exact limits are defined in the **High limit** (→ [60](#)) und **Low limit** (→ [61](#)) parameters.



[17](#) Effect of the "Level limit mode", "High limit" and "Low limit" parameters

- A "Level limit mode" = "High limit"
- B "Level limit mode" = "Low limit"
- C "Level limit mode" = "Low + High Limit"
- a "High limit"
- b "Low limit"
- 1 Level before limitation
- 2 Level after limitation

Read access	Operator
Write access	Maintenance

**High limit****Navigation**

[17](#) [Expert](#) → Sensor → Level → High limit (2312)

**Prerequisite**

**Level limit mode** (→ [59](#)) = **High limit** oder **Low + High Limit**

**Description**

Specify upper limit.

**User entry**

Signed floating-point number

**Factory setting**

0 %

**Additional information**

Levels exceeding the value specified in this parameter will be ignored. Instead, the device uses the maximum level specified in this parameter (for measured value transformation and output).

Read access	Operator
Write access	Maintenance

---

**Low limit****Navigation**

Expert → Sensor → Level → Low limit (2313)

**Prerequisite****Level limit mode** (→ 59) = **Low limit** oder **Low + High Limit****Description**

Specify lower level limit.

**User entry**

-200 000.0 to 200 000.0 %

**Factory setting**

0.0 %

**Additional information**

Levels falling below the value specified in this parameter will be ignored. Instead, the device uses the minimum level specified in this parameter (for measured value transformation and output).

Read access	Operator
Write access	Maintenance

---

**Level correction****Navigation**

Expert → Sensor → Level → Level correction (2325)

**Description**

Specify level correction (if required).

**User entry**

-200 000.0 to 200 000.0 %

**Factory setting**

0.0 %

**Additional information**

The value specified in this parameter is added to the measured level (before linearization).

Read access	Operator
Write access	Maintenance

---

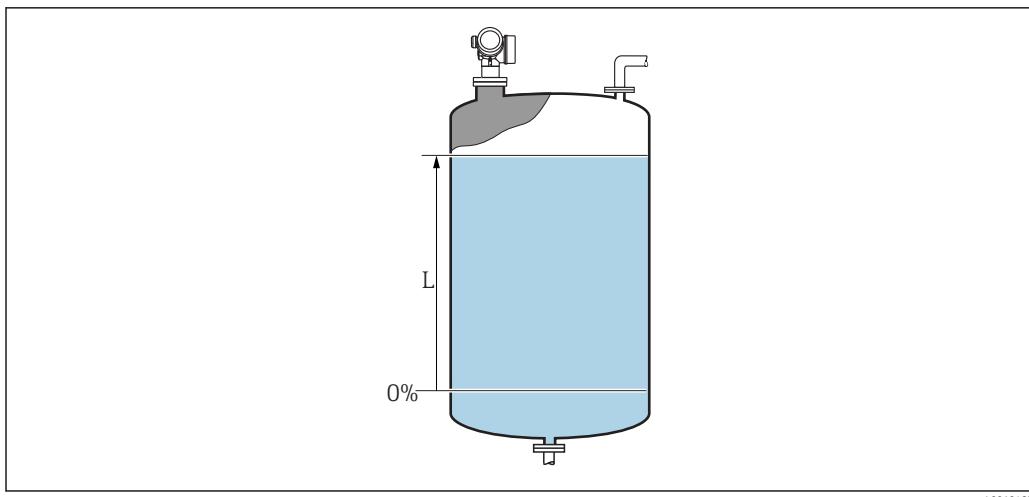
**Level****Navigation**

Expert → Sensor → Level → Level (2319)

**Description**

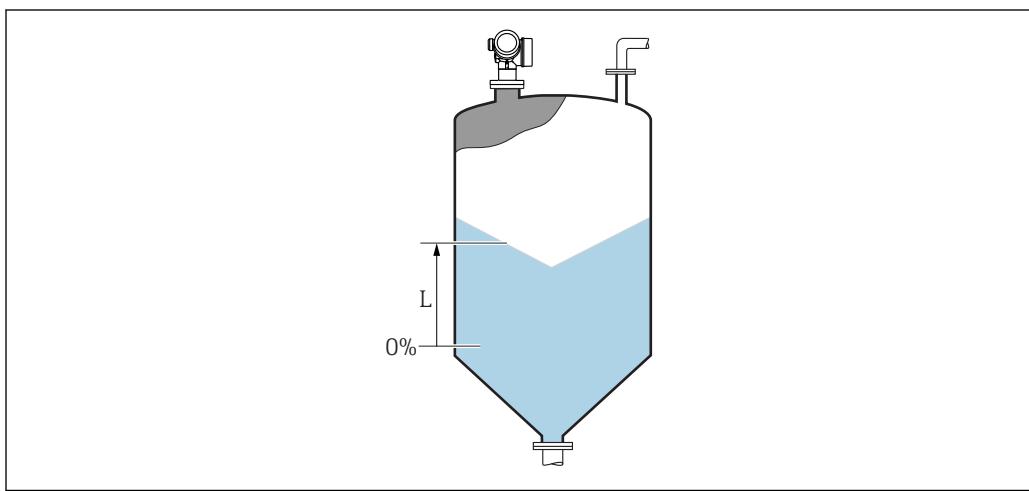
Displays measured level L (before linearization).

## Additional information



A0019482

图 18 Level in case of liquid measurements



A0019484

图 19 Level in case of bulk solid measurements

**i** The unit is defined in the **Level unit** parameter (→ 图 56).

Read access	Operator
Write access	-

---

Level linearized

---

## Navigation

图 18 Expert → Sensor → Level → Level linearized (2318)

## Description

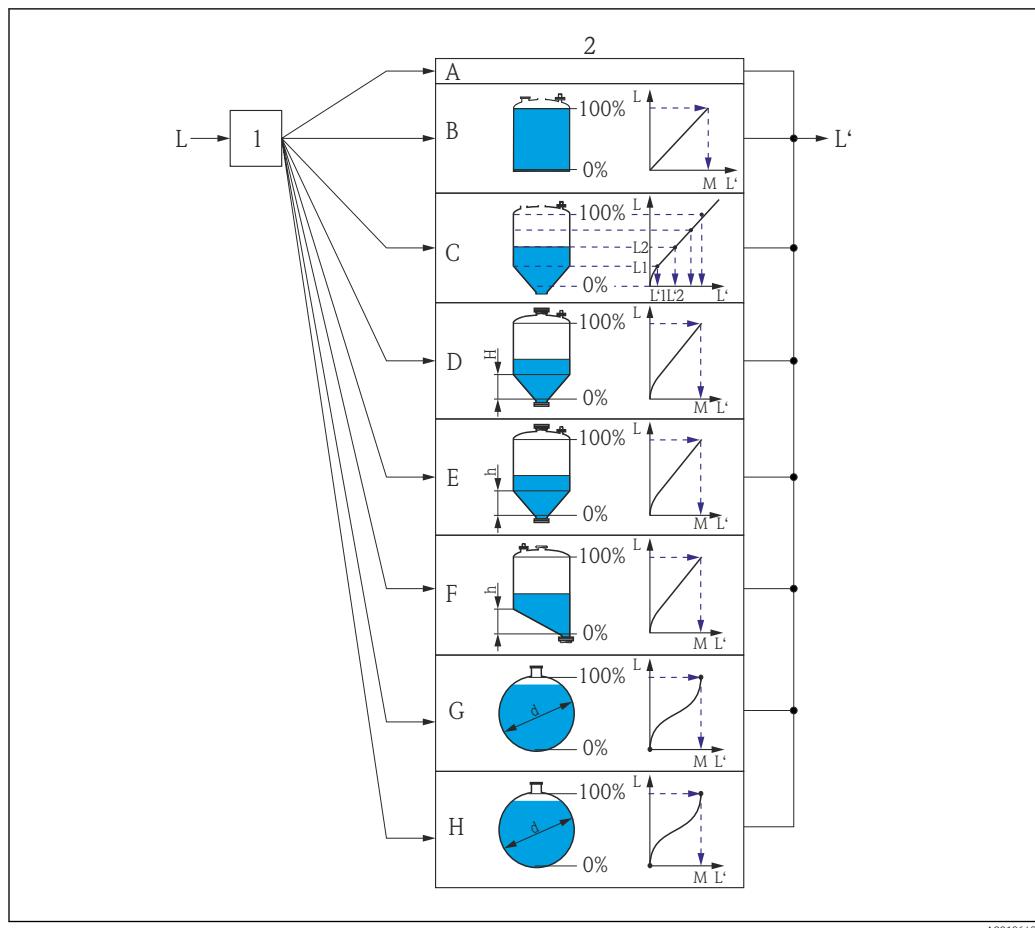
Displays linearized level.

## Additional information

**i** The unit is defined by the **Unit lineariz.** parameter → 图 68.

<b>Read access</b>	Operator
<b>Write access</b>	-

### 3.3.5 "Linearization" submenu



A0019648

**20 Linearization:** Transformation of the level into a volume or weight; the transformation is dependent on the shape of the vessel.

- 1 Selection of linearization type and unit
- 2 Configuration of the linearization
- A Lineariz. type ( $\rightarrow$  66) = None
- B Lineariz. type ( $\rightarrow$  66) = Linear
- C Lineariz. type ( $\rightarrow$  66) = Table
- D Lineariz. type ( $\rightarrow$  66) = Pyramid bottom
- E Lineariz. type ( $\rightarrow$  66) = Conical bottom
- F Lineariz. type ( $\rightarrow$  66) = Angled bottom
- G Lineariz. type ( $\rightarrow$  66) = Horizontal cyl.
- H Lineariz. type ( $\rightarrow$  66) = Sphere
- L Level before linearization (measured in distance units)
- L' Level linearized ( $\rightarrow$  62) (corresponds to volume or weight)
- M Maximum value ( $\rightarrow$  69)
- d Diameter ( $\rightarrow$  69)
- h Intermed. height ( $\rightarrow$  70)

**Structure of the submenu***Navigation*

Expert → Sensor → Linearization

<b>► Linearization</b>	
Lineariz. type	→  66
Unit lineariz.	→  68
Free text	→  68
Level linearized	→  69
Maximum value	→  69
Diameter	→  69
Intermed. height	→  70
Table mode	→  70
Table number	→  71
Level	→  72
Level	→  72
Customer value	→  72
Activate table	→  73

## Description of parameters

Navigation

Expert → Sensor → Linearization

### Lineariz. type



Navigation

Expert → Sensor → Linearization → Lineariz. type (2339)

Description

Select linearization type.

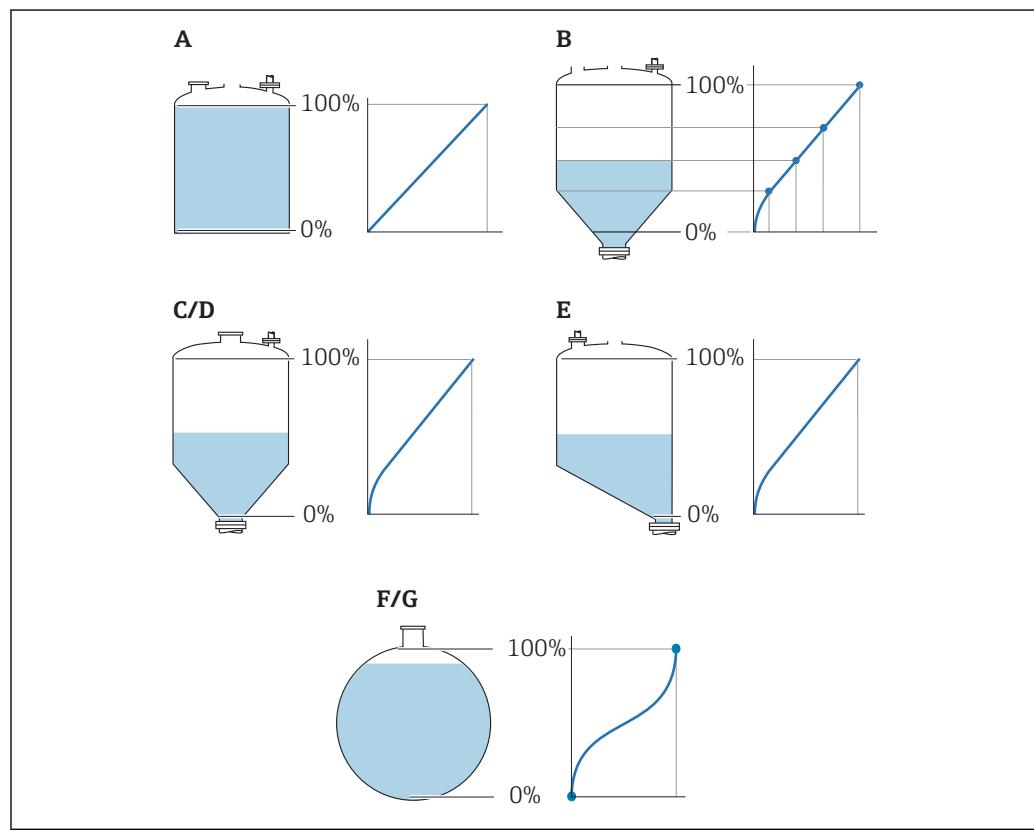
Selection

- None
- Linear
- Table
- Pyramid bottom
- Conical bottom
- Angled bottom
- Horizontal cyl.
- Sphere

Factory setting

None

Additional information



21 Linearization types

- A None
- B Table
- C Pyramid bottom
- D Conical bottom
- E Angled bottom
- F Sphere
- G Horizontal cyl.

### Meaning of the options

- **None**

The level is transmitted in the level unit without linearization.

- **Linear**

The output value (volume/weight) is directly proportional to the level L. This is valid, for example, for vertical cylinders. The following additional parameters have to be specified:

- **Unit lineariz. (→ 68)**
- **Maximum value (→ 69):** Maximum volume or weight

- **Table**

The relationship between the measured level L and the output value (volume/weight) is given by a linearization table consisting of up to 32 pairs of values "level - volume" or "level - weight", respectively. The following additional parameters have to be specified:

- **Unit lineariz. (→ 68)**
- **Table mode (→ 70)**
- For each table point: **Level (→ 72)**
- For each table point: **Customer value (→ 72)**
- **Activate table (→ 73)**

- **Pyramid bottom**

The output value corresponds to the volume or weight in a silo with pyramid bottom.

The following additional parameters have to be specified:

- **Unit lineariz. (→ 68)**
- **Maximum value (→ 69):** Maximum volume or weight
- **Intermed. height (→ 70):** The height of the pyramid

- **Conical bottom**

The output value corresponds to the volume or weight in a tank with conical bottom. The following additional parameters have to be specified:

- **Unit lineariz. (→ 68)**
- **Maximum value (→ 69):** Maximum volume or weight
- **Intermed. height (→ 70):** The height of the conical part of the tank

- **Angled bottom**

The output value corresponds to the volume or weight in a silo with an angled bottom.

The following additional parameters have to be specified:

- **Unit lineariz. (→ 68)**
- **Maximum value (→ 69):** Maximum volume or weight
- **Intermed. height (→ 70):** Height of the angled bottom

- **Horizontal cyl.**

The output value corresponds to the volume or weight in a horizontal cylinder. The following additional parameters have to be specified:

- **Unit lineariz. (→ 68)**
- **Maximum value (→ 69):** Maximum volume or weight
- **Diameter (→ 69)**

- **Sphere**

The output value corresponds to the volume or weight in a spherical tank. The following additional parameters have to be specified:

- **Unit lineariz. (→ 68)**
- **Maximum value (→ 69):** Maximum volume or weight
- **Diameter (→ 69)**

Read access	Operator
Write access	Maintenance

**Unit lineariz.****Navigation**

Expert → Sensor → Linearization → Unit lineariz. (2340)

**Prerequisite**

**Lineariz. type** (→ 66) ≠ None

**Description**

Select unit of the linearized value.

**Selection***SI units*

- STon
- t
- kg
- cm<sup>3</sup>
- dm<sup>3</sup>
- m<sup>3</sup>
- hl
- l
- %
- mm
- m

*US units*

- lb
- UsGal
- ft<sup>3</sup>
- ft
- in

*Imperial units*

impGal

*Custom-specific units*

Free text

**Factory setting**

%

**Additional information**

The selected unit is only used to be indicated on the display. The measured value is **not** transformed according to the selected unit.

It is also possible to configure a distance-to-distance linearization, i.e. a transformation from the level unit to a different distance unit. To do so, select the **Linear** linearization mode. In order to define the new level unit, select the **Free text** option in the **Unit lineariz.** parameter and enter the required unit into the **Free text** parameter (→ 68).

Read access	Operator
Write access	Maintenance

**Free text****Navigation**

Expert → Sensor → Linearization → Free text (2341)

**Prerequisite**

**Unit lineariz.** (→ 68) = **Free text**

**Description**

Enter unit symbol.

**User entry**

Up to 32 alphanumerical characters (letters, numbers, special characters)

**Factory setting**

Free text

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Level linearized**

---

**Navigation**  Expert → Sensor → Linearization → Level linearized (2318)

**Description** Displays linearized level.

**Additional information**  The unit is defined by the **Unit lineariz.** parameter →  68.

Read access	Operator
Write access	-

---

**Maximum value**

---

**Navigation**  Expert → Sensor → Linearization → Maximum value (2315)

**Prerequisite** **Lineariz. type** (→  66) has one of the following values:

- Linear
- Pyramid bottom
- Conical bottom
- Angled bottom
- Horizontal cyl.
- Sphere

**Description** Linearized value corresponding to a level of 100%.

**User entry** -50 000.0 to 50 000.0 %

**Factory setting** 100.0 %

Read access	Operator
Write access	Maintenance

---

**Diameter**

---

**Navigation**  Expert → Sensor → Linearization → Diameter (2342)

**Prerequisite** **Lineariz. type** (→  66) has one of the following values:

- Horizontal cyl.
- Sphere

**Description** Diameter of the cylindrical or spherical tank.

**User entry** 0 to 9 999.999 m

**Factory setting** 2 m

**Additional information** The unit is defined in the **Distance unit** parameter (→  43).

Read access	Operator
Write access	Maintenance

**Intermed. height****Navigation**

Expert → Sensor → Linearization → Intermed. height (2310)

**Prerequisite**

**Lineariz. type** (→ 66) has one of the following values:

- Pyramid bottom
- Conical bottom
- Angled bottom

**Description**

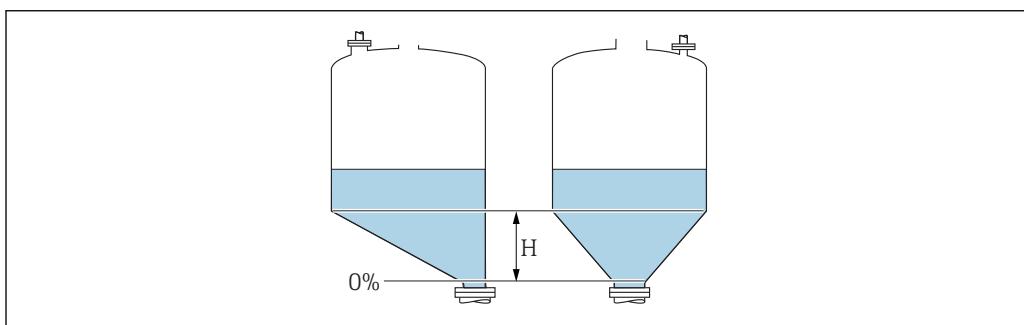
Height of the pyramid, conical or angled bottom.

**User entry**

0 to 200 m

**Factory setting**

0 m

**Additional information**

A0013264

*H      Intermediate height*

The unit is defined in the **Distance unit** parameter (→ 43).

Read access	Operator
Write access	Maintenance

**Table mode****Navigation**

Expert → Sensor → Linearization → Table mode (2303)

**Prerequisite**

**Lineariz. type** (→ 66) = Table

**Description**

Select editing mode of the linearization table.

**Selection**

- Manual
- Semiautomatic
- Clear table
- Sort table

<b>Factory setting</b>	Manual				
<b>Additional information</b>	<p><b>Meaning of the options</b></p> <ul style="list-style-type: none"> <li>▪ <b>Manual</b> The level and the associated linearized value are entered manually for each linearization point.</li> <li>▪ <b>Semiautomatic</b> The level is measured by the device for each linearization point. The associated linearized value is entered manually.</li> <li>▪ <b>Clear table</b> Deletes the existing linearization table.</li> <li>▪ <b>Sort table</b> Rearranges the linerization points into an ascending order.</li> </ul> <p><b>Conditions the linearization table must meet:</b></p> <ul style="list-style-type: none"> <li>▪ The table may consist of up to 32 pairs of values "Level - Linearized Value".</li> <li>▪ The table must be monotonic (monotonically increasing or decreasing).</li> <li>▪ The first linearization point must refer to the minimum level.</li> <li>▪ The last linearization point must refer to the maximum level.</li> </ul> <p><b>i</b> Before entering a linearization table, the values for <b>Empty calibr.</b> (→ 53) and <b>Full calibr.</b> (→ 54) must be set correctly. If values of the table need to be changed after the full or empty calibration have been changed, a correct evaluation is only ensured if the existing table is deleted and the complete table is entered again. To do so delete the existing table (<b>Table mode</b> (→ 70) = <b>Clear table</b>). Then enter a new table.</p> <p><b>How to enter the table</b></p> <ul style="list-style-type: none"> <li>▪ <b>Via FieldCare</b> The table points can be entered via the <b>Table number</b> (→ 71), <b>Level</b> (→ 72) and <b>Customer value</b> (→ 72) parameters. As an alternative, the graphic table editor may be used: Device Operation → Device Functions → Additional Functions → Linearization (Online/Offline)</li> <li>▪ <b>Via local display</b> Select the <b>Edit table</b> submenu to call up the graphic table editor. The table is displayed and can be edited line by line.</li> </ul> <p><b>i</b> The factory setting for the level unit is "%". If you want to enter the linearization table in physical units, you must select the appropriate unit in the <b>Level unit</b> parameter (→ 56) beforehand.</p> <p><b>i</b> If a decreasing table is entered, the values for 20 mA and 4 mA of the current output are interchanged. That means: 20 mA refers to the lowest level, whereas 4 mA refers to the highest level. If required, the current output can be inverted in the <b>Measuring mode</b> parameter (→ 115).</p>				
<hr/>					
<table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="padding: 2px;">Read access</td><td style="padding: 2px;">Operator</td></tr> <tr> <td style="padding: 2px;">Write access</td><td style="padding: 2px;">Maintenance</td></tr> </table>		Read access	Operator	Write access	Maintenance
Read access	Operator				
Write access	Maintenance				

---

**Table number****Navigation**

Expert → Sensor → Linearization → Table number (2370)

**Prerequisite**

**Lineariz. type** (→ 66) = **Table**

**Description** Select table point you are going to enter or change.

**User entry** 1 to 32

**Factory setting** 1

**Additional information**

Read access	Operator
Write access	Maintenance

## Level (Manual)



**Navigation** Expert → Sensor → Linearization → Level (2383)

**Prerequisite**

- **Lineariz. type** (→ 66) = Table
- **Table mode** (→ 70) = Manual

**Description** Enter level value of the table point (value before linearization).

**User entry** Signed floating-point number

**Factory setting** 0 %

**Additional information**

Read access	Operator
Write access	Maintenance

## Level (Semiautomatic)

**Navigation** Expert → Sensor → Linearization → Level (2389)

**Prerequisite**

- **Lineariz. type** (→ 66) = Table
- **Table mode** (→ 70) = Semiautomatic

**Description** Displays measured level (value before linearization). This value is transmitted to the table.

**Additional information**

Read access	Operator
Write access	Maintenance

## Customer value



**Navigation** Expert → Sensor → Linearization → Customer value (2384)

**Prerequisite** **Lineariz. type** (→ 66) = Table

**Description** Enter linearized value for the table point.

**User entry** Signed floating-point number

**Factory setting** 0 %

**Additional information**

Read access	Operator
Write access	Maintenance

## Activate table



**Navigation** Expert → Sensor → Linearization → Activate table (2304)

**Prerequisite** **Lineariz. type (→ 66) = Table**

**Description** Activate (enable) or deactivate (disable) the linearization table.

**Selection**

- Disable
- Enable

**Factory setting** Disable

**Additional information** **Meaning of the options**

**▪ Disable**

The measured level is not linearized.

If **Lineariz. type (→ 66) = Table** at the same time, the device issues error message F435.

**▪ Enable**

The measured level is linearized according to the table.

When editing the table, the **Activate table** parameter is automatically reset to **Disable** and must be reset to **Enable** after the table has been entered.

Read access	Operator
Write access	Maintenance

### 3.3.6 "Information" submenu

The **Information** submenu comprises all display parameters which give information about the current state of the measurement.

#### Structure of the submenu

*Navigation*

Expert → Sensor → Information

► Information	
Signal quality	→ 75
Abs. echo ampl.	→ 75
Relat.echo ampl.	→ 75
Tank bottom ampl	→ 75
Found echoes	→ 76
Used calculation	→ 76
Actual IF gain	→ 76
Sensor temp.	→ 76

### Description of parameters

*Navigation*

 Expert → Sensor → Information

---

## Signal quality

---

**Navigation**

 Expert → Sensor → Information → Signal quality (12477)

**Description**

Shows the quality of the evaluated level signal.

---

## Abs. echo ampl.

---

**Navigation**

 Expert → Sensor → Information → Abs. echo ampl. (12457)

**Description**

Absolute amplitude of the evaluated level signal.

**Additional information**

Read access	Operator
Write access	-

---

## Relat.echo ampl.

---

**Navigation**

 Expert → Sensor → Information → Relat.echo ampl. (12468)

**Description**

Relative amplitude of the evaluated level signal.

**Additional information**

 In the envelope curve display of FieldCare, the absolute echo amplitude is indicated instead of the relative amplitude.

Read access	Operator
Write access	-

---

## Tank bottom ampl

---

**Navigation**

 Expert → Sensor → Information → Tank bottom ampl (12467)

**Description**

Displays the absolute amplitude of the end-of-probe signal in the subtracted curve.

**Additional information**

The tank bottom echo is only evaluated for media with a small dielectric constant (DC).

Read access	Operator
Write access	-

---

**Found echoes**

---

**Navigation**   Expert → Sensor → Information → Found echoes (12492)

**Description** Indicates which echoes have been found.

**Additional information**

Read access	Operator
Write access	-

---

**Used calculation**

---

**Navigation**   Expert → Sensor → Information → Used calculation (12488)

**Description** Indicates which signal is used for the level calculation.

**Additional information**

Read access	Operator
Write access	-

---

**Actual IF gain**

---

**Navigation**   Expert → Sensor → Information → Actual IF gain (12540)

**Description** Indicates the current gain of the intermediate frequency.

**Additional information**

Read access	Operator
Write access	-

---

**Sensor temp.**

---

**Navigation**   Expert → Sensor → Information → Sensor temp. (12499)

**Description** Indicates the current sensor temperature.

**Additional information**

Read access	Operator
Write access	-

### 3.3.7 "Distance" submenu

The **Distance** submenu contains all parameters which control the filtering of the raw distance D1. The resulting distance D0 is used for the subsequent calculation of the level.

