Ultrasonic Level Measurement watersonic FMU 100 (Z)

For level measurement in water treatment plants Designed for use in explosion hazardous areas



















The Watersonic FMU 100 (Z) package comprises the FMU 100 (Z) plug-in card, Monorack housing and sensor DU 100 (Z) or DU 101 (Z)

Nothing beats know-how

Application

The Watersonic FMU 100 (Z) ultrasonic measuring system is designed for non-contact measurement of water levels in drinking and wastewater treatment plants, pumping stations, drainage systems etc.. It comprises a plug-in FMU 100 (Z) card, Monorack housing for wall-mounting and sensor

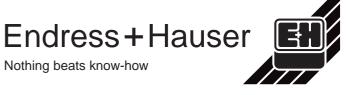
- DU 100 (Z) for range max. 9 m or
- DU 101 (Z) for range max. 15 m.

In addition to standard analogue outputs, three relays with freely selectable switch points are available for control of level and pump or valve sequences.



Features and Benefits

- · Economical stand-alone units for water applications with 0/4...20 mA, 0/2...10 V signal output and 3 relays.
- Rugged, seawater-proof sensor to IP 68 with one-piece diaphragm and seal: resistant to aggressive vapours and condensates.
- Continuous measurement of liquids in tanks, reservoirs, etc. of all shapes and sizes.
- Measurement independent of fluid properties (density, conductivity) and pressure.
- Self-monitoring with immediate indication of fault condition.
- Intrinsically safe Z-versions designed for [EEx ia] IIC applications. All versions with electrically isolated sensor circuit.

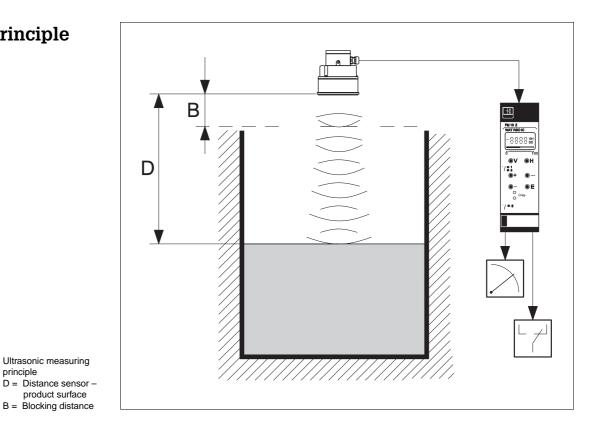


Measuring Principle

Ultrasonic measuring

product surface

principle



Ultrasonic Measurement

A sensor mounted above the product directs an ultrasonic pulse through the air towards the product surface.

The product surface partially or fully reflects the pulse back to the sensor. This echo is detected by the same sensor, now acting as a directional microphone, and converted into an electrical signal.

The time between transmission and reception of the pulse - the run time - is directly proportional to the distance between the sensor and the product surface. The distance D is determined from the velocity of sound c and the run time t by the formula:

 $D = c \cdot t/2$.

For C = 340 m/s, a run time of 10 ms corresponds to a transmission path of 3.4 m and thus to a distance of 1.7 m.

Measuring Range

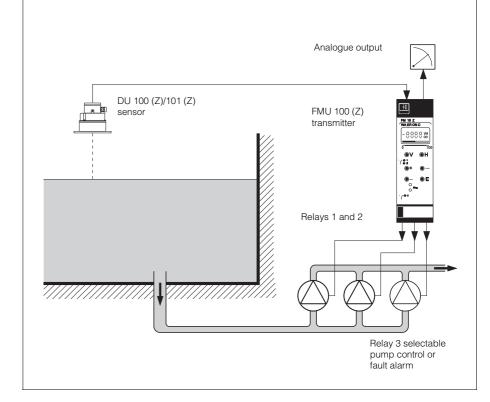
After the ultrasonic pulse has been emitted the sensor requires time - the ringing time - to stop vibrating. Consequently there is a zone immediately below the sensor from which returning echoes cannot be detected. This so-called blocking distance determines the start of the measuring range.