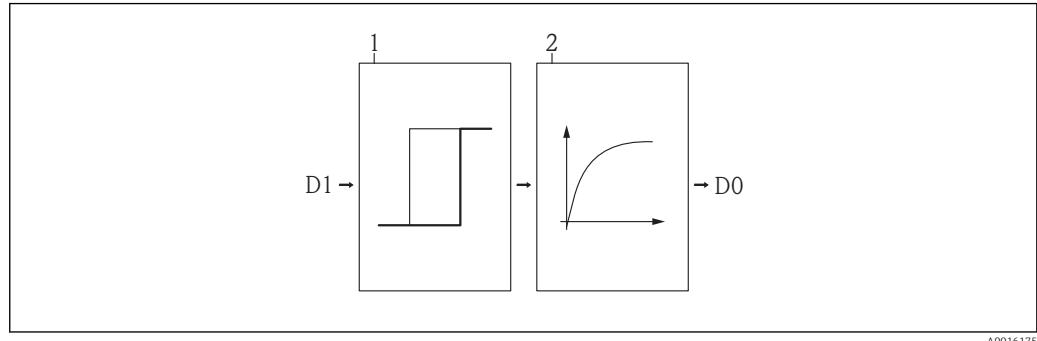


图 22 The configurable distance filters

- 1 Dead time
- 2 Integration time (low pass filter)

#### Low pass filter

The low pass filter dampens the distance signal with a user defined integration time  $\tau$  (**Integration time** parameter). After a sudden change of the level, it takes about  $5 \times \tau$ , until the new measured value is obtained.

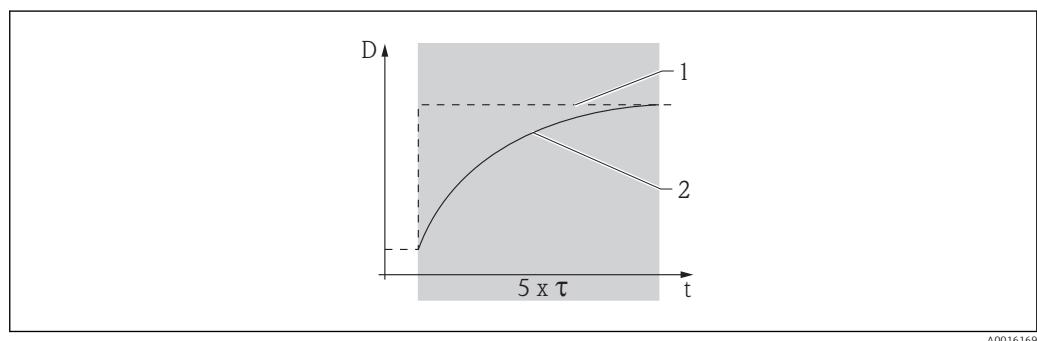
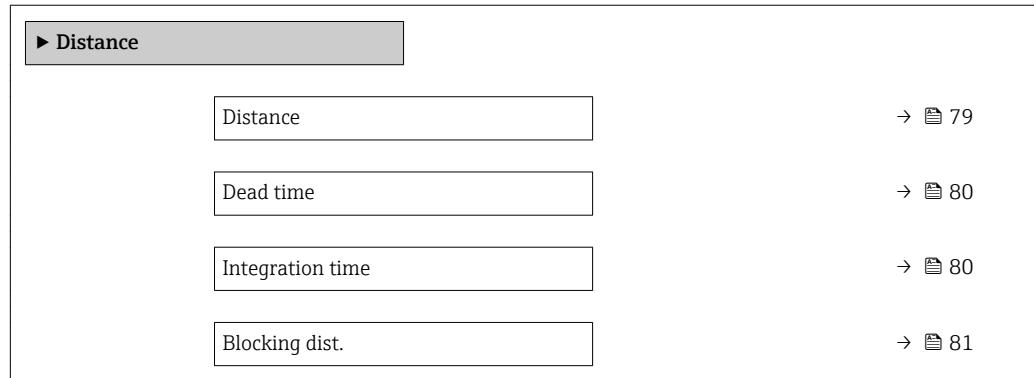


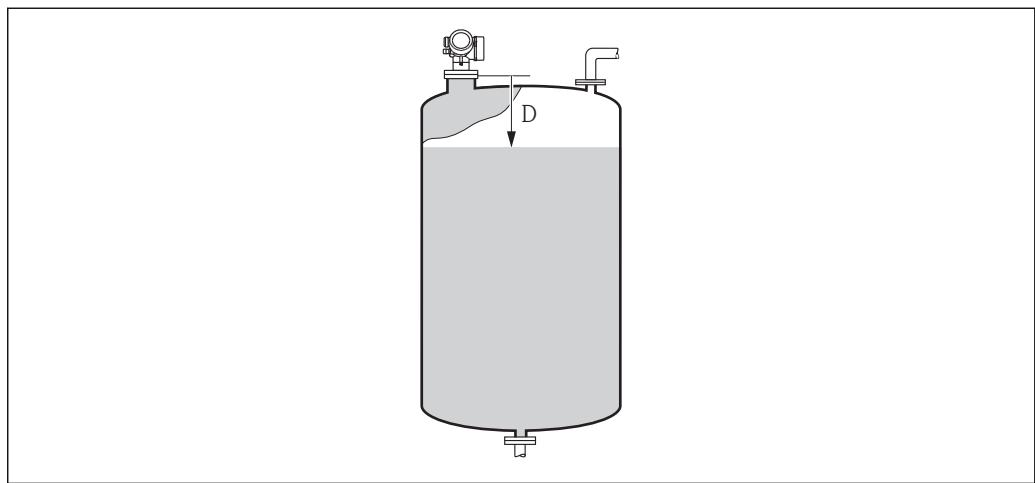
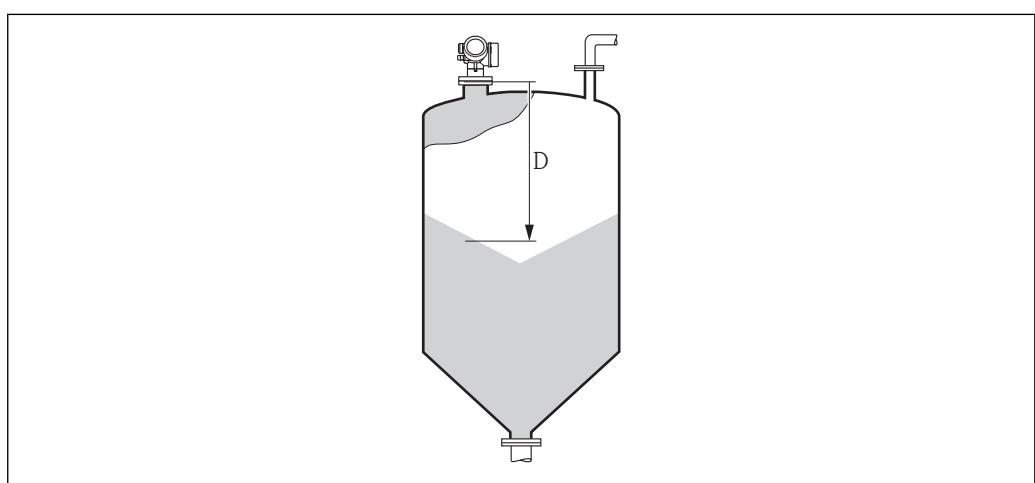
图 23 Low pass filter

- 1 Signal before the low pass filter
- 2 Signal after the low pass filter
- $\tau$  Integration time

**Structure of the submenu***Navigation* Expert → Sensor → Distance

**Description of parameters***Navigation* Expert → Sensor → Distance**Distance****Navigation** Expert → Sensor → Distance → Distance (12401)**Description**

Distance between lower edge of flange or thread and medium surface.

**Additional information** 24 Distance for liquid measurements 25 Distance for bulk solid measurements

Read access	Operator
Write access	-

**Dead time****Navigation**

Expert → Sensor → Distance → Dead time (12521)

**Description**

Dead time in seconds

**Additional information**

Read access	Maintenance
Write access	Service

**Integration time****Navigation**

Expert → Sensor → Distance → Integration time (12489)

**Description**

Integration time for the low pass filter

**User entry**

0.0 to 200 000.0 s

**Factory setting****Dependent on the following parameters:**

- **Medium type**
- **Max. filling speed liquid or Max. filling speed solid**
- **Max. draining speed liquid or Max. draining speed solid**

**Additional information***Factory settings for "Medium type" = "Liquid"*

Max. fill liquid	Max drain liquid					
	Slow < 1cm /min	Medium <10cm/min	Standard <1m/min	Fast < 2m /min	Very fast > 2m/m	No filter / test
Slow < 1cm /min	30 s	15 s	5 s	1 s	0 s	0 s
Medium <10cm/min	15 s	15 s	5 s	1 s	0 s	0 s
Standard <1m/min	5 s	5 s	5 s	1 s	0 s	0 s
Fast < 2m /min	1 s	1 s	1 s	1 s	0 s	0 s
Very fast > 2m/m	0 s	0 s	0 s	0 s	0 s	0 s
No filter / test	0 s	0 s	0 s	0 s	0 s	0 s

*Factory settings for "Medium type" = "Solid"*

Max. fill. solid	Max.drain solid						
	Very slow<0.5m/ h	Slow < 1m /h	Standard < 2m /h	Medium < 4m /h	Fast < 8m /h	Very fast >8m/h	No filter / test
Very slow<0.5m/ h	250 s	200 s	200 s	100 s	50 s	1 s	0 s
Slow < 1m /h	200 s	200 s	200 s	100 s	50 s	1 s	0 s
Standard < 2m /h	200 s	200 s	100 s	100 s	50 s	1 s	0 s
Medium < 4m /h	100 s	100 s	100 s	50 s	50 s	1 s	0 s
Fast < 8m /h	50 s	50 s	50 s	50 s	20 s	1 s	0 s
Very fast >8m/h	1 s	1 s	1 s	1 s	1 s	1 s	0 s
No filter / test	0 s	0 s	0 s	0 s	0 s	0 s	0 s

Read access	Operator
Write access	Maintenance

## Blocking dist.



### Navigation

Diagram Expert → Sensor → Distance → Blocking dist. (12424)

### Description

Dead band in front of the process connection.

### User entry

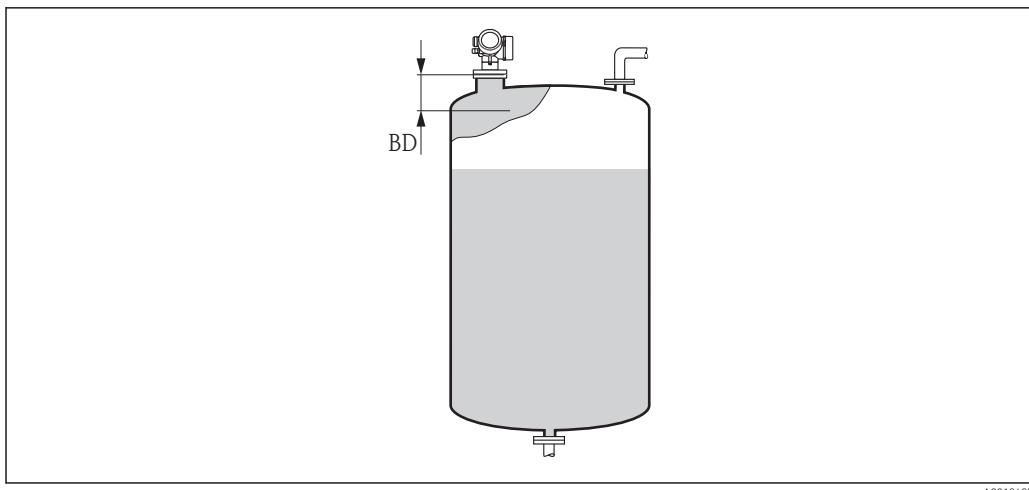
0 to 200 m

### Factory setting

- **Empty calibration - Full calibration** - 200 mm (8 in)
- Minimum value: 150 mm (6 in)

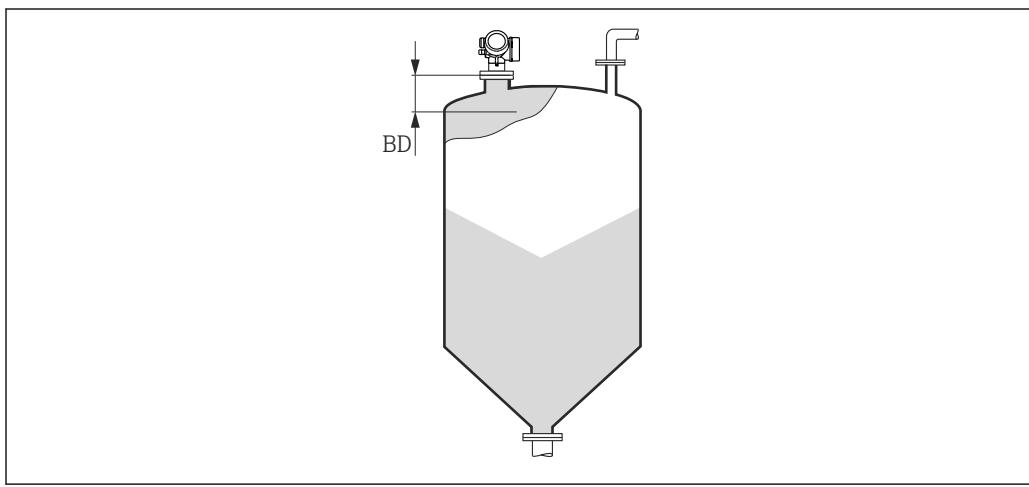
### Additional information

No echos are evaluated within the blocking distance BD. Therefore, BD can be used to suppress interference echos in the vicinity of the antenna.



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■ 26 Blocking distance (BD) for liquid measurements



A0023041

■ 27 Blocking distance (BD) for bulk solid measurements

Read access	Operator
Write access	Maintenance

### 3.3.8 "Sensor diag." submenu

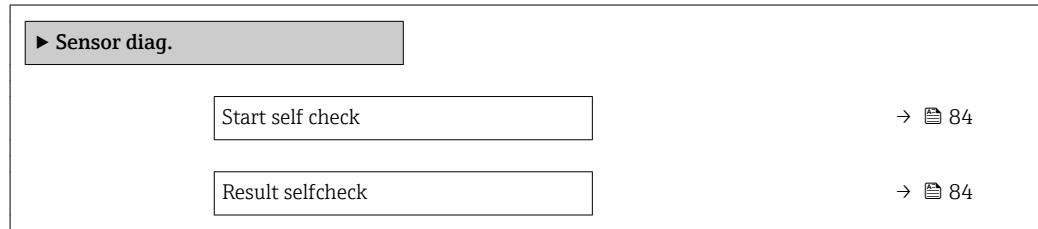
The **Sensor diag.** submenu is used for the proof-test which is required for SIL applications in regular intervals. For details refer to the Functional Safety Manual of the respective device.

For the self check, a test signal is generated in the sensor module and fed onto the analog signal path. The device software checks whether this test signal is within the admissible amplitude and distance ranges. The result of the self check is displayed in the **Result selfcheck** parameter.

#### Structure of the submenu

*Navigation*

Expert → Sensor → Sensor diag.



**Description of parameters***Navigation* Expert → Sensor → Sensor diag.**Start self check****Navigation** Expert → Sensor → Sensor diag. → Start self check (12496)**Description**The **Yes** option starts a self check.**Selection**

- No
- Yes

**Factory setting**

No

**Additional information**

Read access	Operator
Write access	Maintenance

**Result selfcheck****Navigation** Expert → Sensor → Sensor diag. → Result selfcheck (12497)**Description**

Shows the result of the self check.

**Additional information**

Read access	Operator
Write access	-

### 3.3.9 "Safety sett." submenu

The **Safety sett.** submenu contains all parameters which determine the behavior of the device in critical situations such as an echo loss or an undershooting of a user defined safety distance.

#### Behavior in the case of an echo loss

The behavior in case of an echo loss is defined in the **Output echo lost** parameter ( $\rightarrow \text{图 } 90$ ). Depending on the selected option, suitable values must be selected in a number of additional parameters:

Option selected in "Output echo lost ( $\rightarrow \text{图 } 90$ )"	Required additional parameters
Last valid value	Delay echo lost ( $\rightarrow \text{图 } 92$ )
Ramp echo lost	<ul style="list-style-type: none"> <li>▪ Ramp echo lost (<math>\rightarrow \text{图 } 91</math>)</li> <li>▪ Delay echo lost (<math>\rightarrow \text{图 } 92</math>)</li> </ul>
Value echo lost	<ul style="list-style-type: none"> <li>▪ Value echo lost (<math>\rightarrow \text{图 } 90</math>)</li> <li>▪ Delay echo lost (<math>\rightarrow \text{图 } 92</math>)</li> </ul>
Alarm	1)

- 1) The alarm behavior is defined in the submenus "Curr.output" (HART) or "Analog input" (PROFIBUS PA, FOUNDATION Fieldbus).

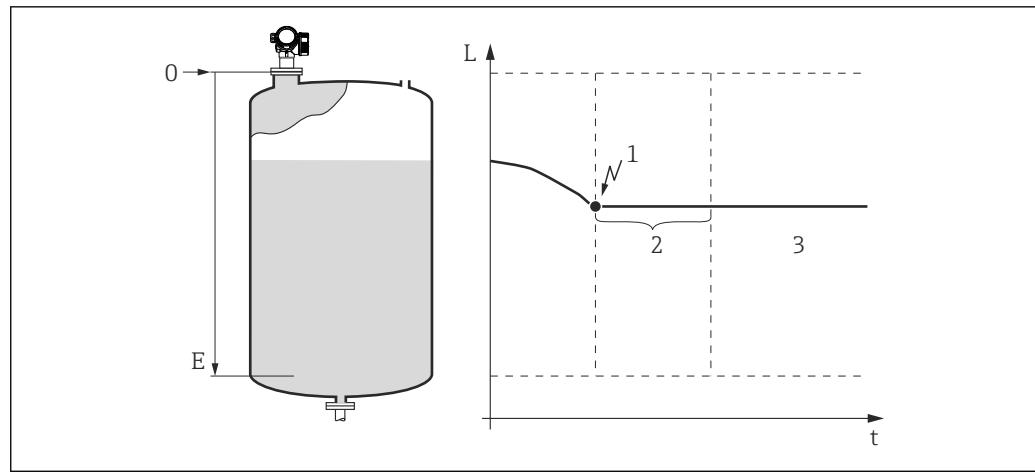
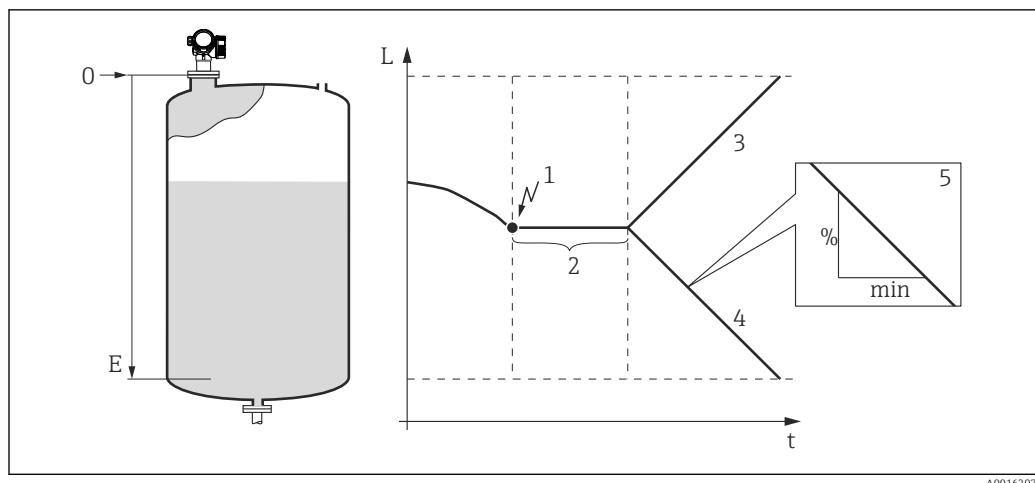


图 28 "Output echo lost ( $\rightarrow \text{图 } 90$ )" = "Last valid value"

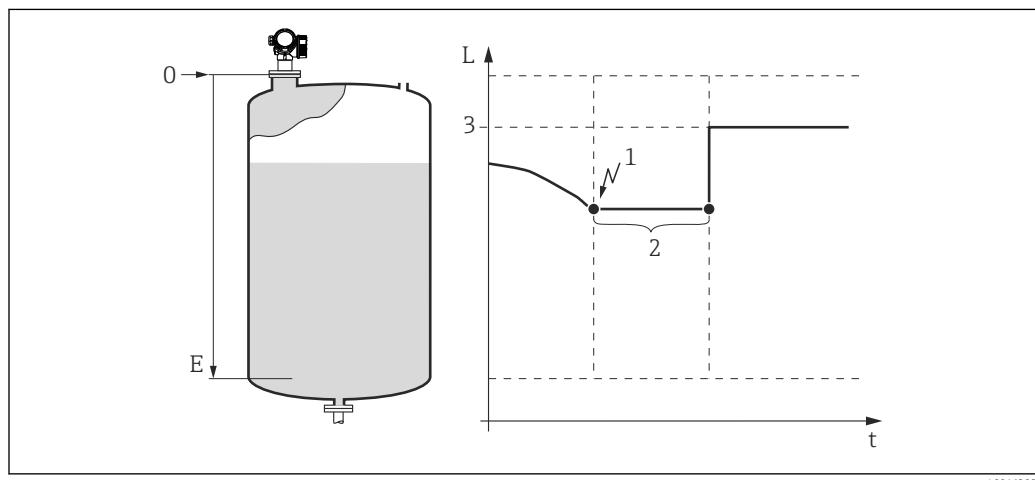
- 1 Echo loss
- 2 Delay echo lost ( $\rightarrow \text{图 } 92$ )
- 3 The last valid measured value is held.



■ 29 "Output echo lost ( $\rightarrow$  ■ 90)" = "Ramp echo lost"

- 1 Echo loss
- 2 Delay echo lost ( $\rightarrow$  ■ 92)
- 3 For a positive ramp: The measured value is increased with a constant rate until it reaches the maximum value (100%).
- 4 For a negative ramp: The measured value is decreased with a constant rate until it reaches the minimum value (0%).
- 5 The ramp is specified as "percentage of the defined measuring span per minute".

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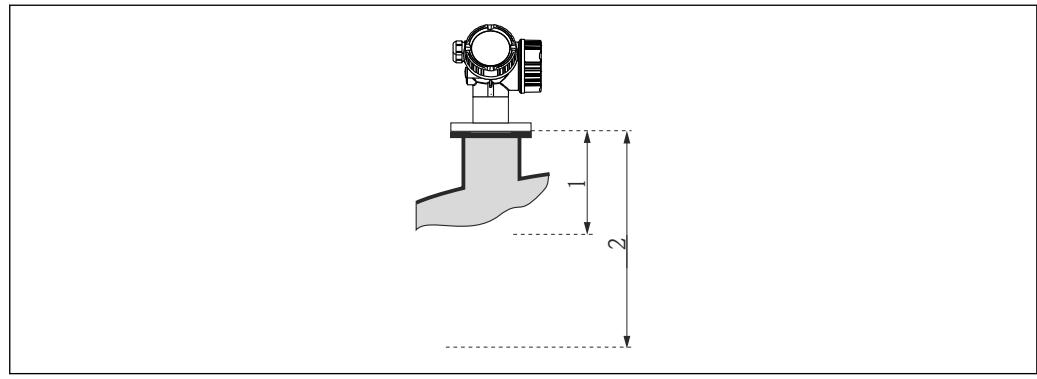
■ 30 "Output echo lost ( $\rightarrow$  ■ 90)" = "Value echo lost"

- 1 Echo loss
- 2 Delay echo lost ( $\rightarrow$  ■ 92)
- 3 Value echo lost ( $\rightarrow$  ■ 90)

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### Safety distance

In order to get a warning message if the level rises into the proximity of the upper blocking distance, a safety distance can be defined in the **Safety distance** parameter (→ 92).

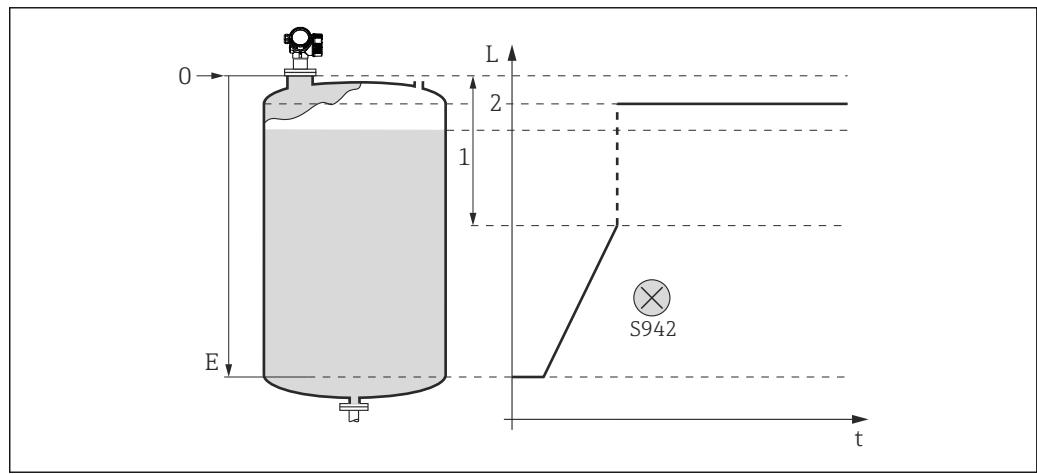


31 Definition of the safety distance

- 1 Blocking dist. (→ 81)
- 2 Safety distance (→ 92)

The behavior of the device in case the level rises into the safety distance is defined in the following parameters:

- In safety dist. (→ 92)
- Acknowl. alarm (→ 93)



32 "In safety dist." = "Alarm". If the safety distance is undershot, the device generates an alarm.

- 1 Safety distance (→ 92)
- 2 Value defined in "Failure mode (→ 112)"

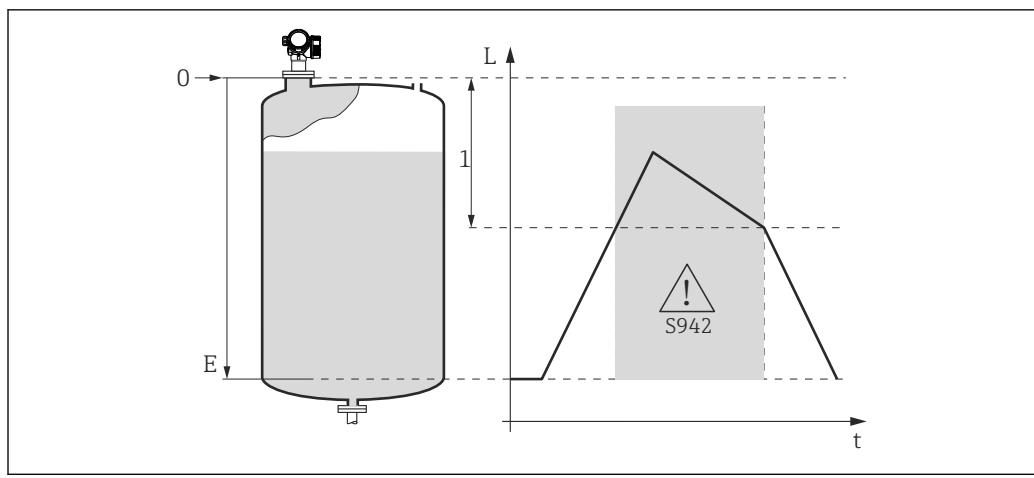


图 33 "In safety dist." = "Warning": If the safety distance is undershot, the device continues measuring but nevertheless generates a warning.

1 Safety distance (→ 图 92)

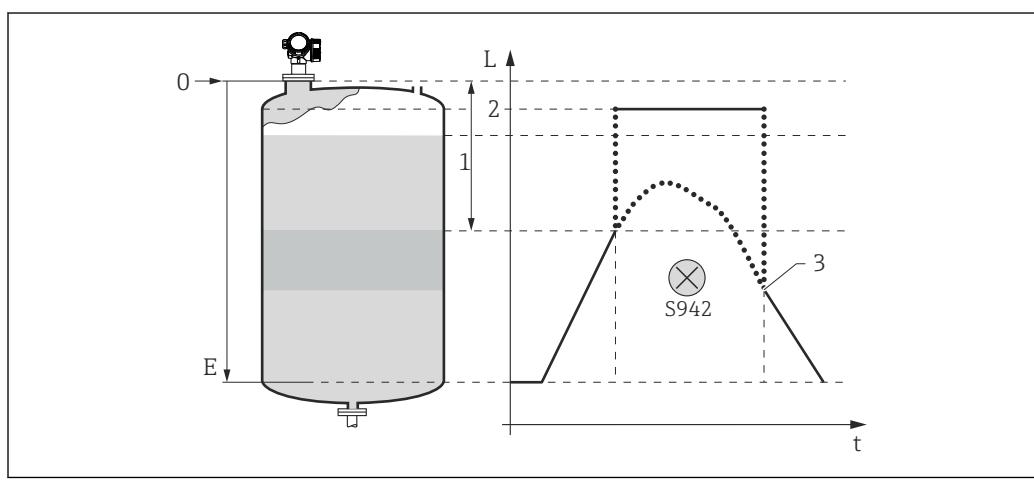
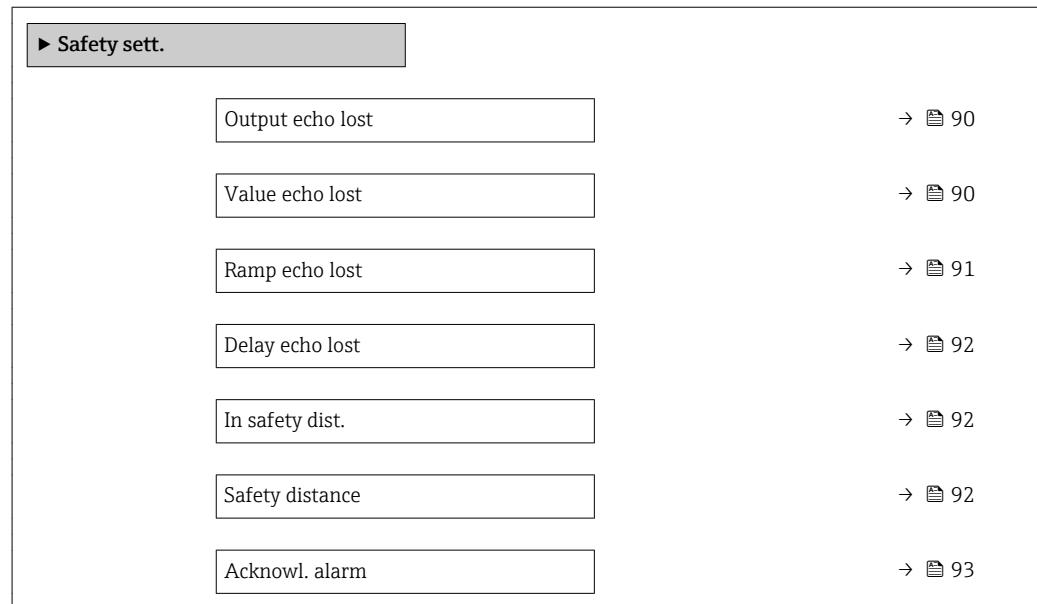


图 34 "In safety dist." = "Self holding": If the safety distance is undershot, the device generates an alarm. The measurement is not resumed until this alarm has been acknowledged by the user.

- 1 Safety distance (→ 图 92)
- 2 Value defined in "Failure mode (→ 图 112)"
- 3 Acknowl. alarm (→ 图 93)

**Structure of the submenu***Navigation* Expert → Sensor → Safety sett.

### Description of parameters

*Navigation*

Expert → Sensor → Safety sett.

#### Output echo lost



**Navigation**

Expert → Sensor → Safety sett. → Output echo lost (2307)

**Description**

Output signal in case of a lost echo.

**Selection**

- Last valid value
- Ramp echo lost
- Value echo lost
- Alarm

**Factory setting**

Last valid value

**Additional information**

#### Meaning of the options

##### ■ Last valid value

The last valid value is kept in the case of a lost echo.

##### ■ Ramp echo lost<sup>1)</sup>

In the case of a lost echo the output value is continuously shifted towards 0% or 100%.  
The slope of the ramp is defined in the **Ramp echo lost** parameter (→ 91).

##### ■ Value echo lost<sup>1)</sup>

In the case of a lost echo the output assumes the value defined in the **Value echo lost** parameter (→ 90).

##### ■ Alarm

In the case of a lost echo the device generates an alarm; see the **Failure mode** parameter (→ 112)

Read access	Operator
Write access	Maintenance

#### Value echo lost



**Navigation**

Expert → Sensor → Safety sett. → Value echo lost (2316)

**Prerequisite**

**Output echo lost (→ 90) = Value echo lost**

**Description**

Output value in case of a lost echo

**User entry**

0 to 200 000.0 %

**Factory setting**

0.0 %

1) Only visible if "Lineariz. type (→ 66)" = "None"

**Additional information**

Use the unit which has been defined for the measured value output:

- without linearization: **Level unit** (→ [66](#))
- with linearization: **Unit lineariz.** (→ [68](#))

Read access	Operator
Write access	Maintenance

**Ramp echo lost****Navigation**

Expert → Sensor → Safety sett. → Ramp echo lost (2323)

**Prerequisite**

**Output echo lost** (→ [90](#)) = **Ramp echo lost**

**Description**

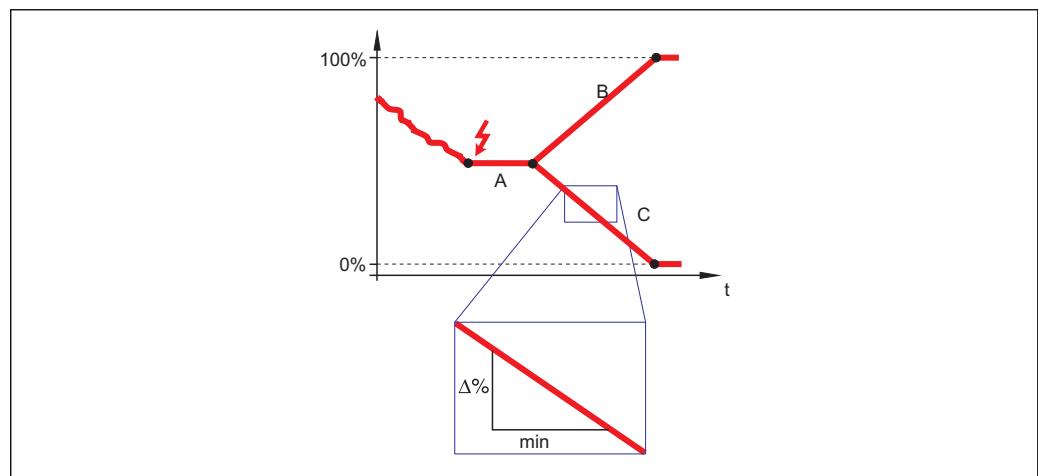
Slope of the ramp in the case of a lost echo

**User entry**

Signed floating-point number

**Factory setting**

0.0 %/min

**Additional information**

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- A Delay echo lost
- B Ramp echo lost (→ [91](#)) (positive value)
- C Ramp echo lost (→ [91](#)) (negative value)

- The unit for the slope of the ramp is "percentage of the measuring range per minute" (%/min).
- For a negative slope of the ramp: The measured value is continuously decreased until it reaches 0%.
- For a positive slope of the ramp: The measured value is continuously increased until it reaches 100%.

Read access	Operator
Write access	Maintenance

---

**Delay echo lost**

**Navigation** Expert → Sensor → Safety sett. → Delay echo lost (12456)

**Description** Time between the echo loss and the reaction defined for the output.

**User entry** 0 to 99 999.9 s

**Factory setting** 60.0 s

**Additional information**

Read access	Operator
Write access	Maintenance

---

**In safety dist.**

**Navigation** Expert → Sensor → Safety sett. → In safety dist. (12530)

**Description** Defines the reaction if the level rises into the safety distance.

**Selection**

- Off
- Alarm
- Warning
- Self holding

**Factory setting** Warning

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Safety distance**

**Navigation** Expert → Sensor → Safety sett. → Safety distance (12517)

**Description** Safety distance, measured from the reference point of the measurement (lower edge of the flange or threaded connection)

**User entry** -200 to 200 m

**Factory setting** 0 m

**Additional information** The safety distance can be used to generate a warning before the level rises into the blocking distance. The **In safety dist.** parameter defines the reaction of the device if the level rises into the safety distance.

Read access	Operator
Write access	Maintenance

**Acknowl. alarm**

**Navigation** Expert → Sensor → Safety sett. → Acknowl. alarm (12536)

**Prerequisite** In safety dist. (→ 92) = Self holding

**Description** Yes option resets an active alarm.

**Selection**

- No
- Yes

**Factory setting** No

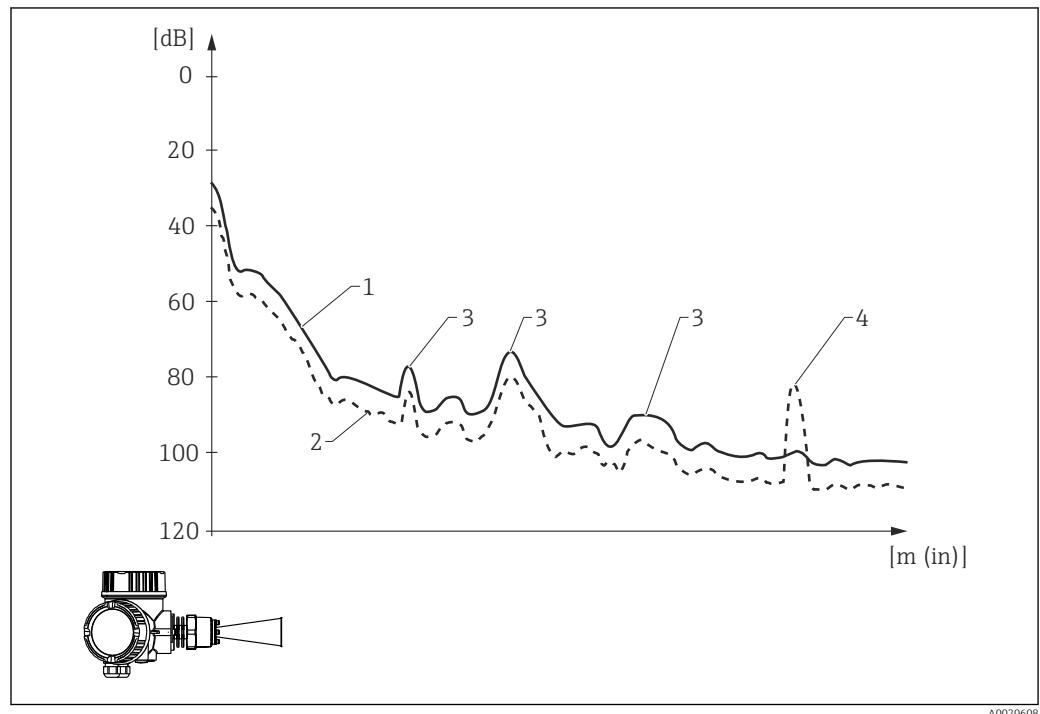
**Additional information**

Read access	Operator
Write access	Maintenance

### 3.3.10 "Mapping" submenu

The mapping is used to suppress static interference signals which may be generated by internal tank or silo fittings. A **mapping curve**, representing the **envelope curve** of an empty tank or silo as precisely as possible, is used for the mapping.

In the case of a **static envelope curve evaluation**<sup>2)</sup> all echos below the mapping curve are ignored in the signal evaluation.



- 1 Mapping curve
- 2 Envelope curve
- 3 Interference echos; covered by the mapping curve
- 4 Level echo; exceeds the envelope curve

In the case of a **dynamic envelope curve evaluation**<sup>2)</sup> echoes from below the map can also be taken into account. In this case the static envelope curve evaluation serves as a starting point as long as enough history information is not yet available.

2) For the difference between static and dynamic envelope curve evaluation refer to the "Expert → Sensor → Echo tracking" submenu.

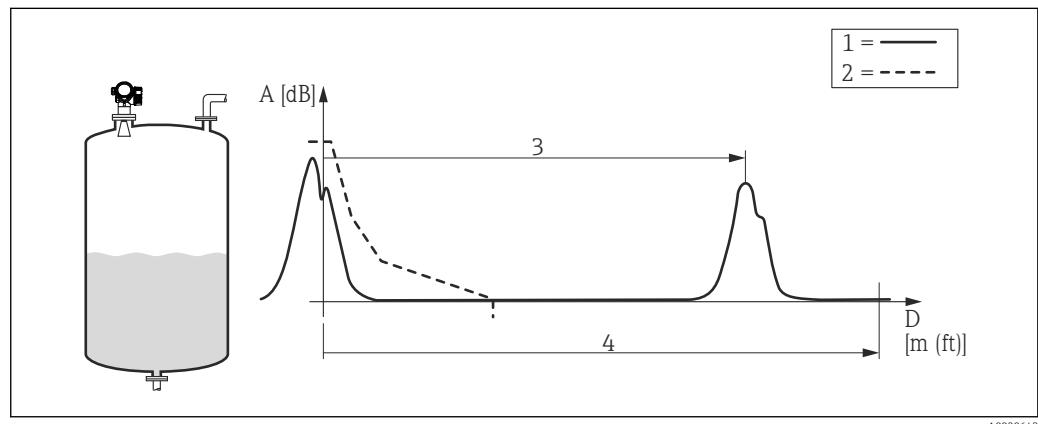
### Recording the mapping curve

There are different methods of recording the mapping curve:

- Factory map
- Overlay map
- Record new map

#### *Factory map*

The factory map is adapted to the individual antenna and is therefore permanently stored in the device and not recorded by the user. It covers the near field of the antenna (ringing area).



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- |   |                       |
|---|-----------------------|
| 1 | <i>Envelope curve</i> |
| 2 | <i>Factory map</i>    |
| 3 | <i>Level distance</i> |
| 4 | <i>Empty distance</i> |

If a new mapping is recorded, the factory map nevertheless remains in the device and can be reactivated when required by selecting the **Factory map** option in the **Confirm distance** parameter (→ 101).

#### *Overlaying the map*

In this case the existing mapping curve (i.e. the factory map or a previously recorded map) initially remains valid.

The envelope curve is observed during the defined **Map overlay time**. At each position the highest value reached during the mapping overlay time is used for the new mapping curve. Depending on the circumstances this may be the amplitude of the old mapping curve or an amplitude obtained during the **Map overlay time**.

With the help of the overlay mapping it is possible to map not only static but also dynamic signals (e.g. from an agitator).

Map overlaying will be used if one of the options **Distance ok** or **Tank empty** has been selected in the **Confirm distance** parameter.

#### *New recording of the mapping curve*

In this case the existing map is deleted and a new map is recorded.

In contrast to the overlaying, only the current envelope curve is used here and there is no mapping overlay time. Therefore the new recording is faster than the overlaying. However, dynamic interference echoes can not be suppressed in this way.

A new recording of the map is started in the following way:

1. Go to the **Confirm distance** parameter (→ 101) and select the **Manual map** option.
2. Go to the **Record map** parameter (→ 103) and select the **Record map** option.

### Partial mapping / Deleting a map partially

The overlaying or new recording of the map does not necessarily cover the complete measuring range. Instead a partial mapping can be performed.

- The mapping starts at -0.25 m (-0.8 ft), i.e. above the reference point.
- The end point of the mapping range can be defined in the **Map. end point** parameter (→ 102).

After these settings, the recording of the mapping curve is started as described above.

The map can also be partially deleted. This is performed as follows:

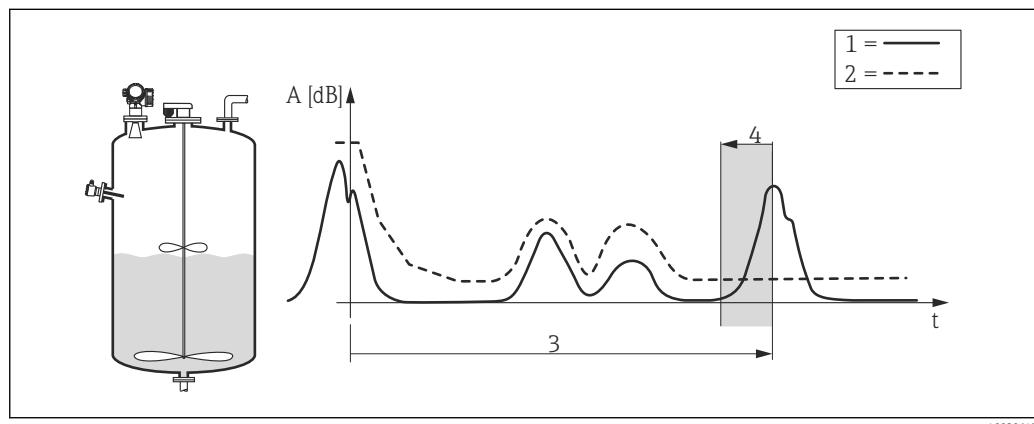
1. Enter the end point of the area to be deleted into the **Map. end point** parameter (→ 102).
2. Go to the **Record map** parameter (→ 103) and select the **Delete part. map** option.

### Mapping in the tank bottom area

Irrespective of the defined mapping range, no mapping is recorded near the end of the measuring range (defined in the **Tank/silo height** parameter ( $\rightarrow$  55)). In this gap the map assumes a constant value as defined by the **End of mapping** ( $\rightarrow$  103) and **End map. ampl.** ( $\rightarrow$  103) parameters.

*"End of mapping" = "Last map value"*

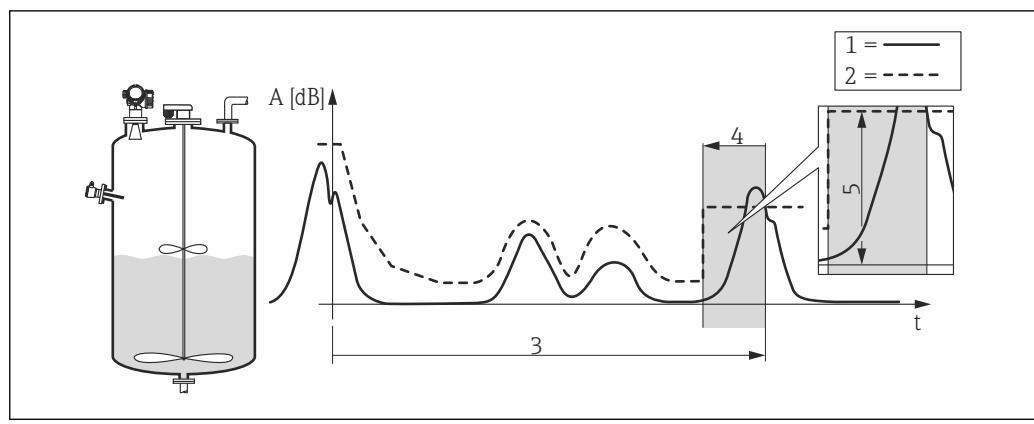
With this setting the last value of the map remains valid within the tank bottom area.



- 1 Envelope curve
- 2 Map
- 3 Tank/silo height ( $\rightarrow$  55)
- 4 Tank bottom area

*"End of mapping" = "Adjustable"*

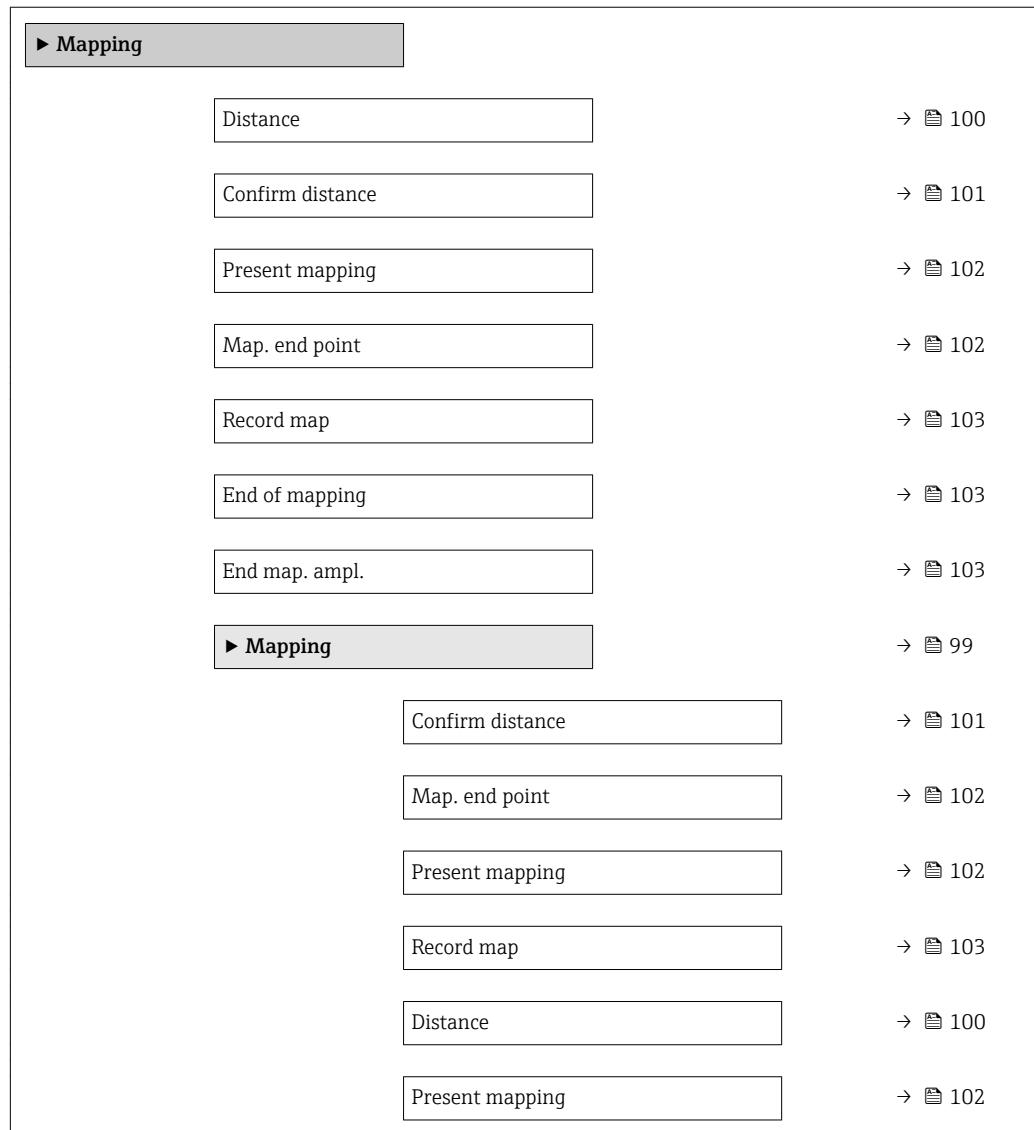
With this setting the value of the mapping curve within the tank bottom area is defined in the **End map. ampl.** parameter ( $\rightarrow$  103).