The end of the measuring range is determined by the attenuation of the ultrasonic pulse by the air as well as by the strength of the reflection from the product surface.

Performance

- The measurement is independent of product properties such as specific gravity, conductivity, viscosity and dielectric constant.
- The measurement is unaffected by changes in ambient temperature within the tank or well: the FMU 100 (Z) transmitter compensates by using the information delivered by the temperature sensor built into the DU 100 (Z)/101 (Z).
- Depending on the DU... sensor employed, the measuring range is up to 9 m or up to 15 m.

Measuring System



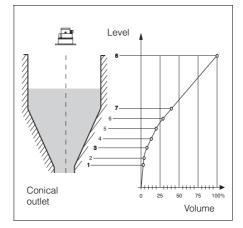
Typical Watersonic FMU 100 (Z) system application: the three pumps are controlled by the relays which switch according to the water level indicated by the DU 100 (Z)/101 (Z) sensor

Input Signal

A three-core installation cable connects the FMU 100 (Z) transmitter to the DU 100 (Z)/101 (Z) ultrasonic sensor. The FMU 100 (Z) transmitter in Monorack housing supplies power and the sensor sends back an echo signal. This is converted to a level or volume indication. The measured value is displayed at the front panel.

Vessel Linearization

Volume is calculated from level via the vessel characteristic which describes the shape of the vessel.



Signal evaluation

Standard 0/4...20 mA and 0/2...10 V outputs, proportional to level or volume, are provided.

• Any initial or end of range value can be accurately set.

Up to three relays operate in minimum or maximum fail-safe mode. The relays can switch pumps on and off when the level falls below or rises above the switch point or if a fault condition is detected.

- The relays switch individually or in sequence as required.
- A preset delay prevents overloading on pump start-up when two relays trip simultaneously.

Function Monitoring

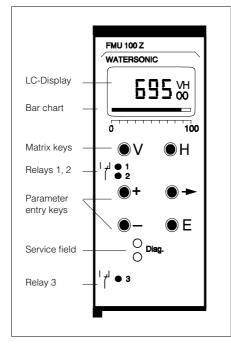
The FMU 100 (Z) transmitter continuously monitors all signal lines from sensor to analogue outputs and fails to safe if a fault is detected.

- All LEDs flash on fault condition.
- The analogue signal drives to -10 % or +110 % level or holds the last measured value.
- The relays respond according to the selected fail-safe mode.
- When used as fault alarm the 3rd relay de-energises

It is possible to enter vessel characteristics for up to 30 break points.

These are obtained by filling the vessel or from drawings provided by the user.

Operation



Front panel of the FMU 100(Z) transmitter • Keys V and H select the matrix field • Parameters are entered using the »+«, »⇒«, »-« and »E« keys

Direct Programming

The FMU 100 (Z) transmitter is programmed and interrogated at the front panel.

- Six keys access a parameter matrix, defined by a vertical (V) and horizontal (H) position, in which the relevant data can be entered.
- The selected matrix field is indicated in the LC-display preventing entry and reading errors.
- During operation level, volume, temperature, echo damping, signal/ noise ratio, and output current parameters are available for display.
- A horizontal 10-step LCD bar strip indicates level or volume as a function of the current output.

Operational Status

The operational status of the transmitter is indicated by means of 3 LEDs, which can be clearly seen from a distance.

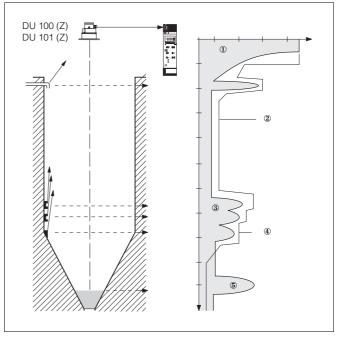
- The yellow LEDs in the central field indicate the output status of relays 1 and 2: when lit energised.
- When relay 3 is used as a fault alarm, the yellow LED in the diagnostics field lights for a fault condition. For pump control a lit LED indicates energised status.
- Should a fault condition arise when all relays are being used for pump control, all LEDs flash.