- 1 Envelope curve
- 2 Map
- 3 Tank/silo height ( $\rightarrow$  55)
- 4 Tank bottom area
- 5 End map. ampl. ( $\rightarrow$  103)

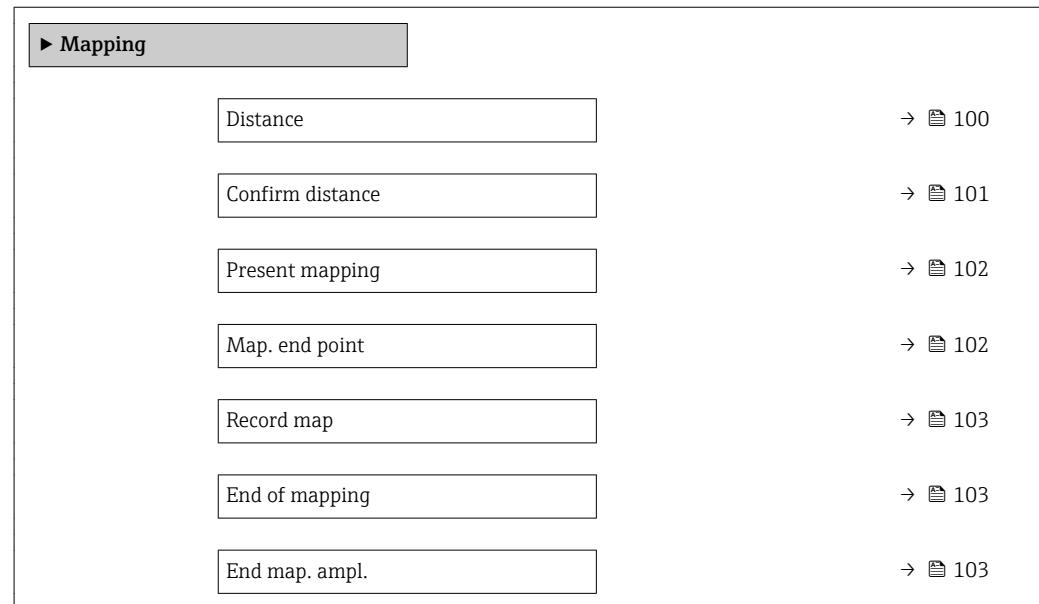
**Structure of the submenu on the local display***Navigation*

Expert → Sensor → Mapping



**Structure of the submenu in an operating tool***Navigation*

Expert → Sensor → Mapping



### Description of parameters

Navigation

Diagram Expert → Sensor → Mapping

#### Distance

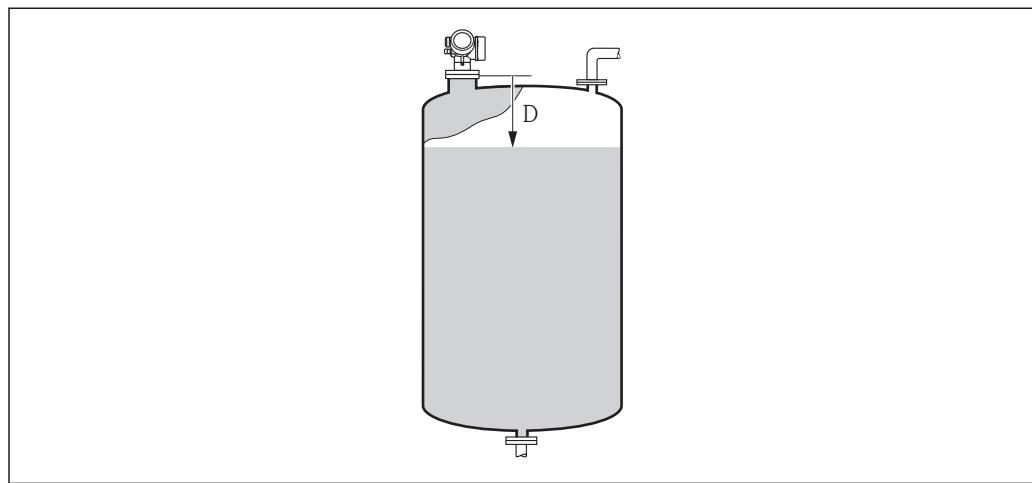
Navigation

Diagram Expert → Sensor → Mapping → Distance (12401)

Description

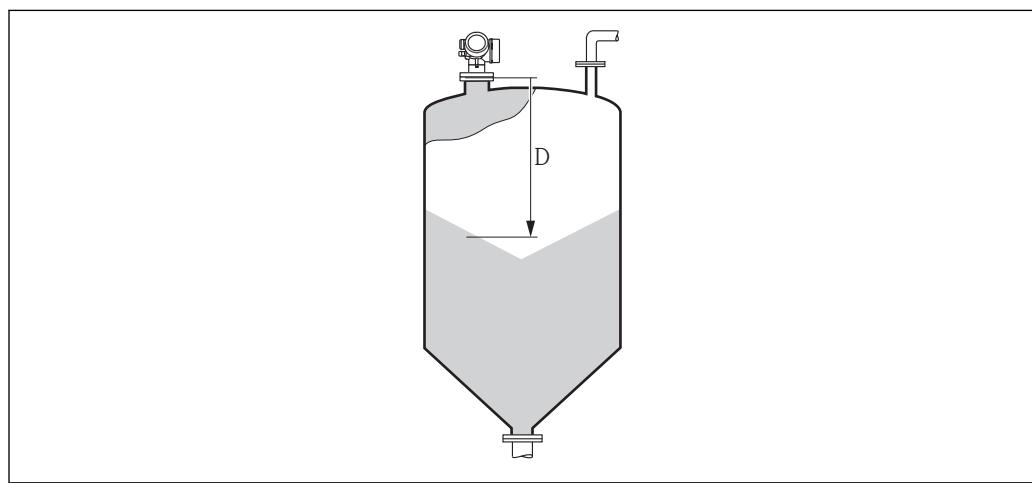
Distance between lower edge of flange or thread and medium surface.

Additional information



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Diagram 35 Distance for liquid measurements



A0019485

Diagram 36 Distance for bulk solid measurements

Read access	Operator
Write access	-

**Confirm distance****Navigation**

Expert → Sensor → Mapping → Confirm distance (12462)

**Description**

Specify, whether the measured distance matches the real distance. Depending on the selection the device automatically sets the range of mapping.

**Selection**

- Manual map
- Distance ok
- Distance unknown
- Dist. too small <sup>\*</sup>
- Distance too big <sup>\*</sup>
- Tank empty
- Factory map

**Factory setting**

Distance unknown

**Additional information****Meaning of the options****■ Manual map**

To be selected if the range of mapping is to be defined manually in the **Map. end point** parameter. In this case it is not necessary to confirm the distance.

**■ Distance ok**

To be selected if the measured distance matches the actual distance. The device performs a mapping.

**■ Distance unknown**

To be selected if the actual distance is unknown. A mapping can not be performed in this case.

**■ Dist. too small <sup>3)</sup>**

To be selected if the measured distance is smaller than the actual distance. The device searches for the next echo and returns to the **Confirm distance** parameter . The distance is recalculated and displayed. The comparison must be repeated until the displayed distance matches the actual distance. After this, the recording of the map can be started by selecting **Distance ok**.

\* Visibility depends on order options or device settings

3) Only available for "Expert → Sensor → Echo tracking → **Evaluation mode** parameter ≠ "History off option"

■ **Distance too big**

To be selected if the measured distance exceeds the actual distance. The device adjusts the signal evaluation and returns to the **Confirm distance** parameter. The distance is recalculated and displayed. The comparison must be repeated until the displayed distance matches the actual distance. After this, the recording of the map can be started by selecting **Distance ok**.

■ **Tank empty**

To be selected if the tank is completely empty. The device records a mapping covering the complete measuring range as defined by the **Tank/silo height** parameter. By default, **Tank/silo height = Empty calibr..**

Take into account that in case of conical outlets, for example, a measurement is only possible up to the point at which the radar hits the bottom of the tank or silo. If the **Tank empty** option is used, **Empty calibr.** (→ 53) and **Tank/silo height** may not reach below this point as otherwise the empty signal is suppressed.

■ **Factory map**

The factory map permanently stored in the device is used.

**i** When operating via the display module, the measured distance is displayed together with this parameter for reference purposes.

**i** If the teaching procedure with the **Dist. too small** option or **Distance too big** option is quit before the distance has been confirmed, a map is **not** recorded and the teaching procedure is reset after 60 s.

Read access	Operator
Write access	Maintenance

---

## Present mapping

---

**Navigation**

Expert → Sensor → Mapping → Present mapping (12487)

**Description**

Present end of mapping.

**Additional information**

Read access	Operator
Write access	-

---

## Map. end point

---



**Navigation**

Expert → Sensor → Mapping → Map. end point (12459)

**Prerequisite**

**Confirm distance** (→ 101) = **Manual map** or **Dist. too small**

**Description**

New end point of mapping.

**User entry**

0.0001 to 999 999.9 m

**Factory setting**

0.1 m

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Record map**

---

**Navigation**  Expert → Sensor → Mapping → Record map (12448)

**Prerequisite** Confirm distance = Manual map or Dist. too small

**Selection**

- No
- Record map
- Overlay map
- Factory map
- Delete part. map

**Factory setting** No

<b>Additional information</b>	Read access	Operator
	Write access	Maintenance

---

**End of mapping**

---



**Navigation**  Expert → Sensor → Mapping → End of mapping (12461)

**Description** Behavior of the mapping curve in the tank bottom area

**Selection**

- Adjustable
- Last map value

**Factory setting** Adjustable

<b>Additional information</b>	Read access	Operator
	Write access	Maintenance

---

**End map. ampl.**

---

**Navigation**  Expert → Sensor → Mapping → End map. ampl. (12478)

**Description** Amplitude of the mapping curve in the tank bottom area

**User entry** -99 999.0 to 99 999.0 dB

**Factory setting** -90 dB

<b>Additional information</b>	Read access	Operator
	Write access	Operator

### 3.3.11 "Tank bottom eval" submenu

The tank bottom evaluation is intended to prevent an echo loss if the tank is empty.

If no echo is found within the defined tank height (**Tank/silo height** (→ 55)) the tank bottom searches beyond this distance in the **TB range**, to see whether an echo from the tank bottom exists.

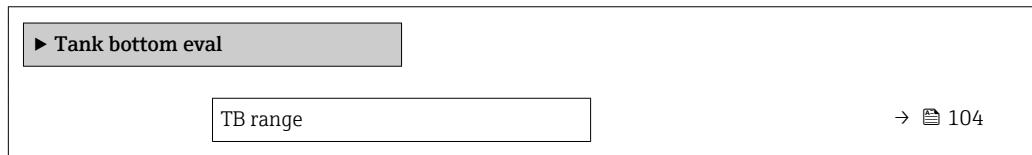
If a tank bottom echo has been found, a level of 0% is assumed. If neither a direct level echo nor a tank bottom echo has been found, an echo loss is reported (error message S941).

-  ▪ Level echoes from within the measuring range always have a higher priority than the tank bottom echo.
- The first echo factor is not applied to the tank bottom echo.

#### Structure of the submenu

*Navigation*

Expert → Sensor → Tank bottom eval



#### Description of parameters

*Navigation*

Expert → Sensor → Tank bottom eval

## TB range



#### Navigation

Expert → Sensor → Tank bottom eval → TB range (12463)

#### Description

Range in which the tank bottom echo is searched for

#### User entry

0 to 99.999 m

#### Factory setting

15 m

#### Additional information

Read access	Operator
Write access	Maintenance

### 3.3.12 "Echo tracking" submenu

The echo tracking algorithm takes into account temporal changes of the level echo when evaluating the envelope curve. This improves the allocation of the echoes to the level signal.

The following types of echo tracking can be selected in the **Evaluation mode** parameter (→ 106):

- **History off**

Static envelope curve evaluation taking into account the mapping.

- **Short time hist.**

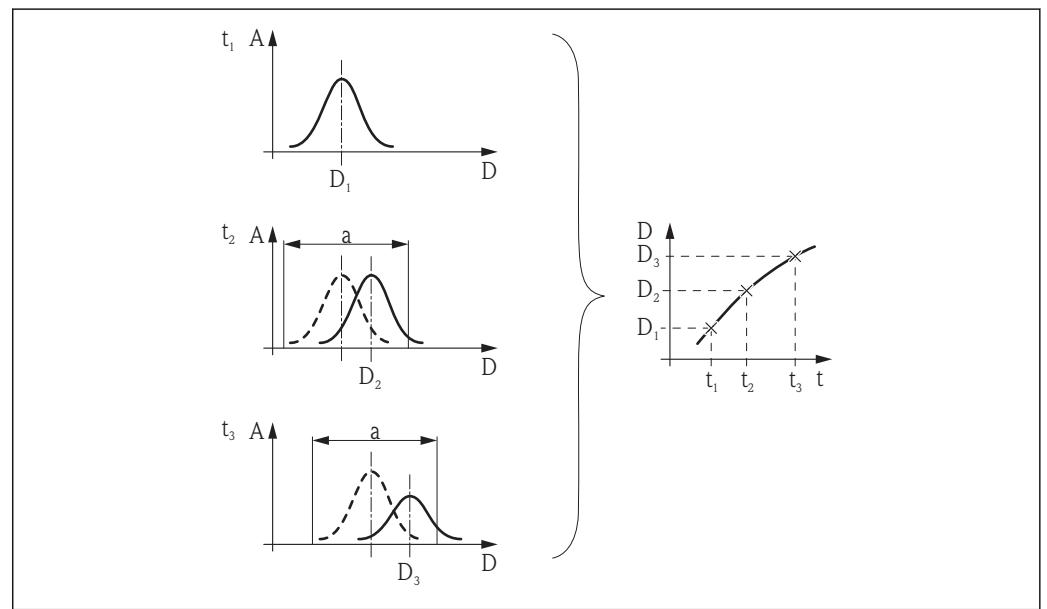
Echo tracking (see below) without consideration of the mapping.

- **Echo track.**

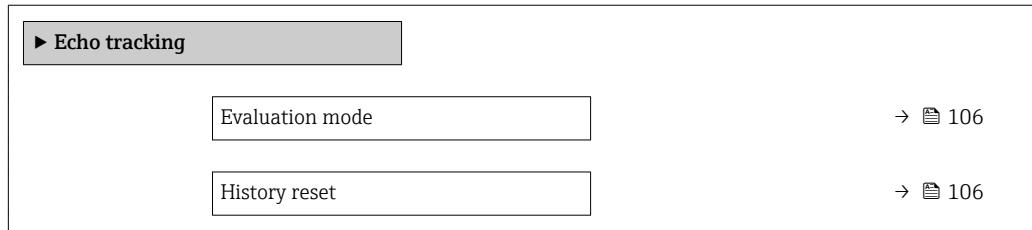
Echo tracking (see below) taking into account the mapping.

#### **Echo tracking**

The position of the individual echoes is tracked. The track contains the position, the velocity, the relative and the absolute echo amplitude. Normally the strongest echo within a search window is selected and allocated to the track.



■ 37 Definition of a track: In a new envelope curve, the echo is searched for in a window of width "a" centered around the echo position in the previous envelope curve. The change of the echo position in the course of time defines the track.

**Structure of the submenu***Navigation* Expert → Sensor → Echo tracking**Description of parameters***Navigation* Expert → Sensor → Echo tracking**Evaluation mode****Navigation** Expert → Sensor → Echo tracking → Evaluation mode (12411)**Description**

Defines the evaluation mode for the echo tracking.

**Selection**

- History off
- Short time hist.
- Echo track.

**Factory setting**

Echo track.

**Additional information**

Read access	Operator
Write access	Maintenance

**History reset****Navigation** Expert → Sensor → Echo tracking → History reset (12449)**Description**

Resets history of the echo and tank tracking.

**Selection**

- Reset done
- Restart tracking
- Delete history

**Factory setting**

Reset done

**Additional information****Meaning of the options****▪ Reset done**

Does not initiate an action but is only a display option. It is displayed as soon as the reset operation has been accomplished.

**▪ Restart tracking**

The echo tracking is reset. The tank trace, however, is maintained.

**▪ Delete history**

The echo tracking and tank trace are reset.

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

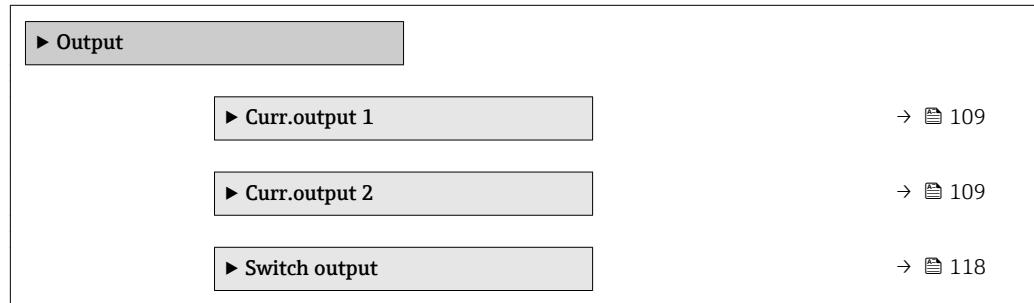
## 3.4 "Output" submenu

The **Output** submenu contains all parameters needed to configure the current and switch outputs.

### 3.4.1 Structure of the submenu

*Navigation*

☰ ☰ Expert → Output



### 3.4.2 "Curr.output 1 to 2" submenu

There is a **Curr.output** submenu for each current output of the device (1 or 2 depending on the device version).

#### Structure of the submenu

*Navigation*

Diagram Expert → Output → Curr.output 1 to 2

► Curr.output 1 to 2	
Assign curr.	→  110
Current span	→  111
Fixed current	→  111
Damping out.	→  112
Output curr. 1 to 2	→  112
Failure mode	→  112
Failure current	→  113
Turn down	→  113
4 mA value	→  114
20 mA value	→  114
Measuring mode	→  115
Start-up mode	→  115
Start-up current	→  116
Measur. curr. 1 to 2	→  116
Terminal volt. 1	→  117

## Description of parameters

*Navigation*

Expert → Output → Curr.output 1 to 2

### Assign curr. 1 to 2



#### Navigation

Expert → Output → Curr.output 1 → Assign curr. 1 (0359)

Expert → Output → Curr.output 2 → Assign curr. 2 (0359-2)

#### Description

Determines which process variable is transmitted via the current output.

#### Selection

- Level linearized
- Distance
- Electronic temp.
- Relat.echo ampl.
- Area incoupling
- Analog out. AD 1
- Analog out. AD 2
- Analog out. AD 3
- Analog out. AD 4

#### Factory setting

- Current output 1: Level linearized
- Current output 2<sup>4)</sup>: Relative echo amplitude

#### Additional information

*Definition of the current range for the process variables*

Process variable	4 mA value	20 mA value
Level linearized	0 % <sup>1)</sup> or the associated linearized value.	100 % <sup>2)</sup> or the associated linearized value.
Distance	0(i.e. level is at the reference point)	<b>Empty calibr.</b> (→  53) (i.e. level is at 0 %)
Electronic temp.	-50 °C (-58 °F)	100 °C (212 °F)
Relat.echo ampl.	0 dB	150 dB
Area incoupling	0	100
Analog out. AD 1/2/3/4	dependent on the parametrization of the Advanced Diagnostics	

1) The 0% level is defined by the **Empty calibr.** parameter (→ 53).

2) The 100% level is defined by the **Full calibr.** parameter (→ 54).

It may be necessary to adjust the 4mA and 20mA values to the application (especially in the case of the **Analog out. AD 1 - 4** and **Area incoupling** options).

This can be done by the following parameters:

- Expert → Output → Curr.output 1 to 2 → Turn down (0358-1 to 2)
- Expert → Output → Curr.output 1 to 2 → 4 mA value (0367-1 to 2)
- Expert → Output → Curr.output 1 to 2 → 20 mA value (0372-1 to 2)

Read access	Operator
Write access	Maintenance

4) only for devices with two current outputs

**Current span****Navigation**

Expert → Output → Curr.output 1 to 2 → Current span (0353–1 to 2)

**Description**

Determines the current range used to transmit the measured value. '4...20mA': Measured variable: 4 ... 20 mA '4...20mA NAMUR': Measured variable: 3.8 ... 20.5 mA '4...20mA US': Measured variable: 3.9 ... 20.8 mA 'Fixed current': Measured variable transmitted via HART only Note: Currents below 3.6 mA or above 21.95 mA can be used to signal an alarm.

**Selection**

- 4...20 mA
- 4...20 mA NAMUR
- 4...20 mA US
- Fixed current

**Factory setting**

4...20 mA NAMUR

**Additional information**

*Meaning of the options*

Option	Current range for process variable	Lower alarm signal level	Upper alarm signal level
4...20 mA	4 to 20.5 mA	< 3.6 mA	> 21.95 mA
4...20 mA NAMUR	3.8 to 20.5 mA	< 3.6 mA	> 21.95 mA
4...20 mA US	3.9 to 20.8 mA	< 3.6 mA	> 21.95 mA
Fixed current	Constant current, defined in the <b>Fixed current</b> parameter (→  111).		

- In the case of an error, the output current assumes the value defined in the **Failure mode** parameter (→ 112).  
 ■ If the measured value is out of the measuring range, diagnostic message **Curr.output** is issued.

- In a HART multidrop loop only one device can use the analog current to transmit a signal. For all other devices one must set:  
 ■ **Current span = Fixed current**  
 ■ **Fixed current (→ 111) = 4 mA**

Read access	Operator
Write access	Maintenance

**Fixed current****Navigation**

Expert → Output → Curr.output 1 to 2 → Fixed current (0365–1 to 2)

**Prerequisite**

**Current span (→ 111) = Fixed current**

**Description**

Define constant value of the output current.

**User entry**

4 to 22.5 mA

**Factory setting**

4 mA

**Additional information**

Read access	Operator
Write access	Maintenance

**Damping out.****Navigation**

Expert → Output → Curr.output 1 to 2 → Damping out. (0363-1 to 2)

**Description**

Reaction time of the output signal on fluctuation in the measured value.

**User entry**

0.0 to 999.9 s

**Factory setting**

0.0 s

**Additional information**

Fluctuations of the measured value affect the output current with an exponential delay, the time constant  $\tau$  of which is defined in this parameter. With a small time constant the output reacts immediately to changes of the measured value. With a big time constant the reaction of the output is more delayed. For  $\tau = 0$  (factory setting) there is no damping.

Read access	Operator
Write access	Maintenance

**Output curr. 1 to 2****Navigation**

Expert → Output → Curr.output 1 to 2 → Output curr. 1 to 2 (0361-1 to 2)

**Description**

The actual calculated value of the output current.

**Additional information**

Read access	Operator
Write access	-

**Failure mode****Navigation**

Expert → Output → Curr.output 1 to 2 → Failure mode (0364-1 to 2)

**Prerequisite**

**Current span (→ 111) ≠ Fixed current**

**Description**

Defines which current the output assumes in the case of an error. 'Min.': < 3.6mA 'Max.': > 21.95mA 'Last valid value': Last valid value before occurrence of the error. 'Actual value': Output current is equal to the measured value; error is ignored. 'Defined value': User defined value.

<b>Selection</b>	<ul style="list-style-type: none"> <li>■ Min.</li> <li>■ Max.</li> <li>■ Last valid value</li> <li>■ Actual value</li> <li>■ Defined value</li> </ul>				
<b>Factory setting</b>	Max.				
<b>Additional information</b>	<b>Meaning of the options</b> <ul style="list-style-type: none"> <li>■ <b>Min.</b> The current output adopts the value of the lower alarm level according to the <b>Current span</b> parameter (→ 111).</li> <li>■ <b>Max.</b> The current output adopts the value of the upper alarm level according to the <b>Current span</b> parameter (→ 111).</li> <li>■ <b>Last valid value</b> The current remains constant at the last value it had before the error occurred.</li> <li>■ <b>Actual value</b> The output current follows the actual measured value; the error is ignored.</li> <li>■ <b>Defined value</b> The output current assumes the value defined in the <b>Failure current</b> parameter (→ 113).</li> </ul> <p><b>i</b> The error behavior of other output channels is not influenced by these settings but is defined in separate parameters.</p>				
<b>Failure current</b>	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="padding: 2px;">Read access</td><td style="padding: 2px;">Operator</td></tr> <tr> <td style="padding: 2px;">Write access</td><td style="padding: 2px;">Maintenance</td></tr> </table>	Read access	Operator	Write access	Maintenance
Read access	Operator				
Write access	Maintenance				

<b>Failure current</b>					
<b>Navigation</b>	  Expert → Output → Curr.output 1 to 2 → Failure current (0352-1 to 2)				
<b>Prerequisite</b>	<b>Failure mode (→ 112) = Defined value</b>				
<b>Description</b>	Defines which current the output assumes in case of an error.				
<b>User entry</b>	3.59 to 22.5 mA				
<b>Factory setting</b>	22.5 mA				
<b>Additional information</b>	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="padding: 2px;">Read access</td><td style="padding: 2px;">Operator</td></tr> <tr> <td style="padding: 2px;">Write access</td><td style="padding: 2px;">Maintenance</td></tr> </table>	Read access	Operator	Write access	Maintenance
Read access	Operator				
Write access	Maintenance				

<b>Turn down</b>	
<b>Navigation</b>	  Expert → Output → Curr.output 1 to 2 → Turn down (0358-1 to 2)
<b>Prerequisite</b>	<b>Current span (→ 111) ≠ Fixed current</b>

<b>Description</b>	Switch the current turn down functionality on or off.				
<b>Selection</b>	<ul style="list-style-type: none"> <li>▪ Off</li> <li>▪ On</li> </ul>				
<b>Factory setting</b>	Off				
<b>Additional information</b>	<p>Using the turn down functionality it is possible to map a section of the measuring range to the total range of the output current (4-20mA). The section is defined by the 4 mA value (→ <a href="#">114</a>) and 20 mA value (→ <a href="#">114</a>) parameters.</p> <p>Without the turn down, the complete measuring range (0 to 100%) is mapped to the current output (4 to 20mA).</p>				
<table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="padding: 2px;">Read access</td> <td style="padding: 2px;">Operator</td> </tr> <tr> <td style="padding: 2px;">Write access</td> <td style="padding: 2px;">Maintenance</td> </tr> </table>		Read access	Operator	Write access	Maintenance
Read access	Operator				
Write access	Maintenance				

<b>4 mA value</b>						
<b>Navigation</b>		  Expert → Output → Curr.output 1 to 2 → 4 mA value (0367-1 to 2)				
<b>Prerequisite</b>		<b>Turn down (→ <a href="#">113</a>) = On</b>				
<b>Description</b>		Enter 4 mA value.				
<b>User entry</b>		Signed floating-point number				
<b>Factory setting</b>		0.0 %				
<b>Additional information</b>		<table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="padding: 2px;">Read access</td> <td style="padding: 2px;">Operator</td> </tr> <tr> <td style="padding: 2px;">Write access</td> <td style="padding: 2px;">Maintenance</td> </tr> </table>	Read access	Operator	Write access	Maintenance
Read access	Operator					
Write access	Maintenance					

<b>20 mA value</b>		
<b>Navigation</b>		  Expert → Output → Curr.output 1 to 2 → 20 mA value (0372-1 to 2)
<b>Prerequisite</b>		<b>Turn down (→ <a href="#">113</a>) = On</b>
<b>Description</b>		Enter 20 mA value.
<b>User entry</b>		Signed floating-point number
<b>Factory setting</b>		0.0 %
<b>Additional information</b>		If <b>20 mA value</b> is smaller than <b>4 mA value</b> (→ <a href="#">114</a> ), the current output is inverted, which means that an increase of the process variable results in a decrease of the output current.

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

**Measuring mode**

**Navigation** Expert → Output → Curr.output 1 to 2 → Measuring mode (0351-1 to 2)

**Prerequisite** **Current span (→ 111) ≠ Fixed current**

**Description** Select measuring mode for output.

**Selection**

- Standard
- Inverse

**Factory setting** Standard

**Additional information** **Meaning of the options**

- **Standard**  
If the level increases, the output current increases as well.
- **Inverse**  
If the level increases, the output current decreases.

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

**Start-up mode**

**Navigation** Expert → Output → Curr.output 1 → Start-up mode (0368-1)

**Prerequisite**

- **Current span (→ 111) ≠ Fixed current**
- Only for current output 1

**Description** Select behavior of the current output during start-up.

**Selection**

- Min.
- Max.
- Defined value

**Factory setting** Min.

**Additional information****Meaning of the options****▪ Min.**

The start-up current corresponds to the lower edge of the range selected in the **Current span** parameter (→ 111).