Interference Echo Suppression

The echo suppression function ensures that measurements can still be made when interference echoes, caused by permanent fixtures, are present in the signal.

• The detection threshold is automatically adjusted to the echo profile so that interference echoes are no longer registered and processed.

Suppression of interference echoes from fixtures: ① Transmission pulse and signal decay ② Time-dependent identification threshold ③ Interference echo ④ Echo suppression by temporary increase of threshold ⑤ Strong echo from product surface

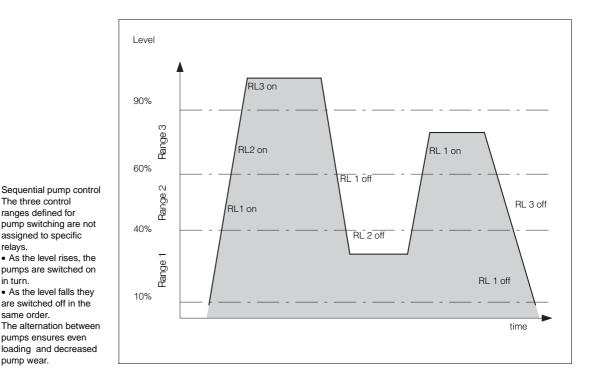


Pump Control

Operating Modes

The FMU 100 (Z) transmitter is equipped with three relays which can be used to control levels by switching pumps on and off. The switching range is defined by two switch points. Relay 3 can be assigned to fault indication or pump control as required. Possible modes are:

- Sequential pump control using two or three relays: the pumps are switched on and off alternately as the switch points are passed.
- Independent control using two relays: the third can e.g. be used as a minimum limit indicator to prevent dry-running of the pump or as a fault indicator for the Watersonic FMU 100 (Z) system.



Max. and Min. Fail-safe Mode

Each relay can be individually set to minimum or maximum fail-safe mode.

- In maximum fail-safe mode the relay de-energises when the level rises above the upper switch point and on fault condition.
- In minimum fail-safe mode the relay de-energises when the level falls below the lower switch point and on fault condition.
- On power failure all relays de-energise.

Overspill Protection/Dry Running

When all three relays are used for pump control:

- Fault conditions can be detected via the 4...20 mA signal which drops to -10% or jumps to +110% (or holds the last value) as set.
- It is recommended that an independent (conductance) system is installed as maximum or minimum switch to prevent overspills or pumps from running dry.

Mini	mum fail-safe n	node	Maximum fail-safe mode			
Level	Relay	LED	Level	Relay	LED	
< Switch point 2	De-energised	Off	< Switch point 2	Energised	On	
	z18 d20 z20 z22 d24 z24 z26 d28 z28			z18 d20 z20 z22 d24 z24 z26 d28 z28		
> Switch point 1	Energised	On	> Switch point 1	De-energised	Off	
	z18 d20 z20 z22 d24 z24 z26 d28 z28			z18 d20 z20 z22 d24 z24 z26 d28 z28		

Truth table for relay status as a function of level and fail-safe mode.

The three control

ranges defined for pump switching are not

assigned to specific

• As the level rises, the

pumps are switched on

As the level falls they

are switched off in the same order.

pumps ensures even loading and decreased

pump wear.

relays.

in turn.