**▪ Max.**

The start-up current corresponds to the upper edge of the range selected in the **Current span** parameter (→ 111).

**▪ Defined value**

The value of the start-up current is defined in the **Start-up current** parameter (→ 116).

Read access	Operator
Write access	Maintenance

**Start-up current****Navigation**

Expert → Output → Curr.output 1 → Start-up current (0369-1)

**Prerequisite**

- **Start-up mode** (→ 115) = **Defined value**
- Only for current output 1

**Description**

Define value the current output assumes during start-up.

**User entry**

3.59 to 22.5 mA

**Factory setting**

3.6 mA

**Additional information**

Read access	Operator
Write access	Maintenance

**Measur. curr. 1****Navigation**

Expert → Output → Curr.output 1 → Measur. curr. 1 (0366-1)

**Prerequisite**

Only available for current output 1

**Description**

Current output value which is currently measured.

**Additional information**

Read access	Operator
Write access	-

---

**Terminal volt. 1**

---

**Navigation** Expert → Output → Curr.output 1 → Terminal volt. 1 (0662)**Description**

Terminal voltage that is applied at the output.

**Additional information**

Read access	Operator
Write access	-

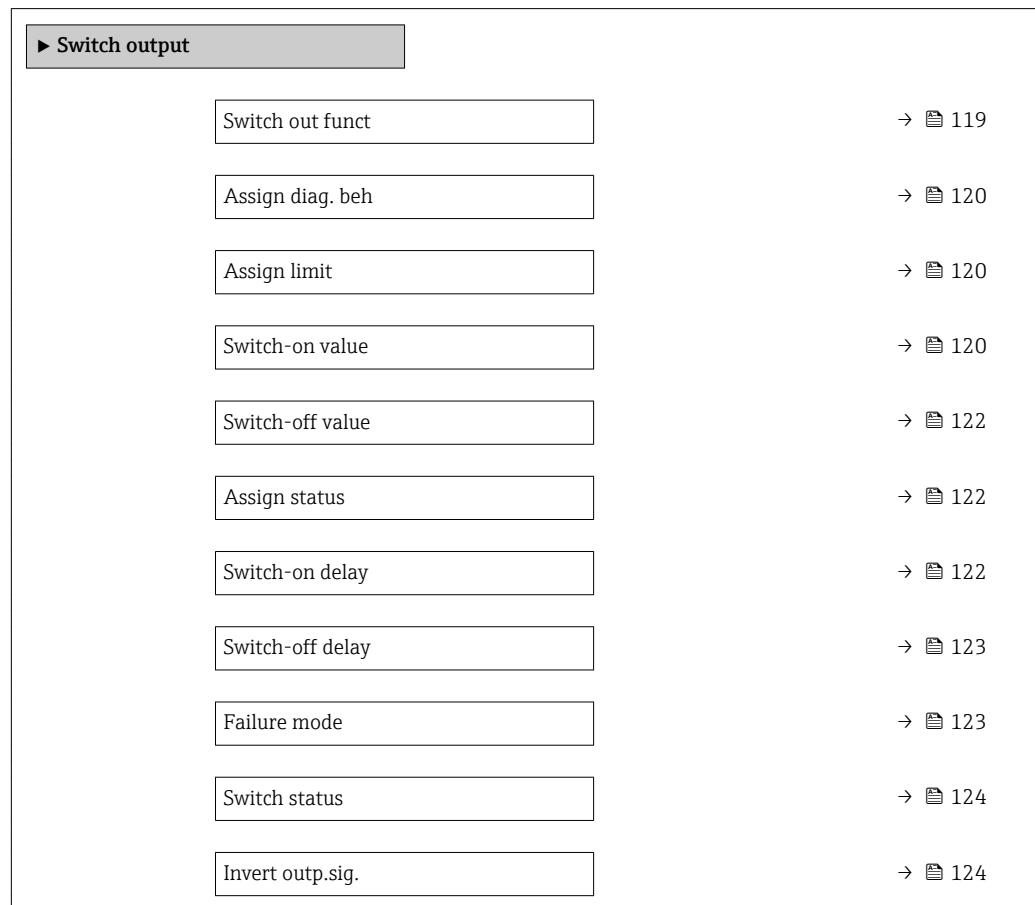
### 3.4.3 "Switch output" submenu

The **Switch output** submenu is used to configure the switch output of the device.

#### Structure of the submenu

*Navigation*

☰ ☰ Expert → Output → Switch output



## Description of parameters

*Navigation*

Diagram Expert → Output → Switch output



### Switch out funct

#### Navigation

Diagram Expert → Output → Switch output → Switch out funct (0481)

#### Description

Defines the function of the switch output. 'Off' The switch output is always open (non-conductive) 'On' The switch output is always closed (conductive). 'Diagnostic behavior' The switch output is normally closed and is only opened if a diagnostic event is present. 'Limit' The switch output is normally closed and is only opened if a measured variable exceeds a defined limit. 'Digital output' The switch output is controlled by one of the digital output blocks of the device.

#### Selection

- Off
- On
- Diag. behavior
- Limit
- Digital Output

#### Factory setting

Off

#### Additional information

##### Meaning of the options

- **Off**  
The output is always open (non-conductive).
- **On**  
The output is always closed (conductive).
- **Diag. behavior**  
The output is normally closed and is only opened if a diagnostic event is present. The **Assign diag. beh** parameter (→ 120) determines for which type of event the output is opened.
- **Limit**  
The output is normally closed and is only opened if a measured variable exceeds or falls below a defined limit. The limit values are defined by the following parameters:  
  - **Assign limit** (→ 120)
  - **Switch-on value** (→ 120)
  - **Switch-off value** (→ 122)
- **Digital Output**  
The switching state of the output tracks the output value of a DI function block. The function block is selected in the **Assign status** parameter (→ 122).



The **Off** and **On** options can be used to simulate the switch output.

Read access	Operator
Write access	Maintenance

---

**Assign diag. beh****Navigation**

Diagram: Expert → Output → Switch output → Assign diag. beh (0482)

**Prerequisite**

**Switch out funct (→ [Diagram 119](#)) = Diag. behavior**

**Description**

Defines to which behavior of diagnostic events the switch output reacts.

**Selection**

- Alarm
- Alarm or warning
- Warning

**Factory setting**

Alarm

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Assign limit****Navigation**

Diagram: Expert → Output → Switch output → Assign limit (0483)

**Prerequisite**

**Switch out funct (→ [Diagram 119](#)) = Limit**

**Selection**

- Off
- Level linearized
- Distance
- Terminal volt.
- Electronic temp.
- Relat.echo ampl.
- Area incoupling

**Factory setting**

Off

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Switch-on value****Navigation**

Diagram: Expert → Output → Switch output → Switch-on value (0466)

**Prerequisite**

**Switch out funct (→ [Diagram 119](#)) = Limit**

**Description**

Defines the switch-on point. The output is closed if the assigned process variable rises above this point.

**User entry**

Signed floating-point number

**Factory setting**

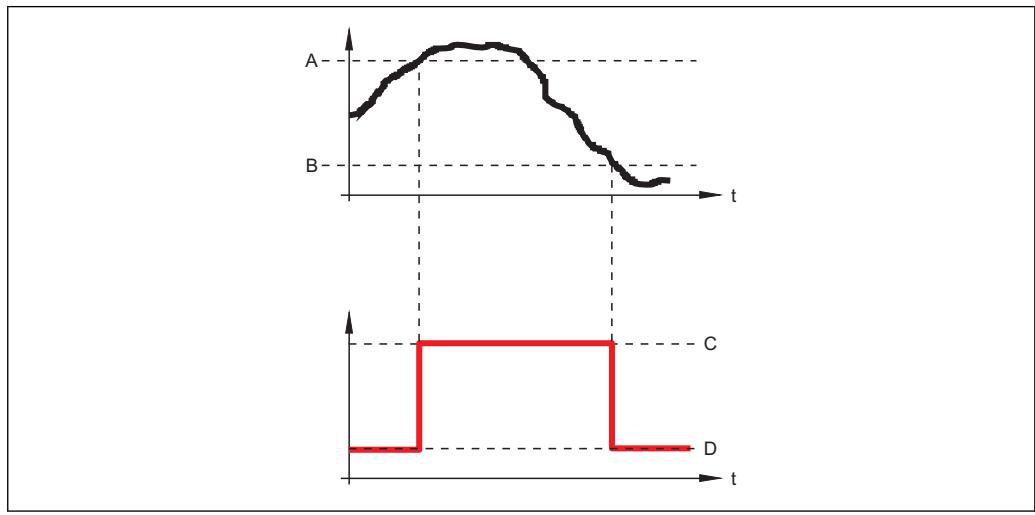
0

**Additional information**

The switching behavior depends on the relative position of the **Switch-on value** and **Switch-off value** parameters:

**Switch-on value > Switch-off value**

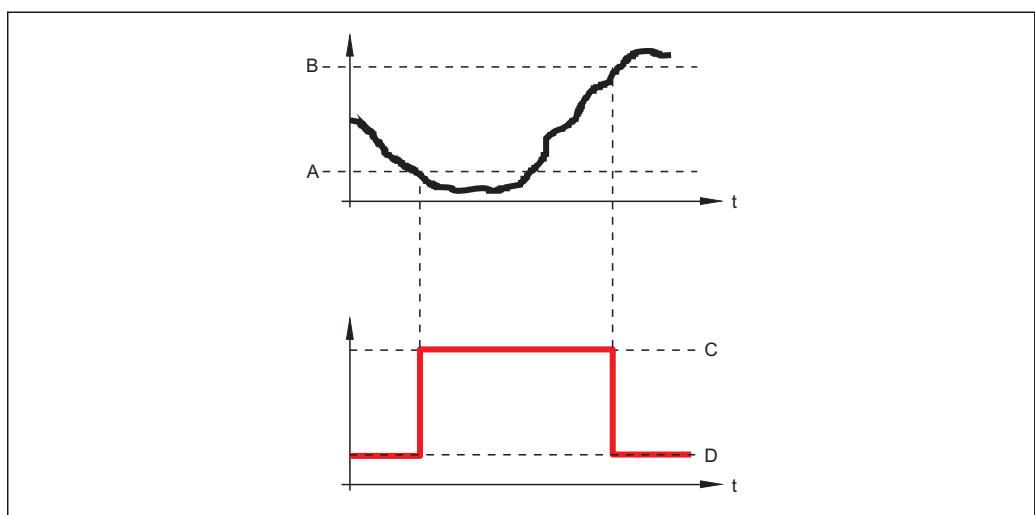
- The output is closed if the measured value is larger than **Switch-on value**.
- The output is opened if the measured value is smaller than **Switch-off value**.



- A *Switch-on value*  
 B *Switch-off value*  
 C *Output closed (conductive)*  
 D *Output opened (non-conductive)*

**Switch-on value < Switch-off value**

- The output is closed if the measured value is smaller than **Switch-on value**.
- The output is opened if the measured value is larger than **Switch-off value**.



- A *Switch-on value*  
 B *Switch-off value*  
 C *Output closed (conductive)*  
 D *Output opened (non-conductive)*

Read access	Operator
Write access	Maintenance

**Switch-off value****Navigation**

Expert → Output → Switch output → Switch-off value (0464)

**Prerequisite**

**Switch out funct (→ [119](#)) = Limit**

**Description**

Defines the switch-off point. The output is opened if the assigned process variable falls below this point.

**User entry**

Signed floating-point number

**Factory setting**

0

**Additional information**

The switching behavior depends on the relative position of the **Switch-on value** and **Switch-off value** parameters; description: see the **Switch-on value** parameter (→ [120](#)).

Read access	Operator
Write access	Maintenance

**Assign status****Navigation**

Expert → Output → Switch output → Assign status (0485)

**Prerequisite**

**Switch out funct (→ [119](#)) = Digital Output**

**Selection**

- Off
- Digital out AD 1
- Digital out AD 2
- Digital out AD 3
- Digital out AD 4

**Factory setting**

Off

**Additional information**

The **Digital out AD 1/2/3/4** options refer to the Advanced Diagnostic Blocks → [173](#). A switch signal generated in these blocks can be transmitted via the switch output.

Read access	Operator
Write access	Maintenance

**Switch-on delay****Navigation**

Expert → Output → Switch output → Switch-on delay (0467)

**Prerequisite**

- **Switch out funct (→ [119](#)) = Limit**
- **Assign limit (→ [120](#)) ≠ Off**

**Description**

Defines the delay applied before the output is switched on.

**User entry** 0.0 to 100.0 s

**Factory setting** 0.0 s

**Additional information**

Read access	Operator
Write access	Maintenance

## Switch-off delay



**Navigation** Expert → Output → Switch output → Switch-off delay (0465)

**Prerequisite**

- **Switch out funct** (→ 119) = **Limit**
- **Assign limit** (→ 120) ≠ **Off**

**Description** Defines the delay applied before the output is switched off.

**User entry** 0.0 to 100.0 s

**Factory setting** 0.0 s

**Additional information**

Read access	Operator
Write access	Maintenance

## Failure mode



**Navigation** Expert → Output → Switch output → Failure mode (0486)

**Prerequisite** **Switch out funct** (→ 119) = **Limit** or **Digital Output**

**Description** Defines the state of the switch output in case of an error.

**Selection**

- Actual status
- Open
- Closed

**Factory setting** Open

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Switch status**

---

**Navigation**  Expert → Output → Switch output → Switch status (0461)**Description**

Current status of the switch output.

**Additional information**

Read access	Operator
Write access	-

---

**Invert outp.sig.**

---

**Navigation**  Expert → Output → Switch output → Invert outp.sig. (0470)**Description**

'No' The switch output behaves as per its parameter setting. 'Yes' The switching behavior is inverted as compared to its parameter setting.

**Selection**

- No
- Yes

**Factory setting**

No

**Additional information****Meaning of the options****■ No**

The behavior of the switch output is as described above.

**■ Yes**The states **Open** and **Closed** are inverted as compared to the description above.

Read access	Operator
Write access	Maintenance

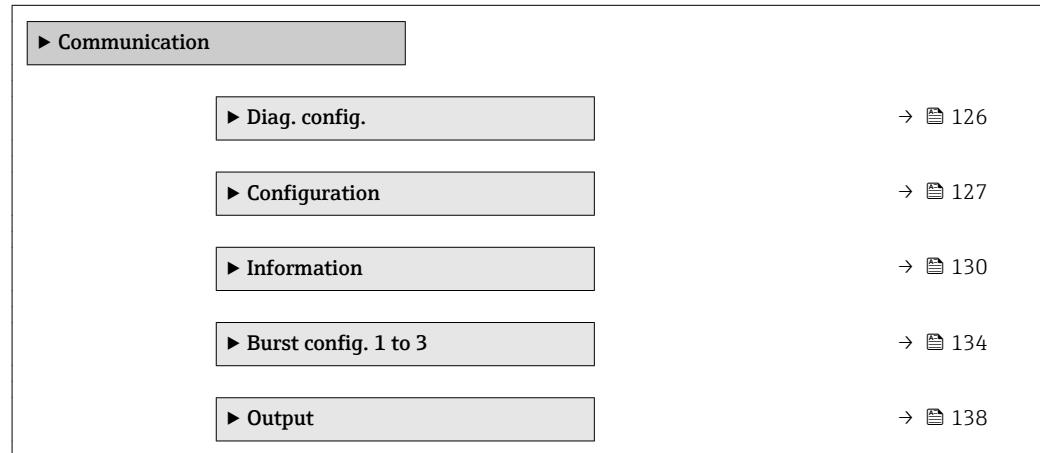
## 3.5 "Communication" submenu

The **Communication** submenu contains all parameters needed to configure the HART communication interface.

### 3.5.1 Structure of the submenu

*Navigation*

◀ ▶ Expert → Communication



### 3.5.2 "Diagnostic configuration" submenu

This submenu is used to allocate a status according to NAMUR recommendation NE107 to individual error messages. This applies to the following error messages:

- In safety dist.
- Echo lost
- AD occured (if an advanced diagnostics has been activated.)

Navigation

Expert → Communication → Diag. config.

#### Configuration via local display

1.

../Communication  
▶ Diag. config.  
▶ Configuration  
▶ Information

A0030197-EN

Go to the **Diag. config.** submenu.

2.

../Diag. config. 65535-1  
Diag. safety dist  
Out of spec. (S)  
Diagn. echo lost  
Stat. AD event1

A0030198-EN

Select an error message.

3.

../Diag. safety dis. 65535-1  
Mainten. reg.(M)  
Funct. check (C)  
✓ Out of spec. (S)  
No effect (N)

A0030199-EN

Select a status according to NE107.

### Configuration via FieldCare

1. Go to the **Diag. config.** submenu.

2.

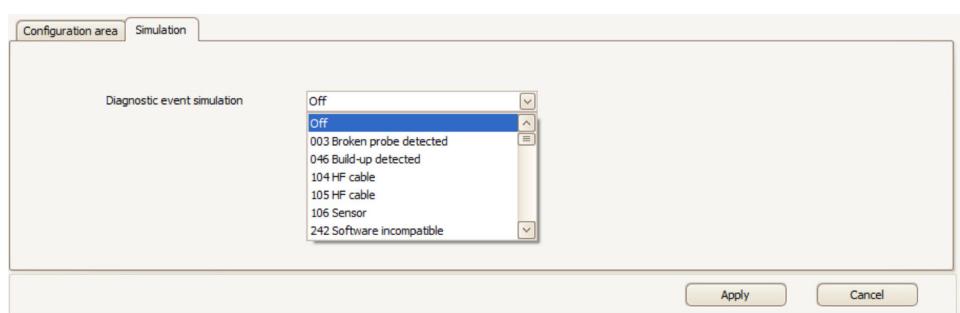
Diagnostic Event	Failure	Function check	Out of specification	Maintenance required	No effect
Diagnostics echo lost	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Diagnostic in safety distance	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>
Assign status signal to AD event 1 ...	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>

Apply

Cancel

Mark the desired behavior of the individual error messages in the table and click "Apply" to confirm your selection.

3.



Apply

Cancel

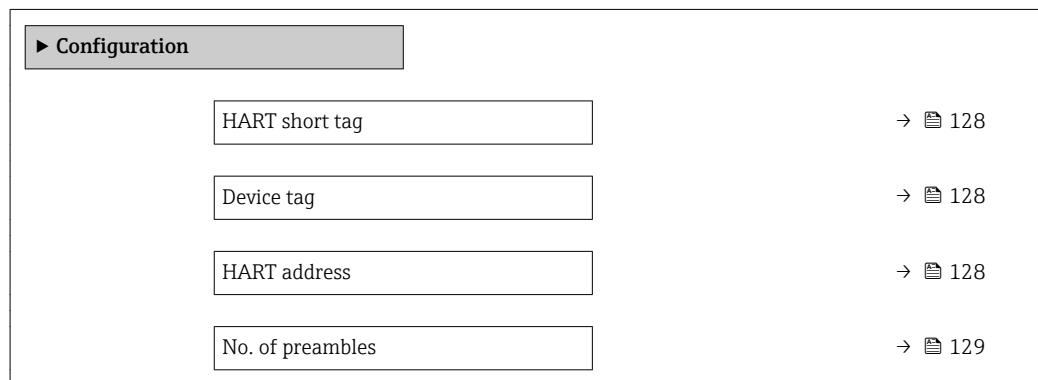
Error messages can be simulated in the "Simulation" dialog in order to check the correct behavior.

### 3.5.3 "Configuration" submenu

#### Structure of the submenu

Navigation

Diagram Expert → Communication → Configuration



**Description of parameters***Navigation*

Expert → Communication → Configuration

**HART short tag****Navigation**

Expert → Communication → Configuration → HART short tag (0220)

**Description**

Defines the short tag for the measuring point. Maximum length: 8 characters Allowed characters: A-Z, 0-9, certain special characters.

**User entry**

Max. 8 characters: A-Z, 0-9 and certain special characters (e.g. punctuation marks, @, %).

**Factory setting**

SHORTTAG

**Additional information**

Read access	Operator
Write access	Maintenance

**Device tag****Navigation**

Expert → Communication → Configuration → Device tag (0215)

**Description**

Enter a unique name for the measuring point to identify the device quickly within the plant.

**Factory setting**

FMR6x

**HART address****Navigation**

Expert → Communication → Configuration → HART address (0219)

**Description**

Define HART address of the device.

**User entry**

0 to 63

**Factory setting**

0

**Additional information**

- Measured value transmission via the current value is only possible for address "0". For any other address the current is fixed at 4.0 mA (multidrop mode).
- For a system according to HART 5.0 possible addresses are 0 to 15.
- For a system according to HART 6.0 possible addresses are 0 to 63.

Read access	Operator
Write access	Maintenance

---

**No. of preambles**

**Navigation** Expert → Communication → Configuration → No. of preambles (0217)

**Description** Number of preambles in the HART telegram.

**User entry** 5 to 20

**Factory setting** 5

**Additional information**

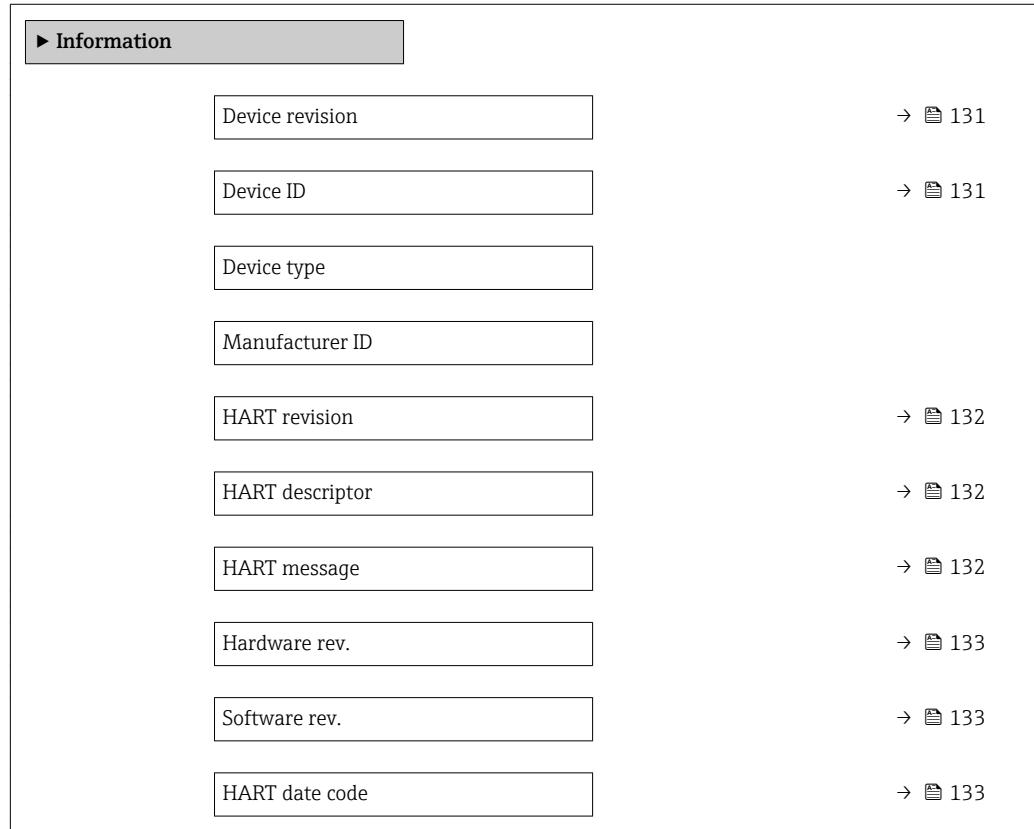
Read access	Operator
Write access	Maintenance

### 3.5.4 "Information" submenu

#### Structure of the submenu

*Navigation*

☰ ☰ Expert → Communication → Information



### Description of parameters

Navigation

Diagram Expert → Communication → Information

---

## Device revision

---

**Navigation**

Diagram Expert → Communication → Information → Device revision (0204)

**Description**

For registration with HART Communic. Foundation.

**Additional information**

The device revision is used to allocate the correct Device Description file (DD) to the device.

Read access	Operator
Write access	-

---

## Device ID

---

**Navigation**

Diagram Expert → Communication → Information → Device ID (0221)

**Description**

For identifying the device in a HART network.

**Additional information**

In addition to the Device type and Manufacturer ID, the Device ID is part of the unique device identification (Unique ID) which characterizes each HART device unambiguously.

Read access	Operator
Write access	-

---

## Device type

---

**Navigation**

Diagram Expert → Communication → Information → Device type (0209)

**Description**

For registration with HART Communic. Foundation.

**Additional information**

Der Gerätetyp wird benötigt, um dem Gerät die passende Gerätebeschreibungsdatei (DD) zuzuordnen.

Lesezugriff	Operator
Schreibzugriff	-

---

**Manufacturer ID**

---

**Navigation**   Expert → Communication → Information → Manufacturer ID (0259)

**Description** For registration with HART Communic. Foundation.

**User interface** 2-digit hexadecimal number

**Factory setting** 0x11 (for Endress+Hauser)

**Additional information**

Read access	Operator
Write access	-

---

**HART revision**

---

**Navigation**   Expert → Communication → Information → HART revision (0205)

**Description** Indicates HART revision of the device.

**Additional information**

Read access	Operator
Write access	Maintenance

---

**HART descriptor**

---



**Navigation**   Expert → Communication → Information → HART descriptor (0212)

**Description** Descriptor for the measuring point.

**Factory setting** FMR6x

**Additional information**

Read access	Operator
Write access	Maintenance

---

**HART message**

---



**Navigation**   Expert → Communication → Information → HART message (0216)

**Description** HART message which is sent via the HART protocol if requested by the master.

**Factory setting** FMR6x

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

**Hardware rev.****Navigation**
 Expert → Communication → Information → Hardware rev. (0206)
**Description**

Indicates hardware revision of the device.

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	-

**Software rev.****Navigation**
 Expert → Communication → Information → Software rev. (0224)
**Description**

Indicates software revision of the device.

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	-

**HART date code****Navigation**
 Expert → Communication → Information → HART date code (0202)
**Description**

Date of the last configuration change

**Additional information**

Datum format: YYYY-MM-DD

 It is essential to use this datum format. Otherwise some HART commands will not function correctly.

<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

### 3.5.5 "Burst config. 1 to 3" submenu

#### Structure of the submenu

*Navigation*

Expert → Communication → Burst config. 1 to 3

► Burst config. 1 to 3	
Burst mode 1 to 3	→ 134
Burst command 1 to 3	→ 135
Burst variable 0...7	→ 135
Trigger mode	→ 136
Trigger level	→ 137
Min. upd. per.	→ 137
Max. upd. per.	→ 137

#### Description of parameters

*Navigation*

Expert → Communication → Burst config. 1 to 3

#### Burst mode



**Navigation**

Expert → Communication → Burst config. 1 to 3 → Burst mode 1 to 3 (2032–1 to 3)

**Description**

Switch HART burst mode for burst message on.