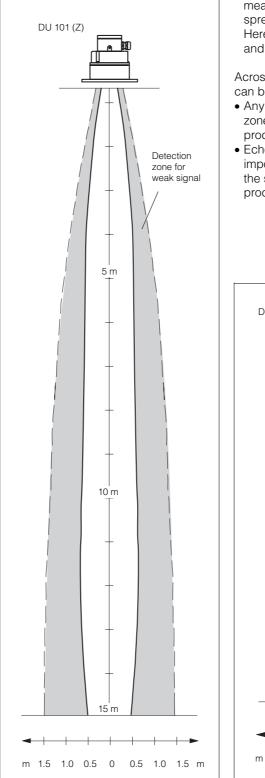
Planning

Sensor Position

If the tank or basin contains internal fittings, e.g ladders, bracing, pipework, correct positioning of the sensor is essential if interference echoes are to be kept to a minimum:

• Check that the ultrasonic pulse arrives unhindered at the product surface.





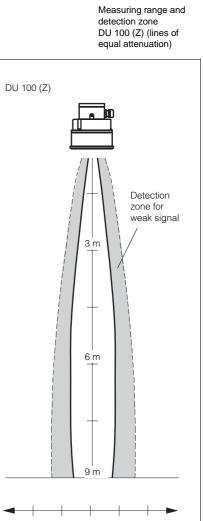
Ultrasonic Beam

The ultrasonic pulse leaves the sensor as a directed beam which slowly widens as it travels towards the product surface. Any object lying within the beam will produce an echo which may be received by the sensor.

- Take care that no edges, fittings etc. lie within the beam for the first third of the selected measuring range, since the sonic energy is still highly concentrated here: small reflecting surfaces can cause very strong echoes.
- In the last third of the selected measuring range the sonic energy is spread across a much larger area. Here reflections from internal fittings and edges are much less critical.

Across the beam two detection zones can be defined:

- Any object within the central detection zone (full line in the illustrations) will produce a strong echo.
- Echoes from the second zone are important to measurement only when the signal from the surface of the product is relatively weak.



1.0

0.5

0

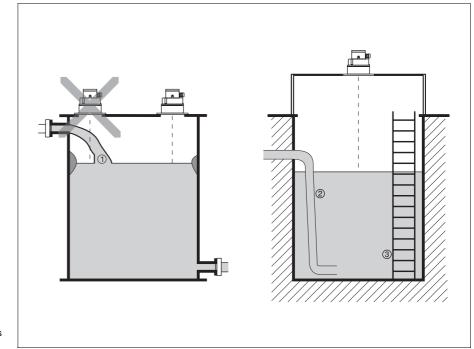
0.5

1.0 m

Recommendations

Internal Fittings

- Do not install the sensor directly above the inflow pipe or filling curtain ①.
- Check the required lateral clearance from any fittings such as pipework ⁽²⁾ or ladders ⁽³⁾ by using the detection zone diagrams



Mount the sensor so that it points to the bottom of the tank or basin. Avoid: • water inlet curtains • piping

 internal fittings such as bracings and ladders

Sensor Mounting

Several possibilities exist for mounting:

- For tanks, the slip-on flange ① can be used. A well-finished mounting pipe, with max. length 2x sensor diameter, can be used if necessary. For flange dimensions see p 11.
- For open tanks, wells and sumps a simple angle iron construction can be used ⁽²⁾. The sensor is secured by two M10 bolts.
- For covered wells and sumps where access is difficult, the sensor can be suspended from a rail by the mounting bracket ③.

Blocking Distance

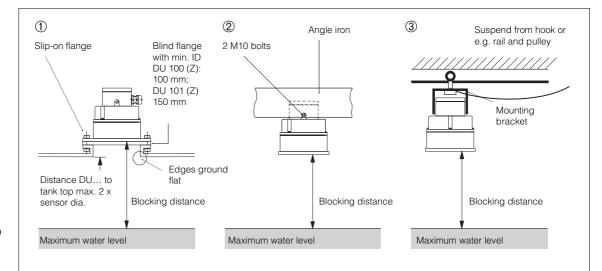
Plan mountings such that even in the event of overfilling, the level does not come within the blocking distance.

• If this criterion is not fulfilled, incorrect measurement will result.

Sensor Orientation

Mount the sensor pointing directly downwards.

- Choose a position where internal fittings are avoided.
- For conical outlets check that the sensor points to the very bottom of the shaft, so that a signal is also received when the tank is empty.



Suggestions for sensor mounting ① with slip-on flange ② with angle irons on an arm or gantry ③ movable on a rail, suspended from the mounting bracket

Electrical Connection

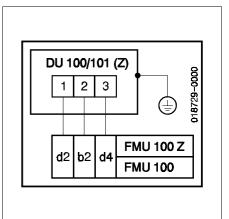
Sensor Connection

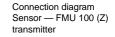
- Power is supplied by the FMU 100 (Z) transmitter in Monorack housing.
- Use commercial 3-core installation cable.
- The max. line resistance 25 Ω /core.
- When installing in explosion hazardous areas (Ex-versions only), observe the relevant regulations.

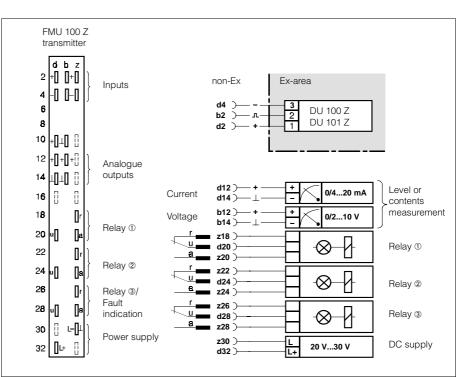
Electromagnetic Interference

In case of electromagnetic interference:

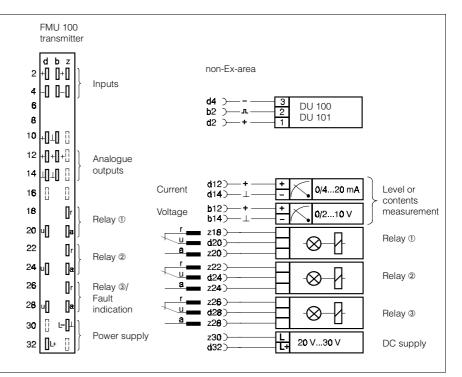
- use shielded cable
- connect to the DU ... internal ground terminal, not to the Watersonic
- connect any potential equalization cable to the DU... external ground terminal







Connection diagram FMU 100 Z transmitter



Connection diagram FMU 100 transmitter

Technical Data Watersonic FMU 100 (Z)

Construction

- Design: wall-mounted housing
- Front panel: black synthetic with blue field inlay, grip and markings,
 Protection: IP 20 (DIN 40050)
- Housing: ABS, grey with black base,
- Protection: IP 40 on flat wall, IP 30 when rail-mounted
- Dimensions: see diagram
- Weight: approx. 1.2 kg/3 lbs
- Operating temperature: -20°C...+60°C Storage temperature: -20°C...+ 85°C

Protective Monorack housing



Protective Housing (Accessory)

- Aluminium housing, for 2 Watersonic units.
- Construction: pollution and sea-water resistant aluminium base, transparent PVC cover with cellular rubber seal
- Protection: IP 55 (DIN 40050)
- Dimensions: 209 x 258 x 235 mm
- Weight: 2.9 kg/6 lbs.
- Operating temperature:
- -20°C...+50°C with 1 Monorack -20°C...+40°C with 2 Monorack

Signal outputs

- Current output: 0...20 mA/4...20 mA selectable, RL max. 500 Ω
- Voltage output:
 0...10 V/2...10 V selectable,
 R_L min. 2 k Ω

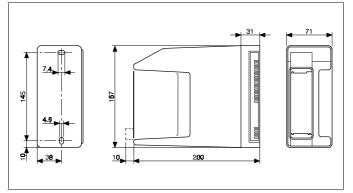
Relays

- Two independent relays each with a potential-free change-over contact; freely selectable switching range.
- Third relay with potential-free change-over contact, for fault indication or pump control as desired
- Fail-safe mode: Minimum or maximum, selectable
- Pump control: individual or sequential assignment for 2 or 3 relays as required
- Switching capacity: max. 2.5 A, max. 250 V AC (for CSA max. 125 V AC) max. 300 VA at $\cos \phi > 0.7$ max. 100 V DC, max. 90 W