**Selection**

- Off
- On

**Factory setting**

Off

**Additional information**

Read access	Operator
Write access	Maintenance

**Burst command**

**Navigation** Expert → Communication → Burst config. 1 to 3 → Burst command 1 to 3 (2031-1 to 3)

**Description** Select the command that is sent to the HART master.

**Selection**

- Primary var (PV)
- Loop Cur./%Range
- Dynamic Variable
- Dev.Vari w.statu
- Device Variables
- Add. Dev. Status

**Factory setting** Loop Cur./%Range

**Additional information**

Read access	Operator
Write access	Maintenance

**Burst variable 0...3**

**Navigation** Expert → Communication → Burst config. 1 to 3 → Burst variable 0 (2033)

**Prerequisite** **Burst command (→ 135) = Dev.Vari w.statu or "Device Variables" option**

**Description** Command 9, 33: assign a variable to burst variable.

**Selection**

- Level linearized
- Distance
- Terminal volt.
- Electronic temp.
- Abs. echo ampl.
- Relat.echo ampl.
- Area incoupling
- Abs. EOP ampl.
- Analog out. AD 1
- Analog out. AD 2
- Not used
- Percent of range
- Measur. curr.
- Primary var (PV)
- Second.var(SV)
- Tertiary var(TV)
- Quaterna.var(QV)

**Factory setting** Not used

**Additional information**

Read access	Operator
Write access	Maintenance

**Burst variable 4...7****Navigation**

Expert → Communication → Burst config. 1 to 3 → Burst variable 4 (2037)

**Prerequisite**

**Burst command (→ 135) = Dev.Vari w.statu**

**Description**

Command 33: assign a variable to burst variable.

**Selection**

- Level linearized
- Distance
- Terminal volt.
- Electronic temp.
- Abs. echo ampl.
- Relat.echo ampl.
- Area incoupling
- Abs. EOP ampl.
- Analog out. AD 1
- Analog out. AD 2
- Not used
- Percent of range
- Measur. curr.
- Primary var (PV)
- Second.var(SV)
- Tertiary var(TV)
- Quaterna.var(QV)

**Factory setting**

Not used

**Additional information**

Read access	Operator
Write access	Maintenance

**Trigger mode****Navigation**

Expert → Communication → Burst config. 1 to 3 → Trigger mode (2044-1 to 3)

**Description**

Select the event that triggers the burst message.

**Selection**

- Continuous
- Window
- Rising
- Falling
- On change

**Factory setting**

Continuous

**Additional information**

Read access	Operator
Write access	Maintenance

---

Trigger level 

**Navigation**  Expert → Communication → Burst config. 1 to 3 → Trigger level (2043–1 to 3)

**Prerequisite** **Trigger mode** (→  136) = **Window, Rising or Falling**

**Description** Define point of time when burst message is sent.

**User entry** Signed floating-point number

**Factory setting** 2.0E-38

**Additional information**

Read access	Operator
Write access	Maintenance

---

Min. upd. per. 

**Navigation**  Expert → Communication → Burst config. 1 to 3 → Min. upd. per. (2042–1 to 3)

**Description** Min. time span between 2 responses of one message.

**User entry** Positive integer

**Factory setting** 1 000 ms

**Additional information**

Read access	Operator
Write access	Maintenance

---

Max. upd. per.

**Navigation**  Expert → Communication → Burst config. 1 to 3 → Max. upd. per. (2041–1 to 3)

**Prerequisite** **Trigger mode** (→  136) = **Rising, Falling or On change**

**Description** Max. time span between 2 responses of one message.

**User entry** Positive integer

**Factory setting** 2 000 ms

**Additional information**

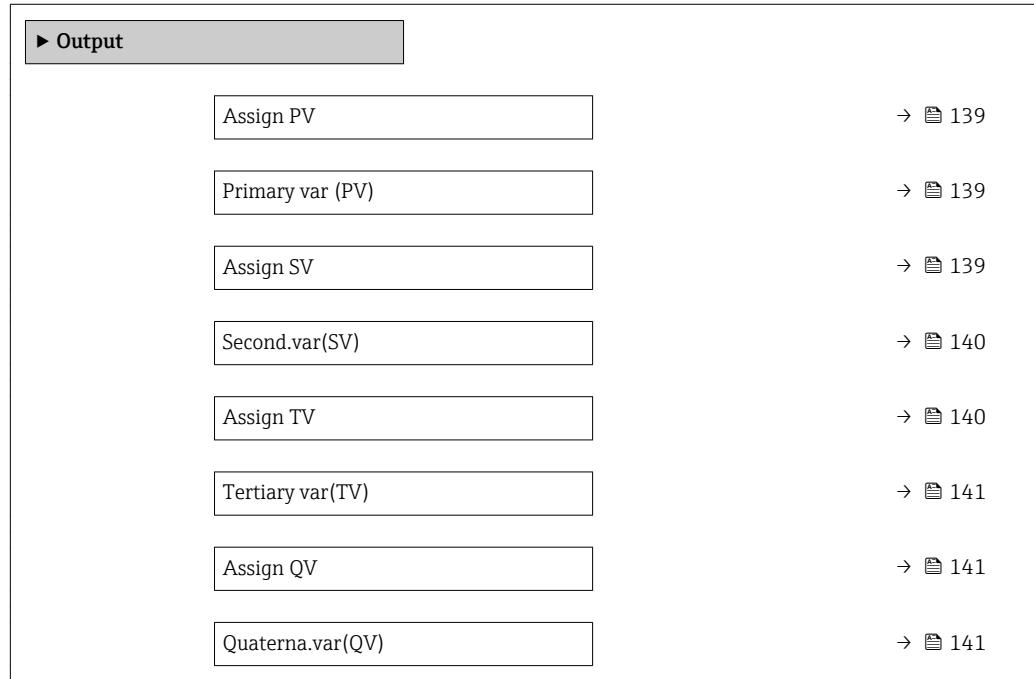
Read access	Operator
Write access	Maintenance

### 3.5.6 "Output" submenu

#### Structure of the submenu

Navigation

Expert → Communication → Output



**Description of parameters***Navigation*
 Expert → Communication → Output
**Assign PV****Navigation**
 Expert → Communication → Output → Assign PV (0234)
**Selection**

- Level linearized
- Distance
- Electronic temp.
- Relat.echo ampl.
- Area incoupling
- Analog out. AD 1
- Analog out. AD 2
- Analog out. AD 3
- Analog out. AD 4

**Factory setting**

Level linearized

**Additional information**

Read access	Operator
Write access	Maintenance

**Primary var (PV)****Navigation**
 Expert → Communication → Output → Primary var (PV) (0201)
**Description**

Displays primary HART variable (PV).

**Additional information**

Read access	Operator
Write access	-

**Assign SV****Navigation**
 Expert → Communication → Output → Assign SV (0235)
**Description**

Select measuring variable for secondary HART variable (SV).

**Selection**

- Level linearized
- Distance
- Terminal volt.
- Electronic temp.
- Abs. echo ampl.
- Abs. EOP ampl.
- Relat.echo ampl.
- Area incoupling

- Analog out. AD 1
- Analog out. AD 2
- Analog out. AD 3
- Analog out. AD 4
- Not used

**Factory setting**

Distance

**Additional information**

Read access	Operator
Write access	Maintenance

**Second.var(SV)****Navigation**
 Expert → Communication → Output → Second.var(SV) (0226)
**Description**

Displays secondary HART variable (SV).

**Additional information**

Read access	Operator
Write access	-

**Assign TV****Navigation**
 Expert → Communication → Output → Assign TV (0236)
**Description**

Select measuring variable for third HART variable (TV).

**Selection**

- Level linearized
- Distance
- Terminal volt.
- Electronic temp.
- Abs. echo ampl.
- Abs. EOP ampl.
- Relat.echo ampl.
- Area incoupling
- Analog out. AD 1
- Analog out. AD 2
- Analog out. AD 3
- Analog out. AD 4
- Not used

**Factory setting**

Abs. echo ampl.

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Tertiary var(TV)**

---

**Navigation**
 Expert → Communication → Output → Tertiary var(TV) (0228)
**Description**

Displays third HART variable (TV).

**Additional information**

Read access	Operator
Write access	-

---

**Assign QV**

---

**Navigation**
 Expert → Communication → Output → Assign QV (0237)
**Description**

Select measuring variable for fourth HART variable (QV).

**Selection**

- Level linearized
- Distance
- Terminal volt.
- Electronic temp.
- Abs. echo ampl.
- Abs. EOP ampl.
- Relat.echo ampl.
- Area incoupling
- Analog out. AD 1
- Analog out. AD 2
- Analog out. AD 3
- Analog out. AD 4
- Not used

**Factory setting**

Relat.echo ampl.

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Quaterna.var(QV)**

---

**Navigation**
 Expert → Communication → Output → Quaterna.var(QV) (0203)
**Description**

Displays fourth HART variable (QV).

**Additional information**

Read access	Operator
Write access	-

## 3.6 "Diagnostics" submenu

### 3.6.1 Structure of the submenu on the local display

Navigation

☰ ☰ Expert → Diagnostics

▶ Diagnostics	
Actual diagnos.	→ ☰ 144
Prev.diagnostics	→ ☰ 144
Time fr. restart	→ ☰ 145
Operating time	→ ☰ 145
▶ Diagnostic list	→ ☰ 146
▶ Event logbook	→ ☰ 148
▶ Device info	→ ☰ 151
▶ Data logging	→ ☰ 155
▶ Min/max val.	→ ☰ 159
▶ Simulation	→ ☰ 165
▶ Device check	→ ☰ 170
▶ Adv.diagn. 1 to 2	→ ☰ 180
▶ Envelope diag.	→ ☰ 190

### 3.6.2 Structure of the submenu in an operating tool

Navigation

◀ ▶ Expert → Diagnostics

▶ Diagnostics	
Actual diagnos.	→ 144
Timestamp	→ 144
Prev.diagnostics	→ 144
Timestamp	→ 145
Time fr. restart	→ 145
Operating time	→ 145
▶ Diagnostic list	→ 146
▶ Event logbook	→ 148
▶ Device info	→ 151
▶ Data logging	→ 155
▶ Min/max val.	→ 159
▶ Simulation	→ 165
▶ Device check	→ 170
▶ Adv.diagn. 1 to 2	→ 180
▶ Envelope diag.	→ 190

### 3.6.3 Description of parameters

*Navigation*

  Expert → Diagnostics

---

#### Actual diagnos.

**Navigation**

  Expert → Diagnostics → Actual diagnos. (0691)

**Description**

Displays current diagnostic message.

**Additional information**

The display consists of:

- Symbol for event behavior
- Code for diagnostic behavior
- Operating time of occurrence
- Event text

 If several messages are active at the same time, the messages with the highest priority is displayed.

 Information on what is causing the message, and remedy measures, can be viewed via the  symbol on the display.

Read access	Operator
Write access	-

---

#### Timestamp

**Navigation**

 Expert → Diagnostics → Timestamp (0667)

**Description**

Timestamp for the current diagnostic message.

**Additional information**

Read access	Operator
Write access	-

---

#### Prev.diagnostics

**Navigation**

  Expert → Diagnostics → Prev.diagnostics (0690)

**Description**

Displays the last diagnostic message which has been active before the current message.

**Additional information**

The display consists of:

- Symbol for event behavior
- Code for diagnostic behavior
- Operating time of occurrence
- Event text

 The condition displayed may still apply. Information on what is causing the message, and remedy measures, can be viewed via the  symbol on the display.

<b>Read access</b>	Operator
<b>Write access</b>	-

---

**Timestamp**

---

**Navigation**  Expert → Diagnostics → Timestamp (0672)**Description** Timestamp of the previous diagnostic message.**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	-

---

**Time fr. restart**

---

**Navigation**   Expert → Diagnostics → Time fr. restart (0653)**Description** Displays the time the device has been in operation since the last device restart.**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	-

---

**Operating time**

---

**Navigation**   Expert → Diagnostics → Operating time (0652)**Description** Indicates how long device has been in operation.**Additional information** *Maximum time*

9 999 d ( ≈ 27 years)

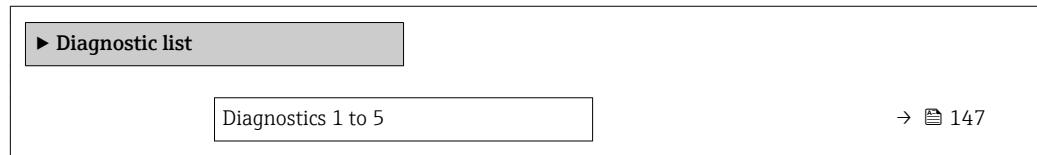
<b>Read access</b>	Operator
<b>Write access</b>	-

### 3.6.4 "Diagnostic list" submenu

Structure of the submenu on the local display

Navigation

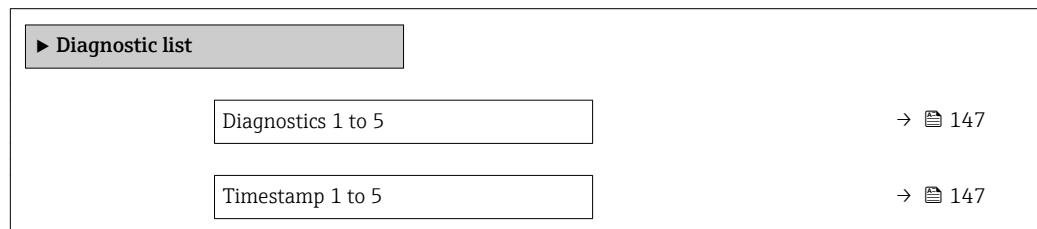
☰ ☰ Expert → Diagnostics → Diagnostic list



Structure of the submenu in an operating tool

Navigation

☰ ☰ Expert → Diagnostics → Diagnostic list



### Description of parameters

Navigation

Diagram Expert → Diagnostics → Diagnostic list

---

## Diagnostics 1 to 5

---

**Navigation**

Diagram Expert → Diagnostics → Diagnostic list → Diagnostics 1 (0692)

**Description**

Display the current diagnostics messages with the highest to fifth-highest priority.

**Additional information**

The display consists of:

- Symbol for event behavior
- Code for diagnostic behavior
- Operating time of occurrence
- Event text

Read access	Operator
Write access	-

---

## Timestamp 1 to 5

---

**Navigation**

Diagram Expert → Diagnostics → Diagnostic list → Timestamp (0683)

**Description**

Timestamp of the diagnostic message.

**Additional information**

Read access	Operator
Write access	-

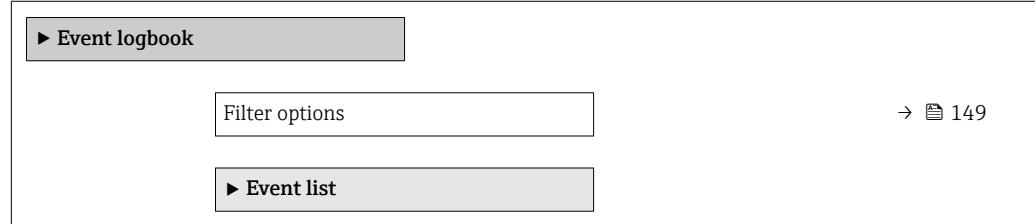
### 3.6.5 "Event logbook" submenu

Structure of the submenu on the local display

*Navigation*



Expert → Diagnostics → Event logbook



**Description of parameters***Navigation*

Expert → Diagnostics → Event logbook

**Filter options****Navigation**

Expert → Diagnostics → Event logbook → Filter options (0705)

**Description**

Define category of messages shown in Events list.

**Selection**

- All
- Failure (F)
- Funct. check (C)
- Out of spec. (S)
- Mainten. req.(M)
- Information (I)

**Factory setting**

All

**Additional information**

- This parameter is only used for operation via the local display.
- The status signals are categorized according to NAMUR NE 107.

Read access	Operator
Write access	Maintenance

### "Event list" submenu

 The **Event list** submenu (→ 150) is only available when operating via the local display.

The **Event list** submenu doesn't contain any parameters but only the list of events of the category selected in the **Filter options** parameter. A maximum of 100 event messages is displayed in chronological order.

The following status symbols indicate, whether an event has appeared or disappeared at the time stated:

- : Event appeared
- : Event disappeared

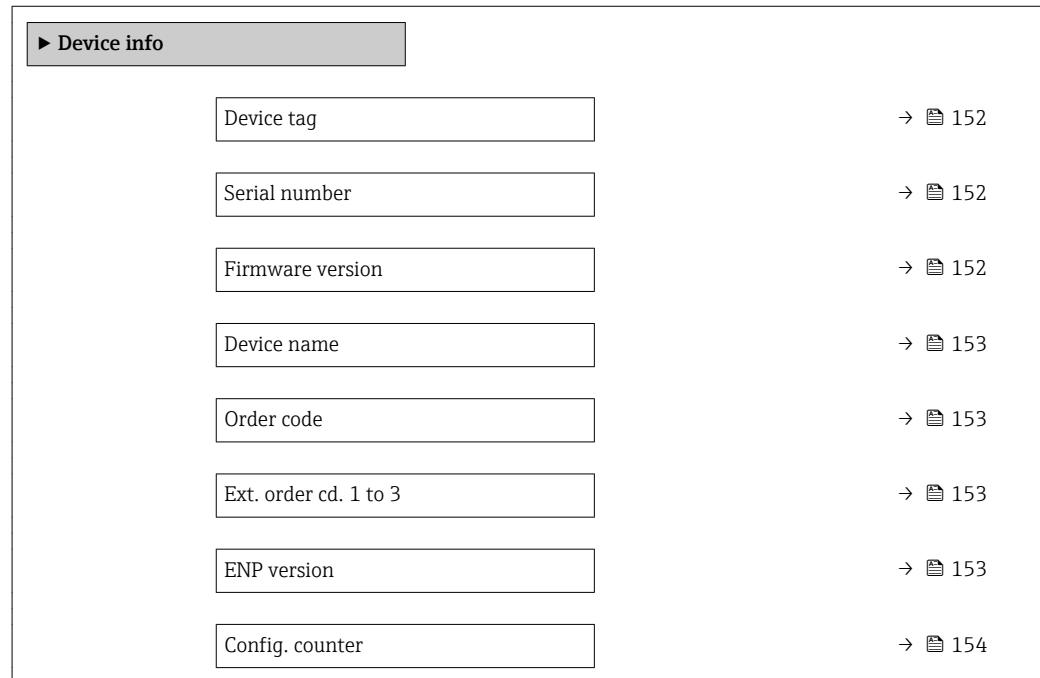
 Remedy measures concerning the cause of the message can be called up via the  symbol on the display.

### 3.6.6 "Device info" submenu

#### Structure of the submenu

*Navigation*

Diagram Expert → Diagnostics → Device info



### Description of parameters

Navigation

Expert → Diagnostics → Device info

#### Device tag

Navigation

Expert → Diagnostics → Device info → Device tag (0011)

Description

Enter the name for the measuring point.

Factory setting

FMR6x

Additional information

Read access	Operator
Write access	-

#### Serial number

Navigation

Expert → Diagnostics → Device info → Serial number (0009)

Description

Shows the serial number of the measuring device.

Additional information

 **Uses of the serial number**

- To identify the device quickly, e.g. when contacting Endress+Hauser.
- To obtain specific information on the device using the Device Viewer:  
[www.endress.com/deviceviewer](http://www.endress.com/deviceviewer)

 The serial number is also indicated on the nameplate.

Read access	Operator
Write access	-

#### Firmware version

Navigation

Expert → Diagnostics → Device info → Firmware version (0010)

Description

Shows the device firmware version installed.

User interface

xx.yy.zz

Additional information

 For firmware versions differing only in the last two digits ("zz") there is no difference concerning functionality or operation.

Read access	Operator
Write access	-

---

**Device name**

---

**Navigation**
 Expert → Diagnostics → Device info → Device name (0013)
**Description**

Shows the name of the transmitter.

**Additional information**

Read access	Operator
Write access	-

---

**Order code**

---

**Navigation**
 Expert → Diagnostics → Device info → Order code (0008)
**Description**

Shows the device order code.

**Additional information**

The order code is generated from the extended order code, which defines all device features of the product structure. In contrast, the device features can not be read directly from the order code.

Read access	Operator
Write access	Service

---

**Ext. order cd. 1 to 3**

---

**Navigation**
 Expert → Diagnostics → Device info → Ext. order cd. 1 (0023)
**Description**

Display the three parts of the extended order code.

**Additional information**

The extended order code indicates the version of all the features of the product structure and thus uniquely identifies the device.

Read access	Operator
Write access	Service

---

**ENP version**

---

**Navigation**
 Expert → Diagnostics → Device info → ENP version (0012)
**Description**

Shows the version of the electronic nameplate.

**User interface**

xx.yy.zz

**Additional information**

Read access	Operator
Write access	-

---

**Config. counter**

---

**Navigation** Expert → Diagnostics → Device info → Config. counter (0233)**Description**

Displays configuration counter.

**Additional information**

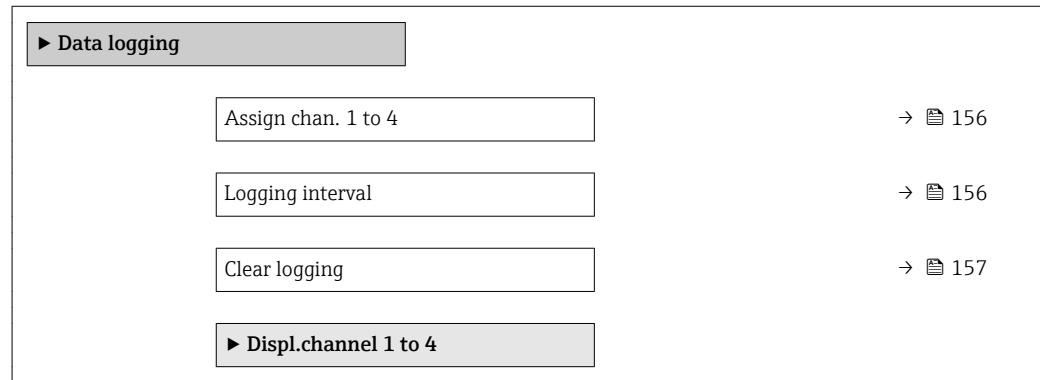
Read access	Operator
Write access	-

### 3.6.7 "Data logging" submenu

#### Structure of the submenu on the local display

*Navigation*

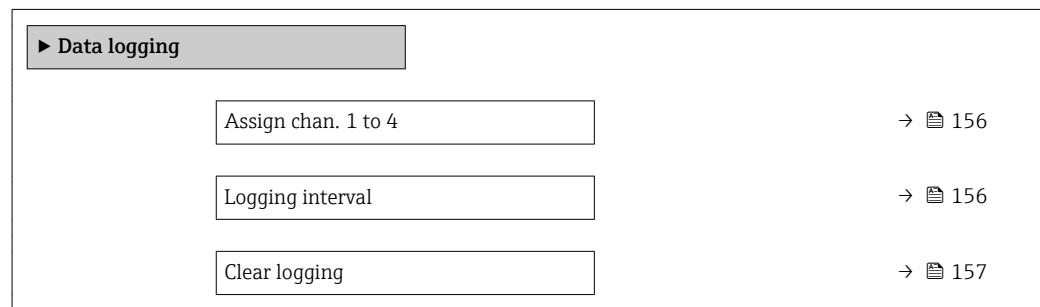
◀ ▶ Expert → Diagnostics → Data logging



#### Structure of the submenu in an operating tool

*Navigation*

◀ ▶ Expert → Diagnostics → Data logging



## Description of parameters

*Navigation*

Expert → Diagnostics → Data logging

### Assign chan. 1 to 4



**Navigation**

Expert → Diagnostics → Data logging → Assign chan. 1 (0851)

**Description**

Assign a process variable to logging channel.

**Selection**

- Off
- Level linearized
- Distance
- Curr.output 1
- Measur. curr.
- Curr.output 2 \*
- Terminal volt.
- Electronic temp.
- Analog out. AD 1
- Analog out. AD 2
- Analog out. AD 3
- Analog out. AD 4

**Factory setting**

Off

**Additional information**

A total of 1000 measured values can be logged. This means:

- 1000 data points if 1 logging channel is used
- 500 data points if 2 logging channels are used
- 333 data points if 3 logging channels are used
- 250 data points if 4 logging channels are used

If the maximum number of data points is reached, the oldest data points in the data log are cyclically overwritten in such a way that the last 1000, 500, 333 or 250 measured values are always in the log (ring memory principle).

The logged data are deleted if a new option is selected in this parameter.

Read access	Operator
Write access	Maintenance

### Logging interval



**Navigation**

Expert → Diagnostics → Data logging → Logging interval (0856)

Expert → Diagnostics → Data logging → Logging interval (0856)

**Description**

Defines the logging interval for data logging.

**User entry**

1.0 to 3 600.0 s

\* Visibility depends on order options or device settings

**Factory setting** 30.0 s

**Additional information** This parameter defines the interval between the individual data points in the data log, and thus the maximum loggable process time  $T_{\log}$ :

- If 1 logging channel is used:  $T_{\log} = 1000 \cdot t_{\log}$
- If 2 logging channels are used:  $T_{\log} = 500 \cdot t_{\log}$
- If 3 logging channels are used:  $T_{\log} = 333 \cdot t_{\log}$
- If 4 logging channels are used:  $T_{\log} = 250 \cdot t_{\log}$

Once this time elapses, the oldest data points in the data log are cyclically overwritten such that a time of  $T_{\log}$  always remains in the memory (ring memory principle).

 The logged data are deleted if this parameter is changed.

*Example*

**When using 1 logging channel**

- $T_{\log} = 1000 \cdot 1 \text{ s} = 1000 \text{ s} \approx 16.5 \text{ min}$
- $T_{\log} = 1000 \cdot 10 \text{ s} = 10000 \text{ s} \approx 2.75 \text{ h}$
- $T_{\log} = 1000 \cdot 80 \text{ s} = 80000 \text{ s} \approx 22 \text{ h}$
- $T_{\log} = 1000 \cdot 3600 \text{ s} = 3600000 \text{ s} \approx 41 \text{ d}$

Read access	Operator
Write access	Maintenance

---

## Clear logging



**Navigation**

- Expert → Diagnostics → Data logging → Clear logging (0855)
- Expert → Diagnostics → Data logging → Clear logging (0855)

**Description** Clear the entire logging data.

**Selection**

- Cancel
- Clear data

**Factory setting** Cancel

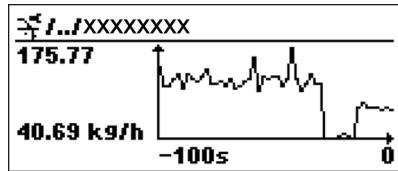
**Additional information**

Read access	Operator
Write access	Maintenance

**"Displ.channel 1 to 4" submenu**

**i** The **Displ.channel 1 to 4** submenu is only available when operating via the local display. When operating via FieldCare, the diagram can be displayed in the "Event List / HistoROM" function.