Certificate

 Transmitter FMU 100 Z: PTB No. Ex-92.C.2026 X

Subject to technical change



Dimensions (mm) of Monorack housing for FMU 100 (Z) transmitter

Plug connection

- Multipoint plug: conforming to DIN 41612, Part 3, Type F (30-pole)
 see Connection Diagram
- Index pins for Z-version coding supplied for insertion at positions 1 and 28

Power Supply

- 220...240 V AC (+15%, 10%), 50/60 Hz switchable to 110...127 V AC (+15%, - 10%) or 100 VAC ±10%, 50/60 Hz switchable to 200 V AC ±10% or 42...48 V AC (+15%, - 10%), 50/60 Hz switchable to 24...28 V AC (+15%, - 10%) or 24 V DC, residual ripple < 600 mV, 100 Hz
- Output current: max. 130 mA
- Power consumption: max. 5.5 W

Signal Inputs

- Electrically isolated from the rest of the circuitry.
- For Z-versions, intrinsically safe, designed to conform to (EEx-ia) IIC
 Probes:
- DU 100 Z and 101 Z for FMU 100 Z DU 100 and DU 101 for FMU 100

DU 100 (Z), DU 101 (Z) Sensors

Housing

- Material: Crastin
- Sealing face and diaphragm: PVDF
- Protection IP 68
- Weight: ca. 4 kg/9 lbs
- Dimensions: see below

Slip-On Flange

- Standard connections to DIN, JIS or ANSI
- Materials: polypropylene, coated steel or stainless steel - see page 11 -
- Counterflange on tank: DU 100 (Z) with ID min. 100 mm DU 101 (Z) with ID min. 150 mm

Operating Conditions

- Operating pressure with metal slip-on flange: pe= max. 3 bar with polypropylene flange: pe= max. 0.5 bar
- Temperature: -20...+80 °C

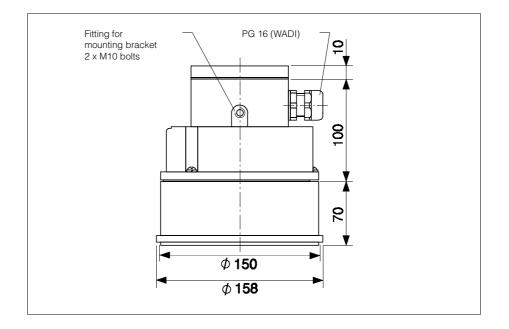
Ultrasonics

	DU 100 (Z)	DU 101 (Z)
 Range: 	9m/29 ft	15m/49 ft
 Frequency: 	38 kHz	31 kHz

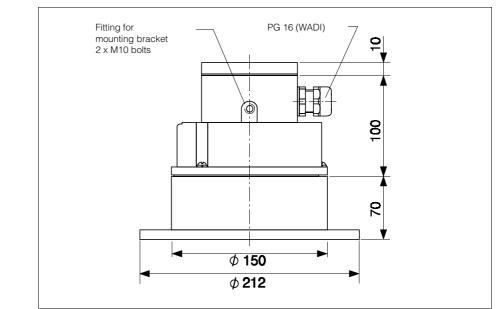
- 4 Hz 2 Hz
- Pulse frequency: 0.8m
- Blocking distance: 0.5m • Angle of emission 5° at -3 dB: 8°

Certificates

- DU 100 Z or DU 101 Z sensor, EEx ia IIC T5, used with FMU 100 Z transmitter in Monorack housing: PTB No. Ex-92.C.2027
- FMU 100 Z: PTB No. Ex-92.C.2026 X







DU 101 (Z) sensor dimensions in mm 1" = 25.4 mm

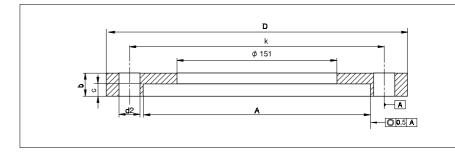
Accessories

Slip-On Flange FAU 60 for DU 100 (Z)

- DN 100 PN 16 (Code D0),
- JIS 100 K 16 (Code J0) or
- ANSI 4" 150 psi (Code A0).