The **Displ.channel 1 to 4** submenu displays the measured value trend of the respective logging channel.



- x-axis: displays 125 to 500 measured values of a process variable (the number of values depending on the number of selected channels).
- y-axis: displays the approximate measured value span and constantly adapts this to the ongoing measurement.

**i** To quit the diagram and to return to the operating menu, press **⊕** and **⊖** simultaneously.

### 3.6.8 "Min/max val." submenu

#### Structure of the submenu

*Navigation*

☰ ☰ Expert → Diagnostics → Min/max val.

► Min/max val.	
Max. level value	→ ☰ 160
Time max. level	→ ☰ 160
Min. level value	→ ☰ 160
Time min. level	→ ☰ 160
Max.drain.speed	→ ☰ 161
Max. fill. speed	→ ☰ 161
Reset min/max	→ ☰ 161
Max.electr.temp.	→ ☰ 161
Time max.el.temp	→ ☰ 162
Min.electr.temp.	→ ☰ 162
Time min.el.temp	→ ☰ 162
Res.min/max temp	→ ☰ 162

### Description of parameters

**Navigation**

Expert → Diagnostics → Min/max val.

---

## Max. level value

---

**Navigation**

Expert → Diagnostics → Min/max val. → Max. level value (2357)

**Description**

Displays maximum level measured in the past.

**Additional information**

Read access	Operator
Write access	-

---

## Time max. level

---

**Navigation**

Expert → Diagnostics → Min/max val. → Time max. level (2385)

**Description**

Displays operating time at which the maximum level has been obtained.

**Additional information**

Read access	Operator
Write access	-

---

## Min. level value

---

**Navigation**

Expert → Diagnostics → Min/max val. → Min. level value (2358)

**Description**

Displays minimum level measured in the past.

**Additional information**

Read access	Operator
Write access	-

---

## Time min. level

---

**Navigation**

Expert → Diagnostics → Min/max val. → Time min. level (2386)

**Description**

Displays operating time at which the minimum level has been obtained.

**Additional information**

Read access	Operator
Write access	-

---

**Max.drain.speed**

---

**Navigation**
 Expert → Diagnostics → Min/max val. → Max.drain.speed (2320)
**Description**

Displays maximum draining speed measured in the past.

**Additional information**

Read access	Operator
Write access	-

---

**Max. fill. speed**

---

**Navigation**
 Expert → Diagnostics → Min/max val. → Max. fill. speed (2360)
**Description**

Displays maximum filling speed measured in the past.

**Additional information**

Read access	Operator
Write access	-

---

**Reset min/max**

---

**Navigation**
 Expert → Diagnostics → Min/max val. → Reset min/max (2324)
**Description**

Select which min/max values are to be reset.

**Selection**

- None
- Drain/fill speed
- Level
- Reset all

**Factory setting**

None

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Max.electr.temp.**

---

**Navigation**
 Expert → Diagnostics → Min/max val. → Max.electr.temp. (12506)
**Description**

Displays maximum electronics temperature measured in the past.

**Additional information**

Read access	Operator
Write access	-

---

**Time max.el.temp**

---

**Navigation**  Expert → Diagnostics → Min/max val. → Time max.el.temp (12507)**Description**

Displays operating time at which the maximum electronics temperature has been obtained.

**Additional information**

Read access	Operator
Write access	-

---

**Min.electr.temp.**

---

**Navigation**  Expert → Diagnostics → Min/max val. → Min.electr.temp. (12508)**Description**

Displays minimum electronics temperature measured in the past.

**Additional information**

Read access	Operator
Write access	-

---

**Time min.el.temp**

---

**Navigation**  Expert → Diagnostics → Min/max val. → Time min.el.temp (12509)**Description**

Displays operating time at which the minimum electronics temperature has been obtained.

**Additional information**

Read access	Operator
Write access	-

---

**Res.min/max temp**

---

**Navigation**  Expert → Diagnostics → Min/max val. → Res.min/max temp (12510)**Description**

Select which min/max values are to be reset.

**User interface**

- None
- Electronic temp.
- Reset all

**Factory setting**

None

**Additional information**

<b>Read access</b>	Operator
<b>Write access</b>	Service

### 3.6.9 "Simulation" submenu

The **Simulation** submenu is used to simulate specific measuring values or other conditions. This helps to check the correct configuration of the device and connected control units.

*Conditions which can be simulated*

Condition to be simulated	Associated parameters
Specific value of a process variable	<ul style="list-style-type: none"><li>▪ Assign meas.var. (→ 166)</li><li>▪ Proc. var. value (→ 166)</li></ul>
Specific value of the output current	<ul style="list-style-type: none"><li>▪ Curr.out. sim. (→ 166)</li><li>▪ Value curr.out (→ 167)</li></ul>
Specific state of the switch output	<ul style="list-style-type: none"><li>▪ Switch sim. (→ 167)</li><li>▪ Switch status (→ 168)</li></ul>
Existence of an alarm	Dev. alarm sim. (→ 168)

**Structure of the submenu***Navigation*

Expert → Diagnostics → Simulation

<b>► Simulation</b>	
Assign meas.var.	→  166
Proc. var. value	→  166
Curr.out. 1 to 2 sim.	→  166
Value curr.out 1 to 2	→  167
Switch sim.	→  167
Switch status	→  168
Dev. alarm sim.	→  168

## Description of parameters

Navigation

Expert → Diagnostics → Simulation

### Assign meas.var.



Navigation

Expert → Diagnostics → Simulation → Assign meas.var. (2328)

Selection

- Off
- Level
- Level linearized

Factory setting

Off

Additional information

- The value of the variable to be simulated is defined in the **Proc. var. value** parameter (→ [166](#)).
- If **Assign meas.var. ≠ Off**, a simulation is active. This is indicated by a diagnostic message of the *Function check (C)* category.

Read access	Maintenance
Write access	Maintenance

### Proc. var. value



Navigation

Expert → Diagnostics → Simulation → Proc. var. value (2329)

Prerequisite

**Assign meas.var. (→ [166](#)) ≠ Off**

User entry

Signed floating-point number

Factory setting

0

Additional information

Downstream measured value processing and the signal output use this simulation value. In this way, users can verify whether the measuring device has been configured correctly.

Read access	Operator
Write access	Maintenance

### Curr.out. 1 to 2 sim.



Navigation

Expert → Diagnostics → Simulation → Curr.out. 1 to 2 sim. (0354-1 to 2)

Description

Switch simulation of the current output on and off.

Selection

- Off
- On

**Factory setting** Off

**Additional information** An active simulation is indicated by a diagnostic message of the *Function check (C)* category.

Read access	Operator
Write access	Maintenance

## Value curr.out 1 to 2



**Navigation** Expert → Diagnostics → Simulation → Value curr.out 1 to 2 (0355-1 to 2)

**Prerequisite** Curr.out. sim. (→ 166) = On

**Description** Defines the value of the simulated output current.

**User entry** 3.59 to 22.5 mA

**Factory setting** 3.59 mA

**Additional information** The current output assumes the value specified in this parameter. In this way, users can verify the correct adjustment of the current output and the correct function of connected control units.

Read access	Operator
Write access	Maintenance

## Switch sim.



**Navigation** Expert → Diagnostics → Simulation → Switch sim. (0462)

**Description** Switch simulation of the switch output on and off.

**Selection**

- Off
- On

**Factory setting** Off

**Additional information**

Read access	Operator
Write access	Maintenance

---

**Switch status****Navigation**

Expert → Diagnostics → Simulation → Switch status (0463)

**Prerequisite****Switch sim. (→ 167) = On****Description**

Current status of the switch output.

**Selection**

- Open
- Closed

**Factory setting**

Open

**Additional information**

The switch status assumes the value defined in this parameter. This helps to check correct operation of connected control units.

Read access	Operator
Write access	Maintenance

---

**Dev. alarm sim.****Navigation**

Expert → Diagnostics → Simulation → Dev. alarm sim. (0654)

**Description**

Switch the device alarm on and off.

**Selection**

- Off
- On

**Factory setting**

Off

**Additional information**When selecting the **On** option, the device generates an alarm. This helps to check the correct output behavior of the device in the case of an alarm.An active simulation is indicated by the diagnostic message **XC484 Failure mode sim.**

Read access	Operator
Write access	Maintenance

---

**Diag. event sim.****Navigation**

Expert → Diagnostics → Simulation → Diag. event sim. (0737)

**Description**

Select the diagnostic event to be simulated. Note: To terminate the simulation, select 'Off'.

**Factory setting**

Off

**Additional information**When operated via the local display, the selection list can be filtered according to the event categories (**Event category** parameter).

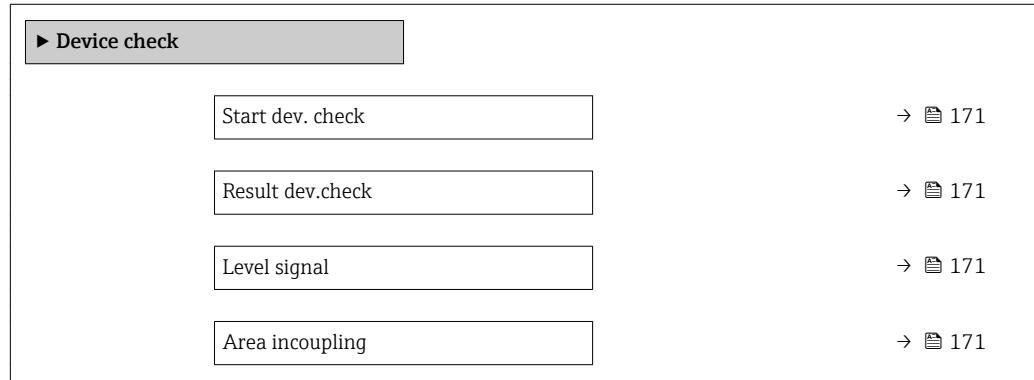
<b>Read access</b>	Operator
<b>Write access</b>	Maintenance

### 3.6.10 "Device check" submenu

#### Structure of the submenu

Navigation

☰ ☰ Expert → Diagnostics → Device check



**Description of parameters****Navigation**
  Expert → Diagnostics → Device check
**Start dev. check****Navigation**
  Expert → Diagnostics → Device check → Start dev. check (12481)
**Description**

Yes option starts a device check.

**Selection**

- No
- Yes

**Factory setting**

No

**Additional information**

Read access	Operator
Write access	Maintenance

**Result dev.check****Navigation**
  Expert → Diagnostics → Device check → Result dev.check (12482)
**Additional information**

Read access	Operator
Write access	-

**Level signal****Navigation**
  Expert → Diagnostics → Device check → Level signal (12483)
**Description**

Shows the result of the device check for the level signal.

**Additional information**

Read access	Operator
Write access	-

**Area incoupling****Navigation**
  Expert → Diagnostics → Device check → Area incoupling (12525)
**Description**

Indicates the area of the ringing signal.

**Additional information**

Read access	Operator
Write access	-

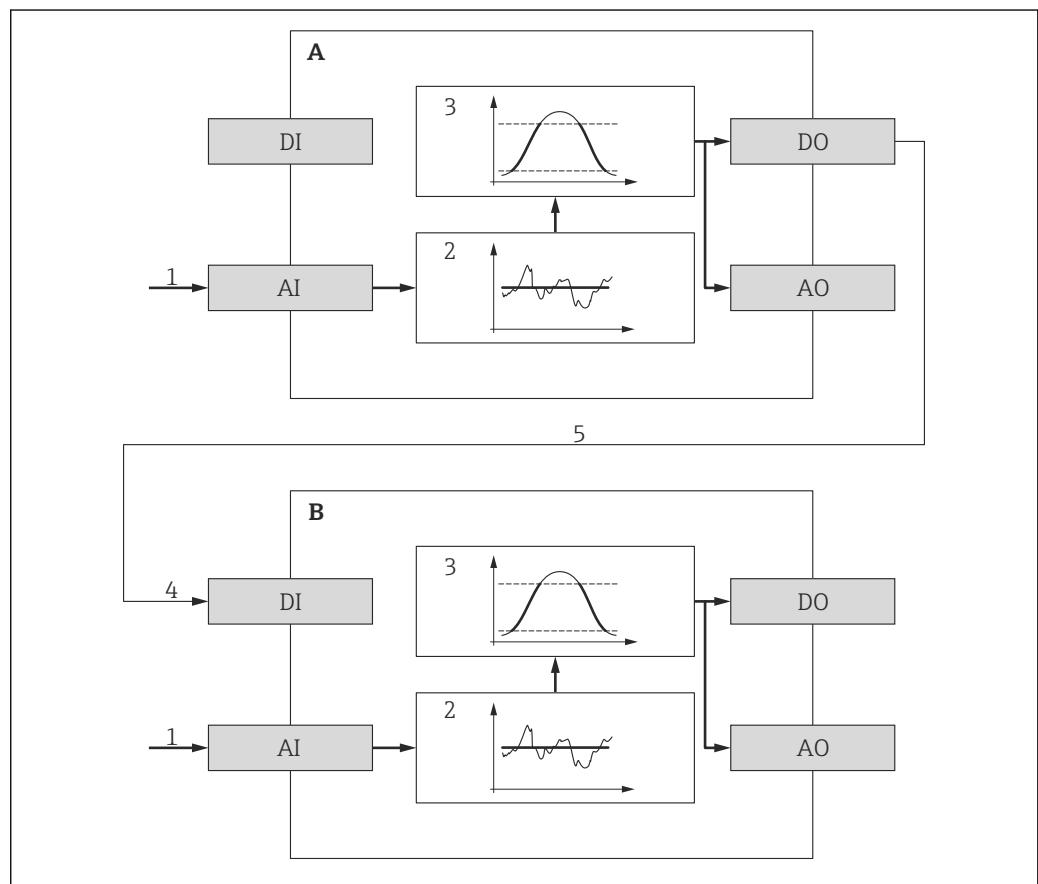
### 3.6.11 "Adv.diagn. 1 to 4" submenu

#### Mode of operation

The Advanced Diagnostics offers additional options to monitor the process. The device contains four Advanced Diagnostic Blocks which can be used separately or in combination.

A measuring variable can be assigned to the input of each Advanced Diagnostic Block. Based on a freely configurable time interval, the variable can be submitted to a statistical function (e.g. maximum, minimum, mean, slope). Finally, a limit detection can be parametrized and its result can be transmitted to a digital output.

The result can be displayed and evaluated by a DCS or PLC. If required, it can also be linked to another Advanced Diagnostic block and thus it is possible to combine the two results by the logical operators AND or OR.



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Fig. 38 Combined Advanced Diagnostic blocks

- A Advanced Diagnsotics 1
- B Advanced Diagnsotics 2
- AI Analog input of the respective block
- DI Digital input of the respective block
- AO Analog output of the respective block
- DO Digital output of the respective block
- 1 Analog process variable
- 2 Statistical calculation (maximum, minimum, mean, slope)
- 3 Limit check
- 4 Digital input of AD2
- 5 Digital output of AD1 is linked to digital input of AD2

## Overview of the Advanced Diagnostic functionalities

Task	Associated parameters
Allocation of a process variable to the analog input of the block.	Assign signal (→ 181)
Linking the digital input to the digital output of the other block.	<ul style="list-style-type: none"> <li>▪ Link AD to (→ 181)</li> <li>▪ Link. logic AD (→ 182)</li> </ul>
Calculation of one of the following quantities for a freely configurable sampling interval: <ul style="list-style-type: none"> <li>▪ Maximum</li> <li>▪ Minimum</li> <li>▪ Mean</li> <li>▪ Std. deviation</li> <li>▪ Diff.Max. - Min.</li> <li>▪ Slope</li> </ul>	<ul style="list-style-type: none"> <li>▪ Sample time (→ 182)</li> <li>▪ Calc. type (→ 182)</li> <li>▪ Calc. unit (→ 184)</li> </ul>
Drag indicator for the calculated quantity	<ul style="list-style-type: none"> <li>▪ Maximum value (→ 186)</li> <li>▪ Minimum value (→ 187)</li> <li>▪ Reset min/max (→ 187)</li> </ul>
Limit check	<ul style="list-style-type: none"> <li>▪ Check mode (→ 183)</li> <li>▪ Upper limit (→ 185)</li> <li>▪ Lower limit (→ 185)</li> <li>▪ Hysteresis (→ 186)</li> </ul>
Reaction in case of a limit violation	<ul style="list-style-type: none"> <li>▪ Application (→ 187)</li> <li>▪ Stat. AD event (→ 188)</li> <li>▪ Evt behaviour (→ 188)</li> <li>▪ Alarm delay (→ 189)</li> </ul>

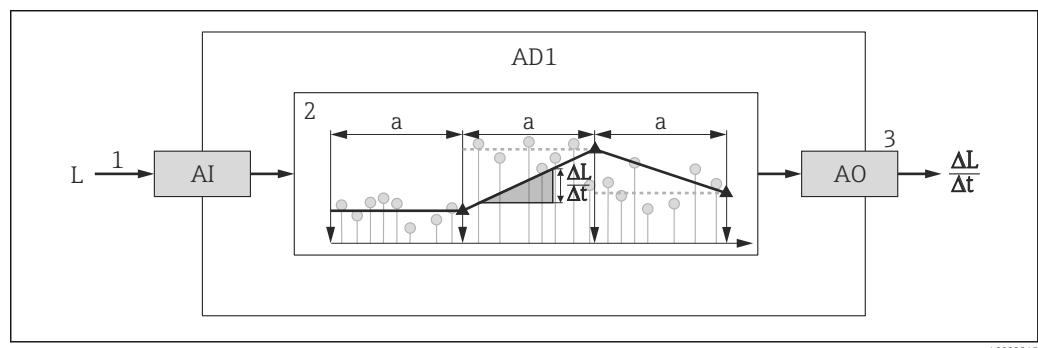
### Example 1: Draining/filling speed

**i** Only one Advanced Diagnostic Block is needed for this application. In the example this is **Adv.diagn. 1**.

The level change rate (i.e. draining or filling speed) allows the customer to instantly realize whether or not the level is changing, and at which rate. The rate at which the level is changing must be observed as powerful pumps can create significant over and underpressure in a tank. Pressure relieve valves can only operate properly up to a certain level change rate. This is in particular valid for almost emptied tanks. The level change rate is also an intermediate result for calculating transfer estimates, such as time to fill, time to empty, time to target, etc.

#### Basic idea

The Advanced Diagnostics is used to calculate the draining or filling speed from the measured level. The result can be transmitted via the current output or the HART communication interface.



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**Fig. 39** Calculation of the draining or filling speed

- 1 Allocation of the (linearized) level to Advanced Diagnostic Block AD1
- 2 Calculation of the draining or filling speed  $\Delta L/\Delta t$  within the sampling interval  $a$ .
- 3  $\Delta L/\Delta t$  can be transmitted via the current output or the HART communication interface.

#### Configuration of the calculation

The calculation of the rate of level change is configured as follows:

1. Select **Assign signal 1 = Level linearized**.
2. Define **Sample time 1** in accordance with the expected draining or filling speed.
3. Select **Calc. type 1 = Slope**.
4. Select a suitable option in **Calc. unit 1**, e.g.: "**Level unit**" / s

**i** As the rate of level change is not to be checked for limit violation, the following parameters may retain their factory settings:  

- **Check mode 1**
- **Stat. AD event** (→ **Fig. 188**)
- **Evt behaviour** (→ **Fig. 188**)
- **Alarm delay** (→ **Fig. 189**)

**i** With this configuration, the **Maximum value 1** and **Minimum value 1** drag indicators display the maximum or minimum value the rate of level change has obtained. Positive values indicate filling (rising level), negative values indicate draining (falling level). If required, the drag indicators can be reset by the **Reset min/max 1** parameter.

*Allocation of the calculated rate of level change to the current output*

1. Navigate to the following submenu: Expert → Output → Curr.output 1.
2. Select **Assign curr.** (→ 110) = **Analog out. AD 1.**
3. Select **Turn down** (→ 113) = **On.**
4. Enter maximum expected draining speed (negative value) in **4 mA value** (→ 114).
5. Enter maximum expected filling speed (positive value) in **20 mA value** (→ 114).

With this configuration, the rate of level change is transmitted via the current output. The relationship between the rate of level change and the output current is as follows:

$$\frac{\Delta L}{\Delta t} = \frac{5W_4 - W_{20}}{4} + \frac{W_{20} - W_4}{16 \text{ mA}} I$$

A0022342

Where:

- $\Delta L/\Delta t$  : Rate of level change <sup>5)</sup>
- $W_4$  : **4 mA value** (→ 114)
- $W_{20}$  : **20 mA value** (→ 114)
- I: Output current

In the case of a constant level ( $\Delta L/\Delta t = 0$ ) the current is:

$$I_0 = 4 \text{ mA} - \frac{W_4}{W_{20} - W_4} 16 \text{ mA}$$

A0022343

*Allocation of the calculated rate of level change to the HART output*

1. Navigate to the following submenu: Expert → Communication → Output
  2. Select **Assign PV** (→ 139) = **Analog out. AD 1.**
- i** With this configuration, the **Primary var (PV)** parameter (→ 139) displays the calculated filling or draining speed. Positive values indicate filling; negative values indicate draining.
- i** Instead of PV, it is also possible to allocate the rate of level change to SV, TV or QV.

5) Negative values: draining speed; Positive values: filling speed

### Example 2: Foam detection

**i** For devices with Heartbeat Monitoring functionality, the foam detection can be configured by the corresponding wizard in FieldCare, DeviceDare, PACTware or a DTM based process control system. In this case all settings described below are automatically performed by the wizard.

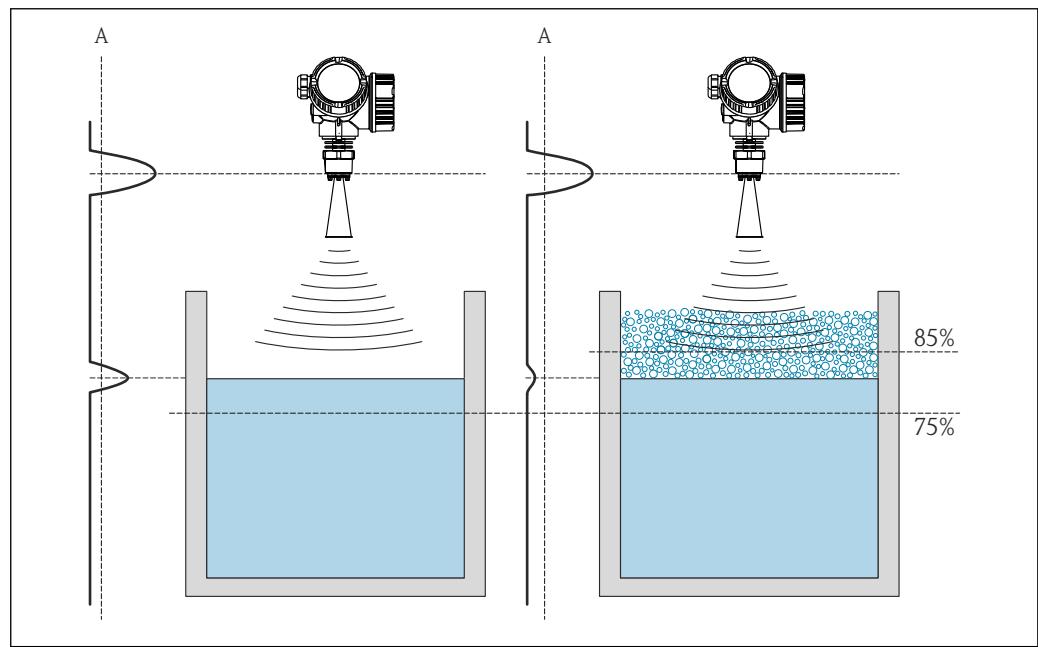
**i** Two Advanced Diagnostic Blocks are required for this application. In the example **Adv.diagn. 1** and **Adv.diagn. 2** are used.

#### Preconditions

- The process runs at a fixed level (in the example: 80 %)
- If foam occurs during the operation, the vessel should automatically be sprinkled with water from the top or an antifoam agent should be added to dissolve the foam.

#### Basic idea

The echo amplitude decreases in the case of foam formation. This can be used by the Advanced Diagnostics to detect the foam. The foam detection, however, should only be active as long as the level is between 75 % and 85 %.



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**40 Decrease of the amplitude in case of foam formation**

A Amplitude threshold for foam detection

#### Configuration of the level monitoring

In order to ensure that the level is within the correct range, configure the **Adv.diagn. 1** submenu ( $\rightarrow$  180) submenu as follows:

1. Navigate to the **Adv.diagn. 1** submenu ( $\rightarrow$  180)
2. Select **Assign signal 1 = Level linearized**.
3. Select **Check mode 1 = Out of range**
4. Set **Upper limit 1 = 85 %**.
5. Set **Lower limit 1 = 75 %**.

**i** **Check mode 1 = Out of range** checks whether the level is outside a defined range. As long as this is the case, the block outputs "0" (INACTIVE). If the level gets into the defined range, the block outputs "1" (ACTIVE).

*Configuration of the foam detection*

For the foam detection, configure the **Adv.diagn. 2** submenu (→ 180) as follows:

1. Select **Assign signal 2 = Relat.echo ampl.**
2. Use the **Minimum value 2** parameter to observe the echo amplitude for the specified level (80 % in the example) for a while and determine a suitable lower limit for the amplitude (10 dB in the example).
3. Select **Calc. type 2 = Mean**.
4. Enter **Sample time 2 = "60 s"**.
5. Select **Check mode 2 = Lower limit**.
6. Enter the amplitude limit determined in step 2 into the **Lower limit 2** parameter (10 dB in the example).

- i** With these settings, the Advanced Diagnostic Block behaves as follows:
  - If the amplitude is above 10 dB (i.e.: no foam), the block assumes the digital value "0" (INACTIVE).
  - If the amplitude is below 10 dB (i.e.: foam present), the block assumes the digital value "1" (ACTIVE).

*Configuration of the block linking*

The linking logic is configured in the **Adv.diagn. 2** submenu (→ 180):

1. Select **Link AD 2 to = Digital out AD 1**.
2. Select **Link. logic AD 2 = AND**.

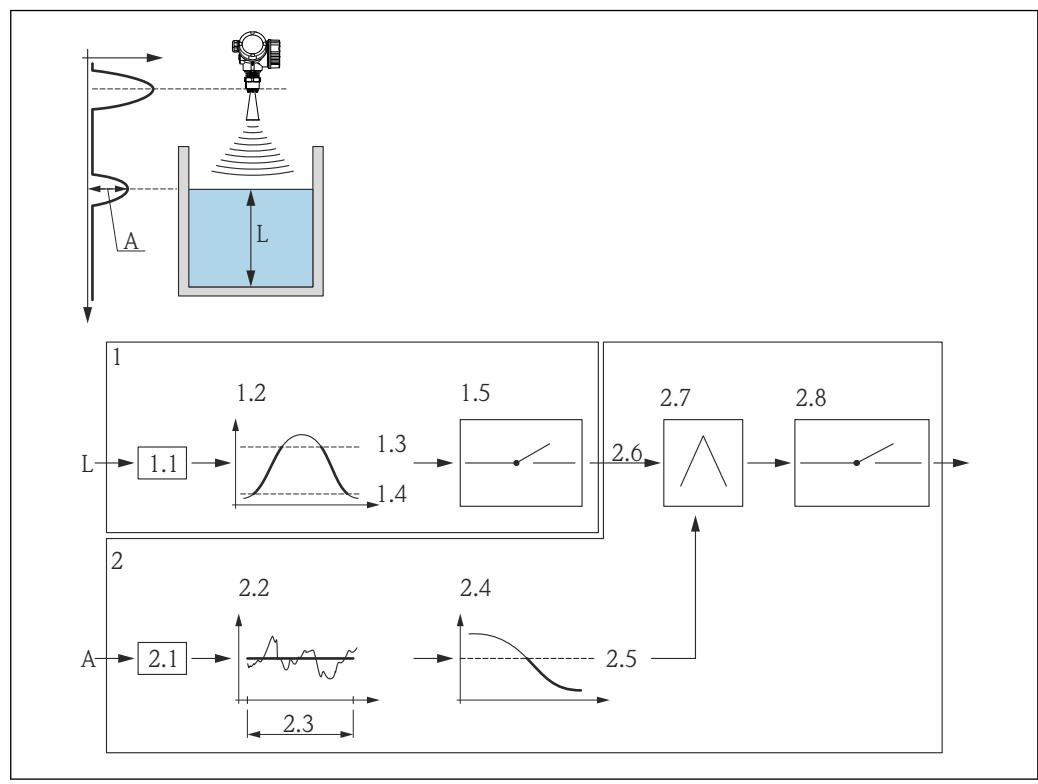
- i** With this configuration the output of **Advanced Diagnostics 2** assumes the following value:
  - 0 (INACTIVE) - if at least one of the two blocks is in the "0" (INACTIVE) status.
  - 1 (ACTIVE) - if both blocks are in the "1" (ACTIVE) status.

For the example this means:

- A diagnostic signal is output, if the level is within the defined range and the signal amplitude is below the threshold (i.e. foam is present).
- If, on the other hand, the level is out of the defined range or if the signal amplitude exceeds the threshold (i.e. no foam), **no** diagnostic signal is transmitted via the switch output.

- i** The digital output signal of **Adv.diagn. 2** can be linked to the switch output of the device:

Expert → Output → Switch output → Assign status (0485) = Digital out AD 2

*Overview: Foam detection with the advanced diagnostics*

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**Fig. 41 Configuration of the Advanced Diagnostics for foam detection** $L$  Level $A$  Amplitude

1 Advanced diagnostics 1: Monitoring the level

1.1 "Assign signal 1" = "Relat.echo ampl."

1.2 "Check mode 1" = "Out of range"

1.3 "Upper limit 1" = 85 %

1.4 "Lower limit 1" = 75 %

1.5 Digital output of Advanced Diagnostics 1

2 Advanced Diagnostics 2: Monitoring the amplitude

2.1 "Assign signal 2" = "Relat.echo ampl."

2.2 "Calc. type 2" = "Mean"

2.3 "Sample time 2" = 60 s

2.4 "Check mode 2" = "Lower limit"

2.5 "Lower limit 2" = 10 dB

2.6 "Link AD 2 to" = "Digital out AD 1"

2.7 "Link. logic AD 2" = "AND"

2.8 Digital output of Advanced Diagnostics 2

**Structure of the submenu***Navigation*  Expert → Diagnostics → Adv.diagn. 1 to 4

<b>► Adv.diagn. 1 to 4</b>	
Assign signal 1 to 4	→  181
Link AD 1 to 4 to	→  181
Link. logic AD 1 to 4	→  182
Sample time 1 to 4	→  182
Calc. type 1 to 4	→  182
Check mode 1 to 4	→  183
Calc. unit 1 to 4	→  184
Upper limit 1 to 4	→  185
Lower limit 1 to 4	→  185
Hysteresis 1 to 4	→  186
Value	→  186
Maximum value 1 to 4	→  186
Minimum value 1 to 4	→  187
Reset min/max 1 to 4	→  187
Application	→  187
Stat. AD event 1 to 4	→  188
Evt behaviour 1 to 4	→  188
Alarm delay 1 to 4	→  189

**Description of parameters***Navigation*
 Expert → Diagnostics → Adv.diagn. 1 to 2
**Assign signal 1 to 4****Navigation**
 Expert → Diagnostics → Adv.diagn. 1 to 4 → Assign signal 1 to 4 (11179–1 to 4)
**Description**

Allocate a measuring variable to the Advanced Diagnostic Block.

**Selection**

- None
- Level linearized
- Distance
- Unfiltered distance
- Electronic temperature
- Relative echo amplitude
- Absolute echo amplitude
- Noise of signal
- Measured current
- Terminal voltage

**Factory setting**

None

**Additional information**

Read access	Operator
Write access	Maintenance

**Link AD 1 to 4 to****Navigation**
 Expert → Diagnostics → Adv.diagn. 1 to 4 → Link AD 1 to 4 to (11180–1 to 4)
**Description**

Link the digital input (DI) of the Advanced Diagnostic Block to the digital output (DO) of the other Advanced Diagnostic Block.

**Selection**

- None
- Digital out AD 1
- Digital out AD 2
- Digital out AD 3
- Digital out AD 4

**Factory setting**

None

**Additional information**

Read access	Maintenance
Write access	Maintenance

**Link. logic AD 1 to 4****Navigation**

Expert → Diagnostics → Adv.diagn. 1 to 4 → Link. logic AD 1 to 4 (11181–1 to 4)

**Prerequisite**

**Link AD to (→ 181) ≠ None**

**Description**

Select linking logic between the two Advanced Diagnostic Blocks.

**Selection**

- AND
- OR

**Factory setting**

AND

**Additional information**

Read access	Operator
Write access	Maintenance

**Sample time 1 to 4****Navigation**

Expert → Diagnostics → Adv.diagn. 1 to 4 → Sample time 1 to 4 (11187–1 to 4)

**Prerequisite**

**Assign signal (→ 181) ≠ None**

**Description**

Specify sampling interval for the calculation.

**User entry**

1 to 3 600 s

**Factory setting**

10 s

**Additional information**

Read access	Operator
Write access	Maintenance

**Calc. type 1 to 4****Navigation**

Expert → Diagnostics → Adv.diagn. 1 to 4 → Calc. type 1 to 4 (11174–1 to 4)

**Prerequisite**

**Assign signal (→ 181) ≠ None**

**Description**

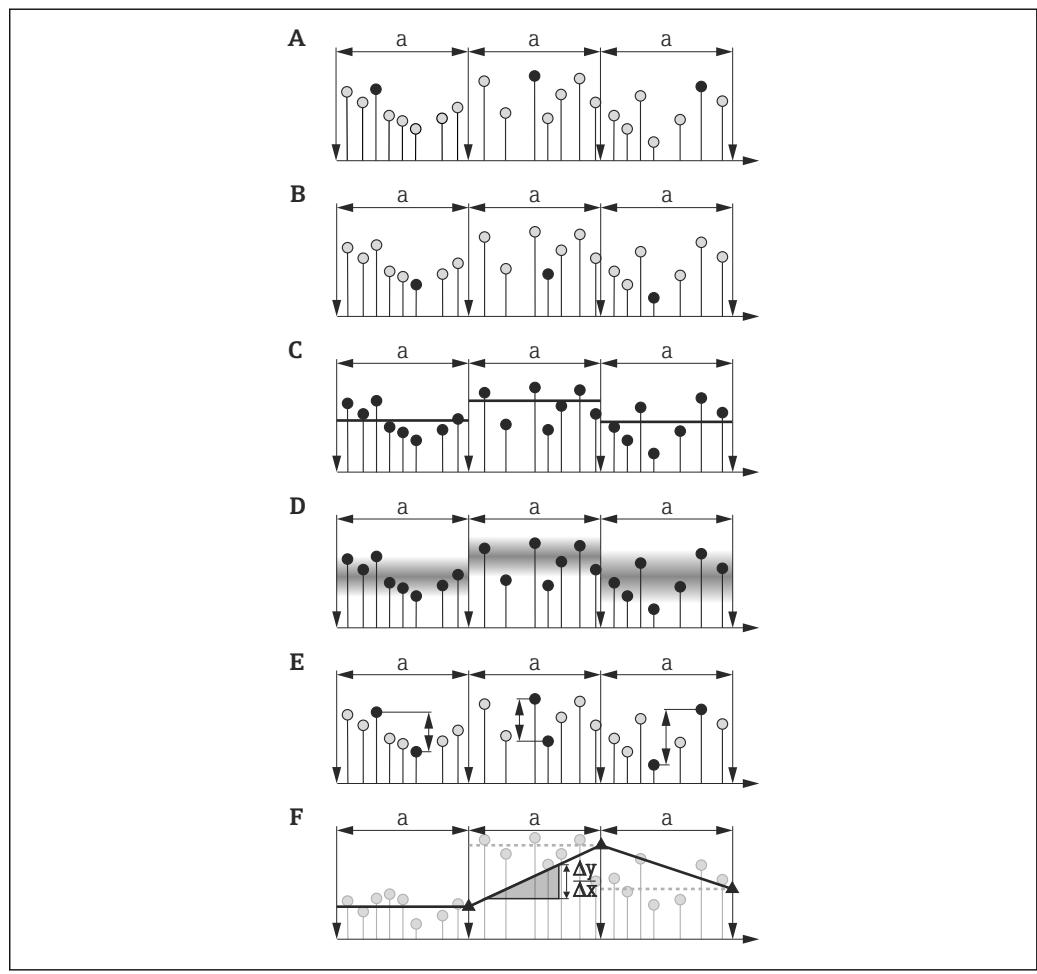
Select quantity to be calculated from the measured variable.

**Selection**

- Off
- Maximum
- Minimum
- Mean
- Std. deviation
- Diff.Max. - Min.
- Slope

**Factory setting**

Off

**Additional information**

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**Fig. 42 Options of the "Calc. type" parameter**

- a Sample time (→ 182)  
 A "Calc. type" = "Maximum"  
 B "Calc. type" = "Minimum"  
 C "Calc. type" = "Mean"  
 D "Calc. type" = "Std. deviation"  
 E "Calc. type" = "Diff.Max. - Min."  
 F "Calc. type" = "Slope"

**i** The calculation is performed based on the sampling interval defined in the **Sample time** parameter (→ 182).

Read access	Operator
Write access	Maintenance

**Check mode 1 to 4****Navigation**

Expert → Diagnostics → Adv.diagn. 1 to 4 → Check mode 1 to 4 (11175–1 to 4)

**Prerequisite**

Assign signal (→ 181) ≠ None

**Description**

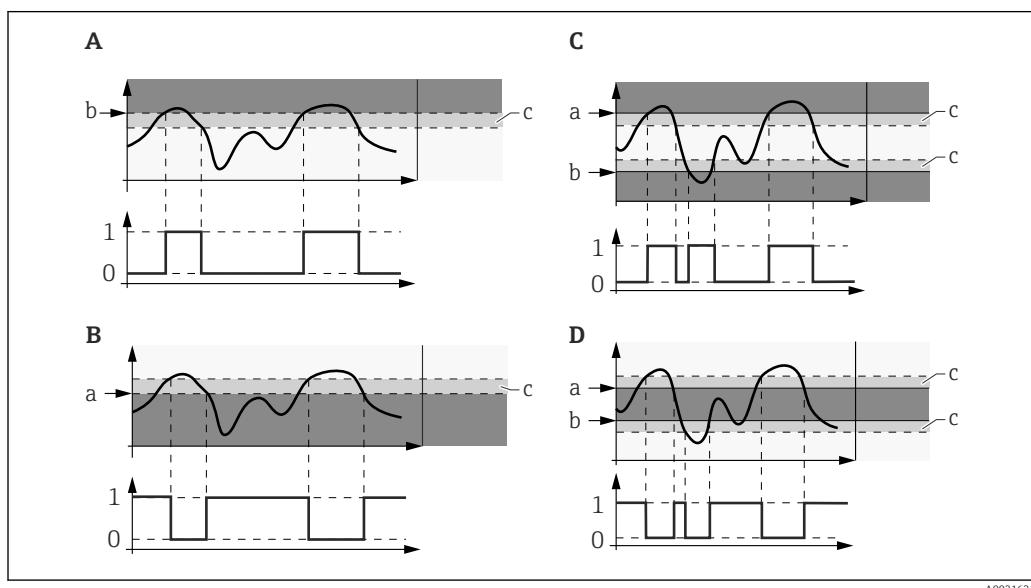
Define check mode for limit monitoring.

**Selection**

- Off
- Upper limit
- Lower limit
- In range
- Out of range

**Factory setting**

Off

**Additional information****Fig. 43 Limit monitoring in the Advanced Diagnostic Block**

- |   |  |
|---|--|
| 0 | Status of digital output: 0 ("INACTIVE") |
| 1 | Status of digital output: 1 ("ACTIVE")   |
| a | Upper limit (→ 185)                      |
| b | Lower limit (→ 185)                      |
| c | Hysteresis (→ 186)                       |
| A | "Check mode" = "Lower limit"             |
| B | "Check mode" = "Upper limit"             |
| C | "Check mode" = "In range"                |
| D | "Check mode" = "Out of range"            |

**i** If a calculation has been selected in the **Calc. type** parameter (→ 182), the check does not refer to the assigned measuring variable but to the quantity calculated from it.

Read access	Operator
Write access	Maintenance

**Calc. unit 1 to 4****Navigation**

Expert → Diagnostics → Adv.diagn. 1 to 4 → Calc. unit 1 to 4 (11188-1 to 4)

**Prerequisite**

Assign signal (→ 181) ≠ None

**Description**

Select unit for the calculation.

**Selection**

Dependent on the following parameters:

- Assign diagnostic signal (→ 181)
- Calculation type (→ 182)

**Factory setting**

Dependent on the following parameters:

- Assign diagnostic signal (→ 181)
- Calculation type (→ 182)

**Additional information**

Read access	Operator
Write access	Operator

**Upper limit 1 to 4****Navigation**

Expert → Diagnostics → Adv.diagn. 1 to 4 → Upper limit 1 to 4 (11182–1 to 4)

**Prerequisite**

**Check mode** parameter (→ 183) has one of the following values:

- Upper limit
- In range
- Out of range

**Description**

Specify upper limit for the limit monitoring.

**User entry**

Dependent on the following parameters:

- Assign diagnostic signal (→ 181)
- Calculation type (→ 182)

**Factory setting**

Dependent on the following parameters:

- Assign diagnostic signal (→ 181)
- Calculation type (→ 182)

**Additional information**

Read access	Operator
Write access	Maintenance

**Lower limit 1 to 4****Navigation**

Expert → Diagnostics → Adv.diagn. 1 to 4 → Lower limit 1 to 4 (11184–1 to 4)

**Prerequisite**

**Check mode** parameter (→ 183) has one of the following values:

- Lower limit
- In range
- Out of range

**Description**

Define lower limit for the limit monitoring.

**User entry**

Dependent on the following parameters:

- Assign diagnostic signal (→ 181)
- Calculation type (→ 182)

**Factory setting**

Dependent on the following parameters:

- Assign diagnostic signal (→ 181)
- Calculation type (→ 182)

**Additional information**

Read access	Operator
Write access	Maintenance

**Hysteresis 1 to 4****Navigation**

Expert → Diagnostics → Adv.diagn. 1 to 4 → Hysteresis 1 to 4 (11178–1 to 4)

**Prerequisite**

**Check mode** parameter (→ 183) has one of the following values:

- Upper limit
- Lower limit
- In range
- Out of range

**Description**

Select hysteresis for the limit monitoring.

**User entry**

Dependent on the following parameters:

- Assign diagnostic signal (→ 181)
- Calculation type (→ 182)

**Factory setting**

Dependent on the following parameters:

- Assign diagnostic signal (→ 181)
- Calculation type (→ 182)

**Additional information**

Read access	Operator
Write access	Maintenance

**Value****Navigation**

Expert → Diagnostics → Adv.diagn. 1 to 4 → Value (11172–1 to 4)

**Description**

Displays the current value of the calculated process variable.

**Additional information**

Read access	Operator
Write access	-

**Maximum value 1 to 4****Navigation**

Expert → Diagnostics → Adv.diagn. 1 to 4 → Maximum value 1 to 4 (11183–1 to 4)

**Prerequisite**

Assign signal (→ 181) ≠ None

**Description** Indicates the maximum value the assigned measuring variable has obtained in the past (drag indicator).

**Additional information**

Read access	Operator
Write access	-

### Minimum value 1 to 4

**Navigation** Expert → Diagnostics → Adv.diagn. 1 to 4 → Minimum value 1 to 4 (11185–1 to 4)

**Prerequisite** **Assign signal (→ 181) ≠ None**

**Description** Indicates minimum value the assigned measuring variable has obtained in the past (drag indicator).

**Additional information**

Read access	Operator
Write access	-

### Reset min/max 1 to 4



**Navigation** Expert → Diagnostics → Adv.diagn. 1 to 4 → Reset min/max 1 to 4 (11186–1 to 4)

**Prerequisite** **Assign signal (→ 181) ≠ None**

**Description** Reset drag indicators (**Maximum value (→ 186)** and/or **Minimum value (→ 187)**).

**Selection**

- Off
- Reset max.
- Reset min.
- Reset min/max

**Factory setting** Off

**Additional information**

Read access	Operator
Write access	Maintenance

### Application

**Navigation** Expert → Diagnostics → Adv.diagn. 1 to 4 → Application (11173–1 to 4)

**Description** Indicates whether the Advanced Diagnostic Block is used for foam or build-up detection.

**Selection**

- Std. application
- Foam detection
- Build-up detect.

**Factory setting** Std. application

**Additional information**



- If a foam or build-up detection has been configured via the Heartbeat wizards in FieldCare, DeviceCare, PACTware or a DTM based process-control system, this parameter is automatically set to the appropriate value.
- If a foam or build-up detection has been configured via the operating menu, this parameter must be manually set to the appropriate value.
- The setting of this parameter causes that the **Foam detected** or **Build-up detect.** diagnostic message is generated if foam or build-up is detected.

Read access	Maintenance
Write access	Operator

---

## Stat. AD event 1 to 4



**Navigation**

Expert → Diagnostics → Adv.diagn. 1 to 4 → Stat. AD event 1 to 4 (11176-1 to 4)

**Prerequisite**

**Assign signal (→ 181) ≠ None**

**Description**

Assign a category according to NAMUR NE107 to the event of the Advanced Diagnostic Block.

**Selection**

- Failure (F)
- Mainten. req.(M)
- Funct. check (C)
- Out of spec. (S)
- No effect (N)

**Factory setting**

Mainten. req.(M)

**Additional information**

Read access	Operator
Write access	Maintenance

---

## Evt behaviour 1 to 4



**Navigation**

Expert → Diagnostics → Adv.diagn. 1 to 4 → Evt behaviour 1 to 4 (11177-1 to 4)

**Prerequisite**

**Assign signal (→ 181) ≠ None**

**Description**

Assign an event behavior to the event of the Advanced Diagnostic Block.

**Selection**

- Off
- Alarm
- Warning
- Logbook only

**Factory setting**

Warning

**Additional information**

Read access	Operator
Write access	Maintenance

**Alarm delay 1 to 4**

**Navigation** Expert → Diagnostics → Adv.diagn. 1 to 4 → Alarm delay 1 to 4 (11171-1 to 4)

**Prerequisite** Assign signal (→ 181) ≠ None

**Description** Define alarm delay for the Advanced Diagnostic Block.

**User entry** 0.0 to 3 600.0 s

**Factory setting** 10.0 s

**Additional information**

Read access	Operator
Write access	Maintenance

### 3.6.12 "Envelope diag." submenu

After the configuration of the measurement it is recommended to record the current envelope curve as a reference curve. The reference curve can be used later for diagnostic purposes. To record the reference curve use the **Save ref. curve** parameter.

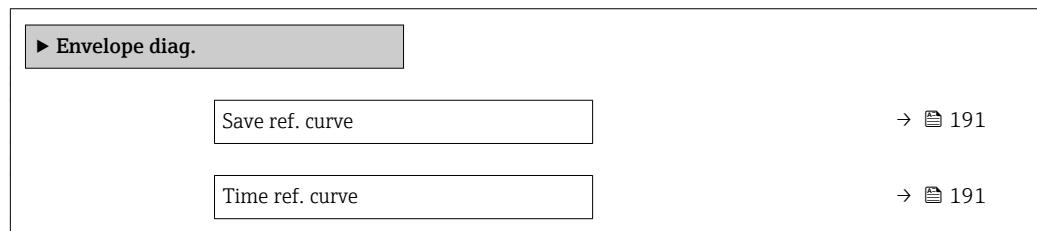
The reference curve can only be displayed in the envelope curve diagram of FieldCare after it has been loaded from the device into FieldCare. This is performed by the "Load Reference Curve" function in FieldCare:



#### Structure of the submenu

Navigation

Expert → Diagnostics → Envelope diag.



**Description of parameters***Navigation*  Expert → Diagnostics → Envelope diag.**Save ref. curve****Navigation**  Expert → Diagnostics → Envelope diag. → Save ref. curve (12513)**Description**

Save current envelope curve as reference curve in the device.

**Selection**

- No
- Yes

**Factory setting**

No

**Additional information****Meaning of the options**

- No  
No action
- Yes

The current envelope curve is saved as reference curve in the device.

Read access	Operator
Write access	Maintenance

---

**Time ref. curve****Navigation**  Expert → Diagnostics → Envelope diag. → Time ref. curve (12514)**Description**

Indicates at which time the existing reference curve has been recorded.

**Additional information**

Read access	Operator
Write access	-

## 4 Overview of information events

Info number	Info name
I1000	----- (Device ok)
I1089	Power on
I1090	Config. reset
I1091	Config. changed
I1092	Embedd.HistoROM
I1110	Prot.swit.chang.
I1137	Electr. changed
I1151	History reset
I1154	Res.v.min/max
I1155	Res.electr.temp.
I1156	Mem.error trend
I1157	Mem.err. ev.list
I1184	Disp.connected
I1185	Disp.backup done
I1186	Restore done
I1187	Set.downl. disp.
I1188	Disp.data clear.
I1189	Backup compared
I1256	Disp.stat.change
I1264	Safety seq.abort
I1335	Firmw. changed
I1397	Bus stat. change
I1398	CDI stat. change
I1512	Downl. started
I1513	Downl. finished
I1514	Upload started
I1515	Upload finished
I1554	Safety seq.start
I1555	Safety seq.conf.
I1556	Safety mode off

## 5 Overview of diagnostic events

Diagnostic number	Short text	Remedy instructions	Status signal [from the factory]	Diagnostic behavior [from the factory]
<b>Diagnostic of sensor</b>				
046	Build-up detect.	Clean sensor	F	Alarm <sup>1)</sup>
102	Sensor incompat	1. Restart device 2. Contact service	F	Alarm
151	SensorElectrFail	Replace sensor electronic module	F	Alarm
<b>Diagnostic of electronic</b>				
242	Software incomp.	1. Check SW 2. Flash or change main elect.module	F	Alarm
252	Modules incomp.	Check or change I/O or main electronic module	F	Alarm
261	Electr. modules	1. Restart device 2. Check or change electr.modules	F	Alarm
262	Module connect.	1. Check module conn. 2. Change elect. modules	F	Alarm
270	Main electronics	Change main electronic module	F	Alarm
271	Main electronics	1. Restart device 2. Change main electronic module	F	Alarm
272	Main electronics	1. Restart device 2. Contact service	F	Alarm
273	Main electronics	1. Use display backup 2. Change main elect.	F	Alarm
275	I/O defective	Change I/O module	F	Alarm
276	I/O faulty	1. Restart device 2. Change I/O module	F	Alarm
276	I/O module		F	Alarm
282	Data storage	1. Restart device 2. Contact service	F	Alarm
283	Memory content	1. Transfer data or reset device 2. Contact service	F	Alarm
311	Electr. failure	Maintenance req. 1. Don't reset 2. Contact service	M	Warning
<b>Diagnostic of configuration</b>				
410	Data transfer	1. Check connection 2. Retry data transfer	F	Alarm
411	Up-/download act	Up-/download active, please wait	C	Warning
412	Process. downl.	Download active, please wait	C	Warning
431	Trim 1 to 2	Carry out trim	C	Warning
435	Linearization	Check linearization table	F	Alarm
437	Config. incomp.	1. Restart device 2. Contact service	F	Alarm
438	Dataset	1. Check data set file 2. Check device config.	M	Warning
441	Curr.output 1 to 2	1. Check process 2. Check current output settings	S	Warning

Diagnostic number	Short text	Remedy instructions	Status signal [from the factory]	Diagnostic behavior [from the factory]
484	Failure mode sim	Deactivate simulation	C	Alarm
485	Simulation value	Deactivate simulation	C	Warning
491	Curr.out. 1 to 2 sim.	Deactivate simulation	C	Warning
494	Switch sim.	Deactivate simulation switch output	C	Warning
495	Diag. event sim.	Deactivate simulation	C	Warning
585	Sim distance	Deactivate simulation	C	Warning
586	Record map	Recording of mapping please wait	C	Warning
<b>Diagnostic of process</b>				
801	Energy too low	Increase supply voltage	S	Warning
803	Current loop	1. Check wiring 2. Change I/O module	F	Alarm
825	Operating temp.	1. Check ambient temp. 2. Check process temp.	S	Warning
825	Operating temp.		F	Alarm
921	Change of refer.	Check reference configuration, pressure, sensor	S	Warning
941	Echo lost	Check parameter 'DC value'	S	Warning <sup>1)</sup>
942	In safety dist.	1. Chk level 2. Chk safe dist 3. Reset self hold	S	Alarm <sup>1)</sup>
943	In blocking dist	Reduced accuracy Check level	S	Warning
950	AD 1 to 4 occured	Maintain your diagnostic event	M	Warning <sup>1)</sup>
952	Foam detected	Check process conditions	F	Alarm <sup>1)</sup>

1) Diagnostic behavior can be changed.

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