Slip-On Flange FAU 60 for DU 101 (Z)

- DN 150 PN 16 (Code D1),
- JIS 150 K 16 (Code J1) or
- ANSI 6" 150 psi (Code A1).



Slip-on flange dimensions (mm). Customer must provide counterflange or blind flange with bore dia. DU 100 (Z): ≥ 100 mm DU 101 (Z): ≥ 150 mm

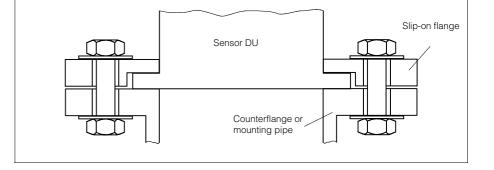
Order No.	A	b	С	ØD	Ø d2	k	No. d2	Material	Standard
DU 100 (Z)									
FAU 60 D0 P	160	20	9,2	220	18	180	8	PP	DN 100 PN 16
FAU 60 D0 S								St/Painted	
FAU 60 D0 R								1.4571	
FAU 60 A0 P		23.9		228.6		190.5		PP	ANSI 4" 150 psi
FAU 60 A0 S								St/Painted	
FAU 60 A0 R								1.4571	
FAU 60 J0 P		22		225	23	185		PP	JIS 16 K 100
FAU 60 J0 S								St/Painted	_
FAU 60 J0 R								1.4571	
DU 101 (Z)									
FAU 60 D1 P	215	22	11.5	285	22	240	8	PP	DN 150 PN 16
FAU 60 D1 S								St/Painted	_
FAU 60 D1 R								1.4571	
FAU 60 A1 P		25.4		279.4		241.3		PP	ANSI 6" 150 psi
FAU 60 A1 S								St/Painted	_
FAU 60 A1 R								1.4571	
FAU 60 J1 P		24		305	25	260	12	PP	JIS 16 K 150
FAU 60 J1 S								St/Painted	
FAU 60 J1 R								1.4571	



Key to slip-on flange drawing, dimensions in mm (1" = 25.4 mm)for DU 100 (Z)

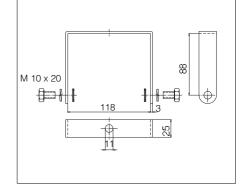
for DU 101 (Z)





Mounting Bracket FAU 10

A mounting bracket is available as an alternative to the slip-on flange. It allows the sensor to be suspended from the top of the tank or silo.



Mounting bracket dimensions in mm



How to Order	Watersonic FMU 100					
	Sensor 1 DU 100 2 DU 101 Power supply A 110 V/220 V AC L 100 V/200 V AC D 24 V/48 V AC E 24 V DC Image: state of the second seco					
	Watersonic FMU 100 Z					
	Sensor 1 DU 100 Z 2 DU 101 Z Power supply A 110 V/220 V L 100 V/200 V D 24 V/48 V A E 24 V DC I Image: state of the state	Z Supply V/220 V AC V/200 V AC /48 V AC				
	Accessories					
	Slip on flange Mounting bracket FAU 10 Protective housing, IP 55 Protective housing, IP 55, plastic coated	Order No. FAU 60- *** Order No. 918815-0000 Order No. 918510-0000 Order No. 918510-0001				
Supplementary Documentation		Monorack Protective Housing Technical Information TI 099F/00/en				
		Endress+Hauser GmbH+Co.				

Instruments International P.O. Box 2222 D-79574 Weil am Rhein Germany

Tel. (07621) 975-02 Tx 773926 Fax (07621) 975345 http://www.endress.com



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